



setup

overhead

tag

```
In[6]:= (* project directory *)
home = "projects/least squares/lines/triangulation/novus/";
(* common variable definitions *)
Get["utility modules.m", Path→dirPack];
(* Get["Bevington modules.m", Path→dirPack]; *)
(* Get["LaTeX-tools.m", Path→dirPack]; *)
(* time, date, system user *)
stamp1;

maximum memory: 0.105512 GB

seed file: /Users/dantopa/Mathematica_files/nb/seed 22_01.nb

user: dantopa, CPU: Quaxolotl, MM v. 13.1.0 for Mac OS X x86

date: Nov 27, 2022, time: 11:38:32

nb:
/Users/dantopa/Mathematica_files/nb/projects/least squares/lines/triangulation/novus/
seed 22-05 least squares.nb
```

modules, functions, settings, ...

1 input

locations

```
In[66]:= target = {1, 1};
```

observation posts

```
In[67]:= posts = {{0, 0}, {2, 2}, {0, 2}};
m = Length[posts]
```

```
Out[68]=
```

3

view

```

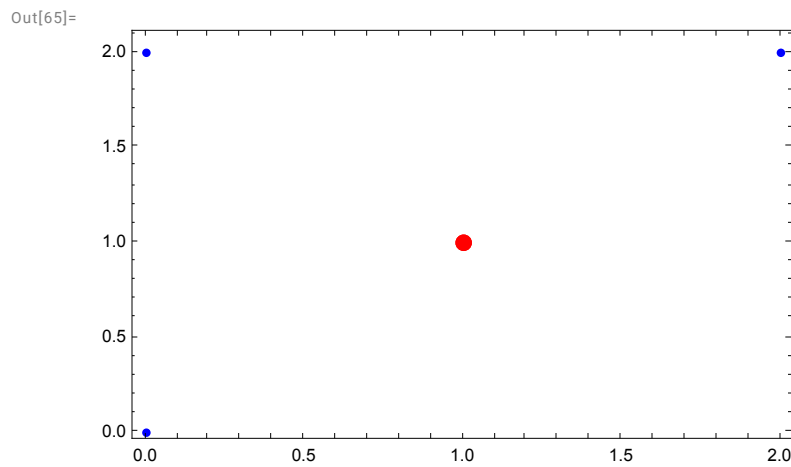
In[64]:= gtarget = ListPlot[{target},
    PlotStyle → {Red, PointSize[0.025]}}];

In[62]:= gpost = ListPlot[{posts},
    PlotStyle → {Blue, PointSize[0.025]}}];

(* gpost=ListPlot[{posts},
    PlotMarkers→{"1","2","3"},
    PlotStyle→{Blue,PointSize[0.025]}}]; *)

In[65]:= Show[{gtarget, gpost},
    PlotRange → All,
    Frame → True]

```



bearings

```

In[69]:= 
$$\frac{\text{target}[[1]] - \#[[1]]}{\text{target}[[2]] - \#[[2]]} \& /@ \text{posts}$$

    ArcTan[%]

```

Out[69]=

$$\{1, 1, -1\}$$

Out[70]=

$$\left\{ \frac{\pi}{4}, \frac{\pi}{4}, -\frac{\pi}{4} \right\}$$

```

In[71]:= angles = ArcTan[target[[1]] - #[[1]], target[[2]] - #[[2]]] & /@ posts

```

Out[71]=

$$\left\{ \frac{\pi}{4}, -\frac{3\pi}{4}, -\frac{\pi}{4} \right\}$$

2

build linear system

```
In[81]:= {Cos[#], -Sin[#]} & /@ angles;
A = %;
% // mf
Out[83]//MatrixForm=

$$\begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}$$

In[84]:= b = Table[
  posts[[k, 1]] Cos[angles[[k]]] - posts[[k, 2]] Sin[angles[[k]]]
, {k, m}]
Out[84]=
 $\{0, 0, \sqrt{2}\}$ 
In[85]:= x = LeastSquares[A, b]
Out[85]=
 $\{1, 1\}$ 
In[86]:= A.x - b
Out[86]=
 $\{0, 0, 0\}$ 
```

3 normal equations

```
In[88]:= W = A^H.A
Out[88]=
 $\left\{ \left\{ \frac{3}{2}, -\frac{1}{2} \right\}, \left\{ -\frac{1}{2}, \frac{3}{2} \right\} \right\}$ 
In[89]:= Det[W]
Out[89]=
2
In[90]:= Winv = Inverse[W]
Out[90]=
 $\left\{ \left\{ \frac{3}{4}, \frac{1}{4} \right\}, \left\{ \frac{1}{4}, \frac{3}{4} \right\} \right\}$ 
```

In[91]:= **A^H.b**

Out[91]=

{1, 1}

In[93]:= **Apinv = Winv.A^H**

Out[93]=

$\left\{ \left\{ \frac{1}{2\sqrt{2}}, -\frac{1}{2\sqrt{2}}, \frac{1}{\sqrt{2}} \right\}, \left\{ -\frac{1}{2\sqrt{2}}, \frac{1}{2\sqrt{2}}, \frac{1}{\sqrt{2}} \right\} \right\}$

In[94]:= **LS = Apinv.b**

Out[94]=

{1, 1}

In[95]:= **A.x - b**

Out[95]=

{0, 0, 0}

In[97]:= **r = A.x - b**

Out[97]=

{0, 0, 0}

end