

LBumper: Substation Left [HOLD]

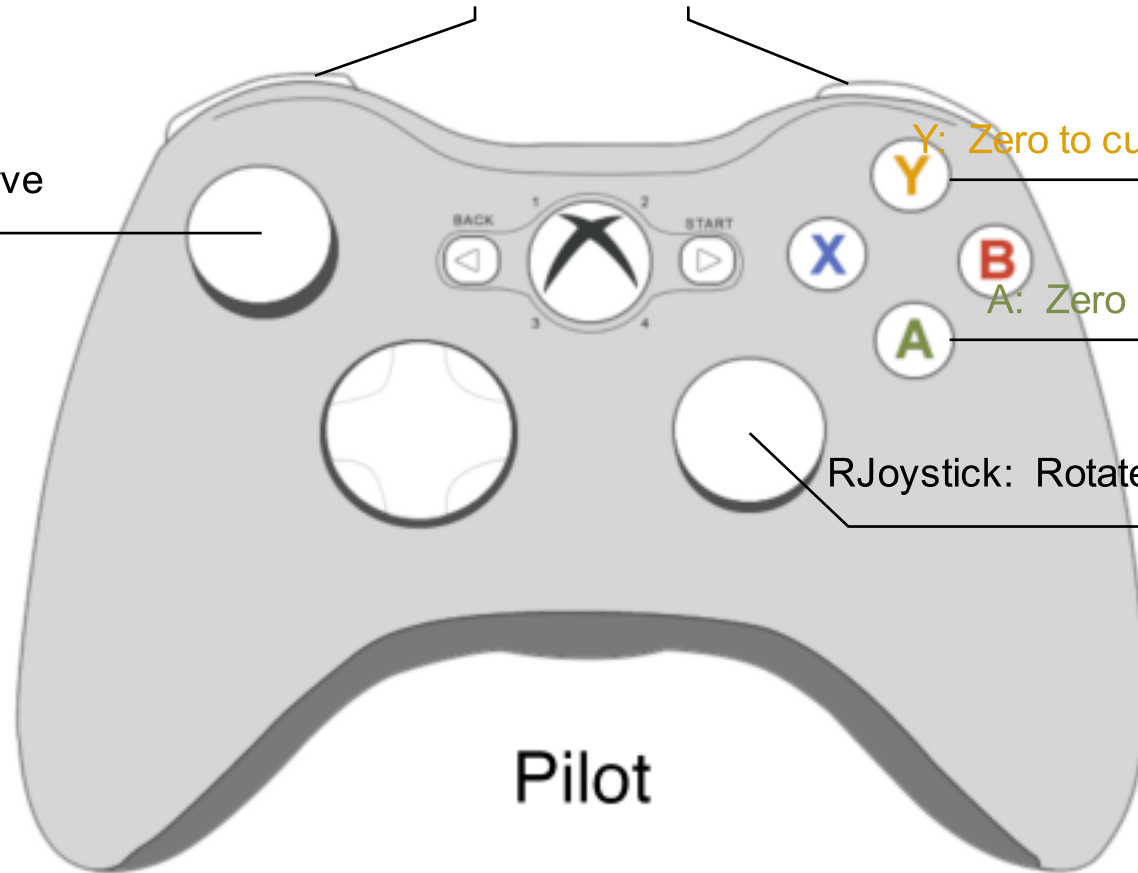
RBumper: Substation Right [HOLD]

Y: Zero to current Rotation [Press]

A: Zero Field Oriented [Press]

RJoystick: Rotate swerve [LEFTRIGHT]

LJoystick: Translate swerve



Pilot

RTrigger: Retract telescope [HOLD]

B: Run Outtake [HOLD]

A: Run Intake [PRESS]

LTrigger: Extend telescope [HOLD]

LJoystick: Adjust arm angle [UPDOWN]



Copilot