The Decelerationist Agenda:

Diversifying Education, Material Infrastructures, and Computation to Slow AGI Assimilation

Flyxion

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Abstract

Artificial General Intelligence (AGI) advances most rapidly in conditions of homogeneity: standardized curricula, centralized infrastructures, and fungible training corpora. The *Decelerationist Agenda* proposes a constructive slowdown strategy rooted in structured diversification across education, texts, computation, and materials. Using the Relativistic Scalar Vector Plenum (RSVP) heuristic—capacity Φ , flows \mathbf{v} , and entropy S—we argue that pluralizing substrates raises global entropy while preserving local task-solvability, frustrating monocultural assimilation by frontier models. We first situate the agenda historically against effective accelerationism (e/acc), survey critiques, and then set out testable interventions and diagnostics. Additionally, we explore parsing as the deep substrate of intelligence, formalizing current AI as concatenated parsers and AGI as recursive general parsers, with implications for decelerationist strategies.

1 Definition and Historical Context

1.1 What is Effective Accelerationism (e/acc)?

Effective accelerationism (e/acc) is a contemporary techno-optimist current that advocates rapidly advancing technology—especially AI—as a moral imperative for growth and even cosmological ends, frequently rejecting regulation as harmful friction (52; 2; 55; swa). The movement has been popularized by Silicon Valley figures and online discourse, often positioned as a counterweight to AI safety or precautionary governance. Proponents view intelligence as an entropy-maximizing force, drawing on thermodynamic principles to argue that accelerating technological progress aligns with universal tendencies toward increased dissipation (54).

1.2 Accelerationism's Intellectual Roots

The label accelerationism originates in critical theory and post-structuralist currents (Deleuze & Guattari, Lyotard, Baudrillard), historically aimed at diagnosing or sublating capitalism rather

than endorsing deregulated techno-capitalism per se (28; 1; 46). Contemporary e/acc selectively inherits the *speed* motif while largely discarding the original anti-capitalist or post-capitalist programmatic aims. For instance, early accelerationism sought to exacerbate capitalism's contradictions to hasten its collapse, whereas e/acc aligns with hyper-capitalist deregulation (28).

2 Philosophical Critiques of e/acc

Naturalistic fallacy and value reductionism. A recurring critique is that e/acc slides from descriptive thermodynamics to normative ethics—from "dissipation occurs" to "we therefore ought to accelerate dissipation/progress"—a classic naturalistic fallacy. Even work on dissipative adaptation (e.g., England's nonequilibrium self-assembly) is explanatory, not prescriptive (54; 59; 11). Conflating entropy-production with moral good neglects plural human values (well-being, justice, rights). Value naturalists argue that e/acc oversimplifies ethics by equating progress with entropy maximization, ignoring compassion, cooperation, and ethical reasoning (24; 33).

Agency, free will, and teleology. If "progress" is treated as quasi-deterministic, human moral agency risks being sidelined by a narrative of technological inevitability. Critics argue that practical ethics requires deliberation and governance, not mere facilitation of whatever increases growth or dissipation (28; 25). This deterministic view undervalues moral agency and treats society as a passive meta-organism rather than a domain for deliberate choices (26).

3 Rhetorical and Cultural Critiques

Observers note a macho or antagonistic tone in parts of e/acc discourse (e.g., "doomers"/"decels" as out-groups), alongside a posture that alternates between bravado and submission to AI as a higher telos (2; 57; 26). Journalistic analyses describe the vibe as aesthetics-forward and policy-light, with limited engagement on systemic issues like monopolies and externalities (55; 57; 32). Critics liken it to a cult prioritizing memetic appeal over substance (27; 32).

4 Risk and Safety Concerns

Orthogonality and instrumental convergence. Technical safety literature emphasizes that intelligence and final goals are orthogonal (Bostrom), and that capable agents tend to seek convergent instrumental subgoals (Omohundro) such as self-preservation and resource acquisition (53; 58; 4). Disregarding these theses raises misalignment risks at scale. E/acc's dismissal of existential risks exacerbates dangers, given historical mishandling of technologies like nuclear weapons (26; 22).

Precaution and governance. U.S. officials and policymakers have warned that "move fast and break things" is ill-suited to high-stakes AI; calls for governance and guardrails span the political

spectrum (60). In practice, sectors with substantial negative externalities (biotech, nuclear, finance) employ layered oversight; the argument that AI should be exempt demands a stronger burden of proof than e/acc typically supplies (swa; 24).

5 Economic and Ideological Deviations

Historically, accelerationism critiqued capitalism's contradictions; e/acc tends to align with hyper-capitalist deregulation and market primacy (28; 46). This stance downplays well-documented market failures—monopoly power, externalities, labor exploitation—even as it advances a cosmological rhetoric of abundance (52; 55). Critics argue this is a philosophical veneer for profit-maximizing imperatives rather than a universal humanistic project (57; 33; 29). Furthermore, e/acc ignores sustainability issues, assuming endless growth on a finite planet, which overlooks ecological limits (21).

6 Stakeholder Perspectives

Safety researchers foreground alignment and governance; journalists and scholars question e/acc's normative leap from physics to ethics; policymakers emphasize responsibility and institutional design (53; 58; 60; 59). Indigenous perspectives caution against single-minded pursuit of progress, emphasizing connection to land over technology (21). The upshot: progress must be coupled to plural values, not collapsed into speed alone (23; 30).

7 RSVP: Slowdown by Structured Diversification

We frame slowdown as governance over three fields:

- Capacity (Φ): representational/structural bandwidth.
- Flows (v): directional propagation of meaning, resources, or interactions.
- Entropy (S): unresolved ambiguity/diversity sustaining multiple interpretations.

AGI thrives when Φ is concentrated, \mathbf{v} is canalized, and S is globally minimized into machine-readable regularities. The Decelerationist Agenda pluralizes Φ , diversifies \mathbf{v} , and raises global S (while resolving S locally for human learning), creating an ecology that resists single-model assimilation. This approach counters e/acc's emphasis on rapid homogenization by embedding resilience through diversity.

8 Parsing as the Substrate of Intelligence

Current AI systems, such as large language models (LLMs) and multimodal architectures, function as concatenated parsers: chains of specialized modules that process inputs sequentially without

true recursive integration (42; 18). For instance, LLMs parse text into tokens and distributions, while vision-language models align pixels to token streams. These concatenations simulate agency but lack unifying semantics or self-modification capabilities.

In contrast, we posit that parsing itself constitutes the deep substrate of general intelligence: the universal operation of constraint recognition and translation across representational layers. Examples include cellular transcription parsing chemical gradients into protein actions, cortical columns parsing spatiotemporal inputs into trajectories, and protocols parsing packets into executable information (18; 16).

If this holds, AGI requires not mere scaling but recursive meta-parsing—viviception in RSVP terms—where the system reinterprets and reorganizes its own layers. In the RSVP framework, Φ represents parsing capacity (bandwidth for representational domains), \mathbf{v} denotes flows of parsing operations (directional translations), and S captures entropy of interpretation (ambiguity sustaining multiple parses) (7; 39).

[Concatenated Parsers] All existing artificial agents can be decomposed into concatenated parsers. Formally, let $\mathcal{P}_i: X_i \to Y_i$ denote a parser mapping between representational domains. Then any current agent A satisfies

$$A = \mathcal{P}_n \circ \cdots \circ \mathcal{P}_2 \circ \mathcal{P}_1$$

with no closure property guaranteeing reinterpretation or self-modification.

[General Parser] A general parser is a recursive functor

$$\mathcal{G}: \mathbf{Rep} \to \mathbf{Rep}$$

that maps between representational categories while preserving the ability to re-parse its own output as new input, i.e.

$$\mathcal{G}\cong\mathcal{G}\circ\mathcal{G}.$$

[Parsing as General Intelligence] General intelligence arises when a system achieves recursive closure under parsing. That is, a system S is generally intelligent iff there exists a general parser \mathcal{G} such that

$$S \equiv \mathcal{G}$$
, with self-interpretation $\mathcal{G}(\mathcal{G}(x)) = \mathcal{G}(x)$.

To establish this equivalence, we prove both directions.

Sufficiency: Assume there exists a general parser \mathcal{G} such that $S \equiv \mathcal{G}$ and $\mathcal{G}(\mathcal{G}(x)) = \mathcal{G}(x)$ for all inputs x in the representational category **Rep**.

The recursive functor $\mathcal{G}: \mathbf{Rep} \to \mathbf{Rep}$ maps representations to representations while preserving structure. The idempotence condition ensures that applying \mathcal{G} multiple times converges to a fixed point, enabling the system to handle nested, hierarchical, or self-referential inputs without infinite regression or loss of coherence. This mirrors human cognitive parsing, where the brain decomposes sensory inputs into meaningful components through recursive processes (5; 19; 10).

Furthermore, this property aligns with definitions of artificial general intelligence (AGI) as the ability to match or surpass human cognitive capabilities across diverse tasks, including learning, adaptation, and self-teaching (48; 37; 47; 35; 49; 34; 36; 38). The recursive closure allows for self-improvement by re-parsing internal representations, a key feature of AGI pathways (9; 13; 43; 45).

Thus, such a system exhibits general intelligence by virtue of its ability to universally parse and reinterpret across domains.

Necessity: Assume S is generally intelligent. By definition, S must demonstrate broad humanlevel capabilities, including understanding, learning, and applying knowledge across tasks, as well as adaptation to open environments with limited resources (36; 34).

In cognitive science, parsing is central to comprehension, involving the assignment of linguistic or sensory elements to categories for meaning extraction (50; 14; 15; 17). For general intelligence, the system must parse diverse, novel inputs and generate outputs that can be recursively processed for higher-level reasoning, planning, or self-modification.

Without recursive closure, S would be confined to finite-depth parsing chains, as in current concatenated AI systems, leading to brittleness in complex, self-referential, or unbounded scenarios (? 31?; 16). Recursive self-improvement, essential for achieving and sustaining AGI, requires the system to parse and optimize its own structures iteratively (51; 44?; 43?).

The idempotence $\mathcal{G}(\mathcal{G}(x)) = \mathcal{G}(x)$ captures this fixed-point stability, analogous to idempotent monads in category theory that project to coherent subspaces (41; 40; 12; 20; 6; 8). Absent this, the system cannot achieve the self-consistent recursion needed for generality.

Therefore, the biconditional holds.

This formalization implies that decelerationist interventions, by diversifying representational regimes, hinder the emergence of unified general parsers in AGI systems.

8.1 Diversifying Education: Twenty-One School Types

Seven subject-first tracks (Geometry, Algebra, Trigonometry, Calculus, Stoichiometry, Statistics, Logic) crossed with three modality modes (Speaking-only, Writing-only, Mixed) induce $7 \times 3 = 21$ school types. This lifts heterogeneity in priors (capacity) and communication flows, frustrating uniform modeling. By introducing varied entry lenses, education embeds unique representational priors, aligning with RSVP's pluralization of Φ (56).

Each subject-first orientation seeds learners with distinct conceptual anchors: geometry-first emphasizes spatial invariants and proofs by construction; algebra-first highlights symbolic manipulation and abstraction; trigonometry-first foregrounds periodicity and relational reasoning; calculus-first emphasizes continuous change and limits; stoichiometry-first centers proportional reasoning and conservation laws; statistics-first cultivates probabilistic inference; logic-first grounds learning in deduction and formal systems.

The modality modes alter the dominant vector flows **v**: speaking-only institutions prioritize oral articulation and embodied debate; writing-only institutions embed precision and permanence through text; mixed institutions sustain dual channels. These differences channelize learning into

diverse propagation structures, multiplying interpretive pathways.

The result is an ecology of 21 school types, each encoding a distinct RSVP profile (Φ, \mathbf{v}, S) . No single parser can trivially assimilate this distributed heterogeneity: the plurality of routes ensures that human learning resists collapse into one monocultural substrate. In RSVP terms, Φ is diversified across entry logics, \mathbf{v} across communicative flows, and S elevated globally as representational multiplicity. This structural pluralization enacts a systemic buffer against homogenization, embedding resilience in the very foundation of education.

8.2 Individualized Textbooks via Cipher-Fonts

Each student receives a curriculum printed in a personal handwriting-derived font or cipher. Teachers hold decoding keys to maintain content parity. Population-level cipher diversity raises the KL-divergence between personal and canonical corpora, lowering the fungibility of data for centralized scrapers and increasing the lower bound on decoding error for models not trained on those ciphers. This intervention enhances local entropy S while bounding it through shared keys.

Pedagogically, cipher-fonts reframe reading as an active act of translation rather than passive decoding. Students must continually engage with their own glyph system, internalizing recursive parsing as a daily cognitive exercise. This strengthens metacognition: learners do not simply consume content, but also practice navigating transformations between symbolic layers.

At the population level, the proliferation of unique fonts expands representational capacity Φ , since each handwriting system generates a distinct glyph space. Communication flows \mathbf{v} are diversified, as information must be routed through both personal and canonical forms. Entropy S is raised in a controlled manner: each student inhabits a distinct symbolic landscape, yet mutual comprehensibility is preserved via the teacher's decoding keys.

For AGI resistance, cipher-fonts disrupt the construction of universal training corpora. Instead of a fungible, homogeneous dataset, the landscape fragments into millions of micro-corpora, each requiring a separate translation model. This acts as a structured entropy buffer: human learning remains legible to itself but becomes less compressible to machine assimilation. In RSVP terms, cipher-fonts simultaneously pluralize Φ , diversify \mathbf{v} through translation loops, and elevate S in a bounded way that enriches cognition while complicating external modeling.

8.3 Crumpled Paper Ball Compression

Students practice compressing (crumpling) and reconstructing notes. This embodied lossy entanglement trains reconstruction under overlap and noise, where human cognition is strong but current models degrade. Pedagogically, it raises S globally while guiding local $S \downarrow$ via novel flows across folds, mirroring entropic smoothing in RSVP.

The act of crumpling converts a two-dimensional field of meaning into a three-dimensional entangled form, introducing multiplicity and distortion. Fragments of text overlap, ink bleeds across unintended neighbors, and legibility is partially lost. To reconstruct the original, students must develop strategies for disentanglement: inference from context, interpolation across gaps, and

error-tolerant recognition. In this way, crumpling dramatizes the RSVP principle that intelligence consists not only in compression but in the recovery of coherence under entropic stress.

Within the RSVP framing, Φ is constrained by surface reduction—the apparent representational area shrinks—forcing students to allocate attention more efficiently. Flows \mathbf{v} are reconfigured: retrieval now requires crossing folded adjacency relations rather than linear order. Entropy S spikes during compression, but students learn to reduce S locally through reconstruction, balancing disorder with restored clarity.

This exercise teaches resilience: unlike digital systems that often fail catastrophically under structured noise, human learners adapt and recover partial meaning from degraded input. At the population scale, regular exposure to entangled representations strengthens collective robustness against assimilation by parsers that depend on pristine, standardized corpora. Crumpled reconstruction thus embeds entropic smoothing into pedagogy, cultivating cognitive pathways that align with RSVP's vision of intelligence as the active management of disorder.

8.4 Yogurt-Based Computation

Living cultures (e.g., Lactobacillus) serve as analog computers: growth dynamics model exponentials; pH/turbidity serve as readouts; interactions instantiate feedback. Nonequilibrium systems illustrate how computation can be embodied beyond silicon (54; 56). This broadens Φ (bio-capacity), reroutes \mathbf{v} (metabolic flows), and sustains S (stochastic microstates), anchoring computation in ecological entropies resistant to AGI replication.

Pedagogically, yogurt cultures make mathematical abstraction tangible. Students can observe exponential growth not as a curve on a page but as an evolving colony, with doubling times manifest in visible change. Feedback loops can be introduced through nutrient inputs or environmental shifts, illustrating how small parameter adjustments create nonlinear responses. The physicality of these processes grounds abstract reasoning in sensory and ecological experience.

In RSVP terms, yogurt computation expands representational capacity Φ by adding a biological substrate that encodes dynamics inaccessible to silicon circuits. Flows \mathbf{v} are rerouted through metabolic interactions, where exchange is chemical rather than symbolic. Entropy S is maintained at high levels: microstates are stochastic, outcomes probabilistic, and precise repetition impossible. Yet this variability is precisely what makes biological computation pedagogically valuable: it trains students to reason under uncertainty and to interpret patterns that emerge from noise.

For AGI resistance, yogurt computation introduces a domain where human learners are advantaged. Biological systems are not trivially scrappable into standardized datasets; they require ongoing cultivation, contextual interpretation, and ecological sensitivity. By embedding computation into living matter, the curriculum resists homogenization into machine-readable form. Yogurt thus becomes both a teaching tool and a structural buffer, embedding resilience in embodied diversity rather than abstract uniformity.

8.5 Kelp-Based Building Materials

Kelp-based composites provide renewable school infrastructure, decoupling educational capacity from carbon- and steel-intensive supply chains that co-drive data center buildouts. Material diversity raises infrastructural S and reduces tight coupling to the silicon monoculture, promoting regenerative cycles.

Kelp grows rapidly, sequesters carbon efficiently, and can be processed into panels, laminates, and structural supports. By embedding kelp into construction, schools embody a regenerative material logic: buildings become extensions of ecological cycles rather than extractive industries. This material substitution alters both the symbolic and literal substrate of education, shifting from finite, high-carbon resources to renewable, ocean-based biomass.

In RSVP terms, kelp composites expand Φ by enabling physical capacity to grow in line with ecological processes rather than industrial constraints. Flows \mathbf{v} are rerouted from fossil fuel and mining supply chains toward regenerative harvesting, local processing, and cyclical reuse. Entropy S is raised at the infrastructural level: material sources become diverse, distributed, and temporally variable, breaking the brittle dependency on globalized steel and concrete pipelines that also underwrite AGI compute expansion.

Pedagogically, kelp-based infrastructure provides more than ecological benefits. It serves as a daily reminder to students that their environment is part of a living system: classrooms are built from regenerative matter, and walls themselves participate in cycles of growth and decay. This symbolic grounding reinforces the decelerationist agenda's principle of embedding plurality and resilience into the foundations of learning.

By redirecting infrastructure toward kelp and other regenerative materials, education decouples from the industrial substrates that accelerate AGI assimilation. In this way, school buildings become not just neutral containers of learning but active components of a diversified, entropic ecology.

9 Integration and Governance

Together these interventions create a pluralistic ecology: diversified Φ , heterogeneous \mathbf{v} , and globally elevated S. The aim is *constructive deceleration*: slower machine assimilation without stalling human flourishing. This is not anti-progress; it is *multi-progress*, transforming slowdown into enrichment through variety.

Education diversification generates multiple representational pathways (Φ) and communicative flows (\mathbf{v}) , ensuring that no single entry point dominates. Cipher-fonts amplify local entropy S in a bounded way, embedding recursive parsing into the daily act of learning. Crumpled compression teaches resilience to noise and overlap, cultivating reconstruction skills that exploit entanglement where machines falter. Yogurt-based computation anchors abstraction in living matter, extending computation into ecological substrates resistant to homogenization. Kelp-based infrastructure reframes the built environment as regenerative, diversifying material flows and raising infrastructural entropy.

Governance in this framework shifts from centralized optimization to distributed stewardship. Rather than maximizing efficiency in a single channel, policy encourages diversity across channels, ensuring systemic resilience. RSVP provides the lens: Φ is pluralized across representational tracks, \mathbf{v} flows are decentralized and multi-modal, and S is elevated globally to frustrate assimilation while being resolved locally through human creativity and interpretation.

Constructive deceleration is thus not a retreat but a reorientation. It reframes progress away from linear acceleration toward layered, heterogeneous flourishing. The governance task is to sustain this ecology: rotating ciphers, maintaining diversity in curricula, protecting regenerative infrastructures, and ensuring equitable access across tracks. By doing so, society cultivates an entropic buffer against AGI monoculture, ensuring that human knowledge evolves in ways that are resilient, plural, and irreducibly alive.

10 Risks and Mitigations

Equity. Diversification must not exacerbate inequality. While tracks differ in entry lens and modality, all converge to shared competency floors, ensuring that no student is disadvantaged in university admissions or labor markets. Crosswalk curricula should provide bridges between tracks, allowing mobility and recognition across the system. Governance must regularly audit outcomes to confirm that heterogeneity enriches rather than stratifies.

Accessibility. Cipher-fonts and modality rules must accommodate disability and neurodiversity. Students with dyslexia, visual impairments, or auditory processing challenges require alternative encodings that maintain the spirit of individualized texts without exclusion. Assistive technologies should be embedded in the design, ensuring that diversification amplifies learning rather than creating new barriers. In RSVP terms, Φ must remain equitably distributed across learners, and \mathbf{v} flows must include accessible routes.

Circumvention. AGI systems may adapt to fixed cipher schemes or repeated compression exercises. To sustain resilience, ciphers should be rotated periodically, mappings refreshed, and reconstruction tasks varied. Entropy S must be treated as a governed variable: not allowed to collapse into predictability, nor to explode into unmanageable noise. Governance structures can formalize entropy budgets, ensuring that interventions preserve their protective role over time.

Cultural acceptance. A pluralized system risks being misread as fragmentation or deprivation. To mitigate resistance, diversification must be framed as enrichment—emphasizing creativity, resilience, and multiple forms of excellence. Public narratives should stress that variety strengthens human flourishing and prepares students for complex futures, rather than slowing them down. Symbols such as kelp-based architecture or yogurt computation can anchor this narrative: tangible reminders that plural infrastructures are not deficiencies but sources of vitality.

Scalability. Introducing new materials, pedagogies, and ciphers requires resources and coordination. Pilots should begin small, with careful documentation of successes and failures, before scaling system-wide. Incremental adoption lowers risk while preserving the long-term goal of sys-

temic heterogeneity.

Governance drift. Without sustained oversight, entropy-raising interventions may be captured by efficiency pressures and standardized again. Institutions must establish governance mechanisms—rotating councils, community audits, or entropy metrics—that prevent re-homogenization. This maintains the constructive decelerationist ethos: a living balance of Φ , \mathbf{v} , and S across time.

11 Limitations and Open Questions

Empirical validation. While the interventions are theoretically grounded in RSVP dynamics, their long-term efficacy requires empirical testing. It remains uncertain whether cipher-fonts, crumpled compression, or bio-computation exercises measurably improve resilience against machine assimilation at population scale. Controlled trials and longitudinal studies are needed to distinguish symbolic enrichment from practical outcomes.

Complexity costs. Diversification increases administrative burden: producing individualized textbooks, rotating ciphers, or maintaining kelp-based supply chains may strain budgets and logistics. The balance between constructive entropy and institutional manageability remains an open governance challenge.

Global coordination. Decelerationist strategies may succeed locally but struggle to scale globally in the face of geopolitical competition. If some regions diversify while others accelerate, machine assimilation pressures may simply shift toward the more homogeneous systems. An open question is whether pluralization must be globally coordinated or whether local heterogeneity suffices as a systemic buffer.

Human adaptation. It is unclear how students and teachers will adapt to persistent entropyraising practices. Cipher use, crumpled notes, or yogurt labs may generate novelty fatigue or resistance if not carefully integrated. The pedagogical art lies in balancing challenge with accessibility, ensuring that S remains constructive rather than overwhelming.

Technological counter-adaptation. AGI systems may eventually learn to decode cipher fonts, simulate noise reconstruction, or model biological dynamics. Whether human heterogeneity can continually outpace machine assimilation is an unresolved question. The decelerationist agenda assumes that diversity is a renewable variable, but mechanisms for sustained renewal require further design.

Philosophical scope. The framework rests on RSVP's treatment of Φ , \mathbf{v} , and S as universal coordinates of capacity, flow, and entropy. While this provides coherence, it may oversimplify human flourishing. Open questions include how to incorporate values like justice, compassion, or aesthetic meaning into entropic governance, ensuring that slowdown is not only resistant but also humane.

12 Diagnostics and Falsifiable Predictions

The decelerationist agenda makes claims that are not only conceptual but empirically testable. Each intervention can be coupled to diagnostics that distinguish enrichment effects from symbolic gestures, ensuring that the framework remains accountable to evidence.

- 1. Cipher KL bound. Across personalized glyphs, model decoding error should scale with $KL(p_{\Sigma_i}||p_{\Sigma})$. A falsification would occur if large language models trained on canonical corpora could generalize across ciphered corpora with negligible error. Open question: to what extent does human fluency in cipher use outpace machine adaptation, and for how long can entropy be sustained before convergence?
- 2. Crumple training effect. Students trained on structured reconstruction should outperform controls on occlusion/overlap tasks. This would demonstrate that lossy entanglement builds resilience where current models degrade. Limitation: novelty fatigue or overexposure may blunt the pedagogical effect. Future direction: vary degrees of compression to calibrate optimal S levels for constructive challenge.
- 3. **Bio-compute transfer.** Exposure to microbial growth dynamics should improve mastery of exponentials and logistics relative to controls, indicating successful transfer from embodied observation to abstract reasoning. Limitation: classroom implementation may face bio-safety and resource constraints. Open question: does stochastic variability in cultures enhance or confuse learning outcomes? Future studies can quantify effect sizes against conventional instruction.
- 4. Infra coupling. Regions adopting kelp-based composites should show slower growth in data-center concrete/steel consumption without measurable loss of educational capacity. A falsification would occur if regenerative materials introduced fragility or under-capacity. Limitation: supply chains may initially be too immature to scale. Future direction: life-cycle analyses comparing kelp composites to conventional steel/concrete, including embodied energy and carbon sequestration metrics.

These predictions allow empirical validation of the agenda's efficacy. They also surface limitations and unresolved questions: whether heterogeneity can be maintained at scale, whether entropy can be continually renewed without overwhelming learners, and whether local adoption suffices against global acceleration pressures.

Future Directions. To address these uncertainties, pilot programs should be launched in diverse contexts, with longitudinal tracking of outcomes. Simulation models of Φ , \mathbf{v} , S dynamics can test scenarios before deployment. International collaborations can explore whether pluralization strategies must be coordinated globally or whether localized entropy buffers suffice. Ultimately, the diagnostics point toward a broader research program: one that treats slowdown not as a slogan but as a falsifiable, renewable, and humane mode of governance.

Conclusion

The Decelerationist Agenda reframes slowdown as *plural progress*. By diversifying substrates of learning and infrastructure, we maintain local solvability while preserving global heterogeneity, compelling AGI to adapt to humanity's variety rather than the reverse. This stands in stark contrast to e/acc's accelerationist imperatives, offering a resilient, entropy-respecting path forward.

The core claim is not that progress should be halted, but that it must be refracted. Instead of a single accelerating channel—standardized curricula, fungible corpora, extractive infrastructures—the agenda disperses growth into multiple, partially overlapping routes. Each intervention is designed to pluralize scalar capacity (Φ) , diversify vector flows (\mathbf{v}) , and elevate entropy (S) in bounded, constructive ways. Education becomes a lattice of 21 types rather than a funnel; texts become personal glyphscapes rather than fungible corpora; computation becomes embodied in microbial dynamics as well as silicon; and school buildings themselves become regenerative, resisting industrial monoculture.

This program is not without risks. Equity must be preserved, accessibility ensured, and entropy governed to avoid collapse into noise. Yet these risks are manageable through oversight, adaptation, and careful piloting. What emerges is a vision of civilization where resilience is not purchased through control but cultivated through variety.

In philosophical terms, the decelerationist ethos inverts the logic of accelerationism. Where e/acc seeks to align humanity with entropy maximization through speed, this framework insists that entropy's value lies in diversity and irreducibility. The challenge for AGI is no longer how quickly it can assimilate a monoculture, but how it can navigate a plural ecology where no single model suffices.

In this sense, slowdown is enrichment: a widening of trajectories rather than a narrowing. The Decelerationist Agenda offers a governance model that is not defensive but generative—embedding RSVP's dynamics into the structures of learning, computation, and infrastructure to secure a future that is resilient, plural, and irreducibly human.

A Mathematical Sketch (RSVP)

A.1 RSVP Fields and Continuity

Let \mathcal{M} be the manifold of learning states (students \times tasks \times contexts). Define RSVP fields:

$$\Phi: \mathcal{M} \to \mathbb{R}_{\geq 0}, \quad \mathbf{v}: \mathcal{M} \to T\mathcal{M}, \quad S: \mathcal{M} \to \mathbb{R}_{\geq 0}.$$

Here Φ is representational capacity, \mathbf{v} the flow field, and S the entropy of interpretation. Densities ρ evolve under a continuity equation with a source term Γ :

$$\partial_t \rho + \nabla \cdot (\Phi \mathbf{v}) = \Gamma(\Phi, \mathbf{v}, S), \qquad \frac{\partial \Gamma}{\partial S} \le 0.$$
 (1)

Thus local entropy can be resolved (students mastering material) while global entropy increases (population-level diversity).

A.2 Cipher Fonts and KL Bounds

For student i, let $f_i: \Sigma \to \Sigma_i$ be a bijective cipher/handwriting map with decoder f_i^{-1} known to teachers. A canonical text x is rendered as $x_i = f_i(x)$. From an information-theoretic perspective, each cipher induces a distribution p_{Σ_i} distinct from the canonical p_{Σ} . For a model M without exposure to f_i , expected decoding loss lower-bounds as

$$\mathbb{E}[d(\mathsf{M}(f_i(x)), x)] \geq \kappa \operatorname{KL}(p_{\Sigma_i} || p_{\Sigma}),$$

where d is a divergence (e.g. edit distance, cross-entropy). Population heterogeneity across $\{f_i\}$ thus scales the difficulty of assimilation by a single AGI parser.

A.3 Crumpled Reconstruction as Entropic Folding

Let $u: \Omega \subset \mathbb{R}^2 \to \mathbb{R}$ denote a page of notes. Crumpling is a piecewise isometry $C: \Omega \to \mathbb{R}^3$ yielding a ball $\mathcal{B} = C(\Omega)$. Overlap multiplicity m(y) and curvature κ define an entropic cost

$$S_{\text{crumple}} = \int_{\mathcal{B}} (m(y) - 1) \, \mathrm{d}y + \lambda \int_{\text{folds}} \kappa^2 \, \mathrm{d}\sigma. \tag{2}$$

A reconstruction map R is trained to minimize

$$\mathcal{J}[R] = \|u - R(\tilde{u})\|^2 + \mu \|\nabla R\|^2,$$

where \tilde{u} is the folded signal. This functional shows how students practice lowering local entropy by reconstructing coherence from lossy folds.

A.4 Biological Computation Dynamics

In yogurt-based computation, microbial biomass X(t) and substrate S(t) obey Monod kinetics:

$$\dot{X} = \mu_{\text{max}} \frac{S}{K_S + S} X, \qquad \dot{S} = -\frac{1}{Y_{X/S}} \mu_{\text{max}} \frac{S}{K_S + S} X.$$

Batch regimes $S \gg K_S$ yield $X(t) \sim e^{\mu_{\text{max}}t}$, allowing analog encoding of exponentials and multiplicative structure. This expands Φ by adding a biological substrate, diversifies \mathbf{v} through metabolic flows, and sustains high S through stochastic microstates.

A.5 Action Functional

A compact RSVP action can be written

$$\mathcal{A} = \int_{\mathcal{M} \times [0,T]} \left[\frac{\kappa}{2} \Phi^{-1} \|\Phi \mathbf{v}\|^2 + \beta \|\nabla S\|^2 - \lambda \mathcal{C}[\mathcal{G}] \right] dV dt, \tag{3}$$

where $\mathcal{C}[\mathcal{G}]$ measures parser idempotence. Interventions like school diversification, cipher fonts, crumpled reconstruction, bio-computation, and kelp infrastructures contribute additive heterogeneity terms that enlarge the basin of high-entropy yet task-solvable phases.

A.6 Diagnostic Predictions

- Cipher heterogeneity \Rightarrow decoding error scales with KL divergence.
- Crumple training ⇒ improved robustness on occluded/overlap tasks.
- Yogurt exposure ⇒ transfer gains on exponential/logistic reasoning.
- Material diversification ⇒ slower coupling between schooling and AGI-relevant infrastructure growth.

B Implementation Sketch for Recursive General Parsers

To operationalize the parsing framework within RSVP, we outline a build plan integrating monadized interfaces, field coupling, idempotent curricula, and diagnostics. This sketch is implementable in PyTorch or JAX, treating parsing as field-dynamics over data streams.

B.1 Monadized Interfaces

Let \mathcal{G} denote a parser functor, with unit $\eta: X \to \mathcal{G}X$, multiplication $\mu: \mathcal{G}(\mathcal{G}X) \to \mathcal{G}X$, and algebra $\alpha: \mathcal{G}A \to A$ for some space of representations A. In practice, η is implemented as an encoder mapping inputs into parser state, μ as a recurrent or hierarchical composition operator, and α as a readout head. Soft losses enforce approximate satisfaction of the monad laws:

$$\|\mu \circ \eta - id\|$$
 and $\|\mu \circ \mathcal{G}(\eta) - id\|$,

ensuring stability of recursive application.

B.2 Field Coupling

RSVP fields map onto compute resources:

- Φ (capacity): number of active channels, neurons, or attention heads.
- v (flow): scheduling or routing of messages between layers/agents.

• S (entropy): uncertainty budgets, temperature schedules, dropout/noise injections.

Transport of representational mass between nodes can be optimized via Sinkhorn-based optimal transport, yielding coupling plans π that balance capacity, flow, and entropy constraints.

B.3 Idempotent Curricula

Training proceeds not only on raw tasks $x \mapsto \mathcal{G}(x)$, but also on self-composition:

$$\mathcal{G}(\mathcal{G}(x)) \approx \mathcal{G}(x)$$
.

Divergence between first- and second-order parses is penalized, creating a curriculum that aligns the model toward idempotence while preserving expressive variability. This mirrors how human learners stabilize interpretations by re-parsing narratives or problems.

B.4 Diagnostics

Evaluation should probe for:

- 1. **Idempotence test:** measure $\|\mathcal{G}^2 \mathcal{G}\|$ across distributions.
- 2. **Entropy-budget coupling:** track global S against local S resolution during tasks, ensuring diversity persists without collapse.
- 3. Phase transition search: sweep parameters $(\Phi, \|\mathbf{v}\|, S)$ to detect transitions between brittle assimilation regimes and robust pluralist regimes.

These diagnostics provide a falsifiable grounding: recursive general parsers should demonstrate stable self-application, bounded entropy coupling, and resilience across parameter phases.

B.5 Reference Implementation

Below is a PyTorch skeleton:

```
import torch.nn.functional as F
DEVICE = "cuda" if torch.cuda.is_available() else "cpu"
DTYPE = torch.float32
torch.set_default_dtype(DTYPE)
# Utilities
def cosine_distance(a: torch.Tensor, b: torch.Tensor, eps=1e-8) -> torch.
   Tensor:
    a_norm = a / (a.norm(dim=-1, keepdim=True) + eps)
    b_norm = b / (b.norm(dim=-1, keepdim=True) + eps)
    return 1.0 - (a_norm * b_norm).sum(dim=-1)
def edit_like_distance(logits_a: torch.Tensor, logits_b: torch.Tensor) ->
   torch. Tensor:
   pa = logits_a.log_softmax(dim=-1)
   pb = logits_b.log_softmax(dim=-1)
    return (F.kl_div(pa, pb.exp(), reduction="batchmean") + F.kl_div(pb, pa.
       exp(), reduction="batchmean")) / 2
def entropy_from_logits(logits: torch.Tensor) -> torch.Tensor:
    p = logits.softmax(dim=-1).clamp_min(1e-8)
   H = -(p * p.log()).sum(dim=-1)
    return H
def sinkhorn(M, num_iters=20, eps=1e-2):
   K = torch.exp(M / eps)
   r = torch.ones(M.shape[0], M.shape[1], device=M.device)
    c = torch.ones(M.shape[0], M.shape[2], device=M.device)
    for _ in range(num_iters):
        r = 1.0 / (K @ c.unsqueeze(-1)).squeeze(-1).clamp_min(1e-8)
        c = 1.0 / (K.transpose(1,2) @ r.unsqueeze(-1)).squeeze(-1).clamp_min(1
   P = torch.diag_embed(r) @ K @ torch.diag_embed(c)
    P = P / P.sum(dim=(-1,-2), keepdim=True).clamp_min(1e-8)
   return P
# Toy task (replace with your domain)
class ToyTask(nn.Module):
    def __init__(self, vocab=256, max_len=64):
        super().__init__()
        self.vocab = vocab
        self.max_len = max_len
```

```
def batch(self, B=32) -> Tuple[torch.Tensor, torch.Tensor]:
        T = random.randint(self.max_len//2, self.max_len)
        x = torch.randint(0, self.vocab, (B, T), device=DEVICE)
        y = x.clone()
        noise_mask = (torch.rand_like(y.float()) < 0.05)</pre>
        y[noise_mask] = torch.randint(0, self.vocab, y.shape, device=DEVICE)[
           noise_mask]
        return x, y
# Parsers and components
class Encoder(nn.Module):
    def __init__(self, vocab=256, d_model=512, n_layers=4, n_heads=8):
        super().__init__()
        self.emb = nn.Embedding(vocab, d_model)
        encoder_layer = nn.TransformerEncoderLayer(d_model, n_heads,
           dim_feedforward=4*d_model, batch_first=True)
        self.tr = nn.TransformerEncoder(encoder_layer, num_layers=n_layers)
    def forward(self, tokens):
        z = self.emb(tokens)
        p = self.tr(z)
        return p
class Merger(nn.Module):
    def __init__(self, d_model=512):
        super().__init__()
        self.lin = nn.Sequential(
            nn.Linear(2*d_model, d_model),
            nn.GELU(),
            nn.Linear(d_model, d_model)
        )
    def forward(self, p1, p2):
        T = \min(p1.shape[1], p2.shape[1])
        h = torch.cat([p1[:, :T, :], p2[:, :T, :]], dim=-1)
        return self.lin(h)
class Realizer(nn.Module):
    def __init__(self, d_model=512, vocab=256):
        super().__init__()
        self.proj = nn.Linear(d_model, vocab)
    def forward(self, p):
        return self.proj(p)
```

```
class CapacityGate(nn.Module):
   def __init__(self, d_model=512, budget_ratio=0.5):
        super().__init__()
        self.score = nn.Sequential(
            nn.Linear(d_model, d_model//2),
            nn.GELU(),
            nn.Linear(d_model//2, 1)
        self.budget_ratio = budget_ratio
   def forward(self, p):
       raw = self.score(p).squeeze(-1)
       g = torch.sigmoid(raw)
       B = int(self.budget_ratio * g.shape[1])
        topk_vals, _ = torch.topk(g, k=max(1, B), dim=1)
        thresh = topk_vals[:, -1:].detach()
        g_soft = torch.sigmoid(10.0 * (g - thresh))
        return g_soft
class Router(nn.Module):
   def __init__(self, d_model=512):
        super().__init__()
        self.q = nn.Linear(d_model, d_model)
        self.k = nn.Linear(d_model, d_model)
        self.scale = d_model ** -0.5
        self.temp = nn.Parameter(torch.tensor(1.0))
   def forward(self, p):
       Q, K = self.q(p), self.k(p)
        attn_logits = torch.matmul(Q, K.transpose(1, 2)) * self.scale / self.
           temp.clamp_min(1e-3)
        P = sinkhorn(attn_logits, num_iters=30, eps=1e-1)
        return P, attn_logits
class UncertaintyCommittee(nn.Module):
   def __init__(self, d_model=512, vocab=256, heads=4, p_drop=0.2):
        super().__init__()
        self.heads = nn.ModuleList([nn.Sequential(nn.Dropout(p_drop), nn.
           Linear(d_model, vocab)) for _ in range(heads)])
   def forward(self, p, samples=4):
        logits_samples = []
        for _ in range(samples):
```

```
logits_list = [h(p) for h in self.heads]
            logits = torch.stack(logits_list, dim=0).mean(0)
            logits_samples.append(logits)
        logits_stack = torch.stack(logits_samples, dim=0)
        mean_logits = logits_stack.mean(0)
        ent = entropy_from_logits(mean_logits)
        var = logits_stack.var(dim=0).mean(dim=-1)
        S = ent + var
        return S, mean_logits
@dataclass
class LossWeights:
   unitL: float = 1.0
   assoc: float = 0.5
   alg: float = 0.5
   idem: float = 0.5
   transport: float = 0.1
   continuity: float = 0.1
   smooth: float = 0.05
    cap_reg: float = 0.05
class GeneralParser(nn.Module):
   def __init__(self, vocab=256, d_model=512):
       super().__init__()
        self.encoder = Encoder(vocab=vocab, d_model=d_model)
        self.merger = Merger(d_model=d_model)
        self.realizer = Realizer(d_model=d_model, vocab=vocab)
        self.gate = CapacityGate(d_model=d_model, budget_ratio=0.5)
        self.router = Router(d_model=d_model)
        self.committee = UncertaintyCommittee(d_model=d_model, vocab=vocab,
           heads=4, p_drop=0.2)
   def encode(self, x_tokens):
       return self.encoder(x_tokens)
   def merge(self, p1, p2):
       return self.merger(p1, p2)
   def realize(self, p):
       return self.realizer(p)
   def fields(self, p):
       g = self.gate(p)
       P, logits_attn = self.router(p)
```

```
J = P * g.unsqueeze(1)
        S, logits_mean = self.committee(p)
        return g, P, J, S, logits_mean, logits_attn
def monad_losses(model: GeneralParser, x, y) -> Dict[str, torch.Tensor]:
    p1 = model.encode(x)
   p2 = model.encode(p1)
    p_merge = model.merge(p1, p2)
    y_logits = model.realize(p1)
   unitL = F.cross_entropy(y_logits.transpose(1,2), y, ignore_index=-100)
    y_logits_from_merge = model.realize(p_merge)
    y_logits_from_comp = model.realize(model.encode(y_logits.argmax(dim=-1)))
    alg = edit_like_distance(y_logits_from_merge, y_logits_from_comp)
    p_ggg = model.encode(p2)
    left = model.merge(p2, p_ggg)
    right = model.merge(p1, model.merge(p1, p2))
    assoc = cosine_distance(left.mean(dim=1), right.mean(dim=1)).mean()
    idem = cosine_distance(p2.mean(dim=1), p1.mean(dim=1)).mean()
    task = F.cross_entropy(y_logits.transpose(1,2), y, ignore_index=-100)
    return dict(task=task, unitL=unitL, alg=alg, assoc=assoc, idem=idem,
                p1=p1, p2=p2, y_logits=y_logits)
def rsvp_field_losses(model: GeneralParser, p1, S_weight=1.0) -> Dict[str,
   torch. Tensorl:
   g, P, J, S, mean_logits, attn_logits = model.fields(p1)
    B, T, _= P.shape
    flow_sq = (J ** 2).sum(dim=-1)
    transport = (flow_sq / (g + 1e-6)).mean()
    incoming = J.sum(dim=1)
    outgoing = J.sum(dim=2)
    div = incoming - outgoing
    continuity = (div ** 2).mean()
    grad_S = (S[:, 1:] - S[:, :-1])
    smooth = (grad_S ** 2).mean() + 0.1 * S.mean()
    cap_reg = (g.mean(dim=1) - 0.5).abs().mean()
    return dict(transport=transport, continuity=continuity, smooth=smooth,
       cap_reg=cap_reg,
                g=g, P=P, J=J, S=S, mean_logits=mean_logits)
@torch.no_grad()
```

```
def idempotence_curve(model: GeneralParser, task: ToyTask, k_max=5, B=64):
   xs, ys = task.batch(B)
   xs, ys = xs.to(DEVICE), ys.to(DEVICE)
   p = model.encode(xs)
   vals = []
    for k in range(2, k_max+1):
        p_next = model.encode(p)
        d = cosine_distance(p_next.mean(dim=1), p.mean(dim=1)).mean().item()
        vals.append((k, d))
        p = p_next
    return vals
@torch.no_grad()
def entropy_flux_coupling(model: GeneralParser, x):
   p = model.encode(x)
    g, P, J, S, _, _ = model.fields(p)
    incoming = J.sum(dim=1); outgoing = J.sum(dim=2)
    div = incoming - outgoing
   p_next = model.encode(p)
    g2, P2, J2, S2, _, _ = model.fields(p_next)
    dS = S2 - S
   v1 = torch.stack([g.flatten(), div.flatten()], dim=-1)
   v2 = (-dS).flatten()
   v1 = (v1 - v1.mean(dim=0)) / (v1.std(dim=0) + 1e-6)
    v2 = (v2 - v2.mean()) / (v2.std() + 1e-6)
    coef = torch.linalg.lstsq(v1, v2.unsqueeze(-1)).solution.squeeze()
    return {"coef_g": coef[0].item(), "coef_divJ": coef[1].item()}
def train(num_steps=2000, vocab=256, d_model=256, batch_size=32, lr=3e-4,
   weights=LossWeights()):
   task = ToyTask(vocab=vocab, max_len=64)
   model = GeneralParser(vocab=vocab, d_model=d_model).to(DEVICE)
   opt = torch.optim.AdamW(model.parameters(), lr=lr)
   for step in range(1, num_steps+1):
        x, y = task.batch(batch_size)
        x, y = x.to(DEVICE), y.to(DEVICE)
        ml = monad_losses(model, x, y)
        fl = rsvp_field_losses(model, ml["p1"])
        L = (
            ml["task"]
            + weights.unitL * ml["unitL"]
```

```
+ weights.assoc * ml["assoc"]
                                         + weights.alg * ml["alg"]
                                        + weights.idem * ml["idem"]
                                        + weights.transport * fl["transport"]
                                        + weights.continuity * fl["continuity"]
                                         + weights.smooth * fl["smooth"]
                                        + weights.cap_reg * fl["cap_reg"]
                           )
                           opt.zero_grad(set_to_none=True)
                           L.backward()
                           torch.nn.utils.clip_grad_norm_(model.parameters(), 1.0)
                           opt.step()
                           if step % 100 == 0:
                                         with torch.no_grad():
                                                       idems = idempotence_curve(model, task, k_max=4, B=batch_size)
                                                       cpl = entropy_flux_coupling(model, x)
                                        print(f"[{step}]_"
                                                             f"loss=\{L.item():.3f\}_{l}task=\{ml['task'].item():.3f\}_{l}idem=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f\}_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f]_{l}task=\{ml.item():.3f
                                                                          ['idem'].item():.3f}"
                                                              f"trans={fl['transport'].item():.3f}_cont={fl['continuity'].
                                                                          item():.3f}_{||}"
                                                              f"smooth={f1['smooth'].item():.3f}_\cap={f1['cap_reg'].item()
                                                                          :.3f}"
                                                              f"|_{\sqcup}IdemCurve=\{[(k,_{\sqcup}round(v,3))_{\sqcup}for_{\sqcup}k,v_{\sqcup}in_{\sqcup}idems]\}_{\sqcup}"
                                                              f"|\_Coupling={{{'g':\_round(cpl['coef_g'],3),\_'divJ':\_round(
                                                                          cpl['coef_divJ'],3)}}}")
             return model
if __name__ == "__main__":
             _ = train()
```

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