Certifiable Neural Networks safeai.ethz.ch



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SafeAl - safeai.ethz.ch

Collaborators



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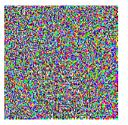
Publications (discussed here):

- ▶ ICML'18 Differentiable Abstract Interpretation for Provably Robust Neural Networks (DiffAI)
- ► ICLR'20 Universal Approximation with Certified Networks
- ► NeurIPS'18 Fast and Effective Robustness Certification (ERAN)
- S&P'18 Al2: Safety and Robustness Certification of Neural Networks with Abstract Interpretation

Motivation - Adversarial Attacks



"panda" 57.7% confidence



 $+.007 \times$



"gibbon" 99.3 % confidence

Overview of Neural Network Safety

Identifying vulnerability

Adversarial attacks: Goodfellow et al. (2014)

Reducing vulnerability

Adversarial training: Madry et al. (2018)

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Robustness certification: AI2, ERAN

Increasing certifiable invulnerability

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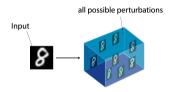
Certifiable training: DiffAl

Al2 - First scalable verifier for neural networks.

DiffAl - First scalable framework for certifiable training.

Preliminary Property - L_{∞} Adversarial Ball

Many developed attacks: Goodfellow et al. (2014); Madry et al. (2018); Evtimov et al. (2017); Athalye & Sutskever (2017); Papernot et al. (2017); Xiao et al. (2018); Carlini & Wagner (2017); Yuan et al. (2017); Tramèr et al. (2017)



$$Ball_{\epsilon}(input) = \{attack \mid ||input - attack||_{\infty} \leq \epsilon \}$$

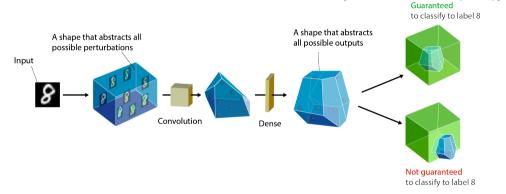
A net is ϵ -robust at x if it classifies every example in $Ball_{\epsilon}(x)$ the same and correctly

Certification

Robustness Certification

 ${\it Verification}$: Prove that a network is ϵ -robust at a point

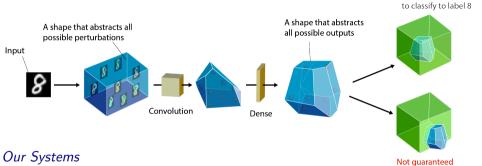
Abstract Interpretation: certify by over-approximation [Cousot & Cousot (1977)]



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- - ► Al2 Box/Interval, Zonotope [Gehr et al. (2018)]
 - ▶ DiffAl HybridZono, zBox, zDiag, zSwitch, zSmooth [Mirman et al. (2018)]
 - ► ERAN DeepZono [Singh et al. (2018)]

Image Credit: Petar Tsankov

Guaranteed

to classify to label 8

Abstract Interpretation

Cousot & Cousot (1977)

Abstract Interpretation is heavily used in industrial large-scale program analysis to compute over-approximation of program behaviors 1

Provide

- ightharpoonup domain $\mathcal D$ of abstract objects d
- concretization function $\gamma: \mathcal{D} \to \mathcal{P}(\mathbb{R}^n)$
- ightharpoonup concrete function $f: \mathbb{R}^n \to \mathbb{R}^n$

Develop a sound transformer $f^\#:\mathcal{D} o\mathcal{D}$

¹For example by Astrée: Blanchet et al. (2003)

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- ▶ Affine transform of *k*-cube onto *p* dims
- ightharpoonup Ball $_{\epsilon}$: perfect
- $(\cdot M)^{\#}$: perfect
- ► ReLU[#]: zBox, zDiag, DeepZono

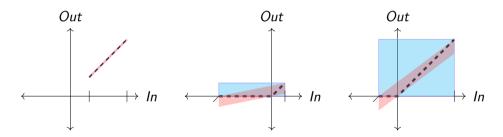
Zonotope Domain

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Zonotope Domain

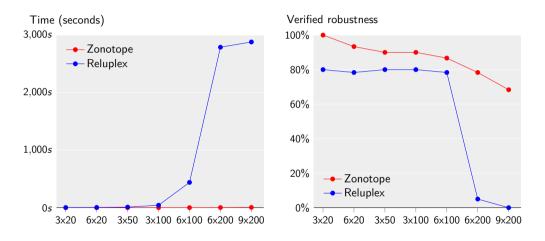
Example ReLU Transformers for Zonotope

Examples of zBox (blue) and DeepZono (red) for approximating Out = ReLU(In) (dashed line).



- zBox: Treat as Box when surrounding zero
- ▶ DeepZono: Minimize area in In/Out plane.

Al2 Certification Results



Comparison to Reluplex, Katz et al. (2017), on small feed-forward networks for MNIST.

Training

Reducing Vulnerability

Certification Caveat

- ▶ Neural networks aren't robust by default.
- Why try to certify non-robust networks?

Adversarial Training

Defense: Train a network so that most inputs are mostly robust.

▶ Madry et al. (2018); Tramèr et al. (2017); Cisse et al. (2017); Yuan et al. (2017)

Certifiable Training

- Experimentally robust nets not necessarily certifiably robust
- ▶ Intuition: not all correct programs are easily provable

Certifiable Training

Train a Network to be Certifiably Robust²

Given:

- ightharpoonup Net $_{\theta}$ with weights θ
- Training inputs and labels

Find:

lacktriangledown that maximizes number of inputs we can *certify* are ϵ -robust

²Also addressed by: Raghunathan et al. (2018); Kolter & Wong (2017); Dvijotham et al. (2018)

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Method

- Design a loss function based on certification goal
- Differentiate through certifier
- Perform SGD

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Scalability CIFAR10

| | | | Time to Train 1 Epoch | |
|-------------------------|-------------|---------------|-----------------------|--------|
| Model | #Neurons | #Weights | Baseline | DiffAl |
| SkipNet-18 ³ | \sim 558k | \sim 16mill | 152s | 260s |

- ► Can use a less precise domain for training than for certification
- ► Can test and train with larger nets than prior work

 $^{^{3}}$ like that described by He et al. (2016) but without pooling or dropout.

Robustness Provability

CIFAR10 with $\epsilon =$ 0.012 4

| Training Method | %Certified DeepZono |
|-----------------|---------------------|
| Baseline | 0 |
| Adversarial | 7 |
| DiffAI | 64 |

- Significantly increases provability with scalable verifiers.
- ightharpoonup For small ϵ we lose little accuracy.

⁴Numbers from Singh et al. (2018) on 100 test images

The Gap

The state of the art still far from goal

- ▶ Balunovic & Vechev (2019) gets 60.5% certified robustness and 78.4% accuracy on CIFAR10 with $\epsilon = \frac{2}{255}$
- ▶ Standard training > 95% accuracy.

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- Universal approximation implies robust networks exist.
- Network verification is NP-complete in general.
- Do robust and convexly certifiable networks exist?

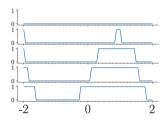
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They provably exist!⁵



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Universal Approximation with Certified Networks

Universal Interval-Certified Approximation

Let $\Gamma \subset \mathbb{R}^m$ be a compact set and let $f \colon \Gamma \to \mathbb{R}$ be a continuous function. For all $\delta > 0$, there exists a ReLU network n such that for all boxes [a,b] in Γ defined by points $a,b \in \Gamma$ where $a_k \leq b_k$ for all k, the propagation of the box [a,b] using interval analysis through the network n, denoted $n^{\sharp}([a,b])$, approximates the set $[I,u] = [\min f([a,b]), \max f([a,b])] \subseteq \mathbb{R}$ up to δ ,

$$[I+\delta,u-\delta]\subseteq n^{\sharp}([a,b])\subseteq [I-\delta,u+\delta]$$

tldr: univeral approximation can be lifted to nets that are certifiably robust with Box.

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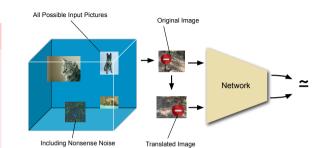
Future Work

Describe lower & upper bounds on size/depth/width with certifiable networks

Beyond Local Robustness

Network Invariants (Future Work)

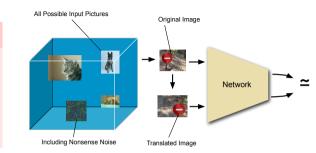
- Verify properties across every possible input.
- ► Invariance to translations, rotations, arbitrary perturbations.

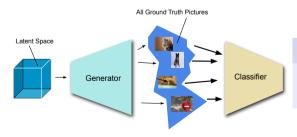


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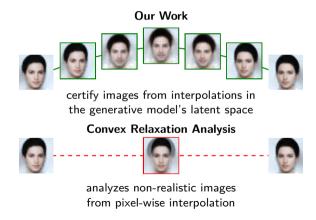


Generative Specifications (Ongoing)

Specify input with generative models [Mirman et al. (2020)]

Generative Specifications

- ► Generative specifications are necessarily non-convex.
- Feasible Restriction: Interpolative Specifications



Conclusion

First scalable certification framework



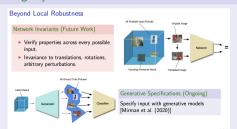
First scalable certification training framework



Existence of interval provable nets



Going beyond local robustness



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