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package flobee.accelerometer;

/*
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 */

import android.app.Activity;
import android.content.Context;
import android.graphics.Bitmap;
import android.graphics.BitmapFactory;
import android.graphics.BitmapFactory.Options;
import android.graphics.Canvas;
import android.hardware.Sensor;
import android.hardware.SensorEvent;
import android.hardware.SensorEventListener;
import android.hardware.SensorManager;
import android.os.Bundle;
import android.os.PowerManager;
import android.os.PowerManager.WakeLock;
import android.util.DisplayMetrics;
import android.view.Display;
import android.view.Surface;
import android.view.View;
import android.view.WindowManager;

/**
 * This is an example of using the accelerometer to integrate the device's
 * acceleration to a position using the Verlet method. This is illustrated with
 * a very simple particle system comprised of a few iron balls freely moving on
 * an inclined wooden table. The inclination of the virtual table is controlled
 * by the device's accelerometer.
 *
 * @see SensorManager
 * @see SensorEvent
 * @see Sensor
 */
public class AccelerometerPlayActivity extends Activity {
    private SimulationView mSimulationView;
    private SensorManager mSensorManager;
    private PowerManager mPowerManager;
    private WindowManager mWindowManager;
    private Display mDisplay;
    private WakeLock mWakeLock;

    /** Called when the activity is first created. */
    @Override
    public void onCreate(Bundle savedInstanceState) {
        super.onCreate(savedInstanceState);
        // Get an instance of the SensorManager
        mSensorManager = (SensorManager) getSystemService(SENSOR_SERVICE);
        // Get an instance of the PowerManager
        mPowerManager = (PowerManager) getSystemService(POWER_SERVICE);
        // Get an instance of the WindowManager
        mWindowManager = (WindowManager) getSystemService(WINDOW_SERVICE);
    }

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mDisplay = mWindowManager.getDefaultDisplay();
// Create a bright wake lock
mWakeLock = mPowerManager.newWakeLock(
    PowerManager.SCREEN_BRIGHT_WAKE_LOCK, getClass().getName());
// instantiate our simulation view and set it as the activity's content
mSimulationView = new SimulationView(this);
setContentView(mSimulationView);
}
@Override
protected void onResume() {
    super.onResume();
}
/*
 * when the activity is resumed, we acquire a wake-lock so that the
 * screen stays on, since the user will likely not be fiddling with the
 * screen or buttons.
 */
mWakeLock.acquire();
// Start the simulation
mSimulationView.startSimulation();
}
@Override
protected void onPause() {
    super.onPause();
}
/*
 * When the activity is paused, we make sure to stop the simulation,
 * release our sensor resources and wake locks
 */
// Stop the simulation
mSimulationView.stopSimulation();
// and release our wake-lock
mWakeLock.release();
}
class SimulationView extends View implements SensorEventListener {
    // diameter of the balls in meters
    private static final float sBallDiameter = 0.004f;
    private Sensor mAccelerometer;
    private float mXDpi;
    private float mYDpi;
    private float mMetersToPixelsX;
    private float mMetersToPixelsY;
    private Bitmap mBitmap;
    private Bitmap mWood;
    private float mXOrigin;
    private float mYOrigin;
    private float mSensorX;
    private float mSensorY;
    private long mSensorTimeStamp;
    private long mCpuTimeStamp;
    private float mHorizontalBound;
    private float mVerticalBound;
    private ParticleSystem mParticleSystem;

    public void startSimulation() {
        /*
         * It is not necessary to get accelerometer events at a very high
         * rate, by using a slower rate (SENSOR_DELAY_UI), we get an
         * automatic low-pass filter, which "extracts" the gravity component
         * of the acceleration. As an added benefit, we use less power and
         * CPU resources.
         */
        mSensorManager.registerListener(this, mAccelerometer,
            SensorManager.SENSOR_DELAY_UI);
    }

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}
public void stopSimulation() {
    mSensorManager.unregisterListener(this);
}

public SimulationView(Context context) {
    super(context);
    mAccelerometer = mSensorManager
        .getDefaultSensor(Sensor.TYPE_ACCELEROMETER);
    DisplayMetrics metrics = new DisplayMetrics();
    getWindowManager().getDefaultDisplay().getMetrics(metrics);
    mXDpi = metrics.xdpi;
    mYDpi = metrics.ydpi;
    mMetersToPixelsX = mXDpi / 0.0254f;
    mMetersToPixelsY = mYDpi / 0.0254f;
    // rescale the ball so it's about 0.5 cm on screen
    Bitmap ball = BitmapFactory.decodeResource(getResources(),
        R.drawable.ball);
    final int dstWidth = (int) (sBallDiameter * mMetersToPixelsX + 0.5f);
    final int dstHeight = (int) (sBallDiameter * mMetersToPixelsY + 0.5f);
    mBitmap = Bitmap
        .createScaledBitmap(ball, dstWidth, dstHeight, true);
    Options opts = new Options();
    opts.inDither = true;
    opts.inPreferredConfig = Bitmap.Config.RGB_565;
    mWood = BitmapFactory.decodeResource(getResources(),
        R.drawable.wood, opts);
}

@Override
protected void onSizeChanged(int w, int h, int oldw, int oldh) {
    // compute the origin of the screen relative to the origin of
    // the bitmap
    mXOrigin = (w - mBitmap.getWidth()) * 0.5f;
    mYOrigin = (h - mBitmap.getHeight()) * 0.5f;
    mHorizontalBound = ((w / mMetersToPixelsX - sBallDiameter) * 0.5f);
    mVerticalBound = ((h / mMetersToPixelsY - sBallDiameter) * 0.5f);
    if (null == mParticleSystem) {
        mParticleSystem =
            new ParticleSystem(sBallDiameter, mHorizontalBound, mVerticalBound);
    }
}

@Override
public void onSensorChanged(SensorEvent event) {
    if (event.sensor.getType() != Sensor.TYPE_ACCELEROMETER)
        return;
}

/*
 * record the accelerometer data, the event's timestamp as well as
 * the current time. The latter is needed so we can calculate the
 * "present" time during rendering.
 */
/*
 * In this application, we need to take into account how the
 * screen is rotated with respect to the sensors (which always
 * return data in a coordinate space aligned to with the screen
 * in its native orientation).
 */
switch (mDisplay.getRotation()) {
    case Surface.ROTATION_0:
        mSensorX = event.values[0];
        mSensorY = event.values[1];
        break;
    case Surface.ROTATION_90:

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        mSensorX = -event.values[1];
        mSensorY = event.values[0];
        break;
    case Surface.ROTATION_180:
        mSensorX = -event.values[0];
        mSensorY = -event.values[1];
        break;
    case Surface.ROTATION_270:
        mSensorX = event.values[1];
        mSensorY = -event.values[0];
        break;
    }
    mSensorTimeStamp = event.timestamp;
    mCpuTimeStamp = System.nanoTime();
}

@Override
protected void onDraw(Canvas canvas) {
    //draw the background
    canvas.drawBitmap(mWood, 0, 0, null);
    //compute the new position of our object, based on accelerometer
    //data and present time.
    final ParticleSystem particleSystem = mParticleSystem;
    final long NOW = mSensorTimeStamp
        + (System.nanoTime() - mCpuTimeStamp);
    final float sx = mSensorX;
    final float sy = mSensorY;
    particleSystem.update(sx, sy, now);
    final float xc = mXOrigin;
    final float yc = mYOrigin;
    final float xs = mMetersToPixelsX;
    final float ys = mMetersToPixelsY;
    final Bitmap bitmap = mBitmap;
    final int count = particleSystem.getParticleCount();
    for (int i = 0; i < count; i++) {
        /*
        * We transform the canvas so that the coordinate system matches
        * the sensors coordinate system with the origin in the center
        * of the screen and the unit is the meter.
        */
        final float x = xc + particleSystem.getPosX(i) * xs;
        final float y = yc - particleSystem.getPosY(i) * ys;
        canvas.drawBitmap(bitmap, x, y, null);
    }
    // and make sure to redraw asap
    invalidate();
}

@Override
public void onAccuracyChanged(Sensor sensor, int accuracy) {}
}
}

```