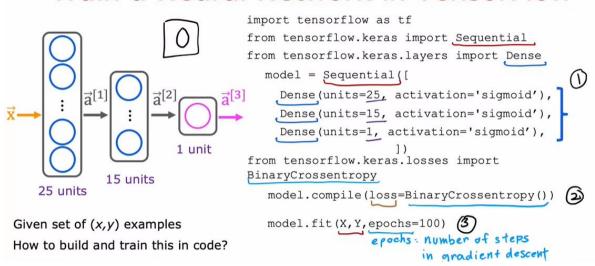
1. TensorFlow implementation

#### Train a Neural Network in TensorFlow



2. Training details

## Model Training Steps Tensor Flow

specify how to compute output given input x and parameters w,b (define model)

$$f_{\overrightarrow{\mathbf{w}},\mathbf{b}}(\overrightarrow{\mathbf{x}}) = ?$$

specify loss and cost

$$L(f_{\overrightarrow{w},b}(\overrightarrow{x}), \underline{y}) \text{ 1 example}$$

$$J(\overrightarrow{w}, b) = \frac{1}{m} \sum_{i=1}^{m} L(f_{\overrightarrow{w},b}(\overrightarrow{x}^{(i)}), y^{(i)})$$

Train on data to minimize  $J(\vec{w}, b)$ 

logistic regression

$$z = np.dot(w,x) + b$$

$$f_x = 1/(1+np.exp(-z))$$

logistic loss

$$\begin{array}{l} loss = -y * np.log(f_x) \\ -(1-y) * np.log(1-f_x) \end{array}$$

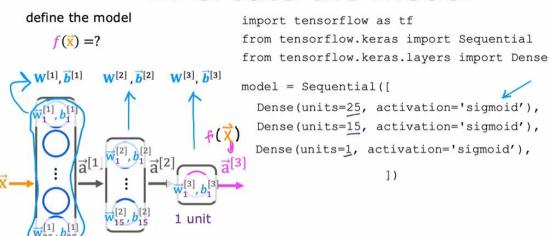
neural network

binary cross entropy

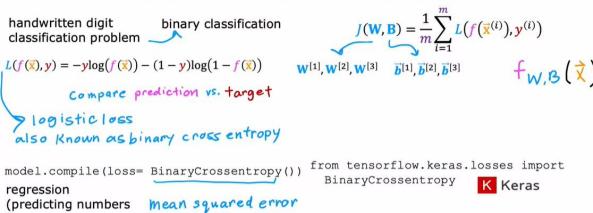
```
model.compile(
loss=BinaryCrossentropy())

model.fit(X,y,epochs=100)
```

#### 1. Create the model



#### Loss and cost functions



and not categories)

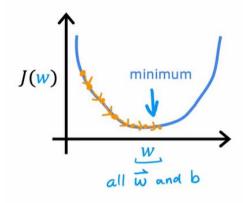
15 units

25 units

model.compile(loss= MeanSquaredError())

from tensorflow.keras.losses import MeanSquaredError

## Gradient descent



repeat {

$$w_{j}^{[l]} = w_{j}^{[l]} - \alpha \frac{\partial}{\partial w_{j}} J(\overrightarrow{w}, b)$$
$$b_{j}^{[l]} = b_{j}^{[l]} - \alpha \frac{\partial}{\partial b_{j}} J(\overrightarrow{w}, b)$$

} Compute derivatives using "back propagation"

model.fit(X,y,epochs=100)

## Neural network libraries

Use code libraries instead of coding "from scratch"





# Good to understand the implementation (for tuning and debugging).

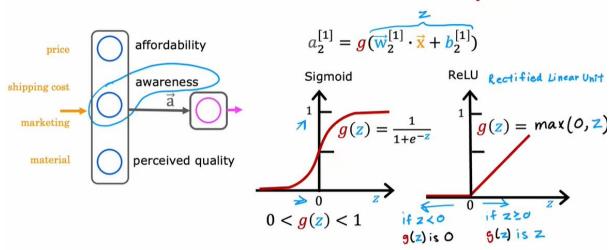
3.	Practice quiz
	Here is some code that you saw in the lecture:
	model.compile(loss=BinaryCrossentropy())
	For which type of task would you use the binary cross entropy loss function?
	A classification task that has 3 or more classes (categories)
	regression tasks (tasks that predict a number)
	O BinaryCrossentropy() should not be used for any task.
	<ul><li>binary classification (classification with exactly 2 classes)</li></ul>
	<ul> <li>Correct</li> <li>Yes! Binary cross entropy, which we've also referred to as logistic loss, is used for classifying between two classes (two categories).</li> </ul>
	Which line of code updates the network parameters in order to reduce the cost?
	model.fit(X,y,epochs=100)
	omodel = Sequential([])
	O None of the above this code does not update the network parameters.
	O model.compile(loss=BinaryCrossentropy())
	Correct

Yes! The third step of model training is to train the model on data in order to minimize the loss (and the

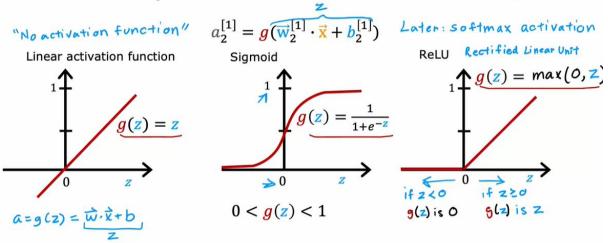
#### **Activation Function**

1. Alternatives to the sigmoid activation

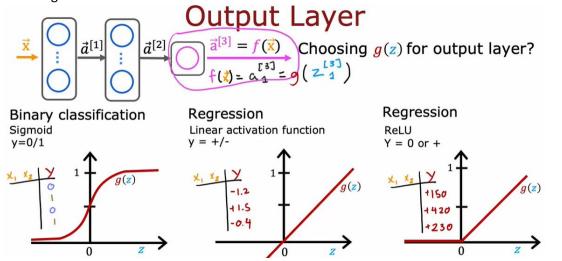
## **Demand Prediction Example**

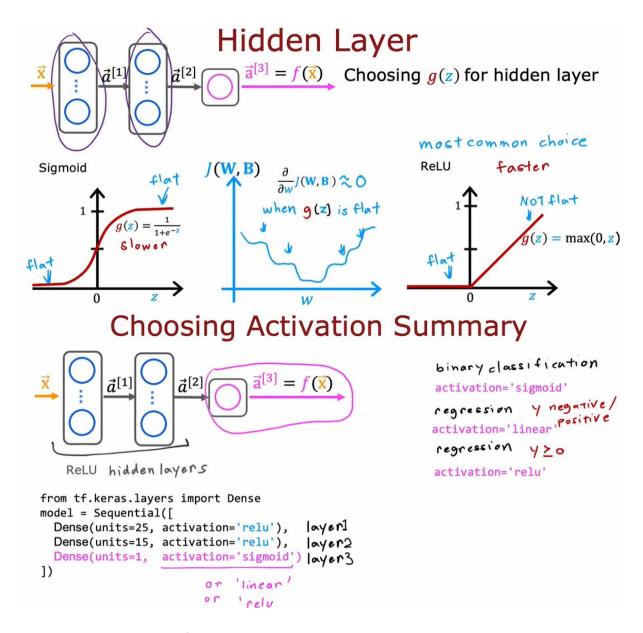


## **Examples of Activation Functions**



2. Choosing activation function



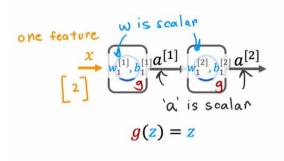


3. Why do we need activation function

## Why do we need activation functions?



#### Linear Example



$$a^{[1]} = \underbrace{w_1^{[1]} x}_{1} + b_1^{[1]}$$

$$a^{[2]} = w_1^{[2]} a^{[1]} + b_1^{[2]}$$

$$= w_1^{[2]} (w_1^{[1]} \times b_1^{[1]}) + b_1^{[2]}$$

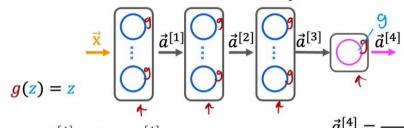
$$= w_1^{[2]} (w_1^{[1]} \times b_1^{[1]}) + b_1^{[2]}$$

$$\vec{a}^{[2]} = (\underbrace{\vec{w}_1^{[2]} \vec{w}_1^{[1]}}) \times + \underbrace{w_1^{[2]} b_1^{[1]}}_{1} + b_1^{[2]}$$

$$\vec{a}^{[2]} = w x + b$$

f(x) = wxtb linear regression

## Example



 $\vec{a}^{[4]} = \vec{w}_1^{[4]} \cdot \vec{a}^{[3]} + b_1^{[4]}$  all linear (including output)

Gequivalent to linear regression

$$\vec{a}^{[4]} = \frac{1}{1 + e^{-(\overrightarrow{w}_1^{[4]} \cdot \overrightarrow{a}^{[3]} + b_1^{[4]})}}$$

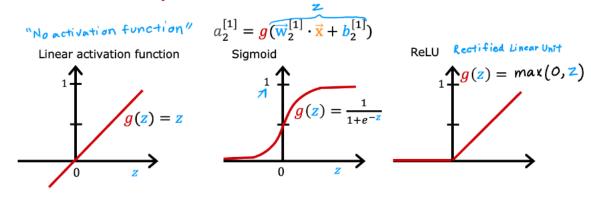
output activation is sigmoid (hidden layers still linear)
4 equivalent to logistic regression

Don't use linear activations in hidden layers

#### 4. Practice quiz

1.

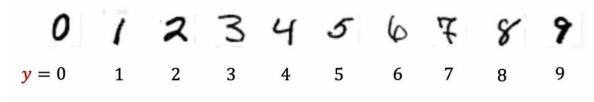
### **Examples of Activation Functions**



Which of the following activation functions is the most common choice for the hidden layers of a neural network?	
ReLU (rectified linear unit)	
O Sigmoid	
O Linear	
O Most hidden layers do not use any activation function	
Correct Yes! A ReLU is most often used because it is faster to train compared to the sigmoid. This is because the ReLU is only flat on one side (the left side) whereas the sigmoid goes flat (horizontal, slope approaching zero) on both sides of the curve.	
For the task of predicting housing prices, which activation functions could you choose for the output layer? Choose the 2 options that apply.	
✓ linear	
Correct Yes! A linear activation function can be used for a regression task where the output can be both negative and positive, but it's also possible to use it for a task where the output is 0 or greater (like with house prices).	
✓ ReLU	
<ul> <li>Correct</li> <li>Yes! ReLU outputs values 0 or greater, and housing prices are positive values.</li> </ul>	
Sigmoid	
3. True/False? A neural network with many layers but no activation function (in the hidden layers) is not effective; that's why we should instead use the linear activation function in every hidden layer.	
O True	
False	
Correct Yes! A neural network with many layers but no activation function is not effective. A linear activation is the same as "no activation function".	

#### 1. Multiclass

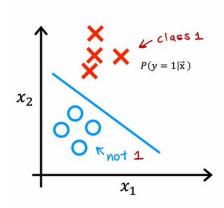
## MNIST example

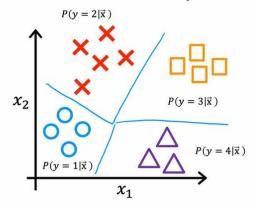


$$y = 7$$

multiclass classification problem: target y can take on more than two possible values

#### Multiclass classification example





#### 2. Softmax

Logistic regression (2 possible output values)  $z = \vec{w} \cdot \vec{x} + b$ 

$$a_{1} = g(z) = \frac{1}{1 + e^{-z}} = P(y = 1 | \vec{x})$$

$$0 \quad a_{2} = |-a_{1}| = P(y = 0 | \vec{x})$$

$$0 \quad 0 \quad 0$$

Softmax regression (N possible outputs) y=1,2,3,...,N

$$z_{j} = \overrightarrow{w}_{j} \cdot \overrightarrow{x} + b_{j} \quad j = 1, ..., N$$

$$w_{1}, w_{2}, ..., w_{N}$$

$$a_{j} = \frac{e^{z_{j}}}{\sum_{k=1}^{N} e^{z_{k}}} = P(y = j | \overrightarrow{x})$$

$$note: a_{1} + a_{2} + ... + a_{N} = 1$$

Softmax regression (4 possible outputs) 4=1,2,3,4

#### Cost

#### Logistic regression

$$z = \overrightarrow{w} \cdot \overrightarrow{x} + b$$

$$a_1 = g(z) = \frac{1}{1 + e^{-z}} = P(y = 1 | \overrightarrow{x})$$

$$a_2 = 1 - a_1 = P(y = 0 | \overrightarrow{x})$$

$$\log s = -y \log a_1 - (1 - y) \log(1 - a_1)$$

$$|f| = 1$$

$$|f| = 0$$

$$J(\overrightarrow{w}, b) = \text{average loss}$$

#### Softmax regression

$$a_{1} = \frac{e^{z_{1}}}{e^{z_{1}} + e^{z_{2}} + \dots + e^{z_{N}}} = P(y = 1 | \vec{x})$$

$$\vdots$$

$$a_{N} = \frac{e^{z_{N}}}{e^{z_{1}} + e^{z_{2}} + \dots + e^{z_{N}}} = P(y = N | \vec{x})$$

$$Crossentropy loss$$

$$loss(a_{1}, \dots, a_{N}, y) = \begin{cases} -\log a_{1} & \text{if } y = 1 \\ -\log a_{2} & \text{if } y = 2 \end{cases}$$

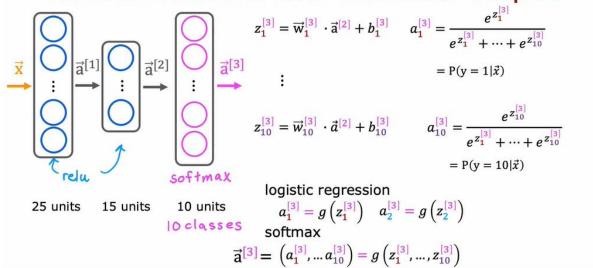
$$\vdots$$

$$-\log a_{N} & \text{if } y = N \end{cases}$$

$$|oss = -\log a_{1} & \text{if } y = 1 \end{cases}$$

3. Neural network with softmax output

## Neural Network with Softmax output

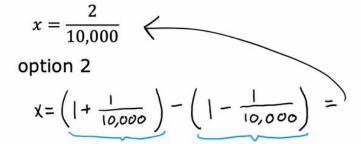


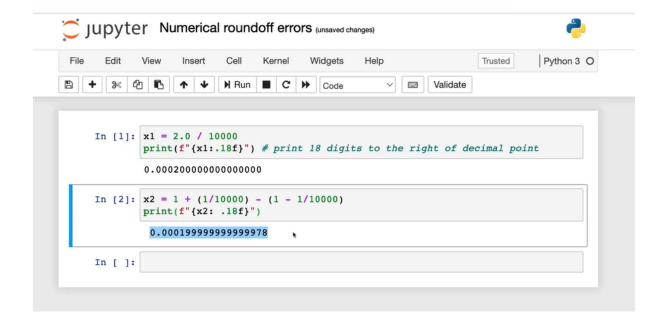


4. Improved implementation of softmax

## **Numerical Roundoff Errors**

option 1





#### Numerical Roundoff Errors

More numerically accurate implementation of logistic loss:  $|+\frac{1}{10,000}|$ model = Sequential([

Logistic regression:

(a)= 
$$g(z) = \frac{1}{1 + e^{-z}}$$

Dense(units=25, activation='relu'), Dense (units=15, activation='relu'), 'linear' Dense(units=1, activation='sigmoid')

Original loss
$$loss = -y \log(a) - (1-y)\log(1-a) \xrightarrow{\text{model.compile (loss=BinaryCrossEntropy (from_logits=True))}}$$

$$loss = -y \log(a) - (1-y)\log(1-a) \xrightarrow{\text{model.compile (loss=BinaryCrossEntropy (from_logits=True))}}$$

$$loss = -y \log\left(\frac{1}{1+e^{-z}}\right) - (1-y)\log(1-\frac{1}{1+e^{-z}})$$

$$loss = -y \log \left(\frac{1}{1 + e^{-z}}\right) - (1 - y) \log(1 - \frac{1}{1 + e^{-z}})$$

#### More numerically accurate implementation of softmax

Softmax regression

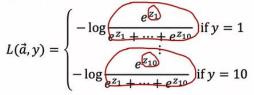
$$(a_{1},...,a_{10}) = g(z_{1},...,z_{10})$$

$$Loss = L(\vec{a},y) = \begin{cases} -\log(\vec{a}) & \text{if } y = 1 \\ -\log(\vec{a}_{10}) & \text{if } y = 10 \end{cases}$$

model = Sequential([ Dense(units=25, activation='relu'), Dense (units=15, activation='relu'), Dense(units=10, activation='softmax')

model.compile(loss=SparseCategoricalCrossEntropy() )

More Accurate





## MNIST (more numerically accurate)

model from tensorflow.keras import Sequential from tensorflow.keras.layers import Dense model = Sequential([ Dense (units=25, activation='relu'), Dense (units=15, activation='relu'), Dense(units=10, activation='linear') ]) loss from tensorflow.keras.losses import SparseCategoricalCrossentropy model.compile(...,loss=SparseCategoricalCrossentropy(from logits=True) ) fit model.fit(X,Y,epochs=100) logits = model(X)  $\leftarrow$  not  $a_1...a_{10}$   $f_x = tf.nn.softmax(logits)$   $a_1...a_{10}$ predict

# logistic regression (more numerically accurate)

5. Classification with multiple outputs

#### Multi-label Classification



Is there a car? 
$$yes$$
Is there a bus?  $yes$ 
Is there a pedestrian  $yes$ 

$$yes$$

### Multi-label Classification



Alternatively, train one neural network with three outputs

$$\vec{x} = \begin{bmatrix} \vec{a}_1^{[3]} \\ \vec{a}_2^{[3]} \end{bmatrix}$$

$$\vec{a}_3^{[3]} = \begin{bmatrix} \vec{a}_1^{[3]} \\ \vec{a}_2^{[3]} \\ \vec{a}_3^{[3]} \end{bmatrix}$$
bus
pedestrian

activations

#### 6. Practice quiz

For a multiclass classification task that has 4 possible outputs, the sum of all the activations adds up to 1. For a multiclass classification task that has 3 possible outputs, the sum of all the activations should add up to ....

1

O More than 1

O It will vary, depending on the input x.

O Less than 1

#### 

Yes! The sum of all the softmax activations should add up to 1. One way to see this is that if  $e^{z_1}=10, e^{z_2}=20, e^{z_3}=30$ , then the sum of  $a_1+a_2+a_3$  is equal to  $\frac{e^{z_1}+e^{z_2}+e^{z_3}}{e^{z_1}+e^{z_2}+e^{z_3}}$  which is 1.

For multiclass classification, the cross entropy loss is used for training the model. If there are 4 possible classes for the output, and for a particular training example, the true class of the example is class 3 (y=3), then what does the cross entropy loss simplify to? [Hint: This loss should get smaller when  $a_3$  gets larger.]

 $\bigcirc -log(a_3)$ 

O z\_3/(z\_1+z\_2+z\_3+z\_4)

O z\_3

 $\bigcirc \frac{-log(a_1) + -log(a_2) + -log(a_3) + -log(a_4)}{4}$ 

#### 

Correct. When the true label is 3, then the cross entropy loss for that training example is just the negative of the log of the activation for the third neuron of the softmax. All other terms of the cross entropy loss equation  $(-log(a_1), -log(a_2), and - log(a_4))$  are ignored

For multiclass classification, the recommended way to implement softmax regression is to set from\_logits=True in the loss function, and also to define the model's output layer with...

a 'linear' activation

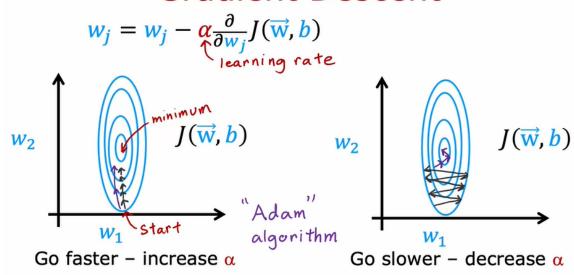
a 'softmax' activation

#### 

Yes! Set the output as linear, because the loss function handles the calculation of the softmax with a more numerically stable method.

1. Advance optimization

## **Gradient Descent**



## Adam Algorithm Intuition

Adam: Adaptive Moment estimation not just one &

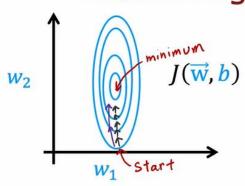
$$w_{1} = w_{1} - \alpha_{1} \frac{\partial}{\partial w_{1}} J(\overrightarrow{w}, b)$$

$$\vdots$$

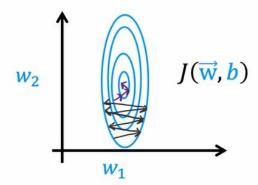
$$w_{10} = w_{10} - \alpha_{10} \frac{\partial}{\partial w_{10}} J(\overrightarrow{w}, b)$$

$$b = b - \alpha_{11} \frac{\partial}{\partial b} J(\overrightarrow{w}, b)$$

## Adam Algorithm Intuition



If  $w_j$  (or b) keeps moving in same direction, increase  $\alpha_j$ .



If  $w_j$  (or b) keeps oscillating, reduce  $\alpha_j$ .

#### MNIST Adam

#### model

```
model = Sequential([
        tf.keras.layers.Dense(units=25, activation='sigmoid'),
        tf.keras.layers.Dense(units=15, activation='sigmoid'),
        tf.keras.layers.Dense(units=10, activation='linear')
])
```

#### compile

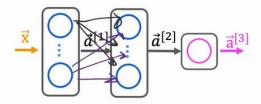
d=10-3=0.001 model.compile(optimizer=tf.keras.optimizers.Adam(learning\_rate=1e-3), loss=tf.keras.losses.SparseCategoricalCrossentropy(from\_logits=True))

fit

model.fit(X,Y,epochs=100)

#### 2. Additional layer types

## Dense Layer



Each neuron output is a function of all the activation outputs of the previous layer.

$$\vec{a}_1^{[2]} = g \left( \vec{w}_1^{[2]} \cdot \vec{a}^{[1]} + b_1^{[2]} \right)$$

## Convolutional Layer



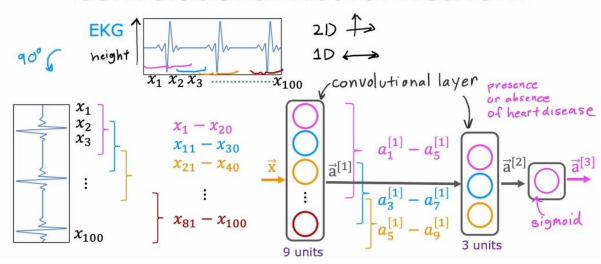


Each neuron only looks at part of the previous layer's outputs.

#### Why?

- Faster computation
- · Need less training data (less prone to overfitting)

## Convolutional Neural Network



#### 3. Practice quiz

The Adam optimizer is the recommended optimizer for finding the optimal parameters of the model. How do you use the Adam optimizer in TensorFlow?

- The Adam optimizer works only with Softmax outputs. So if a neural network has a Softmax output layer, TensorFlow will automatically pick the Adam optimizer.
- O The call to model.compile() will automatically pick the best optimizer, whether it is gradient descent, Adam or something else. So there's no need to pick an optimizer manually.
- O The call to model.compile() uses the Adam optimizer by default
- When calling model.compile, set optimizer=tf.keras.optimizers.Adam(learning\_rate=1e-3).

#### ✓ Correct

Correct. Set the optimizer to Adam.

The lecture covered a different layer type where each single neuron of the layer does not look at all the values of the input vector that is fed into that layer. What is this name of the layer type discussed in lecture?

- O Image layer
- O A fully connected layer
- convolutional layer
- 1D layer or 2D layer (depending on the input dimension)

#### 

Correct. For a convolutional layer, each neuron takes as input a subset of the vector that is fed into that layer.

#### **Back Propagation**

#### 1. What is a derivative?

## **Derivative Example**

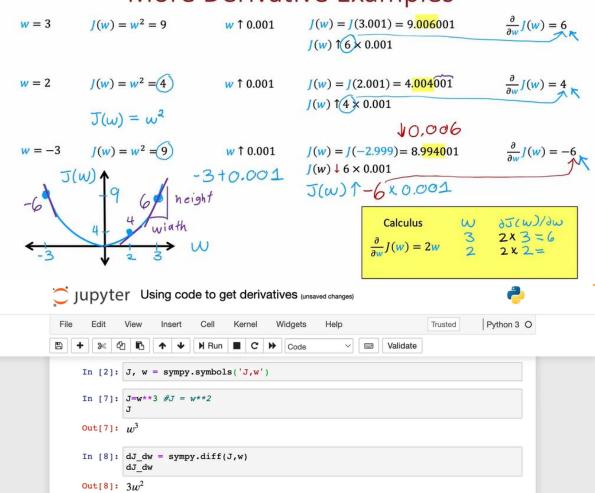
Cost function 
$$J(\omega) = \omega^2$$
  
Say  $w = 3$   $J(\omega) = 3^2 = 9$   
If we increase  $w$  by a tiny amount  $\varepsilon = 0.001$  how does  $J(w)$  change?  
 $w = 3 + 0.001 0.002$  If  $\omega = 0.002$   $\varepsilon = 0.002$ 

## Informal Definition of Derivative

If 
$$\underline{w} \uparrow \varepsilon$$
 causes  $\underline{J(w)} \uparrow (k \times \varepsilon)$  then 
$$\frac{\partial}{\partial w} J(w) = k$$
Gradient descent repeat {
$$w_j = w_j - \alpha \frac{\partial}{\partial w_j} J(\overline{w}, b)$$
}

If derivative is <u>small</u>, then this update step will make a <u>small</u> update to  $w_j$  If the derivative is large, then this update step will make a large, update to  $w_j$ 

## More Derivative Examples

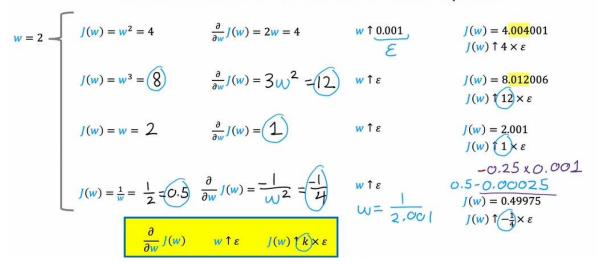


## **Even More Derivative Examples**

In [9]: dJ\_dw.subs([(w,2)])

Out[9]: 12

In [ ]:



#### A note on derivative notation

If J(w) is a function of one variable (w),

$$\frac{d}{dw}J(w)$$

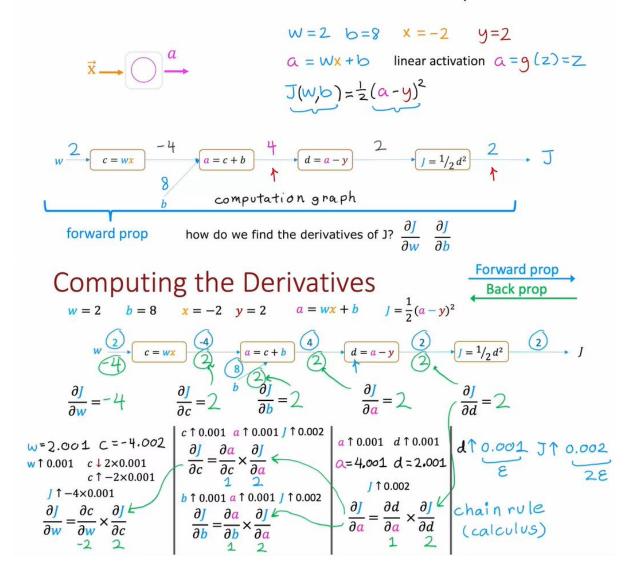
If  $J(w_1, w_2, ..., w_n)$  is a function of more than one variable,

$$\frac{\partial}{\partial w_i} J(w_1, w_2, ..., w_n) \qquad \frac{\partial J}{\partial w_i}$$
u partial derivative"

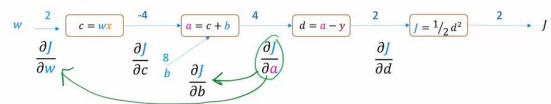
notation used in these courses

#### 2. Computation graph

#### Small Neural Network Example



#### Backprop is an efficient way to compute derivatives

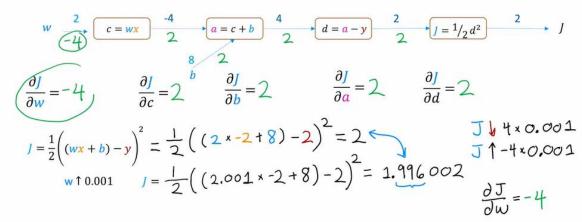


Compute  $\frac{\partial J}{\partial a}$  once and use it to compute both  $\frac{\partial J}{\partial w}$  and  $\frac{\partial J}{\partial h}$ .

If N nodes and P parameters, compute derivatives in roughly N + P steps rather than  $N \times P$  steps.

# Computing the Derivatives $b = 8 \quad x = -2 \quad y = 2 \quad a = wx + b \quad J = \frac{1}{2}(a - y)^2$

$$w = 2$$
  $b = 8$   $x = -2$   $y = 2$   $a = wx + b$   $J = \frac{1}{2}(a - y)^2$ 



#### 3. Larger neural network example

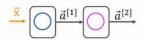
# Neural Network Example $x = 1 \ y = 5$ $w^{[1]} = 2, b^{[1]} = 0$ $w^{[2]} = 3, b^{[2]} = 1$ $g(z) = \max(0, z)$ $g(z) = \max(0, z)$ $g(z) = \max(0, z)$

$$a^{[1]} = g(w^{[1]} \times b^{[1]}) = w^{[1]} \times b^{[1]} = 2 \times 1 + 0 = 2$$

$$a^{[2]} = g(w^{[2]} a^{[1]} + b^{[2]}) = w^{[2]} a^{[1]} + b^{[2]} = 3 \times 2 + 1 = 7$$

$$J(w,b) = \frac{1}{2}(a^{[2]} - y)^2 = \frac{1}{2}(7 - 5)^2 = 2$$

# Neural Network Example x = 1 y = 5Network Example ReLU activation



$$w^{[2]} = 3, b^{[2]} = 1$$
  $g(z) = \max(0, z)$ 

$$g(z) = \max(0, z)$$

 $a^{[1]} = g(w^{[1]} x + b^{[1]}) = w^{[1]} x + b^{[1]} = 2 \times 1 + 0 = 2$   $a^{[2]} = g(w^{[2]} a^{[1]} + b^{[2]}) = w^{[2]} a^{[1]} + b^{[2]} = 3 \times 2 + 1 = 77.003$   $J \uparrow (6 \times 0.001) \xrightarrow{\partial W^{[1]}} = 6$   $J(w, b) = \frac{1}{2} (a^{[2]} - y)^2 = \frac{1}{2} (7 - 5)^2 = 2 2 (7 - 5)^2$ 

N nodes D+D+D

NXP

dJ dw [2] db [2]

P parameters W1, b2, b2...

efficient way (backprop)

N+P