

Macaron/Tonus retreat presentation

Mesh-based methods and physically informed learning

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February 6-7, 2024

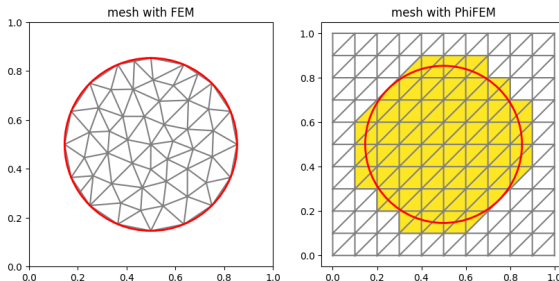
Introduction

Scientific context

Context : Create real-time digital twins of an organ (such as the liver).

ϕ -FEM Method : New fictitious domain finite element method.

- domain given by a level-set function \Rightarrow don't require a mesh fitting the boundary
- allow to work on complex geometries
- ensure geometric quality



Practical case: Real-time simulation, shape optimization...

Objective

Current Objective : Develop hybrid finite element / neural network methods.

OFFLINE :

Several Geometries



+

Several Functions

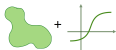


Train a PINNs



ONLINE :

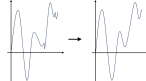
1 Geometry - 1 Function



Get PINNs prediction



Correct prediction with ϕ -FEM



Evolution :

- Geometry : 2D, simple, fixed (as circle, ellipse..) \rightarrow 3D / complex / variable
- PDE : simple, static (Poisson problem) \rightarrow complex / dynamic (elasticity, hyper-elasticity)
- Neural Network : simple and defined everywhere (PINNs) \rightarrow Neural Operator

Problem considered

Elliptic problem with Dirichlet conditions :

Find $u : \Omega \rightarrow \mathbb{R}^d (d = 1, 2, 3)$ such that

$$\begin{cases} L(u) = -\nabla \cdot (A(x)\nabla u(x)) + c(x)u(x) = f(x) & \text{in } \Omega, \\ u(x) = g(x) & \text{on } \partial\Omega \end{cases} \quad (1)$$

with A a definite positive coercivity condition and c a scalar. We consider Δ the Laplace operator, Ω a smooth bounded open set and Γ its boundary.

Weak formulation :

Find $u \in V$ such that $a(u, v) = l(v) \forall v \in V$

with

$$\begin{aligned} a(u, v) &= \int_{\Omega} (A(x)\nabla u(x)) \cdot \nabla v(x) + c(x)u(x)v(x) \, dx \\ l(v) &= \int_{\Omega} f(x)v(x) \, dx \end{aligned}$$

Remark : For simplicity, we will not consider 1st order terms.

Numerical methods

Objective : Show that the philosophy behind most of the methods are the same.

Mesh-based methods // Physically informed learning

Numerical methods : Discretize an infinite-dimensional problem (unknown = function) and solve it in a finite-dimensional space (unknown = vector).

- **Encoding :** we encode the problem in a finite-dimensional space
- **Approximation :** solve the problem in finite-dimensional space
- **Decoding :** bring the solution back into infinite dimensional space

Encoding	Approximation	Decoding
$f \rightarrow \theta_f$	$\theta_f \rightarrow \theta_u$	$\theta_u \rightarrow u_\theta$

Mesh-based methods

Encoding/Decoding

Approximation

Mesh-based methods

Encoding/Decoding

Approximation

Encoding/Decoding - FEMs

- **Decoding** : Linear combination of piecewise polynomial function φ_i .

$$\mathcal{D}_{\theta_u}(x) = \sum_{i=1}^N (\theta_u)_i \varphi_i$$

\Rightarrow linear decoding \Rightarrow approximation space V_N = vectorial space

- **Encoding** : Orthogonal projection on vector space V_N . Appendix 1 1

$$\theta_f = E(f) = M^{-1}b(f)$$

with $M_{ij} = \int_{\omega} \varphi_i(x) \varphi_j(x)$ and $b_i(f) = \int_{\omega} \varphi_i(x) f(x)$.

Mesh-based methods

Encoding/Decoding

Approximation

Internship results

Correction Methods

Results - with FNO

Other results

Internship results

Correction Methods

Results - with FNO

Other results

Correction Methods

We are given u_θ the FNO prediction (for the problem under consideration).

By multiplying :

By adding :

We will consider

$$\tilde{u} = u_\theta + \boxed{\tilde{C}} \approx 0$$

We want $\tilde{C} : \Omega \rightarrow \mathbb{R}^d$ such that

$$\begin{cases} -\Delta \tilde{C} = \tilde{f}, & \text{in } \Omega, \\ \tilde{C} = 0, & \text{on } \Gamma. \end{cases} \quad (\mathcal{C}_+)$$

with $\tilde{f} = f + \Delta u_\theta$ and $\tilde{C} = \phi C$ for the ϕ -FEM method.

Remark : In practice, it may be useful to integrate by parts the term containing Δu_θ .

We will consider

$$\tilde{u} = u_\theta \boxed{C} \approx 1$$

We want $C : \Omega \rightarrow \mathbb{R}^d$ such that

$$\begin{cases} -\Delta(u_\theta C) = f, & \text{on } \Omega, \\ C = 1, & \text{on } \Gamma. \end{cases} \quad (\mathcal{C}_\times)$$

Correction Methods

We are given u_θ the FNO prediction (for the problem under consideration).

By adding :

We will consider

$$\tilde{u} = u_\theta + \tilde{C}$$

We want $\tilde{C} : \Omega \rightarrow \mathbb{R}^d$ such that

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with $\tilde{f} = f + \Delta u_\theta$ and $\tilde{C} = \phi C$ for the ϕ -FEM method.

Remark : In practice, it may be useful to integrate by parts the term containing Δu_θ .

By multiplying - elevated problem :

Find $\hat{u} : \Omega \rightarrow \mathbb{R}^d$ such that

$$\begin{cases} -\Delta \hat{u} = f, & \text{in } \Omega, \\ \hat{u} = g + m, & \text{on } \Gamma, \end{cases} \quad (\mathcal{P}^{\mathcal{M}})$$

with $\hat{u} = u + m$ (m a constant).

We will consider

$$\tilde{u} = \hat{u}_\theta C$$

with $\hat{u}_\theta = u_\theta + m$.

We want $C : \Omega \rightarrow \mathbb{R}^d$ such that

$$\begin{cases} -\Delta(\hat{u}_\theta C) = f, & \text{in } \Omega, \\ C = 1, & \text{on } \Gamma. \end{cases} \quad (\mathcal{C}_\times^{\mathcal{M}})$$

Internship results

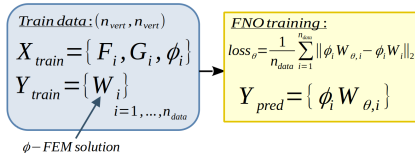
Correction Methods

Results - with FNO

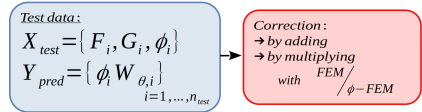
Other results

Explanation

Train a FNO :



Correct the predictions of the FNO :



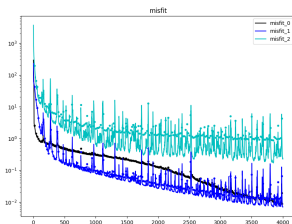
Some important points on the FNO :

- widely used in PDE solving and constitute an active field of research
- FNO are Neural Operator networks : Unlike standard neural networks, which learn using inputs and outputs of fixed dimensions, neural operators **learn operators, which are mappings between spaces of functions.**
- **Mesh resolution independent** : can be evaluated at almost any data resolution without the need for retraining

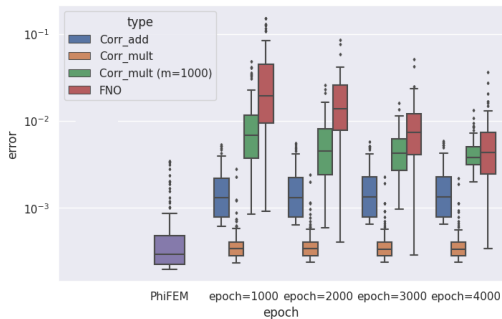
Correction on a FNO prediction - ϕ -FEM

We consider an unknown solution on the circle with f Gaussian (??), $n_{vert} = 63$, $n_{data} = 1000$ (including validation sample) and $n_{test} = 100$.

Training on 4000 epochs
(bs=64, lr=0.01) :



Correction with the different methods :



Remark : We should try to reduce the resolution for correction, maybe we will gain in the time-to-error ratio.

Internship results

Correction Methods

Results - with FNO

Other results

Precision of the prediction - FEM

We consider the trigonometric solution on the circle (??) with

$$u_{ex}(x, y) = S \sin \left(8\pi f \left((x - 0.5)^2 + (y - 0.5)^2 \right) + \varphi \right)$$

with $S = 0.5$ and $\varphi = 0$.

Exact solution : Testing different correction methods for different frequencies.

$$u_\theta = u_{ex} \in \mathbb{P}^{10} \rightarrow \tilde{u} \in \mathbb{P}^1$$

Correction with FEM ($n_{vert} = 100$) :

	fem	Corr_add	Corr_add_IPP	Corr_mult
f = 1	2.10e-03	2.44e-10	1.29e-13	2.97e-13
f = 2	6.62e-03	1.53e-10	1.28e-13	2.80e-13
f = 3	1.41e-02	8.86e-11	1.27e-13	2.68e-13
f = 4	2.42e-02	9.52e-11	1.26e-13	2.61e-13

Precision of the prediction - FEM

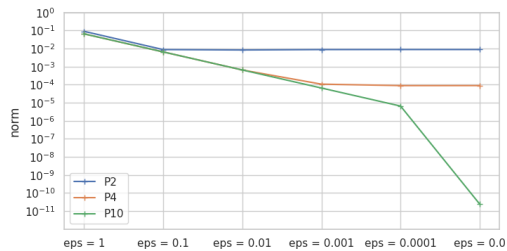
We consider $(S, f, \varphi) = (0.5, 1, 0)$.

Disturbed solution : Testing different ϵ and different degree k .

$$u_\theta = u_{ex} + \epsilon P \in \mathbb{P}^k \rightarrow \tilde{u} \in \mathbb{P}^1$$

with ϵ a real number and P a perturbation.

Correction (\mathcal{C}_+) with FEM ($n_{vert} = 32$) :



Results for $k = 10$:

eps	corr_add
1.00e+00	6.57e-02
1.00e-01	6.57e-03
1.00e-02	6.57e-04
1.00e-03	6.57e-05
1.00e-04	6.57e-06
0.00e+00	2.44e-11

Remark : $P(x, y) = S_p \sin \left(8\pi f_p \left((x - 0.5)^2 + (y - 0.5)^2 \right) \right) + \varphi_p$ with $(S_p, f_p, \varphi_p) = (0.5, 2, 0)$

Theoretical results - FEM

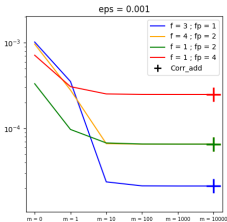
Correction by multiplication on the elevated problem : We consider

- $\hat{u}_{ex} = u_{ex} + m$: the exact solution of $(\mathcal{P}^{\mathcal{M}})$
- $\hat{u}_{\theta} = u_{\theta} + m$: a disturbed solution of $(\mathcal{P}^{\mathcal{M}})$.
- $\tilde{u}_h = \hat{u}_{\theta} C_h$: the approximate solution of $(\mathcal{C}_{\times}^{\mathcal{M}})$

1. When m tends to infinity :

solution of $(\mathcal{C}_{\times}^{\mathcal{M}}) \rightarrow$ solution of (\mathcal{C}_{+})

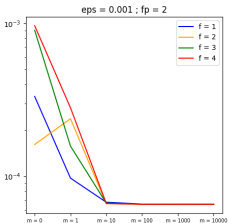
Results : $n_{vert} = 32, \epsilon = 0.001$



2. For m sufficiently large : $C_{ex} = \hat{u}_{ex}/\hat{u}_{\theta}$

$$\|C_{ex} - C_h\|_{0,\Omega} \leq ch^{k+1} \epsilon \|P''\|_{0,\Omega}$$

Results : $n_{vert} = 32, \epsilon = 0.001, f_p = 2$



PhD results

Explanation

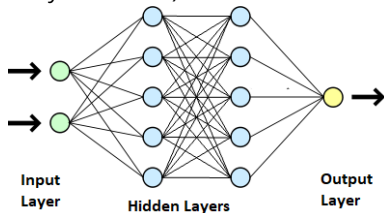
Context : Need $u_\theta \in \mathbb{P}^k$ with k of high degree

FNO
(on a regular grid) \rightarrow

NN which can predict
solution at any point

Solutions :

1. MLP - Multi-Layer Perceptron
(= Fully connected)



Problem : As the prediction is injected into an FEM solver, the accuracy of the derivatives is very important.

2. PINNs - MLP with a physical loss

$$\text{loss} = \text{mse}(\Delta(\phi(x_i, y_i)w_{\theta, i}) + f_i)$$

$$\begin{aligned} \text{inputs} &= \{(x_i, y_i)\} \\ \text{outputs} &= \{u_i\} \\ &\quad i=1, \dots, n_{pts} \\ u_i &= \phi(x_i, y_i)w_{\theta}(x_i, y_i) \end{aligned}$$

with $(x_i, y_i) \in \mathcal{O}$.

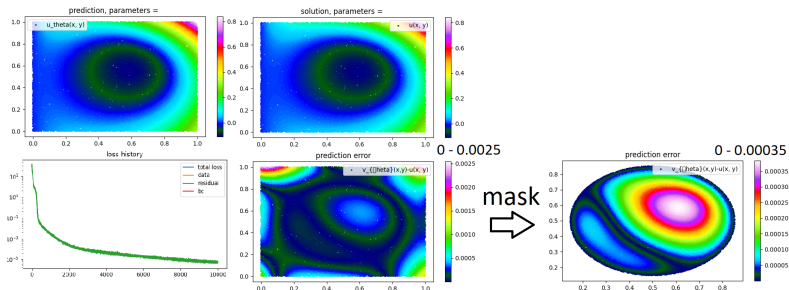
Remark : We impose exact boundary conditions.

PINNs Training

We consider the solution on the circle defined in (??) and defined by

$$u_{ex}(x, y) = \phi(x, y) \sin(x) \exp(y)$$

We train a PINNs with 4 layers of 20 neurons over 10000 epochs (with $n_{pts} = 2000$ points selected uniformly over \mathcal{O}).

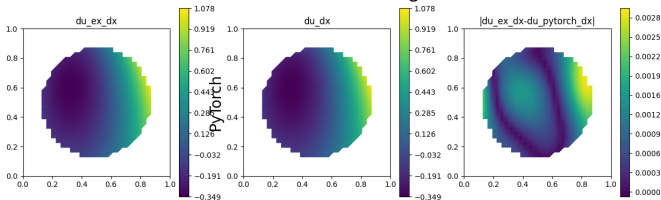


⚠ We consider a single problem (f fixed) on a single geometry (ϕ fixed).

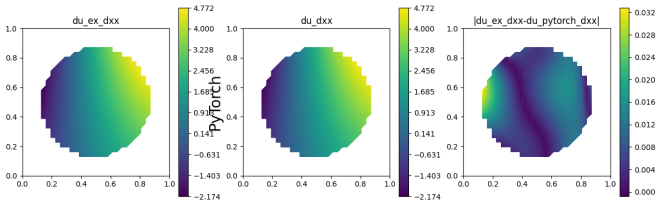
$$\|u_{ex} - u_{\theta}\|_{0, \Omega}^{(rel)} \approx 2.81e - 3$$

Derivatives

First derivative according to x

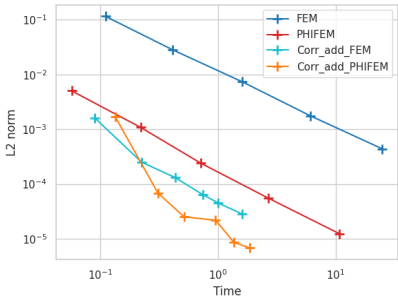


Second derivative according to x



Correction by addition

$u_\theta \in \mathbb{P}^{10} \rightarrow \tilde{u} \in \mathbb{P}^1$



Calculation time (to reach an error of 1e-4)

	mesh	u_PINNs	assemble	solve	TOTAL
FEM	0,08832		29,55516	0,07272	29,71621
PhiFEM	0,33222		1,86924	0,00391	2,20537
Corr_add_FEM	0,00183	0,11187	0,46195	0,00061	0,57626
Corr_add_PhiFEM	0,03213	0,05351	0,22006	0,00040	0,30609

- **mesh** - FEM : construct the mesh
(ϕ -FEM : construct cell/facet sets)
- **u_PINNs** - get u_θ in \mathbb{P}^{10} freedom degrees
- **assemble** - assemble the FE matrix
- **solve** - resolve the linear system

FEM / ϕ -FEM : $n_{vert} \in \{8, 16, 32, 64, 128\}$

Corr : $n_{vert} \in \{5, 10, 15, 20, 25, 30\}$

Remark : The stabilisation parameter σ of the ϕ -FEM method has a major impact on the error obtained.

Conclusion

Conclusion

Observations :

1. Correction by addition seems to be the best choice (based on theoretical results obtained with FEM)
2. We need a high degree prediction ($u_\theta \in \mathbb{P}^{10}$)
 \Rightarrow no longer use FNO (needs NN defined at any point)
3. We need to approximate the derivatives of the solution precisely
 \Rightarrow no longer use simple MLP, replaced by a PINNs

What's next ?

1. Consider multiple problems (varying f)
2. Consider multiple and more complex geometry (varying ϕ)
3. Replace PINNs with a Neural Operator

Bibliography

Bibliography

Appendix 1 : Encoding - FEMs

Pourquoi ?