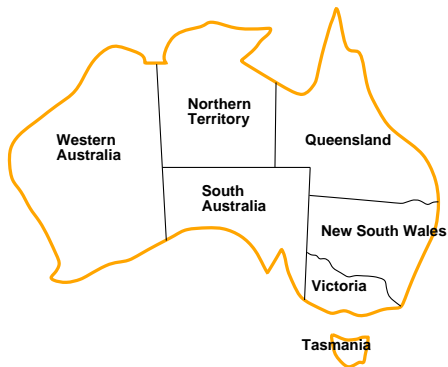
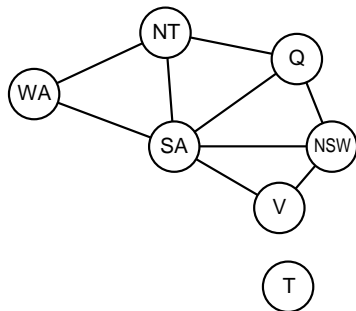


# Graph modeling

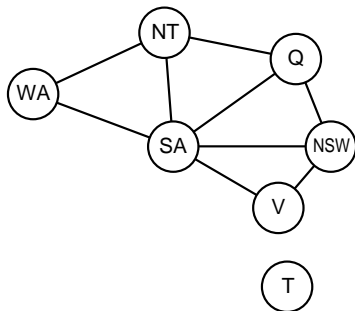
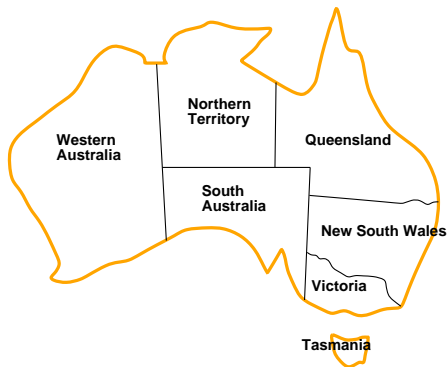


# Graph modeling



Russell & Norvig

# Graph modeling



Russell & Norvig

```
arc(wa,nt).    arc(nt,q).    arc(q,nsw).  
arc(wa,sa).    arc(nt,sa).    arc(sa,q).  
arc(sa,nsw).  arc(sa,v).    arc(v,nsw).  
arc2(X,Y) :- arc(X,Y) ; arc(Y,X).
```

## Non-termination (due to poor choices)

i :- p,q. [i]

i :- r.

p :- i.

r.

---

| ?- i.

prove([],\_).

prove([H|T],KB) :- member([H|B],KB), append(B,T,Next),  
prove(Next,KB).

| ?- prove([i],[[i,p,q],[i,r],[p,i],[r]]).

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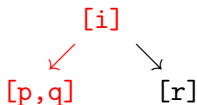
$i :- p, q.$

$i :- r.$

$p :- i.$

$r.$

$| \text{?- } i.$



$\text{prove}([], \_).$

$\text{prove}([H|T], KB) :- \text{member}([H|B], KB), \text{append}(B, T, \text{Next}),$   
 $\text{prove}(\text{Next}, KB).$

$| \text{?- } \text{prove}([i], [[i, p, q], [i, r], [p, i], [r]]).$

## Non-termination (due to poor choices)

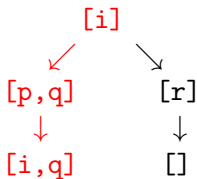
`i :- p,q.`

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`r.`

`| ?- i.`



`prove([],_).`

`prove([H|T],KB) :- member([H|B],KB), append(B,T,Next),  
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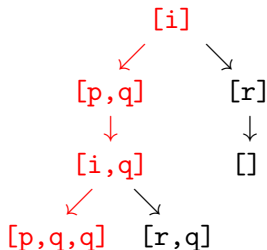
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`i :- r.`

`p :- i.`

`r.`

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`prove([],_).`

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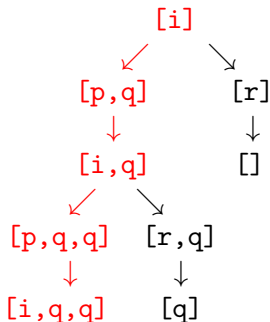
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`i :- r.`

`p :- i.`

`r.`

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`prove([],_).`

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## Non-termination (due to poor choices)

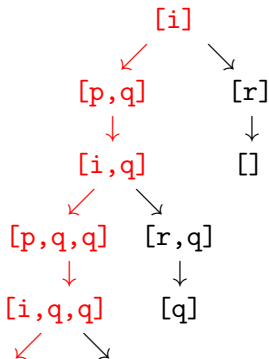
`i :- p,q.`

`i :- r.`

`p :- i.`

`r.`

`| ?- i.`



`prove([],_).`

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prove(Next,KB).`

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## Determinization (eliminate choice)

A fsm  $[Trans, Final, Q_0]$  such that

*for all  $[Q, X, Q_n]$  and  $[Q, X, Q_{n'}]$  in  $Trans$ ,  $Q_n = Q_{n'}$*

is a *deterministic finite automaton* (DFA).

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**Proof:** Subset (powerset) construction

```
arcD(NodeList, NextList) :-  
    setof(Next, arcLN(NodeList, Next), NextList).  
  
arcLN(NodeList, Next) :- member(Node, NodeList),  
    arc(Node, Next).
```

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goalD(NodeList) :- member(Node, NodeList), goal(Node).
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    arc(Node, Next).  
  
goalD(NodeList) :- member(Node, NodeList), goal(Node).  
  
searchD(NL) :- goalD(NL);  
    (arcD(NL, NL2), searchD(NL, NL2)).
```

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A fsm [Trans, Final, Q0] such that

*for all  $[Q, X, Q_n]$  and  $[Q, X, Q_{n'}]$  in Trans,  $Q_n = Q_{n'}$*

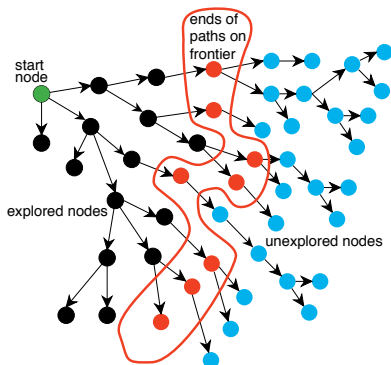
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arcD(NodeList, NextList) :-  
    setof(Next, arcLN(NodeList, Next), NextList).  
  
arcLN(NodeList, Next) :- member(Node, NodeList),  
    arc(Node, Next).  
  
goalD(NodeList) :- member(Node, NodeList), goal(Node).  
  
searchD(NL) :- goalD(NL);  
    (arcD(NL, NL2), searchD(NL, NL2)).  
  
search(Node) :- searchD([Node]).
```

# Frontier search

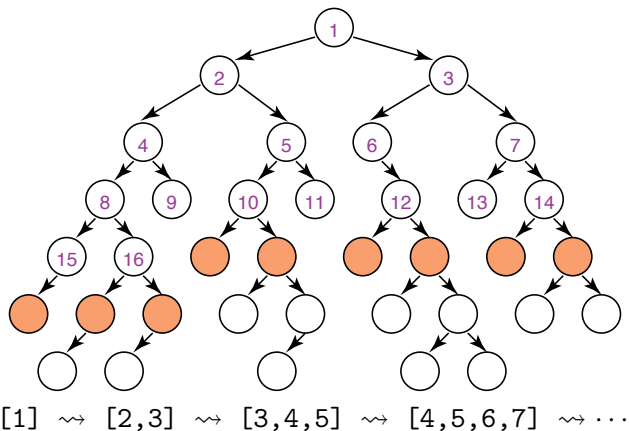


Poole & Mackworth

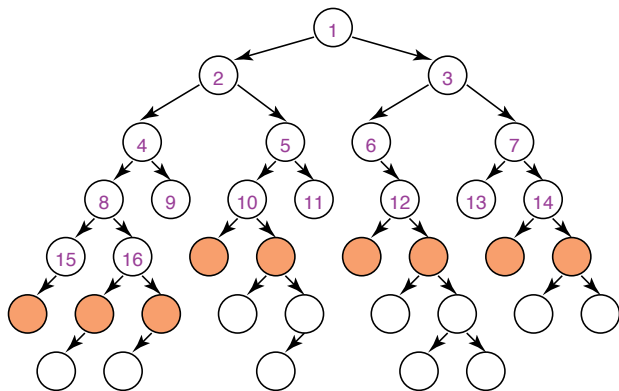
```
search(Node) :- frontierSearch([Node]).  
frontierSearch([Node|_]) :- goal(Node).  
frontierSearch([Node|Rest]) :-  
    findall(Next, arc(Node,Next), Children),  
    add2frontier(Children,Rest,NewFrontier),  
    frontierSearch(NewFrontier).
```



## Breadth-first: queue (FIFO)



## Breadth-first: queue (FIFO)

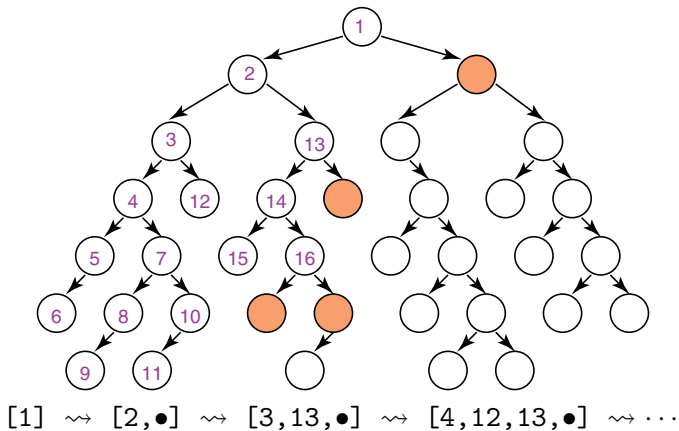


$[1] \rightsquigarrow [2,3] \rightsquigarrow [3,4,5] \rightsquigarrow [4,5,6,7] \rightsquigarrow \dots$

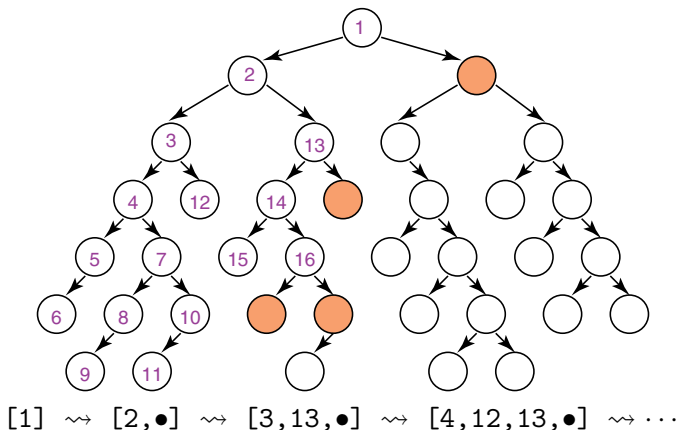
```
add2frontier(Children, [], Children).
```

```
add2frontier(Children, [H|T], [H|More]) :-  
    add2frontier(Children, T, More).
```

## Depth-first: stack (LIFO)



## Depth-first: stack (LIFO)



```
add2frontier([],Rest,Rest).
```

```
add2frontier([H|T],Rest,[H|TRest]) :-
```

```
    add2frontier(T,Rest,TRest).
```

## If-then-else and cut !

`i :- p,!,q.`

`i :- r.`

`p.`

`r.`

---

`| ?- i.`

## If-then-else and cut !

i :- p,!,q. [i]

i :- r.

p.

r.

---

| ?- i.

## If-then-else and cut !

`i :- p,!,q.`

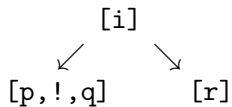
`i :- r.`

`p.`

`r.`

---

`| ?- i.`



## If-then-else and cut !

`i :- p,!,q.`

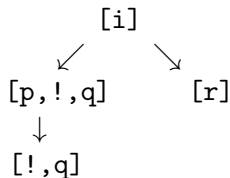
`i :- r.`

`p.`

`r.`

---

`| ?- i.`



Cut ! is true but destroys backtracking.



## If-then-else and cut !

i :- p,!,q.

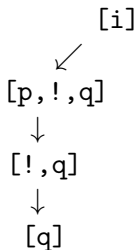
i :- r.

p.

r.

---

| ?- i.



Cut ! is true but destroys backtracking.

## If-then-else and cut !

i :- p,!,q.

i :- r.

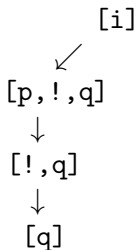
p.

r.

---

| ?- i.

no



Cut ! is true but destroys backtracking.

## Review: Depth-first as frontier search

```
prove([],_).      % goal([]).  
prove(Node,KB) :- arc(Node,Next,KB), prove(Next,KB).
```

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```
prove([],_).      % goal([]).  
prove(Node,KB) :- arc(Node,Next,KB), prove(Next,KB).
```

```
fs([[]|_],_).
```

```
fs([Node|More],KB) :- findall(X,arc(Node,X),L),  
                      append(L,More,NewFrontier),  
                      fs(NewFrontier,KB).
```

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```
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                      fs(NewFrontier,KB).
```

Cut?

## Tracking the frontier

[[i]]

i :- p,!,q.

[i]

i :- r.

p.

r.

---

| ?- i.

## Tracking the frontier

$[[i]] \rightsquigarrow [[p,! ,q],[r]]$

$i :- p,! ,q.$

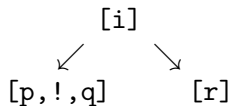
$i :- r.$

$p.$

$r.$

---

$| \text{?- } i.$



## Tracking the frontier

$$[[i]] \rightsquigarrow [[p,! ,q],[r]] \rightsquigarrow [[! ,q],[r]]$$

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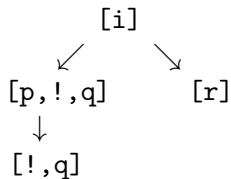
i :- r.

p.

r.

---

| ?- i.





## Tracking the frontier

$$[[i]] \rightsquigarrow [[p,! ,q],[r]] \rightsquigarrow [[! ,q],[r]] \rightsquigarrow [[q]]$$

i :- p,! ,q.

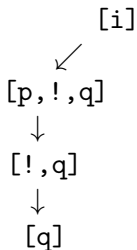
i :- r.

p.

r.

---

| ?- i.



## Tracking the frontier

$$[[i]] \rightsquigarrow [[p,! ,q],[r]] \rightsquigarrow [[! ,q],[r]] \rightsquigarrow [[q]] \rightsquigarrow []$$

`i :- p,! ,q.`

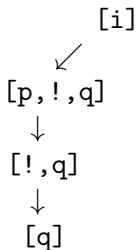
`i :- r.`

`p.`

`r.`

---

`| ?- i.`



## Tracking the frontier

$$[[i]] \rightsquigarrow [[p,! ,q],[r]] \rightsquigarrow [[! ,q],[r]] \rightsquigarrow [[q]] \rightsquigarrow []$$

`i :- p,! ,q.`

`i :- r.`

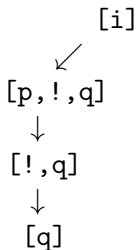
`p.`

`r.`

---

`| ?- i.`

`no`



## Cut via frontier depth-first search

```
fs([],_).
```

```
fs([Node|More],KB) :-  
    findall(X,arc(Node,X),L),  
    append(L,More,NewFrontier),  
    fs(NewFrontier,KB).
```

## Cut via frontier depth-first search

```
fs([],_).
```

```
fs([[cut|T]|_],KB) :- fs([T],KB).
```

```
fs([Node|More],KB) :-
```

```
    findall(X,arc(Node,X),L),  
    append(L,More,NewFrontier),  
    fs(NewFrontier,KB).
```

## Cut via frontier depth-first search

```
fs([],_).
```

```
fs([[cut|T]|_],KB) :- fs([T],KB).
```

```
fs([Node|More],KB) :- Node = [H|_], H\== cut,  
                        findall(X,arc(Node,X),L),  
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```

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```
fs([],_).
```

```
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                        findall(X,arc(Node,X),L),  
                        append(L,More,NewFrontier),  
                        fs(NewFrontier,KB).
```

```
if(p,q,r) :- (p!,q); r.           % contra (p,q);r
```

## Cut via frontier depth-first search

```
fs([],_).
```

```
fs([cut|T]|_,KB) :- fs(T,KB).
```

```
fs([Node|More],KB) :- Node = [H|_], H \== cut,  
                        findall(X,arc(Node,X),L),  
                        append(L,More,NewFrontier),  
                        fs(NewFrontier,KB).
```

```
if(p,q,r) :- (p,!,q); r.           % contra (p,q);r
```

```
negation-as-failure(p) :- (p,!,fail); true.
```