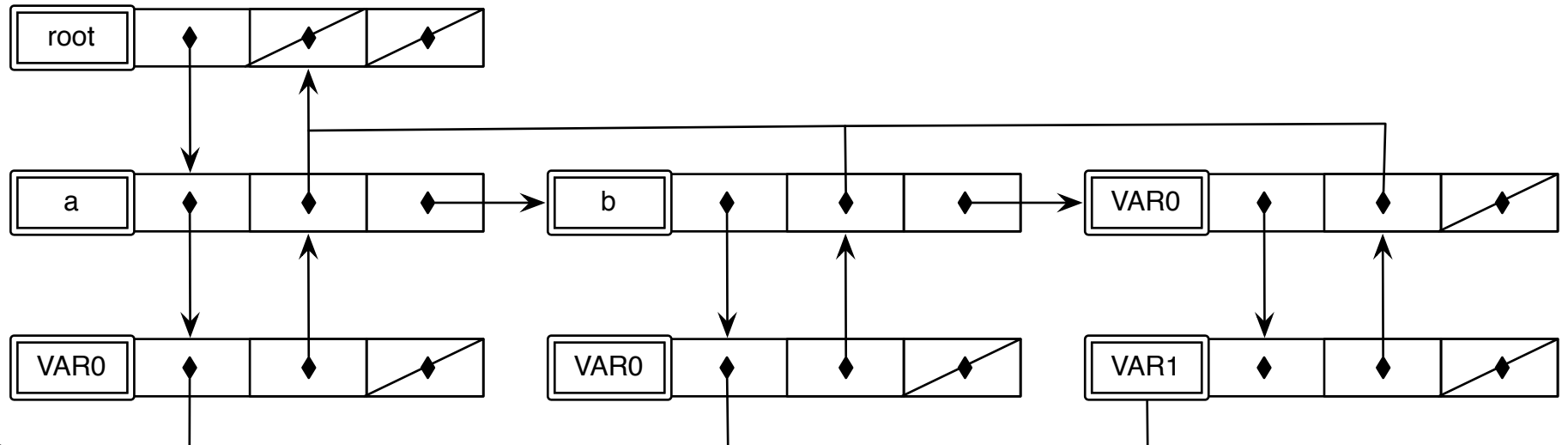


Table entry for path/2

Subgoal trie for path/2



Subgoal Frame for  
path(a, VAR0)

Subgoal Frame for  
path(b, VAR0)

Subgoal Frame for  
path(VAR0, VAR1)

Answer trie for path(a, VAR0)

