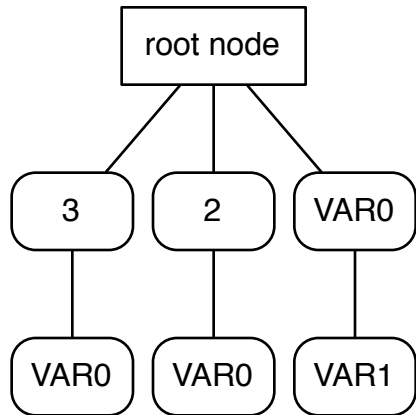


Subgoal Trie: path/2



subgoal frame
path(V0, V1)

Answer Trie: path(V0, V1)

