

## SR

In each step, SR solves the following linear system:

$$(J^\dagger J)\Delta\Theta = J^\dagger E_{\text{loc}}$$

with  $n_s \times n_p$  matrix  $J$  and  $n_s \times 1$  matrix  $E_{\text{loc}}$ .

### SR with pivoted QR

Decompose  $J$  as  $J\Pi = QR$  where  $\Pi$  is an  $n_p \times n_p$  permutation matrix,  $Q^\dagger Q = I$  and  $R$  is upper-trapezoidal. Assume  $J$  is rank-deficient with rank  $r \leq n$ ,  $R$  has a block structure:

$$R = \begin{pmatrix} R_{11} & R_{12} \\ 0 & 0 \end{pmatrix}$$

where  $R_{11}$  is a  $r \times r$  upper-triangular invertible matrix and  $R_{12}$  is a  $r \times (n_p - r)$  matrix.

Then

$$\begin{aligned} (J^\dagger J)\Delta\Theta &= J^\dagger E_{\text{loc}} \\ \Leftrightarrow R^\dagger R\Pi^T \Delta\Theta &= R^\dagger Q^\dagger E_{\text{loc}} \end{aligned}$$

which is the normal equation for the least squares problem  $\min_{\Delta\Theta} \|R\Pi^T \Delta\Theta - Q^\dagger E_{\text{loc}}\|_2^2$ .

For clarity, let  $x \equiv \Pi^T \Delta\Theta$  and  $y \equiv Q^\dagger E_{\text{loc}}$ , the squared 2-norm reads

$$\begin{aligned} &\|Rx - y\|_2^2 \\ &= \left\| \begin{pmatrix} R_{11} & R_{12} \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} - \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \right\|_2^2 \\ &= \left\| \begin{pmatrix} R_{11}x_1 + R_{12}x_2 - y_1 \\ -y_2 \end{pmatrix} \right\|_2^2 \\ &= \|R_{11}x_1 + R_{12}x_2 - y_1\|_2^2 + \|y_2\|_2^2 \end{aligned}$$

Since  $R_{11}$  is invertible, the first term could be zeroed by choosing  $x_1 = R_{11}^{-1}(y_1 - R_{12}x_2)$ . Note that  $R_{11}$  is upper triangular, so this can be efficiently calculated by backward-substitution.

### Naive

Choose  $x_2 = \vec{0}$ , then  $x_1 = R_{11}^{-1}y_1$ .

$$\Delta\Theta = \Pi \begin{pmatrix} R_{11}^{-1}y_1 \\ 0 \end{pmatrix}$$

In this case, most of the parameters remain unchanged, only a few parameters are updated.

Note that this choice does not necessarily minimize the norm of  $x$  and is just one solution of the underdetermined system.

### Least squares

If we take into account the norm of  $x$ , the problem is reduced to a full-rank least squares problem for  $x_2$ :

$$\begin{aligned}
& \min_{x_2} \|x\|_2^2 \\
\Leftrightarrow & \min_{x_2} \|R_{11}^{-1}(y_1 - R_{12}x_2)\|_2^2 + \|x_2\|_2^2 \\
\Leftrightarrow & \min_{x_2} \left\| \begin{pmatrix} R_{11}^{-1}R_{12} \\ I \end{pmatrix} x_2 - \begin{pmatrix} R_{11}^{-1}y_1 \\ 0 \end{pmatrix} \right\|_2^2
\end{aligned}$$

Since  $\begin{pmatrix} R_{11}^{-1}R_{12} \\ I \end{pmatrix}$  has full column rank, the system is well-posed:

$$\begin{aligned}
x_2^* &= \left( \begin{pmatrix} R_{11}^{-1}R_{12} \\ I \end{pmatrix} \right)^{-1} \begin{pmatrix} R_{11}^{-1}y_1 \\ 0 \end{pmatrix} \\
\Delta\Theta &= \Pi \begin{pmatrix} R_{11}^{-1}(y_1 - R_{12}x_2^*) \\ x_2^* \end{pmatrix}
\end{aligned}$$

### MinSR

Note that

$$(J^\dagger J)^{-1} J^\dagger = J^\dagger (J J^\dagger)^{-1}$$

where LHS is the left pseudo-inverse of  $J$  and RHS is the right pseudo-inverse of  $J$ , one have

$$\Delta\Theta = J^\dagger (J J^\dagger)^{-1} E_{\text{loc}}$$

which only requires the pseudo-inverse of a  $n_s \times n_s$  matrix  $J J^\dagger$ .