

LBumper: Autobalance Sideways [HOLD]

RBumper: Autobalance [HOLD]

LJoystick: Translate swerve

A: Zero field oriented [PRESS]

RJoystick: Rotate swerve [LEFTRIGHT]

Pilot

LBumper: Move to arm straight up [HOLD]

RBumper: Move to arm straight forward [HOLD]

LTrigger: Retract telescope [HOLD]

RTrigger: Extend telescope [HOLD]

LJoystick: Adjust arm angle [UPDOWN]

B: Run Outtake [HOLD]

A: Run Intake [PRESS]

Copilot