

## Contents

<b>Continuous Random Variables</b>	<b>1</b>
<b>Cumulative Distribution Function</b>	<b>2</b>
<b>Area Under a Curve</b>	<b>2</b>
<b>Continuous Random Variables: CDF and PDF</b>	<b>3</b>
Example: Uniform Random Variables . . . . .	3
<b>Expectation and Variance</b>	<b>4</b>
<b>The Normal Distribution</b>	<b>5</b>
Linearity of the Normal Distribution . . . . .	5
<b>Central Limit Theorem (CLT)</b>	<b>5</b>
<b>Confidence Intervals (Again)</b>	<b>6</b>
Example: Running Time of New Algorithm . . . . .	7
Wrap Up . . . . .	7

## Continuous Random Variables

All RVs up to now have been discrete

- Take on distinct values, e.g. in set  $\{1, 2, 3\}$
- Often represent binary values or counts

What about continuous RVs?

- Take on real-values
- e.g. Travel time to work, temperature of this room, fraction of Irish population supporting Scotland in the rugby

## Cumulative Distribution Function

Suppose  $Y$  is a random variable, which may be discrete or continuous valued.

- Recall  $F_Y(y) := P(Y \leq y)$  is the cumulative distribution function (CDF)
- CDF exists and makes sense for both discrete and continuous valued random variables
- When  $Y$  takes discrete values  $\{y_1, \dots, y_m\}$  then  $F_Y(y) = \sum_{j: y_j \leq y} P(Y = y_j)$
- $F_Y(-\infty) = 0, F_Y(+\infty) = 1$
- Also

$$P(Y \leq b) = P(Y \leq a) + P(a < Y \leq b)$$

i.e.

$$F_Y(b) = F_Y(a) + P(a < Y \leq b)$$

therefore

$$P(a < Y \leq b) = F_Y(b) - F_Y(a)$$

CDF always starts at 0 and rises to 1, never decreasing.

## Area Under a Curve

- Fit a series of rectangles under the curve, each of width  $h$
- We know the area under a rectangle, its the height  $\times$  width  $h$
- Add up the areas of all the rectangles to get an estimate of the area under the curve
- As  $h$  gets smaller and smaller ( $h \rightarrow 0$ ) this value becomes closer and closer to the true area
- Think of  $f(y)dy$  as the area of the rectangle between  $y$  and  $y + dy$  with  $dy$  infinitesimally small
- Write the area under curve between  $a$  and  $b$  as  $\int_a^b f(y)dy$
- Think of integral as the sum of areas of rectangles each of width  $h$  as  $h \rightarrow 0$ 
  - Integral symbol  $\int$  is supposed to be suggestive of a sum
  - Can think of  $dy$  as  $h$  (infinitesimally small)

Example: CDF  $F_Y(y)$  in right-hand plot is area under curve in left-hand plot between  $-\infty$  and  $y$ , i.e.  $F_Y(y) = \int_{-\infty}^y f_Y(t)dt$

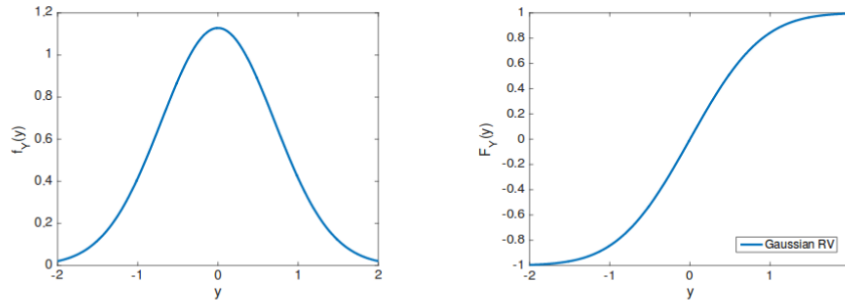


Figure 1: PDF and CDF

## Continuous Random Variables: CDF and PDF

- For a continuous-valued variable  $Y$  there exists a function  $f_Y(y) \geq 0$  such that

$$F_Y(y) = \int_{-\infty}^y f_Y(t) dt$$

- cf  $F_Y(y) = \sum_{j: y_j \leq y} P(Y = y_j)$  in discrete-valued case
- $f_Y$  is called the **probability density function** or **PDF** of  $Y$
- $\int_{-\infty}^{\infty} f_Y(y) dy = 1$  (since  $\int_{-\infty}^{\infty} f_Y(y) dy = F_Y(\infty) - P(Y \leq -\infty) = 1$ )

Note that tricky to define PDF  $f_Y$  for a discrete random variable since its CDF has “jumps” in it

- It follows that

$$P(a < Y \leq b) = F_Y(b) - F_Y(a) = \int_{-\infty}^b f_Y(t) dt - \int_{-\infty}^a f_Y(t) dt = \int_a^b f_Y(t) dt$$

- The probability density function  $f(y)$  for random variable  $Y$  is *not* a probability, e.g. it can take values greater than 1
- Its the *area* under the PDF between points  $a$  and  $b$  that is the probability  $P(a < Y \leq b)$ 
  - i.e. The total area under the curve is 1

### Example: Uniform Random Variables

$Y$  is a **uniform random variable** when it has PDF

$$f_Y(y) = \begin{cases} \frac{1}{\beta - \alpha} & \text{when } \alpha \leq y \leq \beta \\ 0 & \text{otherwise} \end{cases}$$

- For  $\alpha \leq a \leq b \leq \beta : P(a \leq Y \leq b) = \frac{b-a}{\beta-\alpha}$
- `rand()` function in Matlab

A bus arrives at a stop every 10 minutes. You turn up at the stop at a time selected uniformly at random during the day and wait for 5 minutes. What is the probability that the bus turns up?

- Check the area under the PDF is 1. Area of left-hand triangles is  $\frac{1}{2}$ , area of the right hand triangle is the same. Total is 1.
- What is  $P(0 \leq X \leq 1)$ ? Its the area under the PDF between points 0 and 1, i.e. the area of the right hand triangle, so  $P(0 \leq X \leq 1) = 0.5$
- What is  $P(0 \leq X \leq \infty)$ ?  $f_X(x) = 0$  for  $x > 1$ , so  $P(0 \leq X \leq \infty) = P(0 \leq X \leq 1) = 0.5$

## Expectation and Variance

For  $dx$  infinitesimally small,

$$P(x \leq X \leq x + dx) = F_X(x + dx) - F_X(x) \approx f_X(x)dx$$

so we can think of  $f_X(x)dx$  as the probability that  $X$  takes a value between  $x$  and  $x + dx$

For *discrete* RV  $X$

- $E[X] = \sum_x xP(X = x)$
- $E[X^n] = \sum_x x^n P(X = x)$

For *continuous* RV  $X$

- $E[X] = \int_{-\infty}^{\infty} x f_X(x) dx$
- $E[X^n] = \int_{-\infty}^{\infty} x^n f_X(x) dx$

As before  $Var(X) = E[(X - E[X])^2] = E[X^2] - E[X]^2$

For both discrete and continuous random variables

$$E[aX + b] = aE[X] + b$$

$$Var(X) = E[(X - \mu)^2] = E[X^2] - (E[X])^2$$

$$Var(aX + b) = a^2 Var(X)$$

(just replace sum with integral in previous proofs)

## The Normal Distribution

$Y$  is **Normal random variable**  $Y \sim N(\mu, \sigma^2)$  when it has PDF

$$f_Y(y) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(y-\mu)^2}{2\sigma^2}}$$

- $E[Y] = \mu, \text{Var}(Y) = \sigma^2$
- Symmetric about  $\mu$  and defined for all real-valued  $x$
- A Normal RV is also often called a **Gaussian random variable** and the Normal distribution referred to as the Gaussian distribution

## Linearity of the Normal Distribution

Suppose  $X \sim N(\mu, \sigma^2)$ . Let  $Y = aX + b$ , then

- $E[Y] = aE[X] + b = a\mu + b, \text{Var}(Y) = a^2\text{Var}(X)$
- $Y \sim N(a\mu + b, a^2\sigma^2)$ , i.e.  $Y$  is also Normally distributed

Suppose  $X \sim N(\mu_X, \sigma_X^2)$  and  $Y \sim N(\mu_Y, \sigma_Y^2)$  are independent RVs. Let  $Z = X + Y$ , then

- $E[Z] = E[X] + E[Y] = \mu_X + \mu_Y, \text{Var}(Z) = \text{Var}(X) + \text{Var}(Y) = \sigma_X^2 + \sigma_Y^2$
- $Z \sim N(\mu_X + \mu_Y, \sigma_X^2 + \sigma_Y^2)$ , i.e.  $Z$  is also Normally distributed
- NB: Only holds for addition of Normal RVs, .e.g  $X^2$  is not Normally distributed even if  $X$  is

## Central Limit Theorem (CLT)

Why is it called the “Normal” distribution? Suggests its the “default”. Coin toss example again, but now we plot a histogram of  $\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$  as  $N$  increases.

- Curve narrows as  $n$  increases, it concentrates as we already know from weak law of large numbers
- Curve is roughly “bell-shaped” i.e. roughly Normal

Consider  $N$  independent and identically distributed random variables  $X_1, \dots, X_N$  each with mean  $\mu$  and variance  $\sigma^2$ . Let  $\bar{X} = \frac{1}{N} \sum_{k=1}^N X_k$ . Then

$$\bar{X} \sim N\left(\mu, \frac{\sigma^2}{N}\right) \text{ as } N \rightarrow \infty$$

- This says that as  $N$  increases the distribution of  $\bar{X}$  converges to a Normal (or Gaussian) distribution
- The distribution has mean  $\mu$  and variance  $\frac{\sigma^2}{N}$
- Variance  $\frac{\sigma^2}{N} \rightarrow 0$  as  $N \rightarrow \infty$ 
  - So distribution concentrates around the mean  $\mu$  as  $N$  increases

## Confidence Intervals (Again)

- Recall that when a random variable lies in an interval  $a \leq X \leq b$  with a specified probability we call this a confidence interval
- When  $X \sim N(\mu, \sigma^2)$ :

$$P(-\sigma \leq X - \mu \leq \sigma) \approx 0.68$$

$$P(-2\sigma \leq X - \mu \leq 2\sigma) \approx 0.95$$

$$P(-3\sigma \leq X - \mu \leq 3\sigma) \approx 0.997$$

- There are  $1\sigma, 2\sigma, 3\sigma$  confidence intervals
- $\mu \pm 2\sigma$  in the 95 confidence interval for a Normal random variable with mean  $\mu$  and variance  $\sigma^2$ 
  - In practice often use either  $\mu \pm \sigma$  or  $\mu \pm 3\sigma$  as confidence intervals
- Recall claim by Goldman Sachs that crash was a  $25\sigma$  event

But

- These confidence intervals differ from those we previously derived from Chebyshev and Chernoff inequalities
  - Chebyshev and Chernoff confidence intervals are actual confidence intervals
  - Those derived from CLT are only approximate (accuracy depends on how large  $N$  is)
- We need to be careful to check that  $N$  is large enough that distribution really is almost Gaussian
  - This might need large  $N$

## Example: Running Time of New Algorithm

Suppose we have an algorithm to test. We run it  $N$  times and measure the time to complete, gives measurements  $X_1, \dots, X_N$

- Mean running time is  $\mu = 1$ , variance is  $\sigma^2 = 4$
- How many trials do we need to make so that the measured sample mean running time is within 0.5s of the mean  $\mu$  with 95% probability?
  - $P(|X - \mu| \geq 0.5) \leq 0.05$  where  $X = \frac{1}{N} \sum_{k=1}^N X_k$
- CLT tells us that  $X \sim N(\mu, \frac{\sigma^2}{N})$  for large  $N$
- So we need  $2\sigma = 2\sqrt{\frac{\sigma^2}{N}} = 0.5$  i.e.  $N \geq 64$

## Wrap Up

We have three different approaches for estimating confidence intervals, each with their pros and cons

- CLT:  $\bar{X} \sim N(\mu, \frac{\sigma^2}{N})$  as  $N \rightarrow \infty$ 
  - Gives full distribution of  $\bar{X}$
  - Only requires mean and variance to fully describe this distribution
  - But is an approximation when  $N$  finite, and hard to be sure how accurate (how big should  $N$  be?)
- Chebyshev and Chernoff
  - Provides an actual bound
  - Works for all  $N$
  - But loose in general
- Bootstrapping
  - Gives full distribution of  $\bar{X}$ , doesn't assume Normality
  - But is an approximation where  $N$  finite, and hard to be sure how accurate (how big should  $N$  be?)
  - Requires availability of all  $N$  measurements