

Forme pătratice. Metoda Jacobi

Spatii vectoriale euclidiene reale

- $Q: V \rightarrow \mathbb{K}$ formă pătratică \Leftrightarrow
 $\exists g: V \times V \rightarrow \mathbb{K}$ formă biliniară simetrică a.c.
 $Q(x) = g(x, x), \forall x \in V$

$$Q(x) = x^T G x = \sum_{i,j=1}^n g_{ij} x_i x_j, \quad g_{ij} = g(e_i, e_j) \\ \forall i, j = 1, \dots, n$$

$$Q(x) = a_1 x_1^2 + \dots + a_n x_n^2, \quad n = \operatorname{rg} Q$$

formă canonică

Teorema Gauss Fie $Q: V \rightarrow \mathbb{K}$ f. pătratică

$\Rightarrow \exists$ un reper $R = \{e_1, \dots, e_n\}$ în V a.c. Q are o formă canonică.

Teoremă $Q: V \rightarrow \mathbb{R}$ f. pătratică reală

$\Rightarrow \exists R$ reper în V a.c. $Q(x) = x_1^2 + \dots + x_p^2 - x_{p+1}^2 - \dots - x_n^2$
 (formă normală)

$(p, n-p) = \text{signatura}$ (invar. la sch. reperelor)

Q poz. definită $\Leftrightarrow (n, 0)$ signatura

Metoda Jacobi

Fie $Q: V \rightarrow \mathbb{R}$ f. pătratică reală.

Fie $R = \{e_1, \dots, e_n\}$ un reper în V . Dacă matricea G asociată lui Q în raport cu R are minore diagonali $\Delta_1 = \det(g_{11}), \Delta_2 = \det \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix}, \dots, \Delta_n = \det G$ nenuli,

atunci \exists un reper $\mathcal{R}' = \{e'_1, \dots, e'_n\}$ în V a.c.
 Q are o formă canonică

$$Q(x) = \frac{1}{\Delta_1} x_1'^2 + \frac{\Delta_1}{\Delta_2} x_2'^2 + \dots + \frac{\Delta_{n-1}}{\Delta_n} x_n'^2$$

Mai mult, Q pozitiv definită $\Leftrightarrow \Delta_i > 0, \forall i = \overline{1, n}$

$$G = \begin{pmatrix} g_{11} & g_{12} & \dots & g_{1n} \\ g_{21} & g_{22} & \dots & g_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ g_{n1} & g_{n2} & \dots & g_{nn} \end{pmatrix}$$

- OBS
- a) Metoda Jacobi este restrictivă (tb $\Delta_i \neq 0, \forall i = \overline{1, n}$)
 - b) Metoda Gauss se poate aplica totdeauna.

Aplicație Fie $Q: \mathbb{R}^4 \rightarrow \mathbb{R}, Q(x) = x_1^2 + x_3^2 + x_1 x_2 + x_3 x_4$

Să se aducă la o formă canonică, utilizând metoda Jacobi și metoda Gauss.

SOL $\mathcal{R}_0 = \{e_1, e_2, e_3, e_4\}$ reperul canonic.

$$Q(x) = g_{11} x_1^2 + \dots + g_{44} x_4^2 + 2g_{12} x_1 x_2 + \dots + 2g_{34} x_3 x_4$$

$$G = \begin{pmatrix} 1 & \frac{1}{2} & 0 & 0 \\ \frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 1 & \frac{1}{2} \\ 0 & 0 & \frac{1}{2} & 0 \end{pmatrix}$$

Met Jacobi

$$\Delta_1 = \det(1) = 1$$

$$\Delta_2 = \begin{vmatrix} 1 & \frac{1}{2} \\ \frac{1}{2} & 0 \end{vmatrix} = -\frac{1}{4}$$

$$\Delta_3 = \begin{vmatrix} 1 & \frac{1}{2} & 0 \\ \frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 \end{vmatrix} = -\frac{1}{4}$$

$$\Delta_4 = \det G = -\frac{1}{2} \begin{vmatrix} \frac{1}{2} & 0 & 0 \\ 0 & 1 & \frac{1}{2} \\ 0 & \frac{1}{2} & 0 \end{vmatrix} = \frac{1}{16}$$

$$\frac{1}{\Delta_1} = 1; \quad \frac{\Delta_1}{\Delta_2} = -4, \quad \frac{\Delta_2}{\Delta_3} = 1, \quad \frac{\Delta_3}{\Delta_4} = -4.$$

$\exists R' = \{e'_1, \dots, e'_4\}$ reper în \mathbb{R}^4 cu

$$Q(x) = x_1'^2 - 4x_2'^2 + x_3'^2 - 4x_4'^2$$

Fie $R'' = \{e'_1, e'_3, e'_2, e'_4\}$ reper în \mathbb{R}^4

$$Q(x) = x_1''^2 + x_2''^2 - 4x_3''^2 - 4x_4''^2$$

$(2, 2)$ semnatura

Met Gauss

$$Q(x) = x_1^2 + x_3^2 + x_1 x_2 + x_3 x_4 =$$

$$= \left(x_1 + \frac{1}{2}x_2\right)^2 - \frac{x_2^2}{4} + x_3^2 + x_3 x_4 =$$

$$= \left(x_1 + \frac{1}{2}x_2\right)^2 - \frac{x_2^2}{4} + \left(x_3 + \frac{1}{2}x_4\right)^2 - \frac{1}{4}x_4^2$$

$$\begin{cases} x_1' = x_1 + \frac{1}{2}x_2 \\ x_2' = x_3 + \frac{1}{2}x_4 \\ x_3' = x_2 \\ x_4' = x_4 \end{cases} \Rightarrow Q(x) = x_1'^2 + x_2'^2 - \frac{x_3'^2}{4} - \frac{x_4'^2}{4}$$

$(2, 2)$

Spatiu vectoriale euclidiene reale

Def $(V, +, \cdot)_{/\mathbb{R}}$ sp. vect. real si $g: V \times V \rightarrow \mathbb{R}$

g s.n. produs scalar \Leftrightarrow

1) g formă biliniară simetrică

2) g este poz def
 (i.e. $Q: V \rightarrow \mathbb{R}$ f. pătratică ^{asimetrică}, $Q(x) = g(x, x), \forall x \in V$)
 poz definită $\Leftrightarrow Q(x) > 0, \forall x \in V, \{0_V\}$
 $Q(x) = 0 \Leftrightarrow x = 0$

Not $(V, g); (E, \langle \cdot, \cdot \rangle); (E, (\cdot, \cdot))$
 spațiu vect. euclidian real

Def $\|x\| = \sqrt{g(x, x)} = \sqrt{Q(x)}, \forall x \in V$
 norma lui x .

Def $(E, \langle \cdot, \cdot \rangle)$ s.v.e.r., $R = \{e_1, \dots, e_n\}$ reper în V

a) R s.n. reper ortogonal $\Leftrightarrow \langle e_i, e_j \rangle = 0, \forall i, j = \overline{1, n}; i \neq j$

b) R s.n. reper ortonormat $\Leftrightarrow \langle e_i, e_j \rangle = \delta_{ij}, \forall i, j = \overline{1, n}$
 (vectorii sunt mutual \perp și versori)

OBS

$R = \{e_1, \dots, e_n\} \xrightarrow{A} R' = \{e'_1, \dots, e'_n\}$ repere ortonormale

$\Rightarrow A \in O(n)$ i.e. $AA^T = A^T A = I_n$.

$$e'_k = \sum_{i=1}^n a_{ik} e_i$$

$$\begin{aligned} \langle e'_{k_1}, e'_{k_2} \rangle &= \left\langle \sum_{i=1}^n a_{ik_1} e_i, \sum_{j=1}^n a_{jk_2} e_j \right\rangle = \\ &= \sum_{i,j=1}^n a_{ik_1} a_{jk_2} \underbrace{\langle e_i, e_j \rangle}_{\delta_{ij}} \\ \Rightarrow \delta_{k_1 k_2} &= \sum_{i=1}^n a_{ik_1} a_{ik_2} \Rightarrow I_n = A^T A \end{aligned}$$

Dacă R, R' sunt la fel orientate ($\det A > 0$)

$\Rightarrow \det A = 1$ și $A \in SO(n)$

Prop $(E, \langle \cdot, \cdot \rangle)$ s.v.e.r. și $S = \{x_1, \dots, x_k\}, k \leq n = \dim V$
 Dacă S este un sist. de vect. nenuli, mutual \perp ,
 atunci S este un SLI.

Dem

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k

$$\text{Fie } a_1, \dots, a_k \in \mathbb{R} \text{ ai } \sum_{i=1}^k a_i x_i = 0_V \mid \langle \cdot, x_1 \rangle$$

$$\langle \sum_{i=1}^k a_i x_i, x_1 \rangle = 0_{\mathbb{R}} \Rightarrow$$

$$a_1 \underbrace{\langle x_1, x_1 \rangle}_{\|x_1\|^2} + \underbrace{a_2 \langle x_2, x_1 \rangle}_0 + \dots + \underbrace{a_k \langle x_k, x_1 \rangle}_0 = 0_{\mathbb{R}}$$

$$a_1 \|x_1\|^2 = 0_{\mathbb{R}} \Rightarrow a_1 = 0_{\mathbb{R}}$$

$$\text{Analog } \langle \cdot, x_j \rangle, \forall j = 2, \dots, k \Rightarrow a_j = 0, \forall j = 2, \dots, k$$

$$\Rightarrow a_i = 0, \forall i = 1, \dots, k \quad \text{Si este un SLI}$$

Exemplu (\mathbb{R}^n, g_0) , $g_0: \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$, $g_0(x, y) = x_1 y_1 + \dots + x_n y_n$

g_0 produs scalar canonic

g_0 formă bil, sim. $g_0(x, y) = X^T J_n Y$

$$J_n = J_n^T$$

g_0 este poz. def: $Q_0(x) = g_0(x, x) = x_1^2 + \dots + x_n^2$

$(n, 0) = \text{signatura}$

Def (produs vectorial) euclidiană
Fie (\mathbb{R}^3, g_0) s.v.e.r., cu str. canonică

Fie $S = \{x, y\} \subset \mathbb{R}^3$ si $z = x \times y$ numit produs vectorial def astfel:

① Dc S este SLD, atunci $z = 0_{\mathbb{R}^3}$

② Dc S este SLI, atunci

$$a) \|z\|^2 = \begin{vmatrix} \langle x, x \rangle & \langle x, y \rangle \\ \langle y, x \rangle & \langle y, y \rangle \end{vmatrix}$$

$$b) z \perp x, z \perp y \text{ i.e. } \langle z, x \rangle = \langle z, y \rangle = 0$$

c) $\{x, y, z\}$ reper pozitiv orientat
(ca fel orientat ca reperul canonic)

Obs "x" este un "determinant formal"

$$x = x \times y = \begin{vmatrix} e_1 & e_2 & e_3 \\ x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{vmatrix} = \begin{vmatrix} x_1 & y_1 & e_1 \\ x_2 & y_2 & e_2 \\ x_3 & y_3 & e_3 \end{vmatrix}$$

$$= e_1 \begin{vmatrix} x_2 & x_3 \\ y_2 & y_3 \end{vmatrix} - e_2 \begin{vmatrix} x_1 & x_3 \\ y_1 & y_3 \end{vmatrix} + e_3 \begin{vmatrix} x_1 & x_2 \\ y_1 & y_2 \end{vmatrix}$$

$$= (x_2 y_3 - x_3 y_2, x_3 y_1 - x_1 y_3, x_1 y_2 - x_2 y_1)$$

Prop (\mathbb{R}^3, g_0) , $S = \{x, y\}$ un SLI

a) $x \times y = -y \times x$

b) $(x \times y) \times z = \langle x, z \rangle y - \langle y, z \rangle x$ (nu e asociativ)

c) $\sum_{x, y, z} (x \times y) \times z = 0$ (ident. Jacobi)

Dem

a) $x \times y = \begin{vmatrix} e_1 & e_2 & e_3 \\ x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{vmatrix} = - \begin{vmatrix} e_1 & e_2 & e_3 \\ y_1 & y_2 & y_3 \\ x_1 & x_2 & x_3 \end{vmatrix} = -y \times x.$

b) $(x \times y) \times z = \begin{vmatrix} e_1 & e_2 & e_3 \\ x_2 y_3 - x_3 y_2 & x_3 y_1 - x_1 y_3 & x_1 y_2 - x_2 y_1 \\ z_1 & z_2 & z_3 \end{vmatrix}$

$$= e_1 \alpha - e_2 \beta + e_3 \gamma = (\alpha, -\beta, \gamma)$$

$$\langle x, z \rangle y - \langle y, z \rangle x =$$

$$\begin{aligned} &= (\underbrace{x_1 z_1 + x_2 z_2 + x_3 z_3}_{\in \mathbb{R}}) (\underbrace{y_1 e_1 + y_2 e_2 + y_3 e_3}_{\in \mathbb{R}}) - \\ &= (\underbrace{y_1 z_1 + y_2 z_2 + y_3 z_3}_{\in \mathbb{R}}) (\underbrace{x_1 e_1 + x_2 e_2 + x_3 e_3}_{\in \mathbb{R}}) \\ &= e_1 \alpha - e_2 \beta + e_3 \gamma = (\alpha, -\beta, \gamma) \end{aligned}$$

$$c) \sum_{x,y,z}^c (x \times y) \cdot z = \overset{-7}{(x \times y) \cdot z} + (y \times z) \cdot x + (z \times x) \cdot y$$

$$= \langle x, z \rangle y - \langle y, z \rangle x + \langle y, x \rangle z - \langle z, x \rangle y + \langle z, y \rangle x - \langle x, y \rangle z = 0$$

Def (produs mixt)

(\mathbb{R}^3, g_0) , $S = \{x, y\}$ un SLI. Fie $z \in \mathbb{R}^3$

$$z \wedge x \wedge y = \langle z, x \times y \rangle \quad (\text{produsul mixt})$$

obs

$$z \wedge x \wedge y = x \wedge y \wedge z$$

$$z \wedge x \wedge y = \begin{vmatrix} z_1 & z_2 & z_3 \\ x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{vmatrix} = \begin{vmatrix} x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \\ z_1 & z_2 & z_3 \end{vmatrix} = x \wedge y \wedge z$$

Aplicatie

$$(\mathbb{R}^3, g_0) \quad g_0: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}, \quad g_0(x, y) = x_1 y_1 + x_2 y_2 + x_3 y_3$$

$$u = (1, -1, 2)$$

$$v = (0, 1, 3)$$

$$w = (1, 4, 0)$$

$$\{u, v\} \text{ SLI} \Leftrightarrow g_0 \begin{pmatrix} 1 & 0 \\ -1 & 1 \\ 2 & 3 \end{pmatrix} = 2$$

$$a) u \times v = \begin{vmatrix} e_1 & e_2 & e_3 \\ 1 & -1 & 2 \\ 0 & 1 & 3 \end{vmatrix} = e_1 \begin{vmatrix} -1 & 2 \\ 1 & 3 \end{vmatrix} - e_2 \begin{vmatrix} 1 & 2 \\ 0 & 3 \end{vmatrix} + e_3 \begin{vmatrix} 1 & -1 \\ 0 & 1 \end{vmatrix}$$

$$= (-5, -3, 1)$$

$$b) w \wedge u \wedge v = \langle w, u \times v \rangle = \begin{vmatrix} 1 & 4 & 0 \\ 1 & -1 & 2 \\ 0 & 1 & 3 \end{vmatrix}$$

$$= 1(-5) + 4(-3) + 0 \cdot 1 = -5 - 12 = -17$$

$$c) \{u, v, u \times v\} \text{ reper poz. orientat in } \mathbb{R}^3$$

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Teoremă (procedeu Gram-Schmidt)

Fie $(E, \langle \cdot, \cdot \rangle)$ s.v.e.r., $R = \{f_1, \dots, f_n\}$ reper în E .

$\Rightarrow \exists R' = \{e_1, \dots, e_n\}$ reper ortogonal în E și

$$\text{Sp}\{e_1, \dots, e_i\} = \text{Sp}\{f_1, \dots, f_i\}, \quad \forall i = \overline{1, n}, \quad n = \dim E$$

$$\langle \{e_1, \dots, e_i\} \rangle = \langle \{f_1, \dots, f_i\} \rangle$$

Dem.

Met. inductivă.

$$e_1 = f_1 \neq 0$$

$$e_2 = f_2 + \alpha f_1 = f_2 + \alpha e_1$$

$$\langle e_1, e_2 \rangle = 0 \Rightarrow$$

$$\langle e_1, e_2 \rangle = \langle f_2 + \alpha e_1, e_1 \rangle = \langle f_2, e_1 \rangle + \alpha \langle e_1, e_1 \rangle$$

$$\overset{0}{\Rightarrow} \alpha = - \frac{\langle f_2, e_1 \rangle}{\langle e_1, e_1 \rangle}$$

$$e_2 = f_2 - \frac{\langle f_2, e_1 \rangle}{\langle e_1, e_1 \rangle} \cdot e_1$$

$$\begin{cases} f_1 = e_1 \\ f_2 = \frac{\langle f_2, e_1 \rangle}{\langle e_1, e_1 \rangle} e_1 + e_2 \end{cases} \Rightarrow \text{Sp}\{e_1, e_2\} = \text{Sp}\{f_1, f_2\}$$

Pf. adun P_k : $\{e_1, \dots, e_k\}$ sînt veci mutual ortog si

$$\text{Sp}\{e_1, \dots, e_i\} = \text{Sp}\{f_1, \dots, f_i\}, \quad \forall i = \overline{1, k}$$

Dem P_{k+1}

Construim

$$e_{k+1} = f_{k+1} + \sum_{i=1}^k \alpha_{k+1,i} e_i \quad \langle \cdot, e_j \rangle, \quad j = \overline{1, k}$$

$$\langle e_{k+1}, e_j \rangle = \langle f_{k+1}, e_j \rangle + \sum_{i=1}^k \alpha_{k+1,i} \langle e_i, e_j \rangle$$

$$\overset{0}{\Rightarrow} \alpha_{k+1,j} = - \frac{\langle f_{k+1}, e_j \rangle}{\langle e_j, e_j \rangle}$$

$$e_{k+1} = f_{k+1} - \sum_{i=1}^k \frac{\langle f_{k+1}, e_i \rangle}{\langle e_i, e_i \rangle} e_i$$

$$\begin{cases} f_1 = e_1 \\ f_2 = \frac{\langle f_2, e_1 \rangle}{\langle e_1, e_1 \rangle} e_1 + e_2 \\ \vdots \\ f_{k+1} = \sum_{i=1}^k \frac{\langle f_{k+1}, e_i \rangle}{\langle e_i, e_i \rangle} e_i + e_{k+1} \end{cases} \Rightarrow \text{Sp} \{e_1, \dots, e_i\} = \text{Sp} \{f_1, \dots, f_i\} \quad \forall i = \overline{1, k+1}$$

Se continuă raționamentul

$$\begin{cases} f_1 = e_1 \\ f_2 = \frac{\langle f_2, e_1 \rangle}{\langle e_1, e_1 \rangle} e_1 + e_2 \\ \vdots \\ f_m = \frac{\langle f_m, e_1 \rangle}{\langle e_1, e_1 \rangle} e_1 + \dots + \frac{\langle f_m, e_{m-1} \rangle}{\langle e_{m-1}, e_{m-1} \rangle} e_{m-1} + e_m \end{cases}$$

$$\text{Sp} \{e_1, \dots, e_i\} = \text{Sp} \{f_1, \dots, f_i\}, \quad \forall i = \overline{1, m}$$

$$\left. \begin{aligned} \{e_1, \dots, e_n\} \text{ mutual ortog} &\Rightarrow \mathcal{R}' = \{e_1, \dots, e_n\} \text{ S.L.} \\ &\text{dar } \dim E = |\mathcal{R}'| = n \end{aligned} \right\}$$

$\Rightarrow \mathcal{R}'$ reper în E

$$\begin{array}{ccccc} \text{OBS} & \mathcal{R} = \{f_1, \dots, f_m\} & \xrightarrow{A} & \mathcal{R}' = \{e_1, \dots, e_n\} & \xrightarrow{B} & \mathcal{R}'' = \left\{ \frac{e_1}{\|e_1\|}, \dots, \frac{e_n}{\|e_n\|} \right\} \\ & \text{reper arbitrar} & & \text{reper ortogonal} & & \text{reper ortonormat} \\ & A^{-1} = \begin{pmatrix} 1 & \frac{\langle f_2, e_1 \rangle}{\langle e_1, e_1 \rangle} \\ 0 & 1 \\ \vdots & \vdots \\ 0 & 0 \end{pmatrix} & & \begin{pmatrix} \frac{\langle f_1, e_1 \rangle}{\langle e_1, e_1 \rangle} \\ \vdots \\ \frac{\langle f_m, e_{m-1} \rangle}{\langle e_{m-1}, e_{m-1} \rangle} \\ 1 \end{pmatrix} & & B = \begin{pmatrix} \frac{1}{\|e_1\|} & & 0 \\ & \ddots & \\ 0 & & 1 \\ & & & \frac{1}{\|e_n\|} \end{pmatrix} \end{array}$$

$$\det(A^{-1}) = \frac{1}{\det A} = 1 \Rightarrow \det A = 1 > 0; \quad \det B = \frac{1}{\|e_1\|} \cdots \frac{1}{\|e_n\|} > 0$$

$\mathcal{R}, \mathcal{R}', \mathcal{R}''$ sunt repere la fel orientate.

Def $(E, \langle \cdot, \cdot \rangle)$ s.v.e.r.

a) $x \in E, \quad \langle \{x\} \rangle^\perp = \{y \in E \mid \langle x, y \rangle = 0\}$
 subspațiu ortogonal pe x

b) $U \subseteq E \Rightarrow U^\perp = \{x \in E \mid \langle x, y \rangle = 0, \forall y \in U\}$
 sup. rect subsp. ortogonal pe U

Obs

$U \subseteq W \subseteq E \Rightarrow W^\perp \subseteq U^\perp \subseteq E.$

Exercițiu

$(\mathbb{R}^3, g_0), \quad u = (1, 2, -1)$

a) $\langle \{u\} \rangle^\perp$; b) Det. un reper ortonormat în $\langle \{u\} \rangle^\perp$
 (Gram-Schmidt)

Sol

a) $V = \langle \{u\} \rangle^\perp = \{x \in \mathbb{R}^3 \mid g_0(x, u) = 0\}$
 $= \{x \in \mathbb{R}^3 \mid x_1 + 2x_2 - x_3 = 0\}$

$\dim V = 3 - 1 = 2$

$V = \{ (x_1, x_2, x_1 + 2x_2) \mid x_1, x_2 \in \mathbb{R} \}$

$x_1(1, 0, 1) + x_2(0, 1, 2)$

$R = \{ f_1 = (1, 0, 1), f_2 = (0, 1, 2) \}$ SG pt $V \Rightarrow R$ reper în V

$\dim V = |R| = 2$

Aplicăm Gram-Schmidt.

$e_1 = f_1 = (1, 0, 1)$

$e_2 = f_2 - \frac{\langle f_2, e_1 \rangle}{\langle e_1, e_1 \rangle} e_1 = (0, 1, 2) - \frac{2}{2} (1, 0, 1) = (0, 1, 2) - (1, 0, 1) = (-1, 1, 1)$

$\langle f_2, e_1 \rangle = \langle f_2, f_1 \rangle = 1 \cdot 0 + 0 \cdot 1 + 1 \cdot 2 = 2$

$\langle e_1, e_1 \rangle = \langle f_1, f_1 \rangle = 1^2 + 0^2 + 1^2 = 2$

$$R = \{f_1, f_2\} \xrightarrow{-||-} R' = \{e_1, e_2\} \rightarrow R'' = \left\{ \frac{e_1}{\|e_1\|}, \frac{e_2}{\|e_2\|} \right\}$$

$$e_1 = (1, 0, 1) \Rightarrow \|e_1\| = \sqrt{1^2 + 0^2 + 1^2} = \sqrt{2}$$

$$e_2 = (-1, 1, 1) \Rightarrow \|e_2\| = \sqrt{1^2 + 1^2 + 1^2} = \sqrt{3}$$

$$R'' = \left\{ \frac{1}{\sqrt{2}}(1, 0, 1), \frac{1}{\sqrt{3}}(-1, 1, 1) \right\} \text{ reper ortonormat în } \langle u \rangle^\perp$$

OBS A da un produs scalar \Leftrightarrow a declara un reper ortonormat

• $g: V \times V \rightarrow \mathbb{R}$ produs scalar

$$R = \{e_1, \dots, e_n\} \text{ reper ortonormat} \Leftrightarrow g(e_i, e_j) = \delta_{ij}, \forall i, j = \overline{1, n}$$

• Dacă $R = \{e_1, \dots, e_n\}$ reper ortonormat

Construim $g: V \times V \rightarrow \mathbb{R}$ p. scalar ai $g(e_i, e_j) = \delta_{ij}$

Prelungim prin liniaritate

$$\begin{aligned} g(x, y) &= g\left(\sum_{i=1}^n x_i e_i, \sum_{j=1}^n y_j e_j\right) = \sum_{i,j=1}^n x_i y_j g(e_i, e_j) \\ &= \sum_{i=1}^n x_i y_i \end{aligned}$$