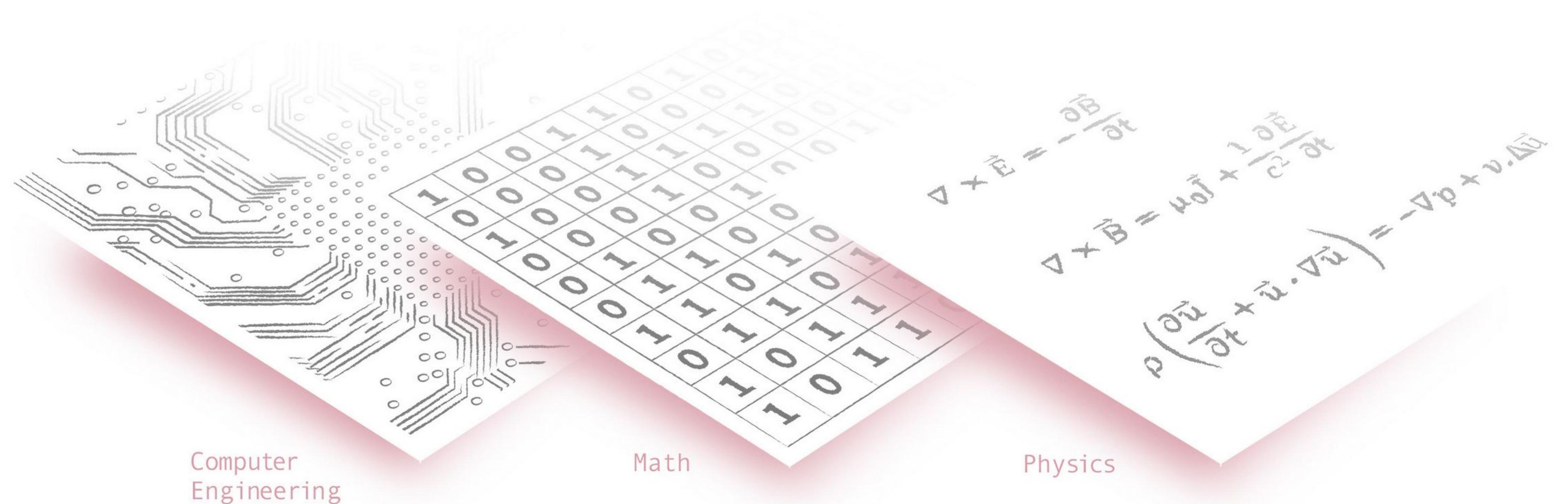




INTRO TO FDTD

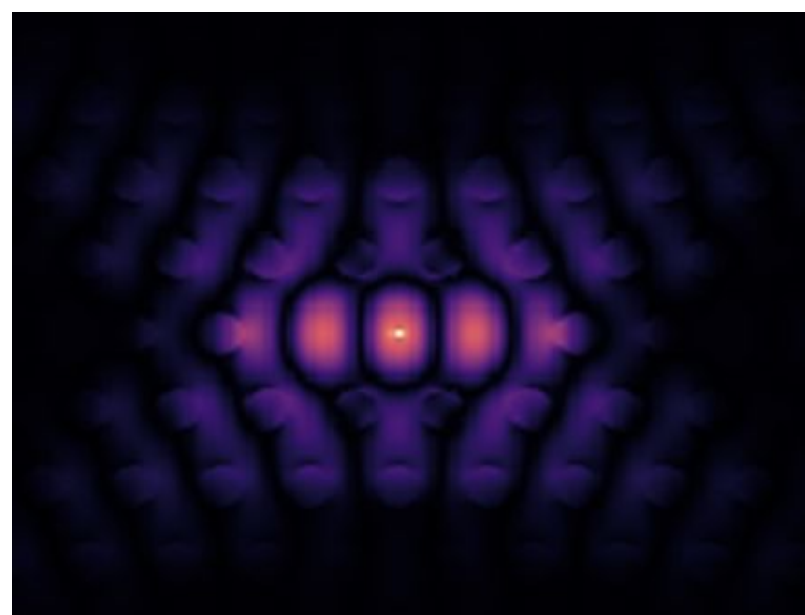
Flexcompute Inc.



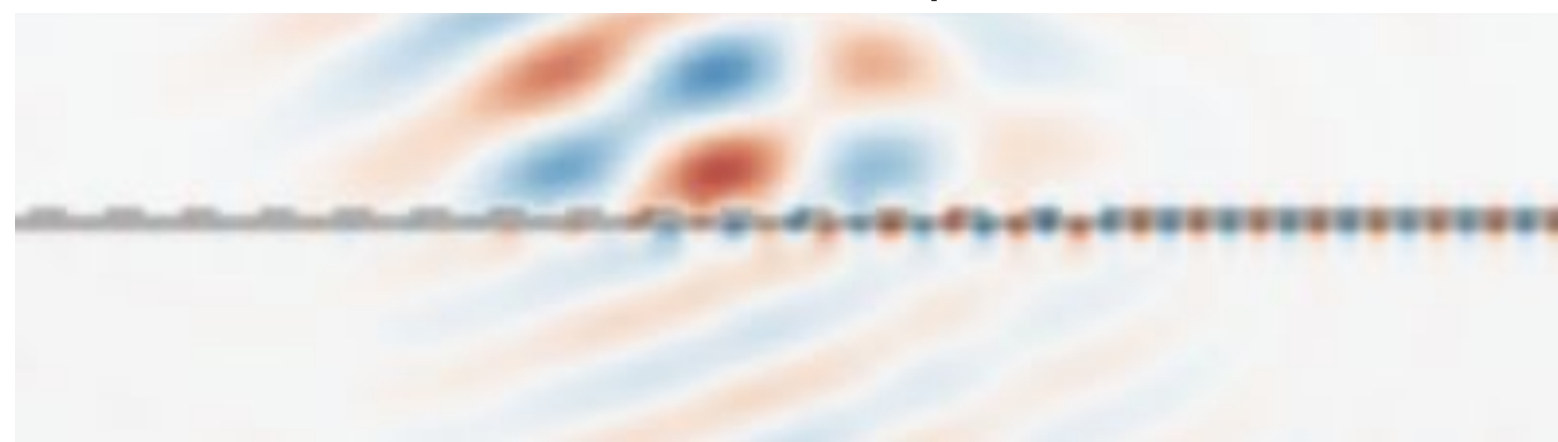
INTRODUCTION

- ▶ The Finite-Difference Time-Domain (FDTD) method is a method for simulating interaction of light with structures and materials.
- ▶ It is the most widely used and general-purpose method.
- ▶ Let's you simulate a wide range of phenomena in photonics.

Photonic crystal cavity



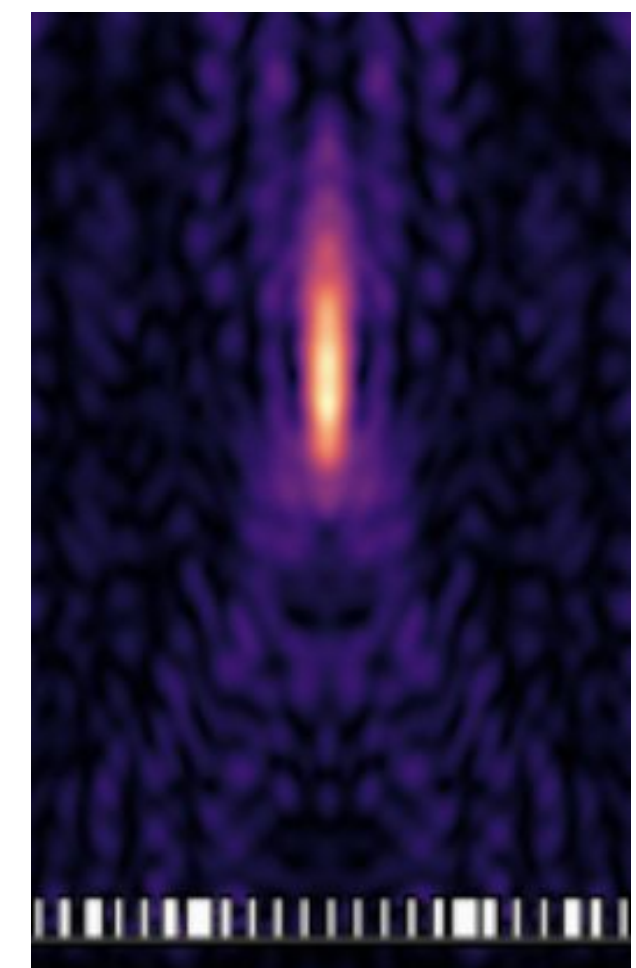
Grating coupler



Ring Resonator

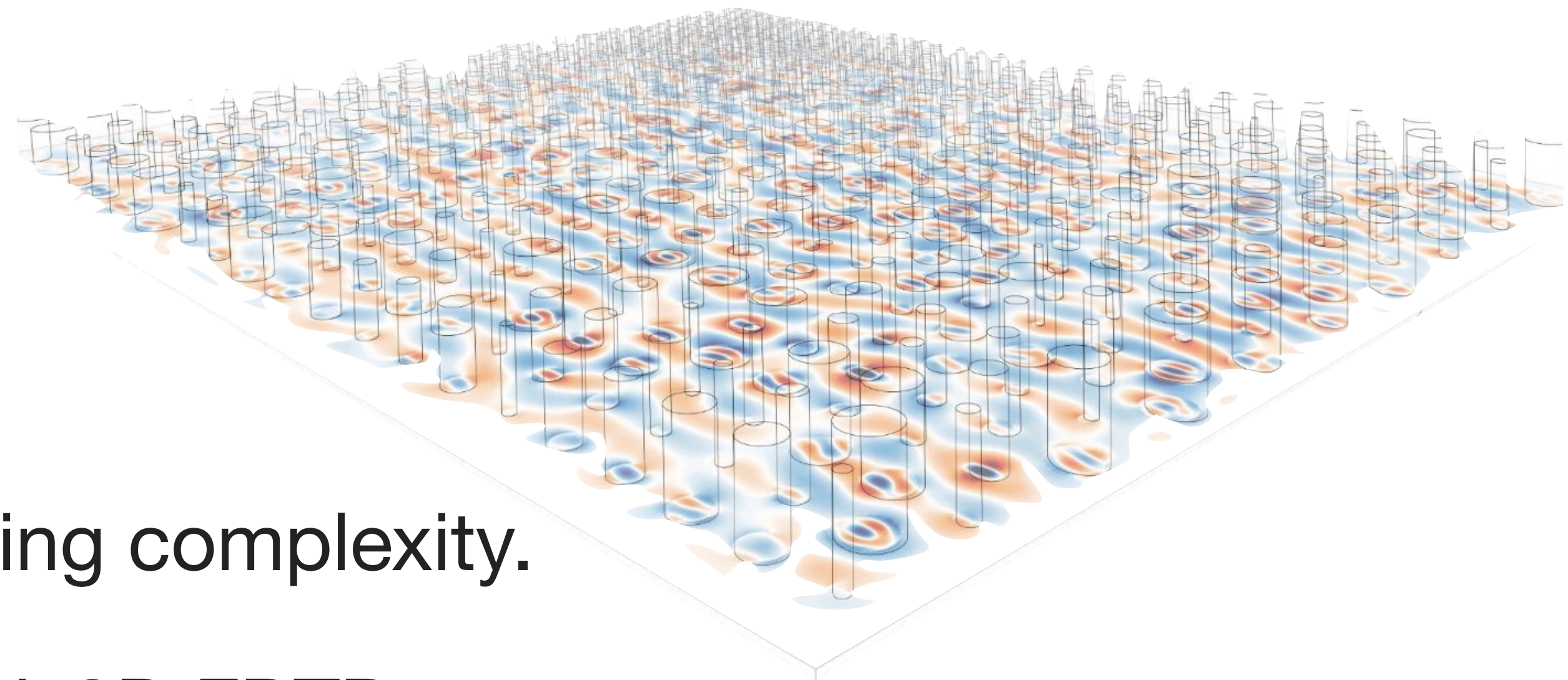


Metasurface



COURSE OVERVIEW

- ▶ This course will give you a broad understanding of FDTD.
 - ▶ What it is used for.
 - ▶ How it works (at a high level).
 - ▶ How to get started using it.
- ▶ The course will use examples in increasing complexity.
- ▶ Implementation using Flexcompute's Tidy3D FDTD solver will accompany examples so you can try them out yourself.



MAXWELL'S EQUATIONS

- In the absence of free charges, electromagnetic phenomena is described by:

$$\nabla \times \vec{E}(\vec{r}, t) = -\mu_0 \frac{\partial \vec{H}(\vec{r}, t)}{\partial t}$$

$\vec{E}(\vec{r}, t)$ and $\vec{H}(\vec{r}, t)$ are the electromagnetic fields, from which we can determine our quantities of interest.

$$\nabla \times \vec{H}(\vec{r}, t) = \epsilon(\vec{r})\epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t} + \vec{j}(\vec{r}, t)$$

$\epsilon(\vec{r})$ describes how the materials are arranged in space, which describe the device being simulated.

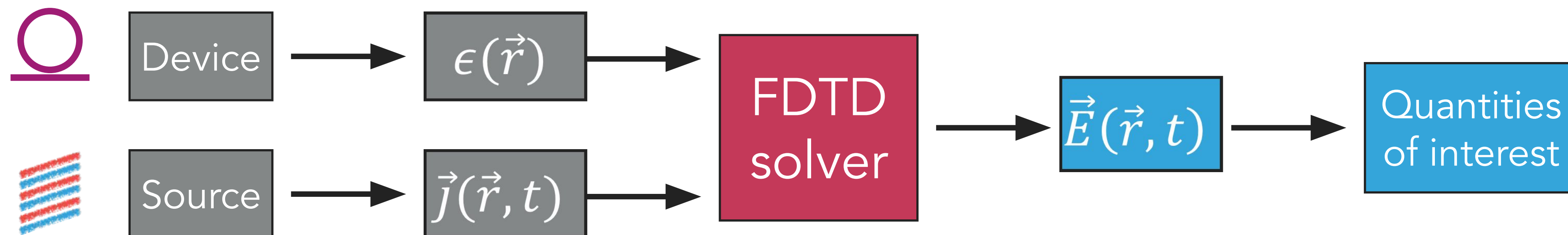
$\vec{j}(\vec{r}, t)$ describes electric currents (moving charges), which inject light into the system.

SOLVING MAXWELL'S EQUATIONS

- ▶ Goal of FDTD is to solve these equations for $\vec{E}(\vec{r}, t)$ and $\vec{H}(\vec{r}, t)$ given $\epsilon(\vec{r})$ and $\vec{j}(\vec{r}, t)$.

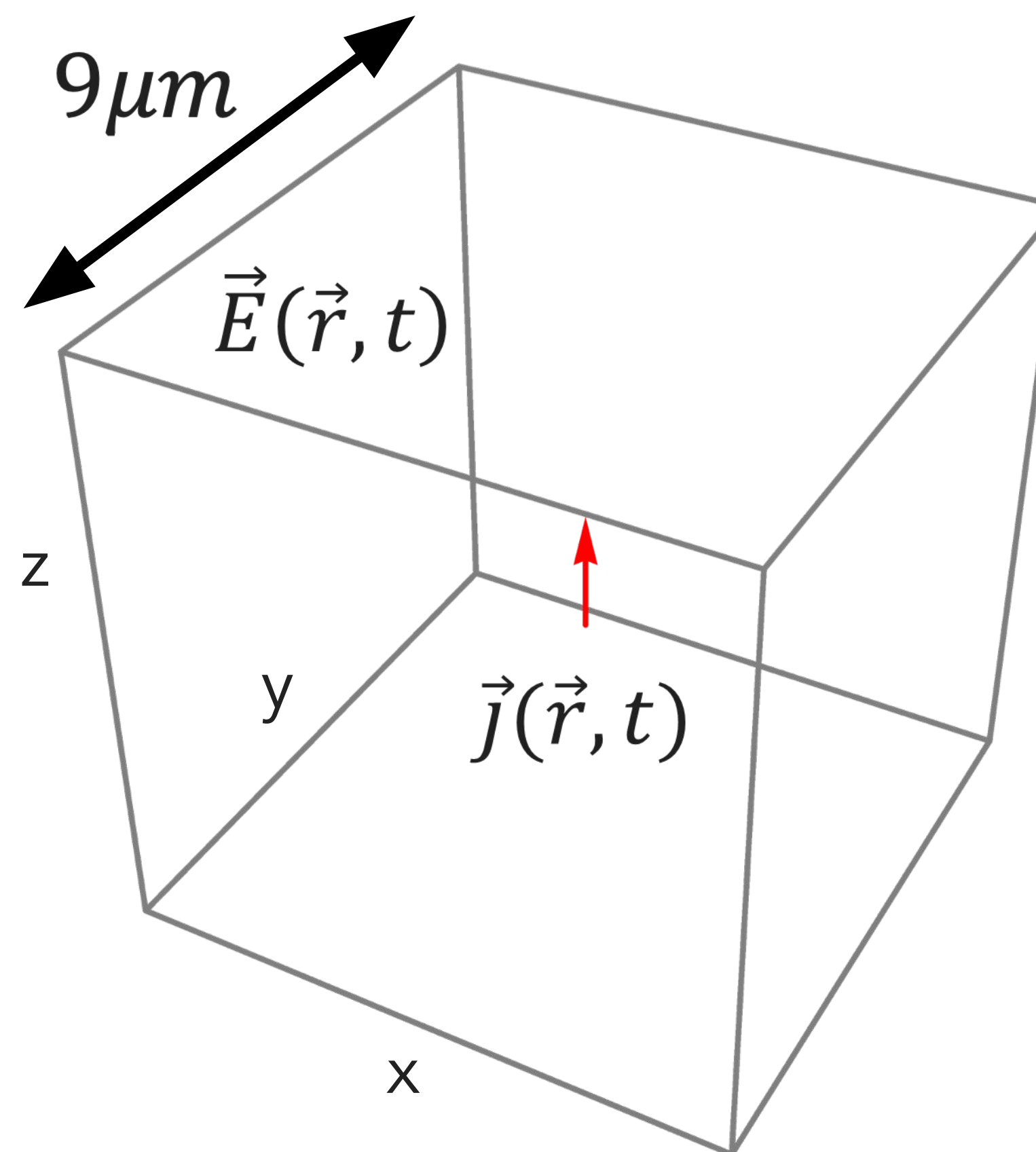
$$\nabla \times \vec{E}(\vec{r}, t) = -\mu_0 \frac{d\vec{H}(\vec{r}, t)}{dt} \quad \nabla \times \vec{H}(\vec{r}, t) = \epsilon(\vec{r})\epsilon_0 \frac{d\vec{E}(\vec{r}, t)}{dt} + \vec{j}(\vec{r}, t)$$

- ▶ Given some device $\epsilon(\vec{r})$ and an incident field or current source $\vec{j}(\vec{r}, t)$.

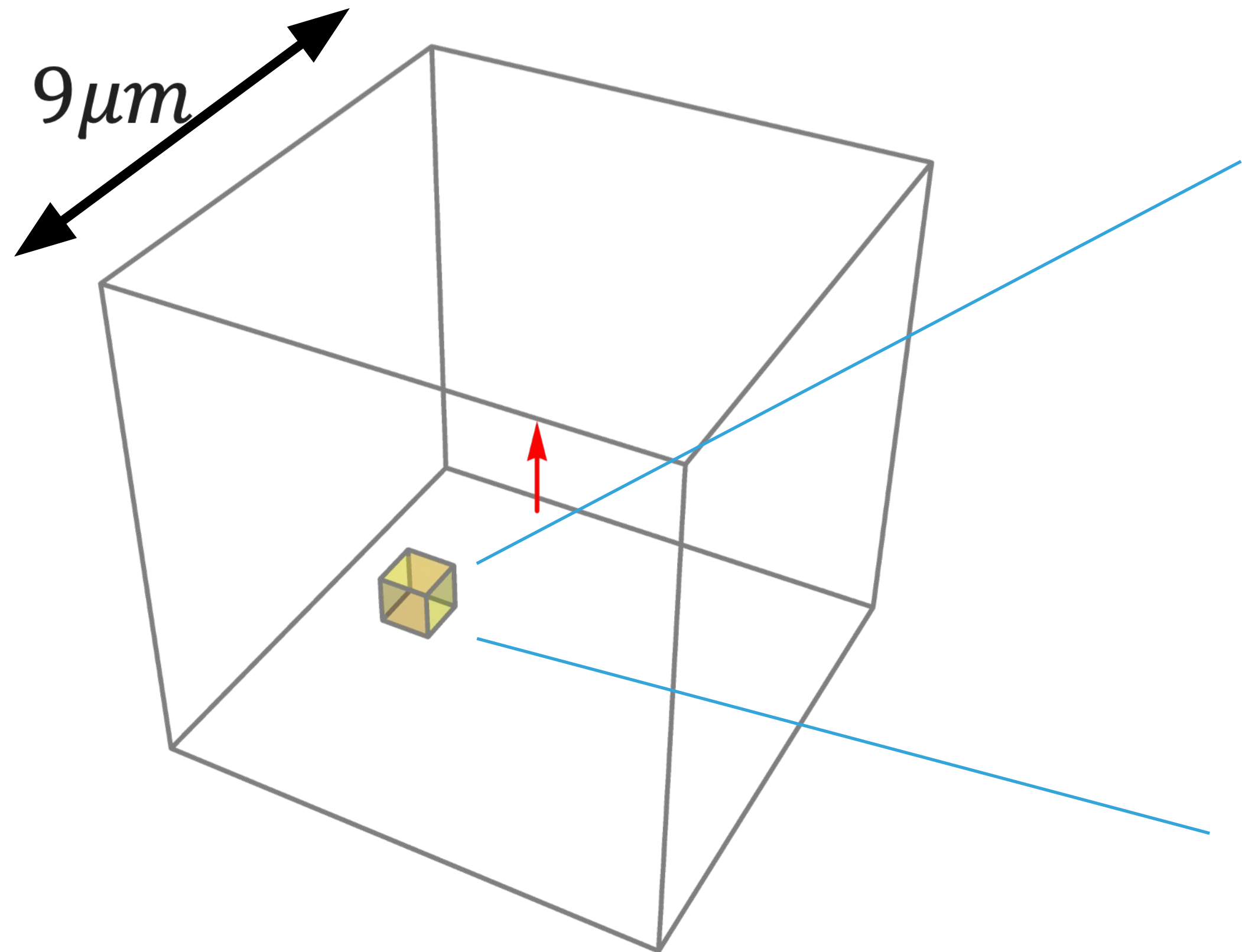


EXAMPLE: DIPOLE IN A VACUUM

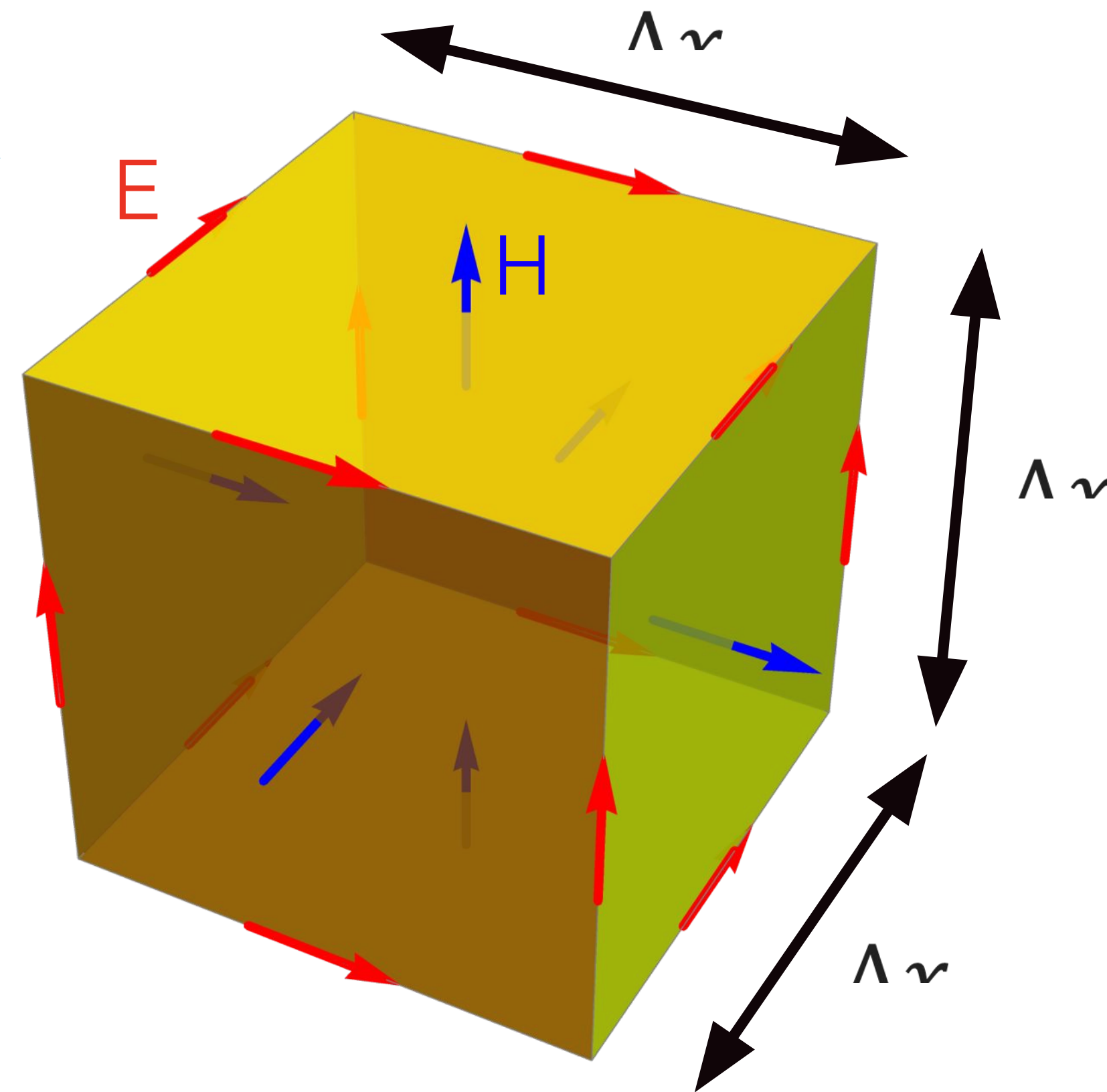
- ▶ Goal: compute $\vec{E}(\vec{r}, t)$ emanating from the source.
- ▶ Let's simulate the following setup:
 - ▶ Only vacuum ($\epsilon(\vec{r}) = 1$).
 - ▶ Dipole source pointing in z direction.
 - ▶ $\vec{j}(\vec{r}, t) \propto \cos\omega t$.
 - ▶ Wavelength $\lambda = 2\pi c/\omega = 1\mu m$.



DISCRETIZATION



Yee Cell

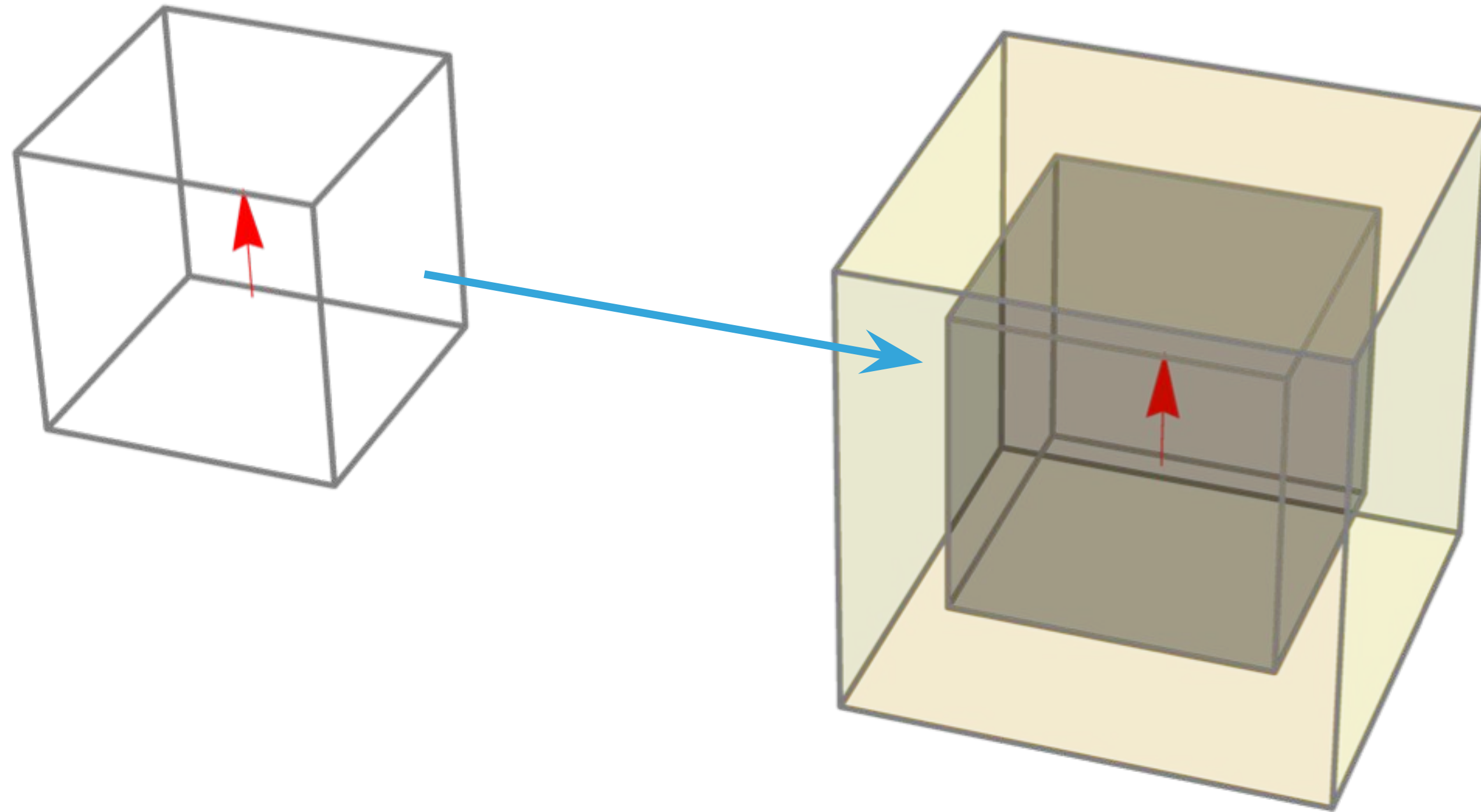


Typical Choice: $\Delta x = \lambda/20 = 50nm$

Here: $\Delta x = \lambda/50 = 20nm$

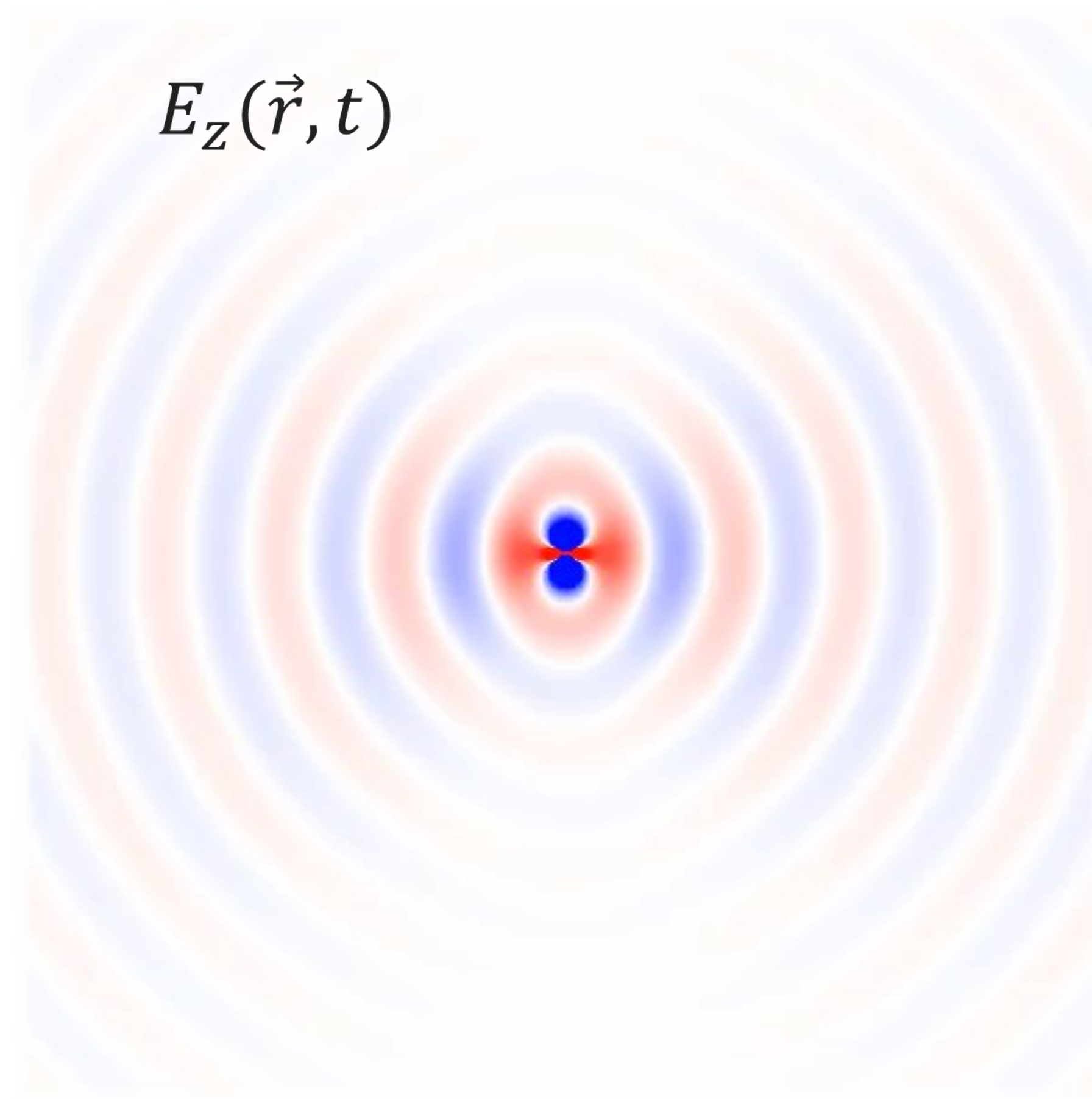
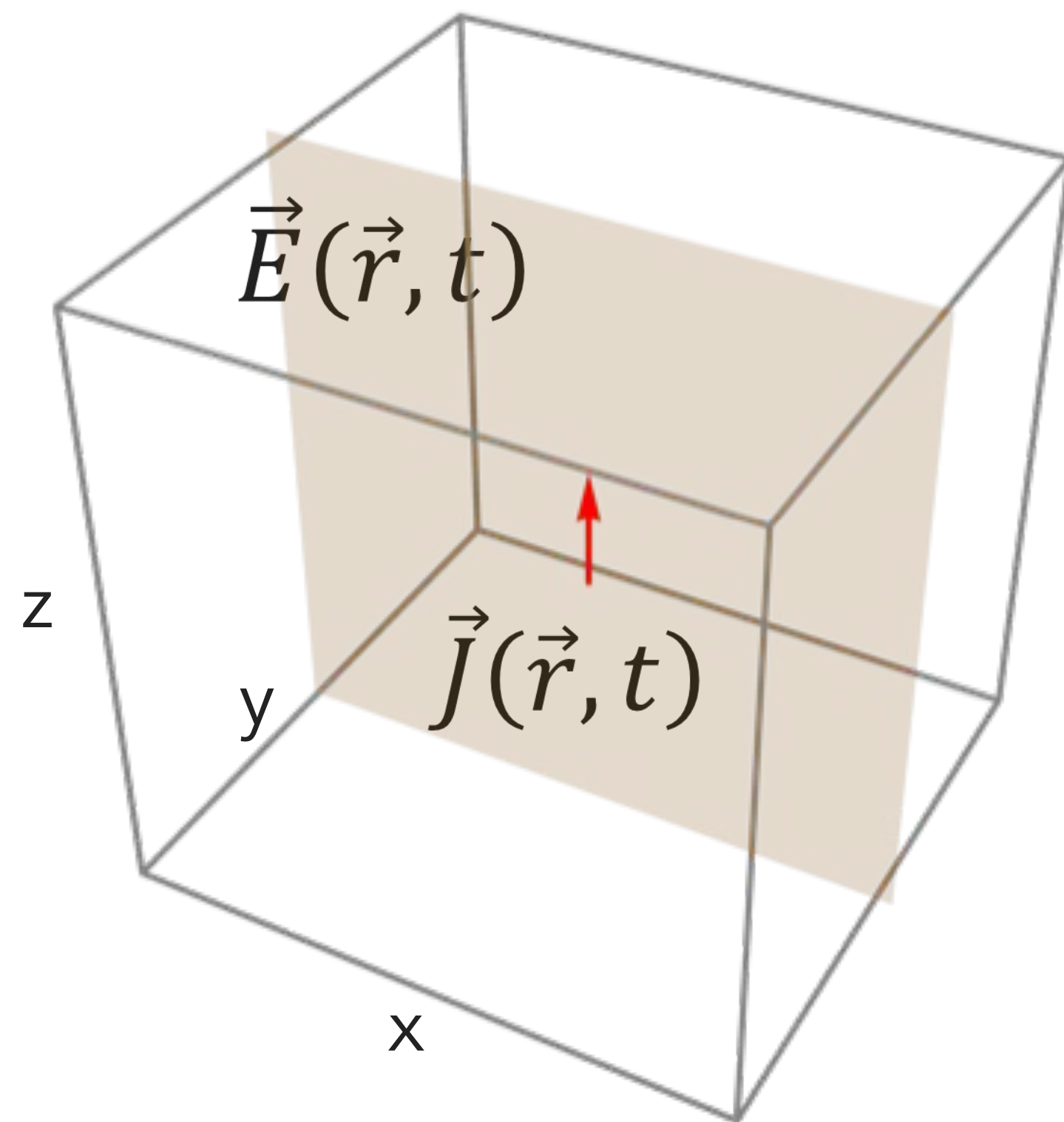
About half a billion unknowns.

BOUNDARY CONDITIONS



Computational domain surrounded by Perfectly Matched Layers (PML), with a thickness of typically 10's Yee cells

VACUUM



COMPLEX STRUCTURES

