## 8.6. Three Position Enabling Device

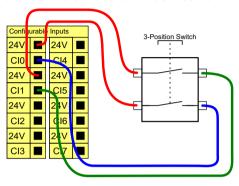
## Description

The robot arm is equipped with an enabling device in the form of the 3PE Teach Pendant.

The Control Box supports the following enabling device configurations:

- · 3PE Teach Pendant
- External Three-Position Enabling device
- External Three-Position device and 3PE Teach Pendant

The illustration below shows how to connect a Three-Position Enabling device.



Note: The two input channels for the Three-Position Enabling Device input have a disagreement tolerance of 1 second.



## NOTICE

The UR robot safety system does not support multiple external Three-Position Enabling Devices.

## Operational Mode Switch

Using a Three-Position Enabling device requires the use of an Operational Mode switch.

The illustration below shows an Operational Mode switch.

