Functional Programming & Constraint Programming

Flip Lijnzaad and Jasper Stammes

Friday 4th February, 2022

Abstract

This is where the abstract should go

Contents

1	Constraint satisfaction problems	2
2	Arc consistency	2
3	The AC-3 algorithm	3
4	Sudokus	4
5	Conclusion	7
	5.1 Further improvements and research	7
\mathbf{A}	Appendix: Python script for sudoku generation	8
Bi	ibliography	10

1 Constraint satisfaction problems

A constraint satisfaction problem (CSP) is a triple $\langle X, D, C \rangle$ where

- X is a set of variables $\{x_1, \ldots, x_n\}$;
- D is a set of domains $\{D_1,\ldots,D_n\}$. Each domain is a set of values for a variable;
- C is a set of constraints on the domains of the variables.

A constraint is a pair $\langle scope, relation \rangle$, where the scope is a tuple of the variables that participate in the constraint, and the relation is a set of tuples determining the allowed combinations of values for the variables in the scope.

Any constraint with a finite scope can be reduced to a set of binary constraints [RN09, p. 206]; this greatly simplifies the representation of constraints. We call the scope of a binary constraint an *arc*.

In our Haskell implementation of CSPs, we define types and newtypes for variables, values, domains, arcs, constraints and CSPs. In the formal definition of a CSP, which domains correspond to which variables is indicated by their subscripted indices matching. In our implementation, we chose to represent a domain as a tuple of the variable it pertains to, together with the list of possible values, e.g. $\langle x_1, D_1 \rangle$. Since then the set of domains already contains the variables as well, there is no need for including the set of variables in the definition of a CSP. Therefore, in our implementation a CSP is just the pair $\langle D, C \rangle$.

```
{-# LANGUAGE
 GeneralizedNewtypeDeriving
# - }
module CSP where
newtype Variable = Var { getVar :: Int } deriving (Eq, Ord, Num)
instance Show Variable where
 show x = show (getVar x)
newtype Value
                = Val { getVal :: Int } deriving (Eq, Ord, Num)
instance Show Value where
 show x = show (getVal x)
                = (Variable, [Value])
type Domain
                 = (Variable, Variable)
type Arc
type Constraint
                = ( Arc, [(Value, Value)] )
                                    :: [Domain]
data Problem
                 = CSP { domains
                       , constraints :: [Constraint] } deriving Show
```

2 Arc consistency

A variable in a CSP is arc-consistent if every value in its domain satisfies the variable's binary constraints. A CSP is arc-consistent if every variable in it is arc-consistent with every other variable. Arc consistency is a desirable property of a CSP, since it restricts and thus minimizes the domains of the CSP's variables. An arc-consistent CSP is not necessarily a solved CSP; a CSP is solved if all constraints are satisfied by any combination of values the variables can take

on. A CSP does not have a solution if one variable has an empty domain (i.e. no possible values it can take on).

The AC-3 algorithm reduces a CSP to its arc-consistent version. The algorithm return true if such an arc-consistent version exists, and it returns false if at any point a variable has an empty domain, i.e. the CSP has no solution.

3 The AC-3 algorithm

This functional implementation of the AC-3 algorithm is based on the imperative pseudocode in [RN09, p. 209].

The implementation makes use of the auxiliary function <code>getVarDomain</code>. When given a variable and a list of domains, it returns the domain of that variable. It performs <code>lookup</code> on the list of domains and returns not only the second argument of the relevant tuple (which is a list of values), but the whole tuple (the whole domain). Moreover, it uses <code>fromJust</code> to strip the domain of its <code>Just</code>. Generally, this is not safe to do, but in this implementation we are certain that the <code>lookup</code> will never return <code>Nothing</code>: the use of <code>getVarDomain</code> is restricted to cases where we are certain that the variable to look up is actually present in the list.

```
module AC3 where

import CSP
import Data.List
import Data.Maybe -- for using "fromJust"

getVarDomain :: Variable -> [Domain] -> Domain
getVarDomain var doms = let dom = fromJust $ lookup var doms in (var, dom)
```

The ac3 function takes as input a tuple containing the full CSP, a Boolean flag and a queue of constraints. The Boolean flag is the true or false that the algorithm returns as described in Section 2. The queue of constraints more or less functions as a to-do list, containing the arcs of which the consistency needs to be checked still. When first calling the function, this queue contains all constraints of the CSP; when the queue of constraints is empty, the CSP is arc-consistent. If at any point during the recursion the Boolean flag is set to false, this means that the domain of a variable is empty and the CSP has no solution. In this case, there is no point in continuing the recursion, so it is halted.

```
ac3 :: (Problem, Bool, [Constraint]) -> (Problem, Bool, [Constraint])
ac3 (p, False, _) = (p, False, [])
ac3 (p, True, []) = (p, True, [])
```

In the recursive case, the first constraint $C = \langle \langle x, y \rangle, R \rangle$ in the constraint queue is considered. The arc $\langle x, y \rangle$ of C is then 'revised' based on this constraint: the domain of x is restricted to those values that satisfy the constraint C. More specifically, the new domain for x, newXDomain, is such that those $x' \in D_x$ are kept for which $\exists y' \in D_y$ such that $\langle x', y' \rangle \in R$.

If this revision did not change the domain of x (i.e., $\langle x, y \rangle$ was already arc-consistent), then the recursion continues with the CSP unchanged, with the flag still set to True (because no domains were changed) and with rest of the queue of constraints.

If the revision did change the domain of x, then this may cause changes in the domains of the 'neighbors' of x: the arcs of which x is the second argument. To propagate these changes, the neighbors of x are added to the queue (newQueue). The domain list is updated (newDoms) by deleting the old domain of x from it and adding the new domain of x to it. The new Boolean flag is whether or not x's new domain is empty.

```
ac3 (p@(CSP doms cons), True, ((x, y), rel):queue) =
  if getVarDomain x doms == newXDomain
    then ac3 (p, True, queue)
    else ac3 (CSP newDoms cons, not $ null $ snd newXDomain, newQueue)
  where
    newXDomain = ( x, [ x' | x' <- xvals, any (\y' -> (x', y') 'elem' rel) yvals ] ) where
    xvals = snd $ getVarDomain x doms
    yvals = snd $ getVarDomain y doms
    newDoms = newXDomain : delete (getVarDomain x doms) doms
    newQueue = queue ++ filter (\(arc, _) -> snd arc == x) cons
```

Since the ac3 function outputs a full CSP, it is useful for practical applications to have a wrapper function that calls ac3 and only outputs the list of domains. Moreover, it is useful to have this list be sorted, since during execution of the AC-3 algorithm, the list of domains has been scrambled.

```
ac3domain :: [Domain] -> [Constraint] -> [Domain]
ac3domain doms cons =
  if succeeded
  then
    sortBy (\(a,_) (b,_) -> compare a b) y
  else []
  where
    (CSP y _, succeeded, _) = ac3 (CSP doms cons, True, cons)
```

4 Sudokus

Sudokus are a well-known constraint satisfaction problem: each square of the 9×9 grid is constrained by the squares in the same row, the same column, and the same 3×3 block. In order to use the AC-3 algorithm on sudokus, the sudoku first needs to be represented as a constraint satisfaction problem (see Section 1). In order to do so, the variables, domains and constraints of the problem need to be specified.

Intermezzo: generating sudokus In order to later test our representation of a sudoku as a CSP and subsequently test our implementation of the AC-3 algorithm (and avoid having to type in sudokus manually), we needed a program that generates sudokus in plaintext. We found a Python script that does just this, and adapted it to fit our program; see Appendix A for its code and a short explanation of its workings.

```
module Sudoku where

import CSP
import AC3
import Data.Char -- for using "digitToInt"
import Data.Maybe -- for using "fromJust"
import Control.Monad -- for using "when"
```

Although a representation of a square as its coordinates within the grid is a natural one, our

definition of a CSP calls for a variable to be an integer. Therefore, we represent the 81 squares of the grid as numbers between 0 and 80, numbered from left to right from top to bottom. As we will see in a bit, for determining the constraints on a square it is useful to use the coordinate notation.

The domain of each empty square of a sudoku (which we represent in our input as 0) is $\{1, \ldots, 9\}$; the domain of a square filled with some x is $\{x\}$. Since a Domain in our CSP definition also consists of the variable's Int, the following code also computes the 'index' of the square as a number between 0 and 80.

Arguably the most interesting part now is how the constraints for each variable are generated. To be able to formulate the constraints in an intuitive way, the function varToCoords takes a variable and returns a tuple of its x- and y-coordinates within the 9×9 grid. varToCoords functions as a wrapper around the varGrid to eliminate some duplicate code.

```
varGrid :: [(Variable, (Int, Int))]
varGrid = zip (map Var [0..80]) [ (i,j) | i <- [0..8], j <- [0..8] ]
varToCoords :: Variable -> (Int, Int)
varToCoords n = fromJust $ lookup n varGrid
```

Now, the function genSudokuCons takes the list of all variables of the sudoku, and returns the list of constraints for the sudoku. It creates this list of constraints by working through the list of variables one by one and generating all constraints for each variable. As said before, each square on the grid is constrained by its row, column and 3×3 block. So a variable n is a member of all arcs $\langle n, x \rangle$ where x is a variable in the same row, column or block. The allowable values for the pair $\langle n, x \rangle$ are then all $y_1, y_2 \in \{1, \dots, 9\}$ such that $y_1 \neq y_2$.

```
genSudokuCons :: [Variable] -> [Constraint]
genSudokuCons [] = []
genSudokuCons (n:xs) =
   map (\x -> ( (n,x), [(y1,y2) | y1 <- map Val [1..9], y2 <- map Val [1..9], y1 /= y2] ) )</pre>
```

The row, column and block constraints are dependent on the position of the variable n within the grid. The following code fragment determines the variables x with which n is participating in a constraint. The variables in the same row as n have the same x-coordinate, and the variables in the same column as n have the same y-coordinate. To obtain the variables in the same 3×3 block as n, we check if the x-coordinates of n and m are the same when divided by 3; we do the same for the y-coordinates.

The list comprehension contains the Boolean condition $m \neq n$ to ensure that there will not be an arc $\langle n, n \rangle$ in the constraints, since there will be no assignment that satisfies the constraint $n \neq n$. Moreover, the list comprehension for the block constraints ensures that variables in the same row or column are ignored, since those have already been taken into account.

The printSudoku function takes the list of Domains of a sudoku and prints the (partially) solved sudoku in a readable format using spaces and newlines. If the list of possible values for a variable only contains one element, this element may be printed; if it does not, then the value of that variable is as of yet undetermined and an underscore is printed to indicate this.

Now the function ac3SudokuFromFile ties this all together: when called it reads in a sudoku, applies the AC-3 algorithm and prints the result.

The code that generates an unsolved sudoku (see Appendix A) writes a string of digits to the file sudoku/sudoku.txt. These digits are in the same order as the squares are numbered with variables. This input is converted to a list of Vals, and ac3domain is called using the functions for generating domains and constraints for this particular sudoku. If the sudoku has a solution¹, the result is printed with printSudoku; if not (if the domain returned by ac3domain is empty), a message on the screen will indicate this fact.

```
ac3SudokuFromFile :: IO ()
ac3SudokuFromFile = do
sudokuString <- readFile "sudoku/sudoku.txt"
let values = map (Val . digitToInt) sudokuString
do
let sudoku = ac3domain (genSudokuDoms values) (genSudokuCons (map Var [0..80]))
if not $ null sudoku
then printSudoku sudoku
else putStrLn "This sudoku has no solution."
```

¹which a sudoku produced by the Appendix A code always will have

5 Conclusion

5.1 Further improvements and research

The double constraints could be eliminated from the sudoku CSP definition by using unordered pairs

A Appendix: Python script for sudoku generation

The following code is an adaptation of code to be found here; we deleted its GUI-related code, improved its formatting, and added some lines at the end so the output of the program was in a usable format for us and is written to a file.

The code generates a finished sudoku, removes some numbers from it and then ensures that the resulting unfinished sudoku has exactly 1 solution.

```
# Sudoku Generator Algorithm - www.101computing.net/sudoku-generator-algorithm/
from random import randint, shuffle
import os
# initialise empty 9 by 9 grid
grid = []
grid.append([0, 0, 0, 0, 0, 0, 0, 0])
grid.append([0, 0, 0, 0, 0, 0, 0, 0, 0])
grid.append([0, 0, 0, 0, 0, 0, 0, 0, 0])
# A function to check if the grid is full
def checkGrid(grid):
 for row in range(0, 9):
   for col in range(0, 9):
      if grid[row][col] == 0:
        return False
 #We have a complete grid!
 return True
# A backtracking/recursive function to check all possible combinations of
# numbers until a solution is found
def solveGrid(grid):
 global counter
  # Find next empty cell
 for i in range(0, 81):
   row = i // 9
    col = i % 9
    if grid[row][col] == 0:
      for value in range (1, 10):
        # Check that this value has not already be used on this row
        if not(value in grid[row]):
          # Check that this value has not already be used on this column
          if not value in \
            (grid[0][col], grid[1][col], grid[2][col], \
             grid[3][col], grid[4][col], grid[5][col], \
             grid[6][col], grid[7][col], grid[8][col]):
            # Identify which of the 9 squares we are working on
            square = []
            if row < 3:
              if col < 3:
                square = [grid[i][0:3] for i in range(0, 3)]
              elif col < 6:
                square = [grid[i][3:6] for i in range(0, 3)]
                square = [grid[i][6:9] for i in range(0, 3)]
            elif row < 6:
              if col < 3:
                square = [grid[i][0:3] for i in range(3, 6)]
              elif col < 6:
                square = [grid[i][3:6] for i in range(3, 6)]
              else:
                square = [grid[i][6:9] for i in range(3, 6)]
```

```
if col < 3:
                square = [grid[i][0:3] for i in range(6, 9)]
              elif col < 6:
                square = [grid[i][3:6] for i in range(6, 9)]
                square = [grid[i][6:9] for i in range(6, 9)]
            # Check that this value has not already be used on this 3x3 square
            if not value in (square[0] + square[1] + square[2]):
              grid[row][col] = value
              if checkGrid(grid):
                counter += 1
                break
              else:
                if solveGrid(grid):
                  return True
      break
  grid[row][col] = 0
numberList = [1, 2, 3, 4, 5, 6, 7, 8, 9]
#shuffle(numberList)
# A backtracking/recursive function to check all possible combinations of
# numbers until a solution is found
def fillGrid(grid):
  global counter
   Find next empty cell
  for i in range(0, 81):
    row = i // 9
    col = i % 9
    if grid[row][col] == 0:
      shuffle(numberList)
      for value in numberList:
        \# Check that this value has not already be used on this row
        if not(value in grid[row]):
          # Check that this value has not already be used on this column
          if not value in \
            (grid[0][col], grid[1][col], grid[2][col], \
             grid[3][col], grid[4][col], grid[5][col], \
grid[6][col], grid[7][col], grid[8][col]):
            # Identify which of the 9 squares we are working on
            square = []
            if row < 3:
              if col < 3:
                square = [grid[i][0:3] for i in range(0, 3)]
              elif col < 6:
                square = [grid[i][3:6] for i in range(0, 3)]
                square = [grid[i][6:9] for i in range(0, 3)]
            elif row < 6:
              if col < 3:
                square = [grid[i][0:3] for i in range(3, 6)]
              elif col < 6:
                square = [grid[i][3:6] for i in range(3, 6)]
              else:
                square = [grid[i][6:9] for i in range(3, 6)]
            else:
              if col < 3:
                square = [grid[i][0:3] for i in range(6, 9)]
              elif col < 6:
                square = [grid[i][3:6] for i in range(6, 9)]
                square = [grid[i][6:9] for i in range(6, 9)]
            \# Check that this value has not already be used on this 3x3 square
            if not value in (square[0] + square[1] + square[2]):
              grid[row][col] = value
              if checkGrid(grid):
                return True
              else:
                if fillGrid(grid):
                  return True
      break
  grid[row][col] = 0
```

```
# Generate a Fully Solved Grid
fillGrid(grid)
# Start Removing Numbers one by one
# A higher number of attempts will end up removing more numbers from the grid,
# potentially resulting in more difficult grids to solve!
attempts = 5
counter = 1
while attempts > 0:
 # Select a random cell that is not already empty
 row = randint(0, 8)
 col = randint(0, 8)
 while grid[row][col] == 0:
   row = randint(0, 8)
   col = randint(0, 8)
  # Remember its cell value in case we need to put it back
 backup = grid[row][col]
 grid[row][col] = 0
 # Take a full copy of the grid
 copyGrid = []
 for r in range(0, 9):
     copyGrid.append([])
    for c in range (0, 9):
       copyGrid[r].append(grid[r][c])
 # Count the number of solutions that this grid has (using a backtracking approach
     implemented in the solveGrid() function)
  counter = 0
 solveGrid(copyGrid)
 # If the number of solution is different from 1 then we need to cancel the change by
     putting the value we took away back in the grid
 if counter != 1:
   grid[row][col] = backup
    # We could stop here, but we can also have another attempt with a different cell just
       to try to remove more numbers
    attempts -= 1
# ADAPTATION BY US:
# flatten the grid into one long list of digits (without trailing newline!)
# and print to file "sudoku.txt"
flat_grid = [item for sublist in grid for item in sublist]
flat_grid = ''.join(map(str,flat_grid))
with open("sudoku.txt", 'w') as file:
   file.write(flat_grid)
print("Sudoku printed to sudoku.txt")
```

References

[RN09] Stuart J. Russell and Peter Norvig. Artificial Intelligence: A Modern Approach. Prentice Hall, 3rd edition, 2009.