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# Automated Microservice Identification: an Approach to Decomposition into a Modular Monolith Architecture

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The modular monolith architecture emerged in recent years as the harmonization of the monolithic and microservices architectures. The paradigm offers a compromise between modularity, flexibility, and scalability. Many monolithic applications are being migrated to modular monoliths or microservices entirely, to satisfy increasingly complex and volatile business requirements. This process is labour-intensive, slow, and may take months to years for larger codebases. Modularization of a codebase typically requires the developer to have an intimate knowledge of both the application code and domain.

In this thesis, we investigate the modular monolith software architecture, and how modules are typically determined as part of the modularization efforts. We propose an automated solution based on dependency analysis and machine learning algorithms to aid in the identification of module boundaries, and evaluate its effectiveness using a case study. We discuss the results and draw conclusions about the propsed solution.

**Keywords:** software architecture, monolith, microservices, modular monolith

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# List of Acronyms

**AST**        Abstract Syntax Tree

**BPMN**     Business Process Model and Notation

**DSRM**    Design Science Research Methodology

**DSRP**     Design Science Research Process

**SDLC**     Software Development Life Cycle

**SLR**       Systematic Literature Review

# 1. Introduction

## 1.1. Scope and goal

This research is centered around three research questions:

**Research Question 1**: What are the challenges and opportunities of the modular monolith architecture compared to traditional monolithic and microservices architectures?

**Research Question 2**: What are the existing approaches and tools for automated microservice candidate identification in monolith codebases?

**Research Question 3**: How can static analysis of source code effectively identify optimal module boundaries in a modular monolith architecture?

To answer the first research question, we will first define the modular monolith architecture, and examine what sets it apart from monolithic and microservices architectures. Then, we will proceed to investigate the merits and drawbacks of the software architecture when applied to an existing codebase.

For the second research question, we will enumerate the existing technologies to aid modularization of monolithic codebases, and choose one automated technology for further examination. *(Automated technology)* will then be implemented for a given use case, and compared to manual modularization efforts in terms of accuracy, efficiency, development velocity. This comparison will help us to answer the third research question.

The goal of this research can be summarized as follows:

1. Investigate the merits and drawbacks of the modular monolith architecture
2. Investigate the use of automated technologies to modularize a monolithic architecture

The proposed solution will add value to the field of software engineering, and will be able to be used as a base for future improvements regarding automated modularization of monolith codebases.

## 1.2. Motivation

## 1.3. Methodology

A literature review is conducted to answer the first and second research question. For the first research question, the study aims to find a definition of the modular monolith architecture, and to list the advantages and disadvantages of the architecture based on existing literature. For the second research question, the state of the art in automated modularization technologies is reviewed and summarized.

The third research question is answered by choosing the most appropriate automated technology, and implementing it for a given use case. The implementation is then evaluated based on quantitative and qualitative metrics, and compared to manual modularization efforts.

Finally, the findings are summarized, and an outlook on future work is given.

For the case study, a Design Science Research Methodology (DSRM) is adopted, which is a research paradigm for information systems research focused at creating and evaluating artifacts. In particular, the research and design of the proposed solution follows the six-step Design Science Research Process (DSRP) model [1]. Their model is based on prior research and is designed to guide researchers through the process of analysis, creation, and evaluation of artifacts.

The six steps of the process are:

1. **Problem identification and motivation**: Research problem statement and justification for existence of a solution.
2. **Objectives of a solution**: Definition of the objectives, derived from the problem statement.
3. **Design and development**: Creation of the artifact.
4. **Demonstration**: Usage of the artifact to demonstrate its effectiveness in solving the problem.
5. **Evaluation**: Observation and measurement of how well the artifact supports a solution to the problem.
6. **Communication**: Transfer of knowledge about the artifact and the problem solution to the relevant audience.



Figure 1: Design Science Research Process (DSRP)

The process is structured sequentially, however the authors suggests that researchers may proceed in a non-linear fashion, and start or stop at any step, depending on the context and requirements of the research.

In this thesis specifically, the DSRP is used to guide the design and development of the automated modularization technology, with a particular focus on the design and development, demonstration, and evaluation steps.

## 1.4. Outline

The thesis is divided into three parts.

The first part comprises the background and related work. In Chapter 1, the scope and goal of the research is defined, and the research questions are formulated. The stakeholders are identified, and the methodology is explained. Chapter 2 introduces the reader to the research background and necessary concepts. In Chapter 3, the existing literature is reviewed, and the state of the art is presented.

The second part of the thesis, starting with Chapter 4, is dedicated to the first research question. The modular monolith architecture is defined, and its merits and drawbacks are discussed.

The third part aims to solve the second and third research question. Chapter 5 gives an introduction into the automated modularization of monolith codebases, listing the existing technologies. It then continues to focus on one automated technology, *(automated technology)*, and explains its implementation. Chapter 7 applies *(automated technology)* on a given case study, and compares it to manual modularization efforts.

Finally, Chapter 8 summarizes the findings, and gives an outlook on future work.

# 2. Background

## 2.1. Monolith architecture

## 2.2. Modular programming

## 2.3. Microservice architecture

## 2.4. Modularization

# 3. Related work

# 4. Modular monolith architecture

## 4.1. Background

## 4.2. Challenges and opportunities

## 4.3. Modularization

# 5. Automated modularization

In this chapter, we investigate the state of the art in automated technologies for modularization of monolith codebases. Using a systematic literature review, we identified and categorized existing literature regarding automated modularization of monolith codebases. We also provided a brief overview of the most relevant approaches and tools.

A systematic literature review is used to identify, evaluate and interpret research literature for a given topic area, or research question [2]. The systematic nature of systematic literature reviews reduces bias through a well-defined sequence of steps to identify and categorize existing literature, although publication bias still has to be considered . Studies directly researching the topic area are called *primary* studies, systematic studies aggregating and summarizing primary studies are called *secondary* studies. *Tertiary* studies are systematic studies aggregating and summarizing secondary studies.

The literature review was conducted using a three-step protocol as defined by Kitchenham & Charters [2]:

|   | Step | Activity |
|---|------|----------|
| 1 | Plan | Identify the need for the review, specifying the research questions, and developing a review protocol |
| 2 | Conduct | Identification and selection of literature, data extraction and synthesis |
| 3 | Report | Evaluation and reporting of the results |

Table 1: Systematic literature review process

## 5.1. Plan

Using the systematic literature review, we answered the following research question:

**Research Question 2**: What are the existing approaches and tools for automated microservice candidate identification in monolith codebases?

The motivation for the research question is discussed in Chapter 1.

In current literature, several systematic mapping studies related to microservices architecture have been conducted [3], [4], as well as systematic literature reviews related to microservice decomposition . However, in these studies the techniques described are mainly used as an aid for the software architect when identifying microservice candidates. Therefore, we believe that there is a need for a systematic literature review aimed at summarizing existing literature regarding fully automated techniques for modularization of monolith codebases.

As a search strategy, the following platforms were queried for relevant publications:

1. IEEE Xplore[1]
2. ACM Digital Library[2]

The platforms were selected based on their academic relevance, as they contain a large number of publications in the field of software engineering. Furthermore, the platforms also contain only peer-reviewed publications, which ensures a certain level of quality in the publications.

Based on a list of relevant topics, we used a combination of related keywords to formulate the search query. We refrained from using more generic keywords, such as "architecture" or "design", as they would yield too many irrelevant results. The topics relevant for the search query are:

- *Architecture*: the architectural styles being discussed in the publications.
  Keywords: microservice, monolith, modular monolith
- *Modularization*: the process of identifying and decomposing modules in a monolith architecture.
  Keywords: service identification, microservice decomposition, monolith modularization
- *Technology*: the technologies, algorithms, or methods for modularization.
  Keywords: automated tool, machine learning, static analysis, dynamic analysis, hybrid analysis

The resulting search query can be expressed as follows:

```
1   (('microservice*' IN title OR abstract) OR
2    ('monolith*' IN title OR abstract))
3 AND
4   (('decompos*' IN title OR abstract) OR
5    ('identificat*' IN title OR abstract))
6 AND
7   ('automate*' IN title OR abstract)
```

Listing 1: Search query

The search query was adapted to the specific search syntax of the platform.

In addition to search queries on the selected platforms, we used snowballing to identify additional relevant publications. Snowballing is a research technique used to find additional publications of interest by following the references of the selected publications .

Based the inclusion/exclusion criteria in Table 2, the results were filtered, and the relevant studies were selected for inclusion in the systematic literature review.

| | Criteria |
|---|---|
| Inclusion | • Title, abstract or keywords include the search terms<br>• Conference papers, research articles, blog posts, or other peer-reviewed publications<br>• Publications addressing (semi-)automated technologies, algorithms, or methods |
| Exclusion | • Publications in languages other than English<br>• Publications not available in full text<br>• Publications using the term "microservice", but not referring to the architectural style<br>• Publications aimed at greenfield[3] or brownfield[4] development of microservice-based systems<br>• Publications published before 2014, as the definition of "microservices" as an architectural style is inconsistent before [4]<br>• Publications addressing manual technologies, algorithms, or methods<br>• Surveys, opinion pieces, or other non-technical publications |

Table 2: Inclusion and exclusion criteria

As a final step, the publications were subjected to a validation scan to ensure relevance and quality. To assess the quality, we mainly focused on the technical soundness of the approach or technique described in the publication.

The quality of the publication was assessed based on the following criteria:

• The publication is peer-reviewed or published in a respectable journal
• The publication thoroughly describes the technical aspects of the approach or technique
• The publication includes a validation phase or case study demonstrating the effectiveness of the approach or technique

This step is necessary to ensure that the selected publications are relevant to the research question and that the results are not biased by low-quality publications.

Once a final selection of publications was made, the resulting publications were qualitatively reviewed and categorized based on the type of approach or technique they describe.

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[3]Development of new software systems lacking constraints imposed by prior work [5]
[4]Development of new software systems in the presence of legacy software systems [5]

## 5.2. Conduct

Using the search strategy outlined in the previous section, we queried the selected platforms and found a total of 507 publications.

| Platform | Search results | Selected publications |
|---|---|---|
| IEEE Xplore | 339 | 33 |
| ACM Digital Library | 168 | 10 |
| Snowballing | | 0 |
| **Total** | 507 | 43 |

Table 3: Summary of search results

After applying the inclusion/exclusion criteria, we selected 43 publications for inclusion in the systematic literature review. Of these publications, 36 are primary studies, and 6 are secondary studies. The secondary studies were used to categorize the selected primary studies (if any), and as a starting point for the snowballing process, which resulted in 0 additional publications being included in the systematic literature review. For a list of the selected publications, see Appendix A.

From the selected publications, we extracted relevant information, such as the type of approach or technique described, the algorithms used, and the metrics discussed. As Kitchenham & Charters [2] suggest for systematic literature reviews done by single researchers, the data extraction was validated by a re-test procedure where the researcher performs a second extraction from a random selection of the publications to check the consistency of the extracted data.

## 5.3. Report

The publications selected for inclusion in the systematic literature review were qualitatively reviewed and categorized in three dimensions.

To begin with, we categorized the publications based on the Software Development Life Cycle (SDLC) artifact they use as input for the microservice candidate identification algorithm. Each artifact category has an associated collection type, either static, dynamic, or hybrid. [6]. Static collection describes a SDLC artifact that was collected without executing the software, while dynamic collection describes a SDLC artifact that was collected after or during execution of the software. Some publications describe algorithms or techniques that use a combination of SDLC artifacts, which we categorized as hybrid.

Thereafter we categorized the publications based on the algorithm used for microservice candidate identification. The algorithms were subdivided into several classes based on the technique.

Ultimately, the publications were also categorized by the metrics discussed.

### 5.3.1. SDLC artifact

The identified SDLC artifact categories used as input for the microservice candidate identification algorithm are described in Table 4. The categories are based on Bajaj, Bharti, Goel, & Gupta [6].

| Artifact | Type | Publications |
|---|---|---|
| Requirements documents and models | Static | [7]–[11] |
| Design documents | Static | [12]–[15] |
| Code | Static | [16]–[33] |
| Execution data | Dynamic | [20], [26], [30], [31], [34]–[37] |

Table 4: SDLC artifact categories

### 5.3.1.1. Requirements documents and models

In software engineering, requirements documents and models are used to formally describe the requirements of a software system following the specification of the business or stakeholder requirements [38]. They include functional and non-functional requirements, use cases, user stories, and business process models. Approaches using requirements documents and models as input for the microservice candidate identification algorithm often times need to pre-process the documents to extract the relevant information, as they are not intended to be directly read by a machine. In many cases, requirements documents and models for legacy systems are no longer available or outdated, which makes this approach less suitable for automated microservice identification.

Amiri [7] and Daoud, El Mezouari, Faci, Benslimane, Maamar, & El Fazziki [8] model a software system as a set of business process using the industry standard Business Process Model and Notation (BPMN), using the machine-readable XML representation as input for the algorithm. Yang, Wu, & Zhang [9] tackle requirements engineering using problem frames [39]. Problem frames are a requirements engineering method, which emphasizes the integration of real-world elements into the software system [9].

Some approaches use schematic requirements documents in XML format as input for the algorithm, as described by Saidi, Tissaoui, & Faiz [10]. The latter use domain-driven design techniques to extract functional dependencies from the software design as starting point in microservice identification. Li, Zhang, Yang, Wang, & Yin [11] employ an intermediate format containing a precise definition of business functionality, generated from validated requirements documents.

### 5.3.1.2. Design documents

Design documents created by software architects are machine-readable representations of the software system. They describe the software functionalities in detail and are used to guide

the implementation of the software system. Design documents include API specifications, UML diagrams (such as class diagrams and sequence diagrams), and entity-relationship diagrams.

Techniques using design documents either use a domain-driven approach, or a data-driven approach. Domain-driven approaches use domain-specific knowledge to identify microservice candidates, while data-driven approaches use knowledge about data storage and data flow to identify microservice candidates. Similar to requirements documents and models, design documents for legacy systems are often not available or outdated, although some design documents can be reconstructed from the software system (e.g., reverse engineering entity-relationship diagrams from the database schema).

For example, Al-Debagy & Martinek [12] propose a data-driven method based on the analysis of the software system's external API, specified in the OpenAPI[5] format. The method extracts the information from the specification and converts it into vector representation for further processing.

Zhou & Xiong [13] use readily available design documents as well, in the form of UML class diagrams, use cases, and object sequence diagrams as starting point for the microservice identification algorithm.

Quattrocchi, Cocco, Staffa, Margara, & Cugola [14] takes a different approach to the problem, using a data-driven approach combined with a domain-driven approach. Software architects describe the software system using a custom architecture description language, and the tool developed by the authors is able to identify microservice candidates. The tool can be prompted to generate different, more efficient decompositions when given additional domain-driven requirements. Wei, Yu, Pan, & Zhang [15] uses a similar approach, gathering a list of features from the software architect, and proposing a microservice decomposition based on pre-trained feature tables.

### 5.3.1.3. Code

A third category of SDLC artifacts is the executable code of the software system. This can be the source code of the software system, or a binary distribution (e.g. a JAR file). For example, the implementation in [24] accepts either source code or compiled binary code for analysis.

As the source code of the software system is the most detailed representation of how the software system works, it is most often used as input for the microservice candidate identification algorithm. The source code can be analyzed using static analysis (i.e., without executing the software system), dynamic analysis (i.e., during the execution of the software system or test suite), or a combination of both. Dynamic analysis has the advantage that it can be used if the source code is not available.

Additionally, the revision history of the source code can also be used as source for valuable information about the behaviour of the software system. For example, Mazlami, Cito, & Leitner [17]

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[5]https://www.openapis.org/

and Lourenço & Silva [30] use both the structure of the source code, as well as the revision history to drive the identification algorithm.

Escobar, Cardenas, Amarillo, Castro, Garces, Parra, & Casallas [16] use the source code of the software system to construct an Abstract Syntax Tree (AST), and map the dependencies between the business and data layer. Kamimura, Yano, Hatano, & Matsuo [18] use a more data-driven approach, and statically trace data access calls in the source code.

Several publications [19], [24], [26]–[28] construct a dependency graph from Java source code, and use the graph as input for a clustering algorithm. Bandara & Perera [21] map object-oriented classes in the source code to specific microservices, but require a list of microservices to be specified before the decomposition is performed.

Filippone, Autili, Rossi, & Tivoli [22] concentrate on the API controllers as entrypoints into the software system. A later paper by the same authors [23] builds on top of this approach by using the API endpoints as entrypoints, and then ascending into the source code by separating the presentation and logic layer. Likewise, Zaragoza, Seriai, Seriai, Shatnawi, & Derras [27] make a distinction between presentation, business, and data layer.

Most of the publications tracing dependencies between classes (or modules) do this at the level of the classes (or modules). As Mazlami, Cito, & Leitner [17] remark, using a more granular approach at the level of methods (or functions) and attributes has the potential to improve the quality of the decomposition. Carvalho, Garcia, Colanzi, Assuncao, Pereira, Fonseca, Ribeiro, De Lima, & Lucena [20] use a more granular approach, identifying dependencies between methods in the source code. On the other hand, Kinoshita & Kanuka [25] do not automatically extract information from the source code, but rely on a software architect to decompose the software system on the basis of business capability.

Romani, Tibermacine, & Tibermacine [29] propose a data-centric microservice candidate identification method based on knowledge gathered from the database schema. The authors extract table and column methods from the database schema, and use the semantically enriched information as input for the identification algorithm. Hao, Zhao, & Li [31] construct access patterns from both the database schema (static) and the database calls during execution of the software system (dynamic).

### 5.3.1.4. Execution

As a last category, information about the behaviour of the system can also be collected during the runtime of the software system. Execution data includes log files, execution traces, and performance metrics. This category is often combined with static analysis on source code, as the execution data can provide additional information to the identification algorithm. In dynamic languages such as Java, dynamic analysis can trace access patterns that static analysis cannot (e.g., due to late binding

and polymorphism). Additionally, execution data can be collected when the source code of the software system is not available.

Examples of approaches using execution traces are Jin, Liu, Cai, Kazman, Mo, & Zheng [34] and Eyitemi & Reiff-Marganiec [37]. Using software probes inserted into the bytecode of respectively Java and .NET applications, the authors are able to monitor execution paths. Zhang, Liu, Dai, Chen, & Cao [35] collect the execution traces of the software system, in combination with performance logs.

Ma, Lu, & Li [36] use a data-centric approach based on the analysis of database access requests.

### 5.3.1.5. Hybrid approach

Some publications suggest a hybrid approach using both static and dynamic analysis. For instance, Wu & Zhang [26] and Carvalho, Garcia, Colanzi, Assuncao, Pereira, Fonseca, Ribeiro, De Lima, & Lucena [20] collect information statically from the source code (entity classes and databases), as well as dynamically from the execution of the software system (execution traces). The approach proposed by Lourenço & Silva [30] uses either static of the source code or dynamic analysis of the system execution to gather access patterns.

Hao, Zhao, & Li [31] use both static and dynamic analysis, albeit aimed at the database schema and database calls, respectively.

### 5.3.2. Algorithms

Microservice candidate identification is a problem that is often solved by representing the architecture as a directed graph. The graph exposes the relationship between the elements of the software architectures. The nodes of the graph represent the classes, modules, or components, and the edges the function or method calls between them. Often the edges are weighted, representing the frequency or cost of the calls. Based on the information contained within, the graph is then divided into several clusters, each encapsulating a microservice candidate. The goal is to find a partitioning of the graph that minimizes the number of edges between clusters and maximizes the number of edges within clusters.

The identified classes of microservice candidate identification algorithms are described in Table 5.

| Type | Example algorithms | Publications |
|---|---|---|
| Clustering algorithms | K-Means, DBSCAN, Hierarchical Agglomerative Clustering, Affinity Propagation | [8], [10], [12], [19], [21], [26]–[31], [36], [33] |
| Evolutionary algorithms | NSGA-II, NSGA-III | [7], [11], [13], [20], [25], [34], [35] |
| Graph algorithms | Kruskal, Louvain method | [9], [17], [23], [32] |
| Other algorithms | Linear optimization, custom algorithms | [14], [16], [18], [19], [22], [24], [37], [15] |

Table 5: Microservice candidate identification algorithm

### 5.3.2.1. Clustering algorithms

The first class of algorithms identified in the literature is clustering algorithms. Clustering algorithms are unsupervised machine learning algorithms that aim to find an optimal partitioning of the graph. Typical clustering algorithms used for this purpose are K-Means clustering and agglomerative clustering.

Examples of publications using K-Means clustering to identify microservice candidates are Saidi, Tissaoui, & Faiz [10], Wu & Zhang [26], Romani, Tibermacine, & Tibermacine [29], and Hao, Zhao, & Li [31].

Al-Debagy & Martinek [12] use Affinity Propagation [40] to cluster vector representations of operation names in a software system. Affinity Propagation is a clustering algorithm that identifies exemplars in the data, which are used to represent the clusters.

Hierarchical clustering approaches are used in various publications [19], [28], [30], [36], [27], [21]. Lourenço & Silva [30] uses similarity between domain entities accesses and development history of source code files as a guiding measure for the clustering algorithm, while Zaragoza, Seriai, Seriai, Shatnawi, & Derras [27] uses structural and data cohesion of microservices. Daoud, El Mezouari, Faci, Benslimane, Maamar, & El Fazziki [8] extend the hierarchical agglomerative clustering (HAC) algorithm [41] with a collaborative approach, where the clustering is performed by multiple homogenous clustering nodes, each responsible for a subset of the data.

Selmadji, Seriai, Bouziane, Oumarou Mahamane, Zaragoza, & Dony [19] propose two possible algorithms for microservice identification: a hierarchical clustering algorithm, and a clustering algorithm based on gravity centers.

Sellami, Saied, & Ouni [33] use the Density-Based Spatial Clustering of Applications with Noise (DBSCAN) algorithm [42] to identify microservices.

### 5.3.2.2. Evolutionary algorithms

Evolutionary algorithms are the second class of algorithms present in the literature. Evolutionary algorithms, and in particular genetic algorithms, are algorithms aimed at solving optimization problems by borrowing techniques from natural selection and genetics. These algorithms typically operate iteratively, selecting the best solutions from a population at each iteration (called a generation), and then combining the selected solutions to create new combinations for the next generation. The process is then repeated until certain criteria are met, for example a maximum number of generations, convergence of the population, or a quality indicator.

Examples of publications using Non-Dominated Sorting Algorithm II (NGSA-II) as multi-objective optimization algorithm to identify microservice candidates are Zhou & Xiong [13], Kinoshita & Kanuka [25], Zhang, Liu, Dai, Chen, & Cao [35], Jin, Liu, Cai, Kazman, Mo, & Zheng [34], and Li, Zhang, Yang, Wang, & Yin [11]. Carvalho, Garcia, Colanzi, Assuncao, Pereira, Fonseca, Ribeiro, De Lima, & Lucena [20] use the next generation of NSGA, NSGA-III, in order to find a solution for the problem.

Amiri [7] rely on a genetic algorithm using Turbo-MQ [43] as fitness function.

### 5.3.2.3. Graph algorithms

Another common approach to identify microservice candidates is to use classical algorithms from graph theory.

For example, Mazlami, Cito, & Leitner [17] and Yang, Wu, & Zhang [9] use Kruskal's algorithm [44] to partition the graph into connected clusters. Kruskal's algorithm is a greedy algorithm that finds the minimum spanning forest for an undirected weighted graph.

Filippone, Qaisar Mehmood, Autili, Rossi, & Tivoli [23] apply the Louvain community detection algorithm [45] to obtain the granularity of the microservices, and high-cohesive communities of nodes. The Louvain method is a greedy optimization algorithm that aims to extract non-overlapping communities from a graph, using the modularity value as optimization target.

### 5.3.2.4. Other algorithms

Other publications using algorithms that do not fit into one of the previous categories are grouped in a single category.

For example, the authors of Quattrocchi, Cocco, Staffa, Margara, & Cugola [14] incorporated a Mixed Integer Linear Programming (MILP) solver in their solution. The MILP solver is used to find a solution for an optimization problem that decomposes the software system into microservices, based on the placement of operations and data entities according to the users' needs. Filippone, Autili, Rossi, & Tivoli [22] use a linear optimization algorithm to solve a combinatorial optimization problem.

The approach taken by Kamimura, Yano, Hatano, & Matsuo [18] is to use a custom clustering algorithm named SArF [46], that aims at identifying software subsystems without the need for human intervention. Escobar, Cardenas, Amarillo, Castro, Garces, Parra, & Casallas [16] also use a custom clustering algorithm, detecting optimal microservices based on a meta-model of the class hierarchy.

Agarwal, Sinha, Sridhara, Das, Desai, Tamilselvam, Singhee, & Nakamuro [24] propose an algorithm based on seed expansion. The seed classes are detected by using formal concept analysis. Then, using a seed expansion algorithm, clusters are created around the seeds by pulling in related code artefacts based on implementation structure of the software system [24].

Eyitemi & Reiff-Marganiec [37] use a rule-based approach to microservice candidate identification. The 6 proposed rules are based on the principles of high cohesion and low coupling, and using a step-based protocol can be used to manually decompose a monolithic system into microservices.

### 5.3.3. Metrics

The quality metrics used in the publications are summarized in Table 6. The metrics are used to quantitatively evaluate the quality of the generated microservice decomposition. Some of the algorithms require the use of a specific metric to guide the process, such as the fitness function in genetic algorithms.

| Metric | Publications |
| --- | --- |
| Cohesion | [8], [11]–[14], [19]–[23], [26]–[28], [30], [34], [35], [32], [15], [33] |
| Coupling | [8], [11], [13], [19]–[24], [26], [28], [30], [34], [35], [32], [15], [33] |
| Network overhead | [13], [14], [20], [22] |
| Complexity | [12], [28], [30] |
| CPU and memory usage | [14], [35] |
| Modularity | [11], [21], [34], [26], [32], [33] |
| Other metrics | [9]–[11], [17]–[19], [23], [30], [31], [36], [15], [33] |
| No metrics | [16], [25], [29], [37] |

Table 6: Quality metrics

### 5.3.3.1. Cohesion and coupling

The quality metrics most frequently mentioned in the literature are cohesion and coupling. The behaviour of information systems has been studied with the help of these metrics and others such as size and complexity since the 1970s [47]. As object-oriented programming became more popular, the concepts of cohesion and coupling were adapted to the new paradigm [48].

Throughout the years, many definitions of cohesion and coupling have been proposed both for procedural and object-oriented systems. For example, Briand et al. [49] define cohesion as the tightness with which related program features are grouped together, and coupling as the amount of relationships between the elements belonging to different modules of a system.

The publications in this review use different definitions for cohesion and coupling, and different methods of calculating them. For example, Selmadji, Seriai, Bouziane, Oumarou Mahamane, Zaragoza, & Dony [19] define (internal) cohesion as the number of direct connections between the methods of the classes belonging to a microservice over the number of possible connections

between the methods of the classes. The authors then define internal coupling as the number of direct method calls between two classes over the total number of method calls in the application.

Others [20], [22], [13], [35], [24], [21] use a similar definition of cohesion, but they define (individual) coupling as the number of method calls from a microservice class to another class outside of the service boundary. The total coupling of the solution is the sum of the coupling of all microservices. Similarly, Filippone, Qaisar Mehmood, Autili, Rossi, & Tivoli [23] define average cohesion and average coupling as ratio of the total cohesion and coupling respectively, to the number of microservices in the decomposition.

Jin, Liu, Cai, Kazman, Mo, & Zheng [34] introduce the concept of inter-service cohesion and inter-call percentage (ICP) as coupling metrics. Several other publications use the metrics introduced by W. Jin, T. Liu, Y. Cai, R. Kazman, R. Mo, and Q. Zheng in their research [26], [32], [33].

Another approach to cohesion and coupling is that of Santos & Silva [28] and Lourenço & Silva [30], who define cohesion as the percentage of entities accessed by a functionality. If all entities belonging to a microservice candidate are accessed each time a microservice candidate is accessed, the service is strongly cohesive. Coupling is defined as the percentage of the entities exposed by a microservice candidate that are accessed by other microservice candidates.

Al-Debagy & Martinek [12] use the inverse of cohesion as a metric, named lack of cohesion (LCOM). It is calculated by the number of times a microservice uses a method from another microservice, divided by the number of operations multiplied by the number of unique parameters. This metric quantifies how the operations in a service are related to each other in terms of functionality.

### 5.3.3.2. Network overhead

Microservices are distributed systems, and communication between services is done over a network. The network overhead is the extra cost of this communication, and many authors consider it an important metric to consider when designing a microservice architecture.

Filippone, Autili, Rossi, & Tivoli [22] and others [20], [13] calculate the value based using a heuristic function that uses the size of primitive types of method call arguments to predict the total network overhead of a microservice decomposition. Carvalho, Garcia, Colanzi, Assuncao, Pereira, Fonseca, Ribeiro, De Lima, & Lucena [20] also includes the protocol overhead in the calculation, which is the cost of the communication protocol used to send messages between services (for example, TCP headers, HTTP headers, etc.).

Quattrocchi, Cocco, Staffa, Margara, & Cugola [14] measure network overhead as part of their operational cost metric. The metric also includes data management costs (CPU and memory).

### 5.3.3.3. Complexity

The complexity of a microservice candidate is another metric that can impact the quality of the microservice decomposition. Al-Debagy & Martinek [12] defines complexity based on Number of Operations, a metric that uses Weighted Methods per Class (WMC), summing the number of methods in a class.

Santos & Silva [28] define the complexity metric in terms of the functionality redesign effort, rather than the complexity of the microservice candidates. The metric is associated with the cognitive load of the software architect when considering a migration from monolith to microservice.

In another publication by the same co-author, Lourenço & Silva [30] define complexity as the effort required to perform the decomposition, and expand the concept to uniform complexity, which is calculated by dividing the complexity of a decomposition by the maximum possible complexity.

### 5.3.3.4. CPU and memory usage

A non-functional metric that is considered by some authors is the CPU and/or memory usage of the microservices. Zhang, Liu, Dai, Chen, & Cao [35] use this metric to evaluate the quality of the microservice decomposition, by predicting the average CPU and memory usage of the microservices. The prediction is made based on performance logs collected by executing the monolith application.

Quattrocchi, Cocco, Staffa, Margara, & Cugola [14] define operational costs as metric to minimize, which includes communication (network) and data management (CPU and memory) costs.

### 5.3.3.5. Modularity

Modularity is a measure of independence of services, and can be divided into many dimensions, such as structure, concept, history, and dynamism [50].

Jin, Liu, Cai, Kazman, Mo, & Zheng [34] use modularity as a metric to evaluate potential decompositions. The authors use Modularity Quality [51] and extend the concept with structural and conceptual dependencies to assess the modularity of microservice candidates.

Carvalho, Garcia, Colanzi, Assuncao, Pereira, Fonseca, Ribeiro, De Lima, & Lucena [20] introduce a metric named feature modularization, which maps a list of features supplied by the software architect onto classes and methods, determining the set of predominant features per microservice.

### 5.3.3.6. Other metrics

Lourenço & Silva [30] introduce the concept of Team Size Reduction (TSR), which indicates if the average team size is shorter after the decomposition, by comparing the average number of authors per microservice to the total number of authors. A Team Size Reduction value of 1 indicates that the microservices architecture has the same number of authors as the monolith, while a value less than

1 indicates a reduction in the number of authors. Mazlami, Cito, & Leitner [17] make use of the TSR metric, as well as the Average Domain Redundancy (ADR) metric, which represents the amount of domain-specific duplication or redundancy between the microservices. The ADR metric uses a scale from 0 to 1, where 0 indicates no redundancy and 1 indicates that all microservices are redundant.

Carvalho, Garcia, Colanzi, Assuncao, Pereira, Fonseca, Ribeiro, De Lima, & Lucena [20] propose a metric called reuse, which measures the reusability of a microservice. Reuse is calculated as the number of times a microservice is called by the user, relying on dynamic analysis to collect this information.

The usage metric of an object-oriented software system, defined as the sum of the inheritance factor (is-a) and the composition factor (has-a) is used by Bandara & Perera [21] as a part of the fitness function for the clustering algorithm.

Saidi, Tissaoui, & Faiz [10] use the intra-domain and inter-domain data dependency metrics to delineate microservice boundaries, based on the read and write access pattern of the operations. In a similar fashion, Selmadji, Seriai, Bouziane, Oumarou Mahamane, Zaragoza, & Dony [19] talk about data autonomy determined by the internal and external data access of a microservice candidate.

Kamimura, Yano, Hatano, & Matsuo [18] introduce a metric called dedication score, which measures the relationships between services as a function of access frequency. Along with a modularity metric, the dedication score is used in their custom SArF dependency-based clustering algorithm [46].

The correlation metric is used by Yang, Wu, & Zhang [9] and indicates the degree of correlation between the microservices. The authors calculate the correlation in two ways: the number of co-occurrence of the problem domain, and the adjacency relationship between problem domains.

Ma, Lu, & Li [36] use the Adjusted Rand Index (ARI) as clustering evaluation criterion. The metric measures the similarity between two clusters in a decomposition, and ranges from −1 to 1, with 0 being the optimal value.

Hao, Zhao, & Li [31] use the Matching Degree metric as quality indicator. The metric is calculated by dividing the number of intersections of database tables in a given microservice and a given cluster by the total number of tables used in the microservice.

### 5.3.3.7. No metrics

Finally, some of the publications publications, do not mention any quality metrics used in the evaluation of the proposed decomposition. These methods typically rely on the selection or approval of a software architect to choose the best decomposition, based on their experience and knowledge of the system. This is the case of Eyitemi & Reiff-Marganiec [37], Romani, Tibermacine, & Tibermacine [29], Amiri [7], and Escobar, Cardenas, Amarillo, Castro, Garces, Parra, & Casallas [16].

The evaluation method by Kinoshita & Kanuka [25] also does not rely on quantifying the quality of the microservice decomposition using metrics, but rather relies on the software architect's judgement to choose a qualitative decomposition.

### 5.3.4. Conclusion

# 6. Proposed solution

In this chapter, we analyze and design our solution for identification of microservice candidates. We start by identifying the functional and non-functional requirements for the solution.

Then, we propose a microservice decomposition approach using the three-step process by Abdellatif et al. [52].

- **Collect**: the necessary data is collected from the application and its environment.
- **Decomposition**: using the collected data, a decomposition of the application into microservices is proposed.
- **Analysis**: the proposed decomposition is analyzed to evaluate the effectiveness of the chosen approach.
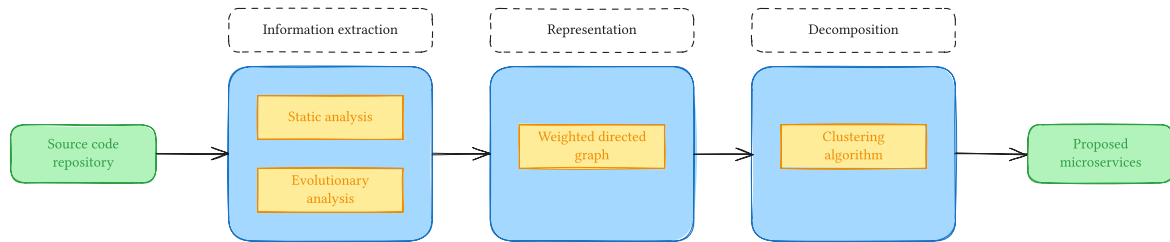


Figure 2: Overview of the architecture of the proposed solution

## 6.1. Requirements

## 6.2. Collection

## 6.3. Decomposition

## 6.4. Analysis

# 7. Case study

## 7.1. Background

## 7.2. Experimental setup

## 7.3. Evaluation and results

## 7.4. Discussion

## 7.5. Threats to validity

# 8. Conclusion

## 8.1. Future work

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# A Systematic Literature Review (SLR) publications

## Primary studies

| | Publication |
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| 1 | [10] M. Saidi, A. Tissaoui, and S. Faiz, "A DDD Approach Towards Automatic Migration To Microservices," in *2023 IEEE International Conference on Advanced Systems and Emergent Technologies (IC_ASET)*, Hammamet, Tunisia: IEEE, Apr. 2023, pp. 1–6. doi: 10.1109/IC_ASET58101.2023.10150522. |
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Table 7: Selected publications (primary studies)

## Secondary studies

| | Publication |
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Table 8: Selected publications (secondary studies)

# B Examples

Examples First page

```ruby
1  class Example
2    def initialize
3      @text = "Hello world"
4    end
5
6    def say_hello
7      puts @text
8    end
9  end
10
11 example = Example.new
12
13 example.say_hello
14 # => Hello world
```

Listing 2: Ruby code example

Examples Second page