

```
1 from TimeIntegration import getbc, get_eigenval
2 from FixedVariables import rho, v, p, nw, xmax, xmin
3 from ComputeTimeStep import computeTimeStep
4 from InputVariables import ngc
5 import numpy as np
6
7 def flux(h):
8     F = [0, 0, 0]
9     F[0] = h[1]
10    F[1] = rho(h)*np.square(v(h)[0]) + p(h)
11    F[2] = (h[-1] + p(h))*v(h)[0]
12    return F
13
14 def IntegrateTimeLF(x,nx):
15     dx = (xmax - xmin) / (nx - 1)
16     w = getbc(x)
17     lam = get_eigenval(w, nx)
18     dt = computeTimeStep(lam, dx, nx)
19     w_adv = [[0 for l in range(nw)] for m in range(nx+ngc*2)]
20     for k in range(nw):
21         w_adv[0][k] = w[0][k]
22         w_adv[-1][k] = w[-1][k]
23     for i in range(ngc, nx + ngc):
24         for j in range(nw):
25             w_adv[i][j] = (w[i+1][j] + w[i-1][j])/2 - (dt/(2*dx))*(
flux(w[i+1])[j] - flux(w[i-1])[j])
26     print(w_adv)
27     return dt, w_adv
```