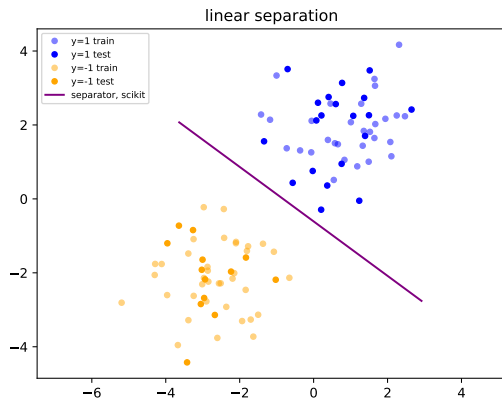


Fondamentaux théoriques du machine learning



Support vector machines

Support vector machines

- Linear separation

- Optimization problem

- Link with empirical risk minimization

Support vector machines

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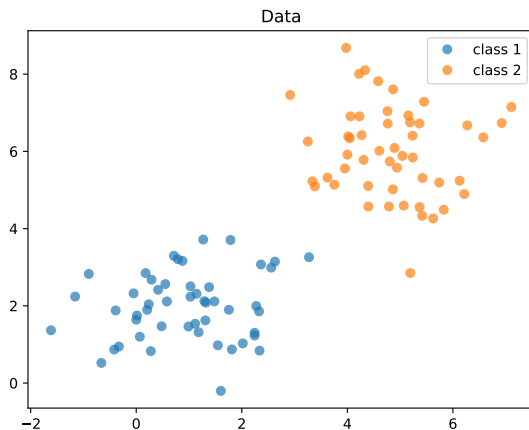


Figure – Linearly separable data

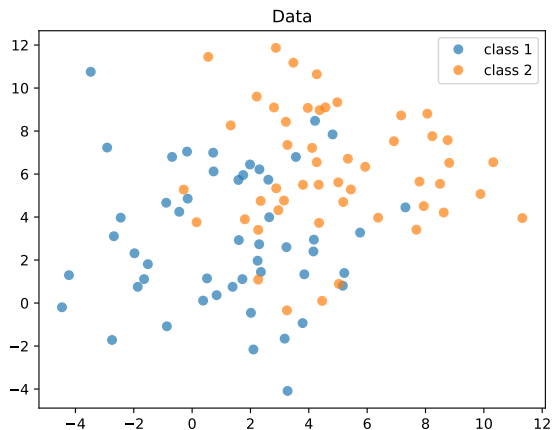


Figure – Non linearly-separable data

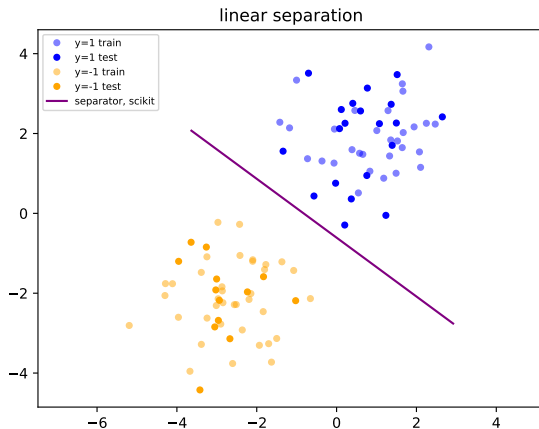


Figure – Linear separator

Linear separator

► $\mathcal{X} = \mathbb{R}^d$

► $\mathcal{Y} = \{-1, 1\}$

Equation of a linear separator

$$\langle w, x \rangle + b = 0 \quad (1)$$

► $w \in \mathbb{R}^d$

► $x \in \mathbb{R}^d$

► $b \in \mathbb{R}$

Notation :

$$h_{w,b}(x) = \langle w, x \rangle + b \quad (2)$$

Affine subspace

$$H = \{x \in \mathbb{R}^d, \langle w, x \rangle + b = 0\} \quad (3)$$

is an affine subspace.

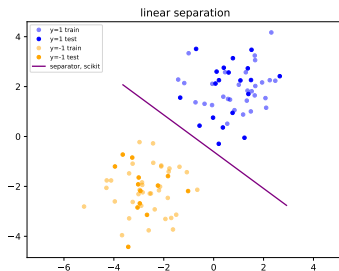
Any vector $x \in \mathbb{R}^d$ can uniquely be decomposed as

$$x = \lambda_w^x \frac{w}{\|w\|} + x_{w^\perp} \quad (4)$$

with $x_{w^\perp} \in \text{vect}(w)^\perp$. $x \in H$ if and only if

$$\begin{aligned} & \langle w, x \rangle + b = 0 \\ \Leftrightarrow & \langle w, \lambda_w^x \frac{w}{\|w\|} + x_{w^\perp} \rangle + b = 0 \\ \Leftrightarrow & \langle w, \lambda_w^x \frac{w}{\|w\|} \rangle + b = 0 \\ \Leftrightarrow & \lambda_w^x \|w\| + b = 0 \\ \Leftrightarrow & \lambda_w^x = \frac{-b}{\|w\|} \end{aligned} \quad (5)$$

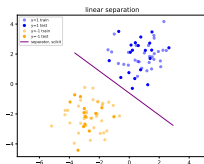
We first consider a linearly separable situation.



We recall the definition $h_{w,b}(x) = \langle w, x \rangle + b$. We look for separators that satisfy :

- ▶ $\forall x_i$ such that $y_i = 1$, $h_{w,b}(x) \geq 0$
- ▶ $\forall x_i$ such that $y_i = -1$, $h_{w,b}(x) \leq 0$

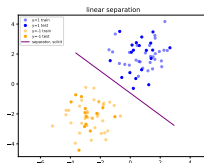
We first consider a linearly separable situation.



We note $h_{w,b}(x) = \langle w, x \rangle + b$. We look for separators that satisfy :

- ▶ $\forall x_i$ such that $y_i = 1$, $h_{w,b}(x) \geq 0$
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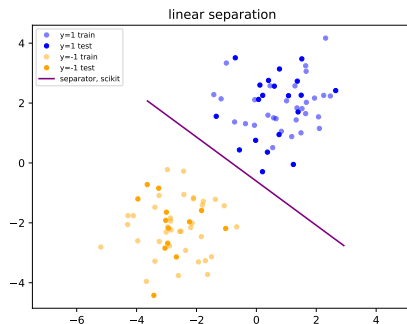
However, there exists an infinite number of such parameters. How could we choose the best one ?



- ▶ $\forall x_i$ such that $y_i = 1$, $h_{w,b}(x) \geq 0$
- ▶ $\forall x_i$ such that $y_i = -1$, $h_{w,b}(x) \leq 0$

The **margin** is the distance from H to the dataset. We look for the separator with the largest margin, leading to **Support vector classification (SVC)**.

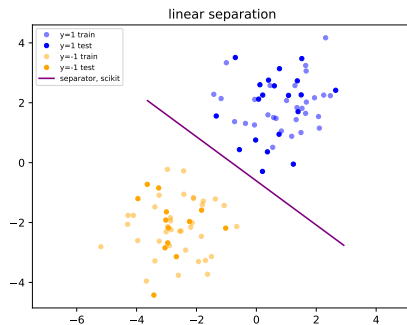
Margin



Let x be a point such that $h_{w,b}(x) = \langle w, x \rangle + b = c$, with $c \in \mathbb{R}$.

Exercise 1: Compute the distance from x to H .

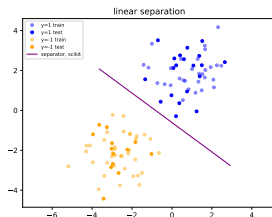
Margin



Let x be a point such that $h_{w,b}(x) = \langle w, x \rangle + b = c$, with $c \in \mathbb{R}$.

The distance is $\frac{|c|}{\|w\|}$.

Support vectors

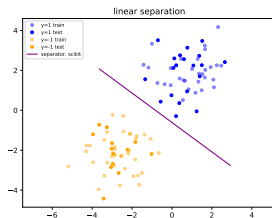


The **support vectors** are the vectors such that $|h_{w,b}(x)|$ is minimal among the dataset.

- ▶ the margin M is the distance from H to these vectors.
- ▶ if H is the optimal separator, there has to be a vector x_- and x_+ on each side, such that

$$M = d(x_-, H) = d(x_+, H) \quad (6)$$

Support vectors



Exercise 2: Show that if H is optimal, then

$$M = d(x_-, H) = d(x_+, H) \quad (7)$$

Rescaling

Important remark : multiplying w and b by a constant $\lambda \neq 0$ does not change H , as :

$$\begin{aligned}\langle \lambda w, x \rangle + \lambda b &= 0 \\ \Leftrightarrow \lambda(\langle w, x \rangle + b) &= 0 \\ \Leftrightarrow \langle w, x \rangle + b &= 0\end{aligned}\tag{8}$$

Rescaling

Important remark : multiplying w and b by a constant $\lambda \neq 0$ does not change H .

If the support vector x is such that $h_{w,b}(x) = c$, we have seen that the margin is

$$\frac{|c|}{\|w\|} \tag{9}$$

When looking for the optimal H , we can impose, without loss of generality, that $|c| = 1$.

This means that we look for w with minimal norm, such that H separates the data (since the margin is $\frac{1}{\|w\|}$).

Optimization problem

We can now formulate the optimization problem.

$$\arg \min_{w,b} \frac{1}{2} \langle w, w \rangle \quad (10)$$

subject to :

$$\forall i \in [1, n], y_i(\langle w, x_i \rangle + b) \geq 1 \quad (11)$$

Slack variables

When the dataset is not linearly separable, the approach is to authorize some of the samples to have a margin smaller than 1. This means relaxing the constraint, from

$$y_i(\langle w, x_i \rangle + b) \geq 1 \quad (12)$$

to

$$y_i(\langle w, x_i \rangle + b) \geq 1 - \xi_i \quad (13)$$

The ξ are called the *slack variables*, they are ≥ 0 . The smaller the slack variables, the better.

Optimization problem

In the general case, the optimization problem is :

$$\arg \min_{w, b, \xi} \frac{1}{2} \langle w, w \rangle + C \sum_{i=1}^n \xi_i \quad (14)$$

subject to :

$$\forall i \in [1, n], y_i(\langle w, x_i \rangle + b) \geq 1 - \xi_i \quad (15)$$

and

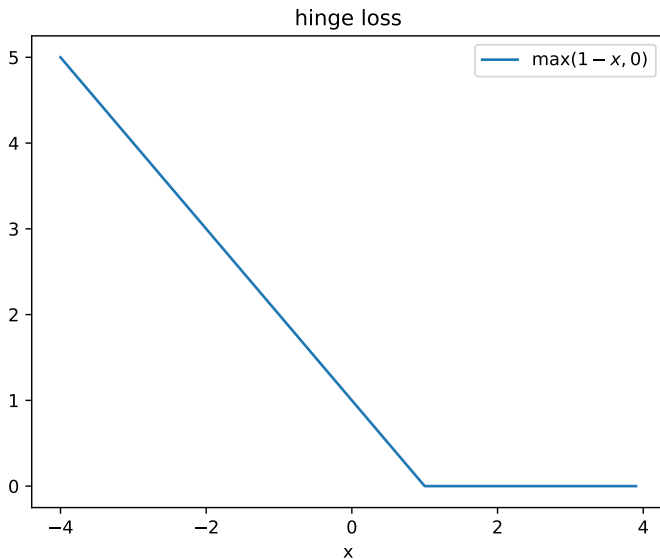
$$\forall i \in [1, n], \xi_i \geq 0 \quad (16)$$

- └ Support vector machines
 - └ Link with empirical risk minimization

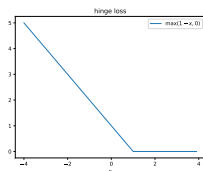
Margin vs ERM

The margin maximisation seems to differ from empirical risk minimization (ERM), which we have studied earlier. However, with a specific loss function, we can show that margin maximisation is in fact an ERM.

- └ Support vector machines
 - └ Link with empirical risk minimization



- └ Support vector machines
- └ Link with empirical risk minimization



- ▶ estimation : $h(x) = \langle w, x \rangle + b$
- ▶ label : $y \in \{-1, 1\}$

Hinge loss :

$$L_{\text{hinge}}(h(x), y) = \max(0, 1 - yh(x)) \quad (17)$$

The hinge loss can be seen as an approximation of the binary loss.

Problem reformulation

We recall the constraints on ξ

$$y_i(\langle w, x_i \rangle + b) \geq 1 - \xi_i \quad (18)$$

and

$$\xi_i \geq 0 \quad (19)$$

Equivalently,

$$\xi_i \geq \max(0, 1 - y_i(\langle w, x_i \rangle + b)) \quad (20)$$

Problem reformulation

The slack variables should be minimal. Hence, we can write that for the optimal solution, the inequality is in fact an equality ;

$$\xi_i = \max(0, 1 - y_i(\langle w, x_i \rangle + b)) \quad (21)$$

Problem reformulation

Finally, we can rewrite the problem as

$$\arg \min_{w,b} \frac{1}{2} \langle w, w \rangle + C \sum_{i=1}^n \max(0, 1 - y_i(\langle w, x_i \rangle + b)) \quad (22)$$

or equivalently

$$\arg \min_{w,b} \frac{1}{2} \langle w, w \rangle + C \sum_{i=1}^n L_{\text{hinge}}(h(x_i), y_i) \quad (23)$$

Which is an ERM problem with a $L2$ regularization.