

Universitat de Girona  
Fundació UdG: Innovació i Formació

ViT Visualization for  
Transparency  
Foundation

MVT

EC

Data Visualization Program-  
ming Anton Bardera Data Visu-  
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Bardera Data Visualization  
Programming Anton Bardera  
Data Visualization Program-  
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alization Programming Anton  
Bardera Data Visualization

# Visual Encoding

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- The way in which data is mapped into visual structures, upon which we build the images on a screen
- Items or links are represented using **marks** or geometrical primitives
- The changes on the mark's appearance based on a data attribute are called **channels**

*Channel = Visual Variable*

# Marks

- Marks for Items: basic geometric elements

- Points
- Lines
- Areas
- Volume: rarely used

➔ Points



➔ Lines

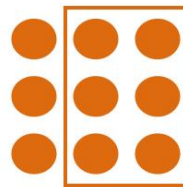


➔ Areas

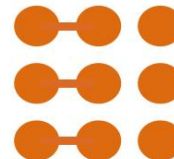


- Marks for Links

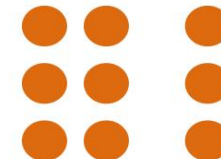
- Containment
- Connection
- Proximity



Containment



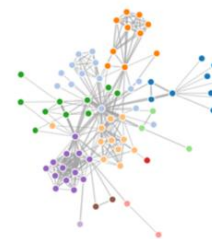
Connection



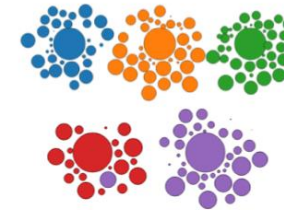
Proximity



Collins et al. 2009



D3.js Example

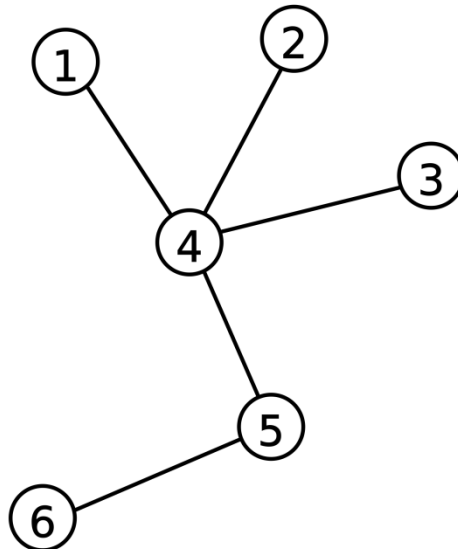


D3.js Example

# Graphs and Trees

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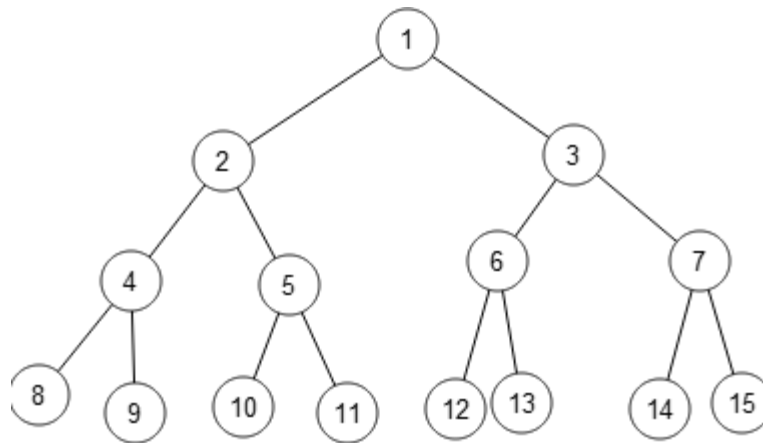
- A graph  $G$  consists of a collection of vertices or nodes  $V$  and a set of edges  $E$
- Each edge  $e$  connects two vertices  $x$  and  $y$
- For example:  $V=\{1,2,3,4,5,6\}$ ,  
 $E=\{(1,4),(2,4),(3,4),(4,5),(4,6)\}$



# Graphs and Trees

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- **Trees:** graphs with no cycles
- *Connected graph with  $N-1$  edges*
- Represent hierarchical structure
- Nodes are related as *parent, children, sibling (family tree)*
- Root node: highest hierarchy



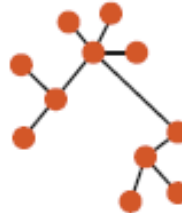
# Graphs representations

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- Three types:

- ➔ **Node-Link Diagrams**  
Connection Marks

✓ NETWORKS    ✓ TREES



- ➔ **Adjacency Matrix**  
Derived Table

✓ NETWORKS    ✓ TREES



- ➔ **Enclosure**  
Containment Marks

✗ NETWORKS    ✓ TREES



# Tree visualization

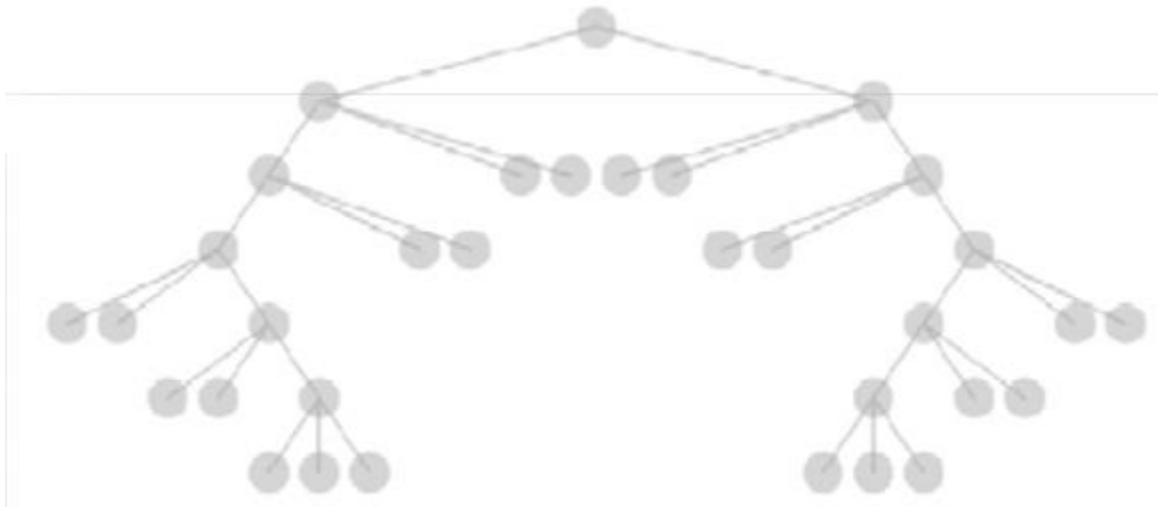
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- Node-link approach
  - Nodes are distributed in space
  - Edges represented by straight or curved lines
  - Typical approach in tree visualization is to use X for breadth and Y for depth (or viceversa)
  - Often space is used to communicate hierarchical orientation
  - Recursion makes it elegant and fast to draw trees

# Tree visualization

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- **Naïve approach:** repeatedly divide space for subtrees by leaf count
- **Problems:**
  - Exponential growth of breadth
  - No efficient use of the whole canvas





# Tree visualization: Reingold-Tilford

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- **Goal**

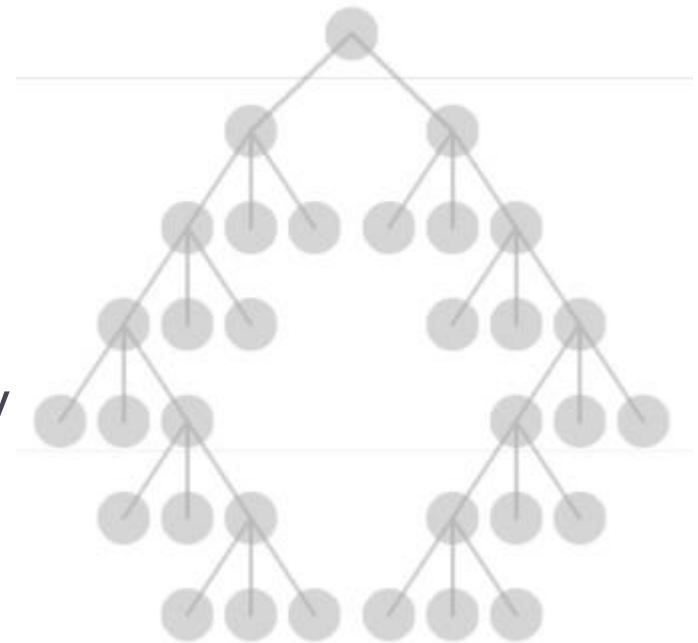
- make smarter use of space
- maximize density and symmetry

- **Design concerns**

- clearly encode depth level
- no edge crossings
- isomorphic subtrees drawn identically
- compact

- **Approach**

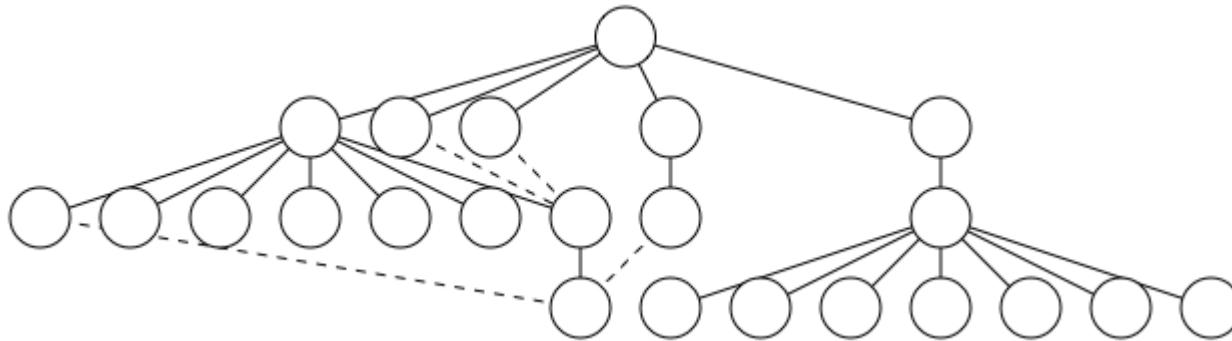
- bottom-up recursive approach
- for each parent make sure every subtree is drawn
- pack subtrees as closely as possible
- center parent over subtrees



# Tree visualization: Reingold-Tilford

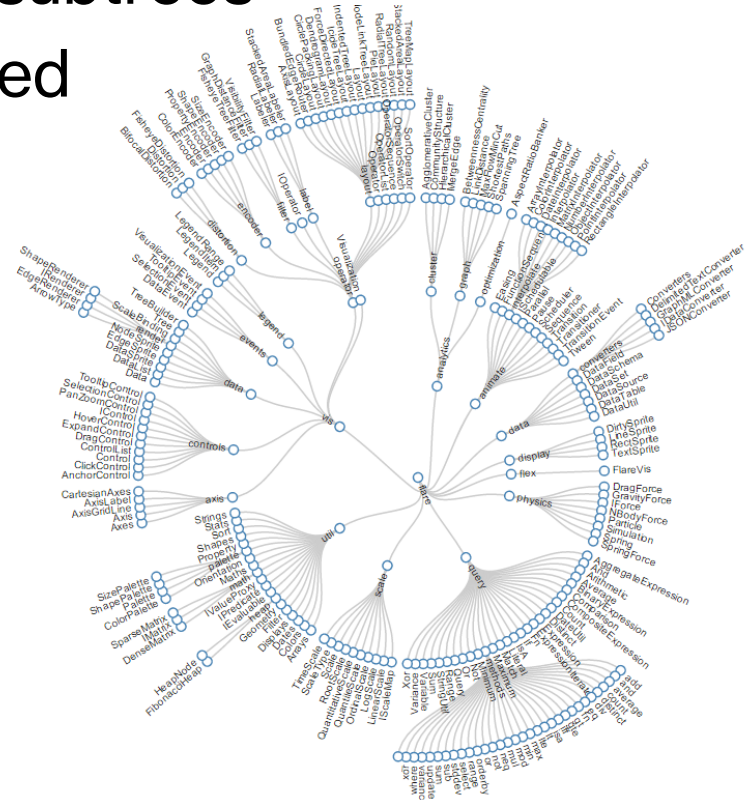
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- Algorithm: [original paper](#)
  - Do a post-order traversal of the tree
  - if the node is a leaf, give it an x coordinate of 0
  - otherwise, for each of its children, place the child as close to its left sibling as possible
  - place the parent node halfway between its leftmost and rightmost children



# Tree visualization: Radial layout

- Node-link diagram in polar coordinates
- Radius encodes depth with root in center
- Angular sectors assigned to subtrees
- Reingold-Tilford can be applied



# Tree visualization: Node-link problems

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- **Scale**

- tree breadth often grows exponentially
- quickly run out of space!

- **Solutions**

- hyperbolic layout
- filtering
- scrolling or panning
- zooming

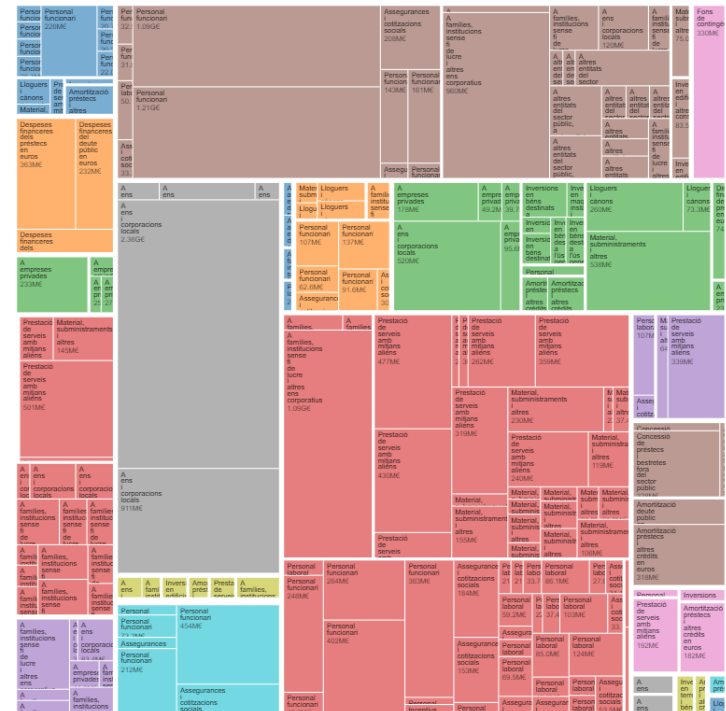
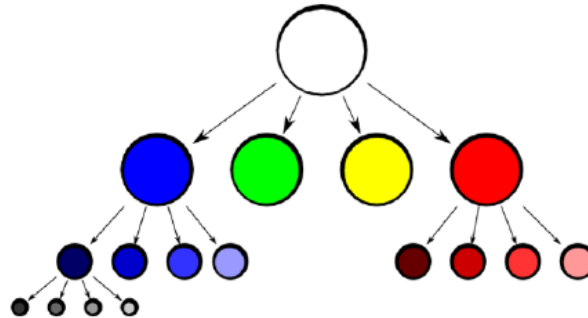
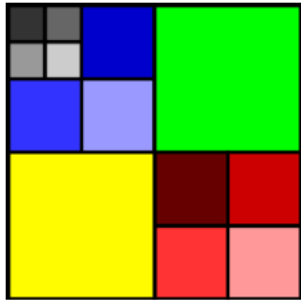
# Tree visualization: Enclosure diagrams

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- **Encode structure using spatial enclosure**
  - often referred to as *treemaps*
- **Benefits**
  - provides single view of entire tree
  - easier to spot small / large nodes
- **Problems**
  - difficult to accurately read depth

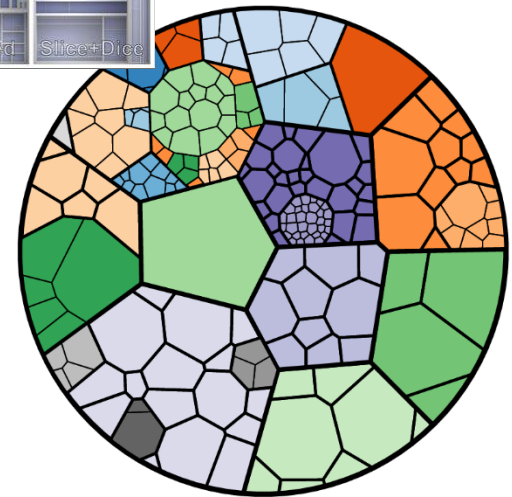
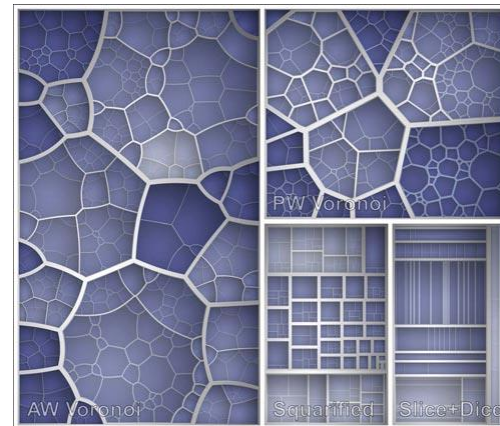
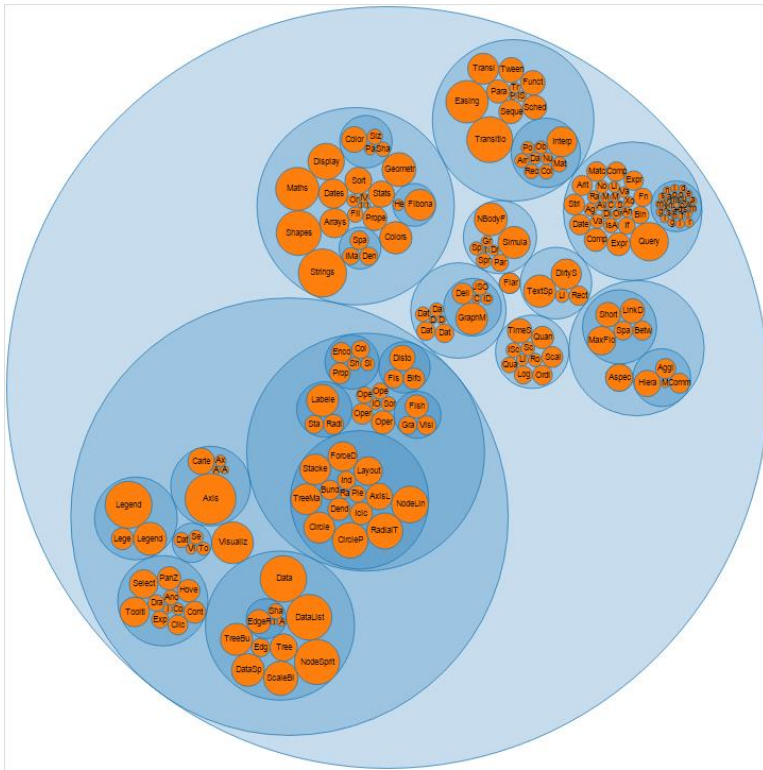
# Tree visualization: Treemaps

- recursively fill space based on a size metric for nodes
- enclosure indicates hierarchy
- additional measures can control aspect ratio of cells



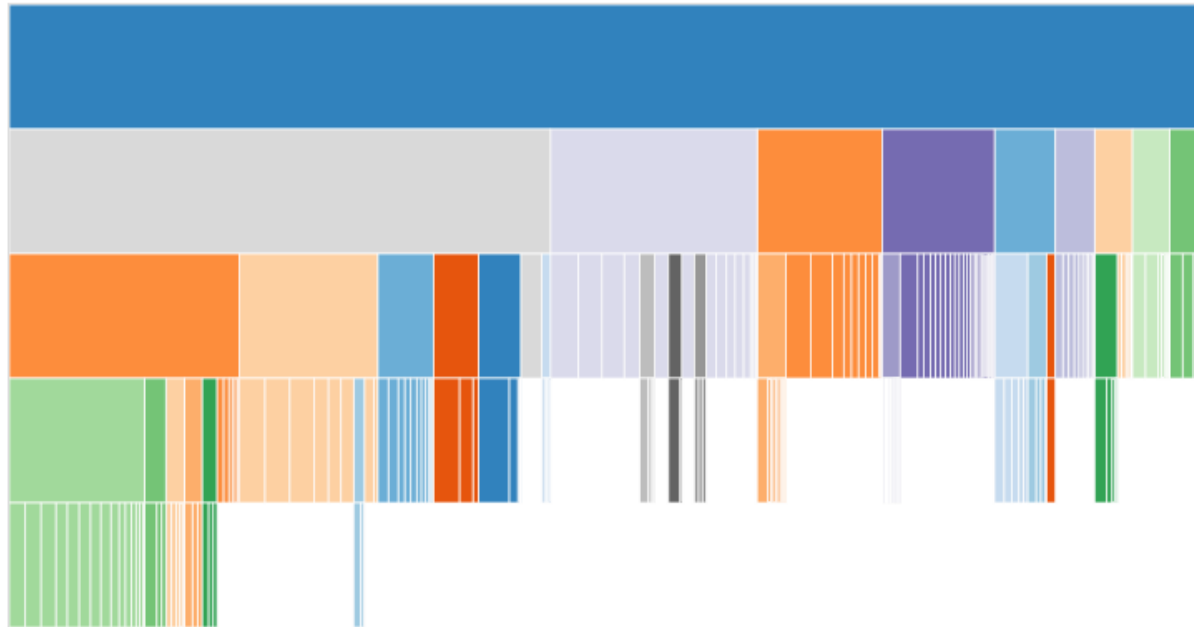
# Tree visualization: Treemaps

- Most often use rectangles, but other shapes are possible: circles, Voronoi tessellation,...



# Tree visualization: Icicle

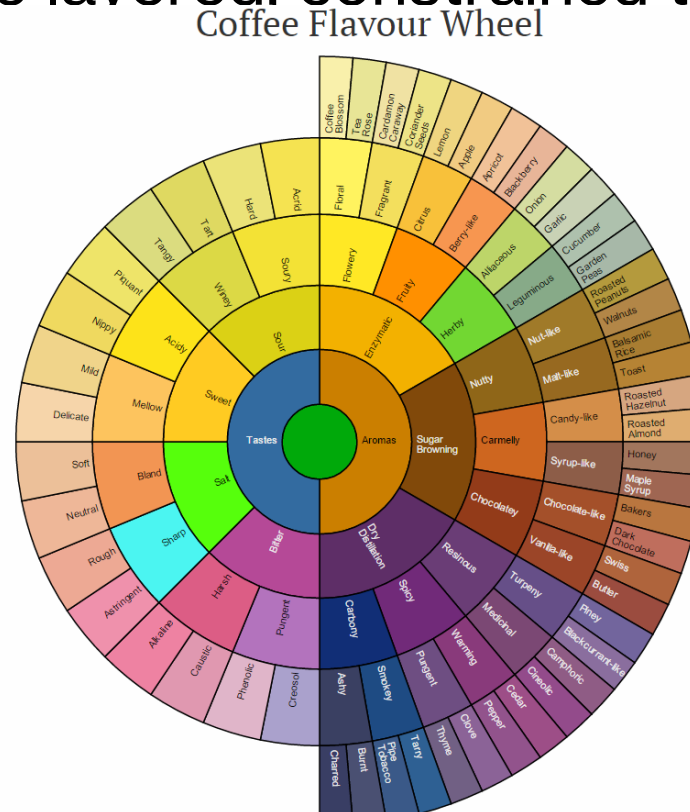
- Higher-level nodes get a larger layer area, whether that is horizontal extent.
- Child levels are layered, constrained to parent's extent





# Tree visualization: Sunburst Trees

- Similar than icicle using circular layout and angular extent
- Child levels are layered. constrained to parent's extent



# Tree visualization survey










- <http://treevis.net/>

How to cite this site?   
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treevis.net - A Visual Bibliography of Tree Visualization 2.0 by Hans-Jörg Schulz

v.28-AUG-2015

Dimensionality Representation Alignment Fulltext Search Techniques Shown

All    All    All     x 286

