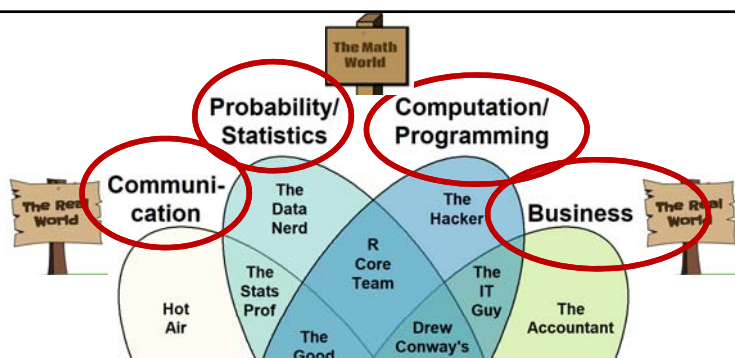
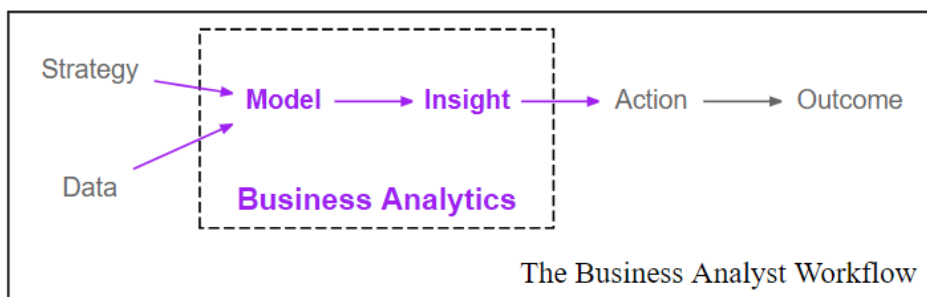


Graphical Models and Intro to greta/causact

Speaking Data Analytics



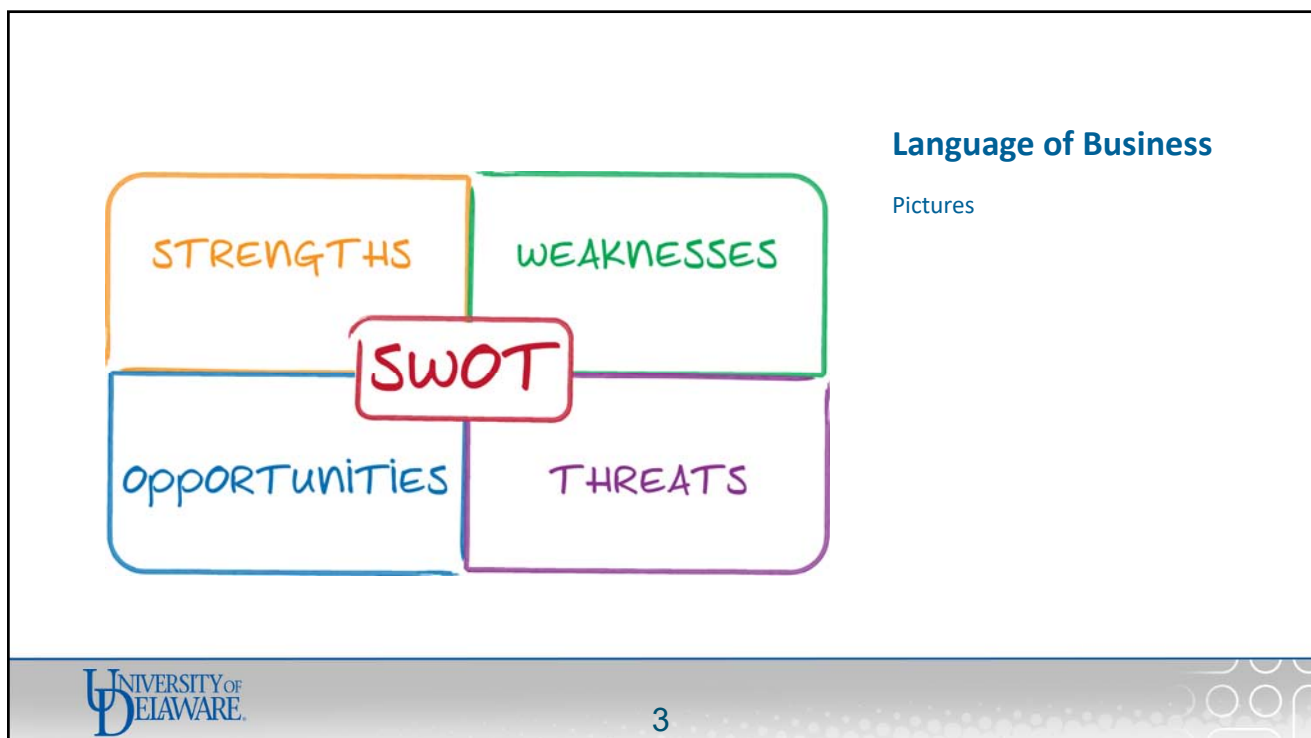
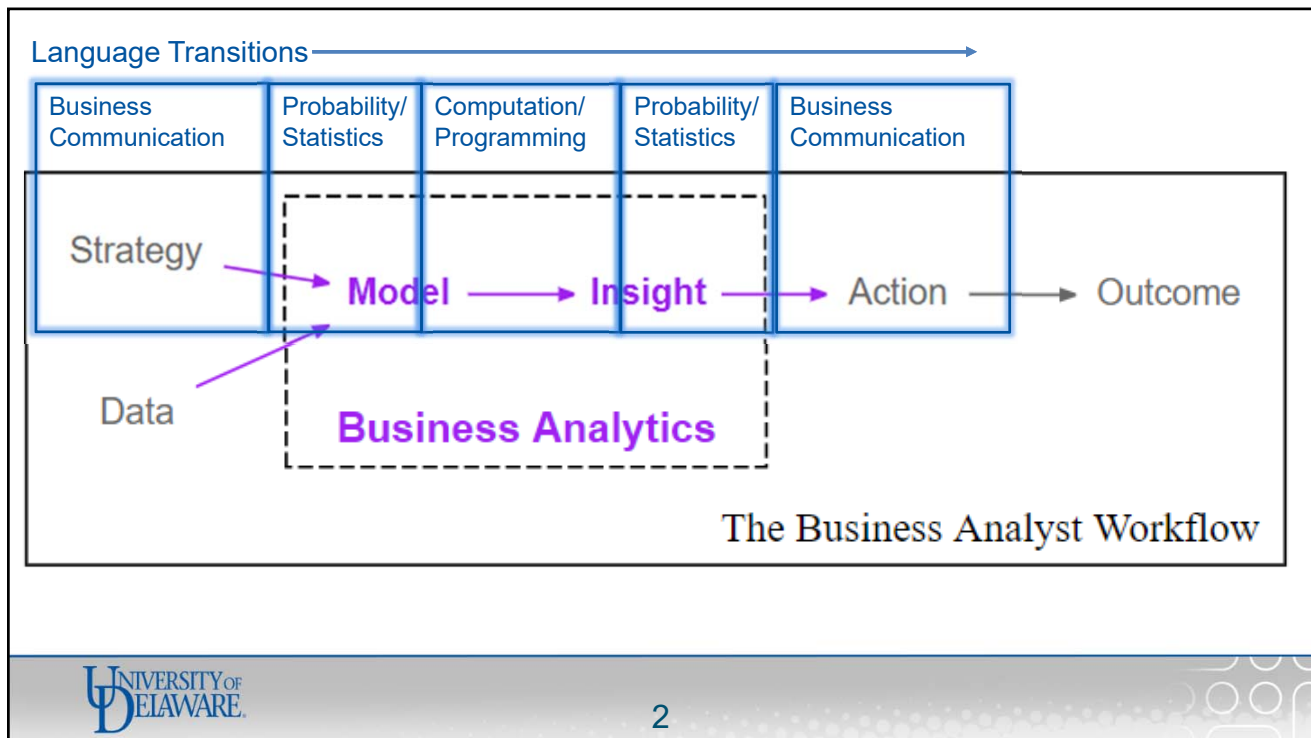
Data Science Venn Diagram



The Business Analyst Workflow

[://bit.ly/2BjqdBt](https://bit.ly/2BjqdBt)





$$\begin{aligned}
 K_i &\sim \text{Binomial}(n_i, p_i) \\
 p_i &= \text{ilogit}(\alpha_j + \beta_j x_i) \\
 \alpha_j &\sim \text{Normal}(\alpha, \sigma_\alpha) \\
 \beta_j &\sim \text{Normal}(\beta, \sigma_\beta) \\
 \alpha &\sim \text{Normal}(0, 10) \\
 \sigma_\alpha &\sim \text{Uniform}(0, 5) \\
 \beta &\sim \text{Normal}(0, 2) \\
 \sigma_\beta &\sim \text{Uniform}(0, 5)
 \end{aligned}$$

Language of Statistics

Formulas

```

class BnLayer(nn.Module):
    def __init__(self, n1, nf, stride=2):
        super().__init__()
        self.conv = nn.Conv2d(n1, nf, kernel_size=3, stride=stride, bias=False, padding=1)
        self.a = nn.Parameter(torch.zeros(nf, 1, 1))
        self.m = nn.Parameter(torch.ones(nf, 1, 1))

    def forward(self, x):
        x = F.relu(self.conv(x))
        x_chan = x.transpose(0, 1).contiguous().view(x.size(1), -1)
        if self.training:
            self.means = x_chan.mean(1)[None, None]
            self.stds = x_chan.std(1)[None, None]
        x = x - self.means
        x = x / self.stds
        return x * self.m + self.a

class ResnetLayer(BnLayer):
    def forward(self, x): return x + super().forward(x)

class Resnet(nn.Module):
    def __init__(self, layers, c):
        super().__init__()
        self.layers = nn.ModuleList([BnLayer(layers[1], layers[1+1])
                                     for i in range(len(layers) - 1)])
        self.layers2 = nn.ModuleList([ResnetLayer(layers[i+1], layers[i + 1], 1)
                                     for i in range(len(layers) - 1)])
        self.layers3 = nn.ModuleList([ResnetLayer(layers[i+1], layers[i + 1], 1)
                                     for i in range(len(layers) - 1)])
        self.out = nn.Linear(layers[-1], c)

    def forward(self, x):
        for l1, l2, l3 in zip(self.layers, self.layers2, self.layers3):
            x = l3(l2(l1(x)))
        x = F.adaptive_max_pool2d(x, 1)
        x = x.view(x.size(0), -1)
        return F.log_softmax(self.out(x), dim=-1)

```

Language of Computers

Code

$$\begin{aligned}
 K_i &\sim \text{Binomial}(n_i, p_i) \\
 p_i &= \text{ilogit}(\alpha_j + \beta_j x_i) \\
 \alpha_j &\sim \text{Normal}(\alpha, \sigma_\alpha) \\
 \beta_j &\sim \text{Normal}(\beta, \sigma_\beta) \\
 \alpha &\sim \text{Normal}(0, 10) \\
 \sigma_\alpha &\sim \text{Uniform}(0, 5) \\
 \beta &\sim \text{Normal}(0, 2) \\
 \sigma_\beta &\sim \text{Uniform}(0, 5)
 \end{aligned}$$

```

class BiLayer(nn.Module):
    def __init__(self, nI, nF, stride=2):
        super().__init__()
        self.conv = nn.Conv2d(nI, nF, kernel_size=stride, stride=stride, bias=False, padding=1)
        self.a = nn.Parameter(torch.zeros(nF, 1, 1))
        self.b = nn.Parameter(torch.zeros(nF, 1, 1))

    def forward(self, x):
        a = F.relu(self.conv(x))
        a_chan = a.transpose(0, 1).contiguous().view(-1, -1)
        if self.training:
            self.mean = a_chan.mean(1); None, None
            self.std = a_chan.std(1); None, None
        a = a - self.mean
        a = a / self.std
        return a*self.a+self.b

class ResnetLayer(BiLayer):
    def forward(self, x): return x + super().forward(x)

class Resnet(nn.Module):
    def __init__(self, layers, c):
        super().__init__()
        self.layers = nn.ModuleList([BiLayer(layers[0], layers[0]-1)])
        for i in range(layers-1):
            self.layers.append(ResnetLayer(layers[i+1], layers[i] + 1, 1))
        self.layers.append(ResnetLayer(layers[-1], layers[-1] + 1, 1))
        self.layers.append(BiLayer(layers[-1], layers[-1] + 1, 1))
        self.pool = nn.Linear(layers[-1], c)

    def forward(self, x):
        for i, l in enumerate(self.layers):
            x = l(x)
        x = F.softmax(x)
        x = F.softmax(x).view(-1, 1)
        return F.log_softmax(x, dim=-1)

```

Joint Distribution Milestone

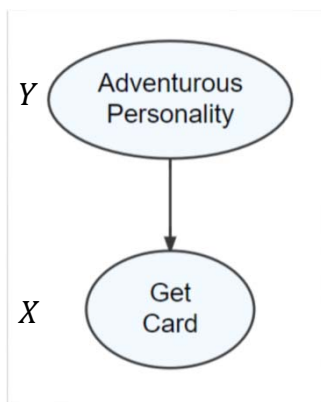
x	y	P(x,y)
0	Toyota Corolla	50%
0	Jeep Wrangler	5%
0	Subaru Outback	5%
0	Kia Forte	4%
1	Toyota Corolla	10%
1	Jeep Wrangler	15%
1	Subaru Outback	10%
1	Kia Forte	1%

Output We Want For Making Decisions Under Uncertainty
A Joint Distribution

6



Wanted:
The Rosetta Stone
Of Data Science

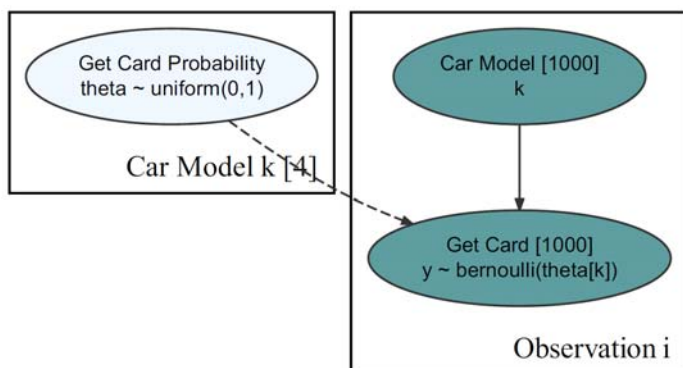

 $P(Y)$
 $P(X|Y)$

The DAG

Nodes are random variables

Edges drawn from parent to child indicate a node's uncertainty is expressed conditionally on its parents

$$P(X, Y) = P(Y) \times P(X|Y)$$



CAUSACT and GRETA Demo

Plates represent a duplication of the random variables inside of them. One per member of the plate's index. For example, there are four car models, hence we will get four theta values.

Mathematical models of distributional assumptions of the random variable are shown.

Walk through R-Code files:

DAGModellingWalkthrough.R

betaDist.R

creditCard.R