

Name: Folarin, Wasiu Junior

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Supervisor: Dr. B.S. Ogundare

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INTRODUCTION

In everyday life, we usually see the need to further classify a collection of items into non-overlapping, exhaustive sub-groups, with each group containing members satisfying a number of constraints. That is, membership in a group is based on a proof-positive check of each members against each of the constraining conditions.

Although, several methods in the field of Operations Research (OR), especially, have been developed to solve various assignment and optimization problems. Nonetheless, Linear Programming (a key tool of OR) is specifically defined thus:

“Linear Programming is a mathematical technique for determining the optimal allocation of resources and obtaining a particular objective(i.e., cost minimization or inversely profit maximization when there are alternative uses of the resources: Land, Labout, Capital, Materials, Machines, etc.”

The question therefore arises – what if our optimization doesn’t involve minimizing cost of maximizing profit; what if we’re just interested in

*Allocation of objects to non-overlapping groups,
based on inate properties of the objects and constraining conditions*

A REFERENCE USE CASE SCENARIO

Given that every intending NYSC corp member would be posted to a serving state based on the following criteria

- He/she should not be posted to his state of origin
- He/she should not be posted to his state of studying
- He/she can only be posted to a state with capacity to absorb him/her

Given these set of constraints how do we efficiently deploy each intending Corp member to a state?

THE ALGORITHM

$$\text{Let } U = \{u_1, u_2, u_3, \dots, u_n\}$$

be a set of objects which are to be grouped into non – overlapping sets

$$\text{Let } P = \{p_1, p_2, p_3, \dots, p_k\}$$

be k number of partitioning sets to which be the elements of the set U are to be uniquely assigned

Also given are the following constraints

1. Each partitioning set , p_i has a maximum capacity of objects it can contain

$$j(p_i) = V, \text{ where } V \in \mathbb{N}$$

Hence the total capacity of all partitions , $p_i, i=1, 2, 3, \dots, k$

$$X = \sum_{i=1}^k j(p_i)$$

And so , we define the weight , w_i of each partition , p_i , thus

$$w_i = \frac{j(p_i)}{\sum_i j(p_i)} = \frac{j(p_i)}{X}$$

We now define the width of each partition p_i as

$$n(p_i) = |p_i| = w_i \cdot |U| = w_i \cdot n$$

2. Inclusion/ Exclusion Constraints , g_{i_k} , defined thus :

$$g_{i_k}(u_j) = \begin{cases} c \in (0,1], & \text{if } u_j \text{ tests positive for partition } k \\ c=0, & \text{otherwise} \end{cases}$$

where g_{i_k} is the g_i th constraint testing for compatibility of the u_j th object in the k th partition

where i is the counter for the total number of inclusion/ exclusion constraints defined

3. We now define the membership function for this algorithm thus :

$$f_i(u_j) = \prod_{s=1}^t g_{i_s}(u_j)$$

where $i=1,2,\dots,k$;

$j=1,2,\dots,n$;

$t = \text{the total number of defined inclusion/exclusion constraints}$

4. We now define the set F_i

$$F_i = \{f_i(u_1), f_i(u_2), f_i(u_3), \dots, f_i(u_n) \quad i=1,2,\dots,k\}$$

$$e.g. F_1 = \{f_1(u_1), f_1(u_2), f_1(u_3), \dots, f_1(u_n)\}$$

5. We now proceed to populate each partition, p_i with matching elements thus :

$$\text{Let } F_{p_i} = F_i \setminus \bigcup_{j=1}^{i-1} \{f_j(u_x) \mid \forall u_x \in p_j\}$$

$$\text{Let } Q_1 = u_x \mid f_i(u_x) = \max\{F_{p_i}\}$$

$$Q_2 = u_x \mid f_i(u_x) = \max\{F_{p_i} \setminus f_i(u_y) \mid u_y \in Q_1\}$$

\vdots

$$\Rightarrow Q_{|p_i|} = u_x \mid f_i(u_x) = \max\{F_{p_i} \setminus \bigcup_{j=1}^{|p_i|-1} \{f_i(u_y) \mid u_y \in Q_j\}\}$$

$$\Rightarrow p_i = \bigcup_{j=1}^{|p_i|} \{Q_j\}$$

$i=1,2,\dots,k$

QED

NEXT STEPS

We shall proceed to verify this algorithm using a computer simulation of a concrete problem, and thereby investigate the proposed solution for correctness

THANK YOU!