Filippo Grazioli

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Education

RWTH Aachen University

 ${\bf September~2015-October~2016}$

Erasmus+ EU International Exchange Program

Aachen, Germany

Polytechnic University of Turin

October 2014 - March 2017

Master of Science (cum laude) in Automotive Engineering

Turin, Italy

University of Ferrara

September 2011 - October 2014

Bachelor of Science (cum laude) in Mechanical Engineering

Ferrara, Italy

Experience

Cruise (General Motors)

April 2023 - Present

Munich, Germany

• 3D object detection for self-driving cars.

• Deep learning and LiDAR/camera/radar sensor fusion.

Senior Machine Learning Engineer II - Computer Vision

• Scene understanding.

NEC Laboratories Europe

July 2020 - March 2023

Heidelberg, Germany

Research Engineer - Biomedical AI Machine learning for precision immuno-oncology, personalized cancer vaccines and drug discovery.

• Prediction of protein binding with Transformers, Graph Neural Networks and 1D CNNs.

• Multimodal variational models for disease prediction.

• Probabilistic simulations and mixed integer programming (MIP) for vaccine optimization.

Bosch Engineering

July 2018 – July 2020

Software Engineer - Camera Perception

Abstatt, Germany

Maranello, Italy

• Embedded C++ perception algorithms for the Bosch Multi Purpose Camera for ADAS and autonomous driving.

• Road sign recognition.

• ROS prototype development.

Ferrari

October 2017 - June 2018

Visiting Researcher - Computer Vision

• Computer vision for driver monitoring with depth and RGB images.

- Depth estimation with GANs from monocular RGB images.
- Multimodal face verification from RGB and depth.

RWTH Aachen University

June 2016 – September 2017

Graduate Research Assistant - Software Engineering (May 2017 - September 2017)

Aachen, Germany

• Model-based software engineering (UML/SysML) for automotive research.

Student Research Assistant - Institute of Automotive Engineering (IKA) (June 2016 - April 2017)

- Eye-tracking and driver behaviour understanding for autonomous driving.
- Master thesis: Development of a Driver State Detector for Autonomous Vehicles.

Selected Publications

Disentangled Wasserstein Autoencoder for T-Cell Receptor Engineering, T Li, H Guo, F Grazioli, M Gerstein, MR Min, NeurIPS, 2023

Attentive Variational Information Bottleneck for TCR-peptide Interaction Prediction, F Grazioli, P Machart, A Moesch, K Li, LV Castorina, N Pfeifer, MR Min, Bioinformatics, 2022

Microbiome-based disease prediction with multimodal variational information bottlenecks, F Grazioli, R Siarheyeu, I Alqassem, A Henschel, G Pileggi, A Meiser, PLOS Computational Biology, 2022

Face Verification from Depth using Privileged Information, G Borghi, S Pini, F Grazioli, R Vezzani, R Cucchiara, The British Machine Vision Conference (BMVC), 2018

Learning to Generate Facial Depth Maps, S Pini, F Grazioli, G Borghi, R Vezzani, R Cucchiara, International Conference on 3D Vision (3DV), 2018

Technical Skills

Computer vision: Multimodal object detection, camera/radar/LiDAR fusion, segmentation, depth estimation Machine learning: Deep learning, geometric deep learning, graph convolutional networks, variational inference,

information bottleneck, multimodal learning, deep sets, transformers, out-of-distribution detection

Relevant libraries: PyTorch, PyTorch Geometric, DGL, Tensorflow/Keras, Transformers, Scikit-learn, ROS, OpenCV

Languages: Python, C, C++

Software development: Docker, Git, Scrum, Jira, GitLab, Continuous Integration

Languages

Italian: Mother tongue English: Fluent German: Fluent Spanish: Basic

Interests

Favourite movie directors: David Lynch, Martin Scorsese Favourite writers: Jorge Luis Borges, Gabriel García Márquez Hobbies: Photography, swimming, playing guitar, cooking, gardening