8.6. Three Position Enabling Device

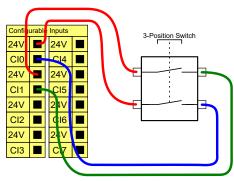
Description

The robot arm is equipped with an enabling device in the form of the 3PE Teach Pendant.

The Control Box supports the following enabling device configurations:

- · 3PE Teach Pendant
- · External Three-Position Enabling device
- · External Three-Position device and 3PE Teach Pendant

The illustration below shows how to connect a Three-Position Enabling device.



Note: The two input channels for the Three-Position Enabling Device input have a disagreement tolerance of 1 second.



NOTICE

The UR robot safety system does not support multiple external Three-Position Enabling Devices.

Operational Mode Switch

Using a Three-Position Enabling device requires the use of an Operational Mode switch.

The illustration below shows an Operational Mode switch.

