### 1. Establish the Foundation

- \*\*Function Signatures\*\* describe how data is modeled and represented.
- Foundation: Start with \*\*Fourier (1D)\*\*, extend to \*\*Zernike (2D)\*\*, and then \*\*Spherical Harmonics (3D)\*\*.

Domain	Basis Functions	Example Input
1D	Sines/Cosines	f(x)
2D (disk)	Zernike Polynomials	f(x,y)
3D (sphere)	Spherical Harmonics	$f( heta,\phi)$

# 2. Trivial Example: Constant Sphere

• Input:  $f(\theta, \phi) = 1$ 

• Output: Only  $c_{00} \neq 0$  in the SH expansion.

uniform\_sphere.png

1	m	Clm
0	0	1.0
1	-1. 0. 1	0.0

## 3. Perturbed Sphere: Higher Modes

- A small localized \*\*bump\*\* perturbs the sphere.
- Higher *I*-modes are excited in the SH expansion.

bumped\_sphere.png

1	m	c <sub>lm</sub> (Uniform)	c <sub>lm</sub> (Bumped)
0	0	1.0	0.95
1	-1. 0. 1	0.0	Small nonzero

## 4. Connecting to Visuals

- Pick an angle  $(\theta, \phi)$ , e.g.,  $(90^{\circ}, 0^{\circ})$ .
- Value  $f(\theta, \phi)$  determines the color/height at that point.
- \*\*Higher SH coefficients  $c_{lm}$ \*\* add detail to the surface.

rcs\_visual.png

## 5. Function Signature

$$\sigma(\theta,\phi) \approx \sum_{l=0}^{L} \sum_{m=-l}^{l} c_{lm} Y_{lm}(\theta,\phi)$$

- \*\*Inputs\*\*: Angles  $(\theta, \phi)$ .
- \*\*Outputs\*\*: Scalar values  $f(\theta, \phi)$  (RCS, etc.).
- \*\*Spherical Harmonics Coefficients  $c_{lm}$ \*\* describe the function.