Last updated in February 28, 2025

Mohammed Azharudeen Farook Deen

Stuttgart, Germany fmdazhar@gmail.com +49-17674702880 Google Scholar fmdazhar
fmdazhar

Summary

Robotics Engineer with a strong focus on deep learning, reinforcement learning, and control engineering for cutting-edge robotic systems. Passionate about pushing the boundaries of intelligent robotics for next-generation humanoid and collaborative systems. Experienced in developing robust, real-time planning and control strategies for complex robotics tasks, including object manipulation and locomotion in simulation (Isaac Sim, Mujoco) and deploying in real-world robotic platforms (UR5e, Unitree A1).

Skills

Programming: Python, C++, MATLAB
Machine Learning & AI: PyTorch, JAX, TensorFlow, Deep Learning (CNNs, RNNs, Transformers), Reinforcement Learning (PPO, SAC), Imitation Learning (BC)
Robotics & Simulation: ROS, ROS2, Isaac Sim, Isaac Gym, Mujoco, NVIDIA Warp, Orbit
Optimization & Control: Model Predictive Control (MPC), Quadratic/Nonlinear Programming (QP, SQP), Position/Force/Torque Control
Development Tools & Systems: Git, Docker, Linux
Languages: English (Business Fluency), German (Beginner), Tamil (Native)

Education

RWTH Aachen University *Oct 2021 – Dec 2024*
Master of Science in Robotic Systems Engineering

- *Coursework:* Robotic Systems, Advanced Machine Learning, Introduction to AI, Computer Vision, Reinforcement Learning and Learning-Based Control, Linear Control Systems, Numerical Optimization, etc.

Shiv Nadar University *Aug 2015 - May 2019*
Bachelor of Technology in Mechanical Engineering

- Specialization in Computational Techniques; Minor in Electronics and Communication Engineering

Relevant Work Experience

Intern *Stuttgart, Germany*
Fraunhofer IPA *July 2024 – Mar 2025*

- Implemented real-time reinforcement learning(SAC) and imitation learning (BC) pipelines for precise object manipulation, integrating GPU-based optimization in Python and JAX.
- Various tuned control modules like Impedance, Inverse Kinematics, and hybrid position-force controllers with keyboard and spacemouse control for **Learning from Demonstrations**.
- Developed a custom Peg-in-Hole Mujoco environment and ROS1/ROS2 frameworks for controlling a real robot equipped with a Robotiq hand gripper.
- Currently evaluating with the simulated and real-world UR5e robot.

Robot Learning of Quadrupedal Locomotion on Deformable Terrain *Master Thesis — RWTH Institute for Data Science in Mechanical Engineering (DSME) and RWTH Institute of Geomechanics and Underground Technology (GUT)* *Aachen, Germany* *Sep 2023 – Mar 2024*

- Identified the challenges quadrupeds face when transitioning from rigid to deformable terrains.
- Implemented a contact model to simulate the complex behaviors of granular materials in NVIDIA Isaac Sim, Developed an adaptable and robust controller using Reinforcement Learning (RL) with PPO algorithm in PyTorch to follow a unified policy under diverse natural environments and evaluated the performance with sim-to-real additions.
- A related paper is being finalized for **submission to CASE 2025** with ongoing experimental results.

Accepted Conferences

Rapid Quadrupedal Locomotion on Deformable Terrain - 1st German Robotics Conference March 2025
Mohammed Azharudeen Farook Deen, Omer Kemal Adak, Raul Fuentes
https://www.robotics-institute-germany.de/conference/

A Novel Heat Transfer Mechanism Using Acoustic Waves - Presented at International Heat and Mass Transfer Conference, IIT Roorke Dec 2019
Azharudeen M, Pothuri C, Subramani K

Journal Publications

Theory of nonlinear acoustic forces acting on inhomogeneous fluids. Journal of Fluid Mechanics. [IF(2022)-3.7] April 2022
Rajendran VK, Jayakumar S,*Azharudeen M*, Subramani K
https://doi.org/10.1017/jfm.2022.257

Heat transfer mechanism driven by acoustic body force under acoustic fields. Physical Review Fluids. [IF(2021)-2.5] July, 2021
Azharudeen M, Kumar V, Pothuri C, Subramani K
https://doi.org/10.1103/PhysRevFluids.6.073501

Rapid mixing in microchannel using standing bulk acoustic waves. Physics of Fluids. [IF(2020)-3.5] Dec 2019
Azharudeen M, Pothuri C, Subramani K
https://doi.org/10.1017/jfm.2022.257

Additional Experience & Projects

Student Assistant *Aachen, Germany*
RWTH Institute for Automatic Control (RWTH IRT) *May 2023 – June 2024*

- Developed a code base to have a unified C++ interface for various quadratic programming solvers (QP) like OSQP, etc. and nonlinear programming (NLP) solvers like IPOPT, etc., with loosely coupled tools for MPC, NMPC, SQP, auto differentiation, and Hessian regularization methods, etc.
- Involved in the Fernbin project, where my tasks included developing simple simulation for testing control systems in Python and ROS2 for ships that react dynamically to the surroundings.

Research Project *Aachen, Germany*
Automated and Connected Driving Challenges — RWTH Institute for Automotive Engineering (ika) *Apr 2023 – Aug 2023*

- Enhanced trajectory planning in autonomous vehicles using Model Predictive Control (MPC) by refining the cost function to include better prioritization of dynamic elements and explored integrating hard constraint-level collision avoidance.

Teaching Assistant *Aachen, Germany*
RWTH Institute of Geomechanics and Underground Technology (RWTH GUT) *Apr 2023 – Sep 2023*

- Implemented engaging programming exercises, conducted tutorial sessions, fostering student understanding of key robotics programming concepts in Python and ROS for the course “Introduction to Robotics”.

Research Assistant *Kancheepuram, India*
Microscale Transport Laboratory, Indian Institute of Information Technology (IIITDM)) *Aug 2019 – Mar 2021*

- Studied predominant microscale phenomena subjected to acoustic fields and published results in various reputed journals.