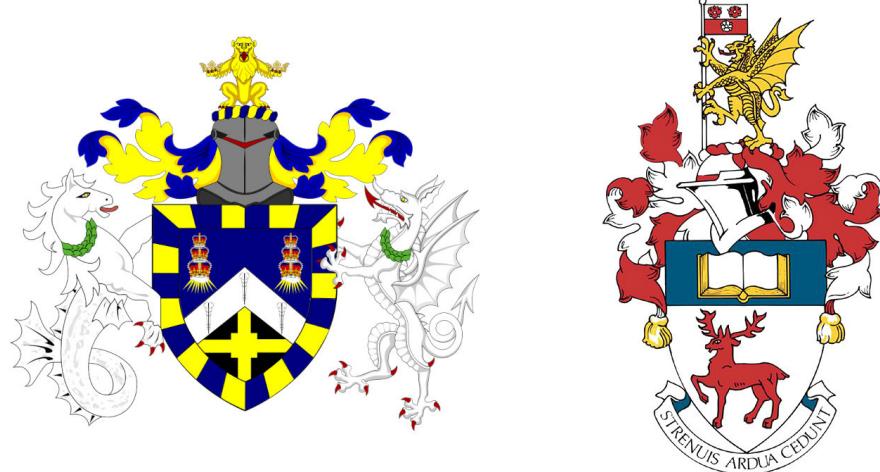


<sup>1</sup> ADVANCING NEUTRINO  
<sup>2</sup> DETECTION AND TRIGGERING IN  
<sup>3</sup> DUNE



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<sup>6</sup> Submitted in partial fulfillment of the requirements  
<sup>7</sup> of the Degree of Doctor of Philosophy

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<sup>12</sup> December 2024



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# <sup>31</sup> Abstract

<sup>32</sup> Work in progress . . .



*¡Oh memoria, enemiga mortal de mi descanso!*

---

*El ingenioso hidalgo don Quijote de la Mancha*

MIGUEL DE CERVANTES SAAVEDRA



## <sup>33</sup> Acknowledgements

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529

<sup>530</sup> **List of Abbreviations**

<b>ADC</b>	Analog to Digital Converter.
<b>ALEPH</b>	Apparatus for LEP PHysics.
<b>ALICE</b>	A Large Ion Collider Experiment.
<b>BDT</b>	Boosted Decision Tree.
<b>CC</b>	Charged Current.
<b>DM</b>	Dark Matter.
<b>DUNE</b>	Deep Underground Neutrino Experiment.
<b>ECal</b>	Electromagnetic Calorimeter.
<b>FD</b>	Far Detector.
<b>FHC</b>	Forward Horn Current.
<b>HPgTPC</b>	High Pressure gaseous Time Projection Chamber.
<b>LBL</b>	Long BaseLine.
<b>MuID</b>	Muon IDentification system.
<b>NC</b>	Neutral Current.
<b>ND</b>	Near Detector.
<b>ND-GAr</b>	Near Detector Gaseous Argon.
<b>ND-LAr</b>	Near Detector Liquid Argon.
<b>PDG</b>	Particle Data Group.
<b>RHC</b>	Reverse Horn Current.



<sup>531</sup> Chapter 1

<sup>532</sup> Introduction



533 Chapter 2

534 Neutrino physics

535       *Little particles of inspiration sleet through the universe all the time traveling*  
536       *through the densest matter in the same way that a neutrino passes through a*  
537       *candyfloss haystack, and most of them miss.*

– Terry Pratchett, *Sourcery*

539 Ever since they were postulated in 1930 by Wolfgang Pauli to explain the continuous  
540  $\beta$  decay spectrum [17] and later found by F. Reines and C. Cowan at the Savannah  
541 River reactor in 1953 [18], neutrinos have had a special place among all other elementary  
542 particles. They provide a unique way to probe a wide range of quite different physics,  
543 from nuclear physics to cosmology, from astrophysics to colliders. Moreover, there is  
544 compelling evidence to believe that the study of neutrinos may be key to unveil different  
545 aspects of physics beyond the SM, difficult to test elsewhere.

In this Chapter, I will review the basics of neutrino physics, from its role within the SM to the main open questions related to the neutrino sector, paying special attention to the phenomenology of neutrino oscillations.

## Chapter 2. Neutrino physics

### 549 2.1 Historical remarks

### 550 2.2 Neutrinos in the SM

551 The SM of fundamental interactions was initially proposed in 1967 by S. Glashow, S.  
552 Weinberg and A. Salam[19–21]. This theoretical framework describes the dynamics of  
553 leptons and quarks, by introducing one scalar particle, the Higgs boson. It assumes  
554 that the local  $SU(3) \times SU(2)_L \times U(1)_Y$  gauge symmetry is an internal symmetry of the  
555 system, with  $SU(3)$  describing quantum chromodynamics, and  $SU(2)_L \times U(1)_Y$  being the  
556 gauge groups of the electroweak sector. For a detailed overview of the SM of electroweak  
557 interactions, see Ref. [22].

558 In the SM, neutrinos appear in three flavours, namely  $\nu_e$ ,  $\nu_\mu$ , and  $\nu_\tau$ . These are  
559 associated with the corresponding charged leptons,  $e$ ,  $\mu$ , and  $\tau$ . Neutrinos exist only  
560 as left-handed particles, grouped in doublets with the charged leptons, while the later  
561 come in both chirality states:

$$\begin{pmatrix} \nu_e \\ e_L^- \end{pmatrix}, \quad \begin{pmatrix} \nu_\mu \\ \mu_L^- \end{pmatrix}, \quad \begin{pmatrix} \nu_\tau \\ \tau_L^- \end{pmatrix}, \quad e_R^-, \quad \mu_R^-, \quad \tau_R^-. \quad (2.1)$$

562 Similarly, quarks also exist in both chirality states, and are grouped as:

$$\begin{pmatrix} u_L \\ d_L \end{pmatrix}, \quad \begin{pmatrix} s_L \\ c_L \end{pmatrix}, \quad \begin{pmatrix} t_L \\ b_L \end{pmatrix}, \quad u_R, \quad d_R, \quad s_R, \quad c_R, \quad t_R, \quad b_R. \quad (2.2)$$

563 The fact that there are no right-handed neutrino fields implies that neutrinos are  
564 strictly massless within the SM. This restriction follows from the experimental observation  
565 that all neutrinos produced via weak interactions are pure left-handed helicity states  
566 (and similarly antineutrinos are pure right-handed states). The hypothetical existence  
567 of right-handed neutrinos could be indirectly inferred from the observation of non-zero  
568 neutrino masses, nevertheless the existence of neutrino masses is not a sufficient condition  
569 for the existence of such fields.

570 Left and right-handed fermions transform differently under  $SU(2)_L \times U(1)_Y$  rotations,

## 2.2. Neutrinos in the SM

**Table 2.1:** Values of  $T_3$  and  $Y/2$  assigned to the first generation of fermions.

	$e_L$	$\nu_e$	$e_R$	$u_L$	$d_L$	$u_R$	$d_R$
$T_3$	-1/2	1/2	0	1/2	-1/2	0	0
$Y/2$	-1/2	-1/2	-1	1/6	1/6	2/3	-1/3

as the right-handed particles are singlets under  $SU(2)_L$ . Applying a local transformation,  
they change as:

$$\begin{aligned} \psi_L &\longrightarrow e^{-iY\beta(x)/2} e^{-iT_a\alpha_a(x)} \psi_L, \\ \psi_R &\longrightarrow e^{-iY\beta(x)/2} \psi_R, \end{aligned} \quad (2.3)$$

where  $Y/2$  and  $T_a$  are the generators of  $SU(2)_L$  and  $U(1)_Y$ , respectively, and  $\beta(x)$  and  $\alpha_a(x)$  are the parameters of the rotation.

The values of the quantum numbers  $Y/2$  and  $T_3$ , the third component of the weak isospin, have to be assigned to the different particles. The values of  $T_3$  follow from the commutation relations of the generators of  $SU(2)$ . After the spontaneous symmetry breaking  $SU(2)_L \times U(1)_Y \rightarrow U(1)_{EM}$ , one finds the relation which determines the electric charge:

$$Q = T_3 + \frac{Y}{2}, \quad (2.4)$$

Setting the electric charge to  $-1$  for electrons, we can find the values of the hypercharge for the rest of the fermions. The resulting values for the first generation of leptons and quarks are shown in Tab. 2.1.

It is clear that the free Lagrangian of the theory is not be invariant under the gauge transformations, as the kinetic terms contain derivatives. Therefore, to make it invariant, one needs to introduce a set of gauge bosons. They appear in the so-called covariant derivative, which replaces the common derivative and transforms in the same way as the fermion fields under local rotations. This constrain fixes completely the transformations of the spin-1 fields. For left and right-handed particles, the covariant derivatives are

## Chapter 2. Neutrino physics

**Table 2.2:** Neutral current couplings.

	$u$	$d$	$\nu_e$	$e$
$2v_f$	$1 - \frac{8}{3}\sin^2\theta_W$	$-1 + \frac{4}{3}\sin^2\theta_W$	1	$-1 + 4\sin^2\theta_W$
$2a_f$	1	-1	1	-1

given by:

$$\begin{aligned} D_\mu \psi_L &= \left( \partial_\mu + ig' \frac{Y}{2} B_\mu + ig T_a W_\mu^a \right) \psi_L, \\ D_\mu \psi_R &= \left( \partial_\mu + ig' \frac{Y}{2} B_\mu \right) \psi_R, \end{aligned} \quad (2.5)$$

where  $W_\mu^i$ ,  $i = 1, 2, 3$  and  $B_\mu$  are the gauge bosons for the  $SU(2)_L$  and  $U(1)_Y$  factors, respectively, and  $g$  and  $g'$  are the corresponding gauge couplings. It can be shown that these fields transform in the adjoint representation of the gauge group.

So far, the theory only contains massless particles, as adding bare mass terms to the Lagrangian would spoil the gauge symmetry. Therefore, the mass terms need to be induced by a spontaneous violation of the symmetries. In the SM, the responsible for this is the Higgs mechanism. The Higgs doublet is coupled to the gauge bosons through the covariant derivative, and to the fermions through the Yukawa couplings. Upon spontaneous symmetry breaking, the vacuum expectation value of the Higgs field generate the mass terms of the particles.

In order to obtain the physical intermediate vector boson states, we need to perform the following redefinitions:

$$\begin{aligned} A_\mu &= \sin \theta_W W_\mu^3 + \cos \theta_W B_\mu, \\ Z_\mu &= \cos \theta_W W_\mu^3 - \sin \theta_W B_\mu, \\ W_\mu^\pm &= \frac{1}{\sqrt{2}} (W_\mu^1 \mp i W_\mu^2), \end{aligned} \quad (2.6)$$

where  $A_\mu$  is the photon field, and  $Z_\mu$  and  $W_\mu^\pm$  are the neutral and the charged weak boson fields, respectively. The Weinberg angle,  $\theta_W$ , relates the weak coupling constants

### 2.3. Massive neutrinos

604 and the electric charge:

$$e = g' \cos \theta_W = g \sin \theta_W. \quad (2.7)$$

605 At this point, the interacting part of the electroweak Lagrangian can be re-written  
 606 as the sum of three contributions: the electromagnetic (EM), charged-current (CC) and  
 607 neutral-current (NC) components:

$$\begin{aligned} \mathcal{L}_{\text{EW}}^{\text{int}} &= \mathcal{L}_{\text{EM}} + \mathcal{L}_{\text{CC}} + \mathcal{L}_{\text{NC}} \\ &= -e A_\mu J_{\text{EM}}^\mu - \frac{g}{2\sqrt{2}} (W^+ J_{\text{CC}}^\mu + \text{h.c.}) - \frac{g}{2\cos\theta_W} Z_\mu J_{\text{NC}}^\mu, \end{aligned} \quad (2.8)$$

608 with the currents defined as:

$$\begin{aligned} J_{\text{EM}}^\mu &= \sum_f Q_f \bar{f} \gamma^\mu f, \\ J_{\text{CC}}^\mu &= \sum_\ell \bar{\nu}_\ell \gamma^\mu (1 - \gamma_5) \ell + \sum_f \bar{u}_f \gamma^\mu (1 - \gamma_5) d_f, \\ J_{\text{NC}}^\mu &= \sum_f \bar{f} \gamma^\mu (v_f - a_f \gamma_5) f, \end{aligned} \quad (2.9)$$

609 where  $f$  denotes any SM fermion,  $\ell$  and  $\nu_\ell$  a charged lepton and a neutrino of any flavour,  
 610 and  $u_f$  and  $d_f$  an up-like and a down-like quarks of any flavour. For the NC case, the  
 611 values of the  $v_f$  and  $a_f$  couplings are given in Tab. 2.2.

612 As seen in Eq. (7.8), in the electroweak theory neutrinos are coupled to the  $Z$  boson  
 613 in a universal way. Therefore, by measuring the so-called invisible decay width of the  $Z$   
 614 boson we have an estimate of the number of light (i.e. lighter than the  $Z$  boson) neutrino  
 615 flavours. This number was measured by LEP in a combined analysis of  $e^+ e^- \rightarrow \mu^+ \mu^-$   
 616 and  $e^+ e^- \rightarrow \text{hadrons}$  to be  $N_\nu = 2.9840 \pm 0.0082$  [23].

### 617 2.3 Massive neutrinos

618 The existence of neutrino oscillations imply . However, as we have seen before, within  
 619 the SM neutrinos are massless, as they do not have a mass term in the Lagrangian. If  
 620 one wants to give neutrinos a mass, the particle content of the SM needs to be expanded.

## Chapter 2. Neutrino physics

621 A way of generating massive neutrinos while maintaining gauge invariance is by  
 622 introducing an arbitrary number of sterile neutrinos  $N_i, i = 1, \dots, m$ . These allow for  
 623 two different types of neutrino mass terms:

$$-\mathcal{L}_{M_\nu} = \sum_{i=1}^m \sum_{j=1}^3 M_D^{ij} \bar{N}_i \nu_{Lj} + \frac{1}{2} \sum_{i=1}^m \sum_{j=1}^m M_N^{ij} \bar{N}_i N_j^c + \text{h.c.}, \quad (2.10)$$

624 where  $M_D$  is a complex  $m \times 3$  matrix and  $M_N$  a complex, symmetric  $m \times m$  matrix.  
 625 The first term, often referred to as the Dirac mass term, arises from the corresponding  
 626 Yukawa interaction after the spontaneous electroweak symmetry breaking, similar to  
 627 the other fermions. The second term, called the Majorana mass term, is allowed in the  
 628 Lagrangian, as it is a singlet of the gauge group. However, it violates lepton number  
 629 conservation by two units.

630 If one imposes lepton number symmetry conservation, the Majorana term must  
 631 banish,  $M_N = 0$ . In this case, if  $m = 3$  we can identify the sterile neutrinos as the  
 632 right-handed component of the neutrino field. The Dirac mass matrix can be diagonalised  
 633 using two unitary matrices,  $V_R^\nu$  and  $V_L^\nu$ , as:

$$M_D = V_R^\nu \text{ diag}(m_1, m_2, m_3) V_L^{\nu\dagger}, \quad (2.11)$$

634 where  $m_i, i = 1, 2, 3$  are the masses of the three neutrino mass eigenstates.

635 The neutrino mass term can be written in term of the resulting eigenstates as:

$$-\mathcal{L}_{M_\nu} = \sum_{i=1}^3 m_i \bar{\nu}_{Di} \nu_{Di}, \quad (2.12)$$

636 with:

$$\nu_{Di} = \left( V_L^{\nu\dagger} \nu_L \right)_i + \left( V_R^{\nu\dagger} N \right)_i. \quad (2.13)$$

637 In this scenario, both the low energy particle budget and the symmetries of the SM  
 638 have to be modified. Moreover, the masses of the neutrinos are generated exclusively  
 639 through the Higgs mechanism, which does not explain why they are much smaller than

## 2.3. Massive neutrinos

640 those of the charged leptons.

641 Going back to the general case, we can re-write Eq. (2.10) in matrix form as:

$$-\mathcal{L}_{M_\nu} = \frac{1}{2} (\bar{\nu}_L^c, \bar{N}) \begin{pmatrix} 0 & M_D^T \\ M_D & M_N \end{pmatrix} \begin{pmatrix} \nu_L \\ N^c \end{pmatrix} + \text{h.c.} = \bar{\nu}^c M_\nu \nu + \text{h.c.}, \quad (2.14)$$

642 with  $\nu = (\nu_L, N^c)^T$  being a  $(3+m)$ -dimensional vector grouping the active and the  
 643 sterile neutrinos. The matrix  $M_\nu$ , which is a complex  $(3+m) \times (3+m)$  symmetric  
 644 matrix, can be diagonalised by means of a unitary matrix  $V^\nu$ , yielding:

$$M_\nu = V^\nu \text{ diag}(m_1, m_2, \dots, m_{3+m}) V^{\nu\dagger}. \quad (2.15)$$

645 Using this eigendecomposition, the neutrino mass term can be expressed as:

$$\begin{aligned} -\mathcal{L}_{M_\nu} &= \frac{1}{2} \sum_{i=1}^{3+m} m_i \left[ (\bar{\nu}^c V^\nu)_i (V^{\nu\dagger} \nu)_i + (\bar{\nu} V^\nu)_i (V^{\nu\dagger} \nu^c)_i \right] \\ &= \frac{1}{2} \sum_{i=1}^{3+m} m_i \bar{\nu}_{Mi} \nu_{Mi}, \end{aligned} \quad (2.16)$$

646 where the states  $\nu_{Mi}$ , commonly referred to as Majorana neutrinos, are defined as:

$$\nu_{Mi} = (V^{\nu\dagger} \nu)_i + (V^{\nu\dagger} \nu^c)_i^c, \quad (2.17)$$

647 in such a way that the Majorana condition,  $\nu_M^c = \nu_M$ , holds true.

648 As a consequence of the Majorana condition, the neutrino and the antineutrino states  
 649 can be described in terms of a single field. As opposed to the charged leptons, which  
 650 need to be represented by a four-component or Dirac spinor, the Majorana neutrino is  
 651 described by a two-component or Weyl spinor.

652 If the eigenvalues of the Majorana mass matrix,  $M_N$ , are much larger than the  
 653 electroweak symmetry breaking scale, the diagonalisation of  $M_\nu$  leads to 3 light and  $m$   
 654 heavy neutrino states:

$$-\mathcal{L}_{M_\nu} = \frac{1}{2} \bar{\nu}_l M_l \nu_l + \frac{1}{2} \bar{\nu}_h M_h \nu_h, \quad (2.18)$$

## Chapter 2. Neutrino physics

### 655 2.4 Neutrino oscillations

656 The evidence for neutrino oscillation [24], and therefore the existence of non-zero neutrino  
 657 masses, constitutes one of the groundbreaking discoveries of modern Physics and has  
 658 acted as driving force for Beyond the Standard Model (BSM) Physics. The minimal  
 659 extension of the Standard Model (SM) we can do to address these phenomena is  
 660 introducing distinct masses for at least two of the neutrinos. This way, we are left with  
 661 three neutrino mass eigenstates  $\nu_1$ ,  $\nu_2$  and  $\nu_3$ , with masses  $m_1$ ,  $m_2$  and  $m_3$  respectively,  
 662 which in general will not coincide with the flavour eigenstates  $\nu_e$ ,  $\nu_\mu$  and  $\nu_\tau$ .

663 The way to relate these two sets of neutrino eigenstates is via a  $3 \times 3$  unitary matrix,  
 664 called the Pontecorvo-Maki-Nakagawa-Sakata (PMNS) matrix [25, 26], as:

$$|\nu_\alpha\rangle = \sum_{i=1}^3 U_{\alpha i}^* |\nu_i\rangle, \quad (2.19)$$

665 where the Greek index  $\alpha$  denotes the flavour  $\{e, \mu, \tau\}$  and the Latin index  $i$  the associated  
 666 masses  $\{1, 2, 3\}$ . This leptonic mixing matrix may be parametrized in terms of 6  
 667 parameters, 3 of which are mixing angles  $\theta_{12}$ ,  $\theta_{13}$  and  $\theta_{23}$ , one CP-violating phase  $\delta_{CP}$   
 668 and 2 Majorana phases  $\alpha$  and  $\beta$ :

$$U = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_{23} & s_{23} \\ 0 & -s_{23} & c_{23} \end{pmatrix} \begin{pmatrix} c_{13} & 0 & s_{13}e^{-i\delta_{CP}} \\ 0 & 1 & 0 \\ -s_{13}e^{-i\delta_{CP}} & 0 & c_{13} \end{pmatrix} \begin{pmatrix} c_{12} & s_{12} & 0 \\ -s_{12} & c_{12} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & e^{i\alpha} & 0 \\ 0 & 0 & e^{i\beta} \end{pmatrix}, \quad (2.20)$$

669 where  $c_{ij} \equiv \cos \theta_{ij}$  and  $s_{ij} \equiv \sin \theta_{ij}$ . This matrix is analogous to the Cabibbo-Kobayashi-  
 670 Maskawa (CKM) matrix in the quark sector. If neutrinos are Dirac fermions, we can  
 671 drop the Majorana phases in the PMNS matrix. But, in any case, these phases play no  
 672 role on the neutrino oscillations.

## 2.4. Neutrino oscillations

### 2.4.1 Oscillations in vacuum

Consider the case where a neutrino of flavour  $\alpha$  is produced at  $t = 0$ , and then it propagates through vacuum. Such a state will evolve in time according to the relation:

$$|\nu_\alpha(t)\rangle = \sum_{i=1}^3 U_{\alpha i}^* e^{-iE_i t} |\nu_i(t=0)\rangle, \quad (2.21)$$

as the mass eigenstates are also eigenstates of the free Hamiltonian. Now, if we express the mass eigenstates as a superposition of flavour eigenstates, the last expression can be rewritten as:

$$|\nu_\alpha(t)\rangle = \sum_{i=1}^3 U_{\beta i} e^{-iE_i t} U_{\alpha i}^* |\nu_\beta\rangle. \quad (2.22)$$

This way, the probability for the neutrino to transition from flavour  $\alpha$  to flavour  $\beta$  will be given by:

$$P(\nu_\alpha \rightarrow \nu_\beta) = |\langle \nu_\beta | \nu_\alpha(t) \rangle|^2 = \left| \sum_{i=1}^3 U_{\beta i} e^{-iE_i t} U_{\alpha i}^* \right|^2. \quad (2.23)$$

A usual approximation to take at this point is to consider ultra-relativistic neutrinos, i.e.  $E \approx |\vec{p}|$ , so we can write the dispersion relations as:

$$E_i = \sqrt{p^2 + m_i^2} \approx E + \frac{m_i^2}{2E}, \quad (2.24)$$

so we can write the oscillation probability as:

$$\begin{aligned} P(\nu_\alpha \rightarrow \nu_\beta) &= \sum_{i,j} U_{\alpha i}^* U_{\beta i} U_{\alpha j} U_{\beta j}^* e^{-i \frac{\Delta m_{ij}^2}{2E} t} \\ &= \delta_{\alpha\beta} - 4 \sum_{i < j} \Re [U_{\alpha i}^* U_{\beta i} U_{\alpha j} U_{\beta j}^*] \sin^2 \left( \frac{\Delta m_{ij}^2}{4E} t \right) \\ &\quad + 2 \sum_{i < j} \Im [U_{\alpha i}^* U_{\beta i} U_{\alpha j} U_{\beta j}^*] \sin \left( \frac{\Delta m_{ij}^2}{2E} t \right), \end{aligned} \quad (2.25)$$

where  $\Delta m_{ij}^2$  is the difference of the squared masses of the  $j$ th and  $i$ th neutrino mass eigenvalues. At this point, it is usual to write the phase responsible for the oscillations

## Chapter 2. Neutrino physics

686 as (under the approximate assumption  $t \approx L$ ):

$$\Delta_{ij} \equiv \frac{\Delta m_{ij}^2}{4E} L \simeq 1.27 \frac{\Delta m_{ij}^2}{(\text{eV}^2)} \frac{L}{(\text{km})} \frac{(\text{GeV})}{E}. \quad (2.26)$$

687 Notice that, in the case of antineutrinos the only difference would be the sign of the  
688 last term in the oscillation probability. This way, one can write the CP asymmetry as:

$$\begin{aligned} A_{CP}^{\alpha\beta} &= P(\nu_\alpha \rightarrow \nu_\beta) - P(\bar{\nu}_\alpha \rightarrow \bar{\nu}_\beta) \\ &= 4 \sum_{i < j} \Im \left[ U_{\alpha i}^* U_{\beta i} U_{\alpha j} U_{\beta j}^* \right] \sin 2\Delta_{ij}. \end{aligned} \quad (2.27)$$

### 689 2.4.2 Oscillations in matter

690 When neutrinos propagate through matter, their oscillation can be affected in mainly  
691 two ways. First, neutrinos can inelastically scatter with nuclei, thus destroying the  
692 coherent propagation of their quantum state. Nevertheless, in most cases this effect is  
693 negligible (even in very dense mediums like the core of the Sun). Second, neutrinos can  
694 also experience coherent or forward scatterings, that can affect their oscillation but not  
695 lose the coherent propagation of the state.

696 The first proposed model to account for neutrino oscillations in matter was proposed  
697 by Mikhaev, Smirnov and Wolfenstein (MSW) [27]. It relies on the fact that, as the  
698 only charged lepton present in ordinary matter is the electron, electron neutrinos can  
699 undergo both charged and neutral-current interactions with matter whereas for muon  
700 and tau neutrinos just neutral currents are possible.

### 701 2.4.3 Current status of neutrino oscillations

702 A wide range of neutrino experiments provide experimental input to the neutrino  
703 oscillation framework, both using natural or synthetic neutrino sources. The results  
704 from one of the neutrino global fit analyses, shown in Tab. 2.3<sup>1</sup>, summarise well our  
705 current understanding of the different oscillation parameters.

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<sup>1</sup>These are the results reported during M. Tórtola's talk at Neutrino 2024 (see this link). I need to keep an eye and see if they publish these or other updated results in the near future.

## 2.5. Open questions in the neutrino sector

706       **Solar neutrino experiments** detect neutrinos produced in thermonuclear reactions  
707   inside the Sun, mainly from the so-called *pp* chain and the CNO cycle. These neutrinos  
708   have a typical energy in the range from 0.1 to 20 MeV. These experiments (Homestake  
709   [28], GALLEX [29], SAGE [30], Borexino [31], Super-Kamiokande [32] and SNO [33])  
710   provide the best sensitivities to  $\theta_{12}$  and  $\Delta m_{21}^2$ .

711       **Atmospheric neutrino experiments** detect the neutrino flux produced when  
712   cosmic rays scatter with particles in Earth's atmosphere. These collisions generate particle  
713   showers that eventually produce electron and muon neutrinos (and antineutrinos). Their  
714   energies range from few MeV to about  $10^9$  GeV. Experiments, like Super-Kamiokande  
715   [34] and IceCube [35] use atmospheric neutrinos to measure oscillations and are specially  
716   sensitive to  $\theta_{23}$  and  $\Delta m_{32}^2$ .

717       **Reactor neutrino experiments** look for the  $\bar{\nu}_e$  spectrum produced by nuclear  
718   reactors, with energies in the MeV scale. Depending on the distance to the source,  
719   long-baseline experiments like KamLAND [36] are sensitive to the solar mass splitting  
720    $\Delta m_{21}^2$  whereas much shorter baseline experiment such as RENO [37] or DayaBay [38]  
721   measure  $\theta_{13}$  and  $\Delta m_{31}^2$ .

722       **Accelerator experiments** measure neutrino fluxes generated in particle accelerators.  
723   Usually mesons are produced in the accelerator to be focused into a beam, then some  
724   decay to muon neutrinos and the rest are absorbed by a target. Depending on the  
725   configuration one can obtain a beam made of mostly neutrinos or antineutrinos. The  
726   typical energies of these neutrinos are in the GeV range. Experiments such as NOvA  
727   [39], T2K [40], MINOS [41], OPERA [42] and K2K [43] (and in the future DUNE [44])  
728   are primarily sensitive to  $\theta_{13}$ ,  $\theta_{23}$  and  $\Delta m_{32}^2$ . Also, in the coming years DUNE [44] and  
729   Hyper-Kamiokande [45] will be sensitive to  $\delta_{CP}$ .

## 730 2.5 Open questions in the neutrino sector

731   A crucial question that remains open these days, and is of vital importance for oscillation  
732   phenomena, is whether the mass eigenvalue  $\nu_3$  is the heaviest (what we call normal

## Chapter 2. Neutrino physics

**Table 2.3:** Summary of neutrino oscillation parameters determined in the Neutrino Global Fit of 2020 [16].

Parameter	Best fit $\pm 1\sigma$	$3\sigma$ range
$\Delta m_{21}^2$ [eV $^2 \times 10^{-5}$ ]	$7.55^{+0.22}_{-0.20}$	6.98 – 8.19
$ \Delta m_{31}^2 $ [eV $^2 \times 10^{-3}$ ] (NO)	$2.51^{+0.02}_{-0.03}$	2.43 – 2.58
$ \Delta m_{31}^2 $ [eV $^2 \times 10^{-3}$ ] (IO)	$2.41^{+0.03}_{-0.02}$	2.34 – 2.49
$\sin^2 \theta_{12}/10^{-1}$	$3.04 \pm 0.16$	2.57 – 3.55
$\sin^2 \theta_{23}/10^{-1}$ (NO)	$5.64^{+0.15}_{-0.21}$	4.23 – 6.04
$\sin^2 \theta_{23}/10^{-1}$ (IO)	$5.64^{+0.15}_{-0.18}$	4.27 – 6.03
$\sin^2 \theta_{13}/10^{-2}$ (NO)	$2.20^{+0.05}_{-0.06}$	2.03 – 2.38
$\sin^2 \theta_{13}/10^{-2}$ (IO)	$2.20^{+0.07}_{-0.04}$	2.04 – 2.38
$\delta_{CP}/\pi$ (NO)	$1.12^{+0.16}_{-0.12}$	0.76 – 2.00
$\delta_{CP}/\pi$ (IO)	$1.50^{+0.13}_{-0.14}$	1.11 – 1.87

ordering) or the lightest (referred to as inverted ordering) of the mass eigenstates. In other words, this means that we do not know the sign of  $\Delta m_{32}^2$ , so we can either have  $m_1 < m_2 < m_3$  (NO) or  $m_3 < m_1 < m_2$  (IO).

Another big puzzle is related to the value of  $\delta_{CP}$ . Nowadays it is poorly constrained, with all values between  $\pi$  and  $2\pi$  being consistent with data. A prospective measurement different from  $\delta_{CP} = 0, \pi$  will predict CP-violation in the leptonic sector, and thus contribute along with the one measured in the quark sector to the total amount of CP-violation. Although it is true that these two contributions by themselves are not enough to explain the matter anti-matter asymmetry in our universe, the amount of CP-violation in the leptonic sector can be key to explain such imbalance.

Both of these questions, because of their nature, could be understood thanks to future oscillation experiments.

Notwithstanding, there are other mysteries that can not be unveiled just by conducting oscillation experiments, as certain quantities do not influence these phenomena. Among these there is the question of the absolute values of the neutrino masses. Depending on the value of the lightest of the neutrino masses we can have different mass spectra, from hierarchical  $m_1 \ll m_2 < m_3$  (NO) or  $m_3 \ll m_1 < m_2$  (IO) to quasi-degenerate

## 2.6. Neutrino interactions

750  $m_1 \simeq m_2 \simeq m_3$ .

751 Other open question concerns the nature itself of the neutrinos. If neutrinos are Dirac  
752 particles then their mass term can be generated through the usual Higgs mechanism  
753 by adding right-handed neutrino fields. However, if they are Majorana particles and  
754 therefore their own antiparticles, there is no need to add extra fields to have the mass  
755 term in the Lagrangian. Experiments like SuperNEMO [46], SNO+ [47] and NEXT  
756 [48], which search for neutrino-less double beta decay, will be able to determine whether  
757 neutrinos are Dirac or Majorana.

### 758 2.6 Neutrino interactions



759 **Chapter 3**

760 **The Deep Underground Neutrino  
761 Experiment**

762 The Deep Underground Neutrino Experiment (DUNE) is a next generation long-baseline  
763 neutrino experiment [1]. It will aim to address several questions in neutrino physics,  
764 study neutrinos from astrophysical sources and search for beyond the standard model  
765 physics.

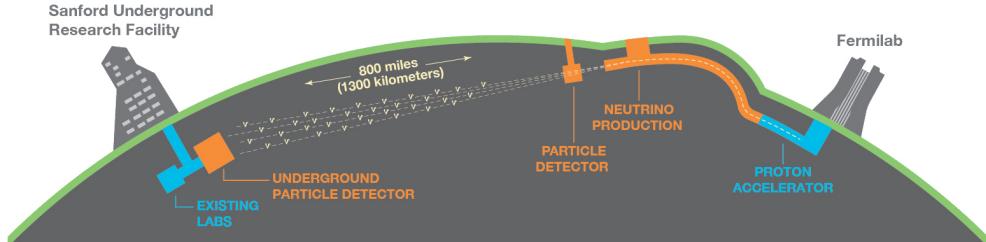
766 This chapter reviews the main goals of the DUNE experiment, the design of the far  
767 detector modules and their data acquisition (DAQ) system, and the role that the near  
768 detector plays in the physics program of DUNE.

769 **3.1 Overview**

770 The main physics goals of DUNE are:

- 771 • measure the neutrino mass hierarchy, the amount of CP violation in the leptonic  
772 sector and the  $\theta_{23}$  octant,
- 773 • detect rare low energy neutrino events, like neutrinos from supernova bursts, and
- 774 • search for proton decay and other beyond the standard model phenomena.

## Chapter 3. The Deep Underground Neutrino Experiment



**Figure 3.1:** Schematic diagram of the DUNE experiment and the LBNF beamline [1].

775        The design of DUNE has bee tailored with these goals in mind. It will consist  
776        of two neutrino detectors. A near detector (ND) complex will be placed in Fermilab,  
777        574 m downstream of the neutrino production point, whereas a larger far detector (FD)  
778        will be built in the Sandford Underground Research Facility (SURF), South Dakota,  
779        approximately 1300 km away. Fig. 3.1 shows a simplified view of the various components  
780        of DUNE (not to scale).

781        The beam neutrinos to be used in DUNE will be provided by the LBNF beamline,  
782        the multi-megawatt wide-band neutrino beam planned for Fermilab. First, an intense  
783        proton beam is extracted from the Fermilab Main Injector. Then, these protons with  
784        energies between 60 GeV and 120 GeV collide with a high-power production target and  
785        produce charged mesons. Two magnetic horns allow to focus the mesons and perform a  
786        sign selection (thus having the capability to switch between neutrino and antineutrino  
787        mode). Soon after that, the mesons decay and produce neutrinos (or antineutrinos)  
788        which are then aimed to SURF.

789        Before arriving to the FD, the neutrino beam meets the ND complex, which serves as  
790        the experiment's control. Its role is to measure the unoscillated neutrino energy spectra.  
791        From these we can predict the unoscillated spectra at the FD, which can be compared to  
792        the spectra measured at the FD in order to extract the oscillation parameters. Therefore,  
793        the design of the DUNE ND is mainly driven by the needs of the oscillation physics  
794        program.

795        The liquid Argon time projection chamber (LArTPC) technology has been chosen for

### 3.2. Physics goals of DUNE

**Table 3.1:** Summary of the two-phased plan for DUNE. Adapted from Ref. [49].

Parameter	Phase I	Phase II	Benefit
FD mass	20 kt fiducial	40 kt fiducial	FD statistics
Beam power	up to 1.2 MW	2.4 MW	FD statistics
ND config.	ND-LAr, TMS, SAND	ND-LAr, ND-GAr, SAND	Systematic constraints

the FD modules of DUNE. Its four modules will record neutrino interactions from the accelerator-produced beam arriving at predictable times. As it also aims at recording rare events, the FD requires trigger schemes which can deal with both kinds of physics, and also maximum uptime.

DUNE is planned to be built using a staged approach consisting on two phases, which are summarised in Tab. 3.1. Phase I consists of a FD with 50% of the total fiducial mass, a reduced version of the ND complex and a 1.2 MW proton beam. It will be sufficient to achieve some early physics goals, like the determination of the neutrino mass ordering. For its Phase II, DUNE will feature the full four FD modules, a more capable ND and a 2.4 MW proton beam. The physics milestones for the two phases are given in Tab. 3.2, in a staging scenario which assumes that Phase II is completed after 6 years of operation.

A summary of the DUNE science program can be found in the DUNE FD Technical Design Report (TDR) Volume I [1]. For a detailed discussion on the two-phased approach the reader is referred to the DUNE Snowmass 2021 report [49].

### 3.2 Physics goals of DUNE

As noted in the literature (see for instance Ref. [16] for a review), the parameter space of the neutrino oscillation phenomena within the three-flavour picture is quite constrained by current experimental data. However, there are still crucial open questions, like the mass ordering, the value of  $\delta_{CP}$  or the  $\theta_{13}$  octant. One of the main goals of DUNE is to shed some light on the values of these parameters [50].

To address these questions DUNE can look to the subdominant oscillation channel  $\nu_\mu \rightarrow \nu_e$  ( $\bar{\nu}_\mu \rightarrow \bar{\nu}_e$ ) and study the energy dependence of the  $\nu_e$  ( $\bar{\nu}_e$ ) appearance probability.

## Chapter 3. The Deep Underground Neutrino Experiment

**Table 3.2:** Exposure and time required to achieve the different physics milestones of the two phases. The predictions assume a Phase II staging scenario where FD modules 3 and 4 are deployed in years 4 and 6 and both the beam and ND are upgraded after 6 years. Adapted from Ref. [49].

Stage	Physics milestone	Exposure (kt-MW-years)	Years (staged)
Phase I	$5\sigma$ MO ( $\delta_{CP} = -\pi/2$ )	16	1-2
	$5\sigma$ MO (100% of the $\delta_{CP}$ values)	66	3-5
	$3\sigma$ CPV ( $\delta_{CP} = -\pi/2$ )	100	4-6
Phase II	$5\sigma$ CPV ( $\delta_{CP} = -\pi/2$ )	334	7-8
	$\delta_{CP}$ resolution of 10 degrees ( $\delta_{CP} = 0$ )	400	8-9
	$5\sigma$ CPV (50% of the $\delta_{CP}$ values)	646	11
	$3\sigma$ CPV (75% of the $\delta_{CP}$ values)	936	14
	$\sin^2(2\theta_{13})$ resolution of 0.004	1079	16

819 When we focus on the antineutrino channel  $\bar{\nu}_\mu \rightarrow \bar{\nu}_e$  there is a change in the sign of  $\delta_{CP}$ ,  
 820 thus introducing CP-violation. Moreover, due to the fact that there are no positrons in  
 821 the composition of Earth, there is a sign difference for the matter effect contribution  
 822 when looking to the antineutrino channel. This asymmetry is proportional to the baseline  
 823 length  $L$  and is sensitive to the sign of  $\Delta_{31}$ , and thus to the neutrino mass ordering.

824 Another of the main physics goals of DUNE is the search for baryon-number violating  
 825 processes. Specifically, it will try to answer the question of whether protons are stable  
 826 or not. There is no symmetry argument that forbids protons from decaying, but its  
 827 apparent stability seems to suggest that baryon number is conserved [51]. However,  
 828 proton decay is a usual feature of grand-unified theories, where electromagnetic, weak  
 829 and strong interactions are unified above a certain energy scale [52].

830 As the energy deposition scale for this kind of searches is nearly the same as the one  
 831 for long-baseline neutrino oscillations, DUNE will be able to look for them. It has several  
 832 advantages over other experiments, such as excellent imaging and particle identification,  
 833 which can be translated to lower backgrounds.

834 The last of the main objectives of DUNE is the detection of neutrinos originated in  
 835 supernovae explosions, what is called a supernova neutrino burst (SNB). These neutrinos  
 836 carry with them information about the core-collapse process, from the progenitor to the  
 837 explosion and the remnant; but also may have information about new exotic physics. So  
 838 far, the only neutrino events ever recorded from such a process were a few dozens of  $\bar{\nu}_e$

### 3.3. Far Detector

839 events from the 1987A supernova located in the Magellanic Cloud, 50 kpc away from  
840 Earth [53, 54].

841 DUNE aims to collect also some SNB events. Although these are quite rare, as the  
842 expected supernovae explosion events are about one every few decades for our galaxy  
843 and Andromeda, the long lifetime of the experiment (around a few decades as well)  
844 makes it reasonable to expect some. Nowadays the main sensitivity to SNB of most  
845 experiments is to the  $\bar{\nu}_e$  through inverse beta decay. One of the advantages of DUNE is  
846 its expected sensitivity to  $\nu_e$ , since the dominant channel will be  $\nu_e$  CC scattering.

847 Moreover, due to the stringent requirements that the main physics goals set for  
848 DUNE, it will allow also to perform searches for all kind of BSM physics. Among  
849 others, DUNE will be able to look for: active-sterile neutrino mixing, non-unitarity of  
850 the PMNS matrix, non-standard interactions, Lorentz and CPT violations, neutrino  
851 trident production, light-mass DM, boosted DM and heavy neutral leptons. The reader  
852 is referred to the DUNE FD TDR Volume II [50] for a full discussion of the physics  
853 scope of DUNE.

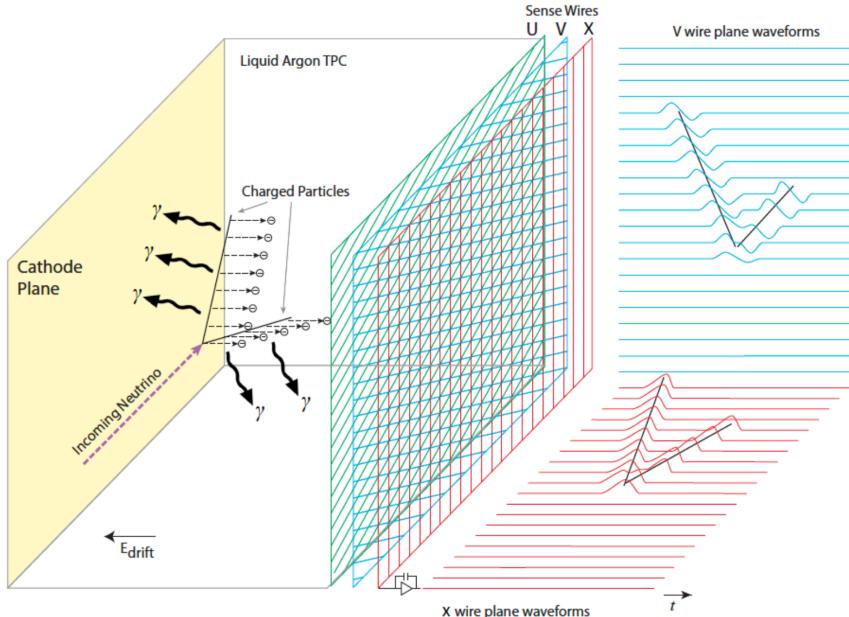
### 854 3.3 Far Detector

855 The so-called DUNE FD complex will sit 1.5 km underground at SURF, South Dakota.  
856 Two caverns will host the four FD modules, two of them per cavern, each embedded in  
857 cryostats of dimensions 18.9 m (w)  $\times$  17.8 m (h)  $\times$  65.8 m (l). A central, smaller cavern  
858 will host the cryogenic system.

859 Three out of the four modules will be liquid argon (LAr) time projection chamber  
860 detectors, often refer to as LArTPCs, with a LAr fiducial mass of at least 10 kt each.  
861 The first and second FD modules, FD-1 and FD-2, will use a Horizontal Drift (HD)  
862 technology, whereas the third module, FD-3, will have a Vertical Drift (VD) direction.  
863 The technology for the fourth module is still to be decided,

864 For each event, with energies ranging from a few MeV to several GeV, these detectors  
865 collect both the scintillation light and the ionisation electrons created when the charged

## Chapter 3. The Deep Underground Neutrino Experiment



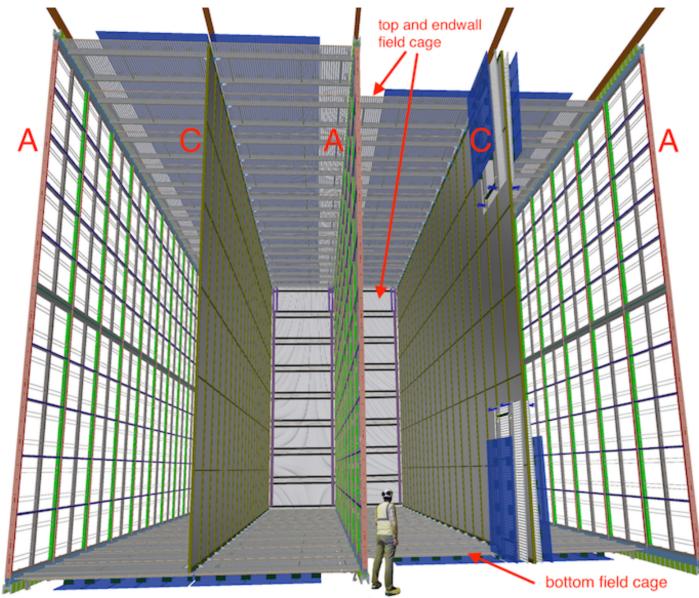
**Figure 3.2:** Schematic diagram showing the operating principle of a LArTPC with wire readout. Figure taken from Ref. [1].

866 particles produced in neutrino-nucleus interactions ionise the argon nuclei. In both HD  
 867 and VD designs the characteristic 128 nm scintillation light of argon is collected by a  
 868 photon detection system (PDS). This light will indicate the time at which electrons  
 869 start to drift, thus enabling reconstruction over the drift coordinate when compared  
 870 to the time when the first ionisation electron arrives to the anode. Reconstruction of  
 871 the topology in the transverse direction is achieved using the charge readout. Fig. 3.2  
 872 illustrates the detection principle described, for the case of a HD detector with a wire  
 873 readout.

### 874 3.3.1 Horizontal Drift

875 Within the HD design the ionisation electrons produced as charged particles traverse the  
 876 LAr drift horizontally towards the anode planes, made out of three layers of wire readout,  
 877 due to the effect of an electric field. This design, previously known as single-phase (SP),  
 878 was tested by the ProtoDUNE-SP detector at CERN. The prototype collected data from  
 879 a hadron beam and cosmic rays, providing high-quality data sets for calibration studies  
 880 and proving the excellent performance of this design.

### 3.3. Far Detector



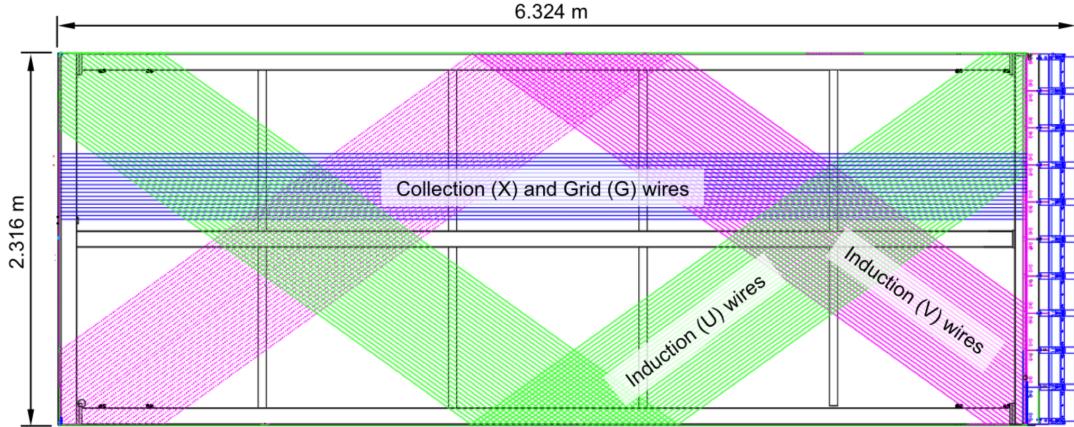
**Figure 3.3:** Proposed design for the FD-1 and FD-2 modules following the HD principle. Figure taken from Ref. [1].

881     Each FD HD detector module is divided in four drift regions, with a maximum drift  
 882   length of 3.5 m, by alternating anode and cathode walls. The surrounding field cage  
 883   ensures the uniformity of the 500 V/cm horizontal electric field across the drift volumes.  
 884   The three anode walls, which constitute the charge readout of the detector, are built by  
 885   stacking anode plane assemblies (APAs), 2 high times 25 wide. The design of the HD  
 886   modules is shown in Fig. 3.3.

887     Each APA is made of 2560 active wires arranged in three layers, plus an extra grid  
 888   layer, wrapped around a metal frame. The two induction wire planes, U and V, sit at  
 889    $\pm 35.7^\circ$  to the vertical on each side of the APA. The collection and shielding plane wires,  
 890   X and G, run parallel to the vertical direction. The ionisation electrons drift past the  
 891   induction planes, generating bipolar signals on those wires, and are collected by the  
 892   collection plane, producing a monopolar positive signal. The spacing between the wires  
 893   is  $\sim 5$  mm, and it defines the spatial resolution of the APA.

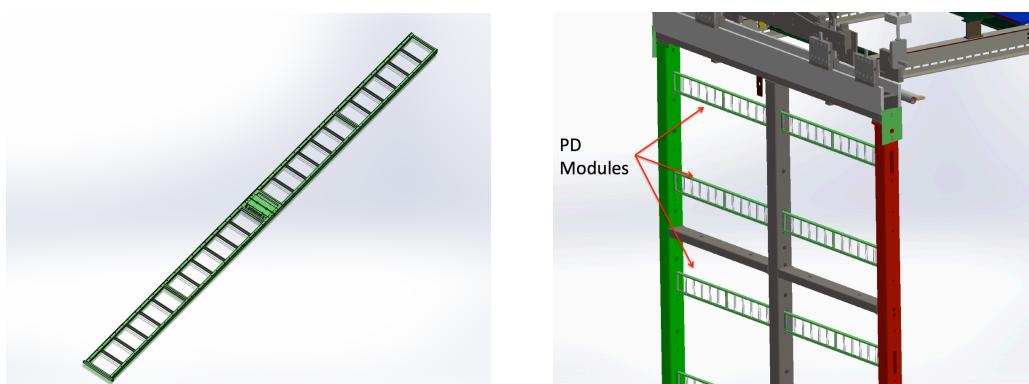
894     The front-end readout electronics, or cold electronics as they are immerse in the LAr,  
 895   are attached to the top of the up APAs and the bottom of the down APAs. Mounted on  
 896   the front-end mother boards we have a series of ASICs that digitize the signals from the

## Chapter 3. The Deep Underground Neutrino Experiment



**Figure 3.4:** Schematic representation of an APA. The black lines represent the APA steel frame. The green and magenta lines correspond to the direction of the U and V induction wires respectively. The blue lines indicate the direction of the X collection wires and the wire shielding G. Figure taken from Ref. [1].

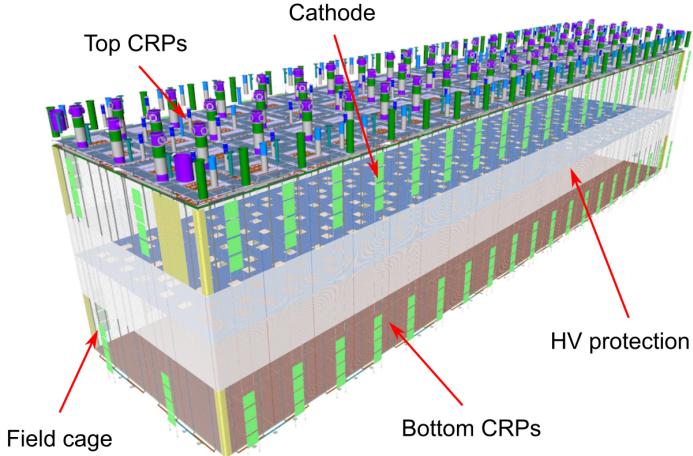
897 collection and induction planes. Each wire signal goes to a charge-sensitive amplifier,  
 898 then there is a pulse-shaping circuit and this is followed by the analogue-to-digital  
 899 converter. This part of the process happens inside the LAr to minimise the number of  
 900 cables penetrating the cryostat. The digitised signals come out finally via a series of  
 901 high-speed serial links to the warm interface boards (WIBs), from where the data is sent  
 902 to the back-end DAQ through optical fibers.



**Figure 3.5:** A PDS module containing 24 X-ARAPUCAs (left) and the location of the modules on the APAs (right). Figure taken from Ref. [1].

903 The PDS uses modules of X-ARAPUCA devices, mounted on the APA frames  
 904 between the wire planes. Each X-ARAPUCA consists of layers of dichroic filter and

### 3.3. Far Detector



**Figure 3.6:** Proposed design for the FD-3 module following the VD principle. Figure adapted from Ref. [55].

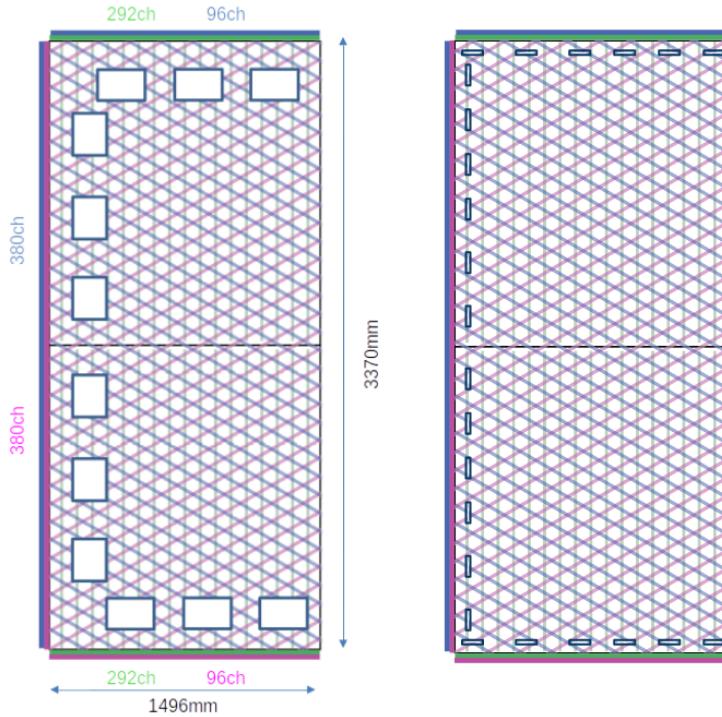
wavelength-shifter. They shift the VUV scintillation light into the visible spectrum, sending then the visible photons to silicon photomultiplier (SiPM) devices. The PDS modules are  $209\text{ cm} \times 12\text{ cm} \times 2\text{ cm}$  bars, containing 24 X-ARAPUCAs. There are 10 of these PDS modules per APA. Fig. 3.5 shows a PDS module (left) and the placement of the modules on the APAs (right).

#### 3.3.2 Vertical Drift

In the VD case the ionisation electrons will drift vertically until they meet a printed circuit board-based (PCB) readout plane. It is based on the original dual-phase (DP) design deployed at CERN, known as ProtoDUNE-DP, used a vertical drift design with an additional amplification of the ionization electrons using a gaseous argon (GAr) layer above the liquid phase. The VD module incorporates the positive features of the DP design without the complications of having the LAr-GAr interface.

The current design of the FD VD module counts with two drift chambers with a maximum drift distance of 6.5 cm. A cathode plane splits the detector volume along the drift direction while the two anode planes are connected to the bottom and top walls of the detector. The layout of the VD module is shown in Fig. 3.6. Compared with

## Chapter 3. The Deep Underground Neutrino Experiment



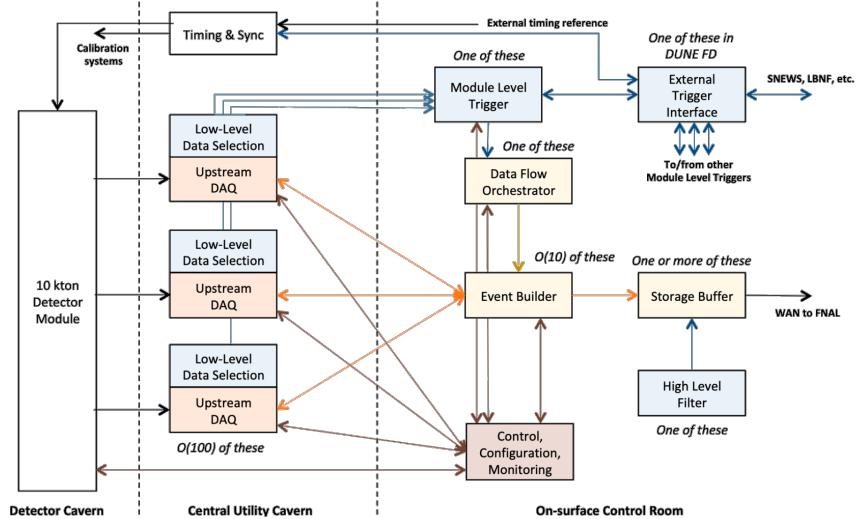
**Figure 3.7:** Schematic representation of the electrode strip configuration for a top (left) and bottom (right) CRU. Figure taken from Ref. [55].

the HD design, the VD option offers a slightly larger instrumented volume and a more cost-effective solution for the charge readout.

As in the HD design, each drift volume features a 500 V/cm electric field and a field cage that ensures its uniformity. The anode planes are arrays of  $3.4\text{ m} \times 3\text{ m}$  charge-readout planes (CRPs). These are formed by a pair of charge-readout units (CRUs), which are built from two double-sided perforated PCBs, with their perforations aligned. The perforations allow the drift electrons to pass between the layers.

The PCB face opposite to the cathode has a copper guard plane which acts as shielding, while its reverse face is etched with electrode strips forming the first induction plane. The outer PCB has electrode strips on both faces, the ones facing the inner PCB form the second induction plane while the outermost ones form the collection plane. Fig. 3.7 shows the layout of the electrode strips for the top (left) and bottom (right) CRUs. The magenta and blue lines represent the first and second induction planes respectively, and the green lines correspond to the collection plane.

### 3.3. Far Detector



**Figure 3.8:** Detailed diagram of the DUNE FD DAQ system. Figure taken from Ref. [2].

935        The PDS in the VD module will use the same X-ARAPUCA technology developed  
 936        for the HD design. The plan is to place the PDS modules on the cryostat walls and on  
 937        the cathode, in order to maximise the photon yield.

938        **3.3.3 FD Data Acquisition System**

939        The task of the data acquisition (DAQ) system is to receive, process and store data from  
 940        the detector modules. In the case of DUNE the DAQ architecture is designed to work  
 941        for all FD modules interchangeably, except some aspects of the upstream part which  
 942        may depend on the specific module technology.

943        The enormous sample rate and the number of channels in TPC and PD readouts  
 944        will produce a very large volume of data. These pose really strong requirements and  
 945        challenges to the DUNE FD DAQ architecture. It will be required to read out data of  
 946        the order of ten thousand or more channels at rates of a few MHz. In order to cope  
 947        with the huge data volume, segmented readouts and compression algorithms are used to  
 948        reduce the data rate to manageable levels.

949        The DAQ system of the DUNE FD is composed of five different subsystems. The  
 950        first one is the upstream DAQ, which receives the raw data from the detector, buffers it

## Chapter 3. The Deep Underground Neutrino Experiment

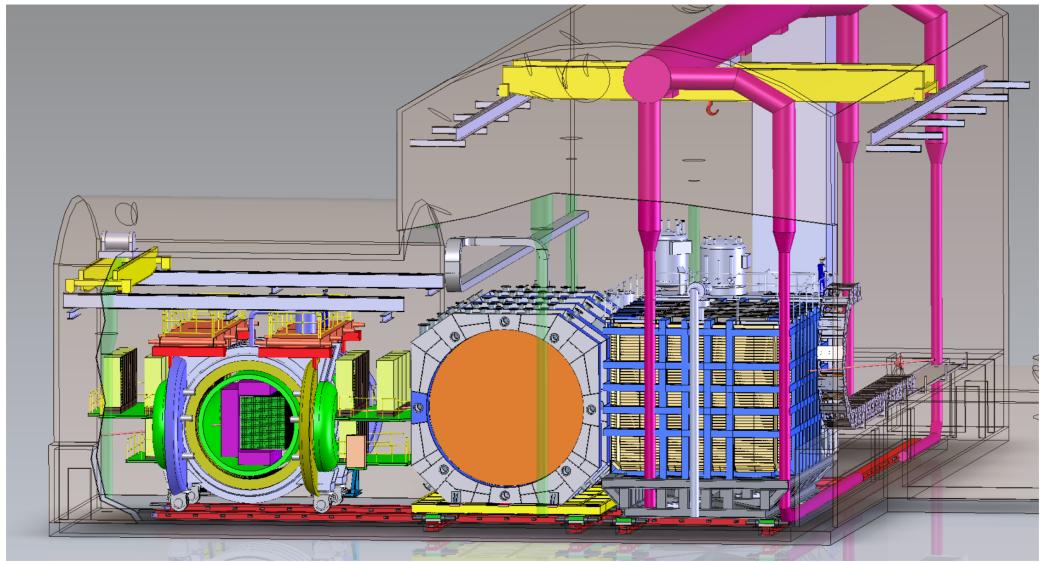
951 and perform some low-level pre-processing. The minimally processed data is then fed  
952 into a hierarchical data selection system, which then performs a module level trigger  
953 decision. In case of a positive decision a trigger command is produced and executed by  
954 the data flow orchestrator, located in the back-end (BE) DAQ subsystem. Subsequently  
955 the DAQ BE retrieves the relevant data from the buffers located in the upstream DAQ,  
956 adds all the data into a cohesive record and saves it to permanent storage. Watching  
957 over all the other subsystems we also have the control, configuration and monitoring  
958 subsystem and the time and synchronization subsystem. Fig. 3.8 shows a schematic  
959 diagram of the DAQ system, showing the different subsystems and their relations.

960 A notorious challenge for the DUNE DAQ system comes from its broad physics  
961 goals. We must be prepared to process events spanning a wide range of time windows  
962 (from 5 ms in the case of beam and cosmic neutrinos and nucleon decay to 100 s in the  
963 case of SNBs) and therefore this requires a continuous readout of the detector modules.  
964 Moreover, because of the off-beam measurements we need to ensure the capabilities  
965 of online data processing and self-triggering. Having this into account, together with  
966 the technical constraints, the DUNE FD DAQ faces a series of challenges: it needs to  
967 be fault tolerant and redundant to reduce downtime, accommodate new components  
968 while it keeps serving the operational modules, have large upstream buffers to handle  
969 SNB physics, be able to support a wide range of readout windows and last reduce the  
970 throughput of data to permanent storage to be at most 30 PB/year.

### 971 3.4 Near Detector

972 In order to estimate the oscillation parameters we measure the neutrino energy spectra  
973 at the FD. This reconstructed energy arises from a convolution of the neutrino flux, cross  
974 section, detector response and the oscillation probability. Using theoretical and empirical  
975 models to account for the other effects, one can extract the oscillation probability using  
976 the measurement. However, these models have associated a number of uncertainties that  
977 are then propagated to the oscillation parameters.

### 3.4. Near Detector



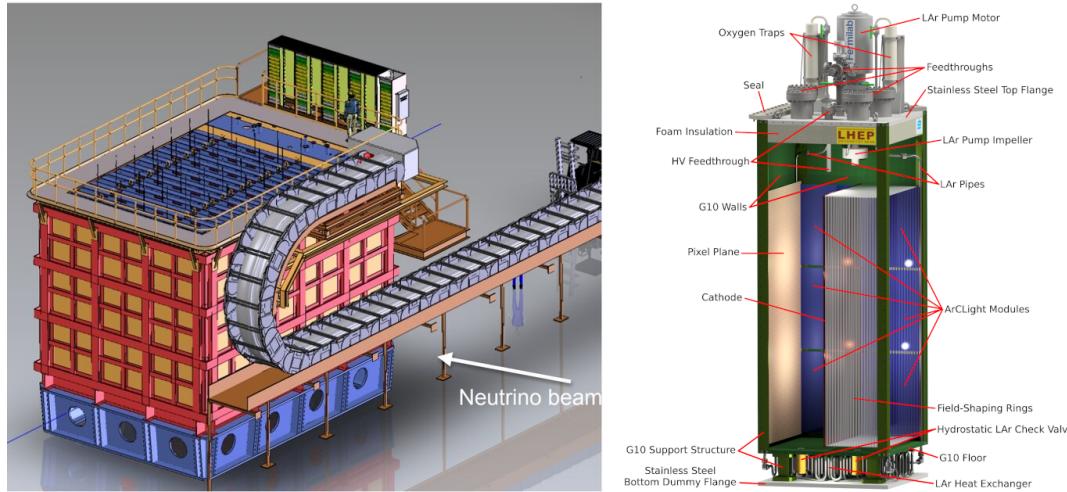
**Figure 3.9:** Representation of the ND hall in Phase II, showing the different subcomponents. From right to left, in the direction of the beam, we have ND-LAr, ND-GAr and SAND. Figure taken from Ref. [56].

978 One of the main roles of the ND is to measure the neutrino interaction rates before  
979 the oscillation effects become relevant, i.e. close to the production point. By measuring  
980 the  $\nu_\mu$  and  $\nu_e$  energy spectra, and that of their corresponding antineutrinos, at the ND  
981 we can constrain the model uncertainties. A complete cancellation of the uncertainties  
982 when taking the ratio between the FD and ND measurements is not possible, as that  
983 would require both detectors to have identical designs and the neutrino fluxes to be  
984 the same. Because of the distance, the flux probed by the FD will have a different  
985 energy and flavour composition than that at the ND, as neutrinos oscillate and the beam  
986 spreads. The differences in the flux also determine the design of the detectors, therefore  
987 the ND is limited in its capability to match the FD design.

988 Nevertheless, having a highly capable ND DUNE can minimise the systematic  
989 uncertainties affecting the observed neutrino energy. The ND data can be used to  
990 tune the model parameters by comparison with the prediction. Then, one uses the  
991 tuned model to predict the unoscillated FD spectra. Comparing the prediction with the  
992 measured spectra it is possible to extract the oscillation parameters.

993 Additionally, the ND will have a physics program of its own. In particular, it will

## Chapter 3. The Deep Underground Neutrino Experiment



**Figure 3.10:** Schematic representation of the external components of ND-LAr, including the cryostat and the PRISM movable system (left) and detailed drawing of one ArgonCube module (right). Figure adapted from Ref. [1].

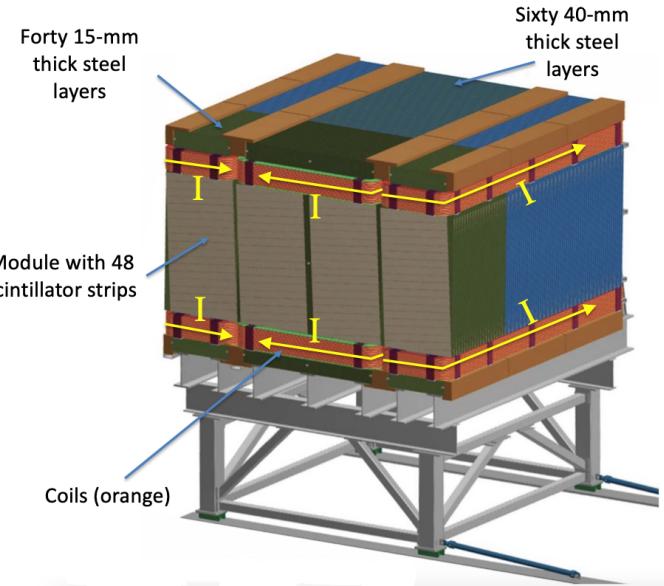
measure neutrino cross sections that will then be used to constrain the model used in the long-baseline oscillation analysis. It will also be used to search for BSM phenomena such as heavy neutral leptons, dark photons, millicharged particles, etc.

The DUNE ND can be divided in three main components, a LArTPC known as ND-LAr, a magnetised muon spectrometer, which will be the Temporary Muon Spectrometer (TMS) in Phase I and ND-GAr in Phase II, and the System for on-Axis Neutrino Detection (SAND). The layout of the Phase II DUNE ND can be seen in Fig. 3.9. The first two components of the ND will be able to move off-axis, in what is called the Precision Reaction-Independent Spectrum Measurement (PRISM) concept. More details on the purpose and design of the ND can be found in the DUNE ND Conceptual Design Report (CDR) [56].

### 3.4.1 ND-LAr

ND-LAr is a LArTPC, as the ND needs a LAr component in order to reduce cross section and detector systematic uncertainties in the oscillation analysis. However, its design differs significantly from those proposed for the FD modules. Because of the high event rates at the ND, approximately 55 neutrino interaction events per 10  $\mu\text{s}$  spill,

### 3.4. Near Detector



**Figure 3.11:** Schematic view of the TMS detector, highlighting its main parts. Figure adapted from Ref. [1].

ND-LAr will be built in a modular way. Each of the modules, based on the ArgonCube technology, is a fully instrumented, optically isolated TPC with a pixelated readout. The pixelisation allows for a fully 3D reconstruction and the optical isolation reduces the problems due to overlapping interactions. Fig. 3.10 shows a representation of the external parts of ND-LAr (left) and a detailed diagram of an ArgonCube module (right).

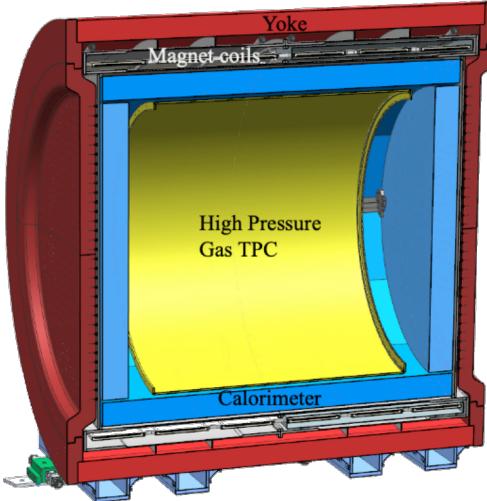
With a fiducial mass of 67 t and dimensions 7 m (w)  $\times$  3 m (h)  $\times$  5 m (l), ND-LAr will be able to provide high statistics and contain the hadronic systems from the beam neutrino interactions, but muons with a momentum higher than 0.7 GeV will exit the detector.

#### 3.4.2 TMS/ND-GAr

In order to accurately estimate the neutrino energy, the momentum of the outgoing muons needs to be determined. That is the reason why a muon spectrometer is needed downstream of ND-LAr.

In Phase I that role will be fulfilled by TMS. It is a magnetised sampling calorimeter, with alternating steel and plastic scintillator layers. Fig. 3.11 shows a schematic view of

## Chapter 3. The Deep Underground Neutrino Experiment



**Figure 3.12:** Cross section of the ND-GAr geometry, showing the HPgTPC, ECal and magnet. Figure adapted from Ref. [1].

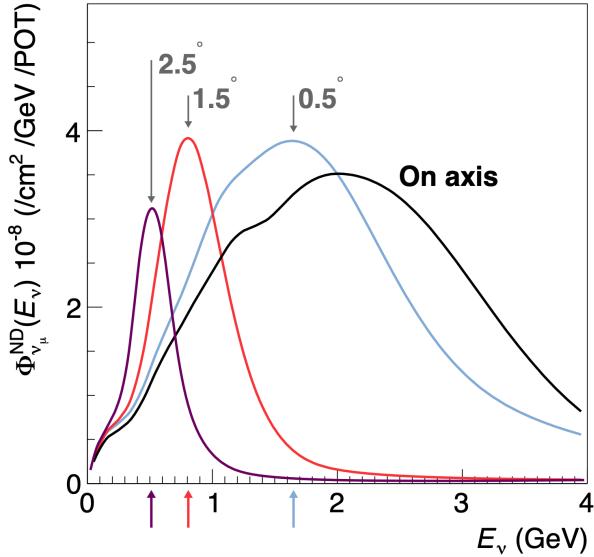
1025 the TMS detector. The magnetic field allows a precise measurement of the sign of the  
1026 muon, so one can distinguish between neutrino and antineutrino interactions.

1027 After the Phase II upgrade, TMS will be replaced with ND-GAr. This detector is  
1028 a magnetised, high-pressure GAr TPC (often denoted as HPgTPC) surrounded by an  
1029 electromagnetic calorimeter (ECal) and a muon tagger. A cross section of its geometry  
1030 can be seen in Fig. 3.12. ND-GAr will be able to measure the momenta of the outgoing  
1031 muons while also detect neutrino interactions inside the GAr volume. This allows  
1032 ND-GAr to constrain the systematic uncertainties even further, as it will be able to  
1033 accurately measure neutrino interactions at low energies thanks to the lower tracking  
1034 thresholds of GAr.

### 1035 3.4.3 PRISM

1036 In general, the observed peak neutrino energy of a neutrino beam decreases as the  
1037 observation angle with respect to the beam direction increases. This feature has been  
1038 used in other long-baseline neutrino experiments, like T2K ( $2.5^\circ$  off-axis) and NOvA  
1039 ( $0.8^\circ$  off-axis), in order to achieve narrower energy distributions. The DUNE PRISM  
1040 concept exploits this effect using a movable ND. Within PRISM both ND-LAr and the

### 3.4. Near Detector



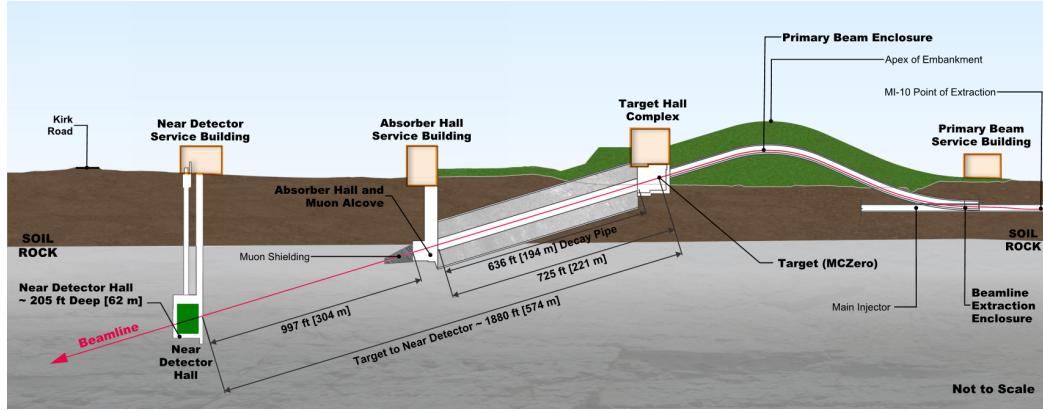
**Figure 3.13:** Predicted beam muon neutrino flux at the ND location for different off-axis positions. Figure taken from Ref. [56].

1041 muon spectrometer (TMS in Phase I and ND-GAr in Phase II) can be moved up to 3.2°  
 1042 off-axis, equivalent to move the detectors 30.5 m laterally through the ND hall.

1043 This allows to record additional data samples with different energy compositions.  
 1044 Fig. 3.13 compares the on-axis muon neutrino flux at the ND with the fluxes at different  
 1045 off-axis positions. As the off-axis position increases the neutrino flux becomes closer to  
 1046 a monoenergetic beam with a lower peak energy. These samples can be used to perform  
 1047 a data-driven determination of the relation between true and reconstructed neutrino  
 1048 energy, in order to reduce the dependence on the interaction model. The off-axis samples  
 1049 are linearly combined to produce a narrow Gaussian energy distribution centered on  
 1050 a target true energy. From the combination coefficients one can build a sample of  
 1051 reconstructed neutrino events that will determine the energy mapping.

1052 The PRISM samples can also be used to form a flux at the ND location similar in  
 1053 shape to the oscillated flux measured by the FD. This method can be used to extract  
 1054 the oscillation parameters with minimal input from the neutrino interaction model.

## Chapter 3. The Deep Underground Neutrino Experiment



**Figure 3.14:** Schematic longitudinal section of the LBNF beamline at Fermilab (not to scale). Figure taken from Ref. [57].

### 1055 3.4.4 SAND

1056 The role of SAND is to monitor the beam stability by measuring the on-axis neutrino  
 1057 energy spectra. As the PRISM program requires that ND-LAr and its downstream  
 1058 muon spectrometer spend about half of the time in off-axis positions, it is not possible  
 1059 to monitor the stability with the movable detectors. Moreover, for the success of PRISM  
 1060 it is essential to have a stable beam configuration, or, at least, a quick assessment and  
 1061 modeling of the distortions.

1062 The SAND detector is magnetised, and it counts with an inner low density tracker,  
 1063 a LAr target with optical readout and surrounding sampling calorimeter.

## 1064 3.5 LBNF beamline

1065 The Long-Baseline Neutrino Facility (LBNF) project is responsible for producing the  
 1066 neutrino beam for the DUNE detectors. A detailed discussion of the LBNF program  
 1067 can be found in the DUNE/LBNF CDR Volume III [57].

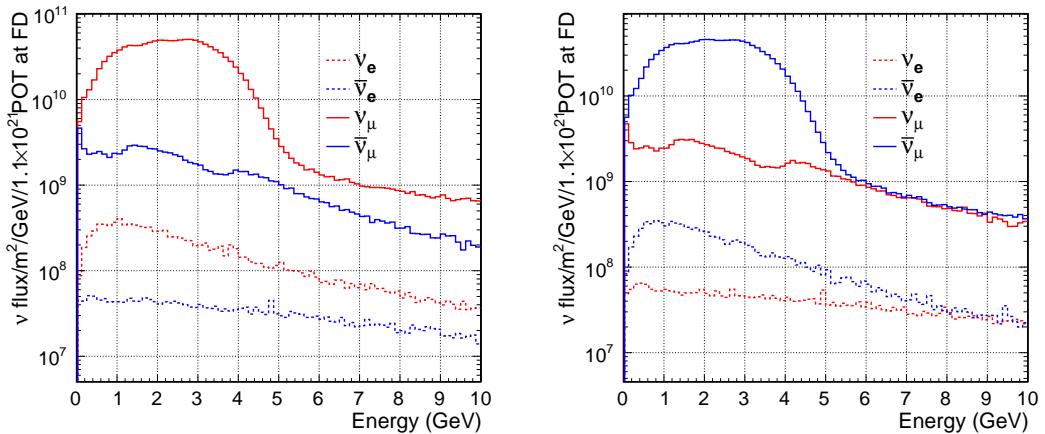
1068 The LBNF beamline will provide a high-intensity neutrino beam within the adequate  
 1069 energy range in order to meet the long-baseline oscillation physics goals of DUNE. A  
 1070 schematic diagram of the longitudinal section of the LBNF beamline is shown in Fig.  
 1071 3.14. First, a beam of  $60 - 120$  GeV protons is extracted from the Fermilab Main

### 3.5. LBNF beamline

1072 Injector. This beam is aimed towards the target area, where it collides with a cylindrical  
 1073 graphite target to produce pions and kaons.

1074 The diffuse, secondary beam of particles is focused by a pair of magnetic horns.  
 1075 These select the positively charged particles when operated in Forward Horn Current  
 1076 (FHC) mode, or the negatively charged ones when the current is reversed, also known as  
 1077 Reverse Horn Current (RHC) mode. The focused secondary beam then enters a 194 m  
 1078 decay pipe where the pions and kaons will predominantly produce  $\mu^+\nu_\mu$  pairs when in  
 1079 FHC mode (or  $\mu^-\bar{\nu}_\mu$  in RHC mode).

1080 At the end of the decay pipe a hadron absorber removes the undecayed hadrons and  
 1081 muons from the beam, which reduces the  $\nu_e$  ( $\bar{\nu}_e$ ) and  $\bar{\nu}_\mu$  ( $\nu_\mu$ ) contamination coming  
 1082 from the  $\mu^+$  ( $\mu^-$ ) decays. The resulting neutrino flux at the FD is shown in Fig. 3.15,  
 1083 both for FHC (left) and RHC (right) modes. These predictions show the intrinsic  $(\bar{\nu}_e)$   
 1084 contamination and wrong sign component from wrong sign and neutral meson decays,  
 1085 as well as muons decaying before reaching the absorber.



**Figure 3.15:** Predicted neutrino fluxes at the FD in FHC mode (left panel) and RHC mode (right panel). Figures taken from Ref. [50].



1086 **Chapter 4**

1087 **ND-GAr**

1088 ND-GAr is a magnetised, high-pressure gaseous argon TPC (HPgTPC), surrounded by  
1089 an electromagnetic calorimeter (ECal) and a muon detector (commonly refer to as  $\mu$ ID).  
1090 A detailed discussion on the requirements, design, performance and physics of ND-GAr  
1091 can be found in the DUNE ND CDR [56] and the ND-GAr whitepaper (cite).

1092 In DUNE Phase II ND-GAr will fulfill the role of TMS, measuring the momentum  
1093 and sign of the charged particles exiting ND-LAr. Additionally, it will be able to measure  
1094 neutrino interactions inside the HPgTPC, achieving lower energy thresholds than those  
1095 of the ND and FD LArTPCs. By doing so ND-GAr will allow to constrain the relevant  
1096 systematic uncertainties for the LBL analysis even further.

1097 The goal of the present chapter is to review the requirements that the physics program  
1098 of DUNE impose on ND-GAr, present the current status of its design and describe the  
1099 GArSoft package, its simulation and reconstruction software.

1100 **4.1 Requirements**

1101 The primary requirement for ND-GAr is to the measure the momentum and charge of  
1102 muons from  $\nu_\mu$  and  $\bar{\nu}_\mu$  CC interactions in ND-LAr, in order to measure their energy  
1103 spectrum. To achieve the sensitivity to the neutrino oscillation parameters described  
1104 in the DUNE FD TDR Volume II [50] ND-GAr should be able to constrain the muon

## Chapter 4. ND-GAr

1105 energy within a 1% uncertainty or better. The main constraint will come from the  
1106 calibration of the magnetic field, performed using neutral kaon decays in the HPgTPC.

1107 Another requirement for ND-GAr is the precise measurement of neutrino interactions  
1108 on argon for the energies relevant to the neutrino oscillation program. The goal is to  
1109 constrain the cross section systematic uncertainties in the regions of phase space that  
1110 are not accessible to ND-LAr. This requires the kinematic acceptance for muons in  
1111 ND-GAr to exceed that of ND-LAr, being comparable to the one observed in the FD.

1112 ND-GAr should also be able to the relationship between true and reconstructed energy  
1113 from neutrino interactions on argon with low thresholds, being sensitive to particles that  
1114 are not observed or may be misidentified in ND-LAr. In particular, ND-GAr needs to  
1115 have low tracking thresholds in order to measure the spectrum of pions and protons  
1116 produced in final-state interactions (FSI). It also must be able to accurately measure  
1117 the pion multiplicity in 1, 2 and 3 pions final states, to inform the pion mass correction  
1118 in the LArTPCs.

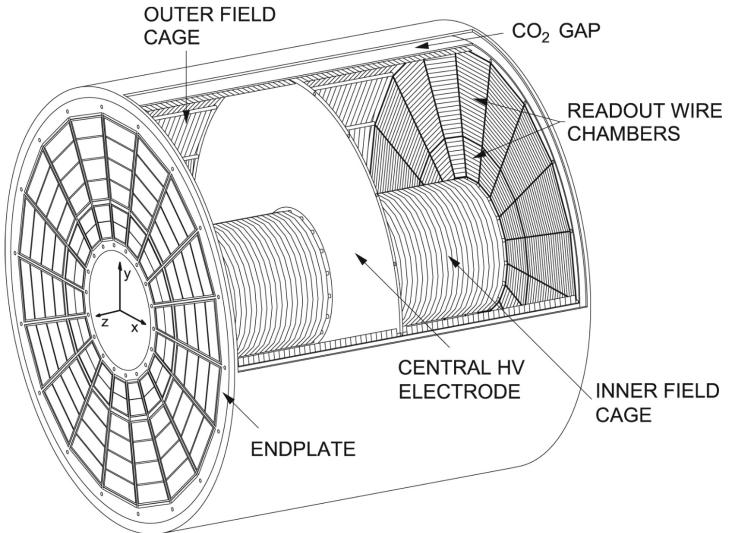
### 1119 4.2 Reference design

1120 The final design of ND-GAr is still under preparation. However, a preliminary baseline  
1121 design was in place at the time of the ND CDR. This section summarises the main  
1122 features of that design, as it is also the one used for the default geometry in our simulation.  
1123 A DUNE Phase II whitepaper, discussing the different options under consideration for  
1124 the ND-GAr design, is in progress.

#### 1125 4.2.1 HPgTPC

1126 The reference design for the ND-GAr HPgTPC follow closely that of the ALICE TPC.  
1127 It is a cylinder with a central high-voltage cathode, generating the electric field for  
1128 the two drift volumes, with a maximum drift distance of 2.5 m each. The anodes will  
1129 be instrumented with charge readout chambers. The original design repurposed the  
1130 multi-wire proportional readout chambers of ALICE, however the current R&D efforts

## 4.2. Reference design



**Figure 4.1:** Diagram of the ALICE TPC, showing the two drift chambers, inner and outer field cages and readout chambers. Figure taken from Ref. [1].

1131 focus on a gas electron multiplier option instead. Fig. 4.1 shows a schematic diagram of  
 1132 the ALICE TPC design. The basic ND-GAr geometry will resemble this, except for the  
 1133 inner field cage.

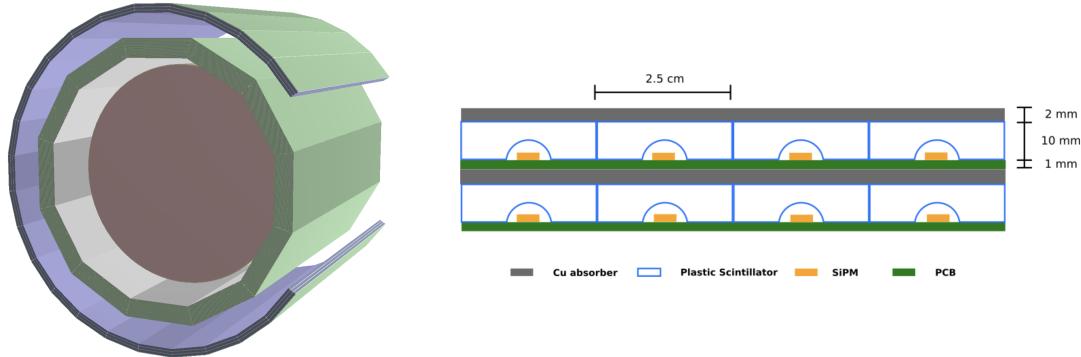
1134 It will use a 90-10 molar fraction argon-CH<sub>4</sub> mixture at 10 bar. With this baseline  
 1135 gas mixture light collection is not possible, as the quenching gas absorbs most of the  
 1136 VUV photons. Additional R&D efforts are underway, to understand if different mixtures  
 1137 allow for the light signal to be used to provide a  $t_0$  while maintaining stable charge gain.

### 1138 4.2.2 ECal

1139 The main role of the ND-GAr ECal is the calorimetric measurement of the electron  
 1140 energies and the reconstruction of photons, in particular those from neutral pion decays.  
 1141 Also, the ECal is able to provide a  $t_0$  timestamp for neutrino interactions, by associating  
 1142 its activity to the tracks in the HPgTPC. The ECal will also be able to perform  
 1143 neutron reconstruction using time of flight and reject external backgrounds, thanks to  
 1144 its sub-nanosecond time resolution.

1145 The ECal design features three independent subdetectors, two end caps at each side  
 1146 and a barrel surrounding the HPgTPC. Each of the detectors is divided in modules,

## Chapter 4. ND-GAr



**Figure 4.2:** View of the 12-sided ECal barrel and outer muon tagger geometries (left) and layout of the ECal tile layers for the 2 mm Cu, 10 mm scintillator option (right). Figure adapted from Ref. [1].

which combine alternating layers of plastic scintillator and absorber material readout by SiPMs. The inner scintillator layers consist of  $2.5 \times 2.5 \text{ cm}^2$  high-granularity tiles, whereas the outer ones are made out of 4 cm wide cross-strips spanning the whole module length. The current barrel geometry consists of 8 tile layers and 34 strip layers, while the end caps feature 6 and 36 respectively. The thickness of the scintillator layers is 7 mm and 5 mm for the Pb absorber layers. The 12-sided geometry of the ECal barrel (left) and the layout of the tile layers (left)<sup>1</sup> can be seen in Fig. 4.2.

### 4.2.3 Magnet

The ND-GAr magnet design, known as the Solenoid with Partial Yoke (SPY), consists of two coupled solenoids with an iron return yoke. The idea behind the design is to have a solenoid as thin as possible, as well as a return yoke mass distribution that minimises the material budget between ND-LAr and ND-GAr. The magnet needs to provide a 0.5 T field in the direction perpendicular to the beam, parallel to the drift electric field. It needs to host the pressure vessel and the surrounding ECal, which points to an inner diameter of  $\sim 6.4 \text{ m}$ .

The solenoid is a single layer coil, based on niobium titanium superconducting

<sup>1</sup>The figure shows the layout of the tile layers for a previous design with 2 mm Cu absorber and 10 mm plastic scintillator, as mentioned in the text the current choice is 5 mm Pb absorber and 7 mm scintillator.

### 4.3. GArSoft

1163 Rutherford cable. The total length of the coil is 7.5 m. The bobbin will be split in four  
1164 segments grouped in pairs with two identical cryostats, connected in series. The iron  
1165 yoke features an aperture in the upstream side to allow the muons coming from ND-LAr.  
1166 Still, its material will be enough to reduce the magnetic field reaching SAND, and also  
1167 stop the charged pions produced inside the HPgTPC.

#### 1168 4.2.4 Muon system

1169 The design of the ND-GAr muon system is still in a preliminary stage. Its role is to  
1170 distinguish between muons and pions punching through the ECal. This is especially  
1171 important for wrong-sign determination, to separate these from neutral current events.

1172 In its current form, the muon system consists of three layers of longitudinal sampling  
1173 structures. It alternates 10 cm Fe absorber slabs with 2 cm plastic scintillator strips.

1174 The transverse granularity required is still under study.

### 1175 4.3 GArSoft

1176 GArSoft is a software package developed for the simulation and reconstruction of events  
1177 in ND-GAr. It is inspired by the LArSoft toolkit used for the simulation of LArTPC  
1178 experiments, like the DUNE FD modules. It is based on `art`, the framework for event  
1179 processing in particle physics experiments [58]. Other of its main dependencies are `ROOT`,  
1180 `NuTools`, `GENIE` and `Geant4`. It allows the user to run all the steps of a generation-  
1181 simulation-reconstruction workflow using FHiCL configuration files.

#### 1182 4.3.1 Event generation

1183 The standard generator FHiCLs in GArSoft run the event generation and particle  
1184 propagation simulation (i.e. Geant4) in the same job by default. However, it is possible  
1185 to split them up if needed. The current version of GArSoft provides five different event  
1186 generators, each of them producing `simb::MCTruth` products defined in `NuTools`. The  
1187 available modules are:

## Chapter 4. ND-GAr

- 1188     • **SingleGen**: particle gun generator. It produces the specified particles with a given  
1189       distribution of momenta, initial positions and angles.
- 1190     • **TextGen**: text file generator. The input file must follow the `hepevt` format<sup>2</sup>, the  
1191       module simply copies this to `simb::MCTruth` data products.
- 1192     • **GENIEGen**: GENIE neutrino event generator. The module runs the neutrino-nucleus  
1193       interaction generator using the options specified in the driver FHiCL file (flux file,  
1194       flavour composition, number of interactions per event,  $t_0$  distribution, ...). Current  
1195       default version is `v3_04_00`.
- 1196     • **RadioGen**: radiological generator. It produces a set list of particles to model  
1197       radiological decays. Not tested.
- 1198     • **CRYGen**: cosmic ray generator. The module runs the CRY event generator with a  
1199       configuration specified in the FHiCL file (latitude and altitude of detector, energy  
1200       threshold, ...). Not tested.

1201       The module `GArG4` searches for all the generated `simb::MCTruth` data products, using  
1202       them as inputs to the Geant4 simulation with the specified detector geometry. A constant  
1203       0.5 T magnetic field along the drift coordinate is assumed. The main outputs of this step  
1204       are `simb::MCParticle` objects for the generated Geant4 particles, `gar::EnergyDeposit`  
1205       data products for the energy deposits in the HPgTPC and `gar::CaloDeposit` data  
1206       products for the energy deposits in the ECal and muon system.

### 1207 4.3.2 Detector simulation

1208       The standard detector simulation step in GArSoft is all run with a single FHiCL, but  
1209       the different modules can be run independently as well. First the `IonizationReadout`

<sup>2</sup>In brief, each event contains at least two lines. The first line contains two entries, the event number and the number of particles in the event. Each following line contains 15 entries to describe each particle. The entries are: status code, pdg code for the particle, entry of the first mother for this particle, entry of the second mother for this particle, entry of the first daughter for this particle, entry of the second daughter for this particle, x component of the particle momentum, y component of the particle momentum, z component of the particle momentum, energy of the particle, mass of the particle, x component of the particle initial position, y component of the particle initial position, z component of the particle initial position and time of the particle production.

### 4.3. GArSoft

1210 module simulates the charge readout of the HPgTPC, and later the `SiPMReadout` module  
1211 runs twice, once for the ECal and then for the muon system, with different configurations.

1212 The `IonizationAndScintillation` module collects all the `gar::EnergyDeposit`  
1213 data products, to compute the equivalent number of ionization electrons for each energy  
1214 deposit. The `ElectronDriftAlg` module simulates the electron diffusion numerically  
1215 both in the longitudinal and transverse directions and applies an electron lifetime  
1216 correction factor. The induced charge on the nearest and neighbouring readout pads  
1217 is modeled using the provided pad response functions. The digitisation of the data is  
1218 then simulated with the `TPCReadoutSimAlg` module. By default, the ADC sampling  
1219 rate used is 50.505 MHz. The resulting raw waveforms for each channel are stored with  
1220 zero-suppression, in order to save memory and CPU time. The algorithms keep blocks  
1221 of ADC values above a certain threshold, plus some adjustable additional early and late  
1222 tick counts. The results of these three steps are `gar::raw::RawDigit` data products.

1223 For the ECal and the muon system the `SiPMReadout` module calls either the  
1224 `ECALReadoutSimStandardAlg` or `MuIDReadoutSimStandardAlg` modules. These take  
1225 all the `gar::CaloDeposit` data products in the corresponding detector and do the  
1226 digitisation depending on whether the hit was in a tile or strip layer. They include single  
1227 photon statistics, electronic noise, SiPM saturation and time smearing. The resulting  
1228 objects are `gar::raw::CaloRawDigit` data products.

#### 1229 4.3.3 Reconstruction

1230 The reconstruction in GArSoft is also run as a single job by default. It first runs the hit  
1231 finding, clustering, track fitting and vertex identification in the HPgTPC, followed by  
1232 the hit finding and clustering in the ECal and muon system. After those it produces the  
1233 associations between the associations between the tracks and the ECal clusters.

1234 Focusing first on the HPgTPC reconstruction, the `CompressedHitFinder` module  
1235 takes the zero-suppressed ADCs from the `gar::raw::RawDigit` data products. The  
1236 reconstructed hits largely correspond to the above threshold blocks, however the hit  
1237 finder identifies waveforms with more than one maximum, diving them in multiple hits

## Chapter 4. ND-GAr

1238 if they dip below a certain threshold. The data products produced are of the form  
1239 `gar::rec::Hit`. These are the inputs to the clustering of hits in the `TPCHitCluster`  
1240 module. Hits close in space and time are merged, and the resulting centroids are found.  
1241 This module outputs `gar::rec::TPCClusters` objects and associations to the input  
1242 hits.

1243 The following step prior to the track fitting is pattern recognition. The module  
1244 called `tpcvechitfinder2` uses the `gar::rec::TPCClusters` data products to find track  
1245 segments, typically called vector hits. They are identified by performing linear 2D fits  
1246 to the positions of the clusters in a 10 cm radius, one fit for each coordinate pair. A  
1247 3D fit defines the line segment of the vector hit, using as independent variable the one  
1248 whose sum of (absolute value) slopes in the 2D fits is the smallest. The clusters are  
1249 merged to a given vector hit if they are less than 2 cm away from the line segment. The  
1250 outputs are `gar::rec::VecHit` data products, as well as associations to the clusters. The  
1251 `tpcpatrec2` module takes the `gar::rec::VecHit` objects to form the track candidates.  
1252 The vector hits are merged together if their direction matches, their centers are within  
1253 60 cm and their direction vectors point roughly to their respective centers. Once  
1254 the clusters of vector hits are formed they are used to make a first estimation of the  
1255 track parameters, simply taking three clusters along the track. The module produces  
1256 `gar::rec::Track` data products and associations between these tracks and the clusters  
1257 and vector hits.

1258 The track is fitted by means of a Kalman filter in the `tpctrackfit2` module, using  
1259 the position along the drift direction as the independent variable. Two different fits are  
1260 performed per track, a forward and a backwards fit, each starting from one of the track  
1261 ends. The Kalman filter state vector ( $y, z, R, \phi, \tan\lambda$ ) is estimated at each point along  
1262 the track using a Bayesian update. The track parameters reported in the forward and  
1263 backwards fits are the ones computed at the opposite end where the fit started. The  
1264 main outputs of the track fit are the `gar::rec::Track` objects. Additionally, the module  
1265 stores the fitted 3D positions along the track in the `gar::rec::TrackTrajectory` data  
1266 products and the total charge and step sizes for each point also get stored in the form of

### 4.3. GArSoft

1267 `gar::rec::TrackIonization` objects.

1268 After the tracking step, the `vertexfinder1` module looks at the reconstructed  
1269 `gar::rec::Track` products, creating vertex candidates with the track ends that are  
1270 within 12 cm of each other. The vertices are then fitted using linear extrapolations from  
1271 the different track ends associated. The results are `gar::rec::Vertex` data products,  
1272 and associations to the tracks and corresponding track ends.

1273 For the ECal and muon tagger, the `SiPMHitFinder` module runs twice with different  
1274 configurations, adapted to the particular capabilities of both. The module simply takes  
1275 the `gar::raw::CaloRawDigit` products, applies a calibration factor to convert the ADC  
1276 counts to MeV and for the strip layer hits it calculates the position along the strip using  
1277 the times recorded of both SiPMs. This module produces `gar::rec::CaloHit` data  
1278 products. Next, these objects are used as inputs to the `CaloClustering` module. It  
1279 merges the hits based on a simple nearest neighbours (NN) algorithm. For the resulting  
1280 clusters it also computes the total energy and position of the centroid. The results are  
1281 stored as `gar::rec::Cluster` data products, with associations to the hits.

1282 The last step in the reconstruction is associating the reconstructed tracks in the  
1283 HPgTPC to the clusters formed in the ECal and muon system. The `TPCECALAssociation`  
1284 module checks first the position of the track end points, considering only the points  
1285 that are at least 215 cm away from the cathode or have a radial distance to the center  
1286 greater than 230 cm. The candidates are propagated up to the radial position, in the  
1287 case of clusters in the barrel, or the drift coordinate position, for the end cap cluster, of  
1288 the different clusters in the collection using the track parameters computed at the end  
1289 point. The end point is associated to the cluster if certain proximity criteria are met.  
1290 This module creates associations between the tracks, the end points and the clusters.  
1291 The criteria for the associations are slightly different for the ECal and the muon tagger.



<sub>1292</sub> Chapter 5

<sub>1293</sub> FWTPG offline software



1294 Chapter 6

1295 Matched Filter approach to  
1296 induction wire Trigger Primitives

1297 6.1 Motivation

1298 The filter implemented in the firmware of the upstream DUNE FD DAQ is a 32nd-order  
1299 low-pass finite impulse-response (FIR) filter. The output of such filter for a discrete  
1300 system can be written as:

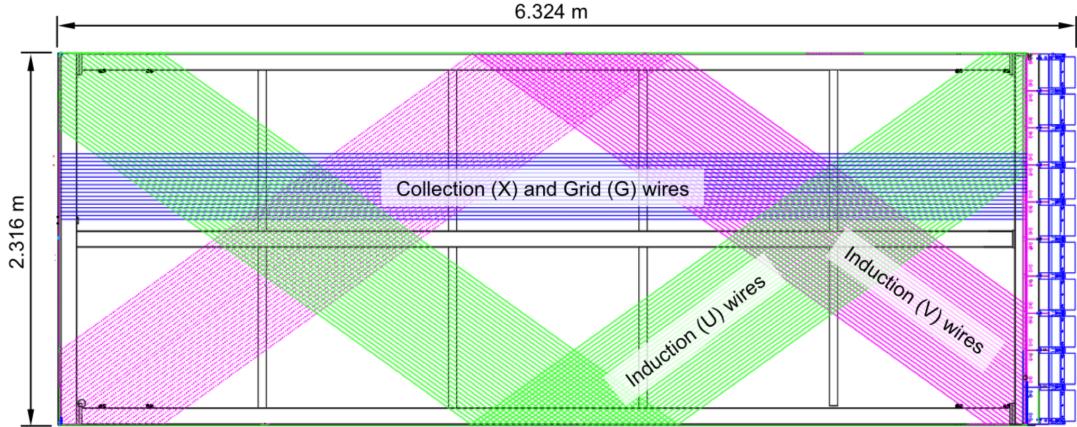
$$y[i] = \sum_{j=0}^N h[j]x[i-j], \quad (6.1)$$

1301 where  $N$  is the order of the filter,  $y$  is the output sequence,  $x$  is the input sequence and  $h$   
1302 is the set of coefficients of the filter. The current implementation within `dtp-firmware`  
1303 [59] uses a set of 16 non-zero integer coefficients.

1304 Filtering is a vital step in the hit finder chain. It helps to suppress the noise and  
1305 enhance the signal peaks with respect to the noiseless baseline. A good filtering strategy  
1306 allows us to use lower thresholds when forming the trigger primitives (TPs) and thus  
1307 increasing the sensitivity of our detector to low energy physics events. In such events,  
1308 the hits produced by the ionisation electrons tend to have lower amplitudes than those  
1309 of interest to the baseline physics programme of the DUNE experiment.

1310 This is particularly important for the induction planes. In general, signal peaks in

## Chapter 6. Matched Filter approach to induction wire Trigger Primitives



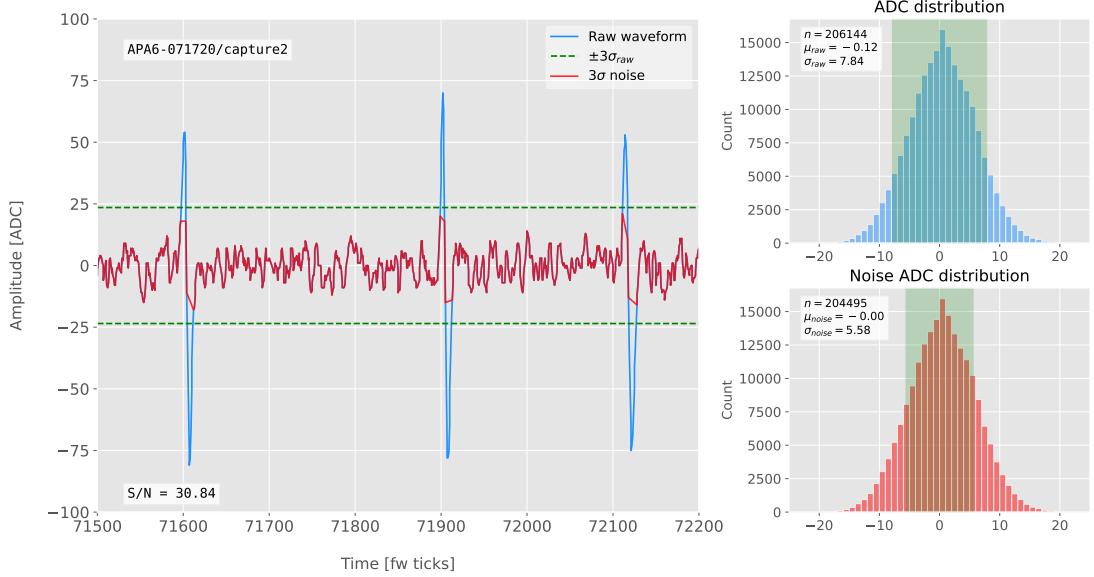
**Figure 6.1:** Schematic representation of an APA. The black lines represent the APA steel frame. The green and magenta lines correspond to the direction of the U and V induction wires respectively. The blue lines indicate the direction of the X collection wires and the wire shielding G.

the induction wires have smaller amplitude than the ones in the induction plane. This, together with the fact that the pulse shapes are bipolar, reduces our capacity to detect the hits on these channels. The inefficiency of detecting TPs in the induction planes (denoted as U and V planes) lead trigger algorithms to focus mainly on the TPs from the collection plane (so-called X plane). As a result, the possibility of making trigger decisions based on the coincidence of TPs across the three wire planes remains nowadays unexploited in DUNE. Fig. 6.1 shows a schematic view of an anode plane assembly (APA), with the different wire plane orientations highlighted.

A possible improvement of the current hit finder chain could require optimising the existing or choosing a new filter implementation. A filter strategy which improves the induction signals may be able to enhance the detection efficiency of TPs from the induction planes and ideally make it comparable to that of the collection plane.

The goal is to implement a better finite-impulse response filter design and to evaluate its performance relative to the current filter. To do so, we need to take into account the limitations of the firmware: the FIR filter shall have maximum 32 coefficients (so-called taps) whose values are 12-bit unsigned integers. Although it is technically possible to include non-integer coefficients, it would be a technical challenge as we have 40 FIR

## 6.2. Signal-to-noise ratio definition



**Figure 6.2:** Left panel: Zoomed unfiltered waveform corresponding to channel 7840 from the ProtoDUNE-SP raw data capture `felix-2020-07-17-21:31:44` (blue line). The green dashed lines mark the region  $\pm 3\sigma_{\text{raw}}$ . The resulting noise waveform is also shown (red line). Top right panel: ADC distribution for channel 7840, where the green shaded region represents  $\pm \sigma_{\text{raw}}$ . Bottom right panel: noise ADC distribution for channel 7840, where the green shaded region represents  $\pm \sigma_{\text{noise}}$ .

1328 instances per APA, as there are 4 FIR per optical link and 10 optical links per APA.  
 1329 With these restrictions, the task is to provide a set of 32 coefficients which yield an  
 1330 optimal filter performance for the induction wires.

## 1331 6.2 Signal-to-noise ratio definition

1332 I introduce the signal to noise ratio (S/N) as a measure of the FIR filter performance  
 1333 and demonstrate how to extract its value for a set of ProtoDUNE-SP data. The S/N  
 1334 metrics allow us to compare different filter implementations and serve as a basis for more  
 1335 detailed studies presented later in this document. Specifically, I use the ADC capture  
 1336 `felix-2020-07-17-21:31:44` (data capture taken for firmware validation purposes). I  
 1337 defined S/N as the height of the signal peaks relative to the size of the noise peaks.  
 1338 To quantify this quantity channel by channel one first need to estimate the standard  
 1339 deviation of the ADC data for each channel,  $\sigma_{\text{ADC}}$ . Then, I define the corresponding

## Chapter 6. Matched Filter approach to induction wire Trigger Primitives

noise waveform to be the ADC values in the range  $\pm 3\sigma_{ADC}$ . From this new noise data one can estimate again the mean and standard deviation,  $\mu_{noise}$  and  $\sigma_{noise}$ , so I can write the S/N for any given channel as:

$$S/N = \frac{\max [ADC] - \mu_{noise}}{\sigma_{noise}}, \quad (6.2)$$

where  $\max [ADC]$  is simply the maximum ADC value found in the corresponding channel.

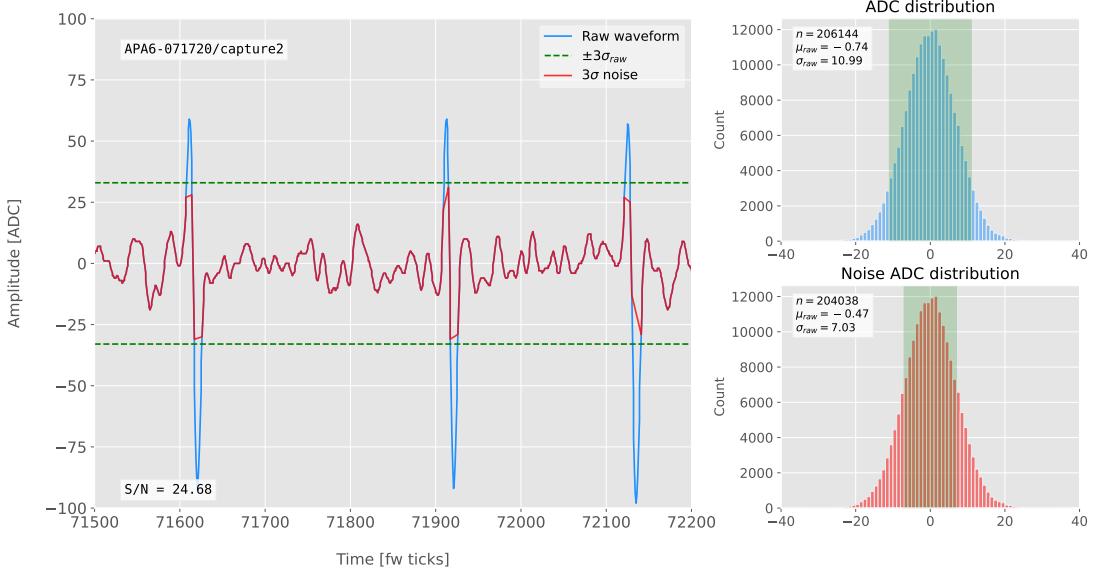
One can apply this definition of the S/N with a waveform from one of the channels of the data capture<sup>1</sup>. Fig. 6.2 shows a zoomed region of the waveform corresponding to channel 7840 (blue line), where one can clearly see three signal peaks and continuous additive noise (we actually see 6 peaks, 3 positive and 3 negative, but, because by design for induction channels the expected signal pulse shapes are bipolar, I treat them as a collection of 3 individual signal peaks). I estimated the standard deviation of this raw waveform to be  $\sigma_{raw} = 7.84$  ADC, so I am able to define the noise waveform (red line) as the ADC values in the range  $\pm 23.52$  ADC. This way one obtains  $\mu_{noise} = 0$  and  $\sigma_{noise} = 5.58$  ADC, which gives  $S/N = 30.84$ .

We can repeat this calculation now for the corresponding filtered waveform (using the current firmware FIR filter). In Fig. 6.3 I plotted the same time window for the filtered waveform from channel 7840 (blue line). In this case, the standard deviation of the waveform is larger than before, giving  $\sigma_{raw} = 10.99$  ADC. The resulting noise waveform (red line) results from selection the ADC values in the range  $\pm 32.91$  ADC, giving now  $\mu_{noise} = -0.47$  ADC and  $\sigma_{noise} = 7.03$  ADC. Finally, one obtains  $S/N = 24.68$ . Notice that the value of S/N decreases after the filtering. Clearly, one can see that the noise baseline has increased by a factor of 1.35 when we applied the FIR filter and at the same time the amplitude of the signal peaks has remained almost unchanged, leading to this poorer S/N value.

---

<sup>1</sup>All the original work was done within the `dtp-simulation` package [60], which offers a variety of tools to read raw data and emulate the TPG block (pedestal subtraction, filtering and hit finder). However, the results shown in this report were re-worked later using the C++ based `dtpemulator` package [61]. Its main purpose is the emulation of the TPG block and, in the same way as its predecessor, it has been cross-checked against the current firmware implementation.

### 6.3. Low-pass FIR filter design



**Figure 6.3:** Left panel: Zoomed filtered waveform corresponding to channel 7840 from the ProtoDUNE-SP raw data capture `felix-2020-07-17-21:31:44` (blue line). The filter used was the current implementation of the low-pass FIR filter in `dtp-firmware`. The green dashed lines mark the region  $\pm 3\sigma_{\text{raw}}$ . The resulting noise waveform is also shown (red line). Top right panel: ADC distribution for channel 7840 after filtering, where the green shaded region represents  $\pm \sigma_{\text{raw}}$ . Bottom right panel: noise ADC distribution for channel 7840 after filtering, where the green shaded region represents  $\pm \sigma_{\text{noise}}$

### 1363 6.3 Low-pass FIR filter design

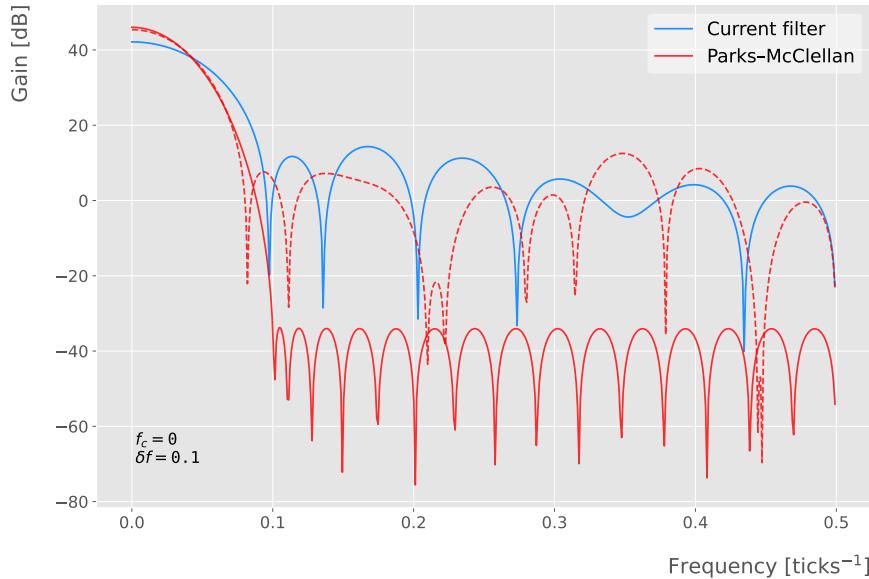
1364 In general, when one uses a method to optimize the frequency response of a digital filter,  
 1365 such as the Parks-McClellan algorithm, one finds a set of  $N$  real coefficients that give  
 1366 the best response for the specified pass-band and order of the filter [62].

1367 In our case, as the sampling frequency is defined as  $1 \text{ ticks}^{-1}$ , the Nyquist frequency  
 1368 will simply be  $1/2 \text{ ticks}^{-1}$ . The current implementation of the filter seems to have as  
 1369 pass-band the range  $[0, 0.1] \text{ ticks}^{-1}$ . This can be seen in Fig. 6.4, where I show the  
 1370 power spectrum, in decibels, of such filter implementation (blue solid line). For instance,  
 1371 the Park-McClellan algorithm finds the optimal Chebyshev FIR filter taking as input  
 1372 the boundaries of the target pass-band and stop-band, which can be written in the form:

$$\left\{ \begin{array}{l} [0, f_c] \\ [f_c + \delta f, f_N] \end{array} \right. , \quad (6.3)$$

## Chapter 6. Matched Filter approach to induction wire Trigger Primitives

where  $f_c$  is the cut-off frequency,  $\delta f$  is the transition width and  $f_N$  is the aforementioned Nyquist frequency. A similar behaviour to the one in the current filter can be obtained by setting  $f_c = 0$  and  $\delta f = 0.1 \text{ ticks}^{-1}$ . The response of the resulting filter is also shown in Fig. 6.4 (blue solid line). Notice that the suppression of the stop-band is enhanced for this optimal filter. For comparison I included the power response of the filter obtained by taking the integer part of the coefficients resulting from the Parks-McClellan method (red dashed line). One can see that it does not suppress that much the stop-band, in a similar way to the current implementation of the filter.

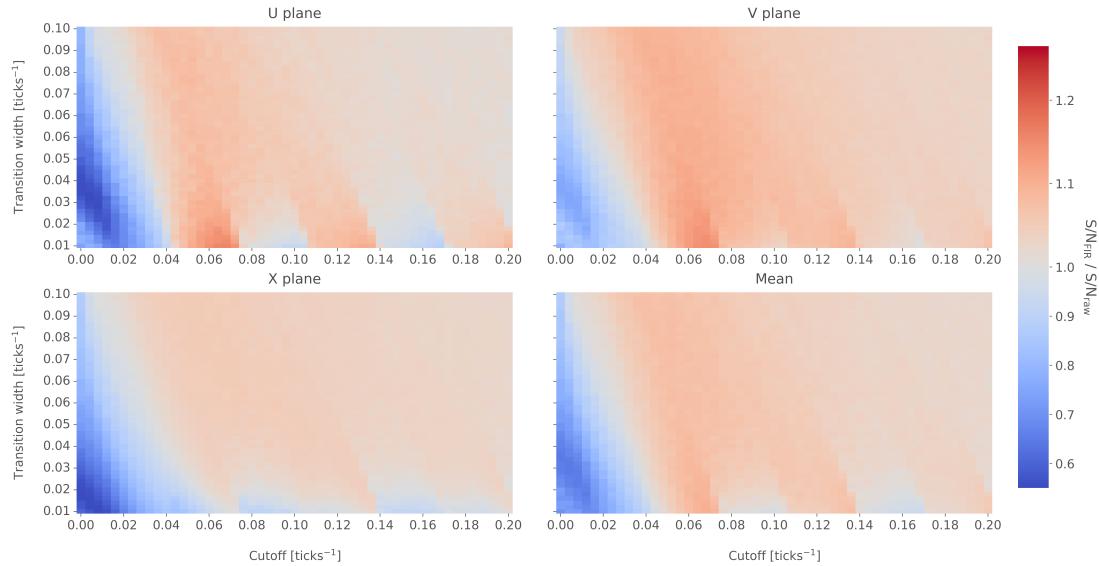


**Figure 6.4:** Power spectrum in decibels for the current implementation of the low-pass FIR filter in `dtp-firmware` (blue line), compared to the response of an optimal filter obtained using the Parks-McClellan algorithm for the same pass-band (red line). Also for comparison I include the spectrum of the optimal filter when taking only the integer part of the coefficients (red dashed line).

At this point, I tried to improve the performance of the FIR filter using the Parks-McClellan method, i.e. maximize the overall S/N, using the available data captures. I did so by varying the values of the two quantities that parametrize the pass-band and stop-band, the cut-off frequency  $f_c$  and the transition width  $\delta f$ .

Fig. 6.5 shows the average relative change in the S/N (i.e. the ratio between the value of the S/N after and before the filtering) for capture `felix-2020-07-17-21:31:44`,

### 6.3. Low-pass FIR filter design

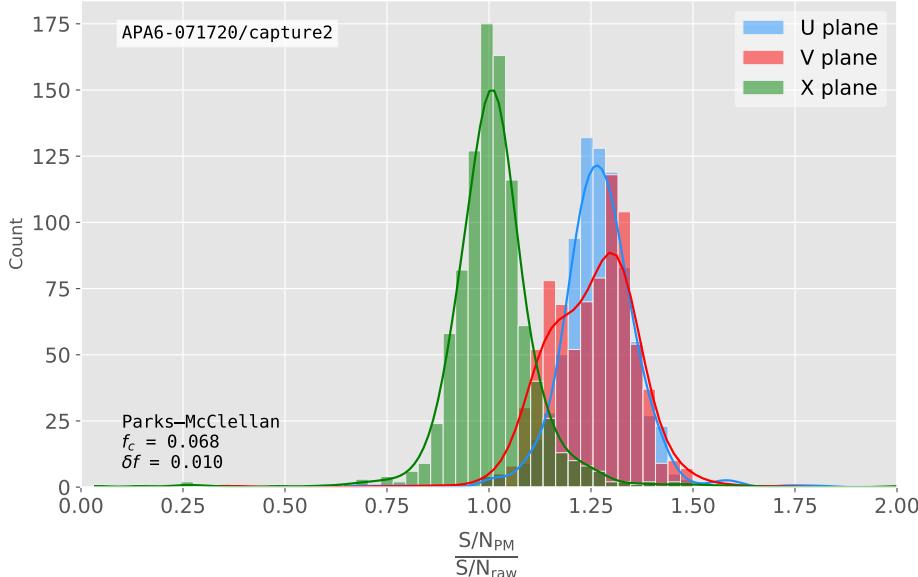


**Figure 6.5:** Relative change in the S/N for the ProtoDUNE-SP raw data capture `felix-2020-07-17-21:31:44`, using different values of the cutoff frequency  $f_c$  and the transition width  $\delta f$ . The optimal Chebyshev filters were applied using just the integer part of the coefficients given by the Parks-McClellan algorithm.

when using filters designed with the Parks-McClellan algorithm for the specified values of the cut-off frequency  $f_c$  and the transition width  $\delta f$ , restricted to integer values for the filter coefficients. One can clearly distinguish different regions where we get an improvement of up to a factor of 1.35 for the U plane. For large values of  $f_c + \delta f$  the ratio tends to 1, as expected (in that limit the width of the stop-band goes to 0, meaning that no frequencies are filtered out and thus the waveform remains the same).

Using the configuration which gives the best mean performance for the three planes (see bottom right panel of Fig. 6.5), i.e.  $f_c = 0.068 \text{ ticks}^{-1}$  and  $\delta f = 0.010 \text{ ticks}^{-1}$ , we can see how such filter affects the different channels. Fig. 6.6 shows the distribution of the S/N improvement values for all the channels in the raw ADC capture `felix-2020-07-17-21:31:44`, separated by wire plane, after the optimal Chebyshev filter was applied. One can see that there is a clear improvement for both U and V induction wire planes, obtaining a mean change of 1.25 and 1.30 for them respectively. However, in the case of the collection plane X the mean of this distribution is roughly 1, meaning that a good fraction of channels in that plane get a slightly worse S/N after the

## Chapter 6. Matched Filter approach to induction wire Trigger Primitives



**Figure 6.6:** Distribution of the relative change of the S/N on the different wire planes from the ProtoDUNE-SP raw data capture *felix-2020-07-17-21:31:44* after the optimal Chebyshev filter was applied. The filter was computed with the Parks-McClellan algorithm using a cutoff of  $f_c = 0.068 \text{ ticks}^{-1}$  and a transition width  $\delta f = 0.010 \text{ ticks}^{-1}$ .

filter is applied. In any case, this is not a big issue as the S/N for collection channels is usually much higher than the one for induction channels.

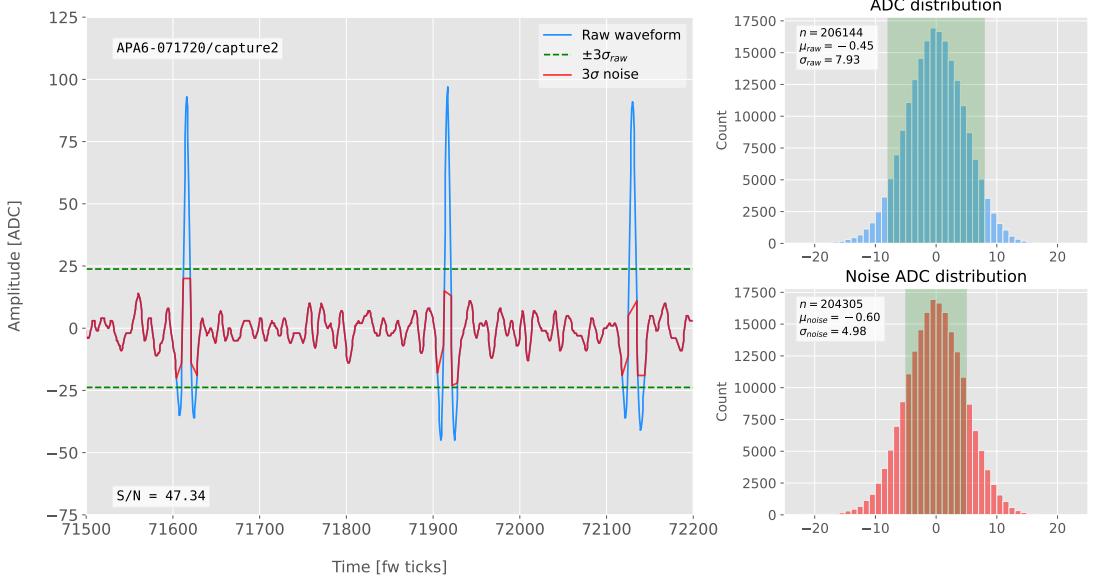
The results I obtained optimising the low pass filter with the Parks-McClellan method are promising. Nonetheless, the improvement found is rather marginal so I wondered if there could be an alternative approach to the filtering problem which yields better outputs. At this point, I found a possible alternative in matched filters. By construction, this kind of filters offer the best improvement on the S/N.

## 6.4 Matched filters

In the context of signal processing, a matched filter is the optimal linear filter for maximising the signal-to-noise ratio (S/N) in the presence of additive noise, obtained by convolving a conjugated time-reversed known template with an unknown signal to detect the presence of the template in the signal [63].

Given a known signal sequence  $s(t)$  and another (a priori unknown) noise sequence

## 6.4. Matched filters



**Figure 6.7:** Left panel: Zoomed match filtered waveform corresponding to channel 7840 from the ProtoDUNE-SP raw data capture felix-2020-07-17-21:31:44 (blue line). The filter used was directly extracted from the data, being the 32 values around the first peak in the original waveform. The green dashed lines mark the region  $\pm 3\sigma_{\text{raw}}$ . The resulting noise waveform is also shown (red line). Top right panel: ADC distribution for channel 7840 after match filtering, where the green shaded region represents  $\pm \sigma_{\text{raw}}$ . Bottom right panel: noise ADC distribution for channel 7840 after match filtering, where the green shaded region represents  $\pm \sigma_{\text{noise}}$

1415  $n(t)$ , the input signal can be written as:

$$x(t) = s(t) + n(t). \quad (6.4)$$

1416 Now, considering a linear time-invariant filter, whose impulse-response function I  
1417 will refer to as  $h(t)$ , one can write the output signal as:

$$\begin{aligned} y(t) &= x(t) * h(t) \\ &= (s(t) + n(t)) * h(t) \\ &= y_s(t) + y_n(t), \end{aligned} \quad (6.5)$$

1418 where  $y_s(t)$  and  $y_n(t)$  are simply the outputs of the filter due to the signal and the noise  
1419 components respectively.

## Chapter 6. Matched Filter approach to induction wire Trigger Primitives

1420 The goal of the matched filter is to detect the presence of the signal  $s(t)$  in the input  
 1421 sample  $x(t)$  at a certain time  $t_0$ , which effectively means we need to maximise the S/N.  
 1422 This way, what one wants is to have a filter which gives a much bigger output when the  
 1423 known signal is present than when it is not. Putting it in other words, the instantaneous  
 1424 power of the signal output  $y_s(t)$  should be much larger than the average power of the  
 1425 noise output  $y_n(t)$  at some time  $t_0$ .

1426 For the case of the filtered signal, one can easily re-write it as an inverse Fourier  
 1427 transform:

$$y_s(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\omega H(\omega)S(\omega)e^{i\omega t}, \quad (6.6)$$

1428 where  $H(\omega)$  and  $S(\omega)$  are the Fourier transforms of the impulse-response function (i.e.  
 1429 the transfer function of the filter) and of the input signal, respectively.

1430 Now focusing on the noise, we can use the Wiener-Khinchin theorem [64] to write  
 1431 the mean power of the noise after filtering as:

$$E|y_n(t)|^2 = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\omega |H(\omega)|^2 S_n(\omega), \quad (6.7)$$

1432 where  $S_n(\omega)$  is the power spectral density of the noise.

1433 Having these, one can write the instantaneous S/N at time  $t_0$  as:

$$\begin{aligned} \left( \frac{S}{N} \right)_{t_0} &= \frac{|y_s|^2}{E|y_n(t)|^2} \\ &= \frac{1}{2\pi} \frac{\left| \int_{-\infty}^{\infty} d\omega H(\omega)S(\omega)e^{i\omega t_0} \right|^2}{\int_{-\infty}^{\infty} d\omega |H(\omega)|^2 S_n(\omega)}. \end{aligned} \quad (6.8)$$

1434 Once we have this expression, we need to find the upper limit of it to determine what  
 1435 would be the optimal choice for the transfer function. One can use the Cauchy-Schwarz  
 1436 inequality, which in the present case takes the form:

$$\left| \int_{-\infty}^{\infty} dx f(x)g(x) \right|^2 \leq \int_{-\infty}^{\infty} dx |f(x)|^2 + \int_{-\infty}^{\infty} dx |g(x)|^2, \quad (6.9)$$

## 6.4. Matched filters

1437 for any two analytical functions  $f(x)$  and  $g(x)$ . One can prove that making the choice:

$$\begin{aligned} f(x) &= H(\omega) \sqrt{S_n(\omega)} e^{i\omega t_0}, \\ g(x) &= \frac{S(\omega)}{\sqrt{S_n(\omega)}}, \end{aligned} \quad (6.10)$$

1438 leads to the following upper bound for the S/N:

$$\left( \frac{S}{N} \right)_{t_0} \leq \frac{1}{2\pi} \int_{-\infty}^{\infty} d\omega \frac{|S(\omega)|^2}{S_n(\omega)}. \quad (6.11)$$

1439 From Eqs. (6.8), (6.9) and (6.10) one can also derive the form of the transfer function

1440 such that the upper bound is exactly reached [65]:

$$H(\omega) \propto \frac{S^*(\omega) e^{-i\omega t_0}}{S_n(\omega)}. \quad (6.12)$$

1441 From this last expression we can clearly see the way the matched filter acts. As the  
1442 transfer function is proportional to the Fourier transform of the signal it will try to only  
1443 pick the frequencies present in the signal [66].

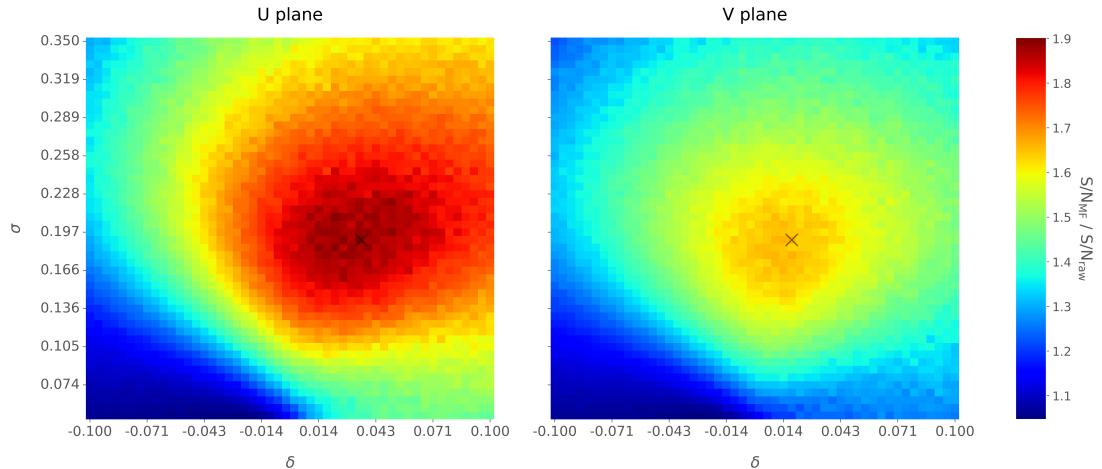
1444 The matched filter transfer function can be greatly simplified if the input noise is  
1445 Gaussian. In that case, the power spectral density of the noise is a constant, so it can be  
1446 re-absorbed in the overall normalisation of the transfer function. Moreover, considering  
1447 that the input signal is a real function, one can simply set  $S^*(\omega) = S(-\omega)$ , which gives:

$$H(\omega) \propto S(-\omega) e^{-i\omega t_0}. \quad (6.13)$$

1448 For a discrete signal, one can think of the input and impulse-response sequences as  
1449 vectors of  $\mathbb{R}^N$ . Then, the matched filter tries to maximise the inner product of the signal  
1450 and the filter while minimising the output due to the noise by choosing a filter vector  
1451 orthogonal to the later. In the case of additive noise, that leads to the impulse-response  
1452 vector:

$$h = \frac{1}{\sqrt{s^\dagger R_n^{-1} s}} R_n^{-1} s, \quad (6.14)$$

## Chapter 6. Matched Filter approach to induction wire Trigger Primitives



**Figure 6.8:** Relative improvement in the S/N for the raw data capture `felix-2020-07-17-21:31:44`, using the matched filter following the parametrisation in Eq. (6.17). The black crosses in both panels denote the location of the maximum ratio value.

1453 where  $s$  is a reversed signal template sequence of length  $N$  equal to the order of the filter  
 1454 and  $R_n$  is the covariance matrix associated with the noise sequence  $n$ . For the Gaussian  
 1455 noise case, the covariance matrix is simply the unit matrix, so the above expression  
 1456 simplifies again to:

$$h = \frac{s}{|s|}. \quad (6.15)$$

1457 For this first stage of the study, I use a definition of the S/N per channel given by:

$$\text{S/N} = \frac{\max [ADC] - \mu_{noise}}{\sigma_{noise}}, \quad (6.16)$$

1458 where the subscript *noise* refers to a subset of the data obtained by only taking into  
 1459 account waveform values within a  $\pm 3\sigma$  range around the mean of the data and  $\max [ADC]$   
 1460 is the maximum of the original waveform. This definition is further discussed in App.  
 1461 6.2, where I also show examples of its application to raw data and to a waveform filtered  
 1462 with the current low-pass FIR filter.

1463 To test whether this choice of filter is appropriate one needs to choose a signal  
 1464 template. As an example of how a matched filter would affect our signal, I simply took  
 1465 the filter coefficients to be the 32 ADC values around a signal peak present in the data.

## 6.4. Matched filters

1466 In Fig. 6.7 (left panel) I plotted a zoomed region for channel 7840 in the raw data capture  
1467 `felix-2020-07-17-21:31:44`, after applying the matched filter described before (blue  
1468 line). When compared to the raw and FIR filtered case (see App. 6.2), after applying  
1469 the match filter the standard deviation of the noise waveform (red line) decreases and at  
1470 the same time the signal peaks are enhanced. This leads to an improvement of the S/N  
1471 by a factor of 1.92 when compared to the raw waveform.

1472 In order to obtain the matched filter that is more suitable for our data, I explored  
1473 different configurations of signal templates. In order to perform this exploration, I  
1474 parametrised the signal using the bipolar function:

$$f(x) = -A(x + \delta) e^{-x^2/\sigma^2}, \quad (6.17)$$

1475 where the parameter  $\delta$  controls the asymmetry between the positive and negative peaks  
1476 and  $\sigma$  controls their width. The amplitude parameter  $A$  is set such that it keeps the  
1477 height of the biggest peak to be less than 200 ADC in absolute value.

1478 As this parametrisation is only adequate for bipolar signals I will focus exclusively  
1479 on the induction channels. Also, the optimal configurations I found for the U and V  
1480 plane will be kept separate, i.e. I will have two sets of coefficients that will be applied to  
1481 either the U and V planes of wires. I do so as I found this was the choice giving the  
1482 best performance. Even so, as I will discuss, the differences are not very pronounced. In  
1483 case it is not technically possible to separate channels in the firmware according to the  
1484 wire plane they come from and use different sets of filter coefficients for them, we can  
1485 just find a common unique set of coefficients. In such case, I do not expect our results  
1486 to change dramatically.

1487 In Fig. 6.8 I present the results of our parameter scan, for channels in the induction  
1488 planes U (left panel) and V (right panel). For each configuration of  $\sigma$  and  $\delta$  the resulting  
1489 matched filter was applied to all channels in the corresponding plane within the data  
1490 capture `felix-2020-07-17-21:31:44`, the S/N improvement was computed with respect  
1491 to the raw waveforms and then the S/N mean value was kept as a score for such filter.

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1492 One can see that the improvement obtained for the U plane is in general higher than the  
1493 one for the V plane. In any case, I got substantially higher ratios than the ones obtained  
1494 for the low-pass FIR filters. For the optimal configurations I attained improvements up  
1495 to a factor of 1.85 for the U plane and 1.65 for the V plane.

1496 The sets of optimal matched filter coefficients were obtained for the parameters  
1497  $\delta = 0.035$ ,  $\sigma = 0.191$  for the U plane and  $\delta = 0.018$ ,  $\sigma = 0.191$  for the V plane. I  
1498 show these two sets of coefficients in Fig. 6.9 (left panel). Also in Fig. 6.9 (right  
1499 panel) I plot the distribution of the S/N improvement after the optimal match filters  
1500 for the U and V were applied to the corresponding channels in the raw data capture  
1501 `felix-2020-07-17-21:31:44`. As mentioned before, the mean improvement achieved  
1502 for the U plane channels is slightly bigger than the one for the V channels. Note, however,  
1503 that the spread of the distribution for the V plane is also smaller than the one for the U  
1504 plane.

1505 I also performed a similar scan for the case of a low-pass FIR filter using the Parks-  
1506 McClellan algorithm. In that case, the parameters to check were the cutoff frequency  
1507 and the transition width of the filter. A summary of the results is given in App. 6.3.

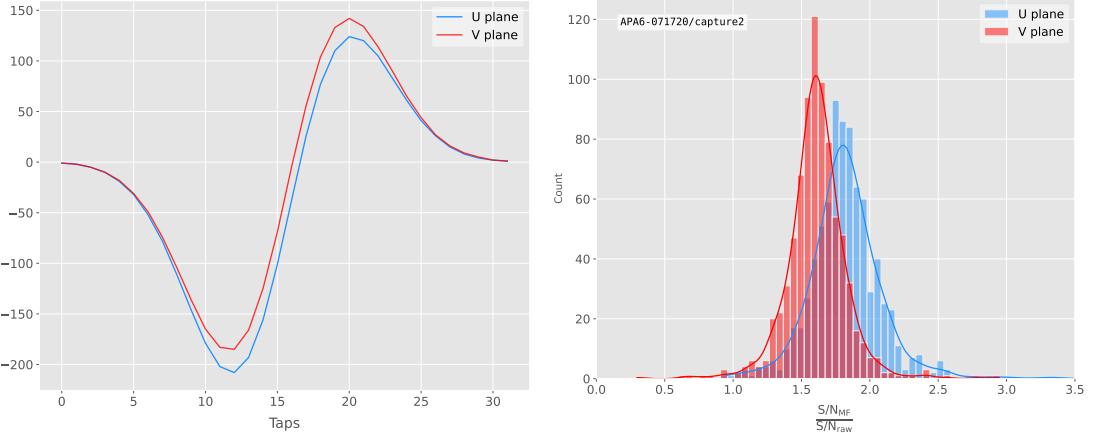
1508 Overall, one can see that the improvements on the S/N are much more significant in  
1509 the case of the matched filter than it is for the low-pass FIR filters. The analysis of this  
1510 and other raw data captures from ProtoDUNE-SP suggest that matched filters increase  
1511 the S/N of induction channels by a factor of 1.5 more than the optimal low-pass FIR  
1512 filters.

1513 Although these results are by themselves great points in favour of the matched  
1514 filter, more studies are needed to completely assess the robustness of this approach. I  
1515 proceeded then to test the matched filter with simulated data samples.

### 1516 6.5 Using simulated samples

1517 In order to further test the matched filter, the next step was to generate and process  
1518 data samples using *LArSoft* [67]. In this way, one can control the particle content of

## 6.5. Using simulated samples



**Figure 6.9:** Left panel: Optimal matched filter coefficients for the U (blue line) and V (red line) planes. The filters were computed with our parametrisation in Eq. (6.17) for the parameter values  $\delta = 0.035$ ,  $\sigma = 0.191$  and  $\delta = 0.018$ ,  $\sigma = 0.191$  respectively. Right panel: Distribution of the relative change of the S/N on the two induction wire planes from the ProtoDUNE-SP raw data capture *felix-2020-07-17-21:31:44* after their respective optimal matched filters were applied.

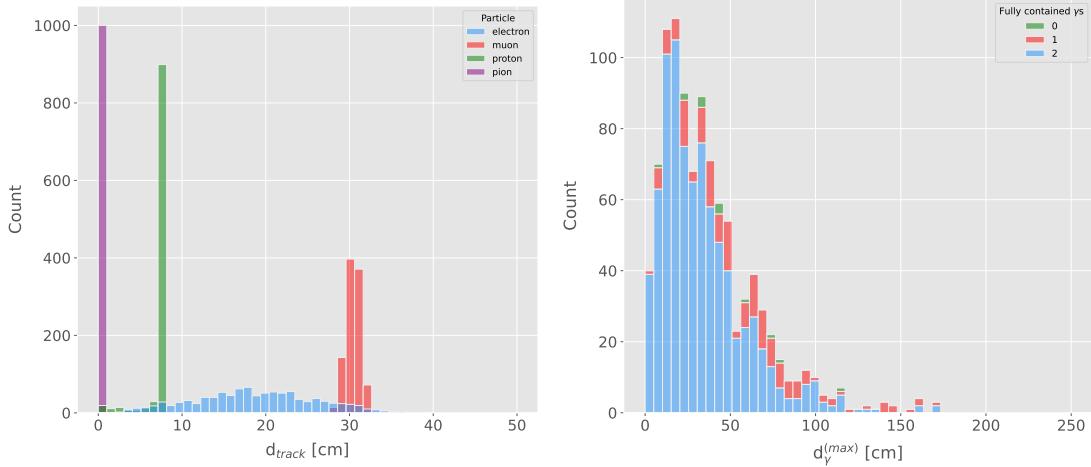
1519 the samples, the orientation of the tracks and their energy, and therefore see how the  
1520 matched filter behaves in various situations.

1521 To begin with, I prepared different monoenergetic and isotropic samples containing  
1522 a single particle per event. Each sample contains a different particle species, namely  
1523 electrons, muons, protons and neutral pions all with a kinetic energy of  $E_k = 100$  MeV.  
1524 I chose these because of the fairly different topologies they generate in the liquid argon,  
1525 ranging from shower-like to track-like. The procedure I followed to generate the samples  
1526 and process them is discussed in detail in App. ??.

1527 These were generated with the single particle gun and the Geant4 stage of the  
1528 *LArSoft* simulation [67] was performed with the standard configuration for the DUNE  
1529 FD 10kt module.

1530 For simplicity, I restricted the particles to start drifting in a single TPC volume  
1531 (in this case TPC 0), so I can focus exclusively on the signals coming from one APA.  
1532 The chosen kinetic energy for all the particles in my first trial is  $E_k = 100$  MeV, so a  
1533 necessary check is to see if all our tracks will be typically contained in one TPC volume.  
1534 Fig. 6.10 (left panel) shows the distributions of the track lengths in the liquid argon

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**Figure 6.10:** Left panel: distributions of the particles track length in the liquid argon for the generated  $E_k = 100$  MeV monoenergetic samples, electrons (blue), muons (red), protons (green) and neutral pions (purple). Right panel: distribution of the length of the longest photon in the neutral pion sample after the decay process  $\pi^0 \rightarrow \gamma\gamma$ .

of all generated particles with  $E_k = 100$  MeV. One can see that, in the case of the track-like particles (i.e. muons and protons), their length distributions are quite sharp and centered at relatively low distances (30 and 8 cm, respectively). For electrons, the distribution is quite broad but it does not extend past  $\sim 30$  cm. The case of neutral pions can be misleading, as they decay promptly the track length associated with the true Monte Carlo particle is always  $< 1$  cm. In Fig. 6.10 (right panel) I show the effective length distribution of the longest photon after the pion decays as  $\pi^0 \rightarrow \gamma\gamma$ , highlighting the number of fully contained photons in the TPC volume per event (either zero, one or both). One can see that the vast majority of events has both photons contained and that just a negligible number of them has none of them contained in the TPC volume. In any case, for the sake of caution, I will only keep the pion events with both photons contained.

Once I have prepared a sample at the Geant4 level, I need to process it through the detector simulation. In order to make adequate estimations of the noise levels and run the filtering and hit finder as I did with the ProtoDUNE data, one needs to turn off the default zero-suppression of the waveforms produced by the simulation. At this first stage I am only concerned with the waveforms with the noise added, so I keep the noise

## 6.5. Using simulated samples

addition option as true in the configuration. However, for studies related to the hit finder performance one will also need to store the noiseless waveforms in order to retrieve the truth information of the hits. I will discuss this approach next.

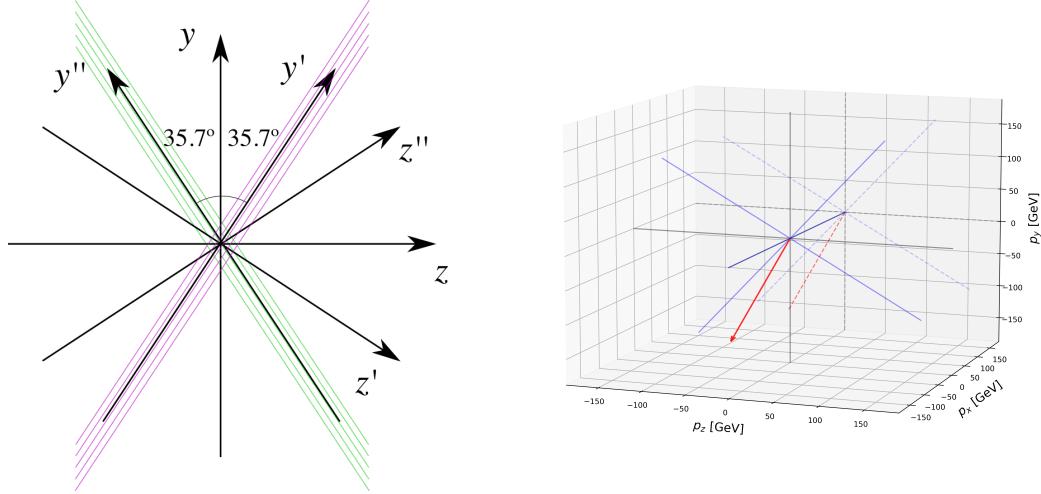
After the detector simulation stage, one needs to extract the no zero-suppressed noisy waveforms, along with their offline channel numbers, and store them in a certain format to be analysed later. To reduce the amount of data that will go for processing, I used the information from the Geant4 step of the simulation to select only the active channels, i.e. the channels where some ionisation electrons arrive. Moreover, as said previously, I only extract the waveforms from APA 0 and exclusively the ones coming from induction channels. The resulting ROOT file contains a tree with two branches, one containing the waveforms for each event and channel and the other with the corresponding offline channel numbers.

Finally, to extract the truth values for the orientation of the tracks and the energies of the particles I used a modified analysis module. This gives a ROOT file with a single tree, containing several branches with different information such as the components of the initial momentum of the particles, initial and final  $xyz$  location, track length, etc.

For the analysis of the resulting waveforms and truth values I used a custom set of Python libraries (available at [??]). Among other functionalities, these enable the user to read the ROOT files, export the raw data as pandas objects, apply the filters and compute the S/N of both the raw and filtered signals. So far, the default configuration for the filtering uses the set of optimal matched filter coefficients that I found using the ProtoDUNE data samples.

Additionally, for the analysis of the samples it was necessary to use two different reference frames, to study separately the signals coming from the U and V induction wire planes. As I am focussing on a single APA, the U and V wires have a different orientation in the  $yz$  plane. In the case of U wires, these are tilted  $35.7^\circ$  clockwise from the vertical ( $y$  direction), whereas the V wires are at the same angle but in the counter clockwise direction. Because of this, the best option is to deal with two new coordinate systems rotated by  $\pm 35.7^\circ$  along the  $x$  axis, so the new  $y'$  and  $y''$  directions are aligned with the

## Chapter 6. Matched Filter approach to induction wire Trigger Primitives

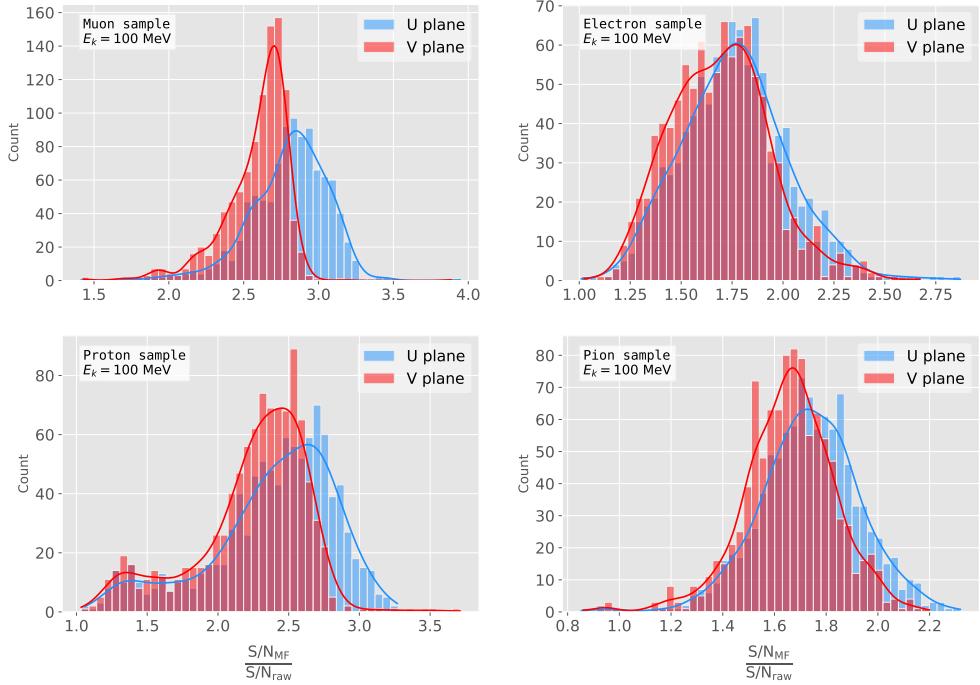


**Figure 6.11:** Left panel: schematic representation of the two new rotated reference frames used in this analysis (denoted as prime and double prime), viewed from the  $yz$  plane. The magenta stack of lines represent the wires in the  $U$  plane, whereas the green lines correspond to the wires in the  $V$  plane. Right panel: 3D representation of the momentum of one of the generated monoenergetic muons (red arrow) in the original reference frame (black lines), along with the new reference frame used for the  $U$  plane waveforms (blue lines). In the  $yz$  plane I added the projection of these three.

1581 U and V induction wires. Fig. 6.11 (left panel) shows a schematic representation of  
 1582 the original reference frame together with the two rotated ones (denoted by primed and  
 1583 double primed). This way, one can easily understand how parallel was a track to the  
 1584 wires in the two induction planes. Fig. 6.11 (right panel) shows a 3D representation of  
 1585 the momentum of a track (red arrow) in the original reference frame (black lines), along  
 1586 with the new reference frame for  $U$  wires (blue lines). I added the projection in the  $yz$   
 1587 plane of this three, to show the usefulness of the new reference frame to tell whether a  
 1588 track is parallel or normal to the wires in the induction plane.

1589 Fig. 6.12 shows the distribution of the average S/N improvement per event when one  
 1590 applies the optimal matched filters. I produced separate distributions for the channels  
 1591 in the  $U$  (red) and  $V$  (blue) induction wire planes. Notice that the S/N distributions  
 1592 for the track-like particles, i.e. muons (top left panel) and protons (bottom left panel),  
 1593 have significantly larger mean values than the distributions of the shower like particles,  
 1594 i.e. electrons (top right panel) and neutral pions (bottom right panel). An important

## 6.5. Using simulated samples



**Figure 6.12:** Distributions of the mean  $S/N$  improvement per event for the corresponding sample after applying the matched filters. Here I separated the change in the U plane (blue) and the V plane (red) channels. From top left to the right: muon, electron, proton and neutral pion. All the events have a fixed kinetic energy of  $E_k = 100 \text{ MeV}$ .

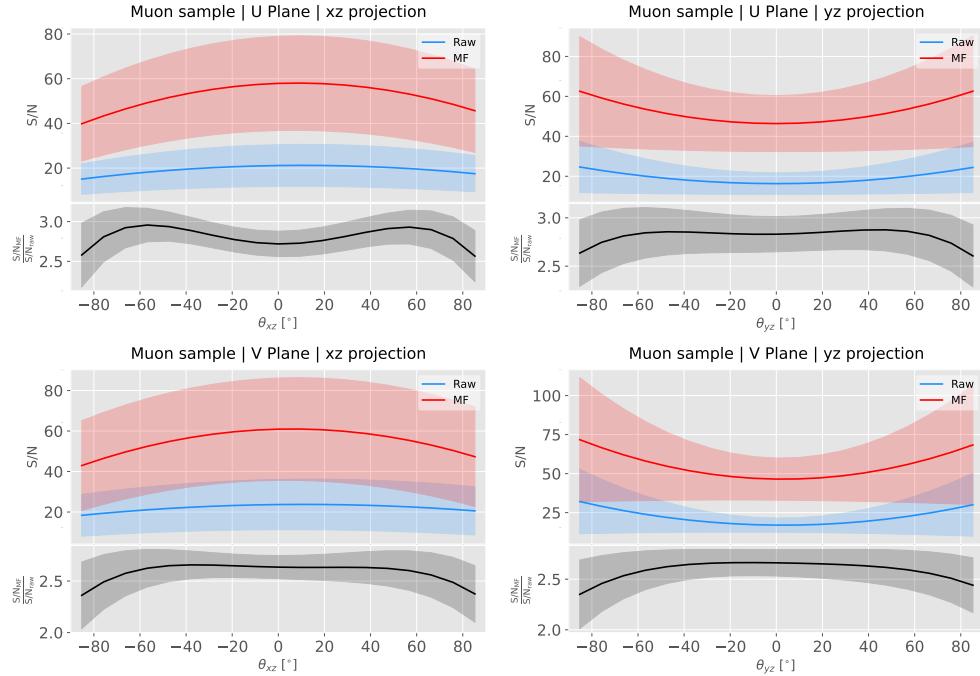
difference between these results and the ones seen before for ProtoDUNE data is that, overall, the improvements that I get for simulated data are bigger. This could be due either to the default noise model used in the *LArSoft* simulation or to the simulated hits having higher energy than the ones in the recorded data. Nonetheless, the concluding message is that the previously optimised matched filters give an overall significant improvement of the S/N for the different samples.

About the convention I followed for the plots and results, in the case of the raw and filtered S/N of each event in the sample I simply took the average of the quantities over all the active channels in the event. That is, if a certain event has  $N_{chan}$  active channels these two quantities are computed as:

$$(S/N_{fir})_{event} = \frac{\sum_{i=0}^{N_{chan}} (S/N_{fir})_i}{N_{chan}},$$

$$(S/N_{raw})_{event} = \frac{\sum_{i=0}^{N_{chan}} (S/N_{raw})_i}{N_{chan}}.$$
(6.18)

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**Figure 6.13:** Angular dependence of the mean S/N and the S/N improvement, for the different monoenergetic samples considered (from top to bottom: electrons, muons, protons and neutral pions). The two columns on the left represent the values for the U plane waveforms. The top subplots show the mean S/N for raw (green) and filtered (red) waveforms whereas the bottom subplots depict the averaged S/N improvement (black).

1605 However, for the ratio of the raw and filtered S/N (what I called the S/N improvement)  
 1606 per event I am not just taking the ratio of the previous two quantities but computing  
 1607 the average of the individual ratios per channel in the event:

$$\left( \frac{S/N_{fir}}{S/N_{raw}} \right)_{event} = \frac{\sum_{i=0}^{N_{chan}} \left( \frac{S/N_{fir}}{S/N_{raw}} \right)_i}{N_{chan}}, \quad (6.19)$$

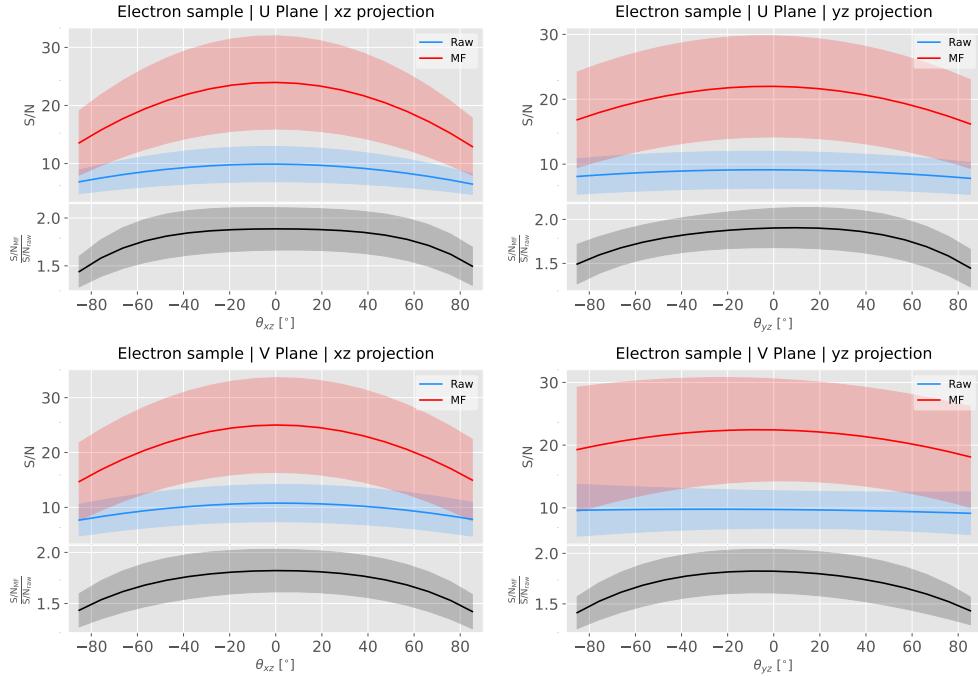
1608 and so:

$$\left( \frac{S/N_{fir}}{S/N_{raw}} \right)_{event} \neq \frac{(S/N_{fir})_{event}}{(S/N_{raw})_{event}}. \quad (6.20)$$

### 1609 6.5.1 Angular dependence

1610 Having these monoenergetic samples, one can also study the angular dependence of the  
 1611 performance of the matched filter. This is an important point, as it is a well established  
 1612 fact that for certain configurations (an extreme case configuration being signals normal

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**Figure 6.14:** Angular dependence of the mean S/N and the S/N improvement, for the different monoenergetic samples considered (from top to bottom: electrons, muons, protons and neutral pions). The two columns on the left represent the values for the U plane waveforms. The top subplots show the mean S/N for raw (green) and filtered (red) waveforms whereas the bottom subplots depict the averaged S/N improvement (black).

to the wire plane and perpendicular to the induction wires at the same time) the S/N is  
 much lower than average as the corresponding waveforms are severely distorted. In this  
 sense, I am interested to see how the matched filter behaves for these cases and how the  
 S/N improvement on those compare to the average.

Fig. 6.13 shows the angular dependence of the S/N for the monoenergetic  $E_k = 100$  MeV isotropic muons, for the different induction wire planes and projections. The angles for each event are given by the components of the initial value of the momentum of the particles, taking the angles of the projections on the  $xz$  and  $yz$  planes with respect to the  $z$  axis (more accurately, one needs to compute these angles twice for each event, a pair for the  $xy'z'$  coordinate system and the other for the  $xy''z''$ ). The top row shows the dependence on the angles corresponding to the U plane, i.e.  $\theta_{xz'}$  and  $\theta_{y'z'}$ , whereas the bottom row shows the angular dependence viewed from the V plane,  $\theta_{xz''}$  and  $\theta_{y''z''}$ . In each plot, the top subplot represents the mean values of the S/N for the raw (blue) and

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1626 matched filtered (red) signals, and the bottom subplot the averaged S/N improvement  
1627 (black). The solid lines represent the mean value obtained for the corresponding angular  
1628 value, whereas the semitransparent bands represent one standard deviation around the  
1629 mean at each point.

1630 As expected, the S/N is in general higher when tracks are parallel to the APA (i.e.  
1631  $\theta_{xz} \sim 0$ ) and lower when it is normal to the plane ( $\theta_{xz} \sim \pm 90^\circ$ ). In the same way, tracks  
1632 parallel to the wires ( $\theta_{yz} \sim \pm 90^\circ$ ) tend to have higher S/N than those perpendicular to  
1633 these ( $\theta_{yz} \sim \pm 0$ ).

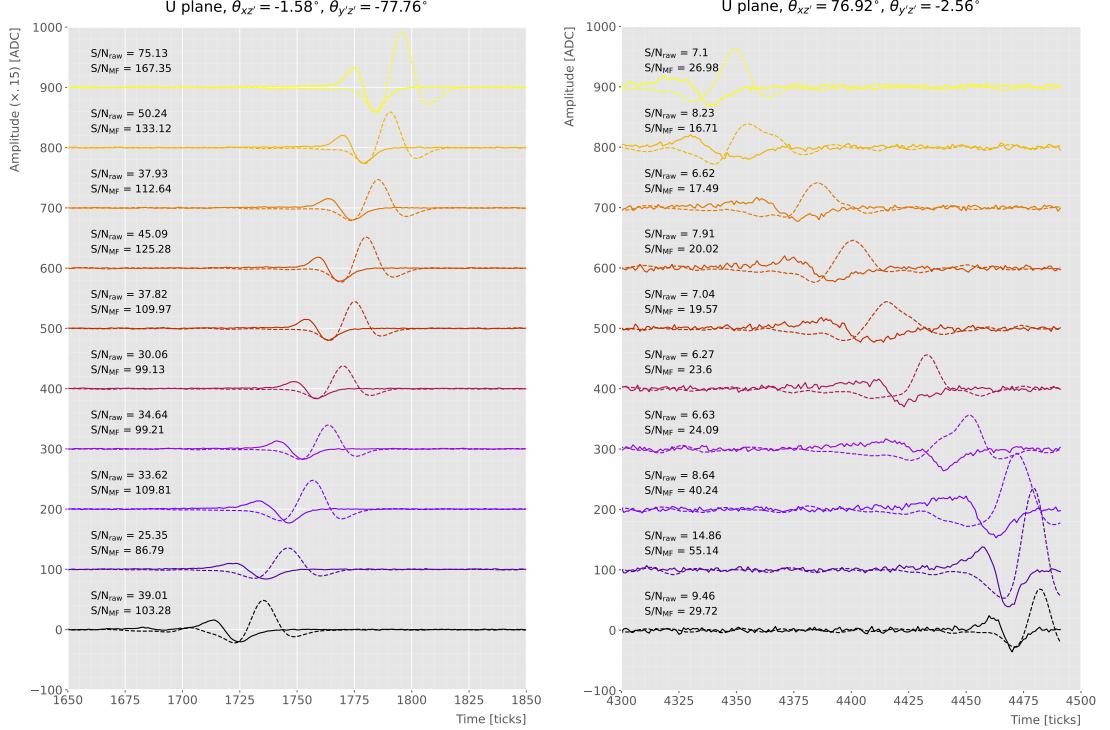
1634 Fig. 6.14 shows the corresponding angular dependence information for the  $E_k =$   
1635 100 MeV electrons sample. Notice that, in this case, the S/N behaviour discussed above  
1636 does not hold. A possible explanation can be that, because most hits in these events  
1637 are produced by the secondary particles generated in the EM shower, the signal peaks  
1638 whose S/N ratios were computed do not correspond to the directional information of  
1639 the primary electron.

### 1640 6.5.2 Distortion and peak asymmetry

1641 As a little case of study, I selected two of the simulated  $E_k = 100$  MeV monoenergetic  
1642 muon events. With respect to the U induction plane, one is parallel to the APA (low  
1643  $\theta_{xz'}$ ) and to the wires (high  $\theta_{y'z'}$ ) and the other is normal to the APA plane (high  $\theta_{xz'}$ )  
1644 and perpendicular to the wires (low  $\theta_{y'z'}$ ). As expected from the results on the angular  
1645 dependence discussed above, the former has a higher S/N (before and after the filtering)  
1646 when compared to the latter. An interesting thing to notice about these two samples  
1647 is that, even though one has a much bigger S/N than the other, it is the one with the  
1648 smallest S/N the one that got the biggest averaged S/N improvement. In Table 6.1  
1649 I included all the relevant parameters of these two  $E_k = 100$  MeV muon events I am  
1650 considering, namely, the angles with respect to the  $xy'z'$  reference frame, the values of  
1651 the S/N, the S/N improvement and also the so-called peak asymmetry  $\Delta_{peak}$  that I will  
1652 discuss next.

1653 One can try to understand better what is going on with these two events by looking

## 6.5. Using simulated samples



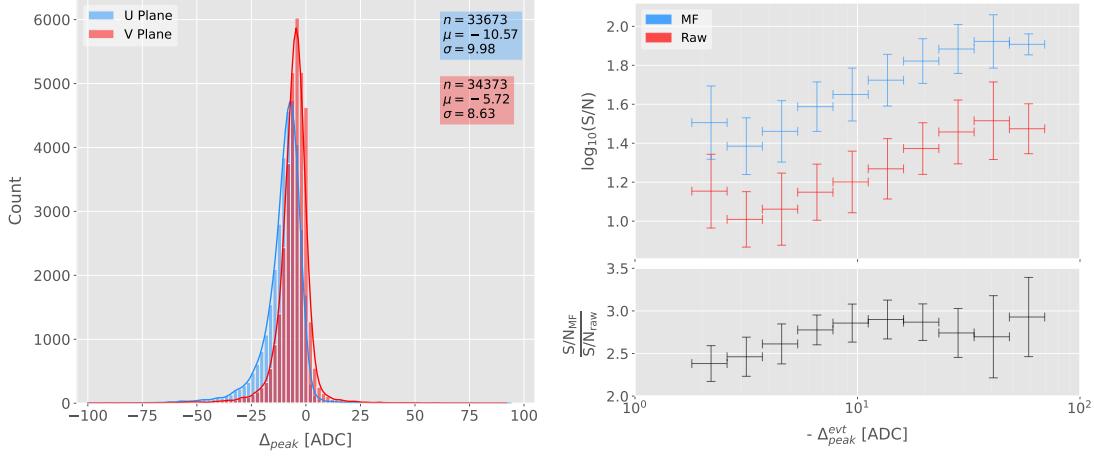
**Figure 6.15:** Selected consecutive waveforms corresponding to two monoenergetic  $E_k = 100$  MeV muon events, one is parallel to the APA and to the wires in the U plane (left panel) and the other is normal to the APA plane and perpendicular to the U plane wires (right panel). The solid lines represent the raw waveforms whereas the dashed lines correspond to the waveforms after the matched filter was applied. The waveforms on the left panel have been scaled by a factor of 0.15 to have similar amplitude to the ones on the right panel.

**Table 6.1:** Characteristic parameters of the two monoenergetic muon events selected, relative to the U plane: projected angles in the  $xz'$  and  $yz'$  planes, S/N values for the raw and filtered waveforms, mean improvement of the S/N and peak asymmetry.

	$\theta_{xz'} (\circ)$	$\theta_{yz'} (\circ)$	S/N <sub>raw</sub>	S/N <sub>MF</sub>	$\frac{S/N_{MF}}{S/N_{raw}}$	$\Delta_{peak}$ (ADC)
High ("parallel")	-1.58	-77.76	41.65	112.44	2.83	-35.73
Low ("normal")	76.92	-2.56	8.07	25.46	3.12	-10.38

at the raw and filtered data from some of their active channels. Fig. 6.15 shows a selection of consecutive raw and filtered U plane waveforms from the event with high S/N (left panel) and the one with low S/N (right panel). Notice that to show both collections of waveforms at a similar scale I had to apply a factor of 0.15 to the waveforms with high S/N. Additionally, next to each waveform I included the values of the raw and matched filtered S/N for the corresponding channel. The first thing to notice in this plot

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**Figure 6.16:** Left panel: peak asymmetry distribution for the case of the monoenergetic  $E_k = 100$  MeV muon sample. Each value corresponds to a single bipolar signal peak from a channel in any event. The blue distribution represents the peaks on U plane channels, whereas the red corresponds to signal peaks in V wires. Right panel: relation between the mean peak asymmetry per event with the S/N for U channel waveforms from the  $E_k = 100$  MeV muon sample. The top subplot shows the decimal logarithm of the mean S/N for the raw (red) and the matched filtered (blue) waveforms. The bottom subplot contains the mean S/N improvement ratio after the matched filter was applied.

is that the amplitude of the signal peaks from the normal track have a much smaller  
 amplitude, and also appear quite distorted when compared to the others. On the other  
 hand, although the matched filtered S/N is still smaller, the relative improvement is  
 bigger than in the parallel case.

A way I found to quantify the difference between the shapes within these two events  
 is their different peak asymmetry. One can define the peak asymmetry as the (signed)  
 difference between the positive and the negative peaks of the bipolar shape, i.e.:

$$\Delta_{peak} \equiv h_+ - h_-, \quad (6.21)$$

where both heights  $h_+$  and  $h_-$  are positive defined. Fig. 6.16 (left panel) shows the distribution of this peak asymmetry for all the waveforms corresponding to channels in the U (blue) and V (red) planes for the monoenergetic muon sample. One can see that these distributions are clearly shifted to negative values (with mean values  $\mu_\Delta^U = -10.57$  ADC and  $\mu_\Delta^V = -5.72$  ADC respectively). It is interesting to notice

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that the peak asymmetry value of the sample with high S/N sits at the left tail of the distribution whereas the corresponding value of the sample with low S/N lies around the mean.

Now, one can try to correlate the peak asymmetry with the S/N and the S/N change per event. Fig. 6.16 (right panel) shows the result of comparing (minus) the mean peak asymmetry per event to the averaged raw (red) and matched filtered (blue) S/N per event (top subplot). The horizontal lines sit at the mean value obtained in the fit and represent the width of the  $-\Delta_{peak}$  bins used, while the vertical lines indicate one standard deviation around that mean value. Notice that, when taking decimal logarithm on both, there is an approximate linear relation between these quantities, except for peak asymmetry values bigger than  $-5$  ADC where the S/N remains constant.

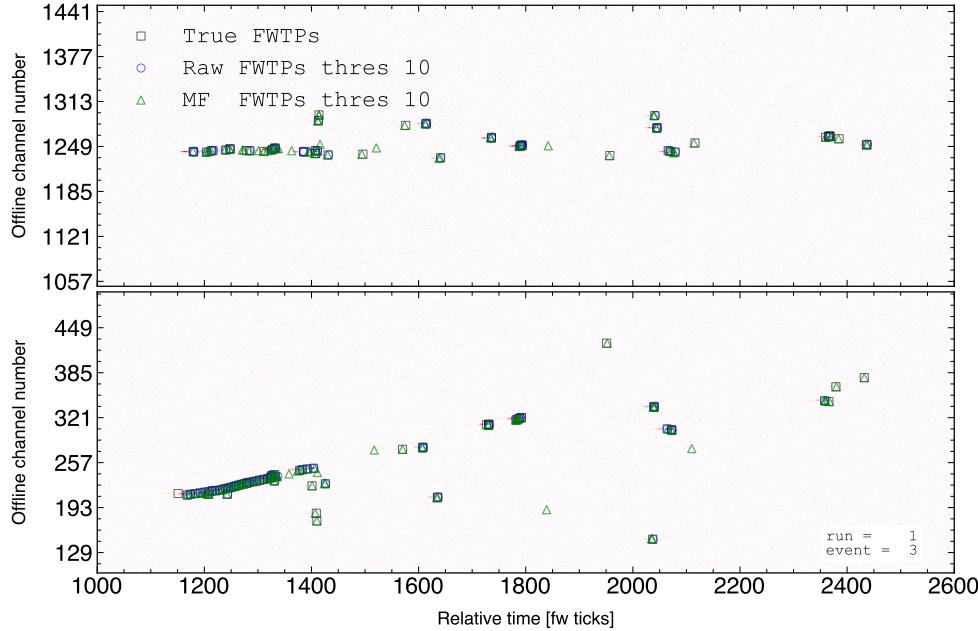
Also, in the bottom subplot of Fig. 6.16 (right panel) I show the relation between the peak asymmetry and the mean S/N improvement. In this case, one see that there is a maximum at  $\Delta_{peak} \sim -10$  ADC. As mentioned previously, this is also the value of the mean of the peak asymmetry distribution. In fact, it is expected that our filter favours the signal peaks with the most common values of the peak asymmetry, as this was one of the features I target in our filter coefficient optimisation through the parameter  $\delta$ .

These results suggest that events with poorer values of the mean S/N, usually associated to non-favourable track orientations, tend to have smaller values of the mean peak asymmetry (in absolute value). Nonetheless, because our matched filters have been optimised to account for these asymmetries, the improvement on the S/N for these events is sizeable if not better than the one for events which already had a high S/N.

### 6.5.3 Hit sensitivity

One of the advantages of the matched filter, directly related to increasing the S/N, is the capability of picking hits that before fell below the threshold. For instance, Fig. 6.17 shows the raw ADC data from an example event (electron,  $E_k = 100$  MeV) with the produced true hits superimposed (black boxes), together with the hits produced by the standard hit finder chain (blue circles), i.e. using the current FIR filter, and the hits

## Chapter 6. Matched Filter approach to induction wire Trigger Primitives



**Figure 6.17:** Raw data display in the plane time (in firmware ticks) vs. offline channel number for an  $E_k = 100$  MeV electron event. The produced true hits are superimposed (black boxes) as well as the hits coming from the standard hit finder chain (blue circles) and the hit finder using the matched filter (green triangles).

1700 obtained using the matched filters (green triangles). Both the standard and the matched  
 1701 filter hit finders were run with a threshold of 10 ADC. Notice that the standard hits  
 1702 match well the true ones at the initial part of the event (where we have a track-like  
 1703 object), but they miss most of the hits produced by the EM shower at later times. On  
 1704 the other hand, the hits produced with the matched filter have a better agreement with  
 1705 the true hits even for the more diffuse shower activity.

1706 Notwithstanding that now I get more hits with this combination of matched filter  
 1707 and low threshold as a results of the enhancement of the signal peaks relative to the  
 1708 noise level, it is also true that I pick some spurious hits not related to any real activity  
 1709 if one lowers the thresholds too much. Therefore, some optimisation of the threshold is  
 1710 needed. Basically one will need to make a trade-off between precision and sensitivity.

1711 Having this in mind, I tried to compare the produced hits one gets from the standard  
 1712 hit finder and the ones resulting from applying the matched filter with the true hits.  
 1713 By running the hit finders on our samples with different values of the threshold one

## 6.5. Using simulated samples

1714 can understand, for instance, how low one can set the threshold without getting mostly  
1715 spurious hits and then evaluate the gains obtained from this.

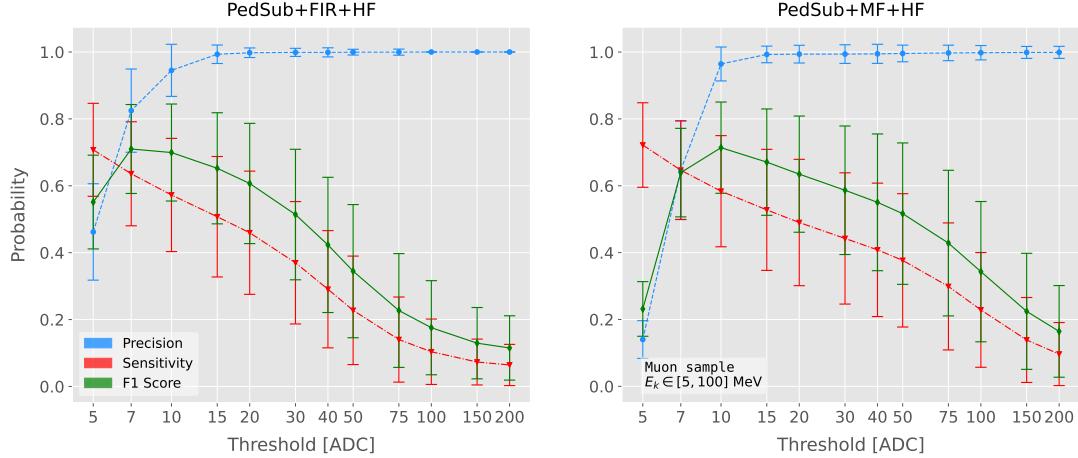
1716 Because now I am also interested in seeing how the hit sensitivity changes with the  
1717 energy, I prepared new isotropic samples with the same types of particles as before  
1718 (muons, electrons, protons and neutral pions) but with a flat kinetic energy distribution  
1719 ranging from 5 to 100 MeV.

1720 In order to estimate the hit sensitivity, given a certain sample, one needs to recover  
1721 the set of true hits to be able to compare these with the ones produced. To do so,  
1722 a modification in the procedure I was using to extract the raw waveforms is needed.  
1723 For this kind of study I run the detector simulation in two steps, first I produce the  
1724 waveforms without noise and extract them in the same format I used for the raw data,  
1725 then the noise is added and the noisy waveforms are then written to a file as well.

1726 To have a better comparison between the true hits and the ones produced from  
1727 the raw waveforms after applying the two filters, I applied also the FIR filter and the  
1728 matched filters to the noiseless waveforms and then I run the hit finder with a minimal  
1729 threshold (in this case I used 1 ADC) on these noiseless filtered waveforms. In this way  
1730 I generated two sets of true hits, I will refer to them as standard true hits (with the  
1731 current/default FIR filter) and matched filter true hits respectively. This allows a more  
1732 precise matching between the different groups of hits produced, as it will account for  
1733 any delays and distortions introduced by the FIR and the matched filters.

1734 In the case of the raw waveforms (with noise), I run the hit finder on them, with  
1735 different values of the threshold, after applying either the FIR or the matched filters. I  
1736 will name them simply standard hits and matched filter hits respectively. Then, I match  
1737 the generated hits to the true hits (the standard hits with the standard true hits and  
1738 the matched filter hits with the matched filter true hits). The matching is performed by  
1739 comparing the channel number and the timestamp of the hits. To count as a match,  
1740 I require that all hits with the same channel number and timestamp have overlapping  
1741 hit windows, i.e. the time windows between their hit end and hit start times need to  
1742 overlap. If more than one hit in one of the groups have hit overlap with the same hit in

## Chapter 6. Matched Filter approach to induction wire Trigger Primitives



**Figure 6.18:** Dependence of the precision (blue), sensitivity (red) and  $F_1$  (green) scores on the threshold values used in the hit finder, for the FIR (left panel) and matched filter (right panel) cases. The results were obtained after matching the hits to the true hits in the case of the isotropic muon sample with kinetic energy in the range 5 to 100 MeV, taking only into account the induction plane channels. The points represent the mean value while the error bars indicate one standard deviation around that mean value.

1743 the other group I only count the hit with closer hit peak time value.

1744 The generation of the samples, the procedure to produce the standard hits (with the  
 1745 default FIR filter) and matched filter hits and the matching of these with the true hits  
 1746 is described in detail in App. ??.

1747 To quantify the performance of the two hit finder approaches, I use a classical method  
 1748 from statistical classification known as confusion matrix [68]. This is basically a way of  
 1749 sorting the outputs of a binary classifier, considering the true values of the classification  
 1750 and the predicted values. It divides the outputs in four categories: true positive (TP,  
 1751 both true and predicted values are 1), false negative (FN, true value is 1 but predicted  
 1752 is 0), false positive (FP, true value is 0 but predicted is 1) and true negative (TN, both  
 1753 true and predicted values are 0)).

1754 The contents of the confusion matrix allow us to compute other derived scores to  
 1755 judge the performance of our classifiers. In this study, I will make use of three of these  
 1756 metrics, namely the precision or positive predictive value:

$$\text{PPV} = \frac{\text{TP}}{\text{TP} + \text{FP}}, \quad (6.22)$$

## 6.5. Using simulated samples

1757 the sensitivity or true positive rate:

$$\text{TPR} = \frac{\text{TP}}{\text{TP} + \text{FN}}, \quad (6.23)$$

1758 and the  $F_1$  score [69]:

$$F_1 = \frac{2\text{TP}}{2\text{TP} + \text{FP} + \text{FN}}, \quad (6.24)$$

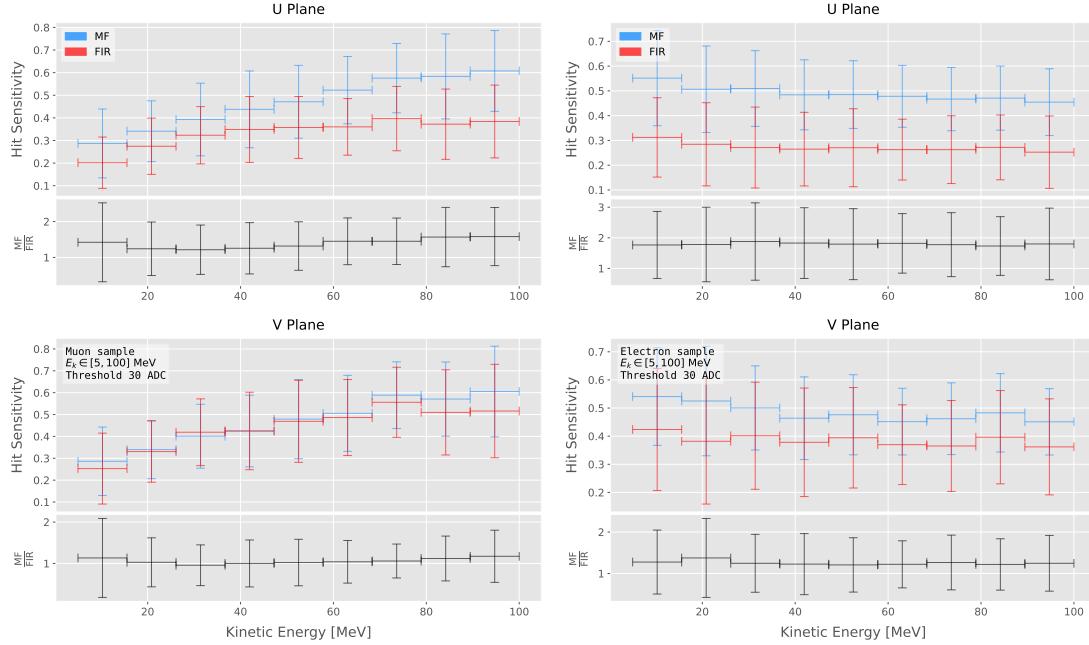
1759 which is the harmonic mean of the precision and the sensitivity.

1760 In our specific case I am not going to make use of the true negative value, as its  
 1761 definition in this context can be ambiguous because one does not have clear instances in  
 1762 the classification process. This way, I will only count the number of true positives as the  
 1763 total amount of hits I can match between true and raw populations, the number of false  
 1764 negatives will be the number of missing true hits and the false positive the number of  
 1765 hits which do not match any true hit.

1766 In Fig. 6.18 I show the precision (blue), sensitivity (red) and  $F_1$  (green) scores I  
 1767 obtained for different values of the threshold used in the hit finder for the case of the  
 1768 muon sample. Because the matched filters are only applied to induction channels, I only  
 1769 consider here hits coming from the U and V planes. The panel on the left corresponds  
 1770 to the scores I got when I ran the hit finder on the FIR filtered waveforms, whereas the  
 1771 right panel contains the scores for the matched filter case. The points are centered at  
 1772 the threshold value used and represent the mean value obtained for each score using all  
 1773 the generated events, while the error bars indicate one standard deviation around the  
 1774 mean value.

1775 One can see that the precision for the matched filter case is lower when the thresholds  
 1776 are very low, as the noise baseline is slightly amplified, but then rises to high values  
 1777 quicker than for the FIR case. The other difference one can spot is that the sensitivity  
 1778 in the FIR case starts dropping faster at around the same threshold values where the  
 1779 precision stabilizes around 1, while in contrast for the matched filter this rapid decrease  
 1780 starts at higher threshold values. A similar scan for the same thresholds was performed  
 1781 for the electron sample in the same energy range, yielding similar results.

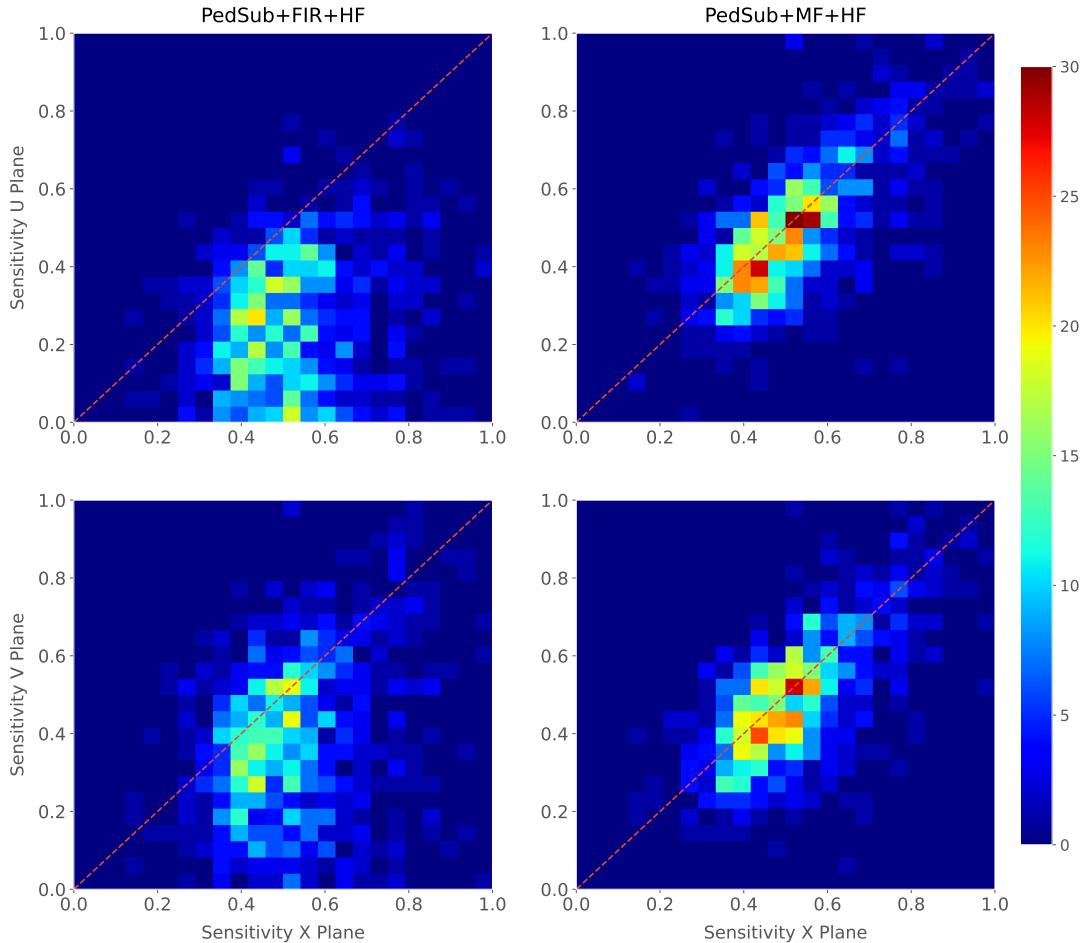
## Chapter 6. Matched Filter approach to induction wire Trigger Primitives



**Figure 6.19:** Dependence of the averaged hit sensitivity on the kinetic energy of the events for the matched filter (blue) and standard (red) hits, for the case of the muon (left panel) and electron (right panel) samples, separated between U (top plots) and V (bottom plots) induction wire planes. The top subplots contain the hit sensitivities for the two hit finder alternatives, while the bottom subplots show the ratio between the two. The horizontal lines sit at the mean value and represent the size of the energy bins, while the vertical error bars indicate one standard deviation around that mean value.

1782 In Fig. 6.19 I show the averaged hit sensitivity versus the kinetic energy of the  
 1783 events, both for the matched filter hits (blue) and the standard hits (red). The left  
 1784 panel corresponds to the muon sample, whereas the one on the right corresponds to the  
 1785 electron sample, both with kinetic energies between 5 and 100 MeV. In each panel the  
 1786 top plot corresponds to hits in the U plane, while the bottom plot contains the same  
 1787 information for the V plane. Each plot contains two subplots, the one on the top shows  
 1788 the hit sensitivity values for the matched filter and standard hits separate, while the  
 1789 bottom subplot depicts the ratio between the matched filter and standard sensitivities.  
 1790 The horizontal lines are placed at the mean value obtained in the fit and represent the  
 1791 width of the  $E_k$  bins used, while the vertical error bars indicate one standard deviation  
 1792 around that mean value. In both cases the threshold used was 30 ADC, as I required  
 1793 the precision to be higher than 0.99 for both matched filter and standard cases.

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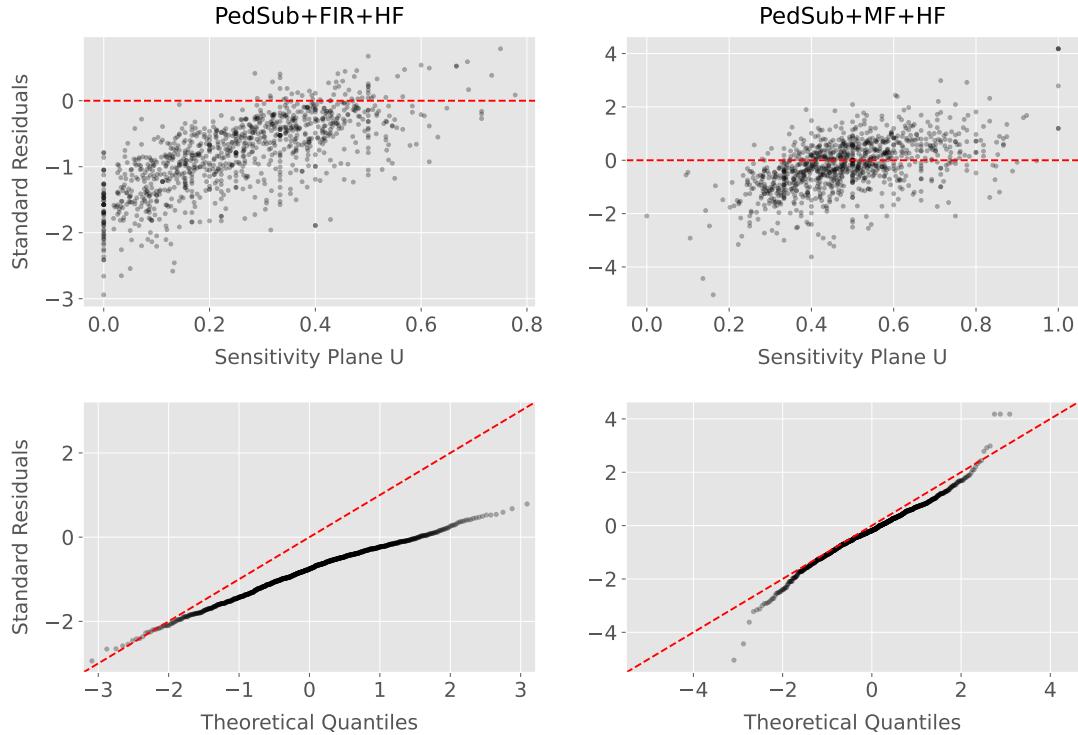


**Figure 6.20:** Distributions of the hit sensitivity in the U (top panels) and V (bottom panels) planes versus the hit sensitivity in the X plane, both for the standard hits (left panels) and the matched filter hits (right panels), in the case of the electron sample and a threshold of 30 ADC.

1794 One can see that, in general, the improvements are better for the U than for the V  
 1795 plane. While for the U channels I achieved a mean improvement of 50% and 80% for  
 1796 muons and electrons respectively, the improvement in the V plane is stalled at 10% and  
 1797 25%. Nevertheless, if I look at the sensitivities for the matched filter hits in both planes  
 1798 one can see these have similar mean values for each energy bin, while on the contrary  
 1799 for the standard hits the sensitivity remains relatively high for the V plane. This way, it  
 1800 looks there was a less significant gain because the hit sensitivity was already high.

1801 Another interesting observation is the different behaviors for muons and electrons.  
 1802 While hit sensitivity for muons grows significantly with energy, in the case of electrons

## Chapter 6. Matched Filter approach to induction wire Trigger Primitives



**Figure 6.21:** Top panels: standard residual plots of the hit sensitivities between the  $X$  and  $U$  planes. Bottom panels: quantile-quantile plots of the hit sensitivity standard residuals between the  $X$  and  $U$  planes. In all cases, the left panel corresponds to the standard hits while the right panel represents the matched filter case, all from the electron sample with a 30 ADC threshold.

1803 this slightly decreases the higher the kinetic energy of the event is. In any case, when it  
 1804 comes to the improvement on the sensitivities, this remains almost constant in all cases.

1805 Furthermore, we can look at how the concurrence of hits between the different wire  
 1806 planes has changed. For any given event, I expect to have a similar number of hits in the  
 1807 three planes. As the ionisation electrons need to cross the  $U$  and  $V$  planes prior to reach  
 1808 the collection plane  $X$  they will induce current in those wire planes. A way to check the  
 1809 concurrence of hits across planes is looking at the relation between the hit sensitivities  
 1810 for each individual event. One cannot expect the sensitivities to be exactly equal across  
 1811 planes, but ideally they should be normally distributed around the diagonal.

1812 Fig. 6.20 shows the hit sensitivity in the  $U$  (top panels) and  $V$  (bottom panels)  
 1813 planes versus the hit sensitivity in the  $X$  plane, for the case of the standard hits (left  
 1814 panels) and the matched filter hits (right panels). All plots were generated for the

## 6.5. Using simulated samples

1815 electron sample and a threshold of 30 ADC. From these one can see a clear trend,  
1816 when I use the standard hit finder chain the sensitivities in the induction planes are  
1817 systematically lower than the hit sensitivity in the X plane, i.e. most of the points sit  
1818 below the diagonal (red dashed line). In contrast, when the matched filters are applied,  
1819 the majority of the events are distributed around the diagonal. This points out that the  
1820 concurrence of hits across planes has improved.

1821 To exemplify the improvement I obtained, one can consider the residuals of the hit  
1822 sensitivities for the X and U planes. Assuming the diagonal hypothesis, i.e. given a  
1823 dataset of the form  $(x, y)$  for any  $x$  I take the predicted  $y$  value to be equal to the value  
1824 of  $x$ , I can compute the standard residuals for the hit sensitivities in U given the ones for  
1825 X. In Fig. 6.21 (top panels) I show these standard residuals against the corresponding  
1826 values of the hit sensitivity in the U plane, for our electron sample with kinetic energy  
1827 between 5 and 100 MeV. If I compare the scatter points in the case of the standard  
1828 hits (left panel) and the matched filter hits (right panel), I see that the residuals of the  
1829 standard hit finder case follow a certain pattern and their mean deviates from 0.

1830 To see clearly if the residuals are normally distributed, in Fig. 6.21 (bottom panels)  
1831 I plot the corresponding quantile-quantile plot for both the standard (left panel) and  
1832 matched filter (right panel) standard residuals. One can clearly see that the points for  
1833 the standard case follow a strongly non-linear pattern, suggesting that the residuals  
1834 do not follow a normal distribution. In contrast, for the matched filter hits the points  
1835 conform to a roughly linear path, implying that in this case the normality condition is  
1836 fulfilled.

1837 All these results hint at the fact that the concurrence of hits across the wire planes  
1838 can be strengthened by applying the matched filters.



<sup>1839</sup> Chapter 7

Dark Matter

(don't use acronym  
in ~ title)

<sup>1840</sup> **DM** searches with neutrinos from  
<sup>1841</sup> the Sun

<sup>1842</sup> **7.1 Motivation**

<sup>1843</sup> The idea of detecting neutrino signals coming from the Sun's core to probe DM is not new.  
<sup>1844</sup> The main focus of these searches has usually been high-energy neutrinos originated from  
<sup>1845</sup> DM annihilations into heavy particles [70–73], although recent studies have proposed to  
<sup>1846</sup> look at the low-energy neutrino flux arising from the decay of light mesons at rest in the  
<sup>1847</sup> Sun [74–77] previously thought undetectable.

<sup>1848</sup> In this chapter I try to demonstrate the capability of DUNE to constrain different  
<sup>1849</sup> DM scenarios. I used the neutrino fluxes arising from DM annihilations in the core  
<sup>1850</sup> of the Sun to compute the projected limits that DUNE would be able to set on the  
<sup>1851</sup> annihilation rates in the Sun and the DM scattering cross sections.

<sup>1852</sup> **7.2 Gravitational capture of DM by the Sun**

<sup>1853</sup> The Sun and the centre of the Earth are possible sources of DM annihilations, specially  
<sup>1854</sup> interesting because of their proximity. Their gravitational attraction ensured the capture  
<sup>1855</sup> of DM from the local halo through repeated scatterings of DM particles crossing them.

## Chapter 7. DM searches with neutrinos from the Sun

1856 Only neutrinos produced from DM annihilations can escape the dense interior of these  
1857 objects. Therefore, neutrino telescopes are the most useful experimental layouts to  
1858 pursue DM searches from their cores.

1859 The neutrino flux from DM annihilations inside the Sun depends on the DM capture  
1860 rate, which is proportional to the DM scattering cross section, and the annihilation rate,  
1861 which is proportional to the velocity-averaged DM annihilation cross-section. The total  
1862 number of DM particles inside the Sun follows the Boltzmann equation [74]:

$$\frac{dN_{DM}}{dt} = C_{\odot} - A_{\odot} N_{DM}^2, \quad (7.1)$$

1863 where  $C_{\odot}$  and  $A_{\odot}$  are the total Sun DM capture and annihilation rates respectively.  
1864 In this expression I neglected the evaporation term, proportional to  $N_{DM}$ , which only  
1865 contribute for  $m_{DM} \lesssim 4$  GeV [78]. As the current threshold of neutrino telescopes is  
1866 a few GeV, this region falls below the probed range but can be important in future  
1867 low-energy projects.

1868 This equation has an equilibrium solution:

$$N_{DM}^{eq} = \sqrt{\frac{C_{\odot}}{A_{\odot}}}, \quad (7.2)$$

1869 which represents the amount of DM inside the Sun if the capture and annihilation have  
1870 reached equilibrium. As the Sun is approximately 4.6 Gyr old, it is usually assumed that  
1871 equilibrium has been achieved. Therefore, the anomalous neutrino flux from the Sun  
1872 would only depend on the DM scattering cross section, enabling us to set limits on this  
1873 quantity. If one does not assume equilibrium, some assumptions on the DM annihilation  
1874 cross section are necessary to extract predictions from neutrino signals.

1875 Here, I am going to consider three possible scenarios for the DM interactions: DM  
1876 scattering off electrons, spin-dependent (SD) and spin-independent interactions off nuclei.  
1877 For the case of these last two, the cross sections will be given in terms of the SD and  
1878 SI elastic scattering DM cross section off protons (assuming that DM interactions off

I'm going to  
have to test you on these  
formulas, however expect questions during  
the exam don't think for

## 7.2. Gravitational capture of DM by the Sun

1879 protons and neutrons are identical),  $\sigma_p^{\text{SD}}$  and  $\sigma_p^{\text{SI}}$ , as [4, 74]:

$$\sigma_i^{\text{SD}} = \left( \frac{\tilde{\mu}_{A_i}}{\tilde{\mu}_p} \right)^2 \frac{4(J_i + 1)}{3J_i} |\langle S_{p,i} \rangle + \langle S_{n,i} \rangle|^2 \sigma_p^{\text{SD}}, \quad (7.3)$$

$$\sigma_i^{\text{SI}} = \left( \frac{\tilde{\mu}_{A_i}}{\tilde{\mu}_p} \right)^2 A_i^2 \sigma_p^{\text{SI}}, \quad (7.4)$$

1880 where  $\tilde{\mu}_{A_i}$  is the reduced mass of the DM-nucleus  $i$  system,  $\tilde{\mu}_p$  is the reduced mass of  
 1881 the DM-proton system,  $A_i$  and  $J_i$  the mass number and total angular momentum of  
 1882 nucleus  $i$  and  $\langle S_{p,i} \rangle$  and  $\langle S_{n,i} \rangle$  the expectation value of the spins of protons and neutrons  
 1883 averaged over all nucleons, respectively (see Ref. [79] for a review on spin expectation  
 1884 values).

1885 Since the Sun is mainly composed of Hydrogen, the capture of DM from the halo  
 1886 is expected to occur mainly through spin-dependent scattering. However, since the  
 1887 spin-independent cross section is proportional to the square of the atomic mass, heavy  
 1888 elements can contribute to the capture rate (even though they constitute less than 2%  
 1889 of the mass of the Sun). Heavy elements can also contribute to the spin-dependent cross  
 1890 section if the DM has also momentum-dependent interactions.

1891 DM particles can get captured by the Sun if after repeated scatterings off solar  
 1892 targets their final velocity is lower than the escape velocity of the Sun. In the limit of  
 1893 weak cross sections, this capture rate can be approximately written as [4]:

$$C_{\odot}^{\text{weak}} = \sum_i \int_0^{R_{\odot}} dr 4\pi r^2 \int_0^{\infty} du_{\chi} \frac{\rho_{\chi}}{m_{\chi}} \frac{f_{v_{\odot}}(u_{\chi})}{u_{\chi}} \omega(r) \int_0^{v_e(r)} dv R_i^-(\omega \rightarrow v) |F_i(q)|^2, \quad (7.5)$$

1894 where the summation extends over all possible nuclear targets. In this expression,  $R_{\odot}$   
 1895 is the radius of the Sun,  $\rho_{\chi}$  is the local DM density,  $m_{\chi}$  the mass of the DM particle,  
 1896  $f_{v_{\odot}}(u_{\chi})$  the DM velocity distribution seen from the Sun's reference frame,  $R_i^-(\omega \rightarrow v)$   
 1897 is the differential rate at which a DM particle with velocity  $v$  scatters a solar target of  
 1898 mass  $m_i$  to end up with a velocity  $\omega$  and  $|F_i(q)|$  is the nuclear form factor of target  $i$ .

1899 The differential scattering rate takes a rather simple form when considering velocity-

## Chapter 7. DM searches with neutrinos from the Sun

1900 independent and isotropic cross sections. In that case, this quantity is given by [4, 80]:

$$R_i^-(\omega \rightarrow v) = \frac{2}{\sqrt{\pi}} \frac{\mu_{i,+}^2}{\mu_i} \frac{v}{\omega} n_i(r) \sigma_i \left[ \chi(-\alpha_-, \alpha_+) + \chi(-\beta_-, \beta_+) e^{\mu_i(\omega^2 - v^2)/u_i^2(r)} \right], \quad (7.6)$$

1901 where  $\mu_i$  is the ratio between the DM mass and the mass of target  $i$ ,  $\mu_{i,\pm}$  is defined as:

$$\mu_{i,\pm} \equiv \frac{\mu_i \pm 1}{2}, \quad (7.7)$$

1902  $n_i(r)$  is the density profile of target  $i$  in the solar medium,  $u_i(r)$  is the most probable

1903 velocity of target  $i$  given by:

$$u_i(r) = \sqrt{\frac{2T_\odot(r)}{m_i}}, \quad (7.8)$$

1904 where  $T_\odot(r)$  is the temperature of the Sun, the quantities  $\alpha_\pm$  and  $\beta_\pm$  are defined as:

$$\alpha_\pm \equiv \frac{\mu_{i,+}v \pm \mu_{i,-}\omega}{u_i(r)}, \quad (7.9)$$

$$\beta_\pm \equiv \frac{\mu_{i,-}v \pm \mu_{i,+}\omega}{u_i(r)}, \quad (7.10)$$

1905 and the function  $\chi(a, b)$  is a Gaussian integral of the form:

$$\chi(a, b) \equiv \int_a^b dx e^{-x^2}. \quad (7.11)$$

1906 Finally, if one assumes the DM halo velocity distribution in the galactic rest frame

1907 to be a Maxwell-Boltzmann distribution, one can write the halo velocity distribution for

1908 an observer moving at the speed of the Sun with respect to the DM rest frame as:

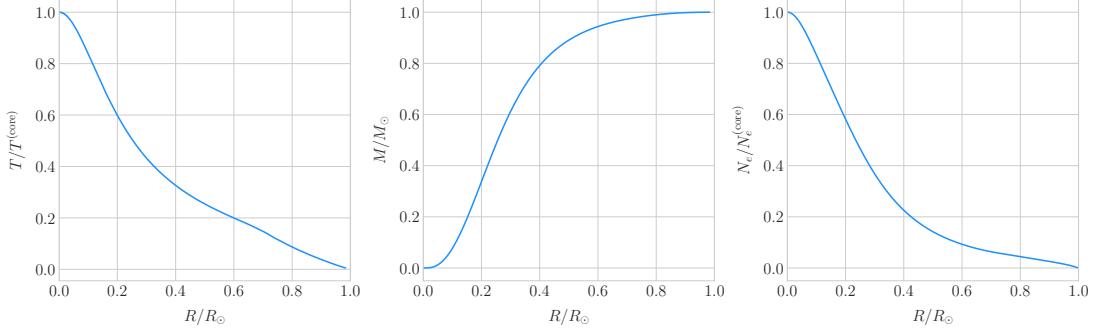
$$f_{v_\odot}(u_\chi) = \sqrt{\frac{3}{2\pi}} \frac{u_\chi}{v_\odot v_d} \left( e^{-\frac{3(u_\chi - v_\odot)^2}{2v_d^2}} - e^{-\frac{3(u_\chi + v_\odot)^2}{2v_d^2}} \right), \quad (7.12)$$

1909 where:

$$\omega^2 = u_\chi + v_e(r)^2, \quad (7.13)$$

1910 is the DM velocity squared,  $v_\odot$  the relative velocity of the Sun from the DM rest frame

## 7.2. Gravitational capture of DM by the Sun



**Figure 7.1:** Input solar parameters used in our capture rate computation as functions of the Sun's radius, from left to right: temperature (with respect to the temperature at the core), mass (in solar masses) and electron number density (with respect to the electron density at the core). All quantities shown correspond to the standard solar model BS2005-OP [3].

and  $v_d \simeq \sqrt{3/2}v_\odot$  the velocity dispersion.

For the case of strong scattering cross section, Eq. (7.5) ceases to be valid, as it escalates indefinitely with the cross section. In that limit, the capture rate saturates to the case where the probability of interaction is equal to one, which can be written as:

$$C_\odot^{\text{geom}} = \pi R_\odot^2 \left( \frac{\rho_\chi}{m_\chi} \right) \langle v \rangle \left( 1 + \frac{3}{2} \frac{v_e^2(R_\odot)}{v_d^2} \right) \xi(v_\odot, v_d), \quad (7.14)$$

where  $v_d = \sqrt{8/3\pi}v_\odot$  is the mean velocity in the DM rest frame and the factor  $\xi(v_\odot, v_d)$  accounts for the suppression due to the motion of the Sun:

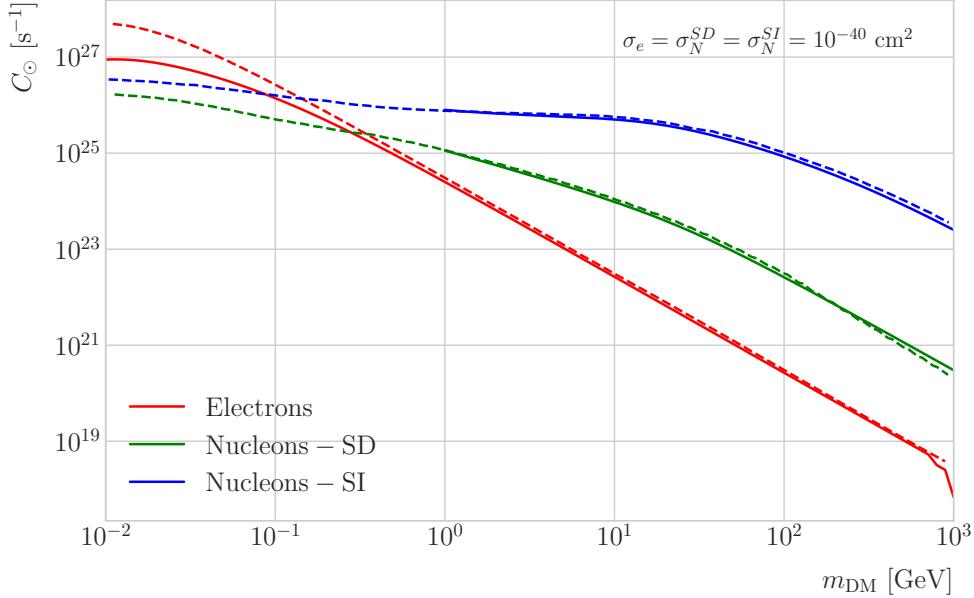
$$\xi(v_\odot, v_d) = \frac{v_d^2 e^{-\frac{3v_\odot^2}{2v_d^2}} + \sqrt{\frac{\pi}{6}} \frac{v_d}{v_\odot} (v_d^2 + 3v_e^2(R_\odot) + 3v_\odot^2) \text{Erf} \left( \sqrt{\frac{3}{2}} \frac{v_\odot}{v_d} \right)}{2v_d^2 + 3v_e^2(R_\odot)}. \quad (7.15)$$

Having these into account, one can write the total capture rate as a combination of both contributions, allowing a smooth transition between the two, as:

$$C_\odot = C_\odot^{\text{weak}} \left( 1 - e^{C_\odot^{\text{geom}}/C_\odot^{\text{weak}}} \right). \quad (7.16)$$

I computed the capture rate from Eq. (7.16) in the case of interactions with electrons. To do so, I used the standard solar model BS2005-OP [3]. Fig. 7.1 shows the

## Chapter 7. DM searches with neutrinos from the Sun



**Figure 7.2:** Capture rates as a function of the DM mass for the DM-electron interactions (red lines), SD DM-nucleons interactions (green lines) and SI DM-nucleons interactions (blue lines). Solid lines represent the values computed in this work while the dashed lines are the one given in Ref. [4]. All the rates are shown for a choice of scattering cross section of  $\sigma_i = 10^{-40} \text{ cm}^2$ .

1921 three parameters from the solar model that are needed for the computation, the solar

1922 temperature (left panel), mass (central panel) and electron density (right panel) profiles.

1923 For the case of the interactions off nuclei, the computations are more convoluted

1924 as one needs to add up the contributions of the different most abundant nuclei in

1925 the Sun. Also, in contrast to the electron scenario where the form factor is trivially

1926  $|F_e(q)|^2 = 1$ , for any nucleus  $i$  one would need to consider some appropriate nuclear

1927 density distribution (either a Gaussian approximation, a Woods-Saxon distribution, etc)

1928 which would complicate the calculations even further.

1929 That is the reason why, at this stage of our study, I decided to take an alternative

1930 approach to the computation of the DM-nucleus capture rates. I used the **DarkSUSY**

1931 software, that allows us to compute these quantities performing a full numerical

1932 integration over the momentum transfer of the form factors. The default standard

1933 solar model used by **DarkSUSY** is BP2000<sup>1</sup> [81].

---

<sup>1</sup>This is what they say in their manual, but I fear it is somewhat outdated. It appears to me this

## 7.2. Gravitational capture of DM by the Sun

you  
Fig.

1934 In Fig. 7.2 I show the results I obtained for the capture rates, for the case of  
 1935 interactions off electrons (red solid line), SD (green solid line) and SI (blue solid line)  
 1936 interactions of nucleons. In all cases I used a value of the scattering cross sections of  
 1937  $\sigma_i = 10^{-40} \text{ cm}^2$ . Note here one of the limitations of the **DarkSUSY** approach, one can  
 1938 not extend the computation below  $m_{\text{DM}} = 1 \text{ GeV}$ . Nevertheless, this is not something  
 1939 to worry about in this case, as I will discuss next. As a comparison, I added also the  
 1940 values computed in Ref. [4] (same color scheme, dashed lines). One can see there is good  
 1941 agreement between these and the **DarkSUSY** computation of the SD and SI interactions  
 1942 for  $m_{\text{DM}} \geq 1 \text{ GeV}$ . In this regime their computations also matches quite well our  
 1943 result for the electron capture rate. However, these start to differ significantly below  
 1944  $m_{\text{DM}} = 1 \text{ GeV}$ , being their estimate up to a factor of 5 bigger than ours for low masses.

1945 Let us comment briefly about the assumption I made before about not including  
 1946 an evaporation term in the Boltzmann equation. If I include this term in the equation  
 1947 (which will be proportional to the number of DM particles) the equilibrium solution  
 1948 takes the form:

$$N_{\text{DM}}^{eq} = \sqrt{\frac{C_{\odot}}{A_{\odot}}} \frac{1}{\kappa + \frac{1}{2} E_{\odot} \tau_{eq}}, \quad (7.17)$$

1949 where  $E_{\odot}$  is the total evaporation rate,  $\tau_{eq}$  is the equilibrium time in the absence of  
 1950 evaporation:

$$\tau_{eq} = \frac{1}{\sqrt{C_{\odot} A_{\odot}}}, \quad (7.18)$$

1951 and  $\kappa$  is defined as:

$$\kappa \equiv \sqrt{1 + \left( \frac{E_{\odot} \tau_{eq}}{2} \right)^2}. \quad (7.19)$$

1952 Now, it is easy to proof that in case evaporation dominates  $\kappa \gg 1$  and therefore:

$$N_{\text{DM}}^{eq} \simeq \frac{C_{\odot}}{E_{\odot}}. \quad (7.20)$$

1953 In contrast, if evaporation is irrelevant  $\kappa \simeq 1$  and one recovers Eq. (7.2).

---

model is relatively old and do not see why they are not using others like [3]. Maybe one can double-check in the code to make sure.

## Chapter 7. DM searches with neutrinos from the Sun

1954 In this way, one can define the evaporation mass as the mass for which the number  
1955 of DM particles in equilibrium approaches Eq. (7.20) at 10% level:

$$\left| N_{DM}^{eq}(m_{\text{evap}}) - \frac{C_{\odot}(m_{\text{evap}})}{E_{\odot}(m_{\text{evap}})} \right| = 0.1 N_{DM}^{eq}(m_{\text{evap}}). \quad (7.21)$$

1956 This can be regarded as the minimum testable mass one can reach using the annihilation  
1957 products of the DM in the Sun.

1958 It was reported in Ref. [4] that, in the case of both SD and SI DM interactions  
1959 off nuclei, this value ranges from 2 to 4 GeV depending on the specific scattering  
1960 cross-section value, compatible with the usual assumptions in the literature. What is  
1961 interesting is the case of the electron capture. It was found that, when one applies a  
1962 cutoff in the velocity distribution of the DM trapped in the Sun slightly below the escape  
1963 velocity, the evaporation mass for the DM-electron interaction decreases remarkably. For  
1964 a moderate choice of  $v_c(r) = 0.9v_e(r)$  one gets an evaporation mass of around 200 to  
1965 600 MeV. This possibility opens a region of the parameter space that could be tested  
1966 with neutrino detectors.

### 1967 7.3 Neutrino flux from DM annihilations

1968 When WIMPs annihilate inside the Sun a flux of high-energy neutrinos is expected from  
1969 heavy quarks, gauge bosons and  $\tau^+\tau^-$  final states, which decay before losing energy  
1970 in the dense solar medium, as they will produce a continuum spectra up to  $E_{\nu} \sim m_{\chi}$   
1971 (in the case of direct annihilation to neutrinos one would have a line at  $E_{\nu} = m_{\chi}$ ) [75].  
1972 This kind of signal has been extensively studied in the literature, allowing to put strong  
1973 limits on the SD WIMP-proton cross section for large  $m_{\chi}$ . However, the number of  
1974 high-energy neutrinos per WIMP annihilation is small and the spectrum depends on the  
1975 unknown final state. Moreover, background rejection is easier for large  $m_{\chi}$  but neutrinos  
1976 with  $E_{\nu} \gtrsim 100$  GeV are significantly attenuated by interactions in the Sun.

1977 Nevertheless, most WIMP annihilation final states eventually produce a low-energy  
1978 neutrino spectrum. In this case one does not just consider the more massive final

## 7.4. Computing limits from solar neutrino fluxes

1979 states but also annihilations into  $e^+e^-$ ,  $\mu^+\mu^-$  and light quarks [74]. In particular, light  
 1980 mesons would be produced and stopped in the dense medium, thus decaying at rest and  
 1981 producing a monoenergetic neutrino signal. The decay-at-rest of kaons will produce  
 1982 a  $E_\nu = 236$  MeV  $\nu_\mu$  while in the case of pions one would have a  $E_\nu = 29.8$  MeV  $\nu_\mu$ .  
 1983 In practice only  $K^+$  and  $\pi^+$  contribute to these signals, as  $K^-$  and  $\pi^-$  are usually  
 1984 Coulomb-captured in an atomic orbit and get absorbed by the nucleus. There is also a  
 1985 low-energy neutrino signal coming from muon decays, which are produced in kaon or  
 1986 pion decays, leptonic decays of other hadrons and heavy leptons or even directly from  
 1987 WIMP annihilations, which can decay at rest and contribute to the previous low-energy  
 1988 neutrino flux with a well known spectrum below 52.8 MeV.

1989 These monoenergetic MeV neutrinos were previously considered undetectable but,  
 1990 due to the large yield, the known spectra and the modern advances in the detector  
 1991 technology, these low-energy neutrino flux can be a good probe of the SD WIMP-proton  
 1992 cross-section in standard solar WIMP capture scenario, as it is sensitive to low WIMP  
 1993 masses and insensitive to the particular final state. A good place to look for these signals  
 1994 are next-generation neutrino experiments such as DUNE.

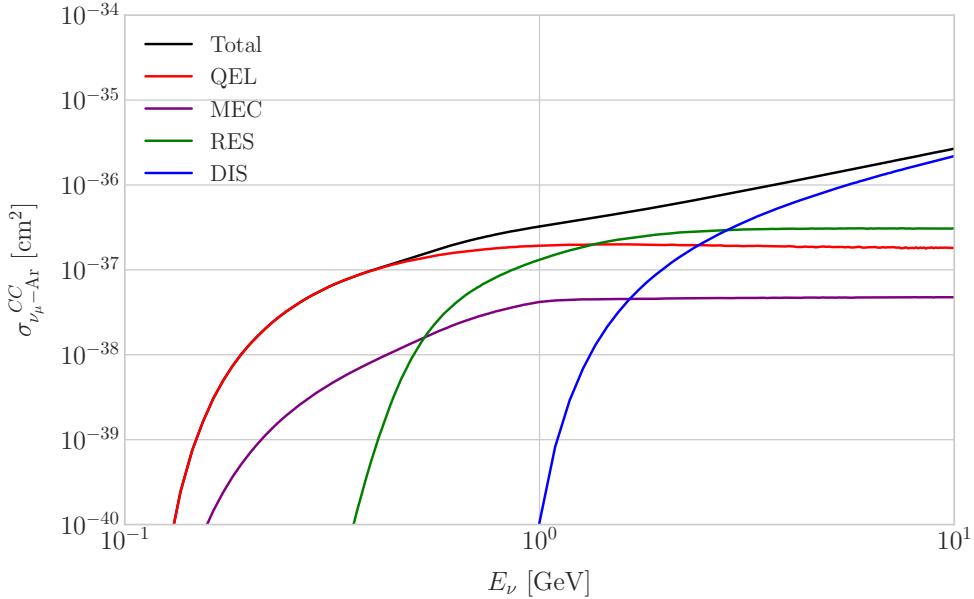
## 1995 7.4 Computing limits from solar neutrino fluxes

1996 In order to use the neutrino fluxes from DM annihilations in the Sun, the first thing I  
 1997 need to do is to determine the expected number of atmospheric background events, for  
 1998 a given exposure, after directionality selection has been applied. I can write this number  
 1999 as:

$$N_B = \eta_B \int d\Omega \int_{E_{min}}^{E_{max}} dE_\nu \frac{d^2\Phi_{atm}^\mu}{dE_\nu d\Omega} \times \left( A_{eff}^{(\mu)}(E_\nu) T \right), \quad (7.22)$$

2000 where  $\eta_B$  is the background efficiency,  $E_{min}$  and  $E_{max}$  the minimum and maximum  
 2001 energies to integrate over,  $d^2\Phi_{atm}^\mu/dE_\nu d\Omega$  the differential flux of atmospheric muon  
 2002 neutrinos,  $A_{eff}^{(\mu)}$  is the effective area of DUNE to muon neutrinos and  $T$  is the exposure  
 2003 time. The effective area can be expressed as the product of the neutrino-nucleus scattering  
 2004 cross section and the number of nuclei in the fiducial volume of the detector. This way

## Chapter 7. DM searches with neutrinos from the Sun



**Figure 7.3:** NuWro computed  $\nu_\mu - {}^{40}\text{Ar}$  charged-current scattering cross section as a function of the neutrino energy  $E_\mu$ . The black line shows to the total cross section, whereas the others correspond to the different contributions (in red quasi-elastic scattering, in green resonant pion exchange, in blue deep inelastic scattering and in purple meson exchange current).

2005 for DUNE I can write:

$$A_{eff}^{(\mu)}(E_\nu) = (6.0 \times 10^{-10} \text{ m}^2) \left( \frac{\sigma_{\nu-\text{Ar}}^{(\mu)}(E_\nu)}{10^{-38} \text{ cm}^2} \right) \left( \frac{M_{target}}{40 \text{ kT}} \right), \quad (7.23)$$

2006 where  $\sigma_{\nu-\text{Ar}}^{(\mu)}$  is the  $\nu_\mu - {}^{40}\text{Ar}$  charged-current scattering cross section. In Fig. 7.3 I  
2007 show the computed value of this cross section as a function of the neutrino energy  $E_\nu$ ,  
2008 in the range of interest both for the atmospheric background and signal events. It was  
2009 computed using the NuWro Monte Carlo neutrino event generator [82], including the  
2010 charged-current contributions of the quasi-elastic scattering (red line), resonant pion  
2011 exchange (green line), deep inelastic scattering (blue line) and meson exchange current  
2012 (purple line).

expect ~ Q  
 to draw  
 Feynman  
 diagrams for  
 these

2013 The background rejection will depend on the resolution of the detector and the  
2014 selection one applies on the events. A geometry argument can be used to estimate  
2015 the maximum background rejection one can achieve in this case, considering one can

## 7.4. Computing limits from solar neutrino fluxes

2016 efficiently discriminate all events coming from a direction different from that of the  
 2017 Sun. In that case, the optimal background efficiency will simply be the relative angular  
 2018 coverage of the Sun. Taking the angular diameter of the Sun as seen from the Earth to  
 2019 be  $0.5^\circ$ , I have:

$$\eta_B^{(opt)} \approx \frac{\pi \left(\frac{0.5}{2}\right)^2}{360 \times 180} \simeq 3.03 \times 10^{-6}. \quad (7.24)$$

2020 This value will give a very optimistic estimate of the number of background events.  
 2021 However, it can be regarded as a lower limit, as it represents the best case scenario.

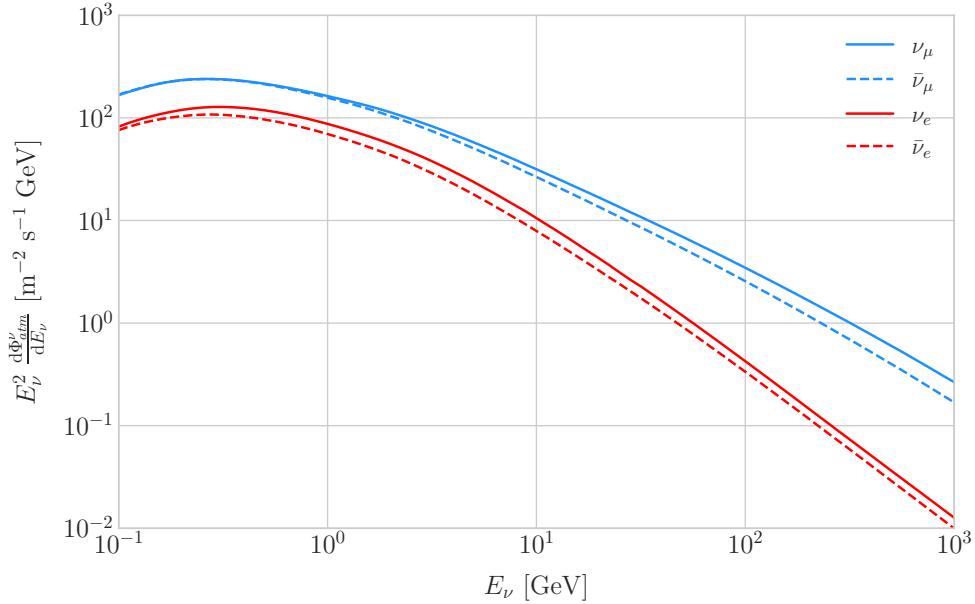
2022 In Fig. 7.4 I show the fluxes of atmospheric neutrinos at the Homestake mine during  
 2023 solar minimum, taken from Ref. [5]. The values are averaged over the two angular  
 2024 directions. In blue I have the flux of muon neutrinos while in red I indicate the flux  
 2025 of electron neutrinos. Additionally, the dashed lines correspond to both antineutrino  
 2026 species.

2027 Using these values for the muon neutrino and the corresponding total CC cross  
 2028 section, one can compute the number of expected background events by integrating over  
 2029 the given energy range (as in this case the angular integral is trivial). As for the energy  
 2030 range to integrate over, I choose the range for DUNE specified in [50],  $E_{min} = 10^{-1}$  GeV  
 2031 and  $E_{max} = 10$  GeV. Taking all these into account, I found the number of background  
 2032 events to be:

$$N_B \simeq \eta_B \times (3.827 \times 10^4) \times \left( \frac{\text{exposure}}{400 \text{ kT yr}} \right). \quad (7.25)$$

2033 In order  to estimate the sensitivity of DUNE to this kind signal, one can consider a  
 2034 hypothetical data set where the number of observed neutrinos is taken to be the expected  
 2035 number of background events rounded to the nearest integer,  $N_{obs} = \text{round}(N_B)$  [83].  
 2036 Now, if I assume that the number of signal and background events seen by DUNE are  
 2037 given by Poisson distributions with means equal to the expected number of signal and  
 2038 background events,  $N_S$  and  $N_B$ , one can denote by  $N_S^{90}$  to the number of expected  
 2039 signal events such that the probability of having an experimental run with a number of  
 2040 events greater than  $N_{obs}$  is 90%. This number can be obtained as the numerical solution

## Chapter 7. DM searches with neutrinos from the Sun



**Figure 7.4:** Expected atmospheric neutrino flux as a function of the neutrino energy  $E_\nu$  at Homestake at solar minimum, taken from Ref. [5]. The blue solid (dashed) line correspond to muon neutrinos (antineutrinos) and the red solid (dashed) line correspond to electron neutrinos (antineutrinos).

2041 to the equation:

$$1 - \frac{\Gamma(N_{obs} + 1, N_S^{90} + N_B)}{N_{obs}!} = 0.9, \quad (7.26)$$

2042 where  $\Gamma(x, y)$  is the upper incomplete gamma function.

2043 The number of signal events is related to the neutrino flux from DM annihilations in  
2044 a similar way as the background events to the atmospheric neutrino flux. In this case I  
2045 have:

$$N_S = \eta_S \Gamma_A^{eq} \int_{z_{min}}^{z_{max}} dz \frac{dN_\nu}{dAdN_Adz} \times (A_{eff}^\mu(z)T), \quad (7.27)$$

2046 where  $\eta_S$  is the signal efficiency,  $\Gamma_A^{eq}$  is the total annihilation rate of DM particles at  
2047 equilibrium,  $\Gamma_A^{eq} = A_\odot (N_{DM}^{eq})^2$ ,  $z_{min}$  and  $z_{max}$  the minimum and maximum relative  
2048 energies to integrate over (in such a way that  $z_{min,max} \leq E_{min,max}/m_{DM}$  for each  $m_{DM}$ )  
2049 and  $dN_\nu/dAdN_Adz$  the muon neutrino flux per DM annihilation in the Sun.

2050 Knowing  $N_S^{90}$  one can use the relation in Eq. (7.27) to obtain  $\Gamma_A^{eq,90}$  for different  
2051 values of the DM mass. From there I can directly translate those values into the

## 7.5. Example: Kaluza-Klein Dark Matter

2052 upper limits for DUNE on the DM scattering cross sections, for a given exposure. The  
2053 relation between the annihilation rate and the DM-nucleon cross section comes from the  
2054 equilibrium condition through the solar DM capture rate. The details of the evolution  
2055 of the number of DM particles inside the Sun and the computation of the capture rates  
2056 are discussed in App. 7.2.

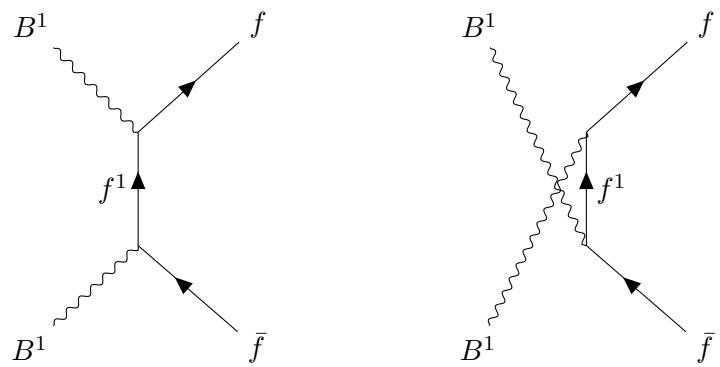
### 2057 7.5 Example: Kaluza-Klein Dark Matter

2058 Even though there are plenty of BSM theories which provide viable dark matter  
2059 candidates, Kaluza-Klein type of models [84, 85] within the universal extra dimensions  
2060 (UED) paradigm naturally predict the existence of a massive, stable particle that can  
2061 play the role of the dark matter. In the UED scenario all the SM fields can propagate  
2062 in one or more compact extra dimensions [86], as opposed to the idea of brane worlds  
2063 [87, 88], where just gravity can propagate in the bulk while SM particles live at fixed  
2064 points.

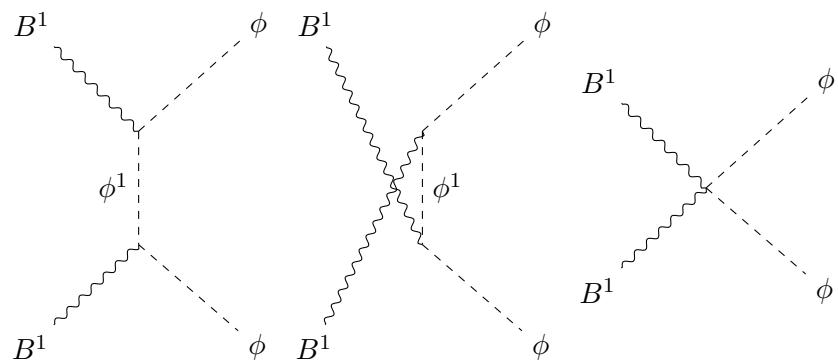
2065 Furthermore, in UED there is no violation of the translational invariance along the  
2066 extra dimensions, thus leading to degenerate KK modes masses and also the conservation  
2067 of the KK number in the effective four dimensional theory. At loop level, radiative  
2068 corrections and boundary terms shift the masses of the KK modes and break KK  
2069 number conservation into a KK parity. As a result, this theory only contains interactions  
2070 between an even number of odd KK modes and therefore the lightest among the first KK  
2071 excitations will be stable. This particle is usually denoted as the lightest Kaluza-Klein  
2072 particle (LKP) and its mass is proportional to  $1/R$ , being  $R$  the size of the extra  
2073 dimension.

2074 A viable DM candidate needs to be electrically neutral and non-baryonic, therefore  
2075 good candidates among the first Kaluza-Klein excitations would be the KK neutral  
2076 gauge bosons and the KK neutrinos [89]. Another possible candidate is the first KK  
2077 excitation of the graviton, which receives negligible radiate contributions and therefore  
2078 has a mass almost equal to  $1/R$ , but it has been shown that the lightest eigenstate from

## Chapter 7. DM searches with neutrinos from the Sun

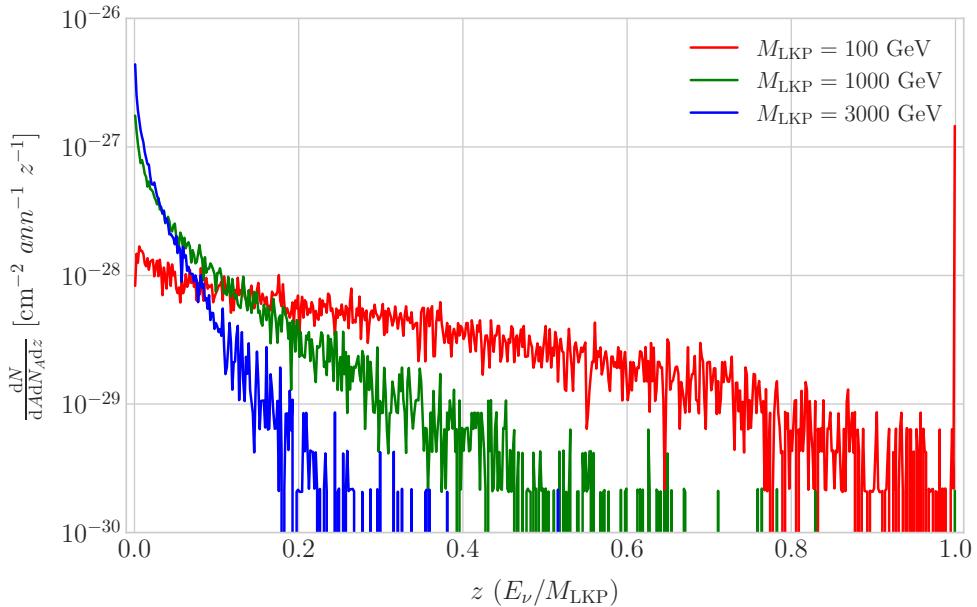


**Figure 7.5:** Feynman diagrams for  $B^1B^1$  annihilation into SM fermions.



**Figure 7.6:** Feynman diagrams for  $B^1B^1$  annihilation into a Higgs boson pair.

## 7.5. Example: Kaluza-Klein Dark Matter

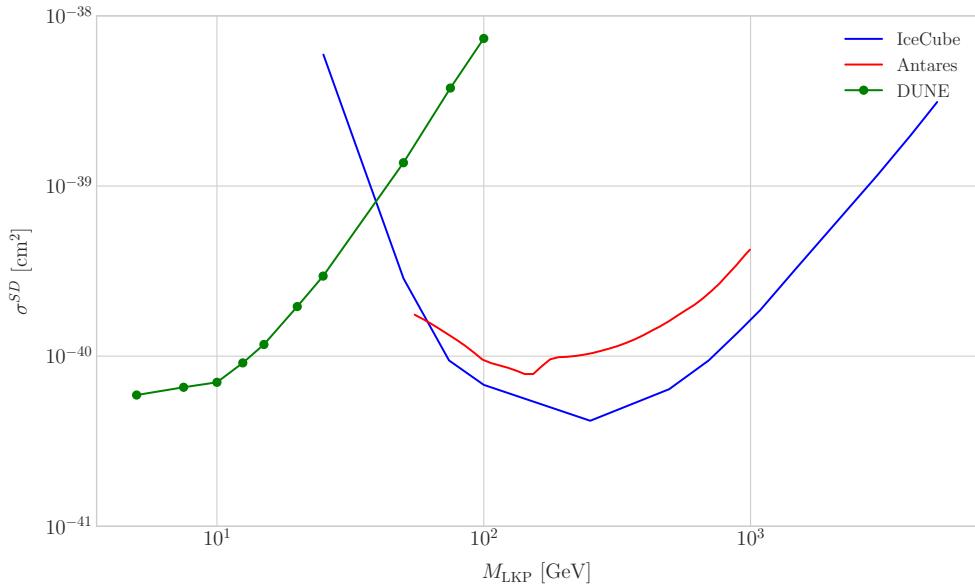


**Figure 7.7:** Computed spectra of muon neutrinos at the DUNE FD site from  $B^1$  annihilations in the Sun for three different values of  $M_{\text{LKP}}$ , plotted in relative energy units for legibility.

the mixing of the gauge mass states  $(B^1, W_3^1)$  would be lighter, as  $B^1$  and  $W_3^1$  receive negative radiative corrections [90]. It is also understood that, when these corrections become sizeable, the eigenstates become approximately pure  $B^1$  and  $W_3^1$  states as the Weinberg mixing angle grows small with the KK number [90]. In that case, the LKP can be well-approximated as being entirely  $B^1$ .

I need to compute the neutrino flux produced by the annihilations of the LKP in the core of the Sun, taking into account their propagation in the solar medium, as well as neutrino oscillations. To this end I used `WimpSim` [91, 92] to generate one million annihilation events in the Sun over a time span of four years and propagate them to the DUNE FD location ( $44^\circ 20' \text{ N}, 103^\circ 45' \text{ W}$ ), for different values of  $M_{\text{LKP}}$ . In Fig. 7.7 I show the obtained muon neutrino spectra arriving to the detector from LKP annihilations in the Sun, per unit area and per annihilation, plotted in relative energy units for different values of the mass. As one could expect the spectra get steeper the higher is the mass, due to the absorption of high-energy neutrinos in the solar medium. Also, one can see the peak at  $z = 1$  due to the direct annihilation into neutrinos  $\chi\chi \rightarrow \nu\bar{\nu}$ .

## Chapter 7. DM searches with neutrinos from the Sun



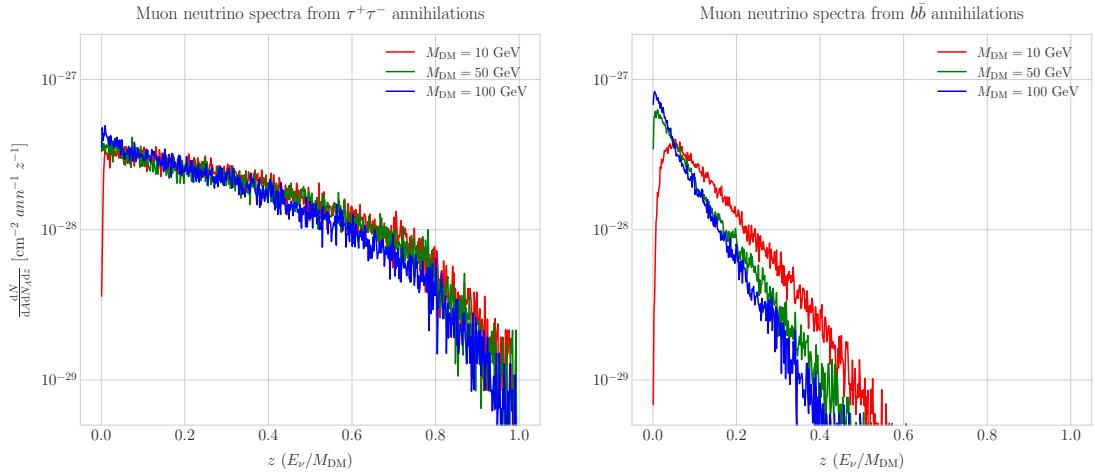
**Figure 7.8:** Projected 90% confidence level upper limit for DUNE (400 kT yr) on the spin-dependent  $B^1$ -proton scattering cross section as a function of  $M_{\text{LKP}}$  (green dots). I also show the previous limits from IceCube [6] (blue line) and Antares [7] (red line) on the LKP cross section. The shaded area represents the disfavoured region (at 95% confidence level) on the mass of the LKP from LHC data [8].

Now, one can estimate the sensitivity of DUNE to this particular model by using the methods I previously discussed. To begin with, I will use the optimistic estimation of the background efficiency in Eq. (7.24) to get our upper bound. Using it, one can directly compute the number of expected background events to be  $N_B = \underline{\underline{0.1101}}$  for an exposure of 400 kT yr. Then, Eq. (7.26) give us a value of  $N_S^{90} = 2.20$  for the 90% exclusion number of expected signal events. By using the NuWro generated cross sections and the computed neutrino fluxes from  $B^1$  annihilations in the Sun I can estimate the limits on the SD and SI DM-nucleus cross section using the relation in Eq. (7.2) and the capture rates I computed with DarkSUSY.

In Fig. 7.8 I show the projected sensitivity for DUNE on the spin-dependent  $B^1$ -proton scattering cross section versus the mass of the DM particle, for a exposure of 400 kT yr (green dots). I also include the previous results from IceCube [6] (blue line) and Antares [7] (red line). The shaded area represents the disfavoured region from combined searches for UED by ATLAS and CMS [8].

too many significant digits

## 7.6. High energy DM neutrino signals



**Figure 7.9:** Computed spectra of muon neutrinos at the DUNE FD site from  $\tau^+\tau^-$  (left panel) and  $b\bar{b}$  (right panel) annihilations in the Sun for the DM masses  $m_{\text{DM}} = 10 \text{ GeV}$  (red line),  $50 \text{ GeV}$  (green line) and  $100 \text{ GeV}$  (blue line), plotted in relative energy units.

From the experimental point of view, this estimation lacked a detailed simulation of the detector response and thus this must be considered as a mere optimistic sensitivity computation. However, it shows the potential of DUNE to constrain this kind of exotic scenarios, showing the region where it will be in a position to compete with other neutrino telescopes. A more detailed analysis is needed if I am to make a realistic estimation. Even though the region of the parameter space where DUNE would be sensitive to this particular model is quite constrained by collider searches [8] and other rare decay measurements [93, 94], it still constitutes an alternative indirect probe.

## 7.6 High energy DM neutrino signals

To have better estimates on the capability of the DUNE FD to constrain the parameter space of DM using solar neutrino fluxes, I need to start accounting for the detector resolution effects and the topologies of the different signatures. As a starting point, I will focus on specific annihilation channels. For the case of DUNE, the relevant ones are mainly the hard channels  $\tau^+\tau^-$  and  $\nu\bar{\nu}$  and the soft channel  $b\bar{b}$ . These are the open annihilation channels for relatively low mass WIMPs that will actually give neutrino fluxes. Other channels, like  $W^+W^-$  and  $ZZ$ , are open for more massive WIMPs, but

## Chapter 7. DM searches with neutrinos from the Sun

2124 those will produce usually a higher energy neutrino flux that will be out of reach for  
2125 DUNE (usually the maximum neutrino energy is taken to be  $E_{max} = 10$  GeV).

2126 In Fig. 7.9 I show the `WimpSim` [91, 92] generated muon neutrino spectra at the  
2127 DUNE FD location ( $44^\circ 20' N, 103^\circ 45' W$ ) from  $\tau^+\tau^-$  (left panel) and  $b\bar{b}$  (right panel)  
2128 annihilations in the core of the Sun, for different DM masses. Here, one can clearly see  
2129 the meaning of the previous distinction between hard and soft channels. For the same  
2130 DM mass value, the muon neutrino spectrum from the  $\tau^+\tau^-$  channel is more flat and  
2131 reaches higher energies than the one from the  $b\bar{b}$  channel, which drops faster.

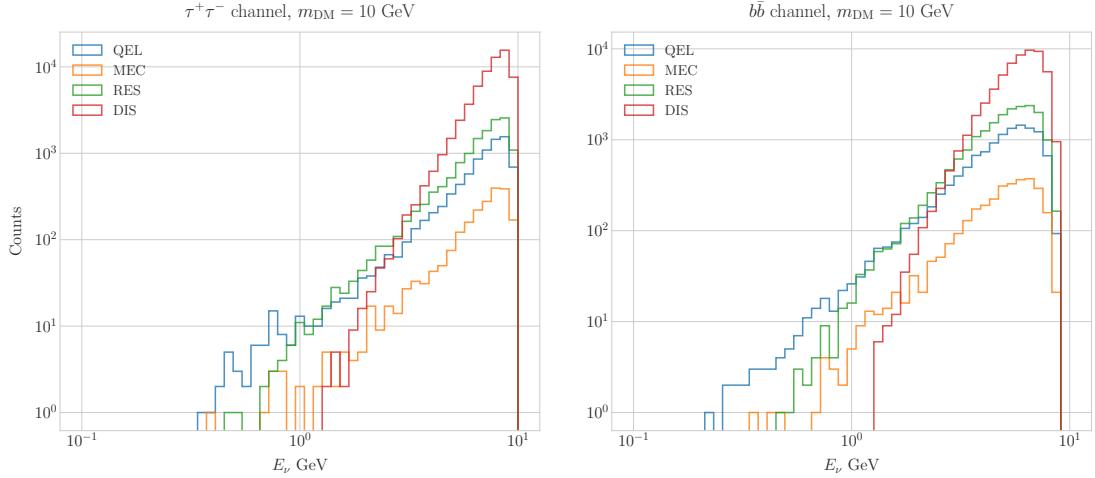
2132 In this case, I prepared two sets of files, one for  $\tau^+\tau^-$  and the other for  $b\bar{b}$ , for DM  
2133 masses in the range from 5 to 100 GeV (actually for  $b\bar{b}$  the first mass point I took is  
2134 7.5 GeV, as a WIMP with  $m_{DM} = 5$  GeV can not kinematically self annihilate into  $b\bar{b}$ ).  
2135 Then, I prepared the `WimpSim` output fluxes in a specific way to use them as inputs to  
2136 `NuWro`, which simulates the neutrino interaction with the argon.

2137 Because `WimpSim` outputs an event list together with the fluxes, I can use the former  
2138 to generate the events. The direction of these is given in terms of the azimuth and  
2139 altitude angles viewed from the specified location, so first I need to convert these into the  
2140 DUNE FD coordinates. Once I have done it, each event can be processed with `NuWro`.  
2141 To increase the number of samples and optimise the computation time, I generate 100  
2142 interactions (i.e. `NuWro` events) for each `WimpSim` event<sup>2</sup>. I restrict the event generation  
2143 to charged current interactions, but I allow all the different contributions to the CC  
2144 cross section, i.e. quasielastic scattering (QEL), meson exchange current process (MEC),  
2145 resonant pion production (RES) and deep inelastic scattering (DIS). I just take into  
2146 account the CC contribution because I am only interested in final states with charged  
2147 leptons, as we have better chances of reconstructing the kinematics of CC events.

2148 For the atmospheric fluxes I follow a similar procedure, only that this time I do not  
2149 have a set of events but the fluxes binned in azimuth and altitude angles. This way, I  
2150 transform these to DUNE coordinates and process the fluxes for each bin separated with

<sup>2</sup>This also solves a problem related with the generation of the neutrino interactions in `NuWro`, as if you only produce one event each time you launch `NuWro` it will always produce an interaction of the dominant interaction type for that particular energy.

## 7.6. High energy DM neutrino signals



**Figure 7.10:** Distribution of the muon neutrino energies from the  $\tau^+\tau^-$  (left panel) and  $b\bar{b}$  (right panel) annihilation channels, for  $m_{\text{DM}} = 10 \text{ GeV}$ , separated by CC interaction type: QEL (blue), MEC (orange), RES (green) and DIS (red).

2151 NuWro.

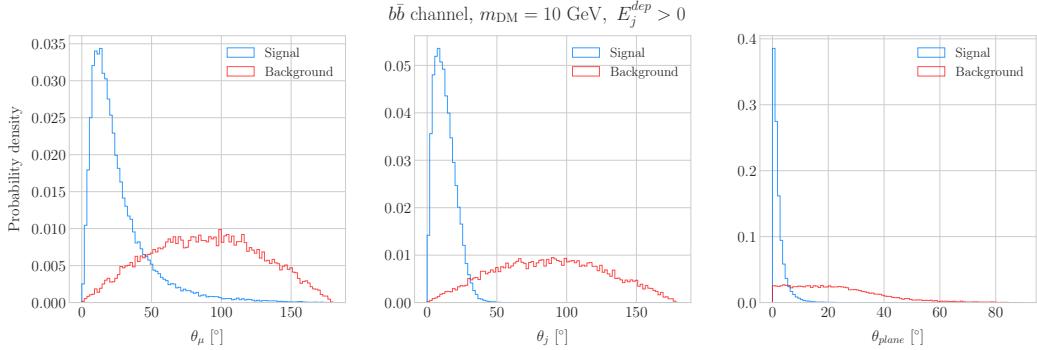
2152 At this point, I have two sets of events with different energies and final states.  
 2153 In Fig. 7.10 one can see the distribution of the muon neutrino energies for the case  
 2154  $m_{\text{DM}} = 10 \text{ GeV}$ , both for the  $\tau^+\tau^-$  (left panel) and  $b\bar{b}$  (right panel) channels, separated  
 2155 by interaction. One can clearly see that there are different energy regimes where the  
 2156 primary interaction type is different. This leads to a plurality of event topologies,  
 2157 therefore making it difficult to implement a general approach to the selection of events  
 2158 in detriment of the background. As a way to proceed, I decided to split our samples,  
 2159 based on the different interaction modes and contents of the final state, into a CC DIS  
 2160 sample and a single proton CC QEL sample.

I wouldn't say "split" or you only consider QEL-like DIS-like

### 2161 7.6.1 DIS events

2162 To begin with, I consider the high energy part of the spectrum. In this region DIS events  
 2163 dominate, i.e. interactions of the form  $\nu_\mu + q_d(\bar{q}_u) \rightarrow \mu^- + q_u(\bar{q}_d)$ . Therefore, our final  
 2164 estates will contain a muon and a hadronic jet from the fragmentation of the outgoing  
 2165 quark. As all these events have  $E_\nu \gtrsim 1 \text{ GeV}$  the momentum transfer to the remnant  
 2166 nucleus is negligible, for this reason the neutrino energy can be effectively reconstructed

## Chapter 7. DM searches with neutrinos from the Sun



**Figure 7.11:** Distributions of  $\theta_\mu$  (left panel),  $\theta_j$  (central panel) and  $\theta_{\text{plane}}$  (right panel) for the  $b\bar{b}$  sample with  $m_{\text{DM}} = 10$  GeV (blue) and the atmospheric background (red).

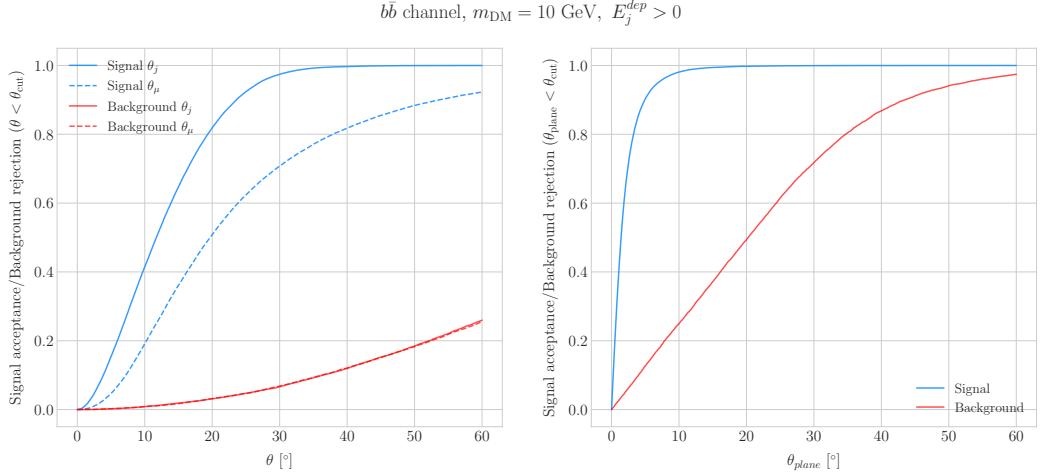
just taking into account the momenta of the muon and the jet. This technique was successfully used in Ref. [95] to select monoenergetic DM solar neutrino events from  $\nu\bar{\nu}$  annihilation channels.

Using momentum conservation one sees that the plane generated by the momenta of the muon and the jet needs to also contain the momentum of the neutrino. As we are interested in neutrinos coming from the Sun, the momentum of the neutrino can be regarded as known beforehand. This will allow us to define the angle of the outgoing muon and jet with respect to the incoming neutrino. Moreover, one can also use that information to reject poorly reconstructed jets, checking for deviations of these from the momentum conservation plane.

To account for the limited angular resolution of the detector, I smeared the momenta of the muons and hadrons. In a liquid argon TPC muons are expected to be tracked with high precision, therefore I take the associated angular resolution to be  $1^\circ$ . In the case of jets, it is expected that for the hadrons dominating the cascade a detector like DUNE has an angular resolution between  $1^\circ$  to  $5^\circ$  [50], so I take the latter, more conservative, estimate.

As a first selection step, I will just take into account particles with kinetic energies above the detection threshold of DUNE. For muons and photons the specified threshold energy is 30 MeV, for charged pions 100 MeV and for other hadrons 50 MeV [50]. This way, if the outgoing muon in a certain event has an energy lower than the required

## 7.6. High energy DM neutrino signals



**Figure 7.12:** Left panel: signal efficiencies (blue lines) and background rejections (red lines) for events passing the cuts  $\theta < \theta_{\text{cut}}$  for the jet (solid lines) and muon (dashed lines) angles. Right panel: signal efficiency (blue line) and background rejection (red line) for events passing the cut  $\theta_{\text{plane}} < \theta_{\text{cut}}$  for the momentum conservation plane deviation.

threshold I will drop such event. For the case of hadrons and photons, I will only require to have at least one particle above the energy threshold, so then one can compute the jet momentum using the (smeared) momenta of the  $N$  particles above threshold as:

$$\vec{p}_j = \sum_{i=1}^N \vec{p}_i. \quad (7.28)$$

Additionally, I will also define an estimation of the deposited hadronic energy as:

$$E_j^{\text{dep}} = m_{^{39}\text{Ar}} - m_{^{40}\text{Ar}} + \sum_{i=1}^N \sqrt{|\vec{p}_i|^2 + m_i^2}. \quad (7.29)$$

This quantity is useful to select events with enough hadronic visible energy in the detector. For events where most of the hadronic energy is scattered across plenty of hadrons with individual energies below the detection threshold, this estimation will give  $E_j^{\text{dep}} \leq 0$ . In these cases it could be expected that the jet momentum is poorly reconstructed, and therefore I require events to pass the cut  $E_j^{\text{dep}} > 0$ .

For the events I can compute the angles for the muon and jet with respect to the

## Chapter 7. DM searches with neutrinos from the Sun

2197 incoming neutrino as:

$$\cos \theta_\mu = \hat{p}_\nu \cdot \hat{p}_\mu, \quad (7.30)$$

$$\cos \theta_j = \hat{p}_\nu \cdot \hat{p}_j, \quad (7.31)$$

2198 and the deviation from the momentum conservation plane as:

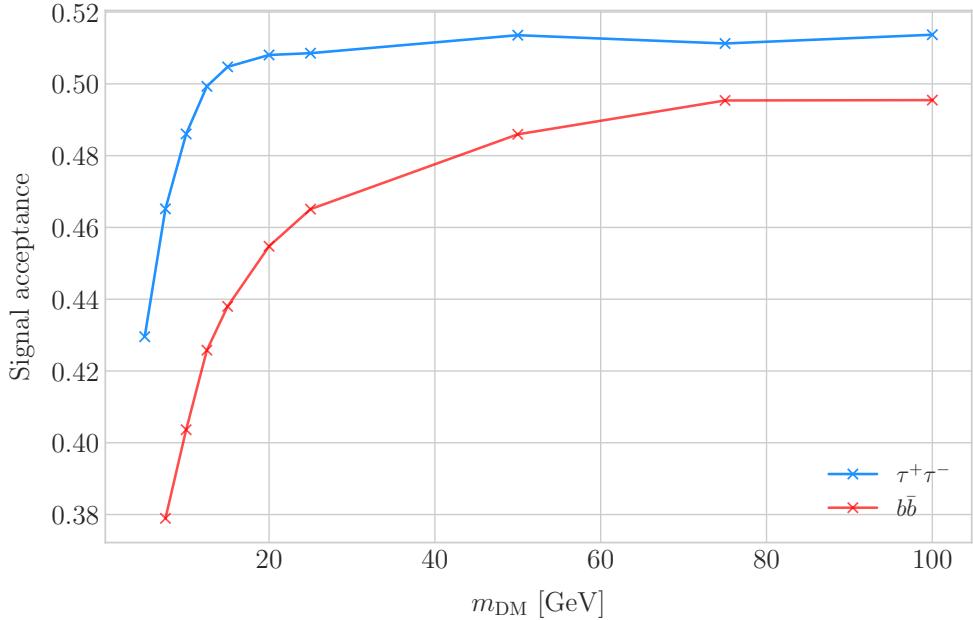
$$\sin \theta_{plane} = \left| \frac{\hat{p}_\mu \times \hat{p}_\nu}{|\hat{p}_\mu \times \hat{p}_\nu|} \cdot \hat{p}_j \right|. \quad (7.32)$$

2199 In Fig. 7.11 I show some distributions of these quantities for the case of the  $b\bar{b}$  sample  
2200 with  $m_{DM} = 10$  GeV (blue histograms) and for the atmospheric backgrounds (red).  
2201 In order to select the atmospheric events I followed the same criteria as for the signal  
2202 events. However, because in the signal case I used the true direction of the neutrino  
2203 as input, as it should be that of the Sun at that time and therefore known, in the  
2204 atmospheric case I used a set of solar positions as our ansatz for the neutrino direction.  
2205 From the distributions, one can see that the muon and the jet for the signal events are  
2206 predominantly forward and also that the deviations from the momentum conservation  
2207 plane are peaked at zero, as one should expect.

2208 Now, I can start applying cuts to maximise our signal selection efficiency while at  
2209 the same time I try to minimise the amount of atmospheric background events passing  
2210 the selection. To this end, I will need to find some lower and upper cuts for  $\theta_j$  and  
2211  $\theta_\mu$  and an upper bound for  $\theta_{plane}$ . In Fig. 7.12 I show how upper bound cuts in the  
2212 different angular variables affect the signal efficiency (blue lines) and the background  
2213 rejection (red lines). Notice that the signal efficiency behaves in a quite different way  
2214 when I apply cuts in the jet and the muon angles. On the contrary, the cuts on both  
2215 variables have a similar effect on the background rejection.

2216 In order to obtain the optimal set of cuts, I perform a multidimensional scan. I  
2217 do this separately for the  $\tau^+\tau^-$  and the  $b\bar{b}$  samples. For each case, I scan the possible  
2218 cuts for each mass point and then I take the mean value of the signal efficiency for

## 7.6. High energy DM neutrino signals

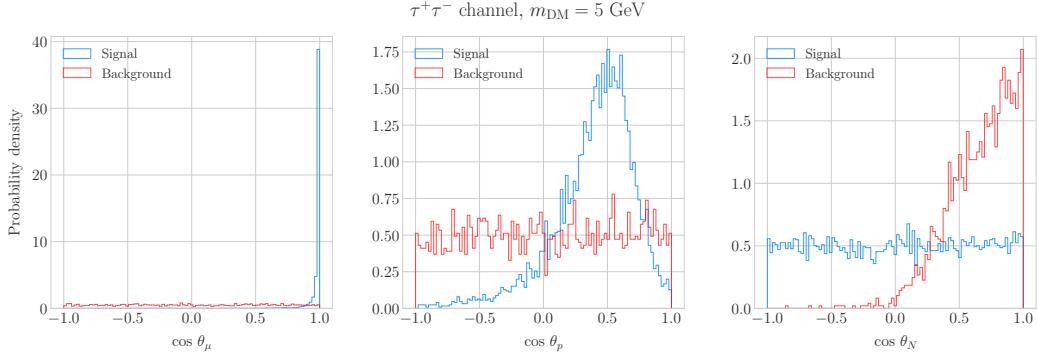


**Figure 7.13:** Signal efficiencies for the  $\tau^+\tau^-$  (blue line) and  $b\bar{b}$  (red line) DIS samples as functions of the DM mass,  $m_{\text{DM}}$ , obtained by applying the optimal angular cuts  $\theta_\mu < 27^\circ$ ,  $4^\circ < \theta_j < 26^\circ$  and  $\theta_{\text{plane}} < 3.5^\circ$ .

each configuration, to get the mean efficiency for each set of cuts. I do a similar scan for the atmospheric sample independently. Then, I take the sets of cuts such that the background rejection achieved is greater than 99.8% and search for the one which maximises the  $\tau^+\tau^-$  and  $b\bar{b}$  sample mean efficiencies. I found that with the cuts  $\theta_\mu < 27^\circ$ ,  $4^\circ < \theta_j < 26^\circ$  and  $\theta_{\text{plane}} < 3.5^\circ$  I get a background rejection of 99.80% while achieving a 49.40% and 44.92% mean signal efficiencies for the  $\tau^+\tau^-$  and  $b\bar{b}$  signals respectively.

In Fig. 7.13 I show the signal efficiencies as a function of the DM mass for the  $\tau^+\tau^-$  (blue line) and the  $b\bar{b}$  (red line) DIS events, after applying the cuts discussed above, as well as the energy threshold and hadronic visible energy selections. One can see that the efficiency grows with the mass, as annihilations of more massive DM particles will produce a neutrino spectrum centered at higher energies, where DIS events dominate. Notice also that the efficiency is higher for the  $\tau^+\tau^-$  case at every mass point, as in general this channel produces neutrinos at higher energies than the corresponding  $b\bar{b}$  channel.

## Chapter 7. DM searches with neutrinos from the Sun



**Figure 7.14:** Distributions of  $\cos \theta_\mu$  (left panel),  $\cos \theta_p$  (central panel) and  $\cos \theta_N$  (right panel) for the  $\tau^+\tau^-$  QEL sample with  $m_{\text{DM}} = 5$  GeV (blue) and the atmospheric background (red).

### 2233 7.6.2 Single proton QEL events

*like  
not sure why suddenly  
QE became QEL ...*

2234 Now, one can try to explore the low energy tail of the neutrino energy distributions. This  
 2235 regime is dominated by the QEL interactions, i.e. events of the type  $\nu_\mu + n \rightarrow \mu^- + p$ .  
 2236 In this case, as the typical energies are  $E_\nu \lesssim 1$  GeV, the momentum transfer to the  
 2237 remnant nucleus is sizeable. Therefore, I can not make the approximation I did before  
 2238 and assume that the momentum of the muon and the proton will give an adequate  
 2239 estimation of the reconstructed neutrino energy.

2240 In any case, as before, I can take the direction of the incoming neutrino as known.  
 2241 That way, one can estimate the energy of the neutrino as:

$$E_\nu^{reco} = E_\mu + E_p + m_{^{39}\text{Ar}} - m_{^{40}\text{Ar}}, \quad (7.33)$$

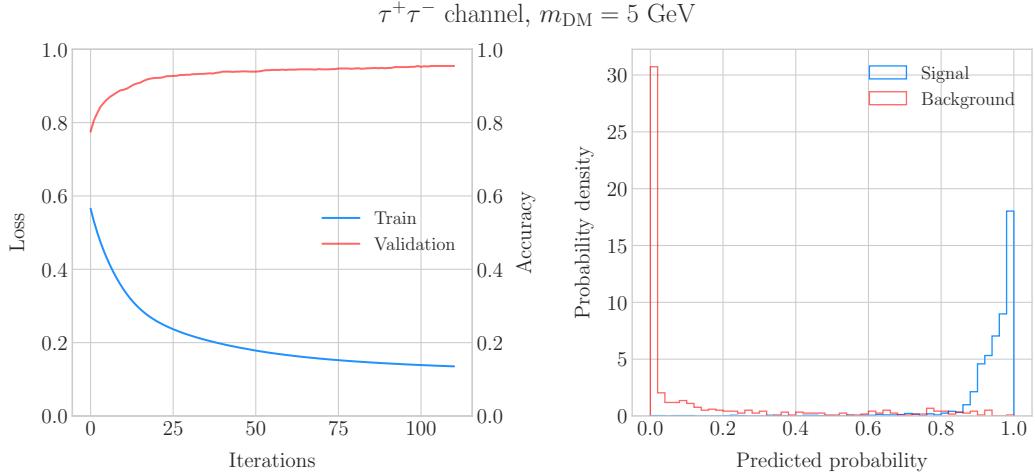
2242 and using momentum conservation I can write the momentum of the remnant nucleus  
 2243 as:

$$\vec{p}_N = \hat{p}_\nu (E_\mu + E_p + m_{^{39}\text{Ar}} - m_{^{40}\text{Ar}}) - \vec{p}_\mu - \vec{p}_p. \quad (7.34)$$

2244 As in the previous case, I need to drop the events where the muon or the proton fall  
 2245 below the kinetic energy detection threshold [50]. Also, I again apply a smearing to the  
 2246 momenta of the particles, a 1% for muons and 5% for protons.

2247 Having done that, one can compute the following angular variables for our selected

## 7.6. High energy DM neutrino signals



**Figure 7.15:** Left panel: value of the loss function for the training sample (blue line) and accuracy for the validation sample (red line) versus the number of iterations for the MLP classifier training. Right panel: distributions of the predicted probabilities assigned by the MLP classifier to the test sample for the  $\tau^+\tau^-$  QEL signal with  $m_{\text{DM}} = 5 \text{ GeV}$  (blue) and the atmospheric background (red).

2248 events:

$$\cos \theta_\mu = \hat{p}_\nu \cdot \hat{p}_\mu, \quad (7.35)$$

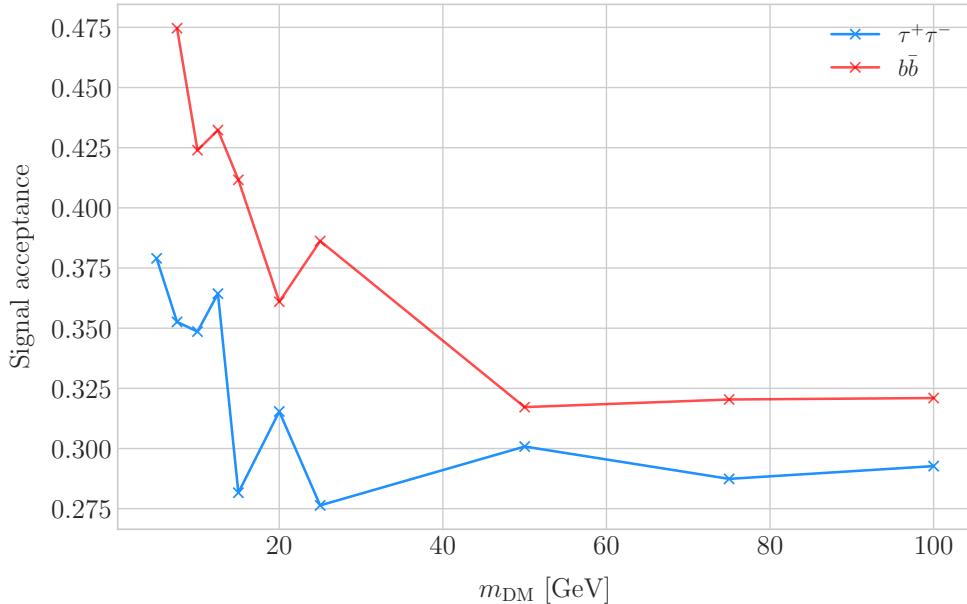
$$\cos \theta_p = \hat{p}_\nu \cdot \hat{p}_p, \quad (7.36)$$

$$\cos \theta_N = \hat{p}_\nu \cdot \hat{p}_N. \quad (7.37)$$

2249 Fig. 7.14 shows the distributions of these angular variables for the  $\tau^+\tau^-$  QEL  
 2250 sample with  $m_{\text{DM}} = 5 \text{ GeV}$  (blue) and the atmospheric background (red). Again, for  
 2251 the atmospheric events I used a random solar position as the ansatz for the incoming  
 2252 neutrino direction. Notice that now, opposed to the DIS case where the signal had very  
 2253 sharp distributions for the variables considered, the shapes of the angular distributions  
 2254 for signal and background are not that much different.

2255 This effectively means that the usual approach of applying simple angular cuts would  
 2256 not work as well as in the previous situation. Therefore, as a possible solution, I tried to  
 2257 use a multilayer perceptron (MLP) classifier to separate between signal and background  
 2258 events. Thus, the power of the hypothesis test will serve as an estimate of the signal

## Chapter 7. DM searches with neutrinos from the Sun



**Figure 7.16:** Signal efficiencies for the  $\tau^+\tau^-$  (blue line) and  $b\bar{b}$  (red line) single proton QEL samples as functions of the DM mass,  $m_{\text{DM}}$ , obtained by requiring a minimum predicted probability from the MLP classifier of 0.97 in order to achieve a background rejection greater than 99.8%.

efficiency, and in the same way one can take the size of the test to be our background rejection.

For each DM mass value and channel, as well as for the background sample, I divide our events into training, validation and test samples. The input variables for the classifier were the reconstructed neutrino energy from Eq. (7.33) and the angular variables defined in Eqs. (7.35 - 7.37). I used the MLP classifier implemented in `scikit-learn` [96], with a total of five hidden layers, the rectified linear unit activation function and adaptive learning rate. In order to account for fluctuations due to artifacts in the training process I repeated the training a thousand times for each sample, redefining each time the training, validation and test subsets, so one can take as our signal efficiency and background rejection the mean values of the powers and sizes of the tests.

The results of one of these training processes for the  $\tau^+\tau^-$  QEL signal with  $m_{\text{DM}} = 5$  GeV is shown in Fig. 7.15. On the left panel I show the loss function values (blue) and accuracy (red) at each iteration for the training and the validation samples respectively.

## 7.6. High energy DM neutrino signals

2273 The training stops either when the maximum number of iterations is reached (1000 in  
2274 this case) or when the accuracy for the validation sample reaches a certain tolerance  
2275 (I chose  $10^{-4}$  as our tolerance). On the right panel I have the distributions for the  
2276 predicted probability by the model, separated in true signal (blue) and background  
2277 (red) events, for the test sample. One can see that both populations are well separated,  
2278 obtaining a power of 44.97% and a size of 0.17% when I require a predicted probability  
2279 greater than 0.97.

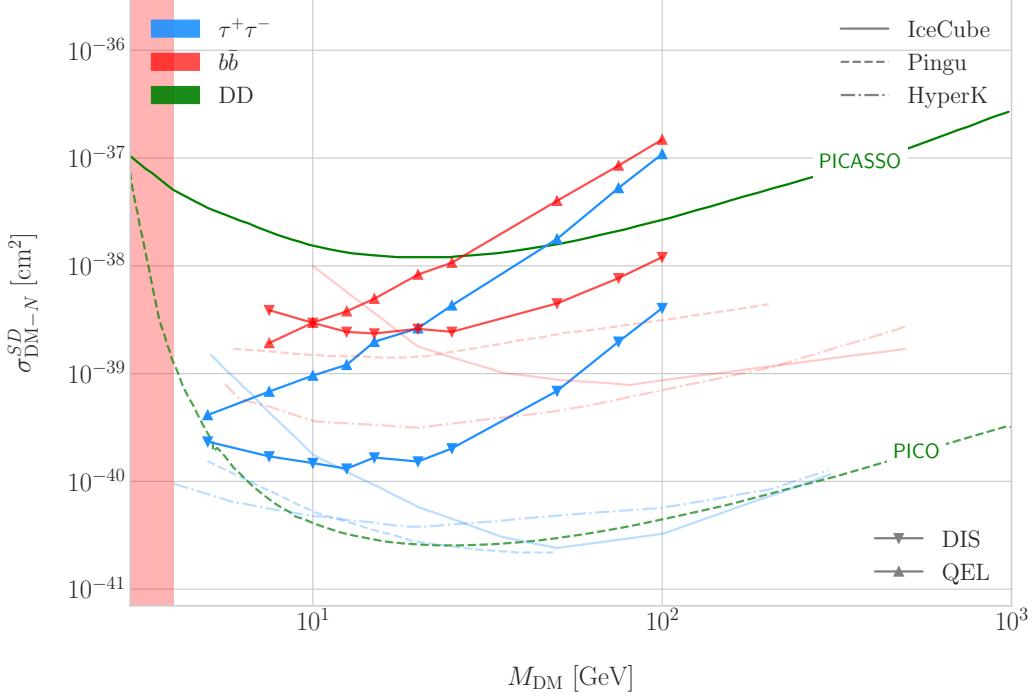
2280 Applying this criteria for each sample, I obtain the mean signal efficiencies shown in  
2281 Fig. 7.16. Notice that the efficiencies for the channel  $\tau^+\tau^-$  (blue line) are consistently  
2282 lower than the ones for the  $b\bar{b}$  channel (red line). This can be due to the fact that, for  
2283 each DM mass point, the neutrino spectrum coming from the  $b\bar{b}$  annihilation channel is  
2284 centered at lower energies when compared to the  $\tau^+\tau^-$  spectrum. This directly translates  
2285 into more low energy neutrinos undergoing QEL interactions, which give signals that  
2286 can be easily separated from the atmospheric background. This explanation also help us  
2287 understand why in both cases the signal acceptance drops when the DM mass increases.  
2288 In all cases, the background rejection took values between 99.8% to 99.9%. I will assume  
2289 a 99.8% background rejection value in all cases to keep our estimation conservative.

### 2290 7.6.3 Results

2291 In order to estimate the DM-nucleon cross section sensitivities in the present case I need  
2292 again to compute the expected number of background events. As I am now separating  
2293 events by interaction type Eq. (7.25) does not hold anymore, as in that case I integrated  
2294 over the total neutrino-argon cross section. In this instance, the expected background  
2295 events for DIS events is approximately given by:

$$N_B^{DIS} \simeq \eta_B^{DIS} \times (4.655 \times 10^3) \times \left( \frac{\text{exposure}}{400 \text{ kT yr}} \right), \quad (7.38)$$

## Chapter 7. DM searches with neutrinos from the Sun



**Figure 7.17:** Projected 90% confidence level upper limit for DUNE (400 kT yr) on the spin-dependent DM-nucleon scattering cross section as a function of  $m_{\text{DM}}$ , for the annihilation channels  $\tau^+\tau^-$  (blue) and  $b\bar{b}$  (red) separated by interaction type (up triangles denote DIS interactions whereas down triangles represent QEL interactions). I also show the previous limits from IceCube [9] (solid lines) and the projected sensitivities for Pingu [10] (dashed lines) and Hyper-Kamiokande [11] (dash-dotted lines), as well as the direct detection limits from PICASSO [12] (solid green line) and PICO-60 C<sub>3</sub>F<sub>8</sub> [13] (dashed green line).

2296 whereas for QEL events we have:

$$N_B^{QEL} \simeq \eta_B^{QEL} \times (2.248 \times 10^4) \times \left( \frac{\text{exposure}}{400 \text{ kT yr}} \right). \quad (7.39)$$

2297 Now, using these together with Eqs. (7.26) and (7.27) one can obtain the 90% C.L.  
 2298 upper limit on the total annihilation rate at equilibrium for both kind of events. Then,  
 2299 applying the computed DM-nucleons capture rates I can translate these into limits on  
 2300 the DM-nucleon cross section by means of Eqs. (7.2), (7.5) and (7.6).

2301 Fig. 7.17 shows the obtained limits on the SD DM-nucleon cross section for DUNE,  
 2302 using the DIS (up triangles) and QEL (down triangles) events both for the  $\tau^+\tau^-$  (blue)  
 2303 and the  $b\bar{b}$  (red) samples, for an exposure of 400 kT yr. I also include the corresponding

## 7.7. Example: Leptophilic Dark Matter

2304 current limits from IceCube [9] (solid lines), as well as the projected sensitivities of Pingu  
2305 [10] (dashed lines) and Hyper-Kamiokande [11] (dash-dotted lines). For comparison, I  
2306 also show the reported direct detection limits from PICASSO [12] (solid green line) and  
2307 PICO-60 C<sub>3</sub>F<sub>8</sub> [13] (dashed green line).

2308 Notice that, for most of the mass range, the limits one can set by using the DIS  
2309 events are stronger than those of the QEL interactions, except for the low mass part  
2310 of both the  $\tau^+\tau^-$  and the  $b\bar{b}$  curves where the QEL events dominate. In general, the  
2311 expected sensitivity of DUNE for DM masses  $\lesssim 25$  GeV surpasses the stronger current  
2312 indirect limits. However, experiments like Hyper-Kamiokande are foreseen to have an  
2313 overall better sensitivity in this kind of searches, as they have a bigger active volume  
2314 and accept a broader energy range.

2315 A pending question is what happens when we add the RES and MEC charged-current  
2316 interaction contributions. In that case it would probably be more convenient to split  
2317 the samples by final state interaction topologies. Also, another necessary improvement  
2318 would be adding a full detector simulation and reconstructions. This will also require  
2319 considering the effect of poorly reconstructed events or final states containing neutral  
2320 particles such that they mimic the desired topology at the reconstruction level.

## 2321 7.7 Example: Leptophilic Dark Matter

2322 In general, the capture rate of DM particles by the Sun via interactions with electrons is  
2323 several orders of magnitude smaller than the capture via DM-nucleus scattering. Thus,  
2324 it would be sub-leading even when nucleon capture is loop suppressed. As I showed in  
2325 Fig. 7.2, the capture rate via scattering off electrons only surpasses the capture rates  
2326 via DM-nucleons interactions for DM masses  $\lesssim 100 - 500$  MeV.

2327 However, if one considers a model where DM-nucleon interactions are forbidden even  
2328 at loop level, then electron interactions will be the sole contributor to DM capture in  
2329 the Sun. One can describe such scenario where the DM particles couple to leptons but  
2330 not to the quark sector using effective operators.

## Chapter 7. DM searches with neutrinos from the Sun

2331 In general, assuming that the DM particle is a Dirac fermion, the dimension six  
2332 operators describing the interaction between two DM particles and two leptons can be  
2333 written as:

$$\mathcal{L}_{eff} = G \sum_i (\bar{\chi} \Gamma_\chi^i \chi) (\bar{\ell} \Gamma_\ell^i \ell), \quad (7.40)$$

2334 where  $G = 1/\Lambda^2$  is the effective coupling strength,  $\Lambda$  the cut-off of the effective field  
2335 theory and  $\ell$  denotes any lepton. In principle, one should consider all the possible  
2336 Lorentz structures  $\Gamma_f^i$  in order to have a complete set of effective operators.

2337 However, some combinations will induce interactions with nucleons at loop level. As  
2338 we are specifically interested in interactions which forbid any communication with the  
2339 quark sector, I will not consider those [97]. In addition, some of the effective operators  
2340 give rise to velocity-suppressed scattering cross sections between DM particles and  
2341 leptons. I will also neglect those, as the suppression goes with the square of the DM  
2342 halo velocity which in units of the speed of light is  $\sim 10^{-6}$ .

2343 This way, the only Lorentz tensor structure that do not induce interactions with  
2344 quarks at loop level and gives a contribution to the scattering cross section that is not  
2345 velocity suppress is the axial-axial interaction. The effective Lagrangian is then given  
2346 by:

$$\mathcal{L}_{eff} = \frac{c_A^\chi c_A^\ell}{\Lambda^2} (\bar{\chi} \gamma^\mu \gamma^5 \chi) (\bar{\ell} \gamma_\mu \gamma^5 \ell), \quad (7.41)$$

2347 where  $c_A^\chi$  and  $c_A^\ell$  are the couplings for the different species. As the DM coupling appears  
2348 as a common factor for any lepton choice, I will redefine the corresponding coupling  $c_A^\ell$   
2349 to absorb  $c_A^\chi$ . Also, for simplicity, I will assume that the couplings between the DM  
2350 particles and the leptons are flavour independent, i.e. I have just two couplings,  $c_A^e$  for  
2351 charged leptons and  $c_A^v$  for neutrinos.

2352 In the case of a scalar DM particle, the lowest order effective interaction with  
2353 leptons happens through a dimension five operator, generating scalar and pseudoscalar  
2354 interactions. However, the former induces interactions with quarks at two loop level  
2355 whereas the latter gives a velocity suppressed scattering cross section.

2356 From the effective Lagrangian in Eq. (7.41) it can be shown that the axial-axial

## 7.7. Example: Leptophilic Dark Matter

2357 contribution to the scattering cross section for the fermionic DM and a charged lepton  
2358 is given by:

$$\sigma_{\text{DM}-e}^{AA} = 3(c_A^e)^2 \frac{m_e^2}{\pi \Lambda^4}. \quad (7.42)$$

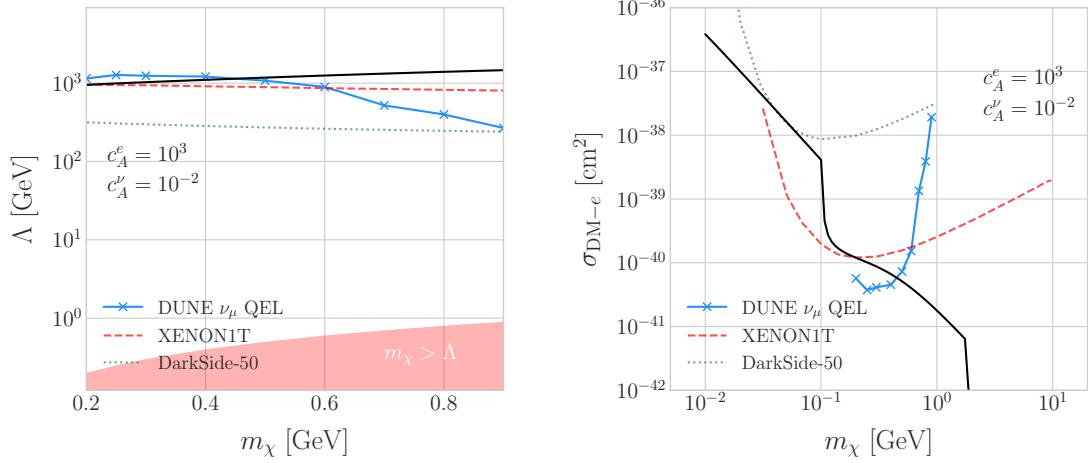
2359 If the DM interacts exclusively with fermions, then the only annihilation channels  
2360 that will give us a measurable neutrino flux coming out of the Sun are  $\tau^+\tau^-$  and  $\nu\bar{\nu}$ . The  
2361 former channel, already explored previously in the more mainstream scenario of the DM  
2362 capture via scattering off nucleons, is open only for  $m_{\text{DM}} > m_\tau \simeq 1776.86 \pm 0.12$  MeV  
2363 [98], a mass region where the solar DM capture by electrons is at least one order of  
2364 magnitude smaller than the capture via interactions with nucleons. On the contrary, the  
2365 latter allows us to explore a region where the capture rate via scattering off electrons  
2366 dominates over the rest.

2367 One downside of focusing in such low mass range is that it falls below the usual  
2368 limit of  $m_{\text{evap}} \sim 4$  GeV usually explored in the literature. The pretext to explore this  
2369 region is the result discussed previously reported in Ref. [4], where DM evaporation in  
2370 the Sun for the case of capture via electron scattering could be negligible for masses  
2371 as low as  $m_{\text{evap}} \sim 200$  MeV. This result is quite sensitive to the high velocity tail of  
2372 the DM velocity distribution in equilibrium inside the Sun, and therefore full numerical  
2373 simulations would be needed to assess the impact of this effect. However, this falls out of  
2374 the scope of our work.

2375 In this case, as I have a specific realisation of the interaction between the DM  
2376 and leptons, one can estimate the relic density of our DM for different values of the  
2377 couplings and the effective field theory scale  $\Lambda$ . The first step to do so is compute the  
2378 self-annihilation cross section. Because I consider cold relics, at the freeze-out time our  
2379 DM particles were non-relativistic and so one can expand the annihilation cross section  
2380 in terms of the relative velocity  $v$  between two annihilating DM particles as [99]:

$$\sigma_{\text{ann}}^{AA}|v| \approx \frac{1}{2\pi\Lambda^4} \sum_\ell \left(c_A^\ell\right)^2 m_\chi^2 \sqrt{1 - \frac{m_\ell^2}{m_\chi^2} \left[ \frac{m_\ell^2}{m_\chi^2} + \frac{1}{12} \left(2 - \frac{m_\ell^2}{m_\chi^2}\right) v^2 \right]}, \quad (7.43)$$

## Chapter 7. DM searches with neutrinos from the Sun



**Figure 7.18:** Left panel: Projected 90% confidence level sensitivity of DUNE (400 kT yr) to the scale  $\Lambda$  of an EFT containing only leptophilic DM axial-axial interactions (blue line). Right panel: . In both cases the corresponding limits from DarkSide-50 [14] (dotted green line) and XENON1T [15] (dashed red line) are also shown, together with the configurations for which the correct relic density is achieved (black line), all for the coupling values  $c_A^e = 10^3$  and  $c_A^\nu = 10^{-2}$ .

2381 where the sum includes all the possible lepton final states with mass  $m_\ell$ .  
 2382 Solving the Boltzmann equation for the evolution of the DM density gives as a  
 2383 solution a relic density of:

$$\Omega_\chi h^2 \approx \frac{(1.04 \times 10^9) x_F}{M_{Pl} \sqrt{g_*} (a + 3b/x_F)}, \quad (7.44)$$

2384 where  $x_F = m_\chi/T_F$  being  $T_F$  the freeze-out temperature,  $g_*$  the number of relativistic  
 2385 degrees of freedom at freeze-out and  $a$  and  $b$  the terms in the annihilation cross section  
 2386 expansion  $\sigma_{ann}|v| \approx a + bv^2 + \mathcal{O}(v^4)$ . Using the current best fit for the relic DM density  
 2387  $\Omega_\chi h^2 = 0.1198 \pm 0.0012$  [100] one can use these relations to compute the required  
 2388 effective theory scale  $\Lambda$  at which the correct density is achieved for any combinations of  
 2389  $m_\chi$  and  $c_A^\ell$ .

2390 As discussed before, in the low DM mass region QEL interactions dominate. Moreover,  
 2391 if I focus on direct annihilation to neutrinos, the energy of the muon neutrino flux is  
 2392 known as it must be equal to the mass of the DM particle,  $E_\nu = m_\chi$ . That way, now  
 2393 I do not need to use Eq. (7.33) in order to estimate the momentum transfer to the

## 7.7. Example: Leptophilic Dark Matter

2394 remnant nucleus, I can simply take:

$$\vec{p}_N = \hat{p}_\nu m_\chi - \vec{p}_\mu - \vec{p}_p. \quad (7.45)$$

2395 To estimate the signal efficiency and background rejection for this case I used again  
2396 the MLP classifier from `scikit-learn`, using the same specifications as before. The  
2397 only difference now is that I add also the reconstructed neutrino energy as one of the  
2398 features to train the classifier with, because the characteristic monoenergetic flux for  
2399 each  $m_\chi$  value will help to distinguish between signal and background events.

2400 In this case, for masses below  $\sim 500$  MeV I obtain a signal efficiency close to unity  
2401 while keeping a background rejection of 99.9%. For bigger values of the mass, the signal  
2402 efficiency drops significantly if I require to keep the background acceptance under 0.01%.  
2403 However, because this kind of search is dominated by the background, sacrificing the  
2404 signal acceptance to keep the background rejection to a minimum enhances the reach  
2405 of the analysis. This way, for DM masses of the order of  $m_\chi \sim 1$  GeV I end up with  
2406 efficiencies as low as 1%.

2407 Now, estimating the number of background events using Eq. (7.39) one can go on  
2408 and apply Eqs. (7.26) and (7.27) together with Eq. (7.42) to derive the sensitivity of  
2409 DUNE to this kind of model. Fig. 7.18 (left panel) shows the potential reach of DUNE  
2410 to constrain the EFT scale  $\Lambda$  this model containing only leptophilic DM axial-axial  
2411 interactions (blue line), for a choice of couplings  $c_A^e = 10^3$  and  $c_A^\nu = 10^{-2}$ . I also included  
2412 the current limits on the DM-electron scattering cross section from DarkSide-50 [14]  
2413 (dotted green line) and XENON1T [15] (dashed red line), reworked with Eq. (7.42) to  
2414 show their implications for the EFT scale. The values of  $\Lambda$  for which the correct DM relic  
2415 density value is achieved for each mass are also shown (black line). This tells us that,  
2416 for that specific choice of couplings, DUNE would be sensitive to DM configurations  
2417 allowed by the relic density constraint up to a mass of  $m_\chi \sim 400$  MeV.

2418 In Fig. 7.18 (right panel) I show the same upper limits but for the DM-electron  
2419 scattering cross section. From this view one can see that DUNE would be able to

## Chapter 7. DM searches with neutrinos from the Sun

2420 offer complementary information to the low energy DM-electron interaction searches  
2421 performed by direct detection experiments, in a slightly higher mass range.

2422 With the present example, although it focuses on a very specific realisation of the DM  
2423 interactions, I show the potential of DUNE to constrain exotic DM scenarios. Thanks  
2424 to its low backgrounds and superb angular resolution DUNE will be able to help with  
2425 the systematic searches for dark sectors physics.

2426 Chapter 8

2427 Particle ID in GArSoft

2428 ND-GAr is a magnetised, high-pressure gaseous argon TPC (HPgTPC), surrounded by  
2429 an electromagnetic calorimeter (ECal) and a muon detector (commonly refer to as  $\mu$ ID).  
2430 A detailed discussion on the requirements, design, performance and physics of ND-GAr  
2431 can be found in the DUNE ND CDR [56] and the ND-GAr whitepaper (cite).

2432 In DUNE Phase II ND-GAr will fulfill the role of TMS, measuring the momentum  
2433 and sign of the charged particles exiting ND-LAr. Additionally, it will be able to measure  
2434 neutrino interactions inside the HPgTPC, achieving lower energy thresholds than those  
2435 of the ND and FD LArTPCs. By doing so ND-GAr will allow to constrain the relevant  
2436 systematic uncertainties for the LBL analysis even further.

2437 The goal of the present chapter is to review the requirements that the physics program  
2438 of DUNE impose on ND-GAr, present the current status of its design and describe the  
2439 GArSoft package, its simulation and reconstruction software.

2440 As decided during the DUNE Phase II workshop in June 2023 [reference], we want  
2441 to build ND-GAr physics case by showing:

- 2442 • That ND-GAr can constrain systematic uncertainties that ND-LAr might miss.
- 2443 • The impact on the neutrino oscillation results if such systematic uncertainties are  
2444 missed.
- 2445 • That ND-GAr is necessary to reach DUNE's main physics goals.

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2446 This way, the design of ND-GAr will be physics driven.

2447 In order to study the effects of final state interactions (FSI) in CC interactions,  
2448 ND-GAr should be able to measure the spectrum of protons and charged pions at low  
2449 energies. ND-GAr also needs to be able to measure the pion multiplicity, specially for  
2450 energies above 100 MeV as at these energies the pions shower in the LAr, to inform the  
2451 pion mass correction in the ND and FD LArTPCs.

2452 In order to correctly identify electrons, muons, pions, kaons and protons ND-GAr  
2453 can use a combination of:  $dE/dx$  measurements in the HPgTPC,  $E_{ECAL}/p$  using the  
2454 ECAL total energy and the momentum obtained from magnetic spectroscopy in the  
2455 HPgTPC and penetration information through the ECAL and muon tagger.

### 2456 8.1 $dE/dx$ measurement in the TPC

2457 Among the parameters extracted from the track fitting, ionisation is particularly useful  
2458 for particle identification, as it is a function of the particle velocity. Although for the  
2459 case of relativistic particles this dependence is not very strong, measuring the track on  
2460 a large number of points may allow us to estimate the amount of ionisation accuratel.  
2461 This, paired with a measurement of the momentum, may allow us to identify the particle  
2462 type.

2463 The first calculation of the energy loss per unit length of relativistic particles using a  
2464 quantum-mechanical treatment is due to Bethe [101]. Using this approach, the mean  
2465 ionisation rate of a charged particle traveling through a material medium is (using  
2466 natural units  $G = \hbar = c = 1$ ):

$$\left\langle \frac{dE}{dx} \right\rangle = \frac{4\pi Ne^4}{m_e \beta^2} z^2 \left( \log \frac{2m_e \beta^2 \gamma^2}{I} - \beta^2 \right), \quad (8.1)$$

2467 where  $N$  is the number density of electrons in the medium,  $e$  the elementary charge,  $m_e$   
2468 is the electron mass,  $z$  the charge of the particle in units of  $e$ ,  $\beta$  is the velocity of the  
2469 particle,  $\gamma = (1 - \beta^2)^{-1}$  and  $I$  denotes the effective ionisation potential averaged over  
2470 all electrons. This relation is known as the Bethe-Bloch formula.

## 8.1. $dE/dx$ measurement in the TPC

From Eq. (8.1) one can see that the ionisation loss does not depend explicitly on the mass of the charged particle, that for non-relativistic velocities it falls as  $\beta^{-2}$ , then goes through a minimum and increases as the logarithm of  $\gamma$ . This behaviour at high velocities is commonly known as the relativistic rise. The physical origin of this effect is partly due to the fact that the transverse electromagnetic field of the particle is proportional to  $\gamma$ , therefore as it increases so does the cross section.

It was later understood that the relativistic rise could not grow indefinitely with  $\gamma$ . A way to add this feature in the Bethe-Bloch formula is by introducing the so-called density effect term. It accounts for the polarisation effect of the atoms in the medium, which effectively shield the electromagnetic field of the charged particle halting any further increase of the energy loss [102]. Denoting the correction as  $\delta(\beta)$ , one can rewrite Eq. (8.1) as:

$$\left\langle \frac{dE}{dx} \right\rangle = \frac{4\pi Ne^4}{m_e \beta^2} z^2 \left( \log \frac{2m_e \beta^2 \gamma^2}{I} - \beta^2 - \frac{\delta(\beta)}{2} \right). \quad (8.2)$$

In general, the form of  $\delta(\beta)$  depends on the medium and its state of aggregation, involving the usage of tabulated parameters and implicit relations [103].

Another standard method to compute the amount of ionisation a charged particle produces is the so-called photo-absorption ionisation (PAI) model proposed by Allison and Cobb [104]. Within their approach, the mean ionisation is evaluated using a semiclassical calculation in which one characterises the continuum material medium by means of a complex dielectric constant  $\epsilon(k, \omega)$ . However, in order to model the dielectric constant they rely on the quantum-mechanical picture of photon absorption and collision. Therefore, in the PAI model the computation of the ionisation loss involves a numerical integration of the measured photo-absorption cross-section for the relevant material.

In a particle physics experiment, the typical way of determining the energy loss per unit length as a function of the particle velocity is studying identified particles over a range of momenta. Once we have established this relation we can use it for other, unknown particles. In this sense, it makes sense to have a regular mathematical expression for this relation that one can use.

## Chapter 8. Particle ID in GArSoft

2498 It happens that neither the Bethe-Bloch theory nor the PAI model from Allison and  
2499 Cobb offer a close mathematical form for the ionisation curve. This is the reason why a  
2500 full parametrisation of the ionisation curves can be useful. A parametrisation originally  
2501 proposed for the ALEPH TPC [105] and later used by the ALICE TPC [106] group that  
2502 manages to capture the features of the ionisation energy loss is:

$$f(\beta\gamma) = \frac{P_1}{\beta^{P_4}} \left( P_2 - \beta^{P_4} - \log \left[ P_3 + \frac{1}{(\beta\gamma)^{P_5}} \right] \right), \quad (8.3)$$

2503 where  $P_i$  are five free parameters. Hereafter, we will refer to Eq. (8.3) as the ALEPH  
2504  $dE/dx$  parametrisation.

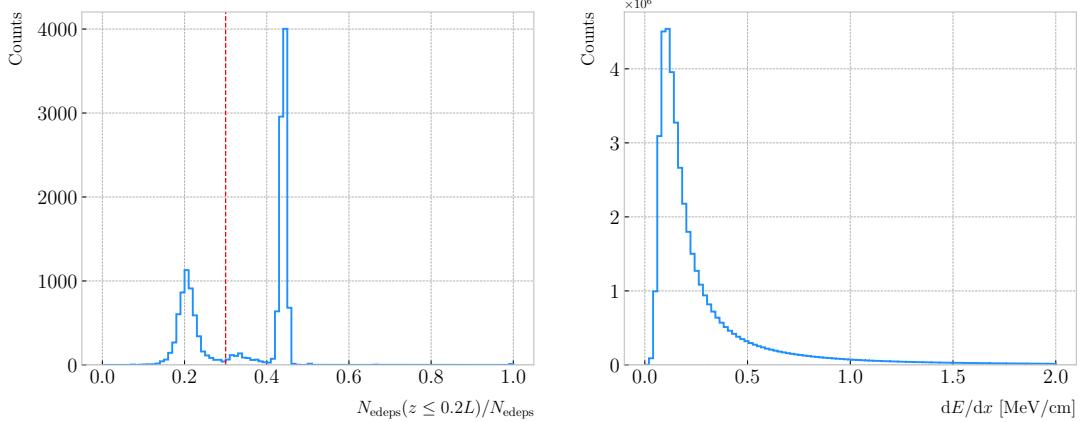
### 2505 8.1.1 Energy calibration

2506 In order to obtain the amount of energy loss by a charged particle due to ionisation  
2507 in our TPC we need to determine the conversion between the charge deposited in our  
2508 readout planes and the actual energy depositions. This procedure is known as energy  
2509 calibration.

2510 In a general, the first step of the calibration involves a non-uniformity correction,  
2511 to make sure that the detector response is uniform throughout the TPC. These are  
2512 typically divided into three categories, non-uniformities in the transverse  $YZ$  plane,  
2513 non-uniformities along the drift direction  $X$  and variations of the detector response  
2514 over time (would not apply to us as the detector is not built yet). These would correct  
2515 for effects such as electron diffusion and attenuation, space charge effects or channel  
2516 misconfiguration. However, because at the moment I am only interested in making sure  
2517 we recover a sensible result from our simulation, I will not apply uniformity corrections  
2518 to our charge deposits.

2519 Other effects, like electron-ion recombination or ADC saturation, lead to a non-linear  
2520 relation between the observed charge and the deposited energy in the detector, with the  
2521 observed readout charge saturating at high ionisation energies. In this case, because we  
2522 are dealing with gaseous argon and therefore recombination is not as important as in

## 8.1. $dE/dx$ measurement in the TPC



**Figure 8.1:** Left panel: distribution of the fraction of Geant4-level energy deposits per track with residual range less than 20% of the total track length, for the isotropic proton sample. Right panel: distribution of the ionisation per unit length of the energy deposits in the proton sample after removing the tracks with less than 30% of their energy deposits in the last 20% of the track.

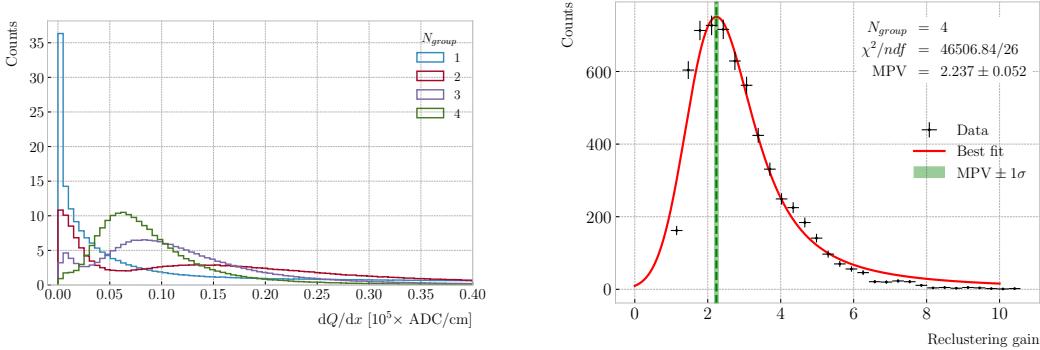
2523 liquid, we do not simulate recombination effects in the TPC. Even so, the simulation of  
 2524 the electronic response will still introduce charge saturation, and one needs to correct  
 2525 for it in order to obtain the exact amount of energy loss due to ionisation.

2526 By default, the track fitting algorithm in GArSoft provides a `TrackIonization`  
 2527 object associated to each reconstructed track. It contains two collections of charge  
 2528 deposits, one for each fitting direction, consisting on pairs of charge values ( $dQ$ , in ADC)  
 2529 and step sizes ( $dx$ , in cm).

2530 In order to estimate the ionisation loss in the ND-GAr TPC, I have used an MC  
 2531 sample consisting of single, isotropic protons propagating in the TPC. The starting points  
 2532 of the protons were sampled inside a  $50 \times 50 \times 25$  cm box centered at  $(100, -150, 1250)$ ,  
 2533 and their momenta are uniformly distributed in the range  $0.25 - 1.75$  GeV. I ran the  
 2534 simulated sample through GArSoft's default detector simulation and reconstruction, and  
 2535 then a custom analyser module that extracts the ionisation data together with other  
 2536 reconstructed track information from the Kalman fit.

2537 For studying the energy loss of the protons I select the reconstructed tracks that  
 2538 range out (i.e. slow down to rest) inside the TPC. A characteristic feature of the energy  
 2539 loss profile of any stopping ionising particle is the so-called Bragg peak, a pronounced

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**Figure 8.2:** Left panel: distribution of the reconstructed ionisation charge per unit length for our MC stopping proton sample. The different colors indicate how many consecutive  $dQ/dx$  pairs were grouped together. Right panel: distribution of the median change in  $dQ/dx$  per track after  $N_{group} = 4$  clusters were reclustered together.

peak that occurs immediately before the particle comes to rest. From Eq. (8.1) we can see that this behaviour is expected, as the energy loss for non-relativistic particles is inversely proportional to  $\beta^2$ . In data, a way of identifying the Bragg peak, and thus select the stopping particles, is checking the number of energy deposits towards the end of the track. In this case, I count the fraction of the Geant4 simulated energy deposits with a residual range value (the distance from a given energy deposit to the last deposit in the track trajectory) less than a 20% of the corresponding track length<sup>1</sup>. The distribution of this fraction of energy deposits for our proton sample is shown in Fig. 8.1 (left panel). We can clearly see two well separated peaks in this distribution, one centered at 0.2 and another, narrower, one centered at a higher value. The first one corresponds to non-stopping protons, as in that case the number of energy deposits towards the end of the track is uniformly distributed due to the absence of the Bragg peak. In that way, I apply a cut in this distribution, requiring that at least 30% of the simulated energy deposits sit in the last 20% of the tracks, to ensure that the Bragg peak is present.

Figure 8.1 (right panel) shows the distribution of the energy loss per unit length for the Geant4 simulated energy deposits of the selected stopping protons. We can see that

<sup>1</sup>As we are applying this selection at the Geant4 level we could have simply selected the stopping protons using the `EndProcess` labels from the simulation. However, the Bragg peak identification method displayed here could serve as a starting point for a selection of stopping protons in real data.

## 8.1. $dE/dx$ measurement in the TPC

it follows the expected shape of a Landau distribution, which describes the fluctuations of the ionisation energy losses [107]. This distribution has a characteristic asymmetric PDF, with a long right tail that translates into a high probability for high-energy ionisation losses. The origin of these fluctuations is mainly the possibility of transferring a high enough energy to an electron, so it becomes a ionising particle itself.

Now, from the point of view of the reconstruction, the objects that we have available to extract the ionisation information for the different reconstructed tracks are the collections of  $dQ$  and  $dx$  pairs, as stated before. The  $dQ$  values come from adding up the amplitude of all the reconstructed hits in a cluster, which is the input object to the Kalman fit.

Figure 8.2 (left panel) shows the distribution of the ionisation charge deposits per unit length for the track in the stopping proton sample (blue line). As one can notice, this distribution does not resemble the expected shape of the Landau PDF. This distribution peaks sharply at 0 and has a heavy tailed behaviour. Notice, however, how the distribution changes its shape as we group together  $N_{group}$  consecutive charge deposit pairs (red, purple and green lines). The distribution in the  $N_{group} = 4$  case already has a shape which resembles that of the Geant4-level ionisation per unit length, so I will proceed using this amount of reclustering for the reconstruction-level depositions.

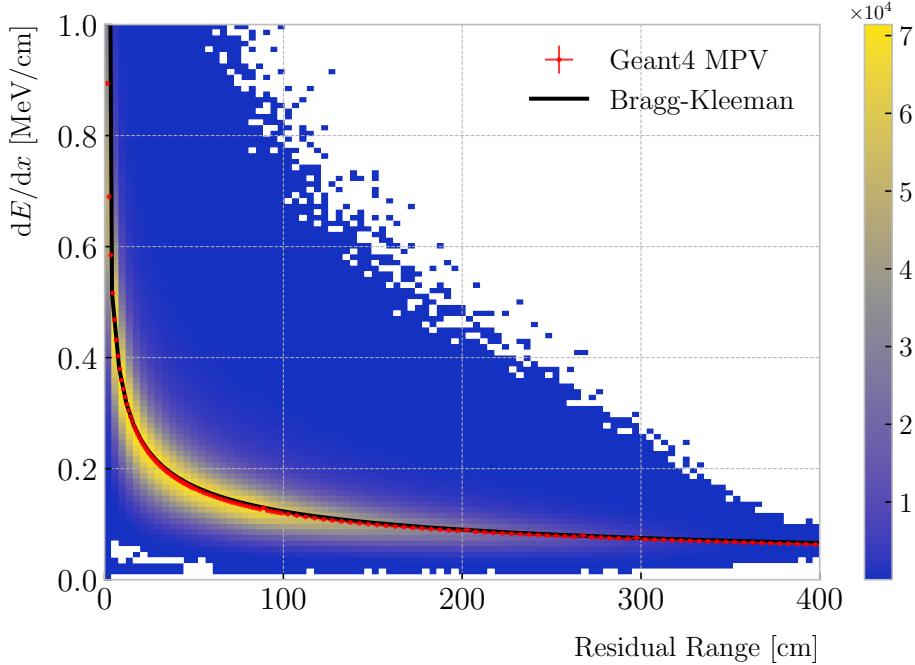
An extra factor I need to account for, when reclustering is applied, is how the overall  $dQ/dx$  per track changes. To do so, we can look at the ratio between the median  $dQ/dx$  after and before the reclustering. Figure 8.2 (right panel) shows the median enhancement in  $dQ/dx$  per track for the stopping proton sample in the case  $N_{group} = 4$ . Fitting a Landau distribution convolved with a Gaussian<sup>2</sup>, I estimate the most probable value of this ratio to be  $G_{group} = 2.24 \pm 0.05$ .

At this point, I am left with determining the conversion between the charge deposits per unit length  $dQ/dx$  and the energy deposits per unit length  $dE/dx$ . To this end, we need a way of comparing the two. I can use the residual range  $z$  to get a prediction of

---

<sup>2</sup>In the literature, this distribution is often referred to as Landau+Gaussian or langau. In the following, I will use LanGauss to refer to such PDF.

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**Figure 8.3:** Distribution of the Geant4-simulated energy losses per unit length versus residual range for the stopping proton sample. The overlaid points represent the fitted most probable value of the  $dE/dx$  distribution in each residual range bin, whereas the curve is their best fit to the Bragg-Kleeman formula from Eq. (8.4).

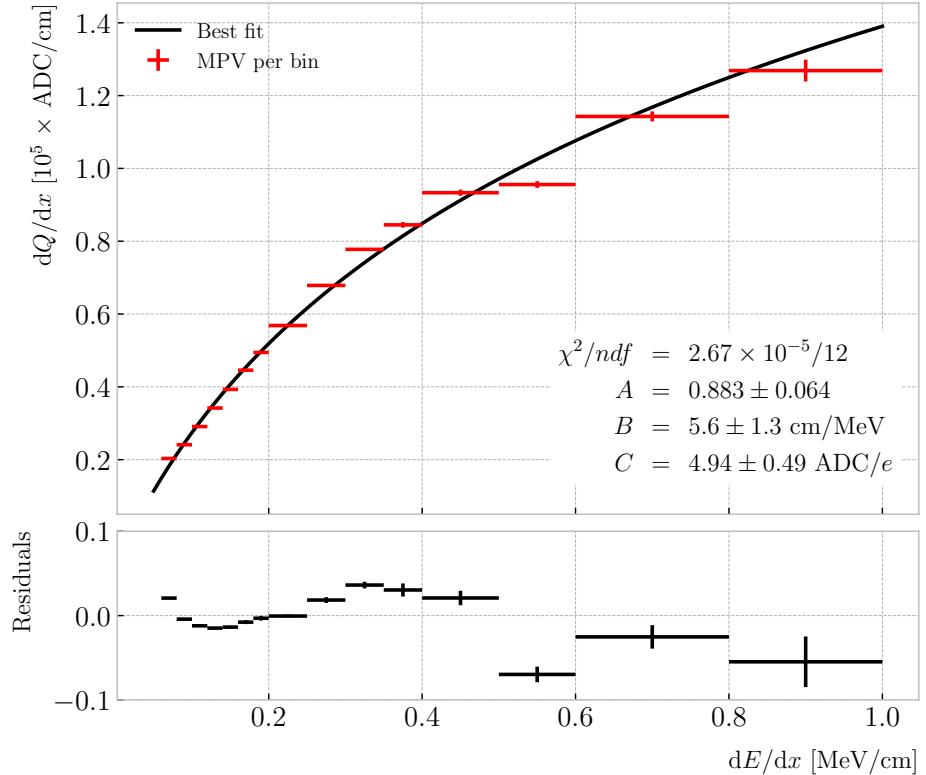
2584 the most probable  $dE/dx$  by using the following empirical parametrisation [108]:

$$\frac{dE}{dx}(z) = \frac{z^{\frac{1}{p}-1}}{p\Lambda^{\frac{1}{p}}}, \quad (8.4)$$

2585 which is quoted in the literature as the Bragg-Kleeman formula. In order to obtain the  
 2586  $p$  and  $\Lambda$  parameters I perform a fit using the energy losses and the residual ranges given  
 2587 by the Geant4 stage of our proton sample.

2588 Within our simulation, the residual range is sampled with a maximum size of  
 2589 5 mm. Therefore, to perform the fit to the Bragg-Kleeman formula, we can use a  
 2590 fine-grained residual range binning. For each of the residual range bins I extract the  
 2591  $dE/dx$  distribution and fit it to a LanGauss distribution, to obtain the value of the  
 2592 most probable  $dE/dx$  in the bin together with a statistical uncertainty. I then fit Eq.  
 2593 (8.4) to these most probable values and the centres of the residual range bins. This

## 8.1. $dE/dx$ measurement in the TPC



**Figure 8.4:** Fitted most probable  $dQ/dx$  values for each  $dE/dx$  bin (red points), obtained from the stopping proton sample. The overlaid curve (black line) represents the best fit to the logarithmic calibration function from Eq. (8.5).

procedure is depicted in Fig. 8.3, where I show the distribution of the energy loss per unit length versus the residual range, together with the most probable  $dE/dx$  values and their uncertainty in each bin (red points) and the curve with the best fit of the Bragg-Kleeman relation to those values (black line). The best fit is obtained for the parameter values  $p = 1.8192 \pm 0.0005$  and  $\Lambda = 0.3497 \pm 0.0008$  cm/MeV<sup>3</sup>.

Having an analytical expression that relates the residual range to  $dE/dx$ , I can take our reconstruction-level residual ranges from the stopping proton sample and compute the most probable energy loss associated.

In order to parametrise the charge saturation, we can use the following logarithmic

---

<sup>3</sup>These strange units for  $\Lambda$  come from dimensional analysis, just to keep the Bragg-Kleeman formula (8.4) consistent.

## Chapter 8. Particle ID in GArSoft

2603 function inspired by the modified box model for recombination:

$$\frac{dE}{dx} = \frac{e^{\frac{dQ}{dx}B\frac{W_{ion}}{G_{group}C}} - A}{B}, \quad (8.5)$$

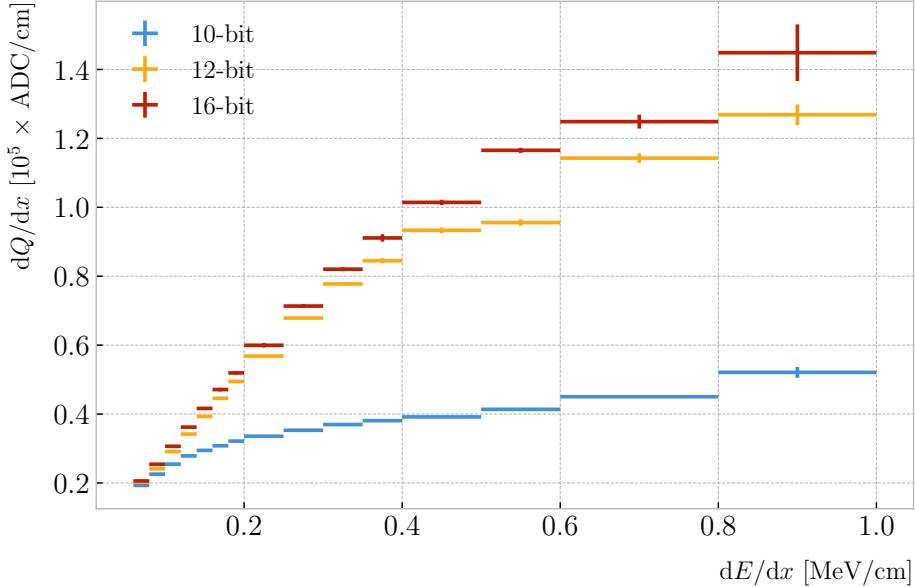
2604 where  $A$  and  $B$  are the calibration parameters we need to determine,  $W_{ion}$  is the average  
 2605 energy to produce an electron-ion pair,  $G_{group}$  is the gain from the reclustering discussed  
 2606 above and  $C$  is the calibration constant to convert number of electrons to ADC counts,  
 2607 commonly refer to as gain (also to be obtained in the fit). In this case, I use a value  
 2608 for the electron-ion production energy of  $W_{ion} = 26.4$  eV [109]. This value, used in our  
 2609 simulation as well, was measured for gaseous argon in normal conditions, and therefore  
 2610 should be checked in the future to describe correctly the high-pressure argon-CH<sub>4</sub> mixture  
 2611 of ND-GAr.

2612 For the calibration fit I follow a procedure similar to the previous one for Eq. (8.4).  
 2613 Binning the  $dE/dx$  range, I fit a LanGauss distribution to the corresponding  $dQ/dx$   
 2614 distribution to obtain the most probable value. The resulting data points (red bars) are  
 2615 shown in Fig. 8.4 (top panel), the horizontal error bars depict the width of the  $dE/dx$   
 2616 bin whereas the vertical bars represent the error associated to the most probable value  
 2617 estimation. A fit to the logarithmic function in Eq. (8.5) is also shown (black line).  
 2618 For this I weighted the data points using the inverse of their relative error, obtaining  
 2619 a reduced chi-square value of  $\chi^2/ndf = 2.22 \times 10^{-6}$ . The best fit parameters I found  
 2620 from this fit are  $A = 0.883 \pm 0.064$ ,  $B = 5.6 \pm 1.3$  cm/MeV and  $C = 4.94 \pm 0.49$  ADC/e.  
 2621 Figure 8.4 (bottom panel) shows the residuals between the data points and the fit.

2622 The value for the gain I obtained from the fit is in reasonable agreement with our  
 2623 expectation. This value is set in GArSoft to 5 ADC/e by default.

2624 One interesting thing to check is what induces this non-linear relation between charge  
 2625 and energy. The only effects that modify the amount of electrons reaching the readout  
 2626 planes in the simulation are the transverse diffusion and the finite electron lifetime.  
 2627 Once the electrons reach the readout chambers, the pad response functions are applied,  
 2628 together with an electrons-to-ADC conversion and the ADC saturation limit.

## 8.1. $dE/dx$ measurement in the TPC



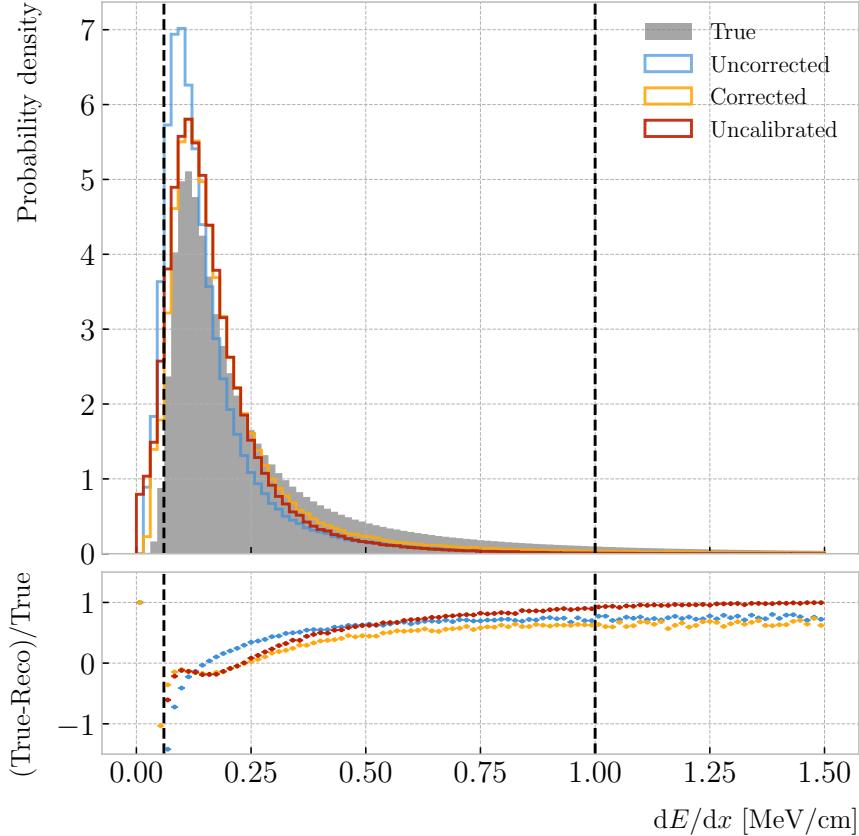
**Figure 8.5:** Fitted most probable  $dQ/dx$  values for each  $dE/dx$  bin for three different ADC bit limits, 10 (blue points), 12 (default, yellow points) and 16-bit (red points).

**Table 8.1:** Calibration parameters obtained from the fit of the ND-GAr simulated stopping proton sample to the calibration function from Eq. (8.5). The fits were performed for the 10, 12, and 16-bit ADC limits.

	$\chi^2/ndf$	Best fit $\pm 1\sigma$		
		A	B (cm/MeV)	C (ADC/e)
10-bit	$1.83 \times 10^{-6}/12$	$-9.3 \pm 3.9$	$270 \pm 69$	$27.1 \pm 5.4$
12-bit	$2.67 \times 10^{-5}/12$	$0.883 \pm 0.064$	$5.6 \pm 1.3$	$4.94 \pm 0.49$
16-bit	$1.44 \times 10^{-5}/12$	$0.949 \pm 0.024$	$3.53 \pm 0.58$	$4.52 \pm 0.29$

By default, GArSot applies a 12-bit ADC limit, which can be changed in the simulation configuration. However, it can only be increased up to 16-bit, as we represent the ADC collection as a `std::vector<short>`. This way, I tried to change the saturation parameter to see how it affects the relation between reconstructed charge and energy. Figure 8.5 shows a comparison between the most probable  $dQ/dx$  for 10, 12 and 16-bit ADC limits. As expected, the lower the limit is the sooner the charge saturates. For higher ADC limits the relation between energy and charge remains linear up to higher  $dE/dx$  values, but even for the 16-bit limit the saturation is noticeable for values  $\gtrsim 0.5$  MeV/cm.

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**Figure 8.6:** Top panel: area normalised  $dE/dx$  distributions for the true (solid grey) and the reconstructed energy deposits in the stopping proton sample, both after applying the calibration (blue) and the calibration and the normalisation correction (yellow). Also shown is the distribution obtained by applying a correction factor to the  $dQ/dx$  values but not the calibration (red). Bottom panel: fractional residuals for the uncorrected (blue), corrected (yellow) and uncalibrated (red) samples.

Table 8.1 shows the results of fitting the samples with 10 and 16-bits ADC limits to the calibration function from Eq. (8.5), using the weights based on their relative error as described previously. One interesting feature to notice is how different the best fit points look for the 10-bit ADC saturation when compared to the other two, which are consistent with each other.

At this point we can compare the  $dE/dx$  distribution one gets from Geant4, i.e. the true energy loss distribution, and the distribution I found by applying the calibration function to our collection of reconstructed  $dQ/dx$  values. Figure 8.6 (top panel) shows the true (solid grey) and reconstructed (blue, labeled as uncorrected) distributions

## 8.1. $dE/dx$ measurement in the TPC

2647 together. The dashed vertical lines indicate the region of validity of the calibration fit, i.e.  
2648 the left and right edges of the first and last  $dE/dx$  bin respectively. Notice that these  
2649 histograms are area-normalised, as the total number of true energy deposits is much  
2650 higher than the number of reconstructed charge deposits. This is due to a combination  
2651 of effects, like the finite spatial resolution of the detector, the hit clustering used in the  
2652 track fitting and the reclustering we have applied here.

2653 The two distributions are significantly different. That can be seen clearly when  
2654 looking at the fractional residuals, shown in Fig. 8.6 (bottom panel). In particular,  
2655 the position of the peak is off, which could bias the mean energy loss predictions. It  
2656 seems like the difference between these may be due to an overall scaling factor. One  
2657 possibility is to scale the most probable value of the reconstructed distribution to  
2658 the most probable value predicted by Geant4. I do this by fitting both distributions  
2659 using a LanGauss function, obtaining  $dE/dx_{MPV, true} = 0.1145 \pm 0.0005$  MeV/cm and  
2660  $dE/dx_{MPV, reco} = 0.0928 \pm 0.0005$  MeV/cm for the true and reconstructed most probable  
2661 values respectively. These can be translated into an scaling factor  $S = 0.579 \pm 0.006$ .

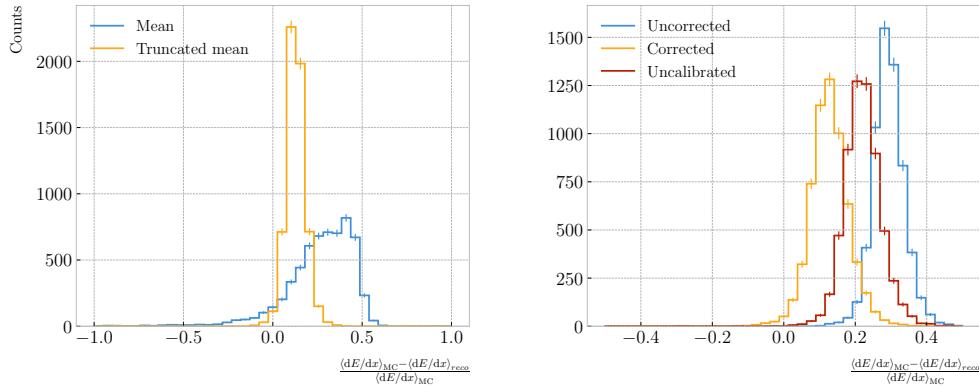
2662 The result of applying the scaling correction can be seen in Fig. 8.6 (top panel).  
2663 The corrected  $dE/dx$  distribution (yellow, labeled as corrected) peaks around the same  
2664 value the true distribution does, as expected. Moreover, the high energy region is also  
2665 slightly better described. For low ionisations, below the lower limit of the calibration  
2666 fit, the differences between true and reconstructed are still significant. This low energy  
2667 excess may be migration of some events from the peak region. The overall effect of the  
2668 correction can be seen in the fractional residual plot in Fig. 8.6 (bottom panel).

2669 One can also check what happens if instead of applying the logarithmic calibration we  
2670 simply scale the  $dQ/dx$  distribution (post reclustering) to have the same most probable  
2671 value as the true  $dE/dx$  distribution. In this case, following an analogous procedure to the  
2672 one described earlier, I found the scaling factor  $S_{uncalibrated} = 0.414 \pm 0.002$  MeV/ADC<sup>4</sup>.  
2673 The resulting distribution (red, labeled as uncalibrated) is also shown in in Fig. 8.6 (top  
2674 panel). The behaviour of the new distribution is similar to the corrected case at low

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<sup>4</sup>Notice that now the scaling factor is not dimensionless, as it acts more like a conversion factor here.

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**Figure 8.7:** Left panel: fractional residuals between the true and the corrected  $dE/dx$  means (blue) and the 60% truncated means (yellow), for each event in the stopping proton sample. Right panel: fractional residuals between the true and the uncorrected (blue), corrected (yellow) and uncalibrated (red)  $dE/dx$  60% truncated means, for each event in the stopping proton sample.

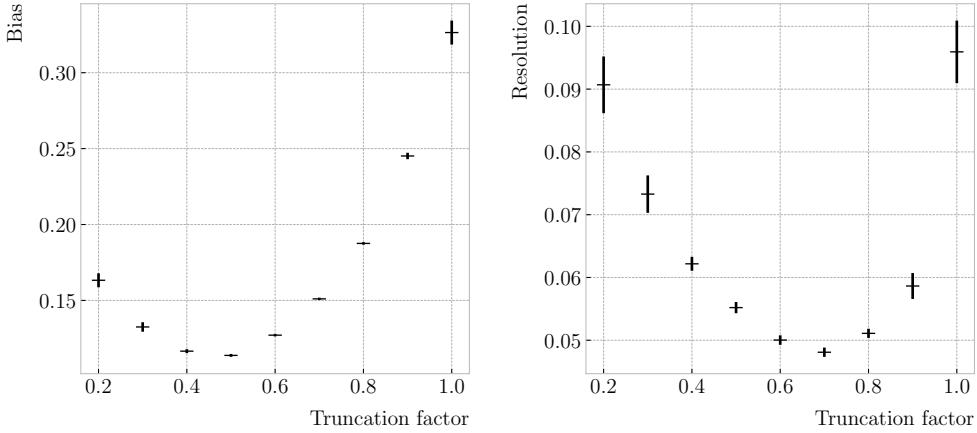
2675 energy losses, around the peak of the true distribution, but it is worse at describing the  
 2676 high energy tail. This is expected, it is in the high ionisation regime where saturation  
 2677 effects apply and therefore calibration is needed.

### 2678 8.1.2 Truncated $dE/dx$ mean

2679 Once we have a collection of  $dE/dx$  values for each reconstructed track, we can compute  
 2680 the corresponding most probable ionisation loss per unit length of the particle. This  
 2681 is the value predicted by the Bethe-Bloch or the PAI models, and together with a  
 2682 measurement of the momentum it allows for particle identification.

2683 However, estimating the most probable  $dE/dx$  value for each reconstructed track  
 2684 is not a trivial task. As mentioned before, the  $dE/dx$  distributions follow Landau-like  
 2685 distributions. Therefore, one should perform e.g. a LanGauss fit to correctly estimate  
 2686 the most probable values. Automating this kind of fits is often problematic, as they  
 2687 usually incur in convergence problems. Moreover, the reconstructed  $dE/dx$  distributions  
 2688 we obtain tend to have relatively small statistics, which may also produce poor fits. In  
 2689 practice, doing these unsupervised fits may degrade our performance, and a more robust  
 2690 method is preferred.

## 8.1. $dE/dx$ measurement in the TPC



**Figure 8.8:** Estimated values of the mean  $dE/dx$  bias (left panel) and resolution (right panel) obtained using the corrected data from the stopping proton sample, for different values of the truncation factor.

A possibility could be taking the mean of the reconstructed  $dE/dx$  distribution for each particle. The problem with this approach is that the high energy Landau tail, combined with our limited statistics, can induce large fluctuations in the computation of the mean. Imagine you have two protons with the same kinetic energy, but due to reconstruction problems in one case you did not get as many charge deposits reconstructed in its high ionisation loss region. If you do not remove the tails the computed  $dE/dx$  means will be significantly different.

In order to avoid those fluctuations, one can compute the mean of a truncated  $dE/dx$  distribution instead. By keeping only a given fraction of the lowest energy deposits we obtain an estimate of the mean energy loss that is more resilient to reconstruction inefficiencies and statistical effects. Figure 8.7 (left panel) shows a comparison between the  $\langle dE/dx \rangle$  computed by taking the mean of the full distribution (blue line) and the 60% lowest energy clusters (yellow line), for the stopping proton sample. The fractional residuals are computed for each proton, taking the corresponding means using their collections of true and reconstructed energy deposits. One can see that using the simple mean translates into a high bias and uncertainty in the  $\langle dE/dx \rangle$  estimation, whereas applying the truncation reduces both significantly.

Additionally, I performed a comparison between the 60% truncated mean  $dE/dx$

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2709 obtained using the different calibration methods discussed earlier, namely the uncorrected  
2710 (blue), corrected (yellow) and uncalibrated (red) distributions. The results are shown  
2711 in Fig. 8.7 (right panel). While the widths of these distributions are similar, the bias  
2712 obtained for the corrected sample, i.e. calibration function and correction factor applied,  
2713 is a factor of  $\sim 2$  lower than in the uncalibrated case and almost three times smaller  
2714 than for the uncorrected sample.

2715 The next step is to optimise the level of truncation we are going to apply to our  
2716 data. To do so, I used different truncation factors, i.e. the percentage of energy-ordered  
2717 reconstructed energy deposits we keep to compute the mean, on the corrected  $dE/dx$   
2718 sample of the stopping protons. Then, following the same procedure of computing the  
2719 fractional residuals as before, I fitted the resulting histograms using a double Gaussian  
2720 function. This is simply the sum of two Gaussian functions of the type:

$$g(x; \mu, \sigma, A) = A e^{-\frac{(x-\mu)^2}{2\sigma^2}}. \quad (8.6)$$

2721 I do not add the classical normalisation factor of the Gaussian,  $1/\sqrt{2\pi}\sigma$ , therefore  
2722 the amplitude  $A$  simply represents the maximum of the function. One of the two  
2723 Gaussian functions describes the core part of the distribution, while the other captures  
2724 the behaviour of the tails.

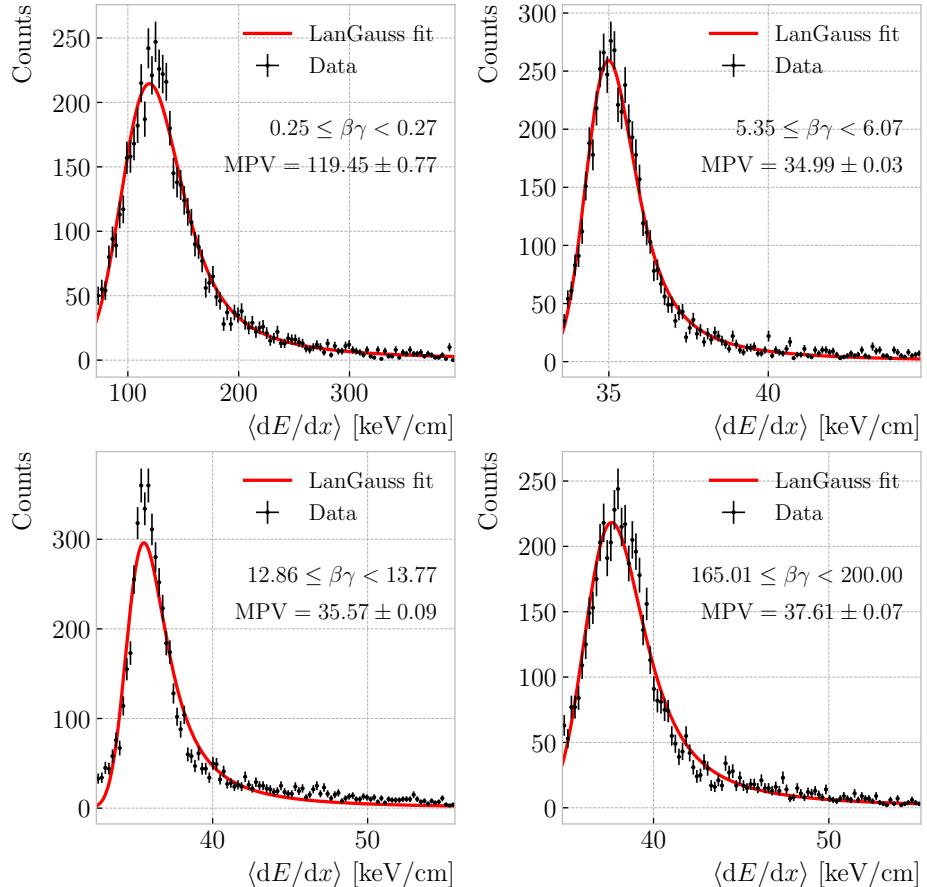
2725 For each truncation factor, I look at the bias and the resolution I obtain. I define  
2726 these as the weighted means of the corresponding parameters in the fits:

$$\bar{x} = \frac{A_{core} x_{core} + A_{tail} x_{tail}}{A_{core} + A_{tail}}, \quad (8.7)$$

2727 where  $A_{core}$  and  $A_{tail}$  are the amplitudes of the core and tail distributions respectively  
2728 and  $x$  is either the mean  $\mu$  or the width  $\sigma$  of said distributions.

2729 Figure 8.8 shows the bias (left panel) and the resolution (right panel) I obtained  
2730 for the stopping proton sample, using different values of the truncation. From these, it  
2731 can be seen that a truncation factor of 50% minimises the bias in the estimation, while

## 8.1. $dE/dx$ measurement in the TPC



**Figure 8.9:** Examples of the truncated mean  $dE/dx$  LanGauss fits for various  $\beta\gamma$  bins, from a simulated FHC neutrino sample.

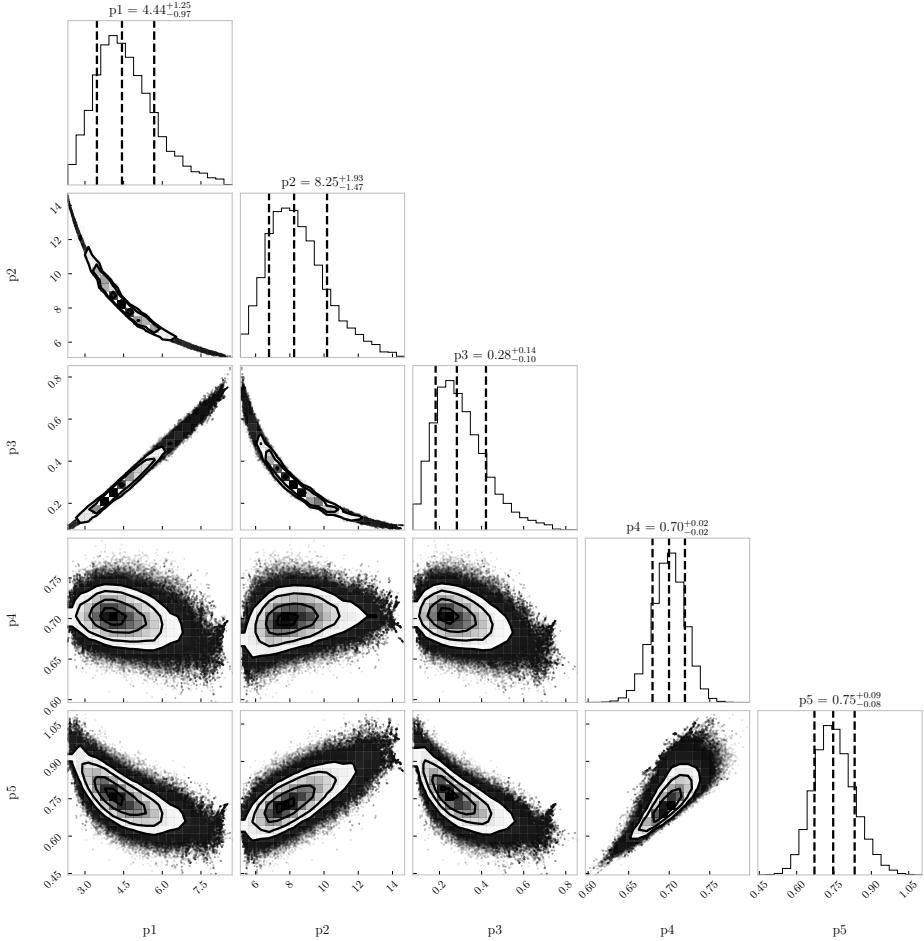
2732 70% gives the best resolution. That way, I settled on the intermediate value of 60%  
 2733 truncation, which yields a  $\langle dE/dx \rangle$  resolution of  $5.00 \pm 0.08$  % for stopping protons.

### 2734 8.1.3 Mean $dE/dx$ parametrisation

2735 Now that we have a way to estimate the mean energy loss of a particle in the HPgTPC,  
 2736 we can determine the value of the free parameters in the ALEPH formula, Eq. (8.3).  
 2737 For this, I used a sample of  $10^5$  reconstructed FHC neutrino events inside ND-GAr. In  
 2738 this case I cannot use the stopping proton sample, as we need to cover the full kinematic  
 2739 range of interest for the neutrino interactions in our detector.

2740 The original data does not contain an estimation of the velocity of the tracks, instead  
 2741 the tracks have a value for the reconstructed momentum and the associated PDG code

## Chapter 8. Particle ID in GArSoft



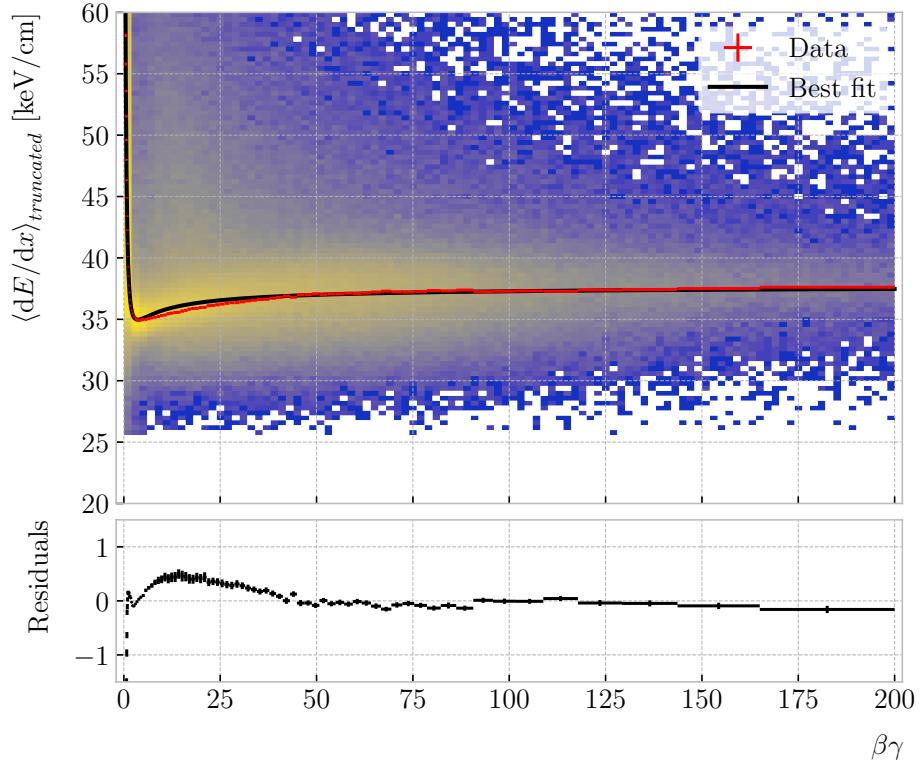
**Figure 8.10:** Resulting one and two dimensional projections of the posterior probability distributions of the ALEPH  $\langle dE/dx \rangle$  parameters obtained by fitting the 60% truncated mean  $dE/dx$  values from a FHC neutrino sample in ND-GAr. The vertical dashed lines in the 1D distributions represent the 16th, 50th and 84th percentiles.

2742 of the Geant4-level particle that created the track. Therefore, one can select some of the  
 2743 particles in the data, in this case I selected electrons, muons, pions and protons, and  
 2744 compute  $\beta$  and  $\gamma$  using the reconstructed momentum and their mass. In terms of  $\beta\gamma$   
 2745 the mean  $dE/dx$  does not depend on the particle species, so one can consider all the  
 2746 dataset as a whole. For this fit, I will express  $\beta$  in terms of the  $\beta\gamma$  product as:

$$\beta = \frac{\beta\gamma}{\sqrt{1 + (\beta\gamma)^2}}, \quad (8.8)$$

2747 which can be easily proven from the definition of  $\gamma$ .

### 8.1. $dE/dx$ measurement in the TPC

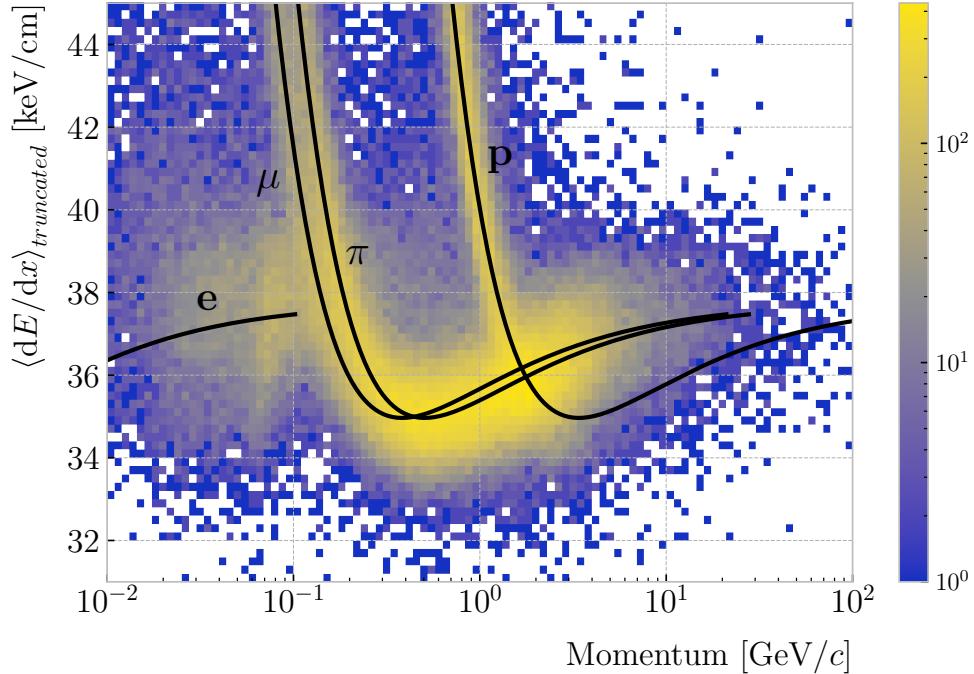


**Figure 8.11:** Truncated mean  $dE/dx$  obtained for the FHC neutrino sample as a function of the  $\beta\gamma$  product (upper panel). Also shown are the fitted most probable values for each  $\beta\gamma$  bin (red points) and the best fit obtained using the ALEPH parametrisation (black line). The residuals resulting from the fit are shown in the lower panel.

2748 Next, I bin the data in  $\beta\gamma$ . I chose a fine binning so as to capture the different  
 2749 features of the ionisation curve. Instead of fixing the bin width, I select them so each one  
 2750 has approximately the same statistics. Then, for each  $\beta\gamma$  slice, I compute the median  
 2751 and the interquartile range (IQR) of the  $\langle dE/dx \rangle$  distribution. Using these, I make a  
 2752 histogram in the range [median – IQR, median + 5 IQR], which I fit to a LanGauss  
 2753 function in order to extract the MPV. Using this range accounts for the asymmetric  
 2754 nature of the distributions, while also helps avoiding a second, lower maximum present  
 2755 at low  $\beta\gamma$ , probably a result of reconstruction failures.

2756 A few examples of these fits are shown in Fig. 8.9. The chosen values of  $\beta\gamma$  sit in  
 2757 very distinct points along the  $\langle dE/dx \rangle$  curve, going from the high ionisation region at  
 2758 low velocities (top left panel), to the minimum point (top right panel), the beginning of

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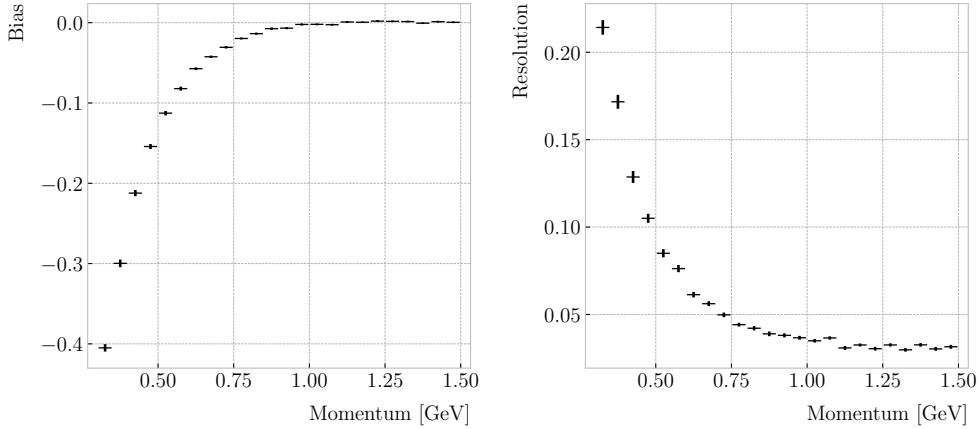
**Figure 8.12:** Distribution of the 60% truncated mean  $\langle dE/dx \rangle$  versus reconstructed momentum for the FHC neutrino sample. The black lines indicate the predictions of the ALEPH parametrisation for electrons, muons, charged pions and protons.

2759 the relativistic rise (bottom left panel), and the plateau produced by the density effect  
 2760 (bottom right panel).

2761 I used the resulting most probable  $\langle dE/dx \rangle$  values and the centres of the  $\beta\gamma$  bins as  
 2762 the points to fit to the ALEPH formula. For this particular fit I used the least-squares  
 2763 method to get a first estimation of the ALEPH parameters. Applying some uniform  
 2764 priors, I then used these values as the starting point of a 100000 steps MCMC. Figure 8.10  
 2765 shows the posterior probability distributions I obtain for each parameter. The reported  
 2766 best fit points are based on the 16th, 50th, and 84th percentiles in the marginalised  
 2767 distributions.

2768 The resulting fit (black line), compared to the data points (red points) and the  
 2769 underlying distribution is shown in Fig. 8.11 (top panel). The overall fit is good, with a  
 2770 reduced chi-squared of  $\chi^2/ndf = 1.02$ . However, there are some regions where the fit  
 2771 does not describe the data correctly, like the very low  $\beta\gamma$  regime, where the fit severely  
 2772 underestimates for energy losses  $\gtrsim 50$  keV/cm, and the start of the relativistic raise,

## 8.2. Muon and pion separation in the ECal and MuID



**Figure 8.13:** Estimated values of the mean  $dE/dx$  bias (left panel) and resolution (right panel) obtained for the true protons in a FHC neutrino sample.

where we have a slight overestimation. This is a result of those points having a larger uncertainty when compared to the ones around the dip or the plateau areas. These differences can be better seen in the residual plot, Fig. 8.11 (bottom panel).

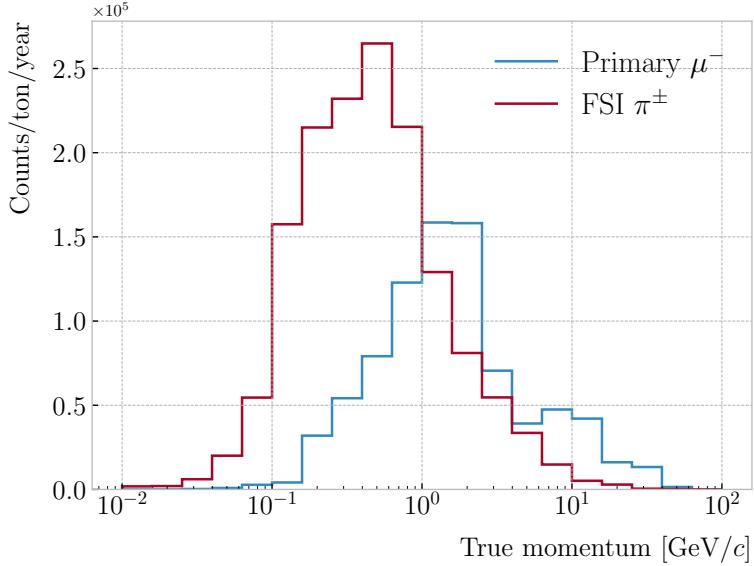
### 8.1.4 Particle identification

## 8.2 Muon and pion separation in the ECal and MuID

As it could be seen from Fig. 8.12, it is not possible to separate muons and charged pions in the HPgTPC using  $dE/dx$  for momenta  $\gtrsim 300 \text{ MeV}/c$ . In ND-GAr, approximately 70% of the interactions in FHC mode will be  $\nu_\mu$  CC (compared to the 47% of  $\bar{\nu}_\mu$  CC interactions when operating in RHC mode), while 24% are neutral currents. Out of these, around 53% and 47% of them will produce at least one charged pion in the final state, respectively. Figure 8.14 shows a comparison between the spectra of the primary muons and the charged pions for  $\nu_\mu$  CC interactions in ND-GAr producing one or more charged pions. From this, one can see that (i) the majority of muons and charged pions are not going to be distinguishable with a  $\langle dE/dx \rangle$  measurement, and that (ii) particle identification is necessary both to classify correctly the  $\nu_\mu$  CC events and identify the primary muon within them.

ND-GAr features two other subdetectors which can provide additional information

## Chapter 8. Particle ID in GArSoft



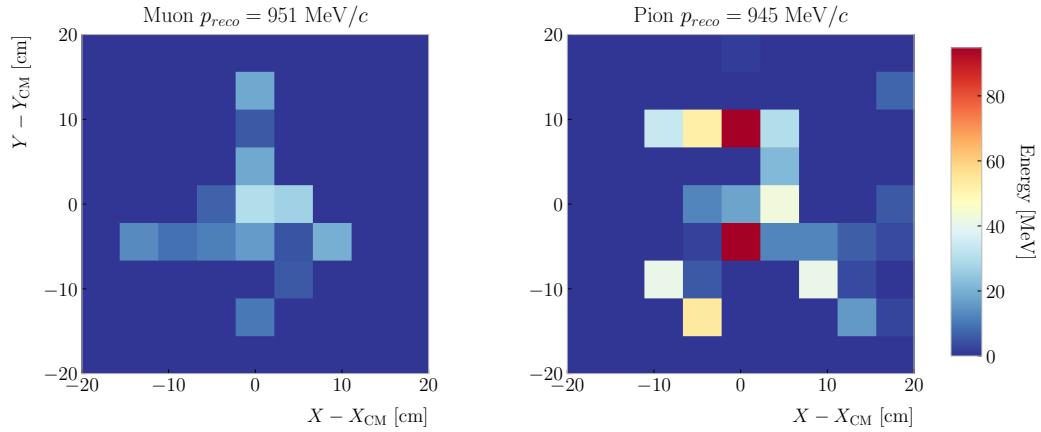
**Figure 8.14:** True momentum distribution for the primary muon in  $\nu_\mu$  CC  $N\pi^\pm$  interactions inside the fiducial volume of ND-GAr (blue line), compared to the post FSI charged pion spectrum (red line).

for this task, namely the ECal and MuID. The current ECal design, described in (ref section), consists of 42 layers, made of 5 mm of Pb, 7 mm of plastic scintillator and a 1 mm PCB board. The total thickness of this calorimeter is 1.66 nuclear interaction lengths or 1.39 pion interaction lengths. The MuID design is in a more conceptual stage, however it is envisioned to feature layers with 10 cm of Fe and 2 cm of plastic scintillator<sup>5</sup>. With its three layers, it will have a thickness of 1.87 or 1.53 nuclear or pion interaction lengths, respectively.

Because pion showers are dominated by inelastic nuclear interactions, the signatures of these particles in the calorimeter will look significantly different from those of muons. Although our ECal is not thick enough to fully contain the hadronic showers of the charged pions at their typical energies in FHC neutrino interactions, they can still be used to understand whether the original particle was more hadron-like or MIP-like. In Fig. 8.15 I show two examples of energy distributions created by a muon (left panel) and a charged pion (right panel) of similar momenta interacting in the ECal. These

<sup>5</sup>It is not mentioned anywhere, but I assume that there should also be another layer of PCB board of 1 mm. However, in this case its contribution to the total thickness of the sampling calorimeter would be negligible.

## 8.2. Muon and pion separation in the ECal and MuID



**Figure 8.15:** Distributions of energy deposits in the ECal for a muon (left panel) and a charged pion (right panel) with similar momenta. The energy is projected onto the plane perpendicular to the principal component of the hits, and the positions are relative to the center of the interaction.

2804 figures represent the transverse development of the interactions. For each of them, I  
 2805 computed the principal component and centre of mass of the interaction, projecting  
 2806 the position of the hits onto the plane perpendicular to that direction, and taking the  
 2807 distances relative to the centre. It can be seen that the muon follows an almost MIP-like  
 2808 behaviour, being the central bin in the histogram the one with the highest deposited  
 2809 energy. On the other hand, the pion not only deposits more energy overall, but also this  
 2810 energy is more spread-out among the different hits. It is this kind of information that  
 2811 would allow us to tell apart muons from pions.

2812 This way, I identify three main action points that need to be addressed if one wants  
 2813 to use these detectors to distinguish between muons and charged pions. These are:

- 2814 1. the way we make the associations between tracks in the HPgTPC to the activities  
 2815 (what in GArSoft we call clusters) in the ECal and the MuID,
- 2816 2. what variables or features one can extract from the calorimeters that encapsulate  
 2817 the information we are interested about,
- 2818 3. and how to carry out the classification problem.

## Chapter 8. Particle ID in GArSoft

### 2819 8.2.1 Track-ECal matching

2820 One of the main players in the muon and pion separation is the way we associate clusters  
2821 in the ECal to reconstructed tracks in the TPC. Missing some associations or making  
2822 wrong ones can bias the ECal quantities that we can use for classifying particles. The  
2823 current algorithm in GArSoft provides precise associations, i.e. most of the associations  
2824 that it produces are correct, but it appears to miss an important number of associations  
2825 (at least when using the default configuration).

2826 The current TPC track-ECal cluster association algorithm is divided in four parts.  
2827 It first checks whether the track end point fulfils certain conditions to be extrapolated.  
2828 There are two cut values in this step, one for the drift direction and other radial.

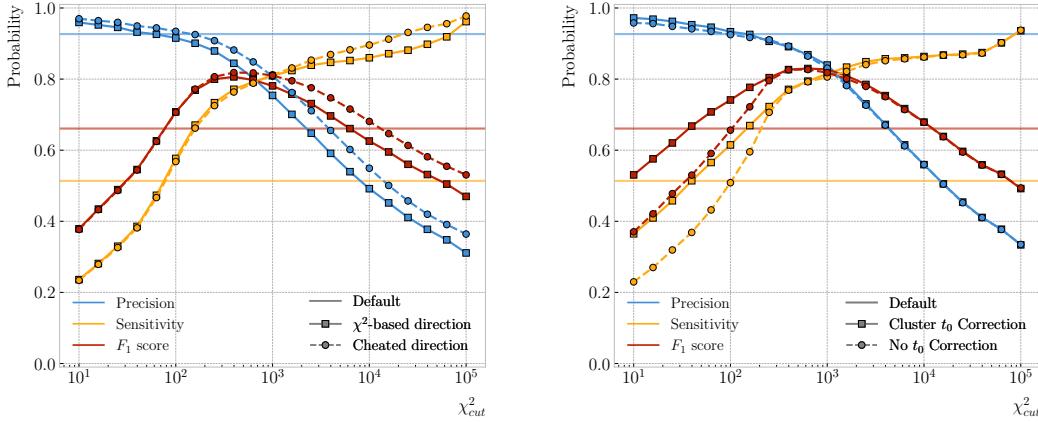
2829 If the point can be extrapolated, the code computes the coordinates of the centre  
2830 of curvature using the Kalman fit estimates at the track end ( $y, z, 1/R, \phi, \tan\lambda$ ). It  
2831 then compares the distance between this and the cluster in the  $(z, y)$  plane with  $R$ . This  
2832 introduces another cut in the perpendicular direction.

2833 The next step is different for clusters in the barrel or in one of the end caps. If it  
2834 is a barrel cluster the algorithm extrapolates the track up to the radial distance of the  
2835 cluster. There are three possible outcomes, the extrapolated helix can cut the cylinder  
2836 of radius  $r_{clus}$  two, one or zero times. I get the cut point that is closer to the cluster and  
2837 check that it is either in the barrel or the end caps. Computing the difference between  
2838 the  $x$  coordinates of the cluster and the extrapolated point, the module checks that this  
2839 is not greater than a certain cut. If the cluster is in an end cap, I propagate the track  
2840 up to the  $x$  position of the cluster. Then, the algorithm computes the angle in the  $(z, y)$   
2841 plane between the centre of curvature and the cluster,  $\alpha$ , and the centre of curvature  
2842 and the propagated point,  $\alpha'$ . A cut is applied to the quantity  $(\alpha - \alpha')R$ .

2843 If the cluster contains more than a certain number  $N$  of hits, I apply an extra cut to  
2844 the dot product of the direction of the track at the propagated  $x$  value and the cluster  
2845 direction.

2846 The code makes sure to only associate one end of the track (if any) to a cluster.

## 8.2. Muon and pion separation in the ECal and MuID



**Figure 8.16:** Left panel: comparison between the precision (blue), sensitivity (yellow) and  $F_1$  score (red) obtained for the default (horizontal lines) and new algorithms, both with the  $\chi^2$ -based direction estimator (squares) and cheating the directions (circles), for different values of the  $\chi^2$  cut. Right panel: comparison of the performance of the new algorithm when applying the cluster  $t_0$  correction (squares) and when (circles).

2847 However, it can associate more than one track to the same cluster. This makes sense,  
2848 as different particles can contribute to the same cluster in the ECal, but it makes it  
2849 difficult to quantify the relative contributions of the tracks to a certain cluster.

2850 As a way of comparing the performance of this algorithm, a new, simpler association  
2851 module was written. The goal was to have a simple and robust algorithm, which depends  
2852 on as few parameters as possible and that can produce a one-to-one matching between  
2853 tracks and ECal clusters.

2854 For each reconstructed track, the new algorithms applies the same procedure to the  
2855 forward and the backward fits irrespective of their end point positions. It first gets the  
2856 Kalman fit parameters at the corresponding end point together with the  $X$  position,  $x_0$ ,  
2857 ( $y_0$ ,  $z_0$ ,  $1/R$ ,  $\phi_0$ ,  $\tan\lambda$ ).

2858 For each ECal cluster, I compute the radial distance to the centre of the TPC and  
2859 find the  $\phi$  value in the range  $[\phi_0, \phi_0 + \text{sign}(R)\phi_{max}]$  that makes the propagated helix  
2860 intersect with the circle defined with such radius. The  $(x, y, z)$  position of the helix for  
2861 the  $\phi$  value found (if any) is then computed. In case there are two intersections, I keep  
2862 the one that minimises the distance between  $(y, z)$  and  $(y_c, z_c)$ .

2863 I then calculate  $\chi^2$  value based on the Euclidean distance between the propagated

## Chapter 8. Particle ID in GArSoft

2864 point and the cluster:

$$\chi^2/ndf = \frac{\sum_{n=0}^2 (x^{(n)} - x_c^{(n)})^2}{3}. \quad (8.9)$$

2865 If there was no intersection I store a  $-1$  instead. In the end, for each reconstructed track  
2866 in the event one ends up with two collections of  $\chi^2$  values, one for each ECal cluster  
2867 and fit directions.

2868 The current code only supports having ECal clusters associated to one end of each  
2869 track. We have two options to decide what track end to keep. The first one tries to  
2870 cheat the selection, looking at the distance between the two track ends and the true  
2871 start position of the associated MC particle. The second one keeps the track end with  
2872 more  $\chi^2$  entries below the cut.

2873 This feature of only considering one track end limits the algorithm, making it not  
2874 suitable for reconstructing events with particles originating outside the TPC. However,  
2875 as for the moment the main concern of the group is the study of neutrino interactions  
2876 off the gaseous argon, this is an acceptable assumption.

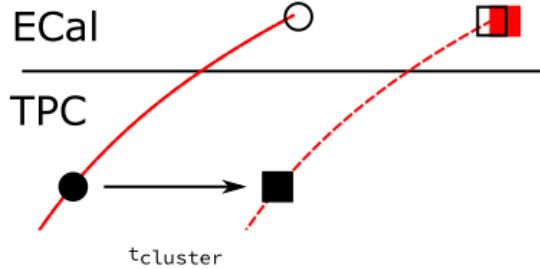
2877 In order to associate a cluster to a track, I take all clusters with a  $\chi^2$  value in the  
2878 range  $[0, \chi_{cut}^2]$ . If a cluster has been assigned to more than one track we leave it with  
2879 the one with the lowest  $\chi^2$ .

2880 This default behaviour of the algorithm can be modified to associate more than one  
2881 track to each cluster. Not only that, but the  $\chi^2$  values can be used to assign relative  
2882 weights to the different contributions.

2883 To evaluate the performance of the association method, I use a binary classification  
2884 approach. In this case, I check the leading MC Track IDs associated to the reconstructed  
2885 tracks and ECal clusters. I count an association as true positive (TP) if both Track  
2886 IDs coincide. An association is considered false positive (FP) when the Track IDs are  
2887 different. If a cluster has not been associated to any track but it shares the Track ID  
2888 with a reconstructed track it is counted as a false negative (FN).

2889 For the testing, I used a sample of 10000 FHC neutrino events inside the HPgTPC.  
2890 Figure 8.16 (left panel) shows the precision (blue line), sensitivity (yellow line), and  $F_1$

## 8.2. Muon and pion separation in the ECal and MuID



**Figure 8.17:** Schematics of a possible option to deal with track-ECal associations in non-zero  $t_0$  neutrino interaction events, trying to correct for the drift direction uncertainty in a cluster-by-cluster basis using the cluster time,  $t_{cluster}$ .

2891 score (red line) I obtained for different values of  $\chi^2_{cut}$ . For comparison, the same metrics  
 2892 computed for the default algorithm with the current configuration are also shown (dashed  
 2893 lines). In the case of the new algorithm, I used both the  $\chi^2$ -based method to estimate  
 2894 the track direction described earlier (square markers) and the cheated direction from the  
 2895 Geant-level information (circle markers). For either of these we achieve similar values of  
 2896 the precision compared to the old code, while having a considerably higher sensitivity.  
 2897 It can be seen that cheating the direction of the tracks only makes a difference at high  
 2898  $\chi^2_{cut}$ , past the optimal value of the cut around the  $F_1$  score maximum. Therefore, I set  
 2899 the  $\chi^2$  method as the default.

2900 One of the possible weak points of this approach is that it relies on the position along  
 2901 the drift direction to make the decisions. Within the current ND-GAr design implemented  
 2902 in GArSoft, the timing information is provided by the ECal. That effectively means  
 2903 that prior to make the track-ECal associations the reconstructed  $x$  positions of the track  
 2904 trajectories differ from the simulated ones by an amount:

$$x_{reco}^{(n)} - x_{sim}^{(n)} = v_{drift} t_0, \quad (8.10)$$

2905 where  $v_{drift}$  is the mean drift velocity in our medium and the initial time is in the range  
 2906  $t_0 \in [0, t_{spill}]$  where  $t_{spill}$  is the spill length. For a 10  $\mu\text{s}$  spill this translates into a  
 2907 maximum 30 cm uncertainty on the drift direction position.

2908 The current default in GArSoft sets  $t_0 = 0$ , but the functionality to randomly sample

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2909 this within the spill time is in place. Therefore, we need to understand what is the impact  
2910 of a non-zero  $t_0$  on the associations algorithm and foresee possible ways of minimising a  
2911 loss in performance.

2912 Figure 8.17 represents a possible option to tackle the association problem when  
2913 having events with a non-zero initial time  $t_0$ . The black and white circles represent the  
2914 original points, whereas the squares indicate the corrected positions. The end points of  
2915 the track and the propagated points up to the cluster radius are indicated using filled  
2916 and unfilled markers respectively. The red square represents the position of the cluster.

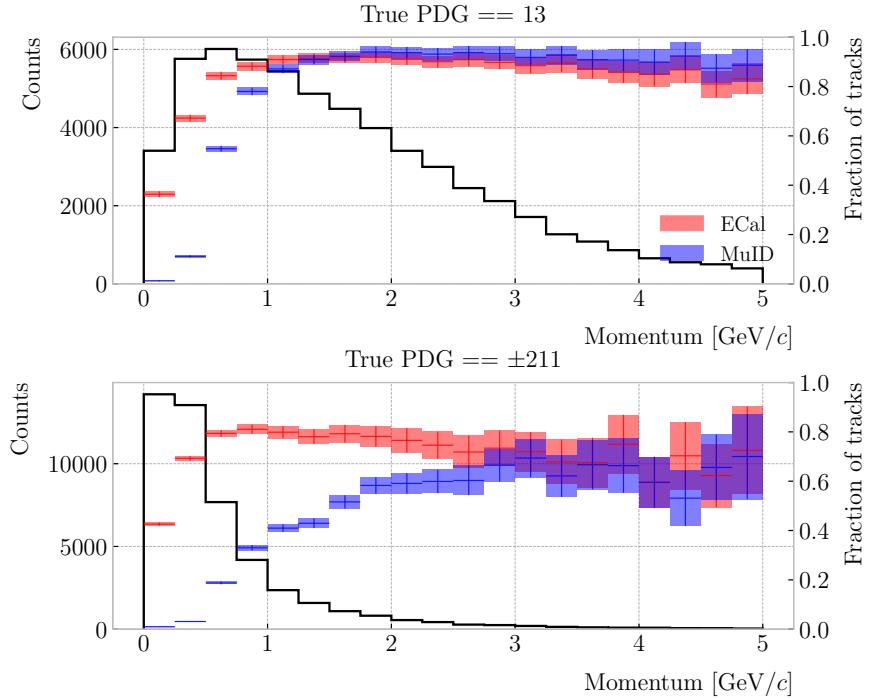
2917 Here I try to correct for the drift coordinate position using the time associated to the  
2918 cluster. Assuming that the drift time is much larger than the propagation time,  $t_{cluster}$   
2919 could be used as a good estimation of the  $t_0$ . An alternative can be using the earliest  
2920 time associated to a hit in said cluster. Doing this for each cluster before computing  
2921 the  $\chi^2$  value could be used as an alternative to knowing the specific value of the  $t_0$ , as  
2922 when the association is correct this will provide the right correction but its impact is  
2923 small enough to not change the position significantly in the case the cluster does not  
2924 correspond to a given track.

2925 I tested the effect of this correction again using a sample of 10000 FHC neutrino  
2926 events. Figure 8.16 (right panel) shows the precision (blue line), sensitivity (yellow line),  
2927 and  $F_1$  score (red line) for the case the cluster  $t_0$  correction is applied (square markers)  
2928 and for the no correction case (circle markers), as a function of  $\chi^2_{cut}$ . In this case, the  
2929 differences are particularly notorious at low values of the cut. It makes sense, as the  $t_0$   
2930 effect becomes subdominant when the distance we consider grows large. Overall, the  
2931 correction increases the sensitivity while keeping the precision almost unchanged. As a  
2932 result, I apply the  $t_0$  correction to the generated samples as the default.

### 2933 8.2.2 Classification strategy

2934 The problem of the muon and charged pion separation has to be viewed in the broader  
2935 context of the particle identification in our detector. Focusing on the beam neutrino  
2936 interactions, it is clear that we are going to have muons and pions spanning a broad

## 8.2. Muon and pion separation in the ECal and MuID

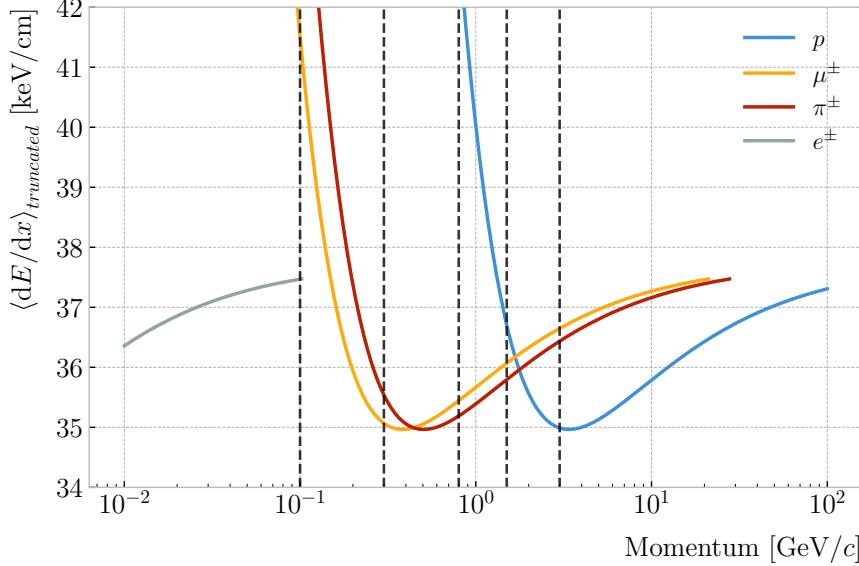


**Figure 8.18:** Momentum distribution for the reconstructed muons (top panel) and charged pions (bottom panel) in a FHC neutrino sample, together with the fraction of them reaching the ECal (red) and MuID (blue). Each entry corresponds to a reconstructed track, backtracked to a true muon or pion which has not produced any other reconstructed track.

2937 momentum range. Not only that, but we will also have other particles with similar  
 2938 characteristics that will make the classification even more challenging. Therefore, we are  
 2939 presented with a task that will depend heavily on the kinematic range we are looking at  
 2940 each time, as both the available information and the possible impurities of other particle  
 2941 species vary.

2942 For instance, distinguishing muons from pions could be difficult at low momenta, as  
 2943 a great number of them do not reach the ECal. Therefore, we could think of tailoring a  
 2944 version of the classification for that particular case, which could be complemented with  
 2945 a  $dE/dx$  measurement. Likewise, for momenta  $\gtrsim 1$  GeV muons and pions reach the  
 2946 calorimeters efficiently, but so do protons. Because of this, one can try to train another  
 2947 classifier for this energy range, and rely on other methods to remove as many of the  
 2948 protons as possible.

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**Figure 8.19:** Predicted truncated mean  $dE/dx$  versus momentum, for electrons, muons, charged pions and protons, obtained using the ALEPH parametrisation. The vertical dashed lines represent the boundaries of the six regions used for the muon and pion classification training.

2949     Figure 8.18 shows the momentum distribution of the reconstructed muons (top) and  
 2950     pions (bottom) in a FHC sample. It also contains the fraction of particles reaching the  
 2951     ECal (red) and MuID (blue), for the different momentum bins. In Fig. 8.19 I show the  
 2952     mean  $dE/dx$  of different particles as a function of the momentum, computed using the  
 2953     ALEPH parametrisation with the best fit parameters found in Subsec. 8.1.2.

2954     Using these two figures as references, I decided to approach the classification by  
 2955     dividing the problem into six different momentum regions. A summary of these can be  
 2956     found in Tab. 8.2. The basic idea is to exploit all the information that is available in  
 2957     each region and . For the problem at hand, I prepared separated samples of isotropic  
 2958     single muons and pions, with momenta uniformly distributed along the corresponding  
 2959     momentum range. Each sample contains 50000 events of the corresponding particle  
 2960     species. I did not generate samples for the first region, as it is assumed that the separation  
 2961     can be achieved using  $dE/dx$  only. For the last region, I generated particles up to a  
 2962     momentum of 10 GeV/c, as that is well above the typical energies of muons and pions  
 2963     from FHC neutrino interactions in ND-GAr.

## 8.2. Muon and pion separation in the ECal and MuID

**Table 8.2:** Momentum ranges and description of the PID approach assumed for the muon and pion classification task.

Momentum range	Description
$< 0.1 \text{ GeV}/c$	All tracks can be separated with $dE/dx$
$[0.1, 0.3) \text{ GeV}/c$	Use ECal for reaching muons and pions, $dE/dx$ for the rest
$[0.3, 0.8) \text{ GeV}/c$	Use ECal for muons and pions, $dE/dx$ for protons
$[0.8, 1.5) \text{ GeV}/c$	Use ECal and MuID for muons and pions, $dE/dx$ for protons
$[1.5, 3.0) \text{ GeV}/c$	Use ECal and MuID for muons and pions, ToF for protons
$\geq 3.0 \text{ GeV}/c$	Use ECal and MuID for muons and pions, $dE/dx$ and ToF for protons

2964        Additionally, I prepared another sample of 100000 FHC neutrino events. For each  
 2965      interaction, I select the reconstructed particles which were backtracked to true muons or  
 2966      charged pions. I use this dataset to perform validation checks, to see how the models  
 2967      trained with the single particle data generalise to a more realistic scenario.

2968        To tackle this classification problem, I make use of Boosted Decision Trees (BDT). A  
 2969      decision tree uses a flowchart-like structure to make decisions based on some input data.  
 2970      It starts from a root node, which represents the complete dataset, and then it splits  
 2971      this based on the variable or feature which gives the best separation between classes,  
 2972      creating two new nodes. The process repeats for each node until it reaches a certain  
 2973      limit, like a maximum number of splits or some tolerance criteria. The last set of nodes  
 2974      are often called leave nodes, and represent the final prediction of the classifier.

2975        Boosting refers to a family of methods to combine the predictions from multiple  
 2976      classifiers, following a sequential approach where each new model learns from the errors  
 2977      of the previous one. The process starts with a simple decision tree, which is used to  
 2978      make predictions on the training data. Then, the data points misclassified by the first  
 2979      model are assigned higher weights, and another decision tree is trained on the data with  
 2980      adjusted weights. The predictions of the two trees are then combined, and the cycle  
 2981      repeats for a predefined number of iterations. Gradient boosting uses the direction of  
 2982      the steepest error descent to guide the learning process and improve the accuracy with  
 2983      each iteration.

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### 2984 8.2.3 Feature selection and importance

2985 Using the reconstructed tracks as a starting point, I compute a number of ECal and  
2986 MuID variables for each of them. As there can be more than one cluster associated to a  
2987 track, what I do is collect all associated clusters and compute these variables from the  
2988 complete collection of associated hits. For the MuID, because it only features three layers  
2989 and typically there will be less hits, I also allow single hits to be associated with tracks<sup>6</sup>.  
2990 I can roughly divide the variables in three types: energy-related, geometry-related and  
2991 statistical. In the following, I briefly describe the variables related exclusively to the  
2992 ECal:

2993 • Energy-related ECal

- 2994 – ECal total energy (ClusterTotalEnergy): sum of the energy of all the ECal  
2995 hits.
- 2996 – Mean ECal hit energy (HitMeanEnergy): mean of the hit energy distribution.
- 2997 – Standard deviation ECal hit energy (HitStdEnergy): standard deviation of  
2998 the hit energy distribution.
- 2999 – Maximum ECal hit energy (HitMaxEnergy): maximum of the hit energy  
3000 distribution.

3001 • Geometry-related ECal

- 3002 – Mean distance hit-to-cluster (DistHitClusterMean): mean of the distance  
3003 distribution between the hits and the corresponding cluster's main axis.
- 3004 – RMS distance hit-to-cluster (DistHitClusterRMS): root mean square of the  
3005 distance distribution between the hits and the corresponding cluster's main  
3006 axis.
- 3007 – Maximum distance hit-to-centre (DistHitCenterMax): maximum of the  
3008 distance distribution between the hits and the centre of the TPC.

---

<sup>6</sup>At the reconstruction level what happens is that non-clustered hits are put into single hit clusters, instead of being thrown away. This is necessary to keep the consistency of the track-cluster association code.

## 8.2. Muon and pion separation in the ECal and MuID

- 3009        – Time-of-Flight velocity (TOFVelocity): slope obtained when fitting a straight  
3010                  line to the hit time versus hit distance to the centre (i.e.  $d = v \times t$ ).

3011        • Energy and geometry ECal

- 3012        – Radius 90% energy (Radius90E): distance in the hit-to-cluster distribution  
3013                  for which 90% of the total energy is contained in the hits that are closer to  
3014                  the axis (i.e. radius that contains 90% of the energy).

3015        • Statistical ECal

- 3016        – Number of hits (NHits): total number of hits associated to the track.  
3017        – Number of layers with hits (NLayers): not really a count of all layers with  
3018                  hits but the difference between the last and the first layer with hits.

3019        Figure 8.20 shows the distributions of three different ECal variables, separating true  
3020        muons (blue) and charged pions (red), for the five momentum ranges considered. I chose  
3021        to show one feature from each category, namely the mean energy per hit (left column),  
3022        the mean distance between the hits and the centre of the cluster (middle column), and  
3023        the number of ECal layers with hits (right column). These give an idea of the separating  
3024        power of the different features, and how it changes considerably with the energy. In  
3025        the number of layers with hits distributions, the peak at 6 is due to the fact that the  
3026        first six ECal layers sit inside the pressure vessel<sup>7</sup>. Therefore, some of the particles get  
3027        stopped crossing it, never making it to the seventh layer.

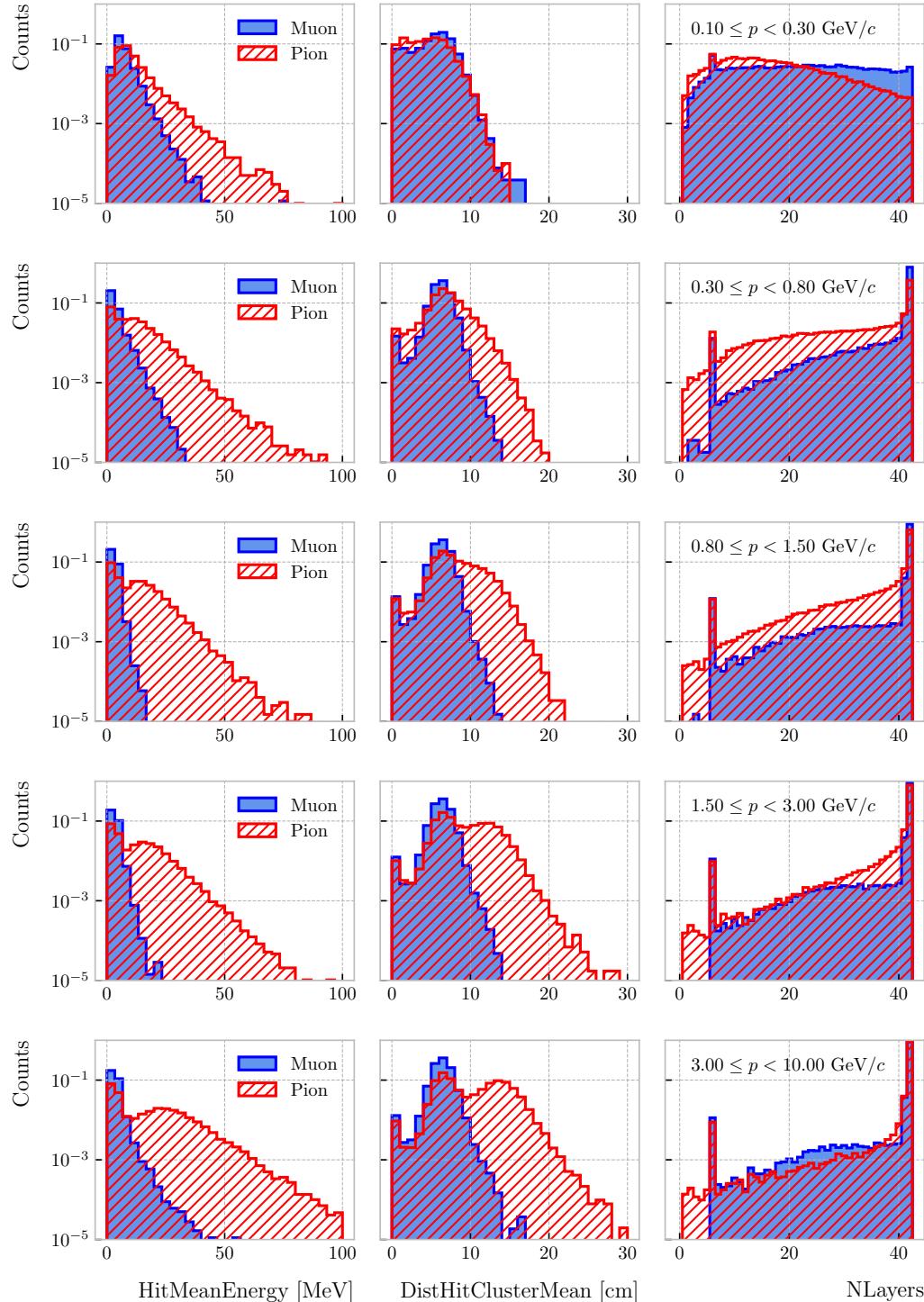
3028        In the case of the MuID, because at low momenta a significant fraction of the particles  
3029        do not make it past the ECal, I only consider the information coming from this detector  
3030        for momenta  $\geq 0.8$  GeV/ $c$ , i.e. for the last three momentum regions. The variables I  
3031        extract from it are the following:

3032        • Energy-related MuID

---

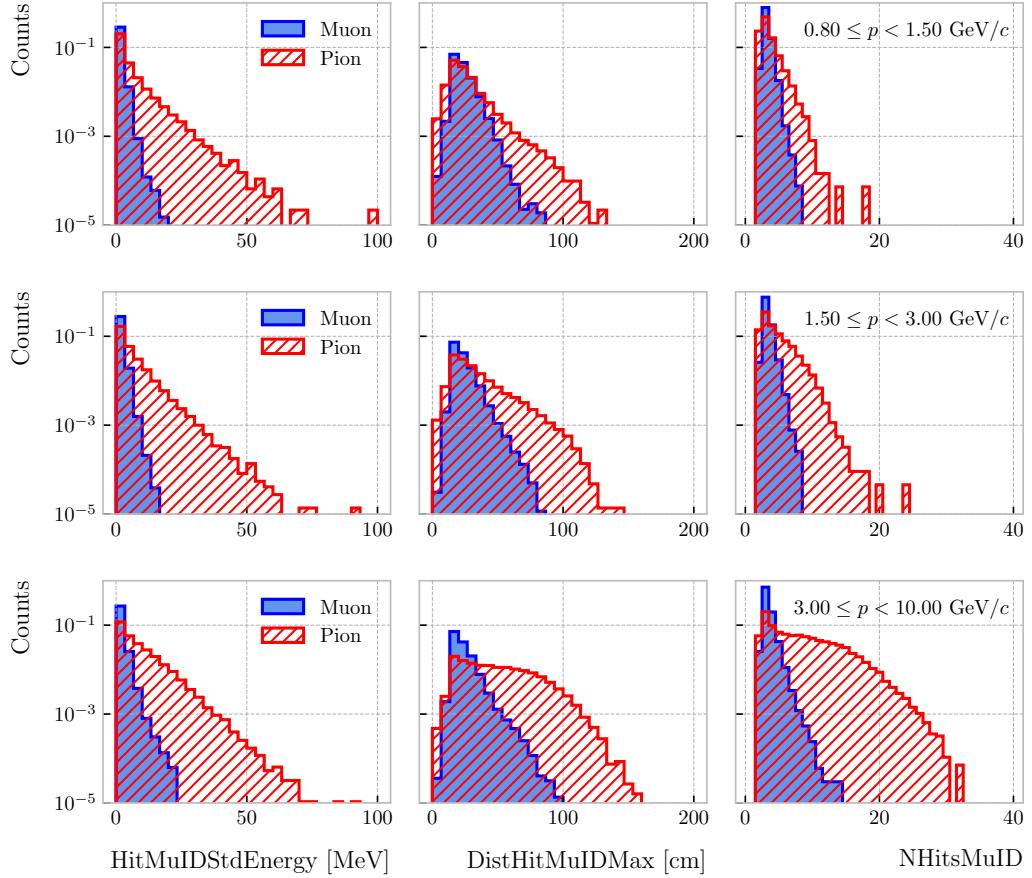
<sup>7</sup>Note to self: check this. I thought the ECal barrel had 8 layers of tiles, and that all of them were inside the pressure vessel.

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**Figure 8.20:** Example ECal feature distributions for muons (blue) and charged pions (red) in the five different momentum ranges considered (from top to bottom, in ascending momentum order). From left to right: mean hit energy, mean distance hit-to-cluster, and number of layers with hits.

## 8.2. Muon and pion separation in the ECal and MuID



**Figure 8.21:** Example MuID feature distributions for muons (blue) and charged pions (red) in the three different momentum ranges considered (from top to bottom, in ascending momentum order). From left to right: standard deviation hit energy, maximum distance hit-to-hit, and number of hits.

- 3033           – MuID total energy (ClusterMuIDTotalEnergy): sum of the energy of all the
- 3034            MuID hits.
- 3035           – Mean MuID hit energy (HitMuIDMeanEnergy): mean of the MuID hit energy
- 3036            distribution.
- 3037           – Standard deviation MuID hit energy (HitMuIDStdEnergy): standard deviation
- 3038            of the MuID hit energy distribution.
- 3039           – Maximum MuID hit energy (HitMuIDMaxEnergy): maximum of the MuID
- 3040            hit energy distribution.

- 3041           • **Geometry-related MuID**

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- 3042       – Maximum distance MuID hit-to-hit (DistHitMuIDMax): maximum distance  
3043            between pairs of MuID hits (not sure this is a good variable, distribution  
3044            looks nuts).  
3045       – Maximum distance MuID hit-to-centre (DistHitCenterMuIDMax): maximum  
3046            of the distance distribution between the MuID hits and the centre of the  
3047            TPC.

3048       • **Statistical MuID**

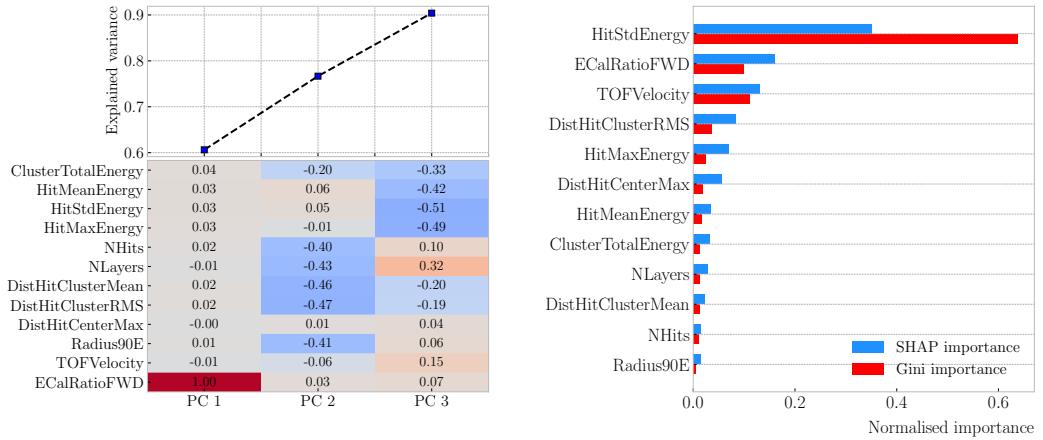
- 3049       – Number of hits (NHitsMuID): total number of MuID hits associated to the  
3050            track.  
3051       – Number of layers with hits (NLayersMuID): not really a count of all layers  
3052            with MuID hits but the difference between the last and the first layer with  
3053            MuIDhits.

3054       Figure 8.21 shows the distributions of three different MuID variables, separating true  
3055       muons (blue) and charged pions (red), for the three momentum ranges which use the  
3056       muon tagger information. In this case I decided to standard deviation of the MuID hit  
3057       energy distribution (left column), the maximum distance between the MuID hit pairs  
3058       (middle column), and the number of MuID hits (right column). These variables are used  
3059       together with the ECal features at high momenta, providing additional disambiguation  
3060       power.

3061       Once our features have been defined, one can do some exploratory analysis to  
3062       understand how well the variables describe the target class, and avoid the black-box  
3063       approach by what features are most relevant for the learning process. This way, I  
3064       performed a feature analysis for each of the momentum ranges I divided this classification  
3065       problem into. It follows three steps: first a principal component analysis (PCA), followed  
3066       by a feature importance study using Gini and Shapley values, and finally a feature  
3067       permutation importance analysis.

3068       The PCA is useful to understand the variance of the feature space. It is an  
3069       unsupervised machine learning technique that allows the user to perform a dimensionality

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**Figure 8.22:** Left panel: cumulative explained variance for the first three principal components (top panel) and contribution of the different features to the principal axes in feature space (bottom panel). Right panel: Shapley (blue) and Gini (red) feature importances for the different input features. Both figures correspond to the samples in the momentum range  $0.3 \leq p < 0.8$  GeV/c.

reduction. It uses a singular value decomposition of the input features to project them into a lower dimensional space. The idea is to find the matrix  $\mathbf{C}_m$ , whose columns are the first  $m$  orthonormal eigenvectors of the input covariance matrix. Consider the  $n \times p$  real matrix of input data  $\mathbf{X}$ , where  $n$  is the number of samples and  $p$  the number of features. If  $\mathbf{X}$  is centred, i.e. the means of its columns are equal to zero, we can write the covariance matrix of  $\mathbf{X}$  as  $\mathbf{C} = \mathbf{X}^\top \mathbf{X} / (n - 1)$ . This matrix can be diagonalised, yielding:

$$\mathbf{C} = \mathbf{V} \mathbf{L} \mathbf{V}^\top, \quad (8.11)$$

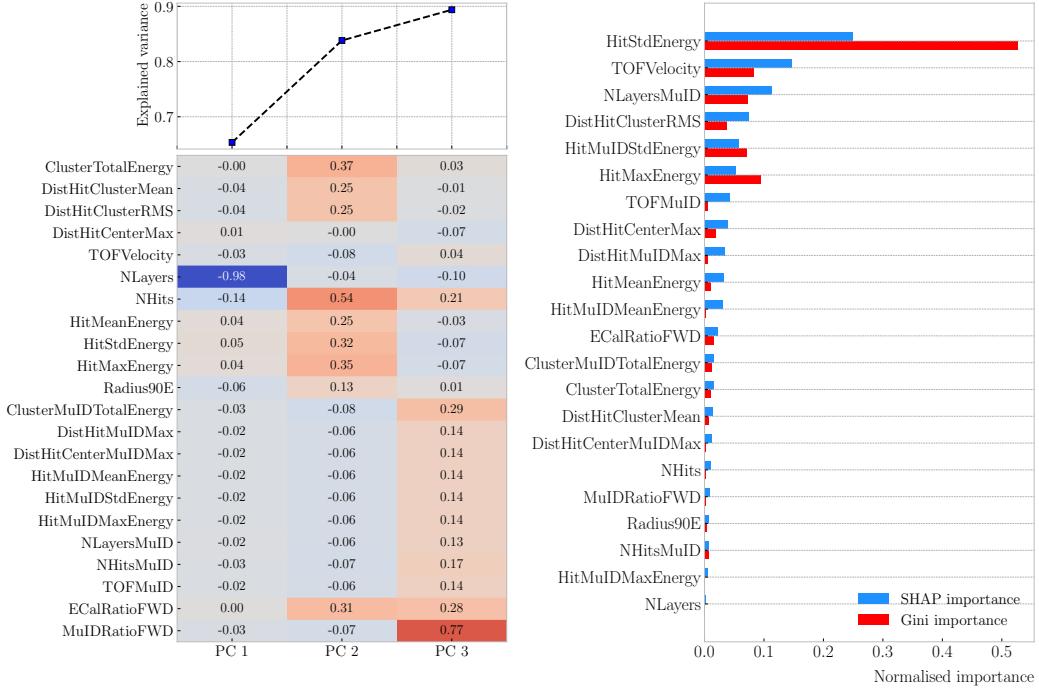
where  $\mathbf{V}$  is a matrix of eigenvectors and  $\mathbf{L}$  a diagonal matrix with eigenvalues  $\lambda_i$ . Then, performing SVD on  $\mathbf{X}$  gives us:

$$\mathbf{X} = \mathbf{U} \mathbf{S} \mathbf{W}^\top, \quad (8.12)$$

where  $\mathbf{U}$  is a unitary matrix, whose columns are called left singular vectors,  $\mathbf{S}$  is a diagonal matrix of single values  $s_i$ , and  $\mathbf{W}$  is another unitary matrix, its columns known as right singular vectors. This way, we can write:

$$\mathbf{C} = \mathbf{W} \mathbf{S} \mathbf{U}^\top \mathbf{U} \mathbf{S} \mathbf{W}^\top / (n - 1) = \mathbf{W} \frac{\mathbf{S}^2}{n - 1} \mathbf{W}^\top. \quad (8.13)$$

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**Figure 8.23:** Left panel: cumulative explained variance for the first three principal components (top panel) and contribution of the different features to the principal axes in feature space (bottom panel). Right panel: Shapley (blue) and Gini (red) feature importances for the different input features. Both figures correspond to the samples in the momentum range  $0.8 \leq p < 1.5 \text{ GeV}/c$ .

meaning that the right singular vectors are also the eigenvectors of the covariance matrix.

The SVD can be computed numerically following an iterative approach.

This way, taking an input data vector  $X \in \mathbb{R}^n$ , the resulting feature vector  $Y \in \mathbb{R}^m$

is given by:

$$Y = \mathbf{C}_m^\top X. \quad (8.14)$$

The new features capture most of the variance of the original sample, while being lower dimensional, as  $m < n$ .

Before applying the PCA reduction one needs to centre and scale the input data.

Centring is necessary when using SVD to obtain the eigenvectors of the covariance matrix, as only in that case we can do the identification with the right singular vectors from the input data. Scaling is needed when variables are on different scales, as some can then dominate the PCA procedure.

## 8.2. Muon and pion separation in the ECal and MuID

3092 I used the PCA module of `scikit-learn`, together with the `RobustScaler`, which  
 3093 centres the data and scales it based on the interquartile range. In Fig. 8.22 (left panel)  
 3094 and Fig. 8.23 (left panel) I show the results I obtained from the PCA for the momentum  
 3095 ranges  $0.3 \leq p < 0.8 \text{ GeV}/c$  and  $0.8 \leq p < 1.5 \text{ GeV}/c$ , respectively. Notice that in  
 3096 the second case the number of features increases considerably, as this is the first region  
 3097 which uses the MuID variables. I found that, in all the cases, adding a fourth PC does  
 3098 not add additional information. As it can be seen in the top panels of the figures, the  
 3099 cumulative explained variance is already over 80% with three PCs.

3100 The bottom panels show the contribution of the variables to the principal axes. For  
 3101 the two first momentum regions, I observe a tendency of the energy-related and the  
 3102 geometry-related ECal variables to be clustered together. For the other ranges, when  
 3103 I include the MuID variables, there seems to be a division between ECal and MuID  
 3104 variables. For these, it seems like the number of ECal layers with hits also plays an  
 3105 important role.

3106 The next step in the analysis is to quantify the importance of the features based on  
 3107 two additional metrics, namely the Gini and the Shapley values. The Gini importance,  
 3108 often called mean decrease impurity, is based on how much a feature contributes to the  
 3109 purity improvement at the splits in each decision tree. The purity is measured in terms  
 3110 of the Gini impurity index, defined as:

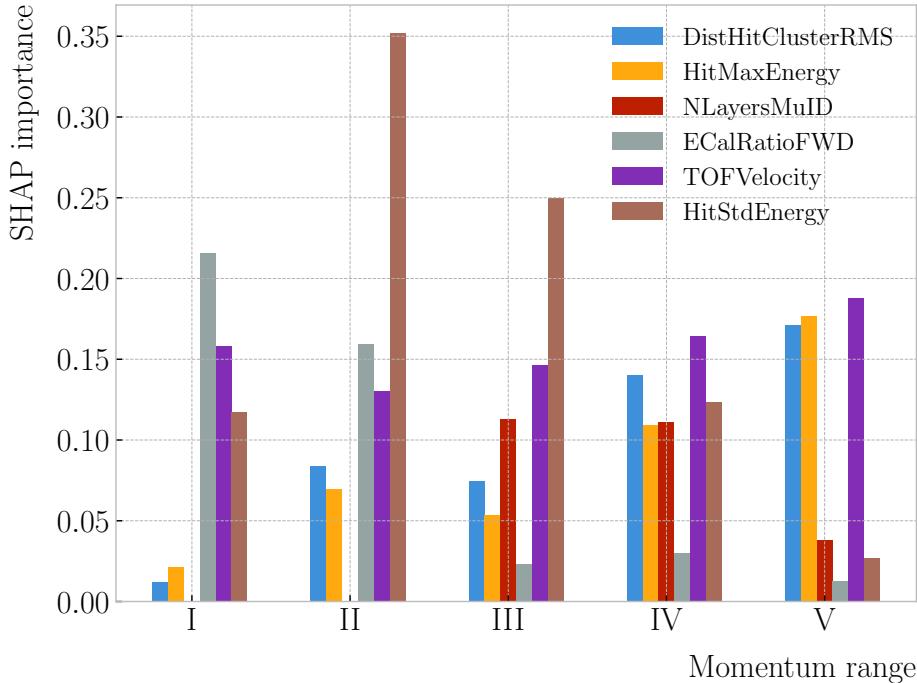
$$I_G = 1 - \sum_i f_i, \quad (8.15)$$

3111 where  $f_i$  is the fractional abundance of the  $i$ -th class. Then, for each split one can  
 3112 compute the weighted decrease in impurity as:

$$\Delta_G = \frac{N_t}{N} \left( I_G - \frac{N_t^R}{N_t} I_G^R - \frac{N_t^L}{N_t} I_G^L \right), \quad (8.16)$$

3113 where  $N$  represents the total number of samples,  $N_t$  the number of samples at the current  
 3114 node,  $N_t^R$  and  $N_t^L$  the number of samples in the right and left children respectively,

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**Figure 8.24:** Evolution of the SHAP importance for the top six most important features across all five momentum ranges.

3115  $I_G$  is the Gini impurity at the current node, and  $I_G^R$  and  $I_G^L$  the Gini impurities of the  
3116 resulting right and left children.

3117 For each decision tree, one will have a normalised vector with the accumulated  
3118 decrease in Gini impurity for each feature. In the case of a BDT, the feature importances  
3119 are simply the mean for all the estimators in the ensemble<sup>8</sup>.

3120 The concept of Shapley values originated in the context of game theory, and it  
3121 measures the marginal contribution of a feature in enhancing the accuracy of a classifier.  
3122 Take  $F$  to be the set of all features in a problem, and  $S \subseteq F$  the subset of features. To  
3123 compute the Shapley value of the  $i$ -th feature, one has to train a model with that feature  
3124 present,  $f_{S \cup \{i\}}$ , and another model trained without it,  $f_S$ . This has to be repeated for  
3125 all possible combinations of subsets  $S \subset F \setminus \{i\}$ , and evaluating the models predictions

---

<sup>8</sup>Note to self: this appears not to be the case. If you get the `feature_importance` for each tree in the BDT and take the average, the result is not the same to be one reported in the `feature_importance` attribute of the BDT.

## 8.2. Muon and pion separation in the ECal and MuID

3126 on the appropriate sets of data  $x_S$ . This way, the Shapley value results:

$$\varphi_i = \sum_{S \subset F \setminus \{i\}} \frac{|S|! (|F| - |S| - 1)!}{|F|!} [f_{S \cup \{i\}}(x_{S \cup \{i\}}) - f_S(x_S)]. \quad (8.17)$$

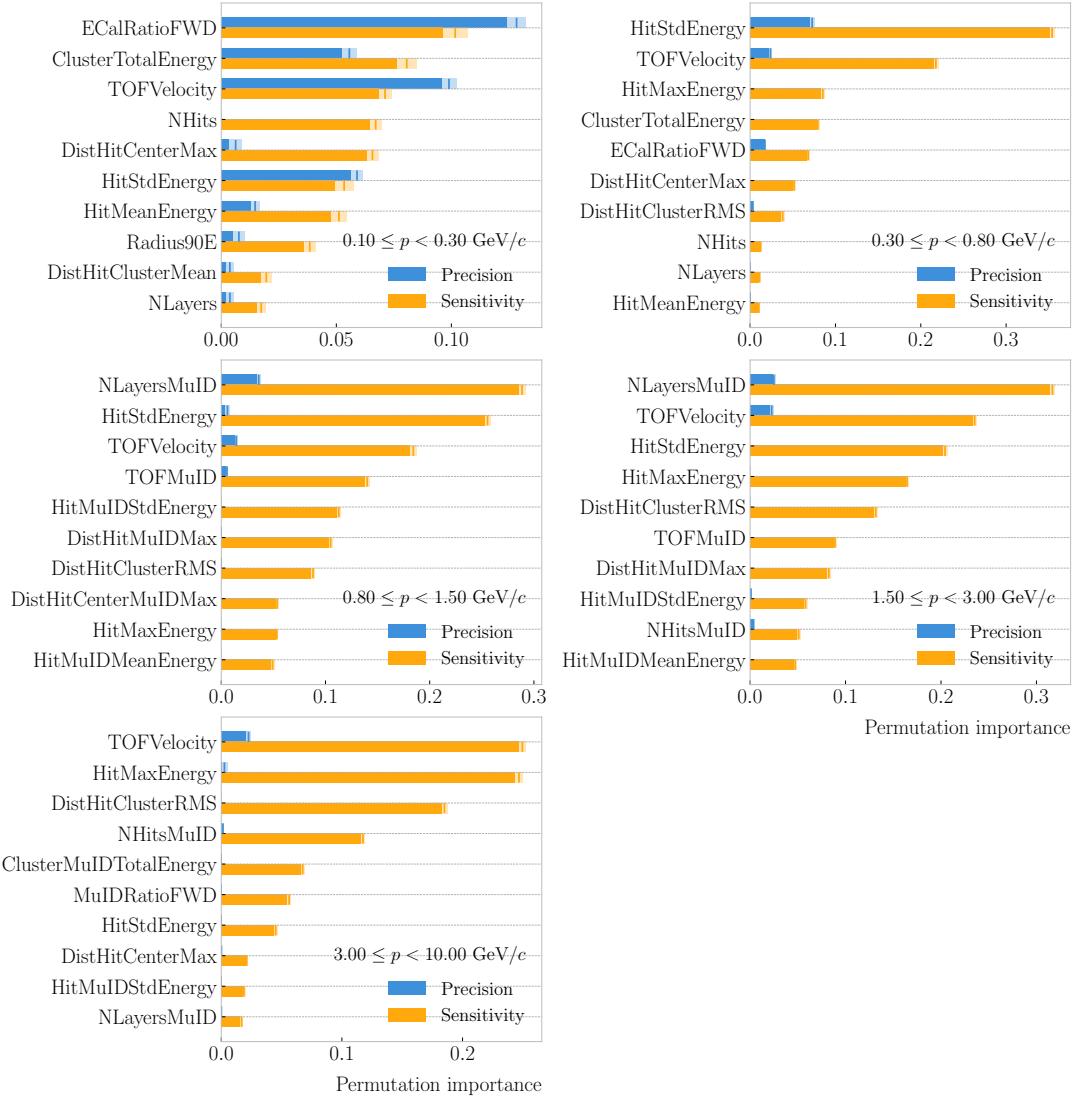
3127 I trained the `GradientBoostingClassifier` from `scikit-learn` with the default  
 3128 configuration in order to evaluate both the Gini and Shapley importances. The Gini  
 3129 scores are automatically computed by `scikit-learn`, using the training data. For the  
 3130 Shapley importance, I used the implementation from the `SHAP` package, computing  
 3131 it using the test sample. The results can be seen in Fig. 8.22 (right panel) and  
 3132 Fig. 8.23 (right panel), again for the momentum ranges  $0.3 \leq p < 0.8 \text{ GeV}/c$  and  
 3133  $0.8 \leq p < 1.5 \text{ GeV}/c$ . The length of the bars denote either the SHAP (blue) or the Gini  
 3134 (red) importance of the feature. One interesting thing to notice is that, when looking at  
 3135 the Gini importance, there is always one feature that dominates over the rest. This is  
 3136 not the case for the SHAP importance, where importances tend to be more balanced.

3137 Across all momentum ranges, I observe that the most important features are. For  
 3138 the five momentum ranges considered, only six variables sit in the top five at least once.  
 3139 Figure 8.24 shows the evolution of the SHAP importance of these six features. It is  
 3140 interesting to see that the time-of-flight variable keeps its importance almost unchanged  
 3141 for all momenta. Also, it looks like the ECal energy ratio gets less relevant the higher the  
 3142 momentum is, but the RMS of the hit-to-cluster distance distribution and the maximum  
 3143 ECal hit energy become more important in the last momentum ranges.

3144 The last step in the feature selection analysis is the feature permutation. This  
 3145 technique measures the contribution of each feature to the performance of a model by  
 3146 randomly shuffling its values and checking how some scores degrade. For the present  
 3147 case, I am interested in the precision or purity, and the sensitivity or efficiency, as these  
 3148 two are the most relevant metrics from a physics point of view. The `scikit-learn`  
 3149 module provides the user with a method to perform the permutation scans.

3150 The results of these are shown in Fig. 8.25. For the different momentum ranges  
 3151 I show the permutation importances for the ten most important features. For each

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**Figure 8.25:** Permutation importances for the ten most important features in the different momentum ranges (from left to right, top to bottom, in increasing momentum order). The bars indicate the effect that permutations of each feature have on the purity (blue) and the sensitivity (yellow), the translucent regions representing one standard deviation around the central value.

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3152 of the variables I report the effect the permutations have on the precision (blue) and  
3153 sensitivity (yellow) of the models. The bars indicate the importance value, with the  
3154 lighter part representing one standard deviation around the mean (hinted as an additional  
3155 vertical line). Something to notice is that, in the first momentum region, the feature  
3156 permutations have an effect on both the precision and the sensitivity. However, for the  
3157 rest the precision is almost unaffected, while the sensitivity changes are considerably  
3158 larger.

3159 It is also interesting to see that most of the variables identified as important here  
3160 are the same I found when looking at the Shapley values. The behaviour of these across  
3161 the momentum ranges is also similar, with the same patterns of some features being  
3162 important at low momenta and then dropping in importance for the high momentum  
3163 ranges.

3164 Wit this, I conclude the study of the features. I have prepared the training and  
3165 testing datasets and understood what features are likely to have the largest impact on  
3166 the performance of the classifiers.

### 3167 8.2.4 Hyperparameter optimisation

3168 Any BDT requires the user to specify a number of parameters that will dictate its  
3169 behaviour. They can be divided into two categories: (i) tree-specific parameters, which  
3170 affect each individual tree in the model, and (ii) boosting parameters, which control the  
3171 boosting operation in the model. The value of these so-called hyperparameters affect the  
3172 performance and predictive power of the models. Therefore, one needs to carefully select  
3173 their optimal values in order to extract as much information as possible from the data.

3174 From all the parameters used to define a tree in the `scikit-learn` implementation  
3175 of the BDT classifier, I only consider a subset of them. This is due to the fact that some  
3176 are mutually exclusive, but also because I noticed that others have little effect on the  
3177 problem at hand. Therefore, the parameters I investigate are the following:

- 3178 • `min_samples_split`: defines the minimum number of samples required in a node  
3179 to be considered for splitting. Higher values prevent a model from learning relations

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3180 which might be highly specific to the particular sample, but may lead to under-fitting  
3181 if the value is too low.

3182 • `min_samples_leaf`: defines the minimum samples required in a leaf node. For  
3183 imbalanced problems it should take a low value, as there will not be many cases  
3184 where the minority class dominates.

3185 • `max_depth`: maximum depth of a tree. Useful to prevent over-fitting, as higher  
3186 depth will allow a model to learn relations specific to the training sample.

3187 In the case of the boosting parameters, the ones I look at are:

3188 • `learning_rate`: determines the impact of each tree on the final outcome. Low  
3189 values make the model robust to the specific characteristics of a tree, and thus  
3190 allow it to generalise well. However, that usually requires a large number of trees  
3191 to model the data properly.

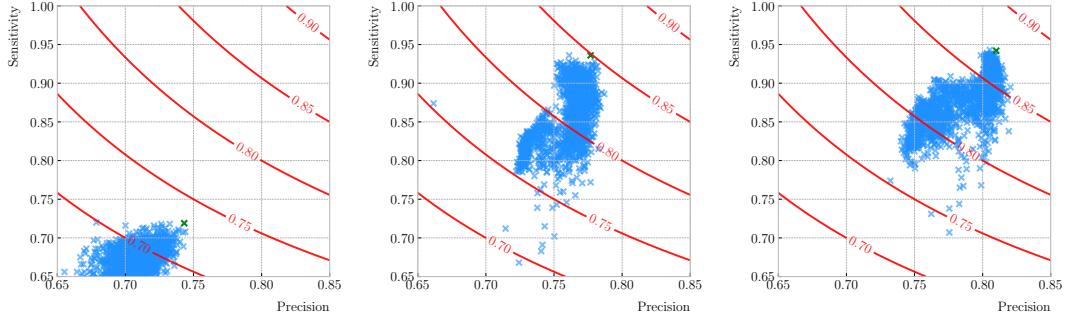
3192 • `n_estimators`: number of sequential trees to be trained. In general, BDTs are  
3193 fairly robust at higher number of trees but it can still overfit at a point.

3194 • `subsample`: fraction of observations to be selected for each tree. Values slightly  
3195 less than 1 make the model robust by reducing the variance.

3196 In general, hyperparameters depend on each other. Thus, it is not possible to  
3197 optimise them independently. In the literature, we find two main strategies to explore  
3198 the hyperparameter space. We could use a grid search, in which one discretises a  
3199 portion of the space of hyperparameters and evaluates the model at each point. Another  
3200 approach is the randomised search, where a certain number of random configurations of  
3201 hyperparameters are explored.

3202 In this case, I used the random search to scan the hyperparameter space. Also,  
3203 because it is not guaranteed that a set of hyperparameters can be efficiently applied  
3204 across different datasets, I perform the optimisation for each of the momentum ranges  
3205 considered. Table 8.3 shows the list of hyperparameters considered, and the range within

## 8.2. Muon and pion separation in the ECal and MuID



**Figure 8.26:** Values of the precision and sensitivity obtained for 10000 BDT hyperparameter configurations, for the momentum regions I, III and V. The red contours indicate the curves of equal  $F_1$ -score, while the green crosses are the selected configurations.

3206 which I let them vary. I decided to fix the number of estimators to 400 in all cases, as  
3207 its value is correlated with that of the learning rate.

3208 I evaluate 10000 different hyperparameter configurations for each momentum range.  
3209 For the hyperparameter tuning, I used subsamples containing 10% of the full datasets,  
3210 keeping the original proportions between classes, in order to reduce the computational  
3211 load. The performance of the models was assessed using a stratified 3-fold cross-validation  
3212 with replacement. Cross-validation involves dividing the data in a number of subsets,  
3213 training the model using some of them, and testing it with the rest. In our case, I  
3214 divide the data in 3 equal-sized subsets, maintaining the class proportions of the original  
3215 dataset. Then, for 3 consecutive iterations, I train the models using 2 of the subsets  
3216 while I compute the precision and sensitivity scores with the other. This approach  
3217 provides a more robust estimate of the performance on unseen data.

3218 Figure 8.26 shows the results in the precision versus sensitivity plane, for the  
3219 momentum regions I, III and V (from left to right). The contours represent the curves  
3220 of equal  $F_1$ -score, i.e. the harmonic mean of the precision and the sensitivity. In order  
3221 to select the optimal configurations (indicated in the plots with a green cross), I chose  
3222 the point with the highest  $F_1$ -score.

3223 The results for the different momentum ranges are summarised in Tab. 8.3. One  
3224 can see some consistency in hyperparameter choices, with models generally preferring

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**Table 8.3:** Optimal values of the hyperparameters used by the BDT, for each momentum range.

Hyperparameter	Range	Best value				
		I	II	III	IV	V
<code>min_samples_split</code>	[0.001, 1]	0.10	0.06	0.05	0.27	0.06
<code>min_samples_leaf</code>	[0.001, 1]	0.02	0.03	0.01	0.02	0.07
<code>max_depth</code>	{2, 3, ..., 8}	8	2	4	2	7
<code>learning_rate</code>	[0.05, 1]	0.10	0.23	0.07	0.13	0.09
<code>subsample</code>	[0.01, 1]	0.75	0.65	0.79	0.86	0.95

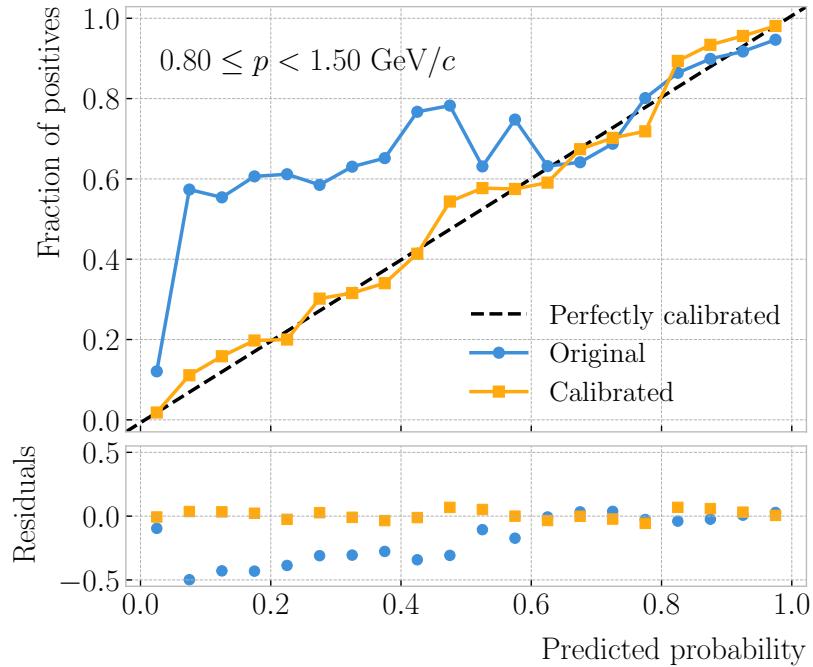
**Table 8.4:** Performance metrics of the BDTs with optimal hyperparameters, for the different momentum ranges.

Metric	Value $\pm 1\sigma$				
	I	II	III	IV	V
Accuracy	$0.779 \pm 0.003$	$0.812 \pm 0.003$	$0.846 \pm 0.002$	$0.861 \pm 0.003$	$0.874 \pm 0.002$
Precision	$0.769 \pm 0.003$	$0.752 \pm 0.005$	$0.788 \pm 0.002$	$0.805 \pm 0.003$	$0.815 \pm 0.003$
Sensitivity	$0.745 \pm 0.009$	$0.921 \pm 0.006$	$0.965 \pm 0.002$	$0.967 \pm 0.002$	$0.976 \pm 0.001$
$F_1$ -score	$0.757 \pm 0.004$	$0.828 \pm 0.003$	$0.867 \pm 0.002$	$0.879 \pm 0.002$	$0.889 \pm 0.002$
ROC AUC	$0.868 \pm 0.003$	$0.865 \pm 0.003$	$0.899 \pm 0.002$	$0.902 \pm 0.002$	$0.911 \pm 0.001$

3225 small values for the tree-specific parameters, small learning rate, and relatively large  
 3226 subsample sizes.

3227 Now that I have obtained the optimal values of the hyperparameters, I can train  
 3228 the different BDTs. In this case I use the complete datasets, keeping 20% of the data  
 3229 for testing. Table 8.4 shows the values of the different performance metrics obtained  
 3230 using the selected hyperparameters and 5-fold cross-validation. The last row indicates  
 3231 the value of the area under the receiver operating characteristic (ROC) curve. This  
 3232 represents the sensitivity of a model as a function of the false positive rate. I have  
 3233 included it here as it is a classic model metric used in the machine learning community.  
 3234 Overall, there is a clear trend of models performing better at higher momentum.

## 8.2. Muon and pion separation in the ECal and MuID



**Figure 8.27:** Reliability diagrams for the BDT classifier used in the momentum range  $0.3 \leq p < 0.8$  GeV/ $c$ , both for the original (blue circles) and calibrated (yellow squares) responses. For reference, the response of a perfectly calibrated classifier is also shown (black dashed line).

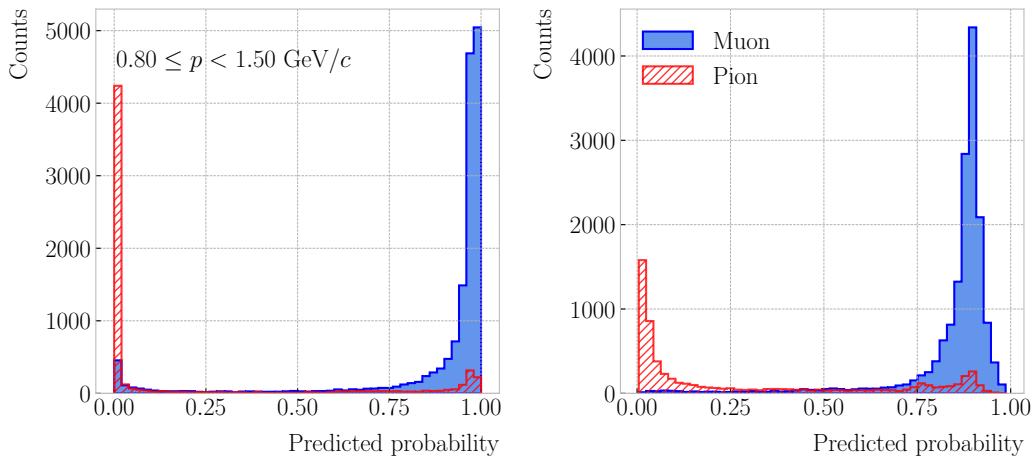
### 8.2.5 Probability calibration

So far, the trained BDTs are able to provide predictions of the class labels. Ideally, one would like the output of a classifier to give a confidence level about the prediction. However, it is not straightforward to interpret the outputs of our BDTs in terms of probabilities.

A way to visualise how well the predictions of a classifier are calibrated is using reliability diagrams [110]. They represent the probability of the positive label versus the probability predicted by the classifier. These can be obtained by binning the predicted probabilities, and then compute the conditional probability  $P(y_{true} = 1 | y_i \leq y_{pred} < y_{i+1})$  by checking the fraction of true positive instances in each bin. The reliability diagram of a perfectly calibrated classifier would be a diagonal line.

In this case, I try to correct the raw response of the classifiers by applying a sigmoid

## Chapter 8. Particle ID in GArSoft



**Figure 8.28:** Uncalibrated (left panel) and calibrated (right panel) predicted probabilities assigned by the BDT classifiers for true muons (blue) and charged pions (red) in the momentum range  $0.3 \leq p < 0.8 \text{ GeV}/c$ .

3247 function:

$$\sigma(x; A, B) = \frac{1}{1 + e^{Ax+B}}, \quad (8.18)$$

3248 where the parameters  $A$  and  $B$  are real numbers determined using the method of least  
3249 squares.

3250 For each classifier, I perform a grid search to obtain the optimal values of  $A$  and  $B$ .  
3251 For any pair, I compute the predicted probabilities as  $y_{pred} = \sigma(y_{raw}; A, B)$ , where  $y_{raw}$   
3252 are the raw predictions of the classifier<sup>9</sup>. Then, I calculate the corresponding reliability  
3253 curve, and take the sum of the squared residuals between it and the response of the  
3254 perfectly calibrated classifier.

3255 Figure 8.27 shows the reliability diagrams for the original (blue) and calibrated  
3256 (yellow) probability predictions of the classifier for the III momentum range,  $0.3 \leq p <$   
3257  $0.8 \text{ GeV}/c$ . The original response of the classifier is given by  $y_{pred} = \sigma(y_{raw}; -2, 0)$ ,  
3258 which is the transformation applied by `scikit-learn` to produce the probability estimate.  
3259 Notice how the calibrated prediction matches the ideal response much better than the  
3260 original, across all the probability range.

3261 One can also compare the responses of the uncalibrated and calibrated classifiers

---

<sup>9</sup>In `scikit-learn` these correspond to the outputs of the `decision_function` method.

### 8.3. ECal time-of-flight

3262 broken down by true particle type, as shown in Fig. 8.28. It can be seen that the  
3263 distributions for both muons (blue) and charged pions (red) smoothen after calibration,  
3264 but still the separating power of the classifier remains unchanged.

3265 At this point, having the trained classifiers and the probability calibration parameters,  
3266 I am able to assess the performance of the classification strategy in a physics-relevant  
3267 case.

#### 3268 8.2.6 Performance

### 3269 8.3 ECal time-of-flight

3270 Looking at Fig. 8.19, it is clear that for momentum values in the range  $1.0 - 3.0 \text{ GeV}/c$   
3271 it is not possible to separate pions and protons using a  $\langle dE/dx \rangle$  measurement in the  
3272 HPgTPC. However, in the previous section I assumed that protons at those energies  
3273 could be identified by other means, and therefore were not an issue for the muon and  
3274 pion discrimination.

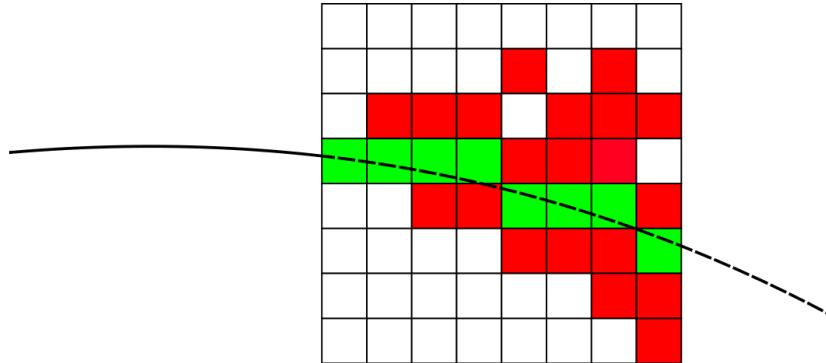
3275 Some detectors, like ALICE [111] or the ILD concept [112], complement the PID  
3276 capabilities of their gaseous trackers with time-of-flight measurements. The use of  
3277 fast timing silicon sensors, with hit time resolutions under 100 ps, would allow for the  
3278 identification of charged hadrons via a ToF measurement up to  $5.0 \text{ GeV}/c$ . In the case  
3279 of ND-GAr, one could think of using the inner layers of the ECal, the ones consisting of  
3280 high-granularity tiles, to obtain a ToF-based PID, with some inputs from the TPC.

3281 Measuring the momentum and the velocity of a charged particle allows for a  
3282 determination of the mass through the relativistic momentum formula:

$$m = \frac{p}{\beta} \sqrt{1 - \beta^2}. \quad (8.19)$$

3283 In our case, the momentum is measured in the TPC, using the curvature and the dip  
3284 angle of the helix inside the magnetic field. The velocity of the particle can be written

## Chapter 8. Particle ID in GArSoft



**Figure 8.29:** Schematic of the hit selection used for the ToF measurement. The grid represents the layers of the inner ECal, with coloured squares indicating the tiles with hits. Green squares indicate the selected hits.

3285 as:

$$\beta = \frac{\ell_{track}}{c\tau}, \quad (8.20)$$

3286 where  $\ell_{track}$  is the length of the track, and  $\tau$  the arrival time to the ECal.

3287 In GArSoft, the track length is computed at the Kalman filter stage. It is simply the  
 3288 sum of the line segments along the track, either in the forward or backward fit. In this  
 3289 case, because we are only interested in the particles that make it to the ECal, I choose  
 3290 the fit direction based on the results of the track-cluster associations.

3291 Additionally, because the last 30 cm of the TPC radius are uninstrumented<sup>10</sup>, I need  
 3292 to correct for the length of the tracks. Using the track fit parameters to propagate the  
 3293 helix to its entry point in the ECal, one can write the total track length as:

$$\ell_{track} = \ell + \left| \frac{\phi_{EP} - \phi}{R^{-1}} \right| \sqrt{1 + \tan^2 \lambda}, \quad (8.21)$$

3294 where  $\phi_{EP}$  is the angle of rotation at the entry point to the calorimeter, and  $\ell$ ,  $\phi$ ,  $R$  and  
 3295  $\lambda$  are the track length, angle of rotation, radius of curvature and dip angle at the last  
 3296 point in the fit, respectively.

3297 To test the idea of performing a ToF measurement with the inner ECal, I generated  
 3298 two data samples. Each consists of 10000 single particle events, either charged pions or

---

<sup>10</sup>Note to self: check this number.

### 8.3. ECal time-of-flight

3299 protons. Their momenta are uniformly distributed in the range  $0.5 - 5.0 \text{ GeV}/c$ , and  
3300 their directions are isotropic. I process each sample using different values of the time  
3301 resolution, from  $\Delta\tau = 0$ , the perfect time resolution case for comparison, to the current  
3302 nominal value of  $\Delta\tau = 0.7 \text{ ns}$ , and the worse scenario of  $\Delta\tau = 1.0 \text{ ns}$ .

#### 3303 8.3.1 Arrival time estimations

3304 In the simulation, the limited time resolution of the ECal is taken into account by  
3305 applying a Gaussian smearing to the true hit times. Other effects, like the digitisation  
3306 of the signals, are not taken into account and fall beyond the scope of this study. After  
3307 the track-cluster, one ends up with a collection of ECal hits associated to each particle.  
3308 From these, the arrival time of the particle to the ECal can be extracted.

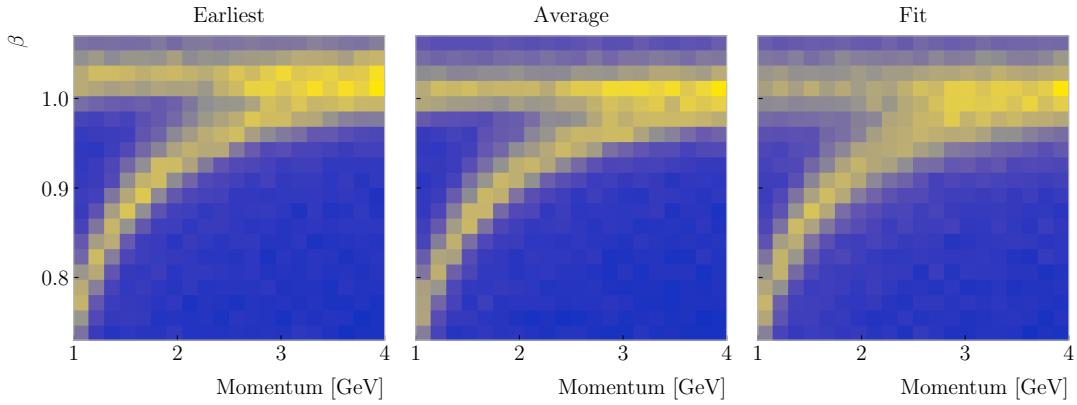
3309 The simplest possibilities are to either take the time of the earliest hit or the hit  
3310 closest to the entry point. Because these two coincide, in general, I focused only in  
3311 the earliest hit time. However, this needs to be corrected, to account for the distance  
3312 travelled from the entry point to the position of the hit:

$$\tau_{earliest} = \tau_{hit} - \frac{d_{EP-hit}}{c}, \quad (8.22)$$

3313 where  $\tau_{hit}$  is the time of the earliest hit, and  $d_{EP-hit}$  is the distance between that hit  
3314 and the entry point of the particle to the ECal. This is computed as the arc length  
3315 between the entry point and the point of the extrapolated helix up to the layer of the  
3316 hit. This way of correcting the time assumes  $c$  for the propagation of the particle, which  
3317 may lead to biased estimates.

3318 I also tried to estimate the arrival times using information from the rest of the hits.  
3319 In order to do this, as a simplifying assumption, I approximate the hadronic shower  
3320 considering only its MIP component. For each layer, I keep only the hit in the tile closest  
3321 to the point of the extrapolated track up to that layer. Figure 8.29 shows an example of  
3322 how this hit selection works. The dashed line represents the extrapolated track, while  
3323 the coloured squares are the tiles containing hits. Green indicates the tiles closer to the

## Chapter 8. Particle ID in GArSoft



**Figure 8.30:** Particle velocity versus momentum measured with different ECal arrival time estimations. From left to right: earliest hit time, average hit time, and fitted hit time. In all cases the time resolution is  $\Delta\tau = 0.1$  ns.

3324 track in each layer (in the sketch they correspond to the grid columns).

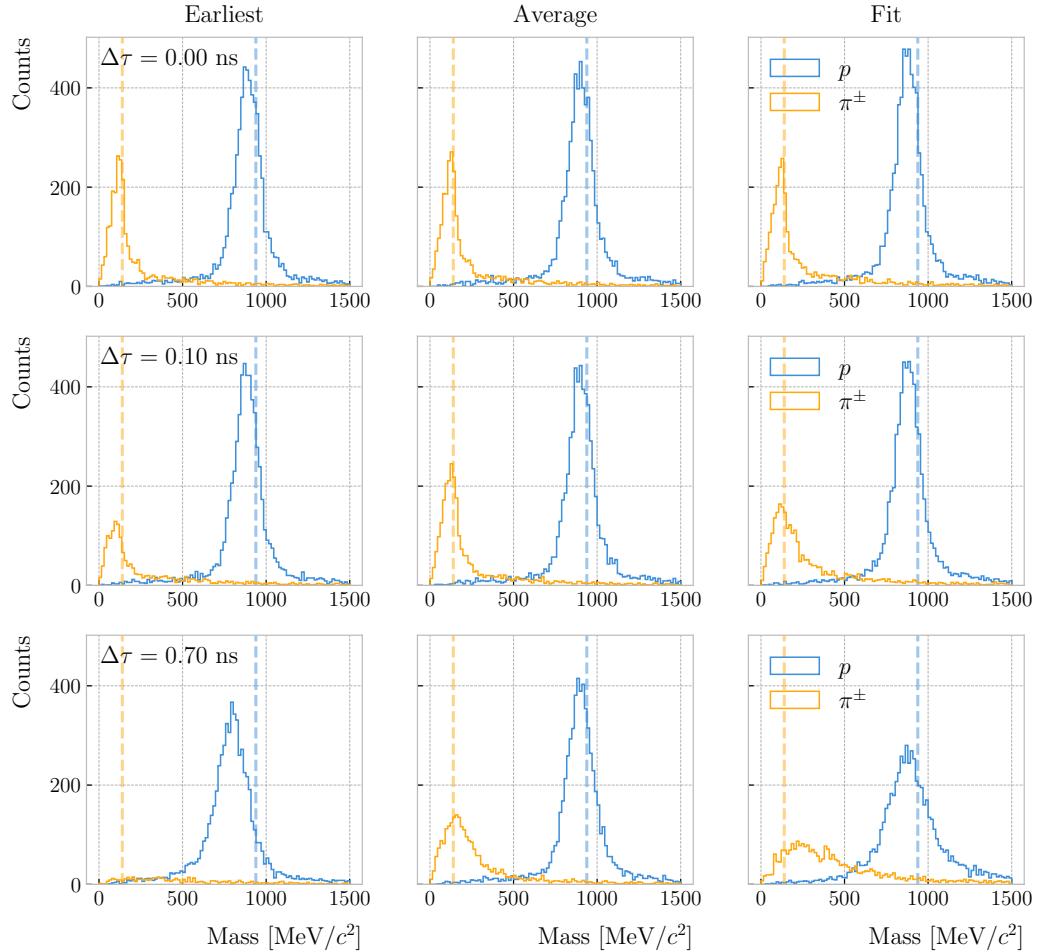
3325 Now, I can use these collections of hits to estimate the arrival times. A possibility  
 3326 is to take the average of the times of the selected hits, denoted  $\tau_{average}$ . For that to  
 3327 work, one needs to correct these times, in a similar way as in Eq. (8.22), before taking  
 3328 the average. However, as before, this correction assumes that the particle travels at the  
 3329 speed of light inside the ECal. Another option is to perform a linear fit to the hit times  
 3330 and the distances to the entry point. In that case, the arrival time would be the fitted  
 3331 value of the intercept,  $\tau_{fit}$ . This method would not assume a speed of light propagation.

3332 Figure 8.30 shows the velocity estimations as a function of the particle momentum,  
 3333 for the earliest hit time (left panel), average hit time (middle panel), and fitted hit time  
 3334 (right panel). The two bands correspond to the  $\pi^\pm$  and the  $p$  particles.  $\Delta\tau = 0.1$  ns.  
 3335 Notice how, for the earliest hit time method, the velocities are significantly biased  
 3336 towards larger values. For the multi-hit methods, the  $\tau_{fit}$  estimate appears to produce a  
 3337 larger variance than when using the  $\tau_{average}$  method.

### 3338 8.3.2 Proton and pion separation

3339 Once we have the velocities of the particles, one can estimate their masses through  
 3340 Eq. (8.19). The resulting mass spectra are shown in Fig. 8.31. I computed the masses

### 8.3. ECal time-of-flight

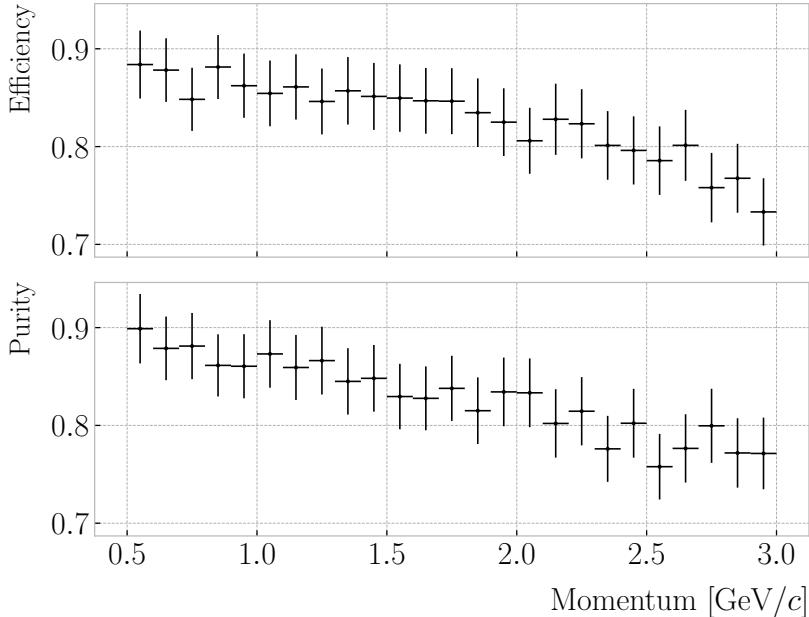


**Figure 8.31:** Mass spectra for  $p$  (blue) and  $\pi^\pm$  (yellow) particles, using different ECal time resolution values (from top to bottom, in ascending order), and arrival time estimates. From left to right: earliest hit time, average hit time, and fitted hit time. The dashed lines indicate the true masses of the particles.

for the three arrival time estimates discussed above, and three different values of the time resolution:  $\Delta\tau = 0.00$  (perfect time resolution),  $\Delta\tau = 0.10$  ns, and  $\Delta\tau = 0.70$  ns. Although in all cases we have the same number of events, it appears as if the entries in the histograms decrease as the time resolution increases. Sometimes, the particles get unphysical values of  $\beta > 1$ , and in turn they do not contribute to the mass spectra. This is more likely to happen for higher values of  $\Delta\tau$ .

As noted before, the average hit time method produces the most robust estimates when increasing  $\Delta\tau$ . Intuitively this makes sense, as by taking the mean one averages

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**Figure 8.32:** Efficiency (top panel) and purity (bottom panel) for the proton selection as a function of the momentum, for  $\Delta\tau = 0.10$  ns.

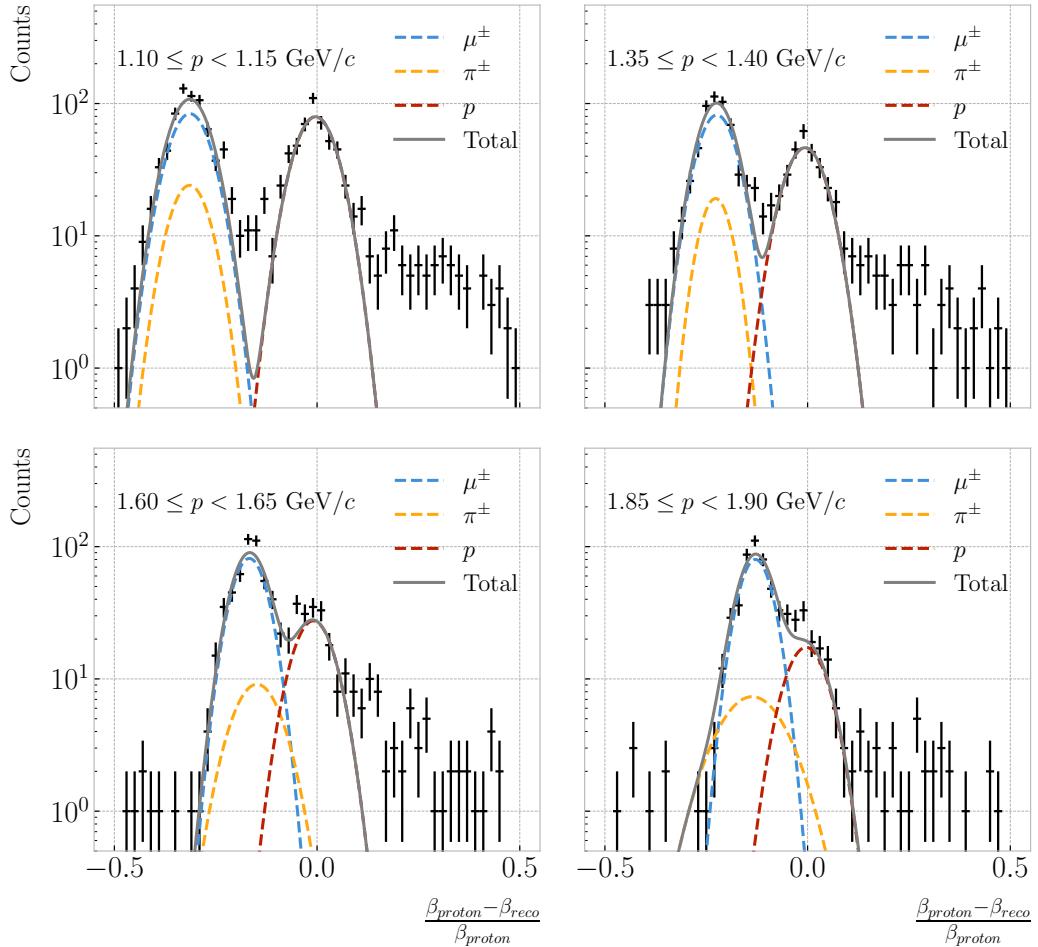
3349 out the effect of the Gaussian smearing. Going forward, I will use this arrival time  
 3350 estimator, as it appears to be the best performing one.

3351 It is possible to use the velocity estimations to select a sample of protons. In this  
 3352 case, I do so by dividing the relevant momentum range in bins of  $0.1$   $\text{GeV}/c$ . For each  
 3353 momentum bin, I compute the expected velocity for the protons via the inverse of Eq.  
 3354 (8.19), and then take the fractional residuals of the measured velocities. Using that  
 3355 distribution, I choose the cut that maximises the  $F_1$ -score of the proton selection.

3356 The results can be seen in Fig. 8.32, for the case  $\Delta\tau = 0.10$  ns. As expected from  
 3357 Fig. 8.30, the performance of the selection degrades rapidly with increasing momentum.  
 3358 However, the purity is still around 75% at  $3.0$   $\text{GeV}/c$ . This is likely to be sufficient, as  
 3359 we do not expect protons or charged pions with higher energies from the beam neutrino  
 3360 interactions.

3361 Figure 8.33

## 8.4. Charged pion decay in flight



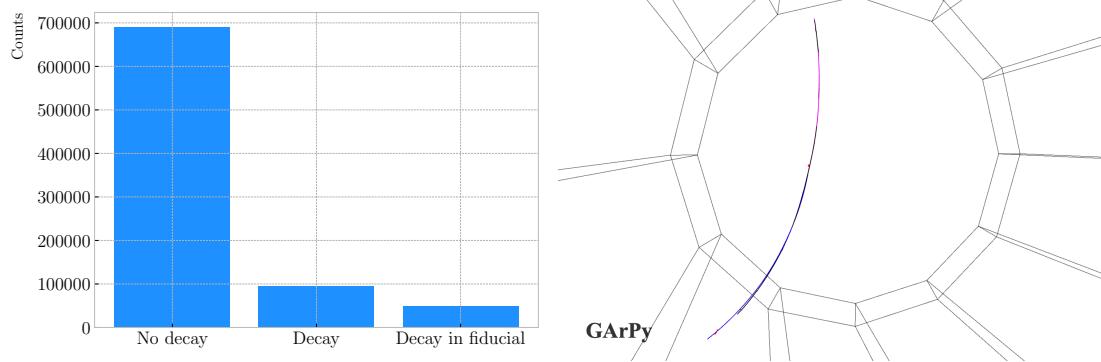
**Figure 8.33:** Distributions of the velocities measured by ToF with the inner ECal, for different momentum bins, in a FHC neutrino interaction sample. The Gaussian fits are performed around the maxima for each particle species.

## 3362 8.4 Charged pion decay in flight

3363 As discussed previously, in GArSoft the TPC tracks are formed after a pattern recognition  
 3364 algorithm and a Kalman filter are applied to the TPC clusters. These two steps can  
 3365 find discontinuities in the track candidates (e.g. due to a particle decay) when these  
 3366 so-called breakpoints are large enough. However, for some, more subtle, cases they may  
 3367 miss them and form a single reconstructed track. It has been noted in the literature  
 3368 that Kalman filters offer, as a by-product, additional information to form test statistics  
 3369 to identify these breakpoints [113, 114].

3370 Considering the mean life of the charged pion,  $\tau = (2.6033 \pm 0.0005) \times 10^{-8} \text{ s}$ , one

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**Figure 8.34:** Left panel: number of non-decaying, decaying and decaying in the fiducial volume pions for a MC sample of 100000,  $p = 500 \text{ MeV}/c$  isotropic positively charged pions inside the TPC. Right panel: event display for a positive pion decaying inside the fiducial volume, with a single reconstructed track for the pion and muon system.

3371 can estimate that about 12% of the pions with momentum  $p \sim \mathcal{O}(500 \text{ MeV}/c)$  (roughly  
 3372 the peak of the pion momentum distribution in  $\nu_\mu$  CC interactions off argon) decay  
 3373 inside the TPC. Figure 8.34 (left panel) shows the amount of charged pions decaying in  
 3374 the full TPC and fiducial volumes from an isotropic, monoenergetic sample of 100000  
 3375 negatively charged pions with  $p = 500 \text{ MeV}/c$ . We see that about 10% of those decayed,  
 3376 with more than half of them decaying inside the TPC fiducial volume.

3377 Figure 8.34 (right panel) shows an example event display of a charged pion (magenta  
 3378 line) decays in flight inside the TPC, but because the angle of the muon (blue line) is  
 3379 small both were reconstructed as one single track (black line). In this case, the composite  
 3380 track reaches the ECal, where it undergoes a muon-like interaction, thus being classified  
 3381 as a muon.

3382 A way to understand what decaying pion tracks were totally or partially reconstructed  
 3383 together with the daughter muon is looking at the relative energy contributions to the  
 3384 reconstructed track. In order to select a sample of such events, I require that a minimum  
 3385 50% of the total energy comes from the pion and at least 20% from the muon.

### 3386 8.4.1 Track breakpoints

3387 To identify potential decays we can use the information we obtain from the Kalman  
 3388 filter at each step of the fitted track. The simplest test we can think about is computing

## 8.4. Charged pion decay in flight

3389 the  $\chi^2$  of the mismatch between all the parameters in the forward and the backward fits:

$$\chi_k^{2 (FB)} = (\hat{x}_k^B - \hat{x}_k^F)^T [V^{(\hat{x}_k, B)} + V^{(\hat{x}_k, F)}]^{-1} (\hat{x}_k^B - \hat{x}_k^F), \quad (8.23)$$

3390 where  $\hat{x}_k^F$ ,  $\hat{x}_k^B$  are the Kalman filter state vector estimates at step  $k$  in the forward and  
3391 backward fits and  $V^{(\hat{x}_k, F)}$ ,  $V^{(\hat{x}_k, B)}$  the covariance matrices of  $\hat{x}_k^F$  and  $\hat{x}_k^B$  respectively.  
3392 Using the values of the  $\chi^2$  at measurement  $k$  for the forward and backward fits we can  
3393 compute another  $\chi^2$  value that characterises the overall track fit:

$$\chi_{track}^2 = \chi_k^{2 (F)} + \chi_k^{2 (B)} + \chi_k^{2 (FB)}, \quad (8.24)$$

3394 which remains approximately constant for all  $k$ .

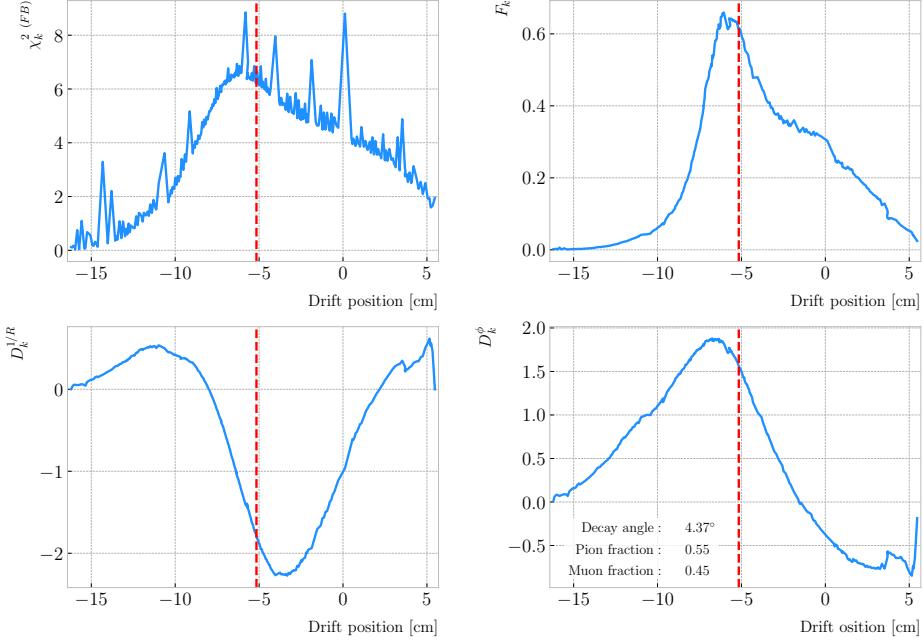
3395 An alternative approach proposed in the context of the NOMAD experiment was  
3396 using a fit with a more elaborate breakpoint hypothesis, so we can perform a comparison  
3397 of the  $\chi^2$  with and without breakpoints. This can be achieved by using some alternative  
3398 parametrisation with extra parameters, which allows some of the track parameters to  
3399 be discontinuous at certain points. A decay changes the momentum magnitude and  
3400 direction, so we can use the new state vector:

$$\alpha = (y, z, 1/R_F, 1/R_B, \phi_F, \phi_B, \tan\lambda_F, \tan\lambda_B)^T. \quad (8.25)$$

3401 As we already have the estimates from the standard Kalman filter and their  
3402 covariance matrices at each point, we do not need to repeat the Kalman fit for the new  
3403 parametrisation. Instead, I can compute the values of  $\alpha$  at each point  $k$  that minimise  
3404 the  $\chi^2$  resulting from comparing them to  $\{\hat{x}_k^B, \hat{x}_k^F\}$ . Introducing the two  $5 \times 8$  matrices:

$$H^F = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix}, H^B = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}, \quad (8.26)$$

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**Figure 8.35:** Values of  $\chi_k^{2(FB)}$  (top left panel),  $F_k$  (top right panel),  $D_k^{1/R}$  (bottom left panel) and  $D_k^\phi$  (bottom right panel) versus position along the drift direction for a reconstructed track in a positive pion decay event. The vertical red dashed line indicates the true location of the decay point.

3405 we can write this as:

$$\begin{aligned}\chi_k^{2(FB)}(\alpha) &= (\hat{x}_k^F - H^F \alpha)^T \left[ V^{(\hat{x}_k, F)} \right]^{-1} (\hat{x}_k^F - H^F \alpha) \\ &\quad + (\hat{x}_k^B - H^B \alpha)^T \left[ V^{(\hat{x}_k, B)} \right]^{-1} (\hat{x}_k^B - H^B \alpha).\end{aligned}\tag{8.27}$$

3406 The minimum of  $\chi_k^{2(FB)}(\alpha)$  is found when the measured new state vector takes the

3407 value:

$$\hat{\alpha}_k = V^{(\hat{\alpha}_k)} H^T (V^{(\hat{x}_k)})^{-1} \hat{X},\tag{8.28}$$

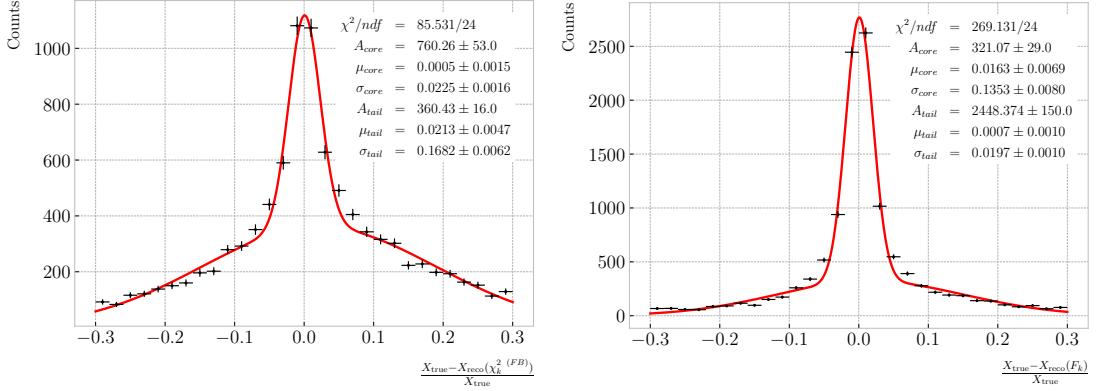
3408 where  $\hat{X} = \{\hat{x}_k^B, \hat{x}_k^F\}$ ,  $V^{(\hat{x}_k)}$  is the block diagonal matrix formed by  $V^{(\hat{x}_k, F)}$  and  $V^{(\hat{x}_k, B)}$

3409 and  $V^{(\hat{\alpha}_k)}$  is the covariance matrix of  $\hat{\alpha}_k$ , given by:

$$V^{(\hat{\alpha}_k)} = \left( H^T (V^{(\hat{x}_k)})^{-1} H \right)^{-1}.\tag{8.29}$$

3410 From these new fit estimates we can compute the  $F$  statistic, which tells us whether

## 8.4. Charged pion decay in flight



**Figure 8.36:** Fractional residual distributions of the true and reconstructed decay position along the drift coordinate, using the position of the maximum of  $\chi_k^2 \text{ (FB)}$  (left panel) and  $F_k$  (right panel) as estimates of the decay position. Also shown are double Gaussian fits to these points (red lines).

3411 the model with breakpoint provides a statistically significant better fit:

$$F_k = \left( \frac{\chi_{\text{track},k}^2 - \chi_{\text{full},k}^2}{8 - 5} \right) / \left( \frac{\chi_{\text{full},k}^2}{N - 8} \right). \quad (8.30)$$

3412 One can also compute the signed difference of the duplicated variables divided by  
 3413 their standard deviation at each point. These represent how significant the discontinuity  
 3414 in each variable is. For any variable  $\eta$  we can write it as:

$$D_k^\eta = \frac{\hat{\eta}_k^B - \hat{\eta}_k^F}{\sqrt{\text{Var}[\hat{\eta}_k^F] + \text{Var}[\hat{\eta}_k^B] - 2\text{Cov}[\hat{\eta}_k^F, \hat{\eta}_k^B]}}. \quad (8.31)$$

3415 In our case, the relevant ones to look at are  $D_k^{1/R}$  and  $D_k^\phi$ .

3416 Figure 8.35 shows the values of  $\chi_k^2 \text{ (FB)}$ ,  $F_k$ ,  $D_k^{1/R}$  and  $D_k^\phi$  as functions of the position  
 3417 along the drift direction, for an example reconstructed track with 55.5% of the energy  
 3418 coming from the charged pion and 45.5% from the daughter muon. The true position of  
 3419 the decay is indicated (dashed red lines). Notice how  $\chi_k^2 \text{ (FB)}$  and  $F_k$ ,  $D_k^{1/R}$  reach their  
 3420 maxima near the decay point. In the former case this indicates a large forward-backward  
 3421 difference in the track fit. In the later it represents that the extended state vector  
 3422 improves the fit particularly around that point.

## Chapter 8. Particle ID in GArSoft

3423 I can estimate the decay position finding resolution by computing the difference  
 3424 between the  $X$  position of the maxima of  $\chi_k^2(FB)$  and  $F_k$  and the  $X$  position of the  
 3425 true decay. Figure 8.36 represent the the fractional residual distributions for both  
 3426 cases, from the sample of tracks containing pion decays. Fitting a double Gaussian to  
 3427 the distributions (red lines) I find a resolution of  $(3.31 \pm 0.15)\%$  and  $(6.94 \pm 0.31)\%$   
 3428 respectively.

3429 In principle, the  $F$ -statistic should follow a Fisher distribution with  $(8 - 5)$  and  
 3430  $(N - 8)$  degrees of freedom under the null hypothesis. In most of our cases  $N \sim \mathcal{O}(100)$ ,  
 3431 so the probability density functions will look very similar. In this case, it is safe to take  
 3432 the limit  $N \rightarrow \infty$  in the Fisher PDF:

$$\begin{aligned}\tilde{f}(x; a - b) &= \lim_{N \rightarrow \infty} f(x; a - b, N - a) \\ &= \frac{2^{-\frac{a-b}{2}}}{\Gamma(\frac{a-b}{2})} (a - b)^{\frac{a-b}{2}} x^{\frac{a-b}{2}-1} e^{-\frac{a-b}{2}x}.\end{aligned}\tag{8.32}$$

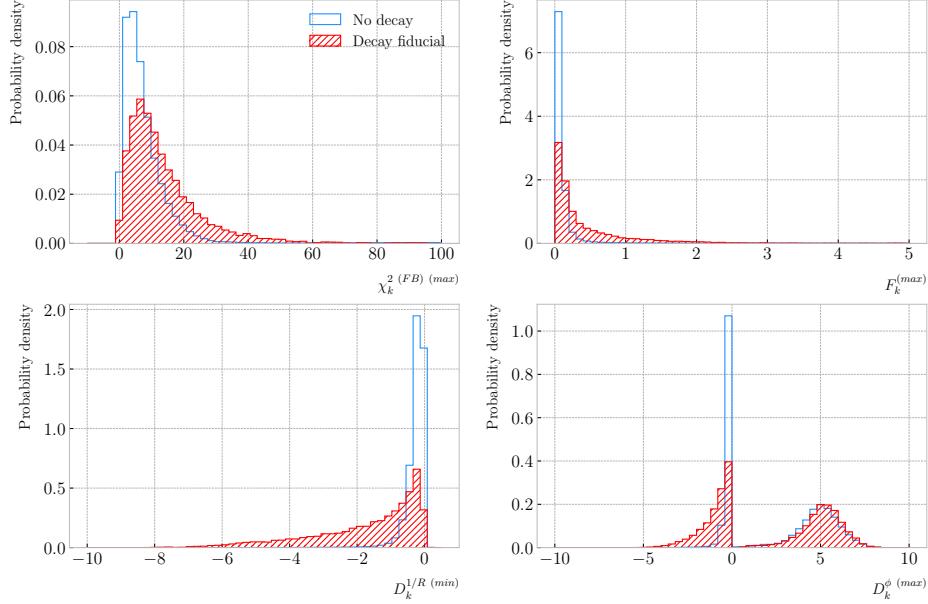
3433 In our case  $a - b = 8 - 5 = 3$ , so we would obtain a p-value of 0.05 at  $x = 2.60$ .

3434 Figure 8.37 contains the distributions of the maxima of  $\chi_k^2(FB)$ ,  $F_k$  and  $D_k^\phi$  and the  
 3435 minima of  $D_k^{1/R}$  for a sample of non-decaying pion tracks (blue) and another sample of  
 3436 reconstructed tracks containing part of the pion and the daughter muon from a decay  
 3437 inside the fiducial volume (red). Notice that, even though the values of  $F_k^{(max)}$  for the  
 3438 decay sample are typically larger than for the non-decaying one, just a small fraction of  
 3439 the events go beyond the aforementioned value of  $F = 2.60$ . Therefore, from a practical  
 3440 point of view, it is not the most efficient variable to use for selecting the decay events.

3441 However, looking at the  $D_k^{1/R \text{ (min)}}$  distribution we can see there is a big difference  
 3442 between non-decaying and decaying events in this variable. One can use a combination  
 3443 of these four variables to distinguish between the pion decay events (signal) and the  
 3444 non-decaying pions (background).

3445 An approach to this classification could be using a boosted decision tree (BDT). One  
 3446 of the advantages of BDTs is that they are easy to interpret and identify the relative  
 3447 importance of the different input variables. Training a BDT with 400 estimators and a

## 8.4. Charged pion decay in flight



**Figure 8.37:** Distributions of the extreme values of  $\chi_k^2(FB)$  (top left panel),  $F_k$  (top right panel),  $D_k^{1/R}$  (bottom left panel) and  $D_k^\phi$  (bottom right panel) for non-decaying reconstructed pion tracks (blue) and tracks which include the decay inside the fiducial volume (red).

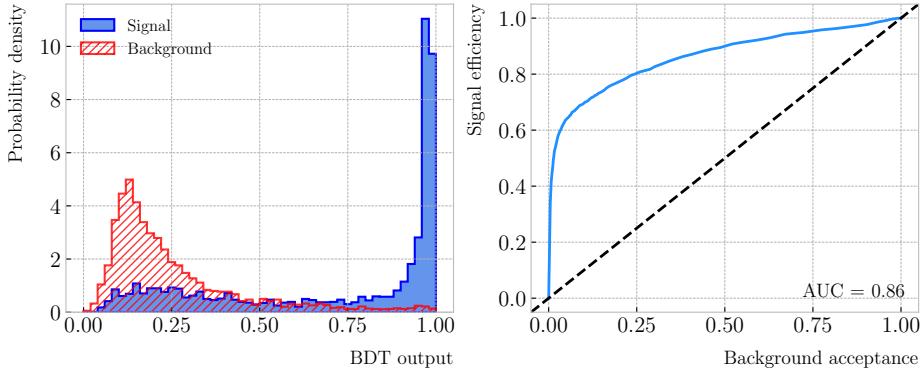
maximum depth of 4 I can obtain an efficient classification without overtraining. Figure 8.38 (left panel) shows the distribution of probabilities predicted by the BDT for a test sample. The signal efficiency as a function of background acceptance, the so-called ROC curve, is shown in Fig. 8.38 (right panel). With a relative importance of 0.83, the most important variable turned out to be  $D_k^{1/R}$  (min).

One thing we can check is how the resolution to the decay and the signal efficiency in the classification changes with the true decay angle. Using an equal-frequency binning for the decay angles, we can repeat the previous steps for each bin.

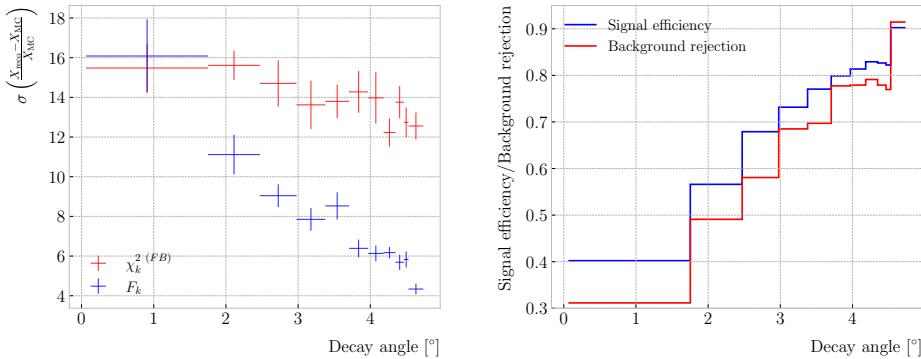
Figure 8.39 (left panel) shows the dependence on the decay angle of the decay finding resolution. We can see that for the  $\chi_k^2(FB)$  maximum location method the resolution consistently lies between 12 to 16%. However, the  $F_k^{(max)}$  approach gives a significantly better resolution for high angle values, reaching the 4 – 6% range for decay angles  $\geq 4^\circ$ .

For the classification dependence on the angle, I use the same classifier I trained before but evaluating the test sample for each individual angular bin. I compute the

## Chapter 8. Particle ID in GArSoft



**Figure 8.38:** Left panel: distributions of the predicted probabilities assigned by the BDT classifier to a test sample of decaying pion+muon tracks (blue) and non-decaying pion tracks (red). Left: signal efficiency versus background acceptance (ROC curve) obtained from the BDT for the test sample.



**Figure 8.39:** Left panel: dependence of the decay position finding resolution on the true value of the decay angle for the  $\chi_k^2(FB)$  (red) and  $F_k$  (blue) methods. Right panel: signal efficiency (blue line) and background rejection (red line) from the BDT classifier versus true decay angle.

3462 signal efficiency in each bin for a fixed value of the background rejection, in this case  
 3463 90%. Similarly, for the background rejection estimation I use a fixed signal efficiency  
 3464 value of 90%. Figure 8.39 (right panel) represents the change in signal efficiency (blue)  
 3465 and background rejection (red) with the value of the true decay angles.

## 8.5. Neutral particle identification

### 3466 8.5 Neutral particle identification

#### 3467 8.5.1 ECal clustering

3468 Another important reconstruction item is the clustering algorithm of ECal hits in  
3469 GArSoft. The default module features a NN algorithm that treats all hits in the same  
3470 way, independently of the layer each hit comes from. However, the current ECal design  
3471 of ND-GAr has two very different types of scintillator layers. The inner layers are made  
3472 out of tiles, which provide excellent angular and timing resolutions. On the other hand,  
3473 the outer layers are cross scintillator strips. That way, an algorithm that treats hits  
3474 from both kinds of layers differently may be able to improve the current performance.

3475 Inspired by the reconstruction of T2K's ND280 downstream ECal [115], the idea  
3476 was to put together a clustering module that first builds clusters for the different ECal  
3477 views (tiles, strips segmented in the  $X$  direction and strips segmented in  $Y$  direction),  
3478 and then tries to match them together to form the final clusters.

3479 Working on a module-by-module basis, the algorithm first separates the hits depending  
3480 on the layer type they come from. Then, it performs a NN clustering for the 3 sets of  
3481 hits separately. For the tile hits it clusters together all the hits which are in nearest-  
3482 neighbouring tiles and nearest-neighbouring layers, for strip hits it looks at nearest-  
3483 neighbouring strips and next-to-nearest-neighbouring layers (as the layers with strips  
3484 along the two directions are alternated). For strip clusters an additional cut in the  
3485 direction along the strip length is needed.

3486 After this first clustering I then apply a recursive re-clustering for each collection  
3487 of strip clusters based on a PCA method. In each case, we loop over the clusters with  
3488  $N_{hits} \geq 2$ , computing the centre of mass and three principal components. Propagating  
3489 these axes up to the layers of the rest of the clusters, we check if the propagated point  
3490 and the centre of mass of the second cluster are within next-to-nearest-neighbouring  
3491 strips. An additional cut in the direction along the strip length is also needed. Moreover,  
3492 I require that the two closest hits across the two clusters are at most in next-to-nearest-  
3493 neighbouring strips. I merge the clusters if these three conditions are satisfied. The

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3494 re-clustering is repeated until no more cluster pairs pass the cuts.

3495 The clusters in each strip view are combined if their centres of mass are close enough  
3496 and they point in the same direction. An alternative approach for the strip cluster  
3497 merging could be to compute the overlap between the ellipsoids defined by the principal  
3498 axes of the clusters, and then merge the pair if the overlap exceeds some threshold.  
3499 Further study is needed to understand if this change would have an impact in the overall  
3500 clustering performance.

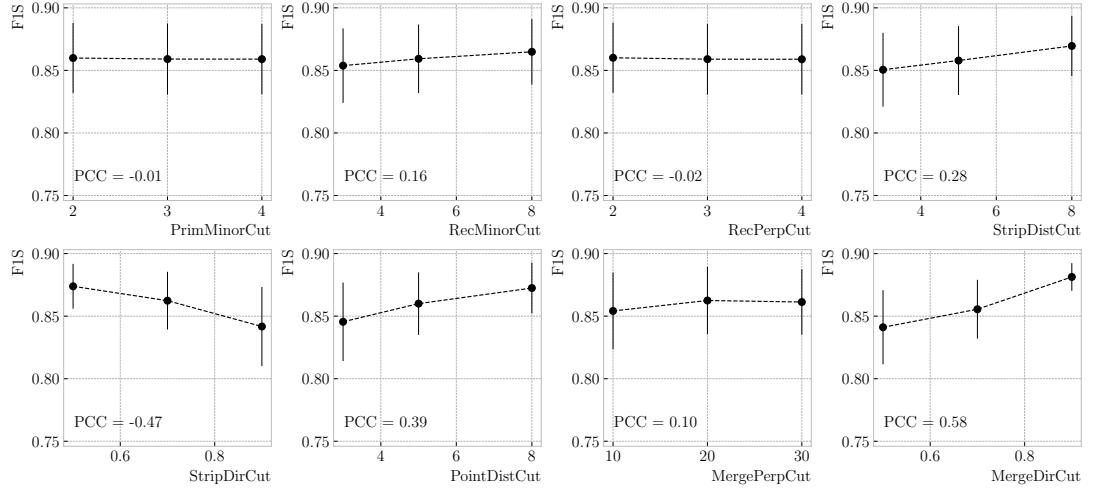
3501 To merge the tile clusters to the combined strip clusters I propagate the principal  
3502 axis of the strip cluster towards the inner layers, up to the centre of mass layer of the  
3503 tile cluster. I merge the clusters if the distance between the propagated point and the  
3504 centre of mass is below a certain cut.

3505 The last step is to check if clusters in neighbouring modules should be merged  
3506 together, both across two barrel modules, across end cap modules and between barrel  
3507 end cap modules. I check the distance between the two closest hits in the pair of clusters  
3508 and merge them if it passes this and an additional direction cut.

3509 Figure ?? presents an example of the clustering steps relevant for strip layer hits, from  
3510 the input hits (top left panel) to the NN clustering (top right panel) and re-clustering  
3511 (bottom left panel) for each strip view and the final merging strip clusters (bottom  
3512 right panel). It shows the hits from a single ECal barrel module in a  $\nu_\mu$  CC interaction  
3513 event with a neutral pion and a proton in the final state. The two clusters on the left  
3514 correspond to the photon pair from the  $\pi^0$  decay and the one on the upper right corner  
3515 is associated to the proton.

3516 This algorithm has a total number of eight free parameters that need to be optimised.  
3517 I used a sample of 1000  $\nu_\mu$  CC interactions in order to obtain the optimal configuration of  
3518 clustering parameters. This sample was generated up to the default ECal hit clustering  
3519 level, so then I could run the new clustering algorithm each time with a different  
3520 configuration of parameters. As the number of parameters is relatively large, I only  
3521 performed a coarse-grained scan of the parameter space. Sampling each of the eight  
3522 parameters at three different points each I obtain 6561 different configurations. These

## 8.5. Neutral particle identification



**Figure 8.40:** Mean values of the  $F_1$ -score marginal distributions for the different free parameters of the new clustering algorithm, with the error bars representing one standard deviation around the mean. The  $F_1$ -score values were computed for the 6561 possible parameter configurations using 1000  $\nu_\mu$  CC interaction events.

**Table 8.5:** Summary of parameters and sampled values used in the optimisation of the clustering algorithm.

Name	Units	Sampled values	Description
PrimMinorCut	strips	2, 3, 4	Distance along strip length in NN clustering
RecMinorCut	strips	3, 5, 8	Distance between propagated point and CM along strip length in re-clustering
RecPerpCut	strips	2, 3, 4	Closest hit pair distance in re-clustering
StripDistCut	strips	3, 5, 8	Distance between CMs in strip cluster merging
StripDirCut	cos	0.5, 0.7, 0.9	Main axes direction cut in strip cluster merging
PointDistCut	tiles	3, 5, 8	Distance between propagated point and CM in strip-tile matching
MergePerpCut	cm	10, 20, 30	Closest hit pair distance in module merging
MergeDirCut	cos	0.5, 0.7, 0.9	Main axes direction cut in module merging

parameters, together with the used values, are summarised in Tab. 8.5.

In order to measure the performance of the clustering, I use a binary classification approach. For each formed cluster, I identify the Geant4 Track ID of the matching MC particle and the energy fraction of each hit. Then, I assign to each cluster the Track ID with the highest total energy fraction. For each of the different Track IDs associated to the clusters, I select the cluster with the highest energy (only from the hits with the same Track ID). I identify such a cluster as the main cluster for that Track ID. I count

## Chapter 8. Particle ID in GArSoft

as true positives (TPs) the hits with the correct Track ID in each main cluster. False positives (FPs) are the hits with the incorrect Track ID for the cluster they are in, not only main clusters. The false negatives (FNs) are the hits with the correct Track ID in clusters other than the main.

Figure 8.40 shows the computed  $F_1$ -score values for the different cuts. In each case, the central value represents the mean of the  $F_1$ -score distribution for the specified value of the corresponding variable and the vertical error bar represents one standard deviation around the mean. Also shown are the Pearson correlation coefficients of these central values. We can see that five of the variables have a sizeable effect on the  $F_1$ -score, with an absolute difference between the last and first values as big as 4%.

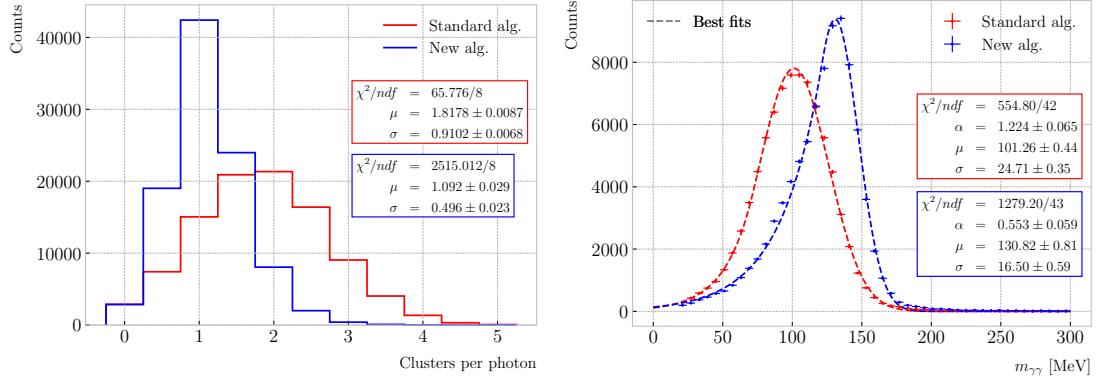
The working configuration is obtained as follows. I first select all configurations with purity  $\geq 90\%$ . Among those, I choose the combinations that yield the maximum  $F_1$ -score. If more than one configuration remains I select the one with the highest sensitivity. Doing so, I end up with a parameter configuration with an efficiency of 88% and a 90% purity. Compared with the default algorithm, which gives an efficiency of 76% and a purity of 91% for the same sample, I have managed to improve the efficiency by a factor of 1.16.

### 8.5.2 $\pi^0$ reconstruction

One of the potential applications of the new ECal hit clustering is the reconstruction of neutral particles, in particular pions. Neutral pions decay promptly after being produced, through the  $\pi^0 \rightarrow \gamma\gamma$  channel ( $98.823 \pm 0.034\%$ ) of the time. The photon pair does not leave any traces in the HPgTPC (unless one or both of them converts into an electron-positron pair), but each of them will produce an electromagnetic shower in the ECal.

To test the potential impact of the new algorithm in  $\pi^0$  reconstruction, I generated a MC sample of single, isotropic neutral pions inside the HPgTPC. All pions were generated with a momentum  $p = 500$  MeV and their initial positions were uniformly sampled inside a  $2 \times 2 \times 2$  m box aligned with the centre of the TPC. I ran both the

## 8.5. Neutral particle identification



**Figure 8.41:** Left panel: distributions of the number of ECal clusters per photon from  $\pi^0$  decays for the standard (red) and new (blue) clustering algorithms. Right panel: reconstructed invariant mass distributions for photon pairs from single  $\pi^0$  events using the standard (red) and new (blue) ECal clustering algorithms.

3558 default and the new clustering algorithms, using for the latter the optimised configuration  
 3559 discussed above.

3560 The first thing to notice is that the number of clusters produced per photon has  
 3561 decreased. Figure 8.41 (left panel) shows these distributions for the default (red) and  
 3562 new (blue) algorithms. Using a simple Gaussian fit, we see that the mean number of  
 3563 ECal clusters per photon went from  $1.82 \pm 0.01$  to  $1.09 \pm 0.03$ . This effectively means that  
 3564 with the new algorithm the ECal activity of one true particle is typically reconstructed  
 3565 as a single object. From the reconstruction point of view this can be an advantage. As  
 3566 now most of the photon energy ends up in a single ECal cluster, I can simply use cluster  
 3567 pairs to identify the  $\pi^0$  decay.

3568 In general, one calculates the invariant mass of the photon pair as:

$$m_{\gamma\gamma} = \sqrt{2E_1E_2(1 - \cos \theta)}, \quad (8.33)$$

3569 where  $E_i$  are the energies of the photons and  $\theta$  the opening angle between them. In this  
 3570 case I can use the energies deposited in the ECal and their incident directions. This  
 3571 quantity is computed for all possible pairs of clusters, using their position together with  
 3572 the true decay point. In a more realistic scenario, e.g.  $\nu_\mu$  CC interaction, one could use  
 3573 the position of the reconstructed primary vertex instead. I also tried to use the principal

## Chapter 8. Particle ID in GArSoft

3574 direction of the clusters, but that approach gave considerably worse results. For each  
3575 event I only keep the pair with an invariant mass closer to the true  $\pi^0$  mass value.

3576 Figure 8.41 (right panel) shows the invariant mass distributions for the photon pairs  
3577 we get using the default (red) and the new (blue) ECal clustering algorithms. For the fit  
3578 I used a modified version of the Crystal Ball function [116], obtained by taking the limit  
3579 where the parameter controlling the power-law tail goes to infinity:

$$f(x; N, \mu, \sigma, \alpha) = N \cdot \begin{cases} e^{\frac{\alpha(2x-2\mu+\alpha\sigma)}{2\sigma}}; & x \leq \mu - \alpha\sigma, \\ e^{-\frac{(x-\mu)^2}{2\sigma^2}}; & x > \mu - \alpha\sigma. \end{cases} \quad (8.34)$$

3580 Comparing the fitted mean and standard deviation values for the Gaussian cores, we  
3581 see that the distribution for the new algorithm is a 67% narrower and also peaks much  
3582 closer to the true  $m_{\pi^0}$  value, going from  $101.3 \pm 0.4$  MeV to  $130.8 \pm 0.6$  MeV.

<sup>3583</sup> Chapter 9

<sup>3584</sup> Event selection in ND-GAr

<sup>3585</sup> 9.1 CAFs and CAFAna

<sup>3586</sup> 9.2 Event selection

<sup>3587</sup> 9.2.1  $\nu_\mu$  CC selection

<sup>3588</sup> 9.2.2 Charged pion multiplicity



3589 Chapter 10

3590 Conclusions



<sub>3591</sub> Appendix A

<sub>3592</sub> An appendix



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