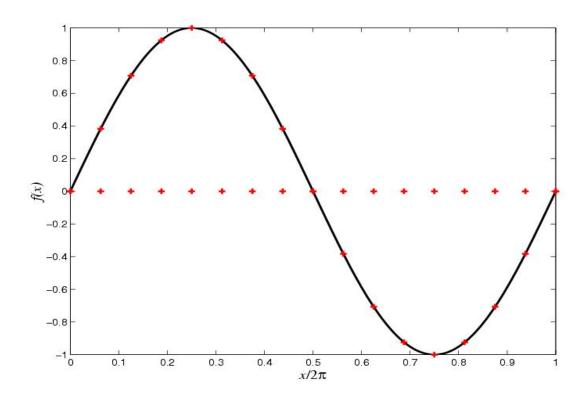
#### **MAE 6220**

# **Applied Computational Fluid Dynamics**

ELIAS BALARAS

 Consider a function only known at a set of uniformly distributed discrete points



 Finite differences are obtained by removing the limit from the definition of a derivative:

$$\frac{df_i}{dx} = \lim_{\Delta x \to 0} \frac{f(x_i + \Delta x) - f(x_i)}{\Delta x}$$

$$\simeq \frac{f(x_i + \Delta x) - f(x_i)}{\Delta x}$$

$$= \frac{f(x_{i+1}) - f(x_i)}{\Delta x}$$

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Forward Finite-Difference Approximation

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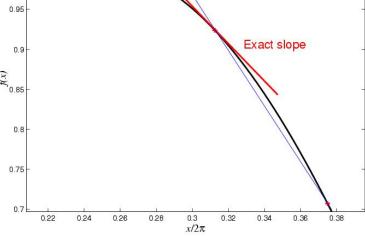
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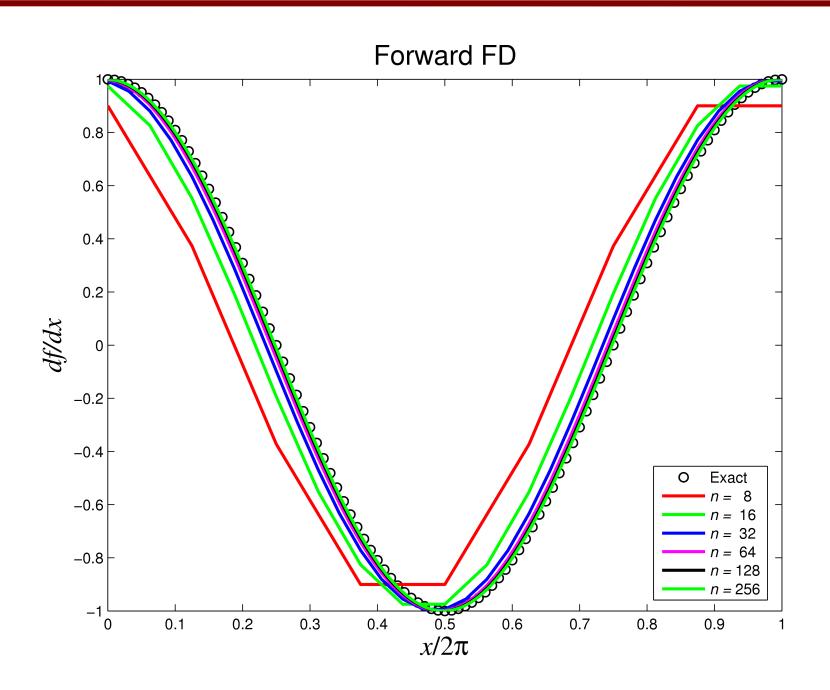
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Forward Finite-Difference Approximation 4.000



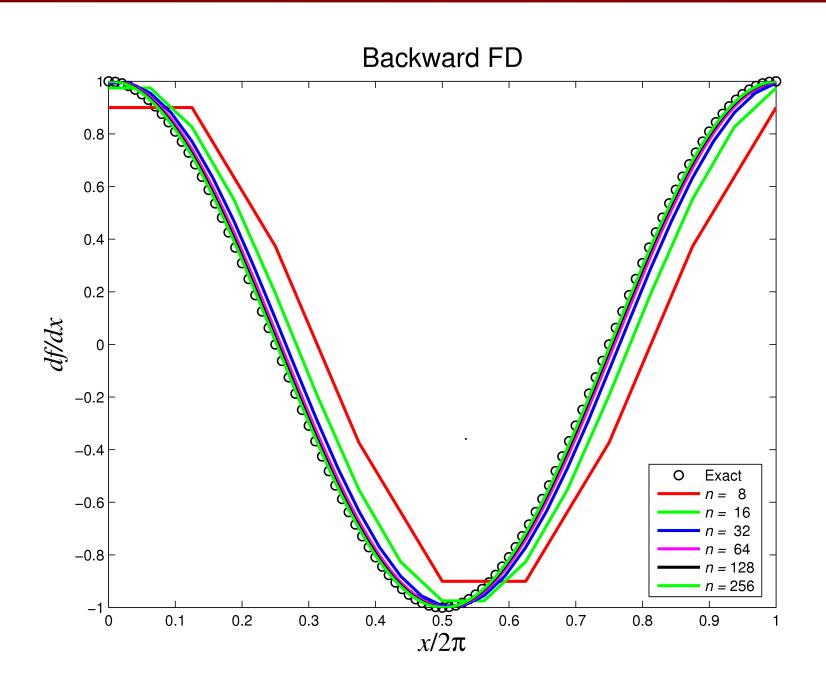
Forward difference



 Finite differences are obtained by removing the limit from the definition of a derivative:

$$rac{df_i}{dx} = \lim_{\Delta x o 0} rac{f(x_i) - f(x_i - \Delta x)}{\Delta x}$$
 $\simeq rac{f(x_i) - f(x_i - \Delta x)}{\Delta x}$ 
 $= rac{f(x_i) - f(x_{i-1})}{\Delta x}$ 
 $= rac{f_i - f_{i-1}}{\Delta x}$ 
Backward difference
e-difference Approximation

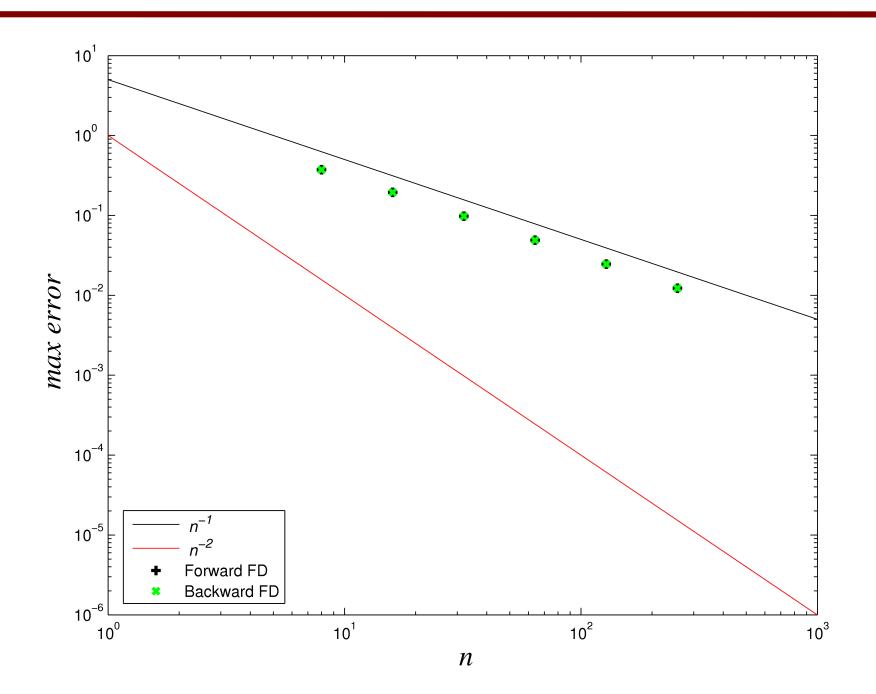
**Backward Finite-difference Approximation** 

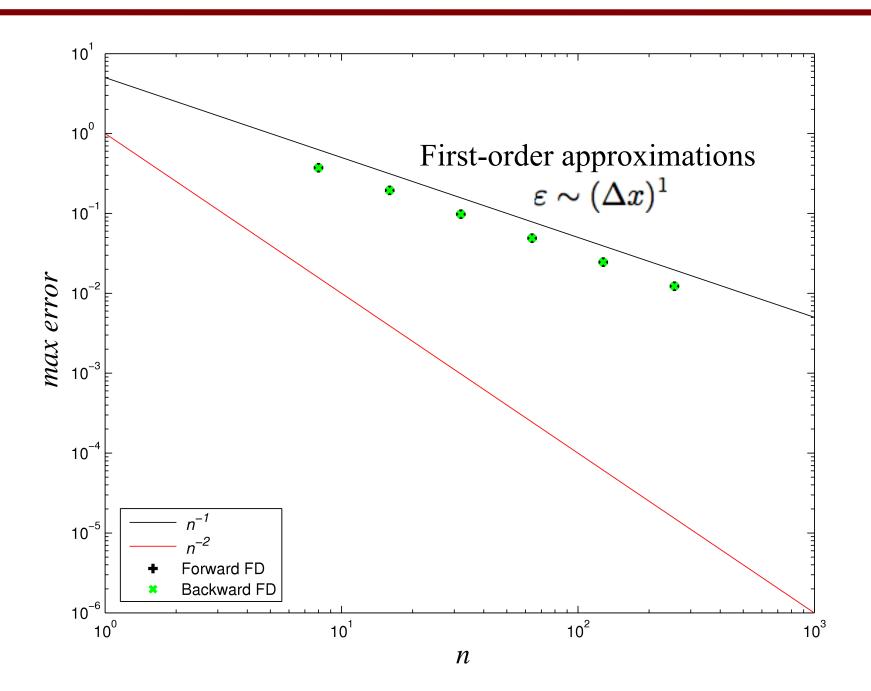


• Define an error norm:

$$\varepsilon = \max\left(\left|\frac{df}{dx} - \frac{\delta f}{\delta x}\right|\right)$$

• Evaluate as the grid is refined (number of points is increased).

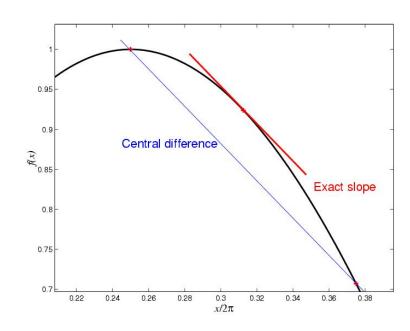


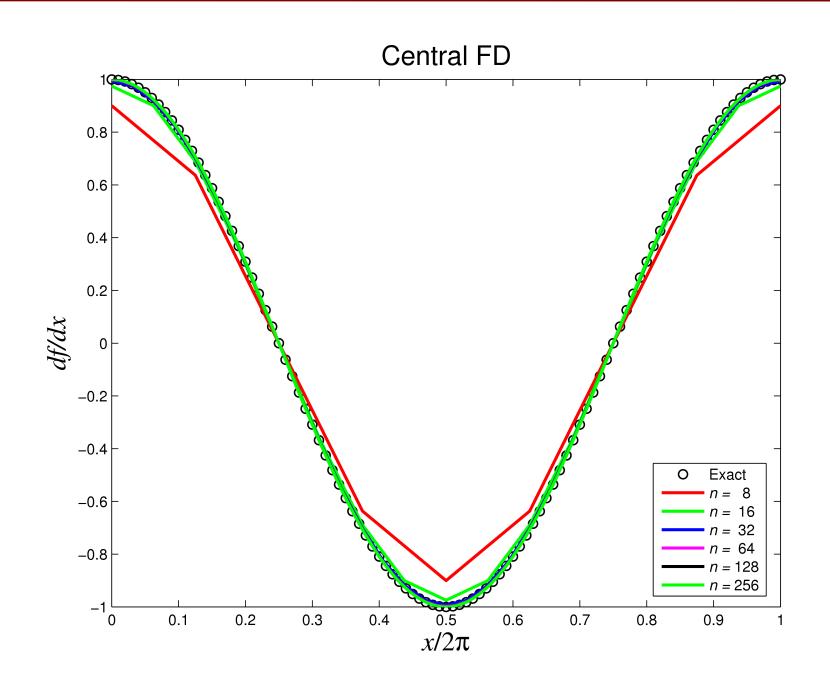


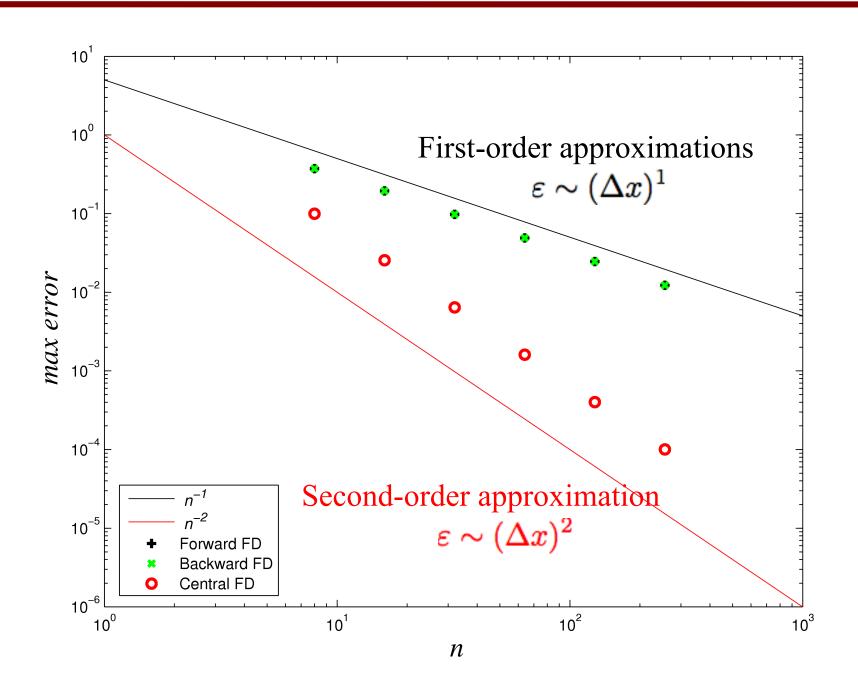
Taking the average of the two:

$$\frac{df_i}{dx} \simeq \frac{1}{2} \left( \frac{f_{i+1} - f_i}{\Delta x} + \frac{f_i - f_{i-1}}{\Delta x} \right)$$
$$= \frac{f_{i+1} - f_{i-1}}{2\Delta x}$$

#### **Central Finite-Difference Approximation**



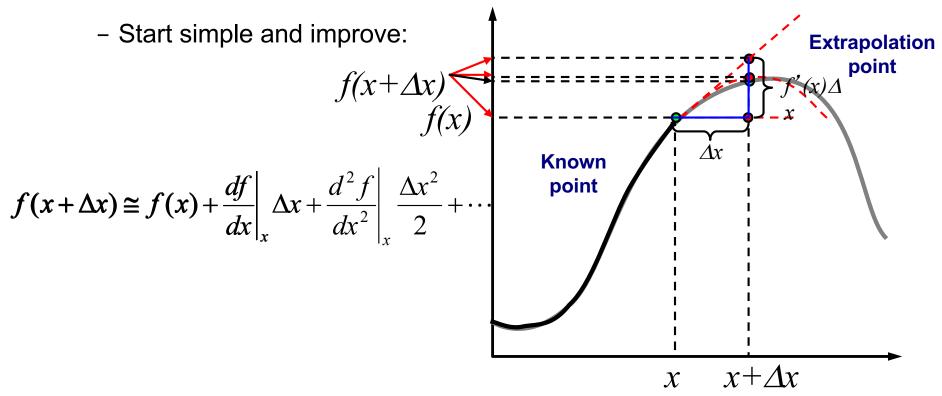




#### **Taylor series - review**

#### Taylor series:

- □ *Method to extrapolate function value at positions where f is unknown, using known values of f and its derivatives*
- □ How?



 Given any finite-difference approximation of a derivative, its order of accuracy can be calculated by using Taylor series.

$$\phi_{j+1} = \phi_j + \phi'_j h + \frac{h^2}{2!} \phi''_j + \frac{h^3}{3!} \phi'''_j + o(h^4)$$

$$\phi_{j-1} = \phi_j - \phi'_j h + \frac{h^2}{2!} \phi''_j - \frac{h^3}{3!} \phi'''_j + o(h^4)$$

$$\frac{\delta_c \phi}{\delta x} = \frac{\phi_{j+1} - \phi_{j-1}}{2h} = \phi'_j + \frac{h^2}{3!} \phi'''_j$$

- One can use Taylor series to construct a finite-difference scheme of any order of accuracy.
- Example: three-point forward (j+2, j+1 and j) 2nd-order approximation to  $\delta \phi / \delta x$ :

$$\phi_{j+2} = \phi_j + \phi'_j 2h + \frac{4h^2}{2!} \phi''_j + \frac{8h^3}{3!} \phi'''_j + o(h^4)$$

$$\phi_{j+1} = \phi_j + \phi'_j h + \frac{h^2}{2!} \phi''_j + \frac{h^3}{3!} \phi'''_j + o(h^4)$$

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$$\frac{\delta \phi}{\delta x} = \alpha \phi_{j+2} + \beta \phi_{j+1} + \gamma \phi_j$$

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$$\phi_{j+1} = \phi_j + \phi'_j h + \frac{h^2}{2!} \phi''_j + \frac{h^3}{3!} \phi'''_j + o(h^4)$$

$$\phi_j = \phi_j$$

$$\frac{\delta \phi}{\delta x} = \alpha \phi_{j+2} + \beta \phi_{j+1} + \gamma \phi_j$$

$$= (\alpha + \beta + \gamma) \phi_j + (2\alpha + \beta) h \phi'_j$$

$$+ (4\alpha + \beta) \frac{h^2}{2} \phi''_j + (8\alpha + \beta) \frac{h^3}{6} \phi'''_j + o(h^4)$$

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- Example: three-point forward (j+2, j+1 and j) 2nd-order approximation to  $\delta \phi / \delta x$ :

$$lpha = -rac{1}{2h}; \qquad eta = rac{4}{2h}; \qquad \gamma = -rac{3}{2h}$$
  $rac{\delta\phi}{\delta x} = lpha\phi_{j+2} + eta\phi_{j+1} + \gamma\phi_{j}$   $= rac{-\phi_{j+2} + 4\phi_{j+1} - 3\phi_{j}}{2h} - rac{2h^{2}}{3}\phi_{j}''' + o(h^{3})$ 

Commonly used schemes for the first derivative:

Commonly used schemes for the first derivative: 
$$\phi'_{j} = \frac{\phi_{j} - \phi_{j-1}}{h} + o(h) \qquad 1^{\text{st-order backwards}}$$

$$= \frac{\phi_{j+1} - \phi_{j}}{h} + o(h) \qquad 1^{\text{st-order forwards}}$$

$$= \frac{\phi_{j+1} - \phi_{j-1}}{2h} + o(h^{2}) \qquad 2^{\text{nd-order central}}$$

$$= \frac{3\phi_{j} - 4\phi_{j-1} + \phi_{j-2}}{2h} + o(h^{2}) \qquad 2^{\text{nd-order backwards}}$$

$$= \frac{-3\phi_{j} + 4\phi_{j+1} - \phi_{j+2}}{2h} + o(h^{2}) \qquad 2^{\text{nd-order forwards}}$$

$$= \frac{-\phi_{j+2} + 8\phi_{j+1} - 8\phi_{j-1} + \phi_{j-2}}{12h} + o(h^{4}) \qquad 4^{\text{th-order central}}$$

Commonly used schemes for the second derivative:

$$\phi_j'' = \frac{\phi_{j+1} - 2\phi_j + \phi_{j-1}}{h^2} + o(h^2)$$

$$= \frac{\phi_j - 2\phi_{j-1} + \phi_{j-2}}{h^2} + o(h)$$

$$= \frac{\phi_j - 2\phi_{j+1} + \phi_{j+2}}{h^2} + o(h)$$

$$= \frac{\phi_j - 2\phi_{j+1} + \phi_{j+2}}{h^2} + o(h)$$
1st-order forwards

- If a stencil with n points is used to calculate a finite-difference approximation for a derivative, at most one can obtain an approximation of order n-1.
- More accurate approximations (for a given stencil) can be obtained by expanding both the function and its derivatives in Taylor series.

$$\alpha_{1}\phi_{j+1} + \alpha_{2}\phi_{j} + \alpha_{3}\phi_{j-1} + \beta_{1}h\phi'_{j+1} + \beta_{3}h\phi'_{j-1}$$

$$= (\alpha_{1} + \alpha_{2} + \alpha_{3}) \phi_{j}$$

$$+ (\alpha_{1} - \alpha_{3} + \beta_{1} + \beta_{3}) \phi'_{j}h$$

$$+ (\alpha_{1} + \alpha_{3} + 2\beta_{1} - 2\beta_{3}) \phi''_{j}h^{2}/2!$$

$$+ (\alpha_{1} - \alpha_{3} + 3\beta_{1} + 3\beta_{3}) \phi'''_{j}h^{3}/3!$$

$$+ (\alpha_{1} + \alpha_{3} + 4\beta_{1} - 4\beta_{3}) \phi_{j}^{iv}h^{4}/4!$$

$$+ (\alpha_{1} - \alpha_{3} + 5\beta_{1} + 5\beta_{3}) \phi_{j}^{v}h^{5}/5! + o(h^{6}).$$

$$\alpha_{1}\phi_{j+1} + \alpha_{2}\phi_{j} + \alpha_{3}\phi_{j-1} + \beta_{1}h\phi'_{j+1} + \beta_{3}h\phi'_{j-1}$$

$$= (\alpha_{1} + \alpha_{2} + \alpha_{3})\phi_{j}$$

$$= (\alpha_{1} - \alpha_{3} + \beta_{1} + \beta_{3})\phi'_{j}h$$

$$+ (\alpha_{1} - \alpha_{3} + 2\beta_{1} - 2\beta_{3})\phi''_{j}h^{2}/2!$$

$$+ (\alpha_{1} - \alpha_{3} + 3\beta_{1} + 3\beta_{3})\phi''_{j}h^{3}/3!$$

$$+ (\alpha_{1} + \alpha_{3} + 4\beta_{1} - 4\beta_{3})\phi''_{j}h^{5}/5! + o(h^{6}).$$

$$\alpha_{1}\phi_{j+1} + \alpha_{2}\phi_{j} + \alpha_{3}\phi_{j-1} + \beta_{1}h\phi'_{j+1} + \beta_{3}h\phi'_{j-1}$$

$$= (\alpha_{1} + \alpha_{2} + \alpha_{3})\phi_{j}$$

$$= 1 + (\alpha_{1} - \alpha_{3} + \beta_{1} + \beta_{3})\phi'_{j}h$$

$$= 0$$

$$+ (\alpha_{1} + \alpha_{3} + 2\beta_{1} - 2\beta_{3})\phi''_{j}h^{2}/2!$$

$$= 0$$

$$+ (\alpha_{1} - \alpha_{3} + 3\beta_{1} + 3\beta_{3})\phi''_{j}h^{3}/3!$$

$$= 0$$

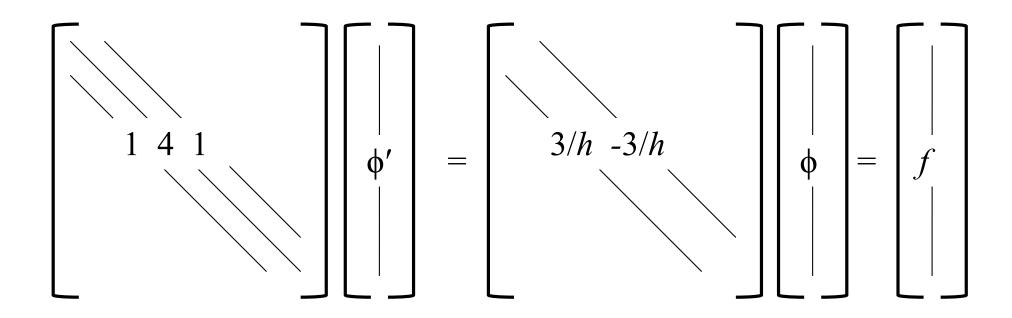
$$+ (\alpha_{1} + \alpha_{3} + 4\beta_{1} - 4\beta_{3})\phi''_{j}h^{5}/5! + o(h^{6}).$$

$$\alpha_1 = -\alpha_3 = 3/4;$$
  $\alpha_2 = 0;$   $\beta_1 = \beta_3 = -1/4.$ 

$$\phi'_{j-1} + 4\phi'_j + \phi'_{j+1} = \frac{3}{h} (\phi_{j+1} - \phi_{j-1}) + o(h^4).$$

$$\phi'_{j-1} + 4\phi'_j + \phi'_{j+1} = \frac{3}{h} (\phi_{j+1} - \phi_{j-1}) + o(h^4).$$

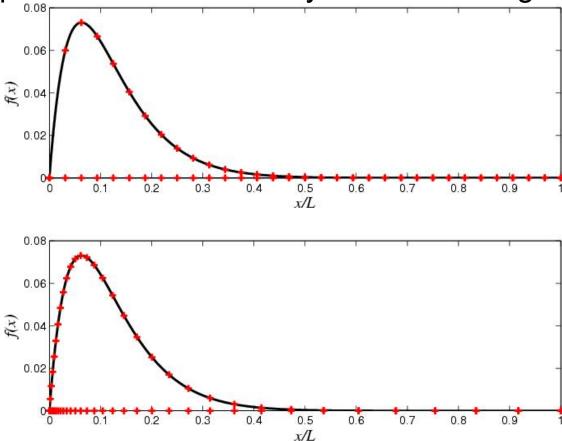
 The evaluation of the derivative requires matrix inversion (tridiagonal in this case)



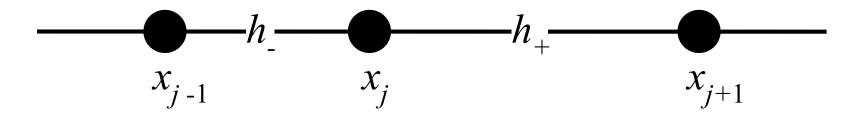
### Non-uniform grids

 Sometime the function has sharp gradients confined to a small region of the domain:

 In such cases a uniform mesh may be inconvenient, since the number of points is determined by the minimum grid spacing.



#### Non-uniform grids



Nominally 1st-order; 2nd-order on smooth grids

$$\frac{\delta\phi_j}{\delta x} = \frac{\phi_+ - \phi_-}{h_+ + h_-} = \phi_j' + \frac{h_+ - h_-}{2}\phi'' + o(h^2)$$

• 2nd-order

$$\frac{\delta\phi_j}{\delta x} = \frac{1}{h_+ + h_-} \left[ \frac{h_-}{h_+} \phi_+ - \left( \frac{h_-}{h_+} - \frac{h_+}{h_-} \right) \phi - \frac{h_+}{h_-} \phi_- \right] = \phi_j' + o(h^2)$$

## **Grid types**

Hyperbolic tangent

$$x_j = L \left[ 1 + \frac{\tanh(\eta_j \tanh a)}{a} \right]; \qquad \eta_j = -1 + \frac{j-1}{N};$$

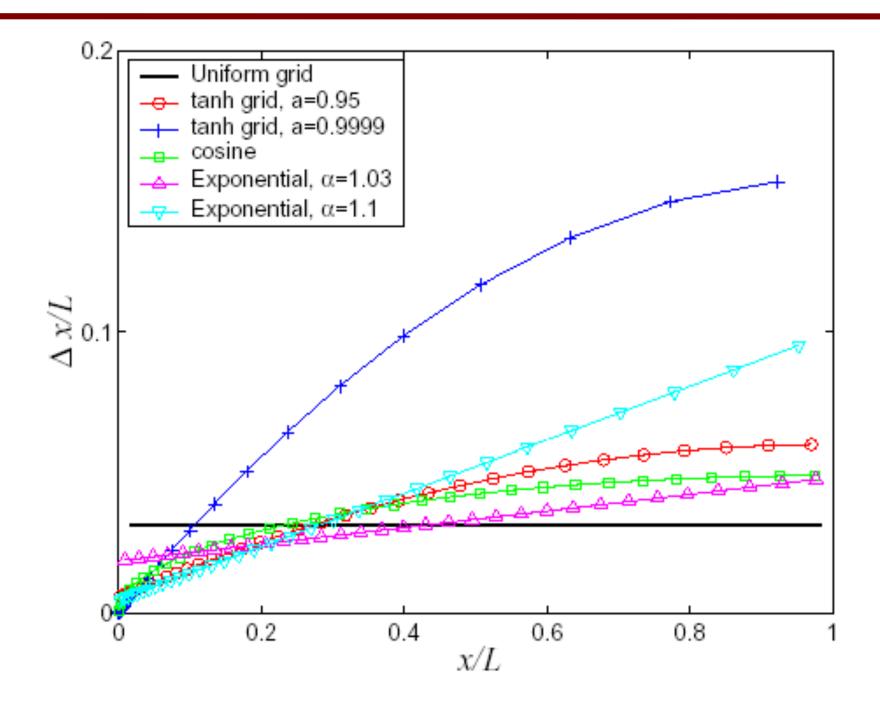
Cosine

$$x_j = L\left(-1 + \cos\theta_j\right); \qquad \theta_j = \frac{j-1}{N}\frac{\pi}{2};$$

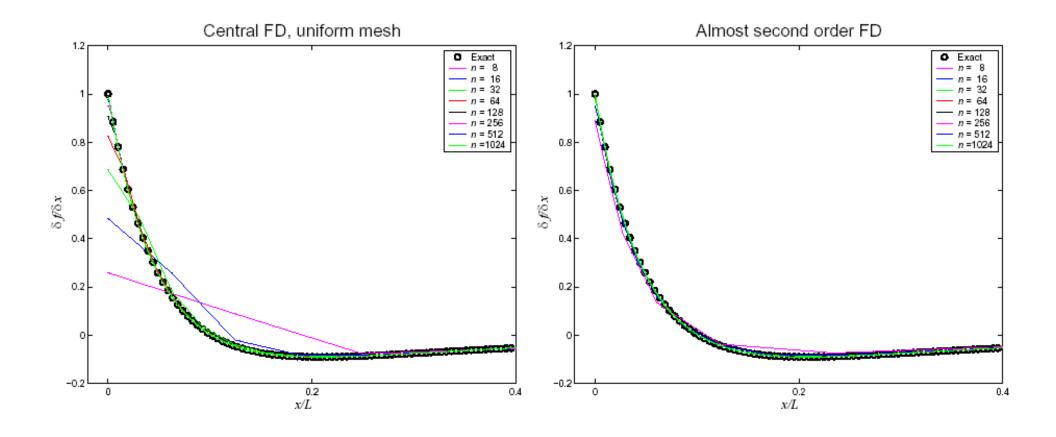
Exponential

$$x_j = x_{j-1} + \Delta x_{j-1}; \qquad \Delta x_j = \Delta x_o \alpha^j;$$

## **Grid types**



# Non-uniform grids



## Non-uniform grids

