# 4041 Homework 1

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6.5

### 6.5-8

The operation HEAP-DELETE(A,i) deletes the item in node i from heap A. Give an implementation of HEAP-DELETE that runs in  $O(\lg n)$  time for an n-element max-heap.

```
HEAP-DELETE(A,i)

if (i < 1 or i > A.heap-size)
    return error "not a valid node"

else
    swap(A[i], A[A.heap-size])
    popVal = A[A.heap-size]
    A.heap-size -= 1

HEAP-INCREASE-KEY(A,i,A[i])
    MAX-HEAPIFY(A,i)
    return popVal
```

#### 6.5 - 9

Give an  $O(n \lg k)$ -time algorithm to merge k sorted lists into one sorted list, where n is the total number of elements in all the input lists. (*Hint:* a min-heap for k-way merging.)

The most efficient way to sort pre-sorted lists into one large list is to use a priority queue, or more specifically, a min-heap. First thing to do is put the first elements of each list into a binary heap structure. Once this is done, we can pop the root node, and replace it with it's corresponding next element, then the priority queue will heapify everything for us in  $\lg k$  time. We keep appending the root nodes of the min-heap onto our new sorted list until all the lists in the heap have been emptied. When an array runs out of elements in our min-heap, we can just call HEAP-DELETE to completely remove the node for us, and finally continue until every element has been removed from the heap.

It takes O(k) time to build the heap out of the lists. Each value is extracted from the heap in constant time O(1), but we extract n times, so we can treat it as O(n). And for re-organizing the heap, it takes  $O(\lg k)$  time, which is called n times (for each time an element is removed) making it  $O(n \lg k)$ . Finally there are the times where we need to delete an element from the heap when a list runs out of elements. This takes  $O(\lg k)$  time, and is called k times, making it  $O(k \lg k)$ . Therefore our whole algorithm runs in  $O(k) + O(n) + O(n \lg k) + O(k \lg k) = O(n \lg k)$  time.

Technically the above time complexities weren't 100% accurate because every time HEAP-DELETE is called, there's one less element on the heap, making it's run time a bit more efficient than  $k \lg k$ . This also makes the HEAPIFY call a bit more efficient too, because instead of  $n \lg k$ , it's more like  $n_1 \lg k + n_2 \lg (k-1) + \cdots + n_k \lg 1$ , where  $n_1, \ldots, n_k$  represent the number of elements in each input list. But this is essentially equal to  $n \lg k$ , and big-O notation is pretty lenient.

# 2.3

#### 2.3-2

Rewrite the MERGE procedure so that it does not use sentinels, instead stopping once either array L or R has had all its elements copied back to A and then copying the remainder of the other array back into A.

```
MERGE(A,p,q,r)
 n1 = q - p + 1
 n2 = r - q
  new arr L[1 ... n1+1]
  for (int i = 1; i <= n1; i++)
   L[i] = A[p + i - 1]
  new arr R[1 ... n2+1]
  for (int j = 1; j \le n1; j++)
   L[i] = A[q + j]
  int i,j = 1
  int k = p;
  while (i <= n1 and j <= n2)
    if (L[i] < R[j])
      A[k++] = L[i++] // assignment followed by increment
    else
      A[k++] = R[j++]
  if (i <= n1)
    for (; i <= n1; i++)
                          // initial condition already stated => not necessary
     A[k++] = L[i]
                            // k incremented after assignment, and i incremented
  if (j \le n2)
                             // through the for loop
    for (; j <= n2; j++)
      A[k++] = R[j]
```

#### 2.3 - 3

Use mathematical induction to show that when n is an exact power of 2, the solution of the recurrence

$$T(n) = \begin{cases} 2 & \text{if } n = 2, \\ 2T(n/2) + n & \text{if } n = 2^k, \text{ for } k > 1 \end{cases}$$

is  $T(n) = n \lg n$ .

BASE CASE: n = 2.  $2 \lg 2 = 2$ , so the base case holds.

INDUCTIVE STEP: Assume  $T(a) = a \lg a$  is true if  $a = 2^b$  for some  $b \in \mathbb{Z}, b > 1$ . We can use this assumption to show that  $T(c) = c \lg c$ , where  $c = 2^{b+1}$ .

$$\begin{split} T(c) &= T(2^{b+1}) \\ &= 2T(2^b) + 2^{b+1} \\ &= 2 \cdot 2^b \lg(2^b) + 2^{b+1} \\ &= 2^{b+1} (\lg(2^b) + 1) \\ &= 2^{b+1} (\lg(2^b) + \lg(2)) \\ &= 2^{b+1} \lg(2 \cdot 2^b) \\ &= 2^{b+1} \lg(2^{b+1}) \\ &= c \lg c \end{split}$$

Since we know that  $T(2) = 2 \lg 2$  (base case), and that  $T(2^k) = 2^k \lg(2^k) \Rightarrow T(2^{k+1}) = 2^{k+1} \lg(2^{k+1})$  for k > 1 (inductive step), we know that the solution to the above recurrence must be  $T(n) = n \lg n$ .

#### 2.3 - 4

We can express insertion sort as a recursive procedure as follows. In order to sort A[1...n] we recursively sort A[1...n-1] and then insert A[n] into the sorted array A[1...n-1]. Write a recurrence for the running time of this recursive version of insertion sort.

#### 2.3-5

Referring back to the searching problem (see Exercise 2.1-3), observe that if the sequence A is sorted, we can check the midpoint of the sequence against v and eliminate half of the sequence from further consideration. The binary search algorithm repeats this procedure, halving the size of the remaining portion of the sequence each time. Write pseudocode, either iterative or recursive, for binary search. Argue that the worst-case running time of binary search is  $\Theta(\lg n)$ .

# 7.2

### 7.2 - 1

Use the substitution method to prove that the recurrence  $T(n) = T(n-1) + \Theta(n)$  has the solution  $T(n) = \Theta(n^2)$ , as claimed at the beginning of Section 7.2.

# 7.3

#### 7.3 - 1

Why do we analyze the expected running time of a randomized algorithm and not its worst-case running time?