

SEMINAR 10

Spatii vectoriale euclidieneTransformări ortogonale

OBS

 $(E, \langle \cdot, \cdot \rangle)$ s.v.e.r., $f \in \text{End}(E)$

$$\bullet f \in O(E) \text{ (transformare ortogonală)} \Leftrightarrow \langle f(x), f(y) \rangle = \langle x, y \rangle \quad \forall x, y \in E$$

$$\Leftrightarrow \|f(x)\| = \|x\|, \quad \forall x \in E.$$

$$\bullet f \in O(E) \Leftrightarrow A = [f]_R, R \in O(n) \Leftrightarrow \text{schimbare de repere ortonormate}$$

$$\forall R = \text{reper ortonormat}$$

$$\bullet f \in O(E) \Rightarrow \text{valorile proprii sunt } \pm 1.$$

Clasificare

$$\textcircled{1} \dim E = 1 \Rightarrow O(E) = \{id_E, -id_E\}$$

$$\textcircled{2} \dim E = 2$$

a) $\det A = 1$, $\exists R = \{e_1, e_2\}$ reper ortonormal $A = \begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix}$

b) $\det A = -1$ $\quad \quad \quad A = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$

$$\textcircled{3} \dim E = 3$$

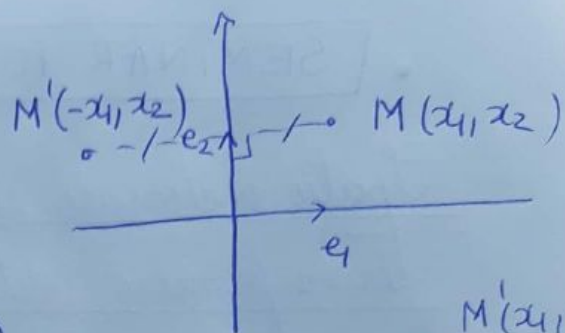
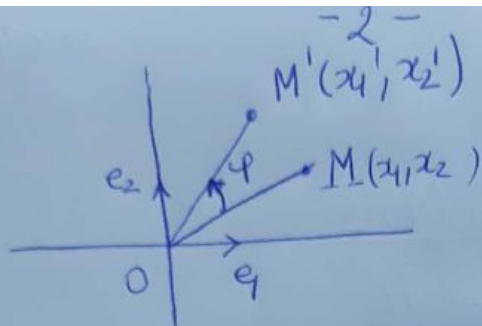
a) $\det A = 1$, $\exists R = \{e_1, e_2, e_3\}$ reper ortonormal

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \varphi & -\sin \varphi \\ 0 & \sin \varphi & \cos \varphi \end{pmatrix} \begin{cases} \rightarrow \text{Tr} A = 1 + 2\cos \varphi \\ \rightarrow \text{Axa: } f(x) = x \end{cases}$$

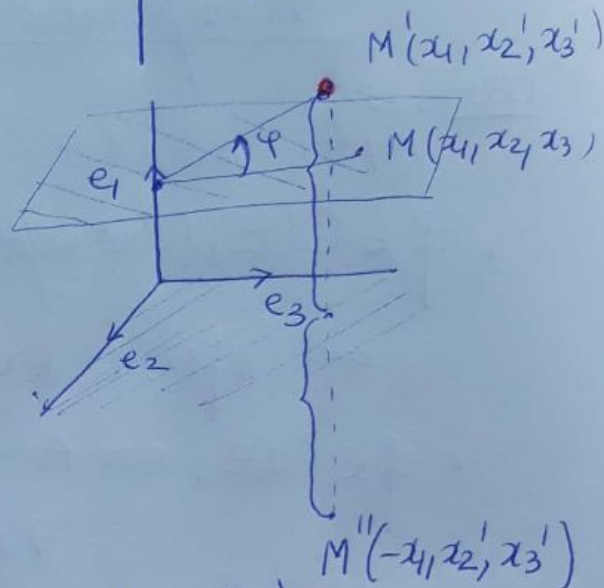
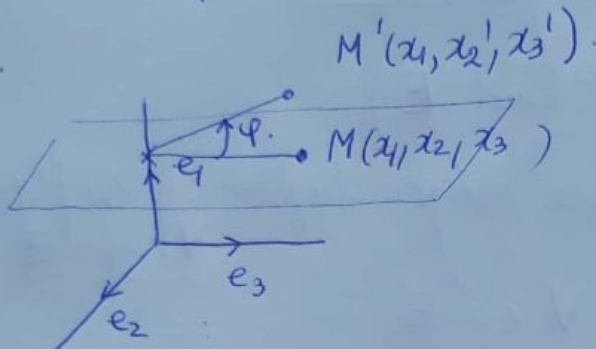
b) $\det A = -1$, $\exists R = \{e_1, e_2, e_3\}$ reper ortonormal

$$A = \begin{pmatrix} -1 & 0 & 0 \\ 0 & \cos \varphi & -\sin \varphi \\ 0 & \sin \varphi & \cos \varphi \end{pmatrix} \begin{cases} \rightarrow \text{Tr} A = -1 + 2\cos \varphi \\ \rightarrow \text{Axa: } f(x) = -x \end{cases}$$

$n=2$



$n=3$



Ex1. (\mathbb{R}^3, g_0) s.v.e.r, cu str. canonică

$$f \in \text{End}(\mathbb{R}^3), A = [f]_{R_0, R_0} = \frac{1}{g} \begin{pmatrix} 8 & 1 & -4 \\ 1 & 8 & 4 \\ -4 & 4 & -7 \end{pmatrix}$$

$R_0 = \text{reperul canonic}$

a) Să se arate că $f \in O(\mathbb{R}^3)$ de spectră 2 $\Rightarrow f = s \circ R_\varphi$

b) Să se det φ de rot φ și axa de simetrie

c) Să se det un reper $R = \{e_1, e_2, e_3\}$ ortonormat

$$\text{cu } [f]_{R, R} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & \cos \varphi & -\sin \varphi \\ 0 & \sin \varphi & \cos \varphi \end{pmatrix}$$

SOL

a) Dem că $A \in O(3)$ i.e. $A A^T = I_3$ și $\det A = -1$.

$$\begin{aligned} \textcircled{M_1} \quad A \cdot A^T &= \frac{1}{g^2} \begin{pmatrix} 8 & 1 & -4 \\ 1 & 8 & 4 \\ -4 & 4 & -7 \end{pmatrix} \begin{pmatrix} 8 & 1 & -4 \\ 1 & 8 & 4 \\ -4 & 4 & -7 \end{pmatrix} \\ &= \frac{1}{g^2} \begin{pmatrix} g^2 & 0 & 0 \\ 0 & g^2 & 0 \\ 0 & 0 & g^2 \end{pmatrix} = I_3 \Rightarrow A \in O(3) \end{aligned}$$

$$(M_2) \mathcal{R}_0 = \{e_1^0, e_2^0, e_3^0\} \xrightarrow{A} \mathcal{R}' = \{e_1', e_2', e_3'\}$$

$$f(e_i^0) = e_i'$$

$$e_1' = \frac{1}{9}(8, 1, -4); e_2' = \frac{1}{9}(1, 8, 4); e_3' = \frac{1}{9}(-4, 4, -7)$$

$$\|e_1'\| = \frac{1}{9} \sqrt{64+1+16} = \frac{1}{9} \cdot 9 = 1$$

$$\|e_2'\| = \frac{1}{9} \sqrt{1+64+16} = 1$$

$$\|e_3'\| = \frac{1}{9} \sqrt{16+16+49} = \frac{1}{9} \cdot 9 = 1.$$

$$\langle e_1', e_2' \rangle = \frac{1}{9^2} (8+8-16) = 0$$

$$\langle e_1', e_3' \rangle = \frac{1}{9^2} (-32+4+28) = 0$$

$$\langle e_2', e_3' \rangle = \frac{1}{9^2} (-4+32-28) = 0$$

$$\mathcal{R}' \text{ repere orthonormal} \Leftrightarrow f \in O(\mathbb{R}^3)$$

$$\det A = \frac{1}{9^3} \begin{vmatrix} 8 & 1 & -4 \\ 1 & 8 & 4 \\ -4 & 4 & -7 \end{vmatrix} = \frac{1}{9^3} \begin{vmatrix} 0 & 1 & 0 \\ -63 & 8 & 36 \\ -36 & 4 & 9 \end{vmatrix}$$

$$= + \frac{1}{9^3} \cdot 9^2 \begin{vmatrix} 7 & 4 \\ 4 & 1 \end{vmatrix} = \frac{1}{9} (7-16) = -\frac{9}{9} = -1$$

$$f \in O(\mathbb{R}^3) \text{ de speta } 2.$$

$$b) \operatorname{Tr} A = -1 + 2 \cos \varphi = \frac{1}{9} (8+8-7) = 1$$

$$\left. \begin{array}{l} 2 \cos \varphi = 2 \Rightarrow \cos \varphi = 1 \\ \text{dar } \varphi \in (-\pi, \pi] \end{array} \right\} \Rightarrow \varphi = 0$$

$$\text{Axa: } f(x) = -x$$

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}^3, f(x_1, x_2, x_3) = \frac{1}{9} (8x_1 + x_2 - 4x_3, x_1 + 8x_2 + 4x_3, -4x_1 + 4x_2 - 7x_3)$$

$$\begin{cases} 8x_1 + x_2 - 4x_3 = -9x_1 \\ x_1 + 8x_2 + 4x_3 = -9x_2 \\ -4x_1 + 4x_2 - 7x_3 = -9x_3 \end{cases} \Rightarrow \begin{cases} 17x_1 + x_2 - 4x_3 = 0 \\ x_1 + 17x_2 + 4x_3 = 0 \\ -4x_1 + 4x_2 + 2x_3 = 0 \end{cases}$$

$$M = \left(\begin{array}{ccc|c} 17 & 1 & -4 & -4 \\ 1 & 17 & 4 & 0 \\ -4 & 4 & 2 & 0 \end{array} \right)$$

$$\det M = 0, \operatorname{rg} M = 2.$$

$$\begin{vmatrix} 17 & 1 & -4 \\ 1 & 17 & 4 \\ -4 & 4 & 2 \end{vmatrix} = 2 \begin{vmatrix} 17 & 1 & -2 \\ 1 & 17 & 2 \\ -4 & 4 & 1 \end{vmatrix} = 2 \begin{vmatrix} 9 & 9 & -2 \\ 9 & 9 & 2 \\ 0 & 0 & 1 \end{vmatrix} = 0$$

$$ec1 + ec2: 18(x_1 + x_2) = 0 \Rightarrow x_2 = -x_1.$$

$$ec3: -4x_1 - 4x_1 + 2x_3 = 0 \Rightarrow 8x_1 = 2x_3 \Rightarrow x_1 = \frac{x_3}{4}$$

$$x_2 = -\frac{x_3}{4}$$

$$(x_1, x_2, x_3) = \left(\frac{x_3}{4}, -\frac{x_3}{4}, x_3 \right) = \frac{x_3}{4} \underbrace{(1, -1, 4)}_{u}$$

$$Ax = \langle \{u\} \rangle$$

$$e_1 = \frac{1}{3\sqrt{2}} (1, -1, 4) \text{ versorul axei } (x_2, x_2, 0) + (-4x_3, 0, x_3)$$

$$c) \langle \{u\} \rangle^\perp = \{x \in \mathbb{R}^3 \mid q_0(x, u) = 0\} = \left\{ \begin{array}{l} (x_2 - 4x_3, x_2, x_3) \\ x_2, x_3 \in \mathbb{R} \end{array} \right\}$$

$x = (x_1, x_2, x_3)$
 $u = (1, -1, 4)$
 $q_0(x, u) = x_1 - x_2 + 4x_3$

$$= \left\{ \underbrace{x_2(1, 1, 0)}_{f_2} + \underbrace{x_3(-4, 0, 1)}_{f_3} \mid x_2, x_3 \in \mathbb{R} \right\}$$

$$\{f_2, f_3\} \text{ SG pt } \langle \{u\} \rangle^\perp \Rightarrow \{f_2, f_3\} \text{ reper in } \langle \{u\} \rangle^\perp$$

$$\mathbb{R}^3 = \langle \{u\} \rangle \oplus \langle \{u\} \rangle^\perp$$

\downarrow 1-dim \downarrow 2-dim

Aplicăm Gram-Schmidt

$$\bar{e}_2 = f_2$$

$$\bar{e}_3 = f_3 - \frac{\langle f_3, \bar{e}_2 \rangle}{\langle \bar{e}_2, \bar{e}_2 \rangle} \bar{e}_2$$

$$\bar{e}_2 = (1, 1, 0)$$

$$\bar{e}_3 = (-4, 0, 1) - \frac{-4}{2} (1, 1, 0) = (-4, 0, 1) + (2, 2, 0) = (-2, 2, 1)$$

$\{\bar{e}_2, \bar{e}_3\}$ reper ortog în $\langle \{u\} \rangle^\perp$

$$\left\{ e_2 = \frac{\bar{e}_2}{\|\bar{e}_2\|} = \frac{1}{\sqrt{2}} (1, 1, 0), e_3 = \frac{\bar{e}_3}{\|\bar{e}_3\|} = \frac{1}{3} (-2, 2, 1) \right\}$$

reper ortonormat în $\langle \{u\} \rangle^\perp$

$\mathcal{R} = \{e_1, e_2, e_3\}$ reper orton în \mathbb{R}^3 ai

$$[f]_{\mathcal{R}, \mathcal{R}} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & \cos \varphi & -\sin \varphi \\ 0 & \sin \varphi & \cos \varphi \end{pmatrix} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Ex2 $(\mathbb{R}^3, g_0), u = (1, 1, 0)$

a) $\langle \{u\} \rangle^\perp = ?$. Să se precizeze un reper ortonormat

b) Să se det transf. ortogonală de spați 1, care este rotație de \neq orientat $\varphi = \frac{\pi}{2}$ și axă $\langle \{u\} \rangle$.

Sol

$$a) \langle \{u\} \rangle^\perp = \left\{ x \in \mathbb{R}^3 \mid g_0(\underbrace{u}_{x_1+x_2}, x) = 0 \right\} = \left\{ \underbrace{(-x_2, x_2, x_3)}_{x_2(-1, 1, 0) + x_3(0, 0, 1)} \mid x_2, x_3 \in \mathbb{R} \right\}$$

$\{f_2, f_3\}$ reper în $\langle \{u\} \rangle^\perp \Rightarrow$ reper ortogonal

$$g_0(f_2, f_3) = 0$$

$\left\{ e_2 = \frac{1}{\sqrt{2}} (-1, 1, 0), e_3 = (0, 0, 1) \right\}$ reper ortonormat în $\langle \{u\} \rangle^\perp$.

b) $e_1 = \frac{u}{\|u\|} = \frac{1}{\sqrt{2}} (1, 1, 0)$ vectorul axei

$\mathcal{R} = \{e_1, e_2, e_3\}$ reper ortonormat în \mathbb{R}^3

$$[f]_{R,R} = A' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \varphi & -\sin \varphi \\ 0 & \sin \varphi & \cos \varphi \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\mathcal{R}_0 = \{e_1^0, e_2^0, e_3^0\} \xrightarrow{C} \mathcal{R} = \{\underline{e}_1, \underline{e}_2, \underline{e}_3\} \text{ repere orthonormal canonique} \quad C \in O(3)$$

$$C = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & \sqrt{2} \end{pmatrix}$$

$$e_1 = \frac{1}{\sqrt{2}} (1, 1, 0) = \frac{1}{\sqrt{2}} \underbrace{(1, 0, 0)}_{e_1^0} + \frac{1}{2} \underbrace{(0, 1, 0)}_{e_2^0} + 0 \cdot e_3^0$$

$$\boxed{A' = C^{-1} A C} \Rightarrow A = C A' C^{-1} = C A' C^T$$

$$= \frac{1}{2} \begin{pmatrix} 1 & -1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & \sqrt{2} \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & \sqrt{2} \end{pmatrix}$$

$$= \frac{1}{2} \begin{pmatrix} 1 & 0 & 1 \\ 1 & 0 & -1 \\ 0 & -\sqrt{2} & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & \sqrt{2} \end{pmatrix} =$$

$$A = \frac{1}{2} \begin{pmatrix} 1 & 1 & \sqrt{2} \\ 1 & 1 & -\sqrt{2} \\ -\sqrt{2} & \sqrt{2} & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}^3, f(x) = \frac{1}{2} (x_1 + x_2 + \sqrt{2}x_3, x_1 + x_2 - \sqrt{2}x_3, -\sqrt{2}x_1 + \sqrt{2}x_2)$$

$f \in O(\mathbb{R}^3)$ de sp \check{e} 1

Ex3 $(E, \langle \cdot, \cdot \rangle)$ s.v.e.r, $u, v \in E$

UAE 1) $u \perp v$

2) $\|u+v\| = \|u-v\|$

3) $\|u+v\|^2 = \|u\|^2 + \|v\|^2$

SOL

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$$1) \Leftrightarrow 2$$

$$u \perp v \Leftrightarrow \langle u, v \rangle = 0$$

$$\textcircled{*} \|u+v\|^2 = \langle u+v, u+v \rangle = \|u\|^2 + \|v\|^2 + 2\langle u, v \rangle$$

$$\|u-v\|^2 = \langle u-v, u-v \rangle = \|u\|^2 + \|v\|^2 - 2\langle u, v \rangle$$

$$\|u+v\| = \|u-v\| \Leftrightarrow \langle u, v \rangle = 0 \Leftrightarrow u \perp v$$

$$1) \Leftrightarrow 3)$$

$$\|u+v\|^2 = \|u\|^2 + \|v\|^2 \Leftrightarrow \langle u, v \rangle = 0 \Leftrightarrow u \perp v$$

Ex 4 $(\mathcal{M}_2(\mathbb{R}), +, \cdot) / \mathbb{R}$

$$g: \mathcal{M}_2(\mathbb{R}) \times \mathcal{M}_2(\mathbb{R}) \rightarrow \mathbb{R},$$

$$g(X, Y) = 2 \operatorname{Tr}(X \cdot Y) - \operatorname{Tr}(X) \cdot \operatorname{Tr}(Y), \quad \forall X, Y \in \mathcal{M}_2(\mathbb{R})$$

Este g produs scalar?

SOL

g produs scalar $\Leftrightarrow g$ formă biliniară, simetrică
poz. definită.

$$\operatorname{Tr}(X \cdot Y) = \operatorname{Tr}(Y \cdot X) \Rightarrow g(X, Y) = g(Y, X) \Rightarrow g \text{ simetrică}$$

$$g(aX+bZ, Y) \stackrel{?}{=} a g(X, Y) + b g(Z, Y)$$

$$\forall X, Y, Z \in \mathcal{M}_2(\mathbb{R})$$

$$\forall a, b \in \mathbb{R}$$

$$g(aX+bZ, Y) = 2 \operatorname{Tr}((aX+bZ)Y) - \operatorname{Tr}(aX+bZ) \operatorname{Tr} Y$$

$$aXY + bZY$$

$$= 2a \operatorname{Tr}(XY) + 2b \operatorname{Tr}(ZY) - a \operatorname{Tr}(X) \operatorname{Tr} Y - b \operatorname{Tr}(Z) \operatorname{Tr}(Y)$$

$$= a g(X, Y) + b g(Z, Y)$$

g simetrică

g liniară în primul arg

$\Rightarrow g$ biliniară

$$Q: \mathcal{M}_2(\mathbb{R}) \rightarrow \mathbb{R}, \quad Q(X) = q(X, X) = 2\text{Tr}(X^2) - (\text{Tr} X)^2$$

$$X = \begin{pmatrix} x_1 & x_2 \\ x_3 & x_4 \end{pmatrix} \equiv (x_1, x_2, x_3, x_4)$$

$$X^2 = \begin{pmatrix} x_1 & x_2 \\ x_3 & x_4 \end{pmatrix} \begin{pmatrix} x_1 & x_2 \\ x_3 & x_4 \end{pmatrix} = \begin{pmatrix} x_1^2 + x_2 x_3 & x_1 x_2 + x_2 x_4 \\ x_1 x_3 + x_3 x_4 & x_4^2 + x_2 x_3 \end{pmatrix}$$

$$Q(X) = 2(x_1^2 + x_4^2 + 2x_2 x_3) - (x_1 + x_4)^2$$

$$= \underline{x_1^2 + x_4^2 + 4x_2 x_3 - 2x_1 x_4}.$$

$$G = \begin{pmatrix} \boxed{1} & 0 & 0 & -1 \\ 0 & 0 & 2 & 0 \\ 0 & 2 & 0 & 0 \\ -1 & 0 & 0 & 1 \end{pmatrix}$$

$$Q(X) = (x_1 - x_4)^2 + 4x_2 x_3$$

$$\begin{cases} x_1' = x_1 - x_4 \\ x_k' = x_k, \quad k \in \{2, 3, 4\} \end{cases} \Rightarrow Q(X) = x_1'^2 + 4x_2' x_3'$$

$$\begin{cases} x_2'' = x_2' + x_3' \\ x_3'' = x_2' - x_3' \\ x_k'' = x_k', \quad k \in \{1, 4\} \end{cases} \Rightarrow \begin{cases} x_2' = \frac{1}{2}(x_2'' + x_3'') \\ x_3' = \frac{1}{2}(x_2'' - x_3'') \\ x_k' = x_k'', \quad k \in \{1, 4\} \end{cases}$$

$$Q(X) = x_1''^2 + x_2''^2 - x_3''^2$$

Signatura: $(2, 1) \Rightarrow Q$ nu e poz def
 $\Rightarrow q$ —

Deci q nu e produs scalar.

Ex 5 (\mathbb{R}^3, g_0) , $U = \langle \underbrace{(1, 0, 1)}_{f_1}, \underbrace{(1, 1, 2)}_{f_2} \rangle$

a) $U^\perp = ?$

b) Sa se determine $R = R_1 U R_2$ reper ortonormat in \mathbb{R}^3

ai \mathcal{R}_1 reper ortonormat în U
 \mathcal{R}_2 ————— U^\perp

sol
 a) (M_1) $\{f_1, f_2\}$ SLI $\text{rg} \begin{pmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 2 \end{pmatrix} = 2$
 $\dim U = 2 \Rightarrow \dim U^\perp = 1$ $\mathbb{R}^3 = U \oplus U^\perp$

$f_1 \times f_2 \perp f_k, k=1,2$

$f_1 \times f_2 = \begin{vmatrix} e_1 & e_2 & e_3 \\ 1 & 0 & 1 \\ 1 & 1 & 2 \end{vmatrix} = e_1 \begin{vmatrix} 0 & 1 \\ 1 & 2 \end{vmatrix} - e_2 \begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix} + e_3 \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix}$

$= (-1, -1, 1) \Rightarrow U^\perp = \langle \{(-1, -1, 1)\} \rangle$

(M_2) $U^\perp = \left\{ x \in \mathbb{R}^3 \mid \begin{cases} g_0(x, f_1) = 0 \\ g_0(x, f_2) = 0 \end{cases} \right\}$
 $= \left\{ x \in \mathbb{R}^3 \mid \begin{cases} x_1 + x_3 = 0 \\ x_1 + x_2 + 2x_3 = 0 \end{cases} \right\} = \left\{ \begin{pmatrix} -x_3 \\ -x_3 \\ x_3 \end{pmatrix} \mid x_3 \in \mathbb{R} \right\}$
 $\quad \quad \quad x_3 \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}$

$\begin{cases} x_1 = -x_3 \\ x_2 = x_3 - 2x_3 = -x_3 \end{cases}$

b) $\{f_1, f_2\}$ reper \forall în U . Aplicăm G-S.

$\begin{cases} e_1 = f_1 = (1, 0, 1) \\ e_2 = f_2 - \frac{\langle f_2, e_1 \rangle}{\langle e_1, e_1 \rangle} e_1 = (1, 1, 2) - \frac{3}{2} (1, 0, 1) = \left(-\frac{1}{2}, 1, \frac{1}{2}\right) \end{cases}$
 $= \frac{1}{2} (-1, 2, 1)$

$\{e_1, e_2\}$ reper ortogonal în U .

$\mathcal{R}_1 = \left\{ e_1' = \frac{1}{\sqrt{2}} (1, 0, 1), e_2' = \frac{1}{\sqrt{6}} (-1, 2, 1) \right\}$ reper ortonormat în U

$\mathcal{R}_2 = \left\{ e_3' = \frac{1}{\sqrt{3}} (-1, -1, 1) \right\}$ reper orton în U^\perp

$\mathcal{R} = \mathcal{R}_1 \cup \mathcal{R}_2$ reper ortonormat în \mathbb{R}^3 .

Ex 6 $(\mathbb{R}_2[X], +, \cdot) / \mathcal{R}$, $g: \mathbb{R}_2[X] \times \mathbb{R}_2[X] \rightarrow \mathbb{R}$

$$g(P, Q) = \sum_{k=0}^2 a_k b_k, \quad P = a_0 + a_1 X + a_2 X^2 \equiv (a_0, a_1, a_2) \in \mathbb{R}^3$$

$$Q = b_0 + b_1 X + b_2 X^2 \equiv (b_0, b_1, b_2) \in \mathbb{R}^3$$

$$\mathbb{R}_2[X] \simeq \mathbb{R}^3$$

g produs scalar canonic.

Să se orthonormeze $\{2, 3-2X, 1-2X+X^2\}$

Sol $\{ \overset{f_1}{(2, 0, 0)}, \overset{f_2}{(3, -2, 0)}, \overset{f_3}{(1, -2, 1)} \}$ reper în \mathbb{R}^3

$$\det \begin{pmatrix} 2 & 3 & 1 \\ 0 & -2 & -2 \\ 0 & 0 & 1 \end{pmatrix} \neq 0 \Rightarrow \text{SLI}$$

$$e_1 = f_1 = (2, 0, 0) = \underline{2(1, 0, 0)}$$

$$e_2 = f_2 - \frac{\langle f_2, e_1 \rangle}{\langle e_1, e_1 \rangle} e_1 = (3, -2, 0) - \frac{6}{4} (2, 0, 0) = (3, -2, 0) - (3, 0, 0) = \underline{(0, -2, 0)} = 2(0, -1, 0)$$

$$e_3 = f_3 - \frac{\langle f_3, e_1 \rangle}{\langle e_1, e_1 \rangle} e_1 - \frac{\langle f_3, e_2 \rangle}{\langle e_2, e_2 \rangle} e_2 =$$

$$= (1, -2, 1) - \frac{2}{4} (2, 0, 0) - \frac{4}{4} (0, -2, 0) =$$

$$= (1, -2, 1) - (1, 0, 0) + (0, 2, 0) = (0, 0, 1)$$

$$\{ e_1' = (1, 0, 0), e_2' = (0, -1, 0), e_3' = (0, 0, 1) \}$$

$\{1, -X, X^2\}$ reper orthonormal în $\mathbb{R}_2[X]$
în raport cu g .

T5 (Seminar)

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Ex1 (\mathbb{R}^3, g_0) , $u = (0, 1, -1)$

Să se determine transf. ortog. de spațiu, care este rotație de $\varphi = \pi$ și axă $\{u\}$.

Ex2 $(\mathbb{R}_2[X], g_0)$, $g_0(P, Q) = \sum_{i=0}^2 a_i b_i$, $P = a_0 + a_1 X + a_2 X^2$
 $Q = b_0 + b_1 X + b_2 X^2$

Să se ortonormeze $R = \{X, X - X^2, 1 + X + X^2\}$ în raport cu g_0

Ex3 (\mathbb{R}^3, g_0) , $U = \{x \in \mathbb{R}^3 \mid \begin{cases} x_1 + x_3 = 0 \\ 3x_2 + x_3 = 0 \end{cases}\}$

a) U^\perp

b) Să se determine $R = R_1 \cup R_2$ reper ortonormat în \mathbb{R}^3

cu R_1 reper ortonormat în U
 R_2 / -11- U^\perp .