

NASA Software General Mission Analysis Tool

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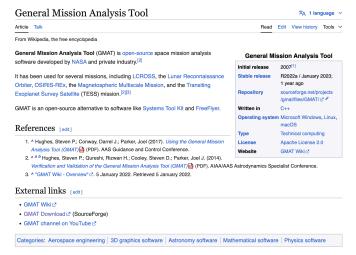
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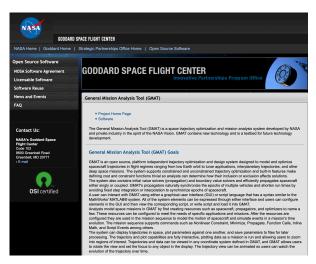
GMAT Wikipedia Page





GMAT Background Backup Slides

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GMAT Overview

Overview

The General Mission Analysis Tool (GMAT) is the worlds only enterprise. multi-mission, open source software system for space mission design. optimization, and navigation. The system supports missions in flight regimes ranging from low Earth orbit to lunar, libration point, and deep space missions. GMAT is developed by a team of NASA, private industry, public, and private contributors and is used for real-world mission support. engineering studies, as a tool for education, and public engagement.GMAT contains models of real world objects such as spacecraft and thrusters, and analysis "objects" such as propagators, plots, and reports. These objects are used in a mission sequence in which the user employs commands supported by the system to model mission events and perform estimation. For a complete list of new features, compatibility changes, and bug fixes, see the Release Notes. Below are just some of the new capabilities contained in this release. Production quality orbit determination (Operational Certification expected in November, 2016)Code 500 ephemeris propagatorSTK ephemeris file outputWrite command to save GMAT configurations during executionInclude macro to load GMAT configurations from external sources during executionMany new built in math functions and parameters 130 pages of new user documentation

Software Details

Category Design and Integration Tools

Reference Number GSC-17177-1 Release Type Open Source

Operating System

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GMAT Contact

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GMAT is an open source, platform independent trajectory optimization and design system



GMAT is an open source, platform independent trajectory optimization and design system designed to model and optimize spacecraft trajectories in flight regimes ranging from low Earth orbit to lunar applications, interplanetary trajectories, and other deep space missions.





Bertrand's Theorem

GMAT Background

Backup Slides

No Bertrand Theorem



Professional Societies: Computational Mechanics



Bibliography I



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