latex

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Contents

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theory MC
imports Main
begin
declare [[show-types]]
thm monotone-def
definition monotone :: ('a \ set \Rightarrow 'a \ set) \Rightarrow bool
where monotone \tau \equiv (\forall p q. p \subseteq q \longrightarrow \tau p \subseteq \tau q)
lemma monotoneE : monotone \ \tau \Longrightarrow p \subseteq q \Longrightarrow \tau \ p \subseteq \tau \ q
by (simp add: monotone-def)
lemma lfp1: monotone \tau \longrightarrow (lfp \ \tau = \bigcap \{Z. \ \tau \ Z \subseteq Z\})
by (simp add: monotone-def lfp-def)
lemma gfp1: monotone \tau \longrightarrow (gfp \ \tau = \bigcup \ \{Z.\ Z \subseteq \tau \ Z\})
by (simp add: monotone-def gfp-def)
primrec power :: ['a \Rightarrow 'a, nat] \Rightarrow ('a \Rightarrow 'a) ((- \hat{\ }-) \not\downarrow 0)
where
power-zero: (f \hat{\ } 0) = (\lambda x. x)
power-suc: (f \hat{f} (Suc n)) = (f o (f \hat{f} n))
lemma predtrans-empty:
  assumes monotone 	au
  shows \forall i. (\tau \hat{i}) (\{\}) \subseteq (\tau \hat{i} + 1))(\{\})
proof (rule allI, induct-tac i)
  show (\tau \ \hat{\ }\theta ::nat) \ \{\} \subseteq (\tau \ \hat{\ }(\theta ::nat) + (1 ::nat)) \ \{\} \ \mathbf{by} \ simp
next show \bigwedge(i::nat) n::nat. (\tau \hat{n}) \{\} \subseteq (\tau \hat{n} + (1::nat)) \{\} \implies (\tau \hat{suc} n) \{\} \subseteq (\tau \hat{suc} n + (1::nat)) \{\}
  proof -
     fix i n
     assume a : (\tau \hat{n}) \{\} \subseteq (\tau \hat{n} + (1::nat)) \{\}
     have (\tau ((\tau \hat{n}) \{\})) \subseteq (\tau ((\tau \hat{n} + (1 :: nat))) \{\})) using assms
       apply (rule monotoneE)
       by (rule \ a)
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thus (\tau \hat{\ } Suc\ n) \ \{\} \subseteq (\tau \hat{\ } Suc\ n + (1::nat)) \ \{\} by simp
  qed
qed
lemma ex-card: finite S \Longrightarrow \exists n :: nat. card S = n
by simp
lemma less-not-le: [(x:: nat) < y; y \le x] \Longrightarrow False
by arith
lemma infchain-outruns-all:
  assumes finite (UNIV :: 'a set)
   and \forall i :: nat. (\tau \hat{i}) (\{\}:: 'a \ set) \subset (\tau \hat{i} + (1 :: nat)) \{\}
 shows \forall j :: nat. \exists i :: nat. j < card ((\tau \hat{i}) \{\})
proof (rule allI, induct-tac j)
  show \exists i::nat. (0::nat) < card ((\tau \hat{i}) \{\}) using assms
   apply (drule-tac \ x = 0 \ in \ spec)
   apply (rule-tac \ x = 1 \ in \ exI)
   apply simp
   apply (subgoal-tac card \{\} = \theta)
   apply (erule subst)
   apply (rule psubset-card-mono)
   apply (rule-tac\ B = UNIV\ in\ finite-subset)
   apply simp
   {\bf apply} \ {\it assumption} +
     by simp
  next show \bigwedge(j::nat) n::nat. \exists i::nat. n < card ((\tau \hat{\ }i) \{\})
            \implies \exists i :: nat. Suc \ n < card \ ((\tau \hat{i}) \ \{\})
   proof -
     fix j n
     assume a: \exists i::nat. \ n < card \ ((\tau \hat{i}) \}
     obtain i where n < card ((\tau \hat{\ } (i :: nat)) \{\})
       apply (rule exE)
        apply (rule \ a)
       by simp
     thus \exists i. Suc \ n < card \ ((\tau \hat{i}) \ \{\}) \ using \ assms
       apply (rule-tac x = i + 1 in exI)
       apply (subgoal-tac card((\tau \hat{i}) {}) < card((\tau \hat{i} + (1 :: nat)) {}))
       apply arith
       apply (rule psubset-card-mono)
       apply (rule-tac\ B = UNIV\ in\ finite-subset)
       apply simp
       apply (rule assms)
       by (erule spec)
   qed
  qed
lemma no-infinite-subset-chain:
  assumes finite (UNIV :: 'a set)
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monotone \ (\tau :: ('a \ set \Rightarrow 'a \ set))
    and
    and
             \forall i :: nat. ((\tau :: 'a \ set \Rightarrow 'a \ set) \hat{\ } i) \{\} \subset (\tau \hat{\ } i + (1 :: nat)) (\{\} :: 'a \} \}
set)
  shows
            False
proof -
 have a: \forall (j :: nat). (\exists (i :: nat). (j :: nat) < card((\tau \hat{i})(\{\} :: 'a set))) using
   apply (erule-tac \tau = \tau in infchain-outruns-all)
   by assumption
  hence b: \exists (n :: nat). \ card(UNIV :: 'a \ set) = n \ using \ assms
    by (erule-tac\ S = UNIV\ in\ ex-card)
  from this obtain n where c: card(UNIV :: 'a \ set) = n \ by \ (erule \ exE)
  hence d: \exists i::nat. \ card \ UNIV < card \ ((\tau \hat{\ }i) \ \{\}) \ using \ a
    apply (drule\text{-}tac \ x = card \ UNIV \ \textbf{in} \ spec)
    by assumption
  from this obtain i where e: card (UNIV :: 'a set) < card ((\tau \hat{i}) {})
    by (erule\ exE)
  hence f: (card((\tau \hat{i})\{\})) \leq (card (UNIV :: 'a set)) using assms
    thm Finite-Set.card-mono
      apply (rule-tac A = ((\tau \hat{i}))) in Finite-Set.card-mono)
     apply assumption
    by (rule subset-UNIV)
  thus False using e
    \mathbf{thm}\ less-not-le
    apply (erule-tac y = card((\tau \hat{i})\{\}) in less-not-le)
    by assumption
qed
lemma finite-fixp:
  assumes finite(UNIV :: 'a set)
     and monotone (\tau :: ('a \ set \Rightarrow 'a \ set))
    shows \exists i. (\tau \hat{i}) (\{\}) = (\tau \hat{i} + 1)(\{\})
proof -
  have a: \forall i::nat. (\tau \hat{i}) (\{\}:: 'a \ set) \subseteq (\tau \hat{i} + (1::nat)) \{\}
    thm predtrans-empty
    apply(rule\ predtrans-empty)
    by (rule\ assms(2))
  hence b: (\exists i :: nat. \neg ((\tau \hat{i}) \{\} \subset (\tau \hat{i} + 1)) \{\})) using assms
    apply (subgoal-tac \neg (\forall i :: nat. (\tau \hat{i}) \{\} \subset (\tau \hat{i} + 1)) \{\}))
    apply blast
    apply (rule\ not I)
    apply (rule no-infinite-subset-chain)
    by assumption
  thus \exists i. (\tau \hat{i}) (\{\}) = (\tau \hat{i} + 1))(\{\}) using a
    by blast
\mathbf{qed}
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lemma predtrans-UNIV:
  assumes monotone \ \tau
  shows \forall i. (\tau \hat{i}) (UNIV) \supseteq (\tau \hat{i} + 1)(UNIV)
proof (rule allI, induct-tac i)
  show (\tau \hat{\ } (0::nat) + (1::nat)) UNIV \subseteq (\tau \hat{\ } 0::nat) UNIV by simp
next show \bigwedge(i::nat) n::nat.
      (\tau \hat{\ } n + (1::nat)) \ \mathit{UNIV} \subseteq (\tau \hat{\ } n) \ \mathit{UNIV} \Longrightarrow (\tau \hat{\ } \mathit{Suc} \ n + (1::nat)) \ \mathit{UNIV}
\subseteq (\tau \ \widehat{\ } Suc\ n) \ UNIV
  proof -
    \mathbf{fix}\ i\ n
    assume a: (\tau \hat{n} + (1::nat)) \ UNIV \subseteq (\tau \hat{n}) \ UNIV
    have (\tau ((\tau \hat{n}) UNIV)) \supseteq (\tau ((\tau \hat{n} (n + (1 :: nat))) UNIV)) using assms
      apply (rule monotoneE)
      by (rule \ a)
    thus (\tau \hat{\ } Suc \ n + (1::nat)) \ UNIV \subseteq (\tau \hat{\ } Suc \ n) \ UNIV  by simp
   qed
 qed
lemma Suc-less-le: x < (y - n) \Longrightarrow x \le (y - (Suc \ n))
by simp
lemma card-univ-subtract:
  assumes finite (UNIV :: 'a set) and monotone (\tau :: 'a set \Rightarrow 'a set)
     and (\forall i :: nat. ((\tau :: 'a \ set \Rightarrow 'a \ set) \hat{i} + (1 :: nat)) (UNIV :: 'a \ set) \subset
(\tau \hat{i}) UNIV
  shows (\forall i :: nat. card((\tau \hat{i}) (UNIV :: 'a set)) \leq (card (UNIV :: 'a set)) - i)
proof (rule allI, induct-tac i)
 show card ((\tau \ \hat{\ } \theta :: nat) \ UNIV) \leq card \ (UNIV :: 'a \ set) - (\theta :: nat) \ using \ assms
    by (simp)
next show \bigwedge(i::nat) n::nat.
       card\ ((\tau \hat{\ } n)\ (\mathit{UNIV} :: 'a\ set)) \leq \mathit{card}\ (\mathit{UNIV} :: 'a\ set) - n \Longrightarrow
       card\ ((\tau \ \hat{\ } Suc\ n)\ (UNIV :: 'a\ set)) \leq card\ (UNIV :: 'a\ set) - Suc\ n\ using
assms
 proof -
    \mathbf{fix} \ i \ n
    assume a: card ((\tau \hat{n}) (UNIV :: 'a set)) < card (UNIV :: 'a set) - n
    have b: (\tau \hat{n} + (1::nat)) (UNIV :: 'a set) \subset (\tau \hat{n}) UNIV using assms
      by (erule-tac \ x = n \ in \ spec)
    have card((\tau \hat{n} + (1 :: nat)) (UNIV :: 'a set)) < card((\tau \hat{n}) (UNIV :: 'a
set))
      apply (rule psubset-card-mono)
      apply (rule finite-subset)
      apply (rule subset-UNIV)
       apply (rule\ assms(1))
      by (rule \ b)
    thus card\ ((\tau \ \hat{\ } Suc\ n)\ (UNIV\ ::\ 'a\ set)) \leq card\ (UNIV\ ::\ 'a\ set)\ -\ Suc\ n
using a
      by simp
    qed
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qed
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\mathbf{lemma}\ \mathit{card}\text{-}\mathit{UNIV}\text{-}\mathit{tau}\text{-}\mathit{i}\text{-}\mathit{below}\text{-}\mathit{zero}\text{:}
 assumes finite (UNIV :: 'a set) and monotone (\tau :: 'a set \Rightarrow 'a set)
  and (\forall i :: nat. ((\tau :: 'a \ set \Rightarrow 'a \ set) \hat{\ } i + (1 :: nat)) (UNIV :: 'a \ set) \subset (\tau)
^ i) UNIV)
 shows card((\tau \ \hat{} \ (card\ (UNIV\ ::'a\ set)))\ (UNIV\ ::'a\ set)) \leq 0
proof -
  have (\forall i :: nat. card((\tau \hat{i}) (UNIV :: 'a set)) \leq (card (UNIV :: 'a set)) - i)
using assms
    by (rule card-univ-subtract)
  thus card((\tau \ \hat{} \ (card\ (UNIV\ ::'a\ set)))\ (UNIV\ ::'a\ set)) \leq 0
  apply (drule\text{-}tac\ x = card\ (UNIV\ ::'a\ set)\ \mathbf{in}\ spec)
    \mathbf{by} \ simp
qed
lemma finite-card-zero-empty: \llbracket finite S; card S \leq 0 \rrbracket \Longrightarrow S = \{\}
by simp
lemma UNIV-tau-i-is-empty:
  assumes finite (UNIV :: 'a set) and monotone (\tau :: 'a set \Rightarrow 'a set)
    and (\forall i :: nat. ((\tau :: 'a \ set \Rightarrow 'a \ set) \hat{i} + (1 :: nat)) (UNIV :: 'a \ set) \subset
(\tau \hat{i}) UNIV
  shows (\tau \ \hat{} \ (card \ (UNIV ::'a \ set))) \ (UNIV ::'a \ set) = \{\}
proof -
  have card ((\tau \ \hat{\ } card \ (UNIV ::'a \ set)) \ UNIV) \leq (\theta::nat) using assms
    apply (rule card-UNIV-tau-i-below-zero)
  thus (\tau \ \hat{} (card (UNIV :: 'a set))) (UNIV :: 'a set) = \{\} using assms
  apply (rule-tac\ S = (\tau \ \hat{\ } (card\ (UNIV::'a\ set)))\ (UNIV::'a\ set) in finite-card-zero-empty)
    apply (rule finite-subset)
    apply (rule subset-UNIV)
qed
lemma down-chain-reaches-empty:
  assumes finite (UNIV :: 'a set) and monotone (\tau :: 'a set \Rightarrow 'a set)
  and (\forall i :: nat. ((\tau :: 'a \ set \Rightarrow 'a \ set) \hat{i} + (1 :: nat)) \ UNIV \subset (\tau \hat{i}) \ UNIV)
 shows \exists (j :: nat). (\tau \hat{j}) UNIV = \{\}
proof -
  have (\tau \ \hat{} \ ((card\ (UNIV\ ::\ 'a\ set))))\ UNIV = \{\}\ using\ assms
    apply (rule UNIV-tau-i-is-empty)
  thus \exists (j :: nat). (\tau \hat{j}) UNIV = \{\}
    by (rule \ exI)
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lemma no-infinite-subset-chain2:

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assumes finite (UNIV :: 'a set) and monotone (\tau :: ('a \ set \Rightarrow 'a \ set))
      and \forall i :: nat. (\tau \hat{i}) \ UNIV \supset (\tau \hat{i} + (1 :: nat)) \ UNIV
  shows False
proof -
  have \exists j :: nat. (\tau \hat{j}) \ UNIV = \{\}  using assms
    apply (rule down-chain-reaches-empty)
  from this obtain j where a: (\tau \hat{j}) UNIV = {} by (erule exE)
  have (\tau \hat{j} + (1::nat)) UNIV \subset (\tau \hat{j}) UNIV using assms
    by (erule-tac \ x = j \ in \ spec)
  thus False using a by simp
qed
lemma finite-fixp2:
  assumes finite(UNIV :: 'a set) and monotone (\tau :: ('a \ set \Rightarrow 'a \ set))
 shows \exists i. (\tau \hat{i}) UNIV = (\tau \hat{i} + 1) UNIV
proof -
  have \forall i::nat. (\tau \hat{i} + (1::nat)) UNIV \subseteq (\tau \hat{i}) UNIV
    apply (rule predtrans-UNIV) using assms
    by (simp \ add: \ assms(2))
  moreover have \exists i::nat. \neg (\tau \hat{i} + (1::nat)) \ UNIV \subset (\tau \hat{i}) \ UNIV using
assms
  proof -
    have \neg (\forall i :: nat. (\tau \hat{i}) UNIV \supset (\tau \hat{i} + 1)) UNIV)
      apply (rule notI)
      apply (rule no-infinite-subset-chain2) using assms
    thus \exists i::nat. \neg (\tau \hat{i} + (1::nat)) \ UNIV \subset (\tau \hat{i}) \ UNIV  by blast
  ultimately show \exists i. (\tau \hat{i}) UNIV = (\tau \hat{i} + 1) UNIV
    by blast
qed
lemma mono-monotone: mono (\tau :: ('a \ set \Rightarrow 'a \ set)) \Longrightarrow monotone \ \tau
by (simp add: monotone-def mono-def)
lemma monotone-mono: monotone (\tau :: ('a \ set \Rightarrow 'a \ set)) \Longrightarrow mono \ \tau
by (simp add: monotone-def mono-def)
lemma power-power: ((\tau :: ('a \ set \Rightarrow 'a \ set)) \ \hat{} \ n) = ((\tau :: ('a \ set \Rightarrow 'a \ set)) \ \hat{} \ 
n)
proof (induct\text{-}tac \ n)
 show \tau ^^ (\theta::nat) = (\tau ^ \theta::nat) by (simp add: id-def)
next show \bigwedge n :: nat. \ \tau \ \hat{} \ n = (\tau \ \hat{} \ n) \Longrightarrow \tau \ \hat{} \ Suc \ n = (\tau \ \hat{} \ Suc \ n)
    \mathbf{by} \ simp
qed
lemma lfp-Kleene-iter-set: monotone (f :: ('a \ set \Rightarrow 'a \ set)) \Longrightarrow
   (f \hat{\ } Suc(n)) \{\} = (f \hat{\ } n) \{\} \Longrightarrow lfp f = (f \hat{\ } n) \{\}
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by (simp add: monotone-mono lfp-Kleene-iter power-power)
lemma lfp-loop:
 assumes finite (UNIV :: 'b set) and monotone (\tau :: ('b set \Rightarrow 'b set))
 shows \exists n . lfp \tau = (\tau \hat{n}) \{ \}
proof -
 have \exists i::nat. (\tau \hat{i}) \{\} = (\tau \hat{i} + (1::nat)) \{\} using assms
   by (rule finite-fixp)
 from this obtain i where (\tau \hat{i}) \{\} = (\tau \hat{i} + (1::nat)) \{\}
   by (erule \ exE)
 hence (\tau \hat{i}) \{\} = (\tau \hat{suc} i) \{\}
   by simp
 hence (\tau \hat{\ } Suc\ i) \ \{\} = (\tau \hat{\ } i) \ \{\}
   by (rule sym)
 hence lfp \ \tau = (\tau \hat{\ }i) \ \{\}
    by (simp add: assms(2) lfp-Kleene-iter-set)
  thus \exists n . lfp \tau = (\tau \hat{n}) \{ \}
  by (rule \ exI)
qed
lemma Kleene-iter-gpfp:
assumes mono f and p \le f p shows p \le (f^{\hat{k}}) (top::'a::order-top)
proof(induction k)
 case \theta show ?case by simp
\mathbf{next}
 from monoD[OF\ assms(1)\ Suc]\ assms(2)
 show ?case by simp
qed
lemma gfp-Kleene-iter: assumes mono f and (f^{\hat{j}}Suc\ k) top = (f^{\hat{j}}k) top
shows gfp f = (f^{\hat{k}}) top
proof(rule antisym)
 show (f^{\hat{}} k) top \leq gfp f
 proof(rule qfp-upperbound)
   show (f^{\hat{}}k) top \leq f ((f^{\hat{}}k) top) using assms(2) by simp
 qed
\mathbf{next}
 show gfp f \leq (f^{\hat{}} k) top
   using Kleene-iter-gpfp[OF\ assms(1)]\ gfp-unfold[OF\ assms(1)] by simp
qed
lemma gfp-Kleene-iter-set:
 assumes monotone (f :: ('a \ set \Rightarrow 'a \ set))
     and (f \hat{\ } Suc(n)) \ UNIV = (f \hat{\ } n) \ UNIV
   shows gfp f = (f \hat{n}) UNIV
proof -
 have a: mono f using assms
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by (erule-tac \tau = f in monotone-mono)
  hence b: (f \hat{\ } Suc \ (n)) \ UNIV = (f \hat{\ } n) \ UNIV  using assms
   by (simp add: power-power)
  hence c: gfp\ f = (f \hat{\ } (n))(UNIV :: 'a\ set) using assms a
   thm qfp-Kleene-iter
   apply (erule-tac f = f and k = n in gfp-Kleene-iter)
  thus gfp f = (f \hat{\ } (n))(\mathit{UNIV} :: 'a \ set) using assms \ a
   by (simp add: power-power)
\mathbf{qed}
lemma gfp-loop:
  assumes finite (UNIV :: 'b set)
  and monotone (\tau :: ('b \ set \Rightarrow 'b \ set))
   shows \exists n . gfp \ \tau = (\tau \hat{n})(UNIV :: 'b set)
proof -
  have \exists i::nat. (\tau \hat{i})(UNIV :: b set) = (\tau \hat{i} + (1::nat)) UNIV using assms
   by (rule finite-fixp2)
  from this obtain i where (\tau \hat{i})(UNIV :: 'b \ set) = (\tau \hat{i} + (1::nat)) \ UNIV
by (erule \ exE)
  thus \exists n : gfp \ \tau = (\tau \hat{n})(UNIV :: 'b \ set) using assms
   apply (rule-tac \ x = i \ in \ exI)
   apply (rule gfp-Kleene-iter-set)
   apply assumption
   apply (rule sym)
   by simp
qed
class state =
 fixes state-transition :: ['a :: type, 'a] \Rightarrow bool ((-\rightarrow_i -) 50)
definition AX where AX f \equiv \{s. \{f0. s \rightarrow_i f0\} \subseteq f\}
definition EX' where EX' f \equiv \{s : \exists f0 \in f. s \rightarrow_i f0 \}
definition AF where AF f \equiv lfp \ (\lambda \ Z. \ f \cup AX \ Z)
definition EF where EF f \equiv lfp \ (\lambda \ Z. \ f \cup EX' \ Z)
definition AG where AG f \equiv gfp \ (\lambda \ Z. \ f \cap AX \ Z)
definition EG where EG f \equiv gfp \ (\lambda \ Z. \ f \cap EX' \ Z)
definition AU where AU f1 f2 \equiv lfp(\lambda Z. f2 \cup (f1 \cap AX Z))
definition EU where EU f1 f2 \equiv lfp(\lambda Z. f2 \cup (f1 \cap EX'Z))
definition AR where AR f1 f2 \equiv gfp(\lambda Z. f2 \cap (f1 \cup AX Z))
definition ER where ER f1 f2 \equiv gfp(\lambda Z. f2 \cap (f1 \cup EX'Z))
datatype 'a kripke =
  Kripke 'a set 'a set
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primrec states where states (Kripke \ S \ I) = S
primrec init where init (Kripke \ S \ I) = I
definition check (-\vdash -50)
where M \vdash f \equiv (init \ M) \subseteq \{s \in (states \ M), s \in f \}
definition state-transition-refl ((-\rightarrow_i * -) 50)
where s \to_i * s' \equiv ((s,s') \in \{(x,y). state-transition \ x \ y\}^*)
lemma EF-lem0: (x \in EF f) = (x \in f \cup EX' (lfp (\lambda Z :: ('a :: state) set. f \cup EY'))
EX'Z)))
proof -
 have lfp (\lambda Z :: ('a :: state) set. f \cup EX' Z) =
                  f \cup (EX'(lfp(\lambda Z :: 'a set. f \cup EX'Z)))
   apply (rule def-lfp-unfold)
   apply (rule reflexive)
   apply (unfold mono-def EX'-def)
   by auto
  thus (x \in EF \ (f :: ('a :: state) \ set)) = (x \in f \cup EX' \ (lfp \ (\lambda Z :: ('a :: state) \ set)))
set. f \cup EX'(Z))
   by (simp \ add: EF-def)
qed
lemma EF-lem00: (EF f) = (f \cup EX' (lfp (\lambda Z :: ('a :: state) set. f \cup EX' Z)))
proof (rule equalityI)
 show EF f \subseteq f \cup EX' (lfp (\lambda Z :: 'a set. f \cup EX' Z))
  apply (rule subsetI)
  by (simp \ add: EF-lem\theta)
 next show f \cup EX' (lfp (\lambda Z :: 'a \ set. \ f \cup EX' \ Z)) \subseteq EF \ f
  apply (rule \ subset I)
  by (simp \ add: EF-lem \theta)
qed
lemma EF-lem000: (EF f) = (f \cup EX'(EF f))
proof (subst EF-lem00)
 show f \cup EX' (lfp(\lambda Z::'a set. f \cup EX' Z)) = f \cup EX' (EF f)
   apply (fold EF-def)
   by (rule refl)
qed
lemma EF-lem1: x \in f \lor x \in (EX'(EFf)) \Longrightarrow x \in EFf
proof (simp add: EF-def)
 assume a: x \in f \lor x \in EX' (lfp (\lambda Z::'a set. f \cup EX' Z))
 show x \in lfp (\lambda Z :: 'a \ set. \ f \cup EX' Z)
 proof -
   have b: lfp (\lambda Z :: ('a :: state) set. f \cup EX' Z) =
                  f \cup (EX'(lfp(\lambda Z :: ('a :: state) set. f \cup EX'Z)))
     apply (rule def-lfp-unfold)
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apply (rule reflexive)
     \mathbf{apply} \ (\mathit{unfold} \ \mathit{mono-def} \ \mathit{EX'-def})
     by auto
   thus x \in lfp \ (\lambda Z :: 'a \ set. \ f \cup EX' \ Z) using a
    apply (subst\ b)
    by blast
\mathbf{qed}
qed
lemma EF-lem2b:
   assumes x \in (EX'(EFf))
  shows x \in EF f
proof (rule EF-lem1)
 show x \in f \lor x \in EX'(EFf)
   apply (rule disjI2)
   by (rule assms)
qed
lemma EF-lem2a: assumes x \in f shows x \in EF f
proof (rule EF-lem1)
 show x \in f \lor x \in EX'(EFf)
   apply (rule disjI1)
   by (rule assms)
qed
lemma EF-lem2c: assumes x \notin f shows x \in EF(-f)
proof -
 have x \in (-f) using assms
   by simp
 thus x \in EF(-f)
   by (rule\ EF-lem2a)
lemma EF-lem2d: assumes x \notin EF f shows x \notin f
proof -
 have x \in f \Longrightarrow x \in EFf
   by (erule EF-lem2a)
 thus x \notin f using assms
   thm contrapos-nn
   apply (erule-tac P = x \in f in contrapos-nn)
   apply (erule meta-mp)
qed
lemma EF-lem3b: assumes x \in EX'(f \cup EX'(EFf)) shows x \in (EFf)
proof (simp \ add: EF-lem \theta)
 show x \in f \lor x \in EX' (lfp (\lambda Z :: 'a set. f \cup EX' Z))
  apply (rule disjI2)
  apply (fold EF-def)
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apply (subst\ EF-lem00)
  apply (fold EF-def)
  by (rule assms)
qed
lemma EX-lem0l: x \in (EX'f) \Longrightarrow x \in (EX'(f \cup g))
proof (unfold EX'-def)
 show x \in \{s::'a. \exists f0::'a \in f. \ s \rightarrow_i f0\} \Longrightarrow x \in \{s::'a. \exists f0::'a \in f \cup g. \ s \rightarrow_i f0\}
    by blast
\mathbf{qed}
lemma EX-lem\theta r: x \in (EX'g) \Longrightarrow x \in (EX'(f \cup g))
proof (unfold EX'-def)
 show x \in \{s::'a. \exists f0::'a \in g. s \rightarrow_i f0\} \Longrightarrow x \in \{s::'a. \exists f0::'a \in f \cup g. s \rightarrow_i f0\}
   by blast
qed
lemma EX-step: assumes x \rightarrow_i y and y \in f shows x \in EX'f
proof (unfold EX'-def)
 show x \in \{s::'a. \exists f\theta::'a \in f. s \rightarrow_i f\theta \}
    apply simp
    apply (rule-tac \ x = y \ in \ bexI)
    by (rule\ assms)+
qed
lemma EF-E[rule-format]: \forall f. x \in (EF (f :: ('a :: state) set)) \longrightarrow x \in (f \cup EX')
(EFf)
proof -
 have a: \bigwedge f::'a \ set. \ EF \ (f:: ('a:: state) \ set) = f \cup EX' \ (EF \ f)
   by (rule\ EF-lem000)
  thus (\forall f. \ x \in EF \ (f :: ('a :: state) \ set) \longrightarrow x \in f \cup EX' \ (EF \ f))
   apply (rule-tac P = (\lambda f. x \in EF (f :: ('a :: state) set) \longrightarrow x \in f \cup EX' (EF)
f)) in allI)
    apply (subst\ a)
    apply (rule\ impI)
    by assumption
qed
lemma EF-step: assumes x \rightarrow_i y and y \in f shows x \in EF f
proof (rule EF-lem3b)
 show x \in EX' (f \cup EX' (EF f))
    apply (rule EX-step)
    apply (rule\ assms(1))
    by (simp \ add: \ assms(2))
qed
lemma EF-step-step: assumes x \rightarrow_i y and y \in EF f shows x \in EF f
proof -
 have y \in f \cup EX'(EFf)
```

```
apply (rule\ EF-E)
    by (rule\ assms(2))
  thus x \in EF f
    apply (rule-tac x = x and f = f in EF-lem3b)
    apply (rule EX-step)
    by (rule assms)
\mathbf{qed}
lemma EF-step-star: [x \rightarrow_i * y; y \in f] \implies x \in EF f
proof (simp add: state-transition-refl-def)
  show (x, y) \in \{(x::'a, y::'a). x \rightarrow_i y\}^* \Longrightarrow y \in f \Longrightarrow x \in EF f
  proof (erule converse-rtrancl-induct)
    show y \in f \Longrightarrow y \in EF f
      by (erule EF-lem2a)
    next show \bigwedge(ya::'a) z::'a. y \in f \Longrightarrow
                  (ya, z) \in \{(x::'a, y::'a). x \rightarrow_i y\} \Longrightarrow
                  (z, y) \in \{(x: 'a, y: 'a). \ x \rightarrow_i y\}^* \Longrightarrow z \in EFf \Longrightarrow ya \in EFf
        \mathbf{apply} \ (\mathit{clarify})
        apply (erule EF-step-step)
        by assumption
    qed
  qed
lemma EF-induct-prep:
  assumes (a::'a::state) \in lfp \ (\lambda \ Z. \ (f::'a::state \ set) \cup EX' \ Z)
       and mono (\lambda Z. (f::'a::state\ set) \cup EX'Z)
     shows (\bigwedge x::'a::state.
     x \in ((\lambda Z. (f::'a::state\ set) \cup EX'Z)(lfp\ (\lambda Z. (f::'a::state\ set) \cup EX'Z) \cap
\{x::'a::state.\ (P::'a::state \Rightarrow bool)\ x\})) \Longrightarrow P\ x) \Longrightarrow
      P a
proof -
  show (\bigwedge x::'a::state.
     x \in ((\lambda Z. (f::'a::state\ set) \cup EX'\ Z)(lfp\ (\lambda\ Z.\ (f::'a::state\ set) \cup EX'\ Z)\cap
\{x::'a::state.\ (P::'a::state \Rightarrow bool)\ x\})) \Longrightarrow P\ x) \Longrightarrow
      P a
    apply (rule-tac A = EF f in def-lfp-induct-set)
    apply (rule EF-def)
    apply (rule\ assms(2))
    by (simp add: EF-def assms)+
qed
lemma EF-induct: (a::'a::state) \in EF \ (f::'a::state\ set) \Longrightarrow
    mono~(\lambda~Z.~(f::'a::state~set) \cup EX'~Z) \Longrightarrow
    (\bigwedge x::'a::state.
        x \in ((\lambda Z. (f::'a::state\ set) \cup EX'\ Z)(EF\ f \cap \{x::'a::state.\ (P::'a::state\ \Rightarrow
bool) \ x\})) \Longrightarrow P \ x) \Longrightarrow
proof (simp add: EF-def)
  show a \in lfp \ (\lambda Z :: 'a \ set. \ f \cup EX' \ Z) \Longrightarrow
```

```
mono\ (\lambda Z ::' a\ set.\ f \cup EX'\ Z) \Longrightarrow
    (\bigwedge x ::'a. \ x \in f \lor x \in EX' \ (\mathit{lfp} \ (\lambda Z ::'a \ set. \ f \cup EX' \ Z) \cap \mathit{Collect} \ P) \Longrightarrow P \ x)
\implies P \ a
    apply (erule EF-induct-prep)
    apply assumption
  by simp
\mathbf{qed}
lemma valEF-E: M \vdash EF f \Longrightarrow x \in init M \Longrightarrow x \in EF f
proof (simp add: check-def)
  show init M \subseteq \{s::'a \in states\ M.\ s \in EF\ f\} \Longrightarrow x \in init\ M \Longrightarrow x \in EF\ f
  apply (drule subsetD)
  apply assumption
    by simp
qed
lemma EF-step-star-rev[rule-format]: x \in EF \ s \Longrightarrow (\exists y \in s. \ x \rightarrow_i * y)
proof (erule EF-induct)
  show mono (\lambda Z::'a \ set. \ s \cup EX' \ Z)
    apply (simp add: mono-def EX'-def)
next show \bigwedge x::'a. \ x \in s \cup EX'(EFs \cap \{x::'a. \ \exists \ y::'a \in s. \ x \rightarrow_i * y\}) \Longrightarrow \exists \ y::'a \in s.
x \to_i * y
apply (erule UnE)
   apply (rule-tac \ x = x \ in \ bexI)
    apply (simp add: state-transition-refl-def)
   apply assumption
  apply (simp\ add:\ EX'-def)
  apply (erule bexE)
  apply (erule IntE)
  apply (drule CollectD)
  apply (erule bexE)
  apply (rule-tac \ x = xb \ in \ bexI)
  apply (simp add: state-transition-refl-def)
   apply (rule rtrancl-trans)
    apply (rule r-into-rtrancl)
    apply (rule CollectI)
    apply simp
  by assumption+
qed
lemma EF-step-inv: (I \subseteq \{sa::'s :: state. (\exists i::'s \in I. i \rightarrow_i * sa) \land sa \in EF s\})
         \implies \forall x \in I. \exists y \in s. x \rightarrow_i * y
proof (clarify)
  show \bigwedge x::'s. I \subseteq \{sa::'s : (\exists i::'s \in I : i \rightarrow_i * sa) \land sa \in EF s\} \Longrightarrow x \in I \Longrightarrow
\exists y :: 's \in s. \ x \rightarrow_i * y
    apply (drule subsetD)
    apply assumption
    apply (drule CollectD)
```

```
apply (erule conjE)
   by (erule EF-step-star-rev)
\mathbf{qed}
lemma AG-in-lem: x \in AG \ s \Longrightarrow x \in s
proof (simp add: AG-def gfp-def)
 show \exists xa \subseteq s. \ xa \subseteq AX \ xa \land x \in xa \Longrightarrow x \in s
   apply (erule exE)
   apply (erule\ conjE)+
   by (erule subsetD, assumption)
qed
lemma AG-lem1: x \in s \land x \in (AX (AG s)) \Longrightarrow x \in AG s
proof (simp add: AG-def)
 show x \in s \land x \in AX \ (gfp \ (\lambda Z :: 'a \ set. \ s \cap AX \ Z)) \Longrightarrow x \in gfp \ (\lambda Z :: 'a \ set. \ s
\cap AXZ
 apply (subgoal-tac gfp (\lambda Z::'a set. s \cap AX Z) =
                     s \cap (AX (gfp (\lambda Z :: 'a set. s \cap AX Z))))
 apply (erule ssubst)
 apply simp
 apply (rule def-gfp-unfold)
 apply (rule reflexive)
 apply (unfold mono-def AX-def)
 by auto
qed
lemma AG-lem2: x \in AG \ s \Longrightarrow x \in (s \cap (AX \ (AG \ s)))
proof -
 have a: AG s = s \cap (AX (AG s))
   apply (simp \ add: AG-def)
   apply (rule def-gfp-unfold)
   apply (rule reflexive)
   apply (unfold mono-def AX-def)
   by auto
  thus x \in AG \ s \Longrightarrow x \in (s \cap (AX \ (AG \ s)))
  by (erule subst)
qed
lemma AG-lem3: AG s = (s \cap (AX (AG s)))
proof (rule equalityI)
 show AG s \subseteq s \cap AX (AG s)
   \mathbf{apply}\ (\mathit{rule}\ \mathit{subset}I)
   by (erule AG-lem2)
  next show s \cap AX (AG s) \subseteq AG s
   apply (rule subsetI)
   apply (rule AG-lem1)
   \mathbf{by} \ simp
```

```
qed
lemma AG-step: y \rightarrow_i z \Longrightarrow y \in AG \ s \Longrightarrow z \in AG \ s
proof (drule AG-lem2)
  show y \rightarrow_i z \Longrightarrow y \in s \cap AX \ (AG \ s) \Longrightarrow z \in AG \ s
    apply (erule IntE)
    apply (unfold\ AX-def)
    apply simp
    apply (erule subsetD)
    by simp
qed
lemma AG-all-s: x \rightarrow_i * y \Longrightarrow x \in AG s \Longrightarrow y \in AG s
proof (simp add: state-transition-refl-def)
  show (x, y) \in \{(x::'a, y::'a). x \rightarrow_i y\}^* \Longrightarrow x \in AG s \Longrightarrow y \in AG s
    apply (erule rtrancl-induct)
  proof -
    show x \in AG s \implies x \in AG s by assumption
  next show \bigwedge(y::'a) z::'a.
       x \in AG s \Longrightarrow
       (x, y) \in \{(x::'a, y::'a). x \rightarrow_i y\}^* \Longrightarrow
       (y, z) \in \{(x::'a, y::'a). \ x \to_i y\} \Longrightarrow y \in AG \ s \Longrightarrow z \in AG \ s
       apply clarify
       by (erule\ AG\text{-}step,\ assumption)
  \mathbf{qed}
qed
lemma AG-imp-notnotEF:
I \neq \{\} \Longrightarrow ((Kripke \{s :: ('s :: state). \exists i \in I. (i \rightarrow_i * s)\} (I :: ('s :: state)set)\}
\vdash AG(s)) \Longrightarrow
(\neg(Kripke \ \{s :: ('s :: state). \ \exists \ i \in I. \ (i \rightarrow_i * s)\} \ (I :: ('s :: state)set) \vdash EF \ (-s)
s)))
proof (rule notI, simp add: check-def)
  assume a\theta: I \neq \{\} and
    a1: I \subseteq \{sa::'s. (\exists i::'s \in I. i \rightarrow_i * sa) \land sa \in AG s\} and
    a2: I \subseteq \{sa::'s. (\exists i::'s \in I. i \rightarrow_i * sa) \land sa \in EF (-s)\}
  show False
  proof -
    have a3: \{sa::'s. (\exists i::'s \in I. i \rightarrow_i * sa) \land sa \in AG s\} \cap
                           \{sa::'s. (\exists i::'s \in I. i \to_i * sa) \land sa \in EF (-s)\} = \{\}
      proof -
         have (? x. x \in \{sa::'s. (\exists i::'s \in I. i \rightarrow_i * sa) \land sa \in AG s\} \land
                                 x \in \{sa::'s. (\exists i::'s \in I. i \rightarrow_i * sa) \land sa \in EF (-s)\}) \Longrightarrow
```

assume $a4: (? x. x \in \{sa::'s. (\exists i::'s \in I. i \rightarrow_i * sa) \land sa \in AG s\} \land$

 $x \in \{sa::'s. \ (\exists i::'s \in I. \ i \rightarrow_i * sa) \land sa \in EF \ (-s)\})$ from a4 obtain x where $a5: x \in \{sa::'s. \ (\exists i::'s \in I. \ i \rightarrow_i * sa) \land sa \in Sa)$

False

AG s \land

proof -

```
x \in \{sa::'s. (\exists i::'s \in I. i \rightarrow_i * sa) \land sa \in EF (-s)\}
       by (erule exE)
       hence x \in s \land x \in -s
       proof -
        have a6: x \in s using a5
          apply (subgoal-tac x \in AG s)
          apply (erule AG-in-lem)
          by simp
        moreover have x \in -s using a5
        proof -
          have x \in EF s
            apply (rule-tac\ y = x\ in\ EF-step-star)
            apply (simp add: state-transition-refl-def)
            by (rule a6)
          thus x \in -s using a5
          proof -
            have x \in EF(-s) using a5
              by simp
            moreover from this obtain y where a7: y \in -s \land x \rightarrow_i * y
              apply (rotate-tac-1)
               \mathbf{apply}\ (\mathit{drule}\ \mathit{EF-step-star-rev})
              by blast
            moreover have y \in AG s using a 7 a 5
              apply (subgoal-tac x \in AG s)
              apply (erule \ conjE)
               apply (drule\ AG-all-s)
                apply assumption+
              by simp
            ultimately show x \in -s using a5
               apply (rotate-tac -1)
               apply (drule\ AG-in-lem)
               by blast
          \mathbf{qed}
        qed
        ultimately show x \in s \land x \in -s
          by (rule \ conjI)
       \mathbf{qed}
       thus False
        by blast
   thus \{sa::'s. (\exists i::'s \in I. i \rightarrow_i * sa) \land sa \in AG s\} \cap
                  \{sa::'s. (\exists i::'s \in I. i \rightarrow_i * sa) \land sa \in EF (-s)\} = \{\}
   by blast
 qed
moreover have b: ? x. x: I using a\theta
 by blast
moreover obtain x where x \in I
   apply (rule exE)
    apply (rule\ b)
```

```
by simp
    ultimately show False using a0 a1 a2
     \mathbf{by} blast
 qed
qed
lemma check2-def: (Kripke\ S\ I \vdash f) = (I \subseteq S \cap f)
proof (simp add: check-def)
 show (I \subseteq \{s:: 'a \in S. \ s \in f\}) = (I \subseteq S \land I \subseteq f) by blast
qed
end
theory AirInsider
imports MC
begin
datatype action = get \mid move \mid eval \mid put
typedecl actor
consts Actor :: string \Rightarrow actor
type-synonym identity = string
type-synonym policy = ((actor \Rightarrow bool) * action set)
definition ID :: [actor, string] \Rightarrow bool
where ID \ a \ s \equiv (a = Actor \ s)
datatype location = Location nat
datatype igraph = Lgraph (location * location) set location \Rightarrow identity list
                         actor \Rightarrow (string \ list * string \ list) \ location \Rightarrow string \ list
{\bf datatype} \ {\it infrastructure} =
         Infrastructure\ igraph
                        [igraph, location] \Rightarrow policy set
primrec loc :: location \Rightarrow nat
where loc(Location n) = n
primrec gra :: igraph \Rightarrow (location * location) set
where gra(Lgraph \ g \ a \ c \ l) = g
primrec agra :: igraph \Rightarrow (location \Rightarrow identity \ list)
where agra(Lgraph \ g \ a \ c \ l) = a
primrec cgra :: igraph \Rightarrow (actor \Rightarrow string \ list * string \ list)
where cgra(Lgraph \ g \ a \ c \ l) = c
primrec lgra :: igraph \Rightarrow (location \Rightarrow string \ list)
where lgra(Lgraph \ g \ a \ c \ l) = l
\textbf{definition} \ \textit{nodes} :: \textit{igraph} \ \Rightarrow \textit{location} \ \textit{set}
where nodes g == \{ x. (? y. ((x,y): gra g) | ((y,x): gra g)) \}
```

```
definition actors-graph :: igraph <math>\Rightarrow identity \ set
\mathbf{where} \ \mathit{actors-graph} \ g == \{x. \ ? \ y. \ y: \mathit{nodes} \ g \ \land \ x \in \mathit{set}(\mathit{agra} \ g \ y)\}
\mathbf{primrec}\ graphI::infrastructure \Rightarrow igraph
where graph I (Infrastructure g(d) = g
\mathbf{primrec}\ \mathit{delta} :: [\mathit{infrastructure},\ \mathit{igraph},\ \mathit{location}] \Rightarrow \mathit{policy}\ \mathit{set}
where delta (Infrastructure g(d) = d
primrec tspace :: [infrastructure, actor] \Rightarrow string list * string list
  where tspace\ (Infrastructure\ g\ d) = cgra\ g
primrec lspace :: [infrastructure, location] \Rightarrow string list
where lspace (Infrastructure\ g\ d) = lgra\ g
definition credentials :: string list * string list \Rightarrow string set
  where credentials lxl \equiv set (fst lxl)
definition has :: [iqraph, actor * string] \Rightarrow bool
  where has G ac \equiv snd ac \in credentials(cgra G (fst ac))
definition roles :: string list * string list <math>\Rightarrow string set
  where roles \ lxl \equiv set \ (snd \ lxl)
definition role :: [igraph, actor * string] \Rightarrow bool
  where role G ac \equiv snd ac \in roles(cgra G (fst ac))
definition isin :: [igraph, location, string] \Rightarrow bool
  where isin G l s \equiv s \in set(lgra G l)
datatype psy-states = happy \mid depressed \mid disgruntled \mid angry \mid stressed
\mathbf{datatype} \ motivations = financial \mid political \mid revenge \mid curious \mid competitive-advantage
| power | peer-recognition
datatype \ actor-state = Actor-state \ psy-states \ motivations \ set
primrec motivation :: actor-state \Rightarrow motivations set
where motivation (Actor-state \ p \ m) = m
primrec psy-state :: actor-state \Rightarrow psy-states
where psy-state (Actor-state \ p \ m) = p
definition tipping-point :: actor-state <math>\Rightarrow bool where
  tipping-point\ a \equiv ((motivation\ a \neq \{\}) \land (happy \neq psy-state\ a))
consts Isolation :: [actor-state, (identity * identity) set ] \Rightarrow bool
definition lay-off :: [infrastructure, actor set] \Rightarrow infrastructure
where lay-off G A \equiv G
```

```
consts social-graph :: (identity * identity) set
```

```
definition UasI :: [identity, identity] \Rightarrow bool
where UasI\ a\ b \equiv (Actor\ a = Actor\ b) \land (\forall\ x\ y.\ x \neq a \land y \neq a \land Actor\ x =
Actor \ y \longrightarrow x = y)
definition UasI' :: [actor => bool, identity, identity] \Rightarrow bool
where UasI' P \ a \ b \equiv P \ (Actor \ b) \longrightarrow P \ (Actor \ a)
definition Insider :: [identity, identity set, identity \Rightarrow actor-state] \Rightarrow bool
where Insider a C as \equiv (tipping-point (as a) \longrightarrow (\forall b \in C. UasI a b))
definition Insider' :: [actor \Rightarrow bool, identity, identity set, identity <math>\Rightarrow actor-state]
where Insider' P a C as \equiv (tipping-point (as a) \longrightarrow (\forall b \in C. UasI' P a b \land
inj-on Actor (C)
definition at I :: [identity, igraph, location] \Rightarrow bool (- <math>@_{(-)} - 50)
where a @_G l \equiv a \in set(agra\ G\ l)
definition enables :: [infrastructure, location, actor, action] \Rightarrow bool
where
enables I \ l \ a \ a' \equiv (\exists \ (p,e) \in delta \ I \ (graph I \ I) \ l. \ a' \in e \land p \ a)
definition behaviour :: infrastructure \Rightarrow (location * actor * action) set
where behaviour I \equiv \{(t,a,a'). \text{ enables } I \text{ t } a \text{ a'}\}
definition misbehaviour :: infrastructure <math>\Rightarrow (location * actor * action)set
  where misbehaviour I \equiv -(behaviour I)
lemma not-enableI: (\forall (p,e) \in delta\ I\ (graphI\ I)\ l.\ (^{\sim}(h:e) \mid (^{\sim}(p(a)))))
                      \implies \sim (enables I l a h)
  by (simp add: enables-def, blast)
lemma not-enable I2: [\![ \bigwedge p \ e. \ (p,e) \in delta \ I \ (graph I \ I) \ l \Longrightarrow
```

```
(^{\sim}(t:e) \mid (^{\sim}(p(a)))) \rrbracket \Longrightarrow ^{\sim}(enables\ I\ l\ a\ t)
 by (rule not-enableI, rule ballI, auto)
lemma not-enable E: [ (enables \ I \ l \ a \ t); (p,e) \in delta \ I \ (graph I \ I) \ l ] ]
                 \implies (^{\sim}(t:e) \mid (^{\sim}(p(a))))
 by (simp add: enables-def, rule impI, force)
lemma not-enable
E2: [ ^{\sim} (enables I l a t); (p,e) \in delta I (graph
I I) l;
                     t:e \ ] \Longrightarrow (^{\sim}(p(a)))
 by (simp add: enables-def, force)
primrec del :: ['a, 'a \ list] \Rightarrow 'a \ list
where
del-nil: del \ a \ [] = [] \ |
del-cons: del a (x\#ls) = (if x = a then ls else x \# (del a ls))
primrec jonce :: ['a, 'a \ list] \Rightarrow bool
where
jonce-nil: jonce \ a \ [] = False \ ]
jonce-cons: jonce a(x\#ls) = (if x = a then (a \notin (set ls)) else jonce a ls)
primrec nodup :: ['a, 'a \ list] \Rightarrow bool
  where
    nodup-nil: nodup \ a \ [] = True \ []
    nodup-step: nodup a (x \# ls) = (if x = a then (a \notin (set ls)) else nodup a ls)
definition move-graph-a :: [identity, location, location, igraph] \Rightarrow igraph
where move-graph-a n l l' g \equiv Lgraph (gra g)
                    (if n \in set ((agra g) l) & n \notin set ((agra g) l') then
                     ((agra\ g)(l:=del\ n\ (agra\ g\ l)))(l':=(n\ \#\ (agra\ g\ l')))
                     else (agra g)(cgra g)(lgra g)
inductive state-transition-in :: [infrastructure, infrastructure] \Rightarrow bool ((-\rightarrow_n-)
50)
where
  move: \llbracket G = graphI \ I; \ a @_G \ l; \ l \in nodes \ G; \ l' \in nodes \ G;
          (a) \in actors-graph(graphI\ I);\ enables\ I\ l'\ (Actor\ a)\ move;
        I' = \textit{Infrastructure} \ (\textit{move-graph-a a l l' (graphI\ I)}) (\textit{delta\ I})\ \rrbracket \Longrightarrow I \to_n I'
\mid get : \llbracket G = graphI \ I; \ a @_{G} \ l; \ a' @_{G} \ l; \ has \ G \ (Actor \ a, \ z);
        enables I l (Actor a) get;
        I' = Infrastructure
                   (Lgraph (gra G)(agra G))
                           ((cgra\ G)(Actor\ a':=
                               (z \# (fst(cgra G (Actor a'))), snd(cgra G (Actor a')))))
                           (lgra\ G))
                   (delta\ I)
```

```
I' = Infrastructure
                  (Lgraph (gra G)(agra G)(cgra G)
                          ((lgra\ G)(l := [z]))
                   (delta\ I)\ ]
         \implies I \rightarrow_n I'
\mid \mathit{put\text{-}remote} : \llbracket \ G = \mathit{graphI} \ I; \ \mathit{enables} \ \mathit{I} \ \mathit{l} \ (\mathit{Actor} \ \mathit{a}) \ \mathit{put};
        I' = Infrastructure
                  (Lgraph (gra G)(agra G)(cgra G))
                            ((lgra\ G)(l:=[z])))
                    (delta\ I)\ 
         \Longrightarrow I \to_n I'
instantiation infrastructure :: state
begin
definition
   state-transition-infra-def: (i \rightarrow_i i') = (i \rightarrow_n (i' :: infrastructure))
instance
  by (rule MC.class.MC.state.of-class.intro)
definition state-transition-in-refl ((-\rightarrow_n * -) 50)
where s \to_n * s' \equiv ((s,s') \in \{(x,y). state-transition-in \ x \ y\}^*)
lemma del-del[rule-format]: n \in set (del a S) \longrightarrow n \in set S
  by (induct\text{-}tac\ S,\ auto)
lemma del\text{-}dec[rule\text{-}format]: a \in set S \longrightarrow length (del a S) < length S
  by (induct-tac S, auto)
lemma del-sort[rule-format]: <math>\forall n. (Suc \ n :: nat) \leq length \ (l) \longrightarrow n \leq length \ (del
a(l)
  by (induct-tac l, simp, clarify, case-tac n, simp, simp)
lemma del-jonce: jonce a l \longrightarrow a \notin set (del \ a \ l)
  by (induct-tac l, auto)
lemma del-nodup[rule-format]: nodup a <math>l \longrightarrow a \notin set(del \ a \ l)
  by (induct-tac\ l,\ auto)
lemma nodup-up[rule-format]: a \in set (del a l) \longrightarrow a \in set l
  by (induct-tac l, auto)
```

```
lemma del-up [rule-format]: a \in set (del \ aa \ l) \longrightarrow a \in set \ l
  by (induct\text{-}tac\ l,\ auto)
lemma nodup-notin[rule-format]: a \notin set \ list \longrightarrow nodup \ a \ list
 by (induct-tac list, auto)
lemma nodup-down[rule-format]: nodup a <math>l \longrightarrow nodup a (del a l)
  by (induct-tac l, simp+, clarify, erule nodup-notin)
lemma del-notin-down[rule-format]: a \notin set\ list \longrightarrow a \notin set\ (del\ aa\ list)
  by (induct-tac list, auto)
lemma del-not-a[rule-format]: x \neq a \longrightarrow x \in set \ l \longrightarrow x \in set \ (del \ a \ l)
  by (induct-tac l, auto)
lemma nodup-down-notin[rule-format]: nodup a <math>l \longrightarrow nodup a (del \ aa \ l)
  by (induct-tac\ l,\ simp+,\ rule\ conjI,\ clarify,\ erule\ nodup-notin,\ (rule\ impI)+,
      erule del-notin-down)
lemma move-graph-eq: move-graph-a a l l g = g
 by (simp add: move-graph-a-def, case-tac g, force)
lemma delta-invariant: \forall z z'. z \rightarrow_n z' \longrightarrow delta(z) = delta(z')
  by (clarify, erule state-transition-in.cases, simp+)
lemma init-state-policy 0:
  assumes \forall z z'. z \rightarrow_n z' \longrightarrow delta(z) = delta(z')
      and (x,y) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*
    shows delta(x) = delta(y)
proof -
 have ind: (x,y) \in \{(x::infrastructure, y::infrastructure). x \to_n y\}^*
             \longrightarrow delta(x) = delta(y)
  proof (insert assms, erule rtrancl.induct)
    show (\bigwedge a::infrastructure.
       (\forall (z :: infrastructure)(z' :: infrastructure). \ (z \rightarrow_n z') \longrightarrow (\textit{delta} \ z = \textit{delta} \ z'))
       (((a, a) \in \{(x :: infrastructure, y :: infrastructure). x \rightarrow_n y\}^*) \longrightarrow
       (delta \ a = delta \ a)))
    by (rule impI, rule refl)
next fix a \ b \ c
 assume a0: \forall (z::infrastructure) \ z'::infrastructure. \ z \rightarrow_n z' \longrightarrow delta \ z = delta
     and a1: (a, b) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*
     and a2: (a, b) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^* \longrightarrow
         delta \ a = delta \ b
     and a3: (b, c) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}
     show (a, c) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^* \longrightarrow
```

```
delta \ a = delta \ c
  proof -
    have a4: delta b = delta c using a0 a1 a2 a3 by simp
    show ?thesis using a0 a1 a2 a3 by simp
  ged
\mathbf{qed}
show ?thesis
  by (insert ind, insert assms(2), simp)
qed
lemma init-state-policy: [(x,y) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*
                         delta(x) = delta(y)
  by (rule init-state-policy0, rule delta-invariant)
lemma same-nodes0[rule-format]: \forall z z'. z \rightarrow_n z' \longrightarrow nodes(graphIz) = nodes(graphI)
  by (clarify, erule state-transition-in.cases,
       (simp add: move-graph-a-def atI-def actors-graph-def nodes-def)+)
lemma same-nodes: (I, y) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*
                   \implies nodes(graphI\ y) = nodes(graphI\ I)
 by (erule rtrancl-induct, rule reft, drule CollectD, simp, drule same-nodes0, simp)
lemma same-actors0[rule-format]: \forall z z'. z \rightarrow_n z' \longrightarrow actors-graph(graphIz) =
actors-graph(graphIz')
proof (clarify, erule state-transition-in.cases)
 show \bigwedge(z::infrastructure) (z'::infrastructure) (G::igraph) (I::infrastructure) (a::char
list)
       (l::location) (a'::char\ list) (za::char\ list) I'::infrastructure.
       z = I \Longrightarrow
       z' = I' \Longrightarrow
       G = graphI I \Longrightarrow
       a @_G l \Longrightarrow
       a' @_G l \Longrightarrow
       has \ \tilde{G} \ (Actor \ a, \ za) \Longrightarrow
       enables I \ l \ (Actor \ a) \ get \Longrightarrow
       I' =
       Infrastructure
        (Lgraph (gra G) (agra G))
          ((cgra\ G)(Actor\ a') := (za\ \#\ fst\ (cgra\ G\ (Actor\ a')),\ snd\ (cgra\ G\ (Actor\ a')))
(a'))))) (lgra G))
        (delta\ I) \Longrightarrow
       actors-graph (graphI z) = actors-graph (graphI z')
     by (simp add: actors-graph-def nodes-def)
\mathbf{next} \ \mathbf{show} \ \bigwedge (z :: infrastructure) \ (z' :: infrastructure) \ (G :: igraph) \ (I :: infrastructure)
(a::char\ list)
       (l::location) (I'::infrastructure) za::char\ list.
```

```
z = I \Longrightarrow
       z' = I' \Longrightarrow
       G = graphI I \Longrightarrow
       a @_G l \Longrightarrow
       enables I \ l \ (Actor \ a) \ put \Longrightarrow
       I' = Infrastructure (Lgraph (gra G) (agra G) (cgra G) ((lgra G)(l := [za])))
(delta\ I) \Longrightarrow
       actors-graph (graphI\ z) = actors-graph (graphI\ z')
   by (simp add: actors-graph-def nodes-def)
next show \bigwedge(z::infrastructure) (z'::infrastructure) (G::igraph) (I::infrastructure)
(l::location)
       (a::char\ list)\ (I'::infrastructure)\ za::char\ list.
       z = I \Longrightarrow
       z' = I' \Longrightarrow
       G = graphI I \Longrightarrow
       enables I l (Actor a) put \Longrightarrow
       I' = Infrastructure (Lgraph (gra G) (agra G) (cgra G) ((lgra G)(l := [za])))
(delta\ I) \Longrightarrow
       actors-graph (graphI\ z) = actors-graph (graphI\ z')
    by (simp add: actors-graph-def nodes-def)
next fix z z' G I a l l' I'
  \mathbf{show}\ z = I \Longrightarrow z' = I' \Longrightarrow G = \operatorname{graph} I I \Longrightarrow a @_{G} I \Longrightarrow
       l \in nodes \ G \Longrightarrow l' \in nodes \ G \Longrightarrow a \in actors\text{-}graph \ (graphI \ I) \Longrightarrow
       enables I l' (Actor a) move \Longrightarrow
       I' = Infrastructure \ (move-graph-a \ a \ l \ l' \ (graph I \ I)) \ (delta \ I) \Longrightarrow
       actors-graph (graphI\ z) = actors-graph (graphI\ z')
  proof (rule\ equalityI)
    show z = I \Longrightarrow z' = I' \Longrightarrow G = graphI \ I \Longrightarrow a @_{G} \ l \Longrightarrow
    l \in nodes \ G \Longrightarrow l' \in nodes \ G \Longrightarrow a \in actors\text{-}graph \ (graphI \ I) \Longrightarrow
    enables I l' (Actor a) move \Longrightarrow
    I' = Infrastructure \ (move-graph-a \ a \ l \ l' \ (graphI \ I)) \ (delta \ I) \Longrightarrow
    actors-graph (graphI\ z) \subseteq actors-graph (graphI\ z')
  by (rule subsetI, simp add: actors-graph-def, (erule exE)+, case-tac x = a,
      rule-tac x = l' in exI, simp add: move-graph-a-def nodes-def atI-def,
        rule-tac \ x = ya \ in \ exI, \ rule \ conjI, \ simp \ add: \ move-graph-a-def \ nodes-def
atI-def,
      (erule conjE)+, simp add: move-graph-a-def, rule conjI, clarify,
       simp add: move-graph-a-def nodes-def at I-def, rule del-not-a, assumption+,
clarify)
\mathbf{next} \ \mathbf{show} \ z = I \Longrightarrow z' = I' \Longrightarrow G = \mathit{graph} I \ I \Longrightarrow a \ @_G \ l \Longrightarrow
    l \in nodes \ G \Longrightarrow l' \in nodes \ G \Longrightarrow a \in actors-graph \ (graphI \ I) \Longrightarrow
    enables I l' (Actor a) move \Longrightarrow
    I' = Infrastructure \ (move-graph-a \ a \ l \ l' \ (graph I \ I)) \ (delta \ I) \Longrightarrow
    actors-graph (graphI z') \subseteq actors-graph (graphI z)
  by (rule subsetI, simp add: actors-graph-def, (erule exE)+,
       case-tac \ x = a, \ rule-tac \ x = l \ in \ exI, \ simp \ add: \ move-graph-a-def \ nodes-def
atI-def.
        rule-tac x = ya in exI, rule conjI, simp add: move-graph-a-def nodes-def
atI-def,
```

```
(erule\ conjE)+,\ simp\ add:\ move-graph-a-def,\ case-tac\ ya=l,\ simp,
     case-tac \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l'), \ simp,
     case-tac\ l=l',\ simp+,\ erule\ del-up,\ simp,
     case-tac \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l'), \ simp,
     case-tac \ ya = l', \ simp+)
qed
qed
lemma same-actors: (I, y) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*
             \implies actors\text{-}graph(graphI\ I) = actors\text{-}graph(graphI\ y)
proof (erule rtrancl-induct)
 show actors-graph (graphI\ I) = actors-graph (graphI\ I)
   by (rule refl)
next show \bigwedge(y::infrastructure) z::infrastructure.
      (I, y) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^* \Longrightarrow
      (y, z) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\} \Longrightarrow
      actors-graph (graphI I) = actors-graph (graphI y) \Longrightarrow
      actors-graph (graphI I) = actors-graph (graphI z)
   by (drule CollectD, simp, drule same-actors0, simp)
qed
end
end
theory Airplane
imports AirInsider
begin
declare [[show-types]]
datatype doorstate = locked \mid norm \mid unlocked
datatype position = air \mid airport \mid ground
locale airplane =
fixes airplane-actors :: identity set
defines airplane-actors-def: airplane-actors ≡ {"Bob", "Charly", "Alice"}
{f fixes} airplane-locations :: location set
defines airplane-locations-def:
airplane-locations \equiv \{Location 0, Location 1, Location 2\}
fixes cockpit :: location
defines cockpit-def: cockpit \equiv Location 2
\mathbf{fixes}\ door::location
defines door\text{-}def: door \equiv Location 1
\mathbf{fixes} cabin :: location
defines cabin-def: cabin \equiv Location 0
```

```
fixes global-policy :: [infrastructure, identity] \Rightarrow bool
defines global-policy-def: global-policy I \ a \equiv a \notin airplane-actors
                \longrightarrow \neg (enables\ I\ cockpit\ (Actor\ a)\ put)
fixes ex-creds :: actor <math>\Rightarrow (string \ list * string \ list)
defines ex-creds-def: ex-creds \equiv
       (\lambda \ x.(if \ x = Actor "Bob")
             then (["PIN"], ["pilot"])
             else (if x = Actor "Charly"
                   then (["PIN"],["copilot"])
                   else (if x = Actor "Alice"
                         then (["PIN"],["flightattendant"])
                               else ([],[]))))
fixes ex-locs :: location \Rightarrow string \ list
defines ex-locs-def: ex-locs \equiv (\lambda x. if x = door then ["norm"] else
                                     (if \ x = cockpit \ then \ ["air"] \ else \ []))
fixes ex-locs':: location \Rightarrow string\ list
defines ex-locs'-def: ex-locs' \equiv (\lambda x. if x = door then ["locked"] else
                                       (if \ x = cockpit \ then \ ["air"] \ else \ []))
\mathbf{fixes} ex-graph :: igraph
defines ex-graph-def: ex-graph \equiv Lgraph
     \{(cockpit, door), (door, cabin)\}
     (\lambda \ x. \ if \ x = cockpit \ then \ ["Bob", "Charly"]
           else (if x = door then []
                 else (if x = cabin then ["Alice"] else [])))
     ex-creds ex-locs
\mathbf{fixes} aid-graph :: igraph
defines aid-graph-def: aid-graph \equiv Lgraph
      \{(cockpit, door), (door, cabin)\}
     (\lambda \ x. \ if \ x = cockpit \ then \ ["Charly"]
           else (if x = door then []
                 else (if x = cabin then ["Bob", "Alice"] else [])))
     ex-creds ex-locs'
fixes aid-graph\theta :: igraph
defines aid-graph0-def: aid-graph0 \equiv Lgraph
      \{(cockpit, door), (door, cabin)\}
     (\lambda \ x. \ if \ x = cockpit \ then \ ["Charly"]
           else (if x = door then ["Bob"]
                 else (if x = cabin then ["Alice"] else [])))
        ex-creds ex-locs
fixes agid-graph :: igraph
defines agid-graph-def: agid-graph \equiv Lgraph
     \{(cockpit, door), (door, cabin)\}
```

```
(\lambda \ x. \ if \ x = cockpit \ then \ ["Charly"]
            else (if x = door then []
                   else (if x = cabin then ["Bob", "Alice"] else [])))
      ex-creds ex-locs
fixes local-policies :: [igraph, location] \Rightarrow policy set
defines local-policies-def: local-policies G \equiv
   (\lambda y. if y = cockpit then
             \{(\lambda \ x. \ (? \ n. \ (n \ @_G \ cockpit) \land Actor \ n = x), \{put\}),\
              (\lambda \ x. \ (? \ n. \ (n \ @_G \ cabin) \land Actor \ n = x \land has \ G \ (x, "PIN")
                     \land isin G door "norm", {move})
         else (if y = door then \{(\lambda x. True, \{move\}),
                        (\lambda \ x. \ (? \ n. \ (n \ @_G \ cockpit) \land Actor \ n = x), \{put\})\}
                else (if y = cabin then \{(\lambda x. True, \{move\})\}
                      else {})))
fixes local-policies-four-eyes :: [igraph, location] \Rightarrow policy set
defines local-policies-four-eyes-def: local-policies-four-eyes G \equiv
   (\lambda y. if y = cockpit then
             \{(\lambda \ x. \ (? \ n. \ (n \ @_G \ cockpit) \land Actor \ n = x) \land \}
                   2 \leq length(agra\ G\ y) \land (\forall\ h \in set(agra\ G\ y).\ h \in airplane-actors),
\{put\}),
              (\lambda \ x. \ (? \ n. \ (n \ @_G \ cabin) \land Actor \ n = x \land has \ G \ (x, "PIN") \land 
                            isin\ G\ door\ ''norm''\ ),\{move\})
         \mathit{else}\ (\mathit{if}\ y = \mathit{door}\ \mathit{then}
                \{(\lambda \ x. \ ((?\ n.\ (n\ @_G\ cockpit)\ \land\ Actor\ n=x)\ \land\ 3\leq length(agra\ G
cockpit)), \{move\})\}
               else (if y = cabin then
                      \{(\lambda \ x. \ ((? \ n. \ (n \ @_G \ door) \land Actor \ n = x)), \ \{move\})\}
                            else {})))
fixes Airplane-scenario :: infrastructure (structure)
defines Airplane-scenario-def:
Airplane-scenario \equiv Infrastructure ex-graph local-policies
{f fixes} Airplane-in-danger :: infrastructure
defines Airplane-in-danger-def:
Airplane-in-danger \equiv Infrastructure \ aid-graph \ local-policies
\mathbf{fixes}\ Airplane\text{-}getting\text{-}in\text{-}danger0\ ::\ infrastructure
\mathbf{defines}\ \mathit{Airplane-getting-in-danger0-def}\colon
Airplane-getting-in-danger0 \equiv Infrastructure \ aid-graph0 \ local-policies
```

 \mathbf{fixes} Airplane-getting-in-danger :: infrastructure

defines Airplane-getting-in-danger-def:

```
Airplane-getting-in-danger \equiv Infrastructure agid-graph local-policies
```

```
fixes Air-states
defines Air-states-def: Air-states \equiv \{ I. Airplane-scenario \rightarrow_n * I \}
fixes Air-Kripke
defines Air-Kripke \equiv Kripke \ Air-states \ \{Airplane-scenario\}
{f fixes}\ Airplane-not-in-danger::infrastructure
defines Airplane-not-in-danger-def:
Airplane-not-in-danger \equiv Infrastructure \ aid-graph \ local-policies-four-eyes
{f fixes} Airplane-not-in-danger-init:: infrastructure
defines Airplane-not-in-danger-init-def:
Airplane-not-in-danger-init \equiv Infrastructure \ ex-graph \ local-policies-four-eyes
fixes Air-tp-states
defines Air-tp-states-def: Air-tp-states \equiv \{I. Airplane-not-in-danger-init \rightarrow_n * I
}
fixes Air-tp-Kripke
defines Air-tp-Kripke \equiv Kripke Air-tp-states \{Airplane-not-in-danger-init\}
fixes Safety :: [infrastructure, identity] \Rightarrow bool
defines Safety-def: Safety I \ a \equiv a \in airplane\text{-}actors
                      \longrightarrow (enables I cockpit (Actor a) move)
fixes Security :: [infrastructure, identity] \Rightarrow bool
defines Security-def: Security I \ a \equiv (isin \ (graphI \ I) \ door \ "locked")
                      \longrightarrow \neg (enables\ I\ cockpit\ (Actor\ a)\ move)
fixes foe-control :: [location, action] \Rightarrow bool
defines foe-control-def: foe-control l c \equiv
   (! I:: infrastructure. (? x :: identity.
       x @_{graphI\ I} l \land Actor\ x \neq Actor\ ''Eve''
             \rightarrow \neg (enables\ I\ l\ (Actor\ ''Eve'')\ c))
fixes astate:: identity \Rightarrow actor-state
defines astate-def: astate x \equiv (case \ x \ of \ astate)
          "Eve" \Rightarrow Actor-state depressed \{revenge, peer-recognition\}
         | - \Rightarrow Actor\text{-state happy } \{\})
{\bf assumes}\ \textit{Eve-precipitating-event: tipping-point (a state\ ''Eve'')}
assumes Insider-Eve: Insider "Eve" {"Charly"} astate
assumes cockpit-foe-control: foe-control cockpit put
```

begin

```
lemma ex-inv: global-policy Airplane-scenario "Bob"
by (simp add: Airplane-scenario-def global-policy-def airplane-actors-def)
lemma ex-inv2: global-policy Airplane-scenario "Charly"
by (simp add: Airplane-scenario-def global-policy-def airplane-actors-def)
lemma ex-inv3: \neg global-policy Airplane-scenario "Eve"
proof (simp add: Airplane-scenario-def global-policy-def, rule conjI)
 show "Eve" ∉ airplane-actors by (simp add: airplane-actors-def)
next show
  enables (Infrastructure ex-graph local-policies) cockpit (Actor "Eve") put
 proof -
   have a: Actor "Charly" = Actor "Eve"
     by (insert Insider-Eve, unfold Insider-def, (drule mp),
        rule Eve-precipitating-event, simp add: UasI-def)
   by (insert a, simp add: Airplane-scenario-def enables-def ex-creds-def local-policies-def
ex-graph-def,
     insert Insider-Eve, unfold Insider-def, (drule mp), rule Eve-precipitating-event,
        simp\ add: UasI-def, rule-tac\ x = "Charly" in exI, simp\ add: cockpit-def
atI-def)
 qed
qed
lemma Safety: Safety Airplane-scenario ("Alice")
proof -
 show Safety Airplane-scenario "Alice"
   by (simp add: Airplane-scenario-def Safety-def enables-def ex-creds-def
              local-policies-def ex-graph-def cockpit-def, rule impI,
      rule-tac \ x = "Alice" \ in \ exI, \ simp \ add: \ atI-def \ cabin-def \ ex-locs-def \ door-def,
     rule conjI, simp add: has-def credentials-def, simp add: isin-def credentials-def)
qed
lemma inj-lem: \llbracket inj f; x \neq y \rrbracket \Longrightarrow f x \neq f y
by (simp add: inj-eq)
lemma inj-on-lem: \llbracket \text{ inj-on } f A; x \neq y; x \in A; y \in A \rrbracket \Longrightarrow f x \neq f y
by (simp add: inj-on-def, blast)
\mathbf{lemma} \ inj\text{-}lemma': \ inj\text{-}on \ (isin \ ex\text{-}graph \ door) \ \{''locked'', ''norm''\}
 by (unfold inj-on-def ex-graph-def isin-def, simp, unfold ex-locs-def, simp)
lemma inj-lemma'': inj-on (isin aid-graph door) {"locked","norm"}
```

```
by (unfold inj-on-def aid-graph-def isin-def, simp, unfold ex-locs'-def, simp)
lemma locl-lemma2: isin ex-graph door "norm" \neq isin ex-graph door "locked"
by (rule-tac A = \{ \text{"locked","norm"} \} and f = isin \ ex-graph \ door \ in \ inj-on-lem,
      rule inj-lemma', simp+)
lemma locl-lemma3: isin ex-graph door "norm" = (\neg isin \ ex-graph \ door "locked")
by (insert locl-lemma2, blast)
lemma locl-lemma2a: isin aid-graph door "norm" \neq isin aid-graph door "locked"
by (rule-tac A = \{"locked", "norm"\} and f = isin \ aid-graph \ door \ in \ inj-on-lem,
     rule inj-lemma'', simp+)
lemma locl-lemma3a: isin aid-graph door "norm" = (\neg isin aid-graph door "locked")
by (insert locl-lemma2a, blast)
lemma Security: Security Airplane-scenario s
  by (simp add: Airplane-scenario-def Security-def enables-def local-policies-def
ex-locs-def locl-lemma3)
lemma Security-problem: Security Airplane-scenario "Bob"
by (rule Security)
lemma pilot-can-leave-cockpit: (enables Airplane-scenario cabin (Actor "Bob")
 by (simp add: Airplane-scenario-def Security-def ex-creds-def ex-graph-def enables-def
            local-policies-def ex-locs-def, simp add: cockpit-def cabin-def door-def)
lemma ex-inv4: ¬global-policy Airplane-in-danger ("Eve")
proof (simp add: Airplane-in-danger-def global-policy-def, rule conjI)
 show "Eve" ∉ airplane-actors by (simp add: airplane-actors-def)
next show enables (Infrastructure aid-graph local-policies) cockpit (Actor "Eve")
put
 proof -
   have a: Actor "Charly" = Actor "Eve"
    by (insert Insider-Eve, unfold Insider-def, (drule mp),
        rule Eve-precipitating-event, simp add: UasI-def)
   show ?thesis
    apply (insert a, erule subst)
    by (simp add: enables-def local-policies-def cockpit-def aid-graph-def atI-def)
qed
qed
lemma Safety-in-danger:
 fixes s
```

```
assumes s \in airplane\text{-}actors
 shows \neg(Safety\ Airplane-in-danger\ s)
proof (simp add: Airplane-in-danger-def Safety-def enables-def assms)
  show \forall x :: (actor \Rightarrow bool) \times action set \in local-policies aid-graph cockpit.
      \neg (case \ x \ of \ (p::actor \Rightarrow bool, \ e::action \ set) \Rightarrow move \in e \land p \ (Actor \ s))
   by ( simp add: local-policies-def aid-graph-def ex-locs'-def isin-def)
qed
lemma Security-problem': ¬(enables Airplane-in-danger cockpit (Actor "Bob")
proof (simp add: Airplane-in-danger-def Security-def enables-def local-policies-def
      ex-locs-def locl-lemma3a, rule impI)
 assume has aid-graph (Actor "Bob", "PIN")
 show (\forall n :: char \ list.
        Actor \ n = Actor \ ''Bob'' \longrightarrow n \ @_{aid\text{-}qraph} \ cabin \ \longrightarrow \ isin \ aid\text{-}graph \ door
"locked"
by (simp add: aid-graph-def isin-def ex-locs'-def)
qed
lemma ex\text{-}inv5: a \in airplane\text{-}actors \longrightarrow global\text{-}policy Airplane\text{-}not\text{-}in\text{-}danger a
by (simp add: Airplane-not-in-danger-def global-policy-def)
lemma ex-inv6: global-policy Airplane-not-in-danger a
proof (simp add: Airplane-not-in-danger-def global-policy-def, rule impI)
 assume a \notin airplane\text{-}actors
 show ¬ enables (Infrastructure aid-graph local-policies-four-eyes) cockpit (Actor
by (simp add: aid-graph-def ex-locs'-def enables-def local-policies-four-eyes-def)
qed
lemma step 0: Airplane-scenario \rightarrow_n Airplane-getting-in-danger 0
proof (rule-tac l = cockpit and l' = door and a = "Bob" in move, rule reft)
 show "Bob" @graphI Airplane-scenario cockpit
 by (simp add: Airplane-scenario-def atI-def ex-graph-def)
\mathbf{next} \ \mathbf{show} \ cockpit \in nodes \ (graphI \ Airplane\text{-}scenario)
   by (simp add: ex-graph-def Airplane-scenario-def nodes-def, blast)+
\mathbf{next} \mathbf{show} \ door \in nodes \ (graphI \ Airplane\text{-}scenario)
  by (simp add: actors-graph-def door-def cockpit-def nodes-def cabin-def,
      rule-tac x = Location 2 in exI,
      simp add: Airplane-scenario-def ex-graph-def cockpit-def door-def)
\mathbf{next} \mathbf{show} \ ''Bob'' \in \mathit{actors-graph} \ (\mathit{graphI} \ \mathit{Airplane-scenario})
    by (simp add: actors-graph-def Airplane-scenario-def nodes-def ex-graph-def,
next show enables Airplane-scenario door (Actor "Bob") move
   by (simp add: Airplane-scenario-def enables-def local-policies-def ex-creds-def
door-def cockpit-def)
next show Airplane-getting-in-danger0 =
```

```
Infrastructure (move-graph-a "Bob" cockpit door (graphI Airplane-scenario))
    (delta Airplane-scenario)
 proof -
    have a: (move-graph-a "Bob" cockpit door (graphI Airplane-scenario)) =
aid-graph0
     by (simp add: move-graph-a-def door-def cockpit-def Airplane-scenario-def
        aid-graph0-def ex-graph-def, rule ext, simp add: cabin-def door-def)
     by (unfold Airplane-getting-in-danger0-def, insert a, erule ssubst,
        simp add: Airplane-scenario-def)
 qed
qed
lemma step1: Airplane-getting-in-danger0 \rightarrow_n Airplane-getting-in-danger
proof (rule-tac l = door and l' = cabin and a = "Bob" in move, rule refl)
 show "Bob" @ graphI Airplane-getting-in-danger0 door
  by (simp add: Airplane-getting-in-danger0-def atI-def aid-graph0-def door-def
cockpit-def)
next show door \in nodes (graph I Airplane-getting-in-danger \theta)
  by (simp\ add:\ aid\ -graph\ 0\ -def\ Airplane\ -getting\ -in\ -danger\ 0\ -def\ nodes\ -def\ ,\ blast) +
next show cabin \in nodes (graphI Airplane-getting-in-danger \theta)
   by (simp add: actors-graph-def door-def cockpit-def nodes-def cabin-def,
   rule-tac x = Location 1 in <math>exI,
    simp add: Airplane-getting-in-danger0-def aid-graph0-def cockpit-def door-def
cabin-def
next show "Bob" \in actors-graph (graphI Airplane-getting-in-danger0)
  by (simp add: actors-graph-def door-def cockpit-def nodes-def cabin-def
               Airplane-getting-in-danger0-def aid-graph0-def, blast)
next show enables Airplane-getting-in-danger0 cabin (Actor "Bob") move
 by (simp add: Airplane-getting-in-danger0-def enables-def local-policies-def ex-creds-def
door-def
             cockpit-def cabin-def)
{f next \ show} \ {\it Airplane-getting-in-danger} =
  Infrastructure (move-graph-a "Bob" door cabin (graphI Airplane-getting-in-danger0))
    (delta Airplane-getting-in-danger0)
   by (unfold Airplane-getting-in-danger-def,
       simp add: Airplane-getting-in-danger0-def agid-graph-def aid-graph0-def
               move-graph-a-def door-def cockpit-def cabin-def, rule ext,
      simp add: cabin-def door-def)
qed
lemma step2: Airplane-getting-in-danger <math>\rightarrow_n Airplane-in-danger
proof (rule-tac l = door and a = "Charly" and z = "locked" in put-remote,
rule refl)
 show enables Airplane-getting-in-danger door (Actor "Charly") put
  by (simp add: enables-def local-policies-def ex-creds-def door-def cockpit-def,
     unfold Airplane-getting-in-danger-def,
     simp add: local-policies-def cockpit-def cabin-def door-def,
     rule-tac x = "Charly" in exI, rule conjI,
```

```
simp add: atI-def agid-graph-def door-def cockpit-def, rule refl)
next show Airplane-in-danger =
   Infrastructure
   (Lgraph (gra (graph I Airplane-getting-in-danger)) (agra (graph I Airplane-getting-in-danger))
      (cqra (qraphI Airplane-qettinq-in-danqer))
      ((lgra\ (graphI\ Airplane-getting-in-danger))(door := [''locked''])))
    (delta Airplane-getting-in-danger)
   by (unfold Airplane-in-danger-def, simp add: aid-graph-def agid-graph-def
              ex-locs'-def ex-locs-def Airplane-getting-in-danger-def, force)
\mathbf{qed}
lemma step\theta r: Airplane-scenario \rightarrow_n * Airplane-getting-in-danger\theta
 by (simp add: state-transition-in-refl-def, insert step0, auto)
lemma step1r: Airplane-getting-in-danger0 \rightarrow_n * Airplane-getting-in-danger
  by (simp add: state-transition-in-refl-def, insert step1, auto)
lemma step2r: Airplane-getting-in-danger \rightarrow_n * Airplane-in-danger
 by (simp add: state-transition-in-refl-def, insert step2, auto)
theorem step-allr: Airplane-scenario \rightarrow_n * Airplane-in-danger
 by (insert step0r step1r step2r, simp add: state-transition-in-refl-def)
theorem aid-attack: Air-Kripke \vdash EF (\{x. \neg global\text{-policy } x \text{ "Eve"}\})
proof (simp add: check-def Air-Kripke-def, rule conjI)
 show Airplane-scenario \in Air-states
   by (simp add: Air-states-def state-transition-in-refl-def)
next show Airplane-scenario \in EF {x::infrastructure. \neg global-policy x "Eve"}
  by (rule EF-lem2b, subst EF-lem000, rule EX-lem0r, subst EF-lem000, rule
EX-step,
    unfold state-transition-infra-def, rule step0, rule EX-lem0r,
    rule-tac y = Airplane-qetting-in-danger in EX-step,
    unfold state-transition-infra-def, rule step1, subst EF-lem000, rule EX-lem0l,
    rule-tac\ y = Airplane-in-danger\ in\ EX-step,\ unfold\ state-transition-infra-def,
    rule step2, rule CollectI, rule ex-inv4)
qed
lemma actors-unique-loc-base:
  assumes I \to_n I'
     and (\forall l l'. a @ graphI I l \wedge a @ graphI I l' \loop l = l') \wedge a
          (\forall \ l. \ nodup \ a \ (agra \ (graphI \ \tilde{I}) \ \tilde{l}))
   shows (\forall \ l \ l'. \ a \ @_{graphI \ I'} \ l \ \land \ a \ @_{graphI \ I'} \ l' \ \longrightarrow \ l = l') \ \land
          (\forall l. \ nodup \ a \ (agra \ (graphI \ I') \ l))
proof (rule state-transition-in.cases, rule assms(1))
 show \bigwedge(G::igraph) (Ia::infrastructure) (aa::char list) (l::location) (a'::char list)
(z::char\ list)
      I'a::infrastructure.
      I = Ia \Longrightarrow
```

```
I' = I'a \Longrightarrow
        G = graphI Ia \Longrightarrow
        aa @_G l \Longrightarrow
        a' @_G l \Longrightarrow
        has\ G\ (Actor\ aa,\ z) \Longrightarrow
        enables Ia l (Actor aa) get \Longrightarrow
        I'a =
        Infrastructure
         (Lgraph (gra G) (agra G)
             ((cgra\ G)(Actor\ a') := (z \ \#\ fst\ (cgra\ G\ (Actor\ a')),\ snd\ (cgra\ G\ (Actor\ a')))
a'))))) (lgra G))
         (delta\ Ia) \Longrightarrow
        (\forall (l::location) \ l'::location. \ a @_{qraphI\ I'}\ l \land a @_{qraphI\ I'}\ l' \longrightarrow l = l') \land l = l'
        (\forall l::location. nodup \ a \ (agra \ (graphI\ I')\ l)) using assms
    by (simp\ add:\ atI-def)
next fix G Ia aa l I'a z
  assume a\theta: I = Ia and a1: I' = I'a and a2: G = graphI Ia and a3: aa @_{G} I
     and a4: enables Ia l (Actor aa) put
      and a5: I'a = Infrastructure (Lgraph (gra G) (agra G) (cgra G) ((lgra G)(lgra G))
:= [z]))) (delta Ia)
  show (\forall (l::location) \ l'::location. \ a @_{qraphI\ I'} \ l \land a @_{qraphI\ I'} \ l' \longrightarrow l = l') \land
        (\forall l::location. nodup \ a \ (agra \ (graphI\ I')\ l))using assms
    by (simp add: a0 a1 a2 a3 a4 a5 atI-def)
next show \bigwedge(G::igraph) (Ia::infrastructure) (I::location) (aa::char list) (I'a::infrastructure)
        z{::}char\ list.
        I = Ia \Longrightarrow
        I' = I'a \Longrightarrow
        G = graphI Ia \Longrightarrow
        enables Ia l (Actor aa) put \Longrightarrow
       I'a = Infrastructure (Lgraph (gra G) (agra G) (cgra G) ((lgra G)(l := [z])))
(delta\ Ia) \Longrightarrow
        (\forall (l::location) \ l'::location. \ a \ @_{qraphI\ I'}\ l \ \land \ a \ @_{qraphI\ I'}\ l' \longrightarrow l = l') \ \land
        (\forall \mathit{l} :: location. \ \mathit{nodup} \ \mathit{a} \ (\mathit{agra} \ (\mathit{graph} \mathit{I} \ \mathit{I'}) \ \mathit{l}))
    by (clarify, simp add: assms at I-def)
next show \bigwedge (G::igraph) (Ia::infrastructure) (aa::char list) (I::location) (I'::location)
        I'a::infrastructure.
        I = Ia \Longrightarrow
        I' = I'a \Longrightarrow
        G = graphI Ia \Longrightarrow
        aa @_G l \Longrightarrow
        l \in nodes \ G \Longrightarrow
        l' \in nodes \ G \Longrightarrow
        aa \in actors\text{-}graph (graphI Ia) \Longrightarrow
        enables Ia l' (Actor aa) move \Longrightarrow
        I'a = Infrastructure \ (move-graph-a \ aa \ l \ l' \ (graphI \ Ia)) \ (delta \ Ia) \Longrightarrow
        (\forall (l::location) \ l'::location. \ a @_{qraphI\ I'}\ l \land a @_{qraphI\ I'}\ l' \longrightarrow l = l') \land \\
        (\forall l::location. nodup \ a \ (agra \ (graphI\ I')\ l))
  \mathbf{proof}\ (\mathit{simp}\ \mathit{add}\colon \mathit{move-graph-a-def}, \mathit{rule}\ \mathit{conj}I,\ \mathit{clarify},\ \mathit{rule}\ \mathit{conj}I,\ \mathit{clarify},\ \mathit{rule}
conjI, clarify)
```

```
show \bigwedge(G::igraph) (Ia::infrastructure) (aa::char list) (l::location) (l'::location)
       (I'a::infrastructure) (la::location) l'a::location.
       I' =
       In frastructure \\
        (Lgraph (gra (graphI I)))
          (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
              then (agra (graphI I))(l := del \ a \ (agra (graphI I) \ l), \ l' := a \ \# \ agra
(graphI\ I)\ l')
           else agra (graphI I))
          (cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))
        (delta\ I) \Longrightarrow
       a @_{qraphI I} l \Longrightarrow
       l \in nodes (graphI I) \Longrightarrow
       l' \in nodes (graphI I) \Longrightarrow
       a \in actors-graph (graphI I) \Longrightarrow
       enables I l' (Actor a) move \Longrightarrow
       a \in set (agra (graphI I) l) \Longrightarrow
       a \notin set (agra (graphI I) l') \Longrightarrow
     a <sup>©</sup>Lgraph (gra (graphI I))
                                                  ((agra\ (graphI\ I))(l:=del\ a\ (agra\ (graphI\ I)\ l),\ l':=a\ \#\ agra\ (graphI\ I)
la \Longrightarrow
     a @ Lgraph (gra (graphI I))
                                                  ((agra\ (graphI\ I))(l:=del\ a\ (agra\ (graphI\ I)\ l),\ l':=a\ \#\ agra\ (graphI\ I)
l'a \Longrightarrow
       la = l'a
      apply (case-tac la \neq l' \land la \neq l \land l'a \neq l' \land l'a \neq l)
       apply (simp add: atI-def)
       apply (subgoal-tac la = l' \lor la = l \lor l'a = l' \lor l'a = l)
      prefer 2
      using assms(2) at I-def apply blast
      apply blast
      by (metis agra.simps assms(2) at I-def del-nodup fun-upd-apply)
 next show \bigwedge (G::igraph) (Ia::infrastructure) (aa::char list) (l::location) (l'::location)
       I'a::infrastructure.
       I' =
       In frastructure \\
        (Lgraph (gra (graphI I)))
          (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
              then (agra (graphI I))(l := del \ a (agra (graphI I) \ l), \ l' := a \# agra
(graphI\ I)\ l')
           else \ agra \ (graphI \ I))
          (cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))
        (delta\ I) \Longrightarrow
       a @_{qraphI I} l \Longrightarrow
       l \in nodes (graphI I) \Longrightarrow
       l' \in nodes (graphI I) \Longrightarrow
       a \in actors\text{-}graph\ (graphI\ I) \Longrightarrow
       enables I l' (Actor a) move \Longrightarrow
       a \in set (agra (graphI I) l) \Longrightarrow
       a \notin set (agra (graphI I) l') \Longrightarrow
       \forall la::location.
```

```
(la = l \longrightarrow l \neq l' \longrightarrow nodup \ a \ (del \ a \ (agra \ (graphI \ I) \ l))) \land
            (la \neq l \longrightarrow la \neq l' \longrightarrow nodup \ a \ (agra \ (graphI \ I) \ la))
       by (simp \ add: \ assms(2) \ nodup-down)
 next show \bigwedge (G::igraph) (Ia::infrastructure) (aa::char list) (l::location) (l'::location)
        I'a::infrastructure.
        I' =
        Infrastructure
         (Lgraph (gra (graphI I)))
            (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
                then (agra (graphI I))(l := del \ a \ (agra (graphI I) \ l), \ l' := a \ \# \ agra
(graphI\ I)\ l')
             else \ agra \ (graphI \ I))
            (cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))
         (delta\ I) \Longrightarrow
        a @_{araphI\ I} l \Longrightarrow
        l \in nodes (graphI I) \Longrightarrow
        l' \in nodes (graphI \ I) \Longrightarrow
        a \in actors-graph (graphI I) \Longrightarrow
        enables I l' (Actor a) move \Longrightarrow
        (a \in \mathit{set} \; (\mathit{agra} \; (\mathit{graphI} \; I) \; l) \, \longrightarrow \, a \in \mathit{set} \; (\mathit{agra} \; (\mathit{graphI} \; I) \; l')) \, \longrightarrow \,
        (\forall (l::location) \ l'::location.
           {\color{blue}a} \stackrel{@}{=} \mathit{Lgraph} \ (\mathit{gra} \ (\mathit{graphI} \ I)) \ (\mathit{agra} \ (\mathit{graphI} \ I)) \ (\mathit{cgra} \ (\mathit{graphI} \ I)) \ (\mathit{lgra} \ (\mathit{graphI} \ I))
l \wedge
          {}^{a} \ @Lgraph \ (gra \ (graphI \ I)) \ (agra \ (graphI \ I)) \ (cgra \ (graphI \ I)) \ (lgra \ (graphI \ I))
             l = l' \land
        (\forall l::location. nodup \ a \ (agra \ (graphI\ I)\ l))
       by (simp\ add:\ assms(2)\ atI-def)
 next show \bigwedge (G::igraph) (Ia::infrastructure) (aa::char\ list) (l::location) (l'::location)
        I'a::infrastructure.
        I = Ia \Longrightarrow
        I' =
        Infrastructure
         (Lgraph (gra (graphI Ia))
            (if\ aa \in set\ (agra\ (graphI\ Ia)\ l) \land aa \notin set\ (agra\ (graphI\ Ia)\ l')
             then (agra (graphI Ia))(l := del \ aa \ (agra \ (graphI Ia) \ l), \ l' := aa \ \# \ agra
(graph I Ia) l'
             else agra (graphI Ia))
            (cgra (graphI Ia)) (lgra (graphI Ia)))
         (delta\ Ia) \Longrightarrow
        G = graphI Ia \Longrightarrow
        aa @_{araphI \ Ia} l \Longrightarrow
        l \in nodes (graphI Ia) \Longrightarrow
        l' \in nodes (qraphI Ia) \Longrightarrow
        aa \in actors\text{-}graph\ (graphI\ Ia) \Longrightarrow
        enables Ia l' (Actor aa) move \Longrightarrow
        I'a =
        In frastructure
         (Lgraph (gra (graphI Ia))
```

```
(if \ aa \in set \ (agra \ (graphI \ Ia) \ l) \land aa \notin set \ (agra \ (graphI \ Ia) \ l')
                  then (agra (graphI Ia))(l := del \ aa \ (agra \ (graphI Ia) \ l), \ l' := aa \ \# \ agra
(graphI Ia) l')
                  else agra (graphI Ia))
                (cgra (graphI Ia)) (lgra (graphI Ia)))
             (delta\ Ia) \Longrightarrow
           aa \neq a \longrightarrow
           (aa \in set \ (agra \ (graphI \ Ia) \ l) \land aa \notin set \ (agra \ (graphI \ Ia) \ l') \longrightarrow
             (\forall (la::location) \ l'a::location.
              a © Lgraph (gra (graphI Ia))
                                                                                           ((agra (graphI Ia))
                                                                                                                                                           (l := del \ aa \ (agra \ (graphI \ Ia) \ l), \ l
la \wedge
             a <sup>©</sup>Lgraph (gra (graphI Ia))
                                                                                           ((agra (graphI Ia))
                                                                                                                                                           (l := del \ aa \ (agra \ (graphI \ Ia) \ l), \ l
                   la = l'a) \wedge
             (\forall la::location.
                    (la = l \longrightarrow
                     (l = l' \longrightarrow nodup \ a \ (agra \ (graphI \ Ia) \ l')) \land (agra \ (graphI \ Ia) \ l'))
                     (l \neq l' \longrightarrow nodup \ a \ (del \ aa \ (agra \ (graphI \ Ia) \ l)))) \land (l \neq l' \longrightarrow nodup \ a \ (del \ aa \ (agra \ (graphI \ Ia) \ l)))) \land (l \neq l' \longrightarrow nodup \ a \ (del \ aa \ (agra \ (graphI \ Ia) \ l)))) \land (l \neq l' \longrightarrow nodup \ a \ (del \ aa \ (agra \ (graphI \ Ia) \ l)))) \land (l \neq l' \longrightarrow nodup \ a \ (del \ aa \ (agra \ (graphI \ Ia) \ l))))) \land (l \neq l' \longrightarrow nodup \ a \ (del \ aa \ (agra \ (graphI \ Ia) \ l))))) \land (l \neq l' \longrightarrow nodup \ a \ (del \ aa \ (agra \ (graphI \ Ia) \ l))))) \land (l \neq l' \longrightarrow nodup \ a \ (del \ aa \ (agra \ (graphI \ Ia) \ l)))))) \land (l \neq l' \longrightarrow nodup \ a \ (del \ aa \ (agra \ (graphI \ Ia) \ l))))) \land (l \neq l' \longrightarrow nodup \ a \ (del \ aa \ (agra \ (graphI \ Ia) \ l)))))) \land (l \neq l' \longrightarrow nodup \ a \ (del \ aa \ (agra \ (graphI \ Ia) \ l)))))) \land (l \neq l' \longrightarrow nodup \ a \ (agra \ (graphI \ Ia) \ l)))))) \land (l \neq l' \longrightarrow nodup \ a \ (agra \ (graphI \ Ia) \ l))))))))
                     (la = l' \longrightarrow nodup \ a \ (agra \ (graphI \ Ia) \ l')) \land
                     (la \neq l' \longrightarrow nodup \ a \ (agra \ (graphI \ Ia) \ la))))) \land
           ((aa \in set (agra (graphI Ia) l) \longrightarrow aa \in set (agra (graphI Ia) l')) \longrightarrow
             (\forall (l::location) \ l'::location.
              a <sup>@</sup>Lgraph (gra (graphI Ia)) (agra (graphI Ia)) (cgra (graphI Ia))
                                                                                                                                                                  (lgra (graphI Ia))
l \wedge
             a <sup>™</sup>Lgraph (gra (graphI Ia)) (agra (graphI Ia)) (cgra (graphI Ia))
                                                                                                                                                                  (lgra (graphI Ia))
                    l = l' \wedge
             (\forall l::location. nodup \ a \ (agra \ (graphI \ Ia) \ l)))
     proof (clarify, simp add: atI-def,rule conjI,clarify,rule conjI,clarify,rule conjI,
                  clarify, rule\ conjI, clarify, simp, clarify, rule\ conjI, (rule\ impI)+)
          show \bigwedge (aa::char list) (l::location) (l'::location) l'a::location.
           I' =
           In frastructure \\
             (Lgraph (gra (graphI I)))
               ((agra\ (graphI\ I))(l:=del\ aa\ (agra\ (graphI\ I)\ l),\ l':=aa\ \#\ agra\ (graphI
I) l')
                (cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))
             (delta\ I) \Longrightarrow
           aa \in set (agra (graphI I) l) \Longrightarrow
           l \in nodes (graphI I) \Longrightarrow
           l' \in nodes (graphI I) \Longrightarrow
           aa \in actors\text{-}graph \ (graphI \ I) \Longrightarrow
           enables I l' (Actor aa) move \Longrightarrow
           aa \neq a \Longrightarrow
           aa \notin set (agra (graphI I) l') \Longrightarrow
           l \neq l' \Longrightarrow
           l'a \neq l \Longrightarrow
           l'a = l' \Longrightarrow a \in set (del \ aa \ (agra \ (graphI \ I) \ l)) \Longrightarrow a \notin set \ (agra \ (graphI) \ l)
```

```
I) l'
          by (meson \ assms(2) \ atI-def \ del-notin-down)
     next show \bigwedge (aa::char list) (l::location) (l'::location) l'a::location.
        I' =
        Infrastructure
          (Lgraph (gra (graphI I)))
            ((\mathit{agra}\;(\mathit{graphI}\;I))(\mathit{l}:=\mathit{del}\;\mathit{aa}\;(\mathit{agra}\;(\mathit{graphI}\;I)\;\mathit{l}),\;\mathit{l}':=\mathit{aa}\;\#\;\mathit{agra}\;(\mathit{graphI}\;I))
I) l'))
            (\mathit{cgra}\ (\mathit{graphI}\ I))\ (\mathit{lgra}\ (\mathit{graphI}\ I)))
          (delta\ I) \Longrightarrow
        aa \in set (agra (graphI I) l) \Longrightarrow
        l \in nodes (graphI I) \Longrightarrow
        l' \in nodes (graphI I) \Longrightarrow
        aa \in actors\text{-}graph\ (graphI\ I) \Longrightarrow
        enables I l' (Actor aa) move \Longrightarrow
        aa \neq a \Longrightarrow
        aa \notin set (agra (graphI I) l') \Longrightarrow
        l \neq l' \Longrightarrow
        l'a \neq l \Longrightarrow
        l'a \neq l' \longrightarrow a \in set \ (del \ aa \ (agra \ (graphI \ I) \ l)) \longrightarrow a \notin set \ (agra \ (graphI) \ l)
I) l'a)
          by (meson \ assms(2) \ atI-def \ del-notin-down)
     next show \bigwedge(aa::char\ list)\ (l::location)\ (l'::location)\ la::location.
        I' =
        In frastructure \\
          (Lgraph (gra (graphI I)))
            (if aa \notin set (agra (graphI I) l')
               then (agra (graphI I))(l := del \ aa \ (agra \ (graphI I) \ l), \ l' := aa \ \# \ agra
(graphI\ I)\ l')
              else \ agra \ (graphI \ I))
            (cgra (graphI I)) (lgra (graphI I)))
          (delta\ I) \Longrightarrow
        aa \in set (agra (graphI I) l) \Longrightarrow
        l \in nodes (graphI I) \Longrightarrow
        l' \in nodes (graphI I) \Longrightarrow
        aa \in actors\text{-}graph\ (graphI\ I) \Longrightarrow
        enables I l' (Actor aa) move \Longrightarrow
        aa \neq a \Longrightarrow
        aa \notin set (agra (graphI I) l') \Longrightarrow
        la \neq l \longrightarrow
        (la = l' \longrightarrow
          (\forall l'a::location.
               (l'a = l \longrightarrow
               l \neq l' \longrightarrow a \in set (agra (graphI I) l') \longrightarrow a \notin set (del aa (agra (graphI I) l'))
I) \ l))) \wedge
               (l'a \neq l \longrightarrow
                 l'a \neq l' \longrightarrow a \in set (agra (graphI I) l') \longrightarrow a \notin set (agra (graphI I))
l'a)))) \wedge
        (la \neq l' \longrightarrow
```

```
(\forall l'a::location.
             (l'a = l \longrightarrow
               (l = l' \longrightarrow a \in set (agra (graphI I) la) \longrightarrow a \notin set (agra (graphI I) la))
l')) \wedge
             (l \neq l' \longrightarrow a \in set \ (agra \ (graphI \ I) \ la) \longrightarrow a \notin set \ (del \ aa \ (agra \ (graphI) \ la))
I) l)))) \wedge
              (l'a \neq l \longrightarrow
              (l'a = l' \longrightarrow a \in set (agra (graphI I) la) \longrightarrow a \notin set (agra (graphI I) la))
l')) \wedge
               (l'a \neq l' \longrightarrow
                a \in set \ (agra \ (graphI \ I) \ la) \land a \in set \ (agra \ (graphI \ I) \ l'a) \longrightarrow la =
l'(a))))
         by (meson \ assms(2) \ atI-def \ del-notin-down)
    next show \bigwedge (aa::char list) (l::location) l'::location.
        I' =
        Infrastructure
         (Lgraph (gra (graphI I)))
           (if aa \notin set (agra (graphI I) l')
              then (agra (graphI I))(l := del \ aa \ (agra \ (graphI I) \ l), \ l' := aa \# agra
(graphI\ I)\ l')
            else \ agra \ (graphI \ I))
           (cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))
         (delta\ I) \Longrightarrow
        aa \in set (agra (graphI I) l) \Longrightarrow
        l \in nodes (graphI I) \Longrightarrow
        l' \in nodes (graphI I) \Longrightarrow
        aa \in actors\text{-}graph \ (graphI \ I) \Longrightarrow
        enables I l' (Actor aa) move \Longrightarrow
        aa \neq a \Longrightarrow
        aa \notin set (agra (graphI I) l') \Longrightarrow
        \forall la::location.
           (la = l \longrightarrow
            (l = l' \longrightarrow nodup \ a \ (agra \ (graphI \ I) \ l')) \land
            (l \neq l' \longrightarrow nodup \ a \ (del \ aa \ (agra \ (graphI \ l))))) \land
           (la \neq l \longrightarrow
             (la = l' \longrightarrow nodup \ a \ (agra \ (graphI \ l')) \land (la \neq l' \longrightarrow nodup \ a \ (agra
(graphI\ I)\ la)))
         by (simp add: assms(2) nodup-down-notin)
    next show \bigwedge(aa::char\ list)\ (l::location)\ l'::location.
        I' =
        Infrastructure
         (Lgraph (gra (graphI I)))
           (if \ aa \notin set \ (agra \ (graphI \ I) \ l')
              then (agra (graphI I))(l := del \ aa \ (agra \ (graphI I) \ l), \ l' := aa \ \# \ agra
(graphI\ I)\ l')
            else \ agra \ (graphI \ I))
           (cgra (graphI I)) (lgra (graphI I)))
         (delta\ I) \Longrightarrow
        aa \in set (agra (graphI I) l) \Longrightarrow
```

```
l \in nodes (graphI I) \Longrightarrow
         l' \in nodes (graphI \ I) \Longrightarrow
         aa \in actors\text{-}graph\ (graphI\ I) \Longrightarrow
         enables I l' (Actor aa) move \Longrightarrow
         aa \neq a \Longrightarrow
         aa \in set (agra (graphI I) l') \longrightarrow
         (\forall (l::location) \ l'::location.
               a \in set \ (agra \ (graphI \ I) \ l) \land a \in set \ (agra \ (graphI \ I) \ l') \longrightarrow l = l') \land
         (\forall l::location. nodup \ a \ (agra \ (graphI\ I)\ l))
          using assms(2) at I-def by blast
     qed
  qed
qed
lemma actors-unique-loc-step:
  assumes (I, I') \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*
       and \forall a. (\forall l l'. a @_{qraphI I} l \land a @_{qraphI I} l' \longrightarrow l = l') \land
             (\forall l. \ nodup \ a \ (agra \ (graphI \ I) \ l))
     \mathbf{shows} \quad \forall \ a. \ (\forall \ l \ l'. \ a \ @_{graphI \ I'} \ l \ \land \ a \ @_{graphI \ I'} \ l' \ \longrightarrow l = l') \ \land \\
             (\forall l. \ nodup \ a \ (agra \ (graph I \ I') \ l))
proof
  \mathbf{have} \ ind \colon (\forall \ a. \ (\forall \ l \ l'. \ a \ @_{\mathit{graphI} \ I} \ l \ \land \ a \ @_{\mathit{graphI} \ I} \ l' \longrightarrow l = l') \land \\
             (\forall l. nodup \ a \ (agra \ (graphI \ I) \ l))) \ -
         (\forall \ a. \ (\forall \ l \ l'. \ a \ @_{graphI \ I'} \ l \ \land \ a' \ @_{graphI \ I'} \ l' \ \longrightarrow \ l = l') \ \land \\
             (\forall l. \ nodup \ a \ (agra \ (graphI \ I') \ \tilde{l})))
   proof (insert assms(1), erule rtrancl.induct)
     show \bigwedge a::infrastructure.
         (\forall aa::char\ list.
              (\forall (l::location) \ l'::location. \ aa \ @_{qraphI \ a} \ l \land \ aa \ @_{qraphI \ a} \ l' \longrightarrow l = l') \ \land \\
               (\forall l::location. \ nodup \ aa \ (agra \ (graphI \ a) \ l))) \longrightarrow
         (\forall aa::char\ list.
              (\forall (l::location) \ l'::location. \ aa @_{qraphI \ a} \ l \land aa @_{qraphI \ a} \ l' \longrightarrow l = l') \land l = l'
               (\forall l::location. \ nodup \ aa \ (agra \ (graphI \ a) \ l))) by simp
  next show \bigwedge (a::infrastructure) (b::infrastructure) (c::infrastructure).
         (a, b) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^* \Longrightarrow
         (\forall \ aa{::}char \ list.
               (\forall\,(l::location)\,\,(l'::location).\,\,(aa\,\,@_{qraphI\,\,a}\,\,l\,\wedge\,\,aa\,\,@_{qraphI\,\,a}\,\,l')\,\longrightarrow\,l=1
l') \wedge
               (\forall l::location. \ nodup \ aa \ (agra \ (graphI \ a) \ l))) \longrightarrow
         (\forall a :: char \ list.
             (\forall \, (l::location) \,\, (l'::location). \,\, (a \,\, @_{graphI \,\, b} \,\, l \,\, \wedge \,\, a \,\, @_{graphI \,\, b} \,\, l') \,\, \longrightarrow \,\, l \,= \, l') \,\, \wedge \,\,
              (\forall l::location. \ nodup \ a \ (agra \ (graphI \ b) \ l))) \Longrightarrow
         (b, c) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\} \Longrightarrow
         (\forall aa::char\ list.
              (\forall (l::location) \ l'::location. \ (aa @_{oranhI \ a} \ l \land aa @_{oranhI \ a} \ l') \longrightarrow l = l')
\land
               (\forall l::location. \ nodup \ aa \ (agra \ (graphI \ a) \ l))) \longrightarrow
```

```
(\forall a :: char \ list.
          (\forall (l::location) \ l'::location. \ (a @_{qraphI \ c} \ l \land a @_{qraphI \ c} \ l') \longrightarrow l = l') \land 
          (\forall l::location. nodup \ a \ (agra \ (graphI \ c) \ l)))
     by (rule impI, rule allI, rule actors-unique-loc-base, drule CollectD,
            simp,erule\ impE,\ assumption,\ erule\ spec)
  qed
  show ?thesis
  by (insert ind, insert assms(2), simp)
\mathbf{qed}
lemma actors-unique-loc-aid-base:
\forall \ a. \ (\forall \ l \ l'. \ a \ @_{graphI \ Airplane-not-in-danger-init} \ l \ \land
              a @_{graphI \ Airplane-not-in-danger-init} l' \longrightarrow l = l') \land
        (\forall l. nodup \ a (agra (graph I Airplane-not-in-danger-init) l))
proof (simp add: Airplane-not-in-danger-init-def ex-graph-def, clarify, rule conjI,
clarify,
     rule conjI, clarify, rule impI, (rule allI)+, rule impI, simp add: atI-def)
 show \bigwedge (l::location) l'::location.
      "Charly"
      \in set (if l = cockpit then ["Bob", "Charly"]
              else if l = door then [] else if <math>l = cabin then [''Alice''] else []) \land
       "Charly"
      \in set (if l' = cockpit then ["Bob", "Charly"]
              else if l' = door then [] else if l' = cabin then ["Alice"] else []) \Longrightarrow
  by (case-tac l = l', assumption, rule FalseE, case-tac l = cockpit \lor l = door \lor
l = cabin,
      erule disjE, simp, case-tac l' = door \lor l' = cabin, erule disjE, simp,
    simp add: cabin-def door-def, simp, erule disjE, simp add: door-def cockpit-def,
     simp add: cabin-def door-def cockpit-def, simp)
next show \bigwedge a :: char \ list.
       "Charly" \neq a \longrightarrow
      (\forall (l::location) \ l'::location.
       a @Lqraph {(cockpit, door), (door, cabin)}
                                                                     (\lambda x::location.
                                                                                                      if x = cockpit then ["Bob
       a <sup>©</sup>Lgraph {(cockpit, door), (door, cabin)}
                                                                                                      if x = cockpit then ["Bob
                                                                     (\lambda x::location.
          l = l'
 by (clarify, simp add: at I-def, case-tac l = l', assumption, rule False E,
     case-tac\ l = cockpit\ \lor\ l = door\ \lor\ l = cabin,\ erule\ disjE,\ simp,
    case-tac\ l'=door\lor l'=cabin,\ erule\ disjE,\ simp,\ simp\ add:\ cabin-def\ door-def,
     simp, erule disjE, simp add: door\text{-}def cockpit\text{-}def, case\text{-}tac l = cockpit,
      simp\ add: cabin-def\ cockpit-def\ , simp\ add: cabin-def\ door-def\ , \ case-tac\ l'=
cockpit,
       simp, simp add: cabin-def, case-tac l' = door, simp, simp add: cabin-def,
```

simp) **qed**

```
lemma actors-unique-loc-aid-step:
(Airplane-not-in-danger-init, I) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*
          \forall \ a. \ (\forall \ l \ l'. \ a \ @_{qraphI \ I} \ l \ \land \ a \ @_{qraphI \ I} \ l' \longrightarrow l = l') \land
         (\forall l. nodup \ a \ (agra \ (graphI \ I) \ l))
 by (erule actors-unique-loc-step, rule actors-unique-loc-aid-base)
\mathbf{lemma}\ Anid\text{-}airplane\text{-}actors:\ actors\text{-}graph\ (graphI\ Airplane\text{-}not\text{-}in\text{-}danger\text{-}init) =
airplane-actors
proof (simp add: Airplane-not-in-danger-init-def ex-graph-def actors-graph-def nodes-def
                 airplane-actors-def, rule\ equalityI)
  show \{x:: char\ list.
     \exists y :: location.
        (y = door \longrightarrow
         (door = cockpit \longrightarrow
           (\exists y::location.\ y = cockpit \lor y = cabin \lor y = cockpit \lor y = cockpit \land
cockpit = cabin) \wedge
          (x = "Bob" \lor x = "Charly")) \land
         door = cockpit) \land
        (y \neq door \longrightarrow
         (y = cockpit \longrightarrow
          (\exists y :: location.
              y = door \lor
               cockpit = door \land y = cabin \lor
              y = cockpit \land cockpit = door \lor y = door \land cockpit = cabin) \land
          (x = "Bob" \lor x = "Charly")) \land
         (y \neq cockpit \longrightarrow y = cabin \land x = "Alice" \land y = cabin))
    \subseteq \{"Bob", "Charly", "Alice"\}
  by (rule\ subset I,\ drule\ Collect D,\ erule\ ex E,\ (erule\ conj E)+,
      simp add: door-def cockpit-def cabin-def, (erule conjE)+, force)
next show {"Bob", "Charly", "Alice"}
    \subseteq \{x:: char \ list.
        \exists y :: location.
           (y = door \longrightarrow
            (door = cockpit \longrightarrow
                  y = cockpit \lor y = cabin \lor y = cockpit \lor y = cockpit \land cockpit =
cabin) \wedge
             (x = "Bob" \lor x = "Charly")) \land
            door = cockpit) \wedge
           (y \neq door \longrightarrow
            (y = cockpit \longrightarrow
             (\exists y :: location.
                 y = door \lor
                 cockpit = door \land y = cabin \lor
                 y = cockpit \land cockpit = door \lor y = door \land cockpit = cabin) \land
```

 $(x = "Bob" \lor x = "Charly")) \land$

```
(y \neq cockpit \longrightarrow y = cabin \land x = "Alice" \land y = cabin))
  by (rule subsetI, rule CollectI, simp add: door-def cockpit-def cabin-def,
     case-tac \ x = "Bob", force, case-tac \ x = "Charly", force,
     subgoal-tac \ x = "Alice", force, simp)
ged
lemma all-airplane-actors: (Airplane-not-in-danger-init, y) \in {(x::infrastructure,
y::infrastructure). \ x \rightarrow_n y
            \implies actors\text{-}graph(graphI\ y) = airplane\text{-}actors
 by (insert Anid-airplane-actors, erule subst, rule sym, erule same-actors)
lemma actors-at-loc-in-graph: [ <math>l \in nodes(graphI\ I); \ a @_{qraphI\ I} \ l ] ]
                            \implies a \in actors\text{-}graph\ (graphI\ I)
  by (simp add: atI-def actors-graph-def, rule exI, rule conjI)
lemma not-en-get-Aprid:
 assumes (Airplane-not-in-danger-init,y) \in \{(x::infrastructure, y::infrastructure).
x \to_n y\}^*
  shows \sim (enables y l (Actor a) get)
proof -
  have delta \ y = delta(Airplane-not-in-danger-init)
  by (insert assms, rule sym, erule-tac init-state-policy)
  with assms show ?thesis
  by (simp add: Airplane-not-in-danger-init-def enables-def local-policies-four-eyes-def)
qed
lemma Apnid-tsp-test: ~(enables Airplane-not-in-danger-init cockpit (Actor "Alice")
get
 by (simp add: Airplane-not-in-danger-init-def ex-creds-def enables-def
              local-policies-four-eyes-def cabin-def door-def cockpit-def
              ex-graph-def ex-locs-def)
lemma Apnid-tsp-test-gen: ~(enables Airplane-not-in-danger-init l (Actor a) get)
  by (simp add: Airplane-not-in-danger-init-def ex-creds-def enables-def
              local-policies-four-eyes-def cabin-def door-def cockpit-def
              ex-graph-def ex-locs-def)
\mathbf{lemma}\ \textit{test-graph-atI:}\ ''Bob'' @ \textit{graphI}\ \textit{Airplane-not-in-danger-init}\ \textit{cockpit}
  by (simp add: Airplane-not-in-danger-init-def ex-graph-def atI-def)
lemma two-person-inv:
 fixes z z'
  assumes (2::nat) \leq length (agra (graphI z) cockpit)
     and nodes(qraphI\ z) = nodes(qraphI\ Airplane-not-in-danger-init)
     and delta(z) = delta(Airplane-not-in-danger-init)
```

```
and (Airplane-not-in-danger-init,z) \in \{(x::infrastructure, y::infrastructure).
x \to_n y\}^*
      and z \to_n z'
    shows (2::nat) \leq length (agra (graphI z') cockpit)
proof (insert assms(5), erule state-transition-in.cases)
  show \bigwedge(G::igraph) (I::infrastructure) (a::char list) (l::location) (a'::char list)
(za::char\ list)
       I'::infrastructure.
       z = I \Longrightarrow
       z' = I' \Longrightarrow
       G = graphI \ I \Longrightarrow
       a @_G l \Longrightarrow
       a' @_G l \Longrightarrow
       has \ G \ (Actor \ a, \ za) \Longrightarrow
       enables I \ l \ (Actor \ a) \ get \Longrightarrow
       I' =
       Infrastructure
        (Lgraph (gra G) (agra G))
           ((cgra\ G)(Actor\ a'):=(za\ \#\ fst\ (cgra\ G\ (Actor\ a')),\ snd\ (cgra\ G\ (Actor\ a')))
a'))))) (lgra G))
        (delta\ I) \Longrightarrow
       (2::nat) \leq length (agra (graphI z') cockpit) using assms by simp
next show \bigwedge (G::igraph) (I::infrastructure) (a::char list) (l::location) (I'::infrastructure)
       za::char\ list.
       z = I \Longrightarrow
       z' = I' \Longrightarrow
       G = graphI I \Longrightarrow
       a @_G l \Longrightarrow
       enables I \ l \ (Actor \ a) \ put \Longrightarrow
       I' = Infrastructure \ (Lgraph \ (gra \ G) \ (agra \ G) \ (cgra \ G) \ ((lgra \ G)(l := [za])))
(delta\ I) \Longrightarrow
       (2::nat) \leq length (agra (graphI z') cockpit) using assms by simp
next show \bigwedge (G::igraph) (I::infrastructure) (l::location) (a::char list) (I'::infrastructure)
       za::char\ list.
       z = I \Longrightarrow
       z' = I' \Longrightarrow
       G = qraphI I \Longrightarrow
       enables I \ l \ (Actor \ a) \ put \Longrightarrow
       I' = Infrastructure (Lgraph (gra G) (agra G) (cgra G) ((lgra G)(l := [za])))
(delta\ I) \Longrightarrow
       (2::nat) \leq length (agra (graphI z') cockpit) using assms by simp
next show \bigwedge(G::igraph) (I::infrastructure) (a::char\ list) (l::location) (l'::location)
       I'::infrastructure.
       z = I \Longrightarrow
       z' = I' \Longrightarrow
       G = graphI I \Longrightarrow
       a @_G l \Longrightarrow
       l \in nodes \ G \Longrightarrow
       l' \in nodes \ G \Longrightarrow
```

```
a \in actors\text{-}graph\ (graphI\ I) \Longrightarrow
       enables I l' (Actor a) move \Longrightarrow
       I' = Infrastructure \ (move-graph-a \ a \ l \ l' \ (graphI \ I)) \ (delta \ I) \Longrightarrow
       (2::nat) \leq length (agra (graphI z') cockpit)
proof -
fix G :: igraph and I :: infrastructure and a :: char list and l :: location and l'
:: location \ \mathbf{and} \ I' :: infrastructure
 have f1: UasI "Eve" "Charly"
    using Eve-precipitating-event Insider-Eve Insider-def by force
  obtain ccs :: char \ list \Rightarrow char \ list and ccsa :: char \ list \Rightarrow char \ list where
   f2: \forall cs \ csa. \ (\neg \ UasI \ cs \ csa \lor Actor \ cs = Actor \ csa \land (\forall \ csa \ csb. \ (csa = cs \lor actor \ csa))
csb = cs \lor Actor \ csa \ne Actor \ csb) \lor csa = csb) \land (UasI \ cs \ csa \lor Actor \ cs \ne actor \ csb)
Actor\ csa\ \lor\ (ccs\ cs \neq cs\ \land\ ccsa\ cs \neq cs\ \land\ Actor\ (ccs\ cs) = Actor\ (ccsa\ cs))\ \land
ccs \ cs \neq ccsa \ cs)
   using UasI-def by moura
 \mathbf{have}\ ''Bob'' @_{graphI\ (Infrastructure\ ex\text{-}graph\ local\text{-}policies)}\ Location\ 2
   using Airplane-not-in-danger-init-def cockpit-def test-graph-at I by force
  then have Actor "Bob" = Actor "Eve"
  using Airplane-scenario-def airplane.cockpit-foe-control airplane-axioms cockpit-def
ex\hbox{-}inv3\ global\hbox{-}policy\hbox{-}def\ \mathbf{by}\ blast
  then show 2 \le length (agra (graphI z') cockpit)
    using f2 f1 by auto
\mathbf{qed}
qed
lemma two-person-inv1:
 assumes (Airplane-not-in-danger-init, z) \in {(x::infrastructure, y::infrastructure)}.
x \to_n y
 shows (2::nat) \leq length (agra (graphIz) cockpit)
proof (insert assms, erule rtrancl-induct)
 show (2::nat) \leq length (agra (graphI Airplane-not-in-danger-init) cockpit)
  by (simp add: Airplane-not-in-danger-init-def ex-graph-def)
next show \bigwedge(y::infrastructure) z::infrastructure.
        (Airplane-not-in-danger-init, y) \in \{(x::infrastructure, y::infrastructure). x\}
\rightarrow_n y}* \Longrightarrow
       (y, z) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\} \Longrightarrow
         (2::nat) \leq length (agra (graphI y) cockpit) \Longrightarrow (2::nat) \leq length (agra
(graphI\ z)\ cockpit)
   by (rule two-person-inv, assumption, rule same-nodes, assumption, rule sym,
        rule init-state-policy, assumption+, simp)
qed
lemma nodup-card-insert:
       a \notin set \ l \longrightarrow card \ (insert \ a \ (set \ l)) = Suc \ (card \ (set \ l))
by auto
lemma no-dup-set-list-num-eq[rule-format]:
```

```
(\forall a. nodup \ a \ l) \longrightarrow card \ (set \ l) = length \ l
  by (induct-tac l, simp, clarify, simp, erule impE, rule allI,
      drule-tac x = aa in spec, case-tac a = aa, simp, erule nodup-notin, simp)
lemma two-person-set-inv:
 assumes (Airplane-not-in-danger-init, z) \in {(x::infrastructure, y::infrastructure)}.
x \to_n y\}^*
   shows (2::nat) \leq card (set (agra (graphIz) cockpit))
proof -
  have a: card (set (agra (graphI z) cockpit)) = length(agra (graphI z) cockpit)
  by (rule no-dup-set-list-num-eq, insert assms, drule actors-unique-loc-aid-step,
       drule-tac x = a in spec, erule conjE, erule-tac x = cockpit in spec)
 show ?thesis
  by (insert a, erule ssubst, rule two-person-inv1, rule assms)
lemma Pred-all-unique: [?x. Px; (!x. Px \longrightarrow x = c)] \Longrightarrow Pc
  by (case-tac P c, assumption, erule exE, drule-tac x = x in spec,
      drule mp, assumption, erule subst)
lemma Set-all-unique: [S \neq \{\}; (\forall x \in S. x = c)] \implies c \in S
  by (rule-tac P = \lambda x. x \in S in Pred-all-unique, force, simp)
lemma airplane-actors-inv0[rule-format]:
   \forall z z'. (\forall h::char list \in set (agra (graphIz) cockpit). h \in airplane-actors) \land
          (Airplane-not-in-danger-init,z) \in \{(x::infrastructure, y::infrastructure).\ x
\rightarrow_n y\}^* \wedge
                 z \rightarrow_n z' \longrightarrow (\forall h :: char \ list \in set \ (agra \ (graphI \ z') \ cockpit). \ h \in
airplane-actors)
proof (clarify, erule state-transition-in.cases)
 show \bigwedge(z::infrastructure) (z'::infrastructure) (h::char list) (G::igraph) (I::infrastructure)
       (a::char list) (l::location) (a'::char list) (za::char list) I'::infrastructure.
       h \in set (agra (graphI z') cockpit) \Longrightarrow
      \forall h:: char \ list \in set \ (agra \ (graphI \ z) \ cockpit). \ h \in airplane-actors \Longrightarrow
        (Airplane-not-in-danger-init, z) \in \{(x::infrastructure, y::infrastructure). x\}
\rightarrow_n y}* \Longrightarrow
      z = I \Longrightarrow
       z' = I' \Longrightarrow
       G = \operatorname{graph} I \, I \Longrightarrow
       a @_G l \Longrightarrow
       a' @_{G} l \Longrightarrow
       has \ G \ (Actor \ a, \ za) \Longrightarrow
       enables I \ l \ (Actor \ a) \ get \Longrightarrow
       I' =
       In frastructure \\
       (Lgraph (gra G) (agra G)
          ((cgra\ G)(Actor\ a'):=(za\ \#\ fst\ (cgra\ G\ (Actor\ a')),\ snd\ (cgra\ G\ (Actor\ a')))
a'))))) (lgra G))
        (delta\ I) \Longrightarrow
```

```
h \in airplane-actors
    by simp
next show \bigwedge(z::infrastructure) (z'::infrastructure) (h::char\ list) (G::igraph) (I::infrastructure)
        (a::char\ list)\ (l::location)\ (I'::infrastructure)\ za::char\ list.
        h \in set (agra (graphI z') cockpit) \Longrightarrow
       \forall h:: char \ list \in set \ (agra \ (graphI \ z) \ cockpit). \ h \in airplane-actors \Longrightarrow
         (Airplane-not-in-danger-init, z) \in \{(x::infrastructure, y::infrastructure). x\}
\rightarrow_n y\}^* \Longrightarrow
       z = I \Longrightarrow
        z' = I' \Longrightarrow
        G = graphI \ I \Longrightarrow
        a @_G l \Longrightarrow
        enables I \ l \ (Actor \ a) \ put \Longrightarrow
       I' = Infrastructure (Lgraph (gra G) (agra G) (cgra G) ((lgra G)(l := [za])))
(delta\ I) \Longrightarrow
       h \in airplane-actors
    by simp
next show \bigwedge(z::infrastructure) (z'::infrastructure) (h::char \ list) (G::igraph) (I::infrastructure)
        (l::location) (a::char list) (I'::infrastructure) za::char list.
        h \in set (agra (graphI z') cockpit) \Longrightarrow
       \forall \, h {::} char \, \mathit{list} {\in} \mathit{set} \, \left( \mathit{agra} \, \left( \mathit{graphI} \, z \right) \, \mathit{cockpit} \right) . \, h \, \in \, \mathit{airplane-actors} \Longrightarrow
         (Airplane-not-in-danger-init, z) \in \{(x::infrastructure, y::infrastructure). x\}
\rightarrow_n y\}^* \Longrightarrow
       z = I \Longrightarrow
        z' = I' \Longrightarrow
        G = graphI I \Longrightarrow
        enables I \ l \ (Actor \ a) \ put \Longrightarrow
       I' = Infrastructure (Lgraph (gra G) (agra G) (cgra G) ((lgra G)(l := [za])))
(delta\ I) \Longrightarrow
       h \in airplane-actors
    by simp
next show \bigwedge(z::infrastructure) (z'::infrastructure) (h::char\ list) (G::igraph) (I::infrastructure)
        (a::char\ list)\ (l::location)\ (l'::location)\ I'::infrastructure.
        h \in set (agra (graphI z') cockpit) \Longrightarrow
       \forall h::char \ list \in set \ (agra \ (graphI \ z) \ cockpit). \ h \in airplane-actors \Longrightarrow
         (Airplane-not-in-danger-init, z) \in \{(x::infrastructure, y::infrastructure). x\}
\rightarrow_n y\}^* \Longrightarrow
       z = I \Longrightarrow
        z' = I' \Longrightarrow
        G = graphI I \Longrightarrow
        a @_G l \Longrightarrow
        l \in nodes G \Longrightarrow
        l' \in nodes \ G \Longrightarrow
        a \in actors\text{-}graph\ (graphI\ I) \Longrightarrow
        enables I l' (Actor a) move \Longrightarrow
           I' = Infrastructure \ (move-graph-a \ a \ l \ l' \ (graphI \ I)) \ (delta \ I) \implies h \in
airplane-actors
  proof (simp add: move-graph-a-def,
          case\text{-}tac \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l'))
```

```
show \bigwedge(z::infrastructure) (z'::infrastructure) (h::char\ list) (G::igraph) (I::infrastructure)
        (a::char\ list)\ (l::location)\ (l'::location)\ I'::infrastructure.
        h \in set \ ((if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
                     then (agra (graphI I))
                          (l := del \ a \ (agra \ (graphI \ I) \ l), \ l' := a \# agra \ (graphI \ I) \ l')
                     else \ agra \ (graphI \ I))
                     cockpit) \Longrightarrow
        \forall h::char \ list \in set \ (agra \ (graphI \ I) \ cockpit). \ h \in airplane-actors \Longrightarrow
         (Airplane-not-in-danger-init, I) \in \{(x::infrastructure, y::infrastructure). x\}
\rightarrow_n y\}^* \Longrightarrow
       z = I \Longrightarrow
        z' =
        Infrastructure
         (Lgraph (gra (graphI I)))
           (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
               then (agra (graphI I))(l := del \ a (agra (graphI I) \ l), \ l' := a \# agra
(graphI\ I)\ l')
            else \ agra \ (graphI \ I))
           (cgra (graphI I)) (lgra (graphI I)))
         (delta\ I) \Longrightarrow
        G = graphI I \Longrightarrow
        a @_{graphI \ I} l \Longrightarrow
        l \in \stackrel{\cdot}{nodes} (graphI \ I) \Longrightarrow
        l' \in nodes (graphI I) \Longrightarrow
        a \in actors\text{-}graph\ (graphI\ I) \Longrightarrow
        enables I l' (Actor a) move \Longrightarrow
        I' =
        Infrastructure
         (Lgraph (gra (graphI I)))
           (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
               then (agra (graphI I))(l := del \ a \ (agra (graphI I) \ l), \ l' := a \ \# \ agra
(graphI\ I)\ l')
            else agra (graphI I))
           (cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))
         (delta\ I) \Longrightarrow
          \neg (a \in set (agra (graphI \ I) \ l) \land a \notin set (agra (graphI \ I) \ l')) \Longrightarrow h \in
airplane\text{-}actors
       by simp
   next show \bigwedge(z::infrastructure) (z'::infrastructure) (h::char list) (G::igraph)
(I::infrastructure)
        (a::char\ list)\ (l::location)\ (l'::location)\ I'::infrastructure.
        h \in set \ ((if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
                     then (agra (graphI I))
                          (\mathit{l} := \mathit{del} \ \mathit{a} \ (\mathit{agra} \ (\mathit{graphI} \ \mathit{I}) \ \mathit{l}), \ \mathit{l}' := \mathit{a} \ \# \ \mathit{agra} \ (\mathit{graphI} \ \mathit{I}) \ \mathit{l}')
                     else \ agra \ (graphI \ I))
                     cockpit) \Longrightarrow
       \forall h::char \ list \in set \ (agra \ (graphI \ I) \ cockpit). \ h \in airplane-actors \Longrightarrow
         (Airplane-not-in-danger-init, I) \in \{(x::infrastructure, y::infrastructure). x\}
\rightarrow_n y}* \Longrightarrow
```

```
z = I \Longrightarrow
       z' =
       In frastructure \\
        (Lgraph (gra (graphI I)))
           (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
              then (agra (graphI I))(l := del \ a \ (agra (graphI I) \ l), \ l' := a \ \# \ agra
(graphI\ I)\ l')
            else \ agra \ (graphI \ I))
           (cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))
         (delta\ I) \Longrightarrow
       G = graphI I \Longrightarrow
       a @_{qraphI \ I} l \Longrightarrow
       l \in nodes (graphI I) \Longrightarrow
       l' \in nodes (graphI I) \Longrightarrow
       a \in actors-graph (graphII) \Longrightarrow
       enables I l' (Actor a) move \Longrightarrow
       I' =
       Infrastructure
        (Lgraph (gra (graphI I)))
           (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
              then (agra (graphI I))(l := del \ a (agra (graphI I) \ l), \ l' := a \# agra
(graphI\ I)\ l')
            else agra (graphI I))
           (cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))
         (delta\ I) \Longrightarrow
           a \in \mathit{set} \ (\mathit{agra} \ (\mathit{graphI}\ I)\ l) \ \land \ a \not \in \mathit{set} \ (\mathit{agra} \ (\mathit{graphI}\ I)\ l') \Longrightarrow h \in
airplane-actors
    proof (case-tac\ l' = cockpit)
    show \bigwedge(z::infrastructure) (z'::infrastructure) (h::char\ list) (G::igraph) (I::infrastructure)
       (a::char\ list)\ (l::location)\ (l'::location)\ I'::infrastructure.
       h \in set \ ((if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
                    then (agra (graphI I))
                         (l := del \ a \ (agra \ (graphI \ I) \ l), \ l' := a \# agra \ (graphI \ I) \ l')
                    else agra (graphI I))
                    cockpit) \Longrightarrow
       \forall h::char \ list \in set \ (agra \ (graphI\ I) \ cockpit). \ h \in airplane-actors \Longrightarrow
         (Airplane-not-in-danger-init, I) \in \{(x::infrastructure, y::infrastructure). x\}
\rightarrow_n y\}^* \Longrightarrow
       z = I \Longrightarrow
       z' =
       In frastructure \\
        (Lgraph (gra (graphI I)))
           (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
              then (agra\ (graphI\ I))(l:=del\ a\ (agra\ (graphI\ I)\ l),\ l':=a\ \#\ agra
(graphI\ I)\ l')
            else agra (graphII))
           (cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))
         (delta\ I) \Longrightarrow
       G = graphI I \Longrightarrow
```

```
a @_{graphI\ I} l \Longrightarrow
       l \in nodes (graphI I) \Longrightarrow
       l' \in nodes (qraphI I) \Longrightarrow
       a \in actors-graph (graphII) \Longrightarrow
       enables I l' (Actor a) move \Longrightarrow
       I' =
       Infrastructure
        (Lgraph (gra (graphI I)))
           (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
              then (agra (graphI I))(l := del \ a (agra (graphI I) \ l), \ l' := a \# agra
(graphI\ I)\ l')
            else agra (graphI I))
           (cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))
         (delta\ I) \Longrightarrow
       a \in set (agra (graphI I) l) \land a \notin set (agra (graphI I) l') \Longrightarrow
       l' \neq cockpit \Longrightarrow h \in airplane\text{-}actors
      \mathbf{proof}\ (\mathit{case-tac}\ \mathit{cockpit}\ =\ l)
            show \bigwedge(z::infrastructure) (z'::infrastructure) (h::char\ list) (G::igraph)
(I::infrastructure)
       (a::char\ list)\ (l::location)\ (l'::location)\ I'::infrastructure.
       h \in set \ ((if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
                    then (agra (graphI I))
                         (l := del \ a \ (agra \ (graphI \ I) \ l), \ l' := a \ \# \ agra \ (graphI \ I) \ l')
                    else \ agra \ (graphI \ I))
                    cockpit) \Longrightarrow
       \forall h:: char \ list \in set \ (agra \ (graphI \ I) \ cockpit). \ h \in airplane-actors \Longrightarrow
         (Airplane-not-in-danger-init, I) \in \{(x::infrastructure, y::infrastructure). x\}
\rightarrow_n y}* \Longrightarrow
       z = I \Longrightarrow
       z' =
       Infrastructure
        (Lgraph (gra (graphI I)))
           (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
              then (agra (graphI I))(l := del \ a \ (agra (graphI I) \ l), \ l' := a \ \# \ agra
(graphI\ I)\ l')
            else \ agra \ (graphI \ I))
           (cgra (graphI I)) (lgra (graphI I)))
         (delta\ I) \Longrightarrow
       G = graphI I \Longrightarrow
       a @_{qraphI \ I} l \Longrightarrow
       l \in nodes (graphI I) \Longrightarrow
       l' \in nodes (graphI \ I) \Longrightarrow
       a \in actors\text{-}graph\ (graphI\ I) \Longrightarrow
       enables I l' (Actor a) move \Longrightarrow
       I' =
       Infrastructure
        (Lgraph (gra (graphI I)))
           (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
              then (agra (graphI I))(l := del \ a (agra (graphI I) \ l), \ l' := a \# agra
```

```
(graphI\ I)\ l')
           else agra (graphI I))
           (cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))
        (delta\ I) \Longrightarrow
       a \in set (agra (graphI I) l) \land a \notin set (agra (graphI I) l') \Longrightarrow
       l' \neq cockpit \implies cockpit \neq l \implies h \in airplane-actors
          by simp
      next show \bigwedge(z::infrastructure) (z'::infrastructure) (h::char\ list) (G::igraph)
(I::infrastructure)
       (a::char\ list)\ (l::location)\ (l'::location)\ I'::infrastructure.
       h \in set \ ((if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
                   then (agra (graphI I))
                        (l := del \ a \ (agra \ (graphI \ I) \ l), \ l' := a \# agra \ (graphI \ I) \ l')
                   else \ agra \ (graphI \ I))
                   cockpit) \Longrightarrow
       \forall h::char \ list \in set \ (agra \ (graphI\ I) \ cockpit). \ h \in airplane-actors \Longrightarrow
         (Airplane-not-in-danger-init, I) \in \{(x::infrastructure, y::infrastructure). x\}
\rightarrow_n y}* \Longrightarrow
       z = I \Longrightarrow
       z' =
       Infrastructure
        (Lgraph (gra (graphI I)))
          (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
              then (agra (graphI I))(l := del \ a \ (agra (graphI I) \ l), \ l' := a \ \# \ agra
(graphI\ I)\ l')
           else \ agra \ (graphI \ I))
          (cgra (graphI I)) (lgra (graphI I)))
        (delta\ I) \Longrightarrow
       G = graphI I \Longrightarrow
       a @_{qraphI\ I} l \Longrightarrow
       l \in nodes (graphI I) \Longrightarrow
       l' \in nodes (graphI \ I) \Longrightarrow
       a \in actors\text{-}graph\ (graphI\ I) \Longrightarrow
       enables I l' (Actor a) move \Longrightarrow
       I' =
       Infrastructure
        (Lgraph (gra (graphI I)))
          (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
              then (agra (graphI I))(l := del \ a (agra (graphI I) \ l), \ l' := a \# agra
(graphI\ I)\ l')
           else \ agra \ (graphI \ I))
          (cgra (graphI I)) (lgra (graphI I)))
        (delta\ I) \Longrightarrow
       a \in set (agra (graphI \ l) \land a \notin set (agra (graphI \ l') \Longrightarrow
       l' \neq cockpit \Longrightarrow cockpit = l \Longrightarrow h \in airplane-actors
          by (simp, erule bspec, erule del-up)
      ged
     next show \bigwedge(z::infrastructure) (z'::infrastructure) (h::char\ list) (G::igraph)
(I::infrastructure)
```

```
(a::char\ list)\ (l::location)\ (l'::location)\ I'::infrastructure.
       h \in set \ ((if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
                    then (agra (graphI I))
                         (l := del \ a \ (agra \ (graphI \ I) \ l), \ l' := a \# agra \ (graphI \ I) \ l')
                    else \ agra \ (graphI \ I))
                    cockpit) \Longrightarrow
       \forall h::char \ list \in set \ (agra \ (graphI\ I) \ cockpit). \ h \in airplane-actors \Longrightarrow
         (Airplane-not-in-danger-init, I) \in \{(x::infrastructure, y::infrastructure). x\}
\rightarrow_n y}* \Longrightarrow
       z = I \Longrightarrow
       z' =
       Infrastructure
        (Lgraph\ (gra\ (graphI\ I))
           (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
               then (agra (graphI I))(l := del \ a (agra (graphI I) \ l), \ l' := a \# agra
(graphI\ I)\ l')
            else \ agra \ (graphI \ I))
           (cgra (graphI I)) (lgra (graphI I)))
         (delta\ I) \Longrightarrow
       G = graphI I \Longrightarrow
       a @_{qraphI \ I} l \Longrightarrow
       l \in nodes (graphI I) \Longrightarrow
       l' \in nodes (graphI I) \Longrightarrow
       a \in actors\text{-}graph\ (graphI\ I) \Longrightarrow
       enables I l' (Actor a) move \Longrightarrow
       I' =
       Infrastructure
        (Lgraph (gra (graphI I)))
           (if \ a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ l')
               then (agra (graphI I))(l := del \ a (agra (graphI I) \ l), \ l' := a \# agra
(graphI\ I)\ l')
            else \ agra \ (graphI \ I))
           (cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))
        (delta\ I) \Longrightarrow
       a \in \mathit{set} \ (\mathit{agra} \ (\mathit{graphI}\ I)\ l) \ \land \ a \notin \mathit{set} \ (\mathit{agra} \ (\mathit{graphI}\ I)\ l') \Longrightarrow
       l' = cockpit \Longrightarrow h \in airplane\text{-}actors
      proof (simp, erule \ disjE)
            show \bigwedge(z::infrastructure) (z'::infrastructure) (h::char\ list) (G::igraph)
(I::infrastructure)
       (a::char\ list)\ (l::location)\ (l'::location)\ I'::infrastructure.
       \forall h::char \ list \in set \ (agra \ (graphI \ I) \ cockpit). \ h \in airplane-actors \Longrightarrow
         (Airplane-not-in-danger-init, I) \in \{(x::infrastructure, y::infrastructure). x\}
\rightarrow_n y}* \Longrightarrow
       z = I \Longrightarrow
       z' =
       Infrastructure
        (Lgraph (gra (graphI I)))
           ((agra (graphI I))
            (l := del\ a\ (agra\ (graphI\ I)\ l),\ cockpit := a\ \#\ agra\ (graphI\ I)\ cockpit))
```

```
(cgra (graphI I)) (lgra (graphI I)))
        (delta\ I) \Longrightarrow
       G = graphI I \Longrightarrow
       a @_{qraphI\ I} l \Longrightarrow
       l \in nodes (graphI I) \Longrightarrow
       cockpit \in nodes (graphI I) \Longrightarrow
       a \in actors\text{-}graph (graphI I) \Longrightarrow
       enables I \ cockpit \ (Actor \ a) \ move \Longrightarrow
       I' =
       Infrastructure
       (Lgraph (gra (graphI I)))
         ((agra (graphI I))
          (l := del \ a \ (agra \ (graphI \ I) \ l), \ cockpit := a \ \# \ agra \ (graphI \ I) \ cockpit))
         (cgra (graphI I)) (lgra (graphI I)))
        (delta\ I) \Longrightarrow
       a \in set \ (agra \ (graphI \ I) \ l) \land a \notin set \ (agra \ (graphI \ I) \ cockpit) \Longrightarrow
       l' = cockpit \Longrightarrow h \in set (agra (graphI I) cockpit) \Longrightarrow h \in airplane-actors
         by (erule bspec)
      next fix z z' h G I a l l' I'
       assume a\theta: \forall h::char \ list \in set \ (agra \ (graphI\ I) \ cockpit). \ h \in airplane-actors
    and a1: (Airplane-not-in-danger-init, I) \in \{(x::infrastructure, y::infrastructure)\}
x \to_n y\}^*
     and a2: z = I
     and a3: z' =
      Infrastructure
       (Lgraph (gra (graphI I)))
         ((agra (graphI I))
          (l := del\ a\ (agra\ (graphI\ I)\ l),\ cockpit := a\ \#\ agra\ (graphI\ I)\ cockpit))
         (cgra (graphI I)) (lgra (graphI I)))
        (delta\ I)
      and a \not= G = graphII
      and a5: a @_{graphI \ I} l
      and a6: l \in nodes (graphI I)
      and a7: cockpit \in nodes (graphI I)
      and a8: a \in actors\text{-}graph (graphI I)
      and a9: enables I cockpit (Actor a) move
      and a10: I' =
      Infrastructure
       (Lgraph (gra (graphI I)))
         ((agra (graphI I))
          (l := del\ a\ (agra\ (graphI\ I)\ l),\ cockpit := a\ \#\ agra\ (graphI\ I)\ cockpit))
         (cgra\ (graphI\ I))\ (lgra\ (graphI\ I)))
        (delta\ I)
       and a11: a \in set (agra (graphI I) l) \land a \notin set (agra (graphI I) cockpit)
       and a12: l' = cockpit
       and a13: h = a
       show h \in airplane-actors
       proof -
       have a: delta(I) = delta(Airplane-not-in-danger-init)
```

```
by (rule sym, rule init-state-policy, rule a1)
      show ?thesis
        by (insert a0 a1 a2 a3 a4 a5 a6 a7 a8 a9 a10 a11 a12 a13 a,
         simp add: enables-def, erule bexE, simp add: Airplane-not-in-danger-init-def,
            unfold local-policies-four-eyes-def, simp, erule disjE, simp+,
            erule\ exE,\ (erule\ conjE)+,
            fold local-policies-four-eyes-def Airplane-not-in-danger-init-def,
            drule all-airplane-actors, erule subst)
    qed
  qed
qed
qed
qed
lemma airplane-actors-inv:
 assumes (Airplane-not-in-danger-init,z) \in \{(x::infrastructure, y::infrastructure).
   shows \forall h :: char \ list \in set \ (agra \ (graphI \ z) \ cockpit). \ h \in airplane-actors
proof -
 have ind: (Airplane-not-in-danger-init, z) \in \{(x::infrastructure, y::infrastructure).
x \to_n y \}^* \longrightarrow
    (\forall h :: char \ list \in set \ (agra \ (graphI \ z) \ cockpit). \ h \in airplane-actors)
  proof (insert assms, erule rtrancl-induct)
     show (Airplane-not-in-danger-init, Airplane-not-in-danger-init) \in \{(x,y), x\}
\rightarrow_n y}* \longrightarrow
     (\forall h::char \ list \in set \ (agra \ (graphI \ Airplane-not-in-danger-init) \ cockpit). \ h \in
airplane-actors)
    by (rule impI, rule ballI,
         simp add: Airplane-not-in-danger-init-def ex-graph-def airplane-actors-def
ex-locs-def,
        blast)
   next show \bigwedge(y::infrastructure) z::infrastructure.
        (Airplane-not-in-danger-init, y) \in \{(x::infrastructure, y::infrastructure). x\}
\rightarrow_n y}* \Longrightarrow
      (y, z) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\} \Longrightarrow
      (Airplane-not-in-danger-init, y) \in \{(x,y). x \rightarrow_n y\}^* \longrightarrow
      (\forall h :: char \ list \in set \ (agra \ (graphI \ y) \ cockpit). \ h \in airplane-actors) \Longrightarrow
      (Airplane-not-in-danger-init, z) \in \{(x,y). \ x \to_n y\}^* \longrightarrow
      (\forall h::char \ list \in set \ (agra \ (graphI \ z) \ cockpit). \ h \in airplane-actors)
   by (rule impI, rule ballI, rule-tac z = y in airplane-actors-inv0,
       rule conjI, erule impE, assumption+, simp)
  qed
  show ?thesis
  by (insert ind, insert assms, simp)
lemma Eve-not-in-cockpit: (Airplane-not-in-danger-init, I)
```

```
\in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^* \Longrightarrow
      x \in set (agra (graphI I) cockpit) \Longrightarrow x \neq "Eve"
by (drule airplane-actors-inv, simp add: airplane-actors-def,
    drule-tac x = x in bspec, assumption, force)
lemma tp-imp-control:
 assumes (Airplane-not-in-danger-init, I) \in {(x::infrastructure, y::infrastructure)}.
x \to_n y\}^*
 shows (? x :: identity. x @_{qraphI\ I} cockpit \land Actor\ x \neq Actor\ "Eve")
proof -
 have a\theta: (2::nat) \leq card (set (agra (graphI I) cockpit))
   by (insert assms, erule two-person-set-inv)
 have a1: is-singleton({"Charly"})
   by (rule is-singletonI)
  have a6: \neg(\forall x \in set(aqra (qraphI I) cockpit). (Actor x = Actor "Eve"))
   proof (rule notI)
      assume a7: \forall x :: char \ list \in set \ (agra \ (graphI \ I) \ cockpit). \ Actor \ x = Actor
"Eve"
     have a5: \forall x :: char \ list \in set \ (agra \ (graphI \ I) \ cockpit). \ x = "Charly"
       by (insert assms a0 a7, rule ball, drule-tac x = x in bspec, assumption,
         subgoal-tac x \neq "Eve", insert Insider-Eve, unfold Insider-def, (drule mp),
         rule Eve-precipitating-event, simp add: UasI-def, erule Eve-not-in-cockpit)
     have a4: set (agra (graphI I) cockpit) = {"Charly"}
       by (rule equalityI, rule subsetI, insert a5, simp,
          rule subsetI, simp, rule Set-all-unique, insert a0, force, rule a5)
     have a2: (card((set (agra (graphI I) cockpit)) :: char list set)) = (1 :: nat)
      by (insert a1, unfold is-singleton-altdef, erule ssubst, insert a4, erule ssubst,
           fold is-singleton-altdef, rule a1)
     have a3: (2 :: nat) \leq (1 :: nat)
        by (insert a0, insert a2, erule subst, assumption)
     show False
       by (insert a5 a4 a3 a2, arith)
 show ?thesis by (insert assms a0 a6, simp add: atI-def, blast)
qed
lemma Fend-2: (Airplane-not-in-danger-init, I) \in \{(x::infrastructure, y::infrastructure).
x \to_n y\}^* \Longrightarrow
        ¬ enables I cockpit (Actor "Eve") put
 by (insert cockpit-foe-control, simp add: foe-control-def, drule-tac x = I in spec,
     erule mp, erule tp-imp-control)
theorem Four-eyes-no-danger: Air-tp-Kripke \vdash AG (\{x.\ global\text{-policy}\ x\ ''Eve''\})
proof (simp add: Air-tp-Kripke-def check-def, rule conjI)
 show Airplane-not-in-danger-init \in Air-tp-states
   by (simp add: Airplane-not-in-danger-init-def Air-tp-states-def
```

```
state-transition-in-refl-def)
next show Airplane-not-in-danger-init \in AG \{x::infrastructure.\ global-policy\ x
"Eve"}
  proof (unfold AG-def, simp add: gfp-def,
   rule-tac \ x = \{(x :: infrastructure) \in states \ Air-tp-Kripke. \ ^{("Eve")} @_{araphI \ x} \}
cockpit)} in exI,
   rule\ conjI)
    show \{x::infrastructure \in states \ Air-tp-Kripke. \neg "Eve" @_{oranhI \ x} \ cockpit \}
    \subseteq \{x::infrastructure. global-policy x "Eve"\}
     by (unfold global-policy-def, simp add: airplane-actors-def, rule subsetI,
         drule CollectD, rule CollectI, erule conjE,
         simp add: Air-tp-Kripke-def Air-tp-states-def state-transition-in-refl-def,
         erule Fend-2)
 next show \{x::infrastructure \in states \ Air-tp-Kripke. \neg "Eve" @ araphI x cockpit \}
    \subseteq AX \{x::infrastructure \in states \ Air-tp-Kripke. \ \neg "Eve" @_{araphI \ x} \ cockpit \} \land
    Airplane-not-in-danger-init
    \in \{x:: infrastructure \in states \ Air-tp-Kripke. \ \neg \ ''Eve'' @_{graphI \ x} \ cockpit \}
   proof
     show Airplane-not-in-danger-init
          \in \{x::infrastructure \in states \ Air-tp-Kripke. \ \neg \ "Eve" @_{qraphI} \ x \ cockpit \}
    by (simp add: Airplane-not-in-danger-init-def Air-tp-Kripke-def Air-tp-states-def
                    state-transition-refl-def ex-graph-def atI-def Air-tp-Kripke-def
                    state-transition-in-refl-def)
 next show \{x::infrastructure \in states \ Air-tp-Kripke. \neg "Eve" @ _{araphI \ x} \ cockpit \}
    \subseteq AX \ \{x::infrastructure \in states \ Air-tp-Kripke. \ \neg \ "Eve" @_{qraphI} \ x \ cockpit \}
    proof (rule subsetI, simp add: AX-def, rule subsetI, rule CollectI, rule conjI)
      show \bigwedge(x::infrastructure) xa::infrastructure.
       x \in states \ Air-tp-Kripke \land \neg "Eve" @_{qraphI \ x} \ cockpit \Longrightarrow
       xa \in Collect \ (state-transition \ x) \Longrightarrow xa \in states \ Air-tp-Kripke
      by (simp add: Air-tp-Kripke-def Air-tp-states-def state-transition-in-refl-def,
            simp\ add: atI-def, erule\ conjE,
            unfold state-transition-infra-def state-transition-in-refl-def,
            erule rtrancl-into-rtrancl, rule CollectI, simp)
    \mathbf{next} fix x xa
        assume a\theta: x \in states \ Air-tp-Kripke \land \neg "Eve" @_{graphI \ x} \ cockpit
         and a1: xa \in Collect (state-transition x)
        show ¬ "Eve" @ graphI xa cockpit
      proof -
        have b: (Airplane-not-in-danger-init, xa)
       \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*
        proof (insert a0 a1, rule rtrancl-trans)
          \mathbf{show}\ x \in \mathit{states}\ \mathit{Air-tp-Kripke}\ \land \ \neg\ ''\mathit{Eve''}\ @_{\mathit{qraphI}\ x}\ \mathit{cockpit} \Longrightarrow
                xa \in Collect (state-transition x) \Longrightarrow
                (x, xa) \in \{(x::infrastructure, y::infrastructure). x \rightarrow_n y\}^*
            by (unfold\ state-transition-infra-def,\ force)
        \mathbf{next} \ \mathbf{show} \ x \in \mathit{states} \ \mathit{Air-tp-Kripke} \ \land \ \neg \ ''\mathit{Eve''} \ @_{\mathit{qraphI} \ x} \ \mathit{cockpit} \Longrightarrow
                  xa \in Collect (state-transition x) \Longrightarrow
             (Airplane-not-in-danger-init, x) \in \{(x::infrastructure, y::infrastructure).
```

```
x \to_n y\}^*
       by (erule conjE, simp add: Air-tp-Kripke-def Air-tp-states-def state-transition-in-refl-def)+
       qed
       show ?thesis
        by (insert a0 a1 b, rule-tac P= "Eve" @_{qraphI\ xa}\ cockpit in notI,
           simp add: atI-def, drule Eve-not-in-cockpit, assumption, simp)
    qed
  qed
qed
qed
qed
end
definition airplane-actors-def': airplane-actors \equiv \{"Bob", "Charly", "Alice"\}
definition airplane-locations-def':
airplane-locations \equiv \{Location 0, Location 1, Location 2\}
definition cockpit\text{-}def': cockpit \equiv Location 2
definition door\text{-}def': door \equiv Location 1
definition cabin-def': cabin \equiv Location 0
definition global-policy-def': global-policy I \ a \equiv a \notin airplane-actors
                \longrightarrow \neg (enables\ I\ cockpit\ (Actor\ a)\ put)
definition ex-creds-def': ex-creds \equiv
       (\lambda \ x.(if \ x = Actor \ ''Bob'')
             then (["PIN"], ["pilot"])
             else (if x = Actor "Charly"
                  then (["PIN"],["copilot"])
                  else (if x = Actor "Alice"
                        then (["PIN"],["flightattendant"])
                             else ([],[]))))
definition ex-locs-def': ex-locs \equiv (\lambda x. if x = door then ["norm"] else
                                    (if \ x = cockpit \ then \ ["air"] \ else \ []))
definition ex-locs'-def': ex-locs' \equiv (\lambda x. if x = door then ["locked"] else
                                      (if x = cockpit then ["air" else []))
definition ex-graph-def': ex-graph \equiv Lgraph
     \{(cockpit, door), (door, cabin)\}
     (\lambda \ x. \ if \ x = cockpit \ then \ ["Bob", "Charly"]
           else (if x = door then []
                 else (if x = cabin then ["Alice"] else [])))
     ex	ext{-}creds \ ex	ext{-}locs
definition aid-graph-def': aid-graph \equiv Lgraph
     \{(cockpit, door), (door, cabin)\}
     (\lambda \ x. \ if \ x = cockpit \ then \ ["Charly"]
```

```
else (if x = door then []
                  else (if x = cabin then ["Bob", "Alice"] else [])))
      ex-creds ex-locs'
definition aid-graph0-def': aid-graph0 \equiv Lgraph
      \{(cockpit, door), (door, cabin)\}
      (\lambda \ x. \ if \ x = cockpit \ then \ ["Charly"]
            else (if x = door then ["Bob"]
                  else (if x = cabin then ["Alice"] else [])))
        ex-creds ex-locs
definition agid-graph-def': agid-graph \equiv Lgraph
      \{(cockpit, door), (door, cabin)\}
      (\lambda \ x. \ if \ x = cockpit \ then \ ["Charly"]
            else (if x = door then []
                  else (if x = cabin then ["Bob", "Alice"] else [])))
      ex-creds ex-locs
definition local-policies-def': local-policies G \equiv
   (\lambda y. if y = cockpit then
             \{(\lambda \ x. \ (? \ n. \ (n \ @_G \ cockpit) \land Actor \ n = x), \{put\}),\
              (\lambda \ x. \ (? \ n. \ (n \ @_G \ cabin) \land Actor \ n = x \land has \ G \ (x, "PIN")
                   \land isin G door "norm", {move})
        else (if y = door then \{(\lambda x. True, \{move\}),
                      (\lambda \ x. \ (? \ n. \ (n \ @_G \ cockpit) \land Actor \ n = x), \{put\})\}
               else (if y = cabin then \{(\lambda x. True, \{move\})\}\
                    else~\{\})))
definition local-policies-four-eyes-def': local-policies-four-eyes G \equiv
   (\lambda y. if y = cockpit then
             \{(\lambda x. \ (? n. \ (n @_G \ cockpit) \land Actor \ n = x) \land \}
                  2 \leq length(agra\ G\ y) \land (\forall\ h \in set(agra\ G\ y).\ h \in airplane-actors),
\{put\}),
              (\lambda x. (? n. (n @ G cabin) \lambda Actor n = x \lambda has G (x, "PIN") \lambda
                          isin \ G \ door \ "norm"), \{move\})
         else (if y = door then
               \{(\lambda \ x. \ ((? \ n. \ (n \ @_G \ cockpit) \land Actor \ n = x) \land 3 \leq length(agra \ G
cockpit), \{move\})
               else\ (if\ y=cabin\ then
                    \{(\lambda \ x. \ ((? \ n. \ (n \ @_G \ door) \land Actor \ n = x)), \ \{move\})\}
                           else {})))
definition Airplane-scenario-def':
Airplane-scenario \equiv Infrastructure ex-graph local-policies
definition Airplane-in-danger-def':
Airplane-in-danger \equiv Infrastructure \ aid-graph \ local-policies
```

```
definition Airplane-getting-in-danger0-def':
Airplane-getting-in-danger0 \equiv Infrastructure \ aid-graph0 \ local-policies
definition Airplane-getting-in-danger-def':
Airplane-getting-in-danger \equiv Infrastructure agid-graph local-policies
definition Air-states-def': Air-states \equiv \{ I. Airplane-scenario \rightarrow_n * I \}
definition Air-Kripke-def': Air-Kripke \equiv Kripke Air-states {Airplane-scenario}
definition Airplane-not-in-danger-def':
Airplane-not-in-danger \equiv Infrastructure \ aid-graph \ local-policies-four-eyes
\mathbf{definition}\ \mathit{Airplane-not-in-danger-init-def'}:
Airplane-not-in-danger-init \equiv Infrastructure \ ex-graph \ local-policies-four-eyes
definition Air-tp-states-def': Air-tp-states \equiv \{ I. Airplane-not-in-danger-init \rightarrow_n * \}
I
definition Air-tp-Kripke-def':
Air-tp-Kripke \equiv Kripke \ Air-tp-states \ \{Airplane-not-in-danger-init\}
definition Safety-def': Safety I \ a \equiv a \in airplane\text{-}actors
                     \longrightarrow (enables I cockpit (Actor a) move)
definition Security-def': Security I a \equiv (isin (graphI I) door "locked")
                      \longrightarrow \neg (enables\ I\ cockpit\ (Actor\ a)\ move)
definition foe-control-def': foe-control l c \equiv
  (! I:: infrastructure. (? x :: identity.
       x @_{graphI\ I} l \land Actor\ x \neq Actor\ ''Eve''
            \longrightarrow \neg (enables\ I\ l\ (Actor\ ''Eve'')\ c))
definition astate-def': astate x \equiv
         (case x of
          "Eve" \Rightarrow Actor-state depressed {revenge, peer-recognition}
         | - \Rightarrow Actor-state\ happy\ \{\})
print-interps airplane
axiomatization where
cockpit-foe-control': foe-control cockpit put
definition Actor-Abs :: identity \Rightarrow identity option
```

where

```
Actor-Abs x \equiv (if \ x \in \{"Eve", "Charly"\} \ then \ None \ else \ Some \ x)
lemma UasI-ActorAbs: Actor-Abs "Eve" = Actor-Abs "Charly" \land
  (\forall (x::char\ list)\ y::char\ list.\ x \neq "Eve" \land y \neq "Eve" \land Actor-Abs\ x = Actor-Abs
y \longrightarrow x = y
 by (simp add: Actor-Abs-def)
lemma Actor-Abs-ran: Actor-Abs x \in \{y :: identity \ option. \ y \in Some \ ` \{x :: identity \ option \ \} \}
identity. x \notin \{"Eve", "Charly"\}\} | y = None\}
 by (simp add: Actor-Abs-def)
axiomatization where Actor-type-def:
type-definition (Rep :: actor \Rightarrow identity option)(Abs :: identity option <math>\Rightarrow actor)
\{y :: identity \ option. \ y \in Some \ `\{x :: identity. \ x \notin \{"Eve", "Charly"\}\}\} \ y =
None}
lemma Abs-inj-on: \bigwedge Abs Rep:: actor \Rightarrow char \ list \ option. x \in \{y :: identity \ option.
y \in Some ` \{x :: identity. x \notin \{"Eve", "Charly"\}\} | y = None \}
              \implies y \in \{y :: identity \ option. \ y \in Some \ `\{x :: identity. \ x \notin \{''Eve'', \}\} \}
"Charly"}| y = None}
              \implies (Abs :: char \ list \ option \Rightarrow actor) \ x = Abs \ y \implies x = y
by (insert Actor-type-def, drule-tac x = Rep in meta-spec, drule-tac x = Abs in
meta-spec,
  frule-tac x = Abs x and y = Abs y in type-definition. Rep-inject,
   subgoal-tac\ (Rep\ (Abs\ x) = Rep\ (Abs\ y)),\ subgoal-tac\ Rep\ (Abs\ x) = x,
   subgoal-tac Rep\ (Abs\ y) = y, erule\ subst, erule\ subst, assumption,
   (erule\ type-definition. Abs-inverse,\ assumption)+,\ simp)
\mathbf{lemma}\ Actor\text{-}td\text{-}Abs\text{-}inverse:
(y \in \{y :: identity \ option. \ y \in Some \ `\{x :: identity. \ x \notin \{"Eve", "Charly"\}\}] \ y
= None\}) \Longrightarrow
(Rep :: actor \Rightarrow identity \ option)((Abs :: identity \ option \Rightarrow actor) \ y) = y
by (insert Actor-type-def, drule-tac x = Rep in meta-spec, drule-tac x = Abs in
meta-spec,
  erule type-definition. Abs-inverse, assumption)
axiomatization where Actor-redef: Actor = (Abs :: identity option <math>\Rightarrow actor)o
Actor-Abs
lemma UasI-Actor-redef:
\land Abs Rep:: actor \Rightarrow char \ list \ option.
((Abs :: identity \ option \Rightarrow actor) \ o \ Actor-Abs) "Eve" = ((Abs :: identity \ option \Rightarrow
actor) o Actor-Abs) "Charly" ∧
   (\forall (x::char\ list)\ y::char\ list.\ x \neq "Eve" \land y \neq "Eve" \land
  ((Abs :: identity \ option \Rightarrow actor)o \ Actor-Abs) \ x = ((Abs :: identity \ option \Rightarrow
```

actor) o Actor-Abs) y

```
\longrightarrow x = y
by (insert UasI-ActorAbs, simp, clarify, drule-tac x = x in spec, drule-tac x = y
in spec,
     subgoal-tac\ Actor-Abs\ x=Actor-Abs\ y,\ simp,\ rule\ Abs-inj-on,\ rule\ Actor-Abs-ran,
rule Actor-Abs-ran)
lemma UasI-Actor: UasI "Eve" "Charly"
 by (unfold UasI-def, insert Actor-redef, drule meta-spec, erule ssubst, rule UasI-Actor-redef)
interpretation airplane airplane-actors airplane-locations cockpit door cabin global-policy
                            ex-creds ex-locs ex-locs' ex-graph aid-graph aid-graph0 agid-graph
                      local	ext{-}policies\ local	ext{-}policies-four-eyes\ Airplane-scenario\ Airplane-in-danger
                                      Airplane-getting-in-danger Air-states
Air-Kripke
                            Airplane-not-in-danger Airplane-not-in-danger-init Air-tp-states
                            Air-tp-Kripke Safety Security foe-control astate
 by (rule airplane.intro, simp add: tipping-point-def,
         simp add: Insider-def UasI-def tipping-point-def atI-def,
         insert UasI-Actor, simp add: UasI-def,
         insert cockpit-foe-control', simp add: foe-control-def' cockpit-def',
         rule airplane-actors-def',
     (simp add: airplane-locations-def' cockpit-def' door-def' cabin-def' global-policy-def'
                                  ex-creds-def' ex-locs-def' ex-locs'-def' ex-graph-def' aid-graph-def'
aid-graph0-def'
                    agid-graph-def' local-policies-def' local-policies-four-eyes-def' Airplane-scenario-def'
                    Airplane-in-danger-def'\ Airplane-getting-in-danger0-def'\ Airplane-getting-in-danger-def'\ Airpl
                    Air-states-def' Air-Kripke-def' Airplane-not-in-danger-def' Airplane-not-in-danger-init-def'
                            Air-tp-states-def' Air-tp-Kripke-def' Safety-def' Security-def'
                            foe-control-def' astate-def')+)
```

end