

## 1st CSI

# Development of hybrid finite element/neural network methods to help create digital surgical twins

## Authors:

Frédérique LECOURTIER

## Supervisors:

Emmanuel FRANCK

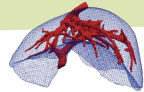
Michel DUPREZ

Vanessa LLERAS

June 14, 2024

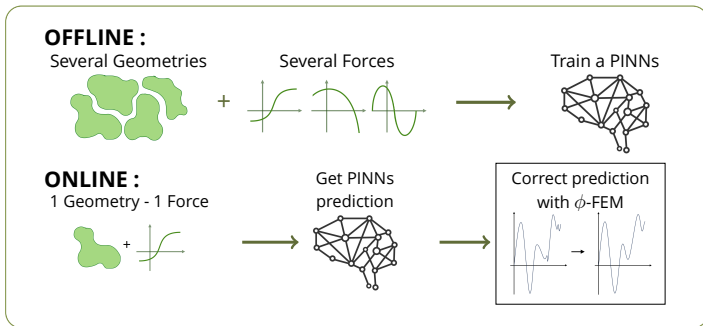
# Introduction

# Scientific context



**Context :** Create real-time digital twins of an organ (e.g. liver).

**Current Objective :** Develop hybrid **finite element** / **neural network** methods.  
**accurate**                      **quick + parameterized**



**$\phi$ -FEM :** New fictitious domain finite element method.

⇒ domain given by a level-set function [Duprez and Lozinski, 2020]

Appendix 2

# Outline

## Two lines of research :

1. How to deal with complex geometry in PINNs ?
2. Once we have the prediction, how can we improve it (using FEM-type methods) ?

## Poisson problem with Dirichlet conditions :

Find  $u : \Omega \rightarrow \mathbb{R}^d (d = 1, 2, 3)$  such that

$$\begin{cases} -\Delta u(x) = f(x) & \text{in } \Omega, \\ u(x) = g(x) & \text{on } \Gamma \end{cases} \quad (\mathcal{P})$$

with  $\Delta$  the Laplace operator,  $\Omega$  a smooth bounded open set and  $\Gamma$  its boundary.

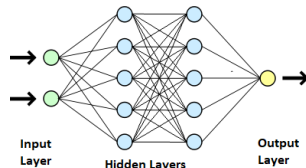
# How to deal with complex geometry in PINNs ?

# Standard PINNs

## Implicit neural representation.

$$u_{\theta}(x) = u_{NN}(x)$$

with  $u_{NN}$  a neural network (e.g. a MLP).



## DoFs Minimization Problem : [Raissi et al., 2019]

Considering the least-square form of  $(\mathcal{P})$ , our discrete problem is

$$\bar{\theta} = \underset{\theta \in \mathbb{R}^m}{\operatorname{argmin}} \alpha J_{in}(\theta) + \beta J_{bc}(\theta)$$

with  $m$  the number of parameters of the NN and

$$J_{in}(\theta) = \frac{1}{2} \int_{\Omega} (\Delta u_{\theta} + f)^2 \quad \text{and} \quad J_{bc}(\theta) = \frac{1}{2} \int_{\partial\Omega} (u_{\theta} - g)^2$$

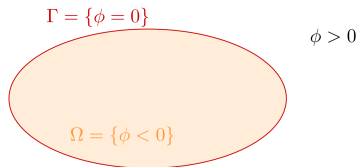
**Monte-Carlo method** : Discretize the cost function by random process.

# Limits

**Claim on PINNs :** No mesh, so easy to go on complex geometry !

⚠ *In practice* : Not so easy ! We need to find how to sample in the geometry.

**Solution :** Approach by levelset. [Sukumar and Srivastava, 2022]



## Advantages :

- Sample is easy in this case.
- Allow to impose in hard the BC :

$$u_{\theta}(X) = \phi(X)w_{\theta}(X) + g(X)$$

(→ Can be used for  $\phi$ -FEM)

## Natural LevelSet :

Signed Distance Function (SDF)

**Problem :** SDF is a  $C^0$  function

⇒ its derivatives explode

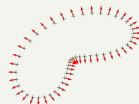
⇒ we need a regular levelset

# Learn a regular levelset

If we have a boundary domain  $\Gamma$ , the SDF is solution to the Eikonal equation:

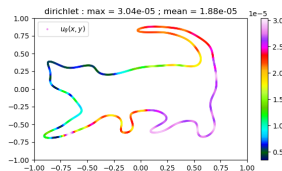
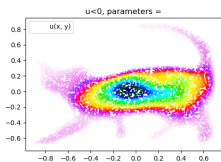
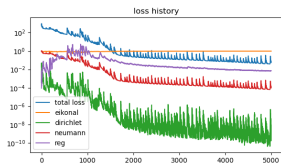
$$\begin{cases} \|\nabla\phi(x)\| = 1, & x \in \mathcal{O} \\ \phi(x) = 0, & x \in \Gamma \\ \nabla\phi(x) = n, & x \in \Gamma \end{cases}$$

with  $\mathcal{O}$  a box which contains  $\Omega$  completely and  $n$  the exterior normal to  $\Gamma$ .



**How to do that ?** with a PINNs [Clémot and Digne, 2023] by adding a regularization term,

$$J_{reg} = \int_{\mathcal{O}} |\Delta\phi|^2$$



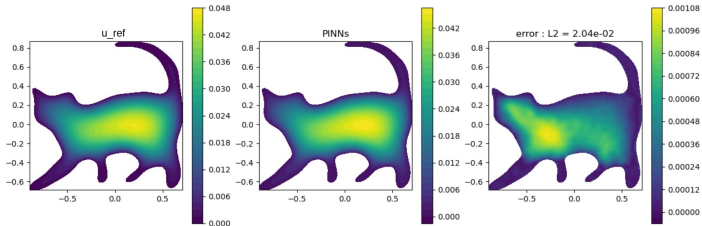
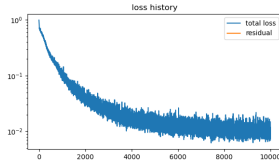
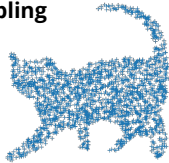
Remark : PINNs non parametric - 1 geometry



# Poisson On Cat

- Solving ( $\mathcal{P}$ ) with  $f = 1$  (non parametric) and homogeneous Dirichlet BC ( $g = 0$ ).
- Looking for  $u_\theta = \phi w_\theta$  with  $\phi$  the levelset learned.

**Sampling**



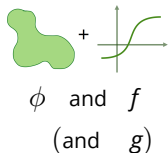
Remark : Poisson on Bean **Appendix 3**

# How improve PINNs prediction ?

⚠ Considering simple geometry (i.e analytic levelset  $\phi$ ).

# Idea

1 Geometry + 1 Force



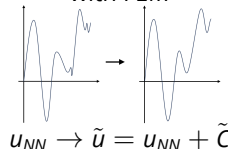
Get PINNs prediction



$$u_{NN} = \phi w_{NN} + g$$

$$u_{NN} = g \text{ on } \Gamma$$

Correct prediction  
with FEM



**Correct by adding :** Considering  $u_{NN}$  as the prediction of our PINNs for  $(\mathcal{P})$ , the correction problem consists in writing the solution as

$$\tilde{u} = u_{NN} + \tilde{c}$$

$\ll 1$

and searching  $\tilde{c} : \Omega \rightarrow \mathbb{R}^d$  such that

$$\begin{cases} -\Delta \tilde{c} = \tilde{f}, & \text{in } \Omega, \\ \tilde{c} = 0, & \text{on } \Gamma, \end{cases} \quad (\mathcal{P}^+)$$

with  $\tilde{f} = f + \Delta u_{NN}$ . Appendix 1 Appendix 5

# Poisson on Square

Solving ( $\mathcal{P}$ ) with homogeneous Dirichlet BC ( $g = 0$ ).

→ **Domain (fixed)** :  $\Omega = [-0.5\pi, 0.5\pi]^2$

→ **Analytical levelset function** :

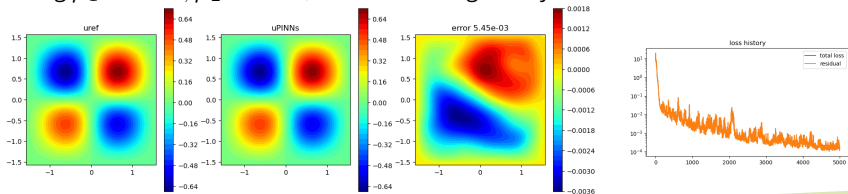
$$\phi(x, y) = (x - 0.5\pi)(x + 0.5\pi)(y - 0.5\pi)(y + 0.5\pi)$$

→ **Analytical solution** :

$$u_{ex}(x, y) = \exp\left(-\frac{(x - \mu_1)^2 + (y - \mu_2)^2}{2}\right) \sin(2x) \sin(2y)$$

with  $\mu_1, \mu_2 \in [-0.5, 0.5]$  (**parametric**).

Taking  $\mu_1 = 0.05, \mu_2 = 0.22$ , the solution is given by



# Theoretical results

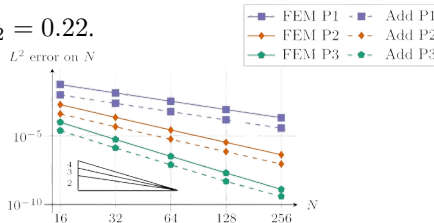
## Theorem 1: [Lecourtier et al., in progress]

We denote  $u$  the solution of  $(\mathcal{P})$  and  $u_h$  the discrete solution of the correction problem (10) with  $V_h$  a  $\mathbb{P}_k$  Lagrange space. Thus

$$\|u - u_h\|_0 \leq \frac{|u - u_\theta|_{H^{k+1}}}{|u|_{H^{k+1}}} \left( \frac{\gamma}{\alpha} ch^{k+1} |u|_{H^{k+1}} \right)$$

with  $\alpha$  and  $\gamma$  respectively the coercivity and continuity constant.

Taking  $\mu_1 = 0.05, \mu_2 = 0.22$ .



*Remark :* We note  $N$  the number of nodes in each direction of the square.

# Gains using our approach

Considering a set of  $n_p = 50$  parameters:  $\left\{(\mu_1^{(1)}, \mu_2^{(1)}), \dots, (\mu_1^{(n_p)}, \mu_2^{(n_p)})\right\}$ .

**Solution  $\mathbb{P}_1$**

N	Gains on PINNs				Gains on FEM			
	min	max	mean	std	min	max	mean	std
20	15.7	48.35	33.64	5.57	134.31	377.36	269.4	43.67
40	61.47	195.75	135.41	23.21	131.18	362.09	262.12	41.67

**Solution  $\mathbb{P}_2$**

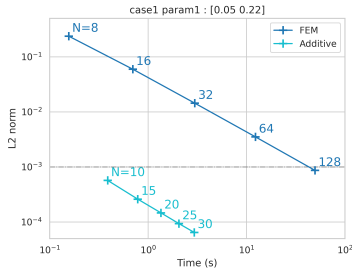
N	Gains on PINNs				Gains on FEM			
	min	max	mean	std	min	max	mean	std
20	244.81	996.23	655.08	153.63	67.12	165.13	135.21	21.37
40	2,056.2	8,345.4	5,504.89	1,287.16	66.52	159.73	132.05	20.38

**Solution  $\mathbb{P}_3$**

N	Gains on PINNs				Gains on FEM			
	min	max	mean	std	min	max	mean	std
20	2,804.27	11,797.23	7,607.51	1,780.7	39.72	72.99	61.85	7.05
40	50,989.23	212,714.99	137,711.77	32,125.57	40.02	73	61.98	6.92

# Time/Precision I

Taking  $\mu_1 = 0.05, \mu_2 = 0.22$ .



Precision	N		time (s)	
	FEM	Add	FEM	Add
$1e-3$	120	8	43	0.24
$1e-4$	373	25	423.89	1.93

*t<sub>FEM</sub>*                      *t<sub>Add</sub>*

**Question :** Where is the PINNs training time ?

$$t_{PINNs} \approx 240s$$

# Time/Precision II

Taking a **set of  $n_p$  parameters**  $\left\{ (\mu_1^{(1)}, \mu_2^{(1)}), \dots, (\mu_1^{(n_p)}, \mu_2^{(n_p)}) \right\}$ .

The time of our approach (including the PINNs training) to solve  $n_p$  problems is

$$Tot_{Add} = t_{PINNs} + n_p t_{Add}$$

and the time of FEM is

$$Tot_{FEM} = n_p t_{FEM}.$$

Let's suppose we want to achieve an **error of  $1e-3$** .

To solve  $n_p$  problems, our method is faster than FEM (when considering network training time) if

$$Tot_{Add} < Tot_{FEM} \Rightarrow n_p > \frac{t_{PINNs}}{t_{FEM} - t_{Add}} \approx 5.61 \Rightarrow \boxed{n_p = 6}$$

*Remark:* Considering that the times are of the same order for each parameter considered.



# Conclusion

# Conclusion

## Current progress :

- Levelset learning works on complex geometries  
*Advantage* : enables “exact” imposition of BC in PINNs
- Additive approach works on simple geometries  
*Advantage (compared with standard FEM)* :
  - More accurate solution (smaller error)
  - Better execution time

## Perspectives :

- Working on parametric models for Levelset learning
- Combine the 2 axis to improve NN predictions on complex geometries
- Use  $\phi$ -FEM (fictitious domain method) to improve NN predictions  
*Advantage* : The levelset learned by PINNs can be used in  $\phi$ -FEM
- Start considering 3D cases

Appendix 4

# Supplementary work I

## Teaching at the university

- ▶ 16h of Computer Science Practical Work (Python) - L2S3
- ▶ 34h of Computer Science Practical Work (C++) - L3S6

## Formations (Total : $\approx 65h$ )

- ▶ "Charte de déontologie des métiers de la Recherche" (OBLIGATORY)
- ▶ MOOC Bordeaux - "Intégrité scientifique dans les métiers de la recherche" (OBLIGATORY)
- ▶ "Enseigner et apprendre (public : mission enseignement)"
- ▶ "Gérer ses ressources bibliographiques avec Zotero"
- ▶ 3 Workshops on EDP at IRMA
- ▶ 19 Remote Sessions ( $\approx 40h$ ) - "Formation Introduction au Deep Learning" (FIDLE)

# Supplementary work II

## Talks

- ▶ Team meeting (Mimesis) - December 12, 2023 - "Development of hybrid finite element/neural network methods to help create digital surgical twins"
- ▶ Retreat (Macaron/Tonus) - February 6, 2024  
"Mesh-based methods and physically informed learning"
- ▶ Exama project, WP2 reunion - March 26, 2024  
"How to work with complex geometries in PINNs ?"

## Publications

- ▶ **Lecourtier**, Victorion, Barucq, Duprez, Faucher, Franck, Lleras, and Michel-Dansac. Enhanced finite element methods using neural networks. in progress.

## Coming soon...

- ▶ July 8 - 12, 2024 - Poster for a Workshop on Scientific Machine Learning ([SciML 2024](#))

# Thank you !

## Bibliography

- Clémot and Digne. Neural skeleton: Implicit neural representation away from the surface. *Computers and Graphics*, 2023.
- Cotin, Duprez, Lleras, Lozinski, and Vuillemot.  $\phi$ -fem: an efficient simulation tool using simple meshes for problems in structure mechanics and heat transfer. 2021.
- Duprez and Lozinski.  $\phi$ -fem: A Finite Element Method on Domains Defined by Level-Sets. *SIAM Journal on Numerical Analysis*, 2020.
- Duprez, Lleras, and Lozinski. A new  $\phi$ -fem approach for problems with natural boundary conditions, 2020.
- Duprez, Lleras, and Lozinski.  $\phi$ -fem: an optimally convergent and easily implementable immersed boundary method for particulate flows and Stokes equations. *ESAIM: Mathematical Modelling and Numerical Analysis*, 2023.
- Raissi, Perdikaris, and Karniadakis. Physics-informed neural networks: A deep learning framework for solving forward and inverse problems involving nonlinear partial differential equations. *Journal of Computational Physics*, 2019.
- Sukumar and Srivastava. Exact imposition of boundary conditions with distance functions in physics-informed deep neural networks. *Computer Methods in Applied Mechanics and Engineering*, 2022.
- Lecourtier**, Victorion, Barucq, Duprez, Faucher, Franck, Lleras, and Michel-Dansac. Enhanced finite element methods using neural networks. in progress.



# Appendix

# Appendix 1 : Standard FEM

# Appendix 1 : General Idea

**Variational Problem :** Find  $u \in V \mid a(u, v) = l(v), \forall v \in V$   
with  $V$  - Hilbert space,  $a$  - bilinear form,  $l$  - linear form.

**Approach Problem :** Find  $u_h \in V_h \mid a(u_h, v_h) = l(v_h), \forall v_h \in V_h$   
with  $\bullet u_h \in V_h$  an approximate solution of  $u$ ,

$\bullet V_h \subset V, \dim V_h = N_h < \infty, (\forall h > 0)$

$\Rightarrow$  Construct a piecewise continuous functions space

$$V_h := P_{C,h}^k = \{v_h \in C^0(\bar{\Omega}), \forall K \in \mathcal{T}_h, v_h|_K \in \mathbb{P}_k\}$$

where  $\mathbb{P}_k$  is the vector space of polynomials of total degree  $\leq k$ .

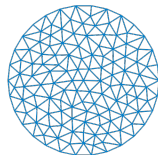
Finding an approximation of the PDE solution  $\Rightarrow$  solving the following linear system:

$$AU = b$$

with

$$A = (a(\varphi_i, \varphi_j))_{1 \leq i, j \leq N_h}, \quad U = (u_i)_{1 \leq i \leq N_h} \quad \text{and} \quad b = (l(\varphi_j))_{1 \leq j \leq N_h}$$

where  $(\varphi_1, \dots, \varphi_{N_h})$  is a basis of  $V_h$ .



$$\mathcal{T}_h = \{K_1, \dots, K_{N_e}\}$$

( $N_e$  : number of elements)



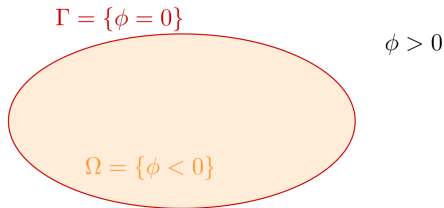
# Appendix 2 : $\phi$ -FEM

## Appendix 2 : Problem

Let  $u = \phi w + g$  such that

$$\begin{cases} -\Delta u = f, & \text{in } \Omega, \\ u = g, & \text{on } \Gamma, \end{cases}$$

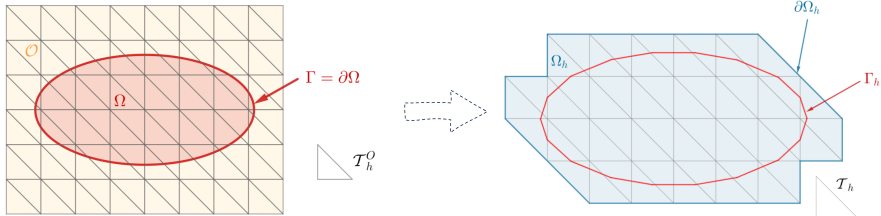
where  $\phi$  is the level-set function and  $\Omega$  and  $\Gamma$  are given by :



The level-set function  $\phi$  is supposed to be known on  $\mathbb{R}^d$  and sufficiently smooth. For instance, the signed distance to  $\Gamma$  is a good candidate.

*Remark :* Thanks to  $\phi$  and  $g$ , the boundary conditions are respected.

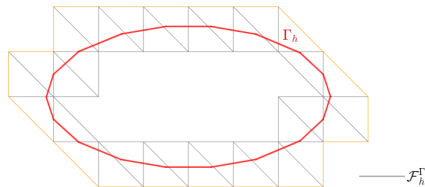
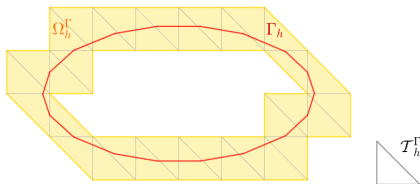
# Appendix 2 : Fictitious domain



- $\phi_h$  : approximation of  $\phi$
- $\Gamma_h = \{\phi_h = 0\}$  : approximate boundary of  $\Gamma$
- $\Omega_h$  : computational mesh
- $\partial\Omega_h$  : boundary of  $\Omega_h$  ( $\partial\Omega_h \neq \Gamma_h$ )

*Remark* :  $n_{vert}$  will denote the number of vertices in each direction

# Appendix 2 : Facets and Cells sets



- $\mathcal{T}_h^\Gamma$  : mesh elements cut by  $\Gamma_h$
- $\mathcal{F}_h^\Gamma$  : collects the interior facets of  $\mathcal{T}_h^\Gamma$   
(either cut by  $\Gamma_h$  or belonging to a cut mesh element)

## Appendix 2 : Poisson problem

**Approach Problem :** Find  $w_h \in V_h^{(k)}$  such that

$$a_h(w_h, v_h) = l_h(v_h) \quad \forall v_h \in V_h^{(k)}$$

where

$$a_h(w, v) = \int_{\Omega_h} \nabla(\phi_h w) \cdot \nabla(\phi_h v) - \int_{\partial\Omega_h} \frac{\partial}{\partial n}(\phi_h w) \phi_h v + \boxed{G_h(w, v)},$$

$$l_h(v) = \int_{\Omega_h} f \phi_h v + \boxed{G_h^{hs}(v)} \quad \text{Stabilization terms}$$

and

$$V_h^{(k)} = \{v_h \in H^1(\Omega_h) : v_h|_T \in \mathbb{P}_k(T), \forall T \in \mathcal{T}_h\}.$$

For the non homogeneous case, we replace

$$u = \phi w \quad \rightarrow \quad u = \phi w + g$$

by supposing that  $g$  is currently given over the entire  $\Omega_h$ .

# Appendix 2 : Stabilization terms

Independent parameter of  $h$       Jump on the interface  $E$

$$G_h(w, v) = \underbrace{\sigma h \sum_{E \in \mathcal{F}_h^\Gamma} \int_E \left[ \frac{\partial}{\partial n}(\phi_h w) \right] \left[ \frac{\partial}{\partial n}(\phi_h v) \right]}_{\text{1st order term}} + \underbrace{\sigma h^2 \sum_{T \in \mathcal{T}_h^\Gamma} \int_T \Delta(\phi_h w) \Delta(\phi_h v)}_{\text{2nd order term}}$$

$$G_h^{rhs}(v) = \underbrace{-\sigma h^2 \sum_{T \in \mathcal{T}_h^\Gamma} \int_T f \Delta(\phi_h v)}_{\text{2nd order term}} - \underbrace{\sigma h^2 \sum_{T \in \mathcal{T}_h^\Gamma} \int_T (\Delta(\phi_h w) + f) \Delta(\phi_h v)}_{\text{2nd order term}}$$

1st term : ensure continuity of the solution by penalizing gradient jumps.

→ Ghost penalty [Burman, 2010]

2nd term : require the solution to verify the strong form on  $\Omega_h^\Gamma$ .

## Purpose :

- ➔ reduce the errors created by the "fictitious" boundary
- ➔ ensure the correct condition number of the finite element matrix
- ➔ restore the coercivity of the bilinear scheme

# Other results

Poisson on Bean

Additive approach on Cat

Multiplicative approach

# Other results

Poisson on Bean

Additive approach on Cat

Multiplicative approach



# Appendix 3 : Learn a levelset

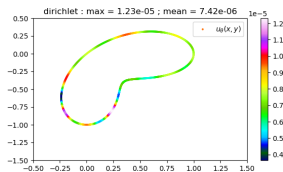
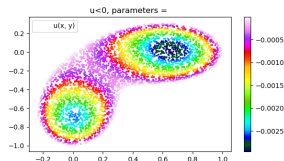
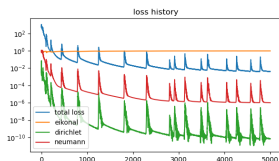
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with  $\mathcal{O}$  a box which contains  $\Omega$  completely and  $n$  the exterior normal to  $\Gamma$ .

**How make that ?** with a PINNs [Clémot and Digne, 2023] by adding a term to regularize.

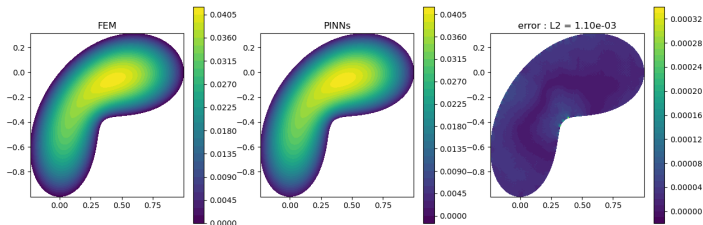
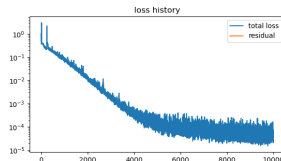
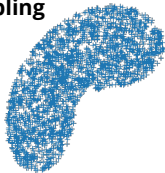
$$J_{reg} = \int_{\mathcal{O}} |\Delta\phi|^2$$



# Appendix 3 : Poisson 2D

- Solving the **Poisson problem** with  $f = 1$  and homogeneous Dirichlet BC.
- Looking for  $u_\theta = \phi w_\theta$  with  $\phi$  the levelset learned.

**Sampling**



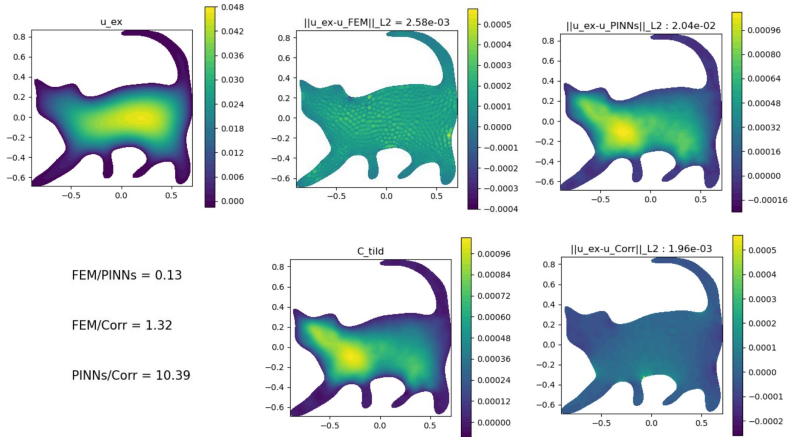
# Other results

Poisson on Bean

Additive approach on Cat

Multiplicative approach

# Appendix 4 : Add on Cat



# Other results

Poisson on Bean

Additive approach on Cat

Multiplicative approach

## Appendix 5 : Multiplicative approach

**Correct by multiplying :** Considering  $u_{NN}$  as the prediction of our PINNs for  $(\mathcal{P})$ , we define

$$u_M = u_{NN} + M$$

with  $M$  a constant chosen so that  $u_M > 0$ , called the enhancement constant. Thus, the correction problem consists in writing the solution as

$$\tilde{u} = u_M \times \boxed{\tilde{C}}_{\approx 1}$$

and searching  $\tilde{C} : \Omega \rightarrow \mathbb{R}^d$  such that

$$\begin{cases} -\Delta(u_M \tilde{C}) = f, & \text{in } \Omega, \\ \tilde{C} = 1, & \text{on } \Gamma. \end{cases}$$