

# DAVID BARSOUM

+1 508-654-8516 • [davidbarsoum.com](http://davidbarsoum.com) • [dbarsoum@olin.edu](mailto:dbarsoum@olin.edu)

## EDUCATION

### Olin College of Engineering, B.S. Robotics/Computer Engineering

2027

- GPA: 4.0/4.0. Coursework: Computational Robotics, Thermodynamics, Linear Algebra, Modeling & Simulation, Fundamentals of Robotics, Sensors & Instrumentation.

### Worcester Polytechnic Institute via Massachusetts Academy of Math and Science

2022 - 2024

- *Dual-enrolled during my senior year of high school as a full-time freshman at WPI.*
- GPA: 4.0/4.0. Relevant coursework: Intro to Robotics Engineering, Assembly Language, Intro to Electrical Engineering. Multivariable calculus.

## SKILLS

- **Programming:** ROS2, Docker, Gazebo, C++. C, Java, Python, MATLAB. Git & GitHub, Linux, MySQL & Firebase. Arduino & Raspberry Pi.
- **Mechanical:** SolidWorks, FEA, Fusion360 CAM, OnShape, HAAS Mill, CNC Router, Formlab printers, machine shop tools.
- **Mathematics:** Mathematical modeling, statistics.
- **Languages:** Spanish (Advanced Proficient), Arabic (Proficient), English (native).

## EXPERIENCE

### Robotics Engineering Intern (3<sup>rd</sup> Employee) | ReviMo @ Mass Robotics

Jun 2025 - Aug 2025

- Applied design for manufacturing principles to reduce machining time and optimize prototype manufacturing
- Machined ~100 hours of prototype parts on a CNC Mill, programming Fusion360 CAM toolpaths
- Designed and built an autonomous fatigue test setup and validation procedure for 4<sup>th</sup> prototype
- Demonstrated device at presentations, including senators at the MA State House

### Software Testing Intern | Evolv Technology

Jun 2024 - Aug 2024

- Developed randomized traffic flow testing module using Python/PyTest for 4K+ weapon detection scanners worldwide
- Designed system architecture and deployed testing module onto BeagleBone devices hosting APIs (Flask) for testing scanners
- Integrated testing devices with Evolv's CI/CD pipeline (Git, BitBucket, Jira, CircleCI) which runs on a daily basis
- Coordinated with 5+ engineers to document and replicate testing hardware to be used across departments
- Tested 50+ hours of simulated traffic on physical scanners and exposed critical errors (memory leak/performance issues)

### Co-President | FIRST Robotics Team 190

Aug 2022 - May 2024

- Designed 10+ robot components with SolidWorks, created CAM paths with Fusion360, machined parts on CNC mills/routers
- Led robotic development with 30+ students on the club team for the 2 consecutive years of FIRST Robotics competitions
- Coordinated manufacturing, designing, and software projects, winning the 1<sup>st</sup> place engineering award (Excellence Award)
- Grew robotics team by over 70% and sought donors for a multi-million-dollar FIRST robotics facility for the FRC 190 team

## PROJECTS

### Digital Sign in/out System (MAMS SISO) | C++, RFID, MySQL, Python

Oct 2022 - May 2024

- Worked on a 3-person team to create a digital sign-in/out system to replace an existing paper-based system
- Designed system architecture to interact with local hardware (Raspberry Pi), MySQL data storage, and NodeJS website
- Organized MySQL database schema to hold 1000+ unique student schedules that vary each school day and sync with calendar
- Programmed Raspberry Pi to decode proprietary HID RFID card bit format to interact with RFID readers and student ID cards
- Filed HECVAT forms and worked with WPI Information Security team to meet FERPA privacy and security standards.

### Assistive Wheelchair-Mounted Frisbee Launcher | OnShape, Physics, CNC Tools

Feb 2023 - May 2023

- Led a team of 4 to design a wheelchair-mounted frisbee launcher to enable individuals with limited mobility play with their pets.
- Designed 5+ parts using OnShape, integrating a car window motor, spring, and gearbox to launch frisbee like a clay pigeon
- Programmed Arduino to control motor with relay and use device and manufactured parts with machine shop tools
- Modeled mechanical stress using physics to determine required strength of parts and optimal gear ratios

## AWARDS

- **High School Mathematical Contest in Modeling (HiMCM):** 1<sup>st</sup> place rank of 950+ global teams (Outstanding NCTM Award).
- **International Math Modeling Challenge:** #1 U.S. Team out of 216 (Regional Outstanding Award).
- **Division Champions at FIRST Robotics World Championship in Houston '24** (3/80 teams).