Viterbi Algorithm for Intrusion Type Identification in Anomaly Detection System

january 14th 2019

Context

Intrusion Type

- . Buffer overflow
 - . xlock vulnerability
 - . Ipset vulnerability
 - . kcms_sparc vulnerability
- . S/W security vulnerability
- . Setup vulnerability
- . Denial of service

A markov Chain is defined by :

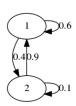
- . S, A finite set of N states
- . π , A vector of initial probabilities over S :

$$\pi_i = P(S_1 = i), 1 \le i \le N$$

. A, A matrix of probabilities of transitions over *SxS* :

$$a_{ij} = P(S_t = j | S_{t-1} = i), 1 \le i \le N$$

. Markov assumption : $P(S_t|S_{t-1},S_{t-2},\ldots,S_1) = P(S_t|S_{t-1})$



$$A = \begin{pmatrix} 0.6 & 0.4 \\ 0.9 & 0.1 \end{pmatrix}$$

Figure: Simple example of Markov Chain

HMM - Hidden Markov Model

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- We define a HMM including :
 - V, A finite set of M observations
 - B, A a matrix of probabilities of observations over state :

$$b_i(k) = P(0_t = V_k | S_t = i)$$

HMM - Forward Algorithm

input : λ The model. O Observed sequence

output : $P(0|\lambda)$

Step 1, Initialization : $\forall i, \alpha_1(i) = \pi_1 b_i(0_1)$

Step 2, Induction:

for $t \leftarrow 2 : T$ do

 $\alpha_t = \left[\sum_{j=1}^N \alpha_{t-1} q_{ij}\right] b_j O_t$

end

Step 3, Termination : $P(0|\lambda) = \sum \alpha_t(i)$

¹L. R. Rabiner (1989). "A tutorial on hidden Markov models and selected applications in speech recognition". In: Proceedings of the IEEE 77.2,

HMM - Viterbi Algorithm

```
input: A All the models. O Observed sequence
output: arg max P(0|\lambda)
Step 1, Initialization :
for i \leftarrow 1 : N do
      \delta_1(i) = \pi_i b_i(0_1)
      \psi_1(i) = 0
end
Step 2. Recursion:
for t \leftarrow 2 \cdot T do
      for j \leftarrow 1 : N do
          \begin{split} & \delta_t(j) = \max_i [\delta_{t-1}(i)a_{ij}]b_j(0_t) \\ & \psi_t(j) = \arg\max_i [\delta_{t-1}(i)a_{ij}]b_j(0_t) \end{split}
                                                                                                             2
      end
end
Step 3, Termination:
P^* = \max_{s \in S} [\delta_T(s)]
S_T^* = \underset{s \in S}{\operatorname{arg max}} [\delta_T(s)]
Step 4. Backtracking:
for t \leftarrow T - 1:1 do
  S_t^* = \psi_{t+1}(s_{t+1}^*)
end
return S*
```

²A. Viterbi (1967). "Error bounds for convolutional codes and an asymptotically optimum decoding algorithm". In: IEEE Transactions on Information Theory 13.2, pp. 260-269

Normal Behaviour Modeling

Normal Behaviour is modelised by a left-to-right HMM λ .

The forward allgorithm is used to decide whether normal or not with a threshold.

Intrusion Detection Initialization

Intrusion Detection Induction

Intrusion Detection Termination

```
if log(P(0|\lambda)) > thresold then
    return Normal Behaviour
else
    return Intrusion
end
Show Example
```

Intrusion Detection

Results

Table: The performance of HMM-based IDS. Best results are in bold

Length	Thresold	Detection Rate	F-P Error	
10	-9.43	100%	2.626	
15	-9.43	100%	3.614	
10	-14.42	100%	1.366	
15	-14.42	100%	2.718	
10	-16.94	100%	0.789	
15	-16.94	100%	2.618	
10	-18.35	100%	0.553	
15	-18.35	100%	2.535	
10	-19.63	100%	0.476	
15	-19.63	100%	2.508	
10	-20.83	100%	0.372	
15	-20.83	100%	2.473	





Intrusion Type Identification

Process in two steps:

Viterbi algorithm used to find the optimal state sequence Euclidiant distance to identify the intrusion type with the optimal state sequence

Intrusion Type Identification

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Intrusion Type Identification Recursion

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Intrusion Type Identification Termination

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Intrusion Type Identification Backtracking

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Intrusion Type Identification Decision

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Intrusion Type Identification Results

Table: The performance of Viterbi-based Intrusion Type Identification

Attack	Trial	Correct	Incorrect	Rate
Buffer Overflow	20	18	2	90%
Denial of Service	25	9	16	36%
Buffer Overflow	45	27	18	60%

Limitations & Remarks

Try other distance metrics for Intrusion Type Identification: Ja-Min Koo and Sung-Bae Cho (2005). "Effective Intrusion Type Identification with Edit Distance for HMM-Based Anomaly Detection System". In: *Pattern Recognition and Machine Intelligence*. Ed. by Sankar K. Pal, Sanghamitra Bandyopadhyay, and Sambhunath Biswas. Springer Berlin Heidelberg

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No baseline to compare results with other methods

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