

## Seminarul 10

Transformări ortogonale. End. sim.

a)  $\mathcal{J} \in \mathbb{O}(\mathbb{R}^3)$   $\Rightarrow$  V.E.R. cu l.m. euclidiană canonica

$$\mathcal{J} \in \text{End}(\mathbb{R}^3), \quad A = [\mathcal{J}]_{\mathbb{R}_0, \mathbb{R}_0} = \frac{1}{g} \begin{pmatrix} 8 & 1 & -4 \\ 1 & 8 & 4 \\ -4 & 4 & -4 \end{pmatrix}$$

$\mathbb{R}_0$  = reperul canonice

b)  $\mathcal{J} \in \mathbb{O}(\mathbb{R}^3)$  și  $\mathcal{J} \in \mathbb{O}(\mathbb{R}^3)$ , să apărtă la i.e.

$$\mathcal{J} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

b) Să se determine  $\alpha$  și  $\beta$  de rotație și axa de rotație

c) Să se determine  $\alpha$  și  $\beta$  un reper  $\mathbb{R} = \{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$  ortonormat

$$\text{a.i. } [\mathcal{J}]_{\mathbb{R}, \mathbb{R}} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & \cos \alpha & -\sin \alpha \\ 0 & \sin \alpha & \cos \alpha \end{pmatrix}$$

$$d) A \cdot A^T = \frac{1}{8} \begin{pmatrix} 8 & 1 & -4 \\ 1 & 8 & 4 \\ -4 & 4 & -4 \end{pmatrix} \cdot \begin{pmatrix} 8 & & \\ & 8 & \\ & & 8 \end{pmatrix} =$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \text{id} \Rightarrow A \in \mathbb{O}_3 \Rightarrow$$

$$\Rightarrow f \in O(\mathbb{R}^3)$$

$$\det A = \frac{1}{9^3} \begin{vmatrix} 8 & 1 & -4 \\ 1 & 8 & 4 \\ -4 & 4 & -1 \end{vmatrix} = \frac{1}{9^3} \cdot (-9)^3 = -1$$

$\rho$  este de apăta 2.

$$b) \operatorname{Tr}(A) = -1 + 2 \cos \varphi = \frac{9}{9} = 1 \Rightarrow \cos \varphi = 1$$

$$\varphi \in (-\pi, \pi] \Rightarrow \varphi = 0.$$

$$A_{x \infty}: f(x) = -x$$

$$f(x) = \frac{1}{9} (8x_1 + x_2 - 4x_3, x_1 + 8x_2 + 4x_3, -4x_1 + 4x_2 - 4x_3)$$

$$\begin{aligned} f(x) &= -x \Rightarrow (8x_1 + x_2 - 4x_3, x_1 + 8x_2 + 4x_3, -4x_1 + 4x_2 - 4x_3) \\ &= (-9x_1, -9x_2, -9x_3) \end{aligned}$$

$$\left\{ \begin{array}{l} 14x_1 + x_2 - 4x_3 = 0 \\ x_1 + 14x_2 + 4x_3 = 0 \\ -4x_1 + 4x_2 + 2x_3 = 0 \end{array} \right.$$

$$B = \begin{pmatrix} 14 & 1 & -4 \\ 1 & 14 & 4 \\ -4 & 4 & 2 \end{pmatrix} \left| \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right., \det B = 0, \operatorname{rg} B = 2.$$

$$14x_1 + x_2 - 4x_3$$

$$x_1 + 14x_2 + 4x_3$$

$$\hline 18x_1 + 18x_2 = 0 \Rightarrow x_1 = -x_2$$

$$x_1 = \frac{1}{4}x_3$$

$$x_2 = -\frac{1}{4}x_3$$

$$= \left\{ \left( \frac{1}{4}x_3, -\frac{1}{4}x_3, x_3 \right) \mid x_3 \in \mathbb{R} \right\} =$$

$$= \left\{ \frac{x_3}{4} \underbrace{\left( 1, -1, 4 \right)}_{f_1} \mid x_3 \in \mathbb{R} \right\}$$

$$e_1 = \frac{f_1}{\|f_1\|} = \frac{(1, -1, 4)}{3\sqrt{2}} \rightarrow \text{normal axis}$$

e)  $\langle e_1 \rangle^\perp = \{ \mathbf{x} \in \mathbb{R}^3 \mid g_0(\mathbf{x}, e_1) = 0 \} =$

$$= \{ \mathbf{x} \in \mathbb{R}^3 \mid \lambda_1 - x_2 + 4x_3 = 0 \} = \{ (x_1, x_2, x_3) \mid$$

$$(x_1, x_2, x_3) \in \{ (1, 1, 0), (0, 4, 1) \} =$$

$$\begin{matrix} f_2 \\ f_3 \end{matrix}$$

$\{f_2, f_3\}$  super in  $\langle e_1 \rangle^\perp$  (SG + CL)

Anwendung Gram-Schmidt

$$e_2' = f_2 = (1, 1, 0)$$

$$e_3' = f_3 - \frac{\langle f_3, e_2' \rangle}{\langle e_2', e_2' \rangle} e_2'$$

$$= (0, 4, 1) - \frac{4}{2} (1, 1, 0)$$

$$= \cancel{(0, 4, 1)} - (2, 2, 0)$$

$$= \sqrt{-2, 2, 1}$$

$$\Rightarrow e_3 = \frac{1}{3}(-2, 2, 1) = \frac{e_3}{\|e_3\|}$$

$$P = \left\{ \frac{1}{\sqrt{2}}(1, -1, 1), \frac{1}{\sqrt{2}}(1, 1, 0), \frac{1}{3}(-2, 2, 1) \right\}$$

Reprezentare ortonormală în  $\mathbb{R}^3$  ai  $[P]_{R, R} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

$f \Rightarrow$  simetria ortogonală față de  $\langle u \rangle^\perp$

• Problema 2:

$(\mathbb{R}^3, g_0)$  p.v.e.n.,  $u = (1, 1, 0)$

a)  $\langle \{u\}^\perp \rangle = ?$ . Precizați un reper ortonormal

b) Se determină transformații ortogonale, de operație, care este roatație de  $\pi/2$  orientată  $\rho = \frac{\pi}{2}$  și axă  $\langle \{u\}^\perp \rangle$

$$\begin{aligned} \text{a)} \quad \langle \{u\}^\perp \rangle &= \{x \in \mathbb{R}^3 \mid g_0(x, u) = 0\} = \{x \in \mathbb{R}^3 \mid x_1 + x_2 = 0\} = \\ &= \{(x_1, -x_1, x_3) \mid x_1, x_3 \in \mathbb{R}\} = \{(1, -1, 0), (0, 0, 1)\} \end{aligned}$$

$\{f_2, f_3\}$  este un reper arbitrar în  $\langle \{u\}^\perp \rangle$  ( $\dim \langle \{u\}^\perp \rangle = 2$ )  
cand  $\{f_2, f_3\} = 2$  în  $\{f_1, f_2, f_3\}$  este S.G.

Aplicăm Gram-Schmidt:

$$l_2 = f_2 = (1, -1, 0) \Rightarrow l_2 = \frac{1}{\sqrt{2}}(1, -1, 0)$$

$$l_3 = f_3 - \frac{\langle f_3, l_2 \rangle}{\langle l_2, l_2 \rangle} \cdot l_2 = (0, 0, 1) - \underline{0} l_2 = (0, 0, 1)$$

$$\text{Atunci } \Rightarrow l_3 = (0, 0, 1)$$

$$l_1 = \frac{u}{\|u\|} = \frac{1}{\sqrt{2}} (1, 1, 0)$$

$$Q = \left\{ l_1 = \frac{1}{\sqrt{2}} (1, 1, 0), l_2 = \frac{1}{\sqrt{2}} (1, -1, 0), l_3 = (0, 0, 1) \right\}$$

reprezentare ortonormală.

$$A' = [f]_{Q, Q} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \frac{\pi}{2} & -\sin \frac{\pi}{2} \\ 0 & \sin \frac{\pi}{2} & \cos \frac{\pi}{2} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$Q_0 = \{l_1^0, l_2^0, l_3^0\} \xrightarrow{C} Q = \{l_1, l_2, l_3\}$$

$$C = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \cdot \begin{pmatrix} 1 & 1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & \sqrt{2} \end{pmatrix}$$

$$A = [f]_{Q_0, Q_0}; \quad A' = C^{-1} \cdot A \cdot C = C^t \cdot A \cdot C$$

$$\boxed{A = C A' C^t}$$

$$3) (\mathbb{R}^3, g_0), \quad g_0 \in \text{End}(\mathbb{R}^3)$$

$$A = [g]_{Q_0, Q_0} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

- a) Dăm că  $f \in \text{lin}(\mathbb{R}^3)$ . Determinați:
- b) Se să scrie ecuația  $Q: \mathbb{R}^3 \rightarrow \mathbb{R}$  formă patratnică asociată
- c) Se să aducă  $Q$  la o formă canonică, efectuând o transformare ortogonală h.  
(i.e. o schimbare de reprezentare ortonormată)

$$Q) A = A' \Rightarrow f \in \text{Lin}(\mathbb{R}^3)$$

$$f(x) = (x_1 + x_3, x_2, x_1 + x_3)$$

$$Q(x) = x^T A x = \sum_{i,j=1}^3 a_{ij} x_i \cdot x_j$$

$$Q(x) = x_1^2 + 2x_1x_3 + x_2^2 + x_3^2$$

Aplicăm metoda vectorilor proprii

## I Polinomul caracteristic

$$\begin{aligned} P(\lambda) = \det(A - \lambda I_3) &= \begin{vmatrix} 1-\lambda & 0 & 1 \\ 0 & 1-\lambda & 0 \\ 1 & 0 & 1-\lambda \end{vmatrix} = \\ &= (1-\lambda) \cdot (-1)^4 \begin{vmatrix} 1-\lambda & 1 \\ 1 & 1-\lambda \end{vmatrix} = (1-\lambda)((1-\lambda)^2 - 1) = \\ &= (1-\lambda)(1-2\lambda+\lambda^2-1) = (1-\lambda)(\lambda^2-2\lambda) = \\ &= \lambda(1-\lambda)(\lambda-2) \end{aligned}$$

$$\text{I. } \lambda_1 = 1, m_1 = 1$$

$$\lambda_2 = 0, m_2 = 1$$

$$\lambda_3 = 2, m_3 = 1$$

$$V_{\lambda_1} = \left\{ x \in \mathbb{R}^3 \mid A \cdot x = \lambda_1 \cdot x = x \right\}$$

$$(A - i_3) \cdot x = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$\downarrow x_3 = 0 \quad \Rightarrow \quad \text{rg} = 1$

$$\therefore x_1 = 0$$

$$\lambda_1 = \left\{ \begin{pmatrix} 0, x_2, 0 \end{pmatrix} \mid x_2 \in \mathbb{R} \right\} \cup \{(0, 1, 0)\} >$$

$e_1 = (0, 1, 0)$

$$\lambda_2 = \left\{ x \in \mathbb{R}^3 \mid A \cdot x = x \cdot \lambda_2 \right\}$$

$$A \cdot x = 0_{3,1}$$

$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{cases} x_1 + x_3 = 0 \\ x_2 = 0 \end{cases} \Leftrightarrow \begin{cases} x_1 = -x_3 \\ x_2 = 0 \end{cases}$$

$$\lambda_2 = \{-1, 0, -1\} >$$

$$e_2 = \frac{1}{\sqrt{2}} (-1, 0, -1)$$

$$\lambda_3 = \left\{ x \in \mathbb{R}^3 \mid A \cdot x = x \cdot \lambda_3 \right\}$$

$$(A - 2e_3) \cdot x = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & -1 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\left\{ \begin{array}{l} -x_1 + x_3 = 0 \Rightarrow x_1 = x_3 \\ -x_2 = 0 \\ x_1 - x_3 = 0 \end{array} \right.$$

$$L_{2,3} = \{ (x_1, 0, x_1) \mid x_1 \in \mathbb{R}\} = \{(1, 0, 1)\}$$

$$e_2 = \frac{1}{\sqrt{2}}(1, 0, 1)$$

$$Q = \left\{ (0, 1, 0), \frac{1}{\sqrt{2}}(1, 0, -1), \frac{1}{\sqrt{2}}(1, 0, 1) \right\} \rightarrow \text{reper orthonormal}$$

$$[g]_{R, R} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix} = I'$$

$$Q(x) = x_1^2 + 2x_3^2$$

Signature: \$(2, 0) \rightarrow\$ nu e definita positiva  
 (nu are fisi 3 si 0)

$$Q = \{e_1^0, e_2^0, e_3^0\} \xrightarrow{\text{Cf}(0)} Q = \{e_1, e_2, e_3\}$$

orthogonale

$$C = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 1 \\ \sqrt{2} & 0 & 0 \\ 0 & -1 & 1 \end{pmatrix}$$

$$R \in O(\mathbb{R}^3)$$

$$R(e_i^0) = e_1, \quad (T) \approx \frac{1}{\sqrt{3}}$$

$$\begin{aligned} R(e_2^0) &= \frac{1}{\sqrt{2}}(e_1 + e_2) \\ R(e_3^0) &= \frac{1}{\sqrt{2}}(e_1 - e_2) \end{aligned}$$

$$\left\langle T(1, 0, 1) \right\rangle = \left\langle R(1, 0, 1) \right\rangle = \text{est}$$

$$(1, 0, 1) \approx 0.9$$

$$\text{vers} \circ T(1, 0, 1) = \text{vers}(1, 0, 1) + (0, 1, 0) = \varphi$$

dommable

$$T = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \rightarrow E(0, 0, 1)$$

$$E(0, 0, 1) \cdot x = (x, 0, 1)$$

definitivt vart att om man rör sig längre ut i rummet  
(dvs i  $\mathbb{R}^3$  men inte i  $\mathbb{R}^2$ )

$$T(1, 0, 1) \rightarrow R(1, 0, 1) \rightarrow (1, 0, 1) = \text{est}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$