Angle Transformations for Double Photoemission

Ameya Patwardhan

February 28, 2022

1 Convention for angles

The following convention is adopted for all global angles:

- Right Handed coordinate system
- positive Z-axis along the manipulator (vertical) axis
- positive X-axis along Analyser 1 away from the sample
- positive Y-axis along Analyser 2 away from the sample
- θ - ϕ coordinate system is constructed with
 - $-\theta = 0$ corresponding to the positive Z-pole
 - $-\phi = 0$ corresponding to the positive X-axis

The convention for the detector angles is as follows:

- θ - ϕ coordinate system with
 - $-\theta = 0$ corresponding to the center of the Analyser
 - $-\phi = 0$ corresponding to the direction towards the manipulator (vertical) axis with rotation in the anticlockwise direction as seen towards $\theta = \pi$

The convention for angles wrt to sample normal is

- alpha is the analogue of the polar angle (theta) away from the sample normal;
- beta is the analogue of the azimuthal angle (phi) measured from the direction towards the z-axis pole towards

2 Angle Transformation

2.1 Analyser Coordinates to Global Coordinates

$$\cos \theta_g = \sin \theta_i \cos \phi_i \tag{1}$$

$$\sin(\phi_g - \phi_d) = \frac{\sin\phi_i \sin\theta_i}{\sin\theta_g} \tag{2}$$

(3)

Global Coordinates to Sample Coordinates 2.2

$$\cos \alpha = \cos \theta_g \cos \theta_s + \sin \theta_g \sin \theta_s \cos (\phi_g - \phi_s) \tag{4}$$

(5)

Defining hav $x = \sin^2 \frac{x}{2}$

$$hav\alpha = hav (\theta_q - \theta_s) + \sin \theta_q \sin \theta_s hav (\phi_q - \phi_s)$$
(6)

$$hav\alpha = hav (\theta_g - \theta_s) + \sin \theta_g \sin \theta_s hav (\phi_g - \phi_s)$$

$$\sin(\frac{\alpha}{2}) = \sqrt{\sin^2 \frac{(\theta_g - \theta_s)}{2} + \sin \theta_g \sin \theta_s \sin^2 \frac{(\phi_g - \phi_s)}{2}}$$
(6)

$$hav\theta_g = hav(\theta_s - \alpha) + \sin\theta_s \sin\alpha hav\beta \tag{8}$$

$$hav\beta = \frac{\sin^2 \frac{\theta_g}{2} - \sin^2 \frac{\theta_s - \alpha}{2}}{\sin \theta_s \sin \alpha} \tag{9}$$

$$hav\beta = \frac{\sin^2 \frac{\theta_g}{2} - \sin^2 \frac{\theta_s - \alpha}{2}}{\sin \theta_s \sin \alpha}$$

$$hav\beta = \frac{1}{2} \frac{\cos (\theta_s - \alpha) - \cos \theta_g}{\sin \theta_s \sin \alpha}$$
(9)

$$2\sin^2\frac{\beta}{2} = -2\frac{\sin\left(\frac{\theta_s - \alpha - \theta_g}{2}\right)\sin\left(\frac{\theta_s - \alpha + \theta_g}{2}\right)}{\sin\theta_s\sin\alpha}$$
(11)

$$\sin^2 \frac{\beta}{2} = \frac{\sin\left(\frac{\theta_g - \theta_s + \alpha}{2}\right)}{\sin \alpha} \frac{\sin\left(\frac{\theta_s + \theta_g - \alpha}{2}\right)}{\sin \theta_s} \tag{12}$$

Define $\gamma = \frac{\theta_g - \theta_s - \alpha}{2}$

$$\sin^2 \frac{\beta}{2} = \frac{\sin(\alpha + \gamma)}{\sin \alpha} \cdot \frac{\sin(\theta_s + \gamma)}{\sin \theta_s}$$
 (13)