

Forme pătratice. Metoda Jacobi

Spații vectoriale euclidiene reale

• Metoda Jacobi

$Q: V \rightarrow \mathbb{R}$ formă pătratică reală și G matricea asociată în raport cu un reper R .

a) Dacă minorii diagonali

$$\Delta_1 = \det(g_{11}) \neq 0$$

$$\Delta_2 = \begin{vmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{vmatrix} \neq 0$$

\vdots

$$\Delta_n = \det G \neq 0$$

$\Rightarrow \exists$ un reper R' în V ai

Q are formă canonică

$$Q(x) = \frac{1}{\Delta_1} x_1'^2 + \frac{\Delta_1}{\Delta_2} x_2'^2 + \dots + \frac{\Delta_{n-1}}{\Delta_n} x_n'^2$$

b) Q este poz. def $\Leftrightarrow \Delta_i > 0, \forall i = \overline{1, n}$

• $(V, +, \cdot) \text{ IR}, g: V \times V \rightarrow \mathbb{R}$ produs scalar

$$\Leftrightarrow 1) g \in L^s(V, V; \mathbb{R})$$

2) g poz. def.

(V, g) sp. vect. euclidian real

$$\bullet \|x\| = \sqrt{g(x, x)} = \sqrt{Q(x)}, \forall x \in V$$

• $R = \{e_1, \dots, e_n\}$ reper $\begin{cases} \text{ortogonal} \Leftrightarrow g(e_i, e_j) = 0, \forall i \neq j, i, j = \overline{1, n} \\ \text{ortonormat} \Leftrightarrow g(e_i, e_j) = \delta_{ij}, \forall i, j = \overline{1, n} \end{cases}$

$R \xrightarrow{A} R', A \in O(n)$
reperu ortonormate

• $(E, \langle \cdot, \cdot \rangle)$
 $U \subseteq E$ subspațiu $\Rightarrow U^\perp = \{y \in E \mid \langle x, y \rangle = 0, \forall x \in U\}$

• (\mathbb{R}^3, g_0) $g_0: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}, g_0(x, y) = x_1 y_1 + x_2 y_2 + x_3 y_3$
 (produs scalar canonic)

$S = \{x, y\}$ s.l.

a) $z = x \wedge y = \begin{vmatrix} e_1 & e_2 & e_3 \\ x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{vmatrix}, \begin{matrix} z \perp x \\ z \perp y \end{matrix}$
 (produs vectorial)

b) $\mu \wedge x \wedge y = \langle \mu, x \wedge y \rangle = \begin{vmatrix} \mu_1 & \mu_2 & \mu_3 \\ x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{vmatrix}$
 (produs mixt)

Teorema (Gram-Schmidt)

$(E, \langle \cdot, \cdot \rangle), R = \{f_1, \dots, f_n\}$ reper arb.

$\Rightarrow \exists R' = \{e_1, \dots, e_n\}$ reper ortogonal cu $Sp\{e_1, \dots, e_n\} = Sp\{f_1, \dots, f_n\}$
 $i=1, n$

$$\begin{cases} e_1 = f_1 \\ e_2 = f_2 - \frac{\langle f_2, e_1 \rangle}{\langle e_1, e_1 \rangle} e_1 \\ \vdots \\ e_n = f_n - \frac{\langle f_n, e_1 \rangle}{\langle e_1, e_1 \rangle} e_1 - \dots - \frac{\langle f_n, e_{n-1} \rangle}{\langle e_{n-1}, e_{n-1} \rangle} e_{n-1} \end{cases}$$

Ex1 Fie $Q: \mathbb{R}^3 \rightarrow \mathbb{R}, Q(x) = x_1^2 + 3x_2^2 + 4x_2 x_3$

Să se aducă la o formă canonică

SOL $R_0 = \{e_1, e_2, e_3\}$ reper canonic

$Q(x) = X^T G X = g_{11} x_1^2 + g_{22} x_2^2 + g_{33} x_3^2 + 2g_{12} x_1 x_2 + 2g_{13} x_1 x_3 + 2g_{23} x_2 x_3$

Met Jacobi

$$G = \begin{pmatrix} \boxed{1} & 0 & 0 \\ 0 & \boxed{3} & 2 \\ 0 & 2 & 0 \end{pmatrix}$$

$$\Delta_1 = 1 \neq 0$$

$$\Delta_2 = \begin{vmatrix} 1 & 0 \\ 0 & 3 \end{vmatrix} = 3 \neq 0$$

$$\Delta_3 = \det G = 1 \begin{vmatrix} 3 & 2 \\ 2 & 0 \end{vmatrix} = -4 \neq 0$$

\exists un reper $R' = \{e'_1, e'_2, e'_3\}$ în \mathbb{R}^3 ai'

$$Q(x) = \frac{1}{\Delta_1} x_1'^2 + \frac{\Delta_1}{\Delta_2} x_2'^2 + \frac{\Delta_2}{\Delta_3} x_3'^2 = 1 \cdot x_1'^2 + \frac{1}{3} x_2'^2 - \frac{3}{4} x_3'^2$$

(2,1) semnatura lui Q (nu e poz. def)

Met. Gauss

$$Q(x) = \underline{x_1^2 + 3x_2^2 + 4x_2x_3} = x_1^2 + 3\left(x_2^2 + \frac{4}{3}x_2x_3\right) =$$

$$= x_1^2 + 3\left(x_2 + \frac{2}{3}x_3\right)^2 - \frac{4}{3}x_3^2$$

$$\text{Fie } \begin{cases} x_1' = x_1 \\ x_2' = x_2 + \frac{2}{3}x_3 \\ x_3' = x_3 \end{cases} \Rightarrow Q(x) = x_1'^2 + 3x_2'^2 - \frac{4}{3}x_3'^2$$

(2,1) semnatura

Ex2 $(\mathbb{R}_1^2, +, \cdot) / \mathbb{R}$, $g: \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$, $g(x, y) = ax_1y_1 + bx_1y_2 + bx_2y_1 + cx_2y_2$

a) g formă biliniară simetrică

b) g produs scalar $\Leftrightarrow \begin{cases} a > 0 \\ ac - b^2 > 0 \end{cases}$

SOL

$R_0 = \{e_1, e_2\}$ reper canonic

$$G = \begin{pmatrix} a & b \\ b & c \end{pmatrix}$$

$$\left. \begin{aligned} g(x, y) &= X^T G Y \Rightarrow g \text{ formă biliniară} \\ G &= G^T \Rightarrow g \text{ simetrică} \end{aligned} \right\} \Rightarrow g \in L^s(\mathbb{R}^2, \mathbb{R}^2; \mathbb{R})$$

$$Q: \mathbb{R}^2 \rightarrow \mathbb{R}, Q(x) = g(x, x) = ax_1^2 + cx_2^2 + 2bx_1x_2$$

Met. Jacobi

$$\Delta_1 = a$$

$$\Delta_2 = \det G = ac - b^2$$

$$Q \text{ poz def} \Leftrightarrow \begin{cases} a > 0 \\ ac - b^2 > 0 \end{cases}$$

$$\exists R' = \{e_1', e_2'\} \text{ reper in } \mathbb{R}^2 \text{ cu } Q(x) = \frac{1}{a} x_1'^2 + \frac{a}{ac - b^2} x_2'^2$$

Met Gauss

$$\begin{aligned} Q(x) &= ax_1^2 + 2bx_1x_2 + cx_2^2 = \frac{1}{a} (a^2x_1^2 + 2abx_1x_2) + cx_2^2 = \\ &= \frac{1}{a} (ax_1 + bx_2)^2 - \frac{b^2}{a} x_2^2 + cx_2^2 = \frac{1}{a} (ax_1 + bx_2)^2 + \left(c - \frac{b^2}{a}\right) x_2^2 \end{aligned}$$

$$\begin{cases} x_1' = ax_1 + bx_2 \\ x_2' = x_2 \end{cases} \Rightarrow Q(x) = \frac{1}{a} x_1'^2 + \frac{ac - b^2}{a} x_2'^2$$

$$Q \text{ poz def} \Leftrightarrow \begin{cases} \frac{1}{a} > 0 \\ \frac{ac - b^2}{a} > 0 \end{cases} \Leftrightarrow \begin{cases} a > 0 \\ ac - b^2 > 0 \end{cases}$$

Ex 3 (\mathbb{R}^3, g) \mathbb{R} , $g: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$ formă biliniară

$$G = \begin{pmatrix} \boxed{3} & 2 & 0 \\ 2 & 2 & 2 \\ 0 & 2 & 1 \end{pmatrix} \text{ matricea asociată în rap. cu } R_0$$

Este (\mathbb{R}^3, g) spațiu vect. euclidian real?

SOL $G = G^T \Rightarrow g$ simetrică

$$Q: \mathbb{R}^3 \rightarrow \mathbb{R}, Q(x) = 3x_1^2 + 4x_1x_2 + 2x_2^2 + 4x_2x_3 + x_3^2$$

Met Jacobi

$$\Delta_1 = 3 > 0$$

$$\Delta_2 = \begin{vmatrix} 3 & 2 \\ 2 & 2 \end{vmatrix} = 6 - 4 = 2 > 0$$

$$\Delta_3 = \det G = 3(2 - 4) - 2(2 - 0) = -6 - 4 = -10 < 0$$

(2,1) semnatura lui $Q \Rightarrow g$ nu e poz. def

(\mathbb{R}^3, g) nu este sp. vect euclidian

Ex4 (\mathbb{R}^3, g_0) , $g_0: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$, $g_0(x, y) = x_1 y_1 + x_2 y_2 + x_3 y_3$
 $U = \{x \in \mathbb{R}^3 \mid x_1 + x_2 - x_3 = 0\} = S(A)$, $A = (1 \ 1 \ -1)$

a) $U^\perp = ?$

b) Sa se det. un reper ortonormat in \mathbb{R}^3

$R = R_1 \cup R_2$, unde R_1 reper ortonormat in U
 $R_2 \perp U$

SOL
a) $\mathbb{R}^3 = U \oplus U^\perp$ complement orthogonal

$U = \{x \in \mathbb{R}^3 \mid g_0((x_1, x_2, x_3), (1, 1, -1)) = 0\}$

$U^\perp = \langle \{(1, 1, -1)\} \rangle$

$\dim U = 2, \dim U^\perp = 1$

b) $U = \{(x_1, x_2, x_1 + x_2) \mid x_1, x_2 \in \mathbb{R}\} = \{(x_1, 0, x_1) + (0, x_2, x_2) \mid x_1, x_2 \in \mathbb{R}\}$
 $x_1(1, 0, 1) + x_2(0, 1, 1)$

$\{f_1, f_2\} \in SG \text{ pt } U \Rightarrow \{f_1, f_2\} \text{ reper arb.}$
 $\dim U = 2$

Aplicăm procedeul Gram-Schmidt

$\begin{cases} e_1 = f_1 = (1, 0, 1) \\ e_2 = f_2 - \frac{\langle f_2, e_1 \rangle}{\langle e_1, e_1 \rangle} \cdot e_1 = (0, 1, 1) - \frac{1}{2}(1, 0, 1) = (-\frac{1}{2}, 1, \frac{1}{2}) = \frac{1}{2}(-1, 2, 1) \end{cases}$

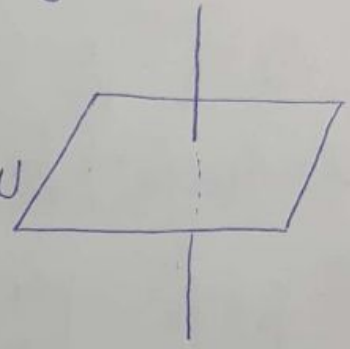
$\langle f_2, e_1 \rangle = g_0(f_2, e_1) = g_0((0, 1, 1), (1, 0, 1)) = 0 \cdot 1 + 1 \cdot 0 + 1 \cdot 1 = 1$

$\langle e_1, e_1 \rangle = g_0(f_1, f_1) = g_0((1, 0, 1), (1, 0, 1)) = 1 + 0 + 1 = 2$

$\{f_1, f_2\} \rightarrow \{e_1, e_2\} \rightarrow \left\{ \frac{e_1}{\|e_1\|}, \frac{e_2}{\|e_2\|} \right\} = R_1$
 reper ∇ reper ortog. reper ortonormat

$\|e_1\| = \sqrt{g_0(e_1, e_1)} = \sqrt{2}$

$R_1 = \left\{ \frac{1}{\sqrt{2}}(1, 0, 1), \frac{1}{\sqrt{6}}(-1, 2, 1) \right\}$ reper ortonormat in U



OBS

$$v = \alpha \cdot u, \alpha > 0$$

$$\|v\| = |\alpha| \cdot \|u\| = \alpha \|u\|$$

$$\frac{v}{\|v\|} = \frac{\alpha u}{\alpha \|u\|} = \frac{u}{\|u\|}$$

$$e_2 = \frac{1}{\sqrt{2}} (-1, 2, 1)$$

$$R_2 = \left\{ \frac{1}{\sqrt{3}} (1, 1, 1) \right\} \text{ reper in } U^\perp$$

$$R = R_1 \cup R_2 = \left\{ \frac{1}{\sqrt{2}} (1, 0, 1), \frac{1}{\sqrt{6}} (-1, 2, 1), \frac{1}{\sqrt{3}} (1, 1, 1) \right\} \text{ reper in } \mathbb{R}^3$$

OBS

$$f_1 \times f_2 = \begin{vmatrix} e_1 & e_2 & e_3 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{vmatrix} = e_1 \begin{vmatrix} 0 & 1 \\ 1 & 1 \end{vmatrix} - e_2 \begin{vmatrix} 1 & 1 \\ 0 & 1 \end{vmatrix} + e_3 \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix}$$

$$= (-1, -1, 1) = - (1, 1, -1)$$

Ex 5 $(\mathbb{C}, +, \cdot) / \mathbb{R}$, $g: \mathbb{C} \times \mathbb{C} \rightarrow \mathbb{R}$ formă biliniară și $G = \begin{pmatrix} 1 & 2 \\ 2 & 5 \end{pmatrix}$

matricea asociată lui g în raport cu $R_0 = \{1, i\}$

a) (\mathbb{C}, g) este sp. vect. euclidian real

b) $u = 2 - i$ este versor în raport cu g

c) $\langle \{u\} \rangle^\perp$

d) Să se ortonormeze R_0 în rap cu g

e) Să se afle intersecția dintre sfera unitate în (\mathbb{C}, g_0) și în (\mathbb{C}, g)

SOL

a) $g: \mathbb{C} \times \mathbb{C} \rightarrow \mathbb{R}$,

$$G = \begin{pmatrix} 1 & 2 \\ 2 & 5 \end{pmatrix}$$

$$g(z, z') = x_1 y_1 + 2x_1 y_2 + 2x_2 y_1 + 5x_2 y_2 = X^T G Y \Rightarrow$$

$$z = x_1 + ix_2 \equiv (x_1, x_2)$$

$$\mathbb{C} \simeq \mathbb{R}^2$$

$$z' = y_1 + iy_2 \equiv (y_1, y_2)$$

g formă biliniară simetrică

$$G = G^T$$

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$$Q: \mathbb{C} \rightarrow \mathbb{R}, Q(z) = g(z, z) = \underline{x_1^2 + 4x_1x_2 + 5x_2^2}$$

Met. Jacobi

$$\Delta_1 = 1 > 0$$

$$\Delta_2 = 5 - 4 = 1 > 0$$

$\Rightarrow \exists$ un reper R' în \mathbb{C} al

$$Q(z) = x_1'^2 + x_2'^2$$

Met Gauss

$$Q(z) = (x_1 + 2x_2)^2 + x_2^2 = x_1'^2 + x_2'^2$$

$$\begin{cases} x_1' = x_1 + 2x_2 \\ x_2' = x_2 \end{cases}$$

$(2, 0)$ semnatura $\Rightarrow Q$ poz def $\Rightarrow g$ poz def.

g este produs scalar $\Rightarrow (\mathbb{C}, g)$ sp. vet. euclidian

b) $u = 2 - i$ versor în rap cu g

$$\|u\|_g = \sqrt{g(u, u)} = \sqrt{Q(u)} = \sqrt{4 + 4 \cdot 2(-1) + 5(-1)^2} = \sqrt{4 - 8 + 5} = 1$$

$$u = 2 - i, x_1 = 2, x_2 = -1$$

$$c) \langle \{u\} \rangle^\perp = \{z \in \mathbb{C} \mid g(z, u) = 0\} = \{z = x_1 + x_2 i \mid -x_2 = 0\} = \mathbb{R}$$

$$z = x_1 + i x_2 \equiv (x_1, x_2)$$

$$u = 2 - i = (2, -1) = (y_1, y_2)$$

$$g(z, z') = g((x_1, x_2), (y_1, y_2)) = x_1 y_1 + 2x_1 y_2 + 2x_2 y_1 + 5x_2 y_2$$

$$g(z, u) = 2x_1 - 2x_1 + 4x_2 - 5x_2 = -x_2$$

$$d) R_0 = \{f_1 = 1, f_2 = i\}$$

Aplicăm procedeele Gram-Schmidt

$$\begin{cases} e_1 = f_1 = 1 \\ e_2 = f_2 - \frac{g(f_2, e_1)}{g(e_1, e_1)} e_1 = i - \frac{2}{1} \cdot 1 = -2 + i \end{cases}$$

$$g(f_2, e_1) = g(i, 1) = 0 \cdot 1 + 2 \cdot 0 \cdot 0 + 2 \cdot 1 \cdot 1 + 5 \cdot 1 \cdot 0 = 2$$

$$g(e_1, e_1) = g(1, 1) = Q(1) = 1^2 + 4 \cdot 1 \cdot 0 + 5 \cdot 0^2 = 1$$

$$\{1, i\} \rightarrow \{e_1=1, e_2=-2+i=u\}$$

reper \forall reper orthonormal

$$g(e_1, e_2) = 0$$

$$g(e_1, e_1) = 1, \quad g(e_2, e_2) = 1$$

e) 1) (\mathbb{C}, g_0) , $g_0: \mathbb{C} \times \mathbb{C} \rightarrow \mathbb{R}, g_0(z, z') = x_1 y_1 + x_2 y_2$.

$$Q_0: \mathbb{C} \rightarrow \mathbb{R}, Q_0(z) = x_1^2 + x_2^2$$

$$S_{g_0}^1 = \{z \in \mathbb{C} \mid \|z\|_{g_0} = 1\} = \{z \in \mathbb{C} \mid x_1^2 + x_2^2 = 1\}$$

$x_1 + ix_2$

2) (\mathbb{C}, g) , $g: \mathbb{C} \times \mathbb{C} \rightarrow \mathbb{R}, g(z, z') = x_1 y_1 + 2x_1 y_2 + 2x_2 y_1 + 5x_2 y_2$

$$Q: \mathbb{C} \rightarrow \mathbb{R}, Q(z) = x_1^2 + 4x_1 x_2 + 5x_2^2$$

$$S_g^1 = \{z \in \mathbb{C} \mid \|z\|_g = 1\} = \{z \in \mathbb{C} \mid x_1^2 + 4x_1 x_2 + 5x_2^2 = 1\}$$

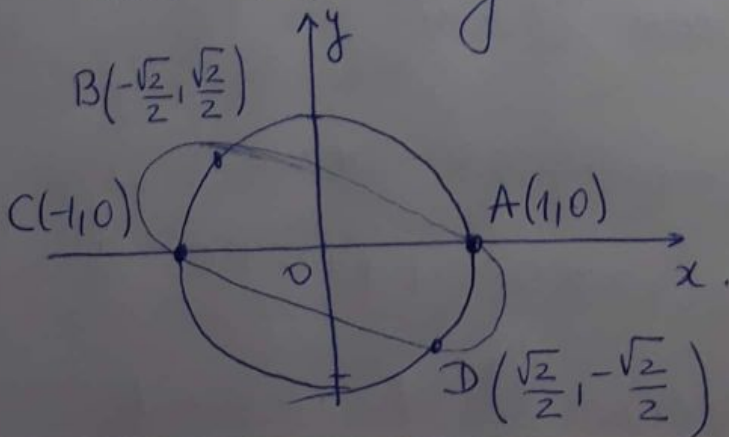
$$S_{g_0}^1 \cap S_g^1: \begin{cases} x_1^2 + x_2^2 = 1 \\ x_1^2 + 4x_1 x_2 + 5x_2^2 = 1 \end{cases} \Rightarrow \begin{cases} x_1^2 + x_2^2 = 1 \\ 4x_1 x_2 + 4x_2^2 = 0 \\ 4x_2(x_1 + x_2) = 0 \end{cases}$$

$$z = x_1 + ix_2 = \cos t + i \sin t, \quad x_1^2 + x_2^2 = 1.$$

$$\sin t (\sin t + \cos t) = 0.$$

• $\sin t = 0 \Rightarrow t = k\pi, k \in \mathbb{Z}.$

• $\sin t = -\cos t \Rightarrow \tan t = -1 \Rightarrow t = -\arctan 1 + k\pi = -\frac{\pi}{4} + k\pi, k \in \mathbb{Z}.$



$$S_{g_0}^1 \cap S_g^1 = \{z_A, z_B, z_C, z_D\}$$

$$z_A = 1$$

$$z_B = -\frac{\sqrt{2}}{2} + i\frac{\sqrt{2}}{2}$$

$$z_C = -1$$

$$z_D = \frac{\sqrt{2}}{2} - i\frac{\sqrt{2}}{2}$$

Ex6. (\mathbb{R}^3, g_0) , $R = \{f_1 = (1, 2, 3), f_2 = (0, 1, 1), f_3 = (1, 2, 5)\}$

a) R reper in \mathbb{R}^3 . f_i o orthonormaze

b) $f_1 \times f_2$; c) $f_1 \wedge f_2 \wedge f_3$

SOL

a) $\det \begin{pmatrix} 1 & 0 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 5 \end{pmatrix} = \begin{vmatrix} \textcircled{1} & \textcircled{0} & \textcircled{1} \\ 2 & 1 & 2 \\ 3 & 1 & 5 \end{vmatrix} = 2 \neq 0 \Rightarrow$

$\Rightarrow R$ este SLI in $\mathbb{R}^3 \} \Rightarrow R$ reper in \mathbb{R}^3

$\dim \mathbb{R}^3 = |R| = 3$

Aplicăm procedeul Gram-Schmidt

$$\begin{cases} e_1 = f_1 = (1, 2, 3) \\ e_2 = f_2 - \frac{g_0(f_2, e_1)}{g_0(e_1, e_1)} e_1 = (0, 1, 1) - \frac{5}{14} (1, 2, 3) = \left(-\frac{5}{14}, \frac{4}{14}, -\frac{1}{14}\right) \\ e_3 = f_3 - \frac{g_0(f_3, e_1)}{g_0(e_1, e_1)} e_1 - \frac{g_0(f_3, e_2)}{g_0(e_2, e_2)} e_2 \end{cases}$$

$g_0(f_2, e_1) = g_0(f_2, f_1) = g_0((0, 1, 1), (1, 2, 3)) = 0 + 2 + 3 = 5$

$g_0(e_1, e_1) = g_0((1, 2, 3), (1, 2, 3)) = 1 + 4 + 9 = 14$

$g_0(f_3, e_1) = g_0((1, 2, 5), (1, 2, 3)) = 1 + 4 + 15 = 20$

$g_0(f_3, e_2) = g_0((1, 2, 5), \left(-\frac{5}{14}, \frac{4}{14}, -\frac{1}{14}\right)) = \frac{-5}{14} + \frac{8}{14} - \frac{5}{14} = \frac{-2}{14} = -\frac{1}{7}$

$g_0(e_2, e_2) = \frac{1}{14^2} g_0((-5, 4, -1), (-5, 4, -1)) = \frac{1}{14^2} (25 + 16 + 1) =$

$= \frac{42}{14^2} = \frac{14 \cdot 3}{14^2} = \frac{3}{14}$

$e_3 = (1, 2, 5) - \frac{20}{14} (1, 2, 3) - \frac{-\frac{1}{7}}{\frac{3}{14}} \cdot \frac{1}{14} (-5, 4, -1) =$
 $= (1, 2, 5) - \frac{10}{7} (1, 2, 3) + \frac{1}{21} (-5, 4, -1) =$

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$$\begin{aligned} e_3 &= \left(1 - \frac{10}{7} - \frac{5}{21}, 2 - \frac{20}{7} + \frac{4}{21}, 5 - \frac{30}{7} - \frac{1}{21} \right) = \\ &= \frac{1}{21} (21 - 30 - 5, 42 - 60 + 4, 105 - 90 - 1) = \\ &= \frac{1}{21} (-14, -14, 14) = \frac{14}{21} (-1, -1, 1) = \frac{2}{3} (-1, -1, 1) \end{aligned}$$

$$\{e_1 = (1, 2, 3), e_2 = \frac{1}{14} (-5, 4, 1), e_3 = \frac{2}{3} (-1, -1, 1)\} \text{ reper orthogonal}$$

$$\left\{ \frac{1}{\sqrt{14}} (1, 2, 3), \frac{1}{\sqrt{42}} (-5, 4, 1), \frac{1}{\sqrt{3}} (-1, -1, 1) \right\} \text{ reper orthonormal}$$

$$\begin{aligned} b) \quad f_1 \times f_2 &= \begin{vmatrix} e_1 & e_2 & e_3 \\ 1 & 2 & 3 \\ 0 & 1 & 1 \end{vmatrix} = e_1 \begin{vmatrix} 2 & 3 \\ 1 & 1 \end{vmatrix} - e_2 \begin{vmatrix} 1 & 3 \\ 0 & 1 \end{vmatrix} + e_3 \begin{vmatrix} 1 & 2 \\ 0 & 1 \end{vmatrix} = \\ &= (-1, -1, 1) \end{aligned}$$

$$\begin{aligned} c) \quad f_1 \wedge f_2 \wedge f_3 &= f_3 \wedge f_1 \wedge f_2 = g_0(f_3, f_1 \times f_2) = -1 - 2 + 5 = 2 \\ f_3 &= (1, 2, 5) \end{aligned}$$

$$\text{SAU} \quad f_1 \wedge f_2 \wedge f_3 = \begin{vmatrix} 1 & 2 & 5 \\ 1 & 2 & 3 \\ 0 & 1 & 1 \end{vmatrix} = 2$$