

## Release Notes for FS-G7P Transmitter Firmware/FS-G7P 软件版本更新记录

Software version 软件版本	1.0.44	Date 日期	10/2025
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- **新增功能：**
1. 新增 [ 低信号报警 ] 功能：  
可以开启或关闭此功能；  
可以开启或关闭报警声音；  
可设置报警值和报警重复周期。
  2. 新增 [ 遥测报警 ] 功能：  
可以开启或关闭此功能；  
可以开启或关闭报警声音；  
可以设置报警灵敏度，避免短暂干扰导致丢失报警。
  3. 新增 [ 竞赛模式 ] 功能项，通过它可快速关闭 [ 低信号报警 ] 功能和 [ 遥测报警 ] 功能。
- **修改功能：**
1. 修改 [ 失控保护 ] 功能，增加失控保护判断时间。
  2. 修复触发计时器复位后报警未复位至所设置状态的问题。
  3. 修改 [ 模型选择 ] 功能，提供 12 组模型数据供选择。
  4. 提升高频刷新速率以获得更平滑的舵机响应。
  5. 修复其他已知问题。
- **特殊变化：** 无

### 注意事项

- 进行固件更新时，建议先使用富斯遥控管家将模型数据进行备份，更新完成后再将备份好的模型数据导入到新的固件中。
- 使用遥控管家备份数据时，须注意以下版本兼容性问题：3.3.5 及以后版本不兼容 3.3.5 之前版本（即 3.0.4 及更早版本互相兼容，3.3.5、4.0.1 及以后版本互相兼容）。因此，导出或导入模型数据时，必须使用相互兼容版本的遥控管家进行操作。

# FLYSKY

## Release Notes for FS-G7P Transmitter Firmware/FS-G7P 软件版本更新记录

Software version 软件版本	1.0.44	Date 日期	10/2025
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- ▶ **New functions:**
  1. Added **LOW SIGNAL ALARM** function:  
The function can be enabled or disabled.  
Alarm sound can be enabled or disabled.  
Alarm value and alarm repetition cycle can be set.
  2. Added **TELEMETRY LOSS** function:  
The function can be enabled or disabled.  
Alarm sound can be enabled or disabled.  
Alarm sensitivity can be set to avoid loss alarms due to brief interference.
  3. Added **RACE MODE** function, which allows for quick disabling of the **LOW SIGNAL ALARM** function and the **TELEMETRY LOSS** function.
- ▶ **Modified functions:**
  1. Modified **Failsafe** function, **RESPONSE TIME** is added.
  2. Fixed the issue where the alarm does not reset to the set state after the trigger timer resets.
  3. Modified the **MODEL** function, 12 sets of model data are provided for selection.
  4. Achieve smoother servo response by improving the RF refresh rate.
  5. Fixed other known issues.
- ▶ **Special changes :**
  - None

### Notes

1. In case of updating the firmware, it is recommended to back up the model data via FlySkyAssistant. And after the firmware has been upgraded, then import the backup model data to the new firmware.
2. When using FlySkyAssistant to back up data, observe the following version-compatibility rules.
  - 3.3.5 and later are incompatible with any release before 3.3.5.
  - 3.0.4 and earlier are mutually compatible.
  - 3.3.5, 4.0.1, and all later releases are mutually compatible.Therefore, export or import model data only with mutually compatible versions of FlySkyAssistant.

## Release Notes for FS-G7P Transmitter Firmware/FS-G7P 软件版本更新记录

Software version 软件版本	1.0.31	Date 日期	06/2024
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- 新增功能：

无
- 修改功能：

1. 优化发射机重新开机后设置数据丢失的问题。

2. 修复将 CH4 分配至 TR-Y 按键后无法生效的问题。
- 特殊变化：

无

### 注意事项

- 进行固件更新时，建议先使用富斯遥控管家将模型数据进行备份，更新完成后再将备份好的模型数据导入到新的固件中。

- New functions:

• None
- Modified functions:

1. Optimized the issue of losing setting datas after restarting the transmitter.

2. Fixed the issue that assigning CH4 to the TR-Y key does not take effect.
- Special changes :

• None

### Notes

- In case of updating the firmware, it is recommended to back up the model data via FlySkyAssistant. And after the firmware has been upgraded, then import the backup model data to the new firmware.

## Release Notes for FS-G7P Transmitter Firmware/FS-G7P 软件版本更新记录

Software version 软件版本	1.0.30	Date 日期	05/2023
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- ▶ 新增功能：无
- ▶ 修改功能：
  1. 修复对码 FS-R7V 陀螺仪接收机使用时舵量异常的问题。
  2. 修复在发射机与 FS-R7V 陀螺仪接收机未双向对码的状态下可进入智能车控功能的问题。
  3. 修复其他已知问题。
- ▶ 特殊变化：无

### 注意事项

1. 进行固件更新时，建议先使用富斯遥控管家将模型数据进行备份，更新完成后再将备份好的模型数据导入到新的固件中；
2. 为了给您带来更好的使用体验，建议将 FS-G7P 发射机固件版本升级至 V1.0.30 版本。

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- ▶ New functions:
    - None
  - ▶ Modified functions:
    1. Fix the bug of abnormal EPA(End point adjustment) when using with the FS-R7V gyroscope receiver.
    2. Fix the bug that the SVC function is available in case of no two-way binding between the transmitter and the FS-R7V gyroscope receiver.
    3. Fix other known issues.
  - ▶ Special changes :
    - None

### Notes

1. In case of updating the firmware, it is recommended to back up the model data via FlySkyAssistant. And after the firmware has been upgraded, then import the backup model data to the new firmware.
2. To bring you a better experience, it is recommended to upgrade the firmware version of FS-G7P transmitter to V1.0.30.

## Release Notes for FS-G7P Transmitter Firmware/FS-G7P 软件版本更新记录

Software version 软件版本	1.0.28	Date 日期	12/2022
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- **新增功能：**
1. 新增 [ 防抱死刹车 ] 功能。
  2. 新增 [ 油门怠速 ] 功能。
  3. 新增 [ 油门锁定 ] 功能。
  4. 新增 [ 通道速度 ] 功能。
  5. 新增 [ 背光亮度 ] 调节功能。
    - 根据不同环境，可调节屏幕亮度。
  6. 新增 [ 息屏时间 ] 调节功能。
    - 发射机进入息屏状态后，可操作五向按键将发射机退出息屏状态。
  7. 新增 [ 失控保护提示 ] 功能。
    - 可根据实际需要，关闭或开启失控保护设置提醒功能。
  8. 新增转速传感器设置界面。
    - 可设置轮子周长以及复位里程。
  9. 新增 [ RF 系统 ] 功能。
    - 分为 Routine 和 Fast 模式，不同模式适应不同的应用环境。Routine 模式：抗干扰更强，Fast 模式延时更低。
  10. 新增低电和超低电压弹窗提示。
    - 防止电池过放或电池电压过低。若因电压过低进而导致发射机强制关机，则不保存电压过低时调整过的数据。
  11. 主页新增可显示 BVD 电压和信号强度信息。
    - 主页下，长按五向按键中键 2S 可选中计时器显示区域，再次按下五向按键中键进入选择界面，选择 [ 传感器 ] 即可。
  12. [ 摇杆校准 ] 功能新增 VR1 旋钮校准。
- **修改功能：**
1. 修改副页 2 传感器显示界面
    - 用户可自定义显示哪些传感器。
  2. 修复已知 Bug 问题
    - 如 SW2 与 TR1 在 [ 按键设定 ] 功能中的冲突问题。
- **特殊变化：** 无

### 注意事项

1. 进行固件更新时，建议先使用富斯遥控管家将模型数据进行备份，更新完成后再将备份好的模型数据导入到新的固件中。
2. 切换不同的 RF 系统后，需要重新对码。
3. 固件更新后，需重新进行摇杆校准。

## Release Notes for FS-G7P Transmitter Firmware/FS-G7P 软件版本更新记录

Software version 软件版本	1.0.28	Date 日期	12/2022
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- **New functions:**
1. Add **ABS** function.
  2. Add **IDLE UP** function.
  3. Add **ENG CUT** (engine cut)function.
  4. Add **CH SPEED**(channel speed) function.
  5. Add **BACKL**(backlight) function.
    - To adjust the screen brightness depending on the condition.
  6. Add **SCREEN TIME** function.
    - When the transmitter's screen is off, you can toggle the Five-way button, then the screen will be on.
  7. Add **FAILSAFE TIPS** function.
    - To set this function on or off according to actual case.
  8. Add RPM sensor setup interface in **SENSOR** function
    - If a RPM sensor is connected to the transimmitter successful, you can set thecircumference of wheel, as well as resetting the milestone.
  9. Add **RF SYS**(RF system) function.
    - Two modes are included, Routine and Fast. Different modes adapt to different application environments. Routine mode has stronger anti-interference, and Fast mode has lower latency.
  10. Add pop-up prompt for low voltage and ultra low voltage.
    - To avoid the battery being over-dischargeing or in ultra low state. If the voltage is too low to cause shutdown, the data set during the period of the low voltage cannot be saved.
  11. Add the display of the **BVD voltage** and **SIGNAL** strength in main interface.
    - Located in main interface, press and hold the Center key of Five-way button to select the area of the Timer. Afterwards, press the Center key again to access the setting interface, then select the **SENSOR**. The **BVD voltage** and **SIGNAL** strength will display in the main interface.
  12. Add **VR1** knob calibration in **CALIBRATION** function.
- **Modified functions:**
1. Revise the display of sensor in main2 interface.
    - To set the sensors displayed in main2 interface.
  2. Fix the known bugs.
    - such as the conflict between SW2 and TR1 in **SW ASSIGN** (switch assignment) function.
- **Special changes :**
- None



## Release Notes for FS-G7P Transmitter Firmware/FS-G7P 软件版本更新记录

Software version 软件版本	1.0.28	Date 日期	12/2022
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### Notes

1. In case of updating the firmware, it is recommended to back up the model data via FlySkyAssistant. And after the firmware has been upgoaded, then import the backup model data to the new firmware.
2. Remember to bind the transmitter and the receiver again after switching the RF system.
3. Do the calibrtn after the firmware has been updated.

## Release Notes for FS-G7P Transmitter Firmware/FS-G7P 软件版本更新记录

Software version 软件版本	1.0.24	Date 日期	05/2022
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► **新增功能：** • 新增支持高度传感器功能。

► **修改功能：** • 修复了已知 Bug 问题。

► **特殊变化：** • 无

### 注意事项

- **修改闲置报警功能逻辑：**
  - ① 超过设置的时间
    - 未操作任何控件（包含手轮和扣机）：息屏 + 蜂鸣器报警；
    - 操作手轮或扣机：仅息屏；
    - 操作除手轮和扣机以外的控件：闲置报警蜂鸣器关闭，屏幕亮度恢复到息屏前的状态。
  - ② 息屏 + 蜂鸣器报警状态下
    - 操作手轮或扣机：闲置报警蜂鸣器关闭，保持息屏状态；
    - 操作除手轮和扣机以外的控件：闲置报警蜂鸣器关闭，屏幕亮度恢复到息屏前的状态。
  - ③ 息屏状态下
    - 操作手轮或扣机：保持息屏状态；
    - 操作除手轮和扣机以外的控件：屏幕亮度恢复到息屏前的状态。

► **New functions:** • Add the function of supporting the altitude sensor.

► **Modified functions:** • Fix the known bugs.

► **Special changes :** • None

### Notes

- **Modify the IDLE ALARM functional logic.**
  - ① Setting time expired
    - No operations on any control including Steering Wheel and Throttle Trigger: Screen turn-off + buzzer alarm.
    - Operations on Steering Wheel or Throttle Trigger: Screen turn-off only.



## Release Notes for FS-G7P Transmitter Firmware/FS-G7P 软件版本更新记录

Software version 软件版本	1.0.24	Date 日期	05/2022
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### Notes

- Operations on controls other than **Steering Wheel** and **Throttle Trigger**: The idle alarm buzzer is turned off and the screen brightness returns to the state prior to screen turn-off.
- ② Screen turn-off + buzzer alarm
- Operations on **Steering Wheel** or **Throttle Trigger**: The idle alarm buzzer is turned off and the screen turn-off state remains.
  - Operations on controls other than **Steering Wheel** and **Throttle Trigger**: The idle alarm buzzer is turned off and the screen brightness returns to the state prior to screen turn-off.
- ③ Screen turn-off
- Operations on **Steering Wheel** or **Throttle Trigger**: The screen turn-off state remains.
  - Operations on controls other than **Steering Wheel** and **Throttle Trigger**: The screen brightness returns to the state prior to screen turn-off.

## Release Notes for FS-G7P Transmitter Firmware/FS-G7P 软件版本更新记录

Software version 软件版本	1.0.23	Date 日期	04/2022
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- ▶ **新增功能：**
  - 新增识别 FS-CVT01 传感器功能。
- ▶ **修改功能：**
  - 修复了已知 Bug 问题。
- ▶ **特殊变化：**
  - 无

### 注意事项

- 更新完成后，仍保留上一版本设置的传感器高低位报警值，需重新设置新限位。例如上一版本 TX 高位报警值为 6V，低位报警值为 7V，更新完成后仍保留上一版本设置，需要重新设置报警值，设置后低位报警值数值不会高过高位报警值数值。

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- ▶ **New functions:**
    - Adds the function of identifying the FS-CVT01 sensor.
  - ▶ **Modified functions:**
    - Fixes the known bugs.
  - ▶ **Special changes :**
    - None

### Note

- After the update is finished, the high and low alarm values of the sensor set in the earlier version are still retained, and the new limit values need to be reset. For example, in the earlier version, TX high alarm value is 6V and low alarm value is 7V, after the update is finished, the settings of the earlier version are still retained. Therefore, you need to reset the alarm values. After setting the alarm values, the low alarm value will not be higher than the high alarm value.