## Linux SDK 使用

# ı. 官网下载 linux SDK

https://www.huatengvision.com/download/1/

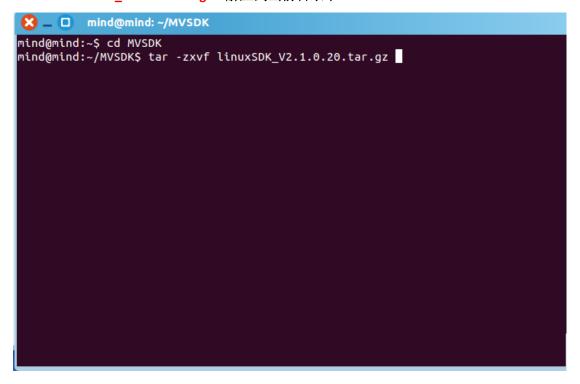
开启虚拟机,创建文件夹 MVSDK,将 linuxSDK 包拷贝到目录下

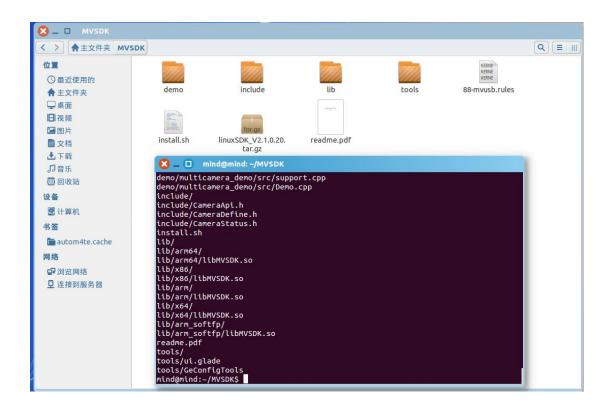


打开终端

输入 cd MVSDK 进入 MVSDK 目录

tar -zxvf linuxSDK\_V2.1.0.20.tar.gz 解压到当前目录下





#### 执行脚本,将库和头文件拷贝到系统目录下 sudo ./install.sh

```
mind@mind:~/MVSDK$ sudo ./install.sh

Your current directory is /home/mind/MVSDK. This is where the MVSDK software wil

l be installed...

Copy header files

Copy x64/libMVSDK.so to /lib

Successful

Please restart system now!!!

mind@mind:~/MVSDK$
```

#### 如果安装脚本失效,可以手动拷贝库和头文件完成安装

#拷贝头文件

sudo cp MVSDK/include/\* /usr/include/

#### #拷贝对应平台库

x86 64 位系统: sudo cp MVSDK/lib/x64/libMVSDK.so /lib

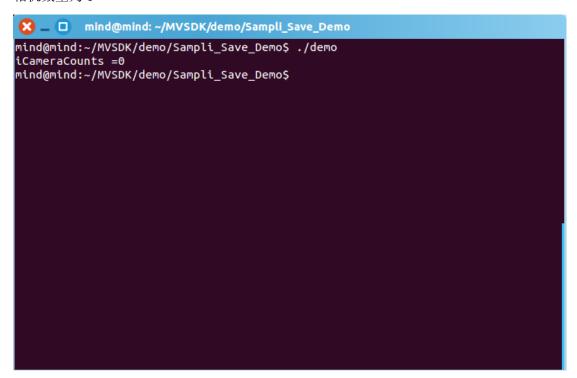
arm 32 硬浮点系统: sudo cp MVSDK/lib/arm/libMVSDK.so /lib

arm 32 软浮点系统: sudo cp MVSDK/lib/arm\_softfp/libMVSDK.so /lib

arm 64 位系统: sudo cp MVSDK/lib/arm64/libMVSDK.so /lib

### 2. 运行 Demo 出现找不到相机情况

相机数量为0



#### 1. 网口

- 1. 关闭防火墙 sudo ufw disable
- 2. 配置 linux 电脑网卡 IP 为固定 IP
- 3. 编辑/etc/sysctl.d/10-network-security.conf 文件,将 rp\_filter 赋为 0,如下: #Turn on Source Address Verification in all interfaces to # prevent some spoofing attacks. net.ipv4.conf.default.rp\_filter=0 net.ipv4.conf.all.rp\_filter=0 重启电脑生效

#### 2. USB

- 1. Lsusb 查看是否加载驱动成功 f622:da01 f622 开头代表迈德威视相机加载驱动成功
- 2. sudo 运行
- 3. 尝试更换其他 USB 口
- 4. 虚拟机, 使用 USB3.0 相机时, USB 控制器设置 USB3.0 模式

### 3. 打开相机常见错误

返回-13,相机已经被打开,或者是网卡 IP 和相机 IP 不在同一网段。尝试修改相机 IP,详见相机 IP 配置。

```
/mind/.config/gtk-2.0/gtkfilechooser.ini": Permission denied
(GTK_demo:4108): Gtk-WARNING **: Failed to read filechooser settings from "/home
/mind/.config/gtk-2.0/gtkfilechooser.ini": Permission denied
(GTK_demo:4108): Gtk-WARNING **: Failed to read filechooser settings from "/home
/mind/.config/gtk-2.0/gtkfilechooser.ini": Permission denied
(GTK_demo:4108): Gtk-WARNING **: Failed to read filechooser settings from "/home
/mind/.config/gtk-2.0/gtkfilechooser.ini": Permission denied
(GTK_demo:4108): Gtk-WARNING **: Failed to read filechooser settings from "/home
/mind/.config/gtk-2.0/gtkfilechooser.ini": Permission denied
(GTK_demo:4108): Gtk-WARNING **: Failed to read filechooser settings from "/home
/mind/.config/gtk-2.0/gtkfilechooser.ini": Permission denied
iCameraCounts =2
num =0 MV-GE502M-T
num =1 MV-GE500M-IT MV-GE500M-IT#1
input 0-1:0
E0105 17:13:09.565629 4108 MVCAMAPI.cpp:342] CameraInit Failed, err:-13,Version
:2.1.0.20,FriendlyName:1,SN:057030319999
CameraInit Failed: -13
mind@mind:~/MVSDK/demo/GTK_Demo$
```

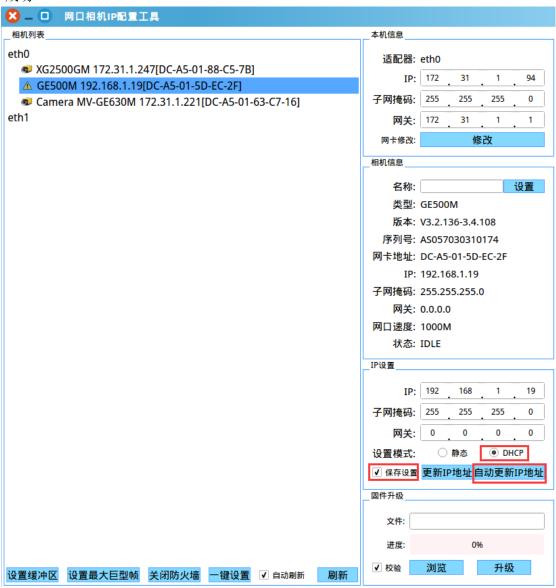
## 4. 相机 IP 配置

### 1. QT 工具修改 IP(仅支持 x64)

工具路径: tools/QGeConfigTools/QGeConfigTools

### 1. 自动更新 IP

选择要修改的相机,选择 DHCP 模式,勾选保存配置,点击自动更新 IP 地址按钮,修改 IP 成功



※ ■ □ 网口相机IP配置工具	
相机列表	本机信息
eth0	
© XG2500GM 172.31.1.247[DC-A5-01-88-C5-7B]	适配器:
© Camera MV-GE630M 172.31.1.221[DC-A5-01-63-C7-16]	IP:
© GE500M 172.31.1.181[DC-A5-01-5D-EC-2F]	子网掩码:
eth1	网关:
	网卡修改: 修改
	M-LISCX IISCX
	相机信息
	名称: 设置
	类型:
	版本:
	序列号:
	网卡地址:
₩ 成功	IP:
i IP设置成功.	子网掩码:
3	网关:
<u>о</u> к	网口速度:
	状态:
	IP设置
	IP:
	子网掩码:
	网关:
	设置模式: ○ 静态 ● DHCP
	▼ 保存设置 更新IP地址 自动更新IP地址
	固件升级
	文件:
	进度: 0%
设置缓冲区 设置最大巨型帧 关闭防火墙 一键设置 ✓ 自动刷新 刷新	▼ 校验 浏览 升级

### 2. 手动更新 IP

如果需要修改成特定 IP,选择静态模式,输入 IP 地址,子网掩码,网关,勾选保存配置,点击更新 IP 地址按钮,修改 IP 成功





### 2. 命令行工具修改 IP(支持 x86、x64、arm、arm64)

#### 工具路径:

x86: tools/GeConfigCmd/x86/GeConfigCmd
 x64: tools/GeConfigCmd/x64/GeConfigCmd
 arm: tools/GeConfigCmd/arm/GeConfigCmd
 arm64: tools/GeConfigCmd/arm64/GeConfigCmd

#### 运行工具,输入r自动修改 IP

./GeConfigCmd

```
🗙 💶 🔲 mind@mind: ~/GeConfigCmd
mind@mind:~/GeConfigCmd$ ./GeConfigCmd
eth0, 172.31.1.155, 255.255.255.0, 0-c-29-18-1f-6e
1 cameras found.
DevName:
ModelName: GE500M
ip: 172.31.1.235
net_mask: 255.255.255.0
gateway: 172.31.1.1
mac: DC-A5-01-5D-EC-2F
serial_number: AS057030310174
linkspeed: 1000M
access: IDLE
IP Valid: true
p(Print Camera List) r(Repair All Cameras) m(Manual Repair Cameras) q(Quit) Inpu
t:r
eth0, 172.31.1.155, 255.255.255.0, 0-c-29-18-1f-6e
Repair 1 Cameras
p(Print Camera List) r(Repair All Cameras) m(Manual Repair Cameras) q(Quit) Inpu
```

### 3.编译 GTK\_Demo

#### 1. 安装 GTK 库

安装 GTK 库,清理项目,make 编译,./Gtk\_Demo 运行,输入 0 打开第 1 个相机 sudo apt-get install libgtk2.0-dev

cd MVSDK/demo/GTK\_Demo #进入目录 make clean #清理项目 make #编译 GTKdemo

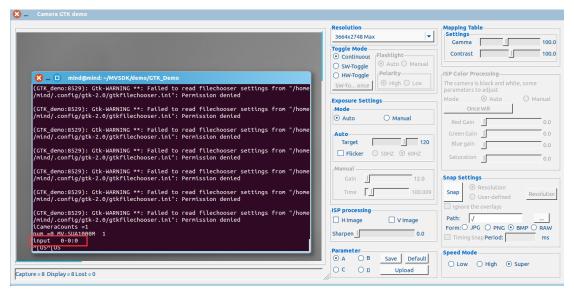
```
mind@mind: ~/MVSDK/demo/GTK_Demo
mind@mind:~/MVSDK/demo/GTK_Demo$ sudo apt-get install libgtk-3-dev
Reading package lists... Done
Building dependency tree
Reading state information... Done
The following packages were automatically installed and are no longer required:
  account-plugin-windows-live gtk3-engines-unico libntdb1 libqpdf13
 libupstart1 python-ntdb
Use 'apt-get autoremove' to remove them.
Suggested packages:
 libgtk-3-doc
The following NEW packages will be installed:
 libgtk-3-dev
O upgraded, 1 newly installed, O to remove and 212 not upgraded.
Need to get 0 B/807 kB of archives.
After this operation, 9859 kB of additional disk space will be used.
WARNING: The following packages cannot be authenticated!
 libgtk-3-dev
Install these packages without verification? [y/N] y
Selecting previously unselected package libgtk-3-dev.
(Reading database ... 216235 files and directories currently installed.)
Preparing to unpack .../libgtk-3-dev_3.10.8-0ubuntu1.6_amd64.deb ...
Unpacking libgtk-3-dev (3.10.8-0ubuntu1.6) ...
Setting up libgtk-3-dev (3.10.8-0ubuntu1.6) ...
mind@mind:~/MVSDK/demo/GTK_Demo$
```

```
Mind@mind: ~/MVSDK/demo/GTK_Demo
size [-Wint-to-pointer-cast]
 ECT(radio_speed[i]), "released", G_CALLBACK(on_radio_speed_clicked), (gpointer)i);
/usr/include/glib-2.0/gobject/gsignal.h:472:73: note: in definition of macro 'g_
signal_connect'
 g_signal_connect_data ((instance), (detailed_signal), (c_handler), (data), NULL
mv -f .deps/interface.Tpo .deps/interface.Po
g++ -DHAVE_CONFIG_H -I. -I./inc  -I../../include -pthread -I/usr/include/gtk-2.
0 -I/usr/lib/x86_64-linux-gnu/gtk-2.0/include -I/usr/include/gio-unix-2.0/ -I/us
r/include/cairo -I/usr/include/pango-1.0 -I/usr/include/atk-1.0 -I/usr/include/c
airo -I/usr/include/pixman-1 -I/usr/include/libpng12 -I/usr/include/gdk-pixbuf-2
.0 -I/usr/include/libpng12 -I/usr/include/pango-1.0 -I/usr/include/harfbuzz -I/u
sr/include/pango-1.0 -I/usr/include/glib-2.0 -I/usr/lib/x86_64-linux-gnu/glib-2.
0/include -I/usr/include/freetype2 -g -O2 -MT support.o -MD -MP -MF .deps/su
pport.Tpo -c -o support.o `test -f './src/support.cpp' || echo './'`./src/suppor
t.cpp
mv -f .deps/support.Tpo .deps/support.Po
g++ -g -O2 -L/lib -o GTK_demo GTK_demo.o callbacks.o Demo.o interface.o suppor
t.o -lgtk-x11-2.0 -lgdk-x11-2.0 -lpangocairo-1.0 -latk-1.0 -lcairo -lgdk_pixbuf-
2.0 -lgio-2.0 -lpangoft2-1.0 -lpango-1.0 -lgobject-2.0 -lglib-2.0 -lfontconfig -
lfreetype -lpthread -lrt -lgthread-2.0 -lMVSDK -lpthread
make[1]: Leaving directory `/home/mind/MVSDK/demo/GTK_Demo'
mind@mind:~/MVSDK/demo/GTK_Demo$
```

无明显错误,可以直接执行 GTK DEMO

sudo ./GTK\_demo

选择第几个相机,默认按0开始输入0回车打开第1个相机



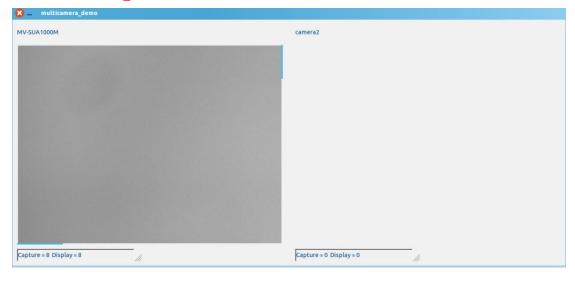
## 4. 编译 multicamera\_demo

清理项目,make 编译,运行程序,打开 2 个相机 cd MVSDK/demo/multicamera\_demo make clean make

```
mind@mind: ~/MVSDK/demo/multicamera_demo
                           from /usr/include/gtk-2.0/gdk/gdk.h:32,
                           from /usr/include/gtk-2.0/gtk/gtk.h:32,
from ./src/interface.cpp:2:
/usr/include/glib-2.0/glib/gmacros.h:229:0: note: this is the location of the pr
evious definition
 #define FALSE (0)
mv -f .deps/interface.Tpo .deps/interface.Po
g++ -DHAVE_CONFIG_H -I. -I./inc -I../../include -pthread -I/usr/include/gtk-2.
0 -I/usr/lib/x86_64-linux-gnu/gtk-2.0/include -I/usr/include/gio-unix-2.0/ -I/us
r/include/cairo -I/usr/include/pango-1.0 -I/usr/include/atk-1.0 -I/usr/include/c
airo -I/usr/include/pixman-1 -I/usr/include/libpng12 -I/usr/include/gdk-pixbuf-2
.0 -I/usr/include/libpng12 -I/usr/include/pango-1.0 -I/usr/include/harfbuzz -I/u
sr/include/pango-1.0 -I/usr/include/glib-2.0 -I/usr/lib/x86_64-linux-gnu/glib-2.
0/include -I/usr/include/freetype2 -g -02 -MT support.o -MD -MP -MF .deps/su
pport.Tpo -c -o support.o `test -f './src/support.cpp' || echo './'`./src/suppor
t.cpp
mv -f .deps/support.Tpo .deps/support.Po
g++ -g -02 -L/lib -o multicamera_demo multicamera_demo.o callbacks.o Demo.o in
terface.o support.o -lgtk-x11-2.0 -lgdk-x11-2.0 -lpangocairo-1.0 -latk-1.0 -lcai
ro -lgdk_pixbuf-2.0 -lgio-2.0 -lpangoft2-1.0 -lpango-1.0 -lgobject-2.0 -lglib-2.
0 -lfontconfig -lfreetype -lpthread -lrt -lgthread-2.0 -lMVSD
make[1]: Leaving directory `/home/mind/MVSDK/demo/multicamera_demo'
                                                                                              -lMVSDK -lpthread
mind@mind:~/MVSDK/demo/multicamera_demo$
```

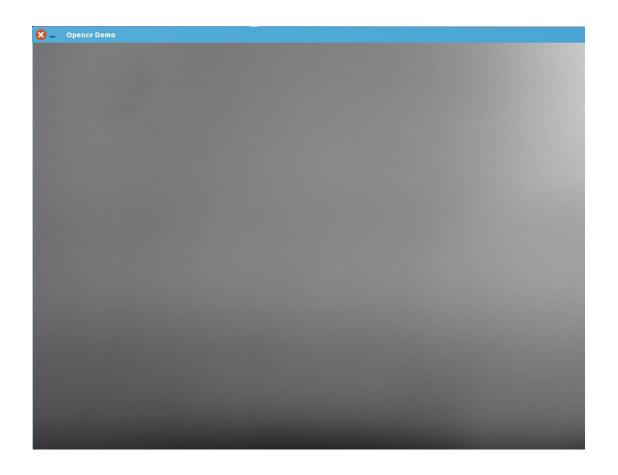
无明显错误,运行程序

sudo ./multicamera\_demo



## 5. 编译 OpenCv

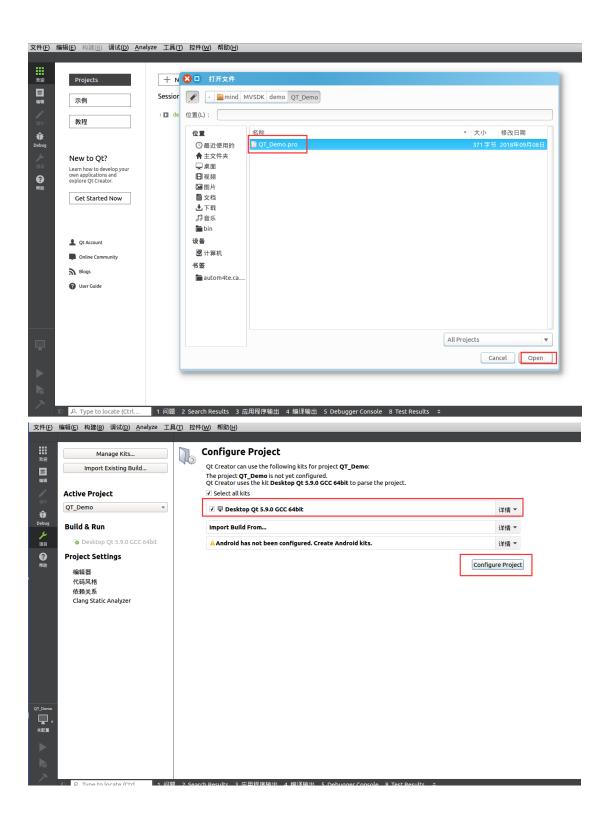
先安装 opency,或者官网下载源码,进行编译进入目录,编译,运行cd MVSDK/demo/OpenCvmakesudo./main #运行



# 6.编译 QT\_Demo4

### 1. 需要先安装 Qt

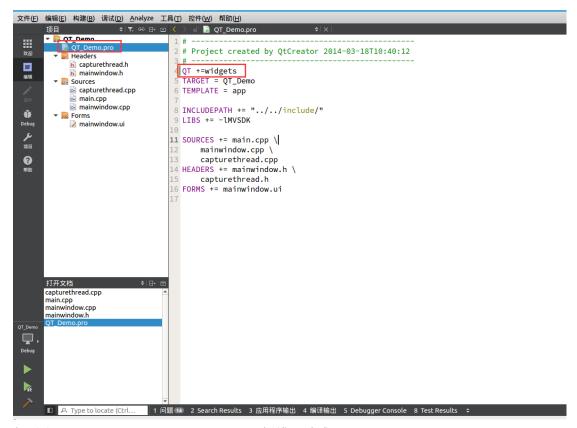
打开 Qt,打开项目,选择 pro 文件,打开,选择对应的构建器 (QT\_Demo4 改 QT5)



#### 开始构建

Pro 文件 添加 QT += widgets

INCLUDEPATH += .././include #修改 LIBS += -L/lib -IMVSDK #修改



如果出现 #include <QtGui/QApplication> 报错 改成#include <QApplication>

出现大量报错,添加头文件引用

mainwindow.h 头文件添加引用

#include <QLabel>

#include <QGraphicsScene>

#include <QGraphicsPixmapItem>

#include < QRadioButton>

#include <QDesktopWidget>

#include <QFileDialog>

#include <QTextCodec>

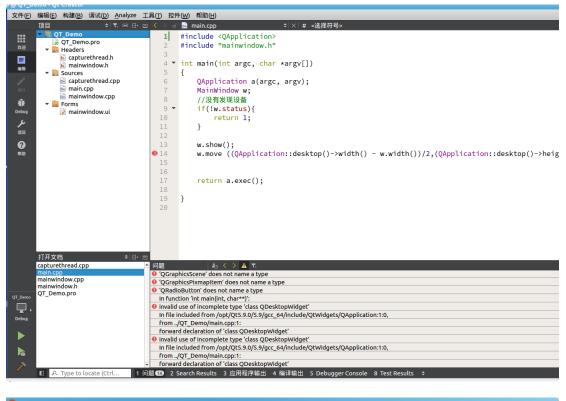
#include <QMessageBox>

QTextCodec::setCodecForCStrings(QTextCodec::codecForName("GB2312")); 删除

fileDialog->seFilterst(tr("config Files(\*.config )"));

改成

fileDialog->setNameFilters(QStringList()<<tr("config Files(\*.config )"));</pre>

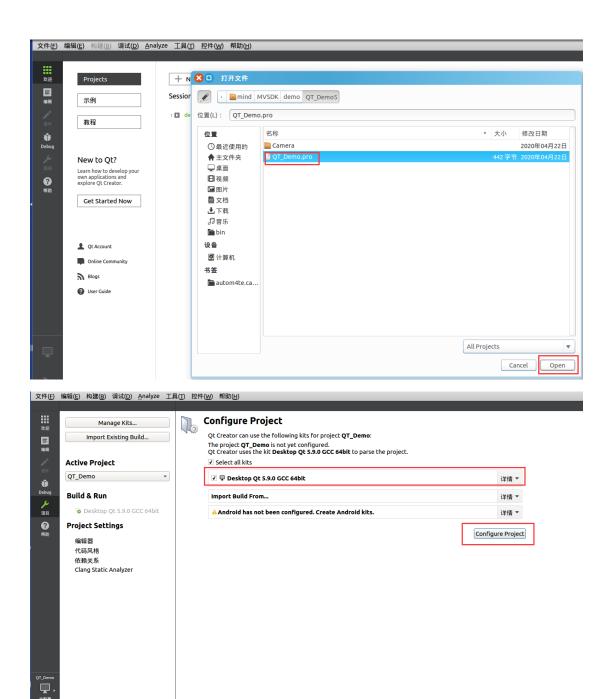




# 7. 编译 QT\_Demo5

### 1. 需要先安装 Qt

打开 Qt,打开项目,选择 pro 文件,打开,选择对应的构建器 编译运行,即可





# 8. 编译 Sampli\_Save\_Demo

进入目录,清理项目,make 编译./demo 运行, 输入 0,打开第 0 个相机,保存一张图像 cd MVSDK/demo/Sampli\_Save\_Demo

make clean make

sudo ./demo

```
mind@mind: ~/MVSDK/demo/Sampli_Save_Demo
make all-am
-g -O2 -MT main.o -MD -MP
-MF .deps/main.Tpo -c -o main.o main.cpp
main.cpp: In function 'int main()':
main.cpp:51:22: warning: ignoring return value of 'int scanf(const char*, ...)'
  declared with attribute warn_unused_result [-Wunused-result]
    scanf("%d", &num);
mv -f .deps/main.Tpo .deps/main.Po
-lMVSDK -lrt -lpthread -lpthread
mind@mind:~/MVSDK/demo/Sampli_Save_Demo$ ./demo
icameracounts =z
num =0 MV-SUA1000M 1
num =1 MV-GE500M-IT MV-GE500M-IT#0
input 0-1:0
you input num 0
.
CameraInit iStatus =0
CameraGetCapability
CameraPlay
CameraSetIspOutFormat
mind@mind:~/MVSDK/demo/Sampli_Save_Demo$
```

