

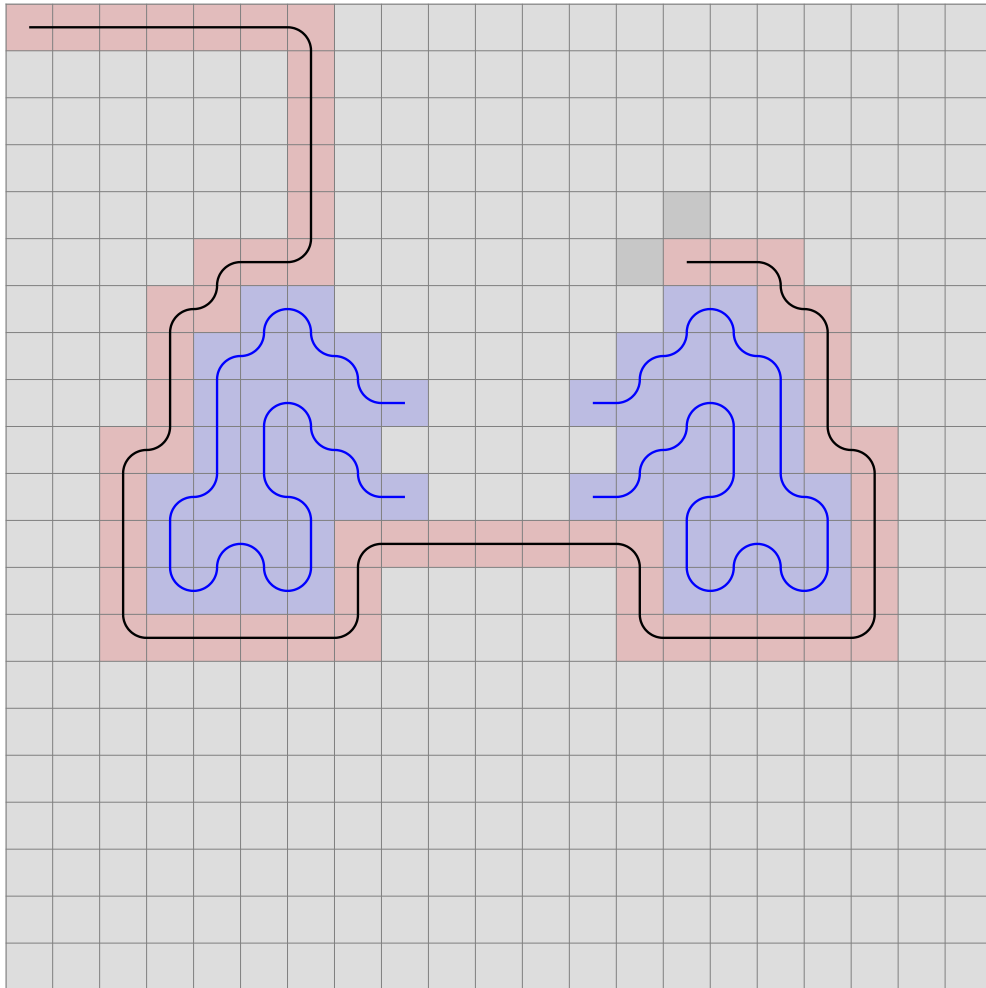
The one-way labyrinth algorithm

(github.com/fodorbalint/OneWayLabyrinth)

This research aims to solve the following problem:

"Draw a line that goes through an $n \times n$ grid (where n is an odd number), passing through each field once. The line has to start from the field at the upper left corner (1,1) and end at (n,n). At any time it is allowed to move left, right, up or down, and it has to randomly choose between the available fields."

At first sight it may look easy. But look at the following example:

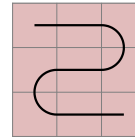


Based on the black line's movement, blue fragments were drawn to indicate a path we have to go through in the future in order to fill the board. Do you see why the situation is impossible from now on?

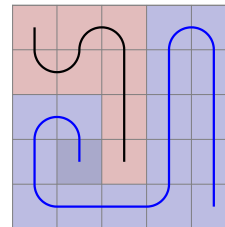
The question is, is there a single rule or a set of rules that will guarantee you can draw a labyrinth of any size? Or do the rules get infinitely complex?

To assist with the research, I have written a computer program. In the beginning, I let it run on a 21×21 field, and whenever I noticed a trouble, I coded the solution into it. While you can discover many patterns this way, they will be random and do not help in gaining a fundamental understanding. At one point you will find things get too complex, and you are still far from solving the 21×21 board. That's where a gradual approach comes in.

A 3×3 area can only be filled in two ways, like this and mirrored:

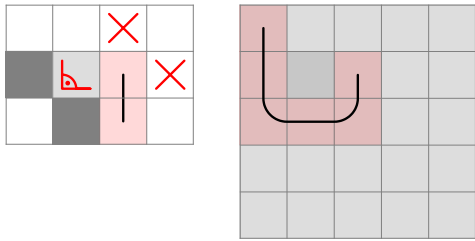


The 5×5 requires much more consideration. Whenever it is possible to draw future lines, the program has to be able to do it. The future lines can not only extend at each step but connect too.

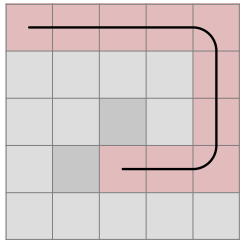


By August 21, 2023 all 5×5 scenarios were discovered. The number of walkthroughs are 104.

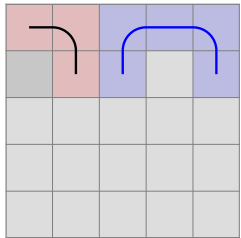
Here are the things to consider on a grid of this size:



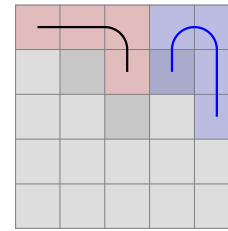
- A single field next to the live end that is walled from two other sides (either by the border or the line) needs to be filled in the next step. I call it C-shape. The pattern is both mirrored and rotated, so that the empty field is straight ahead. To qualify for this rule, the empty field cannot be the end corner. If there is a C-shape, we don't need to check other rules.



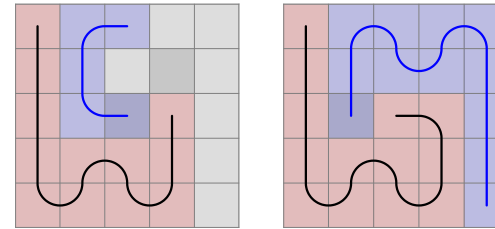
- Movement near the edge: In the example, we cannot step left (3,5), since the (2,5) field is empty.



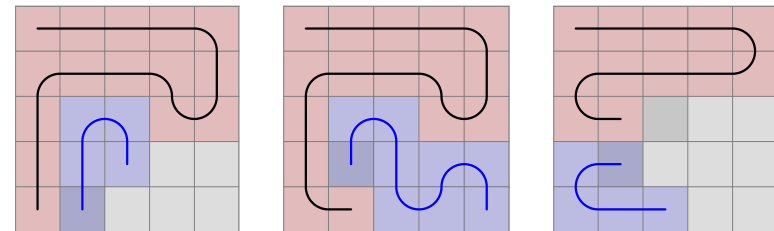
- A 2 x 3 empty area next to the live end that is walled by three sides (2-3-2 long) will have a future line going through along the walls. At the wall next to the main line, its direction is the opposite of the main line, meaning it will go from (3,2) upwards whereas the main line just took a step downwards. How the middle field will be filled is not yet known. Either the near end (the one the main line will go through first) or the far end can fill it.



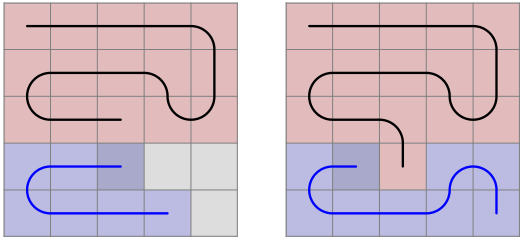
- A 2 x 2 empty area next to the live end that is walled by three sides (2-2-2 long) will have a future line going through along the walls. In this example, the far end is already extended by one step as it had only one option to move.



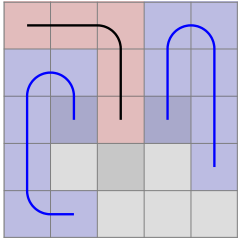
- Future line extension when we step on a future line: The far can be extended if it was 2 distance away from the near end. It can now fill the C-shape.



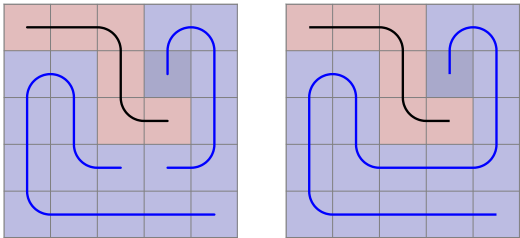
The same goes with 1 x- and y-distance. A C-Shape is not always created in this case.



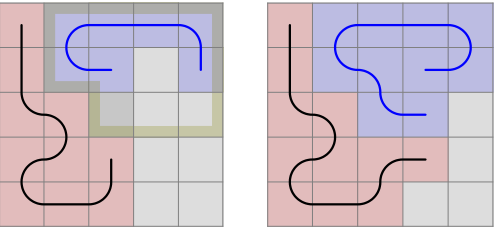
If the far end was near the end corner, it has to choose the other empty field.



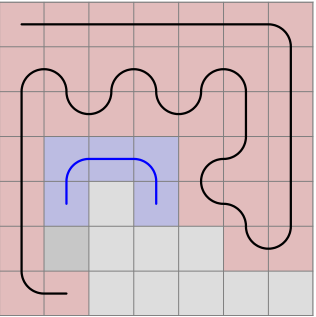
- Future line extension when stepping away: If there was a near end where the main line was in the previous step, it now may have only one choice to move, so it can be extended.



- Future line connection: In this case, the line being stepped on extends until the far end has two options. (When the end corner is one of them, it has to be removed.) Then, the line on the left extends and now has no other option than to connect to the line on the right.

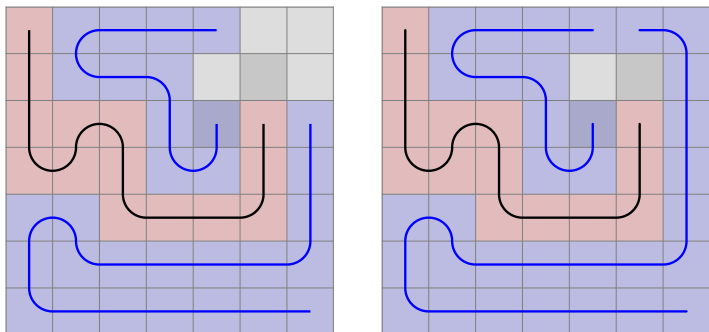


- When we are two distance away from the edge, we need to check if stepping towards it is possible.
It is because if we do so, an enclosed area is created, with one way to go out of it. If that area has an impair amount of cells, it cannot be filled, so we cannot take that step.
The explanation is simple: Imagine if the table was a chess board. In order to step from white to black, you would need to take an impair amount of steps - the color changes at every step. Here, the entry of the area would be (4,3) and the exit (5,3). An impair amount of steps means pair amount of cells.
In the example, you can also say that we cannot step right, because there is a future line start 2 to straight and an end 2 to straight and 2 to right. On 7 x 7, there will be examples where this is the rule we have to apply, because area counting is not getting triggered:

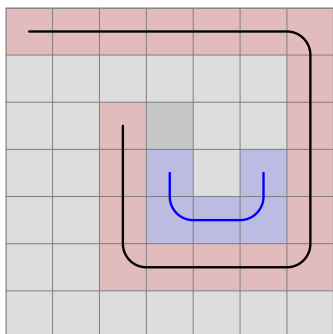


But let's start with the simpler rules:

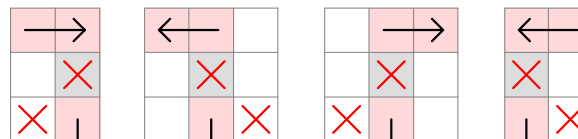
- Future line extension: When a near end is at 2 distance left or right from the live end, it will fill the field between them if the live end steps elsewhere. That's what happened in the 5 x 5 example above before the line failed.



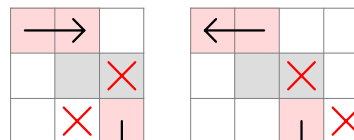
In other situations, there is a 1-thin future line next to the live end that can be extended if its far end is at the corner. Though disabling this rule does not affect the total amount of walkthroughs on a 7 x 7 grid, I chose to include it in the project on the basis that if a future line can be extended, we should do it. It can make a considerable difference. The left picture is without the rule, the right is with it.



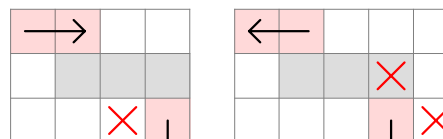
- Just like moving near the edge, we need to disable some fields if we are approaching an older section of the main line. In order to determine on which side the enclosed area is created, we need to examine the direction of the line at the connection point.



The gray square means empty field. When the field 2 to straight is taken, its left or right side will be taken too.

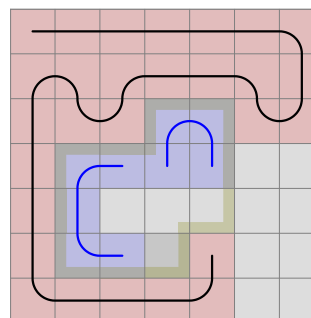


These will only be checked if one of the above 4 situations were not present. (They have to be mirrored, too.)

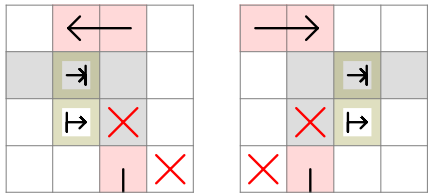


Likewise, these will be not be checked if the previous rules were true.

And when none of the 1-distance situations are valid, we check for 2-distance.



Impair areas can now happen inside the grid, not just on the edge, and the following rules have to be applied:

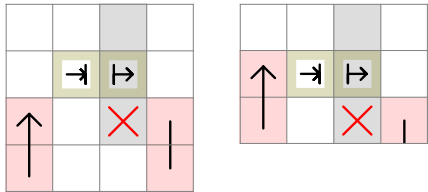


The procedure is similar to the the straight 2-distance rule. The only difference is that we count the area starting and ending at the marked fields. In the first, the direction of the circle is left, in the second right.

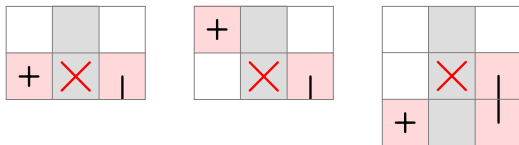
Besides mirroring them, we also have to rotate them both counter-clockwise and clockwise.

But we do not need 12 of such rules. Taking the first, the live end cannot come from the left, because the area parity was already checked in the previous step, and now we just added 2 fields to it. It can come from the right, and then there is naturally only one field we might have to disable.

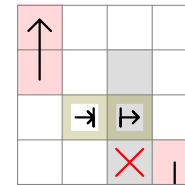
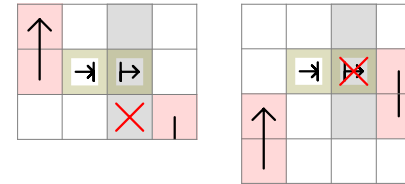
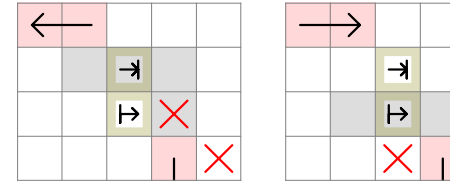
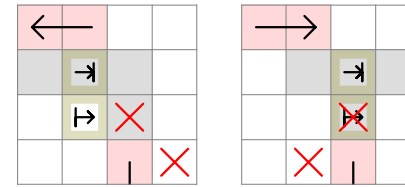
Here are the representations of the two scenarios for the left side:



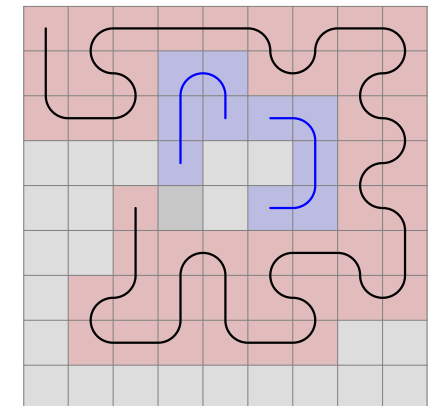
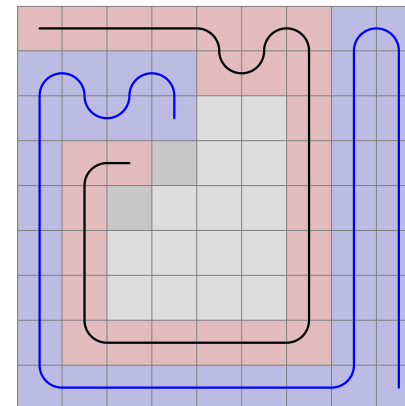
Similarly to the straight rules, these will only apply if there is no wall 2 distance to the left or right. Let's construct these preconditions.



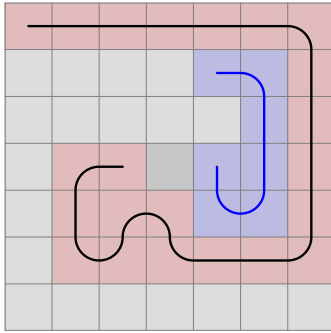
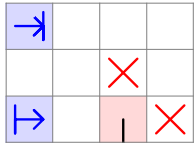
We are not finished. Did you notice the example above is not covered by these rules? We have to move the taken fields 1 and 2 steps to the side, both in straight and side direction.



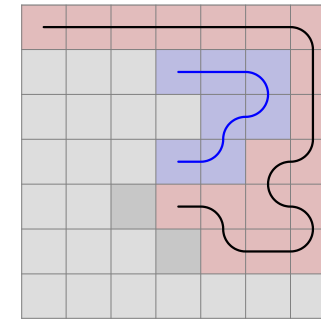
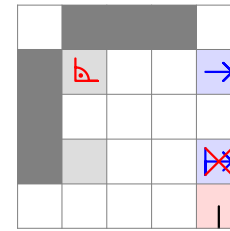
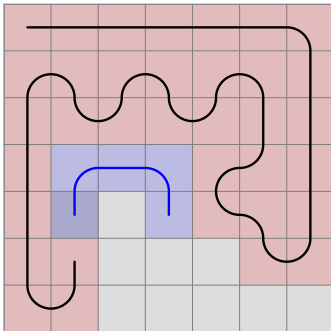
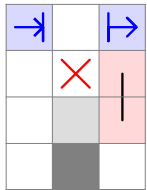
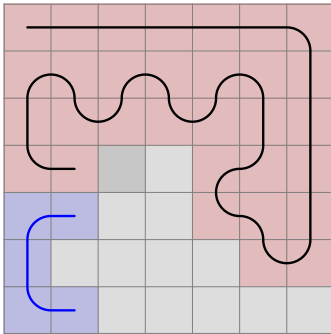
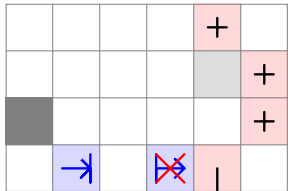
When any of the straight 2-distance rules are present, we don't need to check the side rules or the area created with the border. This is not entirely proven, but take these 9 x 9 examples:



And these are the rest of the rules:



- This is what I started the 7 x 7 introduction with. I will call it Future L.



- And these are the remaining size-specific rules. Future 2 x 2 Start End, Future 2 x 3 Start End and Future 3 x 3 Start End.

The program, in fast mode, can run through approximately 100 cases per second, depending on your computer speed. This enables us to discover all 7 x 7 walkthroughs, which is 111 712.

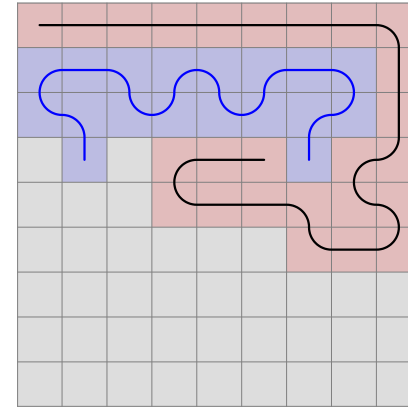
It is equal to what is described in the Online Encyclopedia of Integer Series (Number of simple Hamiltonian paths connecting opposite corners of a $2n+1 \times 2n+1$ grid).

As the sizes grow, it will be impossible to run through all cases with one computer in a reasonable time. In order to discover the patterns, we need to run the program randomly.

Is it possible to develop an algorithm that works for all sizes? The edge-related and area-counting rules are universal, but the size-specific rules get more and more complex. Can you define them with one statement?

I have made statistics about how many random walkthroughs you can complete on different grids using the 7 x 7-specific and the universal rules before running into an error. Based on 1000 attempts, here are the results:

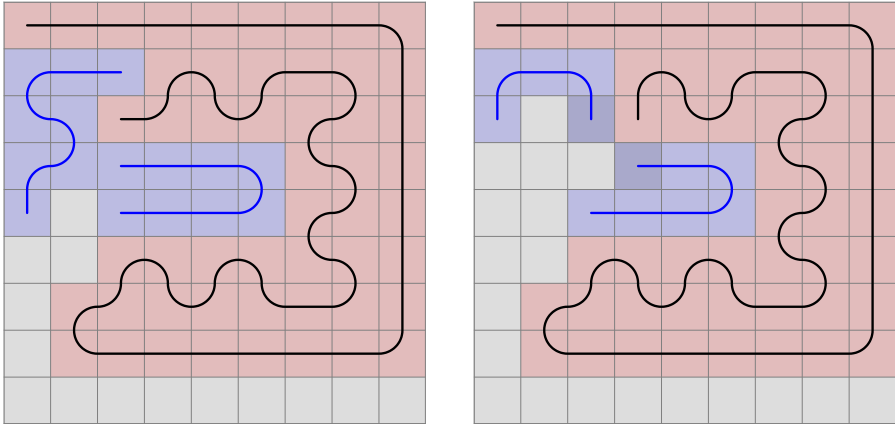
9: 19.5
11: 5.7
13: 2.6
15: 1.2
17: 0.7
19: 0.4
21: 0.2

[illegible]

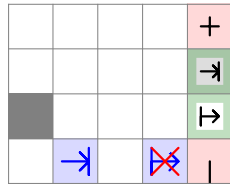
When generating code from the drawing, we have to check on which side the enclosed area was created. Here, we want it to be on the right side, so there are two cases to look at:

- The taken or border field beyond the end field is a taken field. In this case, if the field to its left is taken, its index must be lower. If the field to the right is taken, its index must be higher.
- It is the border. Add together the x- and y-coordinates to get a value. A higher value is closer to the end corner. Here, we compare the border field straight ahead and on its left, and we want the first-mentioned to be the smaller.

Now let's run the program further up to number 13 992:

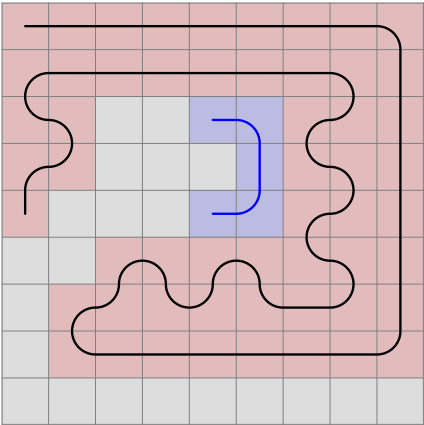


So we need to check if an enclosed has been created on that side, but counting the area is unnecessary. Nevertheless, we can represent the rule this way, setting the circle direction to right:

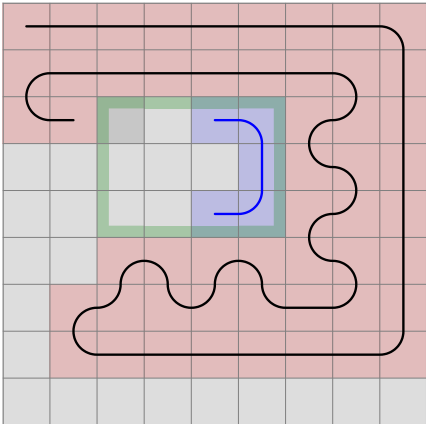
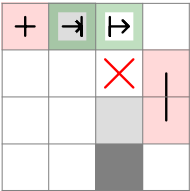


You may ask, why that field is "taken", not "taken or border". From what I found through some examples, if that field is border, the enclosed area on the right is impair, so the line cannot step in the other direction anyway. But it needs further examination.

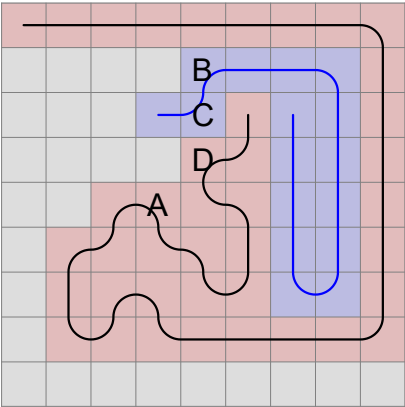
The next error, at 14 004 has something to with how I defined the universal rules of approaching an older section of the line, it needs to be reworked in light of the C-shape the main line can create with the border.



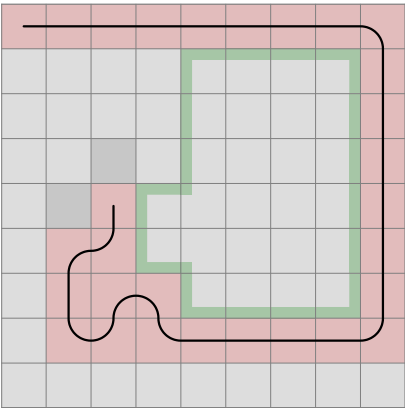
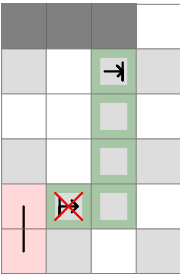
We need to take a few steps back, and then we can create the rule. It is similar to the universal 2-distance rule on the side, it just checks the field 2 behind and 1 to the side too. Even though the area counted is pair, now stepping to the right is disabled.



At 55 298, we get this:

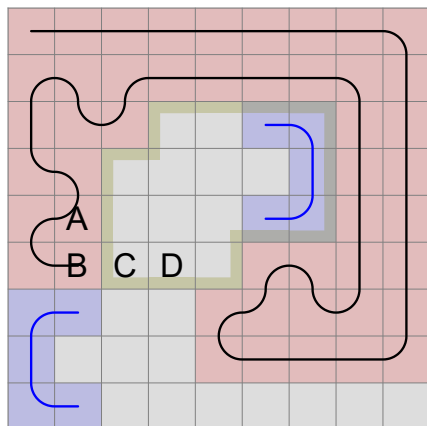


Let's analyze it! A double C-shape is created, because the line occupied the A field, and out of the B, C and D fields it exited the right-side area at C. It means, the area enclosed by the marked fields is pair. In this case, we shouldn't step right and the rule will therefore look like:



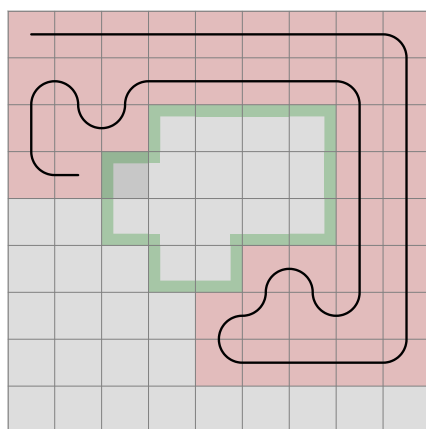
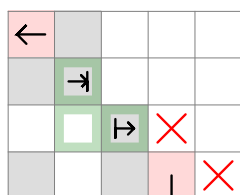
But what if from the A position, we step upwards in another situation? Compare these two on 11 x 11:

233 810 will look like:

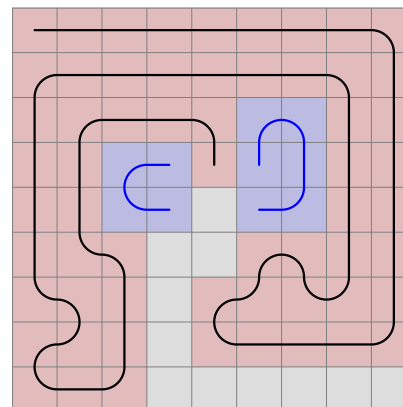


Once we step to A, it is unavoidable to get to B before entering the outlined area. It is because we can only reach B from the left or the bottom. The area is impair, therefore we cannot complete it starting in C and ending in D.

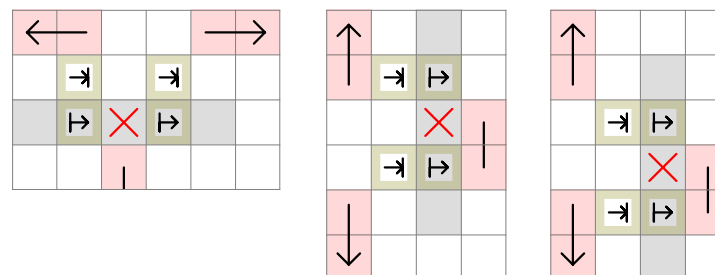
If we omit the C field from the area, the area becomes pair. It is clear that the start and end field being across each other, a pair amount of fields cannot be filled. We must therefore enter the area now.



234 256 has at first sight something to do with future lines.



But it is more than that. Notice that enclosed areas has been created on both sides simultaneously. Because of the universal rules for approaching an older section of the line, now we have no option to move. The areas can be filled individually, but we cannot step to left and right at the same time. We have to create 2-distance rules, which take both sides into account.



These are just a few of the possible combinations.

Any of the far straight rules (straight, mid across and across as I call them, depending on the horizontal distance of the obstacle) on the left side can be combined with any of those on the right side when the enclosed area is going to the same direction - left for left side and right for right side. And the same is true when the pattern is rotated to the left or right side. As far as programming concerned, it just needed a rework of the universal rules, we didn't need to make completely new ones.

We have made a similar rule previously. Now we need to simplify it.

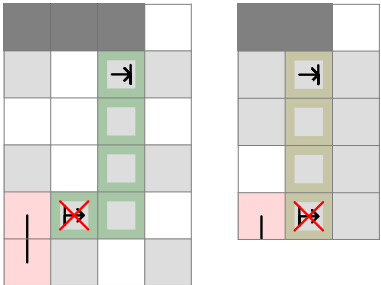
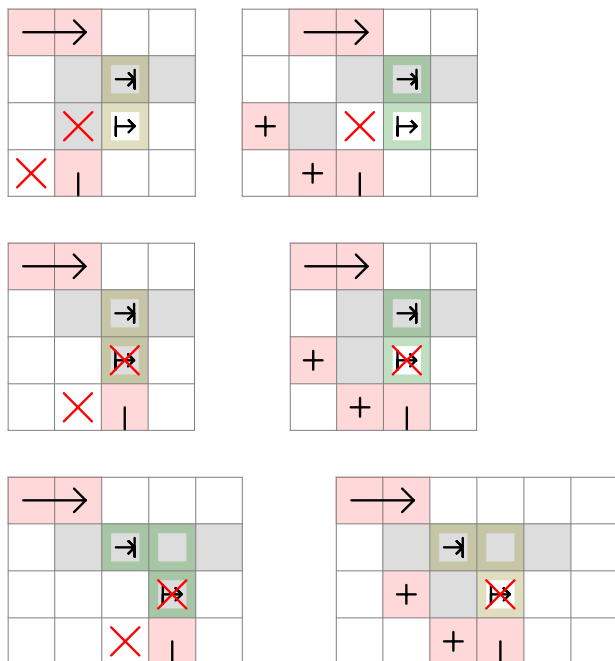
[illegible]

Figure 1 shows two 5x5 grids representing the 8-puzzle problem. The left grid shows a state with a red 'X' in the bottom-left cell and a red '+' in the bottom-right cell. The right grid shows a state with a red 'X' in the bottom-left cell and a red '+' in the bottom-right cell, with a green box highlighting the bottom-right cell and its neighbors.

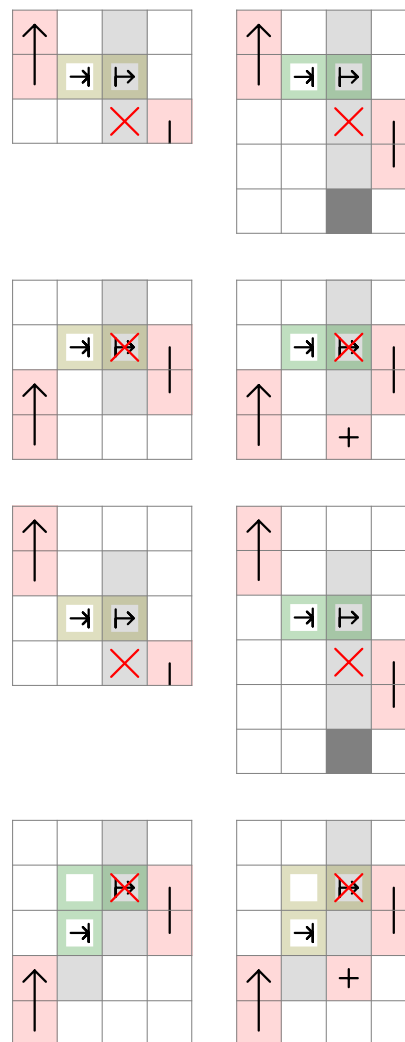
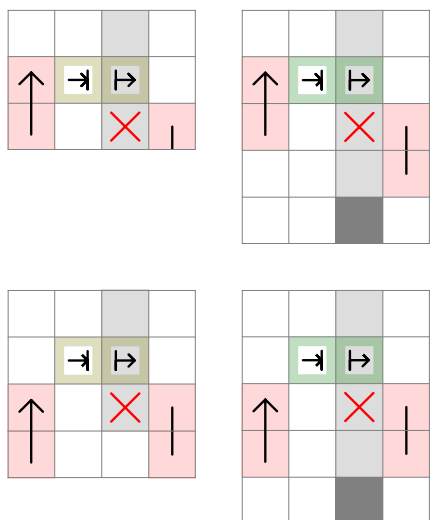
The figure consists of two side-by-side 10x10 grids. Both grids have a black boundary that starts at (0,0), goes right to (10,0), down to (10,10), left to (0,10), and back up to (0,0). The grids are divided into three regions: a light blue region in the top-left, a light green region in the top-right, and a light red region in the bottom-right. The blue path in the left diagram starts at (0,10), goes right to (1,10), down to (1,9), right to (2,9), down to (2,8), right to (3,8), down to (3,7), right to (4,7), down to (4,6), right to (5,6), down to (5,5), right to (6,5), down to (6,4), right to (7,4), down to (7,3), right to (8,3), down to (8,2), right to (9,2), down to (9,1), right to (10,1), and finally down to (10,0). The green path in the right diagram starts at (0,10), goes right to (1,10), down to (1,9), right to (2,9), down to (2,8), right to (3,8), down to (3,7), right to (4,7), down to (4,6), right to (5,6), down to (5,5), right to (6,5), down to (6,4), right to (7,4), down to (7,3), right to (8,3), down to (8,2), right to (9,2), down to (9,1), right to (10,1), and finally down to (10,0). The green path is a subset of the blue path, starting at (0,10) and ending at (10,0). The labels A, B, and C are placed on the green path at (5,5), (6,5), and (7,5) respectively.

[illegible]

Circle direction right:



Side, with taken fields above and below:



I have made some changes by adding some empty fields in side positions, so they are the same as the straight rules, just rotated.

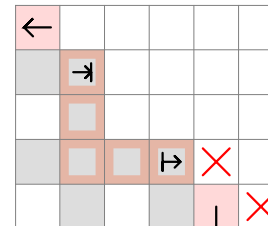
Also, I have added the side across down rule and changed the straight across rule accordingly. Not only fields next to each other can define an area, they can be across too. In that case, if the area originally was marked impair, now it has to be pair.

Notice that in side rules, when the taken field that would create the C-shape is below the obstacle creating the area, it can be a border field too. We have seen an example of that previously.

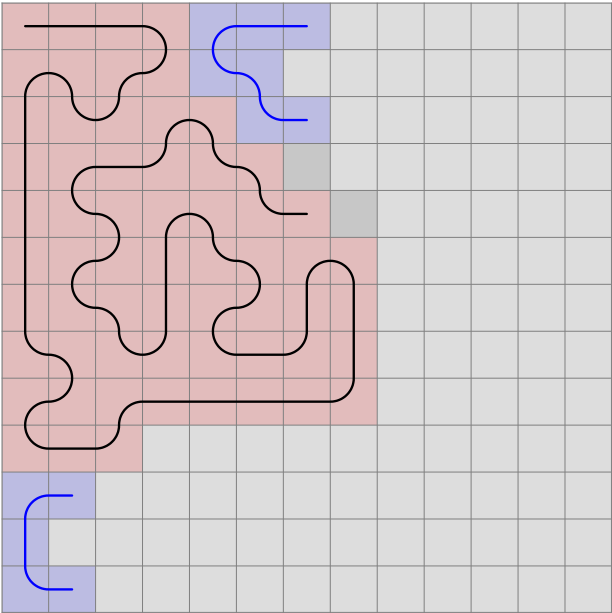
The diagram shows a complex, non-convex shape on a grid. The shape is defined by a black outline. It is divided into several regions: a central white region, a green rectangular region, a blue L-shaped region, and a red region. The regions are labeled A, B, C, D, and E. A blue line segment is also shown within the blue region.

In order to make a walkthroughable area, you would need to extend it by pairs of fields next to each other, like D and E. One will be filled at a pair amount of steps, the other at an impair amount.

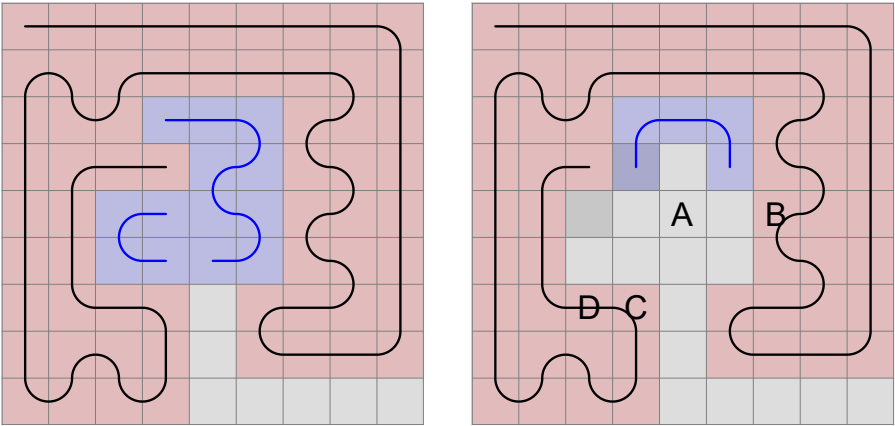
This is the rule representation. The reddish arealine now means the arealine is impair, and we know that the entry and exit points are the arealine start and end fields.



And now the walkthrough is possible.

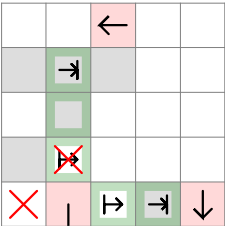


Continuing the 9 x 9 program, we get this at 641 019:

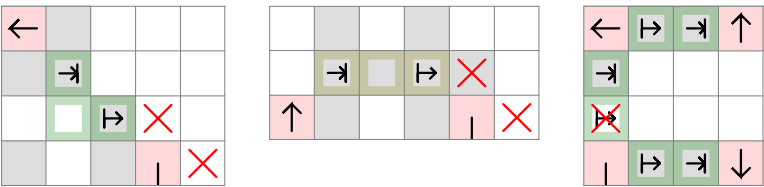


If you enter the pair area straight ahead, you will exit at A, and you need to turn towards B because of the C-shape. Now you cannot go in and out of the area enclosed by C, and the situation would be the same if that obstacle was in D.

To mark the two areas, each one has to be given a directional obstacle next to the count area end field. In this case, it represents a taken field, but we don't go wrong if we include the border as well.

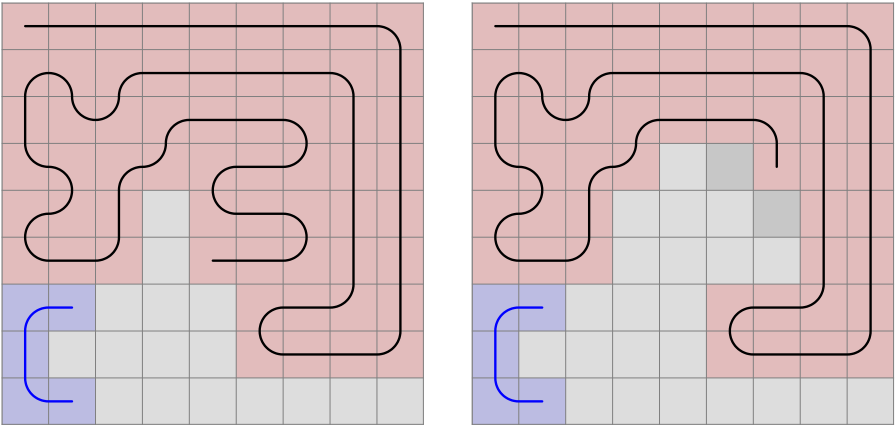


And with this marking system, we can correct the rules previously made. All rules featuring future line start and end fields have to be rewritten to start with. So we get the 2-distance across rule, the straight 3-distance rule to prevent a double C-shape, and the square constellation with 3 areas. All of them are rotated clockwise or counter-clockwise.

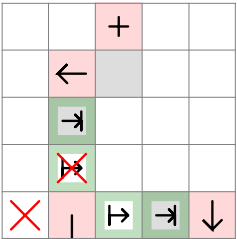


Let's return to the last example and make a modification:

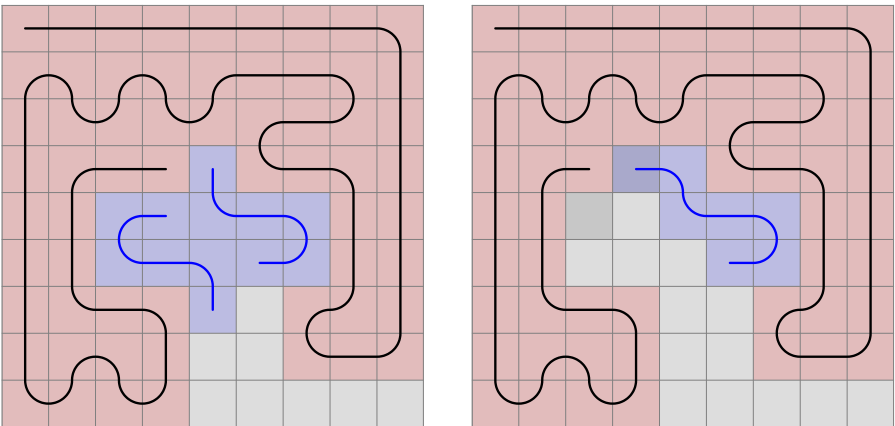
811 808:



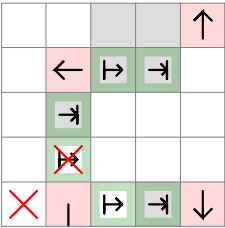
Recognize it is a variation of the square obstacle pattern where instead of an area, there is a C-shape at the rule's upper edge.



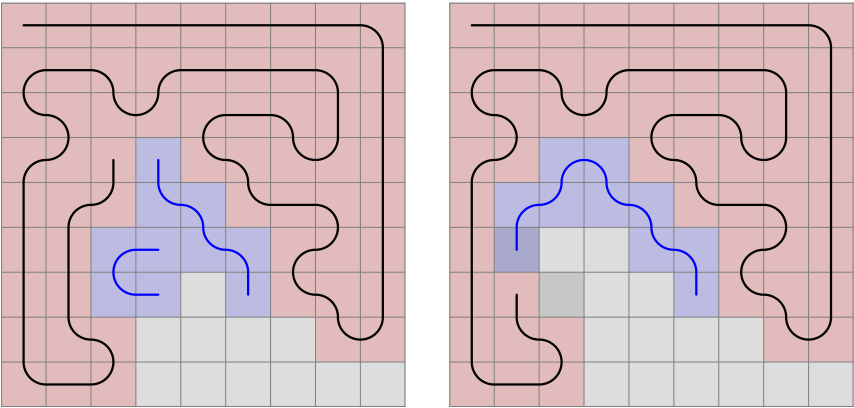
1 261 580:



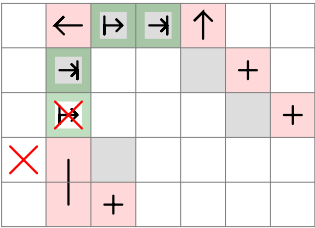
Again, same pattern with area. The upper obstacle is now moved, but it will satisfy the previous examples too. The rule replaces the old one.



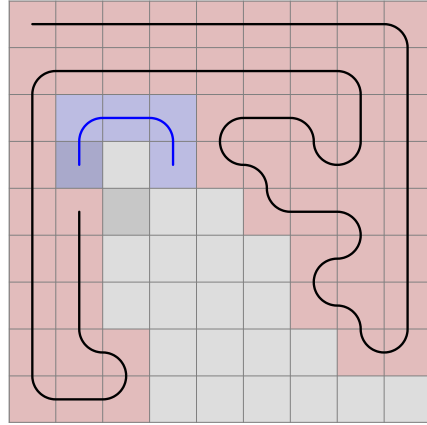
2 022 337 is getting stuck because of the stair-shaped walls that force the future line along them. Therefore, an area is created with only one field to go in and out of it. What is the solution?



Though not as universal as we want it to be, this will solve this specific situation:



A 10x10 grid with a black boundary. The grid is divided into four quadrants by a vertical line at column 5 and a horizontal line at row 5. The top-left quadrant (columns 1-5, rows 1-5) is light blue. The top-right quadrant (columns 6-10, rows 1-5) is light red. The bottom-left quadrant (columns 1-5, rows 6-10) is light green. The bottom-right quadrant (columns 6-10, rows 6-10) is light yellow. A blue path starts at (1, 5), goes right to (5, 5), then down to (5, 10), then left to (1, 10), then up to (1, 5). The path is composed of several segments: a horizontal segment from (1, 5) to (5, 5), a vertical segment from (5, 5) to (5, 10), a horizontal segment from (5, 10) to (1, 10), and a vertical segment from (1, 10) to (1, 5). There are also several small loops and turns along the path, particularly in the top-left and bottom-right quadrants.



		+		
	+			
←				
↖				
→	×	→	↖	↓
	↓			

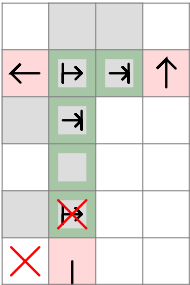
	←		
	↩		
	→	×	
		↓	×

The image contains two side-by-side diagrams of a maze. Each diagram is a 10x10 grid. The maze is defined by black lines. The obstacles are represented by red and blue squares. In the left diagram, a black path is shown, starting from the top left and ending at the bottom right. In the right diagram, a blue path is shown, starting from the top left and ending at the bottom right. The paths are identical in both diagrams.

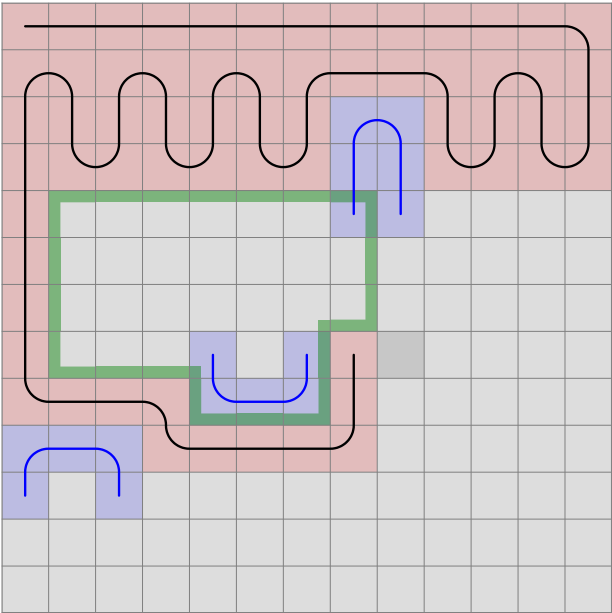
			↑
←	→	→	
	→		
	→		
	↓		

41 42

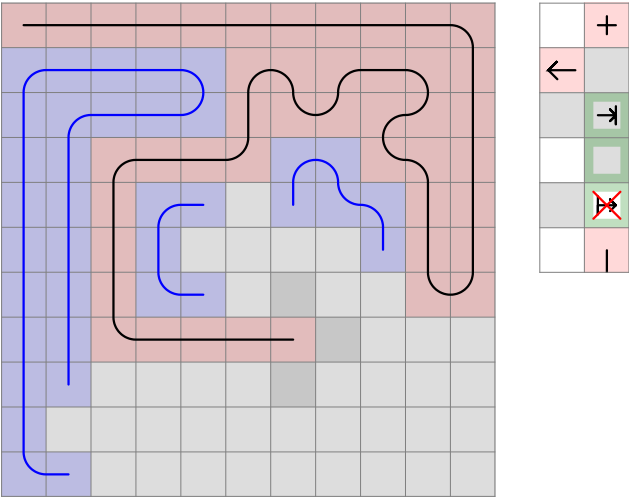
But if the obstacle in the upper right corner is moved down, even this will be impossible.



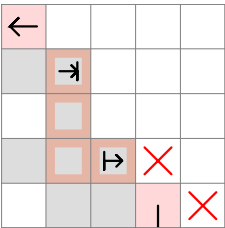
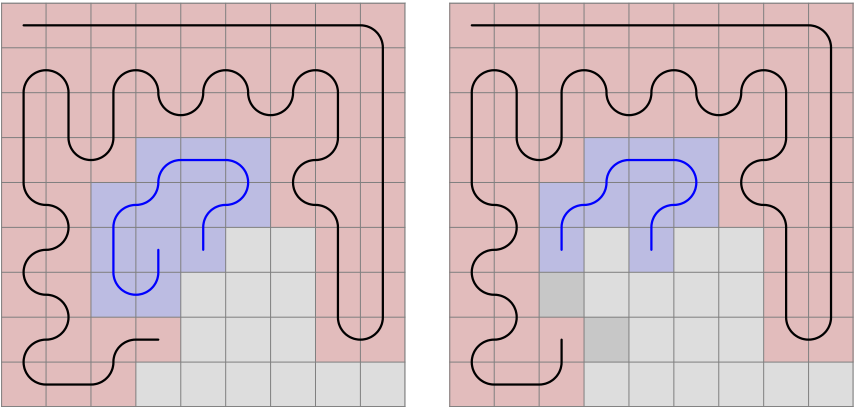
We can recreate this example on 13 x 13.



From our experience, the area can be substituted with C-shape.



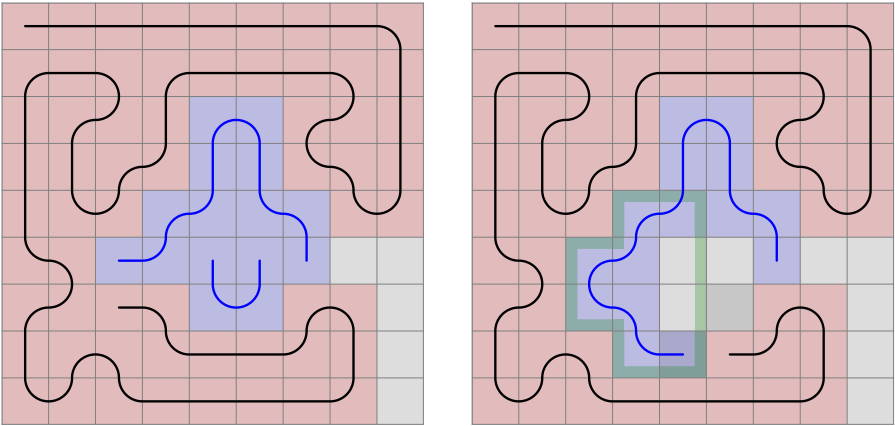
3 225 432 is a variation of the impair area imbalance rules we have seen before.



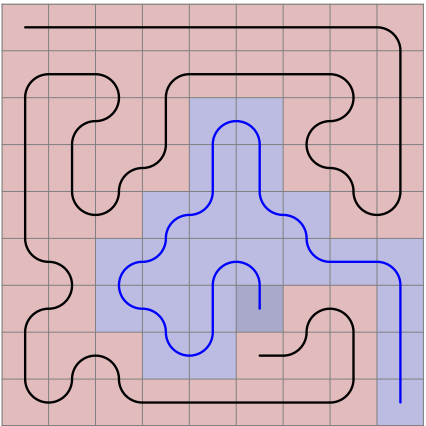
		←
	↗	
	↘	
+		×
	+	—

		←
	→	
	+	
	→	×

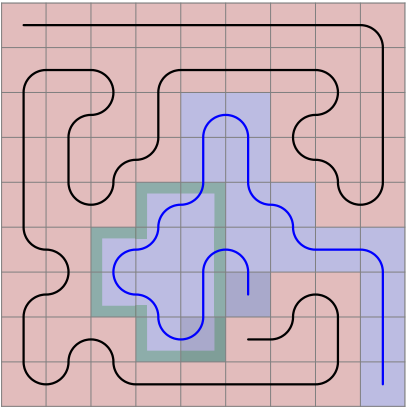
At 19 717 655 the program stops.



Obviously, we cannot step straight, but had we extended the future line until the end corner, the situation would not have occurred and we would have just got this:

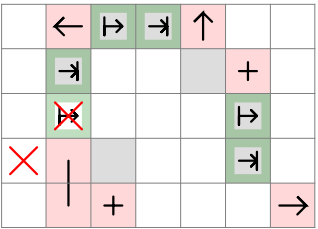


Though the algorithm including the reliance on the future lines is just as solvable, we miss patterns and therefore narrow the spectrum of the discoverable rules. We would eventually discover the patterns as we increase the table, but why not gain the most out of the 9 x 9 study? From now on, future lines are treated as a visible aid, but they do not play a role in deciding which fields are available for the next move. When a possible field is within the body of a future line, the program should stop.

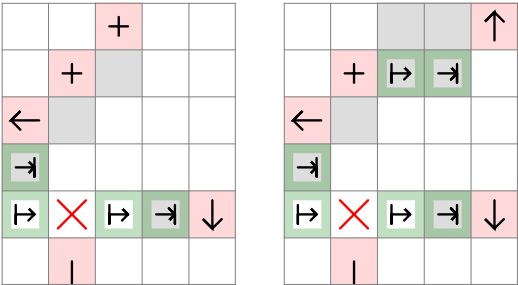
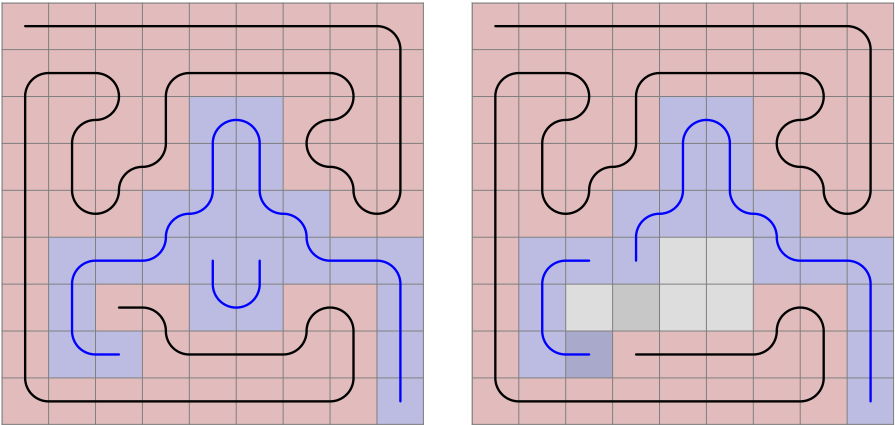


It is not the only thing. So far, when we entered a future line, the program just followed it without checking the possibilities for the next step. This behaviour needs to be changed too. Future lines are no longer needed, and we should restart the 9 x 9 walkthroughs.

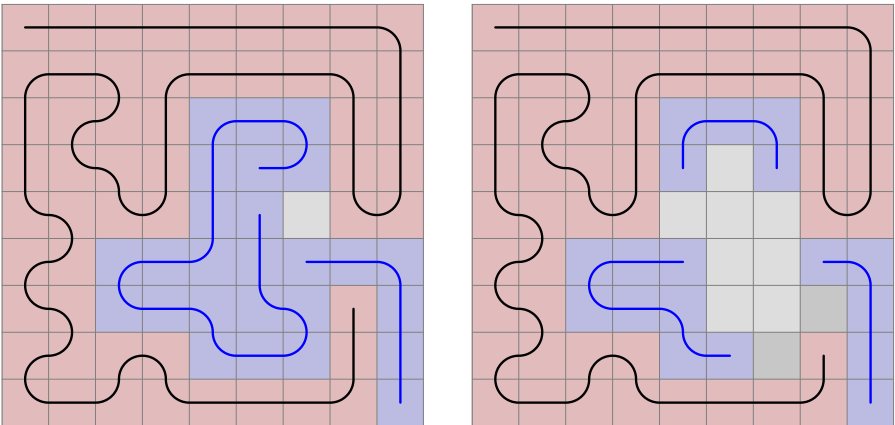
For now, here is the solution to this and the next cases:



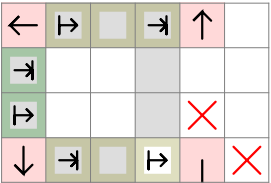
19 718 148 is a slight modification of 2 022 773 where there is an area instead of a C-shape straight ahead.



We encounter a new constellation of 3 areas in 23 310 321 where the exit is next to the live end.



The two empty fields in the middle will not be filled if the don't enter the impair area now.

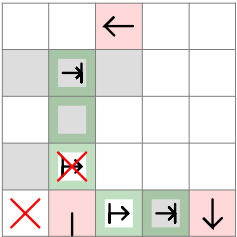
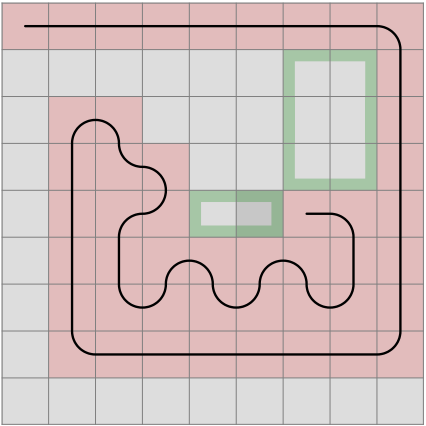


When restarting the run with the new approach, we will find that some walkthroughs were missed previously. The 10 000 th path is slightly younger than before. It is not because the future lines had been drawn incorrectly, but because the 7 x 7 rules that I used in the beginning were not precise for this size.

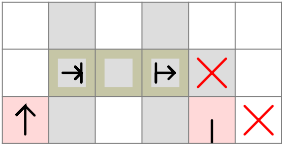
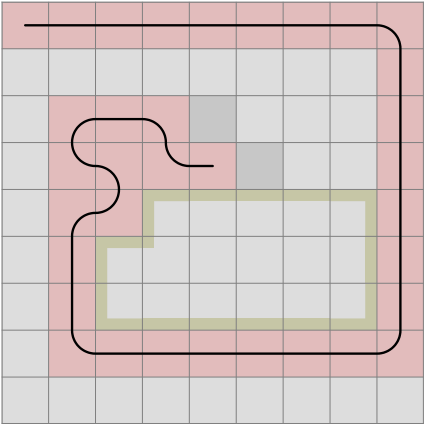
In the following section I list the 9 x 9 rules in chronological order. The patterns are not introduced when they are first recognized, but when they are first needed, meaning that they disable fields that the other rules don't. And the disabled fields have to be empty.

Still, the number of completed walkthroughs before the appereance of the rule may not be the same as the number of those before getting stuck in the lack of that rule. If the rule disables a field right to a possible field, the left branch would run through first.

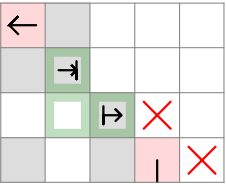
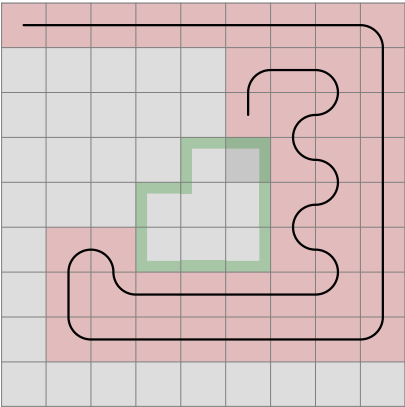
462, Double Area C-Shape



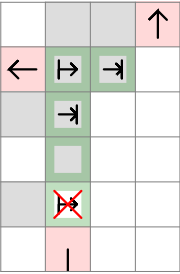
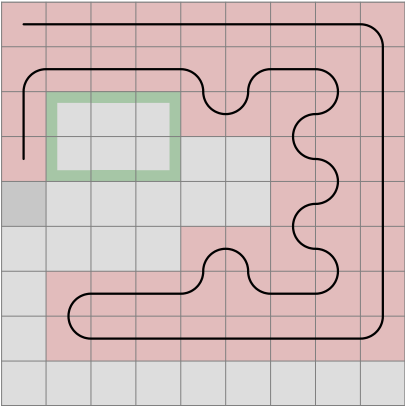
1 861, Double C-Shape

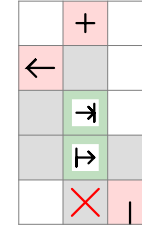


9 121, Count Area 2 Across

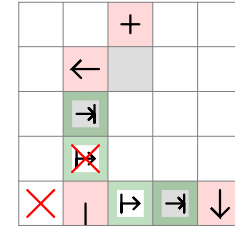


22 328, Straight Mid Across 3 End Area

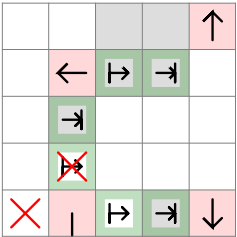
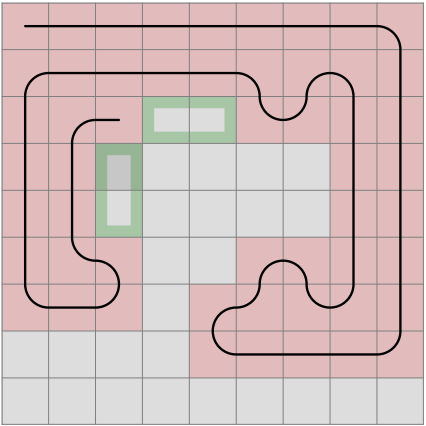


[illegible]

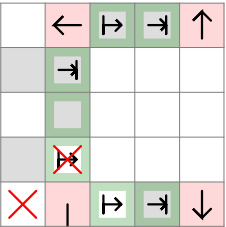
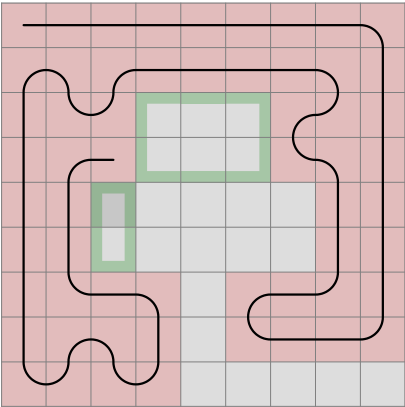
The diagram shows a 5x5 grid. A red path starts at the top-left corner (0,0), goes right to (4,0), then down to (4,4), then left to (0,4), and finally up to (0,0). This path encloses a 3x3 area in the center. Within this 3x3 area, a green path highlights a specific route: it starts at (1,1), goes right to (2,1), then down to (2,2), then left to (1,2), and finally up to (1,1). The cells (1,1), (2,1), (2,2), and (1,2) are highlighted with a green border. The cell (1,2) also contains a small grey rectangle.



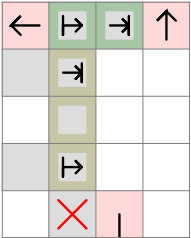
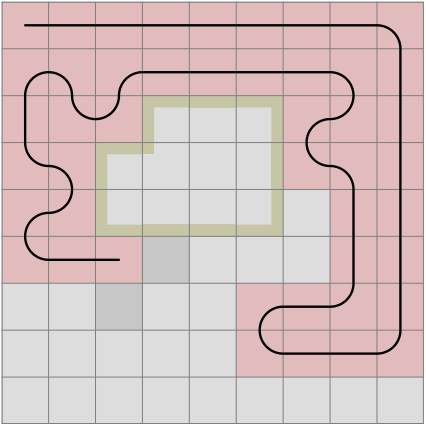
231 960, Square 4 x 2 Area



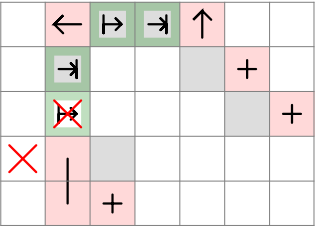
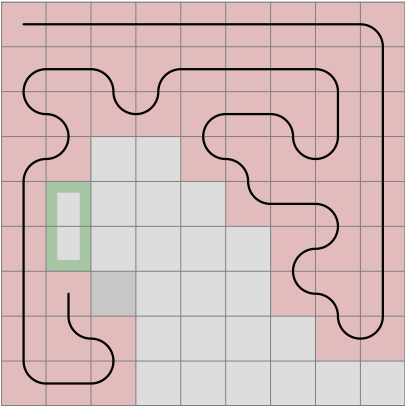
740 363, Triple Area



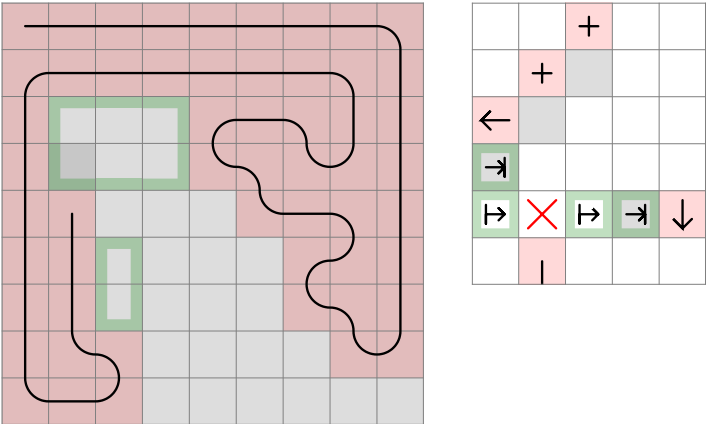
740 129, Straight Across 3 End Area



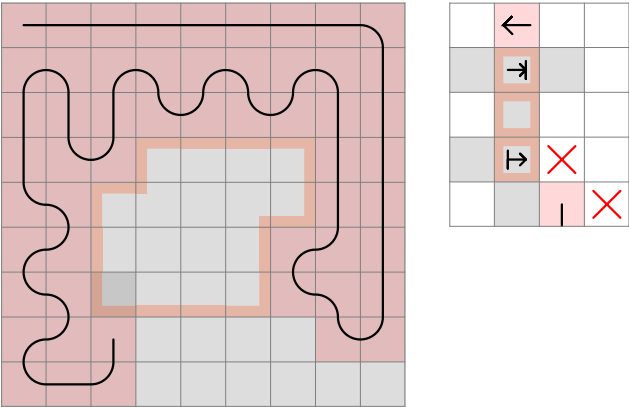
2 022 763, Double Area Stair



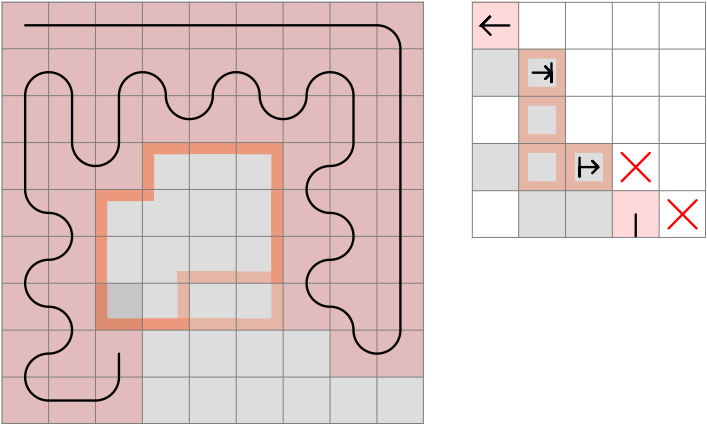
2 023 198, Double Area Stair 2



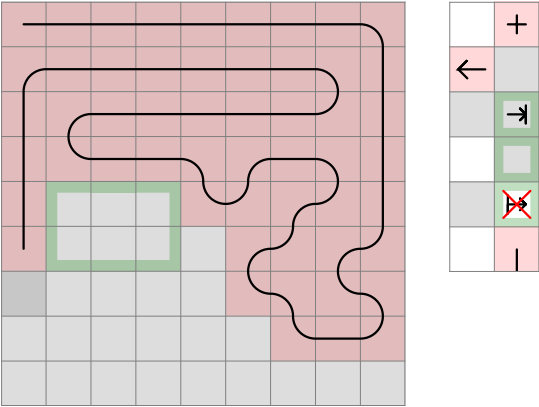
2 059 934, Mid Across 3 Impair Determined



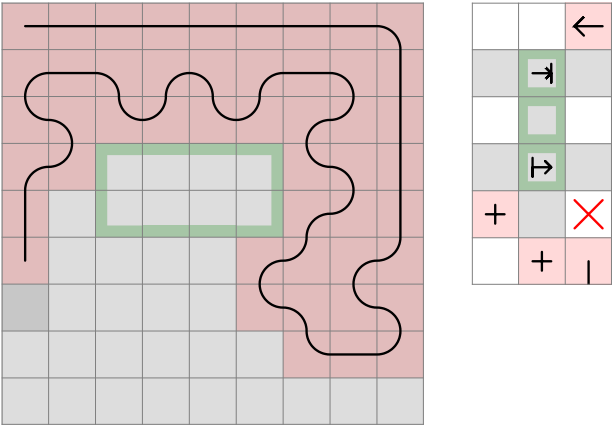
2 034 435, Mid Mid Across 3 Determined (and Mid Across 3 Impair Determined)



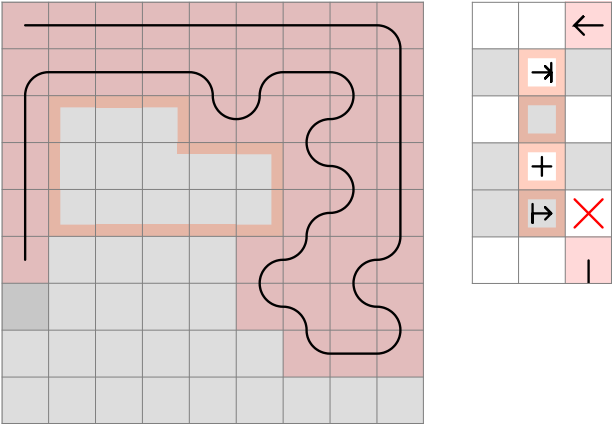
8 076 202, Straight Mid Across 3 End C



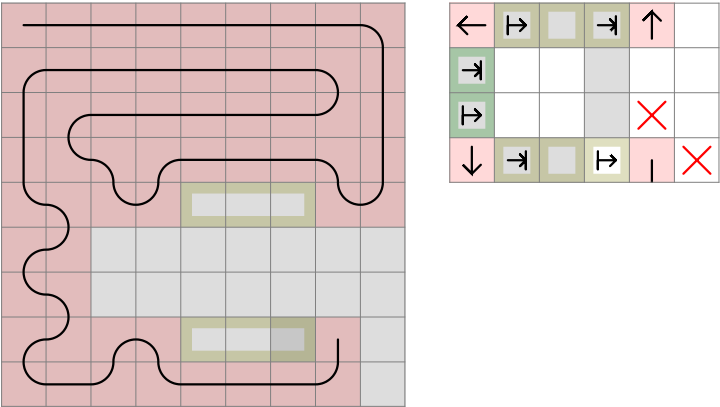
8 076 706, Double C-Shape Start C



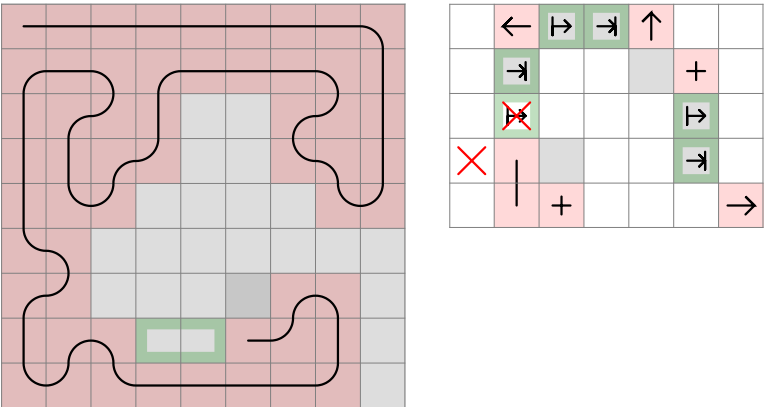
8 076 762, Double C-Shape Determined

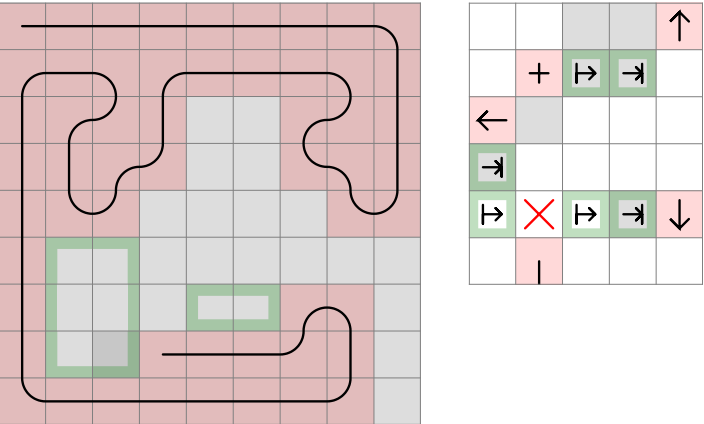


18 665 383, Triple Area Exit Down

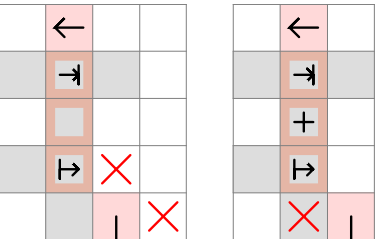
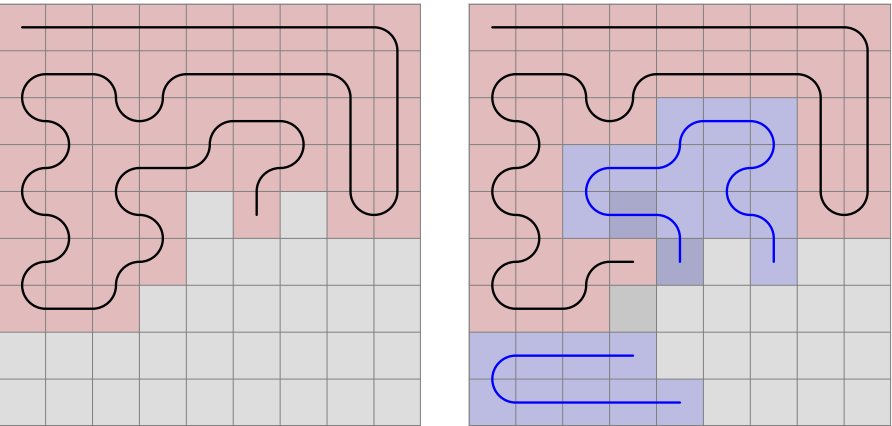


19 720 122, Triple Area Stair



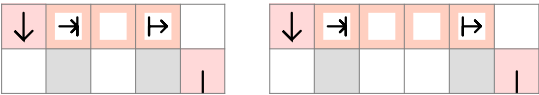


23 350 320 is new, but it shows similarity to the Mid Across 3 Impair Determined rule. As the double C-shape reveals, it is about pair/impair field imbalance.



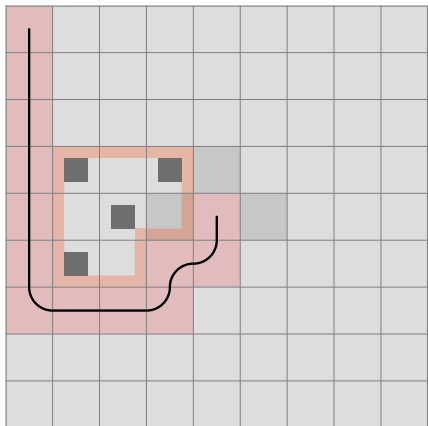
If we step left in the impair area, we can only exit at the count area middle field, but there is one less field of that type than the other.
And no fields can be omitted from the area for entry and exit later.
When the count area start field + middle field is omitted (subtracting a pair amount of cells from the area), the possible exit is the count area end field, which has a different parity than the field to the left.
When the count area middle + end field is omitted, the possible exit is the count area start field, which has again different parity.

By now, we are able to group some rules and even solve the original 21 x 21 example. Previously, we have covered all of the cases where an obstacle is 2 distance away from the live end. Let's examine distances of 3, 4 and so on in this constellation:

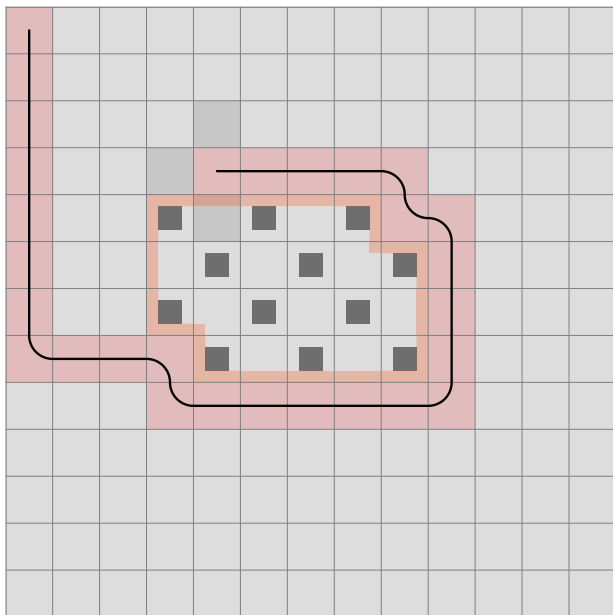


Besides the count area fields being empty, here I also assume that the left field and the field below the obstacle is also empty. In the future, this might have to be changed and new constellations added.
Knowing the difference between the number of pair and impair fields, we can make a decision in some cases.

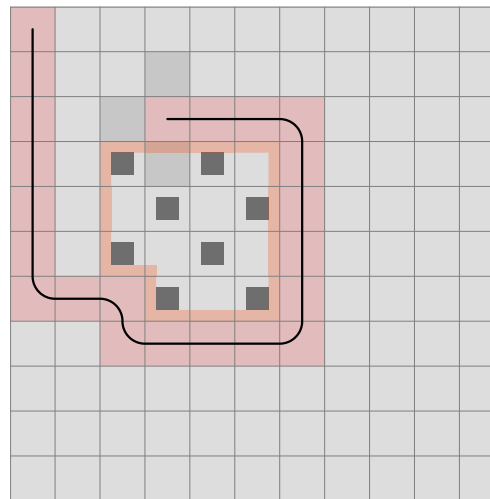
Let's start with this:



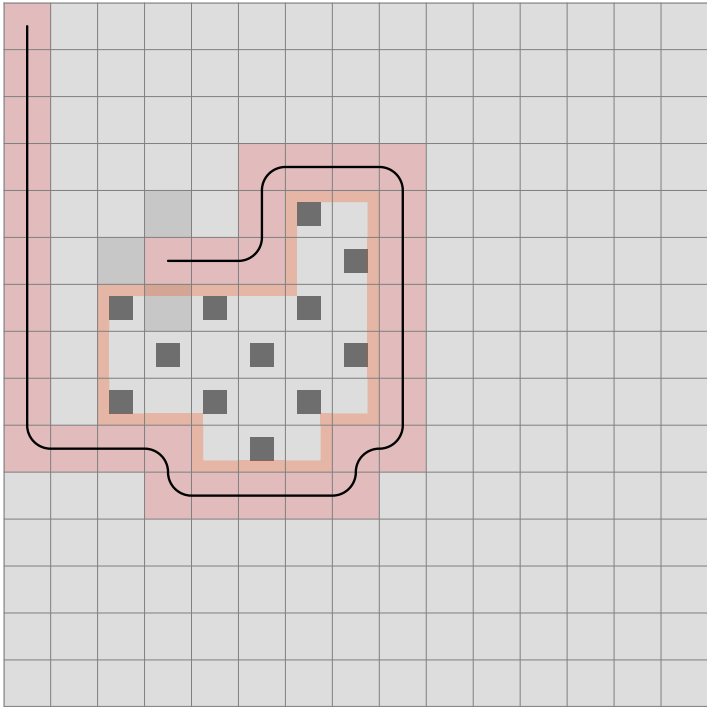
The distance is 3, the area is pair, and the number of pair and impair fields are the same. We can either enter the area now (stepping left) or later (up or right). Either way, we can start and end the area on a different color, so nothing should be disabled.



Here, the area is still pair, but there are 12 black fields and 10 white. To fill it, two lines of an impair length would be needed, each starting and finishing on a black field. Now, it is possible to enter and exit the black field in the upper left corner of the area, but we cannot do it with the field 2 below. And there are no more black fields on the boundary of the area. Filling it is therefore impossible.



When there are one more black field than white (8 and 7 in this case), the area is impair. If we enter now, we can exit at the count area end (to make a line of pair length), and the corner black can be filled later. We can also enter at the corner black later to exit at the count area end.



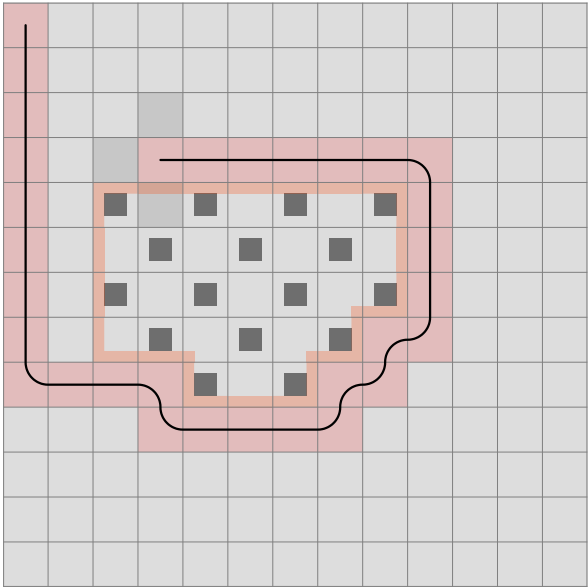
Here, there are one more white field than black. To fill the area, 1 line of impair length would be needed that starts and ends on white, but if the enter the area now, the corner black could not have been filled. Now there are 2 less black fields available for the rest of the area, but making two lines starting and ending on white is impossible, there are not that many white fields on the boundary.

Needless to say that we cannot enter later either, there is only one white field on the boundary.

If there are even fewer black fields relative to the white, the situation is the same.

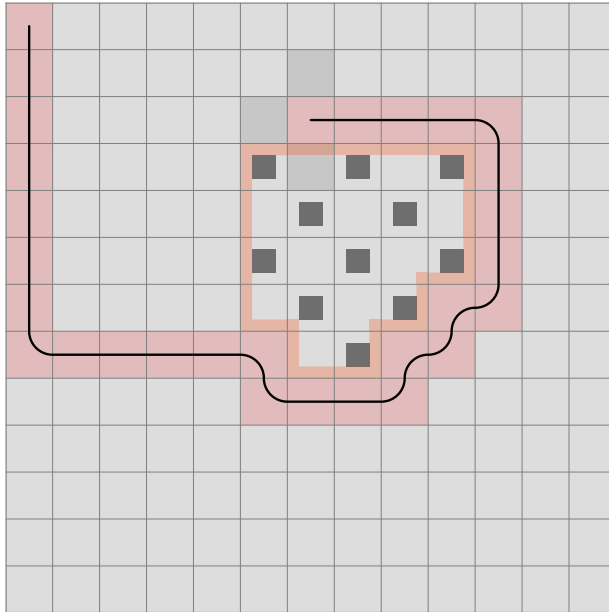
At 4 distance (and in any case), we still don't have a problem filling an area that has equal number of black and white fields.

When the number of black fields are two more than the whites (16 and 14):



Two black to black lines would be needed to fill the area. Apart from the black in the corner, there is only one black field on the boundary.

If $\text{black} = \text{white} + 1$:

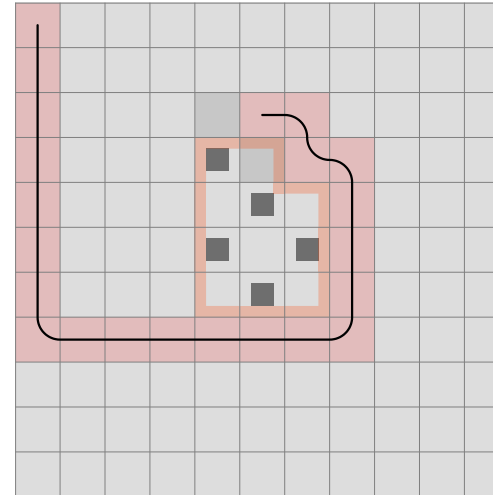


If we enter now by stepping left, there will have to be one more line even if we exit on black. That line has to go from black to black, so it can only be the corner field. Have we exited at the other black field (the third on the boundary), either the second or the fourth could not have been filled.

This direction therefore has to be disabled.

We can enter later without problems to start at the corner field, then the second, go inside the area and end at the third.

If $\text{black} = \text{white} - 1$:



A line that starts and ends on white can be drawn, no matter if we enter now or later. If we enter now, the next field has to be the corner black, and then there will be a line between the two white fields on the boundary.

The diagram illustrates a 3D convolution operation. It shows a 3D input volume of size 10x10x10 (light gray) with a 3x3x3 kernel (orange) applied to it. The resulting 3D output volume is 8x8x8 (pink). The diagram is overlaid on a grid.

Without finding concrete examples, at 5 distance I only draw the boundary and go through the different possibilities.



If we enter now and finish at black, only two black fields remain. Drawing two black to black lines is not possible, so this direction has to be disabled.

We can enter later, go through the corner and draw another black to black line.

There is not enough black fields for three black to black lines.

We can enter now, finish on a black field and draw another black to black line. Or enter later.

A white to white line is possible in either case.

We cannot enter now, because even if we end on a white field, only one white remains, and that is not the corner. And cannot enter later either.

The same procedure applies at 6 distance.



The number of black fields is the same as previously, so entering now is not possible.

black = white + 3 is impossible.

black = white + 1 and black = white - 1 is possible.

Entering now is possible if we step upwards and exit at the neighbouring white field. Two white fields remains.

But we cannot enter later and make two white to white lines using three white fields.

From now on, we can distinguish between four cases:

1) Pair distance, pair black and white (indicated by B and W): 4, 8, 12 etc. distance

If we enter now and exit on black, B-1 black field remains on the border. B-1 is impair, and the corner alone can make a black to black line. Hence $(B-2) / 2 + 1 = B / 2$ black to black line would be possible, but...

- if the first line finishes at the corner black, the opportunity for it to make a single line is lost, and the remaining B-1 black fields cannot make $B / 2$ black lines.
- if it finishes on any other black field, on one side there will be a section that has white fields on both ends (below the greenish fields were taken by the first line)



A black to black line cannot have three white fields on the border (unless more black fields were used up).

So there can be at most $B / 2 - 1$ black to black lines.

If we enter now and exit on white, W-1 white fields remain, so $1 + (W-2) / 2 = W / 2$ white to white lines is possible.

If we enter later, the number of possible black to black lines is at most $B / 2$, and the white ones $W / 2$.

Our rule will look like this: If the number of black fields in the area is greater or equal than the number of white fields plus $B / 2$, we cannot enter now.

2) Pair distance, impair black and white: 6, 10 etc.

If we enter now and exit at black, $(B-1) / 2$ black to black lines can be drawn.

If we exit at white, $(W+1) / 2$ white to white lines can be drawn. (We have to move to the corner black and exit at the first white during the first line)

If we enter later, $(B+1) / 2$ and $(W-1) / 2$ black and white lines are possible, respectively.

The rule is double:

- If the number of black fields is greater or equal than the number of whites plus $(B+1) / 2$, we cannot enter now.
- If the number of white fields is greater or equal than the number of blacks plus $(W+1) / 2$, we have to enter now.

3) Impair distance, impair black and pair white: 5, 9 etc.

If we enter now and exit at black, $(B-1) / 2$ black lines are possible.

If we exit at white, $W/2$ white lines are possible.

If we enter later, the number of black lines can be up to $(B+1)/2$, the whites $W/2$

Single rule: When the difference is at least $(B+1)/2$, we cannot enter now.

4) Impair distance, pair black and impair white: 3, 7 etc.

If we enter now and exit at black, $B / 2$ black lines are possible.

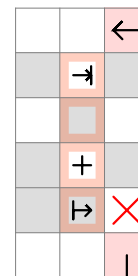
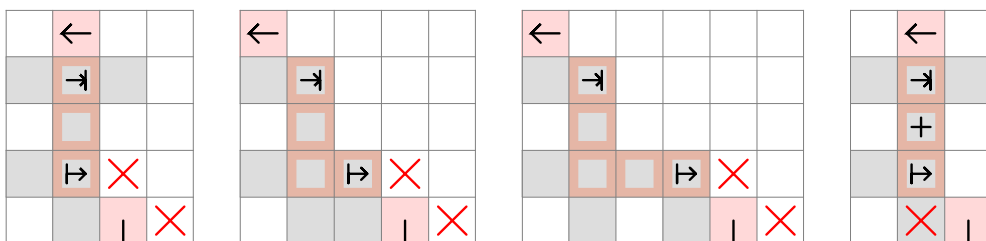
If we exit at white: Similarly to the first of the four cases, a black to black edge will remain on one side. Drawing $(W-1) / 2$ more white lines is either not possible, or if we do so, the corner black may make up a black to black line, decreasing the difference.



When entering later, $B / 2$ and $(W-1) / 2$ are the numbers. Since they match the above, no rule is applied.

Check the original 21 x 21 example. Two steps back, there will be 9 distance with the wall to the left. The number of black fields on the edge is 5, therefore there cannot be 3 more black fields in the area than white, but counting them, they are 51 and 48.

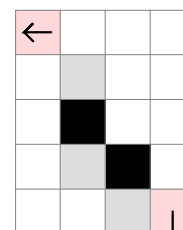
Does this procedure apply to any of the size-specific rules? Not exactly, but let's look them through. Here are all of them that deal with black and white field imbalance:



As a reminder, they indicate impair areas, and in the first two case if the count area start field (black) type is not 1 field more in the area, we cannot enter later.

In the fourth, the field marked with + (white) is the type that needs to be 1 more than black, otherwise stepping forward is forbidden.

I will take the second rule under examination as it contains both a horizontal and vertical offset.



If we enter now:

- We can exit at the end white, so 1 white line is possible.
- We can exit at the black farthest away and then make a line using the black field closest. 1 black line is possible.

I will mark it like this: 1W -> 1B

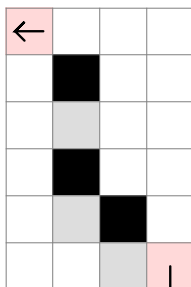
If we enter later:

- Having two black fields, 1 black line is possible.
- There is only one white field. It sits in a corner, but the two black fields will give 1 black line. 0 white line is possible.

0W -> 1B

So if there are 1 more white fields in the area than black (1W), we cannot enter later.

Now let's increase the vertical distance.



If we enter now, 1 white line to 2 black lines are possible. There are 2 black fields on a corner.

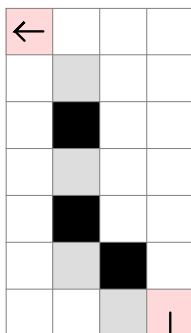
1W -> 2B

Later, 0 white line and 2 black lines can be drawn.

0W -> 2B

Conclusion: in case of 1W, we cannot enter later.

5 distance:



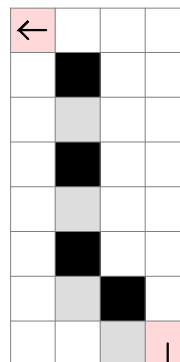
Now: 2W -> 1B

Later: 1W -> 2B

2W: cannot enter later

2B: cannot enter now

6 distance:

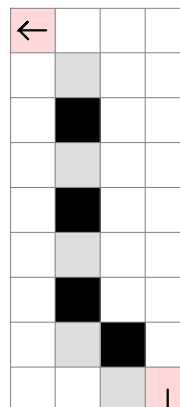


Now: 1W -> 2B

Later: 1W -> 3B

3B: cannot enter now

7 distance:



Now: 2W -> 2B

Later: 2W -> 2B

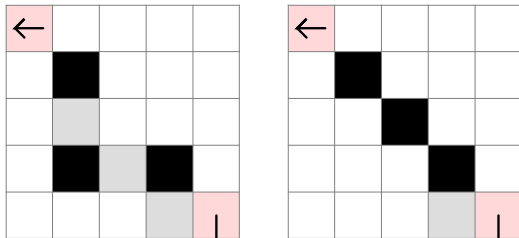
No rule.

In case of 7, there are 4 fields added to the 3-distance example. We would expect that in case of 2W, we cannot enter later, but now, 2W is possible even when entering later, because one line will be the corner white, and the other can go between the other two white fields, taking up all the blacks along the way.

From now on, increasing the numbers by 1 for every 4 distance increase will work.

The next thing to do is the horizontal increase.

3 distance:



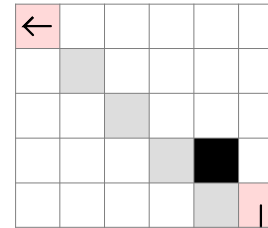
The picture on the left is the representation we have used so far. However, we cannot exit at the black in the middle, and when we exit at one of the whites, the other is only accessible for immediate entry. Therefore, I will add the extra field. If there is a taken field anywhere ahead acting as the obstacle, we can get to it by drawing a straight line and a stair.

Now: 0W -> 2B

Later: 1B -> 2B

If we used all 3 black corners for a separate line, we would not enter the area.

4 distance:

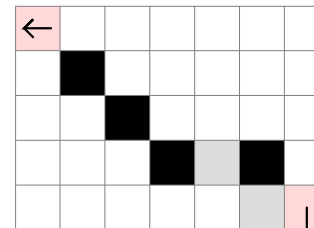


Now: 2W -> 0B

If we exited at the nearest white after entering, we have either not entered the area or not filled the black field.

Later: 2W -> 0B

5 distance:

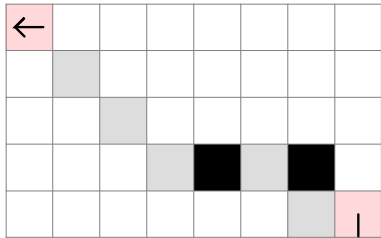


Now: 0W -> 3B

If we reserved the 3 black corners, the only way to end the first line on black is to move downwards after entry.

Later: 0W -> 3B

6 distance:

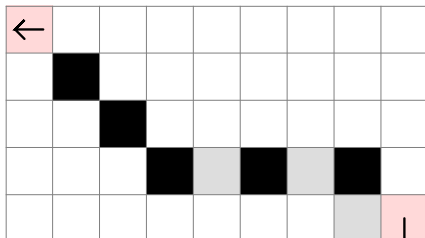


Now: 3W -> 1B

Similarly, we need to move down after entry in order to finish at the second black field, leaving the first for itself.

Later: 3W -> 1B

7 distance:



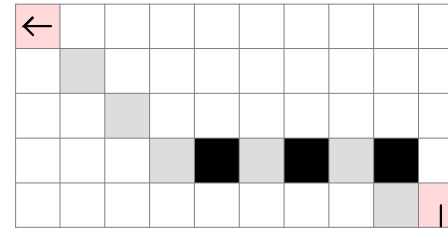
Now: 1W -> 3B

Later: 0W -> 4B

There cannot be one white line, because out of the first three black fields only 2 would be filled.

Notice that as we added 4 distance to 3, now both the white and the black end of the ranges have increased by one.

But we are not finished, we still need to examine the distance of 8.



Now: 4W -> 1B

After entry, we need to move up to fill the corner black and exit at the first white field.

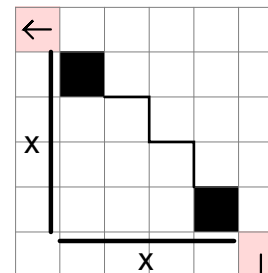
At 4 distance, only 2W was possible, but now we can exit at the first white and fill the area when entering at the second and exiting at the third.

Later: 3W -> 1B

After this practice, let's calculate how many white and black lines we can draw when we have an obstacle x and y distance away.

There are three cases to look at.

1. Equal horizontal and vertical distance



There are an x number of black fields on the area boundary.

$x = 1$:
 Now: $0W \rightarrow 0B$
 We cannot enter later.

$x = 2$:
 Now: $0W \rightarrow 1B$
 Later: $1B$

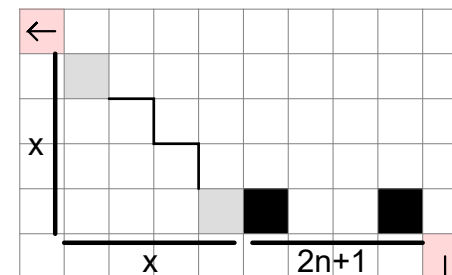
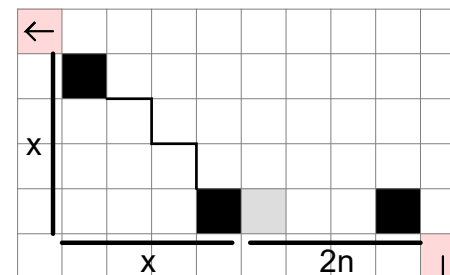
$x = 3$:
 Now: $0W \rightarrow 2B$
 Later: $1B \rightarrow 2B$

$x = 4$:
 Now: $0W \rightarrow 3B$
 Later: $1B \rightarrow 3B$

$x = n$:
 Now: $0W \rightarrow (n-1)B$
 Later: $1B \rightarrow (n-1)B$
 There is an x amount of corner blacks, but we need to enter the area as well.

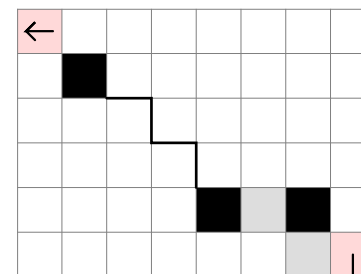
Conclusion: if the white and black fields in the area are equal, we cannot enter later.

2. Larger horizontal distance



If the added distance is pair:

$2n = 2$:



Now: Can we make $1W$? No, because that would require going through the first black field to end at the first white, while filling the other parts of the area too.

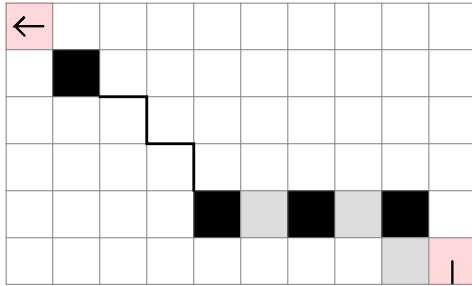
What about the black line count? Without the horizontal addition, $(x-1)B$ was possible. Can we now make x amount? Yes, by stepping down and ending the line at the first white field and the second black, having filled everything except the corner blacks.

$0W \rightarrow xB$

Later: We can use all corner blacks, and the line starting at the first white and ending at the second black will fill the area.

$0W \rightarrow xB$

$2n = 4$:



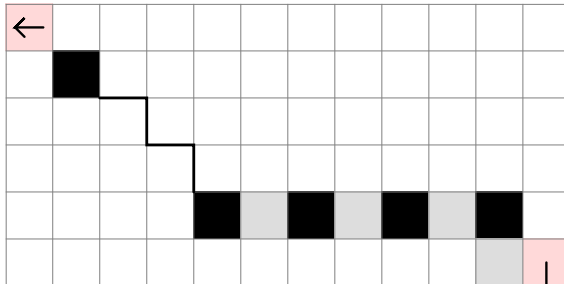
Now: 1W is now possible by ending at the second white, and everything can be filled on the way, while $(x+1)B$ is not possible. Two inline blacks remain after taking off all the corner blacks, and we have to use one of them to exit the first line.

$1W \rightarrow xB$

Later: $1W \rightarrow (x+1)B$

The line connecting the two inline blacks can fill the rest of the area.

$2n = 6$:



Now: If the first line goes through the first black and exits at the first white, the second line can go between the remaining two whites.

As far as the blacks concerned, if we exit at the second black, we can use the third and fourth for a line, plus the x amount of corners.

$2W \rightarrow (x+1)B$

Later: Because of three inline white fields, one white line is possible. For blacks, we can use all the corners and two out of the three inline blacks.
 $1W \rightarrow (x+1)B$

We don't need more examples.

For $2n$ added fields, there will be n amount of inline white fields.

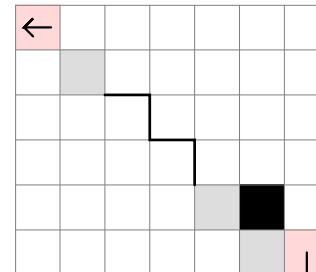
If we enter now, $(n+1 - (n+1) \% 2) / 2$ white lines can be drawn if $n > 1$. The black line count is all the corners minus one for finishing the first line, plus one for each remaining pair.

$x + (n-1 - (n-1) \% 2) / 2$

For entering later, the white line count is $(n - n \% 2) / 2$, and the black line count is $x + (n - n \% 2) / 2$.

If the added distance is impair:

$2n + 1 = 1, n = 0$:



Now: If we end the first line at the first white, we could not have filled the corner black and the area simultaneously. xW is therefore not possible, but $(x-1)W$ is.

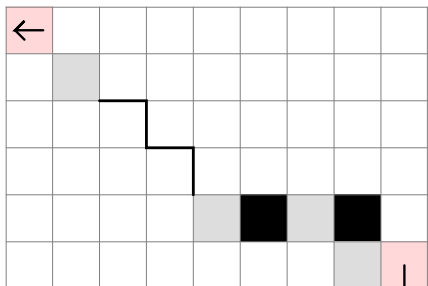
And since there is only one black field, the black line count will be 0.

$(x-1)W \rightarrow 0B$

Later: All the corner whites plus the neutral line makes $(x-1)W$. The black line count is still 0. The black field is a corner, but it will be counterbalanced by at least one white to white line.

$(x-1)W \rightarrow 0B$

$2n + 1 = 3, n = 1$:



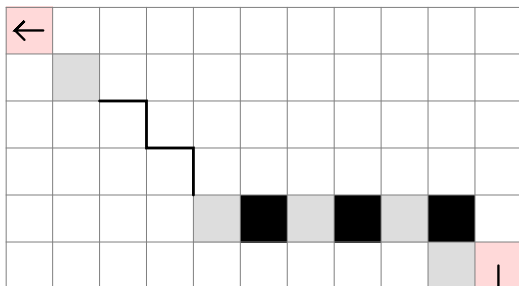
Now: Aside the corner whites, 1W is possible by ending at the second white, just like in the $2n = 4$ case.

The black line count is now 1, but we need to step downwards and finish at the first white and second black in order to have the corner black available.

$xW \rightarrow 1B$

Later: $xW \rightarrow 1B$

$2n + 1 = 5, n = 2$:



Now: We can step up and finish at the first white, because line connecting the remaining two whites can fill the area.

$(x+1)W \rightarrow 1B$

Later: $xW \rightarrow 2B$

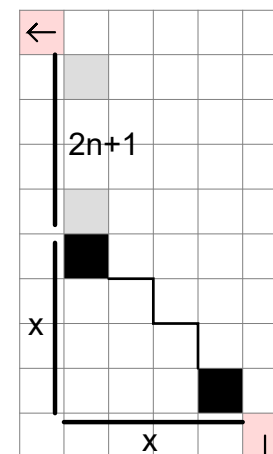
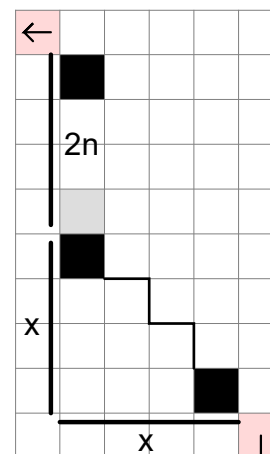
From now on, the calculations are the following:

If we enter now, $x + (n - n \% 2) / 2$ white lines can be drawn if $n > 0$.

The number of black fields is $n+1$, and when we use up one to finish the first line, n amount remains, one of which is a corner. Add one to make pairs, and the formula will be $(n+1 - (n+1) \% 2) / 2$.

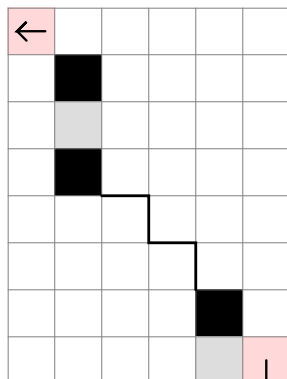
When entering later, the white line count is $x-1 + (n+1 - (n+1) \% 2) / 2$, and the black line count is $(n+2 - (n+2) \% 2) / 2$ if $n > 0$.

3. Larger vertical distance



If the added distance is pair:

$2n = 2$:



Now: It is possible to exit at the white field, having filled everything. The previous step must have been the last black.

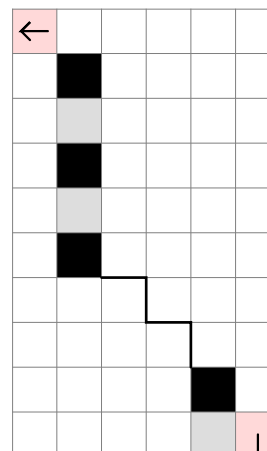
When counting the blacks, we exit the first line at the first black field above the stair, and x amount of corner blacks will remain.

$1W \rightarrow xB$

Later: Same as the $2n = 2$ case previously.

$0W \rightarrow xB$

$2n = 4$:



Now: There cannot be more than $1W$. And the black line count is unchanged too. One of the two inline blacks will be used for completing the first line, and one remains plus x amount of corner.

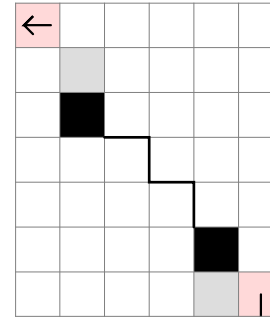
$1W \rightarrow xB$

Later: $1W \rightarrow (x+1)B$

A 10x10 grid with a black path. The path starts at (0,0) and ends at (9,9). The path is defined by the following cells: (0,0), (0,1), (0,2), (0,3), (0,4), (0,5), (1,5), (1,6), (2,6), (2,7), (3,7), (3,8), (4,8), (4,9). The cell (0,0) is red. The cell (9,9) is red. The cell (4,9) is gray. The cell (9,8) is gray. The cell (3,8) is black. The cell (2,7) is black. The cell (1,6) is black. The cell (0,5) is black. The cell (0,4) is black. The cell (0,3) is black. The cell (0,2) is black. The cell (0,1) is black. The cell (0,0) is red. The cell (9,9) is red. The cell (4,9) is gray. The cell (9,8) is gray. The cell (3,8) is black. The cell (2,7) is black. The cell (1,6) is black. The cell (0,5) is black. The cell (0,4) is black. The cell (0,3) is black. The cell (0,2) is black. The cell (0,1) is black. The cell (0,0) is red.

Later: $1W \rightarrow (x+1)B$

The later case is the same as previously, $(n - n \% 2) / 2$ for white and $x + (n - n \% 2) / 2$ for black.

$$2n + 1 = 1, n = 0:$$


Later: (see horizontal case) $0W \rightarrow (x-1)B$

Later: 1W -> xB

Now: The corner white always gives 1. Then make pairs with the remaining inline whites plus the white field we are stepping first.

$$1 + (n+1 - (n+1) \% 2) / 2$$

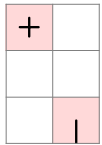
For the blacks, one of the inline black fields will be taken by the first line. We can then make pairs with the remaining inline blacks and add the corners.

$$x - 1 + (n - n \% 2) / 2.$$

Later: The white line count is $1 + (n - n \% 2) / 2$ if $n > 0$, and the black line count is $x - 1 + (n+1 - (n+1) \% 2) / 2$.

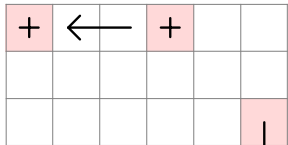
Next, we will look at the corner discovery algorithm.

Starting with 1 horizontal and 2 vertical distance, we check if that field is taken.



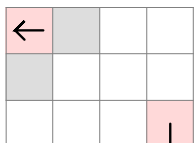
If so, we mirror sides and start the algorithm on the right side.

If not, we increase the horizontal distance by one until we find a taken field or run into the border.



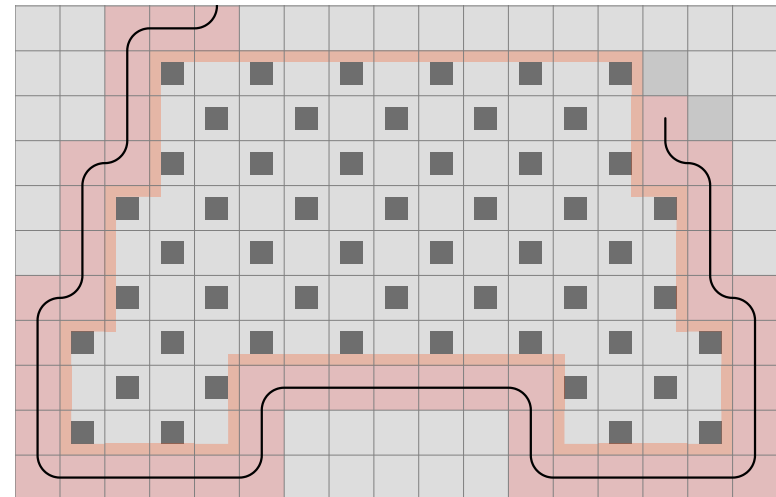
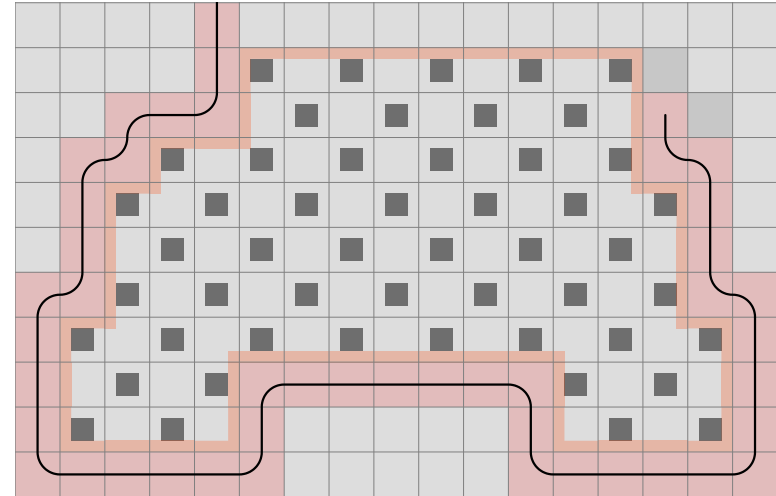
If it is a border field, we increase the vertical distance and start with 1 horizontal distance again.

Otherwise, we check if the bottom field is free, and by comparing the index of the corner field with the field above, we can determine if the line is going down and left, so the enclosed area is on the side we want.

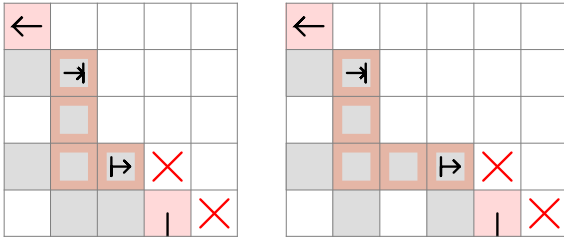


Now the area can be counted. And after this, we increase the vertical distance by one and stop / mirror sides when a field at one horizontal distance is taken or is the border.

Compare these two cases:



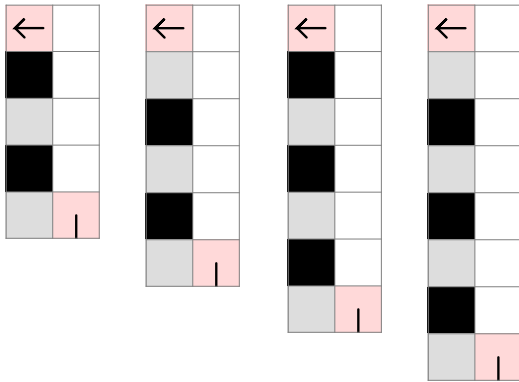
Having the universal algorithm, these two size-specific rules can be deleted:



The image displays a 2D grid representing a convolution operation. The grid is 10 units wide and 10 units high. A 5x5 kernel, represented by orange squares, is applied to the input. The output of the convolution is shown as a 5x5 grid of gray squares. The grid is surrounded by a red border, and a black line indicates the output area.

←	
↵	
→	
	↓

93 94



$D \text{ (distance)} \% 4 = 3$:

Now: $1W \rightarrow 0B$, $2W \rightarrow 1B$ etc. = $(D+1)/4 \text{ W} \rightarrow (D-3)/4 \text{ B}$

Later: $0W \rightarrow 1B$, $1W \rightarrow 2B$ etc. = $(D-3)/4 \text{ W} \rightarrow (D+1)/4 \text{ B}$
(double rule)

$D \% 4 = 0$:

Now: $1W \rightarrow 0B$, $2W \rightarrow 1B$ etc. = $D/4 \text{ W} \rightarrow D/4 - 1 \text{ B}$

Later: $1W \rightarrow 1B$, $2W \rightarrow 2B$ etc. = $D/4 \text{ W} \rightarrow D/4 \text{ B}$
(single rule)

$D \% 4 = 1$:

Now: $1W \rightarrow 1B$, $2W \rightarrow 2B$ etc. = $(D-1)/4 \text{ W} \rightarrow (D-1)/4 \text{ B}$

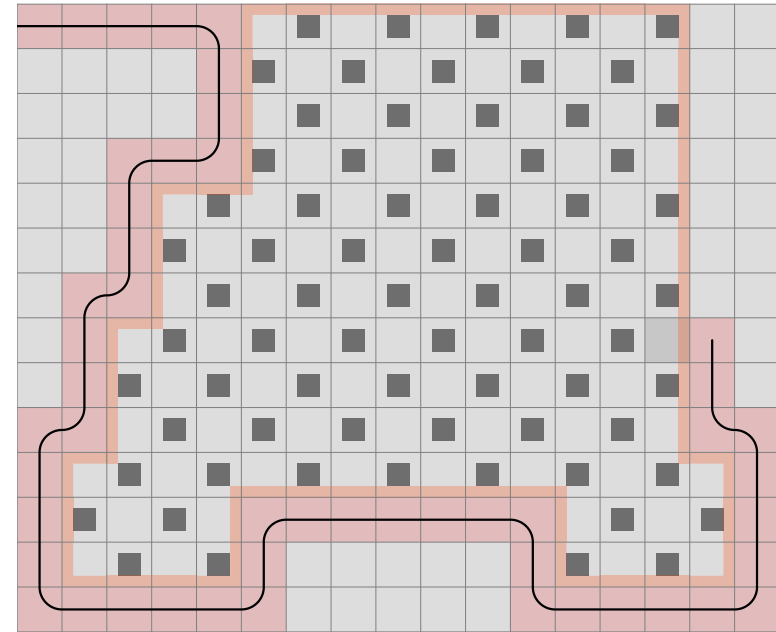
Later: $1W \rightarrow 1B$, $2W \rightarrow 2B$ etc. = $(D-1)/4 \text{ W} \rightarrow (D-1)/4 \text{ B}$
(no rule)

$D \% 4 = 2$:

Now: $2W \rightarrow 1B$, $3W \rightarrow 2B$ etc. = $(D+2)/4 \text{ W} \rightarrow (D-2)/4 \text{ B}$

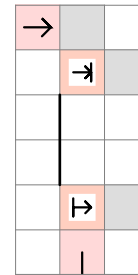
Later: $1W \rightarrow 1B$, $2W \rightarrow 2B$ etc. = $(D-2)/4 \text{ W} \rightarrow (D-2)/4 \text{ B}$
(single rule)

And as we step back, we find the point where the line should move in another direction.

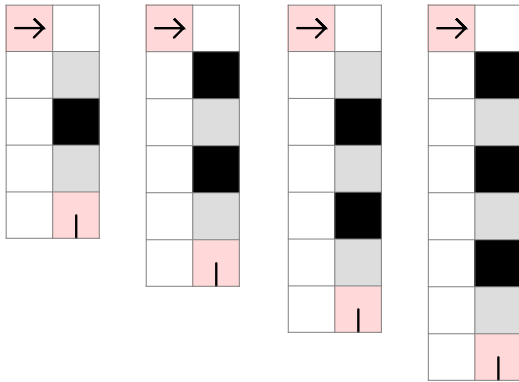


What this actually means is that there would be two fields of the same color that cannot be filled simultaneously.

An extension of the universal rule is necessary to include cases of a "big" area where the obstacle is on the other side of the live end.



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$D \% 4 = 3$:

Now: $1W \rightarrow 0B = (D+1)/4$ $W \rightarrow (D-3)/4$ B

Later: $1W \rightarrow 0B = (D+1)/4$ $W \rightarrow (D-3)/4$ B
(no rule)

$D \% 4 = 0$:

Now: $1W \rightarrow 0B = D/4$ $W \rightarrow D/4 - 1$ B

Later: $1W \rightarrow 1B = D/4$ $W \rightarrow D/4$ B
(single rule)

$D \% 4 = 1$:

Now: $2W \rightarrow 0B = (D+3)/4$ $W \rightarrow (D-5)/4$ B

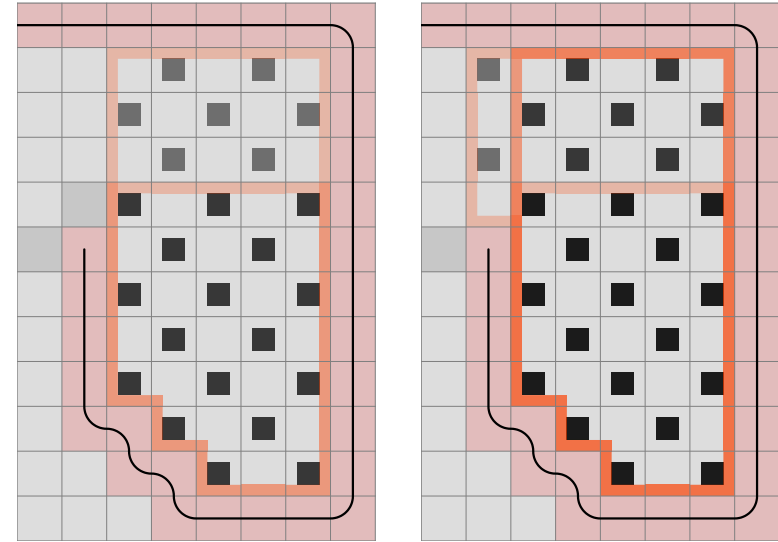
Later: $1W \rightarrow 1B = (D-1)/4$ $W \rightarrow (D-1)/4$ B
(double rule)

$D \% 4 = 2$:

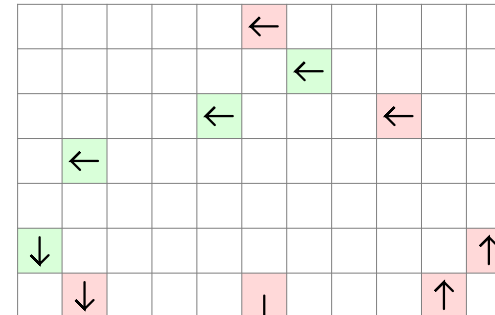
Now: $2W \rightarrow 1B = (D+2)/4$ $W \rightarrow (D-2)/4$ B

Later: $1W \rightarrow 1B = (D-2)/4$ $W \rightarrow (D-2)/4$ B
(single rule)

While this will not solve the case above (we are not able to step left), we can construct one where it is of use when the Double C-Shape Determined rule is turned off.



We can now continue working out all scenarios.



So far we have solved all cases indicated by green:

- 0 vertical distance small area
- x horizontal and y vertical distance small area
- 0 horizontal distance small area
- 0 horizontal distance big area

I will now take the case of x horizontal and y vertical distance big area.
 All representations are the same as in the small area case, only the area is on the other side.
 So I will just summarize the black and white limits here.

1. Equal horizontal and vertical distance

x = 2:

Now: 0W -> 1B

Later: 1B

x = 3:

Now: 0W -> 2B

Later: 1B -> 2B

x = n:

Now: 0W -> (n-1)B

Later: 1B -> (n-1)B

Exactly the same as with the small area.

2. Larger horizontal distance

If the added distance is pair:

$2n = 2$:

Now: 1W is possible. The entry field and the first white is at least 2 distance from each other, the whole area can be filled between them.

1W -> xB

Later: All corner blacks can be used. The line between the first black and first white will fill the area.

0W -> xB

General:

The only difference is the n = 1 case. Otherwise, the number of inline and corner fields are the same.

Now: $(n+1 - (n+1) \% 2) / 2$ W -> x + $(n-1 - (n-1) \% 2) / 2$ B

Later: $(n - n \% 2) / 2$ W -> x + $(n - n \% 2) / 2$ B

If the added distance is impair:

$2n + 1 = 1$, n = 0:

Now: xW is possible.

xW -> 0B

Later: Same values as previously.

$(x-1)W$ -> 0B

$2n + 1 = 3$, n = 1:

Note that in the small area case, there were x-1 corner whites and 1 corner black. Now there are x amount of corner whites and 2 inline blacks insted of 1.

Now: xW -> 0B

Later: xW -> 1B

$2n + 1 = 5$, n = 2:

Now: $(x+1)W$ -> 1B

Later: $(x+1)W$ -> 1B

General:

Now: $x + (n+1 - (n+1) \% 2) / 2$ W -> $(n - n \% 2) / 2$ B

Later: $x + (n - n \% 2) / 2$ W if n > 0 -> $(n+1 - (n+1) \% 2) / 2$ B

3. Larger vertical distance

If the added distance is pair:

We will find it is the same as the small area.

$$2n = 2:$$

Now: $1W \rightarrow xB$

Later: $0W \rightarrow xB$

$$2n = 4:$$

Now: $1W \rightarrow xB$

Later: $1W \rightarrow (x+1)B$

General:

Now: $(n+1 - (n+1) \% 2) / 2 W \rightarrow x + (n-1 - (n-1) \% 2) / 2 B$

Later: $(n - n \% 2) / 2 W \rightarrow x + (n - n \% 2) / 2 B$

If the added distance is impair:

$$2n + 1 = 1, n = 0:$$

Now: $1W \rightarrow (x-1)B$

Later: $0W \rightarrow (x-1)B$

$$2n + 1 = 3, n = 1:$$

Here comes the change again, due to having one more corner black field and one less corner white field than in the small area case.

Now: $1W \rightarrow xB$

Later: $1W \rightarrow xB$

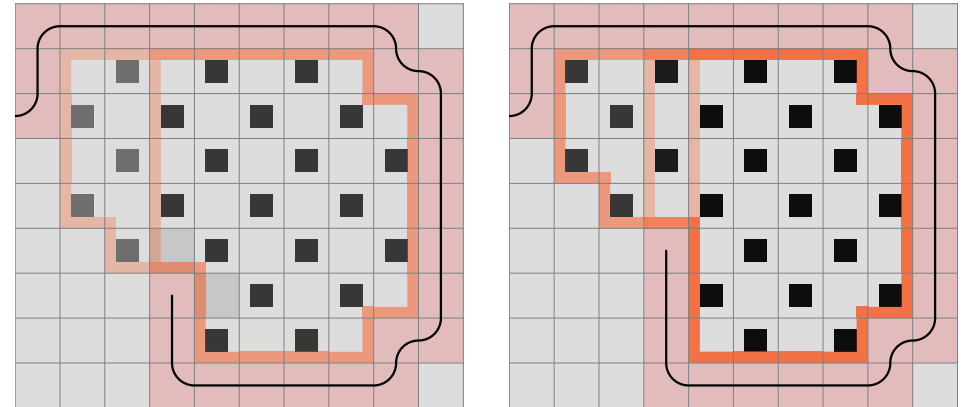
General:

Now: If $n > 0$, we can use all corner blacks after exiting the first line.

$(n+2 - (n+2) \% 2) / 2 W \rightarrow x + (n-1 - (n-1) \% 2) / 2 B$ if $n > 0$.

Later: $(n+1 - (n+1) \% 2) / 2 W \rightarrow x + (n - n \% 2) / 2 B$ if $n > 0$.

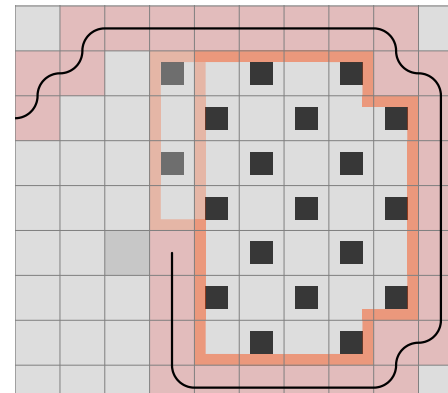
While creating a case to verify the newly created rule set, I have encountered this:



It is not possible to continue after stepping upwards.

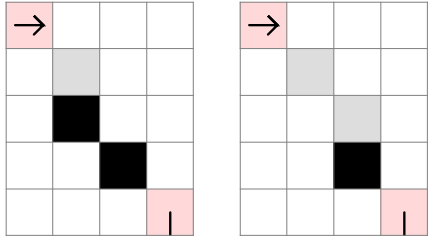
But where is the missing part?

On the left, the largest area contains 1 more white field than black, and on the right it is 2 more black. It would be possible if the upper left corner was filled, like this:



So it is not any of the small area rules and neither the 0 horizontal distance big area rule that has something to do with it.

One thing is sure, we have been using the small area representations when defining the rule set, which does not give us the minimal area in this case. See the difference:



Can it be a problem?

We will see, but let's look at one detail: If we step upwards, we have to step left to fill the corner white, otherwise it is only good for an exit, which we do not want if the area contains 1 more white fields than black (for the left representation).

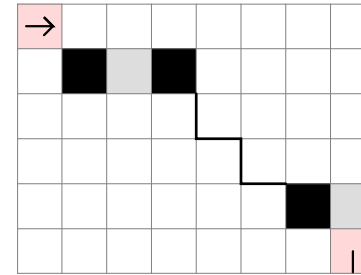
After this, we step upwards and then left again. We did not enter the area.

The 1 added distance case is therefore $0W \rightarrow (x-1)B$ when entering now by stepping upwards and $1W \rightarrow (x-1)B$ when stepping right.

To simplify things, I will specify the cases again using the minimal area representation.

Notice that these are the same as the small area patterns, things are just mirrored, so that the previous horizontal expansion is now vertical.

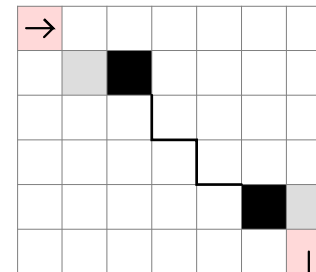
$n = 1$



Now: $(n+1 - (n+1) \% 2) / 2 W \rightarrow x + (n-1 - (n-1) \% 2) / 2 B$

Later: $(n - n \% 2) / 2 W \rightarrow x + (n - n \% 2) / 2 B$

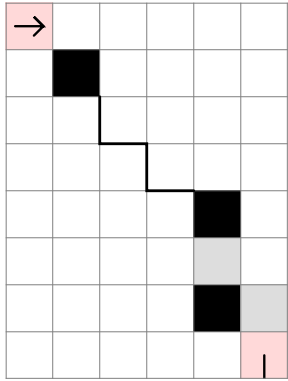
$n = 0$



Now: $1 + (n+1 - (n+1) \% 2) / 2 W \rightarrow x - 1 + (n - n \% 2) / 2 B$

Later: $1 + (n - n \% 2) / 2 W$ if $n > 0$ (0 if $n = 0$) $\rightarrow x - 1 + (n+1 - (n+1) \% 2) / 2 B$

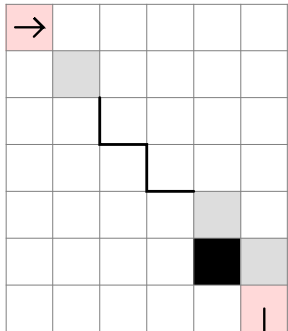
n = 1



Now: $(n+1 - (n+1) \% 2) / 2$ W if $n > 1$ (0 if $n = 1$) $\rightarrow x + (n-1 - (n-1) \% 2) / 2$ B

Later: $(n - n \% 2) / 2$ W $\rightarrow x + (n - n \% 2) / 2$ B

n = 0



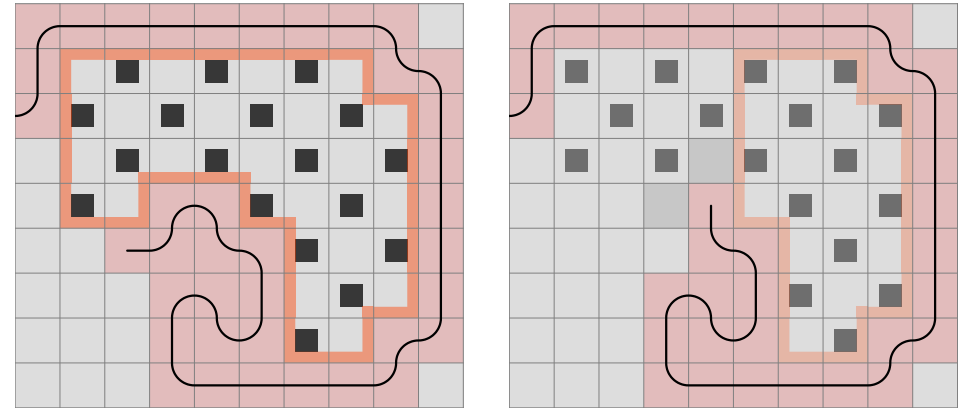
Now: $x - 1 + (n+2 - (n+2) \% 2) / 2$ W if $n > 0$ ($x - 1$ if $n = 0$) $\rightarrow (n+1 - (n+1) \% 2) / 2$ B

Later: $x - 1 + (n+1 - (n+1) \% 2) / 2$ W $\rightarrow (n+2 - (n+2) \% 2) / 2$ B if $n > 0$ (0 if $n = 0$)

The difference between stepping up and right still remains in these vertical expansion cases. We didn't have to deal with it at the small area, because the line could not step backwards.

It just means we have to remove the Now W conditions for stepping right.

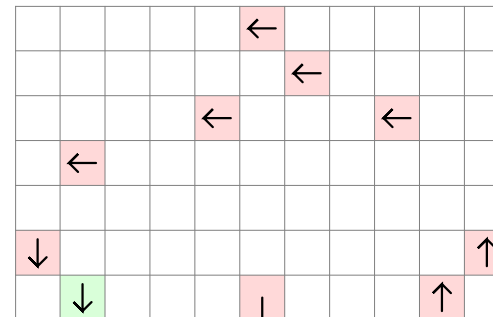
Now we can continue the case, but we will find that we cannot go past this point:



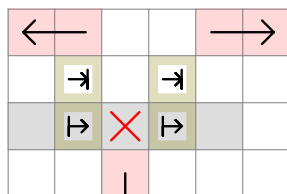
The picture on the right is the crossroad. If we step upwards, the area can be completed.

The area between the live end and the corner on the left contains one more black field than white, so the number could be made by stepping left and up, only we cannot step left because of the C-shape. In other words, when stepping left, the line will not be able to continue, but we need to change the programming algorithm in order to see it.

Now when there is a C-Shape, it is possible to step there, and no other rules will be checked. But C-Shape is just one of the nine cases of area checking.



Remember we have made rules previously that take both sides into account, like this:



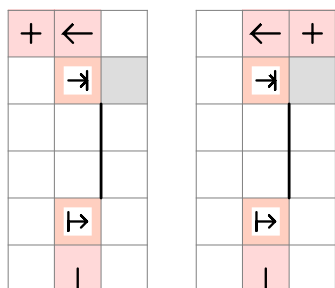
To combine all cases where after the next step, on the left side only the left field will be possible, and on the right, only the right, is not feasible.

Let's say instead that if one of the possible fields will lead to an impossible situation, we cannot step there. It still results in a usable algorithm.

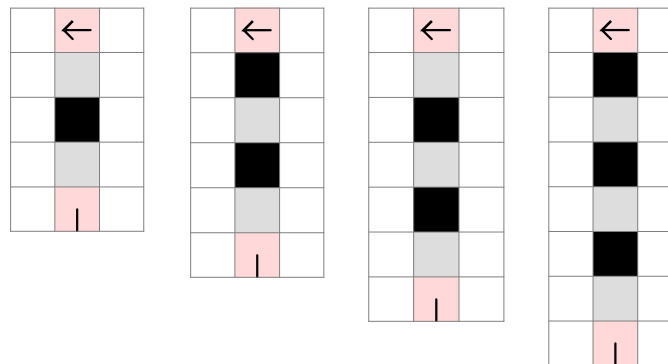
(An algorithm is usable if the number of operations are on the order of n^2 where n indicates the size of the table.

An unusable algorithm would require a number of operations on the order of 2^n or more: that is the random path where you just guess the next step until you get an impossible situation, but the crossroad might have been as far back as almost $n \times n$ steps.)

We are still missing the straight obstacle case:



Besides all the fields straight ahead, the gray field has to be empty in order to apply the rule.



Notice the area is the same as with the case where the obstacle is one field to the right, but there is a difference:

Look at the 3-distance case. Since the obstacle is straight ahead, if we enter now by stepping left, we cannot exit at the black field, because then one of the whites could not have been filled.

The area can only be filled if it is 1W. (This is the case we previously called Double C-Shape.) Adding 4 extra distance does not make the problem disappear: if we exit at the first black and the previous field was the first white, now we get the 5-distance case with 3 white fields and 2 black. A black to black line is therefore not possible.

These are the new values:

$$D \% 4 = 3:$$

$$\text{Now: } 1W \rightarrow -1B = (D+1)/4 \quad W \rightarrow (D-7)/4 \quad B$$

$$\text{Later: } 1W \rightarrow 0B = (D+1)/4 \quad W \rightarrow (D-3)/4 \quad B$$

(single rule)

$$D \% 4 = 5:$$

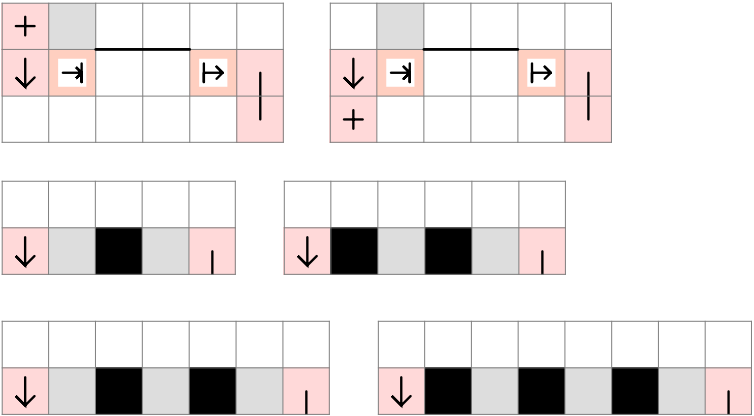
$$\text{Now: } 2W \rightarrow 0B = (D+3)/4 \quad W \rightarrow (D-5)/4 \quad B$$

$$\text{Later: } 1W \rightarrow 0B = (D-1)/4 \quad W \rightarrow (D-5)/4 \quad B$$

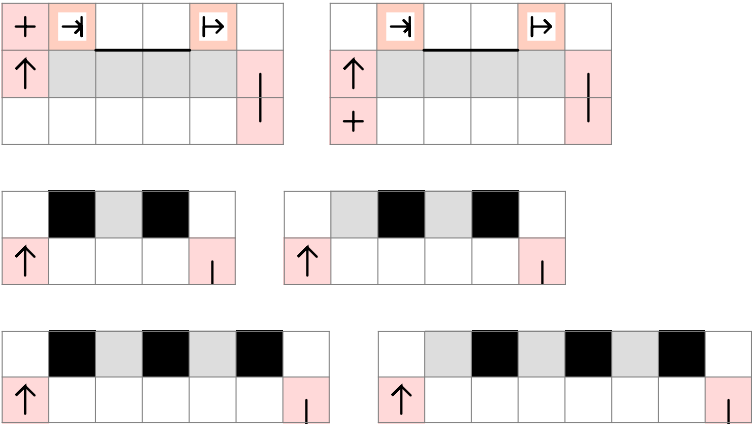
(single rule)

Also, pay attention to the 2-distance case. If we enter now by stepping left, 1W is possible. If we step straight, it is 0W. When the distance is 6, there is no difference, because if the step straight, we can exit the area immediately.

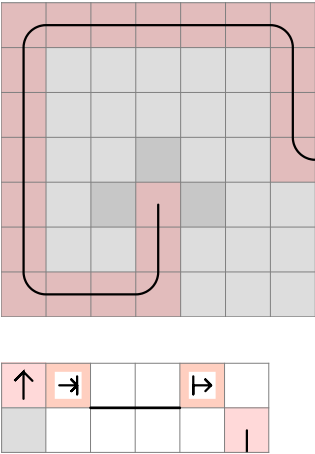
Side straight cases, small area:



Big area:

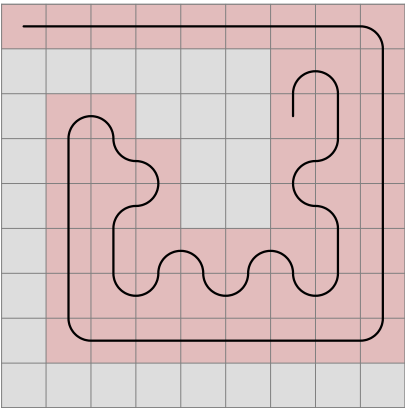


And here is an example of the x horizontal, 0 vertical distance big area corner. None of the existing cases cover it. The area is impair, so we shouldn't be able to step right.

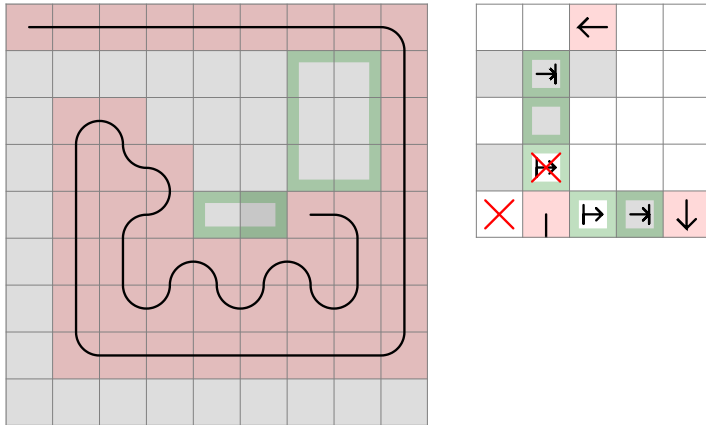


When we re-run the program on 9 x 9, it will be obvious that covering all the above 9 cases of area checking still does not solve everything.

If we don't apply the first size-specific rule, we get stuck here:



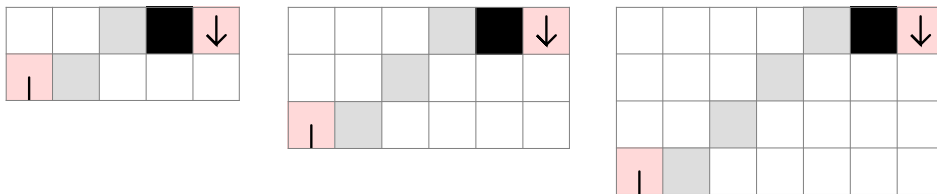
As a reminder:



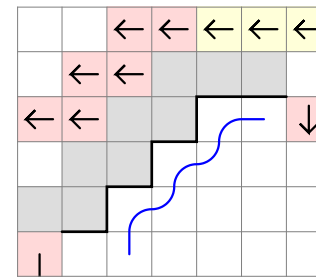
Let's put this into the perspective of our current knowledge.

What happens here is that the 3 x 2 area has a certain exit point, the middle, because the area is pair. Then it will create a C-Shape on one side and an area on the other side with a 1-wide gap.

In general, if we have an area of this shape,



that consists equal amount of black and white fields, and we enter now, we will exit at the black field, and the preceding field could only have been the farthest corner white, and we can continue backwards through all corner whites like this:

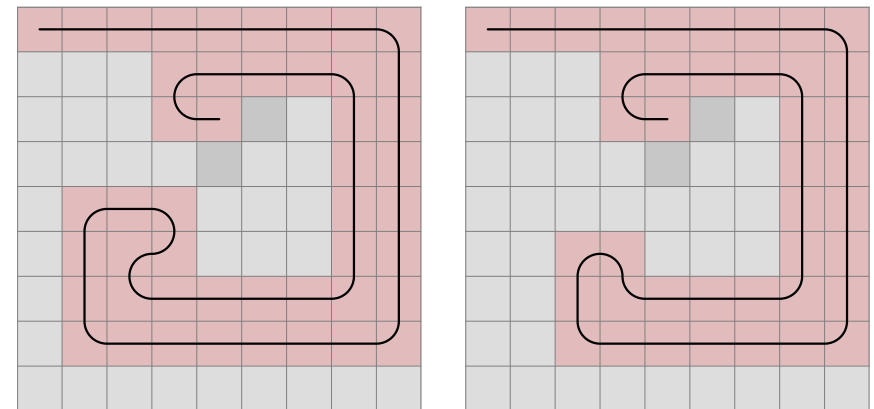


If an area is created with either of the fields marked with left arrow, it cannot be filled.

The gray fields must be empty in order to apply the rule, as well as the fields the blue line is crossing and the field right to the live end.

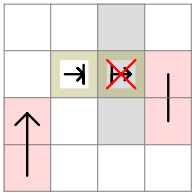
For now, I have only set the program to check the mid across and across cases, marked with pink background. To see if the yellow fields are necessary, we need to construct cases for them.

But let's continue the program. There are still single area cases we haven't thought about yet. (Previously we had rules for them, but not in the new system.)



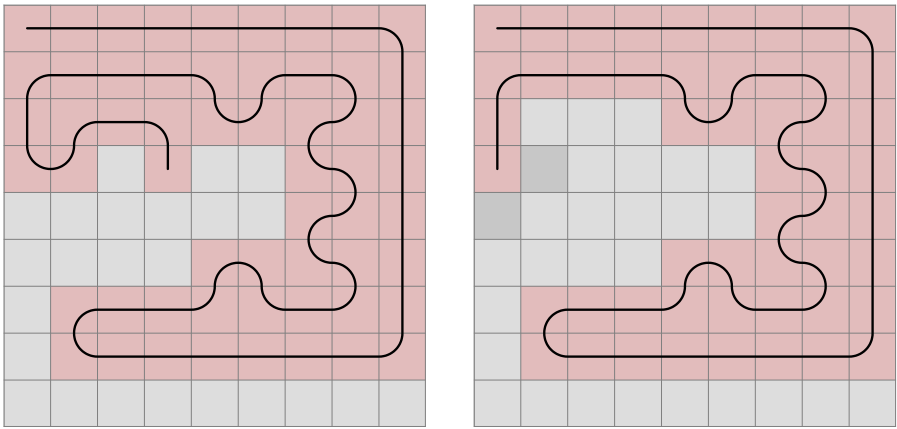
Obviously, at 1 distance we cannot step right, but neither can we at 2 distance if the area is impair. It is because stepping straight allows for 1W, while stepping right only 0W is possible.

Previously, we represented it like this:

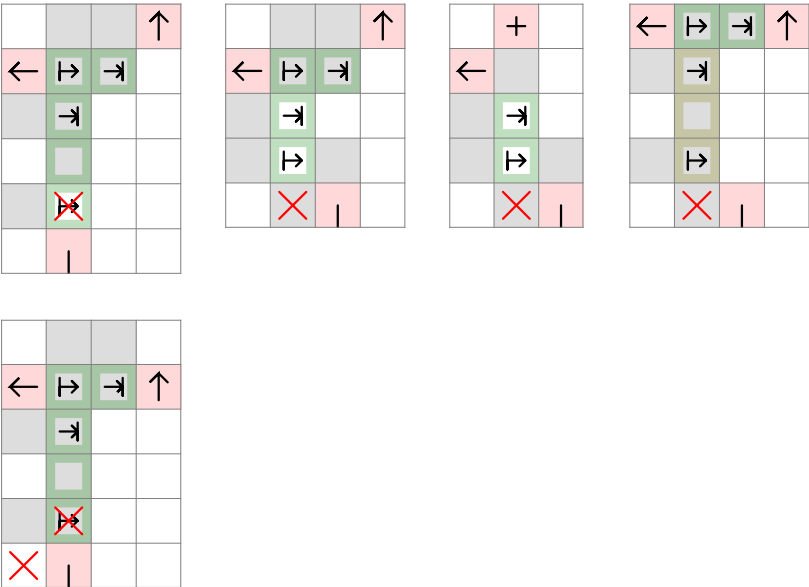


Reviewing those 2-distance rules, we can see that many of them has a double area (one of which is a C-shape). They cannot be solved with the single area patterns. It is best to re-enable the whole set even if it is a repetition in other cases.

Per our expectation, the program stops at the next double area case.

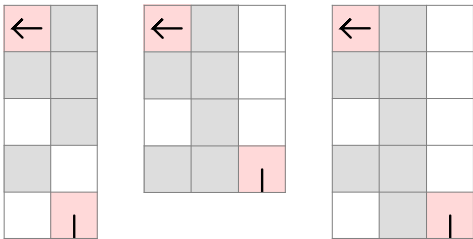


What is common in these rules?



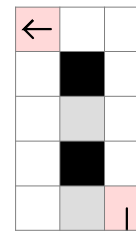
[illegible]

When checking the conditions for the first area, these are the fields that need to be empty:

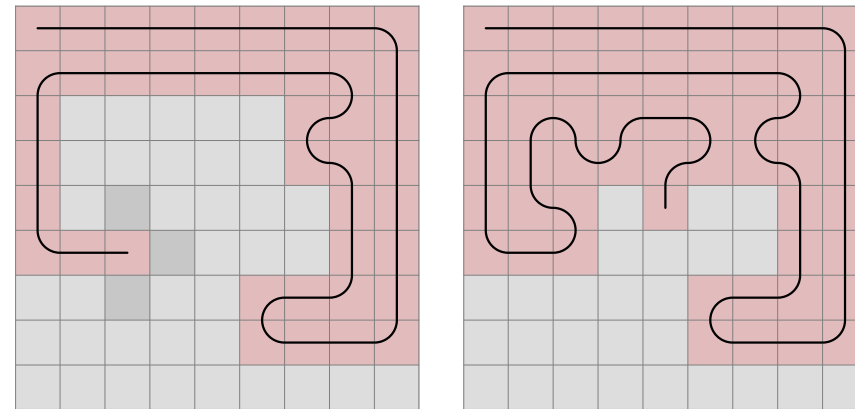


All three has to be applied rotated clockwise as well.

↓				↑



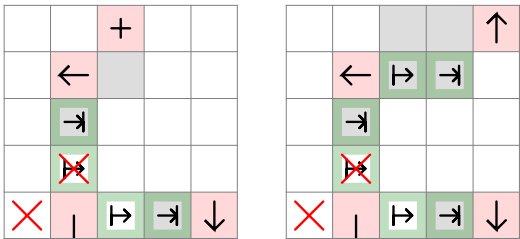
In the third case we assume that since the area is impair, the number of white fields are greater than of the blacks. But what if it is the opposite, and we get here?



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		↓	

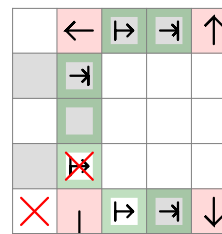
←	
	■
	■
	■
	■
	■

The next stop is similar in concept (Square 4 x 2 C-Shape and Square 4 x 2 Area): When we exit the first area, there are two close obstacles on either side:



A 10x10 grid with a black path and red-shaded cells. The path starts at (0,0), goes right to (9,0), then down to (9,9), then left to (0,9), and finally up to (0,0). The path has several loops and turns. Red-shaded cells are located at (0,0), (0,1), (0,2), (0,3), (0,4), (0,5), (0,6), (0,7), (0,8), (0,9), (1,0), (1,1), (1,2), (1,3), (1,4), (1,5), (1,6), (1,7), (1,8), (1,9), (2,0), (2,1), (2,2), (2,3), (2,4), (2,5), (2,6), (2,7), (2,8), (2,9), (3,0), (3,1), (3,2), (3,3), (3,4), (3,5), (3,6), (3,7), (3,8), (3,9), (4,0), (4,1), (4,2), (4,3), (4,4), (4,5), (4,6), (4,7), (4,8), (4,9), (5,0), (5,1), (5,2), (5,3), (5,4), (5,5), (5,6), (5,7), (5,8), (5,9), (6,0), (6,1), (6,2), (6,3), (6,4), (6,5), (6,6), (6,7), (6,8), (6,9), (7,0), (7,1), (7,2), (7,3), (7,4), (7,5), (7,6), (7,7), (7,8), (7,9), (8,0), (8,1), (8,2), (8,3), (8,4), (8,5), (8,6), (8,7), (8,8), (8,9), (9,0), (9,1), (9,2), (9,3), (9,4), (9,5), (9,6), (9,7), (9,8), (9,9).

But let's build the program step by step, based on the discovered 9 x 9 rules. The second case, Triple Area, uses an area where the obstacle is 3 distance away.



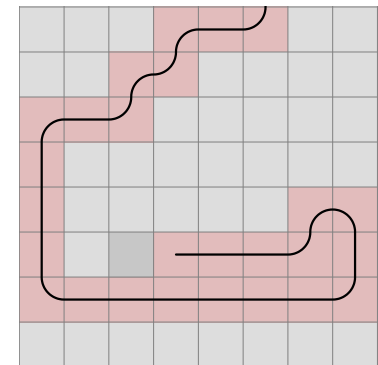
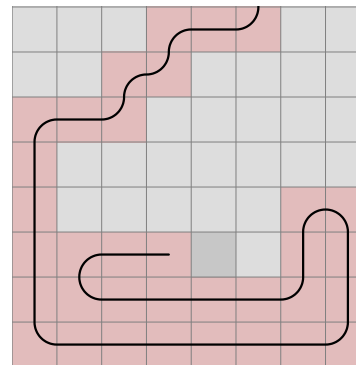
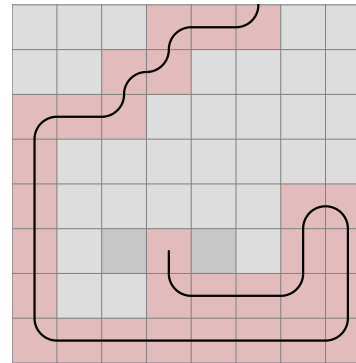
Stepping to the left is already disabled in the single area straight obstacle rule. Otherwise, the pattern is rotated, like in the previous case.

	←	↔	→	↑		
	→	A	B		+	
	↔			C		+
×						
		+				

We do not code the 4 steps in the program. We are writing a recursive function that calls itself until it runs into the double obstacle case. Notice, the start area is the same as in Square 4 x 2 C-Shape and Square 4 x 2 Area. So these are also solved by this algorithm.

		+		
	+			
←				
↖				
→	×	→	↗	↓
	—			

Accordingly, there will be 3 ways the rule is rotated.



The figure consists of two square grids, each divided into four quadrants by a horizontal and vertical axis. The top-left quadrant is light red, the top-right is light gray, the bottom-left is white, and the bottom-right is light blue. In both grids, there are black obstacles: a large L-shaped obstacle in the top-left, a smaller L-shaped obstacle in the bottom-left, and several small squares in the bottom-right. A path is shown in each grid, starting at point A (top-right), going left to point D (middle-left), then down to point C (bottom-left), and finally right to point B (bottom-center). The paths are composed of straight segments and smooth curves.

What is the simplest algorithm to apply?