

Approximations to the solution of the Kushner-Stratonovich equation for the stochastic chemostat

Augusto Magalhães^{*a*}, Muhammad Emzir^{*b*}, Francesco Corona^{*a*}

a Process control and automation, Department of Chemical and Metallurgical Engineering, Aalto University, Finland

b Control and Instrumentation Engineering Department, King Fahd University of Petroleum and Minerals, Saudi Arabia

The chemostat

F_{in} : influent flow rate

F_{out} : outgoing flow rate

V : volume of the vessel

s_{in} : incoming flow of substrate

b : outgoing concentration of biomass

s : outgoing concentration of substrate

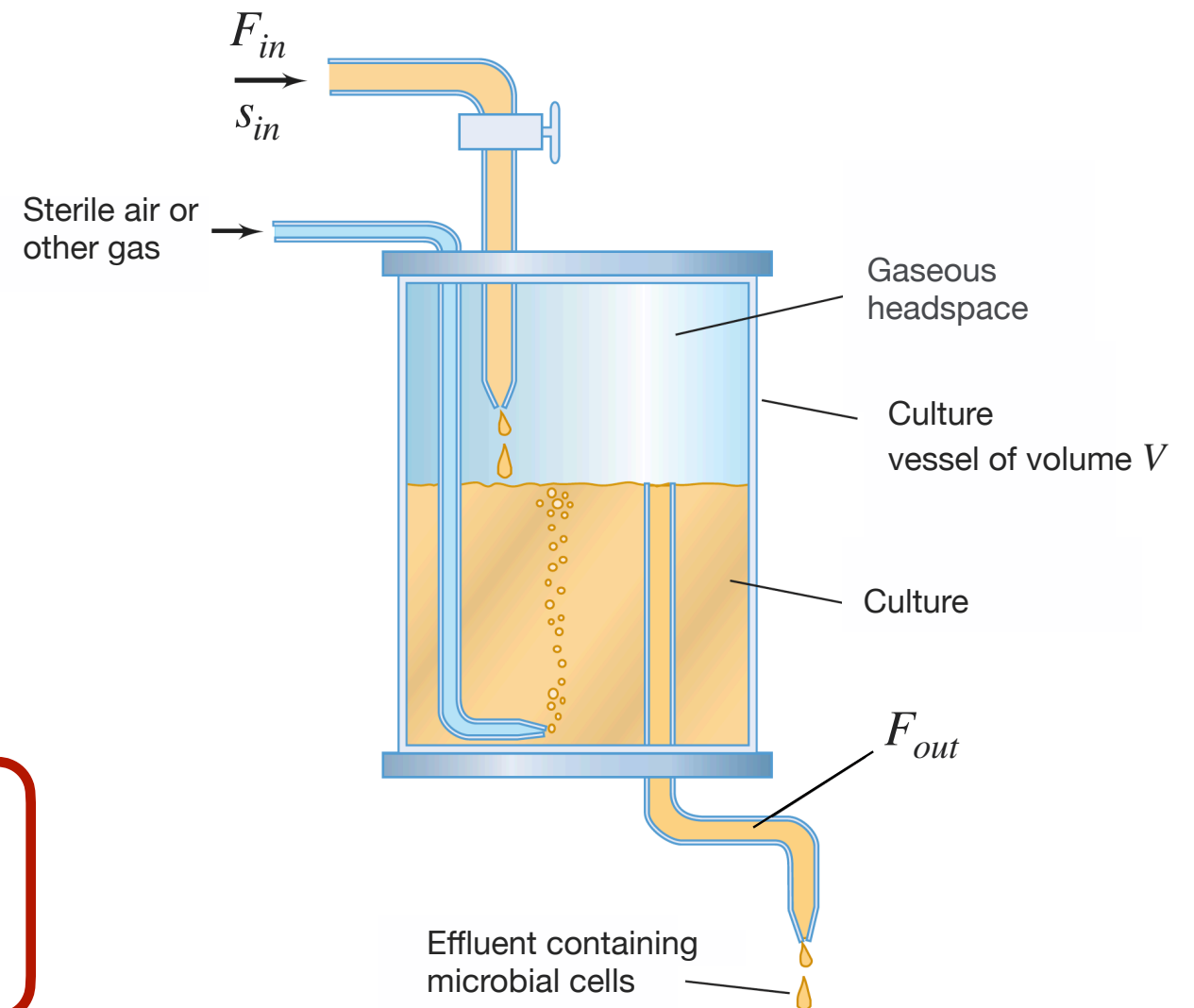


Figure 1: schematic for the chemostat.

The chemostat

$F_{in} = F_{out} = F$: flow rate [Lh^{-1}]

$D = F/V$: dilution rate [h^{-1}]

$\mu(\cdot)$: specific growth function

$$d \begin{bmatrix} b(t) \\ s(t) \end{bmatrix} = \begin{bmatrix} (\mu(b(t), s(t)) - D)b(t) \\ D(s_{in} - s(t)) - \kappa\mu(b(t), s(t))b(t) \end{bmatrix} dt,$$

with $b(0) = b_0, s(0) = s_0$.

The chemostat

$$\underbrace{d \begin{bmatrix} b(t) \\ s(t) \end{bmatrix}}_{x(t)} = \underbrace{\begin{bmatrix} (\mu(b(t), s(t)) - D)b(t) \\ D(s_{in} - s(t)) - \kappa\mu(b(t), s(t))b(t) \end{bmatrix}}_{f(t, x(t))} dt,$$

with $x(0) = (b(0), s(0))^{\top}$.

The chemostat

$$\underbrace{d \begin{bmatrix} b(t) \\ s(t) \end{bmatrix}}_{x(t)} = \underbrace{\begin{bmatrix} (\mu(b(t), s(t)) - D)b(t) \\ D(s_{in} - s(t)) - \kappa\mu(b(t), s(t))b(t) \end{bmatrix}}_{f(t, x(t))} dt,$$

with $x(0) = (b(0), s(0))^T$.

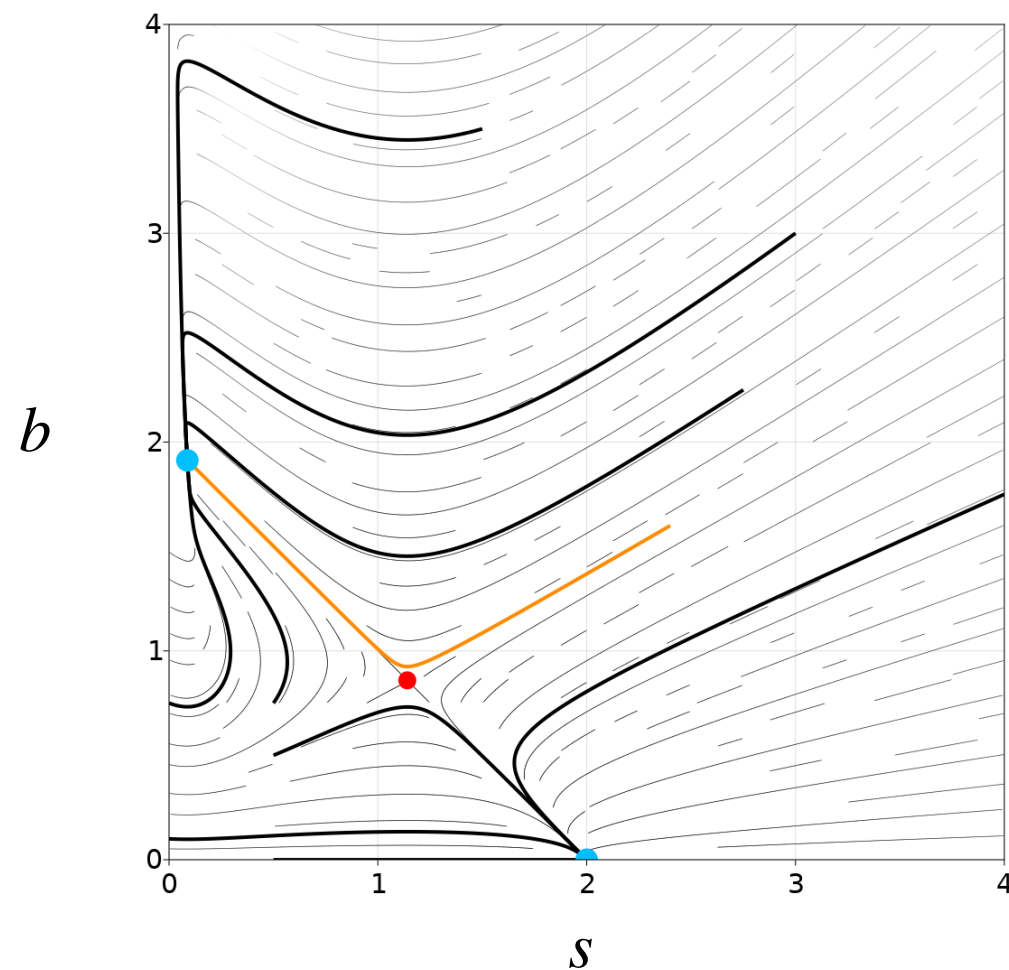


Figure 2: phase portrait for the deterministic model.

The stochastic chemostat

$$\underbrace{d \begin{bmatrix} b(t) \\ s(t) \end{bmatrix}}_{X_t} = \underbrace{\begin{bmatrix} (\mu(b(t), s(t)) - D)b(t) \\ D(s_{in} - s(t)) - \kappa\mu(b(t), s(t))b(t) \end{bmatrix}}_{f(t, X_t)} dt + \underbrace{\begin{bmatrix} \omega_b b(t) & 0 \\ 0 & \omega_s s(t) \end{bmatrix}}_{g(t, X_t)} d \underbrace{\begin{bmatrix} B_t^b \\ B_t^s \end{bmatrix}}_{B_t^x},$$

with initial condition X_0 .

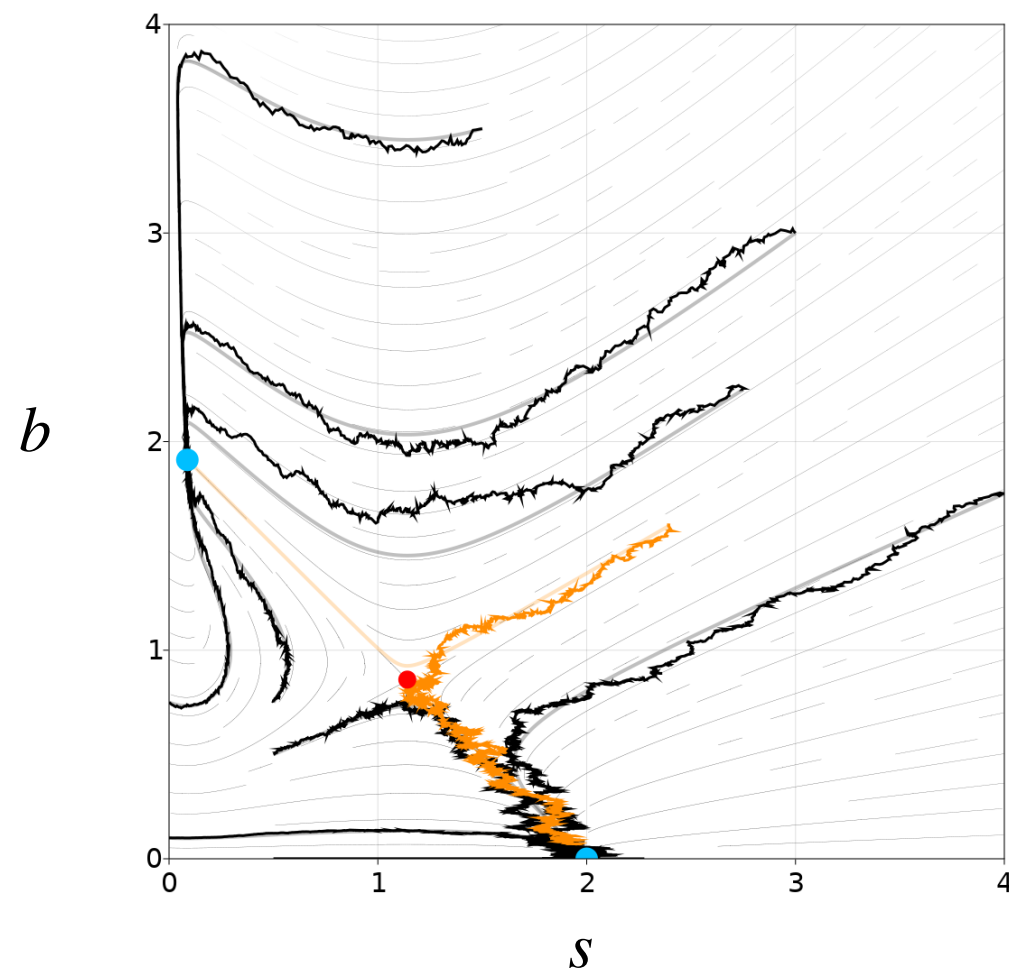


Figure 3: trajectories from the stochastic model.

The Kolmogorov Forward Equation

Also known as the Fokker-Planck equation

Evolution of the probability distribution of the signal $\{X_t\}$:

$$\frac{\partial}{\partial t} p(t, x) = - \sum_{d_x=1}^{D_x} \frac{\partial}{\partial x_{d_x}} [f_{d_x}(t, x) p(t, x)] + \sum_{d_x=1}^{D_x} \sum_{d'_x=1}^{D_x} \frac{\partial^2}{\partial x_{d_x} \partial x_{d'_x}} [G_{d_x d'_x}(t, x) p(t, x)],$$

with diffusion terms $G_{d_x d'_x}(t, x) = \frac{1}{2} \sum_{m=1}^M g_{d_x m}(t, x) g_{d'_x m}(t, x)$,

and initial condition $p(0, x)$.

$$dX_t = f(t, X_t)dt + g(t, X_t)dB_t^x$$

The Kolmogorov Forward Equation

Also known as the Fokker-Planck equation

Evolution of the probability distribution of the signal $\{X_t\}$:

Change in
probability

Advection

Diffusion

$$\frac{\partial}{\partial t} p(t, x) = - \sum_{d_x=1}^{D_x} \frac{\partial}{\partial x_{d_x}} [f_{d_x}(t, x) p(t, x)] + \sum_{d_x=1}^{D_x} \sum_{d'_x=1}^{D_x} \frac{\partial^2}{\partial x_{d_x} \partial x_{d'_x}} [G_{d_x d'_x}(t, x) p(t, x)],$$

with diffusion terms $G_{d_x d'_x}(t, x) = \frac{1}{2} \sum_{m=1}^M g_{d_x m}(t, x) g_{d'_x m}(t, x),$

and initial condition $p(0, x).$

$$dX_t = f(t, X_t)dt + g(t, X_t)dB_t^x$$

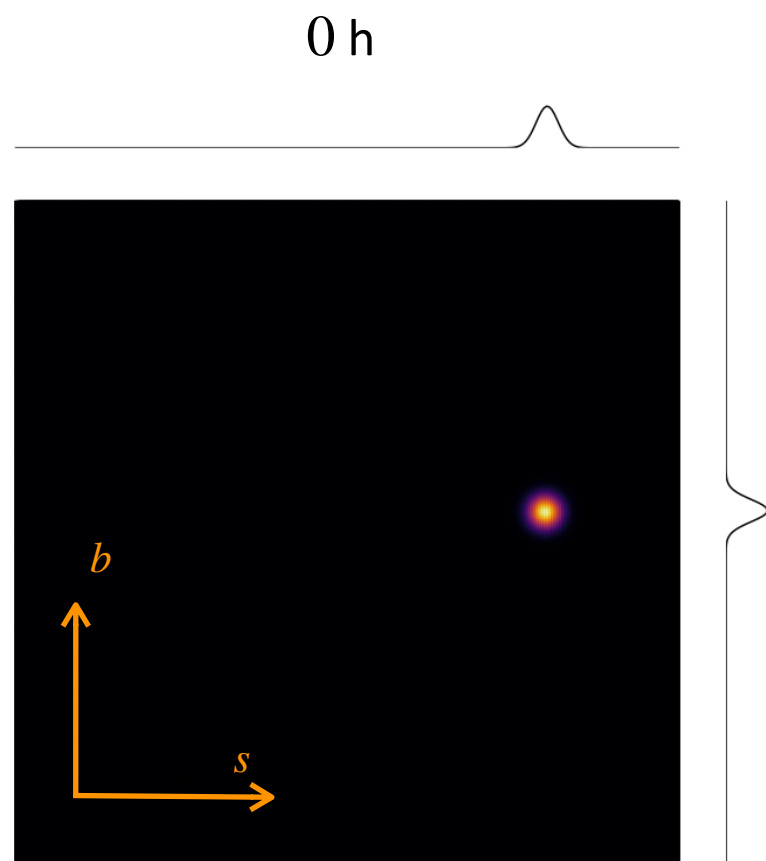


Figure 4: solution to the Fokker-Planck equation.

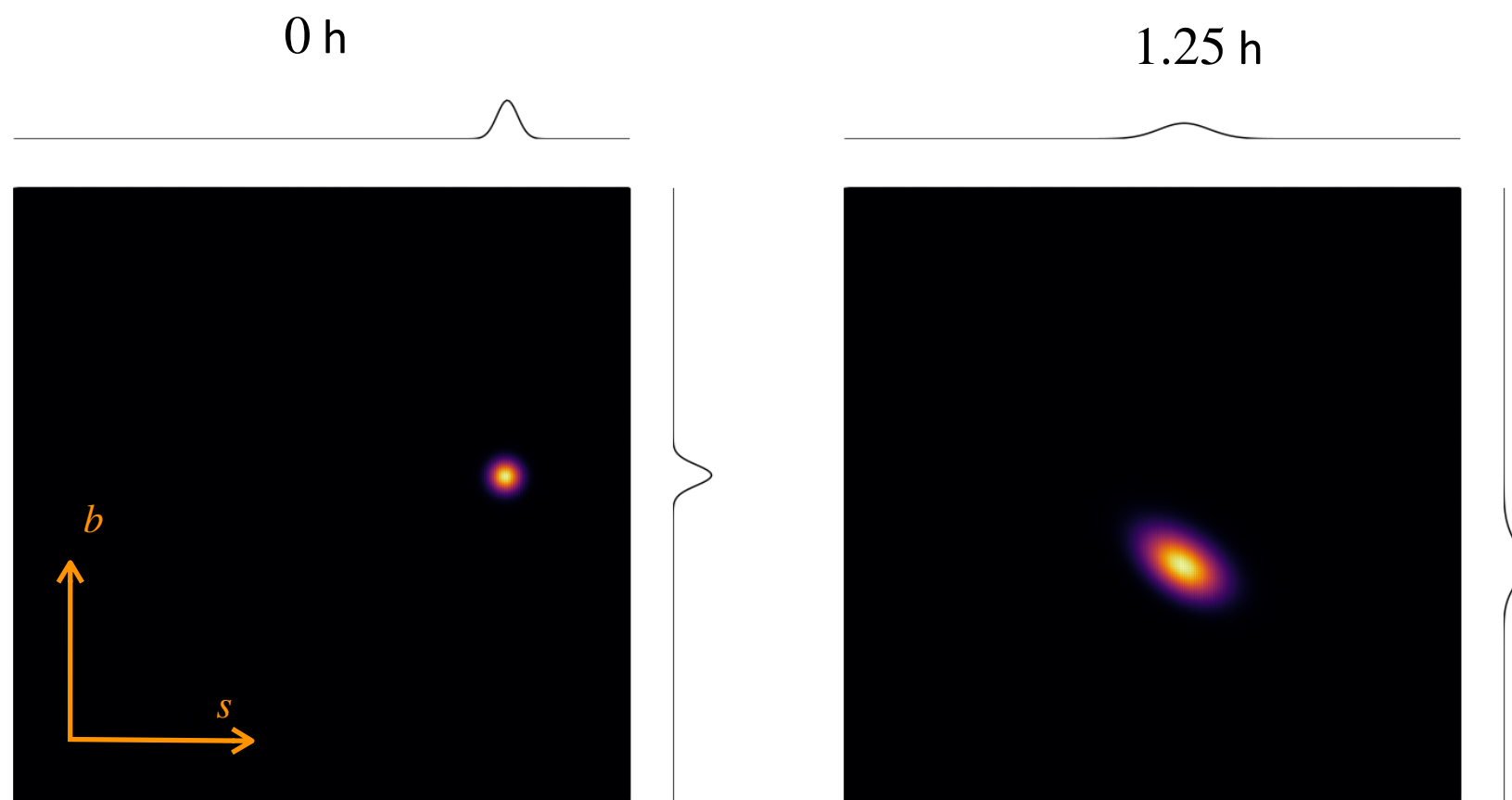


Figure 4: solution to the Fokker-Planck equation.

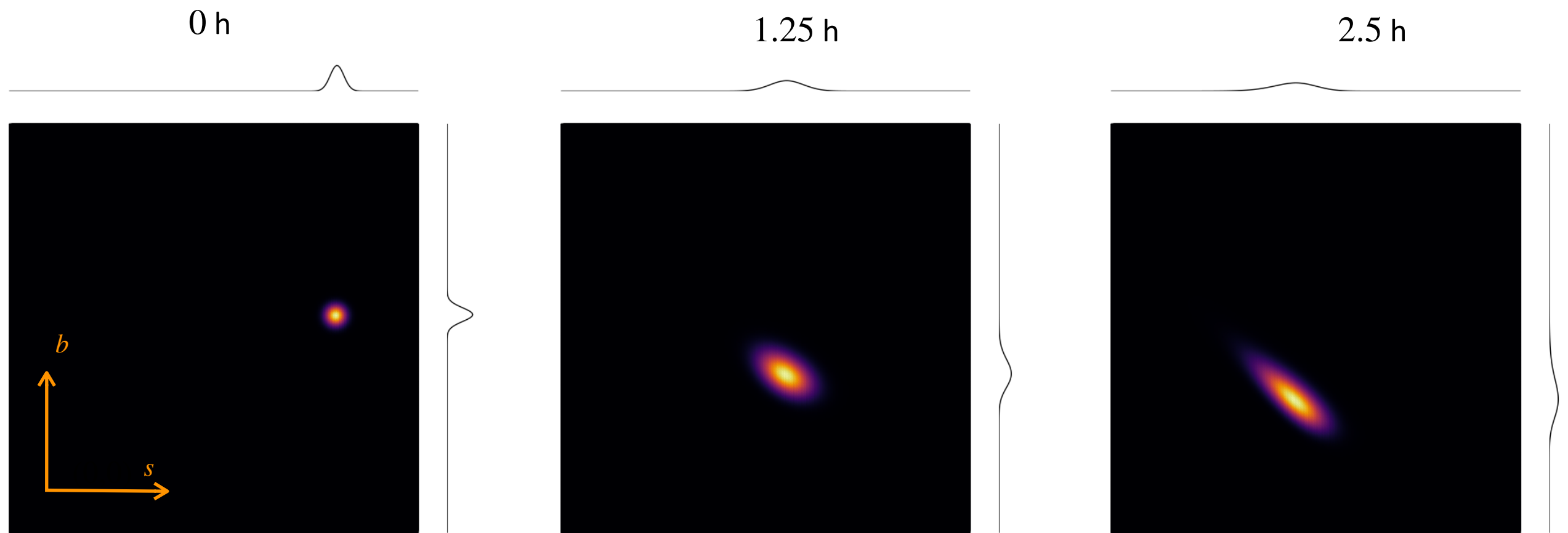


Figure 4: solution to the Fokker-Planck equation.

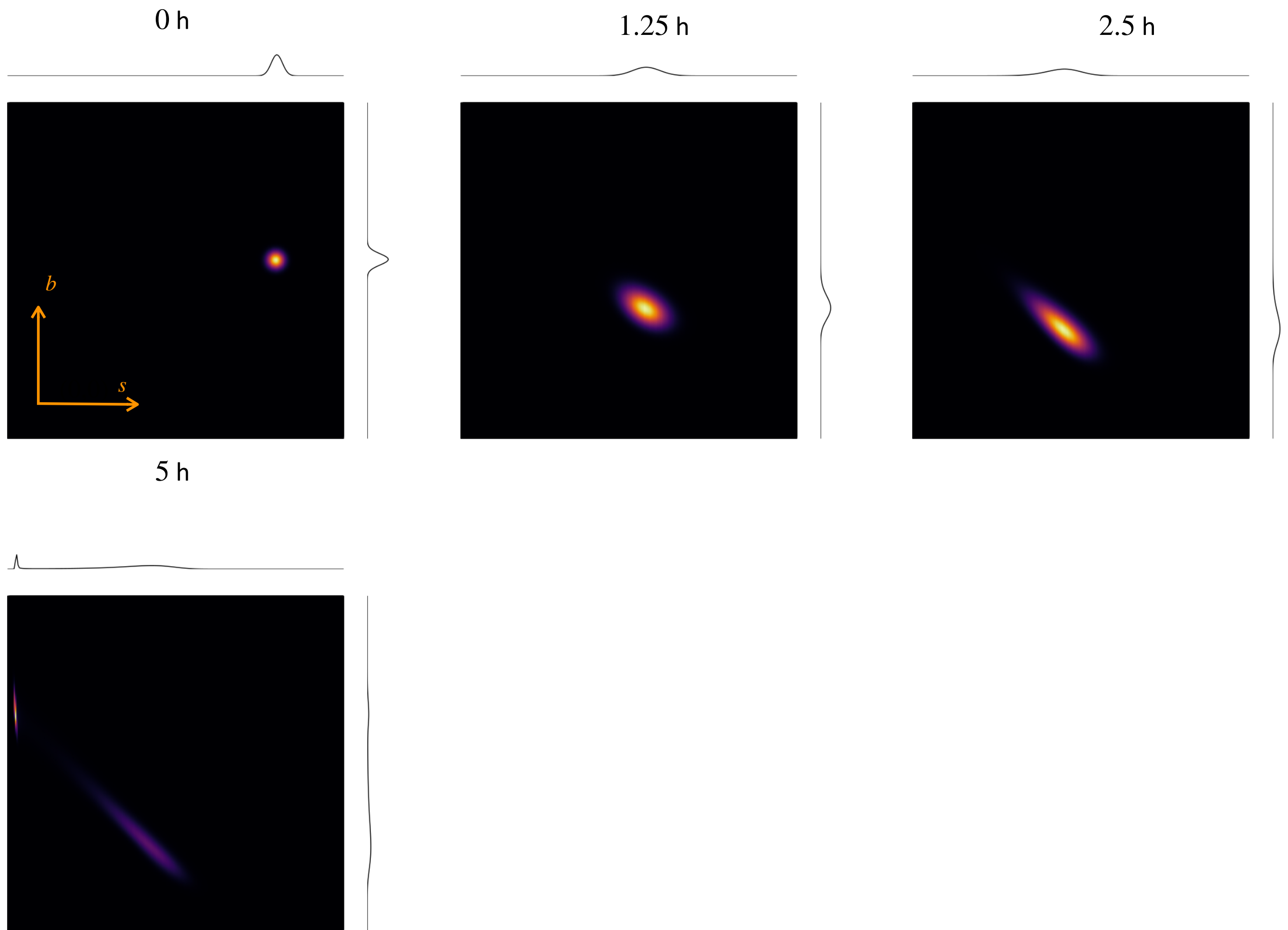


Figure 4: solution to the Fokker-Planck equation.

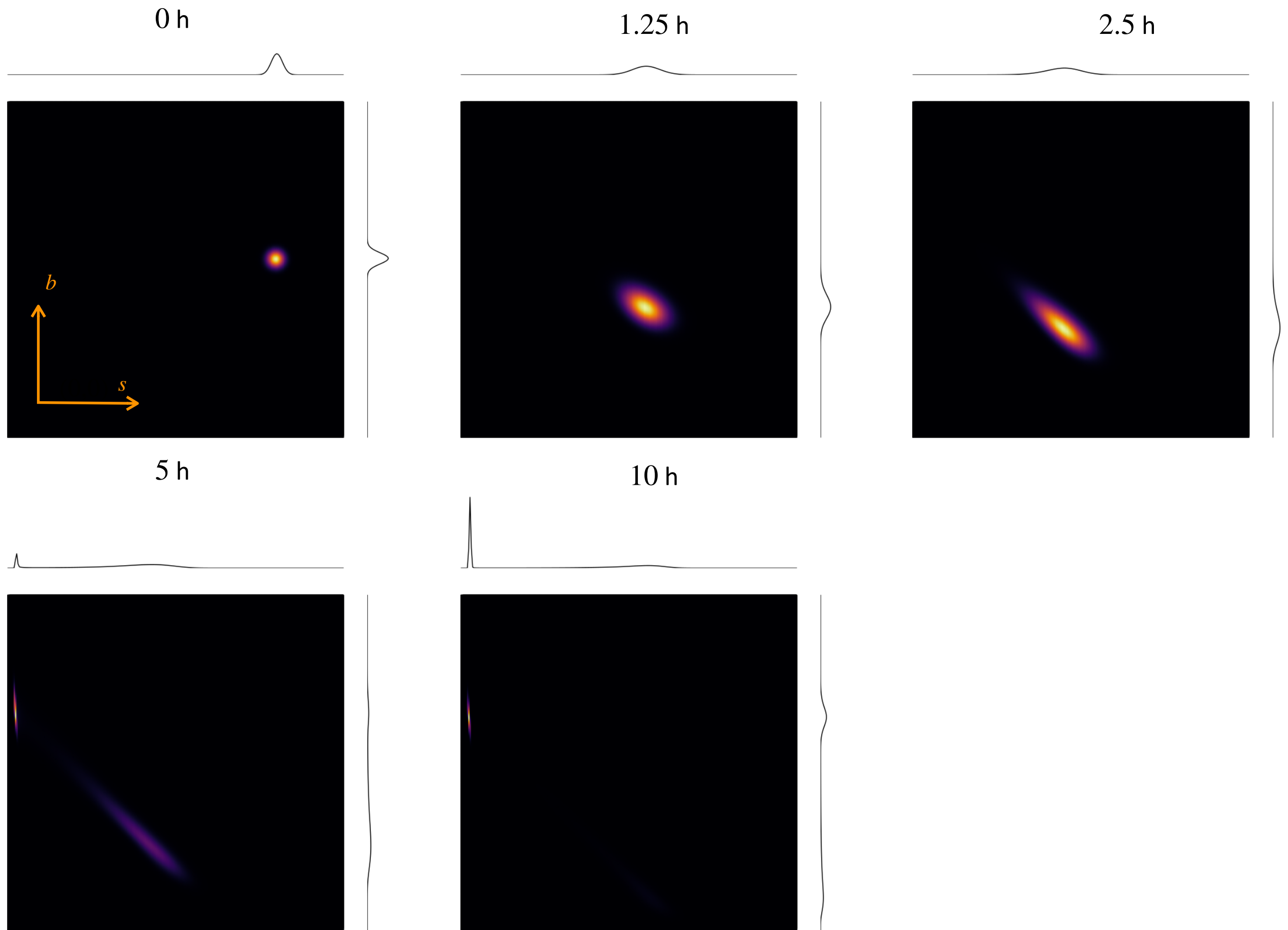


Figure 4: solution to the Fokker-Planck equation.

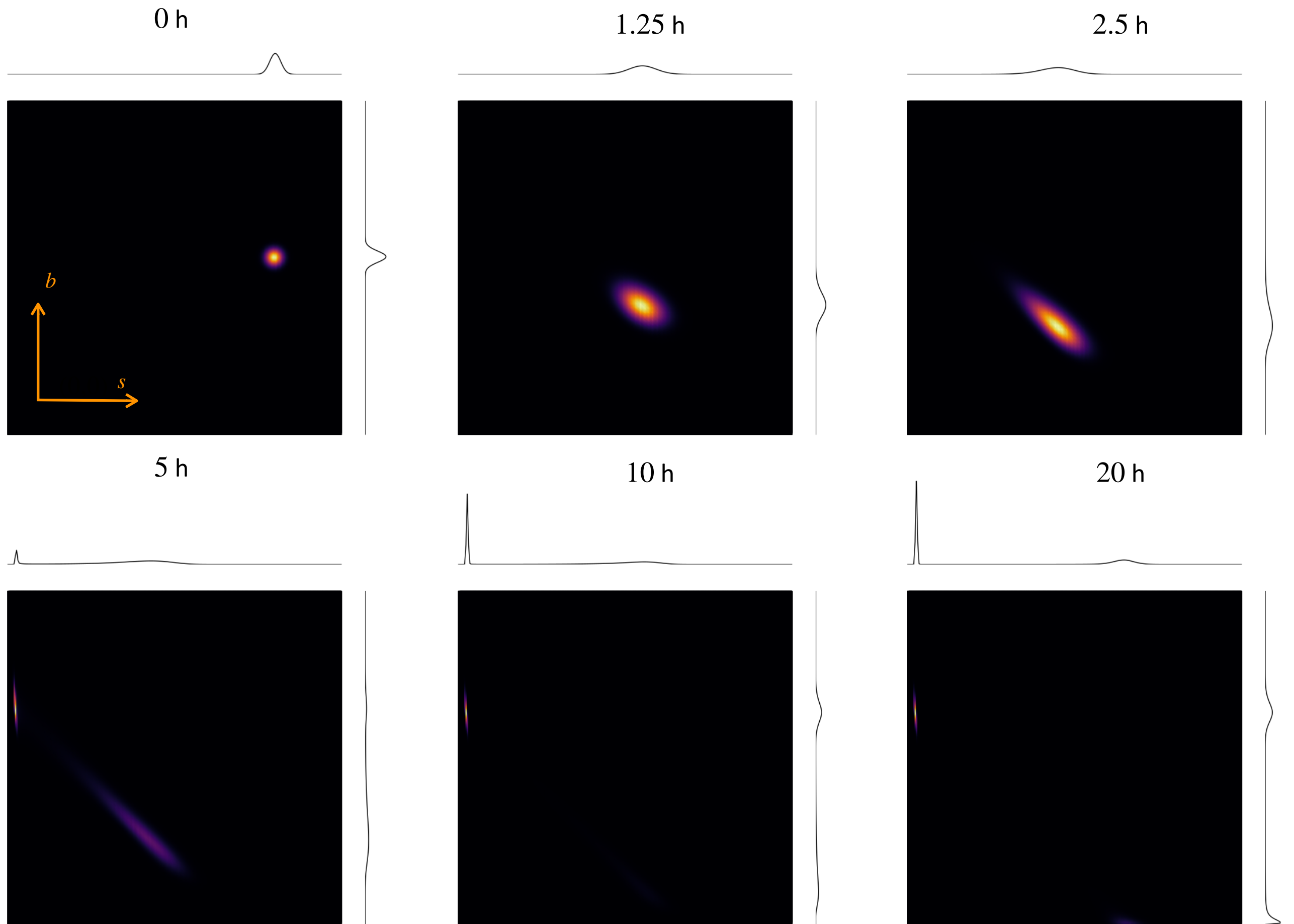


Figure 4: solution to the Fokker-Planck equation.

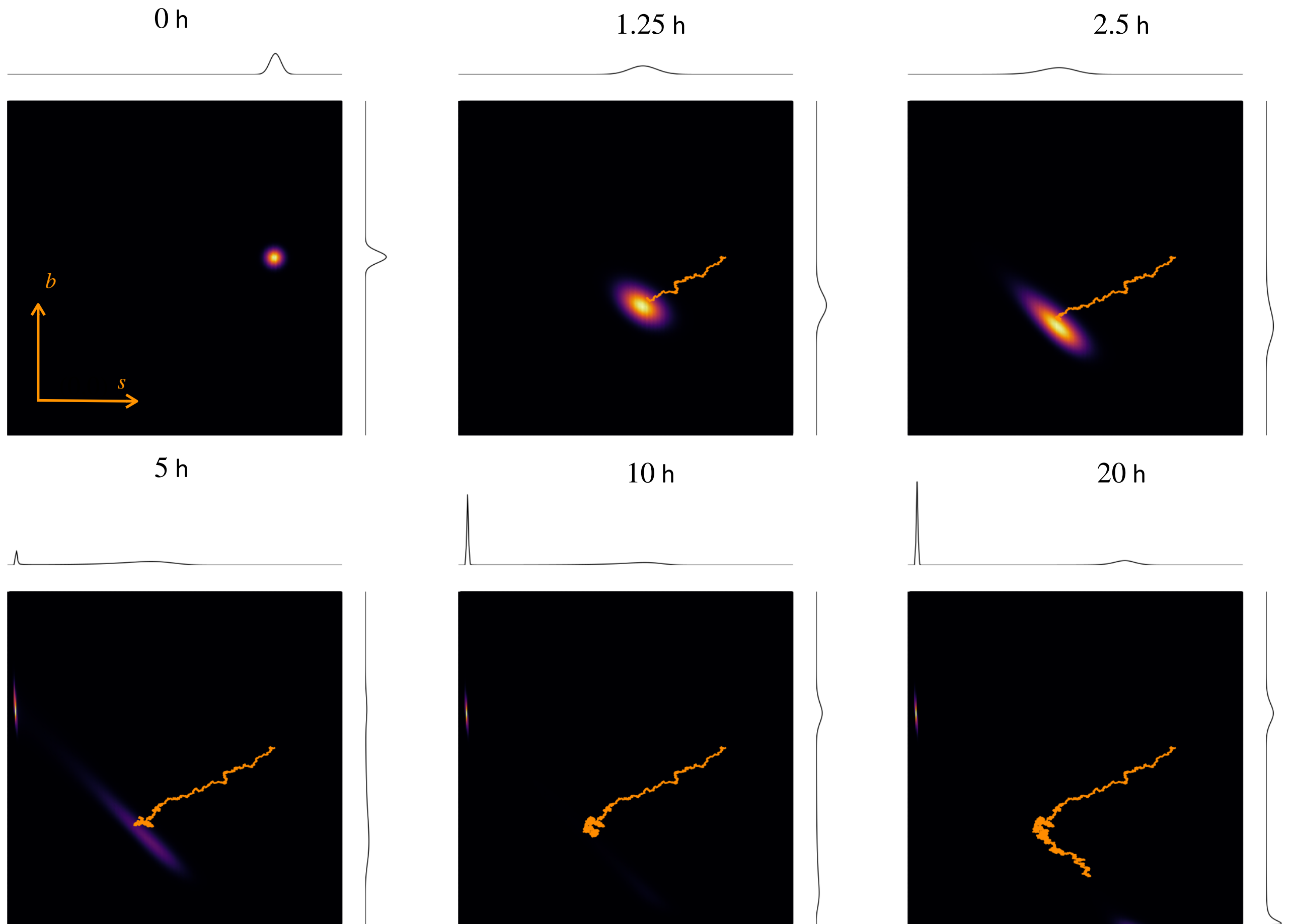


Figure 4: solution to the Fokker-Planck equation.

$$\dot{Q}(t) = V\mu(b(t), s(t))b(t) + \varepsilon$$

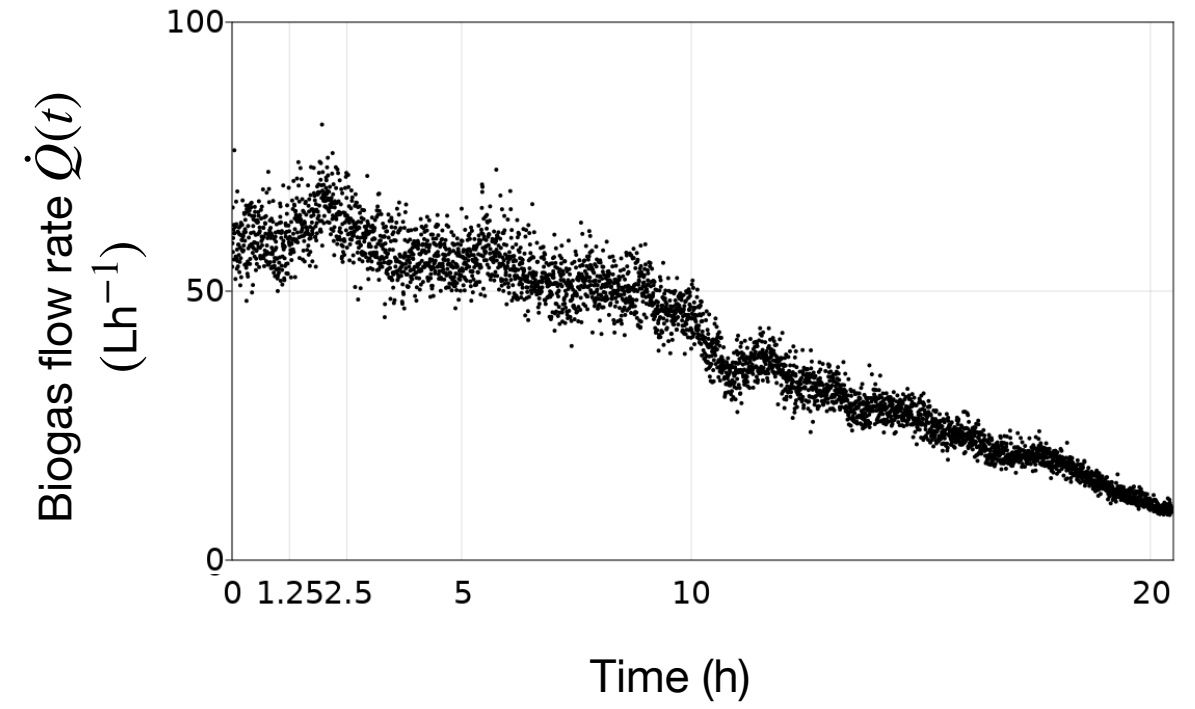


Figure 5: measurements corrupted by noise.

$$\begin{array}{c}
 \underline{\dot{Q}(t)} \\
 Y_t
 \end{array}
 =
 \begin{array}{c}
 \underline{V\mu(b(t), s(t))b(t)} \\
 h(t, X_t)
 \end{array}
 +
 \begin{array}{c}
 \varepsilon \\
 \uparrow \\
 \text{Gaussian noise}
 \end{array}$$

\uparrow
 Observation function

$$dX_t = f(t, X_t)dt + g(t, X_t)dB_t^x,$$

$$Y_t = h(t, X_t) + \varepsilon, \quad \varepsilon \sim \mathcal{N}(0, k^2(t))$$

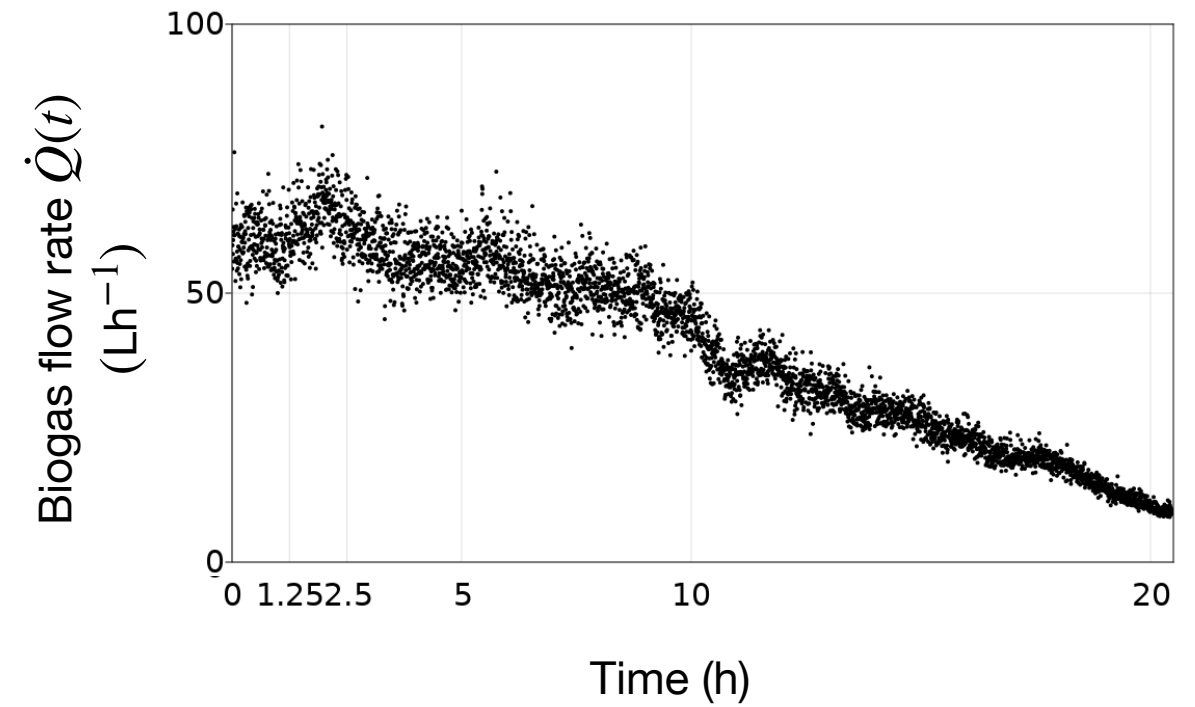


Figure 5: measurements corrupted by noise.

$$\begin{array}{c}
 \underline{\dot{Q}(t)} \\
 Y_t
 \end{array}
 =
 \begin{array}{c}
 \underline{V\mu(b(t), s(t))b(t)} \\
 h(t, X_t)
 \end{array}
 +
 \begin{array}{c}
 \varepsilon \\
 \uparrow \\
 \text{Gaussian noise}
 \end{array}$$

\uparrow
 Observation function

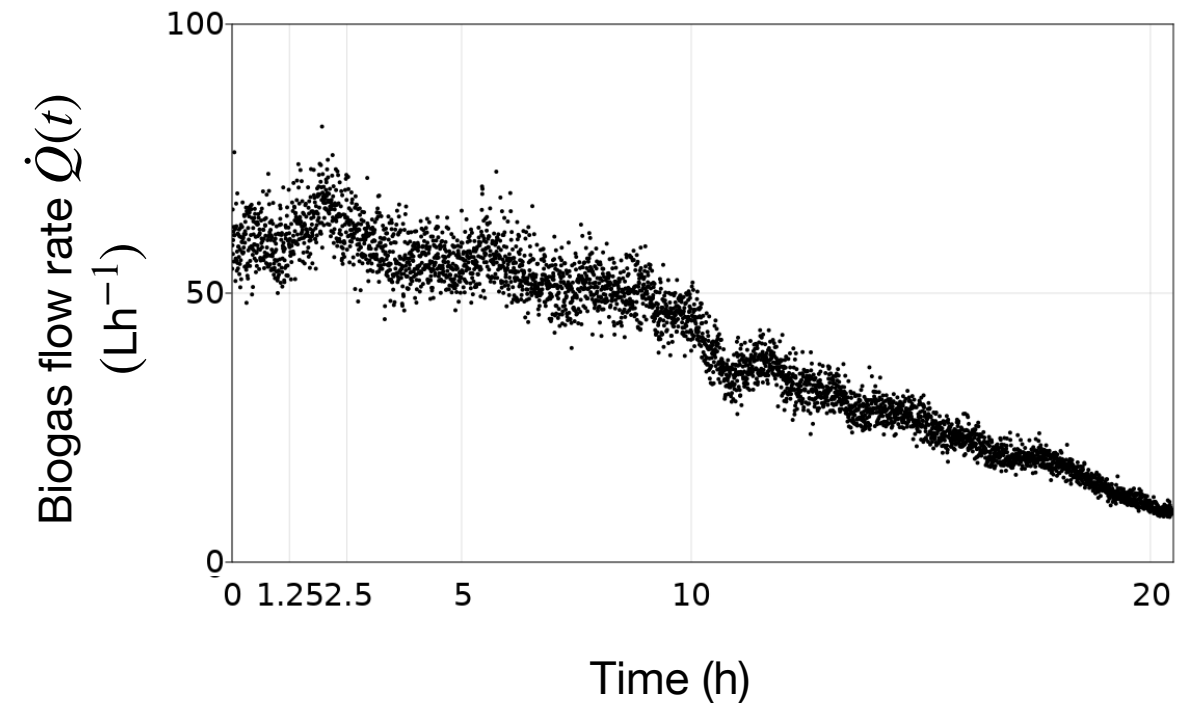


Figure 5: measurements corrupted by noise.

$$dX_t = f(t, X_t)dt + g(t, X_t)dB_t^x,$$

$$Y_t = h(t, X_t) + \varepsilon, \quad \varepsilon \sim \mathcal{N}(0, k^2(t))$$

Goal: find the distribution of the signal $\{X_t\}$ given some information F_τ^y from measurements, for $\tau \leq t$,

i.e. $p_t := p(t, x | F_\tau^y)$.

The Kushner-Stratonovich Equation

Kushner (1964, 1967) and Stratonovich (1968)

$$\begin{aligned} \frac{\partial}{\partial t} p_t = & - \sum_{d_x=1}^{D_x} \frac{\partial}{\partial x_{d_x}} [f_{d_x}(t, x) p_t] + \sum_{d_x=1}^{D_x} \sum_{d'_x=1}^{D_x} \frac{\partial^2}{\partial x_{d_x} \partial x_{d'_x}} [G_{d_x d'_x}(t, x) p_t] \\ & + p_t \times (h(t, x) - \mathbb{E}_t[h(t, x)])^\top (k^2(t))^{-1} \times (dY_t - \mathbb{E}_t[h(t, x)] dt) \end{aligned}$$

$$\begin{aligned} p_t &:= p(t, x \mid F_\tau^y) \\ dX_t &= f(t, X_t) dt + g(t, X_t) dB_t^x \\ Y_t &= h(t, X_t) + \varepsilon \end{aligned}$$

The Kushner-Stratonovich Equation

Kushner (1964, 1967) and Stratonovich (1968)

Partial derivatives in a
 D_x -dimensional grid



$$\begin{aligned} \frac{\partial}{\partial t} p_t = & - \sum_{d_x=1}^{D_x} \frac{\partial}{\partial x_{d_x}} [f_{d_x}(t, x) p_t] + \sum_{d_x=1}^{D_x} \sum_{d'_x=1}^{D_x} \frac{\partial^2}{\partial x_{d_x} \partial x_{d'_x}} [G_{d_x d'_x}(t, x) p_t] \\ & + p_t \times (h(t, x) - \mathbb{E}_t[h(t, x)])^\top (k^2(t))^{-1} \times (dY_t - \mathbb{E}_t[h(t, x)] dt) \end{aligned}$$

$$p_t := p(t, x | F_\tau^y)$$

$$dX_t = f(t, X_t)dt + g(t, X_t)dB_t^x$$

$$Y_t = h(t, X_t) + \varepsilon$$

The Kushner-Stratonovich Equation

Kushner (1964, 1967) and Stratonovich (1968)

Partial derivatives in a
 D_x -dimensional grid



$$\frac{\partial}{\partial t} p_t = - \sum_{d_x=1}^{D_x} \frac{\partial}{\partial x_{d_x}} [f_{d_x}(t, x) p_t] + \sum_{d_x=1}^{D_x} \sum_{d'_x=1}^{D_x} \frac{\partial^2}{\partial x_{d_x} \partial x_{d'_x}} [G_{d_x d'_x}(t, x) p_t]$$

$$+ p_t \times (h(t, x) - \mathbb{E}_t[h(t, x)])^\top (k^2(t))^{-1} \times (dY_t - \mathbb{E}_t[h(t, x)] dt)$$



Nonlinearity on p_t :

$$\mathbb{E}_t[h(t, x)] = \int_{\mathbb{R}_{D_x}} h(t, x) p(t, x | F_\tau^y) dx$$

$$p_t := p(t, x | F_\tau^y)$$

$$dX_t = f(t, X_t)dt + g(t, X_t)dB_t^x$$

$$Y_t = h(t, X_t) + \varepsilon$$

The Kushner-Stratonovich Equation

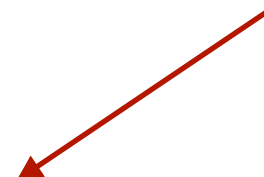
Kushner (1964, 1967) and Stratonovich (1968)

Partial derivatives in a
 D_x -dimensional grid



$$\frac{\partial}{\partial t} p_t = - \sum_{d_x=1}^{D_x} \frac{\partial}{\partial x_{d_x}} [f_{d_x}(t, x) p_t] + \sum_{d_x=1}^{D_x} \sum_{d'_x=1}^{D_x} \frac{\partial^2}{\partial x_{d_x} \partial x_{d'_x}} [G_{d_x d'_x}(t, x) p_t]$$

Stochastic
process



$$+ p_t \times (h(t, x) - \mathbb{E}_t[h(t, x)])^\top (k^2(t))^{-1} \times (dY_t - \mathbb{E}_t[h(t, x)]dt)$$



Nonlinearity on p_t :

$$\mathbb{E}_t[h(t, x)] = \int_{\mathbb{R}_{D_x}} h(t, x) p(t, x | F_\tau^y) dx$$



$$p_t := p(t, x | F_\tau^y)$$

$$dX_t = f(t, X_t)dt + g(t, X_t)dB_t^x$$

$$Y_t = h(t, X_t) + \varepsilon$$

The Kushner-Stratonovich Equation

Kushner (1964, 1967) and Stratonovich (1968)

Partial derivatives in a D_x -dimensional grid

↓ ↓

$$\frac{\partial}{\partial t} p_t = - \sum_{d_x=1}^{D_x} \frac{\partial}{\partial x_{d_x}} [f_{d_x}(t, x) p_t] + \sum_{d_x=1}^{D_x} \sum_{d'_x=1}^{D_x} \frac{\partial^2}{\partial x_{d_x} \partial x_{d'_x}} [G_{d_x d'_x}(t, x) p_t]$$

Stochastic process

$$+ p_t \times (h(t, x) - \mathbb{E}_t[h(t, x)])^\top (k^2(t))^{-1} \times (dY_t - \mathbb{E}_t[h(t, x)] dt)$$

↑ ↑

Nonlinearity on p_t :

$$\mathbb{E}_t[h(t, x)] = \int_{\mathbb{R}_{D_x}} h(t, x) p(t, x | F_\tau^y) dx$$

This is a nonlinear stochastic partial integral differential equation!

$$p_t := p(t, x | F_\tau^y)$$

$$dX_t = f(t, X_t)dt + g(t, X_t)dB_t^x$$

$$Y_t = h(t, X_t) + \varepsilon$$

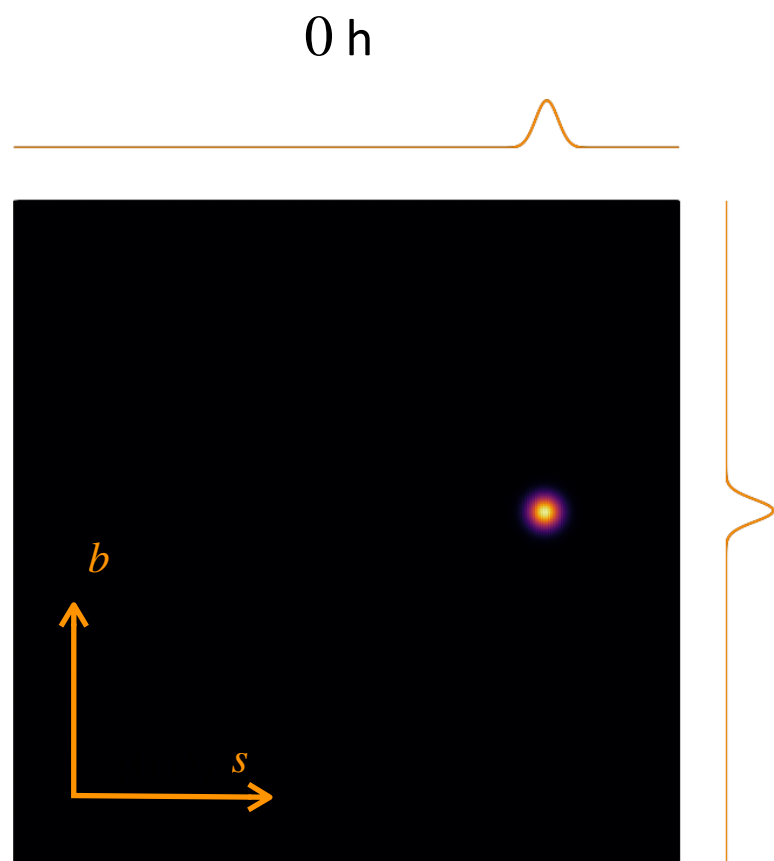


Figure 6: approximated solution to the Kushner-Stratonovich equation.

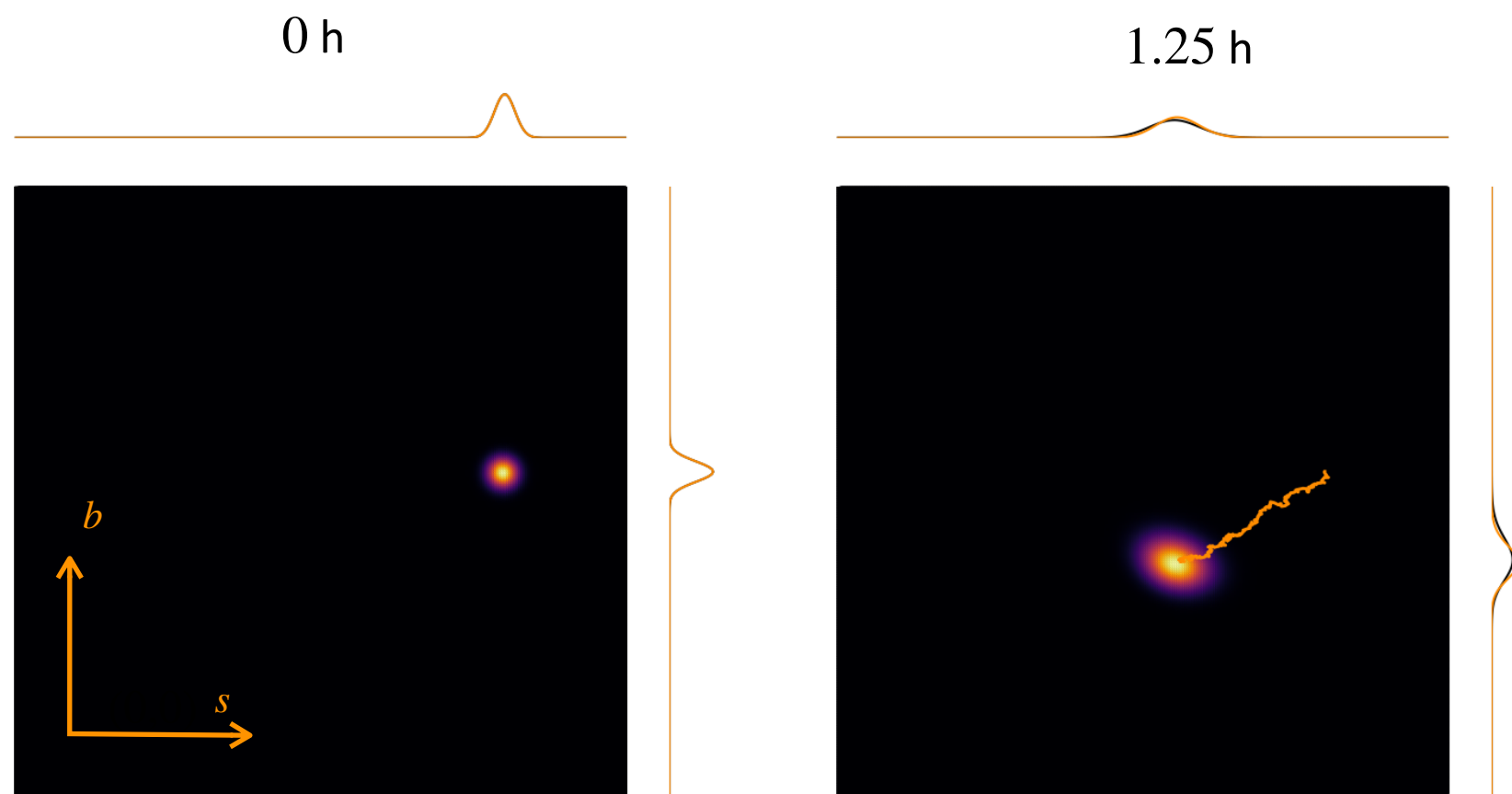


Figure 6: approximated solution to the Kushner-Stratonovich equation.

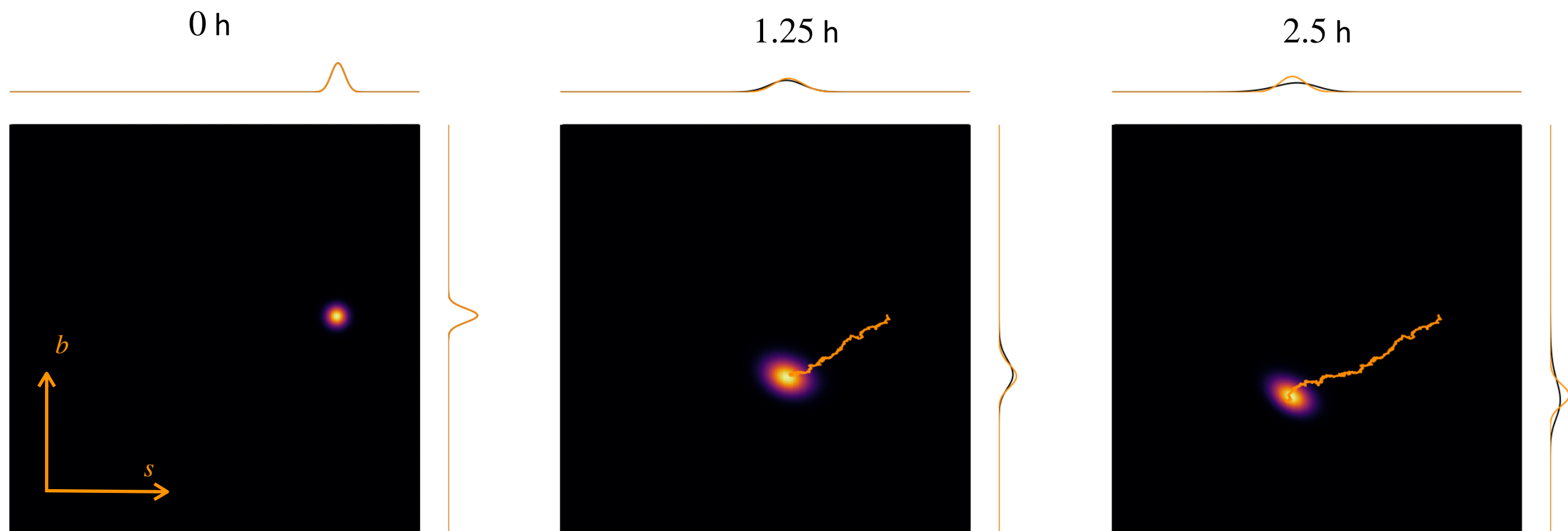


Figure 6: approximated solution to the Kushner-Stratonovich equation.

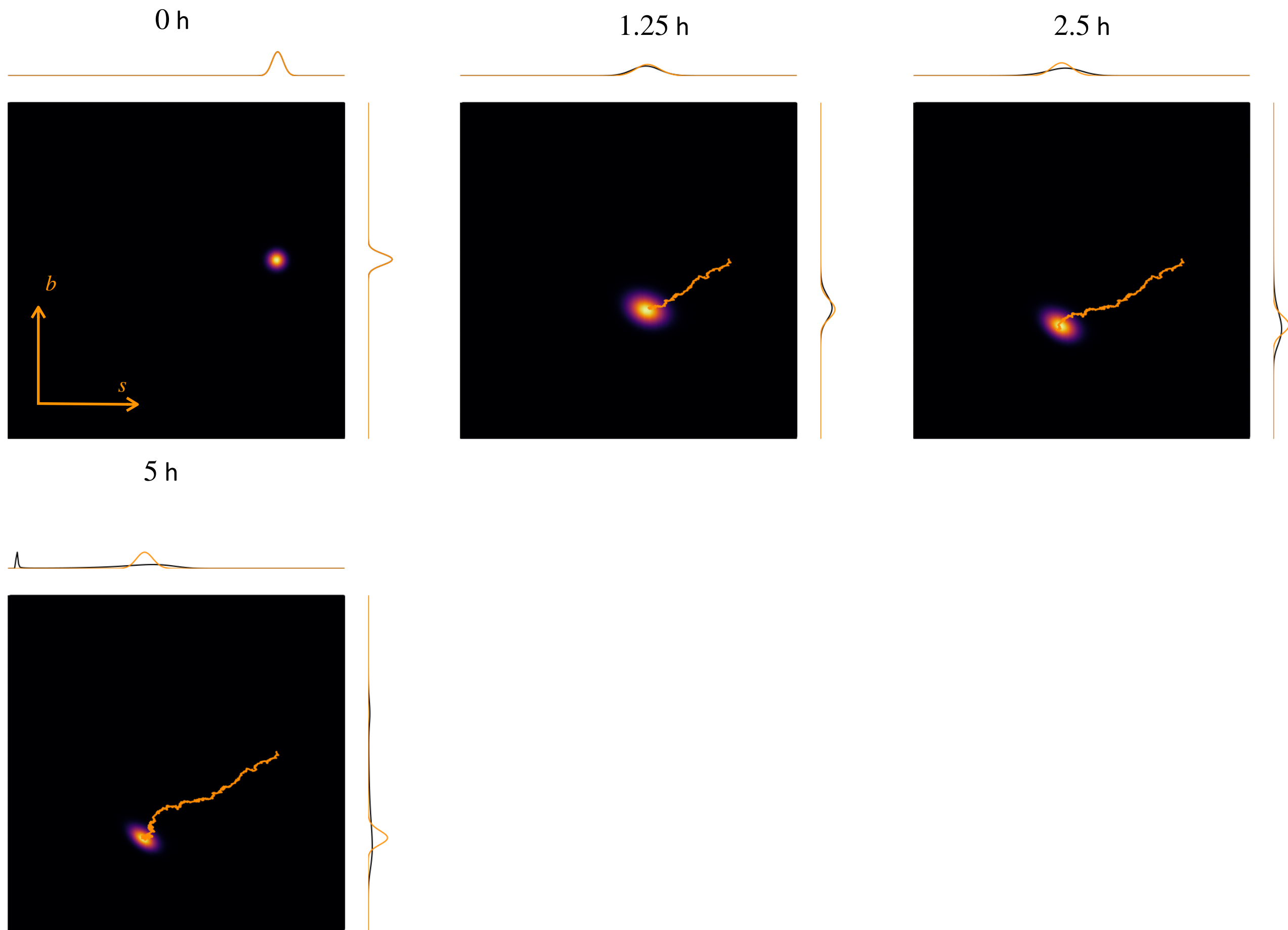


Figure 6: approximated solution to the Kushner-Stratonovich equation.

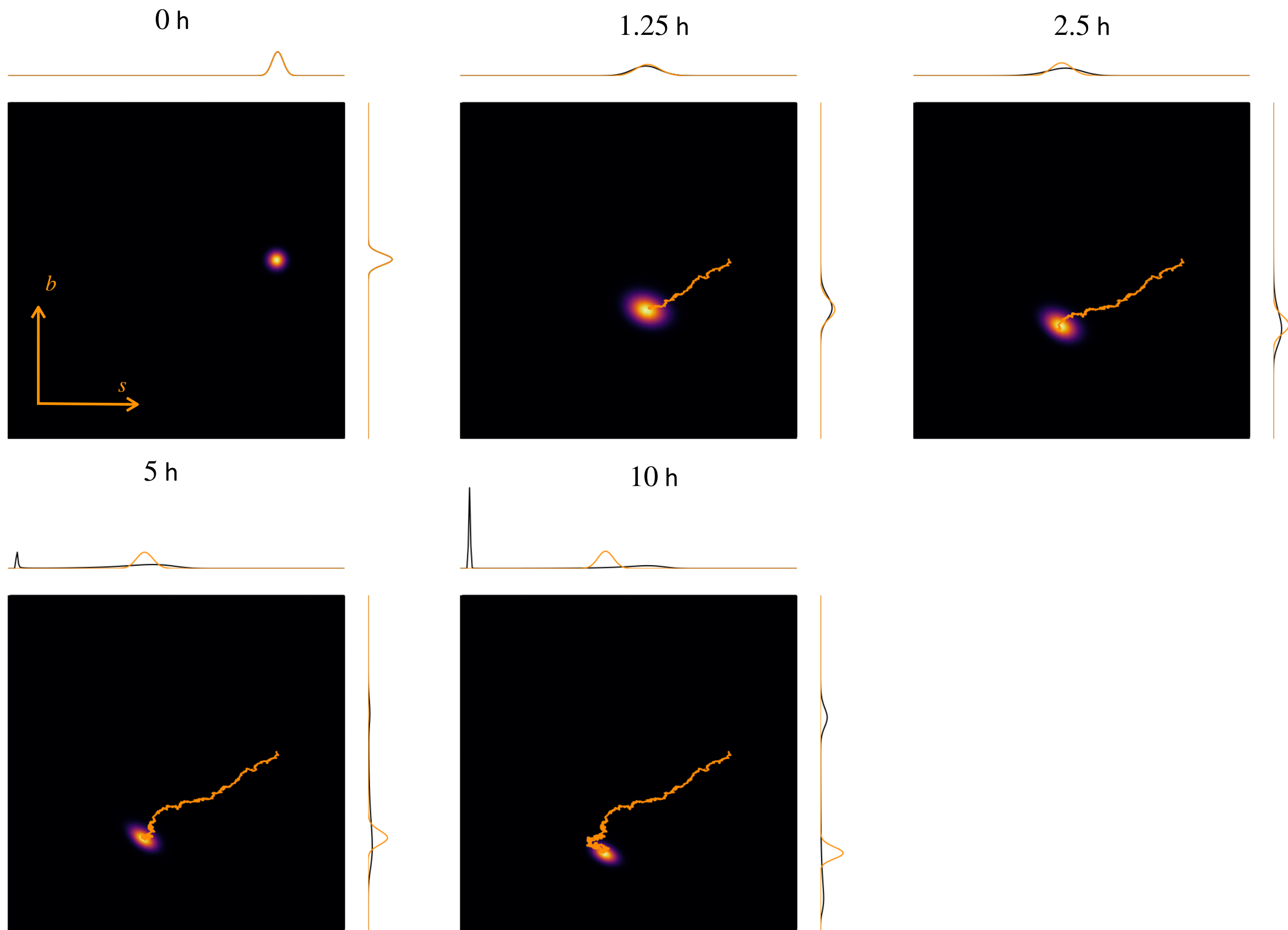


Figure 6: approximated solution to the Kushner-Stratonovich equation.

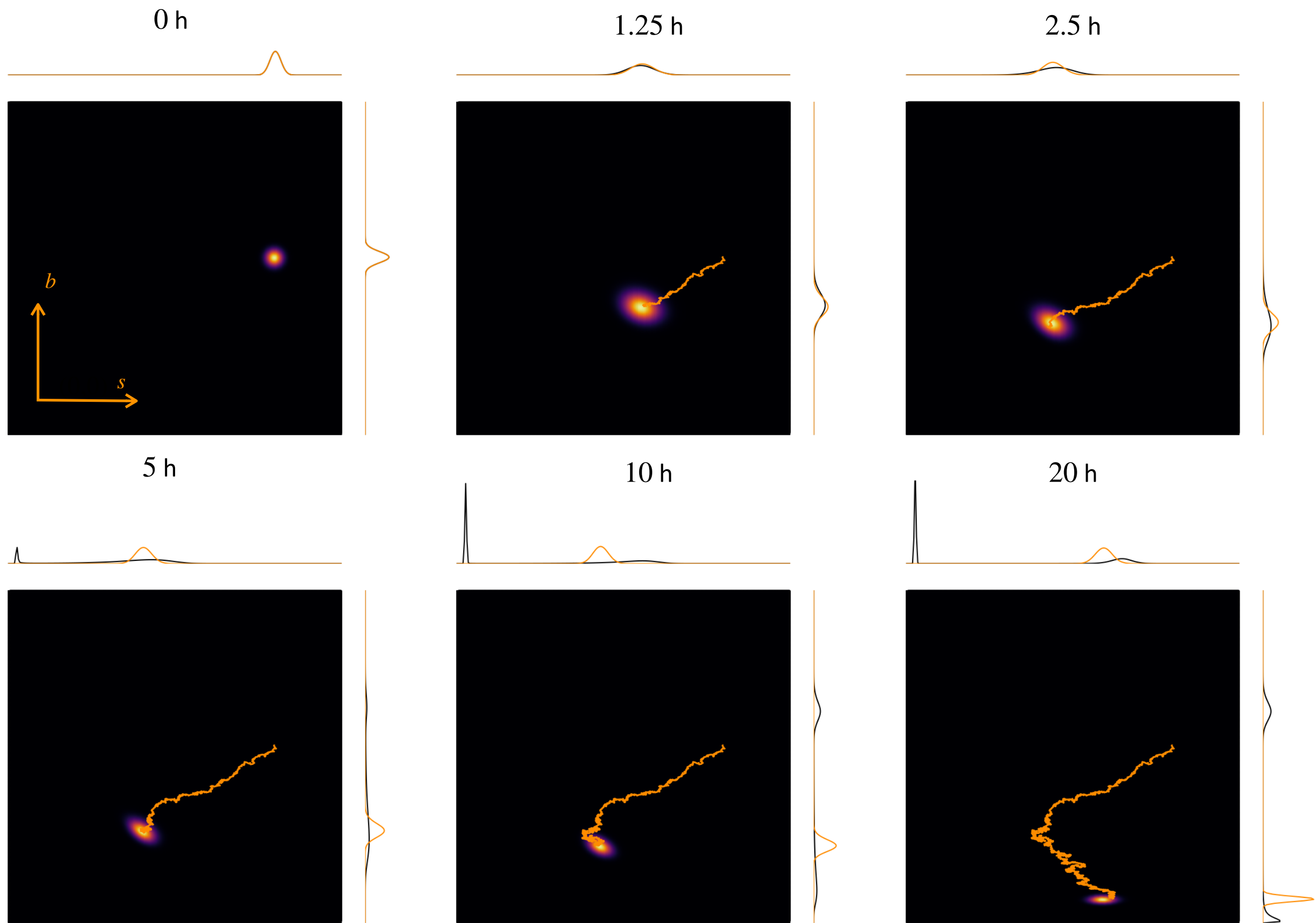


Figure 6: approximated solution to the Kushner-Stratonovich equation.

Summary

Stochastic model for the chemostat

Summary

Stochastic model for the chemostat



**Prior knowledge
(Fokker-Planck equation)**

Summary

Stochastic model for the chemostat



**Prior knowledge
(Fokker-Planck equation)**



Stochastic model for the measurements

Summary

Stochastic model for the chemostat



**Prior knowledge
(Fokker-Planck equation)**



Stochastic model for the measurements



**Refined knowledge
(Kushner-Stratonovich equation)**

Summary

Stochastic model for the chemostat



**Prior knowledge
(Fokker-Planck equation)**



Stochastic model for the measurements



**Refined knowledge
(Kushner-Stratonovich equation)**

Outlook

How to obtain a solution to the Kushner-Stratonovich equation?

- Methods for Partial Differential Equations (PDEs)
- Sequential Monte Carlo (SMC) methods

Summary

Stochastic model for the chemostat



**Prior knowledge
(Fokker-Planck equation)**



Stochastic model for the measurements



**Refined knowledge
(Kushner-Stratonovich equation)**

Outlook

How to obtain a solution to the Kushner-Stratonovich equation?

- Methods for Partial Differential Equations (PDEs)
- Sequential Monte Carlo (SMC) methods



Statistical properties of some SMC methods

Summary

Stochastic model for the chemostat



**Prior knowledge
(Fokker-Planck equation)**



Stochastic model for the measurements



**Refined knowledge
(Kushner-Stratonovich equation)**

Outlook

How to obtain a solution to the Kushner-Stratonovich equation?

- Methods for Partial Differential Equations (PDEs)
- Sequential Monte Carlo (SMC) methods



Statistical properties of some SMC methods

