Swap arguals with y if the latter is simpler.

argvalsy.swap

Description

Preprocess argvals, y, and basisobj. If only one of argvals and y is provided, use it as y and take argvals as a vector spanning basisobj[['rangreval']]. If both are provided, the simpler becomes argvals. If both have the same dimensions but only one lies in basisobj[['rangreval']], that becomes argvals.

Usage

```
argvalsy.swap(argvals=NULL, y=NULL, basisobj=NULL)
```

Arguments

argvals a vector or array of argument values.

y an array containing sampled values of curves.

basisobj One of the following:

basisfd a functional basis object (class basisfd.

fd a functional data object (class fd), from which its basis component is extracted.

fdPar a functional parameter object (class fdPar), from which its basis component is extracted.

integer an integer giving the order of a B-spline basis, create.bspline.basis(argvals, norder=basisobj)

numeric vector specifying the knots for a B-spline basis, create.bspline.basis(basisobj) NULL Defaults to create.bspline.basis(argvals).

Details

- 1. If y is NULL, replace by argvals.
- 2. If argvals is NULL, replace by seq(basisobj[['rangeval']][1], basisobj[['rangeval']][2], dim(y)[1]) with a warning.
- 3. If the dimensions of argvals and y match and only one is contained in basisobj[['rangeval']], use that as argvals and the other as y.
- 4. if y has fewer dimensions than argvals, swap them.

Value

a list with components argvals, y, and basisobj.

See Also

Data2fd smooth.basis, smooth.basisPar

```
## one argument: y
argvalsy.swap(1:5)
# warning ...
##
## (argvals, y), same dimensions: retain order
argy1 <- argvalsy.swap(seq(0, 1, .2), 1:6)</pre>
argy1a <- argvalsy.swap(1:6, seq(0, 1, .2))</pre>
all.equal(argy1[[1]], argy1a[[2]]) &&
all.equal(argy1[[2]], argy1a[[1]])
# TRUE; basisobj different
# lengths do not match
## Not run:
argvalsy.swap(1:4, 1:5)
## End(Not run)
## two numeric arguments, different dimensions: put simplest first
argy2 <- argvalsy.swap(seq(0, 1, .2), matrix(1:12, 6))</pre>
all.equal(argy2,
argvalsy.swap(matrix(1:12, 6), seq(0, 1, .2)))
# TRUE with a warning ...
## Not run:
argvalsy.swap(seq(0, 1, .2), matrix(1:12, 2))
# ERROR: first dimension does not match
## End(Not run)
##
## one numeric, one basisobj
argy3 <- argvalsy.swap(1:6, b=4)</pre>
# warning: argvals assumed seq(0, 1, .2)
argy3. <- argvalsy.swap(1:6, b=create.bspline.basis(breaks=0:1))</pre>
# warning: argvals assumed seq(0, 1, .2)
argy3.6 <- argvalsy.swap(seq(0, 1, .2), b=create.bspline.basis(breaks=1:3))</pre>
# warning: argvals assumed seq(1, 3 length=6)
```

```
##
## two numeric, one basisobj: first matches basisobj
##
# OK
argy3a \leftarrow argvalsy.swap(1:6, seq(0, 1, .2),
              create.bspline.basis(breaks=c(1, 4, 8)))
# Swap (argvals, y)
all.equal(argy3a,
argvalsy.swap(seq(0, 1, .2), 1:6,
              create.bspline.basis(breaks=c(1, 4, 8))) )
# TRUE with a warning
## Not run:
# neither match basisobj: error
argvalsy.swap(seq(0, 1, .2), 1:6,
              create.bspline.basis(breaks=1:3) )
## End(Not run)
```

arithmetic.basisfd

Arithmetic on functional basis objects

Description

Arithmatic on functional basis objects

Usage

```
"==.basisfd"(basis1, basis2)
```

Arguments

basis1, basis2

functional basis object

Value

basisobj1 == basisobj2 returns a logical scalar.

References

Ramsay, James O., and Silverman, Bernard W. (2005), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York.

See Also

basisfd, basisfd.product arithmetic.fd

arithmetic.fd

Arithmetic on functional data ('fd') objects

Description

Arithmetic on functional data objects

Usage

```
"+.fd"(e1, e2)
"-.fd"(e1, e2)
"*.fd"(e1, e2)
plus.fd(e1, e2, basisobj=basisobj1*basisobj2)
minus.fd(e1, e2, basisobj=basisobj1*basisobj2)
times.fd(e1, e2, basisobj=basisobj1*basisobj2)
```

Arguments

e1, e2

object of class 'fd' or a numeric vector. Note that 'e1+e2' will dispatch to plus.fd(e1, e2) only of e1 has class 'fd'. Similarly, 'e1-e2' or 'e1*e2' will dispatch to minus.fd(e1, e2) or time.fd(e1, e2), respetively, only if e1 is of class 'fd'.

basisobj

reference basis

Value

A function data object corresponding to the pointwise sum, difference or product of e1 and e2.

If both arguments are functional data objects, the bases are the same, and the coefficient matrices are the same dims, the indicated operation is applied to the coefficient matrices of the two objects. In other words, e1+e2 is obtained for this case by adding the coefficient matrices from e1 and e2.

If e1 or e2 is a numeric scalar, that scalar is applied to the coefficient matrix of the functional data object.

If either e1 or e2 is a numeric vector, it must be the same length as the number of replicated functional observations in the other argument.

When both arguments are functional data objects, they need not have the same bases. However, if they don't have the same number of replicates, then one of them must have a single replicate. In the second case, the singleton function is replicated to match the number of replicates of the other function. In either case, they must have the same number of functions. When both arguments are functional data objects, and the bases are not the same, the basis used for the sum is constructed to be of higher dimension than the basis for either factor according to rules described in function TIMES for two basis objects.

See Also

basisfd, basisfd.product

Examples

```
##
## add a parabola to itself
bspl4 <- create.bspline.basis(nbasis=4)</pre>
parab4.5 \leftarrow fd(c(3, -1, -1, 3)/3, bspl4)
str(parab4.5+parab4.5)
\# coefs = c(6, -2, -2, 6)/3
str(parab4.5-parab4.5)
\# coefs = c(0, 0, 0, 0)
##
## Same example with interior knots at 1/3 and 1/5
bspl5.3 <- create.bspline.basis(breaks=c(0, 1/3, 1))
plot(bspl5.3)
x. < - seq(0, 1, .1)
para 4.5.3 \leftarrow smooth.basis(x., 4*(x.-0.5)^2, fdParobj=bspl5.3)[['fd']]
plot(para4.5.3)
bspl5.2 <- create.bspline.basis(breaks=c(0, 1/2, 1))
plot(bspl5.2)
para4.5.2 \leftarrow smooth.basis(x., 4*(x.-0.5)^2, fdParobj=bspl5.2)[['fd']]
plot(para4.5.2)
str(para4.5.3+para4.5.2)
str(para4.5.3-para4.5.2)
str(para4.5.3*para4.5.2)
# interior knots of the sum
# = union(interior knots of the summands);
# ditto for difference and product.
```

as.array3

Reshape a vector or array to have 3 dimensions.

Description

Coerce a vector or array to have 3 dimensions, preserving dimnames if feasible. Throw an error if length($\dim(x)$) > 3.

Usage

```
as.array3(x)
```

Arguments

х A vector or array.

Details

```
1. \dim x < -\dim(x); \dim < -\operatorname{length}(\dim x)
2. if(ndim==3)return(x).
3. if(ndim>3)stop.
4. x2 \ll as.matrix(x)
5. \dim(x2) < c(\dim(x2), 1)
6. xnames < -dimnames(x)
```

7. if(is.list(xnames))dimnames(x2) <- list(xnames[[1]], xnames[[2]], NULL)

Value

A 3-dimensional array with names matching x

Author(s)

Spencer Graves

See Also

dim, dimnames checkDims3

```
## vector -> array
as.array3(c(a=1, b=2))
##
## matrix -> array
as.array3(matrix(1:6, 2))
as.array3(matrix(1:6, 2, dimnames=list(letters[1:2], LETTERS[3:5])))
##
## array -> array
as.array3(array(1:6, 1:3))
##
## 4-d array
##
## Not run:
as.array3(array(1:24, 1:4))
Error in as.array3(array(1:24, 1:4)) :
```

```
length(dim(array(1:24, 1:4)) = 4 > 3
## End(Not run)
```

as.fd

Convert a spline object to class 'fd'

Description

Translate a spline object of another class into the Functional Data (class fd) format.

Usage

```
as.fd(x, ...)
## S3 method for class 'fdSmooth':
as.fd(x, ...)
## S3 method for class 'dierckx':
as.fd(x, ...)
## S3 method for class 'function':
as.fd(x, ...)
## S3 method for class 'smooth.spline':
as.fd(x, ...)
```

Arguments

x an object to be converted to class fd.

... optional arguments passed to specific methods, currently unused.

Details

The behavior depends on the class and nature of x.

as.fd.fdSmooth extract the fd component

as.fd.dierckx The 'fda' package (as of version 2.0.0) supports B-splines with coincident boundary knots. For periodic phenomena, the DierckxSpline packages uses periodic spines, while fda recommends finite Fourier series. Accordingly, as.fd.dierckx if x[["periodic"]] is TRUE.

The following describes how the components of a dierckx object are handled by as.dierckx(as.fd(x)):

```
x lost. Restored from the knots.
```

- y lost. Restored from spline predictions at the restored values of 'x'.
- w lost. Restored as rep(1, length(x)).

```
from, to fd[["basis"]][["rangeval"]]
```

- k coded indirectly as fd[["basis"]][["nbasis"]] length(fd[["basis"]][["params"]]) 1.
- s lost, restored as 0.

```
nest lost, restored as length(x) + k + 1
```

n coded indirectly as 2*fd[["basis"]][["nbasis"]] - length(fd[["basis"]][["params"]]).

```
knots The end knots are stored (unreplicated) in fd[["basis"]][["rangeval"]], while the interior knots are stored in fd[["basis"]][["params"]].
```

fp lost. Restored as 0.

wrk, lwrk, iwrk lost. Restore by refitting to the knots.

ier lost. Restored as 0.

message lost. Restored as character(0).

g stored indirectly as length(fd[["basis"]][["params"]]).

method lost. Restored as "ss".

periodic 'dierckx2fd' only translates 'dierckx' objects with coincident boundary knots. Therefore, 'periodic' is restored as FALSE.

routine lost. Restored as 'curfit.default'.

xlab fd[["fdnames"]][["args"]]

ylab fd[["fdnames"]][["funs"]]

as.fd.function Create an fd object from a function of the form created by splinefun. This will translate method = 'fmn' and 'natural' but not 'periodic': 'fmn' splines are isomorphic to standard B-splines with coincident boundary knots, which is the basis produced by create.bspline.basis. 'natural' splines occupy a subspace of this space, with the restriction that the second derivative at the end points is zero (as noted in the Wikipedia spline article). 'periodic' splines do not use coindicent boundary knots and are not currently supported in fda; instead, fda uses finite Fourier bases for periodic phenomena.

as.fd.smooth.spline Create an fd object from a smooth.spline object.

Value

as.fd.dierckx converts an object of class 'dierckx' into one of class fd.

Author(s)

Spencer Graves

References

Dierckx, P. (1991) Curve and Surface Fitting with Splines, Oxford Science Publications.

Ramsay, James O., and Silverman, Bernard W. (2005), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York.

spline entry in Wikipedia http://en.wikipedia.org/wiki/Spline_(mathematics)

See Also

as.dierckx curfit fd splinefun

```
## as.fd.fdSmooth
girlGrowthSm <- with(growth, smooth.basisPar(argvals=age, y=hgtf))</pre>
girlGrowth.fd <- as.fd(girlGrowthSm)</pre>
## as.fd.dierckx
##
x < -0:24
y \leftarrow c(1.0,1.0,1.4,1.1,1.0,1.0,4.0,9.0,13.0,
       13.4,12.8,13.1,13.0,14.0,13.0,13.5,
       10.0,2.0,3.0,2.5,2.5,2.5,3.0,4.0,3.5)
library(DierckxSpline)
curfit.xy <- curfit(x, y, s=0)</pre>
curfit.fd <- as.fd(curfit.xy)</pre>
plot(curfit.fd) # as an 'fd' object
points(x, y) # Curve goes through the points.
x. <- seq(0, 24, length=241)
pred.y <- predict(curfit.xy, x.)</pre>
lines(x., pred.y, lty="dashed", lwd=3, col="blue")
# dierckx and fd objects match.
all.equal(knots(curfit.xy, FALSE), knots(curfit.fd, FALSE))
all.equal(coef(curfit.xy), as.vector(coef(curfit.fd)))
## as.fd.function(splinefun(...), ...)
##
x2 <- 1:7
y2 <- \sin((x2-0.5)*pi)
f <- splinefun(x2, y2)
fd. \leftarrow as.fd(f)
x. < - seq(1, 7, .02)
fx. \leftarrow f(x.)
fdx. <- eval.fd(x., fd.)</pre>
plot(range(x2), range(y2, fx., fdx.), type='n')
points(x2, y2)
lines(x., sin((x.-0.5)*pi), lty='dashed')
lines(x., f(x.), col='blue')
\label{lines} lines({\tt x., eval.fd(x., fd.), col='red', lwd=3, lty='dashed'})
# splinefun and as.fd(splineful(...)) are close
# but quite different from the actual function
```

```
# apart from the actual 7 points fitted,
# which are fitted exactly
# ... and there is no information in the data
# to support a better fit!
# Translate also a natural spline
fn <- splinefun(x2, y2, method='natural')</pre>
fn. <- as.fd(fn)</pre>
lines(x., fn(x.), lty='dotted', col='blue')
lines(x., eval.fd(x., fn.), col='green', lty='dotted', lwd=3)
## Not run:
# Will NOT translate a periodic spline
fp <- splinefun(x, y, method='periodic')</pre>
as.fd(fp)
#Error in as.fd.function(fp) :
# x (fp) uses periodic B-splines, and as.fd is programmed
    to translate only B-splines with coincident boundary knots.
## End(Not run)
## as.fd.smooth.spline
cars.spl <- with(cars, smooth.spline(speed, dist))</pre>
cars.fd <- as.fd(cars.spl)</pre>
plot(dist~speed, cars)
lines(cars.spl)
sp. <- with(cars, seq(min(speed), max(speed), len=101))</pre>
d. <- eval.fd(sp., cars.fd)</pre>
lines(sp., d., lty=2, col='red', lwd=3)
```

axisIntervals

Mark Intervals on a Plot Axis

Description

Adds an axis to the current plot, with tick marks delimiting interval described by labels

Usage

Arguments

side

an integer specifying which side of the plot the axis is to be drawn on. The axis is placed as follows: 1=below, 2=left, 3=above and 4=right.

the points at which tick-marks marking the starting points of the interatTick1 vals are to be drawn. This defaults to 'monthBegin.5' to mark monthly periods for an annual cycle. These are constructed by calling axis(side, at=atTick1, labels=FALSE, ...). For more detail on this, see 'axis'. atTick2 the points at which tick-marks marking the ends of the intervals are to be drawn. This defaults to 'monthBegin.5' to mark monthly periods for an annual cycle. These are constructed by calling axis(side, at=atTick2, labels=FALSE, ...). Use atTick2=NA to rely only on atTick1. For more detail on this, see 'axis'. atLabels the points at which 'labels' should be typed. These are constructed by calling axis(side, at=atLabels, tick=FALSE, ...). For more detail on this, labels Labels to be typed at locations 'atLabels'. This is accomplished by calling axis(side, at=atLabels, labels=labels, tick=FALSE, ...). For more detail on this, see 'axis'. Character expansion (magnification) used for axis annotations ('labels' in cex.axis this function call) relative to the current setting of 'cex'. For more detail, see 'par'. additional arguments passed to axis.

Value

The value from the third (labels) call to 'axis'. This function is usually invoked for its side effect, which is to add an axis to an already existing plot.

Side Effects

An axis is added to the current plot.

Author(s)

Spencer Graves

See Also

axis, par monthBegin.5 monthEnd.5 monthMid month.abb monthLetters

```
axisIntervals(1)
axis(2)
# Depending on the physical size of the plot,
# axis labels may not all print.
# In that case, there are 2 options:
# (1) reduce 'cex.lab'.
# (2) Use different labels as illustrated by adding
# such an axis to the top of this plot

axisIntervals(3, labels=monthLetters, cex.lab=1.2, line=-0.5)
# 'line' argument here is passed to 'axis' via '...'
```

basisfd.product

Product of two basisfd objects

Description

pointwise multiplication method for basisfd class

Usage

```
"*.basisfd"(basisobj1, basisobj2)
```

Arguments

```
basisobj1, basisobj2
objects of class basisfd
```

Details

TIMES for (two basis objects sets up a basis suitable for expanding the pointwise product of two functional data objects with these respective bases. In the absence of a true product basis system in this code, the rules followed are inevitably a compromise: (1) if both bases are B-splines, the norder is the sum of the two orders - 1, and the breaks are the union of the two knot sequences, each knot multiplicity being the maximum of the multiplicities of the value in the two break sequences. That is, no knot in the product knot sequence will have a multiplicity greater than the multiplicities of this value in the two knot sequences. The rationale this rule is that order of differentiability of the product at eachy value will be controlled by whichever knot sequence has the greater multiplicity. In the case where one of the splines is order 1, or a step function, the problem is dealt with by replacing the original knot values by multiple values at that location to give a discontinuous derivative. (2) if both bases are Fourier bases, AND the periods are the the same, the product is a Fourier basis with number of basis functions the sum of the two numbers of basis fns. (3) if only one of the bases is B-spline, the product basis is B-spline with the same knot sequence and order two higher. (4) in all other cases, the product is a B-spline basis with number of basis functions equal to the sum of the two numbers of bases and equally spaced knots.

See Also

basisfd

basisfd

Define a Functional Basis Object

Description

This is the constructor function for objects of the basisfd class. Each function that sets up an object of this class must call this function. This includes functions create.bspline.basis, create.constant.basis, create.fourier.basis, and so forth that set up basis objects of a specific type. Ordinarily, user of the functional data analysis software will not need to call this function directly, but these notes are valuable to understanding what the "slots" or "members" of the basisfd class are.

Usage

Arguments

type

a character string indicating the type of basis. Currently, there are eight possible types:

- 1. bspline
- 2. const
- 3. expon
- 4. fourier
- 5. monom
- 6. polyg
- 7. polynom
- 8. power

rangeval

a vector of length 2 containing the lower and upper boundaries of the range over which the basis is defined

nbasis

the number of basis functions

params

a vector of parameter values defining the basis

dropind

a vector of integers specifiying the basis functions to be dropped, if any. For example, if it is required that a function be zero at the left boundary, this is achieved by dropping the first basis function, the only one that is nonzero at that point. Default value NULL.

quadvals a matrix with two columns and a number of rows equal to the number

of argument values used to approximate an integral using Simpson's rule. The first column contains these argument values. A minimum of 5 values are required for each inter-knot interval, and that is often enough. These are equally spaced between two adjacent knots. The second column contains the weights used for Simpson's rule. These are proportional to 1, 4,

2, 4, ..., 2, 4, 1.

values a list containing the basis functions and their derivatives evaluated at the quadrature points contained in the first column of quadvals.

Details

Previous versions of the 'fda' software used the name basis for this class, and the code in Matlab still does. However, this class name was already used elsewhere in the S languages, and there was a potential for a clash that might produce mysterious and perhaps disastrous consequences.

To check that an object is of this class, use function is.basis.

It is comparatively simple to add new basis types. The code in the following functions needs to be estended to allow for the new type: basisfd, use.proper.basis, getbasismatrix and getbasispenalty. In addition, a new "create" function should be written for the new type, as well as functions analogous to fourier and fourierpen for evaluating basis functions for basis penalty matrices.

The "create" function names are rather long, and users who mind all that typing might be advised to modify these to versions with shorter names, such as "splbas", "conbas", and etc. However, a principle of good programming practice is to keep the code readable, preferably by somebody other than the programmer.

Normally only developers of new basis types will actually need to use this function, so no examples are provided.

Value

an object of class basisfd

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York

See Also

is.basis, is.eqbasis, plot.basisfd, getbasismatrix, getbasispenalty, create.bspline.basis, create.constant.basis, create.exponential.basis, create.fourier.basis, create.monomial.basis, create.polygonal.basis, create.polygonal.basis, create.polygonal.basis

Description

This function creates a bivariate functional data object, which consists of two bases for expanding a functional data object of two variables, s and t, and a set of coefficients defining this expansion. The bases are contained in "basisfd" objects.

Usage

Arguments

coef

a two-, three-, or four-dimensional array containing coefficient values for the expansion of each set of bivariate function values=terms of a set of basis function values

If 'coef' is two dimensional, this implies that there is only one variable and only one replication. In that case, the first and second dimensions correspond to the basis functions for the first and second argument, respectively.

If 'coef' is three dimensional, this implies that there are multiple replicates on only one variable. In that case, the first and second dimensions correspond to the basis functions for the first and second argument, respectively, and the third dimension corresponds to replications.

If 'coef' has four dimensions, the fourth dimension corresponds to variables.

sbasisobj

a functional data basis object for the first argument s of the bivariate function.

tbasisobj

a functional data basis object for the second argument t of the bivariate function.

fdnames

A list of length 4 containing dimnames for 'coefs' if it is a 4-dimensional array. If it is only 2- or 3-dimensional, the later components of fdnames are not applied to 'coefs'. In any event, the components of fdnames describe the following:

- (1) The row of 'coefs' corresponding to the bases in sbasisobj. Defaults to sbasisobj[["names"]] if non-null and of the proper length, or to existing dimnames(coefs)[[1]] if non-null and of the proper length, and to 's1', 's2', ..., otherwise.
- (2) The columns of 'coefs' corresponding to the bases in thasisobj. Defaults to the thasisobj[["names"]] if non-null and of the proper length, or to existing dimnames(coefs)[[2]] if non-null and of the proper length, and to 't1', 't2', ..., otherwise.

- (3) The replicates. Defaults to dimnames(coefs)[[3]] if non-null and of the proper length, and to 'rep1', ..., otherwise.
- (4) Variable names. Defaults to dimnames(coefs)[[4]] if non-null and of the proper length, and to 'var1', ..., otherwise.

Value

A bivariate functional data object = a list of class 'bifd' with the following components:

the input 'coefs' possible with dimnames from dfnames if provided or from

 ${\tt sbasisobj} names and tbasisobsj {\tt names}$

sbasisobj a functional data basis object for the first argument s of the bivariate

function.

tbasisobj a functional data basis object for the second argument t of the bivariate

function.

bifdnames a list of length 4 giving names for the dimensions of coefs, with one or two

unused lists of names if length(dim(coefs)) is only two or one, respectively.

Author(s)

Spencer Graves

See Also

basisfd data2fd objAndNames

Examples

```
Bspl2 <- create.bspline.basis(nbasis=2, norder=1)
Bspl3 <- create.bspline.basis(nbasis=3, norder=2)

(bBspl2.3 <- bifd(array(1:6, dim=2:3), Bspl2, Bspl3))
str(bBspl2.3)</pre>
```

bsplinepen

B-Spline Penalty Matrix

Description

Computes the matrix defining the roughness penalty for functions expressed in terms of a B-spline basis.

Usage

bsplinepen(basisobj, Lfdobj=2, rng=basisobj\$rangeval)

Arguments

basisobj a B-spline basis object.

Lfdobj either a nonnegative integer or a linear differential operator object.

rng a vector of length 2 defining range over which the basis penalty is to be

computed.

Details

A roughness penalty for a function x(t) is defined by integrating the square of either the derivative of x(t) or, more generally, the result of applying a linear differential operator L to it. The most common roughness penalty is the integral of the square of the second derivative, and this is the default. To apply this roughness penalty, the matrix of inner products of the basis functions (possibly after applying the linear differential operator to them) defining this function is necessary. This function just calls the roughness penalty evaluation function specific to the basis involved.

Value

a symmetric matrix of order equal to the number of basis functions defined by the B-spline basis object. Each element is the inner product of two B-spline basis functions after applying the derivative or linear differential operator defined by Lfdobj.

Examples

```
##
## bsplinepen with only one basis function
##
bspl1.1 <- create.bspline.basis(nbasis=1, norder=1)
pen1.1 <- bsplinepen(bspl1.1, 0)

##
## bspline pen for a cubic spline with knots at seq(0, 1, .1)
##
basisobj <- create.bspline.basis(c(0,1),13)
# compute the 13 by 13 matrix of inner products of second derivatives
penmat <- bsplinepen(basisobj)</pre>
```

bsplineS

B-spline Basis Function Values

Description

Evaluates a set of B-spline basis functions, or a derivative of these functions, at a set of arguments.

Usage

```
bsplineS(x, breaks, norder=4, nderiv=0)
```

Arguments

x A vector of argument values at which the B-spline basis functions are to

be evaluated.

breaks A strictly increasing set of break values defining the B-spline basis. The

argument values x should be within the interval spanned by the break

values.

norder The order of the B-spline basis functions. The order less one is the degree

of the piece-wise polynomials that make up any B-spline function. The

default is order 4, meaning piece-wise cubic.

nderiv A nonnegative integer specifying the order of derivative to be evaluated.

The derivative must not exceed the order. The default derivative is 0,

meaning that the basis functions themselves are evaluated.

Value

a matrix of function values. The number of rows equals the number of arguments, and the number of columns equals the number of basis functions.

Examples

```
# Minimal example: A B-spline of order 1 (i.e., a step function)
# with 0 interior knots:
bsplineS(seq(0, 1, .2), 0:1, 1, 0)

# set up break values at 0.0, 0.2,..., 0.8, 1.0.
breaks <- seq(0,1,0.2)
# set up a set of 11 argument values
x <- seq(0,1,0.1)
# the order will1 be 4, and the number of basis functions
# is equal to the number of interior break values (4 here)
# plus the order, for a total here of 8.
norder <- 4
# compute the 11 by 8 matrix of basis function values
basismat <- bsplineS(x, breaks, norder)</pre>
```

CanadianWeather

Canadian average annual weather cycle

Description

Daily temperature and precipitation at 35 different locations in Canada averaged over 1960 to 1994.

Usage

CanadianWeather daily

Format

'CanadianWeather' and 'daily' are lists containing essentially the same data. 'Canadian-Weather' may be preferred for most purposes; 'daily' is included primarily for compatability with scripts written before the other format became available and for compatability with the Matlab 'fda' code.

CanadianWeather A list with the following components:

- dailyAv a three dimensional array c(365, 35, 3) summarizing data collected at 35 different weather stations in Canada on the following:
 - [,1] = [, 'Temperature.C']: average daily temperature for each day of the year
 - [,2] = [, 'Precipitation.mm']: average daily rainfall for each day of the year rounded to 0.1 mm.
 - [,3] = [, 'log10precip']: base 10 logarithm of Precipitation.mm after first replacing 27 zeros by 0.05 mm (Ramsay and Silverman 2006, p. 248).
 - place Names of the 35 different weather stations in Canada whose data are summarized in 'dailyAv'. These names vary between 6 and 11 characters in length. By contrast, daily[["place"]] which are all 11 characters, with names having fewer characters being extended with trailing blanks.

province names of the Canadian province containing each place

- coordinates a numeric matrix giving 'N.longitude' and 'W.latitude' for each place.
 - region Which of 4 climate zones contain each place: Atlantic, Pacific, Continental, Arctic.
- monthlyTemp A matrix of dimensions (12, 35) giving the average temperature in degrees celcius for each month of the year.
- monthlyPrecip A matrix of dimensions (12, 35) giving the average daily precipitation in milimeters for each month of the year.
 - geogindex Order the weather stations from East to West to North
 - daily A list with the following components:
 - place Names of the 35 different weather stations in Canada whose data are summarized in 'dailyAv'. These names are all 11 characters, with shorter names being extended with trailing blanks. This is different from CanadianWeather[["place"]], where trailing blanks have been dropped.
 - tempav a matrix of dimensions (365, 35) giving the average temperature in degrees celcius for each day of the year. This is essentially the same as CanadianWeather[["dailyAv"]][,, "Temperature.C"].
 - precipav a matrix of dimensions (365, 35) giving the average temperature in degrees celcius for each day of the year. This is essentially the same as CanadianWeather[["dailyAv"]][,, "Precipitation.mm"].

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York

See Also

monthAccessories

Examples

```
data(CanadianWeather)
# Expand the left margin to allow space for place names
op \leftarrow par(mar=c(5, 4, 4, 5)+.1)
# Plot
stations <- c("Pr. Rupert", "Montreal", "Edmonton", "Resolute")</pre>
matplot(day.5, CanadianWeather$dailyAv[, stations, "Temperature.C"],
        type="1", axes=FALSE, xlab="", ylab="Mean Temperature (deg C)")
axis(2, las=1)
# Label the horizontal axis with the month names
axis(1, monthBegin.5, labels=FALSE)
axis(1, monthEnd.5, labels=FALSE)
axis(1, monthMid, monthLetters, tick=FALSE)
# Add the monthly averages
matpoints(monthMid, CanadianWeather$monthlyTemp[, stations])
# Add the names of the weather stations
mtext(stations, side=4,
      at=CanadianWeather$dailyAv[365, stations, "Temperature.C"],
     las=1)
# clean up
par(op)
```

cca.fd

Functional Canonical Correlation Analysis

Description

Carry out a functional canonical correlation analysis with regularization or roughness penalties on the estimated canonical variables.

Usage

Arguments

fdobj1 a functional data object.

fdobj2 a functional data object. By default this is fdobj1, in which case the first argument must be a bivariate funnctional data object.

ncan the number of canonical variables and weight functions to be computed. The default is 2.

ccafdParobj1 a functional parameter object defining the first set of canonical weight functions. The object may contain specifications for a roughness penalty.

The default is defined using the same basis as that used for fdobj1 with a slight penalty on its second derivative.

ccafdParobj2 a functional parameter object defining the second set of canonical weight

functions. The object may contain specifications for a roughness penalty.

The default is ccafdParobj1.

centerfns if TRUE, the functions are centered prior to analysis. This is the default.

Value

an object of class cca.fd with the 5 slots:

ccwtfd1 a functional data object for the first canonical variate weight function
ccwtfd2 a functional data object for the second canonical variate weight function
cancorr a vector of canonical correlations
ccavar1 a matrix of scores on the first canonical variable.
ccavar2 a matrix of scores on the second canonical variable.

See Also

```
plot.cca.fd, varmx.cca.fd, pca.fd
```

Examples

Canonical correlation analysis of knee-hip curves

```
gaittime <- (1:20)/21
gaitrange <- c(0,1)
gaitbasis <- create.fourier.basis(gaitrange,21)</pre>
lambda
          <- 10^(-11.5)
harmaccelLfd \leftarrow vec2Lfd(c(0, 0, (2*pi)^2, 0))
gaitfdPar <- fdPar(gaitbasis, harmaccelLfd, lambda)</pre>
gaitfd <- smooth.basis(gaittime, gait, gaitfdPar)$fd
ccafdPar <- fdPar(gaitfd, harmaccelLfd, 1e-8)</pre>
          <- cca.fd(gaitfd[,1], gaitfd[,2], ncan=3, ccafdPar, ccafdPar)
# compute a VARIMAX rotation of the canonical variables
ccafd <- varmx.cca.fd(ccafd0)</pre>
# plot the canonical weight functions
op \leftarrow par(mfrow=c(2,1))
#plot.cca.fd(ccafd, cex=1.2, ask=TRUE)
#plot.cca.fd(ccafd, cex=1.2)
# display the canonical correlations
#round(ccafd$ccacorr[1:6],3)
par(op)
```

Center Functional Data

center.fd

Description

Subtract the pointwise mean from each of the functions in a functional data object; that is, to center them on the mean function.

Usage

```
center.fd(fdobj)
```

Arguments

fdobj

a functional data object to be centered.

Value

a functional data object whose mean is zero.

See Also

```
mean.fd, sum.fd, stddev.fd, std.fd
```

Examples

checkDims3

Compare dimensions and dimnames of arrays

Description

Compare selected dimensions and dimnames of arrays, coercing objects to 3-dimensional arrays and either give an error or force matching.

Usage

Arguments

x, y arrays to be compared. If y is missing, x is used.

Currently, both x and y can have at most 3 dimensions. If either has more, an error will be thrown. If either has fewer, it will be expanded to 3 dimensions using as.array3.

xdim, ydim For checkDim3, these are positive integers indicating which dimension of x will be compared with which dimension of y.

For checkDims3, these are positive integer vectors of the same length, passed one at a time to checkDim3. The default here is to force matching dimensions for plotfit.fd.

defaultNames Either NULL, FALSE or a character string or vector or list. If NULL, no checking is done of dimnames. If FALSE, an error is thrown unless the corresponding dimensions of x and y match exactly.

If it is a character string, vector, or list, it is used as the default names if neither x nor y have dimenames for the compared dimensions. If it is a character vector that is too short, it is extended to the required length using paste(defaultNames, 1:ni), where ni = the required length.

If it is a list, it should have length (length(xdim)+1). Each component must be either a character vector or NULL. If neither x nor y have dimenames for the first compared dimensions, defaultNames[[1]] will be used instead unless it is NULL, in which case the last component of defaultNames will be used. If it is null, an error is thrown.

If 'xiny', and any(dim(y)[ydim] < dim(x)[xdim]), an error is thrown. Else if any(dim(y)[ydim] > dim(x)[xdim]) the larger is reduced to match the

smaller. If 'yinx', this procedure is reversed.

If 'neither', any dimension mismatch generates an error.

xName, yName names of the arguments x and y, used only to in error messages.

Details

subset

For checkDims3, confirm that xdim and ydim have the same length, and call checkDim3 for each pair.

For checkDim3, proceed as follows:

1. if((xdim>3) | (ydim>3)) throw an error.

```
2. ixperm <- list(1:3, c(2, 1, 3), c(3, 2, 1))[xdim]; iyperm <- list(1:3, c(2, 1, 3), c(3, 2, 1))[ydim];
```

- 3. x3 <- aperm(as.array3(x), ixperm); y3 <- aperm(as.array3(y), iyperm)
- 4. xNames <- dimnames(x3); yNames <- dimnames(y3)
- 5. Check subset. For example, for subset='xiny', use the following: if(is.null(xNames)) if(dim(x3)[1]>dim(y3)[1]) stop else y. <-y3[1:dim(x3)[1],,] dimnames(x) <- list(yNames[[1]], NULL, NULL) else if(is.null(xNames[[1]])) if(dim(x3)[1]>dim(y3)[1]) stop else y. <-y3[1:dim(x3)[1],,] dimnames(x3)[[1]] <- yNames[[1]] else if(any(!is.element(xNames[[1]], yNames[[1]]))) stop else y. <-y3[xNames[[1]],,]
- 6. return(list(x=aperm(x3, ixperm), y=aperm(y, iyperm)))

Value

a list with components x and y.

Author(s)

Spencer Graves

See Also

```
as.array3 plotfit.fd
```

```
# Select the first two rows of y
stopifnot(all.equal(
checkDim3(1:2, 3:5),
list(x=array(1:2, c(2,1,1), list(c('x1','x2'), NULL, NULL)),
     y=array(3:4, c(2,1,1), list(c('x1','x2'), NULL, NULL)) )
))
# Select the first two rows of a matrix y
stopifnot(all.equal(
checkDim3(1:2, matrix(3:8, 3)),
                         c(2,1,1), list(c('x1','x2'), NULL, NULL)),
list(x=array(1:2,
     y=array(c(3:4, 6:7), c(2,2,1), list(c('x1','x2'), NULL, NULL)) )
))
# Select the first column of y
stopifnot(all.equal(
checkDim3(1:2, matrix(3:8, 3), 2, 2),
                         c(2,1,1), list(NULL, 'x', NULL)),
list(x=array(1:2,
     y=array(3:5, c(3,1,1), list(NULL, 'x', NULL)) )
# Select the first two rows and the first column of y
stopifnot(all.equal(
checkDims3(1:2, matrix(3:8, 3), 1:2, 1:2),
list(x=array(1:2, c(2,1,1), list(c('x1', 'x2'), 'x', NULL)),
     y=array(3:4, c(2,1,1), list(c('x1','x2'), 'x', NULL)) )
```

```
))
# Select the first 2 rows of y
x1 <- matrix(1:4, 2, dimnames=list(NULL, LETTERS[2:3]))</pre>
x1a <- x1. <- as.array3(x1)
dimnames(x1a)[[1]] \leftarrow c('x1', 'x2')
y1 <- matrix(11:19, 3, dimnames=list(NULL, LETTERS[1:3]))</pre>
y1a <- y1. <- as.array3(y1)
dimnames(y1a)[[1]] <- c('x1', 'x2', 'x3')
stopifnot(all.equal(
checkDim3(x1, y1),
list(x=x1a, y=y1a[1:2, , , drop=FALSE])
))
# Select columns 2 & 3 of y
stopifnot(all.equal(
checkDim3(x1, y1, 2, 2),
list(x=x1., y=y1.[, 2:3, , drop=FALSE ])
))
# Select the first 2 rows and columns 2 & 3 of y
stopifnot(all.equal(
checkDims3(x1, y1, 1:2, 1:2),
list(x=x1a, y=y1a[1:2, 2:3, , drop=FALSE ])
))
# y = columns 2 and 3 of x
x23 <- matrix(1:6, 2, dimnames=list(letters[2:3], letters[1:3]))
x23. <- as.array3(x23)
stopifnot(all.equal(
checkDim3(x23, xdim=1, ydim=2),
list(x=x23., y=x23.[, 2:3,, drop=FALSE])
))
\# Transfer dimnames from y to x
x4a <- x4 <- matrix(1:4, 2)
y4 <- matrix(5:8, 2, dimnames=list(letters[1:2], letters[3:4]))
dimnames(x4a) <- dimnames(t(y4))</pre>
stopifnot(all.equal(
checkDims3(x4, y4, 1:2, 2:1),
list(x=as.array3(x4a), y=as.array3(y4))
))
# as used in plotfit.fd
daybasis65 <- create.fourier.basis(c(0, 365), 65)</pre>
daytempfd <- with(CanadianWeather, data2fd(</pre>
       dailyAv[,, "Temperature.C"], day.5,
       daybasis65, argnames=list("Day", "Station", "Deg C")) )
defaultNms <- with(daytempfd, c(fdnames[2], fdnames[3], x='x'))</pre>
subset <- checkDims3(CanadianWeather$dailyAv[, , "Temperature.C"],</pre>
```

checkLogicalInteger Does an argument satisfy required conditions?

Description

Check whether an argument is a logical vector of a certain length or a numeric vector in a certain range and issue an appropriate error or warning if not:

checkLogical throws an error or returns FALSE with a warning unless x is a logical vector of exactly the required length.

checkNumeric throws an error or returns FALSE with a warning unless x is either NULL or a numeric vector of at most length with x in the desired range.

checkLogicalInteger returns a logical vector of exactly length unless x is neither NULL nor logical of the required length nor numeric with x in the desired range.

Usage

Arguments

x an object to be checked

length. The required length for x if logical and not NULL or the maximum

length if numeric.

lower, upper lower and upper limits for x.

integer logical: If true, a numeric x must be integer.
unique logical: TRUE if duplicates are NOT allowed in x.

inclusion logical vector of length 2, similar to link[ifultools] {checkRange}:

if(inclusion[1]) (lower $\leq x$) else (lower $\leq x$) if(inclusion[2]) ($x \leq upper$) else ($x \leq upper$)

warnOnly logical: If TRUE, violations are reported as warnings, not as errors.

Details

- 1. xName <- departse(substitute(x)) to use in any required error or warning.
- 2. if(is.null(x)) handle appropriately: Return FALSE for checkLogical, TRUE for checkNumeric and rep(TRUE, length.) for checkLogicalInteger.
- 3. Check class(x).
- 4. Check other conditions.

Value

checkLogical returns a logical vector of the required length., unless it issues an error message.

checkNumeric returns a numeric vector of at most length. with all elements between lower and upper, and optionally unique, unless it issues an error message.

checkLogicalInteger returns a logical vector of the required length., unless it issues an error message.

Author(s)

Spencer Graves

See Also

checkVectorType, checkRange checkScalarType isVectorAtomic

```
## checkLogical
##
checkLogical(NULL, length=3, warnOnly=TRUE)
checkLogical(c(FALSE, TRUE, TRUE), length=4, warnOnly=TRUE)
checkLogical(c(FALSE, TRUE, TRUE), length=3)
## checkNumeric
##
checkNumeric(NULL, lower=1, upper=3)
checkNumeric(1:3, 1, 3)
checkNumeric(1:3, 1, 3, inclusion=FALSE, warnOnly=TRUE)
checkNumeric(pi, 1, 4, integer=TRUE, warnOnly=TRUE)
checkNumeric(c(1, 1), 1, 4, warnOnly=TRUE)
checkNumeric(c(1, 1), 1, 4, unique=FALSE, warnOnly=TRUE)
##
## checkLogicalInteger
##
checkLogicalInteger(NULL, 3)
checkLogicalInteger(c(FALSE, TRUE), warnOnly=TRUE)
checkLogicalInteger(1:2, 3)
checkLogicalInteger(2, warnOnly=TRUE)
```

```
checkLogicalInteger(c(2, 4), 3, warnOnly=TRUE)

##
## checkLogicalInteger names its calling function
## rather than itself as the location of error detection
## if possible
##

tstFun <- function(x, length., warnOnly=FALSE){
   checkLogicalInteger(x, length., warnOnly)
}

tstFun(NULL, 3)

tstFun(4, 3, warnOnly=TRUE)

tstFun2 <- function(x, length., warnOnly=FALSE){
   tstFun(x, length., warnOnly)
}

tstFun2(4, 3, warnOnly=TRUE)</pre>
```

coef.fd

Extract functional coefficients

Description

Obtain the coefficients component from a functional object (functional data, class fd, functional parameter, class fdPar, a functional smooth, class fdSmooth, or a Taylor spline representation, class Taylor.

Usage

```
## S3 method for class 'fd':
coef(object, ...)
## S3 method for class 'fdPar':
coef(object, ...)
## S3 method for class 'fdSmooth':
coef(object, ...)
## S3 method for class 'Taylor':
coef(object, ...)
## S3 method for class 'fd':
coefficients(object, ...)
## S3 method for class 'fdPar':
coefficients(object, ...)
## S3 method for class 'fdSmooth':
coefficients(object, ...)
## S3 method for class 'Taylor':
coefficients(object, ...)
```

Arguments

```
object An object whose functional coefficients are desired ... other arguments
```

Details

Functional representations are evaluated by multiplying a basis function matrix times a coefficient vector, matrix or 3-dimensional array. (The basis function matrix contains the basis functions as columns evaluated at the evalarg values as rows.)

Value

A numeric vector or array of the coefficients.

See Also

```
coef fd fdPar smooth.basisPar smooth.basis
```

```
##
## coef.fd
##
bspl1.1 <- create.bspline.basis(norder=1, breaks=0:1)</pre>
fd.bspl1.1 <- fd(0, basisobj=bspl1.1)</pre>
coef(fd.bspl1.1)
##
## coef.fdPar
rangeval <-c(-3,3)
# set up some standard normal data
x <- rnorm(50)
# make sure values within the range
x[x < -3] < -2.99
x[x > 3] \leftarrow 2.99
\# set up basis for W(x)
basisobj <- create.bspline.basis(rangeval, 11)</pre>
# set up initial value for Wfdobj
Wfd0 <- fd(matrix(0,11,1), basisobj)</pre>
WfdParobj <- fdPar(Wfd0)</pre>
coef(WfdParobj)
## coef.fdSmooth
girlGrowthSm <- with(growth, smooth.basisPar(argvals=age, y=hgtf))</pre>
```

```
coef(girlGrowthSm)

##

## coef.Taylor
##

# coming soon.
```

cor.fd

 $Correlation\ matrix\ from\ functional\ data\ object(s)$

Description

Compute a correlation matrix for one or two functional data objects.

Usage

```
cor.fd(evalarg1, fdobj1, evalarg2=evalarg1, fdobj2=fdobj1)
```

Arguments

```
evalarg1 a vector of argument values for fdobj1.

evalarg2 a vector of argument values for fdobj2.

fdobj1, fdobj2

functional data objects
```

Details

- 1. var1 <- var.fd(fdobj1)
- 2. evalVar1 <- eval.bifd(evalarg1, evalarg1, var1)
- 3. if(missing(fdobj2)) Convert evalVar1 to correlations
- 4. else:
- 4.1. var2 <- var.fd(fdobj2)
- 4.2. evalVar2 <- eval.bifd(evalarg2, evalarg2, var2)
- $4.3. \text{ var}12 \leftarrow \text{var.df}(\text{fdobj}1, \text{fdobj}2)$
- 4.4. evalVar12 <- eval.bifd(evalarg1, evalarg2, var12)
- 4.5. Convert evalVar12 to correlations

Value

A matrix or array:

With one or two functional data objects, fdobj1 and possibly fdobj2, the value is a matrix of dimensions length(evalarg1) by length(evalarg2) giving the correlations at those points of fdobj1 if missing(fdojb2) or of correlations between eval.fd(evalarg1, fdobj1) and eval.fd(evalarg2, fdobj2).

With a single multivariate data object with k variables, the value is a 4-dimensional array of $\dim = c(nPts, nPts, 1, choose(k+1, 2))$, where nPts = length(evalarg1).

See Also

```
mean.fd, sd.fd, std.fd stdev.fd var.fd
```

```
daybasis3 <- create.fourier.basis(c(0, 365))</pre>
daybasis5 <- create.fourier.basis(c(0, 365), 5)</pre>
tempfd3 <- with(CanadianWeather, data2fd(</pre>
       dailyAv[,,"Temperature.C"], day.5,
       daybasis3, argnames=list("Day", "Station", "Deg C")) )
precfd5 <- with(CanadianWeather, data2fd(</pre>
       dailyAv[,,"log10precip"], day.5,
       daybasis5, argnames=list("Day", "Station", "Deg C")) )
# Correlation matrix for a single functional data object
(tempCor3 <- cor.fd(seq(0, 356, length=4), tempfd3))</pre>
# Cross correlation matrix between two functional data objects
# Compare with structure described above under 'value':
(tempPrecCor3.5 <- cor.fd(seq(0, 365, length=4), tempfd3,</pre>
                           seq(0, 356, length=6), precfd5))
# The following produces contour and perspective plots
daybasis65 <- create.fourier.basis(rangeval=c(0, 365), nbasis=65)</pre>
daytempfd <- with(CanadianWeather, data2fd(
       dailyAv[,, "Temperature.C"], day.5,
       daybasis65, argnames=list("Day", "Station", "Deg C")) )
dayprecfd <- with(CanadianWeather, data2fd(</pre>
       dailyAv[,,"log10precip"], day.5,
       daybasis65, argnames=list("Day", "Station", "log10(mm)")) )
str(tempPrecCor <- cor.fd(weeks, daytempfd, weeks, dayprecfd))</pre>
# dim(tempPrecCor) = c(53, 53)
op <- par(mfrow=c(1,2), pty="s")
contour(weeks, weeks, tempPrecCor,
        xlab="Average Daily Temperature",
        ylab="Average Daily log10(precipitation)",
        main=paste("Correlation function across locations\n",
          "for Canadian Anual Temperature Cycle"),
```

```
cex.main=0.8, axes=FALSE)
axisIntervals(1, atTick1=seq(0, 365, length=5), atTick2=NA,
            atLabels=seq(1/8, 1, 1/4)*365,
            labels=paste("Q", 1:4) )
axisIntervals(2, atTick1=seq(0, 365, length=5), atTick2=NA,
            atLabels=seq(1/8, 1, 1/4)*365,
            labels=paste("Q", 1:4) )
persp(weeks, weeks, tempPrecCor,
      xlab="Days", ylab="Days", zlab="Correlation")
mtext("Temperature-Precipitation Correlations", line=-4, outer=TRUE)
par(op)
# Correlations and cross correlations
# in a bivariate functional data object
gaitbasis5 <- create.fourier.basis(nbasis=5)</pre>
gaitfd5 <- data2fd(gait, basisobj=gaitbasis5)</pre>
gait.t3 <- (0:2)/2
(gaitCor3.5 <- cor.fd(gait.t3, gaitfd5))</pre>
# Check the answers with manual computations
gait3.5 <- eval.fd(gait.t3, gaitfd5)</pre>
all.equal(cor(t(gait3.5[,,1])), gaitCor3.5[,,,1])
# TRUE
all.equal(cor(t(gait3.5[,,2])), gaitCor3.5[,,,3])
all.equal(cor(t(gait3.5[,,2]), t(gait3.5[,,1])),
               gaitCor3.5[,,,2])
# TRUE
# NOTE:
dimnames(gaitCor3.5)[[4]]
# [1] Hip-Hip
# [2] Knee-Hip
# [3] Knee-Knee
# If [2] were "Hip-Knee", then
# gaitCor3.5[,,,2] would match
# cor(t(gait3.5[,,1]), t(gait3.5[,,2]))
# *** It does NOT. Instead, it matches:
# cor(t(gait3.5[,,2]), t(gait3.5[,,1]))
```

create.bspline.basis Create a B-spline Basis

Description

Functional data objects are constructed by specifying a set of basis functions and a set of coefficients defining a linear combination of these basis functions. The B-spline basis is a system that is usually used for non-periodic functions. It has the advantages of very fast computation and great flexibility. On the other hand, if the data are considered to be periodic, then the Fourier basis is usually preferred.

Usage

Arguments

rangeval

a numeric vector of length 2 defining the interval over which the functional data object can be evaluated; default value is if(is.null(breaks)) 0:1 else range(breaks).

If length(rangeval) == 1 and rangeval $\leq = 0$, this is an error. Otherwise, if length(rangeval) == 1, rangeval is replaced by c(0, rangeval).

If length(rangeval)>2 and neither breaks nor nbasis are provided, this extra long rangeval argument is assigned to breaks, and then rangeval = range(breaks).

nbasis

an integer variable specifying the number of basis functions. Default value NULL.

This 'nbasis' argument is ignored if 'breaks' is supplied, in which case nbasis = nbreaks + norder - 2, where nbreaks = length(breaks).

norder

an integer specifying the order of b-splines, which is one higher than their degree. The default of 4 gives cubic splines.

breaks

a vector specifying the break points defining the b-spline. Also called knots, these are a strictly increasing sequence of junction points between piecewise polynomial segments. They must satisfy breaks[1] = rangeval[1] and breaks[nbreaks] = rangeval[2], where nbreaks is the length of breaks. There must be at least 2 values in breaks. There is a potential for inconsistency among arguments nbasis, norder, and breaks. It is resolved as follows:

If breaks is supplied, nbreaks = length(breaks), and nbasis = nbreaks + norder - 2, no matter what value for nbasis is supplied.

If breaks is not supplied, but nbasis is, nbreaks = nbasis - norder + 2, and if this turns out to be less than 2, an error message results.

If neither breaks nor nbasis is supplied, nbreaks is set to 21.

If breaks is not provided, it is set to seq(rangeval[1], rangeval[2], length=nbreaks).

dropind

a vector of integers specifiying the basis functions to be dropped, if any. For example, if it is required that a function be zero at the left boundary, this is achieved by dropping the first basis function, the only one that is nonzero at that point. Default value NULL.

quadvals

a matrix with two columns and a number of rows equal to the number of argument values used to approximate an integral using Simpson's rule. The first column contains these argument values. A minimum of 5 values are required for each inter-knot interval, and that is often enough. These are equally spaced between two adjacent knots. The second column contains the weights used for Simpson's rule. These are proportional to $1,\,4,\,2,\,4,\,\ldots,\,2,\,4,\,1.$

values a list containing the basis functions and their derivatives evaluated at the

quadrature points contained in the first column of quadvals .

names either a character vector of the same length as the number of basis func-

tions or a single character string to which norder, "." and 1:nbasis are appended as paste(names, norder, ".", 1:nbreaks, sep=""). For example,

if norder = 4, this defaults to 'bspl4.1', 'bspl4.2',

Details

Spline functions are constructed by joining polynomials end-to-end at argument values called *break points* or *knots*. First, the interval is subdivided into a set of adjoining intervals separated the knots. Then a polynomial of order m and degree m-1 is defined for each interval. In order to make the resulting piece-wise polynomial smooth, two adjoining polynomials are constrained to have their values and all their derivatives up to order m-2 match at the point where they join.

Consider as an illustration the very common case where the order is 4 for all polynomials, so that degree of each polynomials is 3. That is, the polynomials are *cubic*. Then at each break point or knot, the values of adjacent polynomials must match, and so also for their first and second derivatives. Only their third derivatives will differ at the point of junction.

The number of degrees of freedom of a cubic spline function of this nature is calculated as follows. First, for the first interval, there are four degrees of freedom. Then, for each additional interval, the polynomial over that interval now has only one degree of freedom because of the requirement for matching values and derivatives. This works out to the following equation: The number of degrees of freedom is equal to the number of interior knots (that is, not counting the lower and upper limits) plus the order of the polynomials.

B-splines are a set of special spline functions that can be used to construct any such piece-wise polynomial by computing the appropriate linear combination. They derive their computational convience from the fact that any B-spline basis function is nonzero over at most m adjacent intervals. The number of basis functions is given by the rule above for the number of degrees of freedom.

The number of intervals controls the flexibility of the spline; the more knots, the more flexible the resulting spline will be. But the position of the knots also plays a role. Where do we position the knots? There is room for judgment here, but two considerations must be kept in mind: (1) you usually want at least one argument value between two adjacent knots, and (2) there should be more knots where the curve needs to have sharp curvatures such as a sharp peak or valley or an abrupt change of level, but only a few knots are required where the curve is changing very slowly.

This function automatically includes norder replicates of the end points rangeval. By contrast, the analogous splines' package functions splineDesign and spline.des do NOT automatically replicate the end points. To compare answers, the end knots must be replicated manually when using splineDesign or spline.des.

Value

a basis object of the type bspline

References

Ramsay, James O., and Silverman, Bernard W. (2005), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York.

See Also

basisfd, create.constant.basis, create.exponential.basis, create.fourier.basis, create.monomial.basis, create.polygonal.basis, create.polynomial.basis, create.power.basis splineDesign spline.des

```
##
## The simplest basis currently available with this function:
bspl1.1 <- create.bspline.basis(norder=1, breaks=2:3)</pre>
plot(bspl1.1)
# 1 basis function, order 1 = degree 0 = step function:
# constant 1 between 2 and 3.
bspl1.2 <- create.bspline.basis(norder=1, breaks=c(0,.5, 1))
plot(bspl1.2)
# 2 bases, order 1 = degree 0 = step functions:
# (1) constant 1 between 0 and 0.5 and 0 otherwise
# (2) constant 1 between 0.5 and 1 and 0 otherwise.
bspl2.3 <- create.bspline.basis(norder=2, breaks=c(0,.5, 1))
plot(bspl2.3)
# 3 bases: order 2 = degree 1 = linear
# (1) line from (0,1) down to (0.5, 0), 0 after
\# (2) line from (0,0) up to (0.5, 1), then down to (1,0)
# (3) 0 to (0.5, 0) then up to (1,1).
bspl3.4 <- create.bspline.basis(norder=3, breaks=c(0,.5, 1))
plot(bspl3.4)
# 4 bases: order 3 = degree 2 = parabolas.
# (1) (x-.5)^2 from 0 to .5, 0 after
# (2) 2*(x-1)^2 from .5 to 1, and a parabola
      from (0,0 to (.5, .5) to match
# (3 \& 4) = complements to (2 \& 1).
# Default B-spline basis
bSpl4.23 <- create.bspline.basis()
# Cubic bspline (norder=4) with nbasis=23,
# so nbreaks = nbasis-norder+2 = 21,
# 2 of which are rangeval, leaving 19 Interior knots.
bSpl4. <- create.bspline.basis(c(-1,1))
# Same as bSp14.23 but over (-1,1) rather than (0,1).
```

```
# set up the b-spline basis for the lip data, using 23 basis functions,
# order 4 (cubic), and equally spaced knots.
# There will be 23 - 4 = 19 interior knots at 0.05, ..., 0.95
lipbasis <- create.bspline.basis(c(0,1), 23)
all.equal(bSpl4.23, lipbasis)
# TRUE
# plot the basis functions
plot(lipbasis)

bSpl.growth <- create.bspline.basis(growth$age)
# cubic spline (order 4)

bSpl.growth6 <- create.bspline.basis(growth$age,norder=6)
# quintic spline (order 6)</pre>
```

create.constant.basis

Create a Constant Basis

Description

Create a constant basis object, defining a single basis function whose value is everywhere 1.0.

Usage

```
create.constant.basis(rangeval=c(0, 1))
```

Arguments

rangeval

a vector of length 2 containing the initial and final values of argument t defining the interval over which the functional data object can be evaluated. However, this is seldom used since the value of the basis function does not depend on the range or any argument values.

Value

a basis object with type component const.

See Also

basisfd, create.bspline.basis, create.exponential.basis, create.fourier.basis, create.monomial.basis, create.polygonal.basis, create.polynomial.basis, create.power.basis

```
basisobj <- create.constant.basis(c(-1,1))</pre>
```

create.exponential.basis

Create an Exponential Basis

Description

Create an exponential basis object defining a set of exponential functions with rate constants in argument ratevec.

Usage

Arguments

rangeval	a vector of length 2 containing the initial and final values of the interval
----------	--

over which the functional data object can be evaluated.

nbasis the number of basis functions.

ratevec a vector of length nbasis of rate constants defining basis functions of the

form exp(rate*x).

dropind a vector of integers specifying the basis functions to be dropped, if any.

For example, if it is required that a function be zero at the left boundary, this is achieved by dropping the first basis function, the only one that is

nonzero at that point. Default value NULL.

quadvals a matrix with two columns and a number of rows equal to the number

of argument values used to approximate an integral using Simpson's rule. The first column contains these argument values. A minimum of 5 values are required for each inter-knot interval, and that is often enough. These are equally spaced between two adjacent knots. The second column contains the weights used for Simpson's rule. These are proportional to 1, 4,

2, 4, ..., 2, 4, 1.

values a list containing the basis functions and their derivatives evaluated at the

quadrature points contained in the first column of quadvals .

Details

Exponential functions are of the type exp(bx) where b is the rate constant. If b=0, the constant function is defined.

Value

a basis object with the type expon.

See Also

basisfd, create.bspline.basis, create.constant.basis, create.fourier.basis, create.monomial.basis, create.polygonal.basis, create.polygonal.basis, create.power.basis

Examples

```
# Create an exponential basis over interval [0,5]
# with basis functions 1, exp(-t) and exp(-5t)
basisobj <- create.exponential.basis(c(0,5),3,c(0,-1,-5))
# plot the basis
plot(basisobj)</pre>
```

create.fourier.basis Create a Fourier Basis

Description

Create an Fourier basis object defining a set of Fourier functions with specified period.

Usage

Arguments

rangeval	a vector of length 2 containing the initial and final values of the interval over which the functional data object can be evaluated. Default value $c(0,1)$
nbasis	the number of basis functions, rounded up to the nearest odd integer. The number of basis functions is always odd, even when an even number is specified, so as to preserve the pairing of sine and cosine functions. Default value 3.
period	the width of any interval over which the Fourier functions repeat them- selves, or are periodic. The default is the width of the interval defined in rangeval.
dropind	a vector of integers specifiying the basis functions to be dropped, if any. For example, if it is required that a function be zero at the left boundary, this is achieved by dropping the first basis function, the only one that is nonzero at that point. Default value NULL.
quadvals	a matrix with two columns and a number of rows equal to the number of argument values used to approximate an integral using Simpson's rule. The first column contains these argument values. A minimum of 5 values are required for each inter-knot interval, and that is often enough. These

are equally spaced between two adjacent knots. The second column contains the weights used for Simpson's rule. These are proportional to 1, 4,

2, 4, ..., 2, 4, 1.

values a list containing the basis functions and their derivatives evaluated at the

quadrature points contained in the first column of quadvals.

longNames if FALSE, the function value will include a component 'names', the first

of which will be 'const', followed by 'sin1', 'cos1', 'sin2',

if TRUE, the function value will include 'names' as when longNames = FALSE, but with the 'period' rounded to 4 significant digits and pasted onto 'sin1', etc. For example, with period=12, the second name would be

'sin1.12'.

if NA, no 'names' will be provided.

Details

Functional data objects are constructed by specifying a set of basis functions and a set of coefficients defining a linear combination of these basis functions. The Fourier basis is a system that is usually used for periodic functions. It has the advantages of very fast computation and great flexibility. If the data are considered to be nonperiod, the Fourier basis is usually preferred. The first Fourier basis function is the constant function. The remainder are sine and cosine pairs with integer multiples of the base period. The number of basis functions generated is always odd.

Value

a basis object with the type fourier.

See Also

```
basisfd, create.bspline.basis, create.constant.basis, create.exponential.basis,
create.monomial.basis, create.polygonal.basis, create.polynomial.basis, create.power.basis
```

```
# Create a minimal Fourier basis for the monthly temperature data,
# using 3 basis functions with period 12 months.
monthbasis3 <- create.fourier.basis(c(0,12))
# plot the basis
plot(monthbasis3)

# set up the Fourier basis for the monthly temperature data,
# using 9 basis functions with period 12 months.
monthbasis <- create.fourier.basis(c(0,12), 9, 12.0)

# plot the basis
plot(monthbasis)

# Create a false Fourier basis using 1 basis function.
falseFourierBasis <- create.fourier.basis(nbasis=1)
# plot the basis: constant</pre>
```

create.monomial.basis

Create a Monomial Basis

Description

Creates a set of basis functions consisting of powers of the argument.

Usage

Arguments

rangeval	a vector of length ?	2 containing the initi	ial and final values	s of the interval
----------	----------------------	------------------------	----------------------	-------------------

over which the functional data object can be evaluated.

nbasis the number of basis functions. The default is 2, which defines a basis for

straight lines.

exponents the nonnegative integer powers to be used. By default, these are 0, 1, 2,

..., nbasis .

dropind a vector of integers specifying the basis functions to be dropped, if any.

For example, if it is required that a function be zero at the left boundary, this is achieved by dropping the first basis function, the only one that is

nonzero at that point. Default value NULL.

quadvals a matrix with two columns and a number of rows equal to the number

of argument values used to approximate an integral using Simpson's rule. The first column contains these argument values. A minimum of 5 values are required for each inter-knot interval, and that is often enough. These are equally spaced between two adjacent knots. The second column contains the weights used for Simpson's rule. These are proportional to 1, 4,

2, 4, ..., 2, 4, 1.

values a list containing the basis functions and their derivatives evaluated at the

quadrature points contained in the first column of quadvals .

Value

a basis object with the type monom.

See Also

basisfd, create.bspline.basis, create.constant.basis, create.fourier.basis, create.exponential.basis create.polygonal.basis, create.polynomial.basis, create.power.basis

Examples

```
##
## simplest example: one constant 'basis function'
##
m0 <- create.monomial.basis(nbasis=1, exponents=0)
plot(m0)

##
## Create a monomial basis over the interval [-1,1]
## consisting of the first three powers of t
##
basisobj <- create.monomial.basis(c(-1,1), 3)
# plot the basis
plot(basisobj)</pre>
```

create.polygonal.basis

Create a Polygonal Basis

Description

A basis is set up for constructing polygonal lines, consisting of straight line segments that join together.

Usage

Arguments

argvals a strictly increasing vector of argument values at which line segments join

to form a polygonal line.

dropind a vector of integers specifying the basis functions to be dropped, if any.

For example, if it is required that a function be zero at the left boundary, this is achieved by dropping the first basis function, the only one that is

nonzero at that point. Default value NULL.

quadvals a matrix with two columns and a number of rows equal to the number

of argument values used to approximate an integral using Simpson's rule. The first column contains these argument values. A minimum of 5 values are required for each inter-knot interval, and that is often enough. These are equally spaced between two adjacent knots. The second column contains the weights used for Simpson's rule. These are proportional to $1,\,4,$

2, 4, ..., 2, 4, 1.

values a list containing the basis functions and their derivatives evaluated at the

quadrature points contained in the first column of quadvals.

Details

The actual basis functions consist of triangles, each with its apex over an argument value. Note that in effect the polygonal basis is identical to a B-spline basis of order 2 and a knot or break value at each argument value. The range of the polygonal basis is set to the interval defined by the smallest and largest argument values.

Value

a basis object with the type polyg.

See Also

```
basisfd, create.bspline.basis, create.constant.basis, create.exponential.basis, create.fourier.basis, create.monomial.basis, create.polynomial.basis, create.power.basis
```

Examples

```
# Create a polygonal basis over the interval [0,1]
# with break points at 0, 0.1, ..., 0.95, 1
(basisobj <- create.polygonal.basis(seq(0,1,0.1)))
# plot the basis
plot(basisobj)</pre>
```

```
create.polynomial.basis
```

Create a Polynomial Basis

Description

Creates a set of basis functions consisting of powers of the argument shifted by a constant.

Usage

Arguments

rangeval a vector of length 2 defining the range.

nbasis the number of basis functions. The default is 2, which defines a basis for

straight lines.

ctr this value is used to shift the argument prior to taking its power.

dropind a vector of integers specifying the basis functions to be dropped, if any.

For example, if it is required that a function be zero at the left boundary, this is achieved by dropping the first basis function, the only one that is

nonzero at that point. Default value NULL.

quadvals a matrix with two columns and a number of rows equal to the number

of argument values used to approximate an integral using Simpson's rule. The first column contains these argument values. A minimum of 5 values are required for each inter-knot interval, and that is often enough. These are equally spaced between two adjacent knots. The second column contains the weights used for Simpson's rule. These are proportional to 1, 4,

2, 4, ..., 2, 4, 1.

values a list containing the basis functions and their derivatives evaluated at the

quadrature points contained in the first column of quadvals .

Details

The only difference between a monomial and a polynomial basis is the use of a shift value. This helps to avoid rounding error when the argument values are a long way from zero.

Value

a basis object with the type polynom.

See Also

basisfd, create.bspline.basis, create.constant.basis, create.fourier.basis, create.exponential.basicreate.monomial.basis, create.polygonal.basis, create.power.basis

Examples

```
# Create a polynomial basis over the years in the 20th century
# and center the basis functions on 1950.
basisobj <- create.polynomial.basis(c(1900, 2000), nbasis=3, ctr=1950)
# plot the basis
# The following should work but doesn't; 2007.05.01
#plot(basisobj)</pre>
```

create.power.basis Create a Power Basis Object

Description

The basis system is a set of powers of argument x. That is, a basis function would be $x^exponent$, where exponent is a vector containing a set of powers or exponents. The power basis would normally only be used for positive values of x, since the power of a negative number is only defined for nonnegative integers, and the exponents here can be any real numbers.

Usage

Arguments

rangeval a vector of length 2 with the first element being the lower limit of the

range of argument values, and the second the upper limit. Of course the

lower limit must be less than the upper limit.

nbasis the number of exponential functions.

exponents a vector of length nbasis containing the powers.

dropind a vector of integers specifying the basis functions to be dropped, if any.

For example, if it is required that a function be zero at the left boundary, this is achieved by dropping the first basis function, the only one that is

nonzero at that point. Default value NULL.

quadvals a matrix with two columns and a number of rows equal to the number

of argument values used to approximate an integral using Simpson's rule. The first column contains these argument values. A minimum of 5 values are required for each inter-knot interval, and that is often enough. These are equally spaced between two adjacent knots. The second column contains the weights used for Simpson's rule. These are proportional to 1, 4,

2, 4, ..., 2, 4, 1.

values a list containing the basis functions and their derivatives evaluated at the

quadrature points contained in the first column of quadvals .

Details

The power basis differs from the monomial and polynomial bases in two ways. First, the powers may be nonintegers. Secondly, they may be negative. Consequently, a power basis is usually used with arguments that only take positive values, although a zero value can be tolerated if none of the powers are negative.

Value

a basis object of type power.

See Also

```
basisfd, create.bspline.basis, create.constant.basis, create.exponential.basis, create.fourier.basis, create.monomial.basis, create.polygonal.basis, create.polygonal.basis
```

```
# Create a power basis over the interval [1e-7,1]
# with powers or exponents -1, -0.5, 0, 0.5 and 1
basisobj <- create.power.basis(c(1e-7,1), 5, seq(-1,1,0.5))
# plot the basis
plot(basisobj)</pre>
```

Description

Functions for solving the Continuously Stirred Temperature Reactor (CSTR) Ordinary Differential Equations (ODEs). A solution for observations where metrology error is assumed to be negligible can be obtained via lsoda(y, Time, CSTR2, parms); CSTR2 calls CSTR2in. When metrology error can not be ignored, use CSTRfn (which calls CSTRfitLS). To estimate parameters in the CSTR differential equation system (kref, EoverR, a, and / or b), pass either CSTRres or CSTRres0 to nls. If nls fails to converge, first use optim or nlminb with CSTRsse, then pass the estimates to nls.

Usage

Arguments

Time	The time(s) for which computation(s) are desired
condition	a character string with the name of one of ten preprogrammed input scenarios.
tau	time for exponential decay of $\exp(-1)$ under condition = 'Tc.hot.exponential' or 'Tc.cool.exponential'; ignored for other values of 'condition'.
У	Either a vector of length 2 or a matrix with 2 columns giving the observation(s) on Concentration and Temperature for which computation(s) are desired
parms	a list of CSTR model parameters passed via the Isoda 'parms' argument. This list consists of the following 3 components:
fi	tstruct a list with 12 components describing the structure for fitting. This is the same as the 'fitstruct' argument of 'CSTRfitLS' and 'CSTRfn' without the 'fit' component; see below.

condition a character string identifying the inputs to the simulation. Currently, any of the following are accepted: 'all.cool.step', 'all.hot.step', 'all.hot.ramp', 'all.cool.ramp', 'Tc.hot.exponential', 'Tc.cool.exponential', 'Tc.hot.ramp', 'Tc.cool.ramp', 'Tc.hot.step', or 'Tc.cool.step'.

Tlim end time for the computations.

coef

a matrix with one row for each basis function in fitstruct and columns c("Conc", "Temp") or a vector form of such a matrix.

datstruct

a list describing the structure of the data. CSTRfitLS uses the following components:

basismat, Dbasismat basis coefficent matrices with one row for each observation and one column for each basis vector. These are typically produced by code something like the following:

> basismat <- eval.basis(Time, CSTRbasis) Dbasismat <- eval.basis(Time, CSTRbasis, 1)

Cwt, Twt scalar variances of 'fd' functional data objects for Concentration and Temperature used to place the two series on comparable scales.

y a matrix with 2 columns for the observed 'Conc' and 'Temp'.

quadbasismat, Dquadbasismat basis coefficient matrices with one row for each quadrature point and one column for each basis vector. These are typically produced by code something like the following:

> quadbasismat <- eval.basis(quadpts, CSTRbasis) Dquadbasismat <- eval.basis(quadpts, CSTRbasis, 1)

Fc, F., CAO, TO, Tc input series for CSTRfitLS and CSTRfn as the output list produced by CSTR2in.

> quadpts Quadrature points created by 'quadset' and stored in CSTRbasis[["quadvals"]][, "quadpts"].

quadwts Quadrature weights created by 'quadset' and stored in CSTRbasis[["quadvals"]][, "quadpts"].

fitstruct

a list with 14 components:

V volume in cubic meters

Cp concentration in cal/(g.K) for computing betaTC and betaTT; see details below.

rho density in grams per cubic meter

delH cal/kmol

Cpc concentration in cal/(g.K) used for computing alpha; see details be-

Tref reference temperature.

kref reference value

EoverR E/R in units of K/1e4

a scale factor for Fco in alpha; see details below.

b power of Fco in alpha; see details below.

Tcin Tc input temperature vector.

fit logical vector of length 2 indicating whether Contentration or Temperature or both are considered to be observed and used for parameter estimation.

coef0 data.frame(Conc = Cfdsmth[["coef"]], Temp = Tfdsmth[["coef"]]), where Cfdsmth and Tfdsmth are the objects returned by smooth.basis when applied to the observations on Conc and Temp, respectively.

estimate logical vector of length 4 indicating which of kref, EoverR, a and b are taken from 'parvec'; all others are taken from 'fitstruct'.

lambda a 2-vector of rate parameters 'lambdaC' and 'lambdaT'.

gradwrd a logical scalar TRUE if the gradient is to be returned as well as the

residuals matrix.

parvec, par initial values for the parameters specified by fitstruct[["estimate"]] to be

estimated.

CSTRbasis Quadrature basis returned by 'quadset'.

kref, EoverR, a, b

the kref, EoverR, a, and b coefficients of the CSTR model as individual arguments of CSTRres to support using 'nls' with the CSTR model. Those actually provided by name will be estimated; the others will be taken from '.fitstruct'; see details.

Details

Ramsay et al. (2007) considers the following differential equation system for a continuously stirred temperature reactor (CSTR):

```
\begin{split} &\mathrm{dC/dt} = (\text{-betaCC}(T,\,F.in)^*C + F.in^*C.in) \\ &\mathrm{dT/dt} = (\text{-betaTT}(Fcvec,\,F.in)^*T + betaTC(T,\,F.in)^*C + alpha(Fcvec)^*T.co) \\ &\mathrm{where} \\ &\mathrm{betaCC}(T,\,F.in) = \mathrm{kref^*exp}(\text{-1e4*EoverR*}(1/T\,\text{-}\,1/\mathrm{Tref})) + F.in \\ &\mathrm{betaTT}(Fcvec,\,F.in) = alpha(Fcvec) + F.in \\ &\mathrm{betaTC}(T,\,F.in) = (\text{-delH/}(\mathrm{rho^*Cp}))^*\mathrm{betaCC}(T,\,F.in) \end{split}
```

$$alpha(Fcvec) = (a * Fcvec^{(b+1)}/(K1 * (Fcvec + K2 * Fcvec^{(b)})))$$

$$K1 = V*rho*Cp$$

 $K2 = 1/(2*rhoc*Cpc)$

The four functions CSTR2in, CSTR2, CSTRfitLS, and CSTRfn compute coefficients of basis vectors for two different solutions to this set of differential equations. Functions CSTR2in and CSTR2 work with 'lsoda' to provide a solution to this system of equations. Functions CSTSRitLS and CSTRfn are used to estimate parameters to fit this differential equation system to noisy data. These solutions are conditioned on specified values for kref, EoverR, a, and b. The other two functions CSTRres and CSTRres0 support estimation of these parameters using 'nls'.

CSTR2in translates a character string 'condition' into a data frame containing system inputs for which the reaction of the system is desired. CSTR2 calls CSTR2in and then computes the corresponding predicted first derivatives of CSTR system outputs according to the right hand side of the system equations. CSTR2 can be called by 'lsoda' in the 'odesolve' package to actually solve the system of equations. To solve the CSTR equations for another set of

inputs, the easiest modification might be to change CSTR2in to return the desired inputs. Another alternative would be to add an argument 'input.data.frame' that would be used in place of CSTR2in when present.

CSTRfitLS computes standardized residuals for systems outputs Conc, Temp or both as specified by fitstruct[["fit"]], a logical vector of length 2. The standardization is sqrt(datstruct[["Cwt"]]) and / or sqrt(datstruct[["Twt"]]) for Conc and Temp, respectively. CSTRfitLS also returns standardized deviations from the predicted first derivatives for Conc and Temp.

CSTRfn uses a Gauss-Newton optimization to estimates the coefficients of CSTRbasis to minimize the weighted sum of squares of residuals returned by CSTRfitLS.

CSTRres and CSTRres0 provide alternative interfaces between 'nls' and 'CSTRfn'. Both get the parameters to be estimated via their official function arguments, kref, EoverR, a, and / or b. The subset of these parameters to estimate must be specified both directly in the function call to 'nls' and indirectly via fitstruct[["estimate"]]. CSTRres gets the other CSTRfn arguments (datstruct, fitstruct, CSTRbasis, and lambda) via the 'data' argument of 'nls'. (The version of 'nls' in the 'stats' package in R 2.5.0 required 'data' to be a data.frame, not merely a list. The version of 'nls' in 'fda' does not require this.) By contrast, CSTRres0 uses 'get' to obtain these other arguments as .datstruct, .fitstruct, .CSTRbasis and .lambda. Thus, before calling nls(CSTRres0(...), ...), the values of these arguments must be assigned to .datstruct, .fitstruct, .CSTRbasis and .lambda. If 'nls' is called from the global environment, it will look for these objects in the global environment.

CSTRres0 has one feature absent from CSTRres: If a variable .CSTRres0.trace is available, it is assumed to be a matrix with columns kref, EoverR, a, b, SSE, plus all residuals. These numbers are rbinded as an additional row of this matrix. This is provided to help diagnose a problem were 'nls' was terminating with "step factor ... reduced below 'minFactor", facilitating the comparison between R and Matlab for the precise sets of parameter values tested by 'nls'.

CSTRsse computes sum of squares of residuals for use with optim or nlminb.

Value

CSTR2in a matrix with number of rows = length(Time) and columns for F., CA0,

T0, Tcin, and Fc. This gives the inputs to the CSTR simulation for the

chosen 'condition'.

CSTR2 a list with one component being a matrix with number of rows = length(tobs)

and 2 columns giving the first derivatives of Conc and Temp according to the right hand side of the differential equation. CSTR2 calls CSTR2in to

get its inputs.

CSTRfitLS a list with one or two components as follows:

res a list with two components

Sres = a matrix giving the residuals between observed and predicted datstruct[["y"]] divided by sqrt(datstruct[[c("Cwt", "Twt")]]) so the result is dimensionless. $\dim(Sres) = \dim(\operatorname{datstruct}["v"]]$). Thus, if datstruct[["y"]] has only one column, 'Sres' has only one column.

Lres = a matrix with two columns giving the difference between left and right hand sides of the CSTR differential equation at all the quadrature points. $\dim(\text{Lres}) = c(\text{nguad}, 2)$.

Dres If gradwrd=TRUE, a list with two components:

DSres = a matrix with one row for each element of res[["Sres"]] and two columns for each basis function.

DLres = a matrix with two rows for each quadrature point and two columns for each basis function.

If gradwrd=FALSE, this component is not present.

CSTRfn

a list with five components:

res the 'res' component of the final 'CSTRfitLS' object reformatted with its component Sres first followed by Lres, using with(CSTRfitLS(...)[["res"]], c(Sres, Lres)).

Dres one of two very different gradient matrices depending on the value of 'gradwrd'.

If gradwrd = TRUE, Dres is a matrix with one row for each observation value to match and one column for each parameter taken from 'parvec' per fitstruct[["estimate"]]. Also, if fitstruct[["fit"]] = c(1,1), CSTRfn tries to match both Concentration and Temperature, and rows corresponding to Concentration come first following by rows corresponding to Temperature.

If gradwrd = FALSE, this is the 'Dres' component of the final 'CSTR-fitLS' object reformatted as follows:

Dres <- with(CSTRfitLS(...)[["Dres"]], rbind(DSres, DLres))

fits truct a list components matching the 'fitstruct' input, with coefficients estimated replaced by their initial values from parvec and with coef0 replace by its final estimate.

df estimated degrees of freedom as the trace of the appropriate matrix. gcv the Generalized cross validation estimate of the mean square error, as discussed in Ramsay and Silverman (2006, sec. 5.4).

CSTRres, CSTRres0

the 'res' component of CSTRfd(...) as a column vector. This allows us to use 'nls' with the CSTR model. This can be especially useful as 'nls' has several helper functions to facilitate evaluating goodness of fit and and uncertainty in parameter estimates.

CSTRsse

sum(res*res) from CSTRfd(...). This allows us to use 'optim' or 'nlminb' with the CSTR model. This can also be used to obtain starting values for 'nls' in cases where 'nls' fails to converge from the initiall provided starting values. Apart from 'par', the other arguments 'datstruct', 'fitstruct', 'CSTRbasis', and 'lambda', must be passed via '...' in 'optim' or 'nlminb'.

References

Ramsay, J. O., Hooker, G., Cao, J. and Campbell, D. (2007) Parameter estimation for differential equations: A generalized smoothing approach (with discussion). Journal of the Royal Statistical Society, Series B. To appear.

Ramsay, J. O., and Silverman, B. W. (2006) Functional Data Analysis, 2nd ed. (Springer) Ramsay, James O., and Silverman, Bernard W. (2002), *Applied Functional Data Analysis*, Springer, New York

See Also

lsoda nls

```
###
###
### 1. lsoda(y, times, func=CSTR2, parms=...)
###
# The system of two nonlinear equations has five forcing or
# input functions.
# These equations are taken from
# Marlin, T. E. (2000) Process Control, 2nd Edition, McGraw Hill,
# pages 899-902.
##
## Set up the problem
##
fitstruct <- list(V
                      = 1.0,# volume in cubic meters
                 Cp = 1.0, \# concentration in cal/(g.K)
                 rho = 1.0,# density in grams per cubic meter
                 delH = -130.0, \# cal/kmol
                 Cpc = 1.0,# concentration in cal/(g.K)
                 rhoc = 1.0,# cal/kmol
                 Tref = 350)# reference temperature
# store true values of known parameters
EoverRtru = 0.83301# E/R in units K/1e4
kreftru = 0.4610 # reference value
         = 1.678#
                      a in units (cal/min)/K/1e6
atru
         = 0.5#
                      dimensionless exponent
btru
fitstruct[["kref"]] = kreftru#
fitstruct[["EoverR"]] = EoverRtru# kref = 0.4610
fitstruct[["a"]]
                  = atru#
                                   a in units (cal/min)/K/1e6
fitstruct[["b"]]
                     = btru#
                                   dimensionless exponent
Tlim = 64#
              reaction observed over interval [0, Tlim]
delta = 1/12# observe every five seconds
tspan = seq(0, Tlim, delta)#
coolStepInput <- CSTR2in(tspan, 'all.cool.step')</pre>
# set constants for ODE solver
# cool condition solution
# initial conditions
Cinit.cool = 1.5965# initial concentration in kmol per cubic meter
Tinit.cool = 341.3754# initial temperature in deg K
yinit = c(Conc = Cinit.cool, Temp=Tinit.cool)
```

cycleplot.fd

Plot Cycles for a Periodic Bivariate Functional Data Object

Description

A plotting function for data such as the knee-hip angles in the gait data or temperature-precipitation curves for the weather data.

Usage

```
cycleplot.fd(fdobj, matplt=TRUE, nx=201, ...)
```

Arguments

fdobj a bivariate functional data object to be plotted.

matplt if TRUE, all cycles are plotted simultaneously; otherwise each cycle in

turn is plotted.

nx the number of argument values in a fine mesh to be plotted. Increase the

default number of 201 if the curves have a lot of detail in them.

.. additional plotting parameters such as axis labels and etc. that are used

in all plot functions.

Value

None

Side Effects

A plot of the cycles

See Also

```
plot.fd, plotfit.fd, demo(gait)
```

data2fd.old

Depricated: use 'Data2fd'

Description

This function converts an array y of function values plus an array argvals of argument values into a functional data object. This a function that tries to do as much for the user as possible. A basis function expansion is used to represent the curve, but no roughness penalty is used. The data are fit using the least squares fitting criterion. NOTE: Interpolation with data2fd(...) can be shockingly bad, as illustrated in one of the examples.

Usage

Arguments

У

an array containing sampled values of curves.

If y is a vector, only one replicate and variable are assumed.

If y is a matrix, rows must correspond to argument values and columns to replications or cases, and it will be assumed that there is only one variable per observation.

If y is a three-dimensional array, the first dimension (rows) corresponds to argument values, the second (columns) to replications, and the third layers) to variables within replications. Missing values are permitted, and the number of values may vary from one replication to another. If this is the case, the number of rows must equal the maximum number of argument values, and columns of y having fewer values must be padded out with NA's.

argvals

a set of argument values.

If this is a vector, the same set of argument values is used for all columns of y. If argvals is a matrix, the columns correspond to the columns of y, and contain the argument values for that replicate or case.

basisobj

either: A basisfd object created by function create.basis.fd(), or the value NULL, in which case a basisfd object is set up by the function, using the values of the next three arguments.

fdnames

A list of length 3, each member being a string vector containing labels for the levels of the corresponding dimension of the discrete data. The first dimension is for argument values, and is given the default name "time", the second is for replications, and is given the default name "reps", and the third is for functions, and is given the default name "values". These default names are assigned in function {tt data2fd}, which also assigns default string vectors by using the dimnames attribute of the discrete data array.

argnames

a character vector of length 3 containing:

- the name of the argument, e.g. "time" or "age"
- a description of the cases, e.g. "weather stations"
- the name of the observed function value, e.g. "temperature"

These strings are used as names for the members of list fdnames.

Details

This function tends to be used in rather simple applications where there is no need to control the roughness of the resulting curve with any great finesse. The roughness is essentially controlled by how many basis functions are used. In more sophisticated applications, it would be better to use the function <code>smooth.basis</code>

Value

an object of the fd class containing:

coefs the coefficient array basis a basis object and

fdnames a list containing names for the arguments, function values and variables

See Also

\line{Data2fd} smooth.basis, smooth.basisPar, project.basis, smooth.fd, smooth.monotone, smooth.pos day.5

```
# Simplest possible example
b1.2 <- create.bspline.basis(norder=1, breaks=c(0, .5, 1))
# 2 bases, order 1 = degree 0 = step functions

str(fd1.2 <- data2fd(0:1, basisobj=b1.2))
plot(fd1.2)
# A step function: 0 to time=0.5, then 1 after

b2.3 <- create.bspline.basis(norder=2, breaks=c(0, .5, 1))
# 3 bases, order 2 = degree 1 =
# continuous, bounded, locally linear

str(fd2.3 <- data2fd(0:1, basisobj=b2.3))</pre>
```

```
round(fd2.3$coefs, 4)
# 0, -.25, 1
plot(fd2.3)
# Officially acceptable but crazy:
# Initial negative slope from (0,0) to (0.5, -0.25),
# then positive slope to (1,1).
b3.4 <- create.bspline.basis(norder=3, breaks=c(0, .5, 1))
# 4 bases, order 3 = degree 2 =
# continuous, bounded, locally quadratic
str(fd3.4 <- data2fd(0:1, basisobj=b3.4))</pre>
round(fd3.4$coefs, 4)
# 0, .25, -.5, 1
plot(fd3.4)
# Officially acceptable but crazy:
# Initial positive then swings negative
# between 0.4 and ~0.75 before becoming positive again
# with a steep slope running to (1,1).
# Simple example
gaitbasis3 <- create.fourier.basis(nbasis=3)</pre>
str(gaitbasis3) # note: 'names' for 3 bases
gaitfd3 <- data2fd(gait, basisobj=gaitbasis3)</pre>
str(gaitfd3)
# Note: dimanes for 'coefs' + basis[['names']]
# + 'fdnames'
     set up the fourier basis
daybasis <- create.fourier.basis(c(0, 365), nbasis=65)</pre>
# Make temperature fd object
# Temperature data are in 12 by 365 matrix tempav
     See analyses of weather data.
# Convert the data to a functional data object
tempfd <- data2fd(CanadianWeather$dailyAv[,,"Temperature.C"],</pre>
                  day.5, daybasis)
# plot the temperature curves
plot(tempfd)
# Terrifying interpolation
hgtbasis <- with(growth, create.bspline.basis(range(age),</pre>
                                                breaks=age, norder=6))
girl.data2fd <- with(growth, data2fd(hgtf, age, hgtbasis))</pre>
age2 <- with(growth, sort(c(age, (age[-1]+age[-length(age)])/2)))</pre>
girlPred <- eval.fd(age2, girl.data2fd)</pre>
range(growth$hgtf)
range(growth$hgtf-girlPred[seq(1, by=2, length=31),])
# 5.5e-6 0.028 <
# The predictions are consistently too small
# but by less than 0.05 percent
```

```
matplot(age2, girlPred, type="1")
with(growth, matpoints(age, hgtf))
# girl.data2fd fits the data fine but goes berzerk
# between points
```

Data2fd

Create a functional data object from data

Description

This function converts an array y of function values plus an array argvals of argument values into a functional data object. This function tries to do as much for the user as possible. NOTE: Interpolation with data2fd(...) can be shockingly bad, as illustrated in one of the examples.

Usage

Arguments

argvals

a set of argument values. If this is a vector, the same set of argument values is used for all columns of y. If argvals is a matrix, the columns correspond to the columns of y, and contain the argument values for that replicate or case.

Dimensions for argvals must match the first dimensions of y, though y can have more dimensions. For example, if $\dim(y) = c(9, 5, 2)$, argvals can be a vector of length 9 or a matrix of dimensions c(9, 5) or an array of dimensions c(9, 5, 2).

У

an array containing sampled values of curves.

If y is a vector, only one replicate and variable are assumed. If y is a matrix, rows must correspond to argument values and columns to replications or cases, and it will be assumed that there is only one variable per observation. If y is a three-dimensional array, the first dimension (rows) corresponds to argument values, the second (columns) to replications, and the third (layers) to variables within replications. Missing values are permitted, and the number of values may vary from one replication to another. If this is the case, the number of rows must equal the maximum number of argument values, and columns of y having fewer values must be padded out with NA's.

basisobj

One of the following:

basisfd a functional basis object (class basisfd).

fd a functional data object (class fd), from which its basis component is extracted.

fdPar a functional parameter object (class fdPar), from which its basis component is extracted.

integer an integer giving the order of a B-spline basis, create.bspline.basis(argvals, norder=basisobj)

numeric vector specifying the knots for a B-spline basis, create.bspline.basis(basisobj) NULL Defaults to create.bspline.basis(argvals).

nderiv Smoothing typically specified as an integer order for the derivative whose

square is integrated and weighted by lambda to smooth. By default, if basisobj[['type']] == 'bspline', the smoothing operator is int2Lfd(max(0,

norder-2)).

A general linear differential operator can also be supplied.

lambda weight on the smoothing operator specified by nderiv.

fdnames Either a charater vector of length 3 or a named list of length 3. In either

case, the three elements correspond to the following:

argname name of the argument, e.g. "time" or "age".

repname a description of the cases, e.g. "reps" or "weather stations"

value the name of the observed function value, e.g. "temperature"

If fdnames is a list, the components provide labels for the levels of the corresponding dimension of y.

Details

This function tends to be used in rather simple applications where there is no need to control the roughness of the resulting curve with any great finesse. The roughness is essentially controlled by how many basis functions are used. In more sophisticated applications, it would be better to use the function smooth.basisPar.

Value

an object of the fd class containing:

coefs the coefficient array

basis a basis object

fdnames a list containing names for the arguments, function values and variables

References

Ramsay, James O., and Silverman, Bernard W. (2005), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York.

See Also

smooth.basisPar, smooth.basis, project.basis, smooth.fd, smooth.monotone, smooth.pos
day.5

```
## Simplest possible example: step function
b1.1 <- create.bspline.basis(nbasis=1, norder=1)</pre>
# 1 basis, order 1 = degree 0 = step function
y12 <- 1:2
fd1.1 <- Data2fd(y12, basisobj=b1.1)
plot(fd1.1)
# fd1.1 = mean(y12) = 1.5
fd1.1.5 <- Data2fd(y12, basisobj=b1.1, lambda=0.5)
eval.fd(seq(0, 1, .2), fd1.1.5)
# fd1.1.5 = sum(y12)/(n+lambda*integral(over arg=0 to 1 of 1))
          = 3 / (2+0.5) = 1.2
##
## 3 step functions
##
b1.2 <- create.bspline.basis(nbasis=2, norder=1)
# 2 bases, order 1 = degree 0 = step functions
fd1.2 <- Data2fd(1:2, basisobj=b1.2)</pre>
op \leftarrow par(mfrow=c(2,1))
plot(b1.2, main='bases')
plot(fd1.2, main='fit')
par(op)
# A step function: 1 to 0.5, then 2
##
## Simple oversmoothing
b1.3 <- create.bspline.basis(nbasis=3, norder=1)</pre>
fd1.3.5 <- Data2fd(y12, basisobj=b1.3, lambda=0.5)
plot(0:1, c(0, 2), type='n')
points(0:1, y12)
lines(fd1.3.5)
# Fit = penalized least squares with penalty =
           = lambda * integral(0:1 of basis^2),
             which shrinks the points towards 0.
# X1.3 = matrix(c(1,0, 0,0, 0,1), 2)
# XtX = crossprod(X1.3) = diag(c(1, 0, 1))
# penmat = diag(3)/3
         = 3x3 matrix of integral(over arg=0:1 of basis[i]*basis[j])
# Xt.y = crossprod(X1.3, y12) = c(1, 0, 2)
# XtX + lambda*penmat = diag(c(7, 1, 7)/6)
# so coef(fd1.3.5) = solve(XtX + lambda*penmat, Xt.y)
                   = c(6/7, 0, 12/7)
##
## linear spline fit
```

```
##
b2.3 <- create.bspline.basis(norder=2, breaks=c(0, .5, 1))
# 3 bases, order 2 = degree 1 =
# continuous, bounded, locally linear
fd2.3 <- Data2fd(0:1, basisobj=b2.3)
round(fd2.3$coefs, 4)
# (0, 0, 1),
# though (0, a, 1) is also a solution for any 'a'
op <- par(mfrow=c(2,1))
plot(b2.3, main='bases')
plot(fd2.3, main='fit')
par(op)
# smoothing?
fd2.3. <- Data2fd(0:1, basisobj=b2.3, lambda=1)
all.equal(as.vector(round(fd2.3.$coefs, 4)),
          c(0.0159, -0.2222, 0.8730))
# The default smoothing with spline of order 2, degree 1
# has nderiv = max(0, norder-2) = 0.
# Direct computations confirm that the optimal B-spline
# weights in this case are the numbers given above.
op <- par(mfrow=c(2,1))</pre>
plot(b2.3, main='bases')
plot(fd2.3., main='fit')
par(op)
##
## quadratic spline fit
b3.4 <- create.bspline.basis(norder=3, breaks=c(0, .5, 1))
# 4 bases, order 3 = degree 2 =
# continuous, bounded, locally quadratic
fd3.4 <- Data2fd(0:1, basisobj=b3.4)
round(fd3.4$coefs, 4)
# (0, 0, 0, 1),
\# but (0, a, b, 1) is also a solution for any 'a' and 'b'
op <- par(mfrow=c(2,1))</pre>
plot(b3.4)
plot(fd3.4)
par(op)
# try smoothing?
fd3.4. <- Data2fd(0:1, basisobj=b3.4, lambda=1)
round(fd3.4.$coef, 4)
op <- par(mfrow=c(2,1))</pre>
plot(b3.4)
plot(fd3.4.)
```

```
par(op)
##
## A simple Fourier example
gaitbasis3 <- create.fourier.basis(nbasis=3)</pre>
# note: 'names' for 3 bases
gaitfd3 <- Data2fd(gait, basisobj=gaitbasis3)</pre>
# Note: dimanes for 'coefs' + basis[['names']]
# + 'fdnames'
     set up the fourier basis
daybasis <- create.fourier.basis(c(0, 365), nbasis=65)
# Make temperature fd object
  Temperature data are in 12 by 365 matrix tempav
     See analyses of weather data.
# Convert the data to a functional data object
tempfd <- Data2fd(CanadianWeather$dailyAv[,,"Temperature.C"],</pre>
                  day.5, daybasis)
# plot the temperature curves
plot(tempfd)
## Terrifying interpolation
hgtbasis <- with(growth, create.bspline.basis(range(age),</pre>
                                                breaks=age, norder=6))
girl.data2fd <- with(growth, Data2fd(hgtf, age, hgtbasis))</pre>
age2 <- with(growth, sort(c(age, (age[-1]+age[-length(age)])/2)))</pre>
girlPred <- eval.fd(age2, girl.data2fd)</pre>
range(growth$hgtf)
range(growth$hgtf-girlPred[seq(1, by=2, length=31),])
# 5.5e-6 0.028 <
# The predictions are consistently too small
# but by less than 0.05 percent
matplot(age2, girlPred, type="1")
with(growth, matpoints(age, hgtf))
# girl.data2fd fits the data fine but goes berzerk
# between points
# Smooth
girl.data2fd1 <- with(growth, Data2fd(age, hgtf, hgtbasis, lambda=1))</pre>
girlPred1 <- eval.fd(age2, girl.data2fd1)</pre>
matplot(age2, girlPred1, type="l")
with(growth, matpoints(age, hgtf))
# problems splikes disappear
```

Description

Numeric and character vectors to simplify functional data computations and plotting involving dates.

Format

dayOfYear a numeric vector = 1:365

day.5 a numeric vector = dayOfYear-0.5 = 0.5, 1.5, ..., 364.5

daysPerMonth a numeric vector of the days in each month (ignoring leap years) with names = month.abb

monthEnd a numeric vector of cumsum(daysPerMonth) with names = month.abb

monthEnd.5 a numeric vector of the middle of the last day of each month with names = month.abb = c(Jan=30.5, Feb=58.5, ..., Dec=364.5)

monthBegin.5 a numeric vector of the middle of the first day of each month with names - month.abb = c(Jan=0.5, Feb=31.5, ..., Dec=334.5)

monthMid a numeric vector of the middle of the month = (monthBegin.5 + monthEnd.5)/2

monthLetters A character vector of c("j", "F", "m", "A", "M", "J", "J", "A", "S", "O", "N", "D"), with 'month.abb' as the names.

weeks a numeric vector of length 53 marking 52 periods of approximately 7 days each throughout the year = c(0, 365/52, ..., 365)

Details

Miscellaneous vectors often used in 'fda' scripts.

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York, pp. 5, 47-53.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York

See Also

axisIntervals month.abb

Examples

density.fd

Compute a Probability Density Function

Description

Like the regular S-PLUS function density, this function computes a probability density function for a sample of values of a random variable. However, in this case the density function is defined by a functional parameter object WfdParobj along with a normalizing constant C.

The density function p(x) has the form $p(x) = C \exp[W(x)]$ where function W(x) is defined by the functional data object WfdParobj.

Usage

Arguments

х

a strictly increasing set variable values. These observations may be one of two forms:

- 1. a vector of observatons x_i
- 2. a two-column matrix, with the observations x_i in the first column, and frequencies f_i in the second.

The first option corresponds to all $f_i = 1$.

WfdParobj

a functional parameter object specifying the initial value, basis object, roughness penalty and smoothing parameter defining function W(t).

conv

a positive constant defining the convergence criterion.

iterlim

the maximum number of iterations allowed.

active

a logical vector of length equal to the number of coefficients defining Wfdobj. If an entry is TRUE, the corresponding coefficient is estimated, and if FALSE, it is held at the value defining the argument Wfdobj. Normally the first coefficient is set to 0 and not estimated, since it is assumed that W(0) = 0.

dbglev either 0, 1, or 2. This controls the amount information printed out on

each iteration, with 0 implying no output, 1 intermediate output level, and 2 full output. If levels 1 and 2 are used, it is helpful to turn off the

output buffering option in S-PLUS.

... Other arguments to match the generic function 'density'

Details

The goal of the function is provide a smooth density function estimate that approaches some target density by an amount that is controlled by the linear differential operator Lfdobj and the penalty parameter. For example, if the second derivative of W(t) is penalized heavily, this will force the function to approach a straight line, which in turn will force the density function itself to be nearly normal or Gaussian. Similarly, to each textbook density function there corresponds a W(t), and to each of these in turn their corresponds a linear differential operator that will, when apply to W(t), produce zero as a result. To plot the density function or to evaluate it, evaluate Wfdobj, exponentiate the resulting vector, and then divide by the normalizing constant C.

Value

a named list of length 4 containing:

Wfdobj a functional data object defining function W(x) that that optimizes the

fit to the data of the monotone function that it defines.

C the normalizing constant.

Flist a named list containing three results for the final converged solution: (1)

f: the optimal function value being minimized, (2) **grad**: the gradient vector at the optimal solution, and (3) **norm**: the norm of the gradient

vector at the optimal solution.

iternum the number of iterations.

iterhist a iternum+1 by 5 matrix containing the iteration history.

See Also

```
intensity.fd density
```

```
# set up range for density rangeval <- c(-3,3) # set up some standard normal data x <- rnorm(50) # make sure values within the range x[x < -3] <- 2.99 x[x > 3] <- 2.99 # set up basis for W(x) basisobj <- create.bspline.basis(rangeval, 11) # set up initial value for Wfdobj
```

```
Wfd0 <- fd(matrix(0,11,1), basisobj)
WfdParobj <- fdPar(Wfd0)
# estimate density
denslist <- density.fd(x, WfdParobj)
# plot density
xval <- seq(-3,3,.2)
wval <- eval.fd(xval, denslist$Wfdobj)
pval <- exp(wval)/denslist$C
plot(xval, pval, type="l", ylim=c(0,0.4))
points(x,rep(0,50))</pre>
```

deriv.fd

Compute a Derivative of a Functional Data Object

Description

A derivative of a functional data object, or the result of applying a linear differential operator to a functional data object, is then converted to a functional data object. This is intended for situations where a derivative is to be manipulated as a functional data object rather than simply evaluated.

Usage

```
deriv.fd(expr, Lfdobj=int2Lfd(1), ...)
```

Arguments

expr a functional data object. It is assumed that the basis for representing the

object can support the order of derivative to be computed. For B-spline bases, this means that the order of the spline must be at least one larger

than the order of the derivative to be computed.

Lfdobj either a positive integer or a linear differential operator object.

... Other arguments to match generic for 'deriv'

Details

Typically, a derivative has more high frequency variation or detail than the function itself. The basis defining the function is used, and therefore this must have enough basis functions to represent the variation in the derivative satisfactorily.

Value

a functional data object for the derivative

See Also

```
getbasismatrix, eval.basis deriv
```

Examples

```
# Estimate the acceleration functions for growth curves
# See the analyses of the growth data.
# Set up the ages of height measurements for Berkeley data
age <- c(seq(1, 2, 0.25), seq(3, 8, 1), seq(8.5, 18, 0.5))
# Range of observations
rng <- c(1,18)
# Set up a B-spline basis of order 6 with knots at ages
knots <- age
norder <- 6
nbasis <- length(knots) + norder - 2</pre>
hgtbasis <- create.bspline.basis(rng, nbasis, norder, knots)
# Set up a functional parameter object for estimating
# growth curves. The 4th derivative is penalyzed to
# ensure a smooth 2nd derivative or acceleration.
Lfdobi <- 4
lambda <- 10^{-0.5}
                    # This value known in advance.
growfdPar <- fdPar(hgtbasis, Lfdobj, lambda)</pre>
# Smooth the data. The data for the boys and girls
  are in matrices hgtm and hgtf, respectively.
hgtmfd <- smooth.basis(age, growth$hgtm, growfdPar)$fd
hgtffd <- smooth.basis(age, growth$hgtf, growfdPar)$fd
# Compute the acceleration functions
accmfd <- deriv.fd(hgtmfd, 2)</pre>
accffd <- deriv.fd(hgtffd, 2)
# Plot the two sets of curves
par(mfrow=c(2,1))
plot(accmfd)
plot(accffd)
```

df2lambda

Convert Degrees of Freedom to a Smoothing Parameter Value

Description

The degree of roughness of an estimated function is controlled by a smoothing parameter lambda that directly multiplies the penalty. However, it can be difficult to interpret or choose this value, and it is often easier to determine the roughness by choosing a value that is equivalent of the degrees of freedom used by the smoothing procedure. This function converts a degrees of freedom value into a multipler lambda.

Usage

Arguments

argvals a vector containing rgument values associated with the values to be smoothed.

basisobj a basis function object.

wtvec a vector of weights for the data to be smoothed.

Lfdobj either a nonnegative integer or a linear differential operator object.

df the degrees of freedom to be converted.

Details

The conversion requires a one-dimensional optimization and may be therefore computationally intensive.

Value

a positive smoothing parameter value lambda

See Also

lambda2df, lambda2gcv

```
# Smooth growth curves using a specified value of
# degrees of freedom.
# Set up the ages of height measurements for Berkeley data
age <- c( seq(1, 2, 0.25), seq(3, 8, 1), seq(8.5, 18, 0.5))
# Range of observations
rng <- c(1,18)
# Set up a B-spline basis of order 6 with knots at ages
knots <- age
norder <- 6
nbasis <- length(knots) + norder - 2</pre>
hgtbasis <- create.bspline.basis(rng, nbasis, norder, knots)
# Find the smoothing parameter equivalent to 12
# degrees of freedom
lambda <- df2lambda(age, hgtbasis, df=12)</pre>
# Set up a functional parameter object for estimating
# growth curves. The 4th derivative is penalyzed to
# ensure a smooth 2nd derivative or acceleration.
Lfdobj <- 4
growfdPar <- fdPar(hgtbasis, Lfdobj, lambda)</pre>
# Smooth the data. The data for the girls are in matrix
hgtffd <- smooth.basis(age, growth$hgtf, growfdPar)$fd
# Plot the curves
plot(hgtffd)
```

Description

If you want only subfolders and no files, use dirs. With recursive = FALSE, dir returns both folders and files. With recursive = TRUE, it returns only files.

Usage

```
dirs(path='.', pattern=NULL, exclude=NULL, all.files=FALSE,
    full.names=FALSE, recursive=FALSE, ignore.case=FALSE)
```

Arguments

Details

- 1. mainDir <- dir(...) without recurse
- 2. Use file.info to restrict mainDir to only directories.
- 3. If !recursive, return the restricted mainDir. Else, if length(mainDir) > 0, create dirList to hold the results of the recursion and call dirs for each component of mainDir. Then unlist and return the result.

Value

A character vector of the desired subdirectories.

Author(s)

Spencer Graves

See Also

```
dir, file.info package.dir
```

```
path2fdaM <- system.file('Matlab/fdaM', package='fda')
dirs(path2fdaM)
dirs(path2fdaM, full.names=TRUE)
dirs(path2fdaM, recursive=TRUE)
dirs(path2fdaM, exclude='^@|^private$', recursive=TRUE)</pre>
```

Eigen

Eigenanalysis preserving dimnames

Description

Compute eigenvalues and vectors, assigning names to the eigenvalues and dimnames to the eigenvectors.

Usage

```
Eigen(x, symmetric, only.values = FALSE, EISPACK = FALSE,
    valuenames )
```

Arguments

a square matrix whose spectral decomposition is to be computed. х logical: If TRUE, the matrix is assumed to be symmetric (or Hermitian symmetric if complex) and only its lower triangle (diagonal included) is used. If 'symmetric' is not specified, the matrix is inspected for symmetry. only.values if 'TRUE', only the eigenvalues are computed and returned, otherwise both eigenvalues and eigenvectors are returned. **EISPACK** logical. Should EISPACK be used (for compatibility with R < 1.7.0)? valuenames character vector of length nrow(x) or a character string that can be extended to that length by appening 1:nrow(x). The default depends on symmetric and whether rownames == colnames: If rownames == colnames and symmetric = TRUE (either specified or determined by inspection), the default is "paste('ev', 1:nrow(x), sep=")". Otherwise, the default is colnames(x) unless this is NULL.

Details

- 1. Check 'symmetric'
- 2. ev <- eigen(x, symmetric, only.values = FALSE, EISPACK = FALSE); see eigen for more details.
- 3. rNames = rownames(x); if this is NULL, rNames = if(symmetric) paste('x', 1:nrow(x), sep=") else paste('xcol', 1:nrow(x)).
- 4. Parse 'valuenames', assign to names(ev[['values']]).

5. dimnames(ev[['vectors']]) <- list(rNames, valuenames)

NOTE: This naming convention is fairly obvious if 'x' is symmetric. Otherwise, dimensional analysis suggests problems with almost any naming convention. To see this, consider the following simple example:

$$X < -matrix(1:4,2,dimnames = list(LETTERS[1:2],letters[3:4]))$$

$$\begin{array}{ccc} & c & d \\ & A & 1 & 3 \\ & B & 2 & 4 \\ \\ & & & & \\ & & & \\ & & & & \\ & & \\ & & & \\ & & & \\ & & \\ & & & \\ & & \\ & & & \\ & & \\ & & & \\$$

$$\begin{array}{cccc} & A & B \\ c & -2 & 1.5 \\ d & 1 & -0.5 \end{array}$$

One way of interpreting this is to assume that colnames are really reciprocals of the units. Thus, in this example, X[1,1] is in units of A/c and X.inv[1,1] is in units of A/c. This would make any matrix with the same row and column names potentially dimensionless. Since eigenvalues are essentially the diagonal of a diagonal matrix, this would mean that eigenvalues are dimensionless, and their names are merely placeholders.

Value

a list with components values and (if only values = FALSE) vectors, as described in eigen.

Author(s)

Spencer Graves

See Also

```
eigen, svd qr chol
```

```
X <- matrix(1:4, 2, dimnames=list(LETTERS[1:2], letters[3:4]))
eigen(X)
Eigen(X, valuenames='eigval')

Y <- matrix(1:4, 2, dimnames=list(letters[5:6], letters[5:6]))
Eigen(Y)

Eigen(Y, symmetric=TRUE)
# only the lower triangle is used;</pre>
```

the upper triangle is ignored.

eval.basis

Values of Basis Functions or their Derivatives

Description

A set of basis functions are evaluated at a vector of argument values. If a linear differential object is provided, the values are the result of applying the the operator to each basis function.

Usage

```
eval.basis(evalarg, basisobj, Lfdobj=0)
```

Arguments

evalarg a vector of argument values.

basisobj a basis object defining basis functions whose values are to be computed.

Lfdobj either a nonnegative integer or a linear differential. operator object.

Details

If a linear differential operator object is supplied, the basis must be such that the highest order derivative can be computed. If a B-spline basis is used, for example, its order must be one larger than the highest order of derivative required.

Value

a matrix of basis function values with rows corresponding to argument values and columns to basis functions.

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York

See Also

```
getbasismatrix, eval.fd, plot.basisfd
```

```
## 1. B-splines
# The simplest basis currently available:
# a single step function
str(bspl1.1 <- create.bspline.basis(norder=1, breaks=0:1))</pre>
(eval.bspl1.1 <- eval.basis(seq(0, 1, .2), bspl1.1))
# The second simplest basis:
# 2 step functions, [0, .5], [.5, 1]
str(bspl1.2 <- create.bspline.basis(norder=1, breaks=c(0,.5, 1)))</pre>
(eval.bspl1.2 <- eval.basis(seq(0, 1, .2), bspl1.2))</pre>
# Second order B-splines (degree 1: linear splines)
str(bspl2.3 <- create.bspline.basis(norder=2, breaks=c(0,.5, 1)))</pre>
(eval.bspl2.3 <- eval.basis(seq(0, 1, .1), bspl2.3))
# 3 bases: order 2 = degree 1 = linear
# (1) line from (0,1) down to (0.5, 0), 0 after
# (2) line from (0,0) up to (0.5, 1), then down to (1,0)
# (3) 0 to (0.5, 0) then up to (1,1).
## 2. Fourier
##
# The false Fourier series with 1 basis function
falseFourierBasis <- create.fourier.basis(nbasis=1)</pre>
(eval.fFB <- eval.basis(seq(0, 1, .2), falseFourierBasis))</pre>
# Simplest real Fourier basis with 3 basis functions
fourier3 <- create.fourier.basis()</pre>
(eval.fourier3 <- eval.basis(seq(0, 1, .2), fourier3))</pre>
# 3 basis functions on [0, 365]
fourier3.365 <- create.fourier.basis(c(0, 365))</pre>
eval.F3.365 <- eval.basis(day.5, fourier3.365)
matplot(eval.F3.365, type="1")
# The next simplest Fourier basis (5 basis functions)
fourier5 <- create.fourier.basis(nbasis=5)</pre>
(eval.F5 <- eval.basis(seq(0, 1, .1), fourier5))</pre>
matplot(eval.F5, type="1")
# A more complicated example
dayrng <- c(0, 365)
nbasis <- 51
norder <- 6
weatherBasis <- create.fourier.basis(dayrng, nbasis)</pre>
basisMat <- eval.basis(day.5, weatherBasis)</pre>
```

```
matplot(basisMat[, 1:5], type="l")
```

eval.bifd

Values a Two-argument Functional Data Object

Description

A vector of argument values for the first argument s of the functional data object to be evaluated.

Usage

```
eval.bifd(sevalarg, tevalarg, bifd, sLfdobj=0, tLfdobj=0)
```

Arguments

iguments	
sevalarg	a vector of argument values for the first argument ${\tt s}$ of the functional data object to be evaluated.
tevalarg	a vector of argument values for the second argument ${\tt t}$ of the functional data object to be evaluated.
bifd	a two-argument functional data object.
sLfdobj	either a nonnegative integer or a linear differential operator object. If present, the derivative or the value of applying the operator to the object as a function of the first argument ${\tt s}$ is evaluated rather than the functions themselves.
tLfdobj	either a nonnegative integer or a linear differential operator object. If

present, the derivative or the value of applying the operator to the object as a function of the second argument t is evaluated rather than the functions themselves.

Value

an array of 2, 3, or 4 dimensions containing the function values. The first dimension corresponds to the argument values in sevalarg, the second to argument values in tevalarg, the third if present to replications, and the fourth if present to functions.

Examples

```
daybasis
           <- create.fourier.basis(c(0,365), 365)
harmLcoef <- c(0,(2*pi/365)^2,0)
           <- vec2Lfd(harmLcoef, c(0,365))</pre>
harmLfd
templambda <- 1.0
tempfdPar <- fdPar(daybasis, harmLfd, lambda=1)</pre>
tempfd
           <- smooth.basis(day.5,
          CanadianWeather$dailyAv[,,"Temperature.C"], tempfdPar)$fd
```

define the variance-covariance bivariate fd object

```
tempvarbifd <- var.fd(tempfd)
# evaluate the variance-covariance surface and plot
weektime <- seq(0,365,len=53)
tempvarmat <- eval.bifd(weektime,weektime,tempvarbifd)
# make a perspective plot of the variance function
persp(tempvarmat)</pre>
```

eval.fd

Values of a Functional Data Object

Description

Evaluate a functional data object at specified argument values, or evaluate a derivative or the result of applying a linear differential operator to the functional object.

Usage

```
eval.fd(evalarg, fdobj, Lfdobj=0)
```

Arguments

evalarg a vector of argument values at which the functional data object is to be

evaluated.

fdobj a functional data object to be evaluated.

Lfdobj either a nonnegative integer or a linear differential operator object. If

present, the derivative or the value of applying the operator is evaluated

rather than the functions themselves.

Value

an array of 2 or 3 dimensions containing the function values. The first dimension corresponds to the argument values in evalarg, the second to replications, and the third if present to functions.

See Also

```
getbasismatrix, eval.bifd, eval.penalty, eval.monfd, eval.posfd
```

```
# set up the fourier basis
daybasis <- create.fourier.basis(c(0, 365), nbasis=65)
# Make temperature fd object
# Temperature data are in 12 by 365 matrix tempav
# See analyses of weather data.
# Set up sampling points at mid days
# Convert the data to a functional data object
tempfd <- data2fd(CanadianWeather$dailyAv[,,"Temperature.C"],</pre>
```

```
day.5, daybasis)
# set up the harmonic acceleration operator
Lbasis <- create.constant.basis(c(0, 365))
Lcoef <- matrix(c(0,(2*pi/365)^2,0),1,3)
bfdobj <- fd(Lcoef,Lbasis)
bwtlist <- fd2list(bfdobj)
harmaccelLfd <- Lfd(3, bwtlist)
# evaluate the value of the harmonic acceleration
# operator at the sampling points
Ltempmat <- eval.fd(day.5, tempfd, harmaccelLfd)
# Plot the values of this operator
matplot(day.5, Ltempmat, type="1")</pre>
```

eval.monfd

Values of a Monotone Functional Data Object

Description

Evaluate a monotone functional data object at specified argument values, or evaluate a derivative of the functional object.

Usage

```
eval.monfd(evalarg, Wfd, Lfdobj=int2Lfd(0))
```

Arguments

evalarg a vector of argument values at which the functional data object is to be

evaluated.

Wfd a functional data object that defines the monotone function to be evalu-

ated. Only univariate functions are permitted.

Lfdobj a nonnegative integer specifying a derivative to be evaluated. AT this

time of writing, permissible derivative values are 0, 1, 2, or 3. A linear

differential operator is not allowed.

Details

A monotone function data object h(t) is defined by $h(t) = [D^{\{}-1\}expWfd](t)$. In this equation, the operator $D^{\{}-1\}$ means taking the indefinite integral of the function to which it applies. Note that this equation implies that the monotone function has a value of zero at the lower limit of the arguments. To actually fit monotone data, it will usually be necessary to estimate an intercept and a regression coefficient to be applied to h(t), usually with the least squares regression function lsfit. The function Wfd that defines the monotone function is usually estimated by monotone smoothing function smooth.monotone.

Value

a matrix containing the monotone function values. The first dimension corresponds to the argument values in evalarg and the second to replications.

See Also

```
eval.fd, eval.posfd
```

```
# Estimate the acceleration functions for growth curves
# See the analyses of the growth data.
# Set up the ages of height measurements for Berkeley data
age \leftarrow c(seq(1, 2, 0.25), seq(3, 8, 1), seq(8.5, 18, 0.5))
# Range of observations
rng <- c(1,18)
# First set up a basis for monotone smooth
# We use b-spline basis functions of order 6
# Knots are positioned at the ages of observation.
norder <- 6
nage
      <- 31
nbasis <- nage + norder - 2
wbasis <- create.bspline.basis(rng, nbasis, norder, age)
# starting values for coefficient
cvec0 <- matrix(0,nbasis,1)</pre>
Wfd0 <- fd(cvec0, wbasis)</pre>
# set up functional parameter object
Lfdobi
          <- 3
                    # penalize curvature of acceleration
          <-10^{(-0.5)} # smoothing parameter
lambda
growfdPar <- fdPar(Wfd0, Lfdobj, lambda)</pre>
# Set up wgt vector
wgt <- rep(1,nage)</pre>
# Smooth the data for the first girl
hgt1 = growth$hgtf[,1]
result <- smooth.monotone(age, hgt1, growfdPar, wgt)
# Extract the functional data object and regression
# coefficients
Wfd <- result$Wfdobj
beta <- result$beta
# Evaluate the fitted height curve over a fine mesh
agefine \leftarrow seq(1,18,len=101)
hgtfine <- beta[1] + beta[2]*eval.monfd(agefine, Wfd)</pre>
# Plot the data and the curve
plot(age, hgt1, type="p")
lines(agefine, hgtfine)
# Evaluate the acceleration curve
accfine <- beta[2]*eval.monfd(agefine, Wfd, 2)</pre>
# Plot the acceleration curve
plot(agefine, accfine, type="l")
lines(c(1,18),c(0,0),lty=4)
```

Description

A basis roughness penalty matrix is the matrix containing the possible inner products of pairs of basis functions. These inner products are typically defined in terms of the value of a derivative or of a linear differential operator applied to the basis function. The basis penalty matrix plays an important role in the computation of functions whose roughness is controlled by a roughness penalty.

Usage

```
eval.penalty(basisobj, Lfdobj=int2Lfd(0), rng=rangeval)
```

Arguments

basisobj a basis object.

Lfdobj either a nonnegative integer defining an order of a derivative or a linear

differential operator.

rng a vector of length 2 defining a restricted range. Optionally, the inner

products can be computed over a range of argument values that lies within

the interval covered by the basis function definition.

Details

The inner product can be computed exactly for many types of bases if m is an integer. These include B-spline, fourier, exponential, monomial, polynomial and power bases. In other cases, and for noninteger operators, the inner products are computed by an iterative numerical integration method called Richard extrapolation using the trapezoidal rule.

If the penalty matrix must be evaluated repeatedly, computation can be greatly speeded up by avoiding the use of this function, and instead using quadrature points and weights defined by Simpson's rule.

Value

a square symmetric matrix whose order is equal to the number of basis functions defined by the basis function object basisobj. If Lfdobj is m or a linear differential operator of order m, the rank of the matrix should be at least approximately equal to its order minus m.

See Also

```
getbasispenalty, eval.basis,
```

Evaluate a Positive Functional Data Obj

eval.posfd

Description

Evaluate a positive functional data object at specified argument values, or evaluate a derivative of the functional object.

Usage

```
eval.posfd(evalarg, Wfdobj, Lfdobj=int2Lfd(0))
```

Arguments

evalarg	a vector of argument	values at which	the functional d	lata object is to be
---------	----------------------	-----------------	------------------	----------------------

evaluated.

Wfdobj a functional data object that defines the positive function to be evaluated.

Only univariate functions are permitted.

Lfdobj a nonnegative integer specifying a derivative to be evaluated. AT this time

of writing, permissible derivative values are 0, 1 or 2. A linear differential

operator is not allowed.

Details

A positive function data object h(t) is defined by h(t) = [expWfd](t). The function Wfdobj that defines the positive function is usually estimated by positive smoothing function smooth.positive

Value

a matrix containing the positive function values. The first dimension corresponds to the argument values in evalarg and the second to replications.

See Also

```
eval.fd, eval.monfd
```

Description

Bivariate function data objects are functions of two arguments, f(s,t). It can be useful to evaluate the function for argument values satisfying s=t, such as evaluating the univariate variance function given the bivariate function that defines the variance-covariance function or surface. A linear differential operator can be applied to function f(s,t) considered as a univariate function of either object holding the other object fixed.

Usage

Arguments

evalarg a vector of values of s = t.

bifdobj a bivariate functional data object of the bifd class.

sLfd either a nonnegative integer or a linear differential operator object.

tLfd either a nonnegative integer or a linear differential operator object.

Value

a vector or matrix of diagonal function values.

See Also

```
var.fd, eval.bifd
```

expect.phi

Expectatation of basis functions

Description

Computes expectations of basis functions with respect to a density by numerical integration using Romberg integration

Usage

Arguments

basisobj a basis function object

cvec coefficient vector defining density, of length NBASIS

Cval normalizing constant defining density

nderiv, nderiv1, nderiv2

order of derivative required for basis function expectation

rng a vector of length 2 giving the interval over which the integration is to

take place

JMAX maximum number of allowable iterations

EPS convergence criterion for relative stop

Details

normint.phi computes integrals of $p(x) = \exp phi'(x)$

normdel.phi computes integrals of $p(x) = \exp phi''(x)$

expect.phi computes expectations of basis functions with respect to intensity $p(x) \leftarrow \exp t(c)*phi(x)$

expectden.phi computes expectations of basis functions with respect to density

$$p(x) < -\exp(t(c)*phi(x))/Cval$$

expectden.phiphit computes expectations of cross product of basis functions with respect to density

$$p(x) \leftarrow \exp(t(c)*phi(x))/Cval$$

Value

A vector SS of length NBASIS of integrals of functions.

See Also

plot.basisfd,

Exponential Basis Function Values

expon

Description

Evaluates a set of exponential basis functions, or a derivative of these functions, at a set of arguments.

Usage

```
expon(x, ratevec=1, nderiv=0)
```

Arguments

x a vector of values at which the basis functions are to be evaluated.

ratevec a vector of rate or time constants defining the exponential functions. That

is, if a is the value of an element of this vector, then the corresponding basis function is exp(at). The number of basis functions is equal to the

length of ratevec.

nderiv a nonnegative integer specifying an order of derivative to be computed.

The default is 0, or the basis function value.

Details

There are no restrictions on the rate constants.

Value

a matrix of basis function values with rows corresponding to argument values and columns to basis functions.

See Also

exponpen

exponpen

Exponential Penalty Matrix

Description

Computes the matrix defining the roughness penalty for functions expressed in terms of an exponential basis.

Usage

```
exponpen(basisobj, Lfdobj=int2Lfd(2))
```

Arguments

basisobj an exponential basis object.

Lfdobj either a nonnegative integer or a linear differential operator object.

Details

A roughness penalty for a function x(t) is defined by integrating the square of either the derivative of x(t) or, more generally, the result of applying a linear differential operator L to it. The most common roughness penalty is the integral of the square of the second derivative, and this is the default. To apply this roughness penalty, the matrix of inner products of the basis functions (possibly after applying the linear differential operator to them) defining this function is necessary. This function just calls the roughness penalty evaluation function specific to the basis involved.

Value

a symmetric matrix of order equal to the number of basis functions defined by the exponential basis object. Each element is the inner product of two exponential basis functions after applying the derivative or linear differential operator defined by Lfdobj.

See Also

```
expon, eval.penalty, getbasispenalty
```

Examples

```
# set up an exponential basis with 3 basis functions ratevec <- c(0, -1, -5) basisobj <- create.exponential.basis(c(0,1),3,ratevec) # compute the 3 by 3 matrix of inner products of # second derivatives penmat <- exponpen(basisobj)
```

fd

Define a Functional Data Object

Description

This is the constructor function for objects of the fd class. Each function that sets up an object of this class must call this function. This includes functions data2fd, smooth.basis, density.fd, and so forth that estimate functional data objects that smooth or otherwise represent data. Ordinarily, user of the functional data analysis software will not need to call this function directly, but these notes are valuable to understanding what the "slots" or "members" of the fd class are.

Usage

fd(coef=NULL, basisobj=NULL, fdnames=defaultnames)

Arguments

coef a vector, matrix, or three-dimensional array of coefficients. The first di-

mension of matrices and arrays, as well as that of a vector, corresponds to basis functions. The second dimension corresponds to the number of functions or curves, or to replicates. The third dimension if present corresponds to variables for multivariate functional data objects. A functional data object is referred to as "univariate" if this argument is a vector or a

matrix, and "multivariate" if it is a three-dimensional array.

if(is.null(coef)) coef <- rep(0, basisobj[['nbasis']])

basisobj a functional basis object defining the basis

if(is.null(basisobj)) rc <- range(coef) if(diff(rc)==0) rc <- rc+0:1 nb <- max(4, nrow(coef)) basisobj <- create.bspline.basis(rc, nbasis = nb)

fdnames A list of length 3, each member being a string vector containing labels for

the levels of the corresponding dimension of the discrete data. The first dimension is for argument values, and is given the default name "time", the second is for replications, and is given the default name "reps", and

the third is for functions, and is given the default name "values".

Details

To check that an object is of this class, use function is.fd.

Normally only developers of new functional data analysis functions will actually need to use this function.

Value

A functional data object (i.e., having class fd), which is a list with components named coefs, basis, and fdnames.

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York

See Also

data2fd smooth.basis density.fd create.bspline.basis

Examples

```
##
## The simplest b-spline basis: order 1, degree 0, zero interior knots:
##
         a single step function
##
bspl1.1 <- create.bspline.basis(norder=1, breaks=0:1)</pre>
fd.bspl1.1 <- fd(0, basisobj=bspl1.1)</pre>
fd.bspl1.1a <- fd(basisobj=bspl1.1)</pre>
all.equal(fd.bspl1.1, fd.bspl1.1a)
# TRUE
## Not run:
fd.bspl1.1b <- fd(0)
Error in fd(0):
  Number of coefficients does not match number of basis functions.
... because fd by default wants to create a cubic spline
## End(Not run)
##
## Cubic spline: 4 basis functions
bspl4 <- create.bspline.basis(nbasis=4)</pre>
plot(bspl4)
parab4.5 <- fd(c(3, -1, -1, 3)/3, bspl4)
# = 4*(x-.5)^2
plot(parab4.5)
```

fda-internal

FDA internal functions

Description

Internal undocumentation functions

Usage

```
center.fd(fdobj)
```

Description

Functions and data sets companion to Ramsay, J. O., and Silverman, B. W. (2005) Functional Data Analysis, 2nd ed. and (2002) Applied Functional Data Analysis (Springer). This includes finite bases approximations (such as splines and Fourier series) to functions fit to data smoothing on the integral of the squared deviations from an arbitrary differential operator.

Details

Package: fda
Type: Package
Version: 2.0.0
Date: 2008-05-05
License: GPL-2
LazyLoad: yes

Author(s)

J. O. Ramsay,

Maintainer: J. O. Ramsay <ramsay@psych.mcgill.ca>

References

Ramsay, James O., and Silverman, Bernard W. (2005), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), *Applied Functional Data Analysis*, Springer, New York.

```
##
## Simple basis
##
bspl1.2 <- create.bspline.basis(norder=1, breaks=c(0,.5, 1))
plot(bspl1.2)
# 2 bases, order 1 = degree 0 = step functions:
# (1) constant 1 between 0 and 0.5 and 0 otherwise
# (2) constant 1 between 0.5 and 1 and 0 otherwise.

fd1.2 <- Data2fd(0:1, basisobj=bspl1.2)
op <- par(mfrow=c(2,1))
plot(bspl1.2, main='bases')
plot(fd1.2, main='fit')
par(op)
# A step function: 0 to time=0.5, then 1 after</pre>
```

fdaMatlabPath

Add 'fdaM' to the Matlab path

Description

Write a sequence of Matlab commands to fdaMatlabPath.m in the working directory containing commands to add fdaM to the path for Matlab.

Usage

```
fdaMatlabPath(R.matlab)
```

Arguments

R.matlab

logical: If TRUE, include ' $^{\prime}$ R/library/R.matlab/externals' in the path. If(missing(R.matlab)) include ' $^{\prime}$ R/library/R.matlab/externals' only if R.matlab is installed.

Details

USAGE If your Matlab installation does NOT have a startup.m file, it might be wise to copy fdaMatlabPath.m into a directory where Matlab would look for startup.m, then rename it to startup.m.

If you have a startup.m, you could add the contents of fdaMatlabPath.m to startup.m. Alternatively, you can copy fdaMatlabPath.m into the directory containing startup.m and add the following to the end of startup.m:

& if exist('fdaMatlabPath') & \ & & fdaMatlabPath ; \ & end &

ALGORITHM 1. path2fdaM = path to the Matlab/fdaM subdiretory of the fda installation directory.

2. Find all subdirectories of path2fdaM except those beginning in '@' or including

'private'.

- 3. if(requires(R.matlab)) add the path to MatlabServer.m to dirs2add
- 4. d2a <- paste("addpath(", dirs2add, ");", sep=")
- 5. writeLines(d2a, 'fdaMatlabPath.m')
- 6. if(exists(startupFile)) append d2a to it

Value

A character vector of Matlab addpath commands is returned invisibly.

Author(s)

Spencer Graves with help from Jerome Besnard

References

Matlab documentation for addpath and startup.m.

See Also

Matlab, dirs

Examples

```
# Modify the Matlab startup.m only when you really want to,
# typically once per installation ... certaintly not
# every time we test this package.
fdaMatlabPath()
```

fdPar

Define a Functional Parameter Object

Description

Functional parameter objects are used as arguments to functions that estimate functional parameters, such as smoothing functions like <code>smooth.basis</code>. A functional parameter object is a functional data object with additional slots specifying a roughness penalty, a smoothing parameter and whether or not the functional parameter is to be estimated or held fixed. Functional parameter objects are used as arguments to functions that estimate functional parameters.

Usage

```
fdPar(fdobj=NULL, Lfdobj=NULL, lambda=0, estimate=TRUE, penmat=NULL)
```

Arguments

fdobj	a functional data object, functional basis object, a functional parameter object or a matrix. If class(fdobj) == 'basisfd', it is converted to functional data objects with the identity matrix as the coefficient matrix. If it a matrix, it is replaced by fd(fdobj).
Lfdobj	either a nonnegative integer or a linear differential operator object. If NULL and fdobj[['type']] == 'bspline', Lfdobj = $int2Lfd(max(0, norder-2))$, where norder = order of fdobj.
lambda	a nonnegative real number specifying the amount of smoothing to be

applied to the estimated functional parameter.

a logical value: if TRUE, the functional parameter is estimated, otherwise,

it is held fixed.

a roughness penalty matrix. Including this can eliminate the need to

a roughness penalty matrix. Including this can eliminate the need to compute this matrix over and over again in some types of calculations.

Details

estimate

penmat

Functional parameters are often needed to specify initial values for iteratively refined estimates, as is the case in functions register.fd and smooth.monotone.

Often a list of functional parameters must be supplied to a function as an argument, and it may be that some of these parameters are considered known and must remain fixed during the analysis. This is the case for functions fRegress and pda.fd, for example.

Value

a functional parameter object

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York

See Also

```
\verb|cca.fd|, density.fd|, fRegress|, intensity.fd|, pca.fd|, smooth.fdPar|, smooth.basis|, smooth.basisPar|, smooth.monotone|, \\line{int2Lfd}|
```

```
##
## Simple example
##
# set up range for density
rangeval <- c(-3,3)
# set up some standard normal data
x <- rnorm(50)</pre>
```

```
# make sure values within the range
x[x < -3] < -2.99
x[x > 3] < 2.99
# set up basis for W(x)
basisobj <- create.bspline.basis(rangeval, 11)</pre>
# set up initial value for Wfdobj
Wfd0 <- fd(matrix(0,11,1), basisobj)</pre>
WfdParobj <- fdPar(Wfd0)</pre>
WfdP3 <- fdPar(seq(-3, 3, length=11))
## smooth the Canadian daily temperature data
##
     set up the fourier basis
        <- 365
nbasis
dayrange \leftarrow c(0,365)
daybasis <- create.fourier.basis(dayrange, nbasis)</pre>
dayperiod <- 365
harmaccelLfd <- vec2Lfd(c(0,(2*pi/365)^2,0), dayrange)</pre>
# Make temperature fd object
# Temperature data are in 12 by 365 matrix tempav
     See analyses of weather data.
# Set up sampling points at mid days
daytime <-(1:365)-0.5
# Convert the data to a functional data object
daybasis65 <- create.fourier.basis(dayrange, nbasis, dayperiod)</pre>
templambda <- 1e1
tempfdPar <- fdPar(fdobj=daybasis65, Lfdobj=harmaccelLfd, lambda=templambda)
#FIXME
#tempfd <- smooth.basis(CanadianWeather$tempav, daytime, tempfdPar)</pre>
# Set up the harmonic acceleration operator
Lbasis <- create.constant.basis(dayrange);</pre>
Lcoef \leftarrow \text{matrix}(c(0,(2*pi/365)^2,0),1,3)
bfdobj <- fd(Lcoef,Lbasis)</pre>
bwtlist <- fd2list(bfdobj)</pre>
harmaccelLfd <- Lfd(3, bwtlist)</pre>
# Define the functional parameter object for
# smoothing the temperature data
        <- 0.01 # minimum GCV estimate
lambda
#tempPar <- fdPar(daybasis365, harmaccelLfd, lambda)</pre>
# smooth the data
#tempfd <- smooth.basis(daytime, CanadialWeather$tempav, tempPar)$fd</pre>
# plot the temperature curves
#plot(tempfd)
```

Copy a file with a default 'to' name

file.copy2

Description

Copy a file appending a number to make the to name unique, with default to = from.

Usage

```
file.copy2(from, to)
```

Arguments

from character: name of a file to be copied
to character: name of copy. Default = from with an integer appended to
the name.

Details

- 1. length(from) != 1: Error: Only one file can be copied.
- 2. file.exists(from)? If no, If no, return FALSE.
- 3. if(missing(to))to <- from; else if(length(to)!=1) error.
- 4. file.exists(to)? If yes, Dir <- dir(dirname(to)), find all Dir starting with to, and find the smallest integer to append to make a unique to name.
- 5. file.copy(from, to)
- 6. Return TRUE.

Value

logical: TRUE (with a name = name of the file created); FALSE if no file created.

Author(s)

Spencer Graves

See Also

```
file.copy,
```

```
## Not run:
file.copy2('startup.m')
# Used by 'fdaMatlabPath' so an existing 'startup.m' is not destroyed
## End(Not run)
```

Fourier Basis Function Values

fourier

Description

Evaluates a set of Fourier basis functions, or a derivative of these functions, at a set of arguments.

Usage

```
fourier(x, nbasis=n, period=span, nderiv=0)
```

Arguments

Х	a vector of argument values at which the Fourier basis functions are to be evaluated.
nbasis	the number of basis functions in the Fourier basis. The first basis function is the constant function, followed by sets of sine/cosine pairs. Normally the number of basis functions will be an odd. The default number is the number of argument values.
period	the width of an interval over which all sine/cosine basis functions repeat themselves. The default is the difference between the largest and smallest argument values.

argument varues

nderiv the derivative to be evaluated. The derivative must not exceed the order.

The default derivative is 0, meaning that the basis functions themselves

are evaluated.

Value

a matrix of function values. The number of rows equals the number of arguments, and the number of columns equals the number of basis functions.

See Also

fourierpen

```
# set up a set of 11 argument values x \leftarrow seq(0,1,0.1) names(x) <- paste("x", 0:10, sep="") # compute values for five Fourier basis functions # with the default period (1) and derivative (0) (basismat <- fourier(x, 5)) # Create a false Fourier basis, i.e., nbasis = 1 # = a constant function
```

fourierpen

Fourier Penalty Matrix

Description

Computes the matrix defining the roughness penalty for functions expressed in terms of a Fourier basis.

Usage

```
fourierpen(basisobj, Lfdobj=int2Lfd(2))
```

Arguments

basisobj a Fourier basis object.

Lfdobj either a nonnegative integer or a linear differential operator object.

Details

A roughness penalty for a function x(t) is defined by integrating the square of either the derivative of x(t) or, more generally, the result of applying a linear differential operator L to it. The most common roughness penalty is the integral of the square of the second derivative, and this is the default. To apply this roughness penalty, the matrix of inner products of the basis functions (possibly after applying the linear differential operator to them) defining this function is necessary. This function just calls the roughness penalty evaluation function specific to the basis involved.

Value

a symmetric matrix of order equal to the number of basis functions defined by the Fourier basis object. Each element is the inner product of two Fourier basis functions after applying the derivative or linear differential operator defined by Lfdobj.

See Also

```
fourier, eval.penalty, getbasispenalty
```

```
# set up a Fourier basis with 13 basis functions
# and and period 1.0.
basisobj <- create.fourier.basis(c(0,1),13)
# compute the 13 by 13 matrix of inner products
# of second derivatives
penmat <- fourierpen(basisobj)</pre>
```

Description

Fperm.fd creates a null distribution for a test of no effect in functional linear regression. It makes generic use of fRegress and permutes the yfdPar input.

Usage

Arguments

yfdPar

the dependent variable object. It may be an object of three possible

vector if the dependent variable is scalar.

fd a functional data object if the dependent variable is functional.

fdPar a functional parameter object if the dependent variable is functional, and if it is necessary to smooth the prediction of the dependent variable

xfdlist

a list of length equal to the number of independent variables. Members of this list are the independent variables. They be objects of either of these two classes:

- a vector if the independent dependent variable is scalar.
- a functional data object if the dependent variable is functional.

In either case, the object must have the same number of replications as the dependent variable object. That is, if it is a scalar, it must be of the same length as the dependent variable, and if it is functional, it must have the same number of replications as the dependent variable.

betalist

a list of length equal to the number of independent variables. Members of this list define the regression functions to be estimated. They are functional parameter objects. Note that even if corresponding independent variable is scalar, its regression coefficient will be functional if the dependent variable is functional. Each of these functional parameter objects defines a single functional data object, that is, with only one replication.

wt

weights for weighted least squares, defaults to all 1.

nperm

number of permutations to use in creating the null distribution.

argvals

If yfdPar is a fd object, the points at which to evaluate the point-wise F-statistic.

q

Critical quantile of the null distribution to compare to the observed F-statistic.

plotres

Argument to plot a visual display of the null distribution displaying the qth quantile and observed F-statistic.

Details

An F-statistic is calculated as the ratio of residual variance to predicted variance. The observed F-statistic is returned along with the permutation distribution.

If yfdPar is a fd object, the maximal value of the pointwise F-statistic is calculated. The pointwise F-statistics are also returned.

The default of setting q = 0.95 is, by now, fairly standard. The default nperm = 200 may be small, depending on the amount of computing time available.

If argvals is not specified and yfdPar is a fd object, it defaults to 101 equally-spaced points on the range of yfdPar.

Value

A list with components

pval the observed p-value of the permutation test.

qval the qth quantile of the null distribution.

Fobs the observed maximal F-statistic.

Fnull a vector of length nperm giving the observed values of the permutation

distribution.

Fvals the pointwise values of the observed F-statistic.

Fnullvals the pointwise values of of the permutation observations.

pvals.pts pointwise p-values of the F-statistic.

qvals.pts pointwise qth quantiles of the null distribution fRegressList the result of fRegress on the observed data

argument values for evaluating the F-statistic if yfdPar is a functional

data object.

normal-bracket70bracket-normal

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

See Also

fRegress Fstat.fd

fRegress.CV

Computes Cross-validated Error Sum of Squares for a Functional Regression Model

Description

For a functional regression model with a scalar dependent variable, a cross-validated error sum of squares is computed. This function aids the choice of smoothing parameters in this model using the cross-validated error sum of squares criterion.

Usage

```
fRegress.CV(yvec, xfdlist, betalist)
```

Arguments

yvec a vector of dependent variable values.

xfdlist a list whose members are functional parameter objects specifying func-

tional independent variables. Some of these may also be vectors specifying

scalar independent variables.

betalist a list containing functional parameter objects specifying the regression

functions and their level of smoothing.

Value

the sum of squared errors in predicting yvec.

See Also

```
fRegress, fRegress.stderr
```

Examples

#See the analyses of the Canadian daily weather data.

fRegress.stderr Compute Standard errors of Coefficient Functions Estimated by

Functional Regression Analysis

Description

Function fRegress carries out a functional regression analysis of the concurrent kind, and estimates a regression coefficient function corresponding to each independent variable, whether it is scalar or functional. This function uses the list that is output by fRegress to provide standard error functions for each regression function. These standard error functions are pointwise, meaning that sampling standard deviation functions only are computed, and not sampling covariances.

Usage

fRegress.stderr(fRegressList, y2cMap, SigmaE)

Arguments

fRegressList the named list of length six that is returned from a call to function

fRegress.

y2cMap a matrix that contains the linear transformation that takes the raw data

values into the coefficients defining a smooth functional data object. Typically, this matrix is returned from a call to function smooth.basis that generates the dependent variable objects. If the dependent variable is scalar, this matrix is an identity matrix of order equal to the length of

the vector.

SigmaE either a matrix or a bivariate functional data object according to whether

the dependent variable is scalar or functional, respectively. This object has a number of replications equal to the length of the dependent variable object. It contains an estimate of the variance-covariance matrix or

function for the residuals.

Value

a named list of length 3 containing:

betastderrlist

a list object of length the number of independent variables. Each member contains a functional parameter object for the standard error of a

regression function.

bvar a symmetric matrix containing sampling variances and covariances for

the matrix of regression coefficients for the regression functions. These

are stored column-wise in defining BVARIANCE.

c2bMap a matrix containing the mapping from response variable coefficients to

coefficients for regression coefficients.

See Also

fRegress, fRegress.CV

Examples

#See the weather data analyses in the file this-is-escaped-codenormal-bracket29bracket-normal for #examples of the use of function this-is-escaped-codenormal-bracket30bracket-normal.

fRegress

Description

This function carries out a functional regression analysis, where either the dependent variable or one or more independent variables are functional. Non-functional variables may be included on either side of the equation. In a concurrent functional linear model all function variables are all evaluated at a common time or argument value t. That is, the fit is defined in terms of the behavior of all variables at a fixed time, or in terms of "now" behavior.

Usage

```
fRegress(yfdPar, xfdlist, betalist, wt=rep(1,N))
```

Arguments

yfdPar

the dependent variable object. It may be an object of three possible classes:

- a vector if the dependent variable is scalar.
- a functional data object if the dependent variable is functional.
- a functional parameter object if the dependent variable is functional, and if it is necessary to smooth the prediction of the dependent variable.

xfdlist

a list of length equal to the number of independent variables. Members of this list are the independent variables. They be objects of either of these two classes:

- a vector if the independent dependent variable is scalar.
- a functional data object if the dependent variable is functional.

In either case, the object must have the same number of replications as the dependent variable object. That is, if it is a scalar, it must be of the same length as the dependent variable, and if it is functional, it must have the same number of replications as the dependent variable.

betalist

a list of length equal to the number of independent variables. Members of this list define the regression functions to be estimated. They are functional parameter objects. Note that even if corresponding independent variable is scalar, its regression coefficient will be functional if the dependent variable is functional. Each of these functional parameter objects defines a single functional data object, that is, with only one replication.

weights for weighted least squares

wt

Details

In the computation of regression function estimates, all independent variables are treated as if they are functional. If argument xfdlist contains one or more vectors, these are converted to functional data objects having the constant basis with coefficients equal to the elements of the vector.

Needless to say, if all the variables in the model are scalar, use this function, but rather either ls or lsfit.

Value

a named list of length 6 with these members:

yfdPar yhe first argument in the call to fRegress.

xfdlist the second argument in the call to fRegress.

betalist the third argument in the call to fRegress.

betaestlist a list of length equal to the number of independent variables and with

members having the same functional parameter structure as the corresponding members of betalist. These are the estimated regression co-

efficient functions.

yhatfdobj a functional data object if the dependent variable is functional or a vector

if the dependent variable is scalar. This is the set of predicted by the

functional regression model for the dependent variable.

Cmatinv a matrix containing the inverse of the coefficient matrix for the linear

equations that define the solution to the regression problem. This matrix is required for function fRegress.stderr that estimates confidence

regions for the regression coefficient function estimates.

See Also

```
fRegress.stderr, fRegress.CV, linmod
```

Examples

```
#See the Canadian daily weather data analyses in the file
# this-is-escaped-code{ for
#examples of all the cases covered by this-is-escaped-codenormal-bracket48bracket-normal.
```

Fstat.fd

F-statistic for functional linear regression.

Description

Fstat.fd calculates a pointwise F-statistic for functional linear regression.

Usage

```
Fstat.fd(y,yhat,argvals=NULL)
```

Arguments

y the dependent variable object. It may be:

• a vector if the dependent variable is scalar.

• a functional data object if the dependent variable is functional.

yhat The predicted values corresponding to y. It must be of the same class.

argvals If yfdPar is a functional data object, the points at which to evaluate the

pointwise F-statistic.

Details

An F-statistic is calculated as the ratio of residual variance to predicted variance.

If argvals is not specified and yfdPar is a fd object, it defaults to 101 equally-spaced points on the range of yfdPar.

Value

A list with components

F the calculated pointwise F-statistics.

argument values for evaluating the F-statistic if yfdPar is a functional

data object.

normal-bracket21bracket-normal

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

See Also

fRegress Fstat.fd

gait

Hip and knee angle while walking

Description

Hip and knee angle in degrees through a 20 point movement cycle for 39 boys

Format

An array of dim c(20, 39, 2) giving the "Hip Angle" and "Knee Angle" for 39 repetitions of a 20 point gait cycle.

Details

The components of dimnames(gait) are as follows:

- [1] standardized gait time = seq(from=0.025, to=0.975, by=0.05)
- [[2]] subject ID = "boy1", "boy2", ..., "boy39"
- [[3]] gait variable = "Hip Angle" or "Knee Angle"

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York.

Examples

```
plot(gait[,1, 1], gait[, 1, 2], type="b")
```

getbasismatrix

Values of Basis Functions or their Derivatives

Description

Evaluate a set of basis functions or their derivatives at a set of argument values.

Usage

```
getbasismatrix(evalarg, basisobj, nderiv=0)
```

Arguments

evalarg a vector of arguments values.

basisobj a basis object.

nderiv a nonnegative integer specifying the derivative to be evaluated.

Value

a matrix of basis function or derivative values. Rows correspond to argument values and columns to basis functions.

See Also

eval.fd

Examples

```
# Minimal example: a B-spline of order 1, i.e., a step function
# with 0 interior knots:
bspl1.1 <- create.bspline.basis(norder=1, breaks=0:1)
getbasismatrix(seq(0, 1, .2), bspl1.1)</pre>
```

getbasispenalty

Evaluate a Roughness Penalty Matrix

Description

A basis roughness penalty matrix is the matrix containing the possible inner products of pairs of basis functions. These inner products are typically defined in terms of the value of a derivative or of a linear differential operator applied to the basis function. The basis penalty matrix plays an important role in the computation of functions whose roughness is controlled by a roughness penalty.

Usage

```
getbasispenalty(basisobj, Lfdobj=NULL)
```

Arguments

```
basisobj a basis object.
Lfdobj
```

Details

A roughness penalty for a function x(t) is defined by integrating the square of either the derivative of x(t) or, more generally, the result of applying a linear differential operator L to it. The most common roughness penalty is the integral of the square of the second derivative, and this is the default. To apply this roughness penalty, the matrix of inner products of the basis functions defining this function is necessary. This function just calls the roughness penalty evaluation function specific to the basis involved.

Value

a symmetric matrix of order equal to the number of basis functions defined by the B-spline basis object. Each element is the inner product of two B-spline basis functions after taking the derivative.

See Also

```
eval.penalty
```

Examples

```
# set up a B-spline basis of order 4 with 13 basis functions
# and knots at 0.0, 0.1,..., 0.9, 1.0.
basisobj <- create.bspline.basis(c(0,1),13)
# compute the 13 by 13 matrix of inner products of second derivatives
penmat <- getbasispenalty(basisobj)
# set up a Fourier basis with 13 basis functions
# and and period 1.0.
basisobj <- create.fourier.basis(c(0,1),13)
# compute the 13 by 13 matrix of inner products of second derivatives
penmat <- getbasispenalty(basisobj)</pre>
```

getbasisrange

Extract the range from a basis object

Description

Extracts the 'range' component from basis object 'basisobj'.

Usage

getbasisrange(basisobj)

Arguments

basisobj

a functional basis object

Value

a numeric vector of length 2

growth

Berkeley Growth Study data

Description

A list containing the heights of 39 boys and 54 girls from age 1 to 18 and the ages at which they were collected.

Format

This list contains the following components:

hgtm a 31 by 39 numeric matrix giving the heights in centimeters of 39 boys at 31 ages. hgtf a 31 by 54 numeric matrix giving the heights in centimeters of 54 girls at 31 ages. age a numeric vector of length 31 giving the ages at which the heights were measured.

Details

The ages are not equally spaced.

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York, ch. 6.

Tuddenham, R. D., and Snyder, M. M. (1954) "Physical growth of California boys and girls from birth to age 18", *University of California Publications in Child Development*, 1, 183-364.

Examples

```
with(growth, matplot(age, hgtf[, 1:10], type="b"))
```

handwrit

Cursive handwriting samples

Description

20 cursive samples of 1401 (x, y,) coordinates for writing "fda"

Format

An array of dimensions (1401, 20, 2) giving 1401 pairs of (x, y) coordinates for each of 20 replicates of cursively writing "fda"

Details

These data are the X-Y coordinates of 20 replications of writing the script "fda". The subject was Jim Ramsay. Each replication is represented by 1401 coordinate values. The scripts have been extensively pre-processed. They have been adjusted to a common length that corresponds to 2.3 seconds or 2300 milliseconds, and they have already been registered so that important features in each script are aligned.

This analysis is designed to illustrate techniques for working with functional data having rather high frequency variation and represented by thousands of data points per record. Comments along the way explain the choices of analysis that were made.

The final result of the analysis is a third order linear differential equation for each coordinate forced by a constant and by time. The equations are able to reconstruct the scripts to a fairly high level of accuracy, and are also able to accommodate a substantial amount of the variation in the observed scripts across replications. by contrast, a second order equation was found to be completely inadequate.

An interesting suprise in the results is the role placed by a 120 millisecond cycle such that sharp features such as cusps correspond closely to this period. This 110-120 msec cycle

seems is usually seen in human movement data involving rapid movements, such as speech, juggling and so on.

These 20 records have already been normalized to a common time interval of 2300 milliseconds and have been also registered so that prominent features occur at the same times across replications. Time will be measured in (approximate) milliseconds and space in meters. The data will require a small amount of smoothing, since an error of 0.5 mm is characteristic of the OPTOTRAK 3D measurement system used to collect the data.

Milliseconds were chosen as a time scale in order to make the ratio of the time unit to the inter-knot interval not too far from one. Otherwise, smoothing parameter values may be extremely small or extremely large.

The basis functions will be B-splines, with a spline placed at each knot. One may question whether so many basis functions are required, but this decision is found to be essential for stable derivative estimation up to the third order at and near the boundaries.

Order 7 was used to get a smooth third derivative, which requires penalizing the size of the 5th derivative, which in turn requires an order of at least 7. This implies norder + no. of interior knots = 1399 + 7 = 1406 basis functions.

The smoothing parameter value 1e8 was chosen to obtain a fitting error of about 0.5 mm, the known error level in the OPTOTRACK equipment.

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

Examples

```
plot(handwrit[, 1, 1], handwrit[, 1, 2], type="1")
```

inprod.bspline

Compute Inner Products B-spline Expansions.

Description

Computes the matrix of inner products when both functions are represented by B-spline expansions and when both derivatives are integers. This function is called by function inprod, and is not normally used directly.

Usage

```
inprod.bspline(fdobj1, fdobj2=fdobj1, nderiv1=0, nderiv2=0)
```

Arguments

fdobj1	a functional data object having a B-spline basis function expansion.
fdobj2	a second functional data object with a B-spline basis function expansion.
	By default, this is the same as the first argument.
nderiv1	a nonnegative integer specifying the derivative for the first argument.
nderiv2	a nonnegative integer specifying the derivative for the second argument.

Value

a matrix of inner products with number of rows equal to the number of replications of the first argument and number of columns equal to the number of replications of the second object.

inprod

Inner products of Functional Data Objects.

Description

Computes a matrix of inner products for each pairing of a replicate for the first argument with a replicate for the second argument. This is perhaps the most important function in the functional data library. Hardly any analysis fails to use inner products in some way, and many employ multiple inner products. While in certain cases these may be computed exactly, this is a more general function that approximates the inner product approximately when required. The inner product is defined by two derivatives or linear differential operators that are applied to the first two arguments. The range used to compute the inner product may be contained within the range over which the functions are defined. A weight functional data object may also be used to define weights for the inner product.

Usage

Arguments

fdobj1	a functional data object or a basis object. If the object is of the basis class, it is converted to a functional data object by using the identity matrix as the coefficient matrix.
fdobj2	a functional data object or a basis object. If the object is of the basis class, it is converted to a functional data object by using the identity matrix as the coefficient matrix.
Lfdobj1	either a nonnegative integer specifying the derivative of the first argument to be used, or a linear differential operator object to be applied to the first argument.
Lfdobj2	either a nonnegative integer specifying the derivative of the second argument to be used, or a linear differential operator object to be applied to the second argument.
rng	a vector of length 2 defining a restricted range contained within the range over which the arguments are defined.
wtfd	a univariate functional data object with a single replicate defining weights to be used in computing the inner product.

Details

The approximation method is Richardson extrapolation using numerical integration by the trapezoidal rule. At each iteration, the number of values at which the functions are evaluated is doubled, and a polynomial extrapolation method is used to estimate the converged integral values as well as an error tolerance. Convergence is declared when the relative error falls below EPS for all products. The extrapolation method generally saves at least one and often two iterations relative to un-extrapolated trapezoidal integration. Functional data analyses will seldom need to use inprod directly, but code developers should be aware of its pivotal role. Future work may require more sophisticated and specialized numerical integration methods. inprod computes the definite integral, but some functions such as smooth.monotone and register.fd also need to compute indefinite integrals. These use the same approximation scheme, but usually require more accuracy, and hence more iterations. When one or both arguments are basis objects, they are converted to functional data objects using identity matrices as the coefficient matrices. inprod is only called when there is no faster or exact method available. In cases where there is, it has been found that the approximation is good to about four to five significant digits, which is sufficient for most applications. Perhaps surprisingly, in the case of B-splines, the exact method is not appreciably faster, but of course is more accurate. inprod calls function eval.fd perhaps thousands of times, so high efficiency for this function and the functions that it calls is important.

Value

a matrix of inner products. The number of rows is the number of functions or basis functions in argument fd1, and the number of columns is the same thing for argument fd2.

References

Press, et, al, Numerical Recipes.

See Also

eval.penalty,

int2Lfd

Convert Integer to Linear Differential Operator

Description

This function turns an integer specifying an order of a derivative into the equivalent linear differential operator object. It is also useful for checking that an object is of the "Lfd" class.

Usage

int2Lfd(m=0)

Arguments

m

either a nonnegative integer or a linear differential operator object.

Value

a linear differential operator object of the "Lfd" class that is equivalent to the integer argument.

intensity.fd

Intensity Function for Point Process

Description

The intensity mu of a series of event times that obey a homogeneous Poisson process is the mean number of events per unit time. When this event rate varies over time, the process is said to be nonhomogeneous, and mu(t), and is estimated by this function intensity.fd.

Usage

```
intensity.fd(x, WfdParobj, conv=0.0001, iterlim=20,
             dbglev=1)
```

Arguments

х	a vector containing a strictly increasing series of event times. These event
	times assume that the the events begin to be observed at time 0, and
	therefore are times since the beginning of observation.
WfdParobj	a functional parameter object estimating the log-intensity function $W(t) =$

log[mu(t)]. Because the intensity function mu(t) is necessarily positive, it is represented by mu(x) = exp[W(x)].

a convergence criterion, required because the estimation process is iteraconv

tive.

iterlim maximum number of iterations that are allowed.

dbglev either 0, 1, or 2. This controls the amount information printed out on

> each iteration, with 0 implying no output, 1 intermediate output level, and 2 full output. If levels 1 and 2 are used, turn off the output buffering

option.

Details

The intensity function I(t) is almost the same thing as a probability density function p(t)estimated by function densify.fd. The only difference is the absence of the normalizing constant C that a density function requires in order to have a unit integral. The goal of the function is provide a smooth intensity function estimate that approaches some target intensity by an amount that is controlled by the linear differential operator Lfdobj and the penalty parameter in argument WfdPar. For example, if the first derivative of W(t) is penalized heavily, this will force the function to approach a constant, which in turn will force the estimated Poisson process itself to be nearly homogeneous. To plot the intensity function or to evaluate it, evaluate Wfdobj, exponentiate the resulting vector.

Value

a named list of length 4 containing:

Wfdobj a functional data object defining function W(x) that that optimizes the

fit to the data of the monotone function that it defines.

Flist a named list containing three results for the final converged solution: (1)

f: the optimal function value being minimized, (2) **grad**: the gradient vector at the optimal solution, and (3) **norm**: the norm of the gradient

vector at the optimal solution.

iternum the number of iterations.

iterhist a iternum+1 by 5 matrix containing the iteration history.

See Also

density.fd

```
# Generate 101 Poisson-distributed event times with
  intensity or rate two events per unit time
N <- 101
mu <- 2
# generate 101 uniform deviates
uvec <- runif(rep(0,N))</pre>
# convert to 101 exponential waiting times
wvec <- -log(1-uvec)/mu
# accumulate to get event times
tvec <- cumsum(wvec)</pre>
tmax <- max(tvec)</pre>
# set up an order 4 B-spline basis over [0,tmax] with
# 21 equally spaced knots
tbasis <- create.bspline.basis(c(0,tmax), 23)
  set up a functional parameter object for W(t),
  the log intensity function. The first derivative
# is penalized in order to smooth toward a constant
lambda <- 10
WfdParobj <- fdPar(tbasis, 1, lambda)
# estimate the intensity function
Wfdobj <- intensity.fd(tvec, WfdParobj)$Wfdobj
# get intensity function values at 0 and event times
events <- c(0,tvec)
intenvec <- exp(eval.fd(events, Wfdobj))</pre>
# plot intensity function
plot(events, intenvec, type="b")
lines(c(0,tmax),c(mu,mu),lty=4)
```

Confirm Object is Class "Basisfd"

is.basis

Description

Check that an argument is a basis object.

Usage

```
is.basis(basisobj)
```

Arguments

basisobj

an object to be checked.

Value

a logical value: TRUE if the class is correct, FALSE otherwise.

See Also

```
is.fd, is.fdPar, is.Lfd
```

is.fd

Confirm Object has Class "fd"

Description

Check that an argument is a functional data object.

Usage

```
is.fd(fdobj)
```

Arguments

fdobj

an object to be checked.

Value

a logical value: TRUE if the class is correct, FALSE otherwise.

See Also

```
is.basis, is.fdPar, is.Lfd
```

Confirm Object has Class "fdPar"

is.fdPar

Description

Check that an argument is a functional parameter object.

Usage

```
is.fdPar(fdParobj)
```

Arguments

fdParobj

an object to be checked.

Value

a logical value: TRUE if the class is correct, FALSE otherwise.

See Also

```
is.basis, is.fd, is.Lfd
```

is.Lfd

Confirm Object has Class "Lfd"

Description

Check that an argument is a linear differential operator object.

Usage

```
is.Lfd(Lfdobj)
```

Arguments

Lfdobj

an object to be checked.

Value

a logical value: TRUE if the class is correct, FALSE otherwise.

See Also

```
is.basis, is.fd, is.fdPar
```

Description

Extract either all or only the interior knots from an object of class basisfd, fd, or fdSmooth.

Usage

```
## S3 method for class 'fd':
knots(Fn, interior=TRUE, ...)
## S3 method for class 'fdSmooth':
knots(Fn, interior=TRUE, ...)
## S3 method for class 'basisfd':
knots(Fn, interior=TRUE, ...)
```

Arguments

Fn an object of class basisfd or containing such an object

interior logical:

if TRUE, the first Fn[["k"]]+1 of Fn[["knots"]] are dropped, and the next

Fn[["g"]] are returned.

Otherwise, the first Fn[["n"]] of Fn[["knots"]] are returned.

... ignored

Details

The interior knots of a bspline basis are stored in the params component. The remaining knots are in the rangeval component, with mulltiplicity norder(Fn).

Value

Numeric vector. If 'interior' is TRUE, this is the params component of the bspline basis. Otherwise, params is bracketed by rep(rangeval, norder(basisfd).

Author(s)

Spencer Graves

References

Dierckx, P. (1991) Curve and Surface Fitting with Splines, Oxford Science Publications.

See Also

```
fd, create.bspline.basis, knots.dierckx
```

Examples

```
x < -0:24
y \leftarrow c(1.0,1.0,1.4,1.1,1.0,1.0,4.0,9.0,13.0,
       13.4,12.8,13.1,13.0,14.0,13.0,13.5,
       10.0,2.0,3.0,2.5,2.5,2.5,3.0,4.0,3.5)
if(require(DierckxSpline)){
   z1 \leftarrow curfit(x, y, method = "ss", s = 0, k = 3)
   knots1 <- knots(z1)</pre>
   knots1All <- knots(z1, interior=FALSE) # to see all knots</pre>
   fda1 <- dierckx2fd(z1)
   fdaKnots <- knots(fda1)
   fdaKnotsA <- knots(fda1, interior=FALSE)</pre>
   stopifnot(all.equal(knots1, fdaKnots))
   stopifnot(all.equal(knots1All, fdaKnotsA))
}
# knots.fdSmooth
girlGrowthSm <- with(growth, smooth.basisPar(argvals=age, y=hgtf))</pre>
girlKnots.fdSm <- knots(girlGrowthSm)</pre>
girlKnots.fdSmA <- knots(girlGrowthSm, interior=FALSE)
stopifnot(all.equal(girlKnots.fdSm, girlKnots.fdSmA[5:33]))
girlKnots.fd <- knots(girlGrowthSm$fd)</pre>
girlKnots.fdA <- knots(girlGrowthSm$fd, interior=FALSE)</pre>
stopifnot(all.equal(girlKnots.fdSm, girlKnots.fd))
stopifnot(all.equal(girlKnots.fdSmA, girlKnots.fdA))
```

lambda2df

Convert Smoothing Parameter to Degrees of Freedom

Description

The degree of roughness of an estimated function is controlled by a smoothing parameter lambda that directly multiplies the penalty. However, it can be difficult to interpret or choose this value, and it is often easier to determine the roughness by choosing a value that is equivalent of the degrees of freedom used by the smoothing procedure. This function converts a multipler lambda into a degrees of freedom value.

Usage

Arguments

arguals a vector containing the argument values used in the smooth of the data.

basisobj the basis object used in the smoothing of the data.

wtvec the weight vector, if any, that was used in the smoothing of the data.

Lfdobj the linear differential operator object used to defining the roughness penalty

employed in smoothing the data.

lambda the smoothing parameter to be converted.

Value

the equivalent degrees of freedom value.

See Also

df2lambda

Description

The generalized cross-validation or GCV criterion is often used to select an appropriate smoothing parameter value, by finding the smoothing parameter that minimizes GCV. This function locates that value.

Usage

Arguments

log10lambda the logarithm (base 10) of the smoothing parameter

argvals a vector of argument values.

y the data to be smoothed.

fdParobj a functional parameter object defining the smooth.

wtvec a weight vector used in the smoothing.

Value

the value of the GCV criterion.

Description

It is common to see that among a set of functions certain prominent features such peaks and valleys, called *landmarks*, do not occur at the same times, or other argument values. This is called *phasevariation*, and it can be essential to align these features before proceeding with further functional data analyses. This function uses the timings of these features to align or register the curves. The registration involves estimating a nonlinear transformation of the argument continuum for each functional observation. This transformation is called a warping function. It must be strictly increasing and smooth.

Usage

Arguments

_	
fdobj	a functional data object containing the curves to be registered.
ximarks	a matrix containing the timings or argument values associated with the landmarks for the observations in fd to be registered. The number of rows N equals the number of observations, and the number of columns NL equals the number of landmarks. These landmark times must be in the interior of the interval over which the functions are defined.
x0marks	a vector of length NL of times of landmarks for target curve. If not supplied, the mean of the landmark times in ximarks is used.
WfdPar	a functional parameter object defining the warping functions that transform time in order to register the curves.
monwrd	A logical value: if TRUE, the warping function is estimated using a monotone smoothing method; otherwise, a regular smoothing method is used, which is not guaranteed to give strictly monotonic warping functions.

Details

It is essential that the location of every landmark be clearly defined in each of the curves as well as the template function. If this is not the case, consider using the continuous registration function register.fd. Although requiring that a monotone smoother be used to estimate the warping functions is safer, it adds considerably to the computatation time since monotone smoothing is itself an iterative process. It is usually better to try an initial registration with this feature to see if there are any failures of monotonicity. Moreover, monotonicity failures can usually be cured by increasing the smoothing parameter defining WfdPar. Not much curvature is usually required in the warping functions, so a rather low power basis, usually B-splines, is suitable for defining the functional parameter argument WfdPar. A registration with a few prominent landmarks is often a good preliminary to using the more sophisticated but more lengthy process in register.fd.

Value

a names list of length 2 with components:

fdreg a functional data object for the registered curves.

warpfd a functional data object for the warping functions.

See Also

```
register.fd, smooth.morph
```

Examples

#See the analysis for the lip data in the examples.

Lfd

Define a Linear Differential Operator Object

Description

A linear differential operator of order m is defined, usually to specify a roughness penalty.

Usage

```
Lfd(nderiv=0, bwtlist=vector("list", 0))
```

Arguments

nderiv a nonnegative integer specifying the order m of the highest order deriva-

tive in the operator

bwtlist a list of length m. Each member contains a functional data object that

acts as a weight function for a derivative. The first member weights the function, the second the first derivative, and so on up to order m-1.

Details

To check that an object is of this class, use functions is.Lfd or int2Lfd.

Linear differential operator objects are often used to define roughness penalties for smoothing towards a "hypersmooth" function that is annihilated by the operator. For example, the harmonic acceleration operator used in the analysis of the Canadian daily weather data annihilates linear combinations of 1, sin(2pit/365) and cos(2pit/365), and the larger the smoothing parameter, the closer the smooth function will be to a function of this shape.

Function pda.fd estimates a linear differential operator object that comes as close as possible to annihilating a functional data object.

A linear differential operator of order m is a linear combination of the derivatives of a functional data object up to order m. The derivatives of orders 0, 1, ..., m-1 can each be multiplied by a weight function b(t) that may or may not vary with argument t.

If the notation D^j is taken to mean "take the derivative of order j", then a linear differental operator L applied to function x has the expression

$$Lx(t) = b_0(t)x(t) + b_1(t)Dx(t) + \dots + b_{\ell}m - 1(t)D^{\ell}m - 1(t) + D^mx(t)$$

Value

a linear differential operator object

See Also

```
int2Lfd, vec2Lfd, fdPar, pda.fd
```

Examples

```
# Set up the harmonic acceleration operator
dayrange <- c(0,365)
Lbasis <- create.constant.basis(dayrange)
Lcoef <- matrix(c(0,(2*pi/365)^2,0),1,3)
bfdobj <- fd(Lcoef,Lbasis)
bwtlist <- fd2list(bfdobj)
harmaccelLfd <- Lfd(3, bwtlist)</pre>
```

lines.fd

Add Lines from Functional Data to a Plot

Description

Lines defined by functional observations are added to an existing plot.

Usage

```
## S3 method for class 'fd':
lines(x, Lfdobj=int2Lfd(0), nx=201, ...)
## S3 method for class 'fdSmooth':
lines(x, Lfdobj=int2Lfd(0), nx=201, ...)
```

Arguments

х	a univariate functional data object to be evaluated at nx points over xlim and added as a line to an existing plot.
Lfdobj	either a nonnegative integer or a linear differential operator object. If present, the derivative or the value of applying the operator is evaluated rather than the functions themselves.
nx	Number of points within $xlim$ at which to evaluate x for plotting.
• • •	additional arguments such as axis titles and so forth that can be used in plotting programs called by lines.fd or lines.fdSmooth.

Side Effects

Lines added to an existing plot.

See Also

```
plot.fd, plotfit.fd
```

Examples

```
##
## plot a fit with 3 levels of smoothing
x \leftarrow seq(-1,1,0.02)
y <- x + 3*exp(-6*x^2) + sin(1:101)/2
# sin not rnorm to make it easier to compare
# results across platforms
result4. <- smooth.basisPar(argvals=x, y=y, lambda=1)
result4.4 <- smooth.basisPar(argvals=x, y=y, lambda=1e-4)
result4.0 <- smooth.basisPar(x, y, lambda=0)
plot(x, y)
lines(result4.)
lines(result4.4, col='green')
lines.fdSmooth(result4.0, col='red')
plot(x, y, xlim=c(0.5, 1))
lines.fdSmooth(result4.)
lines.fdSmooth(result4.4, col='green')
lines.fdSmooth(result4.0, col='red')
lines.fdSmooth(result4.0, col='red', nx=101)
# no visible difference from the default?
lines.fdSmooth(result4.0, col='orange', nx=31)
# Clear difference, especially between 0.95 and 1
```

linmod

Fit Fully Functional Linear Model

Description

A functional dependent variable is approximated by a single functional covariate, and the covariate can affect the dependent variable for all values of its argument. The regression function is a bivariate function.

Usage

Arguments

xfdobj a functional data object for the covariate

yfdobj a functional data object for the dependent variable

wtvec a vector of weights for each observation.

xLfdobj either a nonnegative integer or a linear differential operator object. This

operator is applied to the regression function's first argument.

yLfdobj either a nonnegative integer or a linear differential operator object. This

operator is applied to the regression function's second argument.

xlambda a smoothing parameter for the first argument of the regression function.
ylambda a smoothing parameter for the second argument of the regression function.

Value

a named list of length 3 with the following entries:

alphafd the intercept functional data object.

regfd a bivariate functional data object for the regression function.

yhatfd a functional data object for the approximation to the dependent vari-

able defined by the linear model, if the dependent variable is functional.

Otherwise the matrix of approximate values.

See Also

fRegress

Examples

#See the prediction of precipitation using temperature as #the independent variable in the analysis of the daily weather #data.

lip Lip motion

Description

51 measurements of the position of the lower lip every 7 milliseconds for 20 repitions of the syllable 'bob'.

Usage

lip lipmarks liptime

Format

lip a matrix of dimension c(51, 20) giving the position of the lower lip every 7 milliseconds for 350 miliseconds.

lipmarks a matrix of dimension c(20, 2) giving the positions of the 'leftElbow' and 'rightElbow' in each of the 20 repitions of the syllable 'bob'.

liptime time in seconds from the start = seq(0, 0.35, 51) = every 7 milliseconds.

Details

These are rather simple data, involving the movement of the lower lip while saying "bob". There are 20 replications and 51 sampling points. The data are used to illustrate two techniques: landmark registration and principal differential analysis. Principal differential analysis estimates a linear differential equation that can be used to describe not only the observed curves, but also a certain number of their derivatives. For a rather more elaborate example of principal differential analysis, see the handwriting data.

See the lip demo.

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York, sections 19.2 and 19.3.

Examples

See the this-is-escaped-codenormal-bracket21bracket-normal this-is-escaped-codenormal-bracket22bracket

lmeWinsor

Winsorized Regression with mixed effects

Description

Clip inputs and mixed-effects predictions to (upper, lower) or to selected quantiles to limit wild predictions outside the training set.

Usage

```
lmeWinsor(fixed, data, random, lower=NULL, upper=NULL, trim=0,
    quantileType=7, correlation, weights, subset, method,
    na.action, control, contrasts = NULL, keep.data=TRUE,
    ...)
```

Arguments

trim

fixed a two-sided linear formula object describing the fixed-effects part of the

model, with the response on the left of a '' operator and the terms, separated by '+' operators, on the right. The left hand side of 'formula'

must be a single vector in 'data', untransformed.

data an optional data frame containing the variables named in 'fixed', 'random',

'correlation', 'weights', and 'subset'. By default the variables are taken

from the environment from which lme is called.

random a random- / mixed-effects specification, as described with lme.

NOTE: Unlike lme, 'random' must be provided; it can not be inferred

from 'data'.

lower, upper optional numeric vectors with names matching columns of 'data' giving

limits on the ranges of predictors and predictions: If present, values below 'lower' will be increased to 'lower', and values above 'upper' will be decreased to 'upper'. If absent, these limit(s) will be inferred from quan-

tile(..., prob=c(trim, 1-trim), na.rm=TRUE, type=quantileType).

the fraction (0 to 0.5) of observations to be considered outside the range of the data in determining limits not specified in 'lower' and 'upper'.

NOTES:

(1) trim>0 with a singular fit may give an error. In such cases, fix the singularity and retry.

(2) trim = 0.5 should NOT be used except to check the algorithm, because it trims everything to the median, thereby providing zero leverage for estimating a regression.

(3) The current algorithm does does NOT adjust any of the variance parameter estimates to account for predictions outside 'lower' and 'upper'. This will have no effect for trim =0 or trim otherwise so small that there are not predictions outside 'lower' and 'upper'. However, for more substantive trimming, this could be an issue. This is different from

lmWinsor.

quantileType an integer between 1 and 9 selecting one of the nine quantile algorithms

to be used with 'trim' to determine limits not provided with 'lower' and

'upper'.

correlation an optional correlation structure, as described with lme.

weights an optional heteroscedasticity structure, as described with lme.

subset an optional vector specifying a subset of observations to be used in the

fitting process, as described with lme.

method a character string. If "REML" the model is fit by maximizing the re-

stricted log-likelihood. If "ML" the log-likelihood is maximized. Defaults

to "REML".

na.action a function that indicates what should happen when the data contain

'NA's. The default action ('na.fail') causes 'lme' to print an error message

and terminate if there are any incomplete observations.

control a list of control values for the estimation algorithm to replace the default

values returned by the function lmeControl. Defaults to an empty list.

NOTE: Other control parameters such as 'singular.ok' as documented in

glsControl may also work, but should be used with caution.

contrasts an optional list. See the 'contrasts.arg' of 'model.matrix.default'.

keep.data logical: should the 'data' argument (if supplied and a data frame) be

saved as part of the model object?

... additional arguments to be passed to the low level regression fitting func-

tions; see lm.

Details

1. Identify inputs and outputs as follows:

- 1.1. $mdly \leftarrow mdlx \leftarrow mdlx[[3]] \leftarrow NULL; mdlx[[2]] \leftarrow NULL;$
- 1.2. xNames <- c(all.vars(mdlx), all.vars(random)).
- 1.3. yNames <- all.vars(mdly). Give an error if as.character(mdly[[2]]) != yNames.
- 2. Do 'lower' and 'upper' contain limits for all numeric columns of 'data? Create limits to fill any missing.
- 3. clipData = data with all xNames clipped to (lower, upper).
- 4. fit0 <- lme(...)
- 5. Add components lower and upper to fit0 and convert it to class c('lmeWinsor', 'lme').
- 6. Clip any stored predictions at the Winsor limits for 'y'.

NOTE: This is different from lmWinsor, which uses quadratic programming with predictions outside limits, transferring extreme points one at a time to constraints that force the unWinsorized predictions for those points to be at least as extreme as the limits.

Value

an object of class c('lmeWinsor', 'lme') with 'lower', 'upper', and 'message' components in addition to the standard 'lm' components. The 'message' is a list with its first component being either 'all predictions inside limits' or 'predictions outside limits'. In the latter case, there rest of the list summarizes how many and which points have predictions outside limits.

Author(s)

Spencer Graves

See Also

lmWinsor predict.lmeWinsor lme quantile

Examples

Winsorized Regression

lmWinsor

Description

Clip inputs and predictions to (upper, lower) or to selected quantiles to limit wild predictions outside the training set.

Usage

```
lmWinsor(formula, data, lower=NULL, upper=NULL, trim=0,
    quantileType=7, subset, weights=NULL, na.action,
    method = "qr", model = TRUE, x = FALSE, y = FALSE, qr = TRUE,
    singular.ok = TRUE, contrasts = NULL, offset=NULL,
    eps=sqrt(.Machine$double.eps), ...)
```

Arguments

formula an object of class "formula" (or one that can be coerced to that class):

a symbolic description of the model to be fitted. See lm. The left hand

side of 'formula' must be a single vector in 'data', untransformed.

data an optional data frame, list or environment (or object coercible by 'as.data.frame'

to a data frame) containing the variables in the model. If not found in

'data', the variables are taken from 'environment (formula)'; see $\operatorname{lm}.$

lower, upper optional numeric vectors with names matching columns of 'data' giving

limits on the ranges of predictors and predictions: If present, values below 'lower' will be increased to 'lower', and values above 'upper' will be decreased to 'upper'. If absent, these limit(s) will be inferred from quan-

tile(..., prob=c(trim, 1-trim), na.rm=TRUE, type=quantileType).

trim the fraction (0 to 0.5) of observations to be considered outside the range

of the data in determining limits not specified in 'lower' and 'upper'.

(1) trim = 0.5 should NOT be used except to check the algorithm, because it trims everything to the median, thereby providing zero leverage for estimating a regression.

(2) trim>0 will give an error with a singular fit. In such cases, fix the singularity and retry.

quantileType an integer between 1 and 9 selecting one of the nine quantile algorithms

to be used with 'trim' to determine limits not provided with 'lower' and

'upper'; see quantile.

subset an optional vector specifying a subset of observations to be used in the

fitting process.

weights an optional vector of weights to be used in the fitting process. Should

be 'NULL' or a numeric vector. If non-NULL, weighted least squares is used with weights 'weights' (that is, minimizing 'sum(w*e*e)'); otherwise

ordinary least squares is used.

need a

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na.action

a function which indicates what should happen when the data contain 'NA's. The default is set by the 'na.action' setting of 'options', and is 'na.fail' if that is unset. The factory-fresh default is 'na.omit'. Another possible value is 'NULL', no action. Value 'na.exclude' can be useful.

method

the method to be used; for fitting, currently only 'method = "qr" is supported; 'method = "model.frame" returns the model frame (the same as with 'model = TRUE', see below).

model, x, y, qr

logicals. If 'TRUE' the corresponding components of the fit (the model frame, the model matrix, the response, the QR decomposition) are re-

singular.ok

logical. If 'FALSE' (the default in S but not in R) a singular fit is an error.

contrasts

an optional list. See the 'contrasts.arg' of 'model.matrix.default'.

offset

this can be used to specify an a priori known component to be included in the linear predictor during fitting. This should be 'NULL' or a numeric vector of length either one or equal to the number of cases. One or more 'offset' terms can be included in the formula instead or as well, and if both are specified their sum is used. See 'model.offset'.

eps

small positive number used in two ways:

limits 'pred' is judged between 'lower' and 'upper' for 'y' as follows: First compute mod = mean(abs(y)). If this is 0, let Eps = eps; otherwise let Eps = eps*mod. Then pred is low if it is less than (lower - Eps), high if it exceeds (upper + Eps), and inside limits otherwise.

QP To identify singularity in the quadratic program (QP) discussed in 'details', step 7 below, first compute the model.matrix of the points with interior predictions. Then compute the QR decomposition of this reduced model.matix. Then compute the absolute values of the diagonal elements of R. If the smallest of these numbers is less than eps times the largest, terminate the QP with the previous parameter estimates.

additional arguments to be passed to the low level regression fitting functions; see lm.

Details

. . .

- 1. Identify inputs and outputs via mdly <- mdlx <- formula; mdly[[3]] <- NULL; mdlx[[2]]
- <- NULL; xNames <- all.vars(mdlx); yNames <- all.vars(mdly). Give an error if as.character(mdly[[2]]) != vNames.
- 2. Do 'lower' and 'upper' contain limits for all numeric columns of 'data? Create limits to fill any missing.
- 3. clipData = data with all xNames clipped to (lower, upper).
- 4. fit0 <- lm(formula, clipData, subset = subset, weights = weights, na.action = na.action, method = method, x=x, y=y, qr=qr, singular.ok=singular.ok, contrasts=contrasts, offset=offset, ...)

- 5. Add components lower and upper to fit0 and convert it to class c('lmWinsor', 'lm').
- 6. If all fit0[['fitted.values']] are inside (lower, upper)[yNames], return(fit0).
- 7. Else, use quadratic programming (QP) to minimize the 'Winsorized sum of squares of residuals' as follows:
- 7.1. First find the prediction farthest outside (lower, upper)[yNames]. Set temporary limits at the next closest point inside that point (or at the limit if that's closer).
- 7.2. Use QP to minimize the sum of squares of residuals among all points not outside the temporary limits while keeping the prediction for the exceptional point away from the interior of (lower, upper)[yNames].
- 7.3. Are the predictions for all points unconstrained in QP inside (lower, upper)[yNames]? If yes, quit.
- 7.4. Otherwise, among the points still unconstrained, find the prediction farthest outside (lower, upper)[yNames]. Adjust the temporary limits to the next closest point inside that point (or at the limit if that's closer).
- 7.5. Use QP as in 7.2 but with multiple exceptional points, then return to step 7.3.
- 8. Modify the components of fit0 as appropriate and return the result.

Value

an object of class c('lmWinsor', 'lm') with 'lower', 'upper', and 'message' components in addition to the standard 'lm' components. In addition, if the initial fit produces predictions outside the limits, this object returned will also include components 'coeffter' and 'tempLimits' containing the model coefficients and temporary limits obtained during the iteration.

The options for 'message' are as follows:

- 1 'Initial fit in bounds': All predictions were between 'lower' and 'upper' for 'y'.
- 2 'QP iterations successful': The QP iteration described in 'Details', step 7, terminated with all predictions either at or between the 'lower' and 'upper' for 'y'.
- iteration terminated by a singular quadratic program': The QP iteration described in 'Details', step 7, terminated when the model.matrix for the QP objective function became rank deficient. (Rank deficient in this case means that the smallest singular value is less than 'eps' times the largest.)

normal-bracket54bracket-normal

In addition to the coefficients, 'coeffter' also includes columns for 'SSEraw' and 'SSE-clipped', containing the residual sums of squres from the estimated linear model before and after clipping to the 'lower' and 'upper' limits for 'y', plus 'nLoOut', 'nLo.', 'nIn', 'nHi.', and 'nHiOut', summarizing the distribtion of model predictions at each iteration relative to the limits.

Author(s)

Spencer Graves

See Also

```
predict.lmWinsor lmeWinsor lm quantile solve.QP
```

Examples

```
# example from 'anscombe'
lm.1 <- lmWinsor(y1~x1, data=anscombe)

# no leverage to estimate the slope
lm.1.5 <- lmWinsor(y1~x1, data=anscombe, trim=0.5)

# test nonlinear optimization
lm.1.25 <- lmWinsor(y1~x1, data=anscombe, trim=0.25)</pre>
```

mean.fd

Mean of Functional Data

Description

Evaluate the mean of a set of functions in a functional data object.

Usage

```
mean.fd(x, ...)
```

Arguments

- x a functional data object.
- ... Other arguments to match the generic function for 'mean'

Value

a functional data object with a single replication that contains the mean of the functions in the object fd.

See Also

```
stddev.fd, var.fd, sum.fd, center.fd mean
```

Examples

```
use 31 order 6 splines so we can look at acceleration
nbasis <- 51
norder <- 6
lipbasis <- create.bspline.basis(liprange, nbasis, norder)</pre>
   ----- apply some light smoothing to this object -----
lipLfdobj
            <- int2Lfd(4)
lipLambda <- 1e-12
lipfdPar <- fdPar(lipbasis, lipLfdobj, lipLambda)</pre>
lipfd <- smooth.basis(liptime, lip, lipfdPar)$fd</pre>
names(lipfd$fdnames) = c("Normalized time", "Replications", "mm")
lipmeanfd <- mean.fd(lipfd)</pre>
plot(lipmeanfd)
## 2. Trivariate: CanadianWeather
dayrng <- c(0, 365)
nbasis <- 51
norder <- 6
weatherBasis <- create.fourier.basis(dayrng, nbasis)</pre>
weather.fd <- smooth.basis(day.5, CanadianWeather$dailyAv,
            weatherBasis)
str(weather.fd.mean <- mean.fd(weather.fd$fd))</pre>
```

melanoma

melanoma 1936-1972

Description

These data from the Connecticut Tumor Registry present age-adjusted numbers of melanoma skin-cancer incidences per 100,000 people in Connectict for the years from 1936 to 1972.

Format

A data frame with 37 observations on the following 2 variables.

year Years 1936 to 1972.

incidence Rate of melanoma cancer per 100,000 population.

Details

This is a copy of the 'melanoma' dataset in the 'lattice' package. It is unrelated to the object of the same name in the 'boot' package.

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

See Also

melanoma melanoma

Examples

```
plot(melanoma[, -1], type="b")
```

monomial

Evaluate Monomial Basis

Description

Computes the values of the powers of argument t.

Usage

```
monomial(evalarg, exponents, nderiv=0)
```

Arguments

evalarg a vector of argument values.

exponents a vector of nonnegative integer values specifying the powers to be com-

puted.

nderiv a nonnegative integer specifying the order of derivative to be evaluated.

Value

a matrix of values of basis functions. Rows correspond to argument values and columns to basis functions.

See Also

polynom, power, expon, fourier, polyg, bsplineS

Examples

```
# set up a monomial basis for the first five powers
nbasis <- 5
basisobj <- create.monomial.basis(c(-1,1),nbasis)
# evaluate the basis
tval <- seq(-1,1,0.1)
basismat <- monomial(tval, 1:basisobj$nbasis)</pre>
```

monomialpen

Evaluate Monomial Roughness Penalty Matrix

Description

The roughness penalty matrix is the set of inner products of all pairs of a derivative of integer powers of the argument.

Usage

Arguments

basisobj a monomial basis object.

Lfdobj either a nonnegative integer specifying an order of derivative or a linear

differential operator object.

rng the inner product may be computed over a range that is contained within

the range defined in the basis object. This is a vector or length two

defining the range.

Value

a symmetric matrix of order equal to the number of monomial basis functions.

See Also

```
polynompen, exponpen, fourierpen, bsplinepen, polygpen
```

Examples

```
# set up a monomial basis for the first five powers
nbasis <- 5
basisobj <- create.monomial.basis(c(-1,1),nbasis)
# evaluate the rougness penalty matrix for the
# second derivative.
penmat <- monomialpen(basisobj, 2)</pre>
```

Nondurable goods index

nondurables

Description

US nondurable goods index time series, January 1919 to January 2000.

Format

An object of class 'ts'.

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), *Applied Functional Data Analysis*, Springer, New York, ch. 3.

Examples

```
plot(nondurables, log="y")
```

norder

Order of a B-spline

Description

norder = number of basis functions minus the number of interior knots.

Usage

```
norder(x, ...)
## S3 method for class 'fd':
norder(x, ...)
## S3 method for class 'basisfd':
norder(x, ...)
## Default S3 method:
norder(x, ...)
norder.bspline(x, ...)
```

Arguments

x Either a basisfd object or an object containing a basisfd object as a component.

... optional arguments currently unused

Details

norder throws an error of basisfd[['type']] != 'bspline'.

Value

An integer giving the order of the B-spline.

Author(s)

Spencer Graves

See Also

```
create.bspline.basis
```

Examples

```
bspl1.1 <- create.bspline.basis(norder=1, breaks=0:1)</pre>
stopifnot(norder(bspl1.1)==1)
stopifnot(norder(fd(0, basisobj=bspl1.1))==1)
stopifnot(norder(fd(rep(0,4)))==4)
stopifnot(norder(list(fd(rep(0,4))))==4)
## Not run:
norder(list(list(fd(rep(0,4)))))
Error in norder.default(list(list(fd(rep(0, 4))))) :
  input is not a 'basisfd' object and does not have a 'basisfd'
component.
## End(Not run)
stopifnot(norder(create.bspline.basis(norder=1, breaks=c(0,.5, 1))) == 1)
stopifnot(norder(create.bspline.basis(norder=2, breaks=c(0,.5, 1))) == 2)
# Defaut B-spline basis: Cubic spline: degree 3, order 4,
# 21 breaks, 19 interior knots.
stopifnot(norder(create.bspline.basis()) == 4)
## Not run:
norder(create.fourier.basis(c(0,12) ))
Error in norder.bspline(x) :
  object x is of type = fourier; 'norder' is only defined for type = 'bsline'
## End(Not run)
```

objAndNames

Add names to an object

Description

Add names to an object from 'preferred' if available and 'default' if not.

Usage

```
objAndNames(object, preferred, default)
```

Arguments

object an object of some type to which names must be added. If length(dim(object))>0

add 'dimnames', else add 'names'.

preferred A list to check first for names to add to 'object'.

default A list to check for names to add to 'object' if appropriate names are not

found in 'preferred'.

Details

1. If length(dim(object))<1, names(object) are taken from 'preferred' if they are not NULL and have the correct length, else try 'default'.

2. Else for(lvl in 1:length(dim(object))) take dimnames[[lvl]] from 'preferred[[i]]' if they are not NULL and have the correct length, else try 'default[[lvl]].

Value

An object of the same class and structure as 'object' but with either names or dimnames added or changed.

Author(s)

Spencer Graves

See Also

```
data2fd, bifd
```

Examples

```
# The following should NOT check 'anything' here
tst1 <- objAndNames(1:2, list(letters[1:2], LETTERS[1:2]), anything)
all.equal(tst1, c(a=1, b=2))

# The following should return 'object unchanged
tst2 <- objAndNames(1:2, NULL, list(letters))
all.equal(tst2, 1:2)</pre>
```

odesolv

Numerical Solution mth Order Differential Equation System

Description

The system of differential equations is linear, with possibly time-varying coefficient functions. The numerical solution is computed with the Runge-Kutta method.

Usage

Arguments

bwtlist a list whose members are functional parameter objects defining the weight

functions for the linear differential equation.

ystart a vector of initial values for the equations. These are the values at time

0 of the solution and its first m - 1 derivatives.

h0 a positive initial step size.

hmin the minimum allowable step size.

hmax the maximum allowable step size.

EPS a convergence criterion.

MAXSTP the maximum number of steps allowed.

Details

This function is required to compute a set of solutions of an estimated linear differential equation in order compute a fit to the data that solves the equation. Such a fit will be a linear combinations of m independent solutions.

Value

a named list of length 2 containing

tp a vector of time values at which the system is evaluated

yp a matrix of variable values corresponding to tp.

See Also

```
pda.fd,
```

Examples

#See the analyses of the lip data.

onechild

growth in height of one 10-year-old boy

Description

Heights of a boy of age approximately 10 collected during one school year. The data were collected "over one school year, with gaps corresponding to the school vacations" (AFDA, p. 84)

Format

A data.frame with two columns:

day Integers counting the day into data collection with gaps indicating days during which data were not collected.

height Height of the boy measured on the indicated day.

Source

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, 2nd ed., Springer, New York.

Tuddenham, R. D., and Snyder, M. M. (1954) "Physical growth of California boys and girls from birth to age 18", *University of California Publications in Child Development*, 1, 183-364.

Examples

```
with(onechild, plot(day, height, type="b"))
```

Description

Functional Principal components analysis aims to display types of variation across a sample of functions. Principal components analysis is an exploratory data analysis that tends to be an early part of many projects. These modes of variation are called *principal components* or *harmonics*. This function computes these harmonics, the eigenvalues that indicate how important each mode of variation, and harmonic scores for individual functions. If the functions are multivariate, these harmonics are combined into a composite function that summarizes joint variation among the several functions that make up a multivariate functional observation.

Usage

Arguments

fdobj a functional data object.

nharm the number of harmonics or principal components to compute.

harmfdPar a functional parameter object that defines the harmonic or principal com-

ponent functions to be estimated.

centerfns a logical value: if TRUE, subtract the mean function from each function

before computing principal components.

Value

an object of class "pca.fd" with these named entries:

harmonics a functional data object for the harmonics or eigenfunctions

values the complete set of eigenvalues

scores s matrix of scores on the principal components or harmonics

varprop a vector giving the proportion of variance explained by each eigenfunction

meanfd a functional data object giving the mean function

See Also

```
cca.fd, pda.fd
```

Examples

pda.fd

 $Principal\ Differential\ Analysis$

Description

Principal differential analysis (PDA) estimates a system of linear differential equations that define functions that fit the data and their derivatives.

Usage

Arguments

xfdlist

a list whose members are functional data objects. Each of these objects contain one or more functions that are variables to be represented by a differential equation. The length of the list is the size of the system of differential equations. The number of replications must be the same for each member functional data object.

bwtlist

a list array with the first two dimensions are equal to the number of variables in the system (the length of list $\mathtt{xfdlist}$) and the last dimension equal to the order of each equation. The order of the equations is assumed to be the same for each equation. If only a single differential equation is involved, this argument can be an ordinary list with length equal to the order of the equation.

Each member of bwtlist defines a weight function in the system of linear differential equation. For any equation, there can be a term in the equation for each order of derivative from 0 to m-1, where m is the order of the equation. These derivatives can be those of each variable in the system, moreover. Thus, a two-variable system of order 3 can have, for each of the two equations, contributions from derivatives of order 0, 1 and 2 for each of the variables, or six terms in total.

The first dimension of bwtlist corresponds to equations, and the second dimension to contributions of variables for a fixed derivative within the equation defined by the first index. The third index indicates the order of derivative of the contribution, which is one less than the index value.

Each member of bwtlist is a either a functional parameter object or a functional data object. Functional data objects are converted to functional parameters objects with no smoothing. Functional parameter objects permit selected weight functions to be held fixed and not estimated. These are often constant functions with the value 0, corresponding to variables and derivatives that make no contribution.

For example, the harmonic acceleration differential equation would be of the form $D^3x(t) = -bDx(t)$ so that bwtlist would be an ordinary list of length 3, each functional parameter object being defined with a constant basis, but only the second object would have a value of TRUE for the estimate slot, and the first and third coefficient functions would have value 0.

awtlist

a list containing weight functions for forcing functions.

In addition to terms in each of the equations involving terms corresponding to each derivative of each variable in the system, each equation can also have a contribution from one or more exogenous variables, often called forcing functions.

This argument defines the weights multiplying these forcing functions, and is a list array with first dimension equal to the number of variables or equations, and second dimension equal to the number of forcing functions. It is assumed that the number of forcing functions is the same for all equations. If only one forcing function is involved, or there is only one equation, then awtlist can be an ordinary list.

Each member is a functional parameter object (or a functional data object) defining a weighting function for a forcing function. As with bwtlist, each of these weighting functions may be estimated or held fixed. If the number of forcing functions actually varies from equation to equation, one can still use all forcing functions for all variables, but just weight unwanted ones in a particular equation by a fixed zero function.

Each member's functional data object has only a single replicate.

ufdlist

a list containing forcing functions. This is a list array of the same size as awtlist and each member is a functional data object corresponding to a forcing function. The number of replicates must be equal to that of the variables themselves, which is assumed to be the same for all variables.

nfine

a number of values for a fine mesh. The estimation of the differential equation involves discrete numerical quadrature estimates of integrals,

and these require that functions be evaluated at a fine mesh of values of the argument. This argument defines the number to use. If not constant, this number is set to five times the largest number of basis functions used to represent any variable in the system.

Value

a named list of length 3 with components:

bwtlist a list array of the same dimensions as the corresponding argument, con-

taining the estimated or fixed weight functions defining the system of

linear differential equations.

resfdlist a list of length equal to the number of variables or equations. Each mem-

bers is a functional data object giving the residual functions or forcing functions defined as the left side of the equation (the derivative of order m of a variable) minus the linear fit on the right side. The number of replicates for each residual functional data object is the same as that for

the variables.

awtlist a list of the same dimensions as the corresponding argument. Each mem-

ber is an estimated or fixed weighting function for a forcing function.

See Also

```
pca.fd, cca.fd
```

Examples

#See analyses of daily weather data for examples.

phaseplanePlot

Phase-plane plot

Description

Plot acceleration (or Ldfobj2) vs. velocity (or Lfdobj1) of a function data object.

Usage

Arguments

evalarg	a vector of argument values at which the functional data object is to be evaluated.
	Defaults to a sequence of 181 points in the range specified by fdobj[["basis"]][["rangeval"]]. If(length(evalarg) == 1)it is replaced by seq(evalarg[1], evalarg[1]+1, length=181). If(length(evalarg) == 2)it is replaced by seq(evalarg[1], evalarg[2], length=181).
fdobj	a functional data object to be evaluated.
Lfdobj1	either a nonnegative integer or a linear differential operator object. The points plotted on the horizontal axis are eval.fd(evalarg, fdobj, Lfdobj1). By default, this is the velocity.
Lfdobj2	either a nonnegative integer or a linear differential operator object. The points plotted on the vertical axis are eval.fd(evalarg, fdobj, Lfdobj2). By default, this is the acceleration.
lty	line types for the first and second halves of the plot.
labels	a list of length two:
	evalarg = a numeric vector of 'evalarg' values to be labeled.
	labels = a character vector of labels, replicated to the same length as labels[["evalarg"]] in case it's not of the same length.
abline	arguments to a call to abline.
xlab	x axis label
ylab	y axis label

Value

Invisibly returns a matrix with two columns containg the points plotted.

optional arguments passed to plot.

See Also

```
plot, eval.fd plot.fd
```

Examples

pinch

pinch force data

Description

151 measurements of pinch force during 20 replications, registered, with time from start of measurement.

Usage

```
pinch
pinchtime
```

Format

pinch Matrix of dimension c(151, 20) = 20 replications of measuring pinch force every 2 milliseconds for 300 milliseconds.

pinchtime time in seconds from the start = seq(0, 0.3, 151) = every 2 milliseconds.

Details

Measurements every 2 milliseconds.

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York, p. 13, Figure 1.11, pp. 22-23, Figure 2.2, and p. 144, Figure 7.13.

Examples

```
plot(pinchtime, pinch[, 1], type="b")
```

plot.basisfd

Plot a Basis Object

Description

Plots all the basis functions.

Usage

```
plot.basisfd(x, knots=TRUE, ...)
```

Arguments

x a basis object

knots logical: If TRUE and x[['type']] == 'bslpine', the knot locations are plot-

ted using vertical dotted, red lines. Ignored otherwise.

... additional plotting parameters passed to matplot.

Value

none

Side Effects

a plot of the basis functions

See Also

```
plot.fd
```

Examples

```
# set up the b-spline basis for the lip data, using 23 basis functions,
# order 4 (cubic), and equally spaced knots.
# There will be 23 - 4 = 19 interior knots at 0.05, ..., 0.95
lipbasis <- create.bspline.basis(c(0,1), 23)
# plot the basis functions
plot(lipbasis)</pre>
```

plot.fd

Plot a Functional Data Object

Description

Functional data observations, or a derivative of them, are plotted. These may be either plotted simultaneously, as matplot does for multivariate data, or one by one with a mouse click to move from one plot to another. The function also accepts the other plot specification arguments that the regular plot does. Calling plot with an fdSmooth object is simply plots its codefd component.

Usage

<pre>xlim=NULL,</pre>	<pre>ylim=NULL,</pre>	xlab=NULL,	
vlab=NULL.	ask=FALSE.	nx=201)	

Arguments

x	functional data object(s) to be plotted.
у	sequence of points at which to evaluate the functions 'x' and plot on the horizontal axis. Defaults to $seq(rangex[1], rangex[2], length = nx)$. NOTE: This will be the values on the horizontal axis, NOT the vertical axis.
Lfdobj	either a nonnegative integer or a linear differential operator object. If present, the derivative or the value of applying the operator is plotted rather than the functions themselves.
href	a logical variable: If ${\tt TRUE},$ add a horizontal reference line at 0.
titles	a vector of strings for identifying curves
xlab	a label for the horizontal axis.
ylab	a label for the vertical axis.
xlim	a vector of length 2 containing axis limits for the horizontal axis.
ylim	a vector of length 2 containing axis limits for the vertical axis.
ask	a logical value: If ${\tt TRUE},$ each curve is shown separately, and the plot advances with a mouse click
nx	the number of points to use to define the plot. The default is usually enough, but for a highly variable function more may be required.
	additional plotting arguments that can be used with function plot

Details

Note that for multivariate data, a suitable array must first be defined using the par function.

Value

'done'

Side Effects

a plot of the functional observations

${\bf See}~{\bf Also}$

```
lines.fd, plotfit.fd
```

Examples

```
##
## plot.df
##
#daytime
          <- (1:365)-0.5
#dayrange <- c(0,365)
#dayperiod <- 365
#nbasis
           <- 65
#dayrange <- c(0,365)
daybasis65 <- create.fourier.basis(c(0, 365), 65)</pre>
harmaccelLfd \leftarrow vec2Lfd(c(0,(2*pi/365)^2,0), c(0, 365))
harmfdPar
              <- fdPar(daybasis65, harmaccelLfd, lambda=1e5)
daytempfd <- with(CanadianWeather, data2fd(</pre>
        dailyAv[,,"Temperature.C"], day.5,
        daybasis65,argnames=list("Day", "Station", "Deg C")) )
# plot all the temperature functions for the monthly weather data
plot(daytempfd, main="Temperature Functions")
## Not run:
# To plot one at a time:
# The following pauses to request page changes.
plot(daytempfd, main="Temperature Functions", ask=TRUE)
## End(Not run)
## plot.fdSmooth
##
b3.4 <- create.bspline.basis(norder=3, breaks=c(0, .5, 1))
# 4 bases, order 3 = degree 2 =
# continuous, bounded, locally quadratic
fdPar3 <- fdPar(b3.4, lambda=1)
# Penalize excessive slope Lfdobj=1;
# second derivative Lfdobj=2 is discontinuous.
fd3.4s0 <- smooth.basis(0:1, 0:1, fdPar3)
# using plot.fd directly
plot(fd3.4s0$fd)
# same plot via plot.fdSmooth
plot(fd3.4s0)
```

plot.lmWinsor

lmWinsor plot

Description

plot an lmWinsor model or list of models as line(s) with the data as points

Usage

```
## S3 method for class 'lmWinsor':
plot(x, n=101, lty=1:9, col=1:9,
         lwd=c(2:4, rep(3, 6)), lty.y=c('dotted', 'dashed'),
         lty.x = lty.y, col.y=1:9, col.x=col.y, lwd.y = c(1.2, 1),
         lwd.x=lwd.y, ...)
```

Arguments

an object of class 'lmWinsor', which is either a list of objects of class c('lmWinsor', 'lm') or is a single object of that double class. Each object of class c('lmWinsor', 'lm') is the result of a single 'lmWinsor' fit. If 'x' is a list, it summarizes multiple fits with different limits to the same data.

n

integer; with only one explanatory variable 'xNames' in the model, 'n' is the number of values at which to evaluate the model predictions. This is ignored if the number of explanatory variable 'xNames' in the model is different from 1.

lty, col, lwd, lty.y, lty.x, col.y, col.x, lwd.y, lwd.x

'lty', 'col' and 'lwd' are each replicated to a length matching the number of fits summarized in 'x' and used with one line for each fit in the order appearing in 'x'. The others refer to horizontal and vertical limit lines.

optional arguments for 'plot'

Details

- 1. One fit or several?
- 2. How many explanatory variables are involved in the model(s) in 'x'? If only one, then the response variable is plotted vs. that one explanatory variable. Otherwise, the response is plotted vs. predictions.
- 3. Plot the data.
- 4. Plot one line for each fit with its limits.

Value

```
invisible(NULL)
```

Author(s)

Spencer Graves

See Also

lmWinsor plot

Examples

```
lm.1 <- lmWinsor(y1~x1, data=anscombe)
plot(lm.1)
plot(lm.1, xlim=c(0, 15), main="other title")

# list example
lm.1. <- lmWinsor(y1~x1, data=anscombe, trim=c(0, 0.25, .4, .5))
plot(lm.1.)</pre>
```

plot.pca.fd

Plot Functional Principal Components

Description

Display the types of variation across a sample of functions. Label with the eigenvalues that indicate the relative importance of each mode of variation.

Usage

Arguments

a functional data object. nx Number of points to plot or vector (if length > 1) to use as evalarg in evaluating and plotting the functional principal components. logical: If TRUE, the harmonics / principal components are plotted as pointplot '+' and '-'. Otherwise lines are used. Harmonics / principal components to plot. If 0, plot all. harm If length(harm) > sum(par("mfrow")), the user advised, "Waiting to confirm page change..." and / or 'Click or hit ENTER for next page' for each page after the first. nonnegative real: If expand == 0 then effect of +/-2 standard deviations expand of each pc are given otherwise the factor expand is used. logical: If cycle=TRUE and there are 2 variables then a cycle plot will be cycle drawn If the number of variables is anything else, cycle will be ignored.

Details

Produces one plot for each principal component / harmonic to be plotted.

other arguments for 'plot'.

Value

invisible(NULL)

See Also

```
cca.fd, pda.fd plot.pca.fd
```

Examples

plotfit

Plot a Functional Data Object With Data

Description

Plot either functional data observations 'x' with a fit 'fdobj' or residuals from the fit.

This function is useful for assessing how well a functional data object fits the actual discrete data.

The default is to make one plot per functional observation with fit if residual is FALSE and superimposed lines if residual==TRUE.

With multiple plots, the system waits to confirm a desire to move to the next page unless ask==FALSE.

Usage

```
nfine = 101, residual = FALSE, sortwrd = FALSE, titles=NULL,
ylim=NULL, ask=TRUE, type=c("p", "l")[1+residual],
xlab=NULL, ylab=NULL, sub=NULL, col=1:9, lty=1:9, lwd=1,
cex.pch=1, ...)
```

Arguments

У	a vector, matrix or array containing the discrete observations used to estimate the functional data object. $$
argvals	a vector containing the argument values corresponding to the first dimension of ${\tt y}.$
fdobj	a functional data object estimated from the data.
fdSm	an object of class fdSmooth
rng	a vector of length 2 specifying the limits for the horizontal axis. This must be a subset of $fdobj[['basis']][['rangeval']]$, which is the default.
index	a set of indices of functions if only a subset of the observations are to be plotted. Subsetting can also be achieved by subsetting y ; see $\mathtt{details}$, below.
nfine	the number of argument values used to define the plot of the functional data object. This may need to be increased if the functions have a great deal of fine detail.
residual	a logical variable: if ${\tt TRUE},$ the residuals are plotted rather than the data and functional data object.
sortwrd	a logical variable: if TRUE, the observations (i.e., second dimension of y) are sorted for plotting by the size of the sum of squared residuals.
titles	a vector containing strings that are titles for each observation.
ylim	a numeric vector of length 2 giving the y axis limits; see 'par'.
ask	If TRUE and if 'y' has more levels than the max length of col, lty, lwd and cex.pch, the user must confirm page change before the next plot will be created.
type	type of plot desired, as described with $\verb"plot"$. If residual $==$ FALSE, 'type' controls the representation for 'x', which will typically be 'p' to plot points but not lines; 'fdobj' will always plot as a line. If residual $==$ TRUE, the default type $==$ "l"; an alternative is "b" for both.
xlab	x axis label.
ylab	Character vector of y axis labels. If (residual), ylab defaults to 'Residuals', else to varnames derived from $\mathrm{names}(\mathrm{fdnames}[[3]]$ or $\mathrm{fdnames}[[3]]$ or $\mathrm{dimnames}(y)[[3]].$
sub	subtitle under the x axis label. Defaults to the RMS residual from the smooth.
col, lty, lwd,	cex.pch Numeric or character vectors specifying the color (col), line type (lty), line width (lwd) and size of plotted character symbols (cex.pch) of the data representation on the plot.

If ask==TRUE, the length of the longest of these determines the number of levels of the array 'x' in each plot before asking the user to acknowledge a desire to change to the next page. Each of these is replicated to that length, so col[i] is used for x[,i] (if x is 2 dimensional), with line type and width controlled by lty[i] and lwd[i], respectively.

If ask==FALSE, these are all replicated to length = the number of plots to be superimposed.

For more information on alternative values for these paramters, see 'col', 'lty', 'lwd', or 'cex' with par.

additional arguments such as axis labels that may be used with other plot functions.

Details

. . .

plotfit plots discrete data along with a functional data object for fitting the data. It is designed to be used after something like data2fd, smooth.fd, smooth.basis or smoothe.basisPar to check the fit of the data offered by the fd object.

plotfit.fdSmooth calls plotfit for its 'fd' component.

The plot can be restricted to a subset of observations (i.e., second dimension of y) or variables (i.e., third dimension of y) by providing y with the dimnames for its second and third dimensions matching a subset of the dimnames of fdobj[['coef']] (for plotfit.fd or fdSm[['fdobj']][['coef']] for plotfit.fdSmooth). If only one observation or variable is to be plotted, y must include 'drop = TRUE', as, e.g., y[, 2, 3, drop=TRUE]. If y or fdobj[['coef']] does not have dimnames on its second or third dimension, subsetting is acheived by taking the first few colums so the second or third dimensions match. This is acheived using fdobj[['coef']], fdobj[['coef']]

Value

A matrix of mean square deviations from predicted is returned invisibly. If fdobj[["coefs"]] is a 3-dimensional array, this is a matrix of dimensions equal to the last two dimensions of fdobj[["coefs"]]. This will typically be the case when x is also a 3-dimensional array with the last two dimensions matching those of fdobj[["coefs"]]. The second dimension is typically replications and the third different variables.

If x and fobj[["coefs"]] are vectors or 2-dimensional arrays, they are padded to three dimensions, and then MSE is computed as a matrix with the second dimension = 1; if x and fobj[["coefs"]] are vectors, the first dimension of the returned matrix will also be 1.

Side Effects

a plot of the the data 'x' with the function or the deviations between observed and predicted, depending on whether residual is FALSE or TRUE.

See Also

plot, plot.fd, lines.fd plot.fdSmooth, lines.fdSmooth par data2fd smooth.fd smooth.basis
smooth.basisPar checkDims3

```
daybasis65 <- create.fourier.basis(c(0, 365), 65)</pre>
daytempfd <- with(CanadianWeather, data2fd(</pre>
       dailyAv[,,"Temperature.C"], day.5,
       daybasis65, argnames=list("Day", "Station", "Deg C")) )
with(CanadianWeather, plotfit.fd(dailyAv[, , "Temperature.C"],
     argvals= day.5, daytempfd, index=1, titles=place, axes=FALSE) )
# Default ylab = daytempfd[['fdnames']]
with(CanadianWeather, plotfit.fd(dailyAv[, , "Temperature.C", drop=FALSE],
     argvals= day.5, daytempfd, index=1, titles=place, axes=FALSE) )
# Better: ylab = dimnames(y)[[3]]
# Label the horizontal axis with the month names
axis(1, monthBegin.5, labels=FALSE)
axis(1, monthEnd.5, labels=FALSE)
axis(1, monthMid, monthLetters, tick=FALSE)
axis(2)
## Not run:
# The following pauses to request page changes.
# (Without 'dontrun', the package build process
# might encounter problems with the par(ask=TRUE)
# feature.)
with(CanadianWeather, plotfit.fd(
          dailyAv[,, "Temperature.C"], day.5,
          daytempfd, ask=TRUE) )
## End(Not run)
# If you want only the fitted functions, use plot(daytempfd)
# To plot only a single fit vs. observations, use index
# to request which one you want.
op <- par(mfrow=c(2,1), xpd=NA, bty="n")
# xpd=NA: clip lines to the device region,
        not the plot or figure region
# bty="n": Do not draw boxes around the plots.
ylim <- range(CanadianWeather$dailyAv[,,"Temperature.C"])</pre>
# Force the two plots to have the same scale
with(CanadianWeather, plotfit.fd(dailyAv[,,"Temperature.C"], day.5,
          daytempfd, index=2, titles=place, ylim=ylim, axes=FALSE) )
axis(1, monthBegin.5, labels=FALSE)
axis(1, monthEnd.5, labels=FALSE)
axis(1, monthMid, monthLetters, tick=FALSE)
axis(2)
with(CanadianWeather, plotfit.fd(dailyAv[,,"Temperature.C"], day.5,
          daytempfd, index=35, titles=place, ylim=ylim) )
axis(1, monthBegin.5, labels=FALSE)
```

plotscores

Plot Principal Component Scores

Description

The coefficients multiplying the harmonics or principal component functions are plotted as points.

Usage

Arguments

pcafd	an object of the "pca.fd" class that is output by function pca.fd.
scores	the indices of the harmonics for which coefficients are plotted.
xlab	a label for the horizontal axis.
ylab	a label for the vertical axis.
loc	an integer: if loc >0 , you can then click on the plot in loc places and you'll get plots of the functions with these values of the principal component coefficients.
matplt2	a logical value: if TRUE, the curves are plotted on the same plot; otherwise, they are plotted separately. $$
	additional plotting arguments used in function plot.

Side Effects

a plot of scores

See Also

pca.fd

polyg

Polygonal Basis Function Values

Description

Evaluates a set of polygonal basis functions, or a derivative of these functions, at a set of arguments.

Usage

```
polyg(x, argvals, nderiv=0)
```

Arguments

x a vector of argument values at which the polygonal basis functions are to

evaluated.

argvals a strictly increasing set of argument values containing the range of x

within it that defines the polygonal basis. The default is x itself.

nderiv the order of derivative to be evaluated. The derivative must not exceed

one. The default derivative is 0, meaning that the basis functions them-

selves are evaluated.

Value

a matrix of function values. The number of rows equals the number of arguments, and the number of columns equals the number of basis

See Also

```
create.polygonal.basis, polygpen
```

```
# set up a set of 21 argument values x \leftarrow seq(0,1,0.05) # set up a set of 11 argument values argvals \leftarrow seq(0,1,0.1) # with the default period (1) and derivative (0) basismat \leftarrow polyg(x, argvals) # plot the basis functions matplot(x, basismat, type="l")
```

Polygonal Penalty Matrix

polygpen

Description

Computes the matrix defining the roughness penalty for functions expressed in terms of a polygonal basis.

Usage

```
polygpen(basisobj, Lfdobj=int2Lfd(1))
```

Arguments

basisobj a polygonal functional basis object.

Lfdobj either an integer that is either 0 or 1, or a linear differential operator

object of degree 0 or 1.

Details

a roughness penalty for a function x(t) is defined by integrating the square of either the derivative of x(t) or, more generally, the result of applying a linear differential operator L to it. The only roughness penalty possible aside from penalizing the size of the function itself is the integral of the square of the first derivative, and this is the default. To apply this roughness penalty, the matrix of inner products produced by this function is necessary.

Value

a symmetric matrix of order equal to the number of basis functions defined by the polygonal basis object. Each element is the inner product of two polygonal basis functions after applying the derivative or linear differential operator defined by Lfdobj.

See Also

```
create.polygonal.basis, polyg
```

```
# set up a sequence of 11 argument values
argvals <- seq(0,1,0.1)
# set up the polygonal basis
basisobj <- create.polygonal.basis(argvals)
# compute the 11 by 11 penalty matrix
# The following should work but doesn't; 2007.05.01
#penmat <- polygpen(basisobj)</pre>
```

Power Basis Function Values

powerbasis

Description

Evaluates a set of power basis functions, or a derivative of these functions, at a set of arguments.

Usage

```
powerbasis(x, exponents, nderiv=0)
```

Arguments

x a vector of argument values at which the power basis functions are to eval-

uated. Since exponents may be negative, for example after differentiation,

it is required that all argument values be positive.

exponents a vector of exponents defining the power basis functions. If y is such a

rate value, the corresponding basis function is x to the power y. The

number of basis functions is equal to the number of exponents.

nderiv the derivative to be evaluated. The derivative must not exceed the order.

The default derivative is 0, meaning that the basis functions themselves

are evaluated.

Value

a matrix of function values. The number of rows equals the number of arguments, and the number of columns equals the number of basis functions.

See Also

```
create.power.basis, powerpen
```

```
# set up a set of 10 positive argument values. x \leftarrow seq(0.1,1,0.1) # compute values for three power basis functions exponents <- c(0, 1, 2) # evaluate the basis matrix basismat <- powerbasis(x, exponents)
```

Power Penalty Matrix

powerpen

Description

Computes the matrix defining the roughness penalty for functions expressed in terms of a power basis.

Usage

```
powerpen(basisobj, Lfdobj=int2Lfd(2))
```

Arguments

basisobj a power basis object.

Lfdobj either a nonnegative integer or a linear differential operator object.

Details

A roughness penalty for a function x(t) is defined by integrating the square of either the derivative of x(t) or, more generally, the result of applying a linear differential operator L to it. The most common roughness penalty is the integral of the square of the second derivative, and this is the default. To apply this roughness penalty, the matrix of inner products produced by this function is necessary.

Value

a symmetric matrix of order equal to the number of basis functions defined by the power basis object. Each element is the inner product of two power basis functions after applying the derivative or linear differential operator defined by Lfdobj.

See Also

```
create.power.basis, powerbasis
```

```
# set up an power basis with 3 basis functions.
# the powers are 0, 1, and 2.
basisobj <- create.power.basis(c(0,1),3,c(0,1,2))
# compute the 3 by 3 matrix of inner products of second derivatives
#FIXME
#penmat <- powerpen(basisobj, 2)</pre>
```

Predict method for Winsorized linear model fits with mixed effects

predict.lmeWinsor

Description

Model predictions for object of class 'lmeWinsor'.

Usage

Arguments

level

object	Object of class inheriting from 'lmeWinsor', representing a fitted linear mixed-effects model.
newdata	an optional data frame to be used for obtaining the predictions. All variables used in the fixed and random effects models, as well as the grouping factors, must be present in the data frame. If missing, the fitted values are returned.

an optional integer vector giving the level(s) of grouping to be used in obtaining the predictions. Level values increase from outermost to innermost grouping, with level zero corresponding to the population predictions. De-

faults to the highest or innermost level of grouping.

as List an optional logical value. If 'TRUE' and a single value is given in 'level',

the returned object is a list with the predictions split by groups; else the returned value is either a vector or a data frame, according to the length

of 'level'.

na.action a function that indicates what should happen when 'newdata' contains

'NA's. The default action ('na.fail') causes the function to print an error

message and terminate if there are any incomplete observations.

... additional arguments for other methods

Details

- 1. Identify inputs and outputs as with lmeWinsor.
- 2. If 'newdata' are provided, clip all numeric xNames to (object[["lower"]], object[["upper"]]).
- 3. Call predict.lme
- 4. Clip the responses to the relevant components of (object[["lower"]], object[["upper"]]).
- 5. Done.

Value

'predict.lmeWinsor' produces a vector of predictions or a matrix of predictions with limits or a list, as produced by predict.lme

Author(s)

Spencer Graves

See Also

lmeWinsor predict.lme lmWinsor predict.lm

Examples

predict.lmWinsor

Predict method for Winsorized linear model fits

Description

Model predictions for object of class 'lmWinsor'.

Usage

```
## S3 method for class 'lmWinsor':
predict(object, newdata, se.fit = FALSE,
    scale = NULL, df = Inf,
    interval = c("none", "confidence", "prediction"),
    level = 0.95, type = c("response", "terms"),
    terms = NULL, na.action = na.pass,
    pred.var = res.var/weights, weights = 1, ...)
```

Arguments

object Object of class inheriting from 'lmWinsor'

newdata An optional data frame in which to look for variables with which to predict. If omitted, the fitted values are used.

se.fit a switch indicating if standard errors of predictions are required

scale Scale parameter for std.err. calculation

df degrees of freedom for scale

interval type of prediction (response or model term)

level Tolerance/confidence level

type Type of prediction (response or model term); see predict.lm

terms If 'type="terms", which terms (default is all terms)

na.action function determining what should be done with missing values in 'new-

data'. The default is to predict 'NA'.

pred.var the variance(s) for future observations to be assumed for prediction inter-

vals. See predict.lm 'Details'.

weights variance weights for prediction. This can be a numeric vector or a one-

sided model formula. In the latter case, it is interpreted as an expression

evaluated in 'newdata'

... additional arguments for other methods

Details

1. Identify inputs and outputs via mdly <- mdlx <- formula(object); mdly[[3]] <- NULL; mdlx[[2]] <- NULL; xNames <- all.vars(mdlx); yNames <- all.vars(mdly). Give an error if as.character(mdly[[2]]) != yNames.

- 2. If 'newdata' are provided, clip all xNames to (object[["lower"]], object[["upper"]]).
- 3. Call predict.lm
- 4. Clip the responses to the relevant components of (object[["lower"]], object[["upper"]]).
- 5. Done.

Value

'predict.lmWinsor' produces a vector of predictions or a matrix of predictions with limits or a list, as produced by predict.lm

Author(s)

Spencer Graves

See Also

lmWinsor predict.lm

```
# example from 'anscombe'
lm.1 <- lmWinsor(y1~x1, data=anscombe)
newD <- data.frame(x1=seq(1, 22, .1))
predW <- predict(lm.1, newdata=newD)
plot(y1~x1, anscombe, xlim=c(1, 22))</pre>
```

```
lines(newD[["x1"]], predW, col='blue')
abline(h=lm.1[['lower']]['y1'], col='red', lty='dashed')
abline(h=lm.1[['upper']]['y1'], col='red', lty='dashed')
abline(v=lm.1[['lower']]['x1'], col='green', lty='dashed')
abline(v=lm.1[['upper']]['x1'], col='green', lty='dashed')
```

project.basis

Approximate Functional Data Using a Basis

Description

A vector or matrix of discrete data is projected into the space spanned by the values of a set of basis functions. This amounts to a least squares regression of the data on to the values of the basis functions. A small penalty can be applied to deal with stiautions in which the number of basis functions exceeds the number of basis points. This function is used with function data2fd, and is not normally used directly in a functional data analysis.

Usage

```
project.basis(y, argvals, basisobj, penalize=FALSE)
```

Arguments

y a vector or matrix of discrete data.

arguals a vector containing the argument values correspond to the values in y.

basisobj a basis object.

penalize a logical variable. If TRUE, a small roughness penalty is applied to ensure

that the linear equations defining the least squares solution are linearly

independent or nonsingular.

Value

the matrix of coefficients defining the least squares approximation. This matrix has as many rows are there are basis functions, as many columns as there are curves, and if the data are multivariate, as many layers as there are functions.

See Also

data2fd

Quadrature points and weights for Simpson's rule

quadset

Description

Set up quadrature points and weights for Simpson's rule.

Usage

```
quadset(nquad=5, basisobj=NULL, breaks)
```

Arguments

nquad an odd integer at least 5 giving the number of evenly spaced Simpson's

rule quadrature points to use over each interval (breaks[i], breaks[i+1]).

basisobj the basis object that will contain the quadrature points and weights

breaks optional interval boundaries. If this is provided, the first value must be

the initial point of the interval over which the basis is defined, and the final value must be the end point. If this is not supplied, and 'basisobj'

is of type 'bspline', the knots are used as these values.

Details

Set up quadrature points and weights for Simpson's rule and store information in the output 'basisobj'. Simpson's rule is used to integrate a function between successive values in vector 'breaks'. That is, over each interval (breaks[i], breaks[i+1]). Simpson's rule uses 'nquad' equally spaced quadrature points over this interval, starting with the the left boundary and ending with the right boundary. The quadrature weights are the values delta*c(1,4,2,4,2,4,...,2,4,1) where 'delta' is the difference between successive quadrature points, that is, delta = (breaks[i-1]-breaks[i])/(nquad-1).

Value

If is.null(basisobj), quadset returns a 'quadvals' matrix with columns quadpts and quadwts. Otherwise, it returns basisobj with the two components set as follows:

quadvals cbind(quadpts=quadpts, quadwts=quadwts)

value a list with two components containing eval.basis(quadpts, basisobj, ival-1)

for ival=1, 2.

See Also

create.bspline.basis eval.basis

Examples

```
(qs7.1 <- quadset(nquad=7, breaks=c(0, .3, 1)))
# cbind(quadpts=c(seq(0, 0.3, length=7),
               seq(0.3, 1, length=7)),
#
     quadwts=c((0.3/18)*c(1, 4, 2, 4, 2, 4, 1),
               (0.7/18)*c(1, 4, 2, 4, 2, 4, 1))
# The simplest basis currently available with this function:
bspl2.2 <- create.bspline.basis(norder=2, breaks=c(0,.5, 1))
bspl2.2a <- quadset(basisobj=bspl2.2)</pre>
bspl2.2a$quadvals
# cbind(quadpts=c((0:4)/8, .5+(0:4)/8),
        quadwts=rep(c(1,4,2,4,1)/24, 2))
bspl2.2a$values
# a list of length 2
# [[1]] = matrix of dimension c(10, 3) with the 3 basis
       functions evaluated at the 10 quadrature points:
\# \text{ values}[[1]][, 1] = c(1, .75, .5, .25, rep(0, 6))
\# \text{ values}[[1]][, 2] = c(0, .25, .5, .75, 1, .75, .5, .25, 0)
 values[[1]][, 3] = values[10:1, 1]
 values[[2]] = matrix of dimension c(10, 3) with the
      first derivative of values[[1]], being either
     -2, 0, or 2.
```

refinery

Reflux and tray level in a refinery

Description

194 observations on reflux and "tray 47 level" in a distallation column in an oil refinery.

Format

A data frame with the following components:

Time observation time 0:193

Reflux reflux flow centered on the mean of the first 60 observations

Tray47 tray 47 level centered on the mean of the first 60 observations

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York, p. 4, Figure 1.4, and chapter 17.

Examples

```
attach(refinery)
# allow space for an axis on the right
    op \leftarrow par(mar=c(5, 4, 4, 5)+0.1)
# plot uval
    plot(Time, Reflux, type="l", bty="n")
# add yval
    y.u <- diff(range(Tray47))/diff(range(Reflux))</pre>
    u0 <- min(Reflux)
    y0 <- min(Tray47)
    lines(Time, u0+(Tray47-y0)/y.u, lty=3, lwd=1.5, col="red")
    y.tick <- pretty(range(Tray47))</pre>
    axis(4, at=u0+(y.tick)/y.u, labels=y.tick, col="red", lty=3,
            lwd=1.5)
# restore previous plot margins
    par(op)
    detach(refinery)
```

register.fd

Register Functional Data Objects Using a Continuous Criterion

Description

criterion. By aligned is meant that the shape of each curve is matched as closely as possible to that of the target by means of a smooth increasing transformation of the argument, or a warping function.

Usage

```
register.fd(y0fd=NULL, yfd=NULL, WfdParobj=c(Lfdobj=2, lambda=1),
            conv=1e-04, iterlim=20, dbglev=1, periodic=FALSE, crit=2)
```

Arguments

y0fd

a functional data object defining the target for registration.

If yfd is NULL and y0fd is a multivariate data object, then y0fd is as-

signed to yfd and y0fd is replaced by its mean.

Alternatively, if yfd is a multivariate functional data object and y0fd is missing, y0fd is replaced by the mean of y0fd.

Otherwise, y0fd must be a univariate functional data object taken as the

target to which yfd is registered.

yfd

a multivariate functional data object defining the functions to be registered to target yofd. If it is NULL and yofd is a multivariate functional

data object, yfd takes the value of y0fd.

WfdParobi

a functional parameter object for a single function. This is used as the initial value in the estimation of a function W(t) that defines the warping function h(t) that registers a particular curve. The object also contains information on a roughness penalty and smoothing parameter to control the roughness of h(t).

Alternatively, this can be a vector or a list with components named Lfdobj and lambda, which are passed as arguments to fdPar to create the functional parameter form of WfdParobj required by the rest of the register.fd algorithm.

The default Lfdobj of 2 penalizes curvature, thereby preferring no warping of time, with lambda indicating the strength of that preference. A common alternative is Lfdobj = 3, penalizing the rate of change of curvature

conv a criterion for convergence of the iterations.

iterlim a limit on the number of iterations.

dbglev either 0, 1, or 2. This controls the amount information printed out on

each iteration, with 0 implying no output, 1 intermediate output level, and 2 full output. (If this is run with output buffering such as used with S-Plus, it may be necessary to turn off the output buffering to actually

get the progress reports before the completion of computations.)

periodic a logical variable: if TRUE, the functions are considered to be periodic, in

which case a constant can be added to all argument values after they are

warped.

crit an integer that is either 1 or 2 that indicates the nature of the continuous

registration criterion that is used. If 1, the criterion is least squares, and if 2, the criterion is the minimum eigenvalue of a cross-product matrix.

In general, criterion 2 is to be preferred.

Details

The warping function that smoothly and monotonely transforms the argument is defined by Wfd is the same as that defines the monotone smoothing function in for function smooth.monotone. See the help file for that function for further details.

Value

a named list of length 3 containing the following components:

regfd A functional data object containing the registered functions.

Wfd A functional data object containing the functions hW(t) that define the

warping functions h(t).

shift If the functions are periodic, this is a vector of time shifts.

Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York, ch. 6 & 7.

See Also

```
smooth.monotone, smooth.morph
```

```
#See the analyses of the growth data for examples.
## 1. Simplest call
##
# Specify smoothing weight
lambda.gr2.3 <- .03
# Specify what to smooth, namely the rate of change of curvature
Lfdobj.growth
                 <- 2
# Establish a B-spline basis
nage <- length(growth$age)</pre>
norder.growth <- 6
nbasis.growth <- nage + norder.growth - 2</pre>
rng.growth <- range(growth$age)</pre>
# 1 18
wbasis.growth <- create.bspline.basis(rangeval=rng.growth,
                    nbasis=nbasis.growth, norder=norder.growth,
                    breaks=growth$age)
# Smooth consistent with the analysis of these data
# in afda-ch06.R, and register to individual smooths:
cvec0.growth <- matrix(0,nbasis.growth,1)</pre>
Wfd0.growth <- fd(cvec0.growth, wbasis.growth)
growfdPar2.3 <- fdPar(Wfd0.growth, Lfdobj.growth, lambda.gr2.3)</pre>
# Create a functional data object for all the boys
hgtmfd.all <- with(growth, smooth.basis(age, hgtm, growfdPar2.3))</pre>
nBoys <- 2
# nBoys <- dim(growth[["hgtm"]])[2]</pre>
# register.fd takes time, so use only 2 curves as an illustration
# to minimize compute time in this example;
#Alternative to subsetting later is to subset now:
#hgtmfd.all<-with(growth,smooth.basis(age, hgtm[,1:nBoys],growfdPar2.3))</pre>
# Register the growth velocity rather than the
# growth curves directly
smBv <- deriv(hgtmfd.all$fd, 1)
# This takes time, so limit the number of curves registered to nBoys
## Not run:
smB.reg.0 <- register.fd(smBv[1:nBoys])</pre>
```

```
smB.reg.1 <- register.fd(smBv[1:nBoys],WfdParobj=c(Lfdobj=Lfdobj.growth, lambda=lambda.gr2.3))
##
## 2. Call providing the target
smBv.mean <- deriv(mean(hgtmfd.all$fd[1:nBoys]), 1)</pre>
smB.reg.2a <- register.fd(smBv.mean, smBv[1:nBoys],</pre>
               WfdParobj=c(Lfdobj=Lfdobj.growth, lambda=lambda.gr2.3))
smBv.mean <- mean(smBv[1:nBoys])</pre>
smB.reg.2 <- register.fd(smBv.mean, smBv[1:nBoys],</pre>
               WfdParobj=c(Lfdobj=Lfdobj.growth, lambda=lambda.gr2.3))
all.equal(smB.reg.1, smB.reg.2)
##
## 3. Call using WfdParobj
# Create a dummy functional data object
# to hold the functional data objects for the
# time warping function
# ... start with a zero matrix (nbasis.growth, nBoys)
smBc0 <- matrix(0, nbasis.growth, nBoys)</pre>
# ... convert to a functional data object
smBwfd0 <- fd(smBc0, wbasis.growth)</pre>
# ... convert to a functional parameter object
smB.wfdPar <- fdPar(smBwfd0, Lfdobj.growth, lambda.gr2.3)</pre>
smB.reg.3<- register.fd(smBv[1:nBoys], WfdParobj=smB.wfdPar)</pre>
all.equal(smB.reg.1, smB.reg.3)
## End(Not run)
```

sd.fd

Standard Deviation of Functional Data

Description

Evaluate the standard deviation of a set of functions in a functional data object.

Usage

```
sd.fd(fdobj)
std.fd(fdobj)
stdev.fd(fdobj)
stddev.fd(fdobj)
```

Arguments

fdobj a functional data object.

Details

The multiple aliases are provided for compatibility with previous versions and with other languages. The name for the standard deviation function in R is 'sd'. Matlab uses 'std'. S-Plus and Microsoft Excal use 'stdev'. 'stddev' was used in a previous version of the 'fda' package and is retained for compatibility.

Value

a functional data object with a single replication that contains the standard deviation of the one or several functions in the object fdobj.

See Also

```
mean.fd, sum.fd, center.fd
```

```
liptime \leftarrow seq(0,1,.02)
liprange <- c(0,1)
  ----- create the fd object -----
        use 31 order 6 splines so we can look at acceleration
nbasis <- 51
norder <- 6
lipbasis <- create.bspline.basis(liprange, nbasis, norder)</pre>
lipbasis <- create.bspline.basis(liprange, nbasis, norder)</pre>
  ----- apply some light smoothing to this object -----
Lfdobj
        <- int2Lfd(4)
lambda
        <- 1e-12
lipfdPar <- fdPar(lipbasis, Lfdobj, lambda)</pre>
lipfd <- smooth.basis(liptime, lip, lipfdPar)$fd</pre>
names(lipfd$fdnames) = c("Normalized time", "Replications", "mm")
lipstdfd <- sd.fd(lipfd)</pre>
plot(lipstdfd)
all.equal(lipstdfd, std.fd(lipfd))
all.equal(lipstdfd, stdev.fd(lipfd))
all.equal(lipstdfd, stddev.fd(lipfd))
```

Description

This is the main function for smoothing data using a roughness penalty. Unlike function data2fd, which does not employ a rougness penalty, this function controls the nature and degree of smoothing by penalyzing a measure of rougness. Roughness is definable in a wide variety of ways using either derivatives or a linear differential operator.

Usage

Arguments

	a reaction of anomero out	**************	d to the charmetions	
argvals	a vector of argument	values correspond	a to the observations	m anay y.

y an array containing values of curves at discrete sampling points or ar-

gument values. If the array is a matrix, the rows must correspond to argument values and columns to replications, and it will be assumed that there is only one variable per observation. If ${\tt y}$ is a three-dimensional array, the first dimension corresponds to argument values, the second to replications, and the third to variables within replications. If ${\tt y}$ is a vector,

only one replicate and variable are assumed.

fdParobj a functional parameter object, a functional data object or a functional

basis object. If the object is a functional parameter object, then the linear differential operator object and the smoothing parameter in this object define the roughness penalty. If the object is a functional data object, the basis within this object is used without a roughness penalty, and this is also the case if the object is a functional basis object. In these

latter two cases, smooth.basis is essentially the same as data2fd.

wtvec a vector of the same length as argvals containing weights for the values

to be smoothed.

fdnames a list of length 3 containing character vectors of names for the following:

args name for each observation or point in time at which data are collected

for each 'rep', unit or subject.

reps name for each 'rep', unit or subject.

fun name for each 'fun' or (response) variable measured repeatedly (per $\,$

'args') for each 'rep'.

Details

If the smoothing parameter lambda is zero, there is no penalty on roughness. As lambda increases, usually in logarithmic terms, the penalty on roughness increases and the fitted

curves become more and more smooth. Ultimately, the curves are forced to have zero roughness in the sense of being in the null space of the linear differential operator object Lfdobjthat is a member of the fdParobj.

For example, a common choice of roughness penalty is the integrated square of the second derivative. This penalizes curvature. Since the second derivative of a straight line is zero, very large values of lambda will force the fit to become linear. It is also possible to control the amount of roughness by using a degrees of freedom measure. The value equivalent to lambda is found in the list returned by the function. On the other hand, it is possible to specify a degrees of freedom value, and then use function df2lambda to determine the equivalent value of lambda. One should not put complete faith in any automatic method for selecting lambda, including the GCV method. There are many reasons for this. For example, if derivatives are required, then the smoothing level that is automatically selected may give unacceptably rough derivatives. These methods are also highly sensitive to the assumption of independent errors, which is usually dubious with functional data. The best advice is to start with the value minimizing the gcv measure, and then explore lambda values a few log units up and down from this value to see what the smoothing function and its derivatives look like. The function plotfit.fd was designed for this purpose.

An alternative to using smooth.basis is to first represent the data in a basis system with reasonably high resolution using data2fd, and then smooth the resulting functional data object using function smooth.fd.

Value

an object of class fdSmooth, which is a names list of length 6 with the following components:

fd a functional data object containing a smooth of the data.

df a degrees of freedom measure of the smooth

the value of the generalized cross-validation or GCV criterion. If there are multiple curves, this is a vector of values, one per curve. If the smooth

is multivariate, the result is a matrix of gcv values, with columns corre-

sponding to variables.

 $gcv = n * SSE/((n - df)^2)$

SSE the error sums of squares. SSE is a vector or a matrix of the same size as

GCV.

penmat the penalty matrix.

y2cMap the matrix mapping the data to the coefficients.

See Also

data2fd, df2lambda, lambda2df, lambda2gcv, plot.fd, project.basis, smooth.fd, smooth.monotone, smooth.pos, smooth.basisPar

```
## Example 1: Inappropriate smoothing
# A toy example that creates problems with
# data2fd: (0,0) \rightarrow (0.5, -0.25) \rightarrow (1,1)
b2.3 <- create.bspline.basis(norder=2, breaks=c(0, .5, 1))
# 3 bases, order 2 = degree 1 =
# continuous, bounded, locally linear
fdPar2 <- fdPar(b2.3, Lfdobj=2, lambda=1)
## Not run:
# Penalize excessive slope Lfdobj=1;
# second derivative Lfdobj=2 is discontinuous,
# so the following generates an error:
 fd2.3s0 <- smooth.basis(0:1, 0:1, fdPar2)
Derivative of order 2 cannot be taken for B-spline of order 2
Probable cause is a value of the nbasis argument
in function create.basis.fd that is too small.
Error in bsplinepen(basisobj, Lfdobj, rng) :
## End(Not run)
## Example 2. Better
##
b3.4 <- create.bspline.basis(norder=3, breaks=c(0, .5, 1))
# 4 bases, order 3 = degree 2 =
# continuous, bounded, locally quadratic
fdPar3 <- fdPar(b3.4, lambda=1)
# Penalize excessive slope Lfdobj=1;
# second derivative Lfdobj=2 is discontinuous.
fd3.4s0 <- smooth.basis(0:1, 0:1, fdPar3)
plot(fd3.4s0$fd)
# same plot via plot.fdSmooth
plot(fd3.4s0)
##
## Example 3. lambda = 1, 0.0001, 0
# Example 3. lambda = 1
# Shows the effects of three levels of smoothing
# where the size of the third derivative is penalized.
# The null space contains quadratic functions.
x \leftarrow seq(-1,1,0.02)
y <- x + 3*exp(-6*x^2) + rnorm(rep(1,101))*0.2
# set up a saturated B-spline basis
basisobj <- create.bspline.basis(c(-1,1), 101)</pre>
fdPar1 <- fdPar(basisobj, 2, lambda=1)
result1 <- smooth.basis(x, y, fdPar1)
with(result1, c(df, gcv, SSE))
```

```
# Example 2. lambda = 0.0001
fdPar.0001 <- fdPar(basisobj, 2, lambda=0.0001)
result2 <- smooth.basis(x, y, fdPar.0001)
with(result2, c(df, gcv, SSE))
# less smoothing, more degrees of freedom,
# smaller gcv, smaller SSE
# Example 3. lambda = 0
fdPar0 <- fdPar(basisobj, 2, lambda=0)
result3 <- smooth.basis(x, y, fdPar0)
with(result3, c(df, gcv, SSE))
# Saturate fit: number of observations = nbasis
# with no smoothing, so degrees of freedom = nbasis,
# gcv = Inf indicating overfitting;
# SSE = 0 (to within roundoff error)
                    # plot the data
lines(result1[['fd']], lty=2) # add heavily penalized smooth
lines(result2[['fd']], lty=1) # add reasonably penalized smooth
lines(result3[['fd']], lty=3) # add smooth without any penalty
legend(-1,3,c("1","0.0001","0"),lty=c(2,1,3))
plotfit.fd(y, x, result2[['fd']]) # plot data and smooth
##
## Example 4. Supersaturated
##
basis104 <- create.bspline.basis(c(-1,1), 104)</pre>
fdPar104.0 <- fdPar(basis104, 2, lambda=0)
result104.0 <- smooth.basis(x, y, fdPar104.0)
with(result104.0, c(df, gcv, SSE))
plotfit.fd(y, x, result104.0[['fd']], nfine=501)
# perfect (over)fit
# Need lambda > 0.
## Example 5. gait
gaittime <- (1:20)/21
gaitrange <- c(0,1)</pre>
gaitbasis <- create.fourier.basis(gaitrange,21)</pre>
         <- 10^(-11.5)
harmaccelLfd \leftarrow vec2Lfd(c(0, 0, (2*pi)^2, 0))
gaitfdPar <- fdPar(gaitbasis, harmaccelLfd, lambda)</pre>
gaitfd <- smooth.basis(gaittime, gait, gaitfdPar)$fd</pre>
## Not run:
# by default creats multiple plots, asking for a click between plots
plotfit.fd(gait, gaittime, gaitfd)
## End(Not run)
```

Description

Smooth (argvals, y) data with roughness penalty defined by the remaining arguments.

Usage

Arguments

argvals a vector of argument values correspond to the observations in array y.

У

an array containing values of curves at discrete sampling points or argument values. If the array is a matrix, the rows must correspond to argument values and columns to replications, and it will be assumed that there is only one variable per observation. If ${\tt y}$ is a three-dimensional array, the first dimension corresponds to argument values, the second to replications, and the third to variables within replications. If ${\tt y}$ is a vector, only one replicate and variable are assumed.

fdobj

One of the following:

fd a functional data object (class fd)

basisfd a functional basis object (class basisfd, which is converted to a functional data object with the identity matrix as the coefficient matrix.

fdPar a functional parameter object (class fdPar)

integer an integer giving the order of a B-spline basis, which is further converted to a functional data object with the identity matrix as the coefficient matrix.

matrix or array replaced by fd(fdobj)

NULL Defaults to fdobj = create.bspline.basis(argvals).

Lfdobj either a nonnegative integer or a linear differential operator object. If

 $NULL\ and\ fdobj[['type']] == \ 'bspline',\ Lfdobj = int2Lfd(max(0,\ norder-variable)))$

2)), where norder = order of fdobj.

lambda a nonnegative real number specifying the amount of smoothing to be

applied to the estimated functional parameter.

estimate a logical value: if TRUE, the functional parameter is estimated, otherwise,

it is held fixed.

penmat a roughness penalty matrix. Including this can eliminate the need to

compute this matrix over and over again in some types of calculations.

wtvec a vector of the same length as argvals containing weights for the values

to be smoothed.

fdnames

a list of length 3 containing character vectors of names for the following:

args name for each observation or point in time at which data are collected for each 'rep', unit or subject.

reps name for each 'rep', unit or subject.

fun name for each 'fun' or (response) variable measured repeatedly (per 'args') for each 'rep'.

Details

1. if(is.null(fdobj))fdobj <- create.bspline.basis(argvals). Else if(is.integer(fdobj)) fdobj <- create.bspline.basis(argvals, norder = fdobj)

- 2. fdPar
- 3. smooth.basis

Value

The output of a call to 'smooth.basis', which is a named list of length 6 and class fdSmooth with the following components:

fd a functional data object that smooths the data.

df a degrees of freedom measure of the smooth

gcv the value of the generalized cross-validation or GCV criterion. If there are

multiple curves, this is a vector of values, one per curve. If the smooth is multivariate, the result is a matrix of gcv values, with columns corre-

sponding to variables.

SSE the error sums of squares. SSE is a vector or a matrix of the same size as

'gcv'.

penmat the penalty matrix.

y2cMap the matrix mapping the data to the coefficients.

References

Ramsay, James O., and Silverman, Bernard W. (2005), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York.

See Also

Data2fd, df2lambda, fdPar, lambda2df, lambda2gcv, plot.fd, project.basis, smooth.basis, smooth.fd, smooth.monotone, smooth.pos

```
## simplest call
girlGrowthSm <- with(growth, smooth.basisPar(argvals=age, y=hgtf))</pre>
plot(girlGrowthSm$fd, xlab="age", ylab="height (cm)",
         main="Girls in Berkeley Growth Study" )
plot(deriv(girlGrowthSm$fd), xlab="age", ylab="growth rate (cm / year)",
         main="Girls in Berkeley Growth Study" )
plot(deriv(girlGrowthSm$fd, 2), xlab="age",
        ylab="growth acceleration (cm / year^2)",
        main="Girls in Berkeley Growth Study" )
# Shows the effects of smoothing
# where the size of the third derivative is penalized.
# The null space contains quadratic functions.
## Another simple call
lipSm <- smooth.basisPar(liptime, lip)</pre>
plot(lipSm)
# oversmoothing
plot(smooth.basisPar(liptime, lip, lambda=1e-9))
# more sensible
## A third example
x \leftarrow seq(-1,1,0.02)
y <- x + 3*exp(-6*x^2) + sin(1:101)/2
# sin not rnorm to make it easier to compare
# results across platforms
# set up a saturated B-spline basis
basisobj101 <- create.bspline.basis(x)</pre>
fdParobj101 <- fdPar(basisobj101, 2, lambda=1)
result101 <- smooth.basis(x, y, fdParobj101)</pre>
resultP <- smooth.basisPar(argvals=x, y=y, fdobj=basisobj101, lambda=1)
all.equal(result101, resultP)
# TRUE
result4 <- smooth.basisPar(argvals=x, y=y, fdobj=4, lambda=1)
all.equal(resultP, result4)
# TRUE
result4. <- smooth.basisPar(argvals=x, y=y, lambda=1)</pre>
```

```
all.equal(resultP, result4.)
# TRUE
with(result4, c(df, gcv)) # display df and gcv measures
result4.4 <- smooth.basisPar(argvals=x, y=y, lambda=1e-4)
with(result4.4, c(df, gcv)) # display df and gcv measures
# less smoothing, more degrees of freedom, better fit
plot(result4.4)
lines(result4, col='green')
lines(result4$fd, col='green') # same as lines(result4, ...)
result4.0 <- smooth.basisPar(x, y, basisobj101, lambda=0)
result4.0a <- smooth.basisPar(x, y, lambda=0)
all.equal(result4.0, result4.0a)
with(result4.0, c(df, gcv)) # display df and gcv measures
# no smoothing, degrees of freedom = number of points
# but generalized cross validation = Inf
# suggesting overfitting.
##
## fdnames?
##
girlGrow12 <- with(growth, smooth.basisPar(argvals=age, y=hgtf[, 1:2],</pre>
              fdnames=c('age', 'girl', 'height')) )
girlGrow12. <- with(growth, smooth.basisPar(argvals=age, y=hgtf[, 1:2],</pre>
    fdnames=list(age=age, girl=c('Carol', 'Sally'), value='height')) )
```

smooth.fd

Smooth a Functional Data Object Using an Indirectly Specified Roughness Penalty

Description

Smooth data already converted to a functional data object, fdobj, using criteria consolidated in a functional data parameter object, fdParobj. For example, data may have been converted to a functional data object using function data2fd using a fairly large set of basis functions. This 'fdobj' is then smoothed as specified in 'fdParobj'.

Usage

```
smooth.fd(fdobj, fdParobj)
```

Arguments

fdobj a functional data object to be smoothed.

fdParobj a functional parameter object. This object is defined by a roughness

penalty in slot ${\tt Lfd}$ and a smoothing parameter lambda in slot ${\tt lambda},$

and this information is used to further smooth argument fdobj.

Value

a functional data object.

See Also

```
smooth.basis, data2fd
```

```
# Shows the effects of two levels of smoothing
# where the size of the third derivative is penalized.
# The null space contains quadratic functions.
x \leftarrow seq(-1,1,0.02)
y <- x + 3*exp(-6*x^2) + rnorm(rep(1,101))*0.2
# set up a saturated B-spline basis
basisobj <- create.bspline.basis(c(-1,1),81)</pre>
# convert to a functional data object that interpolates the data.
result <- smooth.basis(x, y, basisobj)
yfd <- result$fd
# set up a functional parameter object with smoothing
# parameter 1e-6 and a penalty on the 3rd derivative.
yfdPar <- fdPar(yfd, 2, 1e-6)
yfd1 <- smooth.fd(yfd, yfdPar)
## Not run:
# FIXME: using 3rd derivative here gave error?????
yfdPar3 <- fdPar(yfd, 3, 1e-6)
yfd1.3 <- smooth.fd(yfd, yfdPar3)</pre>
#Error in bsplinepen(basisobj, Lfdobj, rng):
        Penalty matrix cannot be evaluated
# for derivative of order 3 for B-splines of order 4
## End(Not run)
# set up a functional parameter object with smoothing
# parameter 1 and a penalty on the 3rd derivative.
yfdPar <- fdPar(yfd, 2, 1)
yfd2 <- smooth.fd(yfd, yfdPar)
# plot the data and smooth
plot(x,y)
                   # plot the data
lines(yfd1, lty=1) # add moderately penalized smooth
lines(yfd2, lty=3) # add heavily penalized smooth
legend(-1,3,c("0.000001","1"),lty=c(1,3))
# plot the data and smoothing using function plotfit.fd
```

plotfit.fd(y, x, yfd1) # plot data and smooth

Description

Smooth data already converted to a functional data object, fdobj, using directly specified criteria.

Usage

Arguments

fdobj a functional data object to be smoothed.

Lfdobj either a nonnegative integer or a linear differential operator object

lambda a nonnegative real number specifying the amount of smoothing to be

applied to the estimated functional parameter.

estimate a logical value: if TRUE, the functional parameter is estimated, otherwise,

it is held fixed.

penmat a roughness penalty matrix. Including this can eliminate the need to

compute this matrix over and over again in some types of calculations.

Details

- 1. fdPar
- 2. smooth.fd

Value

a functional data object.

References

Ramsay, James O., and Silverman, Bernard W. (2005), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York.

See Also

```
smooth.fd, fdPar, smooth.basis, smooth.pos, smooth.morph
```

Examples

```
# Shows the effects of two levels of smoothing
# where the size of the third derivative is penalized.
# The null space contains quadratic functions.
x \leftarrow seq(-1,1,0.02)
y <- x + 3*exp(-6*x^2) + rnorm(rep(1,101))*0.2
# set up a saturated B-spline basis
basisobj <- create.bspline.basis(c(-1,1),81)</pre>
# convert to a functional data object that interpolates the data.
result <- smooth.basis(x, y, basisobj)
vfd <- result$fd
# set up a functional parameter object with smoothing
# parameter 1e-6 and a penalty on the 2nd derivative.
yfdPar <- fdPar(yfd, 2, 1e-6)
yfd1 <- smooth.fd(yfd, yfdPar)</pre>
yfd1. <- smooth.fdPar(yfd, 2, 1e-6)
all.equal(yfd1, yfd1.)
# TRUE
# set up a functional parameter object with smoothing
  parameter 1 and a penalty on the 2nd derivative.
yfd2 <- smooth.fdPar(yfd, 2, 1)</pre>
# plot the data and smooth
                    # plot the data
plot(x,y)
lines(yfd1, lty=1) # add moderately penalized smooth
lines(yfd2, lty=3) # add heavily penalized smooth
legend(-1,3,c("0.000001","1"),lty=c(1,3))
# plot the data and smoothing using function plotfit.fd
plotfit.fd(y, x, yfd1) # plot data and smooth
```

smooth.monotone

Monotone Smoothing of Data

Description

When the discrete data that are observed reflect a smooth strictly increasing or strictly decreasing function, it is often desirable to smooth the data with a strictly monotone function, even though the data themselves may not be monotone due to observational error. An example is when data are collected on the size of a growing organism over time. This function computes such a smoothing function, but, unlike other smoothing functions, for only for one curve at a time. The smoothing function minimizes a weighted error sum of squares criterion. This minimization requires iteration, and therefore is more computationally intensive than normal smoothing.

The monotone smooth is beta[1]+beta[2]*integral(exp(Wfdobj)), where Wfdobj is a functional data object. Since exp(Wfdobj)>0, its integral is monotonically increasing.

Usage

Arguments

x a vector of argument values.

y a vector of data values. This function can only smooth one set of data at

a time.

WfdParobj a functional parameter object that provides an initial value for the coef-

ficients defining function W(t), and a roughness penalty on this function.

wt a vector of weights to be used in the smoothing.

zmat a design matrix or a matrix of covariate values that also define the smooth

of the data.

conv a convergence criterion.

iterlim the maximum number of iterations allowed in the minimization of error

sum of squares.

active a logical vector specifying which coefficients defining W(t) are estimated.

Normally, the first coefficient is fixed.

dbglev either 0, 1, or 2. This controls the amount information printed out on

each iteration, with 0 implying no output, 1 intermediate output level, and 2 full output. If either level 1 or 2 is specified, it can be helpful to

turn off the output buffering feature of S-PLUS.

Details

The smoothing function f(x) is determined by three objects that need to be estimated from the data:

- W(x), a functional data object that is first exponentiated and then the result integrated. This is the heart of the monotone smooth. The closer W(x) is to zero, the closer the monotone smooth becomes a straight line. The closer W(x) becomes a constant, the more the monotone smoother becomes an exponential function. It is assumed that W(0) = 0.
- b0, an intercept term that determines the value of the smoothing function at x=0.
- b1, a regression coefficient that determines the slope of the smoothing function at x = 0.

In addition, it is possible to have the intercept b0 depend in turn on the values of one or more covariates through the design matrix Zmat as follows: b0 = Zc. In this case, the single intercept coefficient is replaced by the regression coefficients in vector c multipying the design matrix.

Value

a named list of length 5 containing:

Wfdobj a functional data object defining function W(x) that optimizes the fit to

the data of the monotone function that it defines.

beta the optimal regression coefficient values.

Flist a named list containing three results for the final converged solution: (1)

f: the optimal function value being minimized, (2) **grad**: the gradient vector at the optimal solution, and (3) **norm**: the norm of the gradient

vector at the optimal solution.

iternum the number of iterations.

iterhist iternum+1 by 5 matrix containing the iteration history.

References

Ramsay, James O., and Silverman, Bernard W. (2005), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York.

See Also

```
smooth.basis, smooth.pos, smooth.morph
```

```
# Estimate the acceleration functions for growth curves
  See the analyses of the growth data.
  Set up the ages of height measurements for Berkeley data
age \leftarrow c(seq(1, 2, 0.25), seq(3, 8, 1), seq(8.5, 18, 0.5))
# Range of observations
rng <- c(1,18)
# First set up a basis for monotone smooth
# We use b-spline basis functions of order 6
# Knots are positioned at the ages of observation.
norder <- 6
nage
      <- 31
nbasis <- nage + norder - 2
wbasis <- create.bspline.basis(rng, nbasis, norder, age)</pre>
# starting values for coefficient
cvec0 <- matrix(0,nbasis,1)</pre>
Wfd0 <- fd(cvec0, wbasis)
# set up functional parameter object
          <- 3
                        # penalize curvature of acceleration
Lfdobj
          <- 10^(-0.5) # smoothing parameter
growfdPar <- fdPar(Wfd0, Lfdobj, lambda)</pre>
# Set up wgt vector
wgt <- rep(1,nage)</pre>
# Smooth the data for the first girl
```

```
hgt1 = growth$hgtf[,1]
result <- smooth.monotone(age, hgt1, growfdPar, wgt)
# Extract the functional data object and regression
# coefficients
Wfd <- result$Wfdobj
beta <- result$beta
# Evaluate the fitted height curve over a fine mesh
agefine <- seq(1,18,len=101)
hgtfine <- beta[1] + beta[2]*eval.monfd(agefine, Wfd)</pre>
# Plot the data and the curve
plot(age, hgt1, type="p")
lines(agefine, hgtfine)
# Evaluate the acceleration curve
accfine <- beta[2]*eval.monfd(agefine, Wfd, 2)</pre>
# Plot the acceleration curve
plot(agefine, accfine, type="l")
lines(c(1,18),c(0,0),lty=4)
```

smooth.morph

Estimates a Smooth Warping Function

Description

This function is nearly identical to smooth monotone but is intended to compute a smooth monotone transformation h(t) of argument t such that h(0) = 0 and h(TRUE) = TRUE, where t is the upper limit of t. This function is used primarily to register curves.

Usage

Arguments

x a vector of argument values.

y a vector of data values. This function can only smooth one set of data at

a time.

WfdParobj a functional parameter object that provides an initial value for the coef-

ficients defining function W(t), and a roughness penalty on this function.

wt a vector of weights to be used in the smoothing.

conv a convergence criterion.

iterlim the maximum number of iterations allowed in the minimization of error

sum of squares.

active a logical vector specifying which coefficients defining W(t) are estimated.

Normally, the first coefficient is fixed.

dbglev either 0, 1, or 2. This controls the amount information printed out on

each iteration, with 0 implying no output, 1 intermediate output level, and 2 full output. If either level 1 or 2 is specified, it can be helpful to

turn off the output buffering feature of S-PLUS.

Value

A named list of length 4 containing:

Wfdobj a functional data object defining function W(x) that that optimizes the

fit to the data of the monotone function that it defines.

Flist a named list containing three results for the final converged solution: (1)

f: the optimal function value being minimized, (2) grad: the gradient vector at the optimal solution, and (3) norm: the norm of the gradient

vector at the optimal solution.

iternum the number of iterations.
iternum the number of iterations.

iterhist a by 5 matrix containing the iteration history.

See Also

smooth.monotone, landmarkreg, register.fd

smooth.pos

Smooth Data with a Positive Function

Description

A set of data is smoothed with a functional data object that only takes positive values. For example, this function can be used to estimate a smooth variance function from a set of squared residuals. A function W(t) is estimated such that that the smoothing function is exp[W(t)].

Usage

Arguments

argvals a vector of argument values.

y a vector of data values. This function can only smooth one set of data at

a time.

WfdParobj a functional parameter object that provides an initial value for the coef-

ficients defining function W(t), and a roughness penalty on this function.

wt a vector of weights to be used in the smoothing.

conv a convergence criterion.

iterlim the maximum number of iterations allowed in the minimization of error

sum of squares.

dbglev either 0, 1, or 2. This controls the amount information printed out on

each iteration, with 0 implying no output, 1 intermediate output level, and 2 full output. If either level 1 or 2 is specified, it can be helpful to

turn off the output buffering feature of S-PLUS.

Value

a named list of length 4 containing:

Wfdobj a functional data object defining function W(x) that that optimizes the

fit to the data of the monotone function that it defines.

Flist a named list containing three results for the final converged solution: (1)

f: the optimal function value being minimized, (2) **grad**: the gradient vector at the optimal solution, and (3) **norm**: the norm of the gradient

vector at the optimal solution.

iternum the number of iterations.
iternum the number of iterations.

iterhist a iternum+1 by 5 matrix containing the iteration history.

See Also

smooth.monotone, smooth.morph

Examples

#See the analyses of the daily weather data for examples.

Sum of Functional Data

sum.fd

Description

Evaluate the sum of a set of functions in a functional data object.

Usage

```
sum.fd(..., na.rm)
```

Arguments

... a functional data object to sum.

na.rm Not used.

Value

a functional data object with a single replication that contains the sum of the functions in the object fd.

See Also

```
mean.fd, std.fd, stddev.fd, center.fd
```

summary.basisfd

Summarize a Functional Data Object

Description

Provide a compact summary of the characteristics of a functional data object.

Usage

```
summary.basisfd(object, ...)
```

Arguments

object a functional data object.

... Other arguments to match generic

Value

a displayed summary of the bivariate functional data object.

References

Ramsay, James O., and Silverman, Bernard W. (2005), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., and Silverman, Bernard W. (2002), Applied Functional Data Analysis, Springer, New York.

summary.bifd

Summarize a Bivariate Functional Data Object

Description

Provide a compact summary of the characteristics of a bivariate functional data object.

Usage

```
## S3 method for class 'bifd':
summary(object, ...)
summary.bifd(object, ...)
```

Arguments

object a bivariate functional data object.

... Other arguments to match the generic function for 'summary'

Value

a displayed summary of the bivariate functional data object.

See Also

summary,

summary.fd

Summarize a Functional Data Object

Description

Provide a compact summary of the characteristics of a functional data object.

Usage

```
## S3 method for class 'fd':
summary(object,...)
summary.fd(object,...)
```

Arguments

```
object a functional data object.

Other arguments to match the generic for 'summary'
```

Value

a displayed summary of the functional data object.

See Also

```
summary,
```

summary.fdPar

Summarize a Functional Parameter Object

Description

Provide a compact summary of the characteristics of a functional parameter object.

Usage

```
## S3 method for class 'fdPar':
summary(object, ...)
summary.fdPar(object, ...)
```

Arguments

object a functional parameter object.

... Other arguments to match the generic 'summary' function

Value

a displayed summary of the functional parameter object.

See Also

summary,

summary.Lfd

Description

Provide a compact summary of the characteristics of a linear differential operator object.

Usage

```
## S3 method for class 'Lfd':
summary(object, ...)
summary.Lfd(object, ...)
```

Arguments

object a linear differential operator object.

.. Other arguments to match the generic 'summary' function

Value

a displayed summary of the linear differential operator object.

See Also

summary,

svd2

singular value decomposition with automatic error handling

Description

The 'svd' function in R 2.5.1 occasionally throws an error with a cryptic message. In some such cases, changing the LINPACK argument works.

Usage

```
svd2(x, nu = min(n, p), nv = min(n, p), LINPACK = FALSE)
```

Arguments

```
{\tt x},\ {\tt nu},\ {\tt nv},\ {\tt LINPACK} as for the 'svd' function in the 'base' package.
```

Details

In R 2.5.1, the 'svd' function sometimes stops with a cryptic error message for a matrix x for which a second call to 'svd' with !LINPACK will produce an answer. When such conditions occur, assign 'x' with attributes 'nu', 'nv', and 'LINPACK' to '.svd.LINPACK.error.matrix' in 'env = .GlobalEnv'.

Except for these rare pathologies, 'svd2' should work the same as 'svd'.

Value

a list with components d, u, and v, as described in the help file for 'svd' in the 'base' package.

See Also

svd,

TaylorSpline

Taylor representation of a B-Spline

Description

Convert B-Spline coefficients into a local Taylor series representation expanded about the midpoint between each pair of distinct knots.

Usage

```
TaylorSpline(object, ...)
## S3 method for class 'fd':
TaylorSpline(object, ...)
## S3 method for class 'fdPar':
TaylorSpline(object, ...)
## S3 method for class 'fdSmooth':
TaylorSpline(object, ...)
## S3 method for class 'dierckx':
TaylorSpline(object, ...)
```

Arguments

```
object a spline object, e.g., of class 'dierckx'.
... optional arguments
```

Details

- 1. Is object a spline object with a B-spline basis? If no, throw an error.
- 2. Find knots and midpoints.
- 3. Obtain coef(object).
- 4. Determine the number of dimensions of coef(object) and create empty coef and deriv arrays to match. Then fill the arrays.

Value

a list with the following components:

knots a numeric vector of knots(object, interior=FALSE)
midpoints midpoints of intervals defined by unique(knots)

coef A matrix of dim = c(nKnots-1, norder) containing the coefficients of a poly-

 $nomial\ in\ (x-midpoints[i])\ for\ interval\ i,\ where\ nKnots = length(unique(knots)).$

deriv A matrix of dim = c(nKnots-1, norder) containing the derivatives of the

spline evaluated at midpoints.

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Author(s)

Spencer Graves

See Also

```
fd create.bspline.basis
```

```
##
## The simplest b-spline basis: order 1, degree 0, zero interior knots:
##
         a single step function
##
library(DierckxSpline)
bspl1.1 <- create.bspline.basis(norder=1, breaks=0:1)</pre>
# ... jump to pi to check the code
fd.bspl1.1pi <- fd(pi, basisobj=bspl1.1)</pre>
bspl1.1pi <- TaylorSpline(fd.bspl1.1pi)</pre>
##
## Cubic spline: 4 basis functions
bspl4 <- create.bspline.basis(nbasis=4)</pre>
plot(bspl4)
parab4.5 \leftarrow fd(c(3, -1, -1, 3)/3, bspl4)
# = 4*(x-.5)
TaylorSpline(parab4.5)
## A more realistic example
##
data(titanium)
# Cubic spline with 5 interior knots (6 segments)
titan10 <- with(titanium, curfit.free.knot(x, y))</pre>
(titan10T <- TaylorSpline(titan10) )</pre>
```

Permutation t-test	for two	groups of	functional	data d	biects.
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Description

tperm.fd

tperm.fd creates a null distribution for a test of no difference between two groups of functional data objects.

Usage

```
tperm.fd(x1fd, x2fd, nperm=200, q=0.95, argvals=NULL, plotres=TRUE)
```

Arguments

x1fd x2fd	a functional data object giving the first group of functional observations. a functional data object giving the second group of functional observations.
nperm	number of permutations to use in creating the null distribution.
argvals	If yfdPar is a fd object, the points at which to evaluate the point-wise F-statistic.
q	Critical quantile of the null distribution to compare to the observed F-statistic.
plotres	Argument to plot a visual display of the null distribution displaying the qth quantile and observed F-statistic.

Details

The usual t-statistic is calculated pointwise and the test based on the maximal value. If argvals is not specified, it defaults to 101 equally-spaced points on the range of yfdPar.

Value

A list with components

pval	the observed p-value of the permutation test.
qval	the qth quantile of the null distribution.
Tobs	the observed maximal t-statistic.
Tnull	a vector of length ${\tt nperm}$ giving the observed values of the permutation distribution.
Tvals	the pointwise values of the observed t-statistic.
Tnullvals	the pointwise values of of the permutation observations.
pvals.pts	pointwise p-values of the t-statistic.
qvals.pts	pointwise qth quantiles of the null distribution
argvals	argument values for evaluating the F-statistic if yfdParis a functional data object.

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Source

Ramsay, James O., and Silverman, Bernard W. (2006), Functional Data Analysis, 2nd ed., Springer, New York.

See Also

```
fRegress Fstat.fd
```

var.fd Variance, Covariance, and Correlation Surfaces for Functional Data Object(s)

Description

Compute variance, covariance, and / or correlation functions for functional data.

These are two-argument functions and therefore define surfaces. If only one functional data object is supplied, its variance or correlation function is computed. If two are supplied, the covariance or correlation function between them is computed.

Usage

```
var.fd(fdobj1, fdobj2=fdobj1)
```

Arguments

fdobj1, fdobj2

a functional data object.

Details

a two-argument or bivariate functional data object representing the variance, covariance or correlation surface for a single functional data object or the covariance between two functional data objects or between different variables in a multivariate functional data object.

Value

An list object of class bifd with the following components:

coefs the coefficient array with dimensions fdobj1[["basis"]][["nbasis"]] by fdobj2[["basis"]][["nbasis"]]

giving the coefficients of the covariance matrix in terms of the bases used

by fdobj1 and fdobj2.

sbasis fdobj1[["basis"]] tbasis fdobj2[["basis"]]

bifdnames dimnames list for a 4-dimensional 'coefs' array. If length(dim(coefs)) is

only 2 or 3, the last 2 or 1 component of bifdnames is not used with

dimnames(coefs).

Examples below illustrate this structure in simple cases.

See Also

```
mean.fd, sd.fd, std.fd stdev.fd
```

```
##
## Example with 2 different bases
daybasis3 <- create.fourier.basis(c(0, 365))</pre>
daybasis5 <- create.fourier.basis(c(0, 365), 5)</pre>
tempfd3 <- with(CanadianWeather, data2fd(dailyAv[,,"Temperature.C"],</pre>
       day.5, daybasis3, argnames=list("Day", "Station", "Deg C")) )
precfd5 <- with(CanadianWeather, data2fd(dailyAv[,,"log10precip"],</pre>
       day.5, daybasis5, argnames=list("Day", "Station", "Deg C")) )
# Compare with structure described above under 'value':
str(tempPrecVar3.5 <- var.fd(tempfd3, precfd5))</pre>
## Example with 2 variables, same bases
gaitbasis3 <- create.fourier.basis(nbasis=3)</pre>
str(gaitfd3 <- data2fd(gait, basisobj=gaitbasis3))</pre>
str(gaitVar.fd3 <- var.fd(gaitfd3))</pre>
# Check the answers with manual computations
all.equal(var(t(gaitfd3$coefs[,,1])), gaitVar.fd3$coefs[,,,1])
all.equal(var(t(gaitfd3$coefs[,,2])), gaitVar.fd3$coefs[,,,3])
# TRUE
all.equal(var(t(gaitfd3$coefs[,,2]), t(gaitfd3$coefs[,,1])),
          gaitVar.fd3$coefs[,,,2])
# TRUE
# NOTE:
dimnames(gaitVar.fd3$coefs)[[4]]
# [1] Hip-Hip
# [2] Knee-Hip
# [3] Knee-Knee
# If [2] were "Hip-Knee", then
# gaitVar.fd3$coefs[,,,2] would match
#var(t(gaitfd3$coefs[,,1]), t(gaitfd3$coefs[,,2]))
# *** It does NOT. Instead, it matches:
#var(t(gaitfd3$coefs[,,2]), t(gaitfd3$coefs[,,1])),
## The following produces contour and perspective plots
# Evaluate at a 53 by 53 grid for plotting
daybasis65 <- create.fourier.basis(rangeval=c(0, 365), nbasis=65)</pre>
```

```
daytempfd <- with(CanadianWeather, data2fd(dailyAv[,,"Temperature.C"],</pre>
       day.5, daybasis65, argnames=list("Day", "Station", "Deg C")) )
str(tempvarbifd <- var.fd(daytempfd))</pre>
str(tempvarmat <- eval.bifd(weeks, weeks, tempvarbifd))</pre>
# dim(tempvarmat) = c(53, 53)
op <- par(mfrow=c(1,2), pty="s")
#contour(tempvarmat, xlab="Days", ylab="Days")
contour(weeks, weeks, tempvarmat,
        xlab="Daily Average Temperature",
        ylab="Daily Average Temperature",
        main=paste("Variance function across locations\n",
          "for Canadian Anual Temperature Cycle"),
        cex.main=0.8, axes=FALSE)
axisIntervals(1, atTick1=seq(0, 365, length=5), atTick2=NA,
            atLabels=seq(1/8, 1, 1/4)*365,
            labels=paste("Q", 1:4) )
axisIntervals(2, atTick1=seq(0, 365, length=5), atTick2=NA,
            atLabels=seq(1/8, 1, 1/4)*365,
            labels=paste("Q", 1:4) )
persp(weeks, weeks, tempvarmat,
      xlab="Days", ylab="Days", zlab="Covariance")
mtext("Temperature Covariance", line=-4, outer=TRUE)
par(op)
```

varmx.cca.fd

Rotation of Functional Canonical Components with VARIMAX

Description

Results of canonical correlation analysis are often easier to interpret if they are rotated. Among the many possible ways in which this rotation can be defined, the VARIMAX criterion seems to give satisfactory results most of the time.

Usage

```
varmx.cca.fd(ccafd, nx=201)
```

Arguments

an object of class "cca.fd" that is produced by function cca.fd.

nx the number of points in a fine mesh of points that is required to approxi-

mate canonical variable functional data objects.

Value

a rotated version of argument cca.fd.

See Also

varmx, varmx.pca.fd

Description

Principal components are often easier to interpret if they are rotated. Among the many possible ways in which this rotation can be defined, the VARIMAX criterion seems to give satisfactory results most of the time.

Usage

```
varmx.pca.fd(pcafd, nharm=scoresd[2], nx=501)
```

Arguments

pcafd an object of class pca.fd that is produced by function pca.fd.

nharm the number of harmonics or principal components to be rotated.

nx the number of argument values in a fine mesh used to define the harmonics

to be rotated.

Value

a rotated principal components analysis object of class pca.fd.

See Also

```
varmx, varmx.cca.fd
```

varmx	Rotate a Criterion	of	Component	Loadings	using	the	VARIMAX	

Description

The matrix being rotated contains the values of the component functional data objects computed in either a principal components analysis or a canonical correlation analysis. The values are computed over a fine mesh of argument values.

Usage

varmx(amat)

Arguments

amat

the matrix to be rotated. The number of rows is equal to the number of argument values **nx** used in a fine mesh. The number of columns is the number of components to be rotated.

Details

The VARIMAX criterion is the variance of the squared component values. As this criterion is maximized with respect to a rotation of the space spanned by the columns of the matrix, the squared loadings tend more and more to be either near 0 or near 1, and this tends to help with the process of labelling or interpreting the rotated matrix.

Value

a square rotation matrix of order equal to the number of components that are rotated. A rotation matrix T has that property that T'T = TT' = I.

See Also

```
varmx.pca.fd, varmx.cca.fd
```

vec2Lfd

Make a Linear Differential Operator Object from a Vector

Description

A linear differential operator object of order m is constructed from the number in a vector of length m.

Usage

```
vec2Lfd(bwtvec, rangeval=c(0,1))
```

Arguments

bwtvec

rangeval

a vector of coefficients to define the linear differential operator object a vector of length 2 specifying the range over which the operator is defined

Value

a linear differential operator object

See Also

```
int2Lfd, Lfd
```

Examples

define the harmonic acceleration operator used in the # analysis of the daily temperature data harmaccelLfd <- vec2Lfd($c(0,(2*pi/365)^2,0), c(0,365)$)

zerofind

Does the range of the input contain 0?

Description

Returns TRUE if range of the argument includes 0 and FALSES if not.

Usage

```
zerofind(fmat)
```

Arguments

fmat

An object from which 'range' returns two numbers.

Value

A logical value TRUE or FALSE.

See Also

range

```
zerofind(1:5)
# FALSE
zerofind(0:3)
# TRUE
```