

# Applying the Isabelle Insider Framework to Airplane Security

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## Abstract

Avionics is one of the fields in which verification methods have been pioneered and brought a new level of reliability to systems used in safety critical environments. Tragedies, like the 2015 insider attack on a German airplane, in which all 150 people on board died, show that safety and security crucially depend not only on the well functioning of systems but also on the way how humans interact with the systems. Policies are a way to describe how humans should behave in their interactions with technical systems, formal reasoning about such policies requires integrating the human factor into the verification process.

We model insider attacks on airplanes using logical modelling and analysis of infrastructure models and policies with actors to scrutinize security policies in the presence of insiders [1]. The Isabelle Insider framework framework has been first presented in [3]. Triggered by case studies, like the present one of airplane security, it has been greatly extended now formalizing Kripke structures and the temporal logic CTL to enable reasoning on dynamic system states. Furthermore, we illustrate that Isabelle modelling and invariant reasoning reveal subtle security assumptions: the formal development uses locales to model the assumptions on insider and their access credentials. Technically interesting is how the locale is interpreted in the presence of an abstract type declaration for actor in the Insider framework redefining this type declaration at a later stage like a “post-hoc type definition” as proposed in [4]. The case study and the application of the methodology are described in more detail in the preprint [2].

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# 1 Fixpoint lemmas to support the definition of Kripke structures and CTL

```

theory MC
imports Main
begin

thm monotone-def
definition monotone :: ('a set  $\Rightarrow$  'a set)  $\Rightarrow$  bool
where monotone  $\tau \equiv (\forall p\ q. p \subseteq q \longrightarrow \tau\ p \subseteq \tau\ q)$ 

lemma monotoneE: monotone  $\tau \Longrightarrow p \subseteq q \Longrightarrow \tau\ p \subseteq \tau\ q$ 
by (simp add: monotone-def)

lemma lfp1: monotone  $\tau \longrightarrow (\text{lfp } \tau = \bigcap \{Z. \tau\ Z \subseteq Z\})$ 
by (simp add: monotone-def lfp-def)

lemma gfp1: monotone  $\tau \longrightarrow (\text{gfp } \tau = \bigcup \{Z. Z \subseteq \tau\ Z\})$ 
by (simp add: monotone-def gfp-def)

primrec power :: ['a  $\Rightarrow$  'a, nat]  $\Rightarrow$  ('a  $\Rightarrow$  'a) ((-  $\wedge$  -) 40)
where
  power-zero: (f  $\wedge$  0) = ( $\lambda x. x$ ) |
  power-suc: (f  $\wedge$  (Suc n)) = (f o (f  $\wedge$  n))

lemma predtrans-empty:
  assumes monotone  $\tau$ 
  shows  $\forall i. (\tau \wedge i) (\{\}) \subseteq (\tau \wedge (i + 1)) (\{\})$ 
proof (rule allI, induct-tac i)
  show  $(\tau \wedge 0::\text{nat}) \{\} \subseteq (\tau \wedge (0::\text{nat}) + (1::\text{nat})) \{\}$  by simp
next show  $\bigwedge (i::\text{nat})\ n::\text{nat}. (\tau \wedge n) \{\} \subseteq (\tau \wedge n + (1::\text{nat})) \{\}$ 
   $\Longrightarrow (\tau \wedge \text{Suc } n) \{\} \subseteq (\tau \wedge \text{Suc } n + (1::\text{nat})) \{\}$ 
  proof -
    fix i n
    assume a :  $(\tau \wedge n) \{\} \subseteq (\tau \wedge n + (1::\text{nat})) \{\}$ 
    have  $(\tau ((\tau \wedge n) \{\})) \subseteq (\tau ((\tau \wedge (n + (1::\text{nat})))) \{\}))$  using assms
    apply (rule monotoneE)
    by (rule a)
    thus  $(\tau \wedge \text{Suc } n) \{\} \subseteq (\tau \wedge \text{Suc } n + (1::\text{nat})) \{\}$  by simp
  qed
qed

lemma ex-card: finite S  $\Longrightarrow \exists n::\text{nat}. \text{card } S = n$ 
by simp

lemma less-not-le:  $\llbracket (x::\text{nat}) < y; y \leq x \rrbracket \Longrightarrow \text{False}$ 
by arith

lemma infchain-outruns-all:

```

```

assumes finite (UNIV :: 'a set)
  and  $\forall i :: \text{nat}. (\tau \wedge i) \{\} :: 'a \text{ set} \subset (\tau \wedge i + (1 :: \text{nat})) \{\}$ 
shows  $\forall j :: \text{nat}. \exists i :: \text{nat}. j < \text{card} ((\tau \wedge i) \{\})$ 
proof (rule allI, induct-tac j)
  show  $\exists i :: \text{nat}. (0 :: \text{nat}) < \text{card} ((\tau \wedge i) \{\})$  using assms
    apply (drule-tac x = 0 in spec)
    apply (rule-tac x = 1 in exI)
    apply simp
    apply (subgoal-tac card \{\} = 0)
    apply (erule subst)
    apply (rule psubset-card-mono)
    apply (rule-tac B = UNIV in finite-subset)
    apply simp
    apply assumption+
    by simp
next show  $\bigwedge (j :: \text{nat}) n :: \text{nat}. \exists i :: \text{nat}. n < \text{card} ((\tau \wedge i) \{\})$ 
   $\implies \exists i :: \text{nat}. \text{Suc } n < \text{card} ((\tau \wedge i) \{\})$ 
proof -
  fix j n
  assume a:  $\exists i :: \text{nat}. n < \text{card} ((\tau \wedge i) \{\})$ 
  obtain i where  $n < \text{card} ((\tau \wedge (i :: \text{nat})) \{\})$ 
    apply (rule exE)
    apply (rule a)
    by simp
  thus  $\exists i. \text{Suc } n < \text{card} ((\tau \wedge i) \{\})$  using assms
    apply (rule-tac x = i + 1 in exI)
    apply (subgoal-tac card((\tau \wedge i) \{\}) < card((\tau \wedge i + (1 :: nat)) \{\}))
    apply arith
    apply (rule psubset-card-mono)
    apply (rule-tac B = UNIV in finite-subset)
    apply simp
    apply (rule assms)
    by (erule spec)
qed
qed

```

**lemma** *no-infinite-subset-chain*:

```

assumes finite (UNIV :: 'a set)
  and monotone ( $\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})$ )
  and  $\forall i :: \text{nat}. ((\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}) \wedge i) \{\} \subset (\tau \wedge i + (1 :: \text{nat})) (\{\} :: 'a \text{ set})$ 
shows False

```

idea: Since *UNIV* is finite, we have from *ex\_card* that there is an *n* with  $\text{card } UNIV = n$ . Now, use *infchain\_outruns\_all* to show as contradiction point that  $\exists i. \text{card } UNIV < \text{card} ((\tau \wedge i) \{\})$ . Since all sets are subsets of *UNIV*, we also have  $\text{card} ((\tau \wedge i) \{\}) \leq \text{card } UNIV$ : Contradiction!, i.e. proof of *False*

**proof** -

```

have a:  $\forall (j :: \text{nat}). (\exists (i :: \text{nat}). (j :: \text{nat}) < \text{card}((\tau \wedge i)(\{\} :: 'a \text{ set})))$  using
  assms
  apply (erule-tac  $\tau = \tau$  in infchain-outruns-all)
  by assumption
hence b:  $\exists (n :: \text{nat}). \text{card}(UNIV :: 'a \text{ set}) = n$  using assms
  by (erule-tac  $S = UNIV$  in ex-card)
from this obtain n where c:  $\text{card}(UNIV :: 'a \text{ set}) = n$  by (erule exE)
hence d:  $\exists i :: \text{nat}. \text{card } UNIV < \text{card } ((\tau \wedge i) \{\})$  using a
  apply (drule-tac  $x = \text{card } UNIV$  in spec)
  by assumption
from this obtain i where e:  $\text{card } (UNIV :: 'a \text{ set}) < \text{card } ((\tau \wedge i) \{\})$ 
  by (erule exE)
hence f:  $(\text{card}((\tau \wedge i)\{\})) \leq (\text{card } (UNIV :: 'a \text{ set}))$  using assms
  thm Finite-Set.card-mono
  apply (rule-tac  $A = ((\tau \wedge i)\{\})$  in Finite-Set.card-mono)
  apply assumption
  by (rule subset-UNIV)
thus False using e
  thm less-not-le
  apply (erule-tac  $y = \text{card}((\tau \wedge i)\{\})$  in less-not-le)
  by assumption
qed

```

**lemma** *finite-fixp*:

```

assumes finite( $UNIV :: 'a \text{ set}$ )
  and monotone ( $\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})$ )
shows  $\exists i. (\tau \wedge i) (\{\}) = (\tau \wedge (i + 1))(\{\})$ 

```

idea: with *predtrans-empty* we know  $\forall i. (\tau \wedge i) \{\} \subseteq (\tau \wedge i + 1) \{\}$  (1). If we can additionally show  $\exists i. (\tau \wedge i + 1) \{\} \subseteq (\tau \wedge i) \{\}$  (2), we can get the goal together with equality  $I \subseteq + \supseteq \longrightarrow =$ . To prove (1) we observe that  $(\tau \wedge i + 1) \{\} \subseteq (\tau \wedge i) \{\}$  can be inferred from  $\neg (\tau \wedge i) \{\} \subseteq (\tau \wedge i + 1) \{\}$  and (1). Finally, the latter is solved directly by *no\_infinite\_subset\_chain*.

**proof** –

```

have a:  $\forall i :: \text{nat}. (\tau \wedge i) (\{\}) :: 'a \text{ set} \subseteq (\tau \wedge i + (1 :: \text{nat})) \{\}$ 
  thm predtrans-empty
  apply (rule predtrans-empty)
  by (rule assms(2))
hence b:  $(\exists i :: \text{nat}. \neg ((\tau \wedge i) \{\} \subset (\tau \wedge (i + 1)) \{\}))$  using assms
  apply (subgoal-tac  $\neg (\forall i :: \text{nat}. (\tau \wedge i) \{\} \subset (\tau \wedge (i + 1)) \{\}))$ 
  apply blast
  apply (rule notI)
  apply (rule no-infinite-subset-chain)
  by assumption
thus  $\exists i. (\tau \wedge i) (\{\}) = (\tau \wedge (i + 1))(\{\})$  using a
  by blast

```

**qed**

**lemma** *predtrans-UNIV*:

```

    assumes monotone  $\tau$ 
    shows  $\forall i. (\tau \wedge i) (UNIV) \supseteq (\tau \wedge (i + 1))(UNIV)$ 
  proof (rule allI, induct-tac i)
    show  $(\tau \wedge (0::nat) + (1::nat)) UNIV \subseteq (\tau \wedge 0::nat) UNIV$  by simp
  next show  $\bigwedge(i::nat) n::nat. (\tau \wedge n + (1::nat)) UNIV \subseteq (\tau \wedge n) UNIV \implies (\tau \wedge Suc\ n + (1::nat)) UNIV \subseteq (\tau \wedge Suc\ n) UNIV$ 
  proof -
    fix i n
    assume a:  $(\tau \wedge n + (1::nat)) UNIV \subseteq (\tau \wedge n) UNIV$ 
    have  $(\tau ((\tau \wedge n) UNIV)) \supseteq (\tau ((\tau \wedge (n + (1 :: nat)))) UNIV))$  using assms
    apply (rule monotoneE)
    by (rule a)
    thus  $(\tau \wedge Suc\ n + (1::nat)) UNIV \subseteq (\tau \wedge Suc\ n) UNIV$  by simp
  qed
qed

lemma Suc-less-le:  $x < (y - n) \implies x \leq (y - (Suc\ n))$ 
  by simp

lemma card-univ-subtract:
  assumes finite  $(UNIV :: 'a\ set)$  and monotone  $(\tau :: 'a\ set \Rightarrow 'a\ set)$ 
  and  $(\forall i :: nat. ((\tau :: 'a\ set \Rightarrow 'a\ set) \wedge i + (1 :: nat)) (UNIV :: 'a\ set) \subset (\tau \wedge i) UNIV)$ 
  shows  $(\forall i :: nat. card((\tau \wedge i) (UNIV :: 'a\ set)) \leq (card (UNIV :: 'a\ set)) - i)$ 
  proof (rule allI, induct-tac i)
    show  $card((\tau \wedge 0::nat) UNIV) \leq card (UNIV :: 'a\ set) - (0::nat)$  using assms
    by (simp)
  next show  $\bigwedge(i::nat) n::nat. card((\tau \wedge n) (UNIV :: 'a\ set)) \leq card (UNIV :: 'a\ set) - n \implies card((\tau \wedge Suc\ n) (UNIV :: 'a\ set)) \leq card (UNIV :: 'a\ set) - Suc\ n$  using
  assms
  proof -
    fix i n
    assume a:  $card((\tau \wedge n) (UNIV :: 'a\ set)) \leq card (UNIV :: 'a\ set) - n$ 
    have b:  $(\tau \wedge n + (1::nat)) (UNIV :: 'a\ set) \subset (\tau \wedge n) UNIV$  using assms
    by (erule-tac  $x = n$  in spec)
    have  $card((\tau \wedge n + (1 :: nat)) (UNIV :: 'a\ set)) < card((\tau \wedge n) (UNIV :: 'a\ set))$ 
    apply (rule psubset-card-mono)
    apply (rule finite-subset)
    apply (rule subset-UNIV)
    apply (rule assms(1))
    by (rule b)
    thus  $card((\tau \wedge Suc\ n) (UNIV :: 'a\ set)) \leq card (UNIV :: 'a\ set) - Suc\ n$ 
  using a
  by simp
  qed
qed

```

**lemma** *card-UNIV-tau-i-below-zero*:

**assumes** *finite* (*UNIV* :: 'a set) **and** *monotone* ( $\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}$ )  
**and**  $(\forall i :: \text{nat}. ((\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}) \wedge i + (1 :: \text{nat})) (UNIV :: 'a \text{ set}) \subset (\tau \wedge i) UNIV)$   
**shows**  $\text{card}((\tau \wedge (\text{card } (UNIV :: 'a \text{ set}))) (UNIV :: 'a \text{ set})) \leq 0$   
**proof** –  
**have**  $(\forall i :: \text{nat}. \text{card}((\tau \wedge i) (UNIV :: 'a \text{ set})) \leq (\text{card } (UNIV :: 'a \text{ set})) - i)$   
**using** *assms*  
**by** (*rule card-univ-subtract*)  
**thus**  $\text{card}((\tau \wedge (\text{card } (UNIV :: 'a \text{ set}))) (UNIV :: 'a \text{ set})) \leq 0$   
**apply** (*drule-tac x = card (UNIV :: 'a set) in spec*)  
**by** *simp*  
**qed**

**lemma** *finite-card-zero-empty*:  $\llbracket \text{finite } S; \text{card } S \leq 0 \rrbracket \Rightarrow S = \{\}$   
**by** *simp*

**lemma** *UNIV-tau-i-is-empty*:

**assumes** *finite* (*UNIV* :: 'a set) **and** *monotone* ( $\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}$ )  
**and**  $(\forall i :: \text{nat}. ((\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}) \wedge i + (1 :: \text{nat})) (UNIV :: 'a \text{ set}) \subset (\tau \wedge i) UNIV)$   
**shows**  $(\tau \wedge (\text{card } (UNIV :: 'a \text{ set}))) (UNIV :: 'a \text{ set}) = \{\}$   
**proof** –  
**have**  $\text{card } ((\tau \wedge \text{card } (UNIV :: 'a \text{ set})) UNIV) \leq (0 :: \text{nat})$  **using** *assms*  
**apply** (*rule card-UNIV-tau-i-below-zero*)  
**·**  
**thus**  $(\tau \wedge (\text{card } (UNIV :: 'a \text{ set}))) (UNIV :: 'a \text{ set}) = \{\}$  **using** *assms*  
**apply** (*rule-tac S = (\tau \wedge (\text{card } (UNIV :: 'a \text{ set}))) (UNIV :: 'a \text{ set}) in finite-card-zero-empty*)  
**apply** (*rule finite-subset*)  
**apply** (*rule subset-UNIV*)  
**·**  
**qed**

**lemma** *down-chain-reaches-empty*:

**assumes** *finite* (*UNIV* :: 'a set) **and** *monotone* ( $\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}$ )  
**and**  $(\forall i :: \text{nat}. ((\tau :: 'a \text{ set} \Rightarrow 'a \text{ set}) \wedge i + (1 :: \text{nat})) UNIV \subset (\tau \wedge i) UNIV)$   
**shows**  $\exists (j :: \text{nat}). (\tau \wedge j) UNIV = \{\}$   
**proof** –  
**have**  $(\tau \wedge ((\text{card } (UNIV :: 'a \text{ set})))) UNIV = \{\}$  **using** *assms*  
**apply** (*rule UNIV-tau-i-is-empty*)  
**·**  
**thus**  $\exists (j :: \text{nat}). (\tau \wedge j) UNIV = \{\}$   
**by** (*rule exI*)  
**qed**

**lemma** *no-infinite-subset-chain2*:

**assumes** *finite* (*UNIV* :: 'a set) **and** *monotone* ( $\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})$ )

and  $\forall i :: \text{nat}. (\tau \wedge i) \text{ UNIV} \supset (\tau \wedge i + (1 :: \text{nat})) \text{ UNIV}$   
 shows *False*  
**proof** –  
 have  $\exists j :: \text{nat}. (\tau \wedge j) \text{ UNIV} = \{\}$  **using** *assms*  
 apply (rule *down-chain-reaches-empty*)  
 .  
 from *this* **obtain** *j* **where** *a*:  $(\tau \wedge j) \text{ UNIV} = \{\}$  **by** (erule *exE*)  
 have  $(\tau \wedge j + (1 :: \text{nat})) \text{ UNIV} \subset (\tau \wedge j) \text{ UNIV}$  **using** *assms*  
 by (erule-tac *x = j* in *spec*)  
 thus *False* **using** *a* **by** *simp*  
**qed**

**lemma** *finite-fixp2*:  
 assumes *finite*(*UNIV* :: 'a set) **and** *monotone* ( $\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})$ )  
 shows  $\exists i. (\tau \wedge i) \text{ UNIV} = (\tau \wedge (i + 1)) \text{ UNIV}$   
**proof** –  
 have  $\forall i :: \text{nat}. (\tau \wedge i + (1 :: \text{nat})) \text{ UNIV} \subseteq (\tau \wedge i) \text{ UNIV}$   
 apply (rule *predtrans-UNIV*) **using** *assms*  
 by (*simp add: assms(2)*)  
 moreover have  $\exists i :: \text{nat}. \neg (\tau \wedge i + (1 :: \text{nat})) \text{ UNIV} \subset (\tau \wedge i) \text{ UNIV}$  **using**  
*assms*  
**proof** –  
 have  $\neg (\forall i :: \text{nat}. (\tau \wedge i) \text{ UNIV} \supset (\tau \wedge (i + 1)) \text{ UNIV})$   
 apply (rule *notI*)  
 apply (rule *no-infinite-subset-chain2*) **using** *assms*  
 .  
 thus  $\exists i :: \text{nat}. \neg (\tau \wedge i + (1 :: \text{nat})) \text{ UNIV} \subset (\tau \wedge i) \text{ UNIV}$  **by** *blast*  
**qed**  
 ultimately show  $\exists i. (\tau \wedge i) \text{ UNIV} = (\tau \wedge (i + 1)) \text{ UNIV}$   
 by *blast*  
**qed**

**lemma** *mono-monotone*:  $\text{mono } (\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})) \Longrightarrow \text{monotone } \tau$   
**by** (*simp add: monotone-def mono-def*)

**lemma** *monotone-mono*:  $\text{monotone } (\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})) \Longrightarrow \text{mono } \tau$   
**by** (*simp add: monotone-def mono-def*)

**lemma** *power-power*:  $((\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})) \wedge \wedge n) = ((\tau :: ('a \text{ set} \Rightarrow 'a \text{ set})) \wedge n)$   
**proof** (*induct-tac n*)  
 show  $\tau \wedge \wedge (0 :: \text{nat}) = (\tau \wedge 0 :: \text{nat})$  **by** (*simp add: id-def*)  
 next show  $\bigwedge n :: \text{nat}. \tau \wedge \wedge n = (\tau \wedge n) \Longrightarrow \tau \wedge \wedge \text{Suc } n = (\tau \wedge \text{Suc } n)$   
 by *simp*  
**qed**

**lemma** *lfp-Kleene-iter-set*:  $\text{monotone } (f :: ('a \text{ set} \Rightarrow 'a \text{ set})) \Longrightarrow$   
 $(f \wedge \text{Suc}(n)) \{\} = (f \wedge n) \{\} \Longrightarrow \text{lfp } f = (f \wedge n) \{\}$   
**by** (*simp add: monotone-mono lfp-Kleene-iter power-power*)

```

lemma lfp-loop:
  assumes finite (UNIV :: 'b set) and monotone ( $\tau :: ('b \text{ set} \Rightarrow 'b \text{ set})$ )
  shows  $\exists n . \text{lfp } \tau = (\tau \wedge n) \{\}$ 
proof -
  have  $\exists i :: \text{nat} . (\tau \wedge i) \{\} = (\tau \wedge i + (1 :: \text{nat})) \{\}$  using assms
    by (rule finite-fixp)
  from this obtain i where  $(\tau \wedge i) \{\} = (\tau \wedge i + (1 :: \text{nat})) \{\}$ 
    by (erule exE)
  hence  $(\tau \wedge i) \{\} = (\tau \wedge \text{Suc } i) \{\}$ 
    by simp
  hence  $(\tau \wedge \text{Suc } i) \{\} = (\tau \wedge i) \{\}$ 
    by (rule sym)
  hence  $\text{lfp } \tau = (\tau \wedge i) \{\}$ 
    by (simp add: assms(2) lfp-Kleene-iter-set)
  thus  $\exists n . \text{lfp } \tau = (\tau \wedge n) \{\}$ 
    by (rule exI)
qed

```

These next two are produced as duals from the corresponding theorems in HOL/ZF/Nat.thy. Would make sense to have them in the HOL/Library

```

lemma Kleene-iter-gpfp:
assumes mono f and  $p \leq f p$  shows  $p \leq (f \wedge^k) (\text{top} :: 'a :: \text{order-top})$ 
proof(induction k)
  case 0 show ?case by simp
next
  case Suc
    from monoD[OF assms(1) Suc] assms(2)
    show ?case by simp
qed

```

```

lemma gfp-Kleene-iter: assumes mono f and  $(f \wedge^{\text{Suc } k} \text{top}) = (f \wedge^k) \text{top}$ 
shows  $\text{gfp } f = (f \wedge^k) \text{top}$ 
proof(rule antisym)
  show  $(f \wedge^k) \text{top} \leq \text{gfp } f$ 
    proof(rule gfp-upperbound)
      show  $(f \wedge^k) \text{top} \leq f ((f \wedge^k) \text{top})$  using assms(2) by simp
    qed
  next
    show  $\text{gfp } f \leq (f \wedge^k) \text{top}$ 
      using Kleene-iter-gpfp[OF assms(1)] gfp-unfold[OF assms(1)] by simp
    qed

```

```

lemma gfp-Kleene-iter-set:
  assumes monotone ( $f :: ('a \text{ set} \Rightarrow 'a \text{ set})$ )
    and  $(f \wedge \text{Suc}(n)) \text{UNIV} = (f \wedge n) \text{UNIV}$ 
  shows  $\text{gfp } f = (f \wedge n) \text{UNIV}$ 
proof -
  have a: mono f using assms

```



```

    by (erule-tac  $\tau = f$  in monotone-mono)
  hence b:  $(f \hat{\ } \text{Suc } (n)) \text{ UNIV} = (f \hat{\ } n) \text{ UNIV}$  using assms
    by (simp add: power-power)
  hence c:  $\text{gfp } f = (f \hat{\ } (n))(\text{UNIV} :: 'a \text{ set})$  using assms a
    thm gfp-Kleene-iter
    apply (erule-tac  $f = f$  and  $k = n$  in gfp-Kleene-iter)
  .
  thus  $\text{gfp } f = (f \hat{\ } (n))(\text{UNIV} :: 'a \text{ set})$  using assms a
    by (simp add: power-power)
qed

```

lemma gfp-loop:

```

  assumes finite (UNIV :: 'b set)
  and monotone ( $\tau :: ('b \text{ set} \Rightarrow 'b \text{ set})$ )
  shows  $\exists n . \text{gfp } \tau = (\tau \hat{\ } n)(\text{UNIV} :: 'b \text{ set})$ 
proof -
  have  $\exists i :: \text{nat}. (\tau \hat{\ } i)(\text{UNIV} :: 'b \text{ set}) = (\tau \hat{\ } i + (1 :: \text{nat})) \text{ UNIV}$  using assms
    by (rule finite-fixp2)
  from this obtain i where  $(\tau \hat{\ } i)(\text{UNIV} :: 'b \text{ set}) = (\tau \hat{\ } i + (1 :: \text{nat})) \text{ UNIV}$ 
  by (erule exE)
  thus  $\exists n . \text{gfp } \tau = (\tau \hat{\ } n)(\text{UNIV} :: 'b \text{ set})$  using assms
    apply (rule-tac  $x = i$  in exI)
    apply (rule gfp-Kleene-iter-set)
    apply assumption
    apply (rule sym)
    by simp
qed

```

Definitions of the generic type of state with state transition and CTL Operators

```

class state =
  fixes state-transition :: [ $'a :: \text{type}$ ,  $'a$ ]  $\Rightarrow$  bool  $((- \rightarrow_i -) \ 50)$ 

```

definition AX where  $\text{AX } f \equiv \{s. \{f0. s \rightarrow_i f0\} \subseteq f\}$

definition EX' where  $\text{EX}' f \equiv \{s . \exists f0 \in f. s \rightarrow_i f0\}$

definition AF where  $\text{AF } f \equiv \text{lfp } (\lambda Z. f \cup \text{AX } Z)$

definition EF where  $\text{EF } f \equiv \text{lfp } (\lambda Z. f \cup \text{EX}' Z)$

definition AG where  $\text{AG } f \equiv \text{gfp } (\lambda Z. f \cap \text{AX } Z)$

definition EG where  $\text{EG } f \equiv \text{gfp } (\lambda Z. f \cap \text{EX}' Z)$

definition AU where  $\text{AU } f1 f2 \equiv \text{lfp}(\lambda Z. f2 \cup (f1 \cap \text{AX } Z))$

definition EU where  $\text{EU } f1 f2 \equiv \text{lfp}(\lambda Z. f2 \cup (f1 \cap \text{EX}' Z))$

definition AR where  $\text{AR } f1 f2 \equiv \text{gfp}(\lambda Z. f2 \cap (f1 \cup \text{AX } Z))$

definition ER where  $\text{ER } f1 f2 \equiv \text{gfp}(\lambda Z. f2 \cap (f1 \cup \text{EX}' Z))$

Kripke and Modelchecking

```

datatype 'a kripke =
  Kripke 'a set 'a set

```

**primrec** *states* **where** *states* (*Kripke S I*) = *S*  
**primrec** *init* **where** *init* (*Kripke S I*) = *I*

**definition** *check* ( $- \vdash -$  50)  
**where**  $M \vdash f \equiv (\text{init } M) \subseteq \{s \in (\text{states } M). s \in f\}$

**definition** *state-transition-refl* ( $(- \rightarrow_{i*} -)$  50)  
**where**  $s \rightarrow_{i*} s' \equiv ((s, s') \in \{(x, y). \text{state-transition } x \ y\}^*)$

Support lemmas

**lemma** *EF-lem0*:  $(x \in EF \ f) = (x \in f \cup EX' \ (\text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set. } f \cup EX' \ Z)))$

**proof** –

**have**  $\text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set. } f \cup EX' \ Z) =$   
 $f \cup (EX' \ (\text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set. } f \cup EX' \ Z)))$   
**apply** (*rule def-lfp-unfold*)  
**apply** (*rule reflexive*)  
**apply** (*unfold mono-def EX'-def*)  
**by** *auto*  
**thus**  $(x \in EF \ (f :: ('a :: \text{state}) \text{ set})) = (x \in f \cup EX' \ (\text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set. } f \cup EX' \ Z)))$   
**by** (*simp add: EF-def*)  
**qed**

**lemma** *EF-lem00*:  $(EF \ f) = (f \cup EX' \ (\text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set. } f \cup EX' \ Z)))$

**proof** (*rule equalityI*)

**show**  $EF \ f \subseteq f \cup EX' \ (\text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set. } f \cup EX' \ Z))$   
**apply** (*rule subsetI*)  
**by** (*simp add: EF-lem0*)  
**next show**  $f \cup EX' \ (\text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set. } f \cup EX' \ Z)) \subseteq EF \ f$   
**apply** (*rule subsetI*)  
**by** (*simp add: EF-lem0*)  
**qed**

**lemma** *EF-lem000*:  $(EF \ f) = (f \cup EX' \ (EF \ f))$

**proof** (*subst EF-lem00*)

**show**  $f \cup EX' \ (\text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set. } f \cup EX' \ Z)) = f \cup EX' \ (EF \ f)$   
**apply** (*fold EF-def*)  
**by** (*rule refl*)  
**qed**

**lemma** *EF-lem1*:  $x \in f \vee x \in (EX' \ (EF \ f)) \implies x \in EF \ f$

**proof** (*simp add: EF-def*)

**assume**  $a: x \in f \vee x \in EX' \ (\text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set. } f \cup EX' \ Z))$   
**show**  $x \in \text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set. } f \cup EX' \ Z)$   
**proof** –  
**have**  $b: \text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set. } f \cup EX' \ Z) =$   
 $f \cup (EX' \ (\text{lfp } (\lambda Z :: ('a :: \text{state}) \text{ set. } f \cup EX' \ Z)))$   
**apply** (*rule def-lfp-unfold*)

```

      apply (rule reflexive)
      apply (unfold mono-def EX'-def)
      by auto
    thus  $x \in \text{lfp } (\lambda Z::'a \text{ set. } f \cup EX' Z)$  using  $a$ 
      apply (subst  $b$ )
      by blast
  qed
qed

```

```

lemma EF-lem2b:
  assumes  $x \in (EX' (EF f))$ 
  shows  $x \in EF f$ 
proof (rule EF-lem1)
  show  $x \in f \vee x \in EX' (EF f)$ 
    apply (rule disjI2)
    by (rule assms)
qed

```

```

lemma EF-lem2a: assumes  $x \in f$  shows  $x \in EF f$ 
proof (rule EF-lem1)
  show  $x \in f \vee x \in EX' (EF f)$ 
    apply (rule disjI1)
    by (rule assms)
qed

```

```

lemma EF-lem2c: assumes  $x \notin f$  shows  $x \in EF (- f)$ 
proof -
  have  $x \in (- f)$  using assms
  by simp
  thus  $x \in EF (- f)$ 
    by (rule EF-lem2a)
qed

```

```

lemma EF-lem2d: assumes  $x \notin EF f$  shows  $x \notin f$ 
proof -
  have  $x \in f \implies x \in EF f$ 
    by (erule EF-lem2a)
  thus  $x \notin f$  using assms
    thm contrapos-nn
  apply (erule-tac  $P = x \in f$  in contrapos-nn)
  apply (erule meta-mp)
  .
qed

```

```

lemma EF-lem3b: assumes  $x \in EX' (f \cup EX' (EF f))$  shows  $x \in (EF f)$ 
proof (simp add: EF-lem0)
  show  $x \in f \vee x \in EX' (\text{lfp } (\lambda Z::'a \text{ set. } f \cup EX' Z))$ 
    apply (rule disjI2)
    apply (fold EF-def)

```

**apply** (*subst EF-lem00*)  
**apply** (*fold EF-def*)  
**by** (*rule asms*)  
**qed**

**lemma** *EX-lem0l*:  $x \in (EX' f) \implies x \in (EX' (f \cup g))$   
**proof** (*unfold EX'-def*)  
**show**  $x \in \{s :: 'a. \exists f0 :: 'a \in f. s \rightarrow_i f0\} \implies x \in \{s :: 'a. \exists f0 :: 'a \in f \cup g. s \rightarrow_i f0\}$   
**by** *blast*  
**qed**

**lemma** *EX-lem0r*:  $x \in (EX' g) \implies x \in (EX' (f \cup g))$   
**proof** (*unfold EX'-def*)  
**show**  $x \in \{s :: 'a. \exists f0 :: 'a \in g. s \rightarrow_i f0\} \implies x \in \{s :: 'a. \exists f0 :: 'a \in f \cup g. s \rightarrow_i f0\}$   
**by** *blast*  
**qed**

**lemma** *EX-step*: **assumes**  $x \rightarrow_i y$  **and**  $y \in f$  **shows**  $x \in EX' f$   
**proof** (*unfold EX'-def*)  
**show**  $x \in \{s :: 'a. \exists f0 :: 'a \in f. s \rightarrow_i f0\}$   
**apply** *simp*  
**apply** (*rule-tac*  $x = y$  **in** *bexI*)  
**by** (*rule asms*)+  
**qed**

**lemma** *EF-E[rule-format]*:  $\forall f. x \in (EF (f :: ('a :: state) set)) \longrightarrow x \in (f \cup EX' (EF f))$   
**proof** –  
**have**  $a: \bigwedge f :: 'a \text{ set}. EF (f :: ('a :: state) set) = f \cup EX' (EF f)$   
**by** (*rule EF-lem000*)  
**thus**  $(\forall f. x \in EF (f :: ('a :: state) set) \longrightarrow x \in f \cup EX' (EF f))$   
**apply** (*rule-tac*  $P = (\lambda f. x \in EF (f :: ('a :: state) set) \longrightarrow x \in f \cup EX' (EF f))$  **in** *allI*)  
**apply** (*subst a*)  
**apply** (*rule impI*)  
**by** *assumption*  
**qed**

**lemma** *EF-step*: **assumes**  $x \rightarrow_i y$  **and**  $y \in f$  **shows**  $x \in EF f$   
**proof** (*rule EF-lem3b*)  
**show**  $x \in EX' (f \cup EX' (EF f))$   
**apply** (*rule EX-step*)  
**apply** (*rule asms(1)*)  
**by** (*simp add: asms(2)*)  
**qed**

**lemma** *EF-step-step*: **assumes**  $x \rightarrow_i y$  **and**  $y \in EF f$  **shows**  $x \in EF f$   
**proof** –  
**have**  $y \in f \cup EX' (EF f)$

**apply** (*rule EF-E*)  
**by** (*rule assms(2)*)  
**thus**  $x \in EF\ f$   
**apply** (*rule-tac*  $x = x$  **and**  $f = f$  **in** *EF-lem3b*)  
**apply** (*rule EX-step*)  
**by** (*rule assms*)  
**qed**

**lemma** *EF-step-star*:  $\llbracket x \rightarrow_{i^*} y; y \in f \rrbracket \implies x \in EF\ f$   
**proof** (*simp add: state-transition-refl-def*)  
**show**  $(x, y) \in \{(x::'a, y::'a). x \rightarrow_i y\}^* \implies y \in f \implies x \in EF\ f$   
**proof** (*erule converse-rtrancl-induct*)  
**show**  $y \in f \implies y \in EF\ f$   
**by** (*erule EF-lem2a*)  
**next show**  $\bigwedge (ya::'a) z::'a. y \in f \implies$   
 $(ya, z) \in \{(x::'a, y::'a). x \rightarrow_i y\} \implies$   
 $(z, y) \in \{(x::'a, y::'a). x \rightarrow_i y\}^* \implies z \in EF\ f \implies ya \in EF\ f$   
**apply** (*clarify*)  
**apply** (*erule EF-step-step*)  
**by** *assumption*  
**qed**  
**qed**

**lemma** *EF-induct-prep*:  
**assumes**  $(a::'a::state) \in \text{lfp } (\lambda Z. (f::'a::state\ set) \cup EX'\ Z)$   
**and**  $\text{mono } (\lambda Z. (f::'a::state\ set) \cup EX'\ Z)$   
**shows**  $(\bigwedge x::'a::state.$   
 $x \in ((\lambda Z. (f::'a::state\ set) \cup EX'\ Z)(\text{lfp } (\lambda Z. (f::'a::state\ set) \cup EX'\ Z) \cap$   
 $\{x::'a::state. (P::'a::state \Rightarrow \text{bool})\ x})) \implies P\ x) \implies$   
 $P\ a$   
**proof** –  
**show**  $(\bigwedge x::'a::state.$   
 $x \in ((\lambda Z. (f::'a::state\ set) \cup EX'\ Z)(\text{lfp } (\lambda Z. (f::'a::state\ set) \cup EX'\ Z) \cap$   
 $\{x::'a::state. (P::'a::state \Rightarrow \text{bool})\ x})) \implies P\ x) \implies$   
 $P\ a$   
**apply** (*rule-tac*  $A = EF\ f$  **in** *def-lfp-induct-set*)  
**apply** (*rule EF-def*)  
**apply** (*rule assms(2)*)  
**by** (*simp add: EF-def assms*)  
**qed**

**lemma** *EF-induct*:  $(a::'a::state) \in EF\ (f :: 'a :: state\ set) \implies$   
 $\text{mono } (\lambda Z. (f::'a::state\ set) \cup EX'\ Z) \implies$   
 $(\bigwedge x::'a::state.$   
 $x \in ((\lambda Z. (f::'a::state\ set) \cup EX'\ Z)(EF\ f \cap \{x::'a::state. (P::'a::state \Rightarrow$   
 $\text{bool})\ x})) \implies P\ x) \implies$   
 $P\ a$   
**proof** (*simp add: EF-def*)  
**show**  $a \in \text{lfp } (\lambda Z::'a\ set. f \cup EX'\ Z) \implies$

$\text{mono } (\lambda Z::'a \text{ set. } f \cup EX' Z) \implies$   
 $(\bigwedge x::'a. x \in f \vee x \in EX' (\text{lfp } (\lambda Z::'a \text{ set. } f \cup EX' Z) \cap \text{Collect } P) \implies P x)$   
 $\implies P a$   
**apply** (erule EF-induct-prep)  
**apply** assumption  
**by** simp  
**qed**

**lemma** valEF-E:  $M \vdash EF f \implies x \in \text{init } M \implies x \in EF f$   
**proof** (simp add: check-def)  
**show**  $\text{init } M \subseteq \{s::'a \in \text{states } M. s \in EF f\} \implies x \in \text{init } M \implies x \in EF f$   
**apply** (drule subsetD)  
**apply** assumption  
**by** simp  
**qed**

**lemma** EF-step-star-rev[rule-format]:  $x \in EF s \implies (\exists y \in s. x \rightarrow_i^* y)$   
**proof** (erule EF-induct)  
**show**  $\text{mono } (\lambda Z::'a \text{ set. } s \cup EX' Z)$   
**apply** (simp add: mono-def EX'-def)  
**by** force  
**next show**  $\bigwedge x::'a. x \in s \cup EX' (EF s \cap \{x::'a. \exists y::'a \in s. x \rightarrow_i^* y\}) \implies \exists y::'a \in s. x \rightarrow_i^* y$   
**apply** (erule UnE)  
**apply** (rule-tac  $x = x$  in bexI)  
**apply** (simp add: state-transition-refl-def)  
**apply** assumption  
**apply** (simp add: EX'-def)  
**apply** (erule bexE)  
**apply** (erule IntE)  
**apply** (drule CollectD)  
**apply** (erule bexE)  
**apply** (rule-tac  $x = xb$  in bexI)  
**apply** (simp add: state-transition-refl-def)  
**apply** (rule rtrancl-trans)  
**apply** (rule r-into-rtrancl)  
**apply** (rule CollectI)  
**apply** simp  
**by** assumption+  
**qed**

**lemma** EF-step-inv:  $(I \subseteq \{sa::'s :: \text{state. } (\exists i::'s \in I. i \rightarrow_i^* sa) \wedge sa \in EF s\})$   
 $\implies \forall x \in I. \exists y \in s. x \rightarrow_i^* y$   
**proof** (clarify)  
**show**  $\bigwedge x::'s. I \subseteq \{sa::'s. (\exists i::'s \in I. i \rightarrow_i^* sa) \wedge sa \in EF s\} \implies x \in I \implies \exists y::'s \in s. x \rightarrow_i^* y$   
**apply** (drule subsetD)  
**apply** assumption  
**apply** (drule CollectD)

```

    apply (erule conjE)
    by (erule EF-step-star-rev)
qed

```

AG lemmas

```

lemma AG-in-lem:  $x \in AG\ s \implies x \in s$ 
proof (simp add: AG-def gfp-def)
  show  $\exists xa \subseteq s. xa \subseteq AX\ xa \wedge x \in xa \implies x \in s$ 
    apply (erule exE)
    apply (erule conjE)+
    by (erule subsetD, assumption)
qed

```

```

lemma AG-lem1:  $x \in s \wedge x \in (AX\ (AG\ s)) \implies x \in AG\ s$ 
proof (simp add: AG-def)
  show  $x \in s \wedge x \in AX\ (gfp\ (\lambda Z::'a\ set. s \cap AX\ Z)) \implies x \in gfp\ (\lambda Z::'a\ set. s \cap AX\ Z)$ 
    apply (subgoal-tac gfp (\lambda Z::'a set. s \cap AX Z) =
      s \cap (AX (gfp (\lambda Z::'a set. s \cap AX Z))))
    apply (erule ssubst)
    apply simp
    apply (rule def-gfp-unfold)
    apply (rule reflexive)
    apply (unfold mono-def AX-def)
    by auto
qed

```

```

lemma AG-lem2:  $x \in AG\ s \implies x \in (s \cap (AX\ (AG\ s)))$ 
proof -
  have a:  $AG\ s = s \cap (AX\ (AG\ s))$ 
    apply (simp add: AG-def)
    apply (rule def-gfp-unfold)
    apply (rule reflexive)
    apply (unfold mono-def AX-def)
    by auto
  thus  $x \in AG\ s \implies x \in (s \cap (AX\ (AG\ s)))$ 
    by (erule subst)
qed

```

```

lemma AG-lem3:  $AG\ s = (s \cap (AX\ (AG\ s)))$ 
proof (rule equalityI)
  show  $AG\ s \subseteq s \cap AX\ (AG\ s)$ 
    apply (rule subsetI)
    by (erule AG-lem2)
  next show  $s \cap AX\ (AG\ s) \subseteq AG\ s$ 
    apply (rule subsetI)
    apply (rule AG-lem1)
    by simp
qed

```

**lemma** *AG-step*:  $y \rightarrow_i z \implies y \in AG\ s \implies z \in AG\ s$   
**proof** (*drule AG-lem2*)  
 show  $y \rightarrow_i z \implies y \in s \cap AX\ (AG\ s) \implies z \in AG\ s$   
 apply (*erule IntE*)  
 apply (*unfold AX-def*)  
 apply *simp*  
 apply (*erule subsetD*)  
 by *simp*  
**qed**

**lemma** *AG-all-s*:  $x \rightarrow_i^* y \implies x \in AG\ s \implies y \in AG\ s$   
**proof** (*simp add: state-transition-refl-def*)  
 show  $(x, y) \in \{(x::'a, y::'a). x \rightarrow_i y\}^* \implies x \in AG\ s \implies y \in AG\ s$   
 apply (*erule rtrancl-induct*)  
**proof** –  
 show  $x \in AG\ s \implies x \in AG\ s$  **by** *assumption*  
 next show  $\bigwedge(y::'a) z::'a.$   
    $x \in AG\ s \implies$   
    $(x, y) \in \{(x::'a, y::'a). x \rightarrow_i y\}^* \implies$   
    $(y, z) \in \{(x::'a, y::'a). x \rightarrow_i y\} \implies y \in AG\ s \implies z \in AG\ s$   
 apply *clarify*  
 by (*erule AG-step, assumption*)  
**qed**  
**qed**

**lemma** *AG-imp-notnotEF*:  
 $I \neq \{\} \implies ((Kripke\ \{s :: ('s :: state). \exists i \in I. (i \rightarrow_i^* s)\} (I :: ('s :: state) set)$   
 $\vdash AG\ s)) \implies$   
 $(\neg(Kripke\ \{s :: ('s :: state). \exists i \in I. (i \rightarrow_i^* s)\} (I :: ('s :: state) set) \vdash EF\ (-$   
 $s)))$   
**proof** (*rule notI, simp add: check-def*)  
 assume *a0*:  $I \neq \{\}$  **and**  
    $a1: I \subseteq \{sa::'s. (\exists i::'s \in I. i \rightarrow_i^* sa) \wedge sa \in AG\ s\}$  **and**  
    $a2: I \subseteq \{sa::'s. (\exists i::'s \in I. i \rightarrow_i^* sa) \wedge sa \in EF\ (-\ s)\}$   
 show *False*  
**proof** –  
 have *a3*:  $\{sa::'s. (\exists i::'s \in I. i \rightarrow_i^* sa) \wedge sa \in AG\ s\} \cap$   
    $\{sa::'s. (\exists i::'s \in I. i \rightarrow_i^* sa) \wedge sa \in EF\ (-\ s)\} = \{\}$   
**proof** –  
 have  $(? x. x \in \{sa::'s. (\exists i::'s \in I. i \rightarrow_i^* sa) \wedge sa \in AG\ s\} \wedge$   
    $x \in \{sa::'s. (\exists i::'s \in I. i \rightarrow_i^* sa) \wedge sa \in EF\ (-\ s)\}) \implies$   
*False*  
**proof** –  
 assume *a4*:  $(? x. x \in \{sa::'s. (\exists i::'s \in I. i \rightarrow_i^* sa) \wedge sa \in AG\ s\} \wedge$   
    $x \in \{sa::'s. (\exists i::'s \in I. i \rightarrow_i^* sa) \wedge sa \in EF\ (-\ s)\})$   
 from *a4* **obtain** *x* **where** *a5*:  $x \in \{sa::'s. (\exists i::'s \in I. i \rightarrow_i^* sa) \wedge sa \in$   
 $AG\ s\} \wedge$   
    $x \in \{sa::'s. (\exists i::'s \in I. i \rightarrow_i^* sa) \wedge sa \in EF\ (-\ s)\}$



```

by (erule exE)
hence  $x \in s \wedge x \in -s$ 
proof -
  have  $a6: x \in s$  using  $a5$ 
  apply (subgoal-tac  $x \in AG\ s$ )
  apply (erule AG-in-lem)
  by simp
moreover have  $x \in -s$  using  $a5$ 
proof -
  have  $x \in EF\ s$ 
  apply (rule-tac  $y = x$  in  $EF\text{-step-star}$ )
  apply (simp add: state-transition-refl-def)
  by (rule  $a6$ )
thus  $x \in -s$  using  $a5$ 
proof -
  have  $x \in EF\ (-\ s)$  using  $a5$ 
  by simp
moreover from this obtain  $y$  where  $a7: y \in -\ s \wedge x \rightarrow_{i*} y$ 
  apply (rotate-tac -1)
  apply (drule EF-step-star-rev)
  by blast
moreover have  $y \in AG\ s$  using  $a7\ a5$ 
  apply (subgoal-tac  $x \in AG\ s$ )
  apply (erule conjE)
  apply (drule AG-all-s)
  apply assumption+
  by simp
ultimately show  $x \in -s$  using  $a5$ 
  apply (rotate-tac -1)
  apply (drule AG-in-lem)
  by blast
qed
qed
ultimately show  $x \in s \wedge x \in -s$ 
  by (rule conjI)
qed
thus False
  by blast
qed
thus  $\{sa::'s. (\exists i::'s \in I. i \rightarrow_{i*} sa) \wedge sa \in AG\ s\} \cap$ 
 $\{sa::'s. (\exists i::'s \in I. i \rightarrow_{i*} sa) \wedge sa \in EF\ (-\ s)\} = \{\}$ 
  by blast
qed
moreover have  $b: ?\ x. x : I$  using  $a0$ 
  by blast
moreover obtain  $x$  where  $x \in I$ 
  apply (rule exE)
  apply (rule  $b$ )
  by simp

```

```

    ultimately show False using a0 a1 a2
    by blast
qed
qed

lemma check2-def: (Kripke S I  $\vdash$  f) = (I  $\subseteq$  S  $\cap$  f)
proof (simp add: check-def)
  show (I  $\subseteq$  {s::'a  $\in$  S. s  $\in$  f}) = (I  $\subseteq$  S  $\wedge$  I  $\subseteq$  f) by blast
qed

end

```

## 2 Insider

```

theory AirInsider
imports MC
begin
datatype action = get | move | eval | put

```

We use an abstract type declaration *actor* that can later be instantiated by a more concrete type.

```

typedecl actor
consts Actor :: string  $\Rightarrow$  actor

```

Alternatives to the type declaration do not work.

context fixes *Abs Rep actor* assumes *td*: "type\_definition *Abs Rep actor*"  
begin definition *Actor* where "*Actor* = *Abs*" ...doesn't work for replacing the *actor* typedecl because in "type\_definition" above the "*actor*" is a set not a type! So can't be used for our purposes. Trying a locale instead for polymorphic type *Actor* locale *ACT* = fixes *Actor* :: "*string* =<sub>i</sub> '*actor*'" begin ... That is a nice idea and works quite far but clashes with the generic *state\_transition* later (it's not possible to instantiate within a locale and outside it we cannot instantiate "'a infrastructure" to state (clearly an abstract thing as an instance is strange)

```

type-synonym identity = string
type-synonym policy = ((actor  $\Rightarrow$  bool) * action set)

```

```

definition ID :: [actor, string]  $\Rightarrow$  bool
where ID a s  $\equiv$  (a = Actor s)

```

```

datatype location = Location nat

```

```

datatype igraph = Lgraph (location * location)set location  $\Rightarrow$  identity list
               actor  $\Rightarrow$  (string list * string list) location  $\Rightarrow$  string list

```

```

datatype infrastructure =
  Infrastructure igrph
  [igraph, location]  $\Rightarrow$  policy set

```

```

primrec loc :: location  $\Rightarrow$  nat
where loc(Location n) = n
primrec gra :: igrph  $\Rightarrow$  (location * location)set
where gra(Lgraph g a c l) = g
primrec agra :: igrph  $\Rightarrow$  (location  $\Rightarrow$  identity list)
where agra(Lgraph g a c l) = a
primrec cgra :: igrph  $\Rightarrow$  (actor  $\Rightarrow$  string list * string list)
where cgra(Lgraph g a c l) = c
primrec lgra :: igrph  $\Rightarrow$  (location  $\Rightarrow$  string list)
where lgra(Lgraph g a c l) = l

definition nodes :: igrph  $\Rightarrow$  location set
where nodes g == { x. (? y. ((x,y): gra g) | ((y,x): gra g)) }

definition actors-graph :: igrph  $\Rightarrow$  identity set
where actors-graph g == { x. ? y. y : nodes g  $\wedge$  x  $\in$  set(agra g y) }

primrec graphI :: infrastructure  $\Rightarrow$  igrph
where graphI (Infrastructure g d) = g
primrec delta :: [infrastructure, igrph, location]  $\Rightarrow$  policy set
where delta (Infrastructure g d) = d
primrec tspace :: [infrastructure, actor]  $\Rightarrow$  string list * string list
where tspace (Infrastructure g d) = cgra g
primrec lspace :: [infrastructure, location]  $\Rightarrow$  string list
where lspace (Infrastructure g d) = lgra g

definition credentials :: string list * string list  $\Rightarrow$  string set
where credentials lxl  $\equiv$  set (fst lxl)
definition has :: [igrph, actor * string]  $\Rightarrow$  bool
where has G ac  $\equiv$  snd ac  $\in$  credentials(cgra G (fst ac))
definition roles :: string list * string list  $\Rightarrow$  string set
where roles lxl  $\equiv$  set (snd lxl)
definition role :: [igrph, actor * string]  $\Rightarrow$  bool
where role G ac  $\equiv$  snd ac  $\in$  roles(cgra G (fst ac))

definition isin :: [igrph, location, string]  $\Rightarrow$  bool
where isin G l s  $\equiv$  s  $\in$  set(lgra G l)

datatype psy-states = happy | depressed | disgruntled | angry | stressed
datatype motivations = financial | political | revenge | curious | competitive-advantage
| power | peer-recognition

datatype actor-state = Actor-state psy-states motivations set
primrec motivation :: actor-state  $\Rightarrow$  motivations set
where motivation (Actor-state p m) = m
primrec psy-state :: actor-state  $\Rightarrow$  psy-states
where psy-state (Actor-state p m) = p

```

**definition** *tipping-point* :: *actor-state*  $\Rightarrow$  *bool* **where**  
*tipping-point* *a*  $\equiv ((\text{motivation } a \neq \{\}) \wedge (\text{happy} \neq \text{psy-state } a))$

UasI and UasI' are the central predicates allowing to specify Insiders. They define which identities can be mapped to the same role by the Actor function. For all other identities, Actor is defined as injective on those identities.

**definition** *UasI* :: [*identity*, *identity*]  $\Rightarrow$  *bool*  
**where** *UasI* *a b*  $\equiv (\text{Actor } a = \text{Actor } b) \wedge (\forall x y. x \neq a \wedge y \neq a \wedge \text{Actor } x = \text{Actor } y \longrightarrow x = y)$

**definition** *UasI'* :: [*actor*  $\Rightarrow$  *bool*, *identity*, *identity*]  $\Rightarrow$  *bool*  
**where** *UasI'* *P a b*  $\equiv P (\text{Actor } b) \longrightarrow P (\text{Actor } a)$

Two versions of Insider predicate corresponding to UasI and UasI'. Under the assumption that the tipping point has been reached for a person *a* then *a* can impersonate all *b* (take all of *b*'s "roles") where the *b*'s are specified by a given set of identities

**definition** *Insider* :: [*identity*, *identity set*, *identity*  $\Rightarrow$  *actor-state*]  $\Rightarrow$  *bool*  
**where** *Insider* *a C as*  $\equiv (\text{tipping-point } (as \ a) \longrightarrow (\forall b \in C. \text{UasI } a \ b))$

**definition** *Insider'* :: [*actor*  $\Rightarrow$  *bool*, *identity*, *identity set*, *identity*  $\Rightarrow$  *actor-state*]  $\Rightarrow$  *bool*  
**where** *Insider'* *P a C as*  $\equiv (\text{tipping-point } (as \ a) \longrightarrow (\forall b \in C. \text{UasI}' \ P \ a \ b \wedge \text{inj-on Actor } C))$

**definition** *atI* :: [*identity*, *igraph*, *location*]  $\Rightarrow$  *bool* ( $- @_{(-)} - 50$ )  
**where**  $a @_G l \equiv a \in \text{set}(\text{agra } G \ l)$

*enables* is the central definition of the behaviour as given by a policy that specifies what actions are allowed in a certain location for what actors

**definition** *enables* :: [*infrastructure*, *location*, *actor*, *action*]  $\Rightarrow$  *bool*  
**where**  
*enables* *I l a a'*  $\equiv (\exists (p, e) \in \text{delta } I (\text{graphI } I) \ l. a' \in e \wedge p \ a)$

*behaviour* is the good behaviour, i.e. everything allowed by policy

**definition** *behaviour* :: *infrastructure*  $\Rightarrow$  (*location* \* *actor* \* *action*)*set*  
**where** *behaviour* *I*  $\equiv \{(t, a, a'). \text{enables } I \ t \ a \ a'\}$

*misbehaviour* is the complement of *behaviour*

**definition** *misbehaviour* :: *infrastructure*  $\Rightarrow$  (*location* \* *actor* \* *action*)*set*  
**where** *misbehaviour* *I*  $\equiv \neg(\text{behaviour } I)$

basic lemmas for *enable*

**lemma** *not-enableI*:  $(\forall (p, e) \in \text{delta } I (\text{graphI } I) \ l. (\sim(h : e) \mid (\sim(p(a)))) \implies \sim(\text{enables } I \ l \ a \ h))$   
**by** (*simp add: enables-def, blast*)

**lemma** *not-enableI2*:  $\llbracket \bigwedge p\ e. (p,e) \in \text{delta } I (\text{graphI } I) \ l \implies (\sim(t : e) \mid (\sim(p(a)))) \rrbracket \implies \sim(\text{enables } I \ l \ a \ t)$   
**by** (*rule not-enableI*, *rule ballI*, *auto*)

**lemma** *not-enableE*:  $\llbracket \sim(\text{enables } I \ l \ a \ t); (p,e) \in \text{delta } I (\text{graphI } I) \ l \rrbracket \implies (\sim(t : e) \mid (\sim(p(a))))$   
**by** (*simp add: enables-def*, *rule impI*, *force*)

**lemma** *not-enableE2*:  $\llbracket \sim(\text{enables } I \ l \ a \ t); (p,e) \in \text{delta } I (\text{graphI } I) \ l; t : e \rrbracket \implies (\sim(p(a)))$   
**by** (*simp add: enables-def*, *force*)

some constructions to deal with lists of actors in locations for the semantics of action move

**primrec** *del* ::  $[ 'a, 'a \text{ list}] \Rightarrow 'a \text{ list}$

**where**

*del-nil*:  $\text{del } a \ [] = []$

*del-cons*:  $\text{del } a \ (x \# ls) = (\text{if } x = a \text{ then } ls \text{ else } x \# (\text{del } a \ ls))$

**primrec** *jonce* ::  $[ 'a, 'a \text{ list}] \Rightarrow \text{bool}$

**where**

*jonce-nil*:  $\text{jonce } a \ [] = \text{False}$

*jonce-cons*:  $\text{jonce } a \ (x \# ls) = (\text{if } x = a \text{ then } (a \notin (\text{set } ls)) \text{ else } \text{jonce } a \ ls)$

**primrec** *nodup* ::  $[ 'a, 'a \text{ list}] \Rightarrow \text{bool}$

**where**

*nodup-nil*:  $\text{nodup } a \ [] = \text{True}$

*nodup-step*:  $\text{nodup } a \ (x \# ls) = (\text{if } x = a \text{ then } (a \notin (\text{set } ls)) \text{ else } \text{nodup } a \ ls)$

**definition** *move-graph-a* ::  $[\text{identity}, \text{location}, \text{location}, \text{igraph}] \Rightarrow \text{igraph}$

**where** *move-graph-a*  $n \ l \ l' \ g \equiv \text{Lgraph } (\text{gra } g)$

$(\text{if } n \in \text{set } ((\text{agra } g) \ l) \ \& \ n \notin \text{set } ((\text{agra } g) \ l') \text{ then}$

$((\text{agra } g)(l := \text{del } n \ (\text{agra } g \ l)))(l' := (n \# (\text{agra } g \ l')))$

$\text{else } (\text{agra } g))(cgra \ g)(lgra \ g)$

State transition relation over infrastructures (the states) defining the semantics of actions in systems with humans and potentially insiders \*)

**inductive** *state-transition-in* ::  $[\text{infrastructure}, \text{infrastructure}] \Rightarrow \text{bool } ((- \rightarrow_n -)$   
50)

**where**

*move*:  $\llbracket G = \text{graphI } I; a @_G l; l \in \text{nodes } G; l' \in \text{nodes } G;$

$(a) \in \text{actors-graph}(\text{graphI } I); \text{enables } I \ l' \ (\text{Actor } a) \text{ move};$

$I' = \text{Infrastructure } (\text{move-graph-a } a \ l \ l' (\text{graphI } I))(\text{delta } I) \rrbracket \implies I \rightarrow_n I'$

$\mid \text{get} : \llbracket G = \text{graphI } I; a @_G l; a' @_G l; \text{has } G \ (\text{Actor } a, z);$

$\text{enables } I \ l \ (\text{Actor } a) \text{ get};$

$I' = \text{Infrastructure}$

$(\text{Lgraph } (\text{gra } G)(\text{agra } G)$

$((cgra \ G)(\text{Actor } a' :=$

$(z \# (\text{fst}(cgra \ G \ (\text{Actor } a'))), \text{snd}(cgra \ G \ (\text{Actor } a')))))$

$$\begin{aligned}
& \quad (lgra \ G)) \\
& \quad (\delta I) \\
& \quad \mathbb{I} \implies I \rightarrow_n I' \\
| \text{ put} : & \mathbb{I} \ G = graphI \ I; \ a \ @_G \ l; \ enables \ I \ l \ (\text{Actor } a) \ \text{put}; \\
& \quad I' = Infrastructure \\
& \quad (Lgraph \ (gra \ G)(agra \ G)(cgra \ G) \\
& \quad \quad ((lgra \ G)(l := [z]))) \\
& \quad (\delta I) \ \mathbb{I} \\
& \implies I \rightarrow_n I' \\
| \text{ put-remote} : & \mathbb{I} \ G = graphI \ I; \ enables \ I \ l \ (\text{Actor } a) \ \text{put}; \\
& \quad I' = Infrastructure \\
& \quad (Lgraph \ (gra \ G)(agra \ G)(cgra \ G) \\
& \quad \quad ((lgra \ G)(l := [z]))) \\
& \quad (\delta I) \ \mathbb{I} \\
& \implies I \rightarrow_n I'
\end{aligned}$$

show that this infrastructure is a state as given in MC.thy

**instantiation** *infrastructure* :: *state*  
**begin**

**definition**

*state-transition-infra-def*:  $(i \rightarrow_i i') = (i \rightarrow_n (i' :: infrastructure))$

**instance**

**by** (*rule MC.class.MC.state.of-class.intro*)

**definition** *state-transition-in-refl*  $((- \rightarrow_n^* -) \ 50)$

**where**  $s \rightarrow_n^* s' \equiv ((s, s') \in \{(x, y). \text{state-transition-in } x \ y\}^*)$

**lemma** *del-del*[*rule-format*]:  $n \in \text{set } (del \ a \ S) \longrightarrow n \in \text{set } S$

**by** (*induct-tac S, auto*)

**lemma** *del-dec*[*rule-format*]:  $a \in \text{set } S \longrightarrow \text{length } (del \ a \ S) < \text{length } S$

**by** (*induct-tac S, auto*)

**lemma** *del-sort*[*rule-format*]:  $\forall \ n. (Suc \ n :: nat) \leq \text{length } (l) \longrightarrow n \leq \text{length } (del \ a \ (l))$

**by** (*induct-tac l, simp, clarify, case-tac n, simp, simp*)

**lemma** *del-jonce*:  $jonce \ a \ l \longrightarrow a \notin \text{set } (del \ a \ l)$

**by** (*induct-tac l, auto*)

**lemma** *del-nodup*[*rule-format*]:  $nodup \ a \ l \longrightarrow a \notin \text{set } (del \ a \ l)$

**by** (*induct-tac l, auto*)

**lemma** *nodup-up*[*rule-format*]:  $a \in \text{set } (del \ a \ l) \longrightarrow a \in \text{set } l$

**by** (*induct-tac l, auto*)

**lemma** *del-up* [*rule-format*]:  $a \in \text{set } (del \ aa \ l) \longrightarrow a \in \text{set } l$

**by** (*induct-tac l, auto*)

**lemma** *nodup-notin*[*rule-format*]:  $a \notin \text{set } list \longrightarrow \text{nodup } a \text{ list}$   
**by** (*induct-tac list, auto*)

**lemma** *nodup-down*[*rule-format*]:  $\text{nodup } a \text{ l} \longrightarrow \text{nodup } a \text{ (del } a \text{ l)}$   
**by** (*induct-tac l, simp+, clarify, erule nodup-notin*)

**lemma** *del-notin-down*[*rule-format*]:  $a \notin \text{set } list \longrightarrow a \notin \text{set } (\text{del } aa \text{ list})$   
**by** (*induct-tac list, auto*)

**lemma** *del-not-a*[*rule-format*]:  $x \neq a \longrightarrow x \in \text{set } l \longrightarrow x \in \text{set } (\text{del } a \text{ l})$   
**by** (*induct-tac l, auto*)

**lemma** *nodup-down-notin*[*rule-format*]:  $\text{nodup } a \text{ l} \longrightarrow \text{nodup } a \text{ (del } aa \text{ l)}$   
**by** (*induct-tac l, simp+, rule conjI, clarify, erule nodup-notin, (rule impI)+, erule del-notin-down*)

**lemma** *move-graph-eq*:  $\text{move-graph-a } a \text{ l l } g = g$   
**by** (*simp add: move-graph-a-def, case-tac g, force*)

Some useful properties about the invariance of the nodes, the actors, and the policy with respect to the state transition

**lemma** *delta-invariant*:  $\forall z z'. z \rightarrow_n z' \longrightarrow \text{delta}(z) = \text{delta}(z')$   
**by** (*clarify, erule state-transition-in.cases, simp+*)

**lemma** *init-state-policy0*:  
**assumes**  $\forall z z'. z \rightarrow_n z' \longrightarrow \text{delta}(z) = \text{delta}(z')$   
**and**  $(x, y) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*$   
**shows**  $\text{delta}(x) = \text{delta}(y)$   
**proof** –  
**have** *ind*:  $(x, y) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^* \longrightarrow \text{delta}(x) = \text{delta}(y)$   
**proof** (*insert assms, erule rtrancl.induct*)  
**show**  $(\bigwedge a::\text{infrastructure}. (\forall (z::\text{infrastructure})(z'::\text{infrastructure}). (z \rightarrow_n z') \longrightarrow (\text{delta } z = \text{delta } z'))$   
 $\implies$   
 $((((a, a) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*) \longrightarrow (\text{delta } a = \text{delta } a)))$   
**by** (*rule impI, rule refl*)

**next fix** *a b c*  
**assume** *a0*:  $\forall (z::\text{infrastructure}) z'::\text{infrastructure}. z \rightarrow_n z' \longrightarrow \text{delta } z = \text{delta } z'$   
**and** *a1*:  $(a, b) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*$   
**and** *a2*:  $(a, b) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^* \longrightarrow \text{delta } a = \text{delta } b$   
**and** *a3*:  $(b, c) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}$   
**show**  $(a, c) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^* \longrightarrow \text{delta } a = \text{delta } c$

```

proof –
  have  $a_4$ :  $\text{delta } b = \text{delta } c$  using  $a0\ a1\ a2\ a3$  by simp
  show ?thesis using  $a0\ a1\ a2\ a3$  by simp
qed
qed
show ?thesis
  by (insert ind, insert assms(2), simp)
qed

lemma init-state-policy:  $\llbracket (x,y) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^* \rrbracket \implies$ 

$$\text{delta}(x) = \text{delta}(y)$$

  by (rule init-state-policy0, rule delta-invariant)

lemma same-nodes0[rule-format]:  $\forall\ z\ z'. z \rightarrow_n z' \longrightarrow \text{nodes}(\text{graphI } z) = \text{nodes}(\text{graphI } z')$ 
  by (clarify, erule state-transition-in.cases,
    (simp add: move-graph-a-def atI-def actors-graph-def nodes-def)+)

lemma same-nodes:  $(I, y) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^* \implies \text{nodes}(\text{graphI } y) = \text{nodes}(\text{graphI } I)$ 
  by (erule rtrancl-induct, rule refl, drule CollectD, simp, drule same-nodes0, simp)

lemma same-actors0[rule-format]:  $\forall\ z\ z'. z \rightarrow_n z' \longrightarrow \text{actors-graph}(\text{graphI } z) = \text{actors-graph}(\text{graphI } z')$ 
proof (clarify, erule state-transition-in.cases)
  show  $\bigwedge (z::\text{infrastructure}) (z'::\text{infrastructure}) (G::\text{igraph}) (I::\text{infrastructure}) (a::\text{char list})$ 

$$(l::\text{location}) (a'::\text{char list}) (za::\text{char list}) I'::\text{infrastructure}.$$


$$z = I \implies$$


$$z' = I' \implies$$


$$G = \text{graphI } I \implies$$


$$a @_G l \implies$$


$$a' @_G l \implies$$


$$\text{has } G (\text{Actor } a, za) \implies$$


$$\text{enables } I\ l (\text{Actor } a) \text{ get} \implies$$


$$I' =$$


$$\text{Infrastructure}$$


$$(\text{Lgraph } (\text{gra } G) (\text{agra } G)$$


$$((\text{cgra } G)(\text{Actor } a' := (za \# \text{fst } (\text{cgra } G (\text{Actor } a'))), \text{snd } (\text{cgra } G (\text{Actor } a'))))) (\text{lgra } G))$$


$$(\text{delta } I) \implies$$


$$\text{actors-graph } (\text{graphI } z) = \text{actors-graph } (\text{graphI } z')$$

  by (simp add: actors-graph-def nodes-def)
next show  $\bigwedge (z::\text{infrastructure}) (z'::\text{infrastructure}) (G::\text{igraph}) (I::\text{infrastructure}) (a::\text{char list})$ 

$$(l::\text{location}) (I'::\text{infrastructure}) za::\text{char list}.$$


$$z = I \implies$$


```



```

 $z' = I' \implies$ 
 $G = \text{graphI } I \implies$ 
 $a @_G l \implies$ 
 $\text{enables } I \ l \ (\text{Actor } a) \ \text{put} \implies$ 
 $I' = \text{Infrastructure } (\text{Lgraph } (\text{gra } G) (\text{agra } G) (\text{cgra } G) ((\text{lgra } G)(l := [za])))$ 
 $(\text{delta } I) \implies$ 
 $\text{actors-graph } (\text{graphI } z) = \text{actors-graph } (\text{graphI } z')$ 
by (simp add: actors-graph-def nodes-def)
next show  $\bigwedge(z::\text{infrastructure}) (z'::\text{infrastructure}) (G::\text{igraph}) (I::\text{infrastructure})$ 
 $(l::\text{location})$ 
 $(a::\text{char list}) (I'::\text{infrastructure}) \text{ za}::\text{char list.}$ 
 $z = I \implies$ 
 $z' = I' \implies$ 
 $G = \text{graphI } I \implies$ 
 $\text{enables } I \ l \ (\text{Actor } a) \ \text{put} \implies$ 
 $I' = \text{Infrastructure } (\text{Lgraph } (\text{gra } G) (\text{agra } G) (\text{cgra } G) ((\text{lgra } G)(l := [za])))$ 
 $(\text{delta } I) \implies$ 
 $\text{actors-graph } (\text{graphI } z) = \text{actors-graph } (\text{graphI } z')$ 
by (simp add: actors-graph-def nodes-def)
next fix  $z \ z' \ G \ I \ a \ l \ l' \ I'$ 
show  $z = I \implies z' = I' \implies G = \text{graphI } I \implies a @_G l \implies$ 
 $l \in \text{nodes } G \implies l' \in \text{nodes } G \implies a \in \text{actors-graph } (\text{graphI } I) \implies$ 
 $\text{enables } I \ l' \ (\text{Actor } a) \ \text{move} \implies$ 
 $I' = \text{Infrastructure } (\text{move-graph-a } a \ l \ l' \ (\text{graphI } I)) \ (\text{delta } I) \implies$ 
 $\text{actors-graph } (\text{graphI } z) = \text{actors-graph } (\text{graphI } z')$ 
proof (rule equalityI)
show  $z = I \implies z' = I' \implies G = \text{graphI } I \implies a @_G l \implies$ 
 $l \in \text{nodes } G \implies l' \in \text{nodes } G \implies a \in \text{actors-graph } (\text{graphI } I) \implies$ 
 $\text{enables } I \ l' \ (\text{Actor } a) \ \text{move} \implies$ 
 $I' = \text{Infrastructure } (\text{move-graph-a } a \ l \ l' \ (\text{graphI } I)) \ (\text{delta } I) \implies$ 
 $\text{actors-graph } (\text{graphI } z) \subseteq \text{actors-graph } (\text{graphI } z')$ 
by (rule subsetI, simp add: actors-graph-def, (erule exE)+, case-tac x = a,
rule-tac x = l' in exI, simp add: move-graph-a-def nodes-def atI-def,
rule-tac x = ya in exI, rule conjI, simp add: move-graph-a-def nodes-def
atI-def,
(erule conjE)+, simp add: move-graph-a-def, rule conjI, clarify,
simp add: move-graph-a-def nodes-def atI-def, rule del-not-a, assumption+,
clarify)
next show  $z = I \implies z' = I' \implies G = \text{graphI } I \implies a @_G l \implies$ 
 $l \in \text{nodes } G \implies l' \in \text{nodes } G \implies a \in \text{actors-graph } (\text{graphI } I) \implies$ 
 $\text{enables } I \ l' \ (\text{Actor } a) \ \text{move} \implies$ 
 $I' = \text{Infrastructure } (\text{move-graph-a } a \ l \ l' \ (\text{graphI } I)) \ (\text{delta } I) \implies$ 
 $\text{actors-graph } (\text{graphI } z') \subseteq \text{actors-graph } (\text{graphI } z)$ 
by (rule subsetI, simp add: actors-graph-def, (erule exE)+,
case-tac x = a, rule-tac x = l in exI, simp add: move-graph-a-def nodes-def
atI-def,
rule-tac x = ya in exI, rule conjI, simp add: move-graph-a-def nodes-def
atI-def,
(erule conjE)+, simp add: move-graph-a-def, case-tac ya = l, simp,

```

```

      case-tac a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) l'), simp,
      case-tac l = l', simp+, erule del-up, simp,
      case-tac a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) l'), simp,
      case-tac ya = l', simp+)
qed
qed

lemma same-actors: (I, y) ∈ {(x::infrastructure, y::infrastructure). x →n y}*
  ⇒ actors-graph(graphI I) = actors-graph(graphI y)
proof (erule rtrancl-induct)
  show actors-graph (graphI I) = actors-graph (graphI I)
  by (rule refl)
next show ∧(y::infrastructure) z::infrastructure.
  (I, y) ∈ {(x::infrastructure, y::infrastructure). x →n y}* ⇒
  (y, z) ∈ {(x::infrastructure, y::infrastructure). x →n y} ⇒
  actors-graph (graphI I) = actors-graph (graphI y) ⇒
  actors-graph (graphI I) = actors-graph (graphI z)
  by (drule CollectD, simp, drule same-actors0, simp)
qed

end
end

```

### 3 Airplane case study

```

theory Airplane
imports AirInsider
begin
datatype doorstate = locked | norm | unlocked
datatype position = air | airport | ground

locale airplane =

  fixes airplane-actors :: identity set
  defines airplane-actors-def: airplane-actors ≡ {"Bob", "Charly", "Alice"}

  fixes airplane-locations :: location set
  defines airplane-locations-def:
    airplane-locations ≡ {Location 0, Location 1, Location 2}

  fixes cockpit :: location
  defines cockpit-def: cockpit ≡ Location 2
  fixes door :: location
  defines door-def: door ≡ Location 1
  fixes cabin :: location
  defines cabin-def: cabin ≡ Location 0

  fixes global-policy :: [infrastructure, identity] ⇒ bool
  defines global-policy-def: global-policy I a ≡ a ∉ airplane-actors

```

$\longrightarrow \neg(\text{enables } I \text{ cockpit } (\text{Actor } a) \text{ put})$

**fixes** *ex-creds* :: *actor*  $\Rightarrow$  (*string list* \* *string list*)

**defines** *ex-creds-def*: *ex-creds*  $\equiv$   
 $(\lambda x. (\text{if } x = \text{Actor } "Bob"$   
 $\quad \text{then } (["PIN"], ["pilot"])$   
 $\quad \text{else } (\text{if } x = \text{Actor } "Charly"$   
 $\quad \quad \text{then } (["PIN"], ["copilot"])$   
 $\quad \quad \text{else } (\text{if } x = \text{Actor } "Alice"$   
 $\quad \quad \quad \text{then } (["PIN"], ["flightattendant"])$   
 $\quad \quad \quad \text{else } ([], []))))$

**fixes** *ex-locs* :: *location*  $\Rightarrow$  *string list*

**defines** *ex-locs-def*: *ex-locs*  $\equiv$   $(\lambda x. \text{if } x = \text{door} \text{ then } ["norm"] \text{ else } (\text{if } x = \text{cockpit} \text{ then } ["air"] \text{ else } []))$

**fixes** *ex-locs'* :: *location*  $\Rightarrow$  *string list*

**defines** *ex-locs'-def*: *ex-locs'*  $\equiv$   $(\lambda x. \text{if } x = \text{door} \text{ then } ["locked"] \text{ else } (\text{if } x = \text{cockpit} \text{ then } ["air"] \text{ else } []))$

**fixes** *ex-graph* :: *igraph*

**defines** *ex-graph-def*: *ex-graph*  $\equiv$  *Lgraph*  
 $\{(cockpit, door), (door, cabin)\}$   
 $(\lambda x. \text{if } x = \text{cockpit} \text{ then } ["Bob", "Charly"]$   
 $\quad \text{else } (\text{if } x = \text{door} \text{ then } []$   
 $\quad \quad \text{else } (\text{if } x = \text{cabin} \text{ then } ["Alice"] \text{ else } []))$   
*ex-creds ex-locs*

**fixes** *aid-graph* :: *igraph*

**defines** *aid-graph-def*: *aid-graph*  $\equiv$  *Lgraph*  
 $\{(cockpit, door), (door, cabin)\}$   
 $(\lambda x. \text{if } x = \text{cockpit} \text{ then } ["Charly"]$   
 $\quad \text{else } (\text{if } x = \text{door} \text{ then } []$   
 $\quad \quad \text{else } (\text{if } x = \text{cabin} \text{ then } ["Bob", "Alice"] \text{ else } []))$   
*ex-creds ex-locs'*

**fixes** *aid-graph0* :: *igraph*

**defines** *aid-graph0-def*: *aid-graph0*  $\equiv$  *Lgraph*  
 $\{(cockpit, door), (door, cabin)\}$   
 $(\lambda x. \text{if } x = \text{cockpit} \text{ then } ["Charly"]$   
 $\quad \text{else } (\text{if } x = \text{door} \text{ then } ["Bob"]$   
 $\quad \quad \text{else } (\text{if } x = \text{cabin} \text{ then } ["Alice"] \text{ else } []))$   
*ex-creds ex-locs*

**fixes** *agid-graph* :: *igraph*

**defines** *agid-graph-def*: *agid-graph*  $\equiv$  *Lgraph*  
 $\{(cockpit, door), (door, cabin)\}$   
 $(\lambda x. \text{if } x = \text{cockpit} \text{ then } ["Charly"]$   
 $\quad \text{else } (\text{if } x = \text{door} \text{ then } []$   
 $\quad \quad \text{else } (\text{if } x = \text{cabin} \text{ then } ["Bob", "Alice"] \text{ else } []))$

*ex-creds ex-locs*

**fixes** *local-policies* :: [*igraph*, *location*]  $\Rightarrow$  *policy set*

**defines** *local-policies-def*: *local-policies* *G*  $\equiv$

( $\lambda y$ . if *y* = *cockpit* then  
 $\{(\lambda x$ . ( $? n$ . ( $n @_G$  *cockpit*)  $\wedge$  *Actor* *n* = *x*), {*put*}},  
 $(\lambda x$ . ( $? n$ . ( $n @_G$  *cabin*)  $\wedge$  *Actor* *n* = *x*  $\wedge$  *has* *G* (*x*, "PIN")  
 $\wedge$  *isin* *G* *door* "norm"), {*move*})  
 $\}$   
 else (if *y* = *door* then  $\{(\lambda x$ . *True*, {*move*}},  
 $(\lambda x$ . ( $? n$ . ( $n @_G$  *cockpit*)  $\wedge$  *Actor* *n* = *x*), {*put*})}  
 else (if *y* = *cabin* then  $\{(\lambda x$ . *True*, {*move*})}  
 else {})))

**fixes** *local-policies-four-eyes* :: [*igraph*, *location*]  $\Rightarrow$  *policy set*

**defines** *local-policies-four-eyes-def*: *local-policies-four-eyes* *G*  $\equiv$

( $\lambda y$ . if *y* = *cockpit* then  
 $\{(\lambda x$ . ( $? n$ . ( $n @_G$  *cockpit*)  $\wedge$  *Actor* *n* = *x*)  $\wedge$   
 $2 \leq \text{length}(\text{agra } G y) \wedge (\forall h \in \text{set}(\text{agra } G y). h \in \text{airplane-actors}),$   
 $\{put\}),$   
 $(\lambda x$ . ( $? n$ . ( $n @_G$  *cabin*)  $\wedge$  *Actor* *n* = *x*  $\wedge$  *has* *G* (*x*, "PIN")  $\wedge$   
 $\text{isin } G \text{ door "norm" }, \{move\})$   
 $\}$   
 else (if *y* = *door* then  
 $\{(\lambda x$ . ( $(? n$ . ( $n @_G$  *cockpit*)  $\wedge$  *Actor* *n* = *x*)  $\wedge 3 \leq \text{length}(\text{agra } G$   
*cockpit*), {*move*})}  
 else (if *y* = *cabin* then  
 $\{(\lambda x$ . ( $(? n$ . ( $n @_G$  *door*)  $\wedge$  *Actor* *n* = *x*), {*move*})}  
 else {})))

**fixes** *Airplane-scenario* :: *infrastructure* (**structure**)

**defines** *Airplane-scenario-def*:

*Airplane-scenario*  $\equiv$  *Infrastructure ex-graph local-policies*

**fixes** *Airplane-in-danger* :: *infrastructure*

**defines** *Airplane-in-danger-def*:

*Airplane-in-danger*  $\equiv$  *Infrastructure aid-graph local-policies*

**fixes** *Airplane-getting-in-danger0* :: *infrastructure*

**defines** *Airplane-getting-in-danger0-def*:

*Airplane-getting-in-danger0*  $\equiv$  *Infrastructure aid-graph0 local-policies*

**fixes** *Airplane-getting-in-danger* :: *infrastructure*

**defines** *Airplane-getting-in-danger-def*:

*Airplane-getting-in-danger*  $\equiv$  *Infrastructure agid-graph local-policies*

```

fixes Air-states
defines Air-states-def: Air-states  $\equiv \{ I. \text{Airplane-scenario} \rightarrow_n^* I \}$ 

fixes Air-Kripke
defines Air-Kripke  $\equiv \text{Kripke } \text{Air-states} \{ \text{Airplane-scenario} \}$ 

fixes Airplane-not-in-danger :: infrastructure
defines Airplane-not-in-danger-def:
Airplane-not-in-danger  $\equiv \text{Infrastructure aid-graph local-policies-four-eyes}$ 

fixes Airplane-not-in-danger-init :: infrastructure
defines Airplane-not-in-danger-init-def:
Airplane-not-in-danger-init  $\equiv \text{Infrastructure ex-graph local-policies-four-eyes}$ 

fixes Air-tp-states
defines Air-tp-states-def: Air-tp-states  $\equiv \{ I. \text{Airplane-not-in-danger-init} \rightarrow_n^* I \}$ 

fixes Air-tp-Kripke
defines Air-tp-Kripke  $\equiv \text{Kripke } \text{Air-tp-states} \{ \text{Airplane-not-in-danger-init} \}$ 

fixes Safety :: [infrastructure, identity]  $\Rightarrow$  bool
defines Safety-def: Safety I a  $\equiv a \in \text{airplane-actors}$ 
 $\longrightarrow (\text{enables } I \text{ cockpit } (\text{Actor } a) \text{ move})$ 

fixes Security :: [infrastructure, identity]  $\Rightarrow$  bool
defines Security-def: Security I a  $\equiv (\text{isin } (\text{graphI } I) \text{ door } \text{"locked"})$ 
 $\longrightarrow \neg(\text{enables } I \text{ cockpit } (\text{Actor } a) \text{ move})$ 

fixes foe-control :: [location, action]  $\Rightarrow$  bool
defines foe-control-def: foe-control l c  $\equiv$ 
  (! I :: infrastructure. (? x :: identity.
    x @graphI I l  $\wedge$  Actor x  $\neq$  Actor "Eve")
     $\longrightarrow \neg(\text{enables } I \text{ l } (\text{Actor } \text{"Eve"}) \text{ c}))$ 

fixes astate :: identity  $\Rightarrow$  actor-state
defines astate-def: astate x  $\equiv$  (case x of
  "Eve"  $\Rightarrow$  Actor-state depressed {revenge, peer-recognition}
  | -  $\Rightarrow$  Actor-state happy {})

assumes Eve-precipitating-event: tipping-point (astate "Eve")
assumes Insider-Eve: Insider "Eve" {"Charly"} astate
assumes cockpit-foe-control: foe-control cockpit put

begin

```

```

lemma ex-inv: global-policy Airplane-scenario "Bob"
by (simp add: Airplane-scenario-def global-policy-def airplane-actors-def)

lemma ex-inv2: global-policy Airplane-scenario "Charly"
by (simp add: Airplane-scenario-def global-policy-def airplane-actors-def)

lemma ex-inv3:  $\neg$ global-policy Airplane-scenario "Eve"
proof (simp add: Airplane-scenario-def global-policy-def, rule conjI)
  show "Eve"  $\notin$  airplane-actors by (simp add: airplane-actors-def)
next show
  enables (Infrastructure ex-graph local-policies) cockpit (Actor "Eve") put
proof –
  have a: Actor "Charly" = Actor "Eve"
  by (insert Insider-Eve, unfold Insider-def, (drule mp),
    rule Eve-precipitating-event, simp add: UasI-def)
  show ?thesis
  by (insert a, simp add: Airplane-scenario-def enables-def ex-creds-def local-policies-def
ex-graph-def,
    insert Insider-Eve, unfold Insider-def, (drule mp), rule Eve-precipitating-event,
    simp add: UasI-def, rule-tac x = "Charly" in exI, simp add: cockpit-def
atI-def)
  qed
qed

show Safety for Airplane_scenario

lemma Safety: Safety Airplane-scenario ("Alice")
proof –
  show Safety Airplane-scenario "Alice"
  by (simp add: Airplane-scenario-def Safety-def enables-def ex-creds-def
    local-policies-def ex-graph-def cockpit-def, rule impI,
    rule-tac x = "Alice" in exI, simp add: atI-def cabin-def ex-locs-def door-def,
    rule conjI, simp add: has-def credentials-def, simp add: isin-def credentials-def)
  qed

show Security for Airplane_scenario

lemma inj-lem:  $\llbracket \text{inj } f; x \neq y \rrbracket \implies f\ x \neq f\ y$ 
by (simp add: inj-eq)

lemma inj-on-lem:  $\llbracket \text{inj-on } f\ A; x \neq y; x \in A; y \in A \rrbracket \implies f\ x \neq f\ y$ 
by (simp add: inj-on-def, blast)

lemma inj-lemma': inj-on (isin ex-graph door) {"locked", "norm"}
by (unfold inj-on-def ex-graph-def isin-def, simp, unfold ex-locs-def, simp)

lemma inj-lemma'': inj-on (isin aid-graph door) {"locked", "norm"}
by (unfold inj-on-def aid-graph-def isin-def, simp, unfold ex-locs'-def, simp)

lemma locl-lemma2: isin ex-graph door "norm"  $\neq$  isin ex-graph door "locked"

```

**by** (rule-tac  $A = \{\text{"locked"}, \text{"norm"}\}$  **and**  $f = \text{isin ex-graph door in inj-on-lem, rule inj-lemma', simp+}$ )

**lemma** *locl-lemma3: isin ex-graph door "norm" = ( $\neg$  isin ex-graph door "locked")*  
**by** (insert locl-lemma2, blast)

**lemma** *locl-lemma2a: isin aid-graph door "norm"  $\neq$  isin aid-graph door "locked"*  
**by** (rule-tac  $A = \{\text{"locked"}, \text{"norm"}\}$  **and**  $f = \text{isin aid-graph door in inj-on-lem, rule inj-lemma', simp+}$ )

**lemma** *locl-lemma3a: isin aid-graph door "norm" = ( $\neg$  isin aid-graph door "locked")*  
**by** (insert locl-lemma2a, blast)

**lemma** *Security: Security Airplane-scenario s*  
**by** (simp add: Airplane-scenario-def Security-def enables-def local-policies-def ex-locs-def locl-lemma3)

show that pilot can't get into cockpit if outside and locked = Airplane\_in\_danger

**lemma** *Security-problem: Security Airplane-scenario "Bob"*  
**by** (rule Security)

show that pilot can get out of cockpit

**lemma** *pilot-can-leave-cockpit: (enables Airplane-scenario cabin (Actor "Bob") move)*  
**by** (simp add: Airplane-scenario-def Security-def ex-creds-def ex-graph-def enables-def local-policies-def ex-locs-def, simp add: cockpit-def cabin-def door-def)

show that in Airplane\_in\_danger copilot can still do put = put position to ground

**lemma** *ex-inv4:  $\neg$ global-policy Airplane-in-danger ("Eve")*  
**proof** (simp add: Airplane-in-danger-def global-policy-def, rule conjI)  
**show**  $\text{"Eve"} \notin \text{airplane-actors}$  **by** (simp add: airplane-actors-def)  
**next show** *enables (Infrastructure aid-graph local-policies) cockpit (Actor "Eve") put*  
**proof** –  
**have**  $a: \text{Actor "Charly"} = \text{Actor "Eve"}$   
**by** (insert Insider-Eve, unfold Insider-def, (drule mp), rule Eve-precipitating-event, simp add: UasI-def)  
**show** ?thesis  
**apply** (insert a, erule subst)  
**by** (simp add: enables-def local-policies-def cockpit-def aid-graph-def atI-def)  
**qed**  
**qed**

**lemma** *Safety-in-danger:*  
**fixes**  $s$   
**assumes**  $s \in \text{airplane-actors}$   
**shows**  $\neg(\text{Safety Airplane-in-danger } s)$

**proof** (simp add: Airplane-in-danger-def Safety-def enables-def assms)  
**show**  $\forall x::(\text{actor} \Rightarrow \text{bool}) \times \text{action set} \in \text{local-policies aid-graph cockpit}.$   
 $\neg (\text{case } x \text{ of } (p::\text{actor} \Rightarrow \text{bool}, e::\text{action set}) \Rightarrow \text{move} \in e \wedge p (\text{Actor } s))$   
**by** ( simp add: local-policies-def aid-graph-def ex-locs'-def isin-def)  
**qed**

**lemma** Security-problem':  $\neg(\text{enables Airplane-in-danger cockpit (Actor "Bob") move})$   
**proof** (simp add: Airplane-in-danger-def Security-def enables-def local-policies-def  
 $\text{ex-locs-def locl-lemma3a, rule impI}$   
**assume** has aid-graph (Actor "Bob", "PIN")  
**show**  $(\forall n::\text{char list}.$   
 $\text{Actor } n = \text{Actor "Bob"} \longrightarrow n @_{\text{aid-graph cabin}} \longrightarrow \text{isin aid-graph door}$   
 $\text{"locked"})$   
**by** (simp add: aid-graph-def isin-def ex-locs'-def)  
**qed**

show that with the four eyes rule in Airplane\_not\_in\_danger Eve cannot crash plane, i.e. cannot put position to ground

**lemma** ex-inv5:  $a \in \text{airplane-actors} \longrightarrow \text{global-policy Airplane-not-in-danger } a$   
**by** (simp add: Airplane-not-in-danger-def global-policy-def)

**lemma** ex-inv6:  $\text{global-policy Airplane-not-in-danger } a$   
**proof** (simp add: Airplane-not-in-danger-def global-policy-def, rule impI)  
**assume**  $a \notin \text{airplane-actors}$   
**show**  $\neg \text{enables (Infrastructure aid-graph local-policies-four-eyes) cockpit (Actor } a \text{) put}$   
**by** (simp add: aid-graph-def ex-locs'-def enables-def local-policies-four-eyes-def)  
**qed**

**lemma** step0:  $\text{Airplane-scenario} \rightarrow_n \text{Airplane-getting-in-danger0}$   
**proof** (rule-tac  $l = \text{cockpit}$  **and**  $l' = \text{door}$  **and**  $a = \text{"Bob"}$  **in** move, rule refl)  
**show**  $\text{"Bob"} @_{\text{graphI Airplane-scenario}} \text{cockpit}$   
**by** (simp add: Airplane-scenario-def atI-def ex-graph-def)  
**next show**  $\text{cockpit} \in \text{nodes (graphI Airplane-scenario)}$   
**by** (simp add: ex-graph-def Airplane-scenario-def nodes-def, blast)+  
**next show**  $\text{door} \in \text{nodes (graphI Airplane-scenario)}$   
**by** (simp add: actors-graph-def door-def cockpit-def nodes-def cabin-def,  
rule-tac  $x = \text{Location 2}$  **in** exI,  
simp add: Airplane-scenario-def ex-graph-def cockpit-def door-def)  
**next show**  $\text{"Bob"} \in \text{actors-graph (graphI Airplane-scenario)}$   
**by** (simp add: actors-graph-def Airplane-scenario-def nodes-def ex-graph-def,  
blast)  
**next show**  $\text{enables Airplane-scenario door (Actor "Bob") move}$   
**by** (simp add: Airplane-scenario-def enables-def local-policies-def ex-creds-def  
door-def cockpit-def)  
**next show**  $\text{Airplane-getting-in-danger0} =$   
 $\text{Infrastructure (move-graph-a "Bob" cockpit door (graphI Airplane-scenario))}$



```

(delta Airplane-scenario)
proof -
  have a: (move-graph-a "Bob" cockpit door (graphI Airplane-scenario)) =
aid-graph0
  by (simp add: move-graph-a-def door-def cockpit-def Airplane-scenario-def
aid-graph0-def ex-graph-def, rule ext, simp add: cabin-def door-def)
  show ?thesis
  by (unfold Airplane-getting-in-danger0-def, insert a, erule ssbst,
simp add: Airplane-scenario-def)
qed
qed

lemma step1: Airplane-getting-in-danger0  $\rightarrow_n$  Airplane-getting-in-danger
proof (rule-tac l = door and l' = cabin and a = "Bob" in move, rule refl)
  show "Bob" @graphI Airplane-getting-in-danger0 door
  by (simp add: Airplane-getting-in-danger0-def atI-def aid-graph0-def door-def
cockpit-def)
next show door  $\in$  nodes (graphI Airplane-getting-in-danger0)
  by (simp add: aid-graph0-def Airplane-getting-in-danger0-def nodes-def, blast)+
next show cabin  $\in$  nodes (graphI Airplane-getting-in-danger0)
  by (simp add: actors-graph-def door-def cockpit-def nodes-def cabin-def,
rule-tac x = Location 1 in exI,
simp add: Airplane-getting-in-danger0-def aid-graph0-def cockpit-def door-def
cabin-def)
next show "Bob"  $\in$  actors-graph (graphI Airplane-getting-in-danger0)
  by (simp add: actors-graph-def door-def cockpit-def nodes-def cabin-def
Airplane-getting-in-danger0-def aid-graph0-def, blast)
next show enables Airplane-getting-in-danger0 cabin (Actor "Bob") move
  by (simp add: Airplane-getting-in-danger0-def enables-def local-policies-def ex-creds-def
door-def
cockpit-def cabin-def)
next show Airplane-getting-in-danger =
Infrastructure (move-graph-a "Bob" door cabin (graphI Airplane-getting-in-danger0))
(delta Airplane-getting-in-danger0)
  by (unfold Airplane-getting-in-danger-def,
simp add: Airplane-getting-in-danger0-def agid-graph-def aid-graph0-def
move-graph-a-def door-def cockpit-def cabin-def, rule ext,
simp add: cabin-def door-def)
qed

lemma step2: Airplane-getting-in-danger  $\rightarrow_n$  Airplane-in-danger
proof (rule-tac l = door and a = "Charly" and z = "locked" in put-remote,
rule refl)
  show enables Airplane-getting-in-danger door (Actor "Charly") put
  by (simp add: enables-def local-policies-def ex-creds-def door-def cockpit-def,
unfold Airplane-getting-in-danger-def,
simp add: local-policies-def cockpit-def cabin-def door-def,
rule-tac x = "Charly" in exI, rule conjI,
simp add: atI-def agid-graph-def door-def cockpit-def, rule refl)

```

```

next show Airplane-in-danger =
  Infrastructure
  (Lgraph (gra (graphI Airplane-getting-in-danger)) (agra (graphI Airplane-getting-in-danger))
    (cgra (graphI Airplane-getting-in-danger))
    ((lgra (graphI Airplane-getting-in-danger))(door := ["locked"])))
  (delta Airplane-getting-in-danger)
  by (unfold Airplane-in-danger-def, simp add: aid-graph-def agid-graph-def
    ex-locs'-def ex-locs-def Airplane-getting-in-danger-def, force)
qed

lemma step0r: Airplane-scenario  $\rightarrow_n^*$  Airplane-getting-in-danger0
  by (simp add: state-transition-in-refl-def, insert step0, auto)

lemma step1r: Airplane-getting-in-danger0  $\rightarrow_n^*$  Airplane-getting-in-danger
  by (simp add: state-transition-in-refl-def, insert step1, auto)

lemma step2r: Airplane-getting-in-danger  $\rightarrow_n^*$  Airplane-in-danger
  by (simp add: state-transition-in-refl-def, insert step2, auto)

theorem step-allr: Airplane-scenario  $\rightarrow_n^*$  Airplane-in-danger
  by (insert step0r step1r step2r, simp add: state-transition-in-refl-def)

theorem aid-attack: Air-Kripke  $\vdash EF$  ( $\{x. \neg \text{global-policy } x \text{ "Eve"}\}$ )
proof (simp add: check-def Air-Kripke-def, rule conjI)
  show Airplane-scenario  $\in$  Air-states
  by (simp add: Air-states-def state-transition-in-refl-def)
next show Airplane-scenario  $\in EF$   $\{x::\text{infrastructure}. \neg \text{global-policy } x \text{ "Eve"}\}$ 
  by (rule EF-lem2b, subst EF-lem000, rule EX-lem0r, subst EF-lem000, rule
EX-step,
    unfold state-transition-infra-def, rule step0, rule EX-lem0r,
    rule-tac y = Airplane-getting-in-danger in EX-step,
    unfold state-transition-infra-def, rule step1, subst EF-lem000, rule EX-lem0l,
    rule-tac y = Airplane-in-danger in EX-step, unfold state-transition-infra-def,
    rule step2, rule CollectI, rule ex-inv4)
qed

```

Invariant: actors cannot be at two places at the same time

**lemma** *actors-unique-loc-base*:

```

assumes  $I \rightarrow_n I'$ 
  and ( $\forall l l'. a @_{\text{graphI } I} l \wedge a @_{\text{graphI } I} l' \longrightarrow l = l'$ )  $\wedge$ 
    ( $\forall l. \text{nodup } a (\text{agra } (\text{graphI } I) l)$ )
  shows ( $\forall l l'. a @_{\text{graphI } I'} l \wedge a @_{\text{graphI } I'} l' \longrightarrow l = l'$ )  $\wedge$ 
    ( $\forall l. \text{nodup } a (\text{agra } (\text{graphI } I') l)$ )
proof (rule state-transition-in.cases, rule assms(1))
  show  $\bigwedge (G::\text{igraph}) (Ia::\text{infrastructure}) (aa::\text{char list}) (l::\text{location}) (a'::\text{char list})$ 
    ( $z::\text{char list}$ )
     $I'a::\text{infrastructure}.$ 
     $I = Ia \implies$ 
     $I' = I'a \implies$ 

```

```

    G = graphI Ia ⇒
    aa @G l ⇒
    a' @G l ⇒
    has G (Actor aa, z) ⇒
    enables Ia l (Actor aa) get ⇒
    I'a =
    Infrastructure
    (Lgraph (gra G) (agra G)
      ((cgra G)(Actor a' := (z # fst (cgra G (Actor a')), snd (cgra G (Actor
a'))))) (lgra G))
    (delta Ia) ⇒
    (∀ (l::location) l'::location. a @graphI I' l ∧ a @graphI I' l' → l = l') ∧
    (∀ l::location. nodup a (agra (graphI I') l)) using assms
  by (simp add: atI-def)
next fix G Ia aa l I'a z
  assume a0: I = Ia and a1: I' = I'a and a2: G = graphI Ia and a3: aa @G l
  and a4: enables Ia l (Actor aa) put
  and a5: I'a = Infrastructure (Lgraph (gra G) (agra G) (cgra G) ((lgra G)(l
:= [z]))) (delta Ia)
  show (∀ (l::location) l'::location. a @graphI I' l ∧ a @graphI I' l' → l = l') ∧
    (∀ l::location. nodup a (agra (graphI I') l)) using assms
  by (simp add: a0 a1 a2 a3 a4 a5 atI-def)
next show ∧(G::igraph) (Ia::infrastructure) (l::location) (aa::char list) (I'a::infrastructure)
  z::char list.
  I = Ia ⇒
  I' = I'a ⇒
  G = graphI Ia ⇒
  enables Ia l (Actor aa) put ⇒
  I'a = Infrastructure (Lgraph (gra G) (agra G) (cgra G) ((lgra G)(l := [z])))
(delta Ia) ⇒
  (∀ (l::location) l'::location. a @graphI I' l ∧ a @graphI I' l' → l = l') ∧
  (∀ l::location. nodup a (agra (graphI I') l))
  by (clarify, simp add: assms atI-def)
next show ∧(G::igraph) (Ia::infrastructure) (aa::char list) (l::location) (l'::location)
  I'a::infrastructure.
  I = Ia ⇒
  I' = I'a ⇒
  G = graphI Ia ⇒
  aa @G l ⇒
  l ∈ nodes G ⇒
  l' ∈ nodes G ⇒
  aa ∈ actors-graph (graphI Ia) ⇒
  enables Ia l' (Actor aa) move ⇒
  I'a = Infrastructure (move-graph-a aa l l' (graphI Ia)) (delta Ia) ⇒
  (∀ (l::location) l'::location. a @graphI I' l ∧ a @graphI I' l' → l = l') ∧
  (∀ l::location. nodup a (agra (graphI I') l))
  proof (simp add: move-graph-a-def, rule conjI, clarify, rule conjI, clarify, rule
conjI, clarify)
  show ∧(G::igraph) (Ia::infrastructure) (aa::char list) (l::location) (l'::location)

```

```

(I'a::infrastructure) (la::location) l'a::location.
I' =
Infrastructure
  (Lgraph (gra (graphI I))
    (if a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) l')
      then (agra (graphI I))(l := del a (agra (graphI I) l), l' := a # agra
(graphI I) l')
      else agra (graphI I))
    (cgra (graphI I)) (lgra (graphI I)))
  (delta I) ⇒
  a @graphI I l ⇒
  l ∈ nodes (graphI I) ⇒
  l' ∈ nodes (graphI I) ⇒
  a ∈ actors-graph (graphI I) ⇒
  enables I l' (Actor a) move ⇒
  a ∈ set (agra (graphI I) l) ⇒
  a ∉ set (agra (graphI I) l') ⇒
  a @Lgraph (gra (graphI I))      ((agra (graphI I))(l := del a (agra (graphI I) l), l' := a # agra (graphI I) l))
la ⇒
  a @Lgraph (gra (graphI I))      ((agra (graphI I))(l := del a (agra (graphI I) l), l' := a # agra (graphI I) l))
l'a ⇒
  la = l'a
apply (case-tac la ≠ l' ∧ la ≠ l ∧ l'a ≠ l' ∧ l'a ≠ l)
apply (simp add: atI-def)
apply (subgoal-tac la = l' ∨ la = l ∨ l'a = l' ∨ l'a = l)
prefer 2
using assms(2) atI-def apply blast
apply blast
by (metis agra.simps assms(2) atI-def del-nodup fun-upd-apply)
next show ∧(G::igraph) (Ia::infrastructure) (aa::char list) (l::location) (l'::location)
I'a::infrastructure.
I' =
Infrastructure
  (Lgraph (gra (graphI I))
    (if a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) l')
      then (agra (graphI I))(l := del a (agra (graphI I) l), l' := a # agra
(graphI I) l')
      else agra (graphI I))
    (cgra (graphI I)) (lgra (graphI I)))
  (delta I) ⇒
  a @graphI I l ⇒
  l ∈ nodes (graphI I) ⇒
  l' ∈ nodes (graphI I) ⇒
  a ∈ actors-graph (graphI I) ⇒
  enables I l' (Actor a) move ⇒
  a ∈ set (agra (graphI I) l) ⇒
  a ∉ set (agra (graphI I) l') ⇒
  ∀ la::location.
    (la = l → l ≠ l' → nodup a (del a (agra (graphI I) l))) ∧

```

```

      (la ≠ l → la ≠ l' → nodup a (agra (graphI I) la))
    by (simp add: assms(2) nodup-down)
  next show  $\bigwedge (G::igraph) (Ia::infrastructure) (aa::char\ list) (l::location) (l'::location)$ 
     $I'a::infrastructure.$ 
     $I' =$ 
    Infrastructure
    (Lgraph (gra (graphI I))
      (if a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) l')
        then (agra (graphI I))(l := del a (agra (graphI I) l), l' := a # agra
(graphI I) l')
        else agra (graphI I))
      (cgra (graphI I)) (lgra (graphI I)))
    (delta I) ⇒
    a @graphI I l ⇒
    l ∈ nodes (graphI I) ⇒
    l' ∈ nodes (graphI I) ⇒
    a ∈ actors-graph (graphI I) ⇒
    enables I l' (Actor a) move ⇒
    (a ∈ set (agra (graphI I) l) → a ∈ set (agra (graphI I) l')) →
    (∀ (l::location) l'::location.
      a @Lgraph (gra (graphI I)) (agra (graphI I)) (cgra (graphI I)) (lgra (graphI I))
l ∧
      a @Lgraph (gra (graphI I)) (agra (graphI I)) (cgra (graphI I)) (lgra (graphI I))
l' →
      l = l') ∧
    (∀ l::location. nodup a (agra (graphI I) l))
    by (simp add: assms(2) atI-def)
  next show  $\bigwedge (G::igraph) (Ia::infrastructure) (aa::char\ list) (l::location) (l'::location)$ 
     $I'a::infrastructure.$ 
     $I = Ia ⇒$ 
     $I' =$ 
    Infrastructure
    (Lgraph (gra (graphI Ia))
      (if aa ∈ set (agra (graphI Ia) l) ∧ aa ∉ set (agra (graphI Ia) l')
        then (agra (graphI Ia))(l := del aa (agra (graphI Ia) l), l' := aa # agra
(graphI Ia) l')
        else agra (graphI Ia))
      (cgra (graphI Ia)) (lgra (graphI Ia)))
    (delta Ia) ⇒
    G = graphI Ia ⇒
    aa @graphI Ia l ⇒
    l ∈ nodes (graphI Ia) ⇒
    l' ∈ nodes (graphI Ia) ⇒
    aa ∈ actors-graph (graphI Ia) ⇒
    enables Ia l' (Actor aa) move ⇒
    I'a =
    Infrastructure
    (Lgraph (gra (graphI Ia))
      (if aa ∈ set (agra (graphI Ia) l) ∧ aa ∉ set (agra (graphI Ia) l')

```

$$\begin{aligned}
& \text{then } (agra (\text{graphI } Ia))(l := \text{del } aa (agra (\text{graphI } Ia) l), l' := aa \# agra \\
& (\text{graphI } Ia) l') \\
& \quad \text{else } agra (\text{graphI } Ia) \\
& \quad (cgra (\text{graphI } Ia)) (lgra (\text{graphI } Ia))) \\
& \quad (\text{delta } Ia) \implies \\
& aa \neq a \implies \\
& (aa \in \text{set } (agra (\text{graphI } Ia) l) \wedge aa \notin \text{set } (agra (\text{graphI } Ia) l') \implies \\
& (\forall (la::location) l'a::location. \\
& \quad a @_{Lgraph} (gra (\text{graphI } Ia)) \quad ((agra (\text{graphI } Ia)) \quad (l := \text{del } aa (agra (\text{graphI } Ia) l), l \\
la \wedge \\
& \quad a @_{Lgraph} (gra (\text{graphI } Ia)) \quad ((agra (\text{graphI } Ia)) \quad (l := \text{del } aa (agra (\text{graphI } Ia) l), l \\
l'a \implies \\
& \quad la = l'a) \wedge \\
& (\forall la::location. \\
& \quad (la = l \implies \\
& \quad \quad (l = l' \implies \text{nodup } a (agra (\text{graphI } Ia) l')) \wedge \\
& \quad \quad (l \neq l' \implies \text{nodup } a (\text{del } aa (agra (\text{graphI } Ia) l)))) \wedge \\
& \quad (la \neq l \implies \\
& \quad \quad (la = l' \implies \text{nodup } a (agra (\text{graphI } Ia) l')) \wedge \\
& \quad \quad (la \neq l' \implies \text{nodup } a (agra (\text{graphI } Ia) la)))) \wedge \\
& ((aa \in \text{set } (agra (\text{graphI } Ia) l) \implies aa \in \text{set } (agra (\text{graphI } Ia) l')) \implies \\
& (\forall (l::location) l':location. \\
& \quad a @_{Lgraph} (gra (\text{graphI } Ia)) (agra (\text{graphI } Ia)) (cgra (\text{graphI } Ia)) \quad (lgra (\text{graphI } Ia)) \\
l \wedge \\
& \quad a @_{Lgraph} (gra (\text{graphI } Ia)) (agra (\text{graphI } Ia)) (cgra (\text{graphI } Ia)) \quad (lgra (\text{graphI } Ia)) \\
l' \implies \\
& \quad l = l') \wedge \\
& (\forall l::location. \text{nodup } a (agra (\text{graphI } Ia) l))) \\
\textbf{proof } & (\text{clarify, simp add: atI-def, rule conjI, clarify, rule conjI, clarify, rule conjI,} \\
& \quad \text{clarify, rule conjI, clarify, simp, clarify, rule conjI, (rule impI)+) \\
\textbf{show } & \bigwedge (aa::char \text{ list}) (l::location) (l':location) l'a::location. \\
I' = & \\
\textit{Infrastructure} & \\
& (Lgraph (gra (\text{graphI } I)) \\
& \quad ((agra (\text{graphI } I))(l := \text{del } aa (agra (\text{graphI } I) l), l' := aa \# agra (\text{graphI} \\
I) l')) \\
& \quad (cgra (\text{graphI } I)) (lgra (\text{graphI } I))) \\
& (\text{delta } I) \implies \\
& aa \in \text{set } (agra (\text{graphI } I) l) \implies \\
& l \in \text{nodes } (\text{graphI } I) \implies \\
& l' \in \text{nodes } (\text{graphI } I) \implies \\
& aa \in \text{actors-graph } (\text{graphI } I) \implies \\
& \text{enables } I l' (\text{Actor } aa) \text{ move} \implies \\
& aa \neq a \implies \\
& aa \notin \text{set } (agra (\text{graphI } I) l') \implies \\
& l \neq l' \implies \\
& l'a \neq l \implies \\
& l'a = l' \implies a \in \text{set } (\text{del } aa (agra (\text{graphI } I) l)) \implies a \notin \text{set } (agra (\text{graphI} \\
I) l')
\end{aligned}$$

```

    by (meson assms(2) atI-def del-notin-down)
  next show  $\bigwedge (aa::char\ list) (l::location) (l'::location) l'a::location.$ 
    I' =
    Infrastructure
    (Lgraph (gra (graphI I))
      ((agra (graphI I))(l := del aa (agra (graphI I) l), l' := aa # agra (graphI
I) l'))
      (cgra (graphI I)) (lgra (graphI I)))
    (delta I)  $\implies$ 
    aa  $\in$  set (agra (graphI I) l)  $\implies$ 
    l  $\in$  nodes (graphI I)  $\implies$ 
    l'  $\in$  nodes (graphI I)  $\implies$ 
    aa  $\in$  actors-graph (graphI I)  $\implies$ 
    enables I l' (Actor aa) move  $\implies$ 
    aa  $\neq$  a  $\implies$ 
    aa  $\notin$  set (agra (graphI I) l')  $\implies$ 
    l  $\neq$  l'  $\implies$ 
    l'a  $\neq$  l  $\implies$ 
    l'a  $\neq$  l'  $\longrightarrow$  a  $\in$  set (del aa (agra (graphI I) l))  $\longrightarrow$  a  $\notin$  set (agra (graphI
I) l'a)
    by (meson assms(2) atI-def del-notin-down)
  next show  $\bigwedge (aa::char\ list) (l::location) (l'::location) la::location.$ 
    I' =
    Infrastructure
    (Lgraph (gra (graphI I))
      (if aa  $\notin$  set (agra (graphI I) l')
        then (agra (graphI I))(l := del aa (agra (graphI I) l), l' := aa # agra
(graphI I) l')
        else agra (graphI I))
      (cgra (graphI I)) (lgra (graphI I)))
    (delta I)  $\implies$ 
    aa  $\in$  set (agra (graphI I) l)  $\implies$ 
    l  $\in$  nodes (graphI I)  $\implies$ 
    l'  $\in$  nodes (graphI I)  $\implies$ 
    aa  $\in$  actors-graph (graphI I)  $\implies$ 
    enables I l' (Actor aa) move  $\implies$ 
    aa  $\neq$  a  $\implies$ 
    aa  $\notin$  set (agra (graphI I) l')  $\implies$ 
    la  $\neq$  l  $\longrightarrow$ 
    (la = l'  $\longrightarrow$ 
      ( $\forall l'a::location.$ 
        (l'a = l  $\longrightarrow$ 
          l  $\neq$  l'  $\longrightarrow$  a  $\in$  set (agra (graphI I) l')  $\longrightarrow$  a  $\notin$  set (del aa (agra (graphI
I) l)))  $\wedge$ 
          (l'a  $\neq$  l  $\longrightarrow$ 
            l'a  $\neq$  l'  $\longrightarrow$  a  $\in$  set (agra (graphI I) l')  $\longrightarrow$  a  $\notin$  set (agra (graphI I)
l'a))))  $\wedge$ 
          (la  $\neq$  l'  $\longrightarrow$ 
            ( $\forall l'a::location.$ 

```

$(l'a = l \longrightarrow$   
 $(l = l' \longrightarrow a \in \text{set } (\text{agra } (\text{graphI } I) \text{ la}) \longrightarrow a \notin \text{set } (\text{agra } (\text{graphI } I)$   
 $l')) \wedge$   
 $(l \neq l' \longrightarrow a \in \text{set } (\text{agra } (\text{graphI } I) \text{ la}) \longrightarrow a \notin \text{set } (\text{del aa } (\text{agra } (\text{graphI } I)$   
 $I) \text{ l})))) \wedge$   
 $(l'a \neq l \longrightarrow$   
 $(l'a = l' \longrightarrow a \in \text{set } (\text{agra } (\text{graphI } I) \text{ la}) \longrightarrow a \notin \text{set } (\text{agra } (\text{graphI } I)$   
 $l')) \wedge$   
 $(l'a \neq l' \longrightarrow$   
 $a \in \text{set } (\text{agra } (\text{graphI } I) \text{ la}) \wedge a \in \text{set } (\text{agra } (\text{graphI } I) \text{ l'a}) \longrightarrow \text{la} =$   
 $\text{l'a}))))$   
**by** (*meson assms(2) atI-def del-notin-down*)  
**next show**  $\bigwedge(aa::\text{char list}) (l::\text{location}) \text{ l'}::\text{location}.$   
 $I' =$   
*Infrastructure*  
 $(\text{Lgraph } (\text{gra } (\text{graphI } I))$   
 $(\text{if } aa \notin \text{set } (\text{agra } (\text{graphI } I) \text{ l'})$   
 $\text{then } (\text{agra } (\text{graphI } I))(l := \text{del aa } (\text{agra } (\text{graphI } I) \text{ l}), \text{ l'} := aa \# \text{agra}$   
 $(\text{graphI } I) \text{ l'})$   
 $\text{else } \text{agra } (\text{graphI } I))$   
 $(\text{cgra } (\text{graphI } I)) (\text{lgra } (\text{graphI } I)))$   
 $(\text{delta } I) \implies$   
 $aa \in \text{set } (\text{agra } (\text{graphI } I) \text{ l}) \implies$   
 $l \in \text{nodes } (\text{graphI } I) \implies$   
 $l' \in \text{nodes } (\text{graphI } I) \implies$   
 $aa \in \text{actors-graph } (\text{graphI } I) \implies$   
 $\text{enables } I \text{ l'} (\text{Actor } aa) \text{ move} \implies$   
 $aa \neq a \implies$   
 $aa \notin \text{set } (\text{agra } (\text{graphI } I) \text{ l'}) \implies$   
 $\forall \text{la}::\text{location}.$   
 $(\text{la} = l \longrightarrow$   
 $(l = l' \longrightarrow \text{nodup } a (\text{agra } (\text{graphI } I) \text{ l'})) \wedge$   
 $(l \neq l' \longrightarrow \text{nodup } a (\text{del aa } (\text{agra } (\text{graphI } I) \text{ l})))) \wedge$   
 $(\text{la} \neq l \longrightarrow$   
 $(\text{la} = l' \longrightarrow \text{nodup } a (\text{agra } (\text{graphI } I) \text{ l'})) \wedge (\text{la} \neq l' \longrightarrow \text{nodup } a (\text{agra}$   
 $(\text{graphI } I) \text{ la}))))$   
**by** (*simp add: assms(2) nodup-down-notin*)  
**next show**  $\bigwedge(aa::\text{char list}) (l::\text{location}) \text{ l'}::\text{location}.$   
 $I' =$   
*Infrastructure*  
 $(\text{Lgraph } (\text{gra } (\text{graphI } I))$   
 $(\text{if } aa \notin \text{set } (\text{agra } (\text{graphI } I) \text{ l'})$   
 $\text{then } (\text{agra } (\text{graphI } I))(l := \text{del aa } (\text{agra } (\text{graphI } I) \text{ l}), \text{ l'} := aa \# \text{agra}$   
 $(\text{graphI } I) \text{ l'})$   
 $\text{else } \text{agra } (\text{graphI } I))$   
 $(\text{cgra } (\text{graphI } I)) (\text{lgra } (\text{graphI } I)))$   
 $(\text{delta } I) \implies$   
 $aa \in \text{set } (\text{agra } (\text{graphI } I) \text{ l}) \implies$   
 $l \in \text{nodes } (\text{graphI } I) \implies$



```

    l' ∈ nodes (graphI I) ⇒
    aa ∈ actors-graph (graphI I) ⇒
    enables I l' (Actor aa) move ⇒
    aa ≠ a ⇒
    aa ∈ set (agra (graphI I) l') →
    (∀ l::location. l'::location.
      a ∈ set (agra (graphI I) l) ∧ a ∈ set (agra (graphI I) l') → l = l') ∧
    (∀ l::location. nodup a (agra (graphI I) l))
    using assms(2) atI-def by blast
  qed
qed
qed

```

**lemma** *actors-unique-loc-step*:

```

  assumes (I, I') ∈ {(x::infrastructure, y::infrastructure). x →n y}*
  and ∀ a. (∀ l l'. a @graphI I l ∧ a @graphI I l' → l = l') ∧
    (∀ l. nodup a (agra (graphI I) l))
  shows ∀ a. (∀ l l'. a @graphI I' l ∧ a @graphI I' l' → l = l') ∧
    (∀ l. nodup a (agra (graphI I') l))

```

**proof** –

```

  have ind: (∀ a. (∀ l l'. a @graphI I l ∧ a @graphI I l' → l = l') ∧
    (∀ l. nodup a (agra (graphI I) l))) →
    (∀ a. (∀ l l'. a @graphI I' l ∧ a @graphI I' l' → l = l') ∧
    (∀ l. nodup a (agra (graphI I') l)))

```

**proof** (insert assms(1), erule rtrancl.induct)

**show**  $\bigwedge a::infrastructure.$

( $\forall aa::char\ list.$

( $\forall l::location. l'::location. aa @_{graphI} a l \wedge aa @_{graphI} a l' \rightarrow l = l') \wedge$   
 $(\forall l::location. nodup aa (agra (graphI a) l))) \rightarrow$

( $\forall aa::char\ list.$

( $\forall l::location. l'::location. aa @_{graphI} a l \wedge aa @_{graphI} a l' \rightarrow l = l') \wedge$   
 $(\forall l::location. nodup aa (agra (graphI a) l)))$  **by** *simp*

**next show**  $\bigwedge (a::infrastructure) (b::infrastructure) (c::infrastructure).$

$(a, b) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^* \Rightarrow$

( $\forall aa::char\ list.$

( $\forall l::location) (l'::location). (aa @_{graphI} a l \wedge aa @_{graphI} a l') \rightarrow l =$

$l') \wedge$

( $\forall l::location. nodup aa (agra (graphI a) l))) \rightarrow$

( $\forall a::char\ list.$

( $\forall l::location) (l'::location). (a @_{graphI} b l \wedge a @_{graphI} b l') \rightarrow l = l') \wedge$   
 $(\forall l::location. nodup a (agra (graphI b) l))) \Rightarrow$

$(b, c) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\} \Rightarrow$

( $\forall aa::char\ list.$

( $\forall l::location) l'::location. (aa @_{graphI} a l \wedge aa @_{graphI} a l') \rightarrow l = l')$

$\wedge$

( $\forall l::location. nodup aa (agra (graphI a) l))) \rightarrow$

( $\forall a::char\ list.$

$(\forall (l::location) \ l'::location. (a \ @_{graphI \ c} \ l \wedge a \ @_{graphI \ c} \ l') \longrightarrow l = l') \wedge$   
 $(\forall l::location. \text{nodup } a \ (agra \ (graphI \ c) \ l)))$   
**by** (rule impI, rule allI, rule actors-unique-loc-base, drule CollectD,  
simp,erule impE, assumption, erule spec)  
**qed**  
**show** ?thesis  
**by** (insert ind, insert assms(2), simp)  
**qed**

**lemma** actors-unique-loc-aid-base:

$\forall a. (\forall l \ l'. a \ @_{graphI \ Airplane-not-in-danger-init} \ l \wedge$   
 $a \ @_{graphI \ Airplane-not-in-danger-init} \ l' \longrightarrow l = l') \wedge$   
 $(\forall l. \text{nodup } a \ (agra \ (graphI \ Airplane-not-in-danger-init) \ l)))$   
**proof** (simp add: Airplane-not-in-danger-init-def ex-graph-def, clarify, rule conjI,  
clarify,  
rule conjI, clarify, rule impI, (rule allI)+, rule impI, simp add: atI-def)  
**show**  $\bigwedge (l::location) \ l'::location.$   
"Charly"  
 $\in \text{set } (if \ l = cockpit \text{ then } ["Bob", "Charly"]$   
 $\text{else if } l = door \text{ then } [] \text{ else if } l = cabin \text{ then } ["Alice"] \text{ else } []) \wedge$   
"Charly"  
 $\in \text{set } (if \ l' = cockpit \text{ then } ["Bob", "Charly"]$   
 $\text{else if } l' = door \text{ then } [] \text{ else if } l' = cabin \text{ then } ["Alice"] \text{ else } []) \implies$   
 $l = l'$   
**by** (case-tac  $l = l'$ , assumption, rule FalseE, case-tac  $l = cockpit \vee l = door \vee$   
 $l = cabin,$   
erule disjE, simp, case-tac  $l' = door \vee l' = cabin,$  erule disjE, simp,  
simp add: cabin-def door-def, simp, erule disjE, simp add: door-def cockpit-def,

simp add: cabin-def door-def cockpit-def, simp)

**next show**  $\bigwedge a::char \text{ list.}$

"Charly"  $\neq a \longrightarrow$   
 $(\forall (l::location) \ l'::location.$   
 $a \ @_{Lgraph \ \{(cockpit, door), (door, cabin)\}} \quad (\lambda x::location. \quad \text{if } x = cockpit \text{ then } ["Bob"$   
 $l \wedge$   
 $a \ @_{Lgraph \ \{(cockpit, door), (door, cabin)\}} \quad (\lambda x::location. \quad \text{if } x = cockpit \text{ then } ["Bob"$   
 $l' \longrightarrow$   
 $l = l')$

**by** (clarify, simp add: atI-def, case-tac  $l = l'$ , assumption, rule FalseE,  
case-tac  $l = cockpit \vee l = door \vee l = cabin,$  erule disjE, simp,  
case-tac  $l' = door \vee l' = cabin,$  erule disjE, simp, simp add: cabin-def door-def,  
simp, erule disjE, simp add: door-def cockpit-def, case-tac  $l = cockpit,$   
simp add: cabin-def cockpit-def, simp add: cabin-def door-def, case-tac  $l' =$   
cockpit,  
simp, simp add: cabin-def, case-tac  $l' = door,$  simp, simp add: cabin-def,  
simp)  
**qed**

**lemma** actors-unique-loc-aid-step:

$(Airplane-not-in-danger-init, I) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*$   
 $\implies \forall a. (\forall l l'. a @_{graphI} I l \wedge a @_{graphI} I l' \longrightarrow l = l') \wedge$   
 $(\forall l. nodup a (agra (graphI I) l))$   
**by** (erule actors-unique-loc-step, rule actors-unique-loc-aid-base)

Using the state transition, Kripke structure and CTL, we can now also express (and prove!) unreachability properties which enable to formally verify security properties for specific policies, like two-person rule.

**lemma** *Anid-airplane-actors: actors-graph (graphI Airplane-not-in-danger-init) = airplane-actors*

**proof** (simp add: Airplane-not-in-danger-init-def ex-graph-def actors-graph-def nodes-def

airplane-actors-def, rule equalityI)

**show**  $\{x::char\ list.$   
 $\exists y::location.$   
 $(y = door \longrightarrow$   
 $(door = cockpit \longrightarrow$   
 $(\exists y::location. y = cockpit \vee y = cabin \vee y = cockpit \vee y = cockpit \wedge$   
 $cockpit = cabin) \wedge$   
 $(x = "Bob" \vee x = "Charly")) \wedge$   
 $door = cockpit) \wedge$   
 $(y \neq door \longrightarrow$   
 $(y = cockpit \longrightarrow$   
 $(\exists y::location.$   
 $y = door \vee$   
 $cockpit = door \wedge y = cabin \vee$   
 $y = cockpit \wedge cockpit = door \vee y = door \wedge cockpit = cabin) \wedge$   
 $(x = "Bob" \vee x = "Charly")) \wedge$   
 $(y \neq cockpit \longrightarrow y = cabin \wedge x = "Alice" \wedge y = cabin)))\}$   
 $\subseteq \{"Bob", "Charly", "Alice"\}$   
**by** (rule subsetI, drule CollectD, erule exE, (erule conjE)+,  
 simp add: door-def cockpit-def cabin-def, (erule conjE)+, force)  
**next show**  $\{"Bob", "Charly", "Alice"\}$   
 $\subseteq \{x::char\ list.$   
 $\exists y::location.$   
 $(y = door \longrightarrow$   
 $(door = cockpit \longrightarrow$   
 $(\exists y::location.$   
 $y = cockpit \vee y = cabin \vee y = cockpit \vee y = cockpit \wedge cockpit =$   
 $cabin) \wedge$   
 $(x = "Bob" \vee x = "Charly")) \wedge$   
 $door = cockpit) \wedge$   
 $(y \neq door \longrightarrow$   
 $(y = cockpit \longrightarrow$   
 $(\exists y::location.$   
 $y = door \vee$   
 $cockpit = door \wedge y = cabin \vee$   
 $y = cockpit \wedge cockpit = door \vee y = door \wedge cockpit = cabin) \wedge$   
 $(x = "Bob" \vee x = "Charly")) \wedge$

$(y \neq \text{cockpit} \longrightarrow y = \text{cabin} \wedge x = \text{"Alice"} \wedge y = \text{cabin}))\}$   
**by** (*rule subsetI*, *rule CollectI*, *simp add: door-def cockpit-def cabin-def*,  
*case-tac x = "Bob"*, *force*, *case-tac x = "Charly"*, *force*,  
*subgoal-tac x = "Alice"*, *force*, *simp*)

**qed**

**lemma** *all-airplane-actors*:  $(\text{Airplane-not-in-danger-init}, y) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*$   
 $\implies \text{actors-graph}(\text{graphI } y) = \text{airplane-actors}$   
**by** (*insert Anid-airplane-actors*, *erule subst*, *rule sym*, *erule same-actors*)

**lemma** *actors-at-loc-in-graph*:  $\llbracket l \in \text{nodes}(\text{graphI } I); a \ @_{\text{graphI } I} l \rrbracket$   
 $\implies a \in \text{actors-graph } (\text{graphI } I)$   
**by** (*simp add: atI-def actors-graph-def*, *rule exI*, *rule conjI*)

**lemma** *not-en-get-Apnid*:  
**assumes**  $(\text{Airplane-not-in-danger-init}, y) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^*$   
**shows**  $\sim(\text{enables } y \ l \ (\text{Actor } a) \ \text{get})$   
**proof** –  
**have**  $\text{delta } y = \text{delta}(\text{Airplane-not-in-danger-init})$   
**by** (*insert assms*, *rule sym*, *erule-tac init-state-policy*)  
**with** *assms* **show** *?thesis*  
**by** (*simp add: Airplane-not-in-danger-init-def enables-def local-policies-four-eyes-def*)

**qed**

**lemma** *Apnid-tsp-test*:  $\sim(\text{enables } \text{Airplane-not-in-danger-init cockpit } (\text{Actor } \text{"Alice"}) \ \text{get})$   
**by** (*simp add: Airplane-not-in-danger-init-def ex-creds-def enables-def*  
*local-policies-four-eyes-def cabin-def door-def cockpit-def*  
*ex-graph-def ex-locs-def*)

**lemma** *Apnid-tsp-test-gen*:  $\sim(\text{enables } \text{Airplane-not-in-danger-init } l \ (\text{Actor } a) \ \text{get})$   
**by** (*simp add: Airplane-not-in-danger-init-def ex-creds-def enables-def*  
*local-policies-four-eyes-def cabin-def door-def cockpit-def*  
*ex-graph-def ex-locs-def*)

**lemma** *test-graph-atI*:  $\text{"Bob"} \ @_{\text{graphI } \text{Airplane-not-in-danger-init cockpit}}$   
**by** (*simp add: Airplane-not-in-danger-init-def ex-graph-def atI-def*)

Invariant: number of staff in cockpit never below 2

**lemma** *two-person-inv*:  
**fixes**  $z \ z'$   
**assumes**  $(2::\text{nat}) \leq \text{length } (\text{agra } (\text{graphI } z) \ \text{cockpit})$   
**and**  $\text{nodes}(\text{graphI } z) = \text{nodes}(\text{graphI } \text{Airplane-not-in-danger-init})$   
**and**  $\text{delta}(z) = \text{delta}(\text{Airplane-not-in-danger-init})$   
**and**  $(\text{Airplane-not-in-danger-init}, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}).$

```

 $x \rightarrow_n y\}^*$ 
  and  $z \rightarrow_n z'$ 
  shows  $(2::nat) \leq \text{length } (\text{agra } (\text{graphI } z') \text{ cockpit})$ 
proof (insert assms(5), erule state-transition-in.cases)
  show  $\bigwedge (G::igraph) (I::infrastructure) (a::char \text{ list}) (l::location) (a'::char \text{ list})$ 
     $(za::char \text{ list})$ 
     $I'::infrastructure.$ 
     $z = I \implies$ 
     $z' = I' \implies$ 
     $G = \text{graphI } I \implies$ 
     $a @_G l \implies$ 
     $a' @_G l \implies$ 
     $\text{has } G (\text{Actor } a, za) \implies$ 
     $\text{enables } I l (\text{Actor } a) \text{ get} \implies$ 
     $I' =$ 
     $\text{Infrastructure}$ 
     $(\text{Lgraph } (\text{gra } G) (\text{agra } G)$ 
       $((\text{cgra } G)(\text{Actor } a' := (za \# \text{fst } (\text{cgra } G (\text{Actor } a'))), \text{snd } (\text{cgra } G (\text{Actor } a')))))$ 
       $(\text{lgra } G))$ 
     $(\text{delta } I) \implies$ 
     $(2::nat) \leq \text{length } (\text{agra } (\text{graphI } z') \text{ cockpit})$  using assms by simp
  next show  $\bigwedge (G::igraph) (I::infrastructure) (a::char \text{ list}) (l::location) (I'::infrastructure)$ 
     $za::char \text{ list}.$ 
     $z = I \implies$ 
     $z' = I' \implies$ 
     $G = \text{graphI } I \implies$ 
     $a @_G l \implies$ 
     $\text{enables } I l (\text{Actor } a) \text{ put} \implies$ 
     $I' = \text{Infrastructure } (\text{Lgraph } (\text{gra } G) (\text{agra } G) (\text{cgra } G) ((\text{lgra } G)(l := [za])))$ 
     $(\text{delta } I) \implies$ 
     $(2::nat) \leq \text{length } (\text{agra } (\text{graphI } z') \text{ cockpit})$  using assms by simp
  next show  $\bigwedge (G::igraph) (I::infrastructure) (l::location) (a::char \text{ list}) (I'::infrastructure)$ 
     $za::char \text{ list}.$ 
     $z = I \implies$ 
     $z' = I' \implies$ 
     $G = \text{graphI } I \implies$ 
     $\text{enables } I l (\text{Actor } a) \text{ put} \implies$ 
     $I' = \text{Infrastructure } (\text{Lgraph } (\text{gra } G) (\text{agra } G) (\text{cgra } G) ((\text{lgra } G)(l := [za])))$ 
     $(\text{delta } I) \implies$ 
     $(2::nat) \leq \text{length } (\text{agra } (\text{graphI } z') \text{ cockpit})$  using assms by simp
  next show  $\bigwedge (G::igraph) (I::infrastructure) (a::char \text{ list}) (l::location) (l'::location)$ 
     $I'::infrastructure.$ 
     $z = I \implies$ 
     $z' = I' \implies$ 
     $G = \text{graphI } I \implies$ 
     $a @_G l \implies$ 
     $l \in \text{nodes } G \implies$ 
     $l' \in \text{nodes } G \implies$ 
     $a \in \text{actors-graph } (\text{graphI } I) \implies$ 

```

$enables\ I\ l'\ (Actor\ a)\ move \implies$   
 $I' = Infrastructure\ (move-graph-a\ a\ l\ l'\ (graphI\ I))\ (\delta I) \implies$   
 $(2::nat) \leq length\ (agra\ (graphI\ z')\ cockpit)$   
**proof** –  
**fix**  $G :: igrph$  **and**  $I :: infrastructure$  **and**  $a :: char\ list$  **and**  $l :: location$  **and**  $l' :: location$  **and**  $I' :: infrastructure$   
**have**  $f1: UasI\ "Eve"\ "Charly"$   
**using** *Eve-precipitating-event Insider-Eve Insider-def* **by** *force*  
**obtain**  $ccs :: char\ list \Rightarrow char\ list$  **and**  $ccsa :: char\ list \Rightarrow char\ list$  **where**  
 $f2: \forall cs\ csa. (\neg UasI\ cs\ csa \vee Actor\ cs = Actor\ csa \wedge (\forall csa\ csb. (csa = cs \vee csb = cs \vee Actor\ csa \neq Actor\ csb) \vee csa = csb)) \wedge (UasI\ cs\ csa \vee Actor\ cs \neq Actor\ csa \vee (ccs\ cs \neq cs \wedge ccsa\ cs \neq cs \wedge Actor\ (ccs\ cs) = Actor\ (ccsa\ cs)) \wedge ccs\ cs \neq ccsa\ cs)$   
**using** *UasI-def* **by** *moura*  
**have**  $"Bob" @ graphI\ (Infrastructure\ ex-graph\ local-policies)\ Location\ 2$   
**using** *Airplane-not-in-danger-init-def cockpit-def test-graph-atI* **by** *force*  
**then have**  $Actor\ "Bob" = Actor\ "Eve"$   
**using** *Airplane-scenario-def airplane.cockpit-foe-control airplane-axioms cockpit-def ex-inv3 global-policy-def* **by** *blast*  
**then show**  $2 \leq length\ (agra\ (graphI\ z')\ cockpit)$   
**using**  $f2\ f1$  **by** *auto*  
**qed**  
**qed**

**lemma** *two-person-inv1*:  
**assumes**  $(Airplane-not-in-danger-init, z) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*$   
**shows**  $(2::nat) \leq length\ (agra\ (graphI\ z)\ cockpit)$   
**proof** (*insert assms, erule rtrancl-induct*)  
**show**  $(2::nat) \leq length\ (agra\ (graphI\ Airplane-not-in-danger-init)\ cockpit)$   
**by** (*simp add: Airplane-not-in-danger-init-def ex-graph-def*)  
**next show**  $\bigwedge (y::infrastructure)\ z::infrastructure. (Airplane-not-in-danger-init, y) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^* \implies$   
 $(y, z) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\} \implies$   
 $(2::nat) \leq length\ (agra\ (graphI\ y)\ cockpit) \implies (2::nat) \leq length\ (agra\ (graphI\ z)\ cockpit)$   
**by** (*rule two-person-inv, assumption, rule same-nodes, assumption, rule sym, rule init-state-policy, assumption+, simp*)  
**qed**

The version of `two_person_inv` above we need, uses cardinality of lists of actors rather than length of lists. Therefore first some equivalences and then a restatement of `two_person_inv` in terms of sets

proof idea: show since there are no duplicates in the list  $agra\ (graphI\ z)$  cockpit therefore then  $card(set(agra\ (graphI\ z))) = length(agra\ (graphI\ z))$

**lemma** *nodup-card-insert*:  
 $a \notin set\ l \implies card\ (insert\ a\ (set\ l)) = Suc\ (card\ (set\ l))$

**by** *auto*

**lemma** *no-dup-set-list-num-eq*[*rule-format*]:

$(\forall a. \text{nodup } a \ l) \longrightarrow \text{card } (\text{set } l) = \text{length } l$

**by** (*induct-tac* *l*, *simp*, *clarify*, *simp*, *erule impE*, *rule allI*,  
*drule-tac*  $x = aa$  **in** *spec*, *case-tac*  $a = aa$ , *simp*, *erule nodup-notin*, *simp*)

**lemma** *two-person-set-inv*:

**assumes** (*Airplane-not-in-danger-init*,  $z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}).$   
 $x \rightarrow_n y\}^*$

**shows**  $(2::\text{nat}) \leq \text{card } (\text{set } (\text{agra } (\text{graphI } z) \text{ cockpit}))$

**proof** –

**have**  $a: \text{card } (\text{set } (\text{agra } (\text{graphI } z) \text{ cockpit})) = \text{length}(\text{agra } (\text{graphI } z) \text{ cockpit})$

**by** (*rule no-dup-set-list-num-eq*, *insert assms*, *drule actors-unique-loc-aid-step*,  
*drule-tac*  $x = a$  **in** *spec*, *erule conjE*, *erule-tac*  $x = \text{cockpit}$  **in** *spec*)

**show** *?thesis*

**by** (*insert a*, *erule ssubst*, *rule two-person-inv1*, *rule assms*)

**qed**

**lemma** *Pred-all-unique*:  $\llbracket ? x. P x; (! x. P x \longrightarrow x = c) \rrbracket \Longrightarrow P c$

**by** (*case-tac*  $P c$ , *assumption*, *erule exE*, *drule-tac*  $x = x$  **in** *spec*,  
*drule mp*, *assumption*, *erule subst*)

**lemma** *Set-all-unique*:  $\llbracket S \neq \{\}; (\forall x \in S. x = c) \rrbracket \Longrightarrow c \in S$

**by** (*rule-tac*  $P = \lambda x. x \in S$  **in** *Pred-all-unique*, *force*, *simp*)

**lemma** *airplane-actors-inv0*[*rule-format*]:

$\forall z z'. (\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } z) \text{ cockpit}). h \in \text{airplane-actors}) \wedge$   
 $(\text{Airplane-not-in-danger-init}, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x$   
 $\rightarrow_n y\}^* \wedge$

$z \rightarrow_n z' \longrightarrow (\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } z') \text{ cockpit}). h \in$

*airplane-actors*)

**proof** (*clarify*, *erule state-transition-in.cases*)

**show**  $\bigwedge (z::\text{infrastructure}) (z'::\text{infrastructure}) (h::\text{char list}) (G::\text{igraph}) (I::\text{infrastructure})$

$(a::\text{char list}) (l::\text{location}) (a'::\text{char list}) (za::\text{char list}) I'::\text{infrastructure}.$

$h \in \text{set } (\text{agra } (\text{graphI } z') \text{ cockpit}) \Longrightarrow$

$\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } z) \text{ cockpit}). h \in \text{airplane-actors} \Longrightarrow$

$(\text{Airplane-not-in-danger-init}, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x$   
 $\rightarrow_n y\}^* \Longrightarrow$

$z = I \Longrightarrow$

$z' = I' \Longrightarrow$

$G = \text{graphI } I \Longrightarrow$

$a @_G l \Longrightarrow$

$a' @_G l \Longrightarrow$

$\text{has } G (\text{Actor } a, za) \Longrightarrow$

$\text{enables } I l (\text{Actor } a) \text{ get} \Longrightarrow$

$I' =$

*Infrastructure*

$(L\text{graph } (\text{gra } G) (\text{agra } G))$

$((cgra\ G)(Actor\ a' := (za\ \#\ fst\ (cgra\ G\ (Actor\ a')), snd\ (cgra\ G\ (Actor\ a'))))\ (lgra\ G))$   
 $(\delta I) \implies$   
 $h \in \text{airplane-actors}$   
**by simp**  
**next show**  $\bigwedge(z::\text{infrastructure})\ (z'::\text{infrastructure})\ (h::\text{char list})\ (G::\text{igraph})\ (I::\text{infrastructure})$   
 $(a::\text{char list})\ (l::\text{location})\ (I'::\text{infrastructure})\ za::\text{char list}.$   
 $h \in \text{set}\ (agra\ (\text{graphI}\ z')\ cockpit) \implies$   
 $\forall h::\text{char list} \in \text{set}\ (agra\ (\text{graphI}\ z)\ cockpit). h \in \text{airplane-actors} \implies$   
 $(\text{Airplane-not-in-danger-init}, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x$   
 $\rightarrow_n y\}^* \implies$   
 $z = I \implies$   
 $z' = I' \implies$   
 $G = \text{graphI}\ I \implies$   
 $a @_G l \implies$   
 $\text{enables}\ I\ l\ (Actor\ a)\ \text{put} \implies$   
 $I' = \text{Infrastructure}\ (Lgraph\ (gra\ G)\ (agra\ G)\ (cgra\ G)\ ((lgra\ G)(l := [za])))$   
 $(\delta I) \implies$   
 $h \in \text{airplane-actors}$   
**by simp**  
**next show**  $\bigwedge(z::\text{infrastructure})\ (z'::\text{infrastructure})\ (h::\text{char list})\ (G::\text{igraph})\ (I::\text{infrastructure})$   
 $(l::\text{location})\ (a::\text{char list})\ (I'::\text{infrastructure})\ za::\text{char list}.$   
 $h \in \text{set}\ (agra\ (\text{graphI}\ z')\ cockpit) \implies$   
 $\forall h::\text{char list} \in \text{set}\ (agra\ (\text{graphI}\ z)\ cockpit). h \in \text{airplane-actors} \implies$   
 $(\text{Airplane-not-in-danger-init}, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x$   
 $\rightarrow_n y\}^* \implies$   
 $z = I \implies$   
 $z' = I' \implies$   
 $G = \text{graphI}\ I \implies$   
 $\text{enables}\ I\ l\ (Actor\ a)\ \text{put} \implies$   
 $I' = \text{Infrastructure}\ (Lgraph\ (gra\ G)\ (agra\ G)\ (cgra\ G)\ ((lgra\ G)(l := [za])))$   
 $(\delta I) \implies$   
 $h \in \text{airplane-actors}$   
**by simp**  
**next show**  $\bigwedge(z::\text{infrastructure})\ (z'::\text{infrastructure})\ (h::\text{char list})\ (G::\text{igraph})\ (I::\text{infrastructure})$   
 $(a::\text{char list})\ (l::\text{location})\ (l'::\text{location})\ I'::\text{infrastructure}.$   
 $h \in \text{set}\ (agra\ (\text{graphI}\ z')\ cockpit) \implies$   
 $\forall h::\text{char list} \in \text{set}\ (agra\ (\text{graphI}\ z)\ cockpit). h \in \text{airplane-actors} \implies$   
 $(\text{Airplane-not-in-danger-init}, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x$   
 $\rightarrow_n y\}^* \implies$   
 $z = I \implies$   
 $z' = I' \implies$   
 $G = \text{graphI}\ I \implies$   
 $a @_G l \implies$   
 $l \in \text{nodes}\ G \implies$   
 $l' \in \text{nodes}\ G \implies$   
 $a \in \text{actors-graph}\ (\text{graphI}\ I) \implies$   
 $\text{enables}\ I\ l'\ (Actor\ a)\ \text{move} \implies$   
 $I' = \text{Infrastructure}\ (\text{move-graph-a}\ a\ l\ l'\ (\text{graphI}\ I))\ (\delta I) \implies h \in$



*airplane-actors*

**proof** (*simp add: move-graph-a-def*,  
*case-tac a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) l')*)  
**show**  $\bigwedge(z::\text{infrastructure}) (z'::\text{infrastructure}) (h::\text{char list}) (G::\text{igraph}) (I::\text{infrastructure})$   
 $(a::\text{char list}) (l::\text{location}) (l'::\text{location}) I'::\text{infrastructure}.$   
 $h \in \text{set } ((\text{if } a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l')$   
 $\text{then } (\text{agra } (\text{graphI } I))$   
 $(l := \text{del } a (\text{agra } (\text{graphI } I) l), l' := a \# \text{agra } (\text{graphI } I) l')$   
 $\text{else } \text{agra } (\text{graphI } I))$   
 $\text{cockpit}) \implies$   
 $\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } I) \text{ cockpit}). h \in \text{airplane-actors} \implies$   
 $(\text{Airplane-not-in-danger-init}, I) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x$   
 $\rightarrow_n y\}^* \implies$   
 $z = I \implies$   
 $z' =$   
 $\text{Infrastructure}$   
 $(\text{Lgraph } (\text{gra } (\text{graphI } I))$   
 $(\text{if } a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l')$   
 $\text{then } (\text{agra } (\text{graphI } I))(l := \text{del } a (\text{agra } (\text{graphI } I) l), l' := a \# \text{agra}$   
 $(\text{graphI } I) l')$   
 $\text{else } \text{agra } (\text{graphI } I))$   
 $(\text{cgra } (\text{graphI } I)) (\text{lgra } (\text{graphI } I)))$   
 $(\text{delta } I) \implies$   
 $G = \text{graphI } I \implies$   
 $a @_{\text{graphI } I} l \implies$   
 $l \in \text{nodes } (\text{graphI } I) \implies$   
 $l' \in \text{nodes } (\text{graphI } I) \implies$   
 $a \in \text{actors-graph } (\text{graphI } I) \implies$   
 $\text{enables } I l' (\text{Actor } a) \text{ move} \implies$   
 $I' =$   
 $\text{Infrastructure}$   
 $(\text{Lgraph } (\text{gra } (\text{graphI } I))$   
 $(\text{if } a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l')$   
 $\text{then } (\text{agra } (\text{graphI } I))(l := \text{del } a (\text{agra } (\text{graphI } I) l), l' := a \# \text{agra}$   
 $(\text{graphI } I) l')$   
 $\text{else } \text{agra } (\text{graphI } I))$   
 $(\text{cgra } (\text{graphI } I)) (\text{lgra } (\text{graphI } I)))$   
 $(\text{delta } I) \implies$   
 $\neg (a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l')) \implies h \in$   
*airplane-actors*  
**by simp**  
**next show**  $\bigwedge(z::\text{infrastructure}) (z'::\text{infrastructure}) (h::\text{char list}) (G::\text{igraph})$   
 $(I::\text{infrastructure})$   
 $(a::\text{char list}) (l::\text{location}) (l'::\text{location}) I'::\text{infrastructure}.$   
 $h \in \text{set } ((\text{if } a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l')$   
 $\text{then } (\text{agra } (\text{graphI } I))$   
 $(l := \text{del } a (\text{agra } (\text{graphI } I) l), l' := a \# \text{agra } (\text{graphI } I) l')$   
 $\text{else } \text{agra } (\text{graphI } I))$   
 $\text{cockpit}) \implies$

$$\begin{aligned}
& \forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } I) \text{ cockpit}). h \in \text{airplane-actors} \implies \\
& (\text{Airplane-not-in-danger-init}, I) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \\
\rightarrow_n y\}^* \implies \\
& z = I \implies \\
& z' = \\
& \text{Infrastructure} \\
& (\text{Lgraph } (\text{gra } (\text{graphI } I))) \\
& (\text{if } a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l') \\
& \text{then } (\text{agra } (\text{graphI } I))(l := \text{del } a (\text{agra } (\text{graphI } I) l), l' := a \# \text{agra} \\
& (\text{graphI } I) l') \\
& \text{else } \text{agra } (\text{graphI } I)) \\
& (\text{cgra } (\text{graphI } I)) (\text{lgra } (\text{graphI } I))) \\
& (\text{delta } I) \implies \\
& G = \text{graphI } I \implies \\
& a @_{\text{graphI } I} l \implies \\
& l \in \text{nodes } (\text{graphI } I) \implies \\
& l' \in \text{nodes } (\text{graphI } I) \implies \\
& a \in \text{actors-graph } (\text{graphI } I) \implies \\
& \text{enables } I l' (\text{Actor } a) \text{ move} \implies \\
& I' = \\
& \text{Infrastructure} \\
& (\text{Lgraph } (\text{gra } (\text{graphI } I))) \\
& (\text{if } a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l') \\
& \text{then } (\text{agra } (\text{graphI } I))(l := \text{del } a (\text{agra } (\text{graphI } I) l), l' := a \# \text{agra} \\
& (\text{graphI } I) l') \\
& \text{else } \text{agra } (\text{graphI } I)) \\
& (\text{cgra } (\text{graphI } I)) (\text{lgra } (\text{graphI } I))) \\
& (\text{delta } I) \implies \\
& a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l') \implies h \in \\
& \text{airplane-actors} \\
& \text{proof } (\text{case-tac } l' = \text{cockpit}) \\
& \text{show } \bigwedge (z::\text{infrastructure}) (z'::\text{infrastructure}) (h::\text{char list}) (G::\text{igraph}) (I::\text{infrastructure}) \\
& (a::\text{char list}) (l::\text{location}) (l'::\text{location}) I'::\text{infrastructure}. \\
& h \in \text{set } ((\text{if } a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l') \\
& \text{then } (\text{agra } (\text{graphI } I)) \\
& (l := \text{del } a (\text{agra } (\text{graphI } I) l), l' := a \# \text{agra } (\text{graphI } I) l') \\
& \text{else } \text{agra } (\text{graphI } I)) \\
& \text{cockpit}) \implies \\
& \forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } I) \text{ cockpit}). h \in \text{airplane-actors} \implies \\
& (\text{Airplane-not-in-danger-init}, I) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \\
\rightarrow_n y\}^* \implies \\
& z = I \implies \\
& z' = \\
& \text{Infrastructure} \\
& (\text{Lgraph } (\text{gra } (\text{graphI } I))) \\
& (\text{if } a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l') \\
& \text{then } (\text{agra } (\text{graphI } I))(l := \text{del } a (\text{agra } (\text{graphI } I) l), l' := a \# \text{agra} \\
& (\text{graphI } I) l') \\
& \text{else } \text{agra } (\text{graphI } I))
\end{aligned}$$

$(cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))$   
 $(delta\ I) \implies$   
 $G = graphI\ I \implies$   
 $a @_{graphI\ I}\ l \implies$   
 $l \in nodes\ (graphI\ I) \implies$   
 $l' \in nodes\ (graphI\ I) \implies$   
 $a \in actors-graph\ (graphI\ I) \implies$   
 $enables\ I\ l'\ (Actor\ a)\ move \implies$   
 $I' =$   
*Infrastructure*  
 $(Lgraph\ (gra\ (graphI\ I))$   
 $(if\ a \in set\ (agra\ (graphI\ I)\ l) \wedge a \notin set\ (agra\ (graphI\ I)\ l')$   
 $then\ (agra\ (graphI\ I))(l := del\ a\ (agra\ (graphI\ I)\ l),\ l' := a \# agra$   
 $(graphI\ I)\ l')$   
 $else\ agra\ (graphI\ I))$   
 $(cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))$   
 $(delta\ I) \implies$   
 $a \in set\ (agra\ (graphI\ I)\ l) \wedge a \notin set\ (agra\ (graphI\ I)\ l') \implies$   
 $l' \neq cockpit \implies h \in airplane-actors$   
**proof**  $(case-tac\ cockpit = l)$   
**show**  $\bigwedge(z::infrastructure)\ (z'::infrastructure)\ (h::char\ list)\ (G::igraph)$   
 $(I::infrastructure)$   
 $(a::char\ list)\ (l::location)\ (l'::location)\ I'::infrastructure.$   
 $h \in set\ ((if\ a \in set\ (agra\ (graphI\ I)\ l) \wedge a \notin set\ (agra\ (graphI\ I)\ l')$   
 $then\ (agra\ (graphI\ I))$   
 $(l := del\ a\ (agra\ (graphI\ I)\ l),\ l' := a \# agra\ (graphI\ I)\ l')$   
 $else\ agra\ (graphI\ I))$   
 $cockpit) \implies$   
 $\forall h::char\ list \in set\ (agra\ (graphI\ I)\ cockpit). h \in airplane-actors \implies$   
 $(Airplane-not-in-danger-init,\ I) \in \{(x::infrastructure,\ y::infrastructure). x$   
 $\rightarrow_n y\}^* \implies$   
 $z = I \implies$   
 $z' =$   
*Infrastructure*  
 $(Lgraph\ (gra\ (graphI\ I))$   
 $(if\ a \in set\ (agra\ (graphI\ I)\ l) \wedge a \notin set\ (agra\ (graphI\ I)\ l')$   
 $then\ (agra\ (graphI\ I))(l := del\ a\ (agra\ (graphI\ I)\ l),\ l' := a \# agra$   
 $(graphI\ I)\ l')$   
 $else\ agra\ (graphI\ I))$   
 $(cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))$   
 $(delta\ I) \implies$   
 $G = graphI\ I \implies$   
 $a @_{graphI\ I}\ l \implies$   
 $l \in nodes\ (graphI\ I) \implies$   
 $l' \in nodes\ (graphI\ I) \implies$   
 $a \in actors-graph\ (graphI\ I) \implies$   
 $enables\ I\ l'\ (Actor\ a)\ move \implies$   
 $I' =$   
*Infrastructure*

```

(Lgraph (gra (graphI I))
  (if a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) l')
    then (agra (graphI I))(l := del a (agra (graphI I) l), l' := a # agra
(graphI I) l')
    else agra (graphI I))
  (cgra (graphI I)) (lgra (graphI I)))
(delta I) ⇒
a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) l') ⇒
l' ≠ cockpit ⇒ cockpit ≠ l ⇒ h ∈ airplane-actors
by simp
next show ∧(z::infrastructure) (z'::infrastructure) (h::char list) (G::igraph)
(I::infrastructure)
(a::char list) (l::location) (l'::location) I'::infrastructure.
h ∈ set ((if a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) l')
  then (agra (graphI I))
    (l := del a (agra (graphI I) l), l' := a # agra (graphI I) l')
  else agra (graphI I))
  cockpit) ⇒
∀ h::char list ∈ set (agra (graphI I) cockpit). h ∈ airplane-actors ⇒
(Airplane-not-in-danger-init, I) ∈ {(x::infrastructure, y::infrastructure). x
→n y}* ⇒
z = I ⇒
z' =
Infrastructure
(Lgraph (gra (graphI I))
  (if a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) l')
    then (agra (graphI I))(l := del a (agra (graphI I) l), l' := a # agra
(graphI I) l')
    else agra (graphI I))
  (cgra (graphI I)) (lgra (graphI I)))
(delta I) ⇒
G = graphI I ⇒
a @graphI I l ⇒
l ∈ nodes (graphI I) ⇒
l' ∈ nodes (graphI I) ⇒
a ∈ actors-graph (graphI I) ⇒
enables I l' (Actor a) move ⇒
I' =
Infrastructure
(Lgraph (gra (graphI I))
  (if a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) l')
    then (agra (graphI I))(l := del a (agra (graphI I) l), l' := a # agra
(graphI I) l')
    else agra (graphI I))
  (cgra (graphI I)) (lgra (graphI I)))
(delta I) ⇒
a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) l') ⇒
l' ≠ cockpit ⇒ cockpit = l ⇒ h ∈ airplane-actors
by (simp, erule bspec, erule del-up)

```

```

qed
next show  $\bigwedge(z::\text{infrastructure}) (z'::\text{infrastructure}) (h::\text{char list}) (G::\text{igraph})$ 
 $(I::\text{infrastructure})$ 
   $(a::\text{char list}) (l::\text{location}) (l'::\text{location}) I'::\text{infrastructure}.$ 
   $h \in \text{set } ((\text{if } a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l') \text{ then } (\text{agra } (\text{graphI } I))$ 
     $(l := \text{del } a (\text{agra } (\text{graphI } I) l), l' := a \# \text{agra } (\text{graphI } I) l')$ 
     $\text{else } \text{agra } (\text{graphI } I))$ 
     $\text{cockpit}) \implies$ 
 $\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } I) \text{cockpit}). h \in \text{airplane-actors} \implies$ 
 $(\text{Airplane-not-in-danger-init}, I) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x$ 
 $\rightarrow_n y\}^* \implies$ 
 $z = I \implies$ 
 $z' =$ 
 $\text{Infrastructure}$ 
 $(\text{Lgraph } (\text{gra } (\text{graphI } I))$ 
   $(\text{if } a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l')$ 
     $\text{then } (\text{agra } (\text{graphI } I))(l := \text{del } a (\text{agra } (\text{graphI } I) l), l' := a \# \text{agra}$ 
 $(\text{graphI } I) l')$ 
     $\text{else } \text{agra } (\text{graphI } I))$ 
     $(\text{cgra } (\text{graphI } I)) (\text{lgra } (\text{graphI } I)))$ 
 $(\text{delta } I) \implies$ 
 $G = \text{graphI } I \implies$ 
 $a @_{\text{graphI } I} l \implies$ 
 $l \in \text{nodes } (\text{graphI } I) \implies$ 
 $l' \in \text{nodes } (\text{graphI } I) \implies$ 
 $a \in \text{actors-graph } (\text{graphI } I) \implies$ 
 $\text{enables } I l' (\text{Actor } a) \text{ move} \implies$ 
 $I' =$ 
 $\text{Infrastructure}$ 
 $(\text{Lgraph } (\text{gra } (\text{graphI } I))$ 
   $(\text{if } a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l')$ 
     $\text{then } (\text{agra } (\text{graphI } I))(l := \text{del } a (\text{agra } (\text{graphI } I) l), l' := a \# \text{agra}$ 
 $(\text{graphI } I) l')$ 
     $\text{else } \text{agra } (\text{graphI } I))$ 
     $(\text{cgra } (\text{graphI } I)) (\text{lgra } (\text{graphI } I)))$ 
 $(\text{delta } I) \implies$ 
 $a \in \text{set } (\text{agra } (\text{graphI } I) l) \wedge a \notin \text{set } (\text{agra } (\text{graphI } I) l') \implies$ 
 $l' = \text{cockpit} \implies h \in \text{airplane-actors}$ 
proof  $(\text{simp}, \text{erule } \text{disjE})$ 
show  $\bigwedge(z::\text{infrastructure}) (z'::\text{infrastructure}) (h::\text{char list}) (G::\text{igraph})$ 
 $(I::\text{infrastructure})$ 
   $(a::\text{char list}) (l::\text{location}) (l'::\text{location}) I'::\text{infrastructure}.$ 
 $\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } I) \text{cockpit}). h \in \text{airplane-actors} \implies$ 
 $(\text{Airplane-not-in-danger-init}, I) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x$ 
 $\rightarrow_n y\}^* \implies$ 
 $z = I \implies$ 
 $z' =$ 
 $\text{Infrastructure}$ 

```

```

(Lgraph (gra (graphI I))
  ((agra (graphI I))
    (l := del a (agra (graphI I) l), cockpit := a # agra (graphI I) cockpit))
  (cgra (graphI I)) (lgra (graphI I))))
(delta I) ==>
G = graphI I ==>
a @graphI I l ==>
l ∈ nodes (graphI I) ==>
cockpit ∈ nodes (graphI I) ==>
a ∈ actors-graph (graphI I) ==>
enables I cockpit (Actor a) move ==>
I' =
Infrastructure
(Lgraph (gra (graphI I))
  ((agra (graphI I))
    (l := del a (agra (graphI I) l), cockpit := a # agra (graphI I) cockpit))
  (cgra (graphI I)) (lgra (graphI I))))
(delta I) ==>
a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) cockpit) ==>
l' = cockpit ==> h ∈ set (agra (graphI I) cockpit) ==> h ∈ airplane-actors
  by (erule bspec)
next fix z z' h G I a l l' I'
  assume a0: ∀ h::char list ∈ set (agra (graphI I) cockpit). h ∈ airplane-actors
  and a1: (Airplane-not-in-danger-init, I) ∈ {(x::infrastructure, y::infrastructure)}.
x →n y}*
  and a2: z = I
  and a3: z' =
Infrastructure
(Lgraph (gra (graphI I))
  ((agra (graphI I))
    (l := del a (agra (graphI I) l), cockpit := a # agra (graphI I) cockpit))
  (cgra (graphI I)) (lgra (graphI I))))
(delta I)
  and a4: G = graphI I
  and a5: a @graphI I l
  and a6: l ∈ nodes (graphI I)
  and a7: cockpit ∈ nodes (graphI I)
  and a8: a ∈ actors-graph (graphI I)
  and a9: enables I cockpit (Actor a) move
  and a10: I' =
Infrastructure
(Lgraph (gra (graphI I))
  ((agra (graphI I))
    (l := del a (agra (graphI I) l), cockpit := a # agra (graphI I) cockpit))
  (cgra (graphI I)) (lgra (graphI I))))
(delta I)
  and a11: a ∈ set (agra (graphI I) l) ∧ a ∉ set (agra (graphI I) cockpit)
  and a12: l' = cockpit
  and a13: h = a

```

```

    show  $h \in \text{airplane-actors}$ 
  proof -
    have  $a: \text{delta}(I) = \text{delta}(\text{Airplane-not-in-danger-init})$ 
      by (rule sym, rule init-state-policy, rule a1)
    show ?thesis
      by (insert a0 a1 a2 a3 a4 a5 a6 a7 a8 a9 a10 a11 a12 a13 a,
          simp add: enables-def, erule bexE, simp add: Airplane-not-in-danger-init-def,
          unfold local-policies-four-eyes-def, simp, erule disjE, simp+,

          erule exE, (erule conjE)+,
          fold local-policies-four-eyes-def Airplane-not-in-danger-init-def,
          drule all-airplane-actors, erule subst)
  qed
qed
qed
qed
qed
qed

lemma airplane-actors-inv:
  assumes  $(\text{Airplane-not-in-danger-init}, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}).$ 
 $x \rightarrow_n y\}^*$ 
  shows  $\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } z) \text{ cockpit}). h \in \text{airplane-actors}$ 
  proof -
    have  $\text{ind}: (\text{Airplane-not-in-danger-init}, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}).$ 
 $x \rightarrow_n y\}^* \longrightarrow$ 
 $(\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } z) \text{ cockpit}). h \in \text{airplane-actors})$ 
    proof (insert assms, erule rtrancl-induct)
      show  $(\text{Airplane-not-in-danger-init}, \text{Airplane-not-in-danger-init}) \in \{(x,y). x$ 
 $\rightarrow_n y\}^* \longrightarrow$ 
 $(\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } \text{Airplane-not-in-danger-init}) \text{ cockpit}). h \in$ 
 $\text{airplane-actors})$ 
      by (rule impI, rule ballI,
          simp add: Airplane-not-in-danger-init-def ex-graph-def airplane-actors-def
          ex-locs-def,
          blast)
    next show  $\bigwedge (y::\text{infrastructure}) z::\text{infrastructure}.$ 
 $(\text{Airplane-not-in-danger-init}, y) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x$ 
 $\rightarrow_n y\}^* \Longrightarrow$ 
 $(y, z) \in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\} \Longrightarrow$ 
 $(\text{Airplane-not-in-danger-init}, y) \in \{(x,y). x \rightarrow_n y\}^* \longrightarrow$ 
 $(\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } y) \text{ cockpit}). h \in \text{airplane-actors}) \Longrightarrow$ 
 $(\text{Airplane-not-in-danger-init}, z) \in \{(x,y). x \rightarrow_n y\}^* \longrightarrow$ 
 $(\forall h::\text{char list} \in \text{set } (\text{agra } (\text{graphI } z) \text{ cockpit}). h \in \text{airplane-actors})$ 
      by (rule impI, rule ballI, rule-tac  $z = y$  in airplane-actors-inv0,
          rule conjI, erule impE, assumption+, simp)
    qed
  qed
  show ?thesis
  by (insert ind, insert assms, simp)

```

qed

**lemma** *Eve-not-in-cockpit*: (*Airplane-not-in-danger-init*, *I*)  
 $\in \{(x::\text{infrastructure}, y::\text{infrastructure}). x \rightarrow_n y\}^* \implies$   
 $x \in \text{set } (\text{agra } (\text{graphI } I) \text{ cockpit}) \implies x \neq \text{"Eve"}$   
**by** (*drule airplane-actors-inv*, *simp add: airplane-actors-def*,  
*drule-tac x = x in bspec, assumption, force*)

2 person invariant implies that there is always some x in cockpit x not equal Eve

**lemma** *tp-imp-control*:  
**assumes** (*Airplane-not-in-danger-init*, *I*)  $\in \{(x::\text{infrastructure}, y::\text{infrastructure}).$   
 $x \rightarrow_n y\}^*$   
**shows** ( $? x :: \text{identity}. x @_{\text{graphI } I} \text{cockpit} \wedge \text{Actor } x \neq \text{Actor "Eve"}$ )  
**proof** –  
**have** *a0*:  $(2::\text{nat}) \leq \text{card } (\text{set } (\text{agra } (\text{graphI } I) \text{ cockpit}))$   
**by** (*insert assms, erule two-person-set-inv*)  
**have** *a1*: *is-singleton* ( $\{\text{"Charly"}\}$ )  
**by** (*rule is-singletonI*)  
**have** *a6*:  $\neg(\forall x \in \text{set } (\text{agra } (\text{graphI } I) \text{ cockpit}). (\text{Actor } x = \text{Actor "Eve"}))$   
**proof** (*rule notI*)  
**assume** *a7*:  $\forall x::\text{char list} \in \text{set } (\text{agra } (\text{graphI } I) \text{ cockpit}). \text{Actor } x = \text{Actor "Eve"}$   
**have** *a5*:  $\forall x::\text{char list} \in \text{set } (\text{agra } (\text{graphI } I) \text{ cockpit}). x = \text{"Charly"}$   
**by** (*insert assms a0 a7, rule ballI, drule-tac x = x in bspec, assumption,*  
*subgoal-tac x  $\neq$  "Eve", insert Insider-Eve, unfold Insider-def, (drule mp),*  
*rule Eve-precipitating-event, simp add: UasI-def, erule Eve-not-in-cockpit*)  
**have** *a4*:  $\text{set } (\text{agra } (\text{graphI } I) \text{ cockpit}) = \{\text{"Charly"}\}$   
**by** (*rule equalityI, rule subsetI, insert a5, simp,*  
*rule subsetI, simp, rule Set-all-unique, insert a0, force, rule a5*)  
**have** *a2*:  $(\text{card}(\text{set } (\text{agra } (\text{graphI } I) \text{ cockpit})) :: \text{char list set}) = (1 :: \text{nat})$   
**by** (*insert a1, unfold is-singleton-altdef, erule ssubst, insert a4, erule ssubst,*  
*fold is-singleton-altdef, rule a1*)  
**have** *a3*:  $(2 :: \text{nat}) \leq (1 :: \text{nat})$   
**by** (*insert a0, insert a2, erule subst, assumption*)  
**show** *False*  
**by** (*insert a5 a4 a3 a2, arith*)  
**qed**  
**show** *?thesis* **by** (*insert assms a0 a6, simp add: atI-def, blast*)  
**qed**

**lemma** *Fend-2*: (*Airplane-not-in-danger-init*, *I*)  $\in \{(x::\text{infrastructure}, y::\text{infrastructure}).$   
 $x \rightarrow_n y\}^* \implies$   
 $\neg \text{enables } I \text{ cockpit } (\text{Actor "Eve"}) \text{ put}$   
**by** (*insert cockpit-foe-control, simp add: foe-control-def, drule-tac x = I in spec,*  
*erule mp, erule tp-imp-control*)

**theorem** *Four-eyes-no-danger*: *Air-tp-Kripke*  $\vdash AG (\{x. \text{global-policy } x \text{ "Eve"}\})$



```

proof (simp add: Air-tp-Kripke-def check-def, rule conjI)
  show Airplane-not-in-danger-init ∈ Air-tp-states
    by (simp add: Airplane-not-in-danger-init-def Air-tp-states-def
          state-transition-in-refl-def)
next show Airplane-not-in-danger-init ∈ AG {x::infrastructure. global-policy x
  "Eve"}
  proof (unfold AG-def, simp add: gfp-def,
    rule-tac x = {(x :: infrastructure) ∈ states Air-tp-Kripke. ~("Eve" @graphI x
cockpit)}) in exI,
    rule conjI)
  show {x::infrastructure ∈ states Air-tp-Kripke. ¬ "Eve" @graphI x cockpit}
    ⊆ {x::infrastructure. global-policy x "Eve"}
  by (unfold global-policy-def, simp add: airplane-actors-def, rule subsetI,
    drule CollectD, rule CollectI, erule conjE,
    simp add: Air-tp-Kripke-def Air-tp-states-def state-transition-in-refl-def,
    erule Fend-2)
next show {x::infrastructure ∈ states Air-tp-Kripke. ¬ "Eve" @graphI x cockpit}
  ⊆ AX {x::infrastructure ∈ states Air-tp-Kripke. ¬ "Eve" @graphI x cockpit} ∧
  Airplane-not-in-danger-init
  ∈ {x::infrastructure ∈ states Air-tp-Kripke. ¬ "Eve" @graphI x cockpit}
proof
  show Airplane-not-in-danger-init
    ∈ {x::infrastructure ∈ states Air-tp-Kripke. ¬ "Eve" @graphI x cockpit}
  by (simp add: Airplane-not-in-danger-init-def Air-tp-Kripke-def Air-tp-states-def
    state-transition-refl-def ex-graph-def atI-def Air-tp-Kripke-def
    state-transition-in-refl-def)
next show {x::infrastructure ∈ states Air-tp-Kripke. ¬ "Eve" @graphI x cockpit}
  ⊆ AX {x::infrastructure ∈ states Air-tp-Kripke. ¬ "Eve" @graphI x cockpit}
proof (rule subsetI, simp add: AX-def, rule subsetI, rule CollectI, rule conjI)
  show ∧(x::infrastructure) xa::infrastructure.
    x ∈ states Air-tp-Kripke ∧ ¬ "Eve" @graphI x cockpit ⇒
    xa ∈ Collect (state-transition x) ⇒ xa ∈ states Air-tp-Kripke
  by (simp add: Air-tp-Kripke-def Air-tp-states-def state-transition-in-refl-def,
    simp add: atI-def, erule conjE,
    unfold state-transition-infra-def state-transition-in-refl-def,
    erule rtrancl-into-rtrancl, rule CollectI, simp)
next fix x xa
  assume a0: x ∈ states Air-tp-Kripke ∧ ¬ "Eve" @graphI x cockpit
  and a1: xa ∈ Collect (state-transition x)
  show ¬ "Eve" @graphI xa cockpit
proof –
  have b: (Airplane-not-in-danger-init, xa)
    ∈ {(x::infrastructure, y::infrastructure). x →n y}*
  proof (insert a0 a1, rule rtrancl-trans)
  show x ∈ states Air-tp-Kripke ∧ ¬ "Eve" @graphI x cockpit ⇒
    xa ∈ Collect (state-transition x) ⇒
    (x, xa) ∈ {(x::infrastructure, y::infrastructure). x →n y}*
  by (unfold state-transition-infra-def, force)

```

```

next show  $x \in \text{states Air-tp-Kripke} \wedge \neg \text{"Eve"} @_{\text{graphI } x} \text{cockpit} \implies$ 
 $xa \in \text{Collect (state-transition } x) \implies$ 
 $(\text{Airplane-not-in-danger-init}, x) \in \{(x::\text{infrastructure}, y::\text{infrastructure}).$ 
 $x \rightarrow_n y\}^*$ 
by (erule conjE, simp add: Air-tp-Kripke-def Air-tp-states-def state-transition-in-refl-def)+
qed
show ?thesis
by (insert a0 a1 b, rule-tac  $P = \text{"Eve"} @_{\text{graphI } xa} \text{cockpit}$  in notI,
simp add: atI-def, drule Eve-not-in-cockpit, assumption, simp)
qed
qed
qed
qed
qed
end

```

In the following we construct an instance of the locale airplane and proof that it is an interpretation. This serves the validation.

**definition** airplane-actors-def': airplane-actors  $\equiv \{\text{"Bob"}, \text{"Charly"}, \text{"Alice"}\}$

**definition** airplane-locations-def':

airplane-locations  $\equiv \{\text{Location } 0, \text{Location } 1, \text{Location } 2\}$

**definition** cockpit-def': cockpit  $\equiv \text{Location } 2$

**definition** door-def': door  $\equiv \text{Location } 1$

**definition** cabin-def': cabin  $\equiv \text{Location } 0$

**definition** global-policy-def': global-policy  $I a \equiv a \notin \text{airplane-actors}$   
 $\longrightarrow \neg(\text{enables } I \text{ cockpit (Actor } a) \text{ put})$

**definition** ex-creds-def': ex-creds  $\equiv$

```

(λ x. (if x = Actor "Bob"
then (["PIN"], ["pilot"])
else (if x = Actor "Charly"
then (["PIN"], ["copilot"])
else (if x = Actor "Alice"
then (["PIN"], ["flightattendant"])
else ([], []))))

```

**definition** ex-locs-def': ex-locs  $\equiv (\lambda x. \text{if } x = \text{door} \text{ then } [\text{"norm"}] \text{ else } (\text{if } x = \text{cockpit} \text{ then } [\text{"air"}] \text{ else } []))$

**definition** ex-locs'-def': ex-locs'  $\equiv (\lambda x. \text{if } x = \text{door} \text{ then } [\text{"locked"}] \text{ else } (\text{if } x = \text{cockpit} \text{ then } [\text{"air"}] \text{ else } []))$

**definition** ex-graph-def': ex-graph  $\equiv \text{Lgraph}$

```

{(cockpit, door), (door, cabin)}
(λ x. if x = cockpit then ["Bob", "Charly"]
else (if x = door then []
else (if x = cabin then ["Alice"] else [])))
ex-creds ex-locs

```

**definition** *aid-graph-def'*:  $\text{aid-graph} \equiv \text{Lgraph}$   
 $\{(cockpit, door), (door, cabin)\}$   
 $(\lambda x. \text{if } x = cockpit \text{ then } ["Charly"]$   
 $\quad \text{else } (\text{if } x = door \text{ then } []$   
 $\quad \quad \text{else } (\text{if } x = cabin \text{ then } ["Bob", "Alice"] \text{ else } []))$   
 $\text{ex-creds ex-locs}'$

**definition** *aid-graph0-def'*:  $\text{aid-graph0} \equiv \text{Lgraph}$   
 $\{(cockpit, door), (door, cabin)\}$   
 $(\lambda x. \text{if } x = cockpit \text{ then } ["Charly"]$   
 $\quad \text{else } (\text{if } x = door \text{ then } ["Bob"]$   
 $\quad \quad \text{else } (\text{if } x = cabin \text{ then } ["Alice"] \text{ else } []))$   
 $\text{ex-creds ex-locs}$

**definition** *agid-graph-def'*:  $\text{agid-graph} \equiv \text{Lgraph}$   
 $\{(cockpit, door), (door, cabin)\}$   
 $(\lambda x. \text{if } x = cockpit \text{ then } ["Charly"]$   
 $\quad \text{else } (\text{if } x = door \text{ then } []$   
 $\quad \quad \text{else } (\text{if } x = cabin \text{ then } ["Bob", "Alice"] \text{ else } []))$   
 $\text{ex-creds ex-locs}$

**definition** *local-policies-def'*:  $\text{local-policies } G \equiv$   
 $(\lambda y. \text{if } y = cockpit \text{ then}$   
 $\quad \{(\lambda x. (? n. (n @_G cockpit) \wedge Actor n = x), \{put\}),$   
 $\quad \quad (\lambda x. (? n. (n @_G cabin) \wedge Actor n = x \wedge has G (x, "PIN")$   
 $\quad \quad \quad \wedge isin G door "norm"), \{move\})$   
 $\quad \}$   
 $\quad \text{else } (\text{if } y = door \text{ then } \{(\lambda x. True, \{move\}),$   
 $\quad \quad (\lambda x. (? n. (n @_G cockpit) \wedge Actor n = x), \{put\})\}$   
 $\quad \quad \text{else } (\text{if } y = cabin \text{ then } \{(\lambda x. True, \{move\})\}$   
 $\quad \quad \quad \text{else } \{\})\})$

**definition** *local-policies-four-eyes-def'*:  $\text{local-policies-four-eyes } G \equiv$   
 $(\lambda y. \text{if } y = cockpit \text{ then}$   
 $\quad \{(\lambda x. (? n. (n @_G cockpit) \wedge Actor n = x) \wedge$   
 $\quad \quad 2 \leq \text{length}(\text{agra } G y) \wedge (\forall h \in \text{set}(\text{agra } G y). h \in \text{airplane-actors}),$   
 $\quad \quad \{put\}),$   
 $\quad \quad (\lambda x. (? n. (n @_G cabin) \wedge Actor n = x \wedge has G (x, "PIN") \wedge$   
 $\quad \quad \quad isin G door "norm"), \{move\})$   
 $\quad \}$   
 $\quad \text{else } (\text{if } y = door \text{ then}$   
 $\quad \quad \{(\lambda x. ((? n. (n @_G cockpit) \wedge Actor n = x) \wedge 3 \leq \text{length}(\text{agra } G$   
 $\text{cockpit})), \{move\})\}$   
 $\quad \quad \text{else } (\text{if } y = cabin \text{ then}$   
 $\quad \quad \quad \{(\lambda x. ((? n. (n @_G door) \wedge Actor n = x)), \{move\})\}$   
 $\quad \quad \quad \text{else } \{\})\})$

**definition** *Airplane-scenario-def'*:  
 $\text{Airplane-scenario} \equiv \text{Infrastructure ex-graph local-policies}$

**definition** *Airplane-in-danger-def'*:

*Airplane-in-danger*  $\equiv$  *Infrastructure aid-graph local-policies*

Intermediate step where pilot left cockpit but door still in norm position

**definition** *Airplane-getting-in-danger0-def'*:

*Airplane-getting-in-danger0*  $\equiv$  *Infrastructure aid-graph0 local-policies*

**definition** *Airplane-getting-in-danger-def'*:

*Airplane-getting-in-danger*  $\equiv$  *Infrastructure agid-graph local-policies*

**definition** *Air-states-def'*: *Air-states*  $\equiv$   $\{ I. \text{Airplane-scenario} \rightarrow_n^* I \}$

**definition** *Air-Kripke-def'*: *Air-Kripke*  $\equiv$  *Kripke Air-states*  $\{ \text{Airplane-scenario} \}$

**definition** *Airplane-not-in-danger-def'*:

*Airplane-not-in-danger*  $\equiv$  *Infrastructure aid-graph local-policies-four-eyes*

**definition** *Airplane-not-in-danger-init-def'*:

*Airplane-not-in-danger-init*  $\equiv$  *Infrastructure ex-graph local-policies-four-eyes*

**definition** *Air-tp-states-def'*: *Air-tp-states*  $\equiv$   $\{ I. \text{Airplane-not-in-danger-init} \rightarrow_n^* I \}$

**definition** *Air-tp-Kripke-def'*:

*Air-tp-Kripke*  $\equiv$  *Kripke Air-tp-states*  $\{ \text{Airplane-not-in-danger-init} \}$

**definition** *Safety-def'*: *Safety*  $I a \equiv a \in \text{airplane-actors}$

$\longrightarrow (\text{enables } I \text{ cockpit } (\text{Actor } a) \text{ move})$

**definition** *Security-def'*: *Security*  $I a \equiv (\text{isin } (\text{graph } I) \text{ door } \text{"locked"})$

$\longrightarrow \neg(\text{enables } I \text{ cockpit } (\text{Actor } a) \text{ move})$

**definition** *foe-control-def'*: *foe-control*  $l c \equiv$

$(! I :: \text{infrastructure}. (? x :: \text{identity}.$   
 $x @_{\text{graph } I} l \wedge \text{Actor } x \neq \text{Actor } \text{"Eve"})$   
 $\longrightarrow \neg(\text{enables } I l (\text{Actor } \text{"Eve"}) c))$

**definition** *astate-def'*: *astate*  $x \equiv$

$(\text{case } x \text{ of}$   
 $\text{"Eve"} \Rightarrow \text{Actor-state depressed } \{ \text{revenge}, \text{peer-recognition} \}$   
 $| - \Rightarrow \text{Actor-state happy } \{ \})$

**print-interps** *airplane*

The additional assumption identified in the case study needs to be given as an axiom

**axiomatization where**

*cockpit-foe-control'*: *foe-control cockpit put*

(The following addresses the issue of redefining an abstract type. We experimented with suggestion given here: Makarius Wenzel, Re: [isabelle] typedecl versus explicit type parameters, Isabelle users mailing list, 2009, <https://lists.cam.ac.uk/pipermail/cl-isabelle-users/2009-July/msg00111.html>. ) We furthermore need axiomatization to add the missing semantics to the abstractly declared type actor and thereby be able to redefine consts Actor. Since the function Actor has also been defined as a consts :: identity ⇒ actor as an abstract function without a definition, we now also now add its semantics mimicking some of the concepts of the conservative type definition of HOL. The alternative method of using a Locale to replace the abstract type\_decl actor in the AirInsider is a more elegant method for representing and abstract type actor but it is not working properly for our framework since it necessitates introducing a type parameter 'actor into infrastructures which then makes it impossible to instantiate them to the typeclass state in order to use CTL and Kripke and the generic state transition. Therefore, we go the former way of a post-hoc axiomatic redefinition of the abstract type actor by using axiomatization of the existing Locale "type\_definition". This is done in the following. It allows to abstractedly assume as an axiom that there is a type definition for the abstract type actor. Adding a suitable definition of a representation for this type then additionally enables to introduce a definition for the function Actor (again using axiomatization to enforce the new definition).

**definition** Actor-Abs :: identity ⇒ identity option

**where**

Actor-Abs x ≡ (if x ∈ {"Eve", "Charly"} then None else Some x)

**lemma** UasI-ActorAbs: Actor-Abs "Eve" = Actor-Abs "Charly" ∧

(∀ (x::char list) y::char list. x ≠ "Eve" ∧ y ≠ "Eve" ∧ Actor-Abs x = Actor-Abs y ⟶ x = y)

**by** (simp add: Actor-Abs-def)

**lemma** Actor-Abs-ran: Actor-Abs x ∈ {y :: identity option. y ∈ Some ' {x :: identity. x ∉ {"Eve", "Charly"}} | y = None}

**by** (simp add: Actor-Abs-def)

With the following axiomatization, we can simulate the abstract type actor and postulate some unspecified Abs and Rep functions between it and the simulated identity option subtype.

**axiomatization where** Actor-type-def:

type-definition (Rep :: actor ⇒ identity option)(Abs :: identity option ⇒ actor)  
 {y :: identity option. y ∈ Some ' {x :: identity. x ∉ {"Eve", "Charly"}} | y = None}

**lemma** Abs-inj-on: ∧ Abs Rep:: actor ⇒ char list option. x ∈ {y :: identity option. y ∈ Some ' {x :: identity. x ∉ {"Eve", "Charly"}} | y = None}

⟹ y ∈ {y :: identity option. y ∈ Some ' {x :: identity. x ∉ {"Eve", "Charly"}} | y = None}

$\implies (Abs :: char\ list\ option \Rightarrow actor) x = Abs\ y \implies x = y$   
**by** (insert Actor-type-def, drule-tac  $x = Rep$  **in** meta-spec, drule-tac  $x = Abs$  **in** meta-spec,  
 frule-tac  $x = Abs\ x$  **and**  $y = Abs\ y$  **in** type-definition.Rep-inject,  
 subgoal-tac ( $Rep\ (Abs\ x) = Rep\ (Abs\ y)$ ), subgoal-tac  $Rep\ (Abs\ x) = x$ ,  
 subgoal-tac  $Rep\ (Abs\ y) = y$ , erule subst, erule subst, assumption,  
 (erule type-definition.Abs-inverse, assumption)+, simp)

**lemma** Actor-td-Abs-inverse:

$(y \in \{y :: identity\ option. y \in Some\ ' \{x :: identity. x \notin \{"Eve", "Charly"\}\} | y = None\}) \implies$   
 $(Rep :: actor \Rightarrow identity\ option)((Abs :: identity\ option \Rightarrow actor)\ y) = y$   
**by** (insert Actor-type-def, drule-tac  $x = Rep$  **in** meta-spec, drule-tac  $x = Abs$  **in** meta-spec,  
 erule type-definition.Abs-inverse, assumption)

Now, we can redefine the function Actor using a second axiomatization

**axiomatization where** Actor-redef:  $Actor = (Abs :: identity\ option \Rightarrow actor)o\ Actor-Abs$

need to show that  $Abs\ (Actor-Abs\ x) = Abs\ (Actor-Abs\ y) \longrightarrow Actor-Abs\ x = Actor-Abs\ y$ , i.e. *injective Abs*. Generally, Abs is not injective but *injective-on* the type predicate. So, need to show that for any x, *Actor-Abs* x is in the type predicate, then it would follow. What is the type predicate?  $\{y. y \in Some\ ' \{x. x \notin \{"Eve", "Charly"\}\} \vee y = None\}$

**lemma** UasI-Actor-redef:

$\bigwedge Abs\ Rep :: actor \Rightarrow char\ list\ option.$   
 $((Abs :: identity\ option \Rightarrow actor)o\ Actor-Abs)\ "Eve" = ((Abs :: identity\ option \Rightarrow actor)o\ Actor-Abs)\ "Charly" \wedge$   
 $(\forall (x :: char\ list)\ y :: char\ list. x \neq "Eve" \wedge y \neq "Eve" \wedge$   
 $((Abs :: identity\ option \Rightarrow actor)o\ Actor-Abs)\ x = ((Abs :: identity\ option \Rightarrow actor)o\ Actor-Abs)\ y$   
 $\longrightarrow x = y)$   
**by** (insert UasI-ActorAbs, simp, clarify, drule-tac  $x = x$  **in** spec, drule-tac  $x = y$  **in** spec,  
 subgoal-tac  $Actor-Abs\ x = Actor-Abs\ y$ , simp, rule Abs-inj-on, rule Actor-Abs-ran,  
 rule Actor-Abs-ran)

Finally all of this allows us to show the last assumption contained in the Insider Locale assumption needed for the interpretation of airplane.

**lemma** UasI-Actor:  $UasI\ "Eve"\ "Charly"$

**by** (unfold UasI-def, insert Actor-redef, drule meta-spec, erule ssubst, rule UasI-Actor-redef)

**interpretation** airplane airplane-actors airplane-locations cockpit door cabin global-policy

$ex-creds\ ex-locs\ ex-locs'\ ex-graph\ aid-graph\ aid-graph0\ agid-graph$   
 $local-policies\ local-policies-four-eyes\ Airplane-scenario\ Airplane-in-danger$   
 $Airplane-getting-in-danger0\ Airplane-getting-in-danger\ Air-states$   
*Air-Kripke*

```

    Airplane-not-in-danger Airplane-not-in-danger-init Air-tp-states
    Air-tp-Kripke Safety Security foe-control astate
  by (rule airplane.intro, simp add: tipping-point-def,
    simp add: Insider-def UasI-def tipping-point-def atI-def,
    insert UasI-Actor, simp add: UasI-def,
    insert cockpit-foe-control', simp add: foe-control-def' cockpit-def',
    rule airplane-actors-def',
    (simp add: airplane-locations-def' cockpit-def' door-def' cabin-def' global-policy-def'
      ex-creds-def' ex-locs-def' ex-locs'-def' ex-graph-def' aid-graph-def'
    aid-graph0-def'
      agid-graph-def' local-policies-def' local-policies-four-eyes-def' Airplane-scenario-def'
      Airplane-in-danger-def' Airplane-getting-in-danger0-def' Airplane-getting-in-danger-def'
      Air-states-def' Air-Kripke-def' Airplane-not-in-danger-def' Airplane-not-in-danger-init-def'
      Air-tp-states-def' Air-tp-Kripke-def' Safety-def' Security-def'
      foe-control-def' astate-def')+
  end

```

## References

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