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Example

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Horn-SAT is feasible, whereas 3-SAT is likely not.

Non-monotonicity

Logical consequence is monotonic: adding clauses doesn't invalidate a previous conclusion

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Example: Assume a database of video segments is complete.

Rules

Encode birds fly

$$fly(X) :- bird(X)$$
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to allow for exceptions.

Rules and defaults

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j is true in some model of KB

```
\frac{\text{bird}(X) : \text{fly}(X)}{\text{fly}(X)}
```

```
Let KB be
   bird(robin).
   bird(penguin).
   false :- fly(penguin).
   fly(bee).
```

Conclude:

```
(*) \frac{\text{bird}(X) : \text{fly}(X)}{\text{fly}(X)}
Let KB be
     bird(robin).
     bird(penguin).
     false :- fly(penguin).
     fly(bee).
Conclude:
     fly(robin) by default rule (\star)
but not fly(penguin).
```

Non-determinism

Conflicting defaults

$$\frac{\operatorname{quaker}(X):\operatorname{pacifist}(X)}{\operatorname{pacifist}(X)} \qquad \frac{\operatorname{republican}(X):\operatorname{hawk}(X)}{\operatorname{hawk}(X)}$$

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Applying one default to Nixon makes the other inapplicable.

KB has two incompatible extensions, breaking least fixed point (provability model) for Horn clauses.

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N.B. Checking finite failure can be as hard as the Halting Problem.

3 modes of inference (C.S. Peirce)

Deduction	deduce	modus ponens \cong function app $f(a)$
Abduction	explain	choose input a from assumables
Induction	generalise/program	choose rule/function f

3 modes of inference (C.S. Peirce)

From \models as inclusion \subseteq

$$KB \models g \iff Mod(KB) \subseteq Mod(g)$$
 $KB \text{ satisfiable } \iff Mod(KB) \not\subseteq Mod(false)$
 $\iff Mod(KB) \neq \emptyset$

to weighing alternatives $d \in D$ via probabilities given KB

$$prob(d|KB) = conditional probability of d given KB$$

→ Bayesian networks, from next week on.