#### 1. Goals and philosophy

#### Mechanics of Manipulation

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#### Conflowedges manipulation work?

- Kinematic manipulation
  - Kinematics
  - Kinematic representation
  - Applications to manipulation: Motion planning; kinematic models of contact.

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- Dynamic manipulation
  - Rigid body dynamics
  - Impact
  - Applications to manipulation: Quasidynamic parts orienting, juggling.

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Is it even possible to *not* ...? Perhaps an implicit model?

#### Why build model-based robots?

Maybe you should not.

For many tasks, you can build a robot based on your own knowledge of the mechanics of manipulation. Don't underestimate ad hoc engineering based on human intuition and experience.

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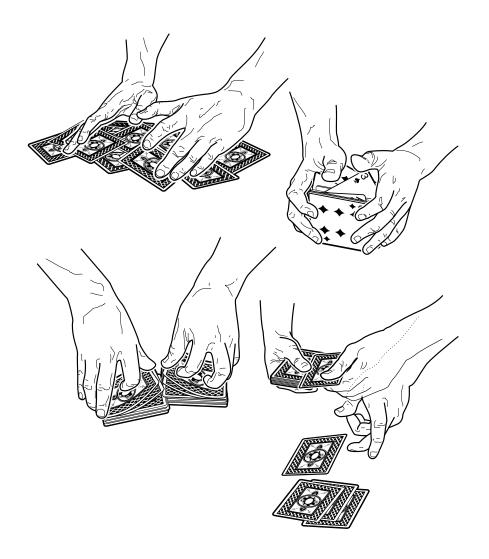
Sometimes scientists should . . .

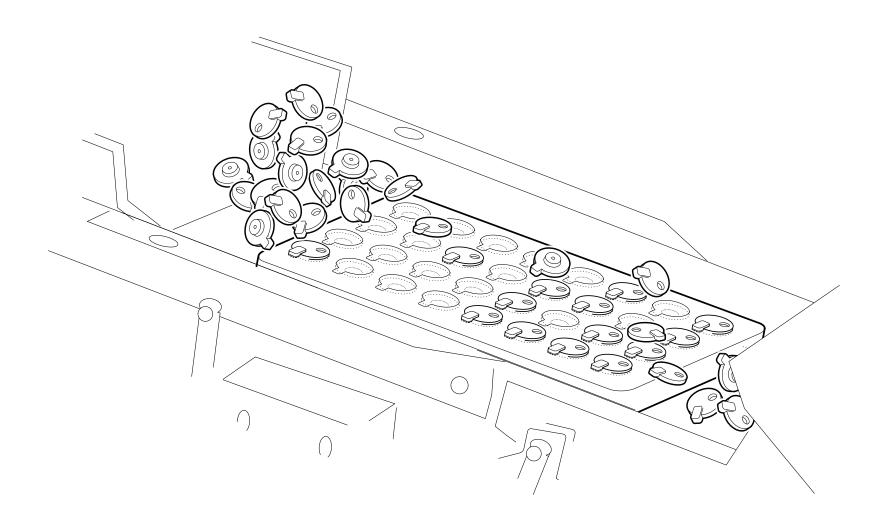
As a properly skeptical scientist, how do you show that some phenomenon is critical in a given task? That you have properly modeled that phenomenon?

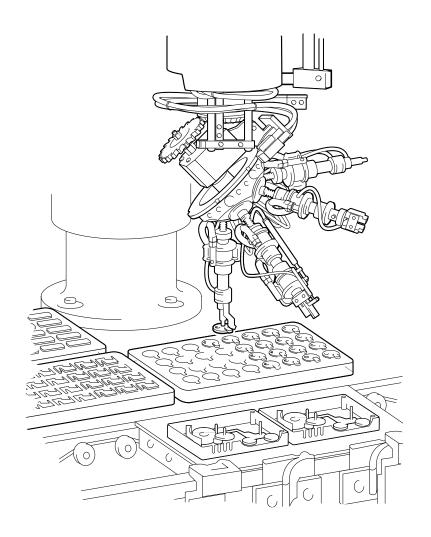
#### **Course organization**

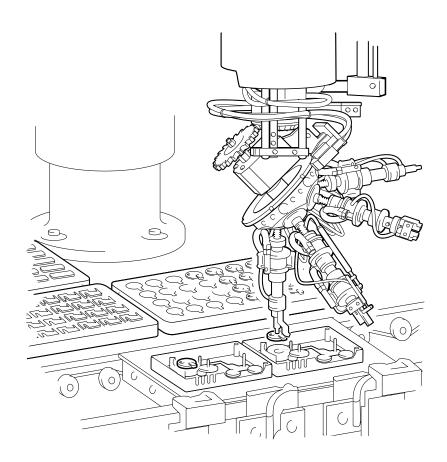
- Lectures: MW 1:30 2:50. Five minute break.
- Textbook: Mechanics of Robotic Manipulation, MIT Press, 2001.
- Conflict of interest: let's spend my royalties.
- Grading:
  - 1. Assignments. Probably just four or so.
  - 2. Term project. Spend 20-40 hours. Proposal. Report.
  - 3. Final.

### What is manipulation? First example: human.









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  - There's probably a lot more . . .

Hayes, K. C., and Hayes, C. Journal Comp. Physiol. Psychol. 45 450. 1952. Lecture 1.

#### What is manipulation? Example 4: Chimps.

It is a little daunting to discover—on the very technological grounds on which human superiority is often claimed—that after months of apprenticeship, human scientists cannot do as well as preadolescent chimps. Teleki remained generous and good-natured about his failure. In the acknowledgments at the end of the paper, among thanks to various organizations for financial and logistical support, there appears this sentence: "I am, in addition, more than grateful to the patient and tolerant Leakey, whose termite-collecting skills so out-stripped mine."

—http://www.mc.maricopa.edu/dept/d10/asb/primates/termiting.html