

# A Quick Literature Survey: Precise Orbit Determination

Daniel Topa

December 4, 2024

## Abstract

What are the current limits on the precision in computing and measuring a satellite's location? A quick literature search outlined here shows sub-meter resolution, and in some cases, centimeter resolution. This report should be read as a gateway to the literature.

## Contents

<b>1</b>	<b>Introduction</b>	<b>1</b>
<b>2</b>	<b>Literature Review</b>	<b>1</b>
<b>3</b>	<b>Open-Source Orbit Propagators</b>	<b>3</b>
3.1	Comparison of Orbit Propagators . . . . .	3
3.2	Complementary Tools . . . . .	3
3.3	Evaluation and Use Cases . . . . .	3
3.4	Emerging Trends . . . . .	3
3.5	Why Open Source Matters . . . . .	3
3.6	Future Directions (Placeholder: Achates' Ideas for Improvement) . . . . .	3
3.7	Figures and Visualizations (Placeholder) . . . . .	4
<b>4</b>	<b>Open-source orbit propagators</b>	<b>4</b>
4.1	KASIOP . . . . .	4
4.1.1	Software . . . . .	4
4.1.2	Post-Newtonian equations of motion . . . . .	4
4.2	NEOPROP . . . . .	4
4.3	Orbit Determination Toolbox (ODTBX) . . . . .	5
4.4	polyastro: Astrodynamics in Python . . . . .	5
4.5	OPI - Orbital Propagation Interface . . . . .	5
4.6	Orbit Predictor . . . . .	5
4.7	Orekit: an Open-source Library for Operational Flight Dynamics Applications . . . . .	6
<b>5</b>	<b>Discussion</b>	<b>6</b>
<b>6</b>	<b>Conclusion</b>	<b>6</b>

## 1 Introduction

The determination of a satellite's precise orbit is crucial for various applications, from Earth observation to deep-space exploration. Recent advances in orbit determination techniques are quickly surveyed and key findings are highlighted.

## 2 Literature Review

In this section, we summarize recent studies on precise orbit determination.  
The results of our navigation experiment demonstrate

### 3 Summary of Selected References

Below is a summary of key insights from selected references. Each entry includes the document title followed by a quote highlighting the relevant content.

Below is a summary of key insights from selected references. Each entry includes the document title followed by a quote highlighting the relevant content.

**1. Real-Time Precise Orbit Determination of Low Earth Orbit Satellites Based on GPS and BDS-3 PPP B2b Service [26]**

*The RMS of the RT orbital errors in the radial, along, and cross directions is 0.10, 0.13, and 0.09 m, respectively, using BDS-3 and GPS PPP-B2b corrections.*

**2. LEO Real-Time Ambiguity-Fixed Precise Orbit Determination with Onboard GPS/Galileo Observations [15]**

*Using onboard GPS and Galileo observations, the 3D orbit accuracy of the ambiguity-fixed solution is significantly improved from 5.17 to 3.61 cm, by 30%, compared to the ambiguity-float solution. Furthermore, the application of IAR also achieves a faster convergence to the centimeter-level orbit.*

**3. A Novel Method for Improving LEO Kinematic Real-Time Precise Orbit Determination with Neural Networks [31]**

*Benefiting from this method, a promising accuracy of 3.2 cm can be achieved in LEO KRTPOD.*

**4. Precise Orbit Determination for Low Earth Orbit Satellites Using GNSS: Observations, Models, and Methods [18]**

*Using a state-of-the-art combination of GNSS observations and satellite dynamics, the absolute orbit determination for a single satellite reached a precision of 1 cm.*

**5. Precise Orbit Determination of the ZY3-03 Satellite Using the Yaw-Attitude Modeling for Drift Angle Compensation [7]**

*The orbit determination experiments revealed that the zero-yaw assumption in the zero-attitude model would result in periodic orbit errors of up to  $\pm 86$  mm in the normal direction, while the proposed model describes yaw angle variations accurately with errors of less than  $\pm 0.01^\circ$ .*

**6. Long-Term Orbit Dynamics of Decommissioned Geostationary Satellites [proietti2021]**

*Orbit propagations are performed using two algorithms based on different equations of motion and numerical integration methods. The numerical results exhibit excellent agreement over integration times of decades.*

**7. Reduced Dynamic and Kinematic Precise Orbit Determination for the Swarm Mission from 4 Years of GPS Tracking [21]**

*30% improvement in the precision of the reduced dynamic orbits with resulting errors at the 0.5–1 cm level (1D RMS).*

**8. Precise Relative Positioning Using Real Tracking Data from COMPASS GEO and IGSO Satellites [25]**

*The precision of COMPASS-only solutions is better than 2 cm for the North component and 4 cm for the vertical.*

**9. Dynamic and Reduced-Dynamic Precise Orbit Determination of Satellites in Low Earth Orbits [28]**

*Orbital arcs over a whole day can be generated with an accuracy of up to 4.5 cm RMS.*

## 10. Aiming at a 1-cm Orbit for Low Earth Orbiters: Reduced-Dynamic and Kinematic Precise Orbit Determination [30]

*Both techniques have reached a high level of maturity and have been successfully applied to missions in the past, such as TOPEX/POSEIDON (T/P), leading to (sub-) decimeter orbit accuracy.*

## 4 Open-Source Orbit Propagators

The use of open-source orbit propagators has expanded significantly in recent years, driven by the need for accurate, flexible, and cost-effective tools for satellite trajectory prediction and mission analysis. In this section, we present an overview of key open-source propagators, compare their features, and provide insights into their applications.

### 4.1 Comparison of Orbit Propagators

Table 1 summarizes the key features of popular open-source orbit propagators, highlighting their precision, supported orbital regimes, ease of use, programming languages, and special features.

### 4.2 Complementary Tools

In addition to orbit propagators, complementary tools such as NASA’s SPICE toolkit and Python libraries like Astropy provide valuable functionality for mission design, time conversions, and astronomical computations. These tools are not orbit propagators per se but significantly enhance the analytical capabilities of mission planners.

### 4.3 Evaluation and Use Cases

The choice of an orbit propagator depends on the specific mission requirements. For example:

- **CubeSat missions:** Tools like FOSSASAT and Orbit Predictor are ideal for their simplicity and ease of use.
- **GNSS and precise orbit determination:** Orekit and ODTBX offer advanced features tailored for such applications.
- **Interplanetary missions:** GMAT excels in trajectory optimization for deep-space missions.

### 4.4 Emerging Trends

The field of open-source orbit propagation continues to evolve. Emerging trends include:

- Integration of artificial intelligence and machine learning to enhance orbit prediction accuracy.
- Real-time data assimilation from global navigation satellite systems (GNSS) and other sensors.
- Collaborative development of modular, extensible propagators tailored to specific mission needs.

### 4.5 Why Open Source Matters

Open-source tools democratize access to advanced orbital mechanics, enabling researchers, small satellite developers, and students to experiment and innovate without prohibitive costs. They also foster collaboration and transparency, ensuring reproducibility and peer review of results.

### 4.6 Future Directions (Placeholder: Achates’ Ideas for Improvement)

In this subsection, we will explore:

- Strategies for integrating multiple tools into a cohesive workflow.
- Enhancements to the accuracy and computational efficiency of open-source propagators.
- Community-driven initiatives to standardize interfaces and outputs for interoperability.

## 4.7 Figures and Visualizations (Placeholder)

Figures showcasing example orbits, computational pipelines, or comparisons of propagator outputs will be included here to illustrate the discussion visually.

# 5 Open-source orbit propagators

Open-source orbit propagators have revolutionized the field of astrodynamics by providing accessible, high-quality tools for a diverse range of applications. Their continued development will be pivotal in shaping the future of space exploration.

## 5.1 KASIOP

### 5.1.1 Software

KASIOP (Korea Astronomy and Space science Institute Orbit Propagator) is a high-fidelity orbit propagation software developed by the Korea Astronomy and Space Science Institute (KASI) designed to simulate the trajectories of Earth-orbiting satellites with high precision, incorporating various perturbative forces, including gravitational harmonics, atmospheric drag, solar radiation pressure, and relativistic effects. KASIOP has been utilized in research to evaluate post-Newtonian perturbations in satellite orbits, demonstrating its capability to model complex orbital dynamics accurately. Details are included in two papers by Roh [24, 23]

- Download: None found
- Documentation: None found

### 5.1.2 Post-Newtonian equations of motion

The Post-Newtonian equations of motion provide a refined framework for modeling the dynamics of celestial bodies and satellites by incorporating relativistic corrections to Newtonian mechanics. These equations arise from the Post-Newtonian approximation, which is a perturbative expansion of General Relativity for systems where gravitational fields are weak and velocities are much smaller than the speed of light. This approach is particularly useful for scenarios involving high-precision orbit determination, such as those required for global navigation satellite systems (GNSS), satellite geodesy, and relativistic tests.

Key corrections include:

Relativistic time dilation due to the satellite’s velocity and the gravitational potential. Frame-dragging effects caused by the Earth’s rotation (Lense-Thirring effect). Periapsis precession, an analog to the relativistic precession of Mercury’s orbit around the Sun.

Post-Newtonian equations are critical for missions with stringent accuracy requirements, such as the LARES (Laser Relativity Satellite) project, where relativistic effects are explicitly measured. They are also increasingly integrated into orbit propagators for precise modeling of satellite trajectories in the Earth’s gravitational field.

The use of Post-Newtonian dynamics is vital in bridging the gap between classical orbital mechanics and full relativistic solutions, enabling groundbreaking advancements in space science and technology.

## 5.2 NEOPROP

The European Space Agency sponsors the Asteroid and Comet Trajectory Propagator NEOPROP<sup>1</sup> to model objects which may impact the Earth. From the website:

New orbital perturbations (e.g. Poynting-Robertson effect, solar radiation pressure, outgassing) to improve the propagator accuracy and to allow the identification and propagation of any celestial body (not only NEOs but also moons, comets, planets, etc.). The pre-existing algorithms were further improved in order to increase the performance and reduce the need for human intervention. Robust and redundant preliminary orbit determination techniques

---

<sup>1</sup>Splash page URL: <https://neo.ssa.esa.int/neo-propagator>

were added in order to deal with very long and disrupted observational arcs, which usually would require a manual split of the observations.

An \*.exe file is available<sup>2</sup> for download.

The User's Manual focuses on running the software and has scant mathematical explanation.

### 5.3 Orbit Determination Toolbox (ODTBX)

The Orbit Determination Toolbox ODTBX is an orbit determination analysis tool based on Matlab and Java that provides a flexible way to do early mission analysis, especially for formation flying and exploration systems. ODTBX is composed of both Matlab and Java code.

Download<sup>3</sup> ODTBX\_4\_0.jar

The Java Astrodynamics Toolbox is used as an engine for things that might be slow or inefficient in MATLAB, such as high-fidelity trajectory propagation, lunar and planetary ephemeris look-ups, precession, nutation, polar motion calculations, ephemeris file parsing, and the like.

### 5.4 polyastro: Astrodynamics in Python

polyastro is an open source (MIT) pure Python library for interactive Astrodynamics and Orbital Mechanics, with a focus on ease of use, speed, and quick visualization. It provides a simple and intuitive API, and handles physical quantities with units.

Some features include orbit propagation, solution of the Lambert's problem, conversion between position and velocity vectors and classical orbital elements and orbit plotting, among others. It focuses on interplanetary applications, but can also be used to analyze artificial satellites in Low-Earth Orbit (LEO).

The application polyastro has a page the PyPI server<sup>4</sup> and adequate documentation

- Website: <https://www.polyastro.space>
- PyPi page: polyastro 0.17.0
- Documentation: polyastro - Astrodynamics in Python

### 5.5 OPI - Orbital Propagation Interface

OPI is an interface with the goal to facilitate the implementation of orbital propagators into different applications.

To calculate orbital motion, many different software programs exist emphasizing on different aspects such as execution speed or accuracy. They often require different input parameters and are written in different languages. This makes comparing or exchanging them a challenging task. OPI aims at simplifying this by providing a common way of handling propagation. Propagators using OPI are designed as plugins/shared libraries that can be loaded by a host program via the interface.

### 5.6 Orbit Predictor

Orbit Predictor is a Python library to propagate orbits of Earth-orbiting objects (satellites, ISS, Santa Claus, etc) using TLE (Two-Line Elements set). We can say Orbit predictor is kind of a "wrapper" for the python implementation of SGP4.

PyPi page: orbit-predictor 1.15.0

Download source: orbit-predictor-1.15.0.tar.gz

---

<sup>2</sup>Download URL: [https://neo.ssa.esa.int/documents/20126/418165/Setup\\_NEOPROP\\_2.1.exe/](https://neo.ssa.esa.int/documents/20126/418165/Setup_NEOPROP_2.1.exe/)

<sup>3</sup>[https://opensource.gsfc.nasa.gov/projects/ODTBX/ODTBX\\_4\\_0.jar](https://opensource.gsfc.nasa.gov/projects/ODTBX/ODTBX_4_0.jar)

<sup>4</sup><https://pypi.org/project/polyastro/>

## 5.7 Orekit: an Open-source Library for Operational Flight Dynamics Applications

poliastro is an open source (MIT) pure Python library for interactive Astrodynamics and Orbital Mechanics, with a focus on ease of use, speed, and quick visualization. It provides a simple and intuitive API, and handles physical quantities with units.

Some features include orbit propagation, solution of the Lambert's problem, conversion between position and velocity vectors and classical orbital elements and orbit plotting, among others. It focuses on interplanetary applications, but can also be used to analyze artificial satellites in Low-Earth Orbit (LEO).

Footnote<sup>5</sup>

## 6 Discussion

The implications of achieving sub-meter or centimeter-level precision in satellite positioning are significant.

## 7 Conclusion

This quick survey outlines the state-of-the-art in precise orbit determination. Readers are encouraged to explore the referenced works for more in-depth information.

---

<sup>5</sup>[https://www.researchgate.net/profile/Luc-Maisonobe/publication/310250345\\_OREKIT\\_AN\\_OPEN\\_SOURCE\\_LIBRARY\\_FOR\\_OPERATIONAL-FLIGHT-DYNAMICS-APPLICATIONS.pdf](https://www.researchgate.net/profile/Luc-Maisonobe/publication/310250345_OREKIT_AN_OPEN_SOURCE_LIBRARY_FOR_OPERATIONAL-FLIGHT-DYNAMICS-APPLICATIONS.pdf)

## References

- [1] Simone Andolfo et al. “Precise orbit determination through a joint analysis of optical and radiometric data”. In: *2024 International Conference on Space Robotics (iSpaRo)*. 2024, pp. 28–35. DOI: 10.1109/iSpaRo60631.2024.10687705.
- [2] Xavier Carreño-Megias et al. “Multistatic SAR Imaging and Precise Orbit Determination Synergies Using Geostationary Telecommunication Satellites”. In: *IGARSS 2023 - 2023 IEEE International Geoscience and Remote Sensing Symposium*. 2023, pp. 7824–7827. DOI: 10.1109/IGARSS52108.2023.10282308.
- [3] Yuan Du et al. “A novel predictive algorithm for double difference observations of obstructed BeiDou geostationary earth orbit (GEO) satellites”. In: *Advances in space research* 63.5 (2019), pp. 1554–1565.
- [4] Roberto Flores, Burhani Makame Burhani, and Elena Fantino. “A method for accurate and efficient propagation of satellite orbits: A case study for a Molniya orbit”. In: *Alexandria Engineering Journal* 60.2 (2021), pp. 2661–2676.
- [5] Antonio Genova et al. “Sensor data fusion for precise orbit determination of interplanetary spacecraft”. In: *2024 International Conference on Space Robotics (iSpaRo)*. IEEE. 2024, pp. 22–27.
- [6] Christian Gilbertson and Bryan Welch. *Demonstrating High-Accuracy Orbital Access Using Open-Source Tools*. Tech. rep. 2017. URL: <https://ntrs.nasa.gov/api/citations/20170010173/downloads/20170010173.pdf>.
- [7] Xuewen Gong et al. “Precise Orbit Determination of the ZY3-03 Satellite Using the Yaw-attitude Modeling for Drift Angle Compensation”. In: *IEEE Sensors Journal* (2024).
- [8] Lina He et al. “Experimental study on the precise orbit determination of the BeiDou navigation satellite system”. In: *Sensors* 13.3 (2013), pp. 2911–2928.
- [9] Guanwen Huang and Qin Zhang. “Real-time estimation of satellite clock offset using adaptively robust Kalman filter with classified adaptive factors”. In: *GPS solutions* 16 (2012), pp. 531–539.
- [10] Guanwen Huang et al. “A real-time robust method to detect BeiDou GEO/IGSO orbital maneuvers”. In: *Sensors* 17.12 (2017), p. 2761.
- [11] Guanwen Huang et al. “An improved predicted model for BDS ultra-rapid satellite clock offsets”. In: *Remote Sensing* 10.1 (2018), p. 60.
- [12] A Jäggi et al. “Swarm kinematic orbits and gravity fields from 18 months of GPS data”. In: *Advances in Space Research* 57.1 (2016), pp. 218–233.
- [13] Sajjad Kazemi et al. “Orbit determination for space situational awareness: A survey”. In: *Acta Astronautica* 222 (2024), pp. 272–295. ISSN: 0094-5765. DOI: <https://doi.org/10.1016/j.actaastro.2024.06.015>. URL: <https://www.sciencedirect.com/science/article/pii/S0094576524003308>.
- [14] Sergei Kopeikin and Igor Vlasov. “Parametrized post-Newtonian theory of reference frames, multipolar expansions and equations of motion in the N-body problem”. In: *Physics Reports* 400.4-6 (2004), pp. 209–318.
- [15] Xingxing Li et al. “LEO real-time ambiguity-fixed precise orbit determination with onboard GPS/Galileo observations”. In: *GPS Solutions* 28.4 (2024), p. 188.
- [16] Shanhong Liu et al. “Precise orbit determination for Tianwen-1 during mapping phase”. In: *Astrodynamics* 8.3 (2024), pp. 471–481.
- [17] Luc Maisonobe, Véronique Pommier, and Pascal Parraud. “Orekit: An open source library for operational flight dynamics applications”. In: *4th international conference on astrodynamics tools and techniques*. European Space Agency Paris. 2010, pp. 3–6. URL: [https://www.researchgate.net/profile/Luc-Maisonobe/publication/310250345\\_OREKIT\\_AN\\_OPEN\\_SOURCE\\_LIBRARY\\_FOR\\_OPERATIONAL\\_FLIGHT\\_DYNAMICS\\_APPLICATIONS/links/6034c01e299bf1cc26e4a550/OREKIT-AN-OPEN-SOURCE-LIBRARY-FOR-OPERATIONAL-FLIGHT-DYNAMICS-APPLICATIONS.pdf](https://www.researchgate.net/profile/Luc-Maisonobe/publication/310250345_OREKIT_AN_OPEN_SOURCE_LIBRARY_FOR_OPERATIONAL_FLIGHT_DYNAMICS_APPLICATIONS/links/6034c01e299bf1cc26e4a550/OREKIT-AN-OPEN-SOURCE-LIBRARY-FOR-OPERATIONAL-FLIGHT-DYNAMICS-APPLICATIONS.pdf).
- [18] Xinyuan Mao, Wenbing Wang, and Yang Gao. “Precise orbit determination for low Earth orbit satellites using GNSS: Observations, models, and methods”. In: *Astrodynamics* (2024), pp. 1–26.
- [19] Oliver Montenbruck, Eberhard Gill, and FH Lutze. “Satellite orbits: models, methods, and applications”. In: *Appl. Mech. Rev.* 55.2 (2002), B27–B28.

- [20] Oliver Montenbruck et al. “GNSS satellite geometry and attitude models”. In: *Advances in Space Research* 56.6 (2015), pp. 1015–1029.
- [21] Oliver Montenbruck et al. “Reduced dynamic and kinematic precise orbit determination for the Swarm mission from 4 years of GPS tracking”. In: *GPS solutions* 22.3 (2018), p. 79.
- [22] Simone Proietti et al. “Long-term orbit dynamics of decommissioned geostationary satellites”. In: *Acta Astronautica* 182 (2021), pp. 559–573. ISSN: 0094-5765. DOI: <https://doi.org/10.1016/j.actaastro.2020.12.017>. URL: <https://www.sciencedirect.com/science/article/pii/S0094576520307517>.
- [23] Kyoung-Min Roh. “Numerical evaluation of post-Newtonian perturbations on the Global Navigation Satellite System”. In: *Journal of Spacecraft and Rockets* 55.4 (2018), pp. 1028–1033.
- [24] Kyoung-Min Roh, Sergei M. Kopeikin, and Jung-Ho Cho. “Numerical simulation of the post-Newtonian equations of motion for the near Earth satellite with an application to the LARES satellite”. In: *Advances in Space Research* 58.11 (2016), pp. 2255–2268. ISSN: 0273-1177. DOI: <https://doi.org/10.1016/j.asr.2016.08.009>. URL: <https://www.sciencedirect.com/science/article/pii/S0273117716304422>.
- [25] Chuang Shi et al. “Precise relative positioning using real tracking data from COMPASS GEO and IGSO satellites”. In: *GPS solutions* 17 (2013), pp. 103–119.
- [26] Yali Shi et al. “Real-time precise orbit determination of low earth orbit satellites based on gps and bds-3 ppp b2b service”. In: *Remote Sensing* 16.5 (2024), p. 833.
- [27] Dražen Švehla and M Rothacher. “Kinematic and reduced-dynamic precise orbit determination of low earth orbiters”. In: *Advances in Geosciences* 1 (2003), pp. 47–56.
- [28] Paul Swatschina. *Dynamic and reduced-dynamic precise orbit determination of satellites in low earth orbits*. Vol. 89. Dep. of Geodesy and Geoinformation of the Vienna Univ. of Technology, 2012.
- [29] Andrea Tantucci, Andrea Wrona, and Antonio Pietrabissa. “Precise orbit determination on leo satellite using pseudorange and pseudorange-rate measurements”. In: *2023 31st Mediterranean Conference on Control and Automation (MED)*. IEEE. 2023, pp. 341–347.
- [30] PNAME Visser and J Van Den Ijssel. “Aiming at a 1-cm orbit for low earth orbiters: reduced-dynamic and kinematic precise orbit determination”. In: *Space science reviews* 108 (2003), pp. 27–36.
- [31] Wei Zhang et al. “A novel method for improving LEO kinematic real-time precise orbit determination with neural networks”. In: *IEEE Transactions on Instrumentation and Measurement* (2024).
- [32] Gang Zhao, XuHua Zhou, and Bin Wu. “Precise orbit determination of Haiyang-2 using satellite laser ranging”. In: *Chinese Science Bulletin* 58 (2013), pp. 589–597.



<b>Tool</b>	<b>Precision</b>	<b>Supported Models</b>	<b>Ease of Use</b>	<b>Language</b>	<b>Special Features</b>
GMAT	High	All orbital regimes	Moderate	C++	Robust mission analysis; trajectory optimization.
Orekit Orbit Predictor	High Moderate	LEO, HEO, GNSS, interplanetary TLE propagation	Advanced Easy	Java Python	Highly customizable library. Simplified for Earth satellite orbits.
NEOPROP Skyfield	High Moderate	GNSS and celestial bodies Astronomical computations	Moderate Easy	Proprietary Python	ESA-backed accuracy. Great for tracking astronomical bodies.
ODTBX FOSSASAT	High Moderate	Matlab-compatible models LEO propagation	Moderate Easy	Matlab/Java Python	Comprehensive GNSS support. New entrant focused on small satellites.

Table 1: Comparison of Open-Source Orbit Propagators

Table 2: Integrators Implemented

Integrator	Step	Step-Size	Integrator Identifier
Runge-Kutta 45	single	variable	Runge_Kutta_45
Dormand Prince 8	single	variable	Dormand_Prince_8
Runge-Kutta 853	single	variable	Runge_Kutta_853
Runge-Kutta 4	single	fixed	Runge_Kutta_4
Runge-Kutta 4 Adapted	single	fixed*	Runge_Kutta_4_Adapted
Gauss-Jackson 8	multi	fixed	Gauss_Jackson_8
Gauss-Jackson 8 Adapted	multi	fixed*	Gauss_Jackson_8_Adapted
Gauss-Jackson 8 Self-Adapted	multi	fixed*	Gauss_Jackson_8_Self_Adapted

\*The integration follows a fixed step-size scheme, but for some trajectory arcs (e.g., close to a celestial body), the step-size might be reduced by a factor of 10.

Source: *Enhanced Orbit Propagator*, ESA Contract No. RFP/D/IPL-PTE/GLC/al/557.2014.  
*NEOPROP2 Software User Manual*.

For more details, see: ESA NEOPROP2 User Manual.