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1 Linear Dependence Model

The linear data generation process simulates mixed continuous and categorical variables via a latent multivariate normal factor model. Given parameters

$$n$$
, $p_{\text{cont}} = |p/2|$, $p_{\text{cat}} = p - p_{\text{cont}}$, $d = \max(p_{\text{cont}}, \text{max_levels})$,

and max_levels the maximum categories per variable, we proceed:

1. Generate a random $d \times d$ matrix M with entries

$$M_{ij} \sim \mathcal{U}(0.05, 0.95)$$
 and set $\Sigma = M M^{\top}$

to ensure a positive–definite covariance.

2. Draw latent factors

$$\mathbf{Z} \in \mathbb{R}^{n \times d} \sim \mathcal{N}(\mathbf{0}, \Sigma).$$

3. Split into continuous and categorical blocks:

Continuous: Select p_{cont} distinct columns of **Z** at random and label them $\{X_1, \ldots, X_{p_{\text{cont}}}\}.$

Categorical: For each $j = 1, ..., p_{\text{cat}}$:

- (a) Sample the number of categories $K_j \in \{2, \dots, \mathtt{max_levels}\}$.
- (b) Choose $s = K_j 1$ columns of **Z** as predictors, forming $\mathbf{Z}_{\text{pred}} \in \mathbb{R}^{n \times s}$.
- (c) Build a coefficient matrix $B \in \mathbb{R}^{s \times K_j}$ by

$$B = [\mathbf{0} \mid \beta], \quad \beta_{ik} \sim \mathcal{U}(-3, 3),$$

where the first column of zeros is the reference.

- (d) Add independent noise $\boldsymbol{\varepsilon} \in \mathbb{R}^{n \times K_j}$, $\varepsilon_{ik} \sim \mathcal{N}(0, 1)$.
- (e) Compute latent utilities

$$Y = \mathbf{Z}_{\text{pred}} B + \boldsymbol{\varepsilon} \in \mathbb{R}^{n \times K_j}.$$

(f) Assign each observation

$$C_j(i) = \arg\max_k Y_{ik}.$$

(g) If any category has fewer than $\min_{\mathbf{o}}\mathbf{o}\mathbf{b}\mathbf{s}$ observations, reassign those cases by choosing the next-largest utility among the remaining valid categories. Finally, relabel categories to consecutive integers $1, \ldots, K'_i$.

Return a data frame containing $\{X_1,\ldots,X_{p_{\text{cont}}}\}$ as numeric and $\{C_1,\ldots,C_{p_{\text{cat}}}\}$ as factors.

2 Hierarchical Tree-Based Dependence Model

The hierarchical generator alternates continuous and categorical features by recursive binary splitting on all previously generated variables.

Given bounds [a,b] for the continuous features and parameters max_depth = 5, min_split = 200, min_bucket = 50, the procedure for the generation of the total set of variables $\{V_1, \ldots, V_p\}$ is:

- **1.** Initialize $X_1 \sim \mathcal{U}(a,b)$ independently.
- **2.** For j = 2, ..., p:
 - (a) Build a binary tree on the index set $\{1, \ldots, n\}$ using all previously generated variables $\{V_1, \ldots, V_{j-1}\}$ as predictors. Call this build_tree($\{1, \ldots, n\}$, data_{1:(j-1)}), which:
 - Stops splitting a node if its size < min_split or if its depth > max_depth.
 - Attempts up to 5 random splits per node:
 - If the chosen predictor is continuous, pick a split threshold at a random truncated-normal quantile of the node's values. The random quantile q is drawn from $\mathcal{N}(0.5, 0.2)$ and then truncated to lie in [0.1, 0.9], ensuring the split always falls between the 10^{th} and 90^{th} percentiles to reduce the likelihood of creating nodes with a sparse observation count.
 - If it is categorical, split by a random nonempty proper subset of its levels.
 - Accepts a split only if both children have ≥ min_bucket observations; otherwise it retries or makes the node a leaf if it attempted the split five times.
 - (b) Continuous (j odd:) Let the resulting tree's leaves correspond to intervals $[L_i, U_i]$. The intervals bounds are specified by the previous hierarchy. The base intervals starts with [0, 10] at the tree's root and then every split parts the previous node's interval in two equally sized new intervals. For each observation t in leaf i, sample

$$X_k(t) \sim \mathcal{N}(\frac{L_i+U_i}{2}, \frac{U_i-L_i}{8}).$$

(c) Categorical (j even:) Collect all L leaves and choose a number of categories $K \sim \{2, \ldots, 7\}$. Assign each leaf one of the K labels, ensuring every label is used at least once. Then for each t in leaf i:

$$C_k(t) = \begin{cases} \ell(i), & \text{with probability } 0.8, \\ \text{a different label in } [1..K] \setminus \{\ell(i)\}, & \text{with probability } 0.2. \end{cases}$$

If after all leafs are assigned to the predefined categories, any category ends up with < 20 observations, the entire assignment is retried; if still invalid, the function errors.

3. Return $\{X_1,\ldots,X_{\lceil p/2\rceil}\}$ as numeric columns and $\{C_1,\ldots,C_{\lfloor p/2\rfloor}\}$ as factors.

This yields a sequence of features where each is conditioned on a random tree built from all previous ones, producing rich, hierarchical dependencies between continuous and categorical variables.

3 Simulation Grid

The complete dataset variations resulting for varying $type \in \{linear, hierarchical\}, p \in \{6, 12, 18\}$ and $seed \in \{1, 2, 3, 4, 5\}$

2 (types) \times 3 (p) \times 5 (seeds) = 30 simulated datasets.