

latex

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Contents

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theory MC
imports Main
begin
declare [[show-types]]

thm monotone-def
definition monotone :: ('a set  $\Rightarrow$  'a set)  $\Rightarrow$  bool
where monotone  $\tau \equiv (\forall p\ q. p \subseteq q \longrightarrow \tau\ p \subseteq \tau\ q)$ 

lemma monotoneE: monotone  $\tau \Longrightarrow p \subseteq q \Longrightarrow \tau\ p \subseteq \tau\ q$ 
 $\langle$ proof $\rangle$ 

lemma lfp1: monotone  $\tau \longrightarrow (\text{lfp}\ \tau = \bigcap \{Z. \tau\ Z \subseteq Z\})$ 
 $\langle$ proof $\rangle$ 

lemma gfp1: monotone  $\tau \longrightarrow (\text{gfp}\ \tau = \bigcup \{Z. Z \subseteq \tau\ Z\})$ 
 $\langle$ proof $\rangle$ 

primrec power :: ['a  $\Rightarrow$  'a, nat]  $\Rightarrow$  ('a  $\Rightarrow$  'a) ((-  $\wedge$  -) 40)
where
  power-zero: (f  $\wedge$  0) = ( $\lambda x. x$ ) |
  power-suc: (f  $\wedge$  (Suc n)) = (f o (f  $\wedge$  n))

lemma predtrans-empty:
  assumes monotone  $\tau$ 
  shows  $\forall i. (\tau \wedge i)\ (\{\}) \subseteq (\tau \wedge (i + 1))(\{\})$ 
 $\langle$ proof $\rangle$ 

lemma ex-card: finite  $S \Longrightarrow \exists n::\text{nat}. \text{card}\ S = n$ 
 $\langle$ proof $\rangle$ 

lemma less-not-le:  $\llbracket (x::\text{nat}) < y; y \leq x \rrbracket \Longrightarrow \text{False}$ 
 $\langle$ proof $\rangle$ 

lemma infchain-outruns-all:
  assumes finite (UNIV :: 'a set)
```

and $\forall i :: \text{nat. } (\tau \wedge i) (\{\} :: 'a \text{ set}) \subset (\tau \wedge i + (1 :: \text{nat})) \{\}$
shows $\forall j :: \text{nat. } \exists i :: \text{nat. } j < \text{card } ((\tau \wedge i) \{\})$
 $\langle \text{proof} \rangle$

lemma *no-infinite-subset-chain*:

assumes *finite* (*UNIV* :: 'a set)
and *monotone* ($\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})$)
and $\forall i :: \text{nat. } ((\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}) \wedge i) \{\} \subset (\tau \wedge i + (1 :: \text{nat})) (\{\} :: 'a \text{ set})$
shows *False*

$\langle \text{proof} \rangle$

lemma *finite-fixp*:

assumes *finite*(*UNIV* :: 'a set)
and *monotone* ($\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})$)
shows $\exists i. (\tau \wedge i) (\{\}) = (\tau \wedge (i + 1))(\{\})$

$\langle \text{proof} \rangle$

lemma *predtrans-UNIV*:

assumes *monotone* τ
shows $\forall i. (\tau \wedge i) (\text{UNIV}) \supseteq (\tau \wedge (i + 1))(\text{UNIV})$
 $\langle \text{proof} \rangle$

lemma *Suc-less-le*: $x < (y - n) \Longrightarrow x \leq (y - (\text{Suc } n))$
 $\langle \text{proof} \rangle$

lemma *card-univ-subtract*:

assumes *finite* (*UNIV* :: 'a set) **and** *monotone* ($\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}$)
and $(\forall i :: \text{nat. } ((\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}) \wedge i + (1 :: \text{nat})) (\text{UNIV} :: 'a \text{ set}) \subset (\tau \wedge i) \text{ UNIV})$
shows $(\forall i :: \text{nat. } \text{card}((\tau \wedge i) (\text{UNIV} :: 'a \text{ set})) \leq (\text{card } (\text{UNIV} :: 'a \text{ set})) - i)$
 $\langle \text{proof} \rangle$

lemma *card-UNIV-tau-i-below-zero*:

assumes *finite* (*UNIV* :: 'a set) **and** *monotone* ($\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}$)
and $(\forall i :: \text{nat. } ((\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}) \wedge i + (1 :: \text{nat})) (\text{UNIV} :: 'a \text{ set}) \subset (\tau \wedge i) \text{ UNIV})$
shows $\text{card}((\tau \wedge (\text{card } (\text{UNIV} :: 'a \text{ set}))) (\text{UNIV} :: 'a \text{ set})) \leq 0$
 $\langle \text{proof} \rangle$

lemma *finite-card-zero-empty*: $\llbracket \text{finite } S; \text{card } S \leq 0 \rrbracket \Longrightarrow S = \{\}$
 $\langle \text{proof} \rangle$

lemma *UNIV-tau-i-is-empty*:

assumes *finite* (*UNIV* :: 'a set) **and** *monotone* ($\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}$)
and $(\forall i :: \text{nat. } ((\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}) \wedge i + (1 :: \text{nat})) (\text{UNIV} :: 'a \text{ set}) \subset (\tau \wedge i) \text{ UNIV})$

shows $(\tau \wedge (\text{card } (UNIV :: 'a \text{ set}))) (UNIV :: 'a \text{ set}) = \{\}$
 $\langle \text{proof} \rangle$

lemma *down-chain-reaches-empty*:

assumes *finite* $(UNIV :: 'a \text{ set})$ **and** *monotone* $(\tau :: 'a \text{ set} \Rightarrow 'a \text{ set})$
and $(\forall i :: \text{nat}. ((\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}) \wedge i + (1 :: \text{nat})) UNIV \subset (\tau \wedge i) UNIV)$
shows $\exists (j :: \text{nat}). (\tau \wedge j) UNIV = \{\}$
 $\langle \text{proof} \rangle$

lemma *no-infinite-subset-chain2*:

assumes *finite* $(UNIV :: 'a \text{ set})$ **and** *monotone* $(\tau :: ('a \text{ set} \Rightarrow 'a \text{ set}))$
and $\forall i :: \text{nat}. (\tau \wedge i) UNIV \supset (\tau \wedge i + (1 :: \text{nat})) UNIV$
shows *False*
 $\langle \text{proof} \rangle$

lemma *finite-fix2*:

assumes *finite* $(UNIV :: 'a \text{ set})$ **and** *monotone* $(\tau :: ('a \text{ set} \Rightarrow 'a \text{ set}))$
shows $\exists i. (\tau \wedge i) UNIV = (\tau \wedge (i + 1)) UNIV$
 $\langle \text{proof} \rangle$

lemma *mono-monotone*: *mono* $(\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})) \Longrightarrow \text{monotone } \tau$
 $\langle \text{proof} \rangle$

lemma *monotone-mono*: *monotone* $(\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})) \Longrightarrow \text{mono } \tau$
 $\langle \text{proof} \rangle$

lemma *power-power*: $((\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})) \wedge \wedge n) = ((\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})) \wedge n)$
 $\langle \text{proof} \rangle$

lemma *lfp-Kleene-iter-set*: *monotone* $(f :: ('a \text{ set} \Rightarrow 'a \text{ set})) \Longrightarrow$
 $(f \wedge \text{Suc}(n)) \{\} = (f \wedge n) \{\} \Longrightarrow \text{lfp } f = (f \wedge n) \{\}$
 $\langle \text{proof} \rangle$

lemma *lfp-loop*:

assumes *finite* $(UNIV :: 'b \text{ set})$ **and** *monotone* $(\tau :: ('b \text{ set} \Rightarrow 'b \text{ set}))$
shows $\exists n. \text{lfp } \tau = (\tau \wedge n) \{\}$
 $\langle \text{proof} \rangle$

lemma *Kleene-iter-gfp*:

assumes *mono* f **and** $p \leq f p$ **shows** $p \leq (f \wedge k) (\text{top} :: 'a :: \text{order-top})$
 $\langle \text{proof} \rangle$

lemma *gfp-Kleene-iter*: **assumes** *mono* f **and** $(f \wedge \text{Suc } k) \text{ top} = (f \wedge k) \text{ top}$
shows $\text{gfp } f = (f \wedge k) \text{ top}$
 $\langle \text{proof} \rangle$

lemma *gfp-Kleene-iter-set*:
assumes *monotone* ($f :: ('a \text{ set} \Rightarrow 'a \text{ set})$)
and ($f \wedge \text{Suc}(n)$) $\text{UNIV} = (f \wedge n) \text{ UNIV}$
shows $\text{gfp } f = (f \wedge n) \text{ UNIV}$
 $\langle \text{proof} \rangle$

lemma *gfp-loop*:
assumes *finite* ($\text{UNIV} :: 'b \text{ set}$)
and *monotone* ($\tau :: ('b \text{ set} \Rightarrow 'b \text{ set})$)
shows $\exists n. \text{gfp } \tau = (\tau \wedge n)(\text{UNIV} :: 'b \text{ set})$
 $\langle \text{proof} \rangle$

class *state* =
fixes *state-transition* :: $['a :: \text{type}, 'a] \Rightarrow \text{bool}$ $((- \rightarrow_i -) \ 50)$

definition *AX* **where** $\text{AX } f \equiv \{s. \{f0. s \rightarrow_i f0\} \subseteq f\}$
definition *EX'* **where** $\text{EX}' f \equiv \{s. \exists f0 \in f. s \rightarrow_i f0\}$

definition *AF* **where** $\text{AF } f \equiv \text{lfp } (\lambda Z. f \cup \text{AX } Z)$
definition *EF* **where** $\text{EF } f \equiv \text{lfp } (\lambda Z. f \cup \text{EX}' Z)$
definition *AG* **where** $\text{AG } f \equiv \text{gfp } (\lambda Z. f \cap \text{AX } Z)$
definition *EG* **where** $\text{EG } f \equiv \text{gfp } (\lambda Z. f \cap \text{EX}' Z)$
definition *AU* **where** $\text{AU } f1 f2 \equiv \text{lfp } (\lambda Z. f2 \cup (f1 \cap \text{AX } Z))$
definition *EU* **where** $\text{EU } f1 f2 \equiv \text{lfp } (\lambda Z. f2 \cup (f1 \cap \text{EX}' Z))$
definition *AR* **where** $\text{AR } f1 f2 \equiv \text{gfp } (\lambda Z. f2 \cap (f1 \cup \text{AX } Z))$
definition *ER* **where** $\text{ER } f1 f2 \equiv \text{gfp } (\lambda Z. f2 \cap (f1 \cup \text{EX}' Z))$

datatype *'a kripke* =
Kripke 'a set 'a set

primrec *states* **where** $\text{states } (\text{Kripke } S \ I) = S$
primrec *init* **where** $\text{init } (\text{Kripke } S \ I) = I$

definition *check* $(- \vdash - \ 50)$
where $M \vdash f \equiv (\text{init } M) \subseteq \{s \in (\text{states } M). s \in f\}$

definition *state-transition-refl* $((- \rightarrow_{i*} -) \ 50)$
where $s \rightarrow_{i*} s' \equiv ((s, s') \in \{(x, y). \text{state-transition } x \ y\}^*)$

lemma *EF-lem0*: $(x \in \text{EF } f) = (x \in f \cup \text{EX}' (\text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set}. f \cup \text{EX}' Z)))$
 $\langle \text{proof} \rangle$

lemma *EF-lem00*: $(\text{EF } f) = (f \cup \text{EX}' (\text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set}. f \cup \text{EX}' Z)))$
 $\langle \text{proof} \rangle$

lemma *EF-lem000*: $(EF\ f) = (f \cup EX'\ (EF\ f))$

<proof>

lemma *EF-lem1*: $x \in f \vee x \in (EX'\ (EF\ f)) \implies x \in EF\ f$

<proof>

lemma *EF-lem2b*:

assumes $x \in (EX'\ (EF\ f))$

shows $x \in EF\ f$

<proof>

lemma *EF-lem2a*: **assumes** $x \in f$ **shows** $x \in EF\ f$

<proof>

lemma *EF-lem2c*: **assumes** $x \notin f$ **shows** $x \in EF\ (\neg f)$

<proof>

lemma *EF-lem2d*: **assumes** $x \notin EF\ f$ **shows** $x \notin f$

<proof>

lemma *EF-lem3b*: **assumes** $x \in EX'\ (f \cup EX'\ (EF\ f))$ **shows** $x \in (EF\ f)$

<proof>

lemma *EX-lem0l*: $x \in (EX'\ f) \implies x \in (EX'\ (f \cup g))$

<proof>

lemma *EX-lem0r*: $x \in (EX'\ g) \implies x \in (EX'\ (f \cup g))$

<proof>

lemma *EX-step*: **assumes** $x \rightarrow_i y$ **and** $y \in f$ **shows** $x \in EX'\ f$

<proof>

lemma *EF-E[rule-format]*: $\forall f. x \in (EF\ (f :: ('a :: state)\ set)) \longrightarrow x \in (f \cup EX'\ (EF\ f))$

<proof>

lemma *EF-step*: **assumes** $x \rightarrow_i y$ **and** $y \in f$ **shows** $x \in EF\ f$

<proof>

lemma *EF-step-step*: **assumes** $x \rightarrow_i y$ **and** $y \in EF\ f$ **shows** $x \in EF\ f$

<proof>

lemma *EF-step-star*: $\llbracket x \rightarrow_i^* y; y \in f \rrbracket \implies x \in EF\ f$

<proof>

lemma *EF-induct-prep*:

assumes $(a :: 'a :: state) \in \text{lfp } (\lambda Z. (f :: 'a :: state\ set) \cup EX'\ Z)$

and $\text{mono } (\lambda Z. (f :: 'a :: state\ set) \cup EX'\ Z)$

shows $(\bigwedge x :: 'a :: \text{state}.$
 $x \in ((\lambda Z. (f :: 'a :: \text{state set}) \cup EX' Z)(\text{lfp } (\lambda Z. (f :: 'a :: \text{state set}) \cup EX' Z) \cap$
 $\{x :: 'a :: \text{state}. (P :: 'a :: \text{state} \Rightarrow \text{bool}) x\})) \Rightarrow P x) \Rightarrow$
 $P a$
 $\langle \text{proof} \rangle$

lemma *EF-induct*: $(a :: 'a :: \text{state}) \in EF (f :: 'a :: \text{state set}) \Rightarrow$
 $\text{mono } (\lambda Z. (f :: 'a :: \text{state set}) \cup EX' Z) \Rightarrow$
 $(\bigwedge x :: 'a :: \text{state}.$
 $x \in ((\lambda Z. (f :: 'a :: \text{state set}) \cup EX' Z)(EF f \cap \{x :: 'a :: \text{state}. (P :: 'a :: \text{state} \Rightarrow$
 $\text{bool}) x\})) \Rightarrow P x) \Rightarrow$
 $P a$
 $\langle \text{proof} \rangle$

lemma *valEF-E*: $M \vdash EF f \Rightarrow x \in \text{init } M \Rightarrow x \in EF f$
 $\langle \text{proof} \rangle$

lemma *EF-step-star-rev[rule-format]*: $x \in EF s \Rightarrow (\exists y \in s. x \rightarrow_i^* y)$
 $\langle \text{proof} \rangle$

lemma *EF-step-inv*: $(I \subseteq \{sa :: 's :: \text{state}. (\exists i :: 's \in I. i \rightarrow_i^* sa) \wedge sa \in EF s\})$
 $\Rightarrow \forall x \in I. \exists y \in s. x \rightarrow_i^* y$
 $\langle \text{proof} \rangle$

lemma *AG-in-lem*: $x \in AG s \Rightarrow x \in s$
 $\langle \text{proof} \rangle$

lemma *AG-lem1*: $x \in s \wedge x \in (AX (AG s)) \Rightarrow x \in AG s$
 $\langle \text{proof} \rangle$

lemma *AG-lem2*: $x \in AG s \Rightarrow x \in (s \cap (AX (AG s)))$
 $\langle \text{proof} \rangle$

lemma *AG-lem3*: $AG s = (s \cap (AX (AG s)))$
 $\langle \text{proof} \rangle$

lemma *AG-step*: $y \rightarrow_i z \Rightarrow y \in AG s \Rightarrow z \in AG s$
 $\langle \text{proof} \rangle$

lemma *AG-all-s*: $x \rightarrow_i^* y \Rightarrow x \in AG s \Rightarrow y \in AG s$
 $\langle \text{proof} \rangle$

lemma *AG-imp-notnotEF*:
 $I \neq \{\} \Rightarrow ((\text{Kripke } \{s :: ('s :: \text{state}). \exists i \in I. (i \rightarrow_i^* s)\} (I :: ('s :: \text{state})\text{set})$
 $\vdash AG s)) \Rightarrow$
 $(\neg(\text{Kripke } \{s :: ('s :: \text{state}). \exists i \in I. (i \rightarrow_i^* s)\} (I :: ('s :: \text{state})\text{set}) \vdash EF (-$
 $s)))$

$\langle proof \rangle$

lemma *check2-def*: $(Kripke\ S\ I \vdash f) = (I \subseteq S \cap f)$

$\langle proof \rangle$

end

theory *AirInsider*

imports *MC*

begin

datatype *action* = *get* | *move* | *eval* | *put*

typedecl *actor*

type-synonym *identity* = *string*

consts *Actor* :: *string* \Rightarrow *actor*

type-synonym *policy* = $((actor \Rightarrow bool) * action\ set)$

definition *ID* :: $[actor, string] \Rightarrow bool$

where *ID* *a s* $\equiv (a = Actor\ s)$

datatype *location* = *Location* *nat*

datatype *igraph* = *Lgraph* $(location * location) set$ *location* \Rightarrow *identity list*

actor \Rightarrow $(string\ list * string\ list)$ *location* \Rightarrow *string list*

datatype *infrastructure* =

Infrastructure *igraph*

$[igraph, location] \Rightarrow policy\ set$

primrec *loc* :: *location* \Rightarrow *nat*

where *loc* $(Location\ n) = n$

primrec *gra* :: *igraph* \Rightarrow $(location * location) set$

where *gra* $(Lgraph\ g\ a\ c\ l) = g$

primrec *agra* :: *igraph* \Rightarrow $(location \Rightarrow identity\ list)$

where *agra* $(Lgraph\ g\ a\ c\ l) = a$

primrec *cgra* :: *igraph* \Rightarrow $(actor \Rightarrow string\ list * string\ list)$

where *cgra* $(Lgraph\ g\ a\ c\ l) = c$

primrec *lgra* :: *igraph* \Rightarrow $(location \Rightarrow string\ list)$

where *lgra* $(Lgraph\ g\ a\ c\ l) = l$

definition *nodes* :: *igraph* \Rightarrow *location set*

where *nodes* *g* == $\{ x. (? y. ((x,y): gra\ g) \mid ((y,x): gra\ g)) \}$

definition *actors-graph* :: *igraph* \Rightarrow *identity set*

where *actors-graph* *g* == $\{ x. ? y. y : nodes\ g \wedge x \in set(agra\ g\ y) \}$

primrec *graphI* :: *infrastructure* \Rightarrow *igraph*

where *graphI* $(Infrastructure\ g\ d) = g$

primrec *delta* :: $[infrastructure, igraph, location] \Rightarrow policy\ set$

where *delta* $(Infrastructure\ g\ d) = d$

primrec *tspace* :: $[infrastructure, actor] \Rightarrow string\ list * string\ list$

where *tspace* $(Infrastructure\ g\ d) = cgra\ g$

primrec *lspace* :: [*infrastructure*, *location*] \Rightarrow *string list*
where *lspace* (*Infrastructure g d*) = *lgra g*

definition *credentials* :: *string list* * *string list* \Rightarrow *string set*
where *credentials lxl* \equiv *set (fst lxl)*

definition *has* :: [*igraph*, *actor* * *string*] \Rightarrow *bool*
where *has G ac* \equiv *snd ac* \in *credentials(cgra G (fst ac))*

definition *roles* :: *string list* * *string list* \Rightarrow *string set*
where *roles lxl* \equiv *set (snd lxl)*

definition *role* :: [*igraph*, *actor* * *string*] \Rightarrow *bool*
where *role G ac* \equiv *snd ac* \in *roles(cgra G (fst ac))*

definition *isin* :: [*igraph*, *location*, *string*] \Rightarrow *bool*
where *isin G l s* \equiv *s* \in *set(lgra G l)*

datatype *psy-states* = *happy* | *depressed* | *disgruntled* | *angry* | *stressed*
datatype *motivations* = *financial* | *political* | *revenge* | *curious* | *competitive-advantage*
| *power* | *peer-recognition*

datatype *actor-state* = *Actor-state psy-states motivations set*
primrec *motivation* :: *actor-state* \Rightarrow *motivations set*
where *motivation (Actor-state p m)* = *m*
primrec *psy-state* :: *actor-state* \Rightarrow *psy-states*
where *psy-state (Actor-state p m)* = *p*

definition *tipping-point* :: *actor-state* \Rightarrow *bool* **where**
tipping-point a \equiv (*motivation a* \neq {}) \wedge (*happy* \neq *psy-state a*)

consts *Isolation* :: [*actor-state*, (*identity* * *identity*) *set*] \Rightarrow *bool*

definition *lay-off* :: [*infrastructure*, *actor set*] \Rightarrow *infrastructure*
where *lay-off G A* \equiv *G*

consts *social-graph* :: (*identity* * *identity*) *set*

definition *UasI* :: [*identity*, *identity*] \Rightarrow *bool*
where *UasI a b* \equiv (*Actor a* = *Actor b*) \wedge ($\forall x y. x \neq a \wedge y \neq a \wedge \text{Actor } x = \text{Actor } y \longrightarrow x = y$)

definition *UasI'* :: [*actor* \Rightarrow *bool*, *identity*, *identity*] \Rightarrow *bool*
where *UasI' P a b* \equiv *P (Actor b)* \longrightarrow *P (Actor a)*

consts $astate :: identity \Rightarrow actor\text{-}state$

definition $Insider :: [identity, identity\ set] \Rightarrow bool$
where $Insider\ a\ C \equiv (tipping\text{-}point\ (astate\ a) \longrightarrow (\forall\ b \in C. UasI\ a\ b))$

definition $Insider' :: [actor \Rightarrow bool, identity, identity\ set] \Rightarrow bool$
where $Insider'\ P\ a\ C \equiv (tipping\text{-}point\ (astate\ a) \longrightarrow (\forall\ b \in C. UasI'\ P\ a\ b \wedge inj\text{-}on\ Actor\ C))$

definition $atI :: [identity, igraph, location] \Rightarrow bool\ (-\ @_{(-)}\ -\ 50)$
where $a\ @_G\ l \equiv a \in set(agra\ G\ l)$

definition $enables :: [infrastructure, location, actor, action] \Rightarrow bool$
where
 $enables\ I\ l\ a\ a' \equiv (\exists\ (p,e) \in delta\ I\ (graphI\ I)\ l. a' \in e \wedge p\ a)$

definition $behaviour :: infrastructure \Rightarrow (location * actor * action)set$
where $behaviour\ I \equiv \{(t,a,a').\ enables\ I\ t\ a\ a'\}$

definition $misbehaviour :: infrastructure \Rightarrow (location * actor * action)set$
where $misbehaviour\ I \equiv \neg(behaviour\ I)$

lemma $not\text{-}enableI: (\forall\ (p,e) \in delta\ I\ (graphI\ I)\ l. (\sim(h : e) \mid (\sim(p(a)))) \implies \sim(enableI\ l\ a\ h))$
 $\langle proof \rangle$

lemma $not\text{-}enableI2: [\bigwedge\ p\ e. (p,e) \in delta\ I\ (graphI\ I)\ l \implies (\sim(t : e) \mid (\sim(p(a))))] \implies \sim(enableI\ l\ a\ t)$
 $\langle proof \rangle$

lemma $not\text{-}enableE: [\sim(enableI\ l\ a\ t); (p,e) \in delta\ I\ (graphI\ I)\ l] \implies (\sim(t : e) \mid (\sim(p(a))))$
 $\langle proof \rangle$

lemma $not\text{-}enableE2: [\sim(enableI\ l\ a\ t); (p,e) \in delta\ I\ (graphI\ I)\ l; t : e] \implies (\sim(p(a)))$
 $\langle proof \rangle$

primrec $del :: ['a, 'a\ list] \Rightarrow 'a\ list$

where

$del\text{-}nil: del\ a\ [] = []$

$del\text{-}cons: del\ a\ (x\#\!ls) = (if\ x = a\ then\ ls\ else\ x\ \#\ (del\ a\ ls))$

primrec $jonce :: ['a, 'a\ list] \Rightarrow bool$

where

$jonce\text{-}nil: jonce\ a\ [] = False$

$jonce\text{-}cons: jonce\ a\ (x\#\!ls) = (if\ x = a\ then\ (a\ \notin\ (set\ ls))\ else\ jonce\ a\ ls)$

primrec $nodup :: ['a, 'a\ list] \Rightarrow bool$

where

$nodup\text{-}nil: nodup\ a\ [] = True$

$nodup\text{-}step: nodup\ a\ (x\ \#\!ls) = (if\ x = a\ then\ (a\ \notin\ (set\ ls))\ else\ nodup\ a\ ls)$

definition $move\text{-}graph\text{-}a :: [identity, location, location, igrph] \Rightarrow igrph$

where $move\text{-}graph\text{-}a\ n\ l\ l'\ g \equiv Lgraph\ (gra\ g)$

$(if\ n \in set\ ((agra\ g)\ l)\ \&\ n \notin set\ ((agra\ g)\ l')\ then$

$((agra\ g)(l := del\ n\ (agra\ g\ l)))(l' := (n\ \#\ (agra\ g\ l')))$

$else\ (agra\ g))(cgra\ g)(lgra\ g)$

inductive $state\text{-}transition\text{-}in :: [infrastructure, infrastructure] \Rightarrow bool\ ((- \rightarrow_n -)$
 $50)$

where

$move: \llbracket G = graphI\ I; a\ @_G\ l; l \in nodes\ G; l' \in nodes\ G;$

$(a) \in actors\text{-}graph(graphI\ I); enables\ I\ l'\ (Actor\ a)\ move;$

$I' = Infrastructure\ (move\text{-}graph\text{-}a\ a\ l\ l'\ (graphI\ I))(delta\ I) \rrbracket \implies I \rightarrow_n I'$

$| get : \llbracket G = graphI\ I; a\ @_G\ l; a' @_G\ l; has\ G\ (Actor\ a, z);$

$enables\ I\ l\ (Actor\ a)\ get;$

$I' = Infrastructure$

$(Lgraph\ (gra\ G)(agra\ G)$

$((cgra\ G)(Actor\ a' :=$

$(z\ \#\ (fst(cgra\ G\ (Actor\ a'))), snd(cgra\ G\ (Actor\ a')))))$

$(lgra\ G))$

$(delta\ I)$

$\rrbracket \implies I \rightarrow_n I'$

$| put : \llbracket G = graphI\ I; a\ @_G\ l; enables\ I\ l\ (Actor\ a)\ put;$

$I' = Infrastructure$

$(Lgraph\ (gra\ G)(agra\ G)(cgra\ G)$

$((lgra\ G)(l := [z])))$

$(delta\ I) \rrbracket$

$\implies I \rightarrow_n I'$

$| put\text{-}remote : \llbracket G = graphI\ I; enables\ I\ l\ (Actor\ a)\ put;$

$I' = Infrastructure$

$(Lgraph\ (gra\ G)(agra\ G)(cgra\ G)$

$((lgra\ G)(l := [z])))$

$$\begin{array}{c} (\text{delta } I) \parallel \\ \implies I \rightarrow_n I' \end{array}$$

instantiation *infrastructure* :: *state*
begin

definition

state-transition-infra-def: $(i \rightarrow_i i') = (i \rightarrow_n (i' :: \text{infrastructure}))$

instance

<proof>

definition *state-transition-in-refl* $((- \rightarrow_n^* -) \ 50)$

where $s \rightarrow_n^* s' \equiv ((s, s') \in \{(x, y). \text{state-transition-in } x \ y\}^*)$

lemma *del-del*[*rule-format*]: $n \in \text{set } (\text{del } a \ S) \longrightarrow n \in \text{set } S$

<proof>

lemma *del-dec*[*rule-format*]: $a \in \text{set } S \longrightarrow \text{length } (\text{del } a \ S) < \text{length } S$

<proof>

lemma *del-sort*[*rule-format*]: $\forall \ n. (\text{Suc } n :: \text{nat}) \leq \text{length } (l) \longrightarrow n \leq \text{length } (\text{del } a \ (l))$

<proof>

lemma *del-jonce*: $\text{jonce } a \ l \longrightarrow a \notin \text{set } (\text{del } a \ l)$

<proof>

lemma *del-nodup*[*rule-format*]: $\text{nodup } a \ l \longrightarrow a \notin \text{set } (\text{del } a \ l)$

<proof>

lemma *nodup-up*[*rule-format*]: $a \in \text{set } (\text{del } a \ l) \longrightarrow a \in \text{set } l$

<proof>

lemma *del-up* [*rule-format*]: $a \in \text{set } (\text{del } aa \ l) \longrightarrow a \in \text{set } l$

<proof>

lemma *nodup-notin*[*rule-format*]: $a \notin \text{set } \text{list} \longrightarrow \text{nodup } a \ \text{list}$

<proof>

lemma *nodup-down*[*rule-format*]: $\text{nodup } a \ l \longrightarrow \text{nodup } a \ (\text{del } a \ l)$

<proof>

lemma *del-notin-down*[*rule-format*]: $a \notin \text{set } \text{list} \longrightarrow a \notin \text{set } (\text{del } aa \ \text{list})$

$\langle proof \rangle$

lemma *del-not-a*[rule-format]: $x \neq a \longrightarrow x \in set\ l \longrightarrow x \in set\ (del\ a\ l)$
 $\langle proof \rangle$

lemma *nodup-down-notin*[rule-format]: $nodup\ a\ l \longrightarrow nodup\ a\ (del\ aa\ l)$
 $\langle proof \rangle$

lemma *move-graph-eq*: $move-graph-a\ a\ l\ l\ g = g$
 $\langle proof \rangle$

lemma *delta-invariant*: $\forall\ z\ z'.\ z \rightarrow_n z' \longrightarrow delta(z) = delta(z')$
 $\langle proof \rangle$

lemma *init-state-policy0*:
 assumes $\forall\ z\ z'.\ z \rightarrow_n z' \longrightarrow delta(z) = delta(z')$
 and $(x,y) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*$
 shows $delta(x) = delta(y)$
 $\langle proof \rangle$

lemma *init-state-policy*: $\llbracket (x,y) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^* \rrbracket \implies$
 $delta(x) = delta(y)$
 $\langle proof \rangle$

lemma *same-nodes0*[rule-format]: $\forall\ z\ z'.\ z \rightarrow_n z' \longrightarrow nodes(graphI\ z) = nodes(graphI\ z')$
 $\langle proof \rangle$

lemma *same-nodes*: $(I, y) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*$
 $\implies nodes(graphI\ y) = nodes(graphI\ I)$
 $\langle proof \rangle$

lemma *same-actors0*[rule-format]: $\forall\ z\ z'.\ z \rightarrow_n z' \longrightarrow actors-graph(graphI\ z) = actors-graph(graphI\ z')$
 $\langle proof \rangle$

lemma *same-actors*: $(I, y) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*$
 $\implies actors-graph(graphI\ I) = actors-graph(graphI\ y)$
 $\langle proof \rangle$

end

end

theory *Airplane*

imports *AirInsider*

begin

```

declare [[show-types]]

datatype doorstate = locked | norm | unlocked
datatype position = air | airport | ground

locale airplane =

fixes airplane-actors :: identity set
defines airplane-actors-def: airplane-actors  $\equiv$  {"Bob", "Charly", "Alice"}

fixes airplane-locations :: location set
defines airplane-locations-def:
airplane-locations  $\equiv$  {Location 0, Location 1, Location 2}

fixes cockpit :: location
defines cockpit-def: cockpit  $\equiv$  Location 2
fixes door :: location
defines door-def: door  $\equiv$  Location 1
fixes cabin :: location
defines cabin-def: cabin  $\equiv$  Location 0

fixes global-policy :: [infrastructure, identity]  $\Rightarrow$  bool
defines global-policy-def: global-policy I a  $\equiv$  a  $\notin$  airplane-actors
 $\longrightarrow \neg(\text{enables } I \text{ cockpit } (\text{Actor } a) \text{ put})$ 

fixes ex-creds :: actor  $\Rightarrow$  (string list * string list)
defines ex-creds-def: ex-creds  $\equiv$ 
  ( $\lambda$  x. (if x = Actor "Bob"
    then (["PIN"], ["pilot"])
    else (if x = Actor "Charly"
      then (["PIN"], ["copilot"])
      else (if x = Actor "Alice"
        then (["PIN"], ["flightattendant"])
        else ([], []))))))

fixes ex-locs :: location  $\Rightarrow$  string list
defines ex-locs-def: ex-locs  $\equiv$  ( $\lambda$  x. if x = door then ["norm"] else
  (if x = cockpit then ["air"] else []))

fixes ex-locs' :: location  $\Rightarrow$  string list
defines ex-locs'-def: ex-locs'  $\equiv$  ( $\lambda$  x. if x = door then ["locked"] else
  (if x = cockpit then ["air"] else []))

fixes ex-graph :: igraph
defines ex-graph-def: ex-graph  $\equiv$  Lgraph
  {(cockpit, door), (door, cabin)}
  ( $\lambda$  x. if x = cockpit then ["Bob", "Charly"])

```

```

      else (if x = door then []
            else (if x = cabin then ["Alice'"] else [])))
ex-creds ex-locs

```

```

fixes aid-graph :: igraph
defines aid-graph-def: aid-graph  $\equiv$  Lgraph
  {(cockpit, door),(door,cabin)}
  ( $\lambda$  x. if x = cockpit then ["Charly'"]
    else (if x = door then []
          else (if x = cabin then ["Bob", "Alice'"] else [])))
ex-creds ex-locs'

```

```

fixes aid-graph0 :: igraph
defines aid-graph0-def: aid-graph0  $\equiv$  Lgraph
  {(cockpit, door),(door,cabin)}
  ( $\lambda$  x. if x = cockpit then ["Charly'"]
    else (if x = door then ["Bob'"]
          else (if x = cabin then ["Alice'"] else [])))
ex-creds ex-locs

```

```

fixes agid-graph :: igraph
defines agid-graph-def: agid-graph  $\equiv$  Lgraph
  {(cockpit, door),(door,cabin)}
  ( $\lambda$  x. if x = cockpit then ["Charly'"]
    else (if x = door then []
          else (if x = cabin then ["Bob", "Alice'"] else [])))
ex-creds ex-locs

```

```

fixes local-policies :: [igraph, location]  $\Rightarrow$  policy set
defines local-policies-def: local-policies G  $\equiv$ 
  ( $\lambda$  y. if y = cockpit then
    {( $\lambda$  x. (? n. (n @G cockpit)  $\wedge$  Actor n = x), {put}),
      ( $\lambda$  x. (? n. (n @G cabin)  $\wedge$  Actor n = x  $\wedge$  has G (x, "PIN")
         $\wedge$  isin G door "norm"),{move})
    }
  else (if y = door then {( $\lambda$  x. True, {move}),
    ( $\lambda$  x. (? n. (n @G cockpit)  $\wedge$  Actor n = x), {put})}
    else (if y = cabin then {( $\lambda$  x. True, {move})}
      else {})))

```

```

fixes local-policies-four-eyes :: [igraph, location]  $\Rightarrow$  policy set
defines local-policies-four-eyes-def: local-policies-four-eyes G  $\equiv$ 
  ( $\lambda$  y. if y = cockpit then
    {( $\lambda$  x. (? n. (n @G cockpit)  $\wedge$  Actor n = x)  $\wedge$ 
      2  $\leq$  length(agra G y)  $\wedge$  ( $\forall$  h  $\in$  set(agra G y). h  $\in$  airplane-actors),
    {put}),

```

$$\begin{aligned}
& (\lambda x. (? n. (n @_G \text{cabin}) \wedge \text{Actor } n = x \wedge \text{has } G(x, \text{"PIN"}) \wedge \\
& \quad \text{isin } G \text{ door "norm"}), \{\text{move}\}) \\
& \} \\
& \text{else (if } y = \text{door then} \\
& \quad \{(\lambda x. ((? n. (n @_G \text{cockpit}) \wedge \text{Actor } n = x) \wedge 3 \leq \text{length}(\text{agra } G \\
& \text{cockpit})), \{\text{move}\})\} \\
& \quad \text{else (if } y = \text{cabin then} \\
& \quad \quad \{(\lambda x. ((? n. (n @_G \text{door}) \wedge \text{Actor } n = x)), \{\text{move}\})\} \\
& \quad \quad \text{else \{\}}))
\end{aligned}$$

fixes *Airplane-scenario* :: *infrastructure*
defines *Airplane-scenario-def*:
Airplane-scenario \equiv *Infrastructure ex-graph local-policies*

fixes *Airplane-in-danger* :: *infrastructure*
defines *Airplane-in-danger-def*:
Airplane-in-danger \equiv *Infrastructure aid-graph local-policies*

fixes *Airplane-getting-in-danger0* :: *infrastructure*
defines *Airplane-getting-in-danger0-def*:
Airplane-getting-in-danger0 \equiv *Infrastructure aid-graph0 local-policies*

fixes *Airplane-getting-in-danger* :: *infrastructure*
defines *Airplane-getting-in-danger-def*:
Airplane-getting-in-danger \equiv *Infrastructure agid-graph local-policies*

fixes *Air-states*
defines *Air-states-def*: *Air-states* $\equiv \{ I. \text{Airplane-scenario} \rightarrow_n^* I \}$

fixes *Air-Kripke*
defines *Air-Kripke* \equiv *Kripke Air-states \{Airplane-scenario\}*

fixes *Airplane-not-in-danger* :: *infrastructure*
defines *Airplane-not-in-danger-def*:
Airplane-not-in-danger \equiv *Infrastructure aid-graph local-policies-four-eyes*

fixes *Airplane-not-in-danger-init* :: *infrastructure*
defines *Airplane-not-in-danger-init-def*:
Airplane-not-in-danger-init \equiv *Infrastructure ex-graph local-policies-four-eyes*

fixes *Air-tp-states*

defines *Air-tp-states-def*: *Air-tp-states* $\equiv \{ I. \text{Airplane-not-in-danger-init} \rightarrow_n^* I \}$

fixes *Air-tp-Kripke*

defines *Air-tp-Kripke* $\equiv \text{Kripke } \text{Air-tp-states} \{ \text{Airplane-not-in-danger-init} \}$

fixes *Safety* :: [*infrastructure*, *identity*] \Rightarrow *bool*

defines *Safety-def*: *Safety* *I* *a* $\equiv a \in \text{airplane-actors}$
 $\longrightarrow (\text{enables } I \text{ cockpit } (\text{Actor } a) \text{ move})$

fixes *Security* :: [*infrastructure*, *identity*] \Rightarrow *bool*

defines *Security-def*: *Security* *I* *a* $\equiv (\text{isin } (\text{graphI } I) \text{ door } \text{"locked"})$
 $\longrightarrow \neg(\text{enables } I \text{ cockpit } (\text{Actor } a) \text{ move})$

fixes *foe-control* :: [*location*, *action*] \Rightarrow *bool*

defines *foe-control-def*: *foe-control* *l* *c* \equiv
 $(! I :: \text{infrastructure}. (? x :: \text{identity}.$
 $x @_{\text{graphI } I} l \wedge \text{Actor } x \neq \text{Actor } \text{"Eve"})$
 $\longrightarrow \neg(\text{enables } I l (\text{Actor } \text{"Eve"}) c))$

assumes *Eve-precipitating-event*: *tipping-point* (*astate* *"Eve"*)

assumes *Insider-Eve*: *Insider* *"Eve"* {*"Charly"*}

assumes *isin-inj*: $\forall G. \text{inj } (\text{isin } G \text{ door})$

assumes *cockpit-foe-control*: *foe-control* *cockpit* *put*

begin

lemma *ex-inv*: *global-policy* *Airplane-scenario* *"Bob"*
 $\langle \text{proof} \rangle$

lemma *ex-inv2*: *global-policy* *Airplane-scenario* *"Charly"*
 $\langle \text{proof} \rangle$

lemma *ex-inv3*: $\neg \text{global-policy } \text{Airplane-scenario } \text{"Eve"}$
 $\langle \text{proof} \rangle$

lemma *Safety*: *Safety* *Airplane-scenario* (*"Alice"*)
 $\langle \text{proof} \rangle$

lemma *inj-lem*: $\llbracket \text{inj } f; x \neq y \rrbracket \implies f x \neq f y$
 $\langle \text{proof} \rangle$

lemma *locl-lemma0*: *isin* *G* *door* *"norm"* \neq *isin* *G* *door* *"locked"*
 $\langle \text{proof} \rangle$

lemma *locl-lemma: isin G door "norm" = (\neg isin G door "locked")*
<proof>

lemma *Security: Security Airplane-scenario s*
<proof>

lemma *Security-problem: Security Airplane-scenario "Bob"*
<proof>

lemma *pilot-can-leave-cockpit: (enables Airplane-scenario cabin (Actor "Bob")*
move)
<proof>

lemma *ex-inv4: \neg global-policy Airplane-in-danger ("Eve")*
<proof>

lemma *Safety-in-danger:*
 fixes *s*
 assumes *s \in airplane-actors*
 shows *\neg (Safety Airplane-in-danger s)*
<proof>

lemma *Security-problem': \neg (enables Airplane-in-danger cockpit (Actor "Bob")*
move)
<proof>

lemma *ex-inv5: $a \in$ airplane-actors \longrightarrow global-policy Airplane-not-in-danger a*
<proof>

lemma *ex-inv6: global-policy Airplane-not-in-danger a*
<proof>

lemma *step0: Airplane-scenario \rightarrow_n Airplane-getting-in-danger0*
<proof>

lemma *step1: Airplane-getting-in-danger0 \rightarrow_n Airplane-getting-in-danger*
<proof>

lemma *step2: Airplane-getting-in-danger \rightarrow_n Airplane-in-danger*
<proof>

lemma *step0r: Airplane-scenario \rightarrow_n^* Airplane-getting-in-danger0*
<proof>

lemma *step1r*: *Airplane-getting-in-danger0* \rightarrow_n^* *Airplane-getting-in-danger*
 $\langle \text{proof} \rangle$

lemma *step2r*: *Airplane-getting-in-danger* \rightarrow_n^* *Airplane-in-danger*
 $\langle \text{proof} \rangle$

theorem *step-allr*: *Airplane-scenario* \rightarrow_n^* *Airplane-in-danger*
 $\langle \text{proof} \rangle$

theorem *aid-attack*: *Air-Kripke* $\vdash EF \{x. \neg \text{global-policy } x \text{ "Eve"}\}$
 $\langle \text{proof} \rangle$

lemma *actors-unique-loc-base*:
assumes $I \rightarrow_n I'$
and $(\forall l l'. a @_{\text{graph} I} l \wedge a @_{\text{graph} I} l' \longrightarrow l = l') \wedge$
 $(\forall l. \text{nodup } a (\text{agra } (\text{graph} I) l))$
shows $(\forall l l'. a @_{\text{graph} I'} l \wedge a @_{\text{graph} I'} l' \longrightarrow l = l') \wedge$
 $(\forall l. \text{nodup } a (\text{agra } (\text{graph} I') l))$
 $\langle \text{proof} \rangle$

lemma *actors-unique-loc-step*:
assumes $(I, I') \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*$
and $\forall a. (\forall l l'. a @_{\text{graph} I} l \wedge a @_{\text{graph} I} l' \longrightarrow l = l') \wedge$
 $(\forall l. \text{nodup } a (\text{agra } (\text{graph} I) l))$
shows $\forall a. (\forall l l'. a @_{\text{graph} I'} l \wedge a @_{\text{graph} I'} l' \longrightarrow l = l') \wedge$
 $(\forall l. \text{nodup } a (\text{agra } (\text{graph} I') l))$
 $\langle \text{proof} \rangle$

lemma *actors-unique-loc-aid-base*:
 $\forall a. (\forall l l'. a @_{\text{graph} I} \text{Airplane-not-in-danger-init } l \wedge$
 $a @_{\text{graph} I} \text{Airplane-not-in-danger-init } l' \longrightarrow l = l') \wedge$
 $(\forall l. \text{nodup } a (\text{agra } (\text{graph} I) \text{Airplane-not-in-danger-init } l))$
 $\langle \text{proof} \rangle$

lemma *actors-unique-loc-aid-step*:
 $(\text{Airplane-not-in-danger-init}, I) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*$
 $\implies \forall a. (\forall l l'. a @_{\text{graph} I} l \wedge a @_{\text{graph} I} l' \longrightarrow l = l') \wedge$
 $(\forall l. \text{nodup } a (\text{agra } (\text{graph} I) l))$
 $\langle \text{proof} \rangle$

lemma *Anid-airplane-actors*: $\text{actors-graph } (\text{graph} I \text{Airplane-not-in-danger-init}) =$
 airplane-actors

$\langle \text{proof} \rangle$

lemma *all-airplane-actors*: $(\text{Airplane-not-in-danger-init}, y) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*$
 $\implies \text{actors-graph}(\text{graphI } y) = \text{airplane-actors}$
 $\langle \text{proof} \rangle$

lemma *actors-at-loc-in-graph*: $\llbracket l \in \text{nodes}(\text{graphI } I); a \text{ @}_{\text{graphI } I} l \rrbracket$
 $\implies a \in \text{actors-graph } (\text{graphI } I)$
 $\langle \text{proof} \rangle$

lemma *not-en-get-Apnid*:
assumes $(\text{Airplane-not-in-danger-init}, y) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*$
shows $\sim(\text{enables } y \text{ l (Actor } a) \text{ get})$
 $\langle \text{proof} \rangle$

lemma *Apnid-tsp-test*: $\sim(\text{enables Airplane-not-in-danger-init cockpit (Actor "Alice") get})$
 $\langle \text{proof} \rangle$

lemma *Apnid-tsp-test-gen*: $\sim(\text{enables Airplane-not-in-danger-init l (Actor } a) \text{ get})$
 $\langle \text{proof} \rangle$

lemma *test-graph-atI*: $\text{"Bob"} \text{ @}_{\text{graphI Airplane-not-in-danger-init cockpit}}$
 $\langle \text{proof} \rangle$

lemma *two-person-inv*:
fixes $z \ z'$
assumes $(2::\text{nat}) \leq \text{length } (\text{agra } (\text{graphI } z) \text{ cockpit})$
and $\text{nodes}(\text{graphI } z) = \text{nodes}(\text{graphI Airplane-not-in-danger-init})$
and $\text{delta}(z) = \text{delta}(\text{Airplane-not-in-danger-init})$
and $(\text{Airplane-not-in-danger-init}, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*$
and $z \rightarrow_n z'$
shows $(2::\text{nat}) \leq \text{length } (\text{agra } (\text{graphI } z') \text{ cockpit})$
 $\langle \text{proof} \rangle$

lemma *two-person-inv1*:
assumes $(\text{Airplane-not-in-danger-init}, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*$
shows $(2::\text{nat}) \leq \text{length } (\text{agra } (\text{graphI } z) \text{ cockpit})$
 $\langle \text{proof} \rangle$

lemma *nodup-card-insert*:

$a \notin \text{set } l \longrightarrow \text{card } (\text{insert } a \text{ (set } l)) = \text{Suc } (\text{card } (\text{set } l))$
 $\langle \text{proof} \rangle$

lemma *no-dup-set-list-num-eq*[*rule-format*]:

$(\forall a. \text{nodup } a \text{ } l) \longrightarrow \text{card } (\text{set } l) = \text{length } l$
 $\langle \text{proof} \rangle$

lemma *two-person-set-inv*:

assumes $(\text{Airplane-not-in-danger-init}, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*$
shows $(2::\text{nat}) \leq \text{card } (\text{set } (\text{agra } (\text{graphI } z) \text{ cockpit}))$
 $\langle \text{proof} \rangle$

lemma *Pred-all-unique*: $\bigwedge P. (\llbracket \forall x. (P x \longrightarrow (x = c)) \rrbracket \Longrightarrow P c)$
 $\langle \text{proof} \rangle$

lemma *Pred-all-unique*: $\llbracket ? x. P x; (! x. P x \longrightarrow x = c) \rrbracket \Longrightarrow P c$
 $\langle \text{proof} \rangle$

lemma *Set-all-unique*: $\llbracket S \neq \{\}; (\forall x \in S. x = c) \rrbracket \Longrightarrow c \in S$
 $\langle \text{proof} \rangle$

lemma *airplane-actors-inv0*[*rule-format*]:

$\forall z z'. (\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } z) \text{ cockpit}). h \in \text{airplane-actors}) \wedge$
 $(\text{Airplane-not-in-danger-init}, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^* \wedge$
 $z \rightarrow_n z' \longrightarrow (\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } z') \text{ cockpit}). h \in$
 $\text{airplane-actors})$
 $\langle \text{proof} \rangle$

lemma *airplane-actors-inv*:

assumes $(\text{Airplane-not-in-danger-init}, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*$
shows $\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } z) \text{ cockpit}). h \in \text{airplane-actors}$
 $\langle \text{proof} \rangle$

lemma *Eve-not-in-cockpit*: $(\text{Airplane-not-in-danger-init}, I)$
 $\in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^* \Longrightarrow$
 $x \in \text{set } (\text{agra } (\text{graphI } I) \text{ cockpit}) \Longrightarrow x \neq \text{"Eve"}$
 $\langle \text{proof} \rangle$

lemma *tp-imp-control*:

assumes $(\text{Airplane-not-in-danger-init}, I) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*$
shows $(? x :: \text{identity}. x @_{\text{graphI } I} \text{ cockpit} \wedge \text{Actor } x \neq \text{Actor "Eve"})$
 $\langle \text{proof} \rangle$

lemma *Fend-2*: $(Airplane-not-in-danger-init, I) \in \{(x::infrastructure, y::infrastructure)\}.$
 $x \rightarrow_n y\}^* \implies$
 $\neg enables\ I\ cockpit\ (Actor\ "Eve")\ put$
 $\langle proof \rangle$

theorem *Four-eyes-no-danger*: $Air-tp-Kripke \vdash AG\ (\{x.\ global-policy\ x\ "Eve"\})$
 $\langle proof \rangle$

end

end