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NeurIPS 2020 L2RPN Robustness and Adaptability Tracks Competition Winning Approach

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(Corresponding author)*

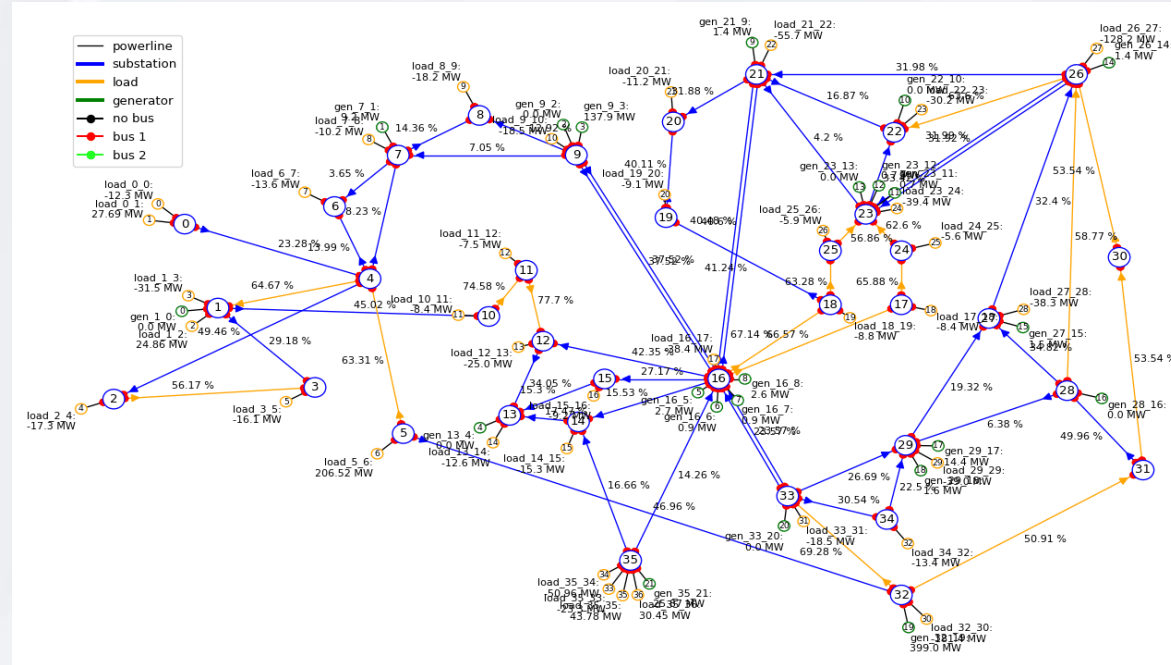
Track1 : Robustness Track

Problem
description

Methodology

Tricks

Results



An adversarial opponent will attack some lines of the grid everyday randomly.

- **Goal:** Develop agent to be robust to unexpected events and keep delivering reliable electricity everywhere even in difficult circumstances.
- **Operation Cost:** Operate the grid as long as possible, minimize the operation cost including powerlines losses, redispatch cost and blackout cost (penalty).



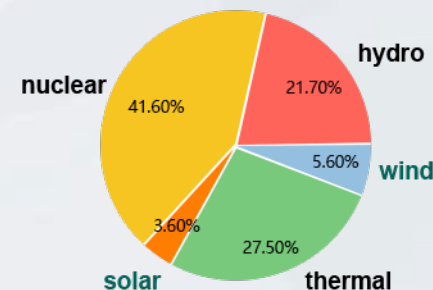
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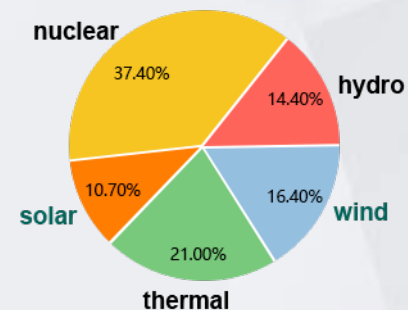
Methodology

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*Renewable energies
varying from 1x to 3x*



- **Goal:** Develop agent to adapt to new energy productions in the grid with an increasing share of renewable energies which might be less controllable.
- **Operation Cost:** Operate the grid for as long as possible, minimize the operation cost including powerlines losses, redispatch cost and blackout cost (penalty).



Rules and Score

Problem
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Rules and Constraints

- Demand-supply balance should be met at any time without load shedding.
- Tripping power plant is not allowed.
- Electrical islands are not allowed.
- Any action has a certain cool down time.

...

Score

The agent with less blackouts and less operation costs will be given higher score.

$$C_{operations}(t) = C_{loss}(t) + C_{redispatching}(t)$$

$$C_{blackout}(t) = Load(t) * \beta * p(t), \beta \geq 1$$

$$C(e) = \sum_{t=1}^{t_{end}} C_{operations}(t) + \sum_{t=t_{end}}^{T_e} C_{blackout}(t)$$

$$Score = \sum_{i=1}^N C(e_i)$$



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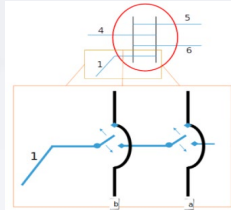
Action



Do-Nothing action



Powerline Status action: reconnecting / disconnecting a power line



Substation Topological action: switching busbar connection between double busbars for each substation object.



Generation redispatch action: modifying the production set point with redispatching



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State

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State chosen:

- Some states (such as **prod_p**, **load_p**, **topology_vect**, **time_next_maintenance**, **line_status**, **rho** etc.) are necessary in our action selecting process.
- Inherent properties in power grid (e.g **thermal_limit** of lines) and some properties of generators (e.g **max_ramp_up**)

State unchosen:

- Another part of states (such as **date**, **time**, **prod_q**, **load_q** etc.) which have no contribution to our action selecting process.



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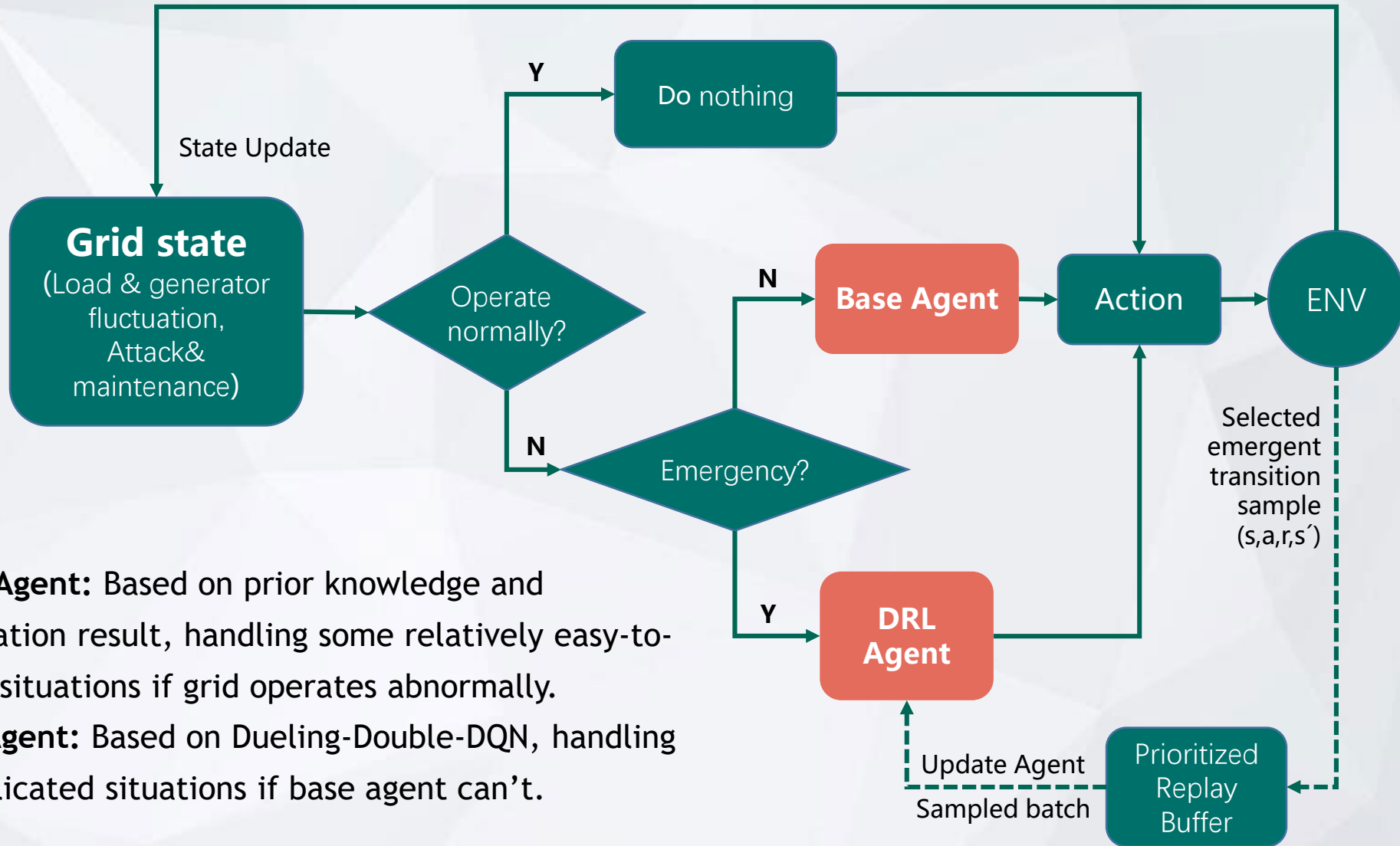
Dual-agent strategy

Problem
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Base Agent: Based on prior knowledge and simulation result, handling some relatively easy-to-solve situations if grid operates abnormally.

DRL Agent: Based on Dueling-Double-DQN, handling complicated situations if base agent can't.

**Inspired by the works of Ziming Yan, Yan Xu, Nanyang Technological University
(https://github.com/ZM-Learn/L2RPN_WCCI_a_Solution)*



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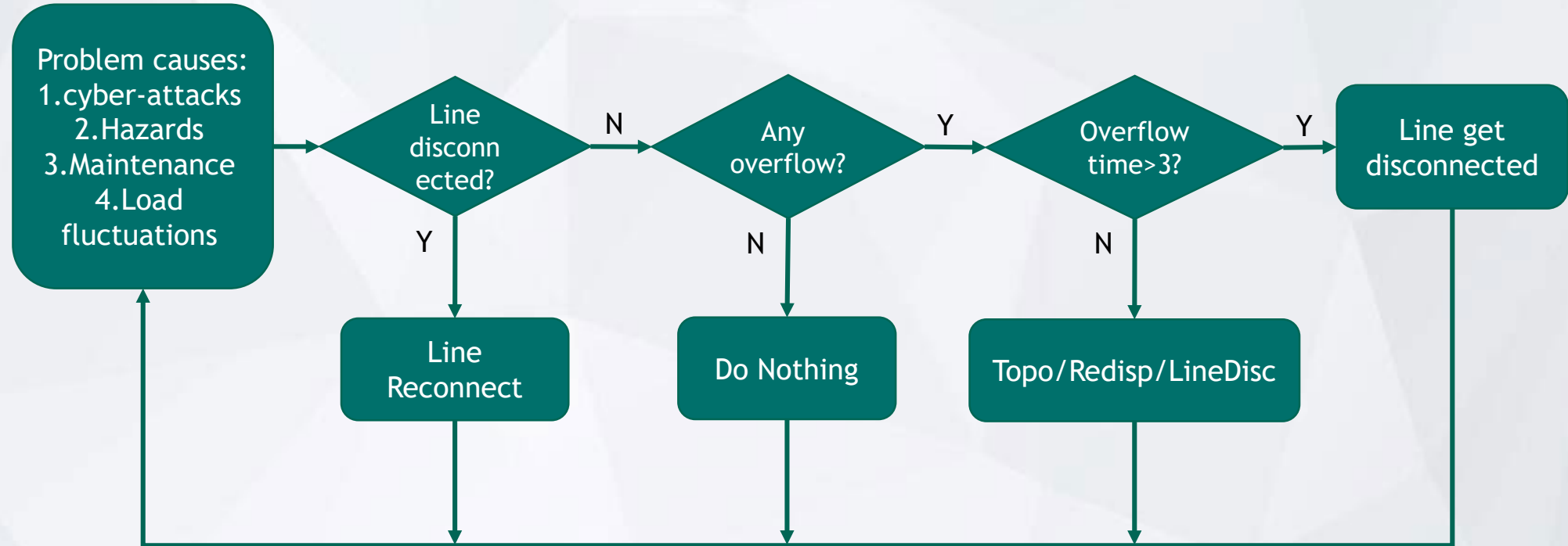
Problem
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Base-agent strategy



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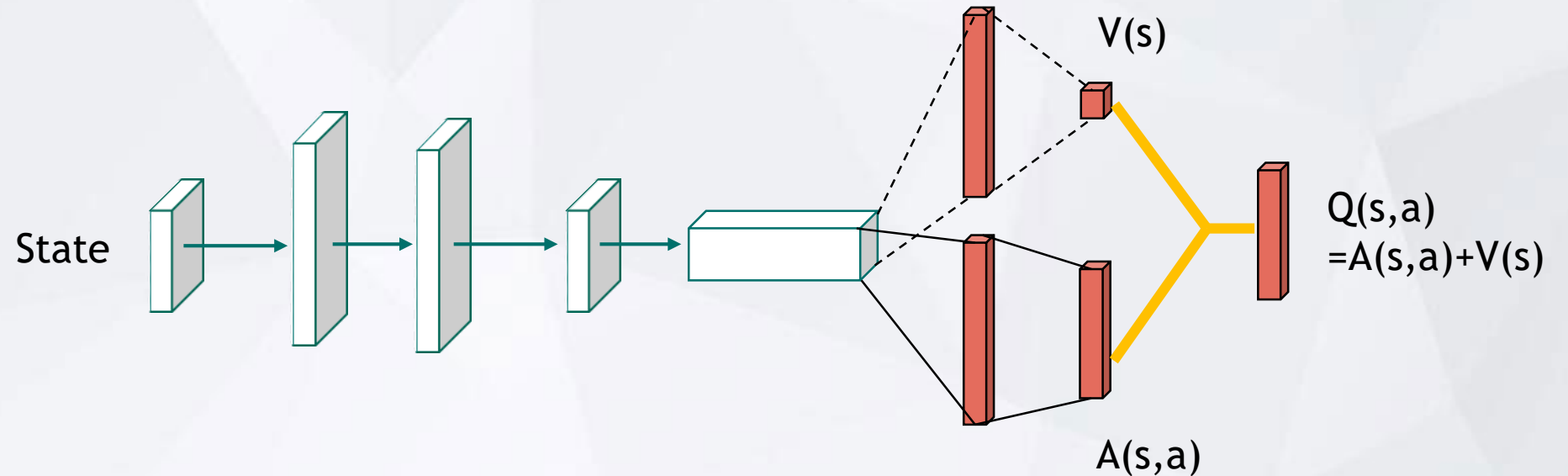
Methodology

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DRL agent

We adopt the Dueling-Double-DQN(D3QN) algorithm for our DRL agent, a kind of value based algorithm which can handle discrete action-space problems.



D3QN Neural network structure diagram

Robustness Track: State size=744, Action size=885

Adaptability Track: State size =2300, Action size =1164



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Rewards

Rewards: (factors considering)

1. **Sandbox** - economic
2. **Close-To-OverFlow** - overflow
3. **Distance** - difference with initial topology
4. **Line-capacity** - available transfer capacity



Robustness Track (Track1)

- Sandbox-Reward
- Close-To-OverFlow-Reward
- Distance-Reward

Adaptability Track (Track2)

- Sandbox-Reward
- Close-To-OverFlow-Reward
- Distance-Reward
- Lines-Capacity-Reward

$$\text{Reward} = \sum \text{Weight}(i) * \text{Reward}(i), i \in (\text{Sandbox}, \text{CloseToOverflow}, \text{Distance}, \text{LineCapacity})$$



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Reduced Action-space

➤ Robustness Track (Track1)

- Before reduce: 130k ($2^{17} = 131,072$)
- After reduce: 885

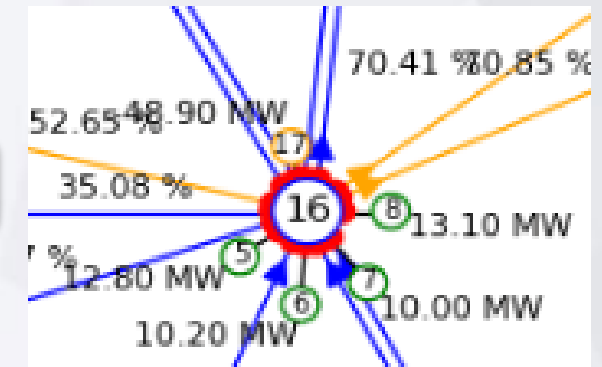
58 line, 786 topo, 40 redisp, 1 donothing

➤ Adaptability Track (Track2)

- Before reduce: even more!
- After reduce: 1164

185 line, 978 topo, 1 donothing

Why action-space need to be reduced?



- The topology action number is huge due to complex action combination.
- Difficult for system simulation and agent training.
- We reduce them according to domain knowledge and experiments.



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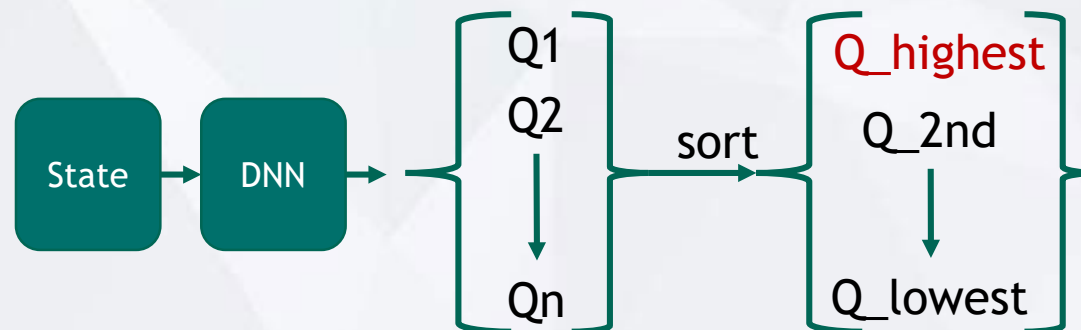
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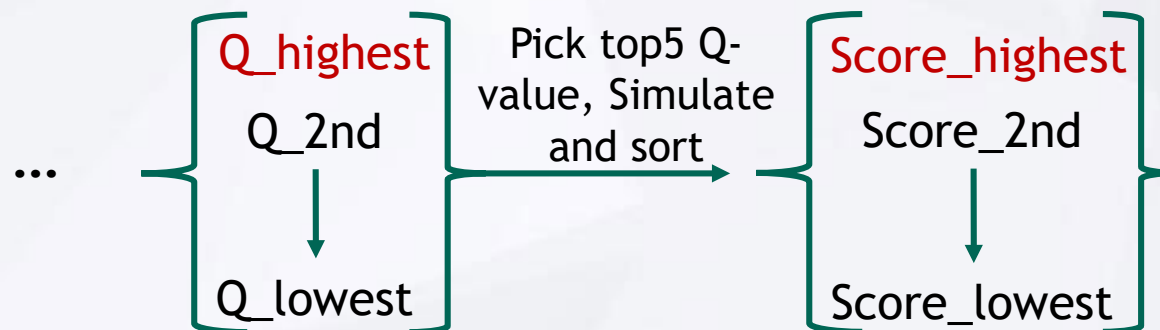
Guided exploration

Epsilon-greedy exploration



- Large Action-space
- Long MDP chain
- Local optimum

Guided exploration



- Stable
- Better experience
- Efficient



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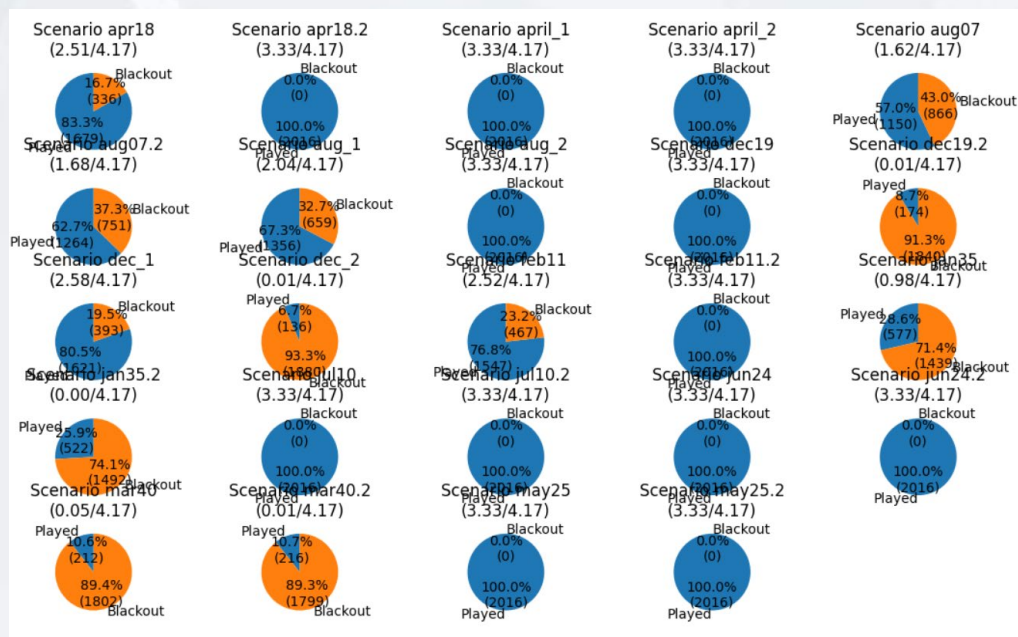
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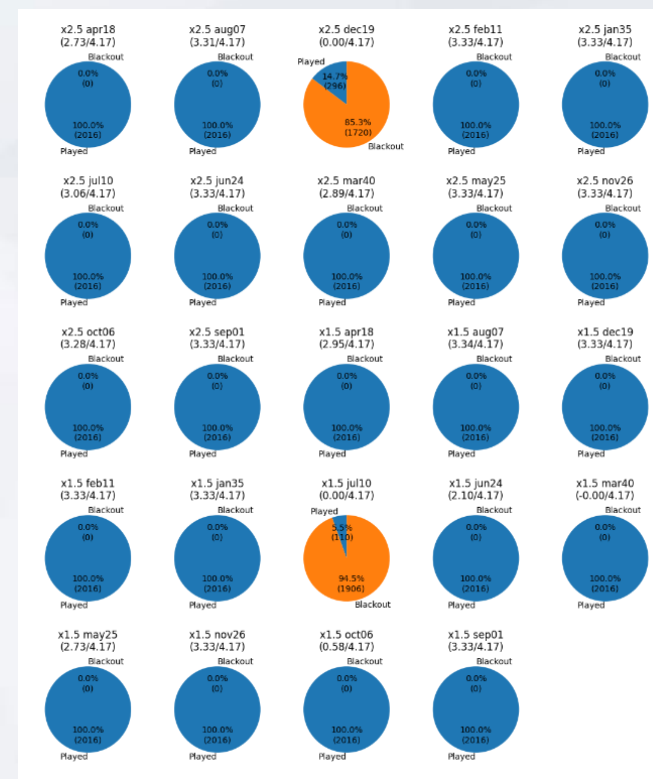
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Robustness Track Test Result



Adaptability Track Test Result

- 50-year simulated training data and 24-week test data for each competition track.
- Blue indicates scenarios passed, orange indicates scenarios black-out.
- We will optimize our agent for the failed cases in future work.



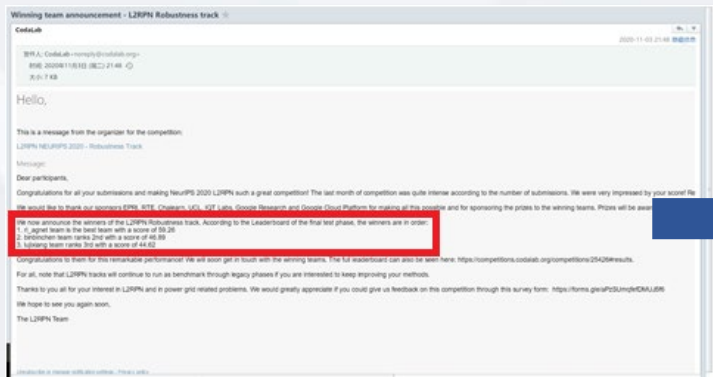
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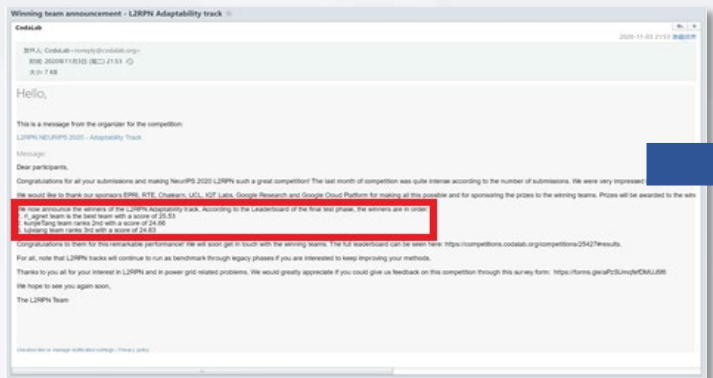
Results

Robustness Track:



- 1.rl_agent team is the best team with a score of 59.26
- 2.binbinChen team ranks 2nd with a score of 46.89
- 3.lujixiang team ranks 3rd with a score of 44.62

Adaptability Track:



- 1.rl_agent team is the best team with a score of 25.53
- 2.kunjieTang team ranks 2nd with a score of 24.66
- 3.lujixiang team ranks 3rd with a score of 24.63

We are one of top performers in both NeurIPS Robustness Track and Adaptability Track competitions.

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Thanks!

