

14. Transportation

Description

Only transport the robot in its original packaging. Save the packaging material in a dry place if you want to move the robot later.

When moving the robot from its packaging to the installation space, hold both tubes of the robot arm at the same time. Hold the robot in place until all mounting bolts are securely tightened at the base of the robot.

Lift the Control Box by its handle.

Warning: Lifting



WARNING

Incorrect lifting techniques, or using improper lifting equipment, can lead to injury.

- Avoid overloading your back or other body parts when lifting the equipment.
- Use proper lifting equipment.
- All regional and national lifting guidelines shall be followed.
- Make sure to mount the robot according to the instructions in Mechanical Interface.



NOTICE

If the robot is attached to 3rd-party application / installation during transport, please refer to the following:

- Transporting the robot without its original packaging will void all warranties from Universal Robots A/S.
- If the robot is transported attached to a 3rd-party application / installation, follow the recommendations for transporting the robot without the original transport packaging.

Disclaimer

Universal Robots cannot be held responsible for any damage caused by transportation of the equipment.

You can see the recommendations for transportation without packaging at: universal-robots.com/manuals

Description

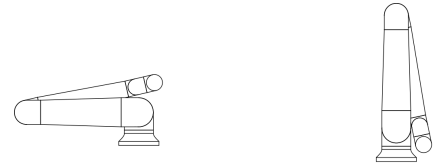
Universal Robots always recommends transporting the robot in its original packaging. These recommendations are written to reduce unwanted vibrations in joints and brake systems and reduce joint rotation.

If the robot is transported without its original packaging, then please refer to the following guidelines:

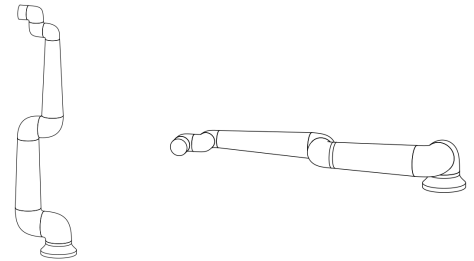
- Fold the robot as much as possible - do not transport the robot in the singularity position.
 - Move the center of gravity in the robot as close to the base as possible.
 - Secure each tube to a solid surface on two different points on the tube.
 - Secure any attached end effector rigidly in 3 axes.
-

Transport

Fold the robot as much as possible.



Do not transport extended.
(singularity position)



Secure the tubes to a solid surface.
Secure attached end effector in 3 axes.

