







Kernel Methods for Koopman-based Modeling

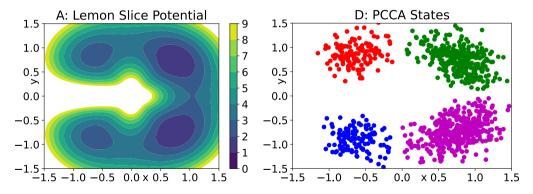
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Metastable Systems

- Goal: Automatically analyse *metastable* systems based on simulation data.
- Model System: Langevin Dynamics $dX_t = -\nabla V(X_t) dt + \sqrt{2kT} dW_t$.





Outline

1. The Koopman Operator and EDMD

2. Variational Approach (VAC)

3. Kernel Methods and Random Features



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• Generate transformed snapshot matrices $(x_k, y_k \text{ separated by time } t)$:

$$\Psi(\mathbf{X}) = \begin{bmatrix} \psi(x_1) & | & \cdots & | & \psi(x_m) \end{bmatrix} \in \mathbb{R}^{n \times m},$$

$$\Psi(\mathbf{Y}) = \begin{bmatrix} \psi(y_1) & | & \cdots & | & \psi(y_m) \end{bmatrix} \in \mathbb{R}^{n \times m}.$$

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■ Solve **regression** problem (EDMD):

$$\mathbf{K}^{t} = \operatorname{argmin}_{K \in \mathbb{R}^{n \times n}} \| \Psi(\mathbf{Y}) - \mathbf{K}^{T} \Psi(\mathbf{X}) \|_{F}$$
$$= (\Psi(\mathbf{X})^{T} \Psi(\mathbf{X}))^{-1} (\Psi(\mathbf{X})^{T} \Psi(\mathbf{Y})).$$

Williams et al, J. Nonlinear Sci. (2015)



EDMD as a Galerkin Method

■ Empirical **Gramian** in Hilbert space L^2_{ρ} :

$$\frac{1}{m} \left[\Psi(\mathbf{X})^T \Psi(\mathbf{X}) \right]_{ij} \xrightarrow{m \to \infty} \mathbb{E}^{\mathcal{X}_0 \sim \rho} \left[\psi_i(\mathcal{X}_0) \psi_j(\mathcal{X}_0) \right] \qquad = \int_{\mathbb{X}} \psi_i(x) \, \psi_j(x) \, \mathrm{d}\rho(x).$$

lacksquare Empirical **Stiffness Matrix** in Hilbert space $L^2_
ho$:

$$\frac{1}{m} \left[\Psi(\mathbf{X})^T \Psi(\mathbf{Y}) \right]_{ij} \xrightarrow{m \to \infty} \mathbb{E}^{x \sim \rho} \left[\psi_i(x) \mathbb{E} \left[\psi_j(\mathcal{X}_t) \middle| \mathcal{X}_0 = x \right] \right].$$

Using the Koopman operator, EDMD becomes a Galerkin method:

$$\mathcal{K}^t \phi(x) = \mathbb{E}[\phi(\mathcal{X}_t) | \mathcal{X}_0 = x]$$

$$\Rightarrow \mathbb{E}^{x \sim \rho} [\psi_i(x) \mathbb{E}[\psi_j(\mathcal{X}_t) | \mathcal{X}_0 = x]] = \int_{\mathbb{X}} \psi_i(x) \mathcal{K}^t \psi_j(x) \, \mathrm{d}\rho(x).$$

Reviews:

Klus, FN, et al, J. Nonlinear Sci., 2018,

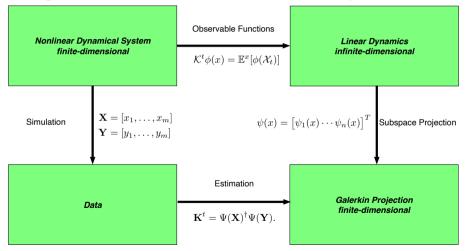
Mauroy, Suzuki, Mezic (eds), Koopman operator in systems and control, Springer 2020,

Berry, Giannakis, Harlim, Notices of the AMS, 2020.



The Koopman Approach

Main Idea: lifting into an infinite-dimensional space where the dynamics become linear.





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- Rayleigh variational principle (RVP):

$$\sum_{i=0}^{M} \left\langle \phi_i, \, \mathcal{K}^t \phi_i \right\rangle_{\mu} =: \mathcal{R}(\phi) \le \sum_{i=0}^{M} \lambda_i(t) \tag{1}$$

$$\langle \phi_k, \, \phi_l \rangle_{\mu} = \delta_{kl}. \tag{2}$$



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- $\blacksquare R(\psi)$ can be used as an **objective function**, subject to the constraint (2).
- All quantities in (1-2) can be **estimated from simulation data**:

$$\langle \phi_i, \phi_i \rangle_{\mu} \approx \frac{1}{m} \sum_{k=1}^m \phi_i(x_k) \phi_i(x_k), \quad \langle \phi_i, \mathcal{K}^t \phi_i \rangle_{\mu} \approx \frac{1}{m} \sum_{k=1}^m \phi_i(x_k) \phi_i(y_k).$$



Linear Variational Approach

■ Applied to a finite-dimensional subspace $\operatorname{span}\{\psi_j\}_{j=1}^n$:

$$\phi_i = \sum_{j=1}^n \mathbf{v}_{ji} \psi_j,$$

leads to generalized eigenvalue problem for Gramian matrices:

$$\mathbf{C}^t \mathbf{V} = \mathbf{C}^0 \mathbf{V} \Lambda, \qquad \mathbf{C}^t = \frac{1}{m} \sum_{l=1}^m \psi_i(x_k) \psi_j(y_k), \qquad \mathbf{C}^0 = \frac{1}{m} \sum_{l=1}^m \psi_i(x_k) \psi_j(x_k).$$

Linear VAC: Noé and FN, SIAM MMS, 2013, FN, Keller, et al, JCTC, 2014, TICA: Pérez-Hernández et al, J. Chem. Phys., 2013, Deep Learning: Mardt et al, Nat. Commun., 2018

Non-reversible systems: Wu and Noé, J. Nonlinear Sci., 2020



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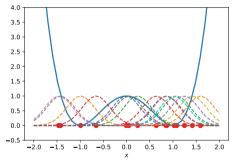
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Data-driven Basis Sets

- Choosing a good basis set is hard.
- Idea: let the data define the basis.



Typical choice: radial basis functions, e.g.

$$k(x_i, y) = \exp\left(-\frac{1}{2\sigma^2} ||x_i - y||^2\right)$$



EDMD and RKHS

• Kernel-based basis functions $k(x_i, \cdot)$ lead to matrices...

$$\mathbf{C}^{0}(r,s) = \mathbf{K}_{X}(r,s) = k(x_{r},x_{s}),$$
 $\mathbf{C}^{t}(r,s) = \mathbf{K}_{X}^{t}(r,s) = k(y_{r},x_{s}).$

• ... and the generalized eigenvalue problem:

$$\mathbf{K}_X^t \mathbf{w}_i = \lambda_i(t) \mathbf{K}_X \mathbf{w}_i.$$

■ Both matrices scale with the data size $(m \times m)$.

Klus et al. J. Nonlinear Sci., 2020:

Klus, FN, and Hamzi, Entropy, 2020



Intro RFF

■ A translation invariant kernel with k(x,x) = 1 can be written as a superposition of complex plane waves:

$$k(x,y) = \mathbb{E}^{\omega \sim \rho} \left[e^{-i\omega^T x} \overline{e^{-i\omega^T y}} \right] \approx \frac{1}{p} \sum_{u=1}^p e^{-i\omega_u^T x} \overline{e^{-i\omega_u^T y}},$$

where ρ is the **spectral measure** in frequency space (Bochner's theorem).

■ The spectral measure is known for most popular kernels, sampling from ρ is easy.

Rahimi and Recht, Advances in Neural Information Processing Systems, 2007 $\,$



Low-Rank Kernel GEV

■ Low-rank rep of kernel Koopman GEV:

$$\mathbf{K}_{X} = [k(x_{r}, x_{s})]_{r,s} \approx \frac{1}{p} \left[\mathbf{M} \mathbf{M}^{\mathrm{H}} \right]_{r,s}, \qquad \mathbf{K}_{X}^{t} = [k(y_{r}, x_{s})]_{r,s} \approx \frac{1}{p} \left[\mathbf{M}^{t} \mathbf{M}^{\mathrm{H}} \right]_{r,s},$$

$$\mathbf{M} = \left[e^{-ix_{r}^{\top} \omega_{u}} \right]_{r,u} \in \mathbb{C}^{m \times p}, \qquad \mathbf{M}^{t} = \left[e^{-iy_{r}^{\top} \omega_{u}} \right]_{r,u} \mathbb{C}^{m \times p}.$$

FN and Klus, J. Chem. Phys., 2023

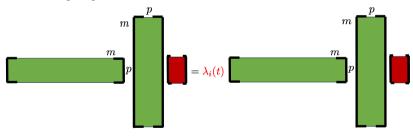


Low-Rank Kernel GEV

Non-zero eigenvalues can be obtained from dual problem

$$\mathbf{M}^{\mathrm{H}}\mathbf{M}^{t}\mathbf{v}_{i} = \hat{\lambda}_{i}(t)\mathbf{M}^{\mathrm{H}}\mathbf{M}\mathbf{v}_{i},$$

which is of dimension $p \times p$.



FN and Klus, J. Chem. Phys., 2023



Algorithm

Algorithm 1 RFF-based Spectral Approximation of the Koopman Operator

Input: data matrices $\mathbf{X} = [x_1, \dots, x_m] \in \mathbb{R}^{d \times m}, \ \mathbf{Y} = [y_1, \dots, y_m] \in \mathbb{R}^{d \times m}$

kernel function k with spectral measure ρ ,

number of features p, truncation rule for singular values.

Output: Approximate eigenpairs $(\hat{\lambda}_i(t), \hat{\psi}_i)$.

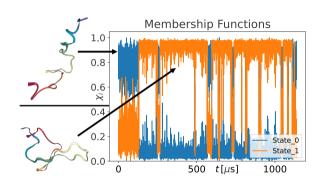
- 1: Draw p samples $\{\omega_u\}_{u=1}^p$ from the spectral measure ρ .
- 2: Form matrices $\mathbf{M} = \left[e^{-ix_r^\top \omega_u}\right]_{r,u}, \quad \mathbf{M}^t = \left[e^{-iy_r^\top \omega_u}\right]_{r,u}.$
- 3: Compute SVD of M, choose rank r according to truncation rule: $\mathbf{M} \approx \mathbf{U} \Sigma \mathbf{W}^{\mathrm{H}}$.
- 4: Form reduced matrix $\mathbf{R} = \mathbf{U}^{\mathrm{H}} \mathbf{M}^t \mathbf{W} \Sigma^{-1}$.
- 5: Compute eigenpairs of reduced problem $\mathbf{R}\mathbf{u}_i = \hat{\lambda}_i(t)\mathbf{u}_i$.
- 6: Transform to original RFF basis: $\mathbf{v}_i = \mathbf{W} \Sigma^{-1} \mathbf{u}_i$, $\hat{\psi}_i(x) = \mathbf{v}_i^{\mathrm{H}} \phi_{\mathrm{RFF}}(x)$.



Fip35

- Small protein, 35 amino acids.
- Gaussian kernel on 600 distances and angles.
- Use p = 1000 Fourier features.
- Compute leading 2 eigenvalues and eigenfunctions.
- Transform into membership functions indicating metastable states.

Philipp, Schaller, Boshoff, Peitz, FN, Worthmann, arxiv 2402.02494, 2024





Acknowledgments

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- Klus, FN, Hamzi, Kernel-Based Approximation of the Koopman Generator and Schrödinger Operator, Entropy, 22, 0722, 2020
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