DD2434/FDD3434 Machine Learning, Advanced Course Module 2 Exercise Solutions

November 2022

1 Directed Graphical Models (DGM)

1.1 Bayes Ball

Question: List all variables that are independent of A given evidence on the shaded node for each of the DGMs a), b) and c) below.

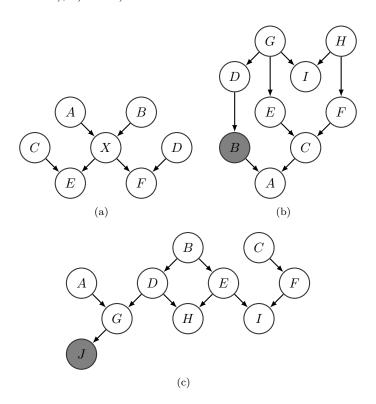


Figure 1: Some DGMs.

Solution: a) See Figure 2, b) See Figure 3, c) See Figure 4.

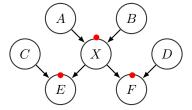


Figure 2: There is no conditioning on any node. Putting the blocks for d-separations, we see that B,C, and D are separated from A or independent of A.

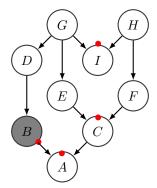


Figure 3: There is a path to A from all variables hence no variable is independent of A.

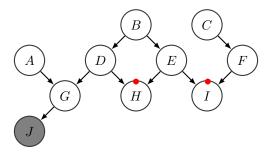


Figure 4: There is a path to A from all variables except F and C. Therefore, only C and F are independent of A.

1.2 PyClone DGM

Consider the graphical model shown in Figure 5. Answer "yes" or "no" to each question:

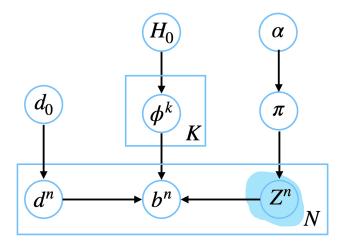


Figure 5: Graphical model of PyClone in plate notation

$$\pi \sim Dirichlet(\alpha)$$
 (1)

$$Z^n \sim Categorical(\pi)$$
 (2)

$$\phi^k \sim H_0 = Beta(a_0, a_1) \tag{3}$$

$$d^n \sim Poisson(d_0) \tag{4}$$

$$b^n \sim Bin(d^n, \phi^{Z^n}) \tag{5}$$

- $b^n \perp b^{n+1} \mid d^n, d^{n+1}$? no because phi
- $d^n \bot Z^n \mid \alpha, H_0$? yes bn not given and not descends
- $d^n \perp Z^n \mid b^n$? no bn given
- $\phi^k \bot d^n \mid d_0, \pi$? yes each all bn not given and not descendants
- $b^{1:N} \perp \pi \mid Z^{1:N}$?

Solution:

- No
- Yes
- No
- Yes
- Yes

1.3 Bayes nets for a rainy day (Exercise 10.5 from Murphy [1])

Question: (Source: Nando de Freitas) In this question you must model a problem with 4 binary variables: G = "gray", V = "Vancouver", R = "rain" and S = "sad". Consider the directed graphical model describing the relationship between these variables shown in Figure 6 (and the probability tables shown in Table 1).

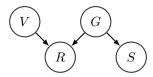


Figure 6: Bayesian net for a rainy day

Table 1: Probability tables of Bayes net for a rainy day

V = 0	V = 1
δ	$1-\delta$

G = 0	G = 1
α	$1 - \alpha$

	S = 0	S = 1
G = 0	γ	$1 - \gamma$
G = 1	β	$1 - \beta$

	R = 0	R = 1
VG = 00	0.6	0.4
VG = 01	0.3	0.7
VG = 10	0.2	0.8
VG = 11	0.1	0.9

- a. Write down an expression for P(S = 1|V = 1) in terms of $\alpha, \beta, \gamma, \delta$.
- b. Write down an expression for P(S = 1|V = 0). Is this the same or different to P(S = 1|V = 1)? Explain why.
- c. Find maximum likelihood estimates of α, β, γ using the following data set, where each row is a training case. (You may state your answers without proof.)

V	G	R	S
1	1	1	1
1	1	0	1
1	0	0	0

Solution: (The solution is taken from Elin Samuelsson's notes from December 2018 and modified slightly.)

a. Write down an expression for P(S = 1|V = 1) in terms of $\alpha, \beta, \gamma, \delta$.

$$P(S = 1|V = 1) = \frac{P(S = 1, V = 1)}{P(V = 1)}$$

$$= \frac{1}{P(V = 1)} \sum_{g=0}^{1} \sum_{r=0}^{1} P(S = 1, V = 1, R = r, G = g)$$

$$= \frac{1}{P(V = 1)} \sum_{g=0}^{1} \sum_{r=0}^{1} P(S = 1, V = 1, R = r|G = g)P(G = g)$$

$$\{G \text{ is tail-to-tail and blocks the path } \rightarrow S \perp \{R, V\}|G\}$$

$$= \frac{1}{P(V = 1)} \sum_{g=0}^{1} P(S = 1|G = g)P(G = g) \sum_{r=0}^{1} P(V = 1, R = r|G = g)$$

$$= \frac{1}{P(V = 1)} \sum_{g=0}^{1} P(S = 1|G = g)P(G = g) \sum_{r=0}^{1} P(R = r|V = 1, G = g)P(V = 1)$$

$$= \frac{P(V = 1)}{P(V = 1)} \sum_{g=0}^{1} P(S = 1|G = g)P(G = g) \sum_{r=0}^{1} P(R = r|V = 1, G = g)$$

$$= \sum_{g=0}^{1} P(S = 1|G = g)P(G = g) \sum_{r=0}^{1} P(R = r|V = 1, G = g)$$

$$\{\sum_{r=0}^{1} P(R = r|V = 1, G = g) = 1, \text{ regardless of the value of } G \text{ and } V\}$$

$$= \sum_{g=0}^{1} P(S = 1|G = g)P(G = g)$$

$$= P(S = 1|G = 0)P(G = 0) + P(S = 1|G = 1)P(G = 1)$$

$$= \alpha(1 - \gamma) + (1 - \alpha)(1 - \beta)$$

$$= 1 - \beta + \alpha\beta - \alpha\gamma$$
(6)

b. Write down an expression for P(S = 1|V = 0). Is this the same or different to P(S = 1|V = 1)? Explain why.

$$P(S = 1|V = 0) = \sum_{g=0}^{1} P(S = 1|G = g)P(G = g) \sum_{r=0}^{1} P(R = r|V = 0, G = g)$$

$$= \sum_{g=0}^{1} P(S = 1|G = g)P(G = g)$$

$$= P(S = 1|V = 1)$$
(7)

since $\sum_{r=0}^{1} P(R = r | V = v, G = g) = 1$, regardless of the value of G and V.

c. Find maximum likelihood estimates of α, β, γ using the following data set, where each row is a training case. (You may state your answers without proof.)

$$\begin{array}{c|cccc} V & G & R & S \\ \hline 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ \end{array}$$

Notation:

$$\mathbf{1}(a=b) = \begin{cases} 1, & \text{if } a=b\\ 0, & \text{if } a\neq b \end{cases}$$
 (8)

Maximum likelihood estimates:

$$\hat{\alpha} = P(G = 0) = \frac{\sum_{n=1}^{N} \mathbf{1}(G_n = 0)}{N} = \frac{1}{3}$$
(9)

$$\hat{\beta} = P(S = 0|G = 1) = \frac{P(S = 0, G = 1)}{P(G = 1)} = \frac{\sum_{n=1}^{N} \mathbf{1}(S_n = 0, G_n = 1)}{\sum_{n=1}^{N} \mathbf{1}(G_n = 1)} = \frac{0}{2}$$
(10)

$$\hat{\gamma} = P(S = 0|G = 0) = \frac{P(S = 0, G = 0)}{P(G = 0)} = \frac{\sum_{n=1}^{N} \mathbf{1}(S_n = 0, G_n = 0)}{\sum_{n=1}^{N} \mathbf{1}(G_n = 0)} = \frac{1}{1}$$
(11)

An Alternative Solution

The more general way to find the MLE is i) write the likelihood (or log-likelihood) ii) take derivative w.r.t the parameter of interest and set it to zero iii) check whether the value actually maximizes the likelihood (by looking at the second derivative [2] is negative or not).

The likelihood of the data is:

$$\mathcal{L} = P(D|\Theta)
= P(D_1, ..., D_N|\Theta)
= \prod_{n=1}^{N} P(D_n|\Theta)
= \prod_{n=1}^{N} P(V_n|\delta) P(G_n|\alpha) P(S_n|G_n, \beta, \gamma) P(R_n|V_n, G_n)
= P(V_n = 1|\delta)^3 P(G_n = 0|\alpha) P(G_n = 1|\alpha)^2 P(S_n = 0|G_n = 0, \beta, \gamma) P(S_n = 1|G_n = 1, \beta, \gamma)^2
P(R_n = 0|V_n = 1, G_n = 0) P(R_n = 0|V_n = 1, G_n = 1) P(R_n = 1|V_n = 1, G_n = 1)
= (1 - \delta)^3 \alpha (1 - \alpha)^2 \gamma (1 - \beta)^2 \times 0.2 \times 0.1 \times 0.9
\propto (1 - \delta)^3 \alpha (1 - \alpha)^2 \gamma (1 - \beta)^2$$
(12)

Let's look at the likelihood (see Figure 7). For the first subplot, I fixed $\alpha, \gamma, \beta \in (0, 1)$ and ranged $\delta \in [0, 1]$. The subplot shows how the likelihood changes w.r.t δ . I repeated the same method for the rest of the parameters. From the figure, we can clearly see which values of the parameters maximize the likelihood ($\hat{\delta} = 0, \hat{\alpha} = 0.3\bar{3}, \hat{\gamma} = 1, \hat{\beta} = 0$).

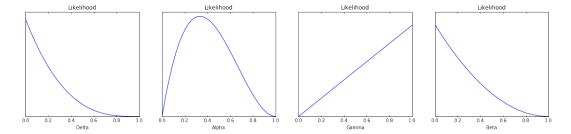


Figure 7: Likelihood of rainy day example with varying parameters

Now, let's show these with the derivatives. First, consider α . Take the first derivative of the likelihood w.r.t α .

$$\frac{\partial}{\partial \alpha} \mathcal{L} = \frac{\partial}{\partial \alpha} \alpha (1 - \alpha)^2 C
= (1 - \alpha)^2 C - 2\alpha (1 - \alpha) C
= (1 - \alpha) (1 - \alpha - 2\alpha) C
= (1 - \alpha) (1 - 3\alpha) C
= 0$$

$$\alpha = 1 \text{ or } \alpha = \frac{1}{3}$$
(13)

where C is a temporary variable that I used to represent all the other terms in the likelihood beside the parameter of interest (notice that C is non-negative). There are two α values which either maximize or minimize the likelihood. We need to check the second derivative of the likelihood w.r.t α :

$$\frac{\partial^2}{\partial \alpha^2} \mathcal{L} = \frac{\partial}{\partial \alpha} \alpha (1 - \alpha)^2 C$$

$$= -(1 - 3\alpha)C - 3(1 - \alpha)C$$

$$= (-4 + 6\alpha)C$$
(14)

When $\alpha=1$, the second derivative becomes 2C, which is non-negative, which means $\alpha=1$ is not a maximizer of the likelihood. When $\alpha=\frac{1}{3}$, the second derivative becomes -2C, which is negative, which means $\hat{\alpha}=\frac{1}{3}$ is the maximum likelihood estimator. We can confirm this result with Figure 7.

Now, we move on to β . We re-write the likelihood as $\mathcal{L} = (1 - \beta)^2 C$. It is clear that the $\hat{\beta}$ which maximizes the likelihood must be $\hat{\beta} = 0$ (since C is non-negative and \mathcal{L} gets the highest value, which is 1C, when $\beta = 0$). Let's look at take the derivatives.

$$\frac{\partial}{\partial \beta} \mathcal{L} = \frac{\partial}{\partial \alpha} (1 - \beta)^2 C$$

$$= -2(1 - \beta)C$$

$$= 0$$

$$\beta = 1$$
(15)

Now, check the second derivative:

$$\frac{\partial^2}{\partial \beta^2} \mathcal{L} = \frac{\partial}{\partial \alpha} (1 - \beta)^2 C$$

$$= 2C$$

$$> 0$$
(16)

Since the second derivative is always non-negative, $\beta=1$ is the minimizer of the likelihood. Notice that we were unable to find the β which maximizes the likelihood with this approach. Why? In our data D, we don't have any samples where S=0 and G=1. Finally, let's re-write the likelihood in terms of γ ; $\mathcal{L}=\gamma C$. It is clear that the $\hat{\gamma}$ which maximizes the likelihood must be $\hat{\gamma}=1$ (because the likelihood is a linearly increasing function of γ).

2 Hidden Markov Models (HMM)

2.1 Forward-Backward Algorithm for Posteriors

Derive forward-backward algorithm for:

- (a) the marginal posterior distribution of one hidden variable, i.e, $p(z_n|x_{1:N})$
- (b) the joint posterior distribution of two hidden variables, i.e, $p(z_{n-1}, z_n | x_{1:N})$
- (c) the posterior predictive distribution, i.e, $p(x_{N+1}|x_{1:N})$

Solutions:

(a) For learning and inference in HMMs (e.g. EM), we need to calculate marginal distribution of the hidden variables, such as $p(z_n|x_{1:N},\theta)$. So we assume to know the model parameters and we have observed the data. For readability, we write $p(z_n|x_{1:N})$. We could calculate this by performing marginalization over all the hidden variables, but, that is costly (we would have to calculate N nested sum with each iterating over J possible values of the hidden variable i.e. $O(J^N)$). Instead we use an approach which takes $O(NJ^2)$ number of calculations. We write the probability as $\frac{p(x_{1:N}|z_n)p(z_n)}{p(x_{1:N})}$ due to Bayes, and then, because of conditional independence, we can write $p(x_{1:N}|z_n)$ as $p(x_{1:n}|z_n)p(x_{n+1:N}|z_n)$. We have now split the problem into two problems which are solved by recursion (this whole process is referred to as dynamic programming). We can rewrite the problem, finally, as: $\frac{p(x_{1:n},z_n)p(x_{n+1:N}|z_n)}{p(x_{1:N})}$ or $\frac{\alpha(z_n)\beta(z_n)}{\sum_{z_N}\alpha(z_N)}$. We calculate the probabilities $\alpha(z_n)$ and $\beta(z_n)$, forward and backward, as follows:

Forward pass

$$\begin{split} \alpha(z_n) &= p(x_{1:n}, z_n) = p(x_{1:n}|z_n)p(z_n) = p(x_n|z_n)p(x_{1:n-1}|z_n)p(z_n) \\ &= p(x_n|z_n)p(x_{1:n-1}, z_n) \\ &= p(x_n|z_n) \sum_{z_{n-1}} p(x_{1:n-1}, z_n, z_{n-1}) \\ &= p(x_n|z_n) \sum_{z_{n-1}} p(x_{1:n-1}, z_n|z_{n-1})p(z_{n-1}) \\ &= p(x_n|z_n) \sum_{z_{n-1}} p(x_{1:n-1}|z_{n-1})p(z_{n-1})p(z_n|z_{n-1}) \\ &= p(x_n|z_n) \sum_{z_{n-1}} p(x_{1:n-1}|z_{n-1})p(z_n|z_{n-1}) = p(x_n|z_n) \sum_{z_{n-1}} \alpha(z_{n-1})p(z_n|z_{n-1}) \\ &, where \quad \alpha(z_1) = p(x_1|z_1)p(z_1) \end{split}$$

Note that we have $\alpha(z_1)$ from the initializations (we initialize the initial and emission probabilities, thus we have $\alpha(z_1)$).

Backward pass

$$\beta(z_n) = p(x_{n+1:N}|z_n)$$

$$= \sum_{z_{n+1}} p(x_{n+1:N}, z_{n+1}|z_n)$$

$$= \sum_{z_{n+1}} p(x_{n+1:N}|z_{n+1}, z_n)p(z_{n+1}|z_n)$$

$$= \sum_{z_{n+1}} p(x_{n+1:N}|z_{n+1})p(z_{n+1}|z_n)$$

$$= \sum_{z_{n+1}} p(x_{n+1}|z_{n+1})p(x_{n+2:N}|z_{n+1})p(z_{n+1}|z_n)$$

$$= \sum_{z_{n+1}} p(x_{n+1}|z_{n+1})\beta(z_{n+1})p(z_{n+1}|z_n)$$

$$, where \qquad \beta(z_N) = 1$$

(b)

$$\begin{split} p(z_{n-1}, z_n | x_{1:N}) &= \frac{p(x_{1:N} | z_{n-1}, z_n) p(z_{n-1}, z_n)}{p(x_{1:N})} \\ &= \frac{p(x_{1:n-1} | z_{n-1}) p(x_n | z_n) p(x_{n+1:N} | z_n) p(z_n | z_{n-1}) p(z_{n-1}))}{p(x_{1:N})} \\ &= \frac{\alpha(z_{n-1}) p(x_n | z_n) p(z_n | z_{n-1}) \beta(z_n)}{\sum_{z_n} \alpha(z_n) \beta(z_n)} \end{split}$$

(c)

$$p(x_{N+1}|x_{1:N}) = \sum_{z_{N+1}} p(x_{N+1}, z_{N+1}|x_{1:N})$$

$$= \sum_{z_{N+1}} p(x_{N+1}|z_{N+1}) P(z_{N+1}|x_{1:N})$$

$$= \sum_{z_{N+1}} p(x_{N+1}|z_{N+1}) \sum_{z_{N}} P(z_{N+1}, z_{N}|x_{1:N})$$

$$= \sum_{z_{N+1}} p(x_{N+1}|z_{N+1}) \sum_{z_{N}} P(z_{N+1}|z_{N}) p(z_{N}|x_{1:N})$$

$$= \sum_{z_{N+1}} p(x_{N+1}|z_{N+1}) \sum_{z_{N}} P(z_{N+1}|z_{N}) \frac{p(z_{N}, x_{1}:N)}{p(x_{1:N})}$$

$$= \frac{1}{p(x_{1:N})} \sum_{z_{N+1}} p(x_{N+1}|z_{N+1}) \sum_{z_{N}} P(z_{N+1}|z_{N}) \alpha(z_{N})$$

References

- [1] Kevin P Murphy. Machine learning: a probabilistic perspective. MIT press, 2012.
- [2] E Weisstein. Second derivative test. From MathWorld-A Wolfram Web Resource. 2004.