

# 10. First Time Use

## Description

This section describes how you get started using the robot. Among other things, it covers easy start-up, an overview of the PolyScope user interface and how to set up your first program. Additionally, it covers free drive mode and basic operation.

## 10.1. Quick System Start-up

### Quick System Start

#### MANDATORY ACTION

Before using the PolyScope, verify the robot arm and Control Box are correctly installed.

This is how you quickly start up the robot.

1. On the **Teach Pendant**, press the emergency stop button.
2. On the Teach Pendant, press the power button and allow the system to start, displaying text on the **PolyScope**.
3. A popup appears on the touch screen indicating that the system is ready and that the robot must be initialized.
4. In the popup dialog, tap **Go to Initialize Screen** to access the Initialize screen.
5. Unlock the emergency stop button to change robot state from **Emergency Stopped** to **Power off**.
6. Step outside the reach (workspace) of the robot.
7. On the **Initialize Robot** screen, tap the **ON** button and allow robot state to change to **Idle**.
8. In the **Payload** field, in **Active Payload**, verify the payload mass. You can also verify the mounting position is correct, in the **Robot** field.
9. Tap the **Start** button, for the robot to release its brake system. The robot vibrates and makes clicking sounds indicating it is ready to be programmed.



#### NOTICE

Learn to program your Universal Robots robot on [www.universal-robots.com/academy/](https://www.universal-robots.com/academy/)