

CHARACTERIZATION OF MDS MAPPINGS

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Abstract. MDS codes and matrices are closely related to combinatorial objects like orthogonal arrays and multipermutations. Conventional MDS codes and matrices were defined on finite fields, but several generalizations of this concept has been done up to now. In this note, we give a criterion for verifying whether a map is MDS or not.

1. Introduction

MDS (Maximum Distance Separable) codes and MDS matrices [7, 8] are closely related to combinatorial objects like orthogonal arrays [1] and multipermutations [2]. MDS matrices have also applications in cryptography [3, 10, 4]. Conventional MDS codes and matrices were defined on finite fields, but several generalizations of this concept has been done up to now [9, 2, 8]. In [5] some types of MDS mappings were investigated. In this note, we give a criterion for verifying whether a map is MDS or not.

2. MDS mappings

Definition 2.1. Let A be a nonempty finite set and n be a natural number. For two vectors $a, b \in A^n$ with

$$a = (a_1; a_2; \dots; a_n);$$

$$b = (b_1; b_2; \dots; b_n);$$

we define the distance between them as

$$\text{dist}(a; b) = \#\{i \mid a_i \neq b_i; 1 \leq i \leq n\};$$

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Definition 2.2. Let A be a nonempty finite set and n be two natural numbers. The (differential) branch number of a map

$$f : A^k \rightarrow A^n;$$

is defined as

$$\text{Br}(f) = \min \{ \text{dist}((a; f(a)); (b; f(b))) \mid a, b \in A^k; a \neq b \};$$

Definition 2.3. Let A be a nonempty finite set and n be two natural numbers. We call a map

$$f : A^k \rightarrow A^n;$$

$(k; n; A)$ -MDS if $\text{Br}(f) = n + 1$.

Note 2.4. It is not hard to see that we can construct an $(n+1)$ -code over A which is an MDS code.

Definition 2.5. Let A and B be two nonempty finite sets, r be a natural number and $f : A^r \rightarrow B$ be a map. Suppose that $x_1, x_2, \dots, x_r \in A^r$ is the input of f and let $I = \{1, 2, \dots, r\}$ be a nonempty subset. We call the arguments of input indexed I "input variables" and the rest of arguments "parameters". We denote the map with this separation on input by f_I and we say that f_I is a "parametric map".

Definition 2.6. Let A be a nonempty finite set and n be two natural numbers. A map $f : A^k \rightarrow A^n$ can be represented as a vector (f_1, f_2, \dots, f_n) of functions. Here $f_i : A^k \rightarrow A, 1 \leq i \leq n$, is called the i -th component (projection) function of f .

Definition 2.7. Let A and B be two nonempty finite sets, r be a natural number and $f : A^r \rightarrow B$ be a map. Suppose that $I = \{1, 2, \dots, r\}$ is a nonempty subset. According to Definition 2.5 we say that f_I is parametric invertible if it is invertible for any permissible values of the parameters.

Definition 2.8. Let A be a nonempty finite set and n be two natural numbers. Let $f : A^k \rightarrow A^n$ be a map. For every $1 \leq t \leq \min\{k, n\}$ and for any set $I = \{i_1, i_2, \dots, i_t\}, 1 \leq i_1 < i_2 < \dots < i_t \leq n$ and $J = \{j_1, j_2, \dots, j_{t-1}\}, 1 \leq j_1 < j_2 < \dots < j_{t-1} \leq k$ we define the parametric map

$$f_I^J : A^k \rightarrow A^t;$$

$$x \mapsto ((f_{j_1})_I(x), (f_{j_2})_I(x), \dots, (f_{j_t})_I(x));$$

We call these parametric functions "square sub-functions" of

Theorem 2.9. Let A be a nonempty finite set and n be two natural numbers. A map $f : A^k \rightarrow A^n$ is $(k; n; A)$ -MDS if all of its square sub-functions are parametric invertible.

Proof. At first we suppose that every square sub-function is parametric invertible. Suppose that f is not a $(k; n; A)$ -MDS map. So, we have $Br(f) \neq n$. Therefore, there exist vectors $X = (a; f(a))$ and $Y = (b; f(b))$ with

$$a = fa_1; a_2; \dots; a_n g;$$

$$b = fb_1; b_2; \dots; b_n g;$$

and $dist(X; Y) \neq n$. Since

$$dist(X; Y) = dist(a; b) + dist(f(a); f(b));$$

if $dist(a; b) = t$, then $dist(f(a); f(b)) \neq n - t$. Let $I = \{i; a_i \neq b_i\}$ and $J = \{j; f_j(a) \neq f_j(b)\}$. There exists $I' \subseteq J'$ with $|I'| = t$. So the square sub-function $f_{I'}^J$ is not parametric invertible, due to the existence of a and b . This is a contradiction.

Conversely, suppose that f is a $(k; n; A)$ -MDS map; for any $1 \leq t \leq \min\{k; n\}$ and nonempty subsets $I = \{i_1; i_2; \dots; i_t\}$ and $J = \{j_1; j_2; \dots; j_t\}$ with $|I| = |J| = t$, suppose that the square sub-function f_I^J is not parametric invertible. Then, there exist $a, b \in A$ with $f_{I'}^J(a) = f_{I'}^J(b)$ and $a_i \neq b_i, i \in I'$. This means that

$$dist(a; b) \neq t;$$

and $dist(f(a); f(b)) \neq n - t$, which is contradiction.

Example 2.10. Let $(G; ?)$ be a finite Abelian group. Suppose that $G \times G$ is a map. Define the map

$$f : G^2 \rightarrow G^2;$$

$$f(g_1; g_2) = (g_1 ? g_2; g_1 ? (g_2));$$

If the mappings and

$$h_1 : G \rightarrow G;$$

$$(g) = g ? (g);$$

are both group isomorphisms, then f is a $(2; 2; G)$ -MDS map.

Proof. By Theorem 2.9 it suffices to show that the square sub-functions of f are parametric invertible. There are five square sub-functions. Suppose that $G \times G$ is fixed. The parametric functions

$$h_1 : G \rightarrow G;$$

$$h_1(g; \varphi) = g \cdot \varphi;$$

and

$$\begin{aligned} h_2 : G &\rightarrow G; \\ h_2(g; \varphi) &= \varphi \cdot g; \end{aligned}$$

and

$$\begin{aligned} h_3 : G &\rightarrow G; \\ h_3(g; \varphi) &= g \cdot (\varphi); \end{aligned}$$

are invertible because G is a group. The parametric function

$$\begin{aligned} h_4 : G &\rightarrow G; \\ h_4(g; \varphi) &= \varphi \cdot (g); \end{aligned}$$

is invertible because \cdot is a group isomorphism. Now suppose that the function

$$\begin{aligned} h_5 = f : G^2 &\rightarrow G^2; \\ f(g_1; g_2) &= (g_1 \cdot g_2; g_1 \cdot (g_2)); \end{aligned}$$

is not invertible. Suppose that we have

$$(g_1 \cdot g_2; g_1 \cdot (g_2)) = (g_1^0 \cdot g_2^0; g_1^0 \cdot (g_2^0));$$

with

$$(g_1; g_2) \neq (g_1^0; g_2^0);$$

Then we have

$$\begin{aligned} g_1 \cdot g_2 &= g_1^0 \cdot g_2^0; \\ g_1 \cdot (g_2) &= g_1^0 \cdot (g_2^0); \end{aligned}$$

which leads to

$$\begin{aligned} g_1 \cdot (g_1^0)^{-1} &= g_2^0 \cdot g_2^{-1}; \\ g_1 \cdot (g_1^0)^{-1} &= (g_2^0 \cdot g_2^{-1}); \end{aligned}$$

by isomorphism of \cdot . So, we get

$$(g_2^0 \cdot g_2^{-1}) \cdot (g_1 \cdot (g_1^0)^{-1})^{-1} = e_G;$$

or

$$(g_2^0 \cdot g_2^{-1}) = e_G;$$

which means that $g_2 = g_2^0$ by isomorphism of \cdot . Thus, $g_1 = g_1^0$ which is a contradiction.

Note 2.11. In some fields of mathematics, the morphism in Example 2.10 is called "orthomorphic" [13].

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