

Flightplan: Dataplane Disaggregation and Placement for P4 programs

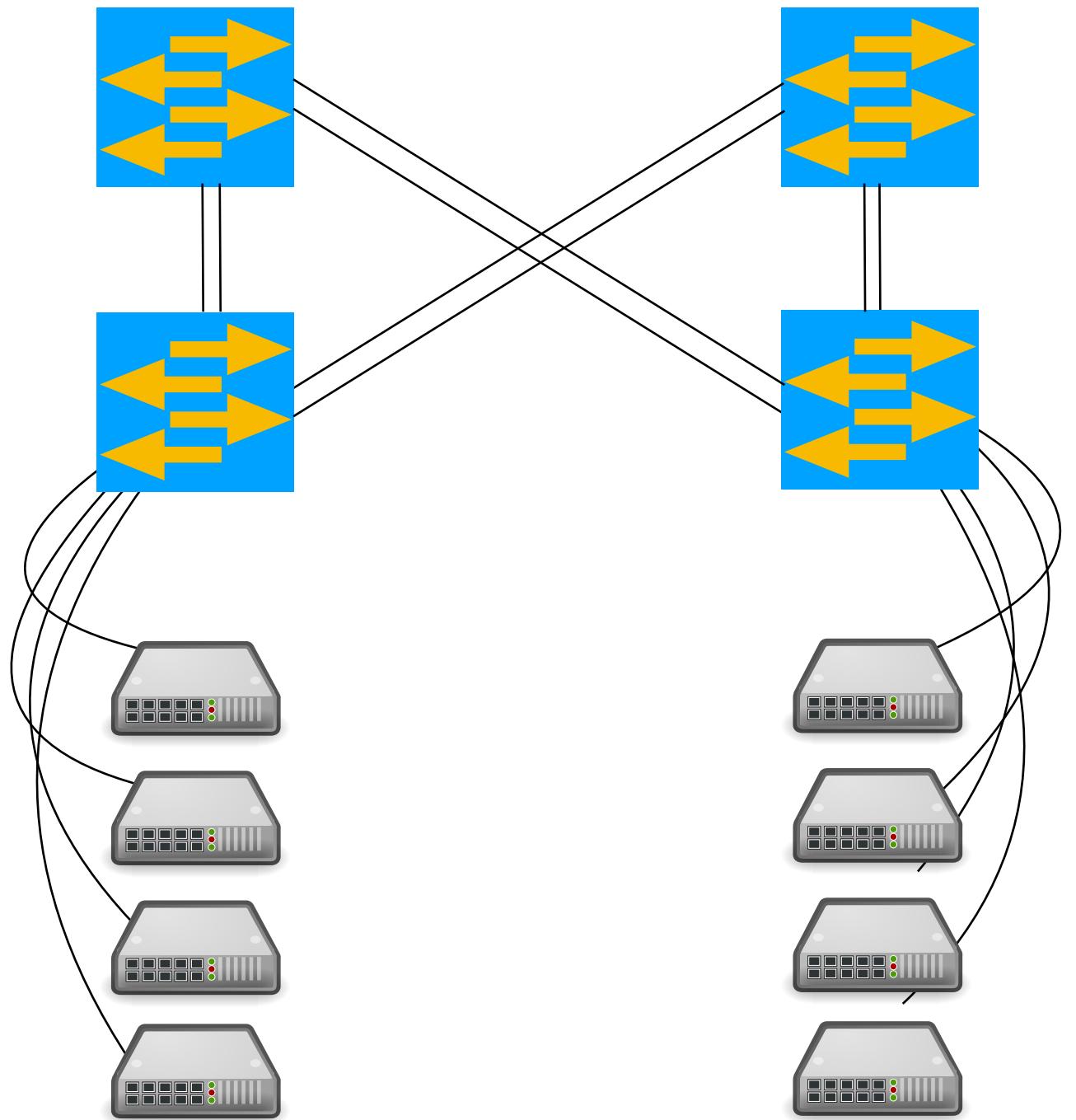
Nik Sultana John Sonchack Hans Giesen Isaac Pedisich Zhaoyang Han
Nishanth Shyamkumar Shivani Burad André DeHon Boon Thau Loo

University of Pennsylvania

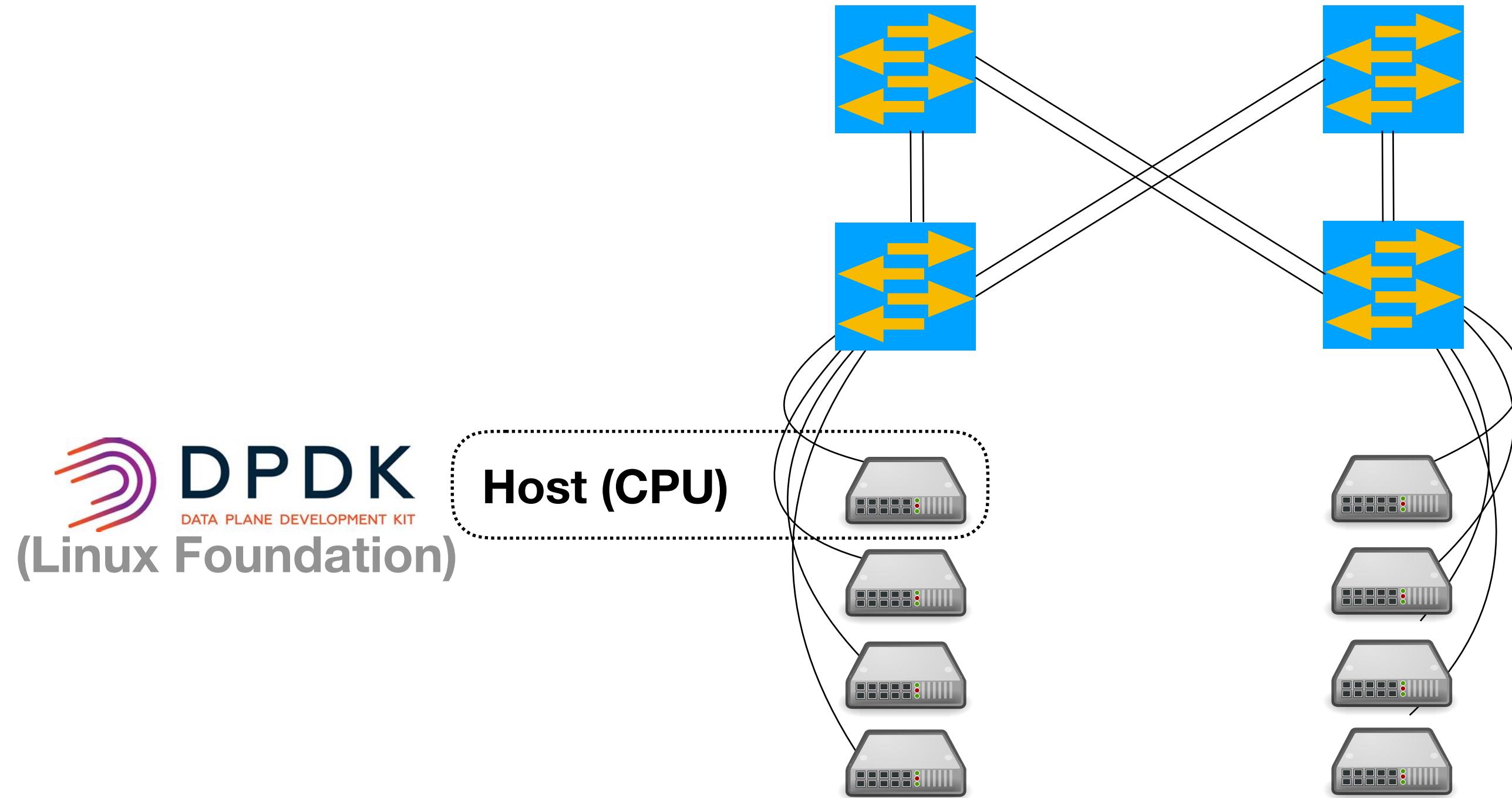
<https://flightplan.cis.upenn.edu/>

NSDI'21

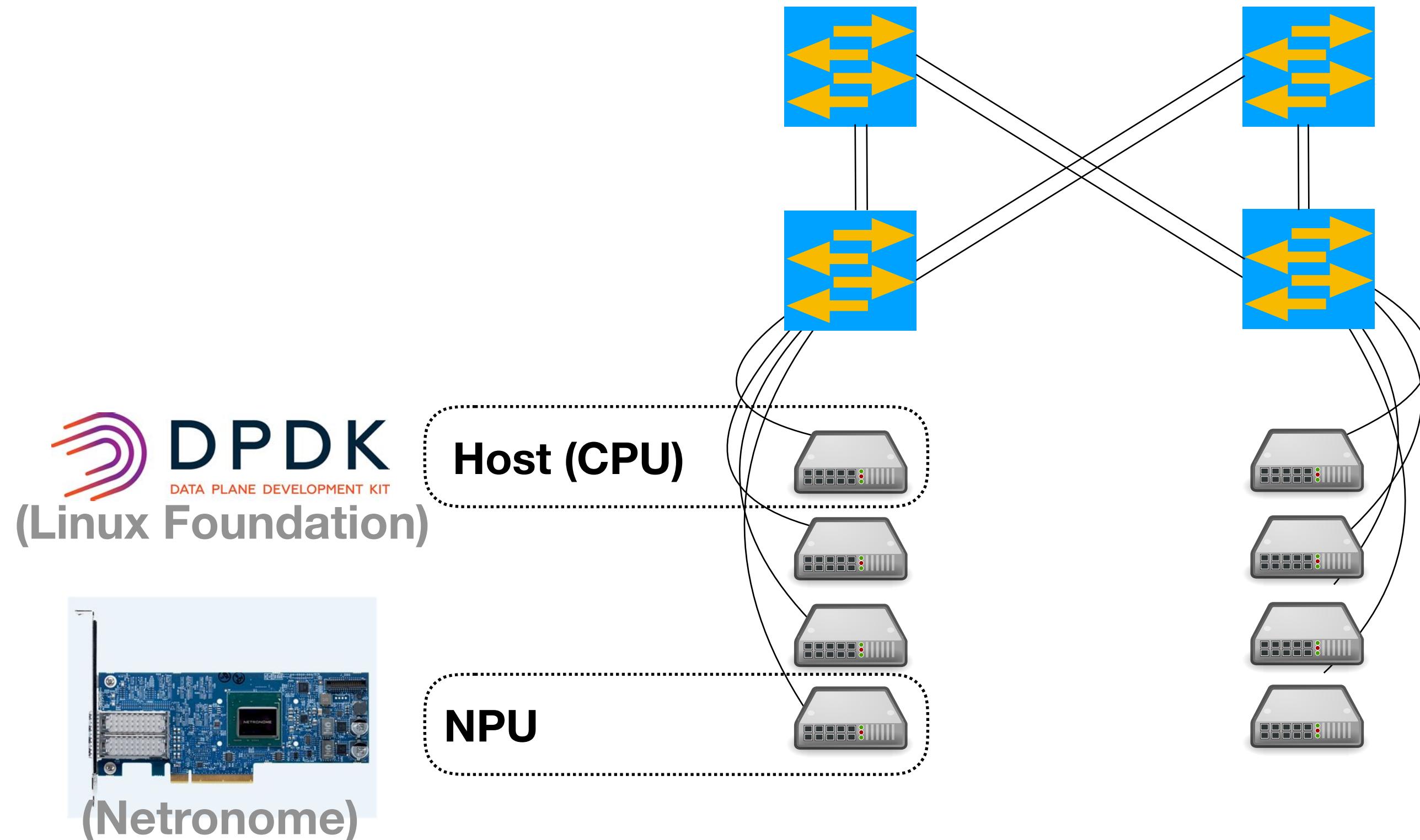
Dataplane Programmability



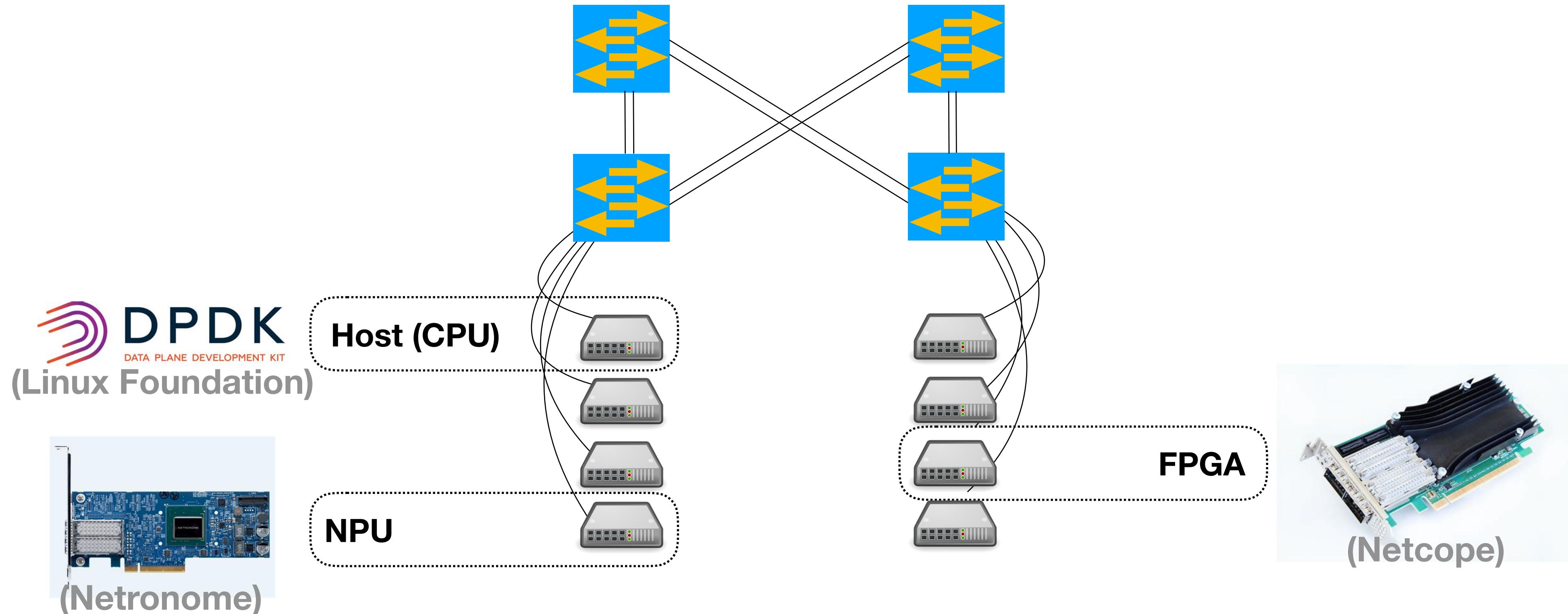
Dataplane Programmability



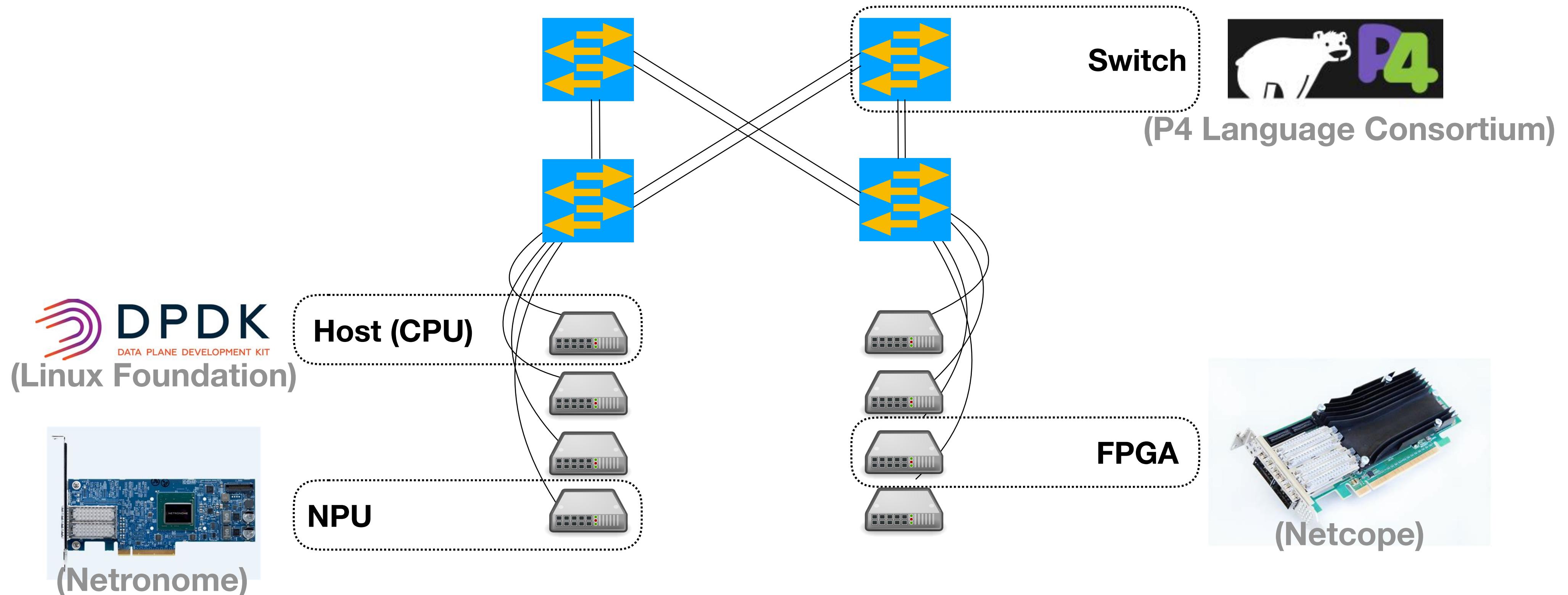
Dataplane Programmability



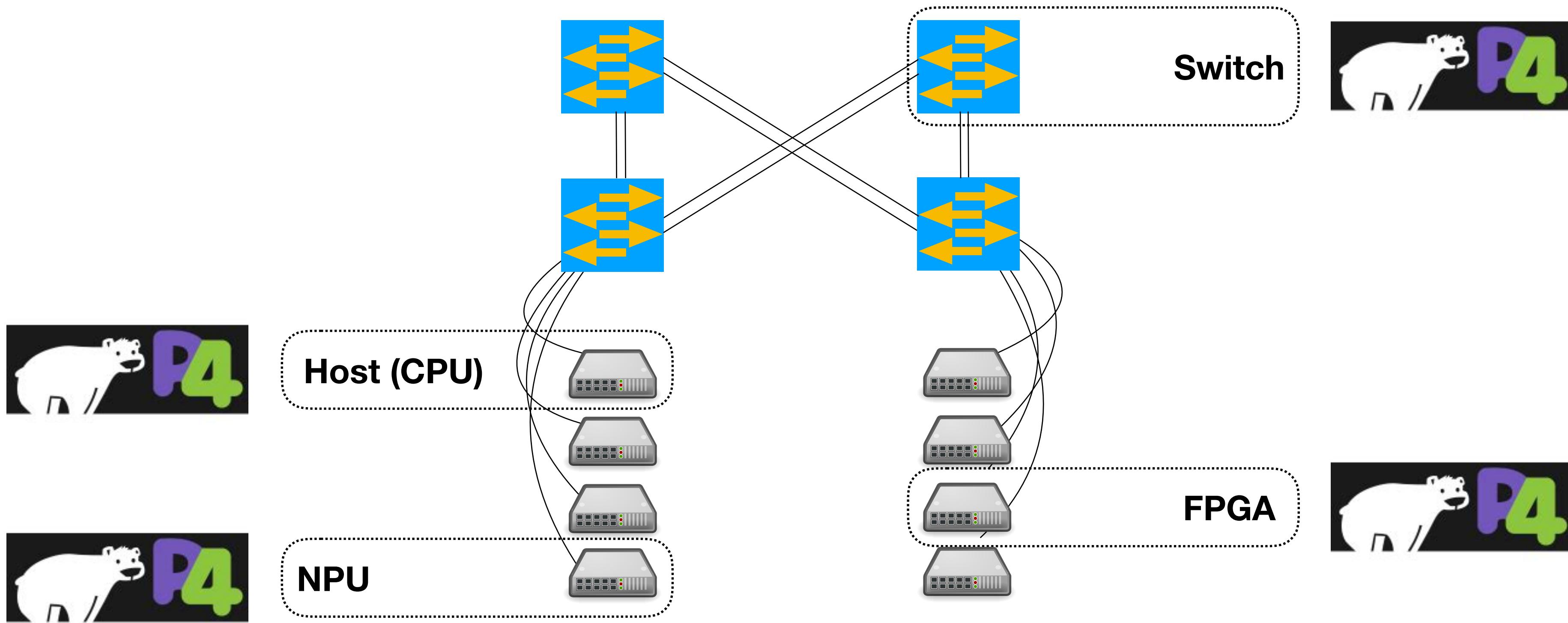
Dataplane Programmability



Dataplane Programmability

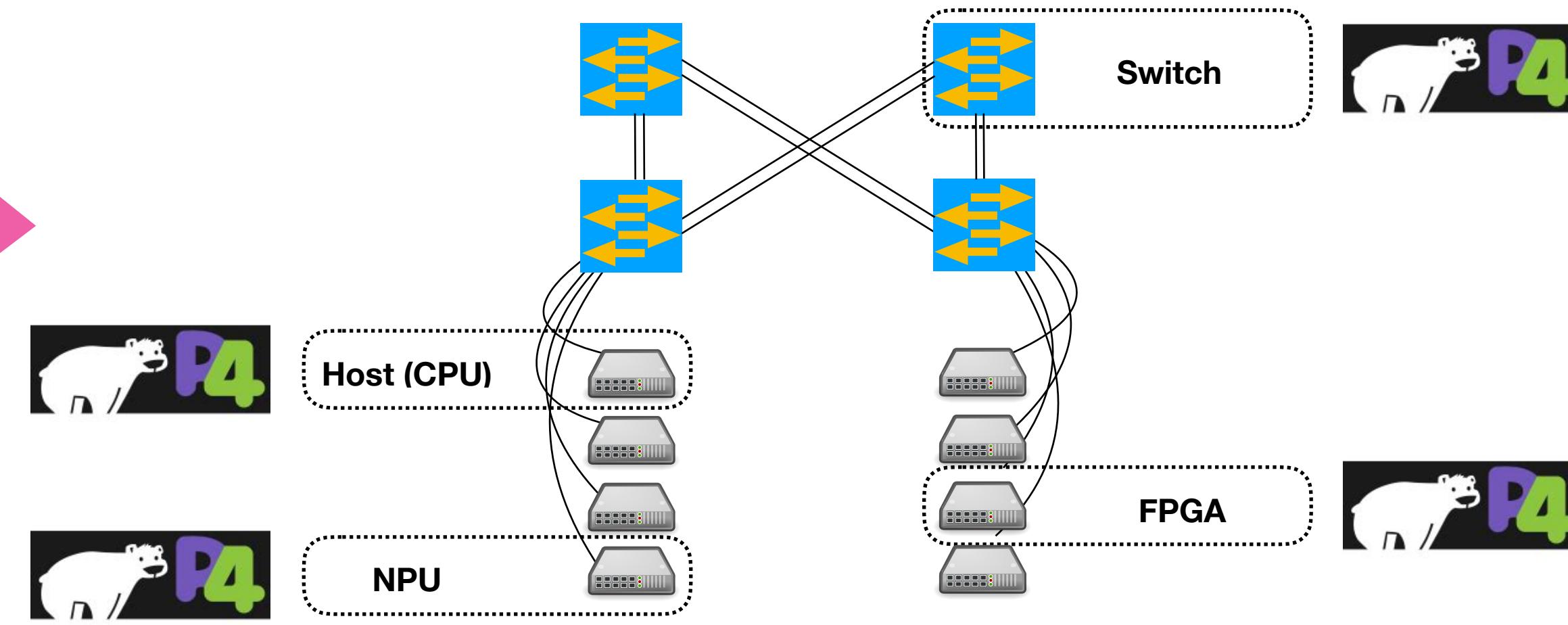


Dataplane Programmability



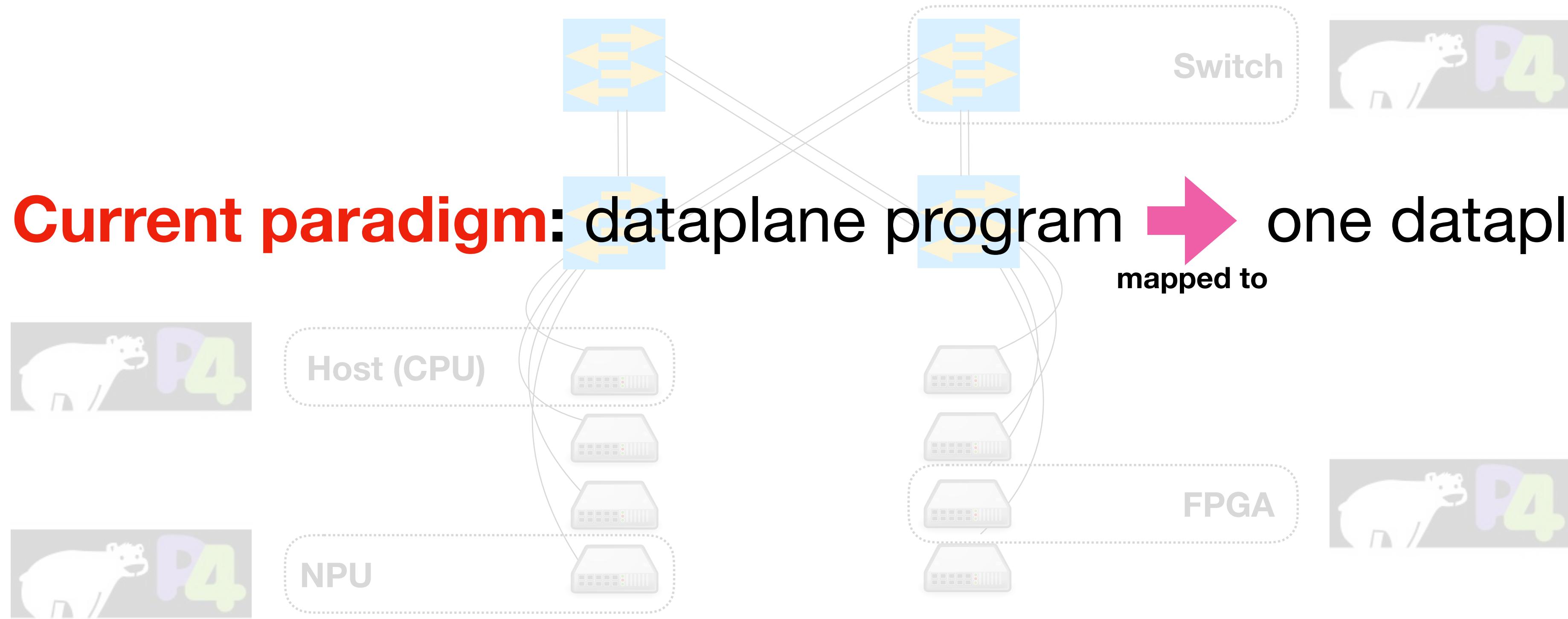
Dataplane Programmability

Research

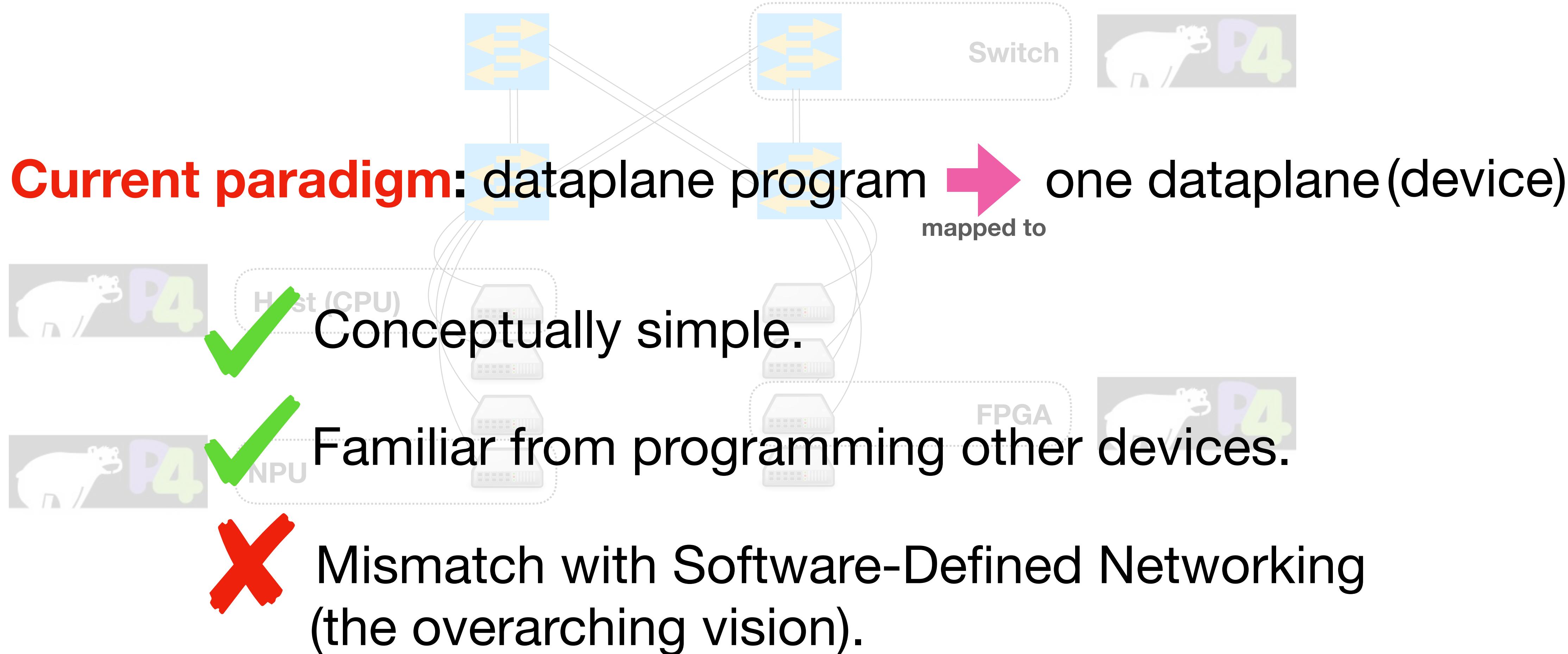


Products

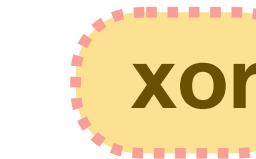
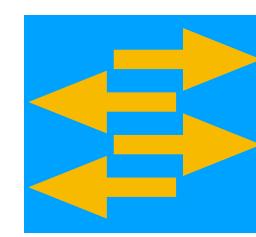
Dataplane Programmability



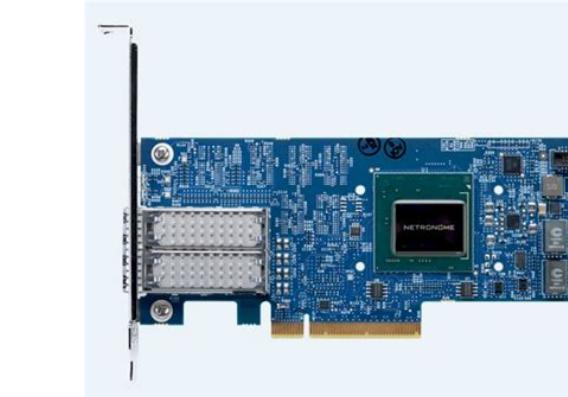
Dataplane Programmability



Current paradigm: dataplane program → one dataplane
mapped to



xor



xor

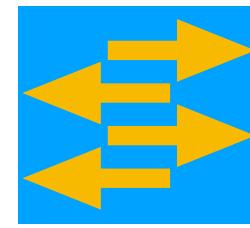


Mismatch with Software-Defined Networking

- **Target's resources are dedicated to the program.**
Inefficient use of individual target resources.
- **Program must entirely execute on a single target.**
Unnecessary constraints of program functionality.
- **We're meant to be “programming the network”.**
Programmability is scoped too conservatively.

Current paradigm: dataplane program → one dataplane

mapped to



xor



xor

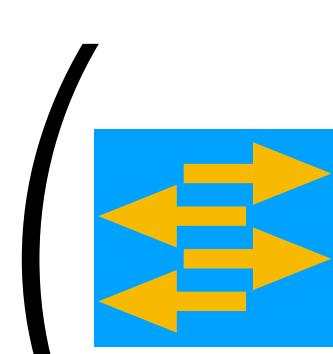


xor



New paradigm:

dataplane program → suitable mix of dataplanes



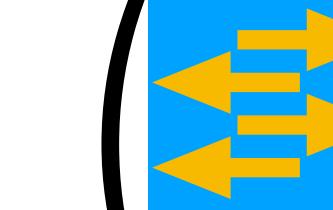
and



or



or



and



or



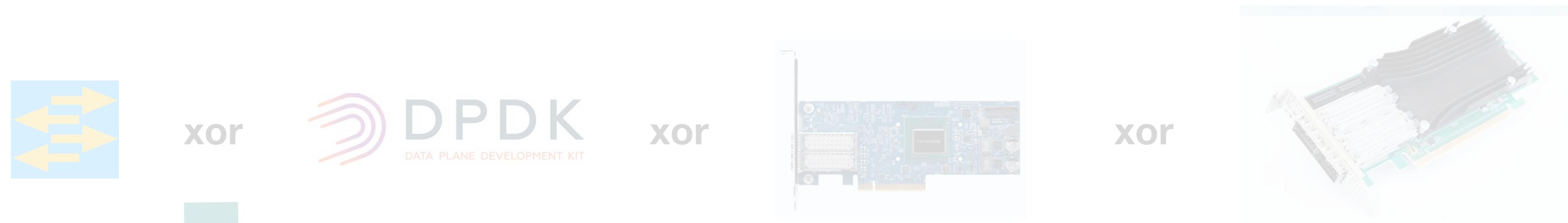
and



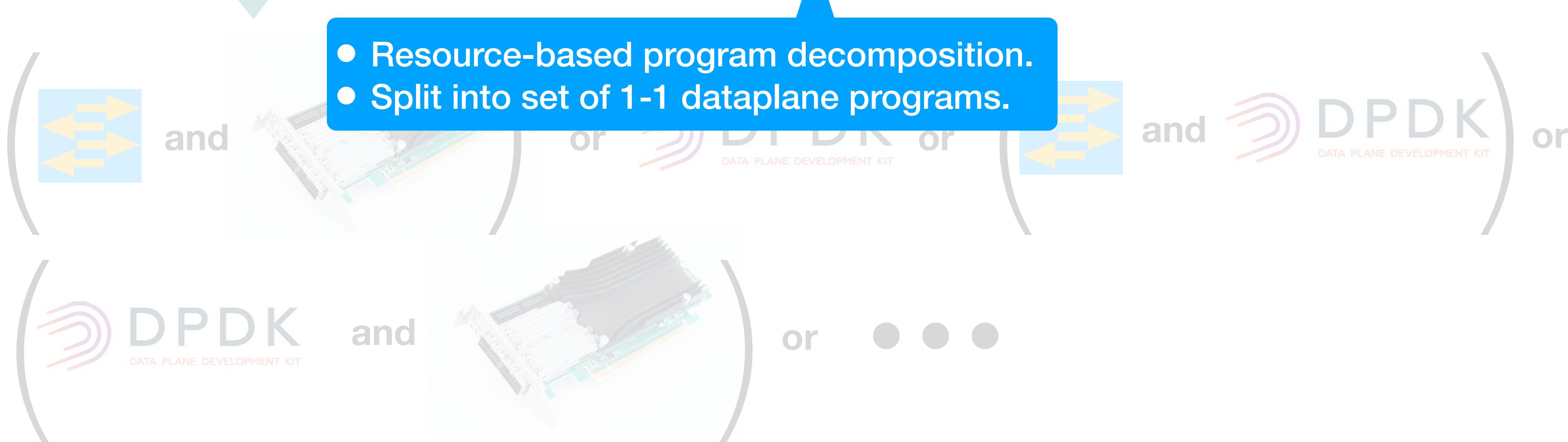
or

• • •

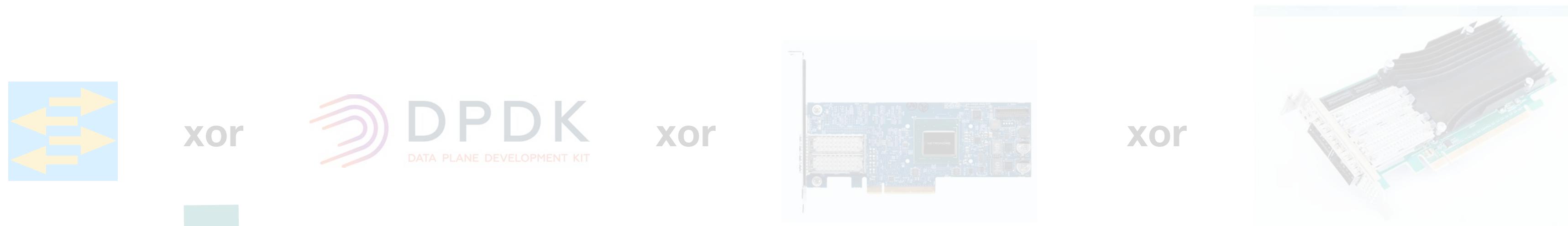
Current paradigm: dataplane program → one dataplane



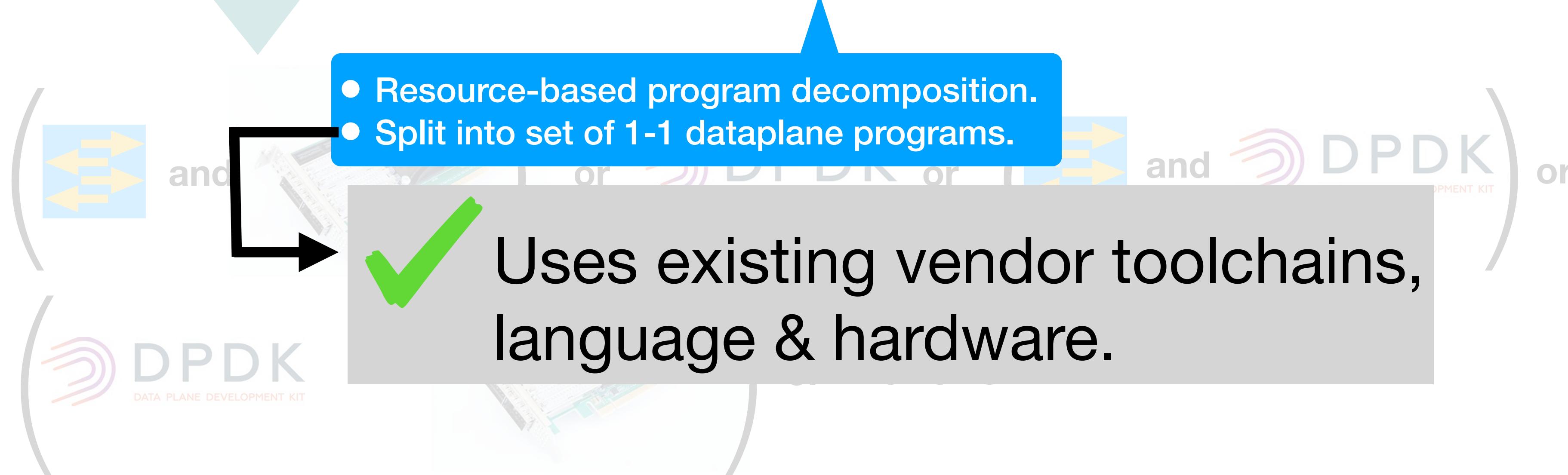
New paradigm:
dataplane program → suitable mix of dataplanes



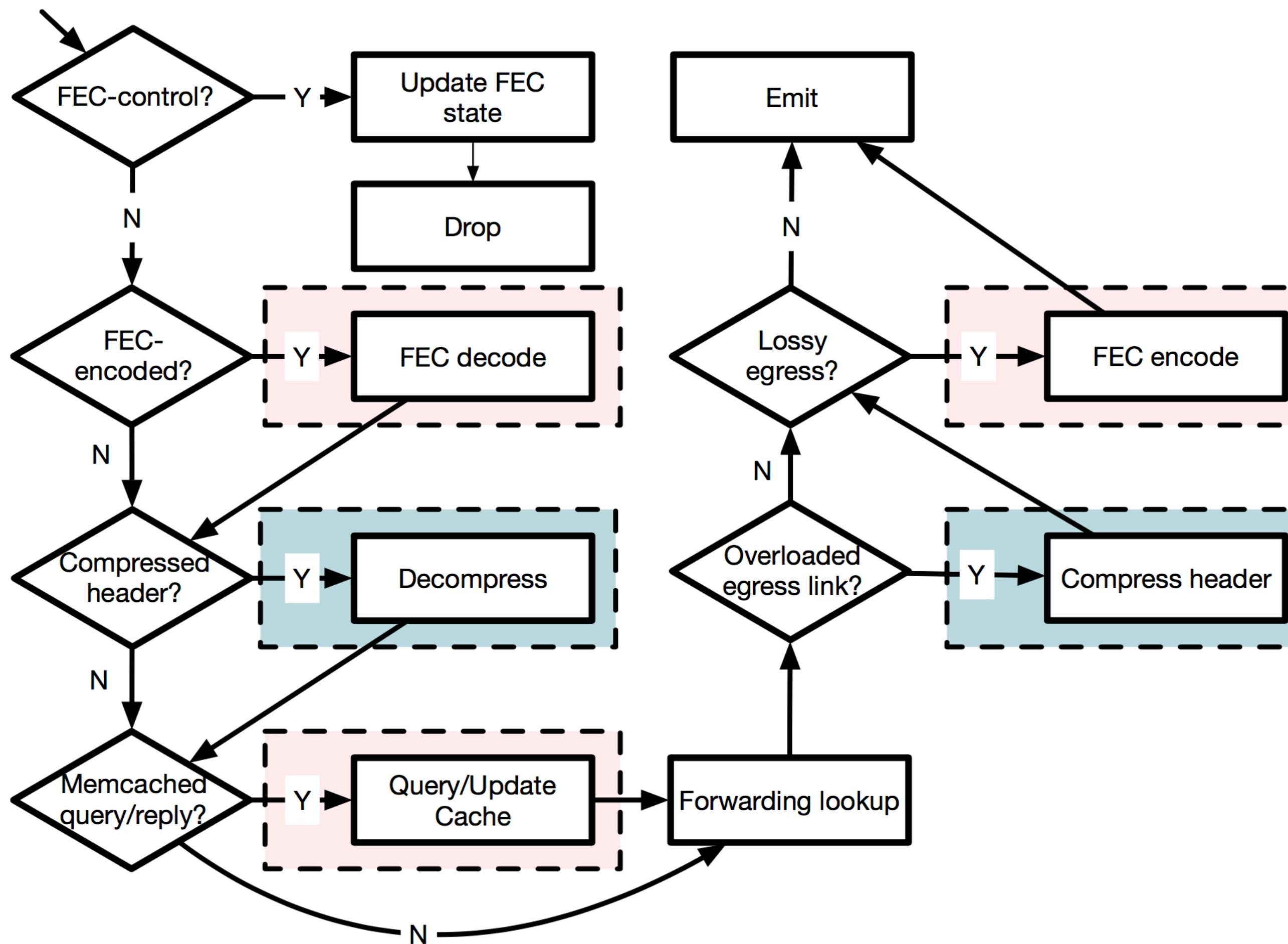
Current paradigm: dataplane program → one dataplane



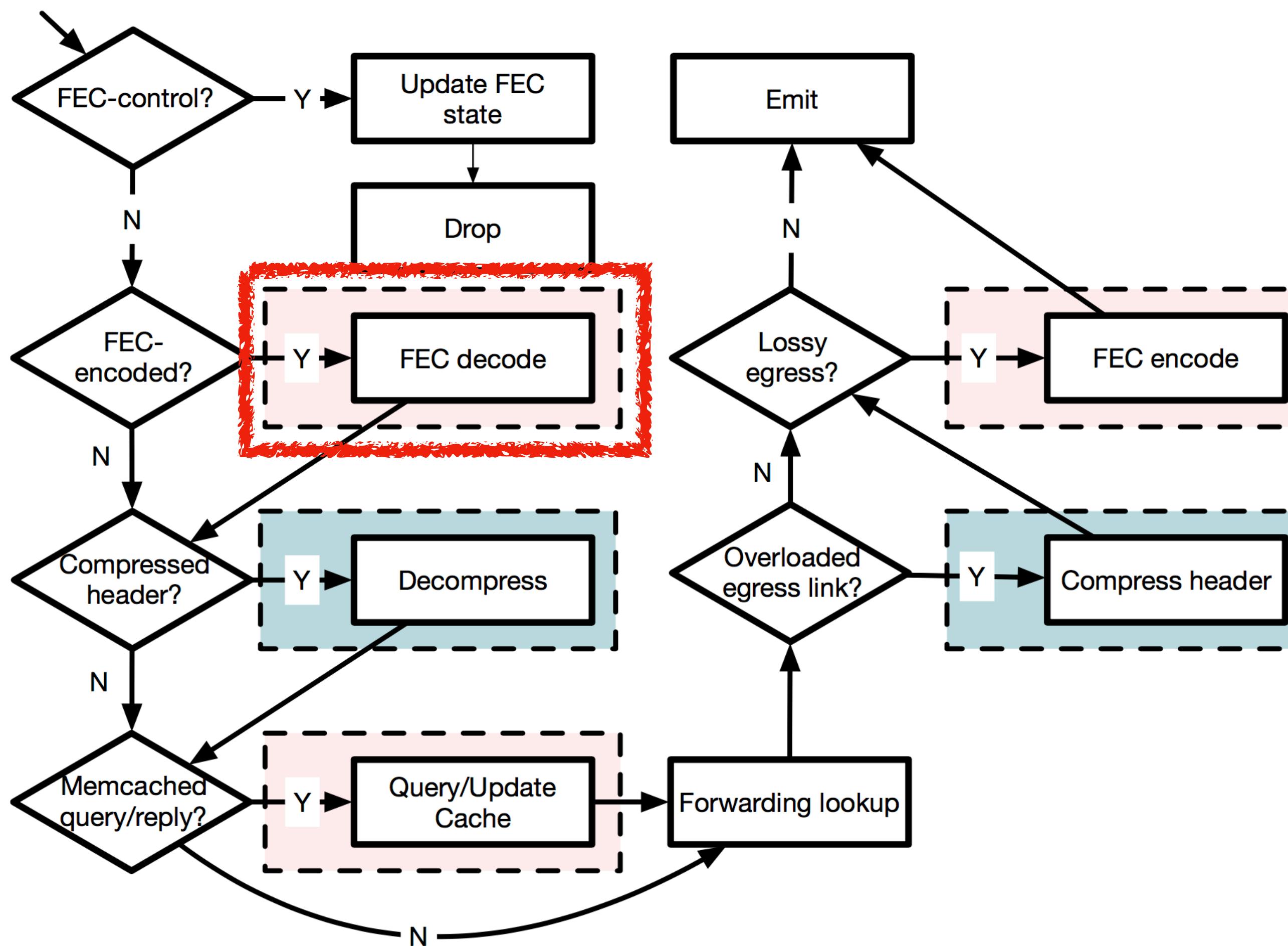
New paradigm:
dataplane program → suitable mix of dataplanes

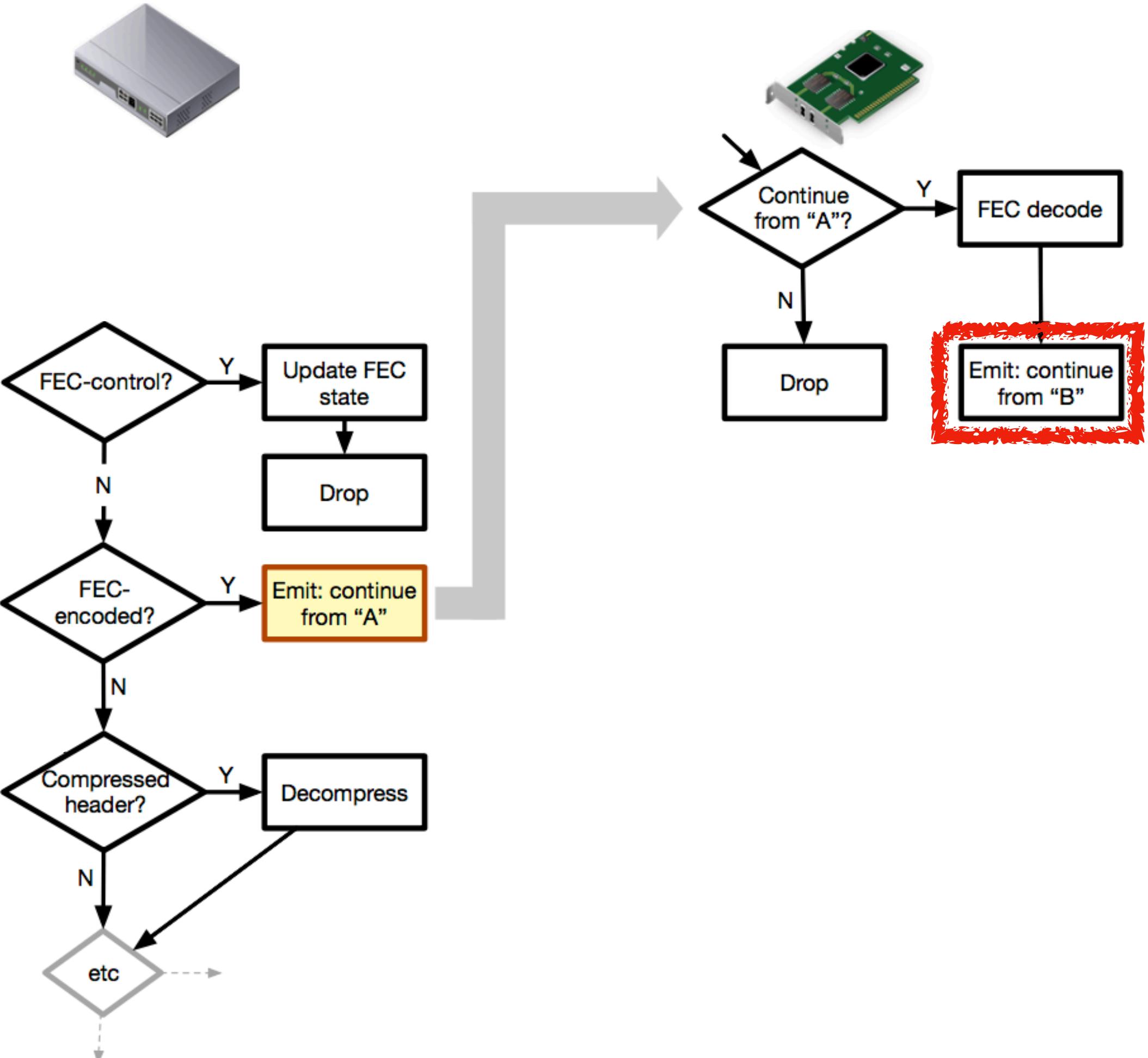


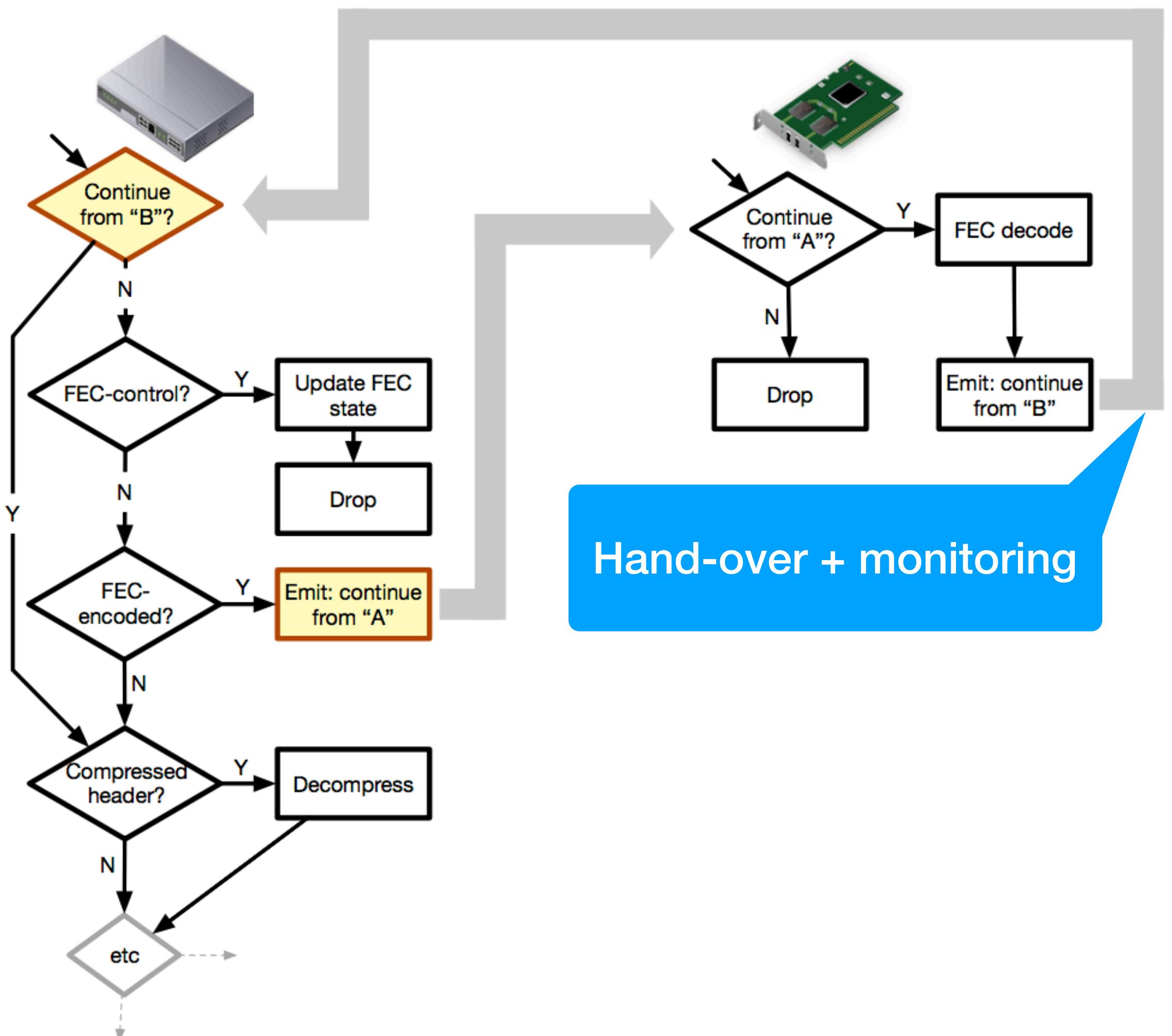
Example: “Crosspod” Program



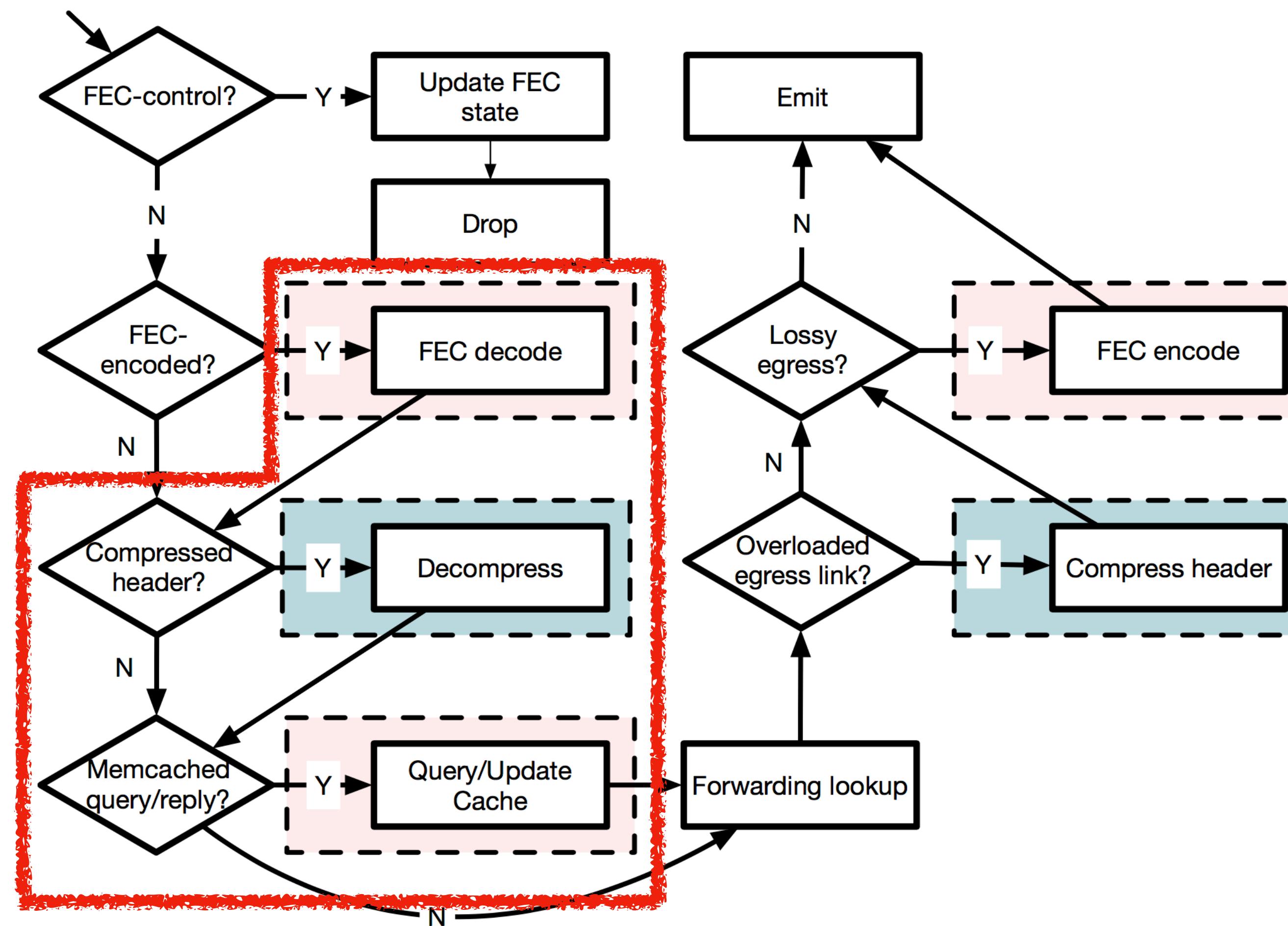
Example: “Crosspod” Program



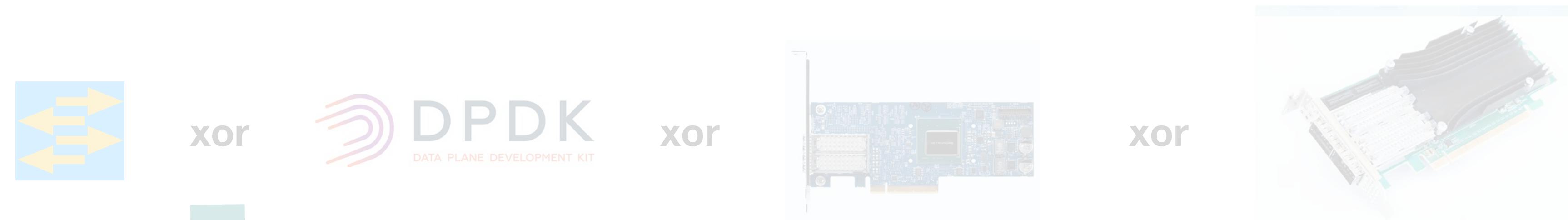




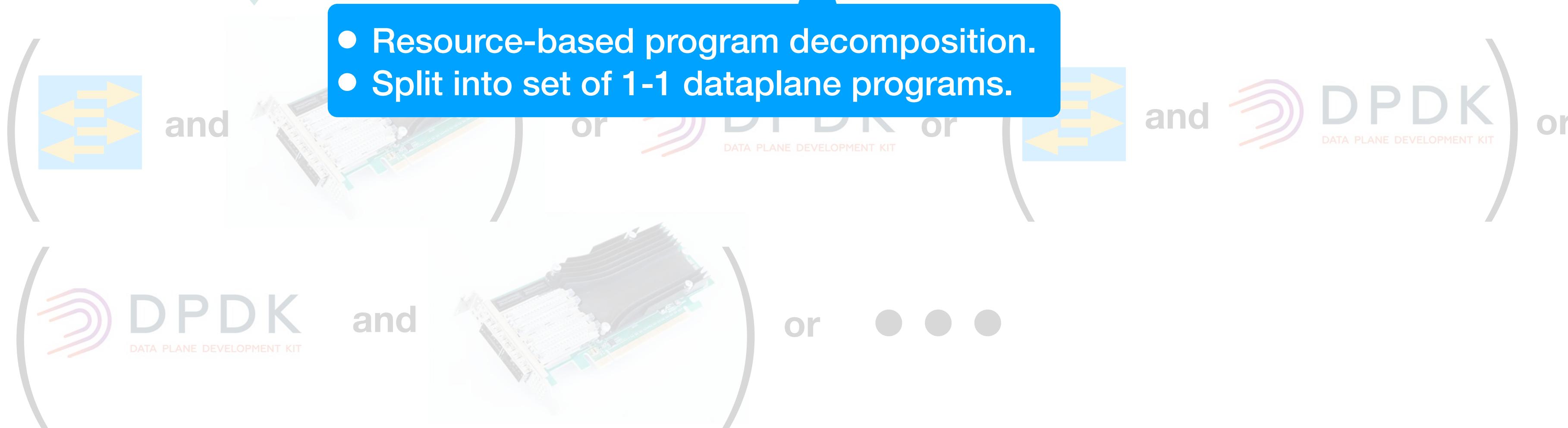
Hand-over + monitoring



Current paradigm: dataplane program → one dataplane



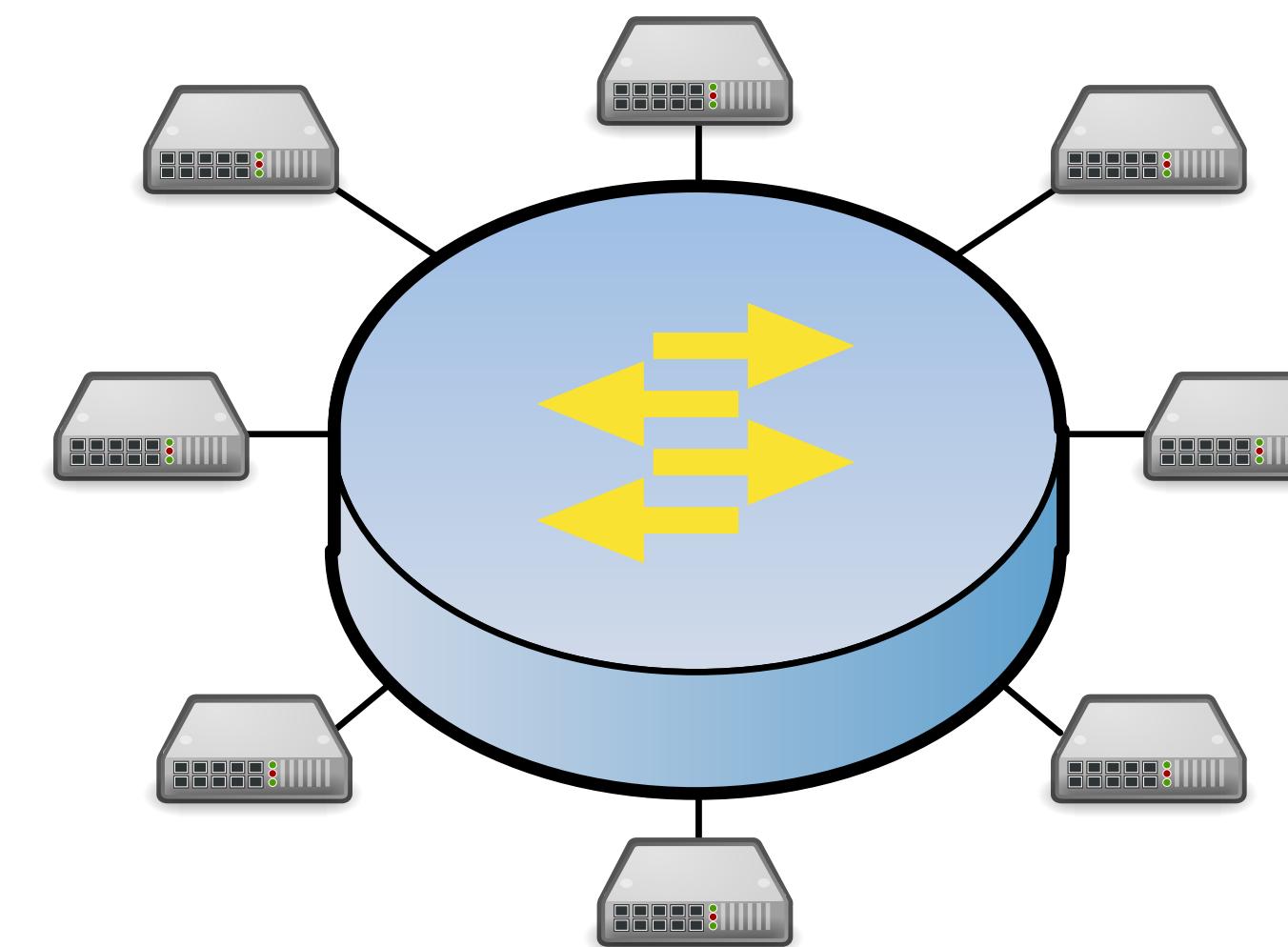
New paradigm: **Dataplane Disaggregation**
dataplane program → suitable mix of dataplanes



Dataplane Disaggregation

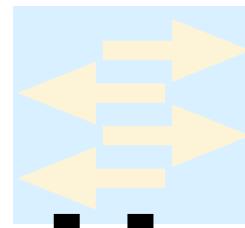
(≠ Server Disaggregation)

Virtual Dataplane → Set of Physical Dataplanes



“One big switch” → “One big *programmable* switch”

Current paradigm: dataplane program → one dataplane



xor



xor

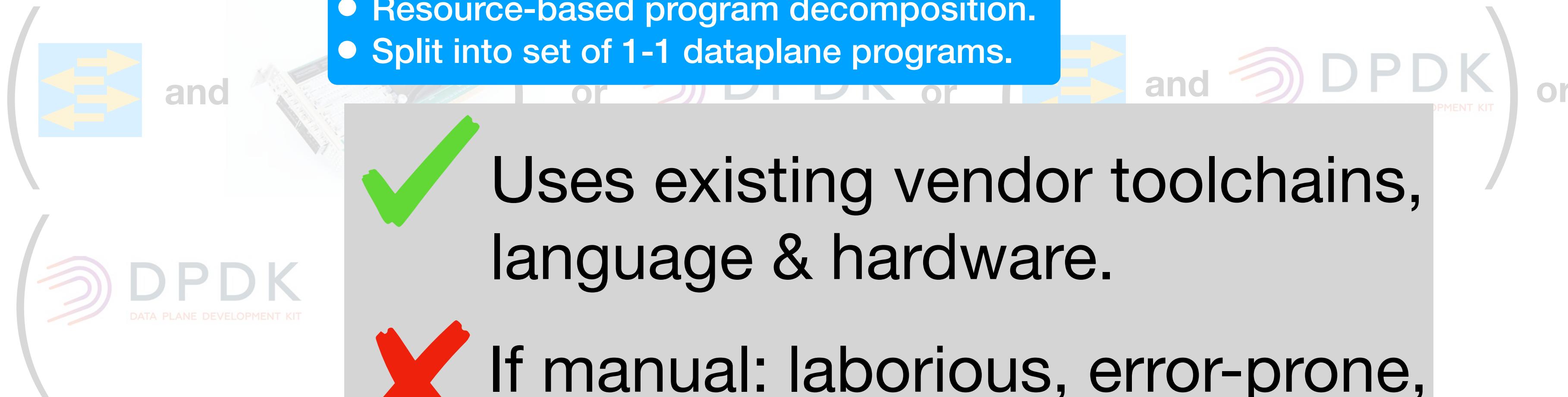
How to implement?

Automated support needed

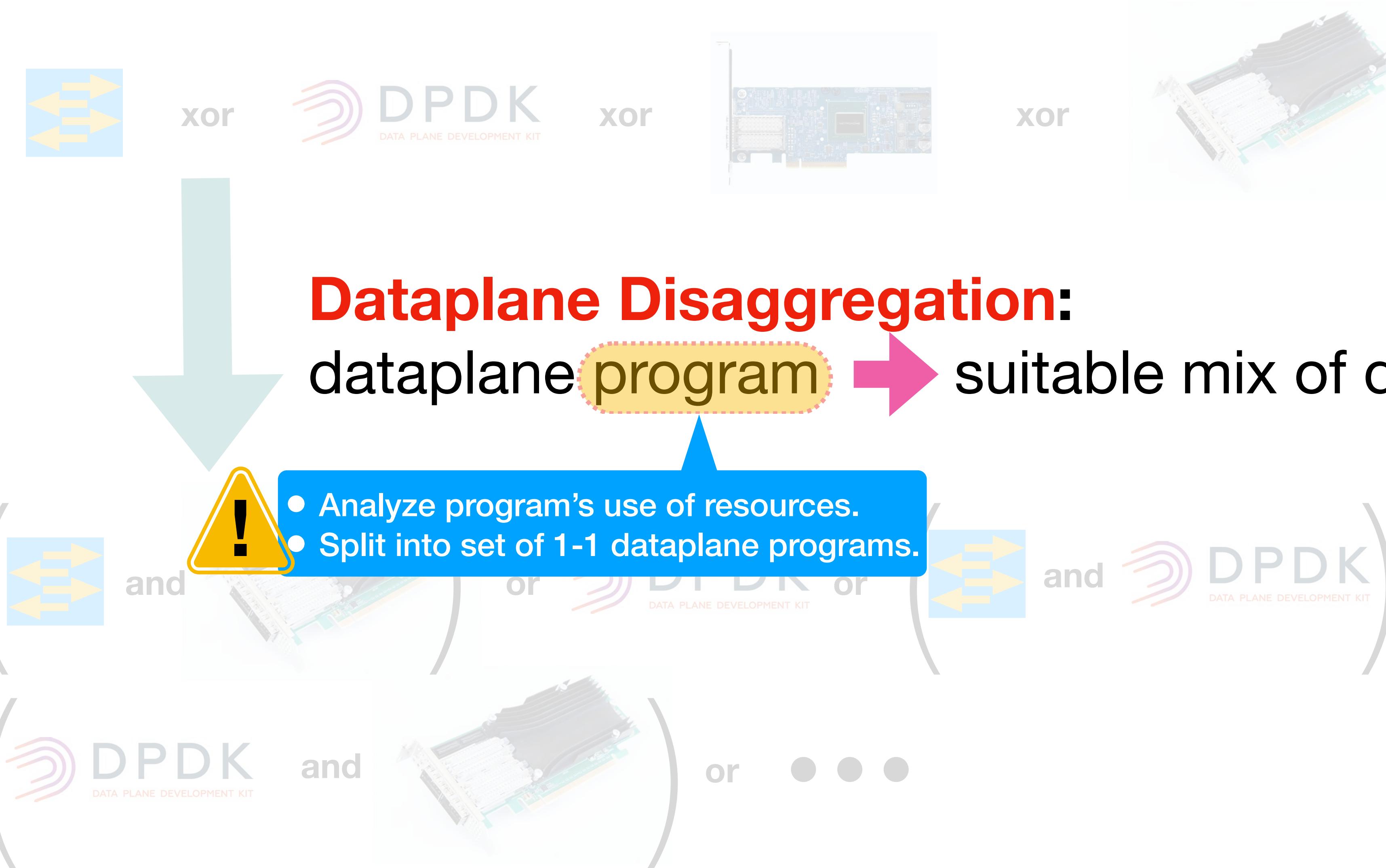
Dataplane Disaggregation:

dataplane program → suitable mix of dataplanes

- Resource-based program decomposition.
- Split into set of 1-1 dataplane programs.



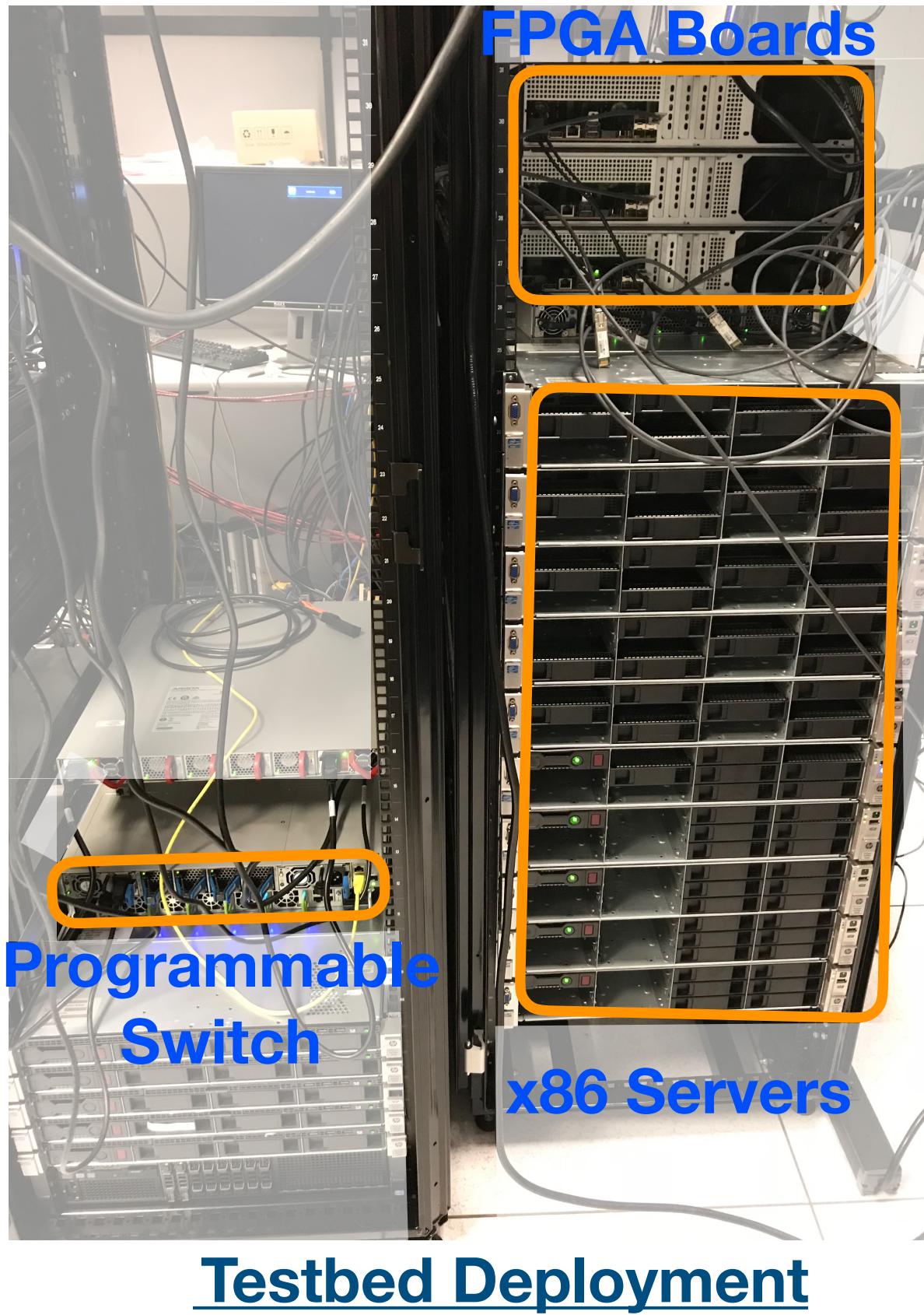
Current paradigm: dataplane program → one dataplane



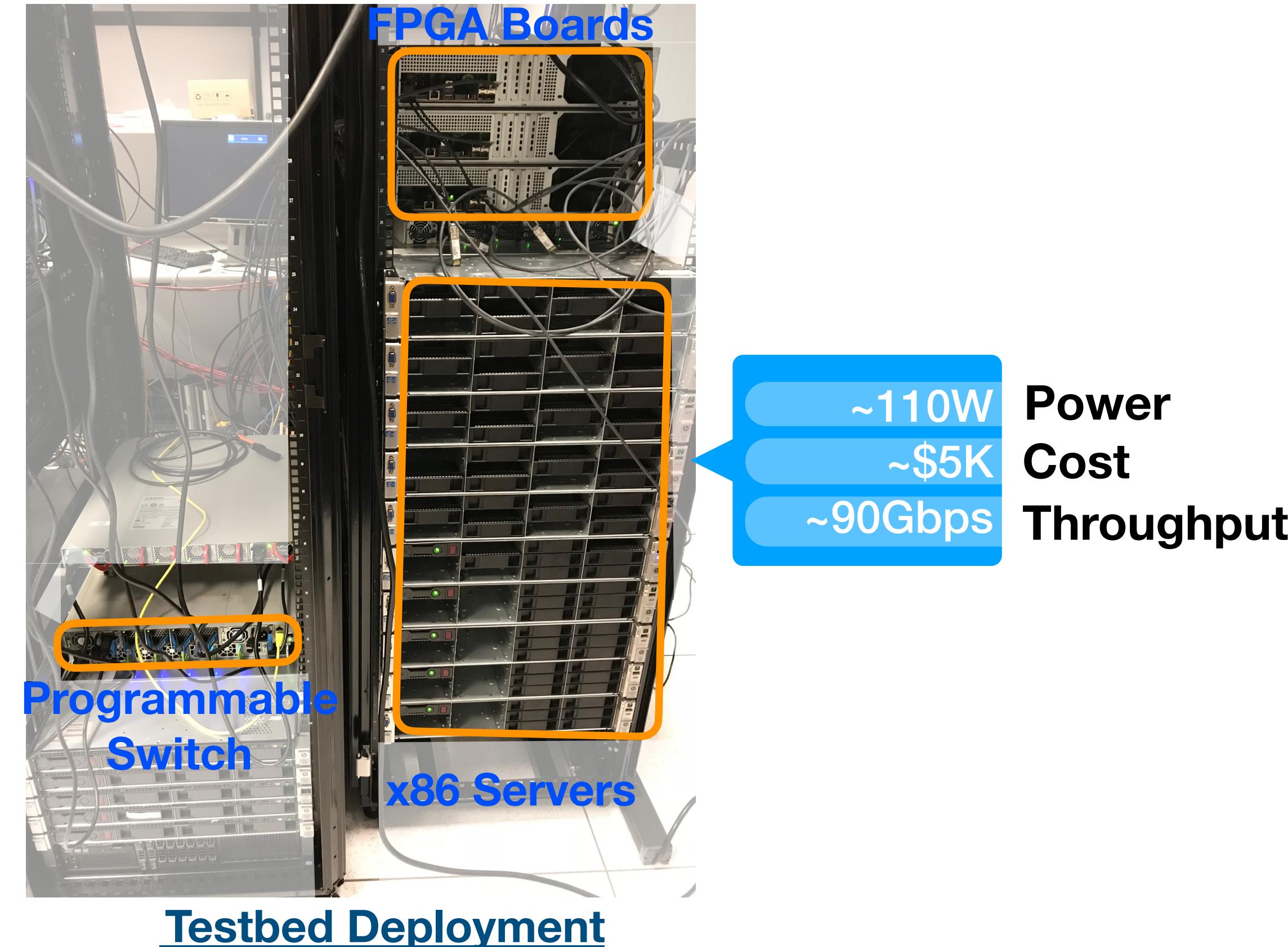
Current paradigm: dataplane program → one dataplane



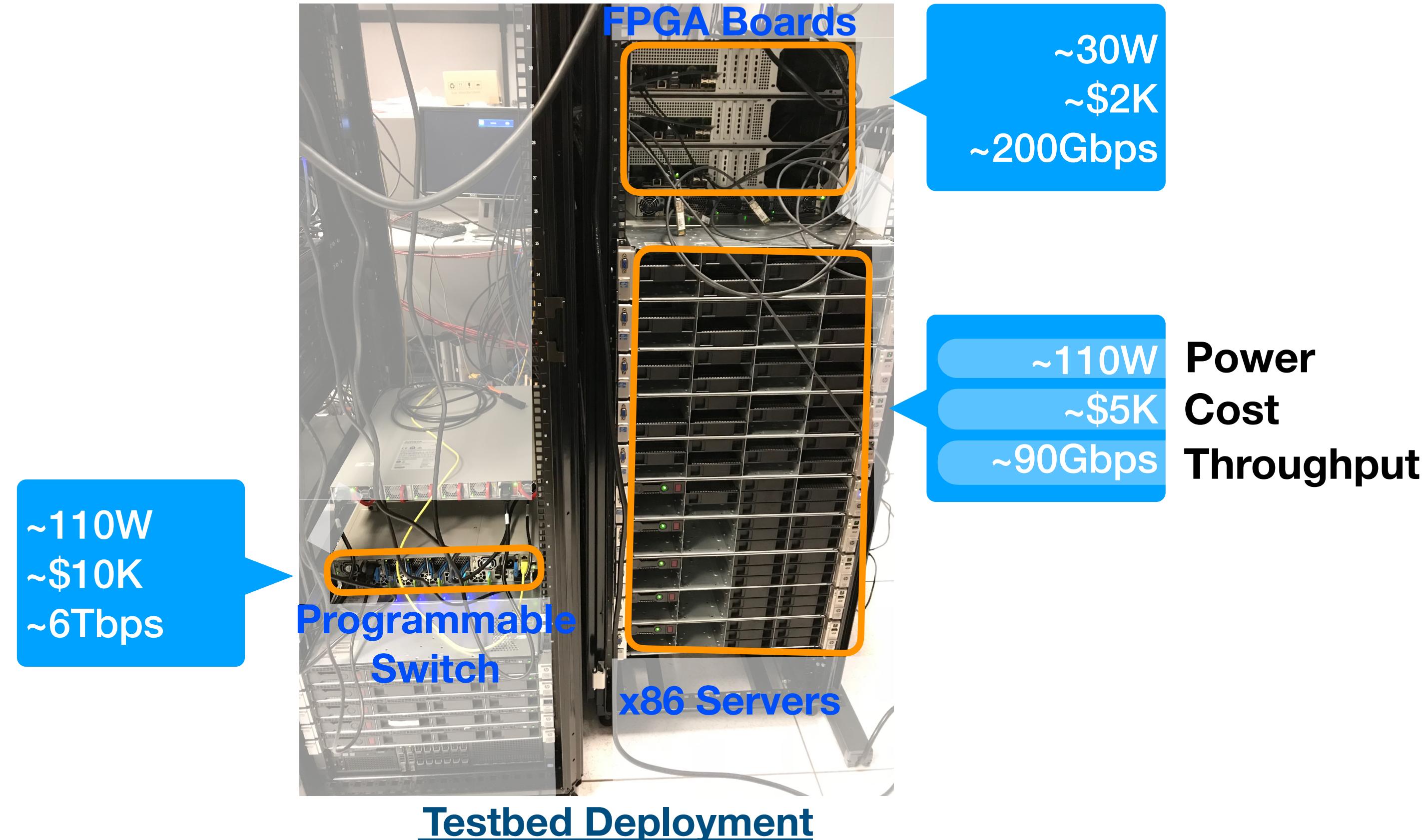
Heterogeneity



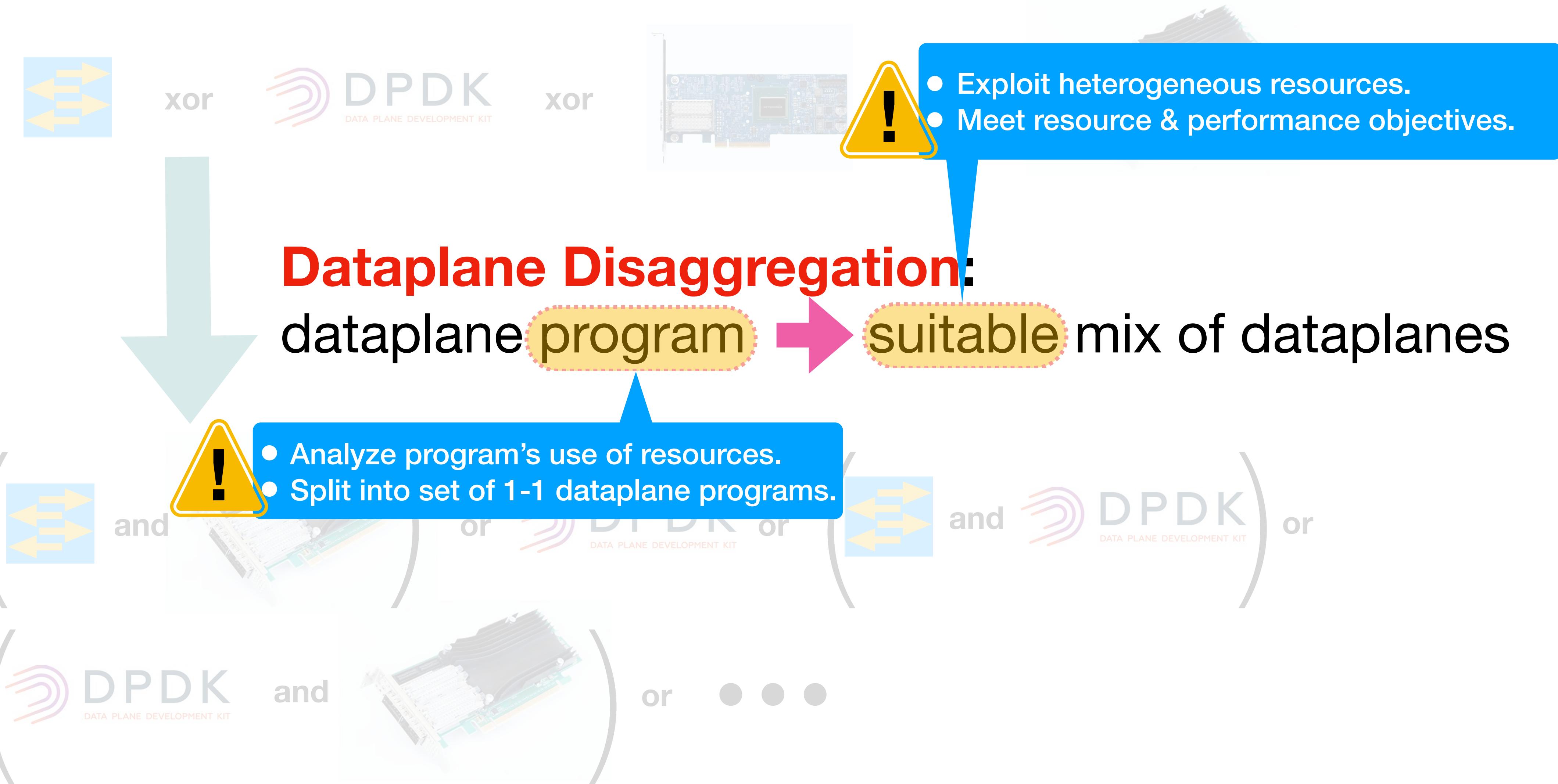
Heterogeneity



Heterogeneity



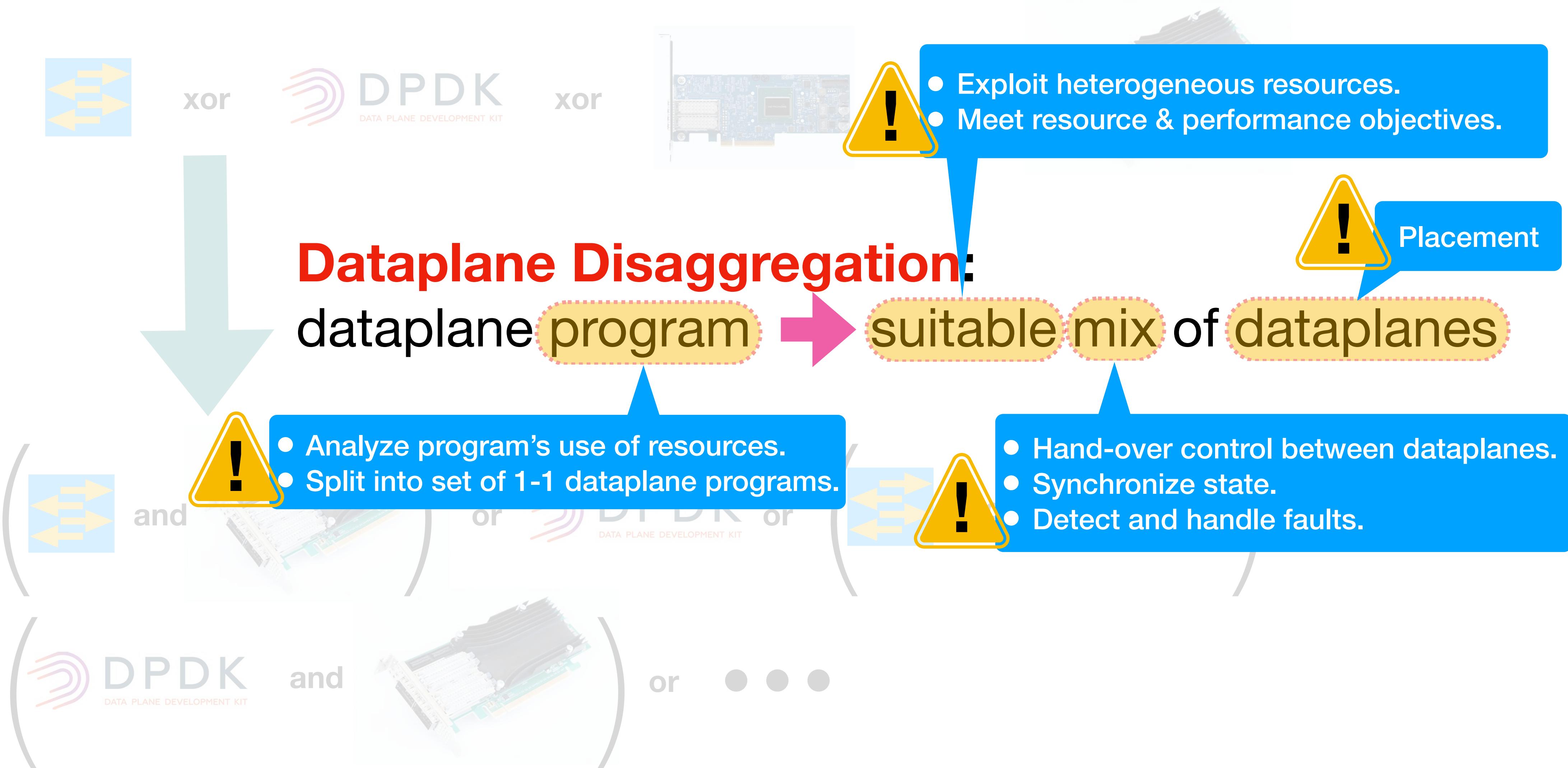
Current paradigm: dataplane program → one dataplane



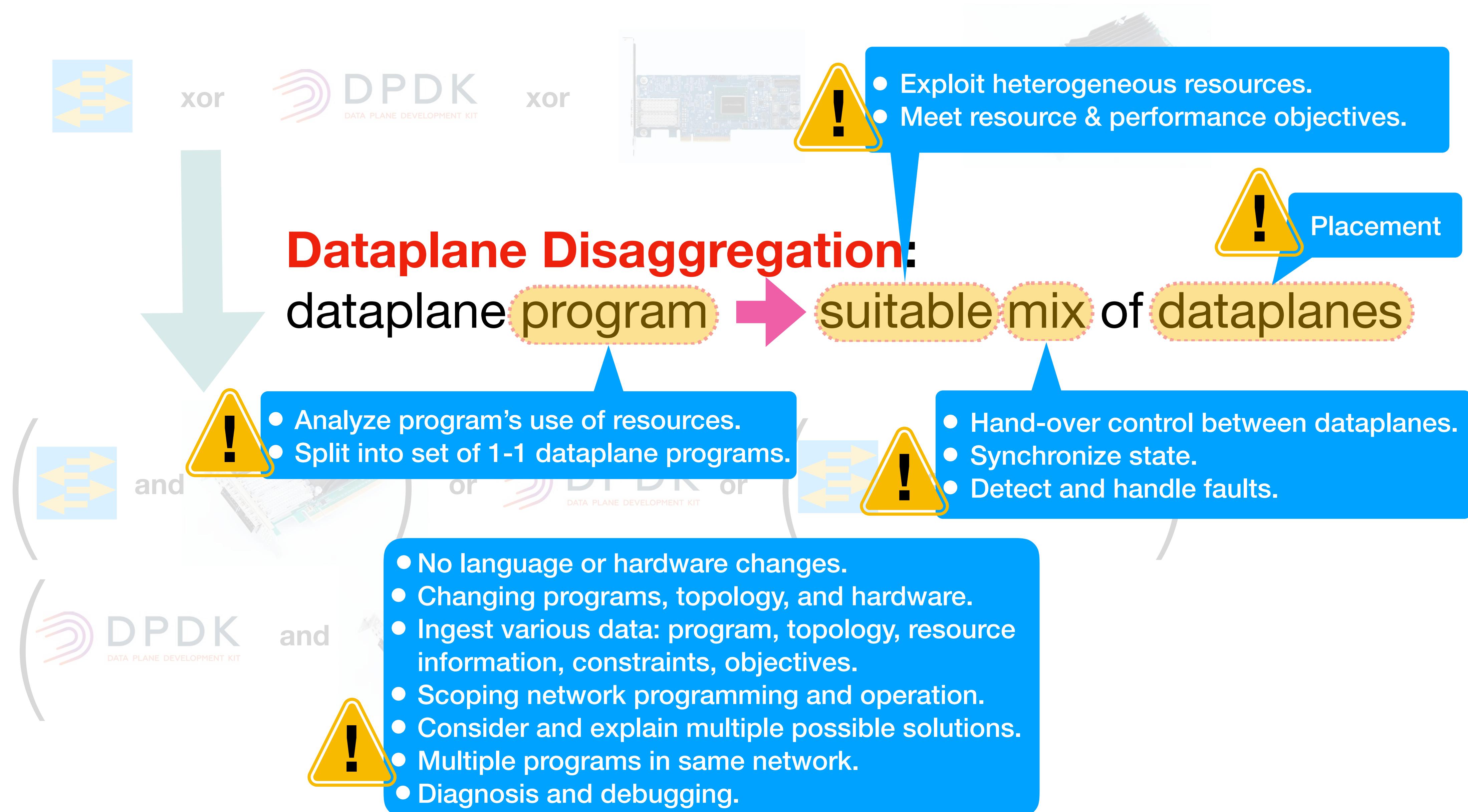
Current paradigm: dataplane program → one dataplane



Current paradigm: dataplane program → one dataplane

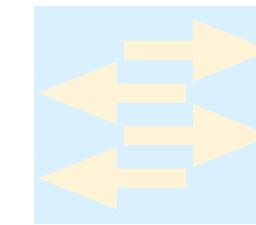


Current paradigm: dataplane program → one dataplane



Code, tests, scripts, data, documentation:
<https://flightplan.cis.upenn.edu/>

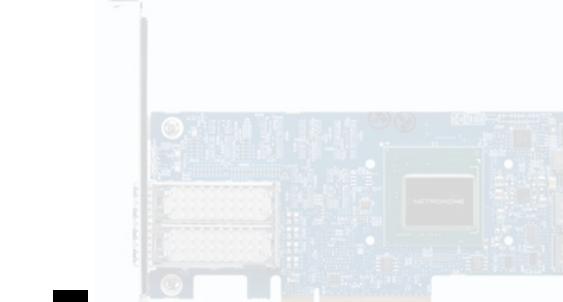
program → one dataplane



xor



xor



Flightplan

Dataplane Disaggregation:

dataplane program



- Exploit heterogeneous resources.
- Meet resource & performance objectives.



suitable mix of dataplanes



and

- 
- Analyze program's use of resources.
 - Split into set of 1-1 dataplane programs.

or



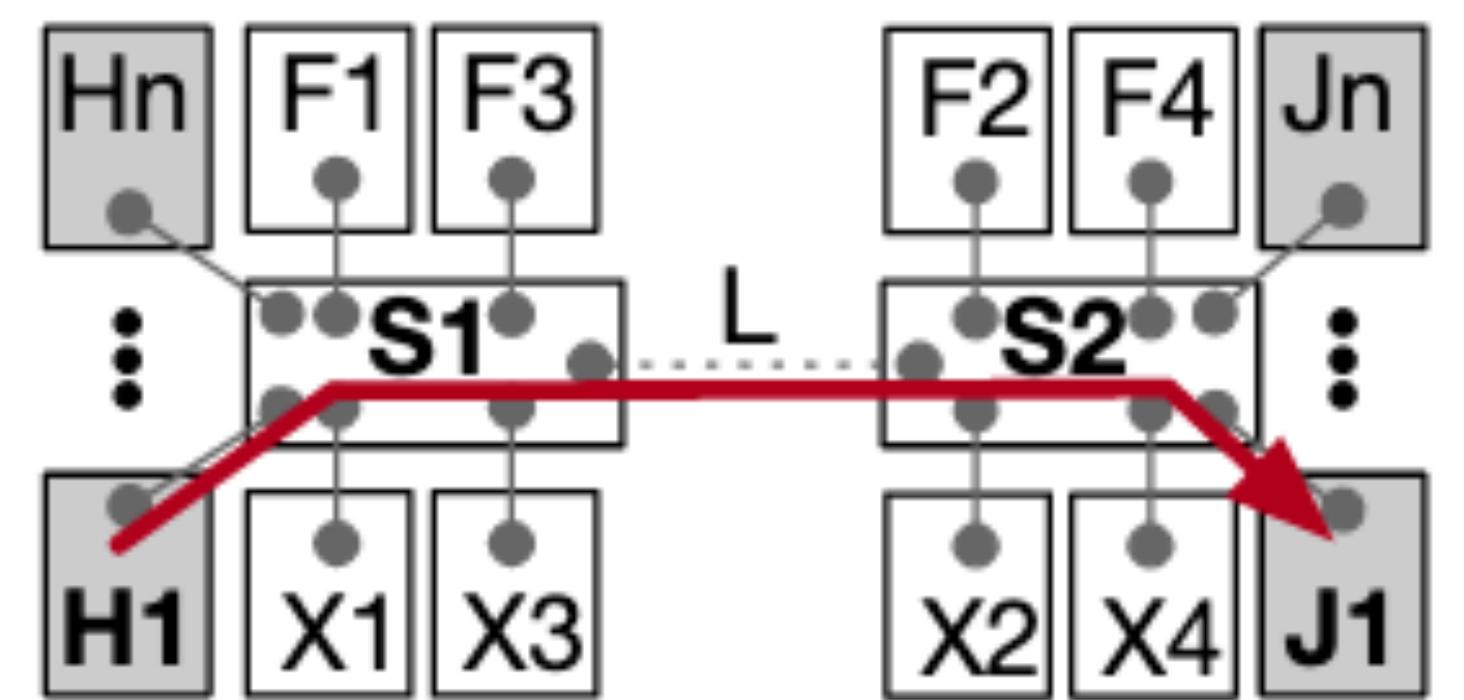
and



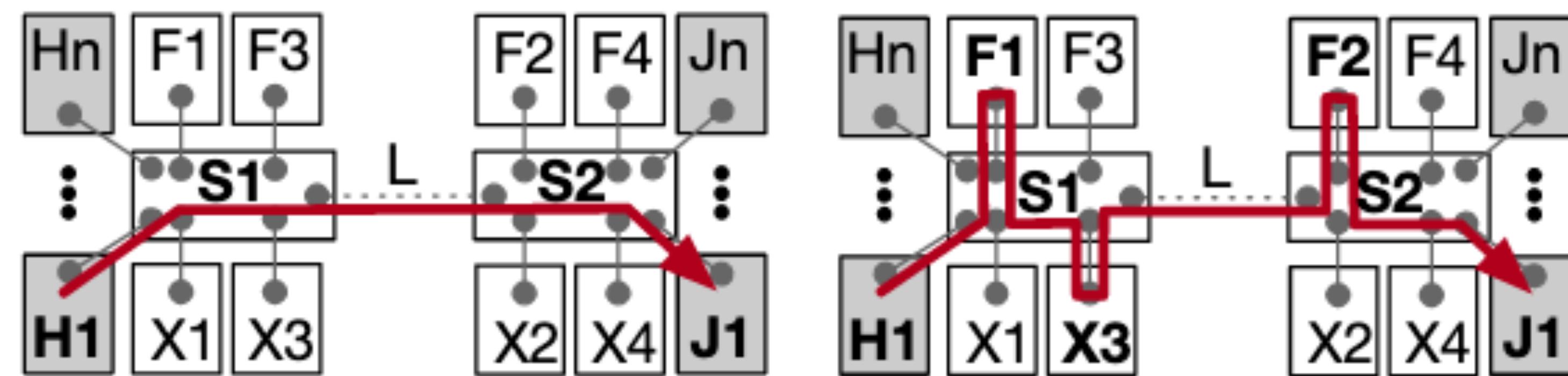
- No language or hardware changes.
- Changing programs, topology, and hardware.
- Ingest various data: program, topology, resource information, constraints, objectives.
- Scoping network programming and operation.
- Consider and explain multiple possible solutions.
- Multiple programs in same network.
- Diagnosis and debugging.



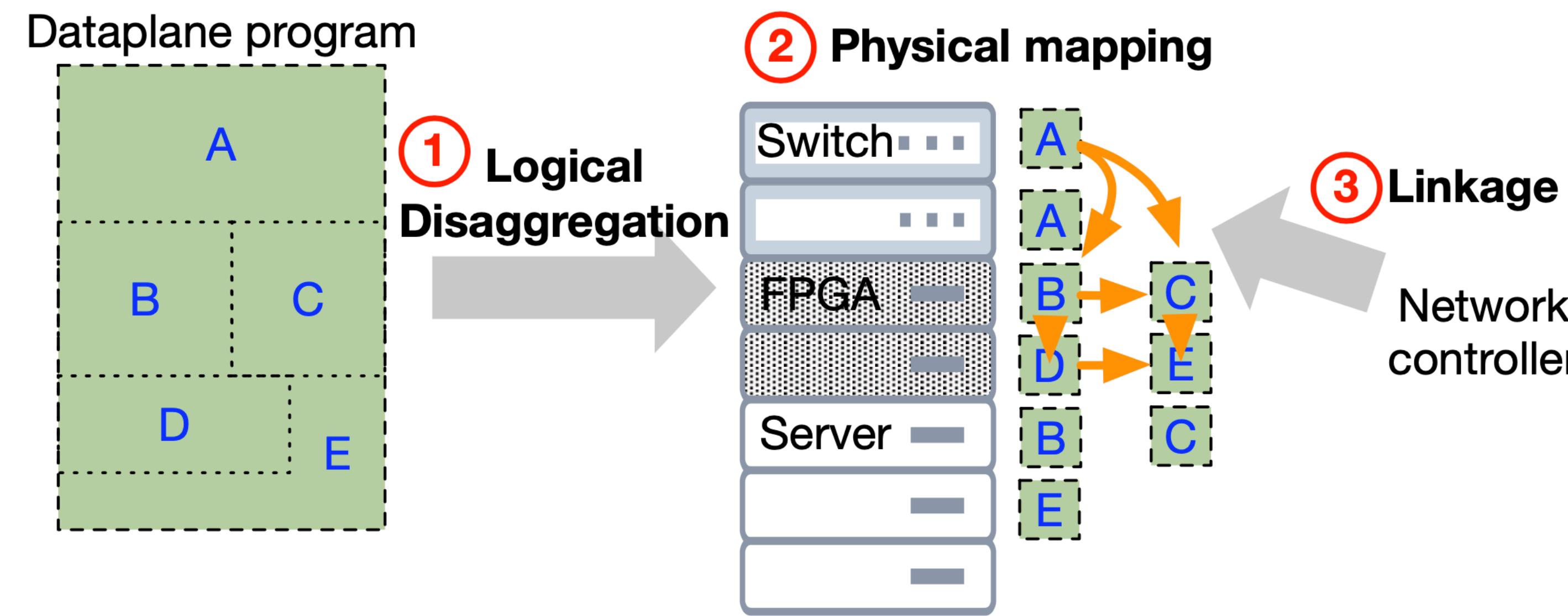
- 
- Hand-over control between dataplanes.
 - Synchronize state.
 - Detect and handle faults.



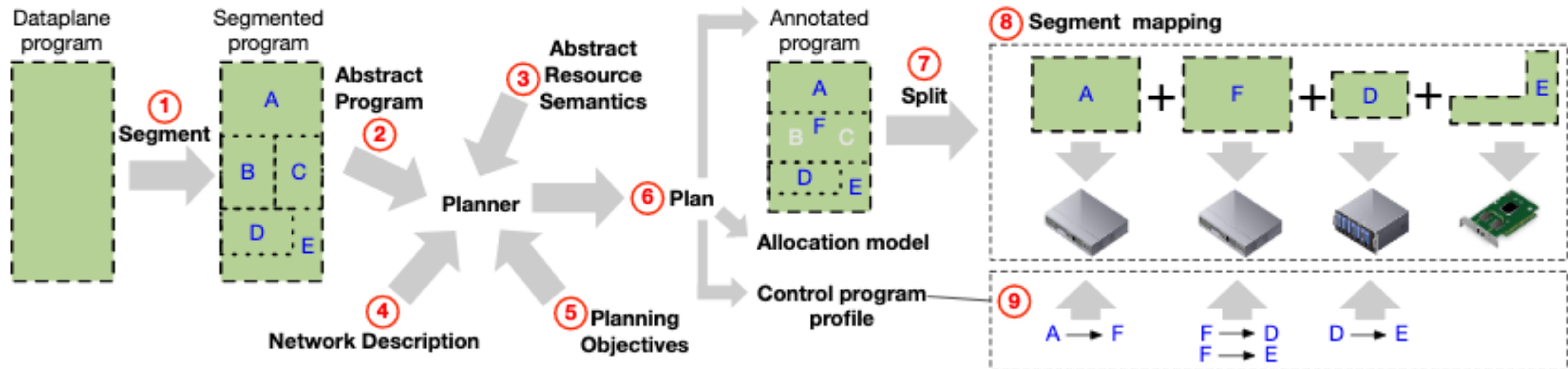
Flightplan



Flightplan

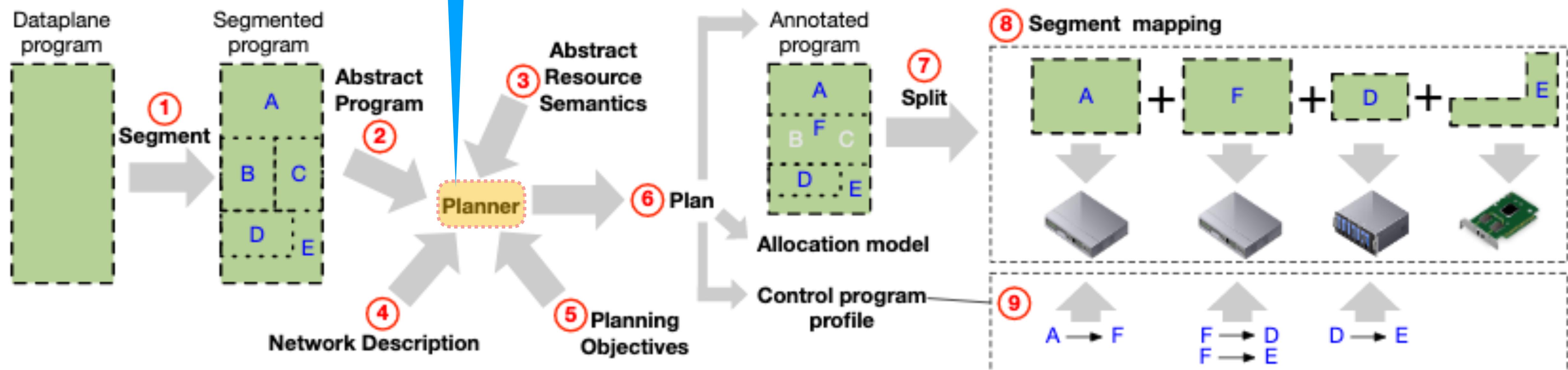


Flightplan

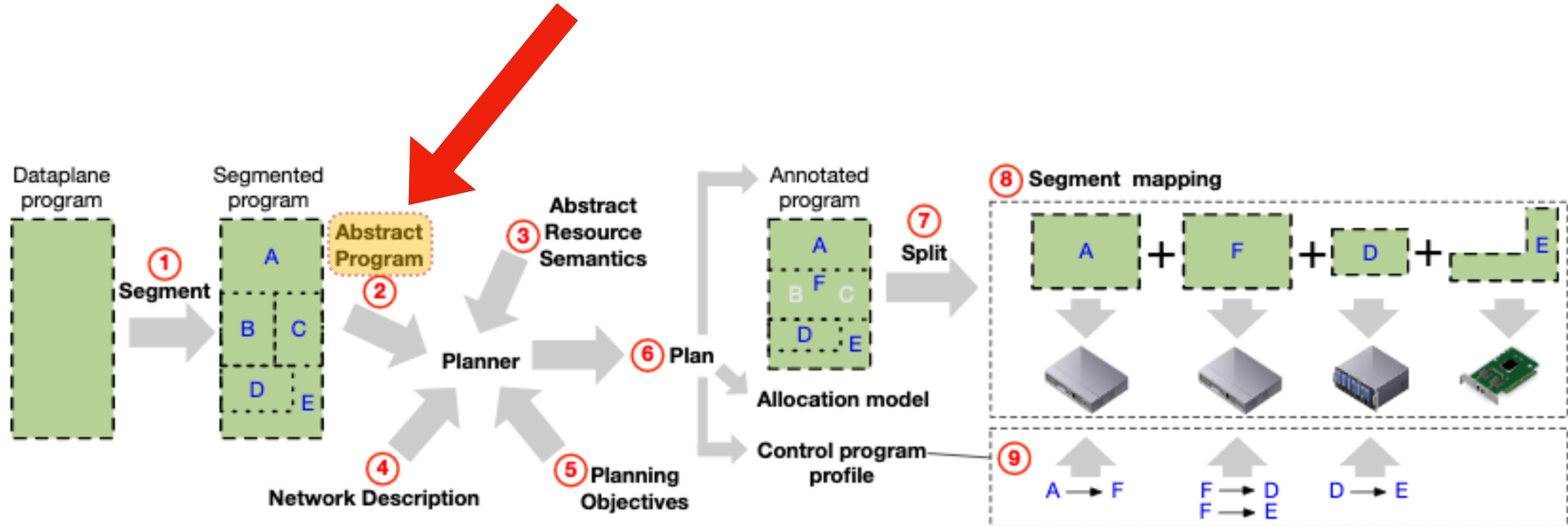


Flightplan

Idea from symbolic AI:
rule-based search.



Flightplan



Flightplan

Example program (Crosspod)

Segment annotation

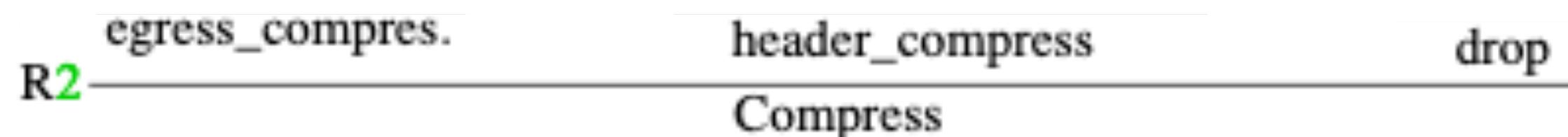
Resource dependence

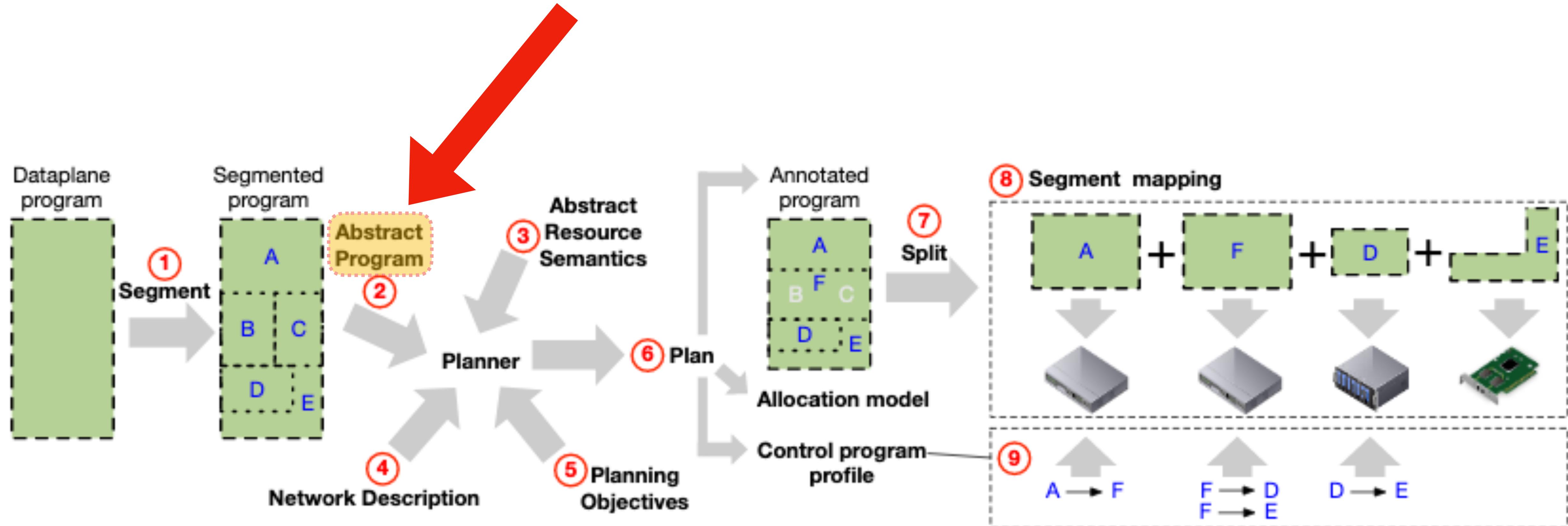
```
1 bit<1> compressed_link = 0;
2 bit<1> run_fec_egress = 0;
3 ...
4 flyto(Compress);
5 // If heading out on a multiplexed link, then header compress.
6 egress_compression.apply(meta.egress_spec, compressed_link);
7 if (compressed_link == 1) {
8     header_compress(forward);
9     if (forward == 0) {
10        drop();
11        return;
12    }
13 }
14 flyto(FEC_Encode);
15 check_run_FEC_egress.apply();
16 // If heading out on a lossy link, then FEC encode.
17 if (run_fec_egress == 1) {
18 ...
19 classification.apply(hdr, proto_and_port); // Sets hdr.fec.isValid()
20 if (hdr.fec.isValid()) {
21     encoder_params.apply(hdr.fec.traffic_class, k, h);
22     update_fec_state(hdr.fec.traffic_class, k, h,
23                      hdr.fec.block_index, hdr.fec.packet_index);
24     hdr.fec.orig_etherstype = hdr.eth.type;
25     FEC_ENCODE(hdr.fec, k, h);
26     ...
}
```

Abstract program

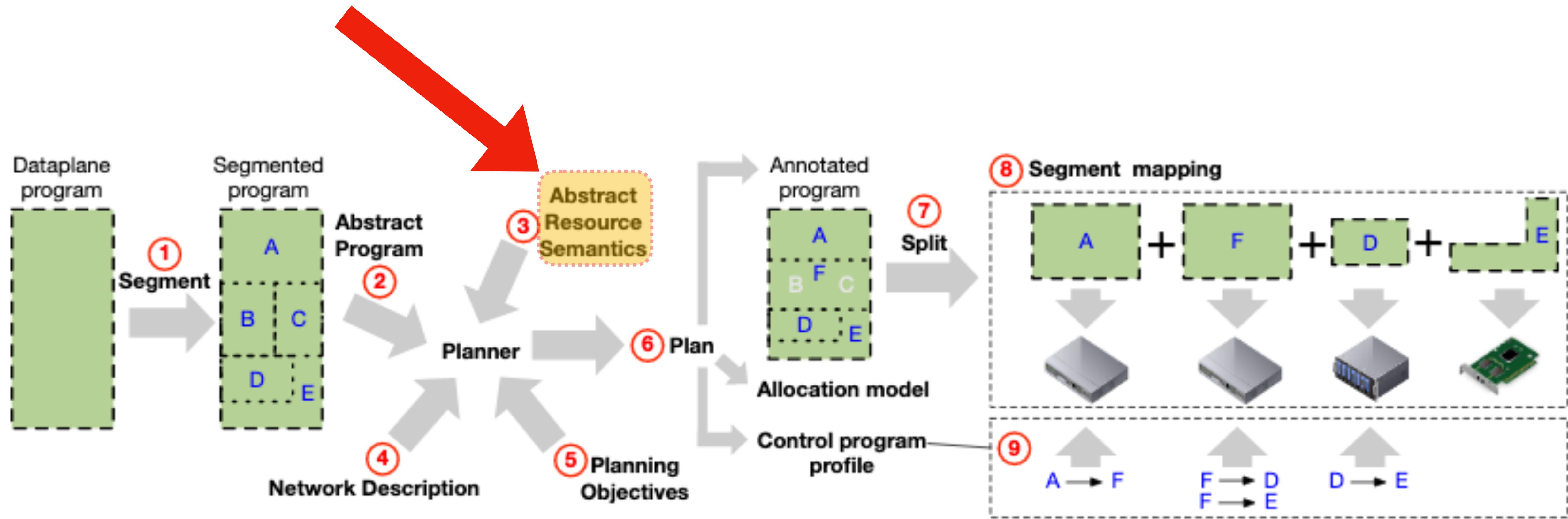
```
flyto(Compress);
// If heading out on a multiplexed link, then header compress.
egress_compression.apply(meta.egress_spec, compressed_link);
if (compressed_link == 1) {
    header_compress(forward);
    if (forward == 0) {
        drop();
        return;
    }
}
flyto(FEC_Encode);
```

(Rule generation is fully automatic)



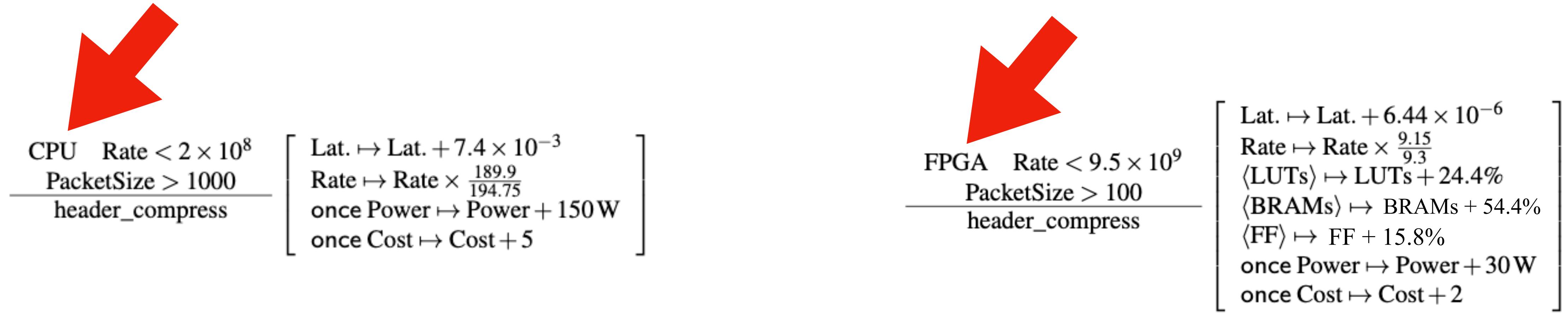


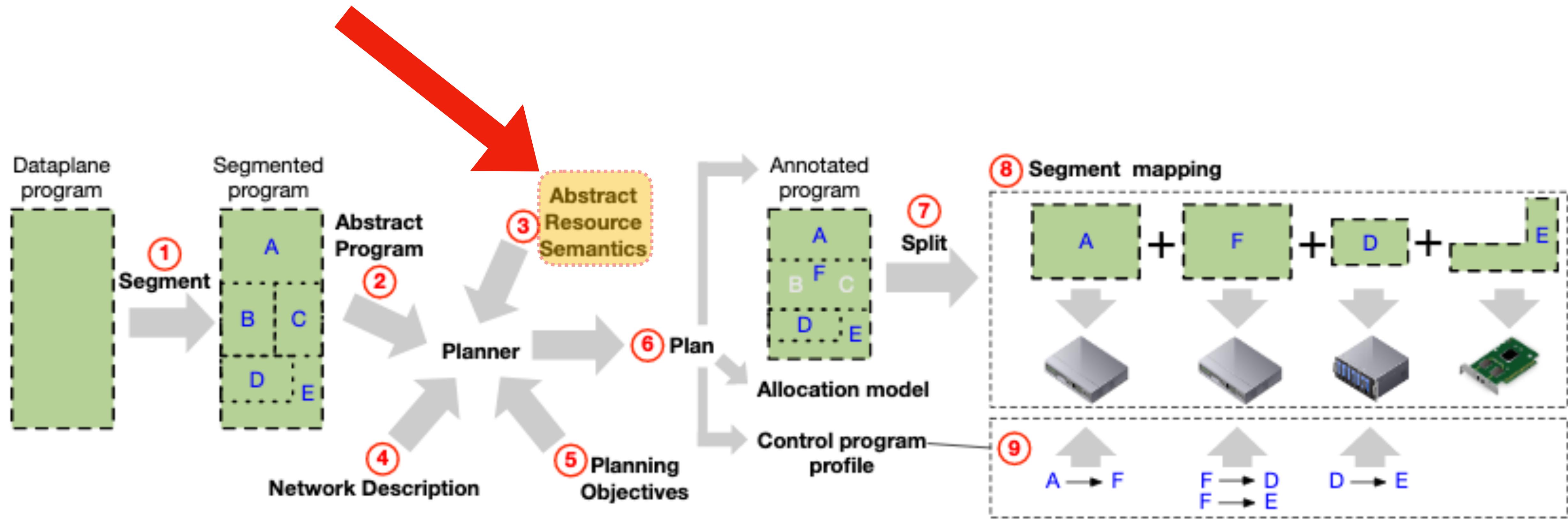
Flightplan



Flightplan

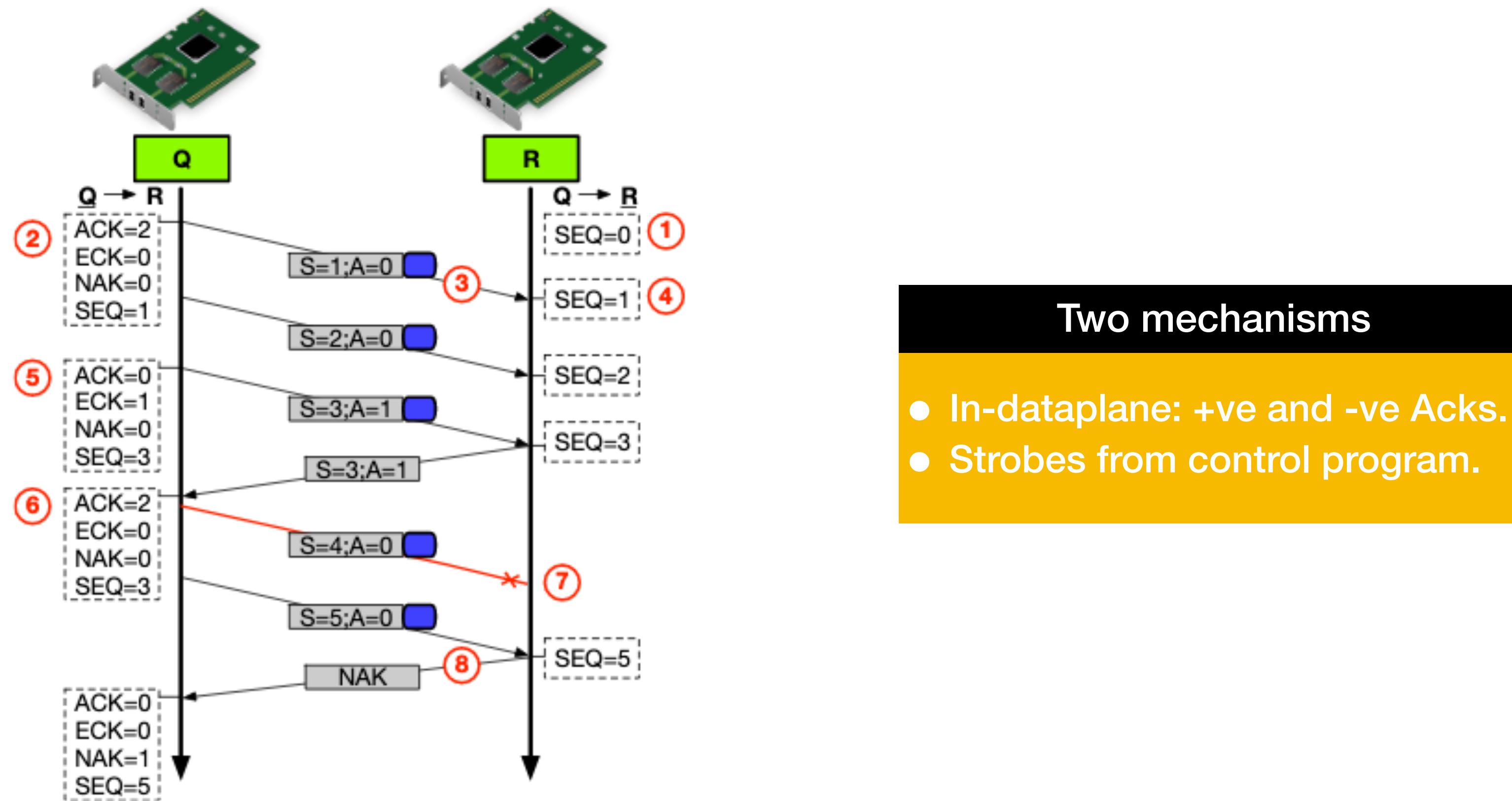
Abstract Resource Semantics





Flightplan

Runtime: Fault Detection + Handling



Evaluation

- **Simulation:**
 - Scale of the network (featuring various programs)
 - Overhead
 - Disaggregation (different programs split in different ways)
 - Fail-over
- **Test-bed:**
 - Throughput, latency, power, resource utilization
 - Plan comparisons for hardware alternatives
 - Single-feature evaluation

Fig 10: Resources & Behavior vs Functions (Testbed experiment)

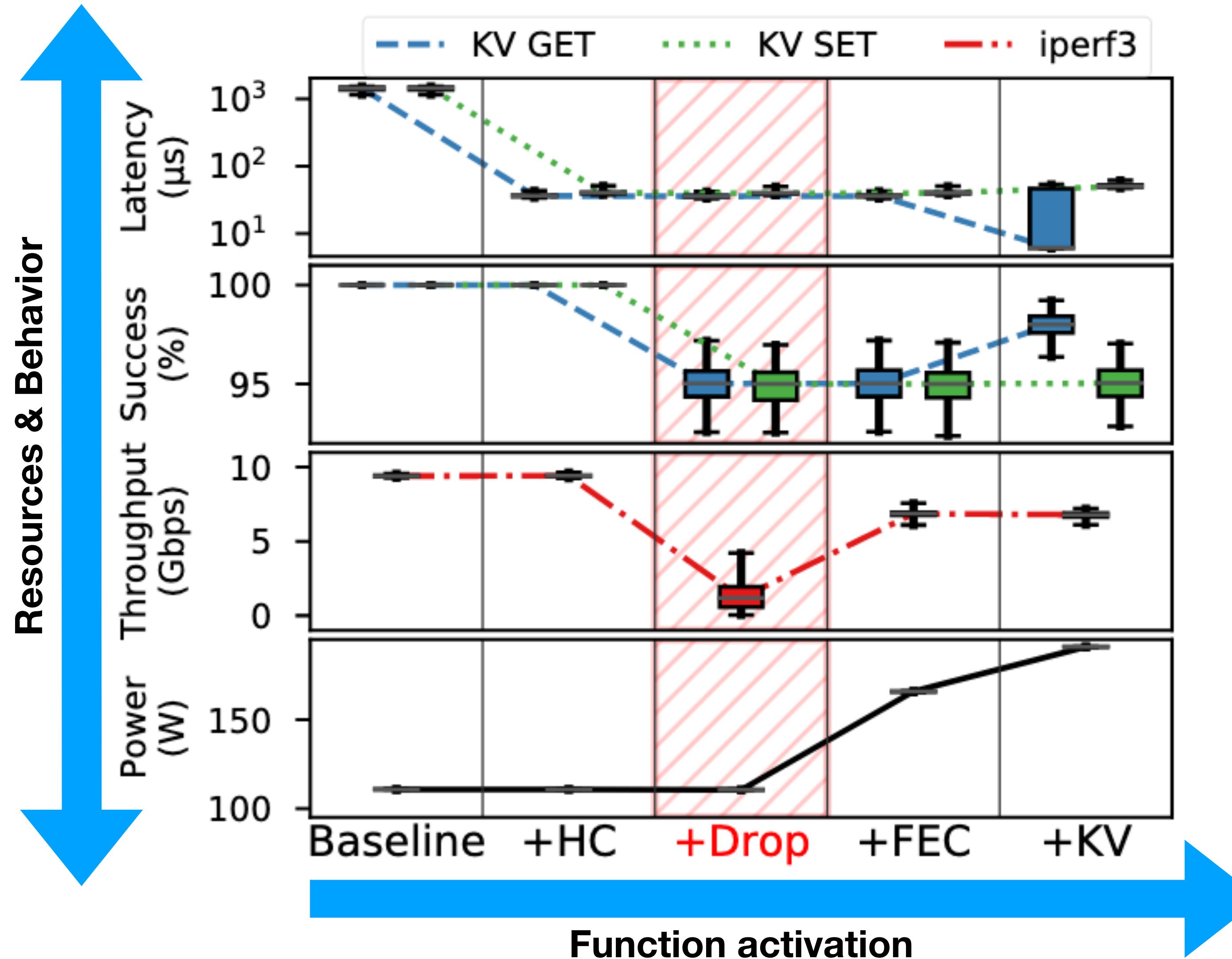


Fig 9: Plan comparison (Testbed + Simulation)

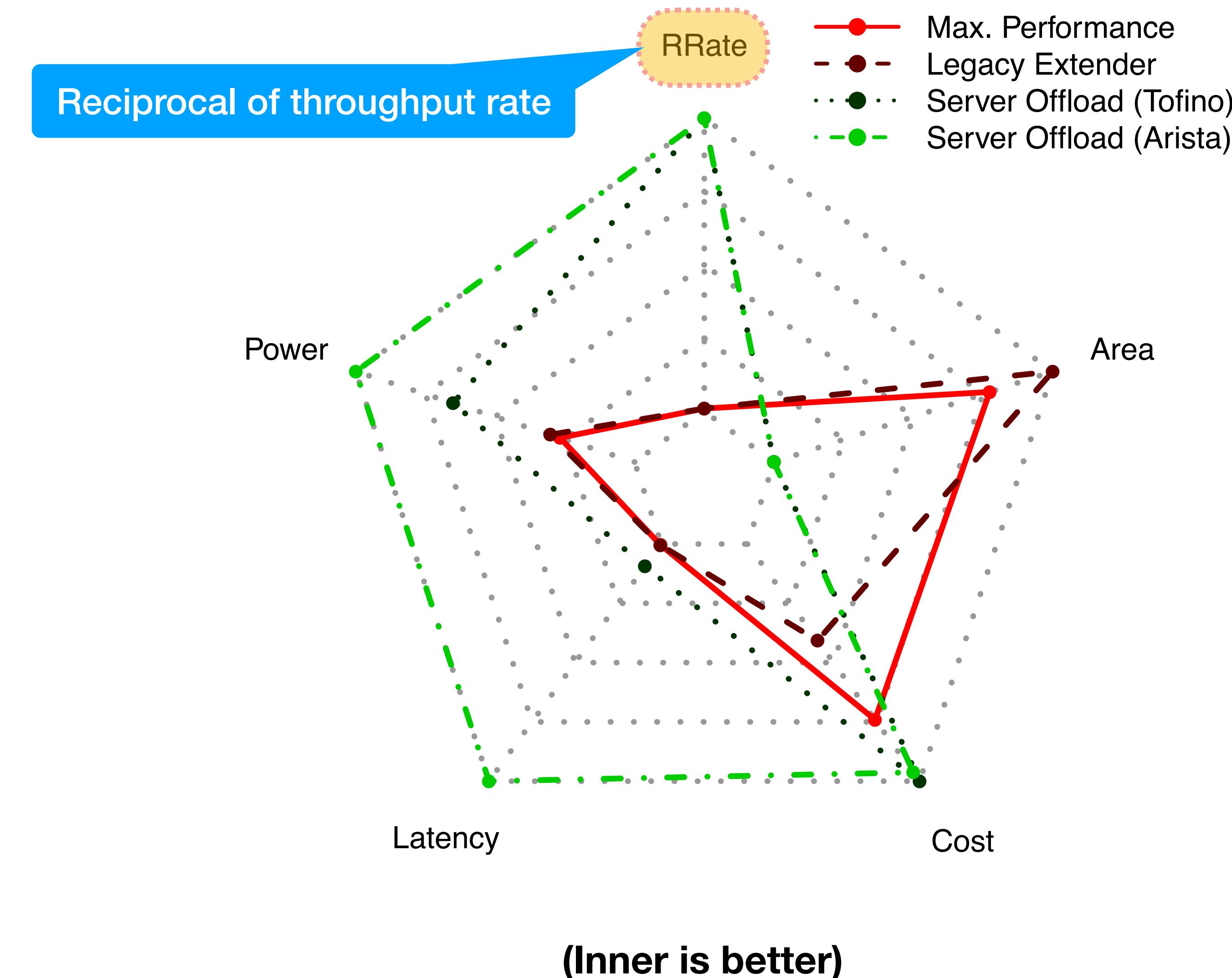


Fig 7: Multiple Programs vs Runtimes vs Splits in same network (Simulation)



Runtimes

- Full
- Headerless

Functions/features

- ALV.p4
- firewall.p4
- KV cache



Header compress/decompress



FEC encode/decode

Fig 7: Multiple Programs vs Runtimes vs Splits in same network (Simulation)

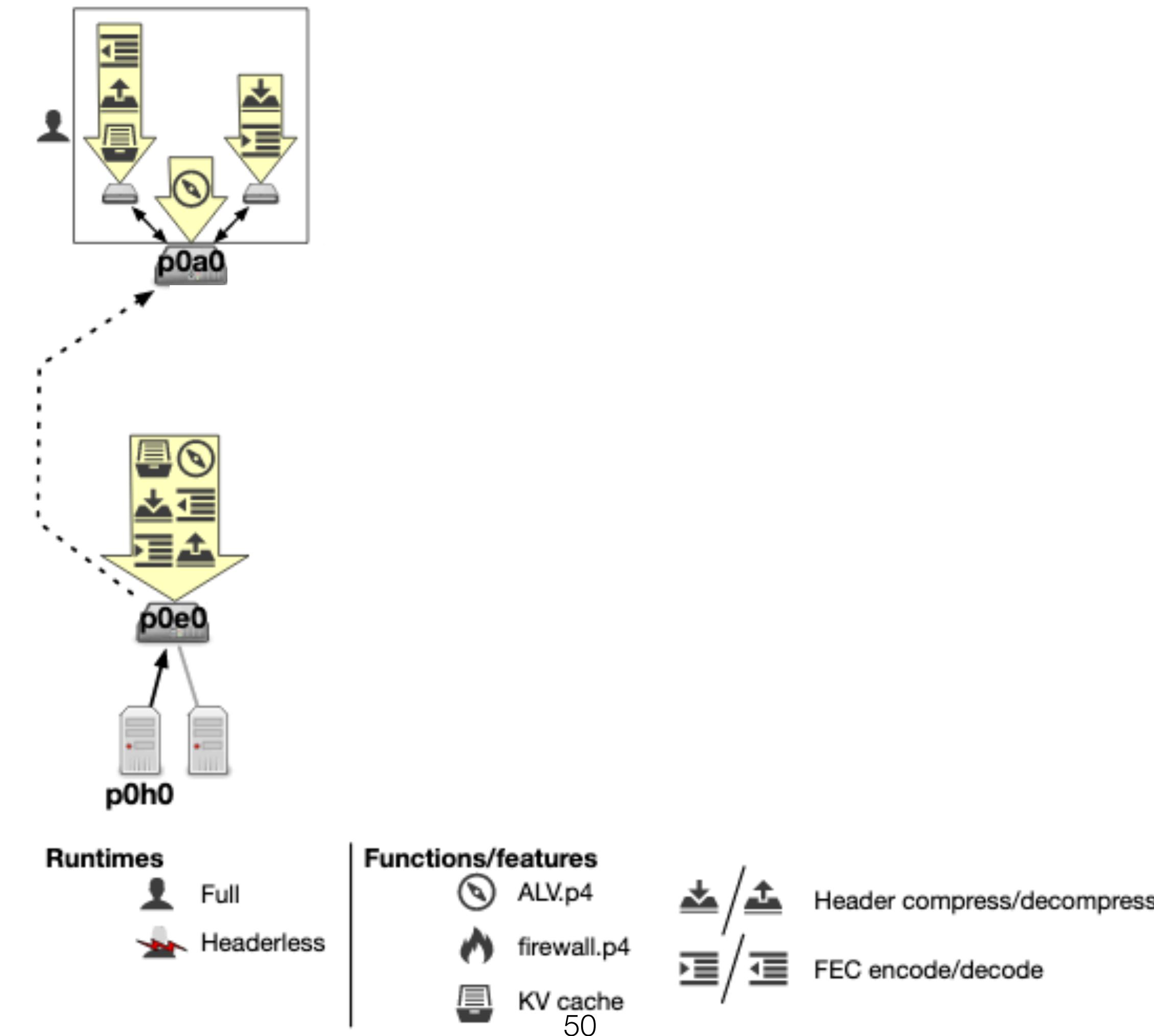
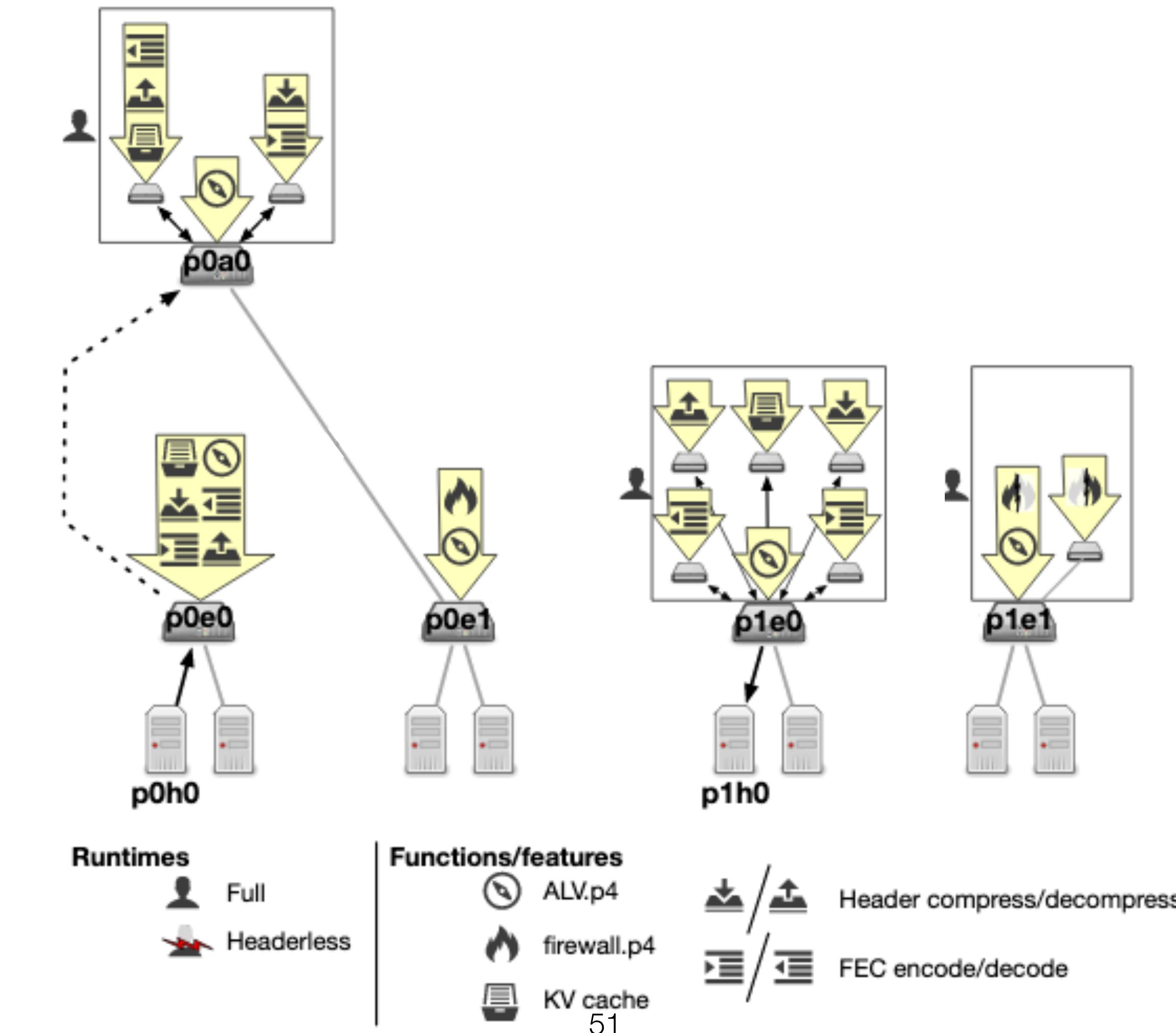
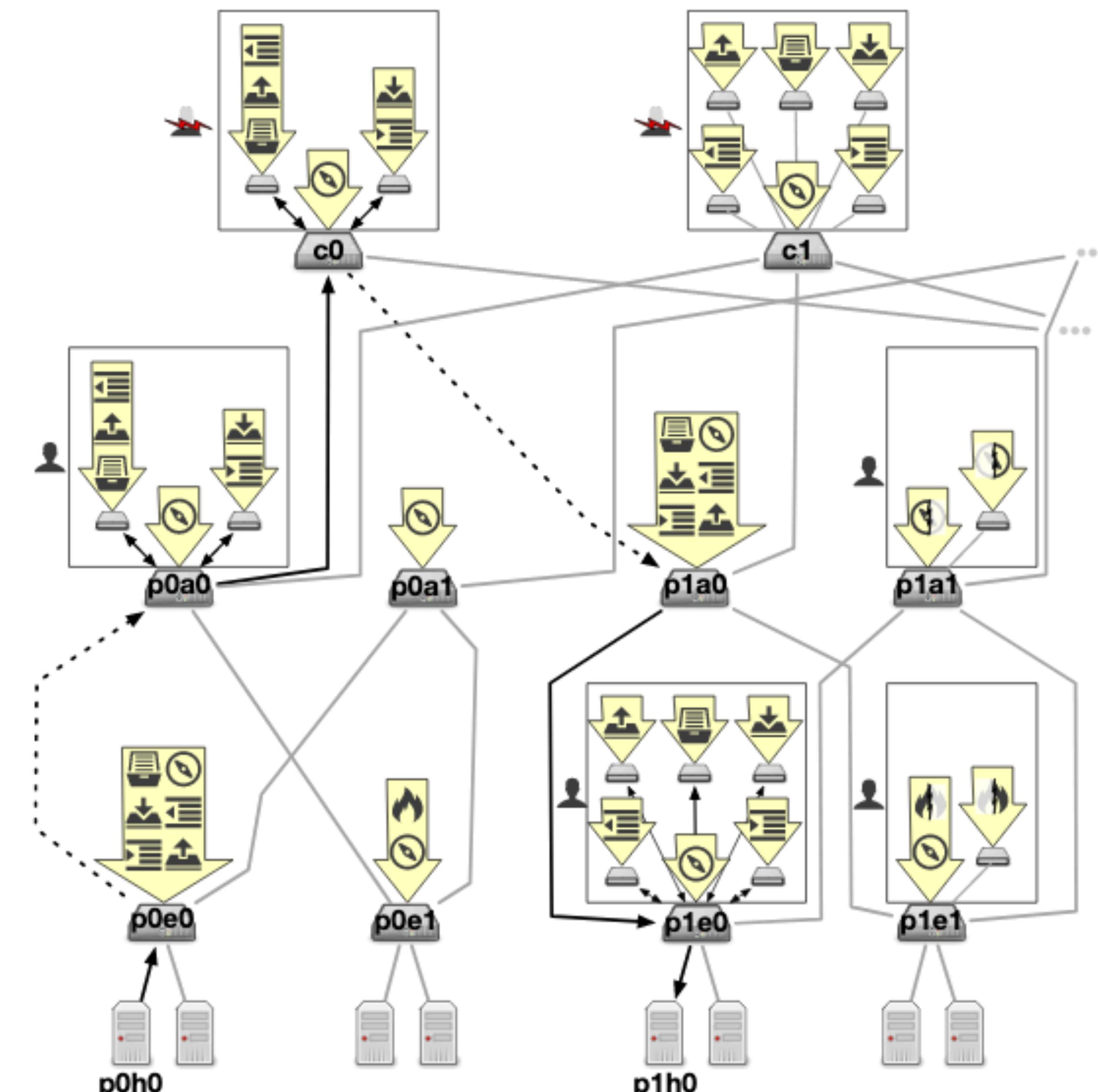


Fig 7: Multiple Programs vs Runtimes vs Splits in same network (Simulation)





Runtimes

Full
 Headerless

Functions/features

- ALV.p4
- firewall.p4
- KV cache
- Header compress/decompress
- FEC encode/decode

FLIGHTPLAN DEMO

Choose an Experiment...

Start

About

Flightplan demo

MSc students: Heena Nagda (GATech), Rakesh Nagda (Penn)

Other features: graphs, multimedia cues (e.g., icons, packet structure), ...

<https://flightplan.cis.upenn.edu/>

Flightplan: Dataplane Disaggregation and Placement for P4 programs

Nik Sultana John Sonchack Hans Giesen Isaac Pedisich Zhaoyang Han
Nishanth Shyamkumar Shivani Burad André DeHon Boon Thau Loo

University of Pennsylvania

<https://flightplan.cis.upenn.edu/>

NSDI'21