

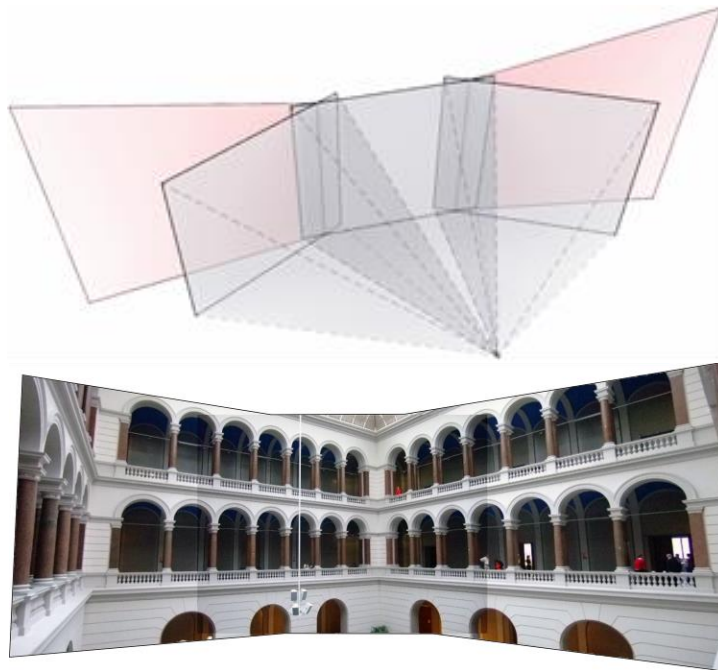
# Photogrammetric Computer Vision Assignment 2

Winter Semester 20/21

Submission Deadline: 29.11.20 13:30 pm

## III. Projective Transformation (Homography)

In this exercise, a fundamental *projective transformation* should be realized. The task consists of rectifying images geometrically and stitching them together, so that a *panoramic image mosaic* is generated.



1. **Image acquisition:** Take pictures with a digital camera, which *overlap at least 30 percent in horizontal direction*. Produce thereby *three images without disparities* (i.e. turn around the projection center or choose a planar object).
2. **Correspondence analysis:** Transfer the three images into the computer (`imread`) and measure *interactively* (`figure`, `imshow`, `ginput`) at least *four corresponding image points*  $\mathbf{x} \leftrightarrow \mathbf{x}'$  between two neighboring images.
3. **Homography computation:** Implement an own function in MATLAB to estimate a 2D homography using the singular value decomposition (`mean`, `abs`, `svd`, `reshape`). Compute the homography matrix  $\mathbf{H}_{12}$  from first to second image.
4. **Projective rectification:** Use the provided auxiliary program `geokor.m` and the estimated homography to *adapt* the first image to the second one (`geokor` combines the respective frames to a common mosaic image). Then, compute the homography  $\mathbf{H}_{32}$  from third image to the intermediate mosaic image and stitch them together.
5. **Visualization:** Show the produced panoramic image on the screen.