

**TOPIC 5**

# **Optimisation Basics and Limited Resources Problems**

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# Time table

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- |             |   |
|-------------|---|
| 10:15-11:10 | <b>-A- Introduction to optimisation</b> <ul style="list-style-type: none"><li>- linkage to problem solving</li><li>- fundamental structure of optimisation models</li></ul>   |
| 11:15-12:00 | <b>-B- Linear programming</b> <ul style="list-style-type: none"><li>- formulate a simple optimisation model for a limited resources problem</li><li>- solve a simple optimisation model<ul style="list-style-type: none"><li>... manually</li><li>... automatically using the Simplex Algorithm [Excel, Matlab]</li></ul></li></ul> |
| 13:15-15:00 | <b>-C- Exercise 5 – Product Portfolio Problem</b><br>[computer lab]   |

# Goals

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After completion of this topic you should be able to:

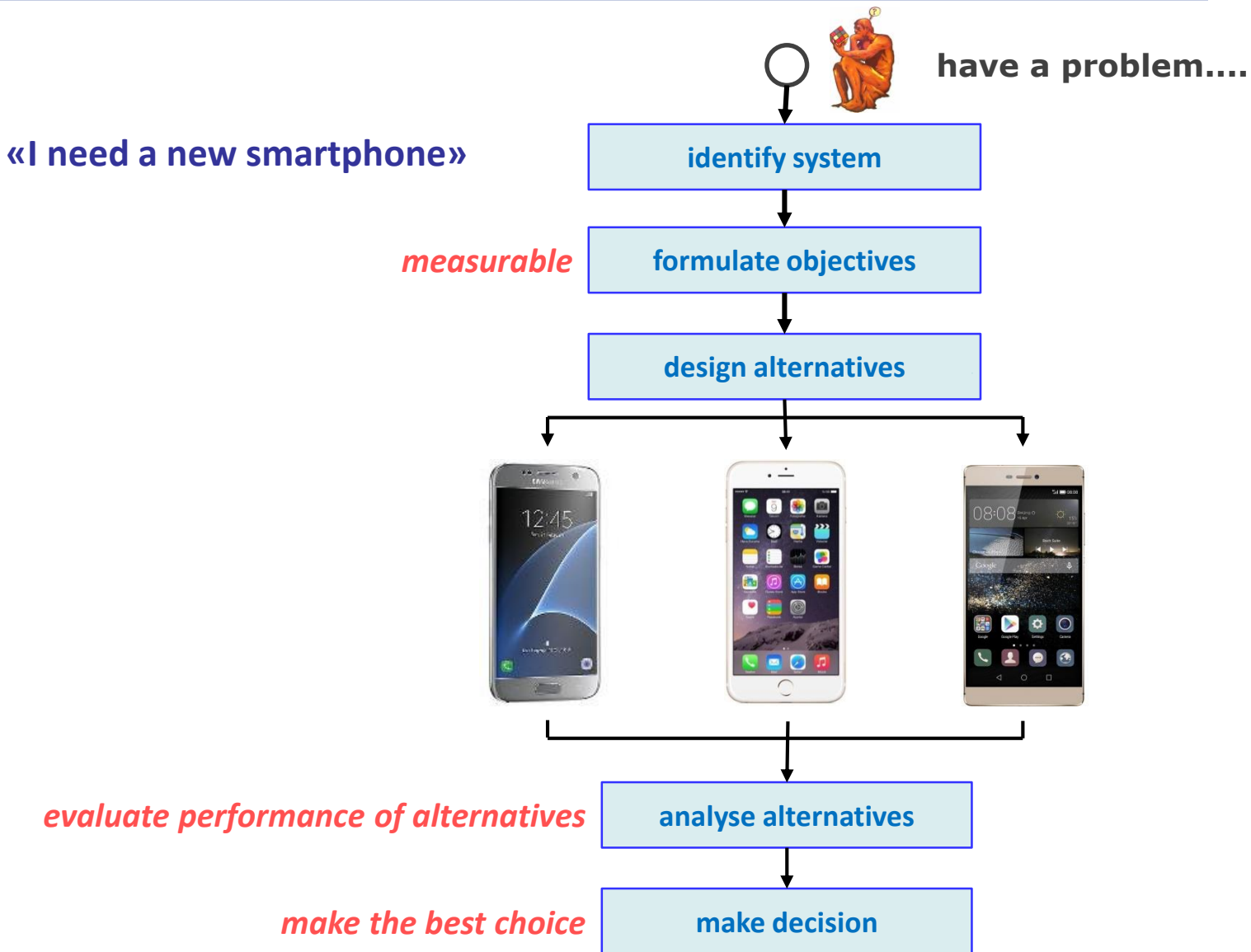
- Explain the **fundamental structure** of optimisation problems
- Explain the basics of the **SIMPLEX ALGORITHM**
- Formulate a simple optimisation model which includes limited resources
- Set up and solve a simple optimisation model in **Excel** and **Matlab**

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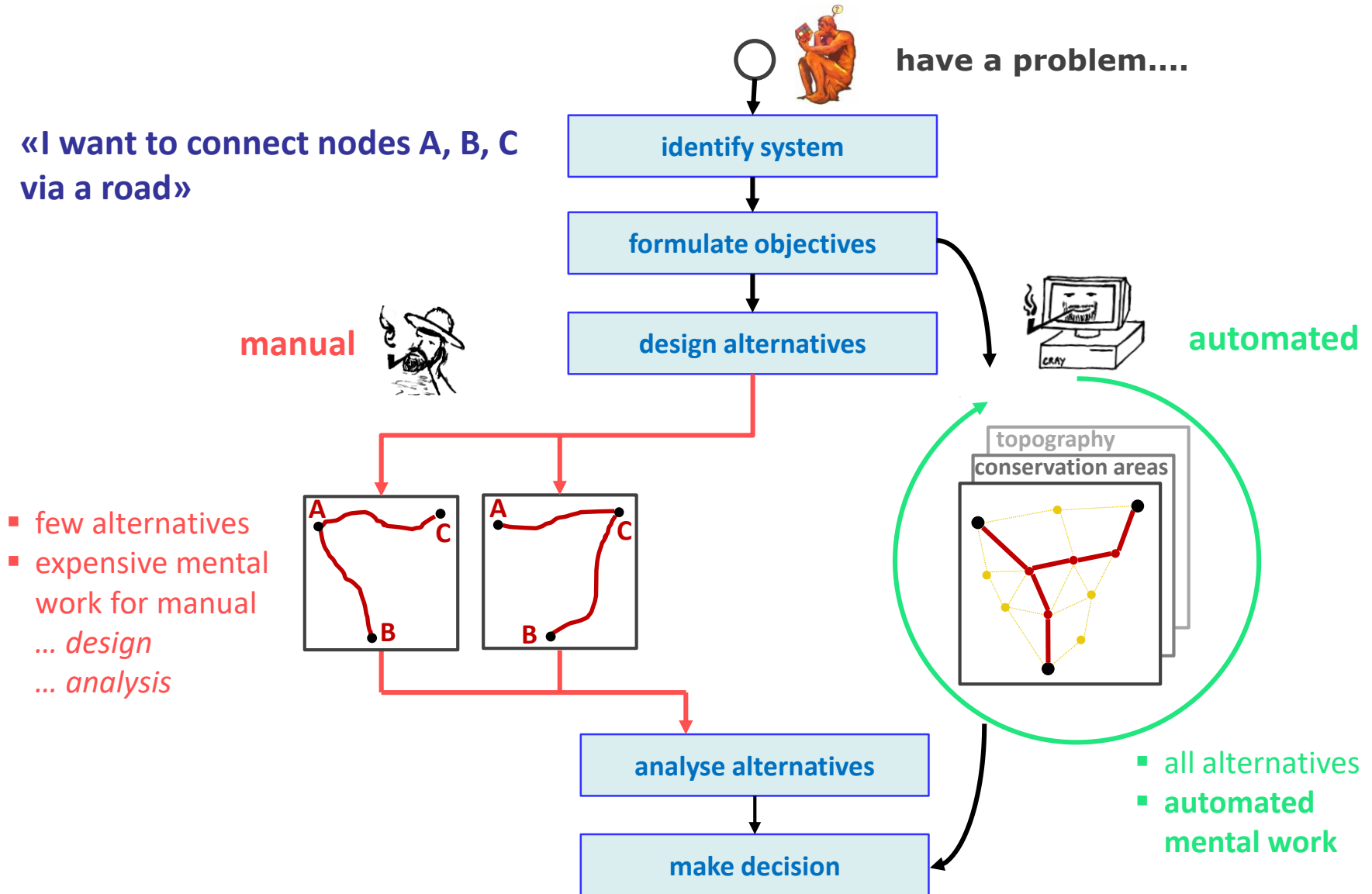
**- A -**

**INTRODUCTION TO  
MATHEMATICAL OPTIMIZATION**

# Analytic problem solving



# Analytic problem solving – many alternatives



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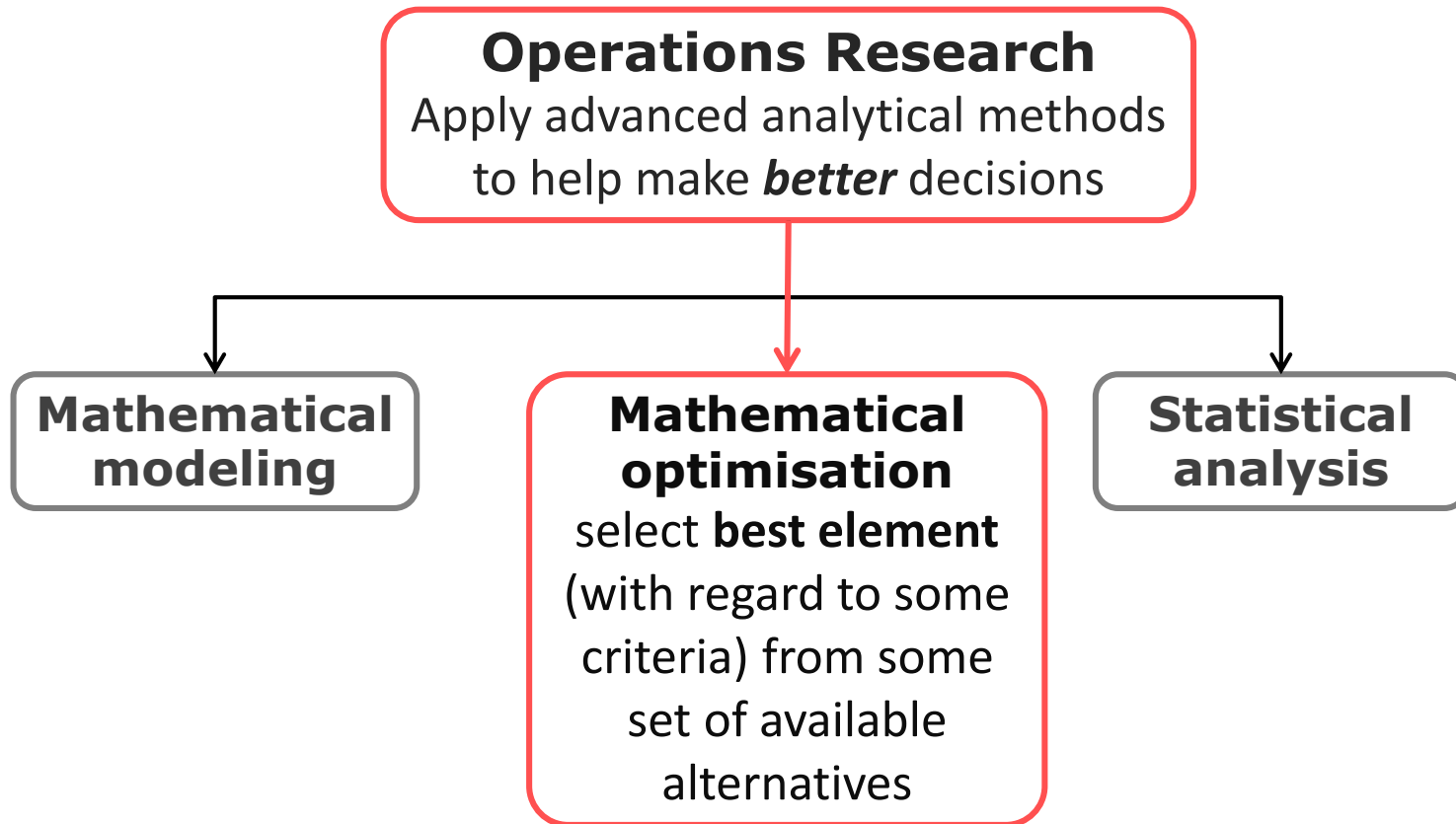
**We need a method that enables the identification of the best choice when numerous alternatives are available and comparing them is laborious.**



**Mathematical optimisation!**

# Science of the better

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<https://www.informs.org/About-INFORMS/What-is-Operations-Research>

[http://en.wikipedia.org/wiki/Mathematical\\_optimization](http://en.wikipedia.org/wiki/Mathematical_optimization)



# Automation of mental work – The starting point

World War II

Scene from movie: THE IMITATION GAME

## **OBJECTIVE**

identify settings of the  
ENIGMA (cipher machine)

## **CONSTRAINTS**

time < 24h



source: <http://www.theguardian.com>

# Learning concept and goals

[III] Improve problem solving skills

[IV] combine spatial information with optimisation models

[I] Fundamental concepts of mathematical optimisation

[II] Representation of time and space



**solve**



**implement**

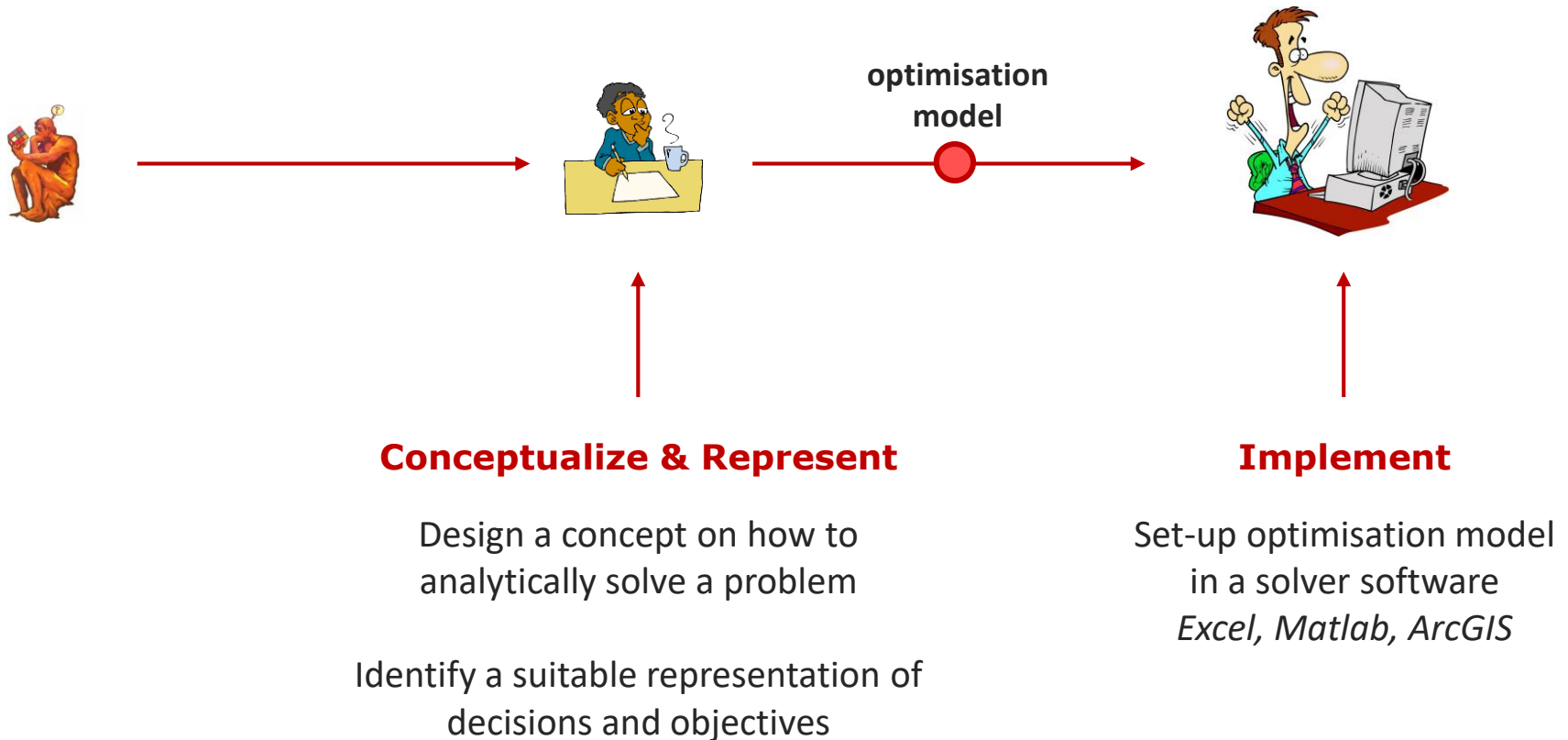


**conceptualize & represent**



**have a problem....**

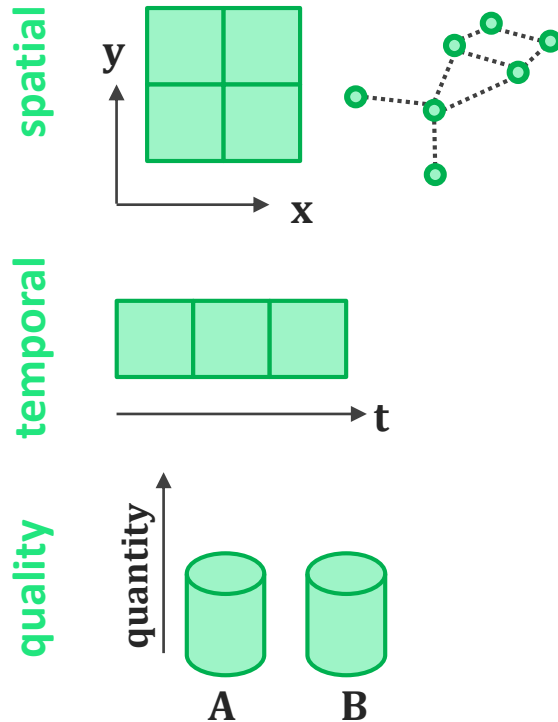
# Workflow for solving optimisation problems



# Fundamental structure of optimisation models

## decision variables

- elements to build a solution



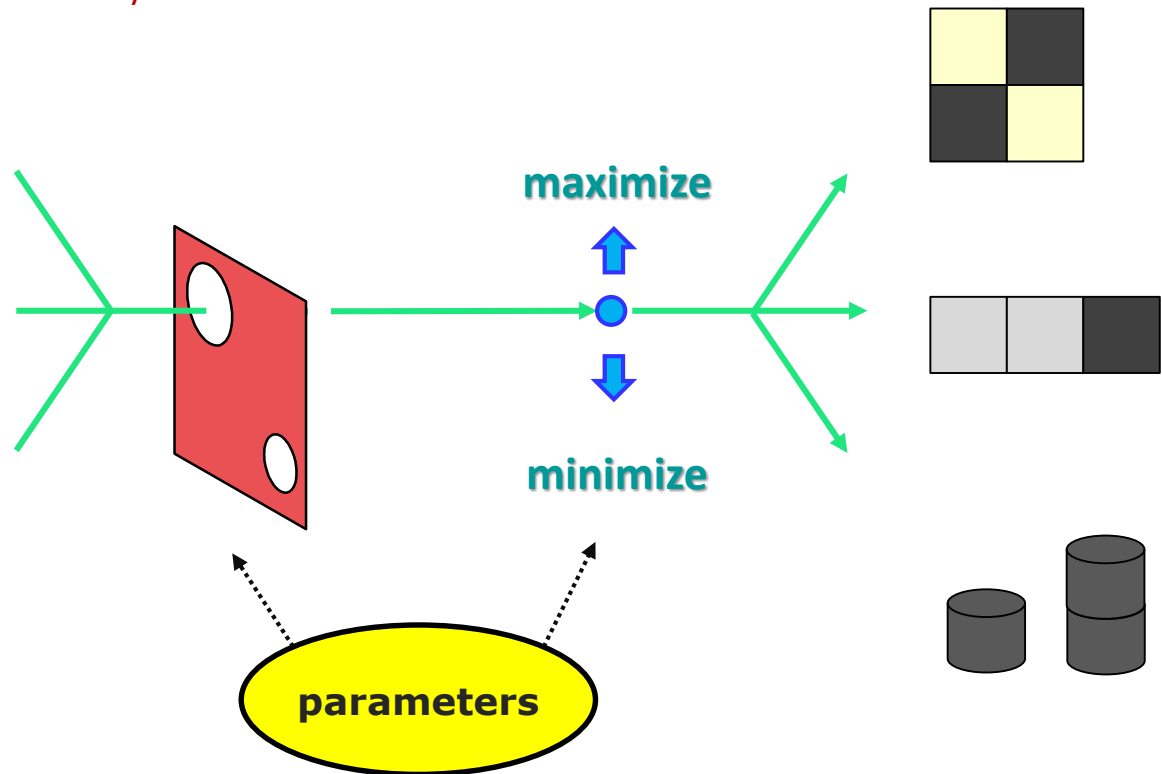
## constraints

- limited resources
- model rules for...
  - ... spatial relationship
  - ... dynamic model

## objective function

## solution

- best performing set of decision variable values



*The solution of a problem is bound to the characterization of the decision variables*

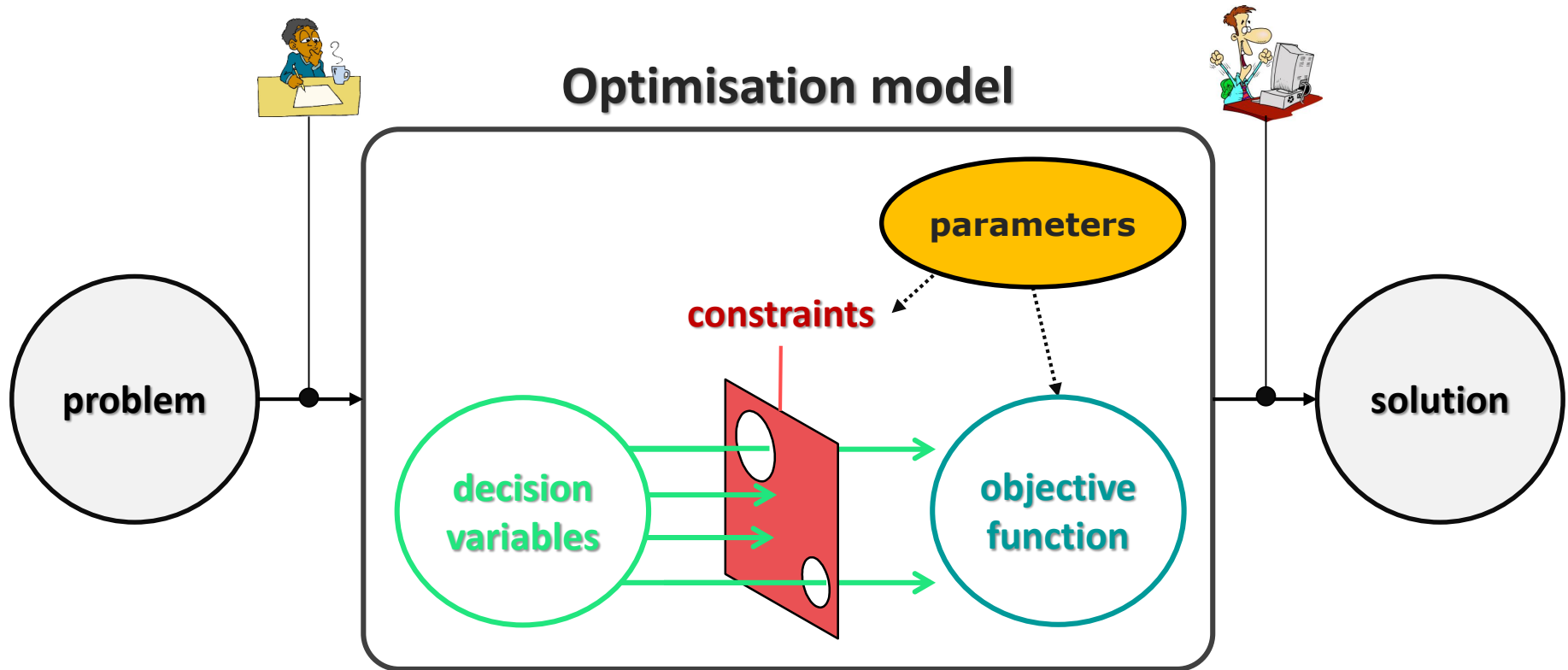


# Constraints





# FS - Definitions



**Decision variables**

representation of all alternatives

**Objective function**

performance of solution (*maximize* or *minimize*)

**Constraints**

control of the choice of alternatives

**Parameters**

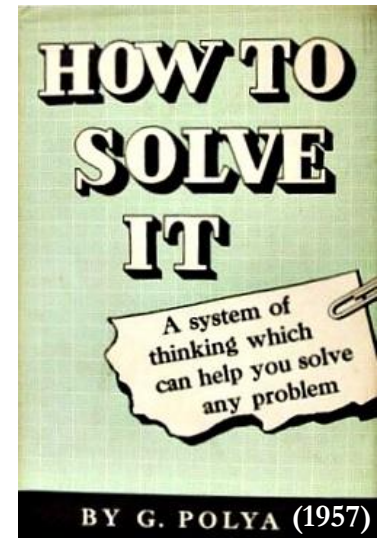
values used to formulate objective function and constraints

# Aim of the optimisation-related exercises

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## Analogy

“Can you find a problem analogous to your problem and solve that?”



*This course provides examples of problem classes which can be adapted to solve many other problems*

# Problem classes discussed in this course

## Topic 5

Limited resources

## Topic 6

Dynamical models  
and scheduling

## Topic 8

Adjacency

## Topic 9

Coverage

## Topic 10

Network Analysis I

## Topic 11

Network Analysis II

identify  
quantities

scheduling  
actions

scheduling  
actions in  
space

location of  
actions in  
space

location of  
actions in  
space

characterize  
connectivity

limited  
resources

simulate  
growth

spatial  
adjacency  
*polygon*

spatial  
coverage

spatial  
adjacency  
*point, line*

spatial  
adjacency  
*point*

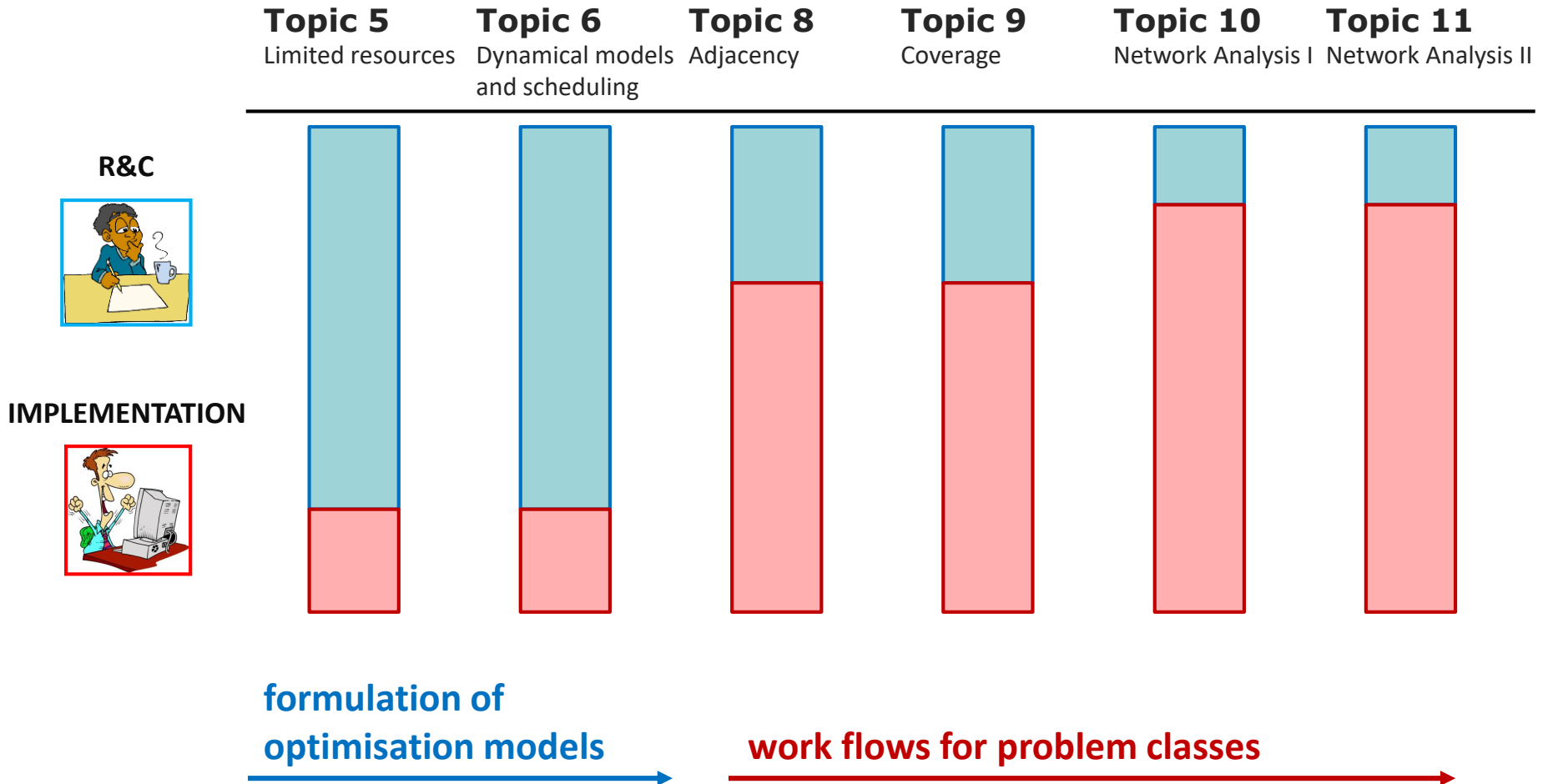
manage/preprocess data using GIS

Particular problem types  
*Linear Programming*

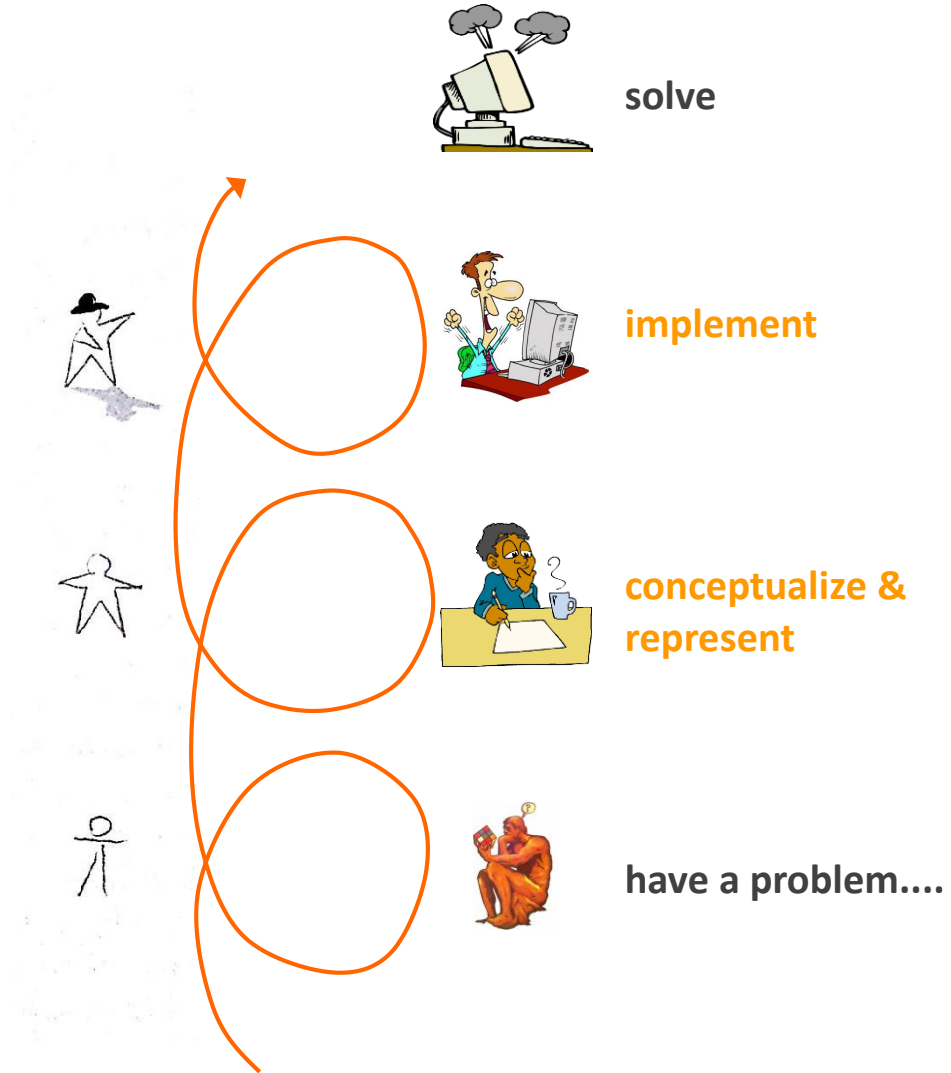
Standard problem types  
ready-to-use algorithms



# Course overview - Workload



# - B - LINEAR PROGRAMMING



# FARMER'S CHOICE PROBLEM

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A farmer owns 9 ha of land that he uses for growing carrots and grain. He wants to know the amount of area for each good which maximizes his revenues. Subsidies are given up to an area threshold. Thus, he has no incentive to plant a larger area than the one which can be subsidised.

## Latest price estimates

Carrots : 5'000 Fr./ha  
Grain : 8'000 Fr./ha

## Regulations

### Area threshold for subsidies

Carrots : 7.0 ha  
Grain : 4.5 ha

# Problem characterization

---

## Decision variables

area carrots  
area grain

## Objective function

### Parameters

MAXIMIZE revenues

profit carrots 5'000 Fr./ha  
profit grain 8'000 Fr./ha

## Constraints

### Parameters

Available land limited  
Thresholds for subsidised area

available area:	9ha
subsidised area of grain:	4.5ha
subsidised area of carrots:	7.0ha

# Optimisation model formulation I

## Decision variables

area carrots  $x_C$  ha

area grain  $x_G$  ha

## Objective function

$$\text{MAX } F = 5000 \cdot x_C + 8000 \cdot x_G$$

or, reformulated:

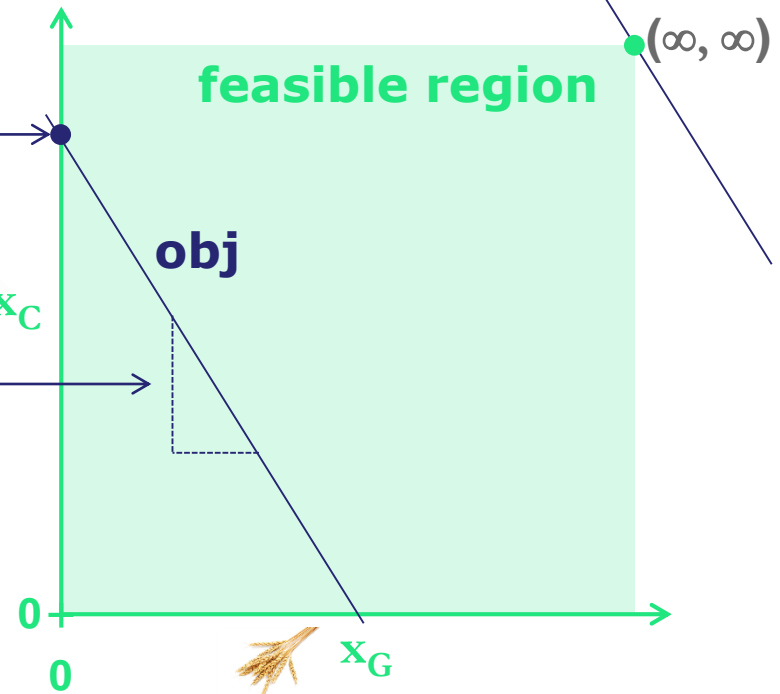
$$\text{obj: } x_C = -\frac{8000}{5000} \cdot x_G + \frac{F}{5000}$$

y-intercept

slope



$x_C$



Find combination  $(x_C, x_G)$  such that y-intercept **F/5000** becomes maximal!

# Optimisation model formulation II

## Decision variables

$$x_C, x_G \in \mathbb{R}_0^+$$

## Objective function

$$\text{MAX } F = 5000 \cdot x_C + 8000 \cdot x_G$$

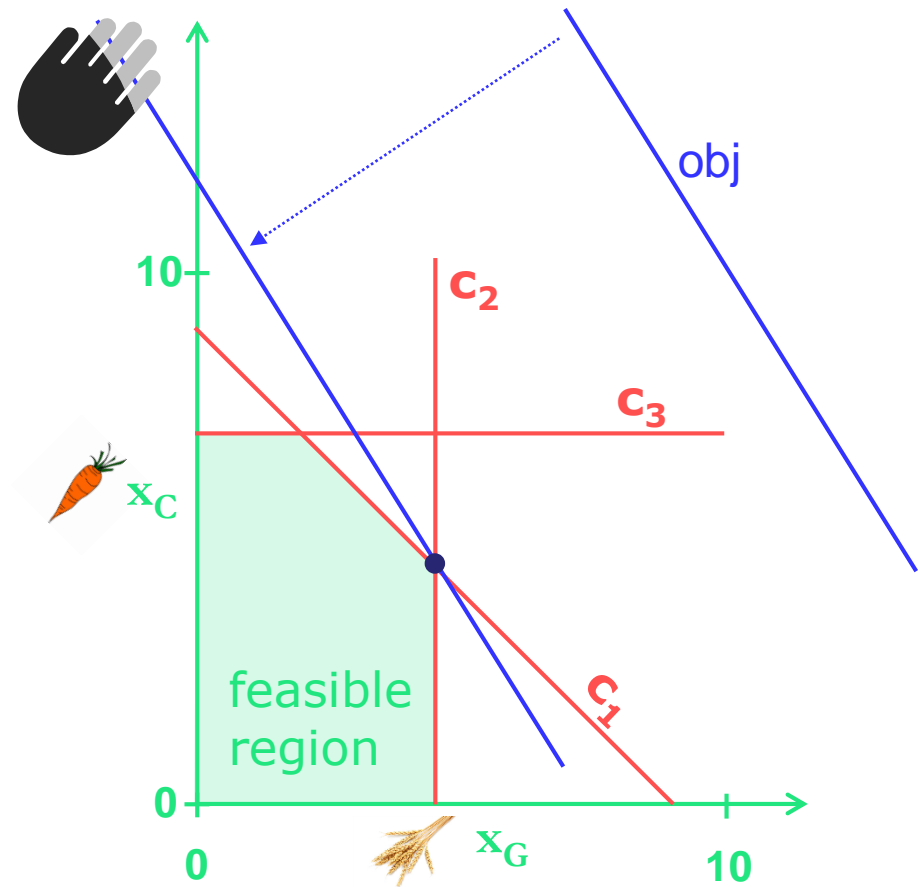
## Constraints

- (1) Farmer owns 9 ha of land
- (2) Grain is subsidised up to 4.5 ha
- (3) Carrot is subsidised up to 7.0 ha

$$C_1: x_C + x_G \leq 9$$

$$C_2: x_G \leq 4.5$$

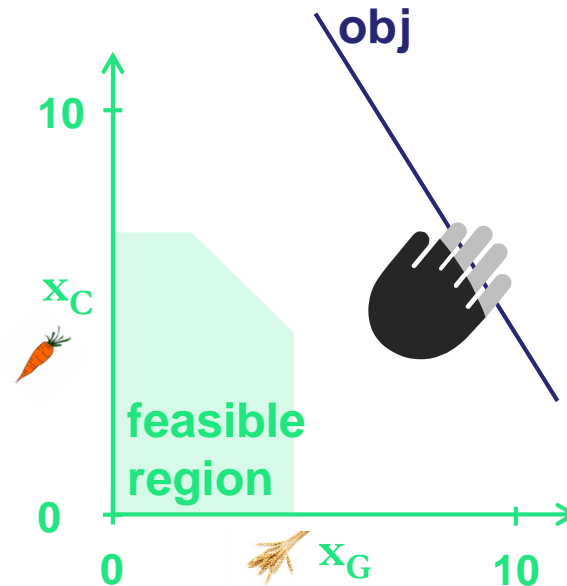
$$C_3: x_C \leq 7$$



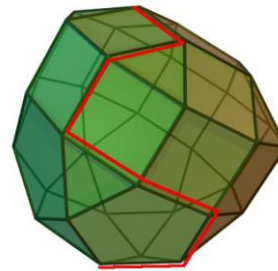
## Graphical solution

# Limitations of graphical identification of solution

2 Variables



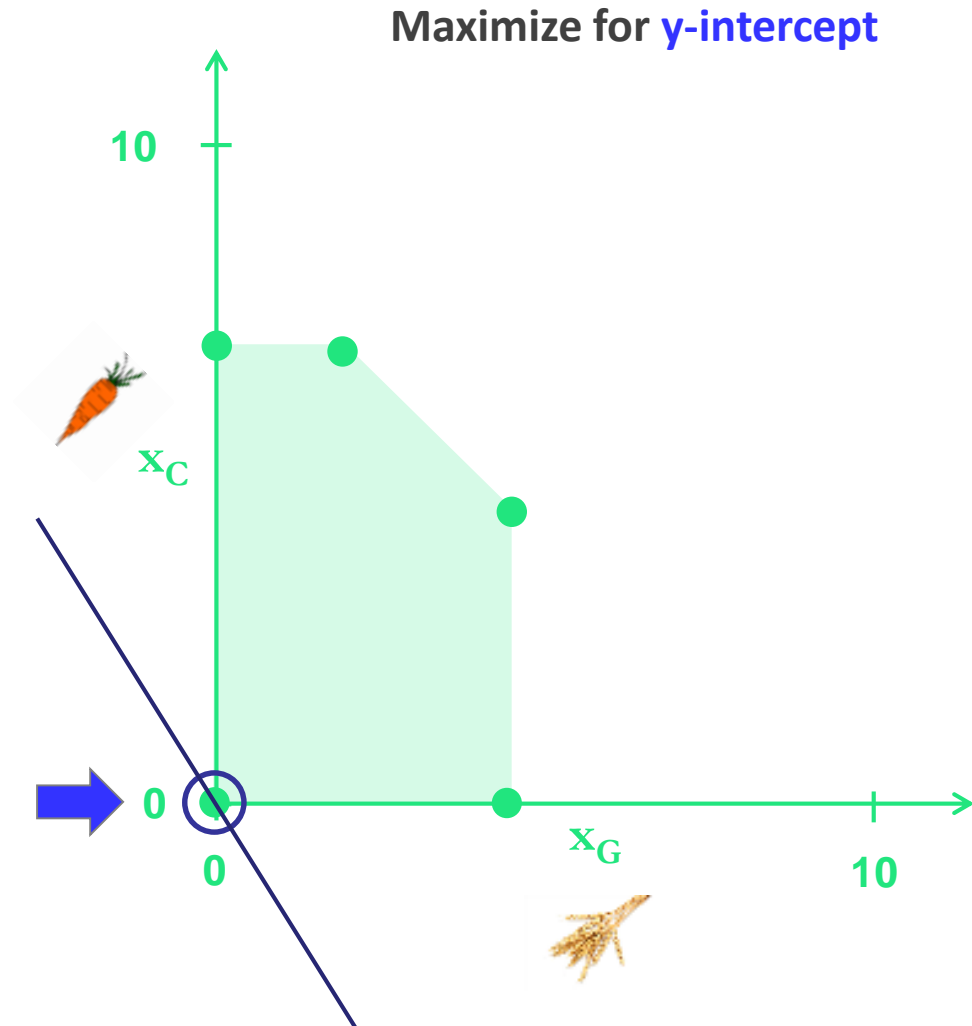
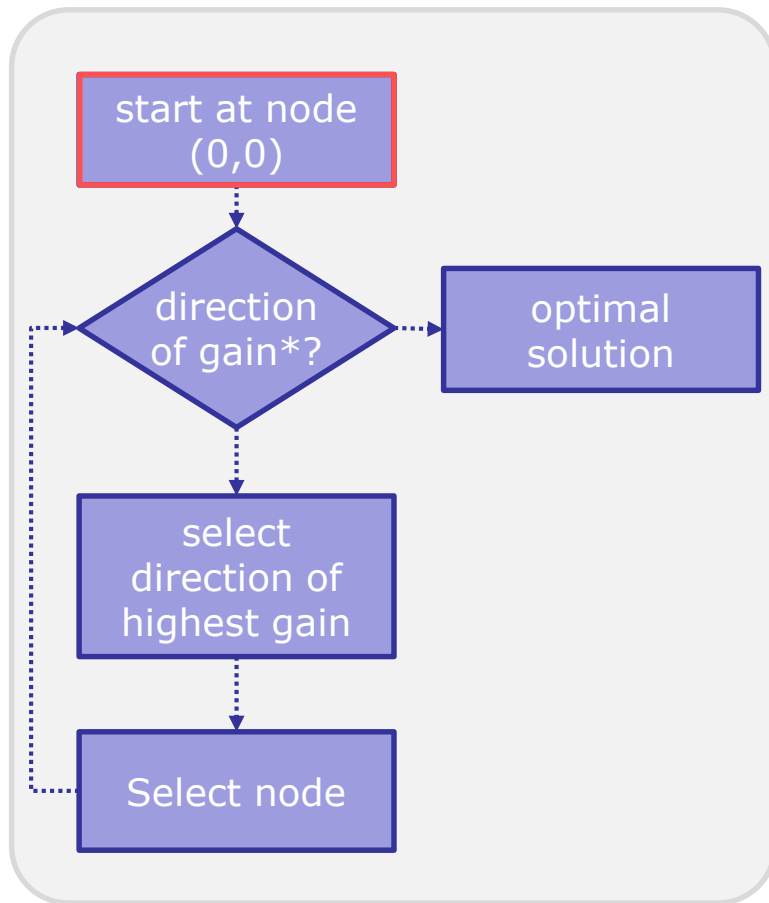
3 Variables



100 Variables ?

# Simplex Algorithm

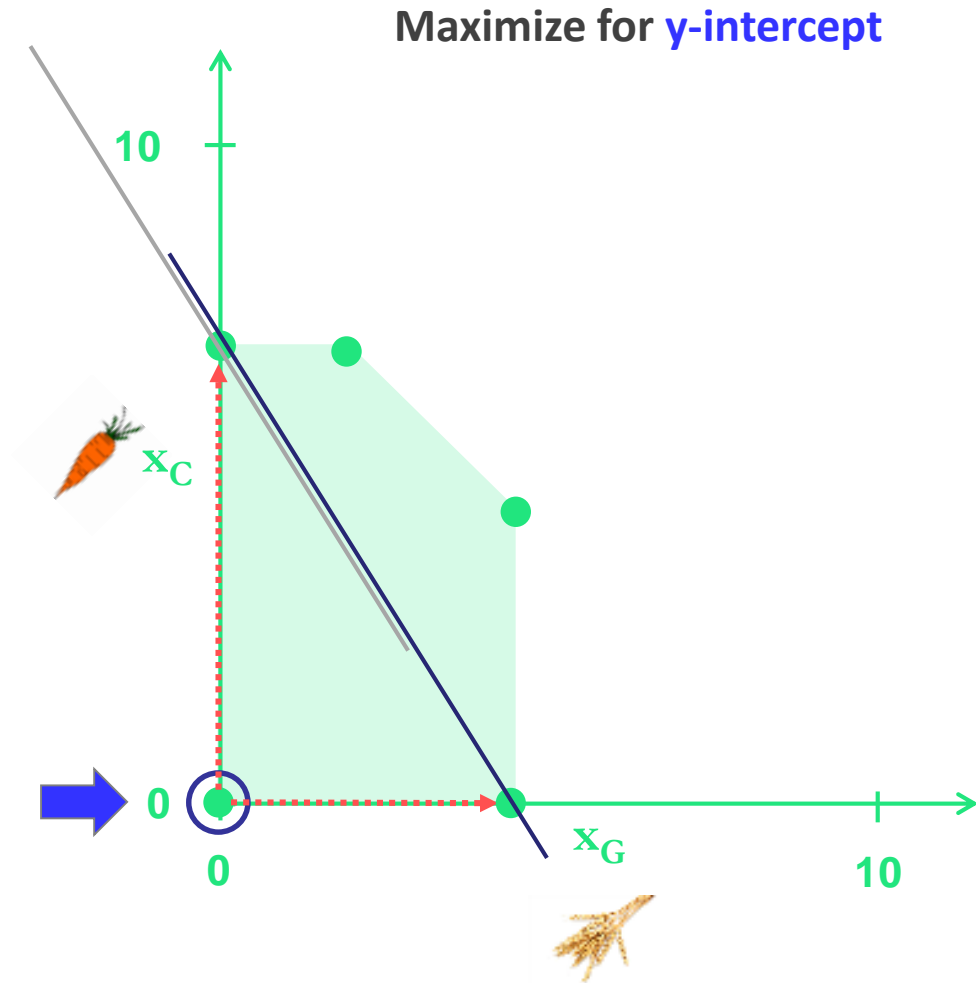
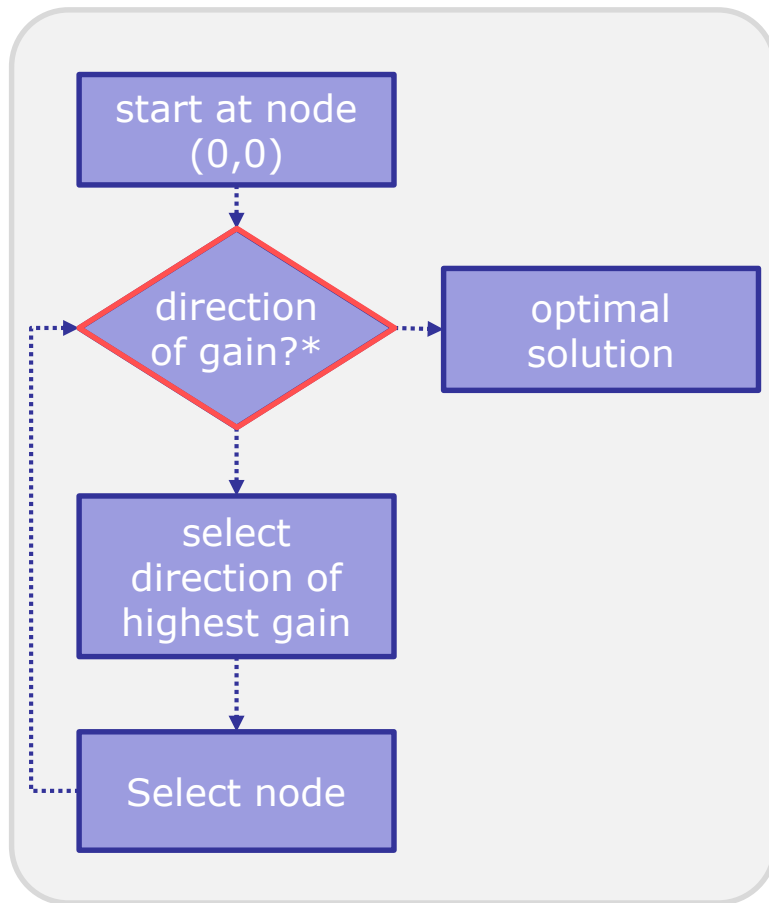
[G. Dantzig]





# Simplex Algorithm

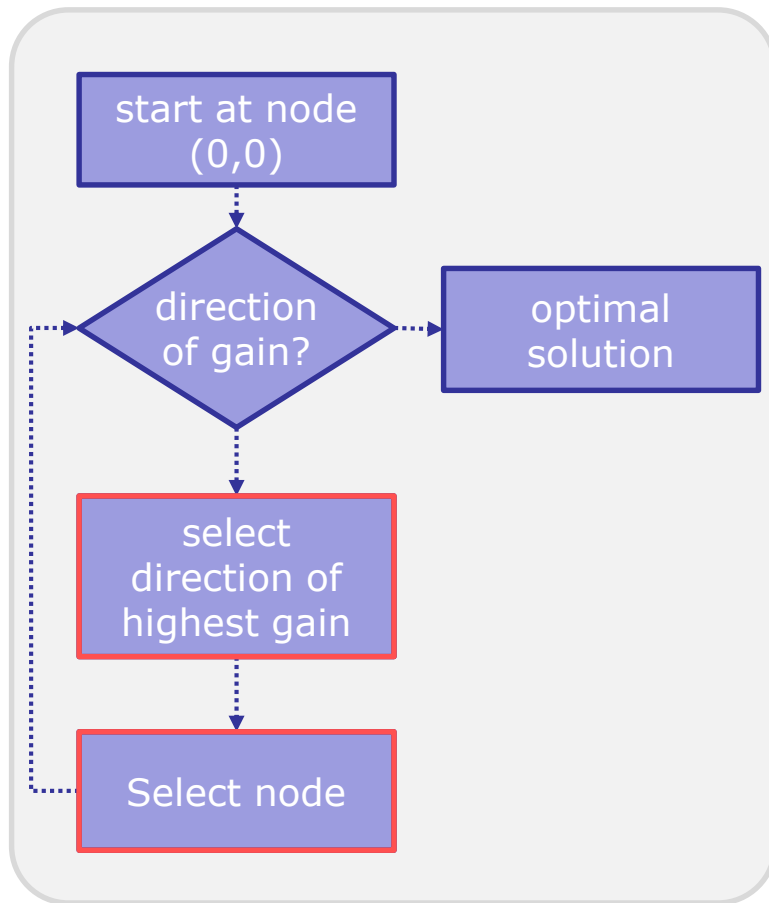
[G. Dantzig]



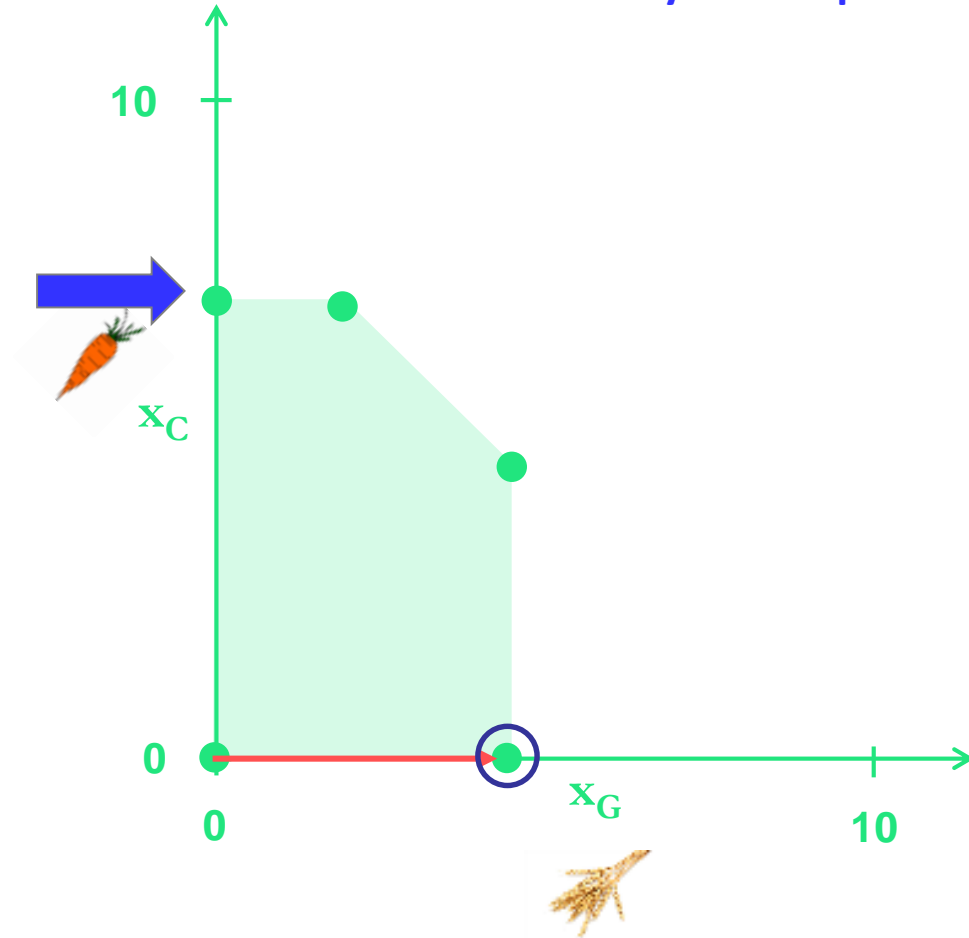
\* A move to a neighboring node which results into a better objective function value

# Simplex Algorithm

[G. Dantzig]

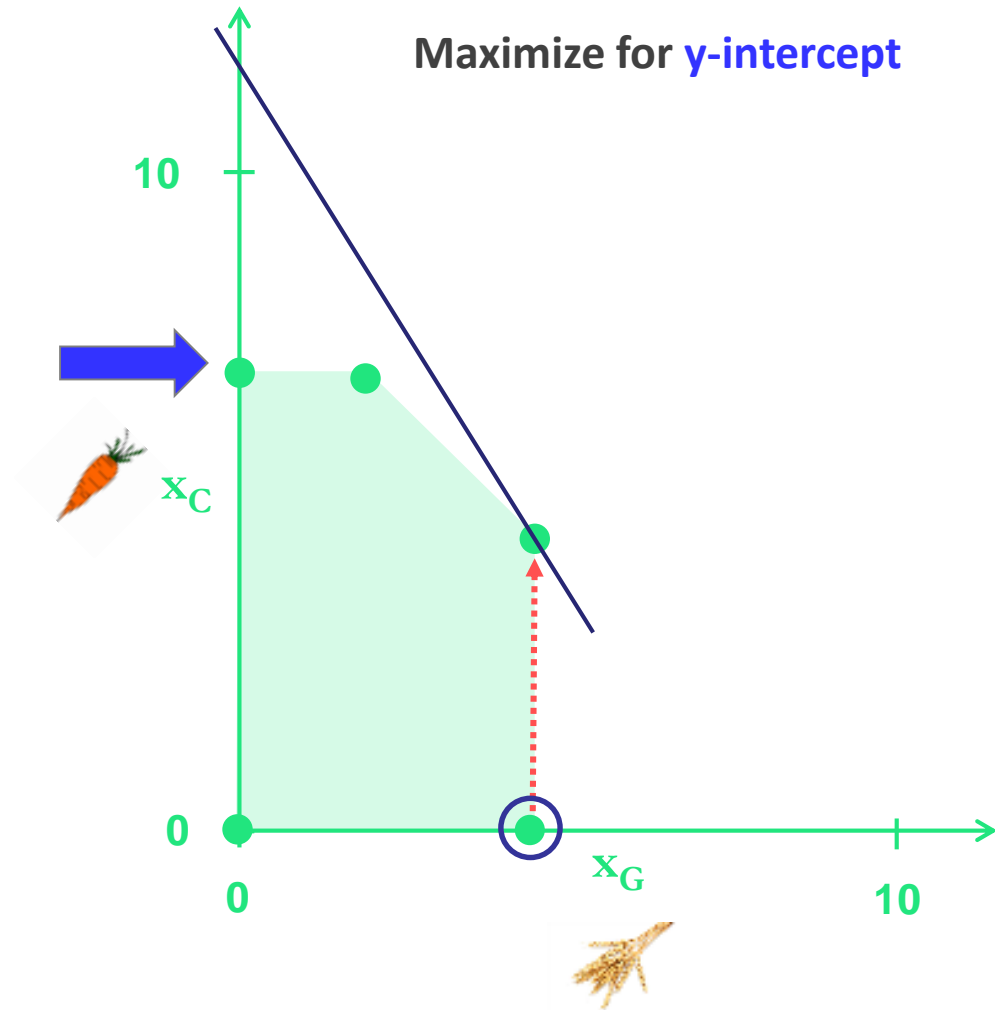
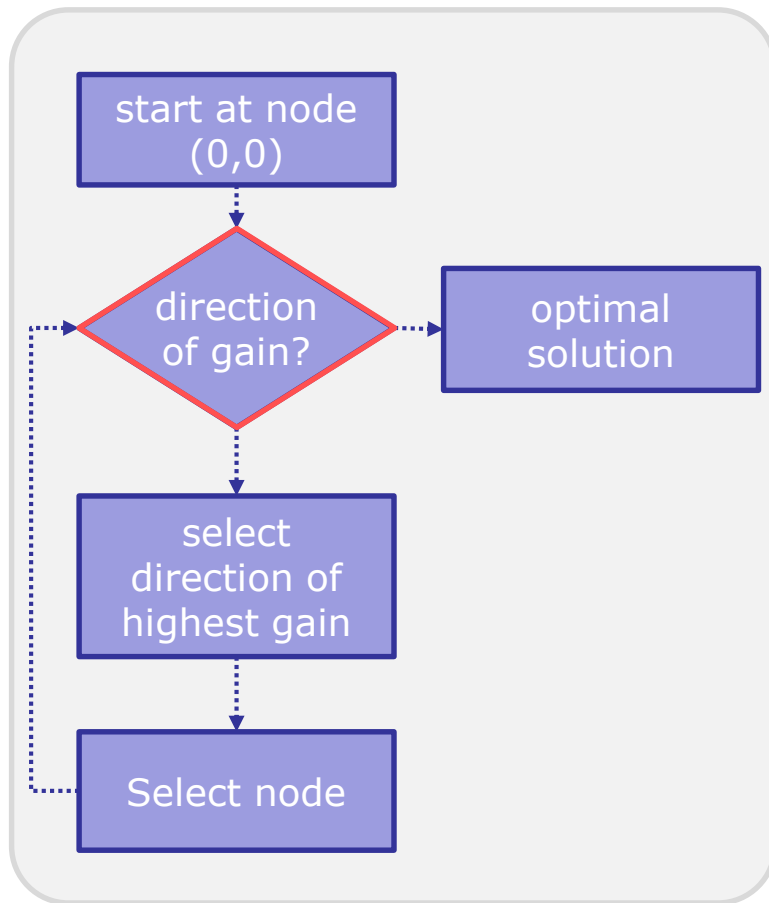


Maximize for **y-intercept**



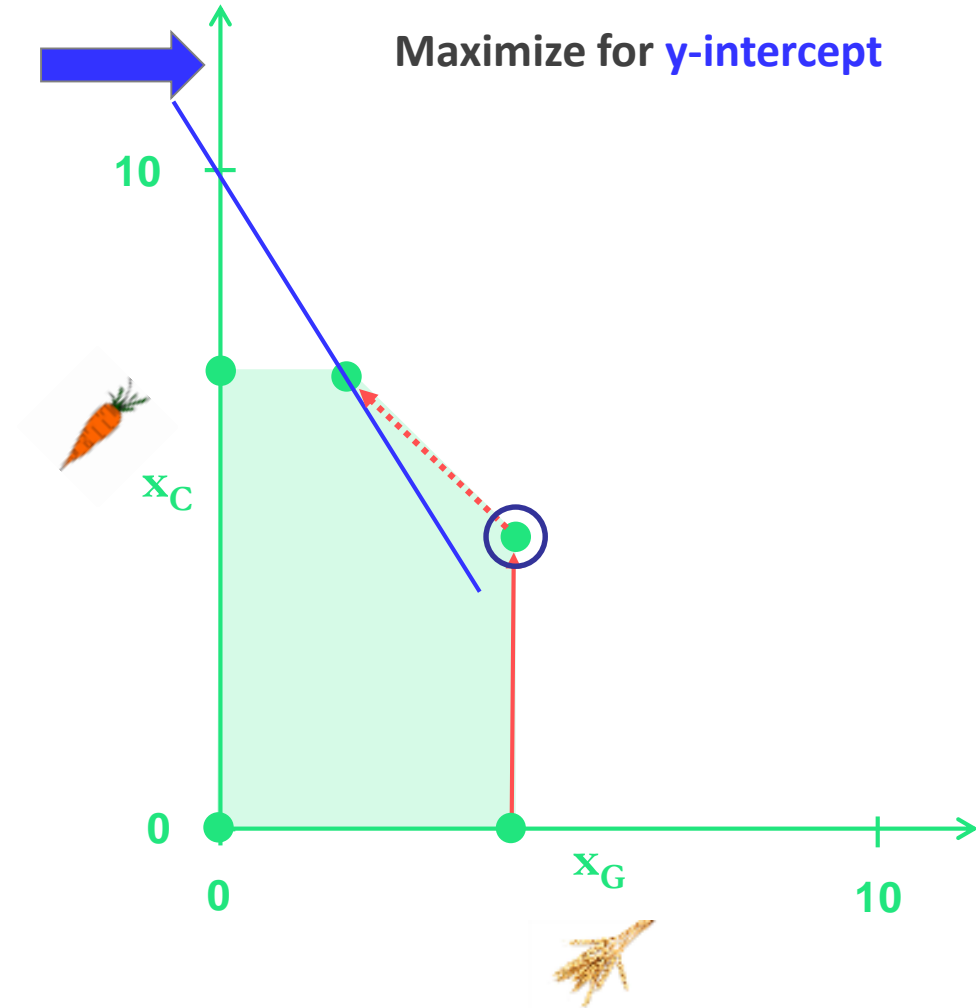
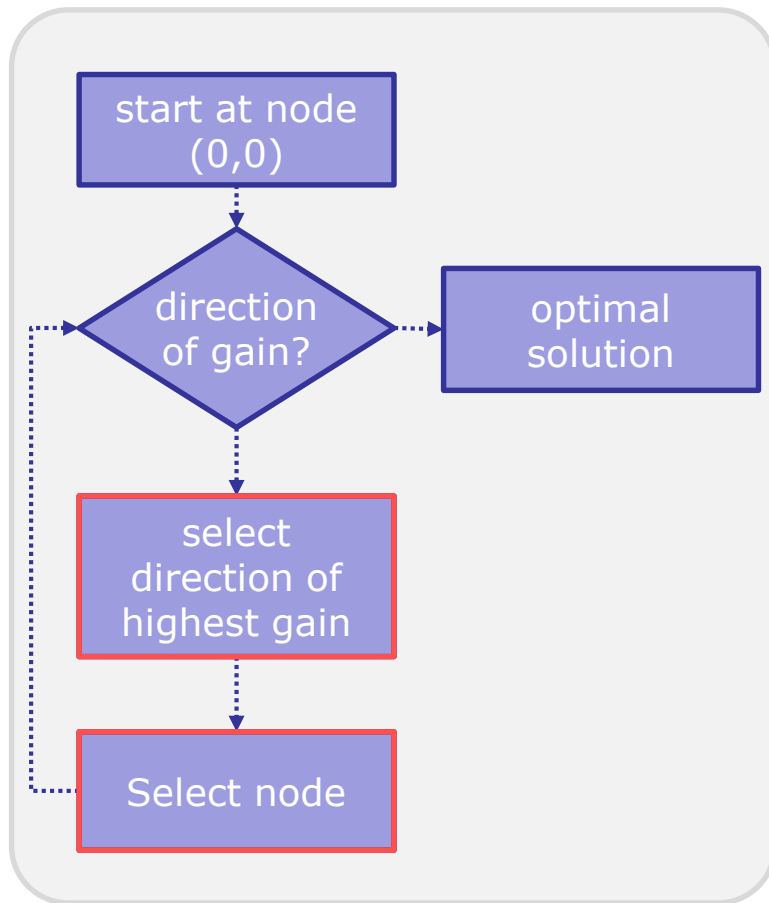
# Simplex Algorithm

[G. Dantzig]



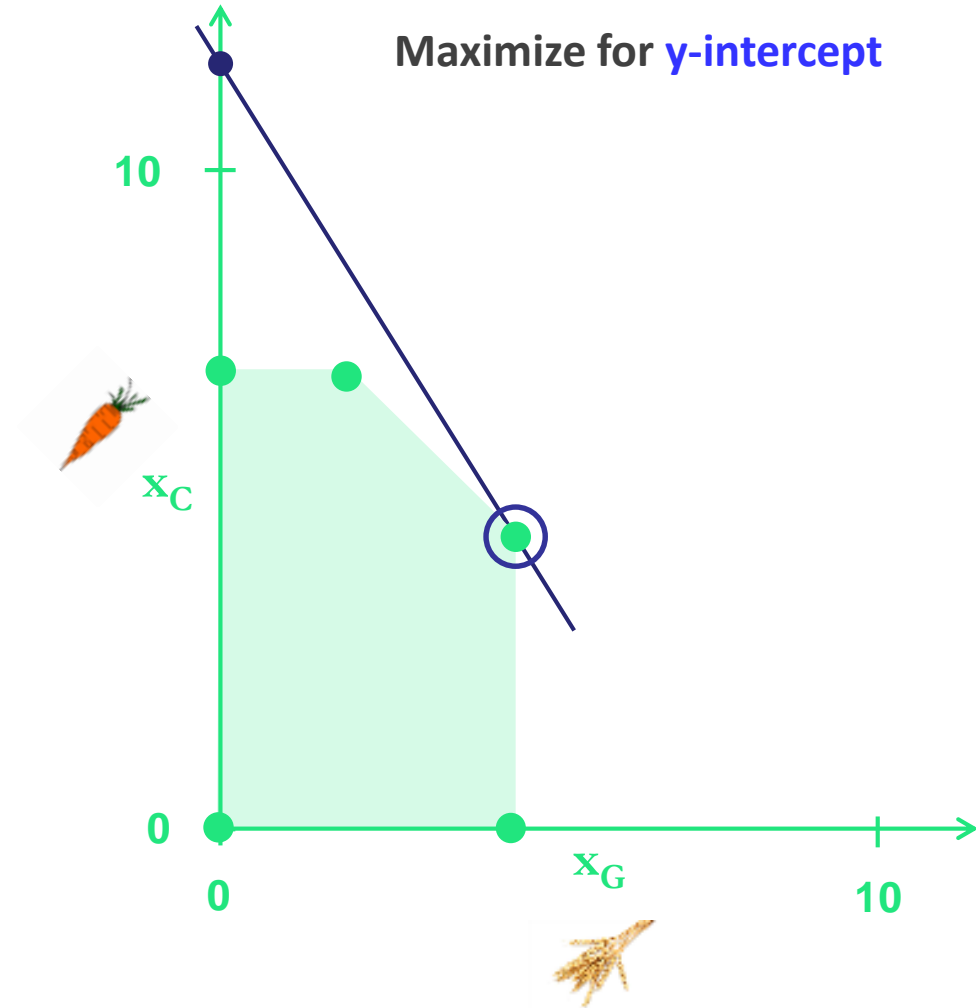
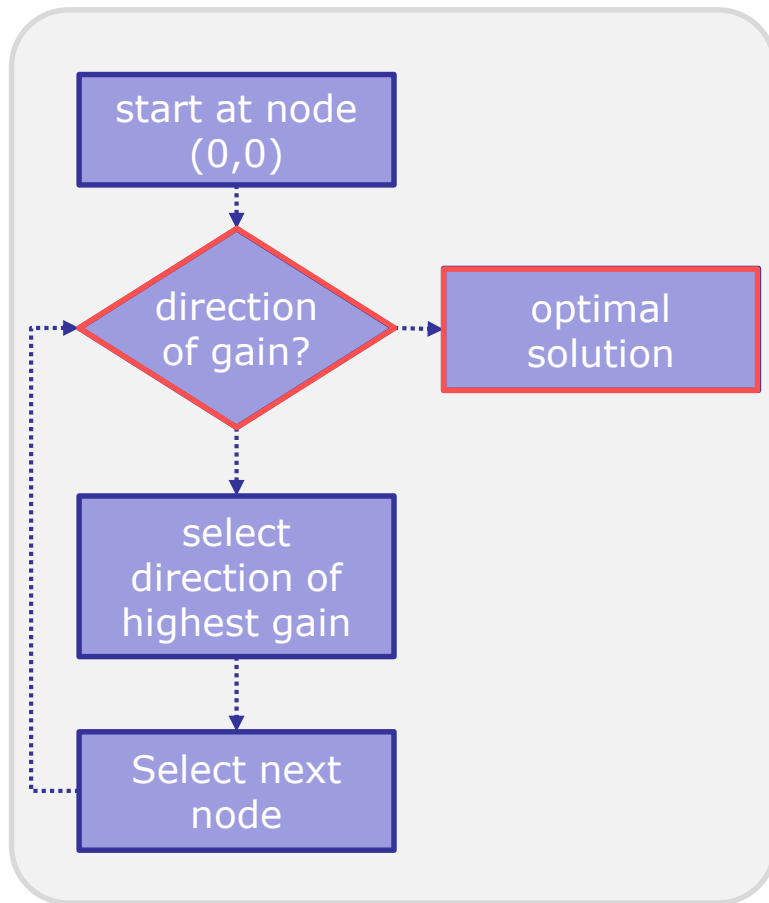
# Simplex Algorithm

[G. Dantzig]



# Simplex Algorithm

[G. Dantzig]



# Notation of an optimization model

## Linear program for the Farmer's Choice Problem

$$\text{MAX } 5000 \cdot x_C + 8000 \cdot x_G$$

$$\begin{aligned} \text{s.t.} \quad & x_C + x_G \leq 9 \\ & x_G \leq 4.5 \\ & x_C \leq 7 \\ & x_C, x_G \in R_0^+ \end{aligned}$$

add «0»  
→

$$\text{MAX } 5000 \cdot x_C + 8000 \cdot x_G$$

$$\begin{aligned} \text{s.t.} \quad & 1 \cdot x_C + 1 \cdot x_G \leq 9 \\ & 0 \cdot x_C + 1 \cdot x_G \leq 4.5 \\ & 1 \cdot x_C + 0 \cdot x_G \leq 7 \\ & x_C, x_G \in R_0^+ \end{aligned}$$

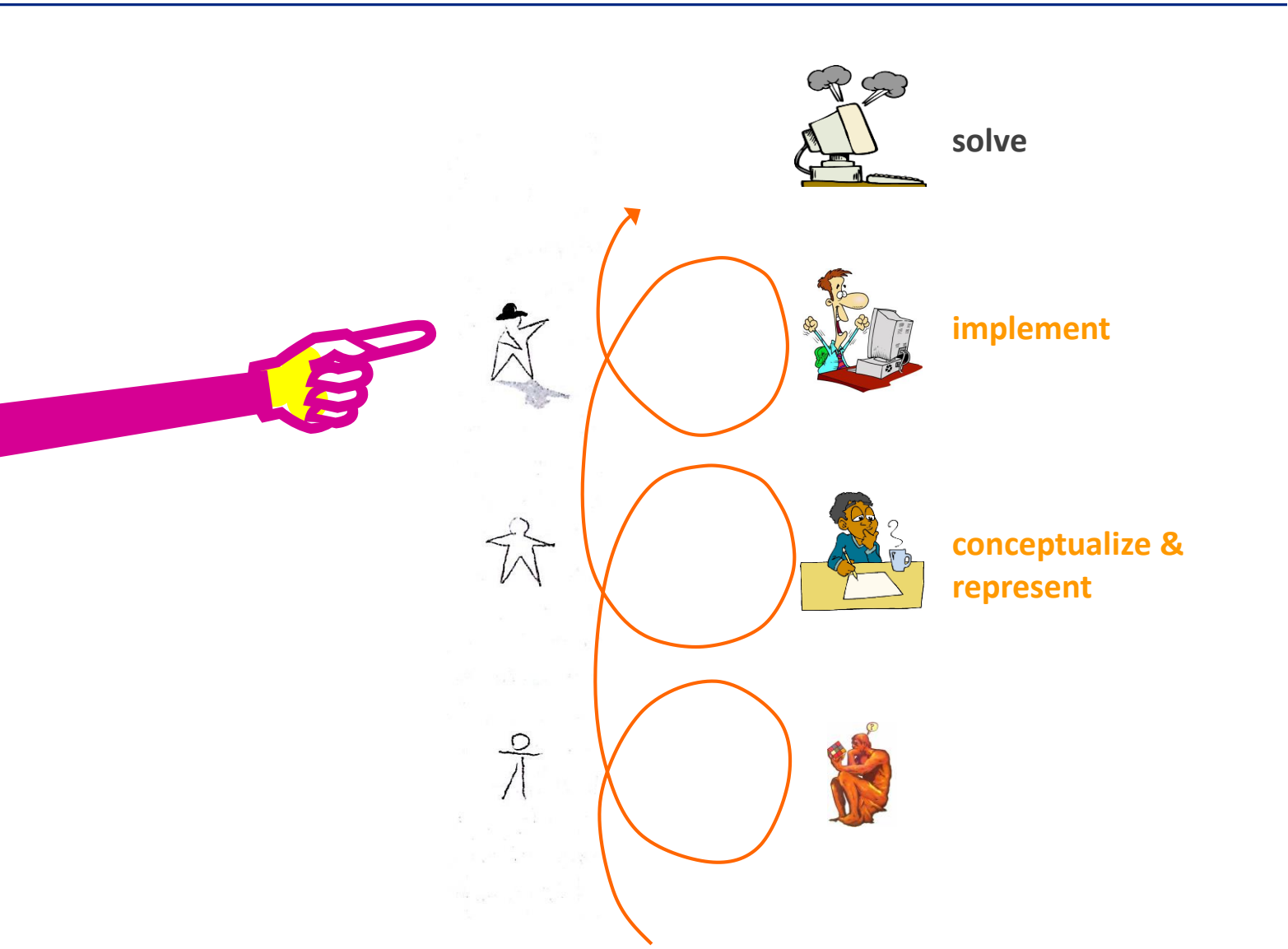
s.t. : subject to



conceptualize  
& represent



implement



THEORY

IMPLEMENTATION

EXAMPLE

# Matrix notation of an optimisation model

$$\text{MAX } 5000 \cdot x_C + 8000 \cdot x_G$$

s.t.

$$1 \cdot x_C + 1 \cdot x_G \leq 9$$

$$0 \cdot x_C + 1 \cdot x_G \leq 4.5$$

$$1 \cdot x_C + 0 \cdot x_G \leq 7$$

$$x_C, x_G \in R_0^+$$

$$\Rightarrow f = \begin{pmatrix} 5000 \\ 8000 \end{pmatrix}$$

$$x = \begin{pmatrix} x_C \\ x_G \end{pmatrix}$$

$$\Rightarrow A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{pmatrix} \leq b = \begin{pmatrix} 9 \\ 4.5 \\ 7 \end{pmatrix}$$

Computer can read this format!



$$\max_x f^T \cdot x$$

$$\text{s.t. } A \cdot x \leq b$$



# MS EXCEL – Set up of matrix notation model I

Specify  $x$ ,  $f$ ,  $A$  and  $b$

$$f = \begin{pmatrix} 5000 \\ 8000 \end{pmatrix} \quad x = \begin{pmatrix} \square \\ \square \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{pmatrix} \leq b = \begin{pmatrix} 9 \\ 4.5 \\ 7 \end{pmatrix}$$

Matrix notation model

	A	B	C	D	E	F	G	H
2		The Farmer's Choice Problem						
3								
4								
5				LHS		sum-	SIGN	RHS
6				$x_C$	$x_G$	product		
7								
8		Decision Variables	field size of C and G [ha]					$x$
9								
10		Objective Function	profit per ha of C and G [1000 CHF/ha]	5000	8000	0		$f$
11								
12		Inequality Constraints	limited total field size of C and G [ha]	1	1	0	$\leq$	9
13		(incl. bounds)	upper bound G [ha]	0	1	0	$\leq$	4.5
14			upper bound C [ha]	1	0	0	$\leq$	7

$A$

$b$

Matrix multiplication

$$\begin{aligned} \min_x \quad & f^T \cdot x \\ \text{s.t.} \quad & A \cdot x \leq b \end{aligned}$$

# Matrix multiplication I

$A \cdot x :$

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{pmatrix} \quad x = \begin{pmatrix} x_C \\ x_G \end{pmatrix}$$

①

$$C_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

②

$$C_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \circ \begin{pmatrix} x_C \\ x_G \end{pmatrix} = 1 \cdot x_C + 1 \cdot x_G$$

scalar product

③

Constraints left hand side

$$= \begin{pmatrix} 1 \cdot x_C + 1 \cdot x_G \\ 1 \cdot x_G \\ 1 \cdot x_C \end{pmatrix}$$

«sum products»

# Matrix multiplication II

$$f = \begin{pmatrix} 5000 \\ 8000 \end{pmatrix} \xrightarrow{\text{transpose}} f^T = (5000 \quad 8000)$$

$f^T \cdot x$  :

$$f^T = (5000 \quad 8000) \quad x = \begin{pmatrix} x_C \\ x_G \end{pmatrix} \quad \xrightarrow{\text{Objective function}} \quad (F) = (5000 \cdot x_C + 8000 \cdot x_G)$$
$$F = \begin{pmatrix} 5000 \\ 8000 \end{pmatrix} \circ \begin{pmatrix} x_C \\ x_G \end{pmatrix} = 5000 \cdot x_C + 8000 \cdot x_G$$

# MS EXCEL – Set up of matrix notation model II

## Implement the «scalar product»

Linear algebra convention

$$f^T = (5000 \quad 8000) \rightarrow (F)$$
$$x = \begin{pmatrix} x_C \\ x_G \end{pmatrix}$$

Diagram illustrating the linear algebra convention for the scalar product. The vector  $f^T$  is represented as a row vector  $(5000 \quad 8000)$ , and the vector  $x$  is represented as a column vector  $\begin{pmatrix} x_C \\ x_G \end{pmatrix}$ . Both are enclosed in dashed orange boxes. An arrow points from the  $(F)$  box to the  $(F)$  box in the Excel table below.

Excel convention

$x =$   
 $f =$

	D	E	F	G	H
5	LHS		sum-	SIGN	RHS
6	$x_C$	$x_G$	product		
7					
8					
9					
10	5000	8000	(F)		
11					
12	1	1	0	≤	9
13	0	1	0	≤	4.5
14	1	0	0	≤	7

Diagram illustrating the Excel convention for the scalar product. The vector  $x$  is represented by the range D8:E8 (green cells), and the vector  $f$  is represented by the range D10:E10 (blue cells). The result of the scalar product is shown in cell F10, labeled (F). A dashed orange box highlights the range D8:E8. A dotted arrow points from the formula bar to the range D8:E8.

=sumproduct(D8:E8;D10:E10)

# MS Excel – Solve the model

	A	B	C	D	E	F	G	H
1								
2		The Farmer's Choice Problem						
3								
4								
5				LHS		sum-		RHS
6				$x_C$	$x_G$	product	SIGN	
7								
8		Decision Variables	field size of C and G [ha]					
9								
10		Objective Function	profit per ha of C and G [1000 CHF/ha]	5000	8000	0		
11								
12		Inequality Constraints	limited total field size of C and G [ha]	1	1	0	≤	9
13		(incl. bounds)	upper bound G [ha]	0	1	0	≤	4.5
14			upper bound C [ha]	1	0	0	≤	7

Change Constraint

Cell Reference:  Constraint:

OK Add Cancel

Define the «sign»

## DATA tab ➡ SOLVER

Solver Parameters

Set Objective:

To: ☒ Max ☐ Min ☐ Value Of:

By Changing Variable Cells:

Subject to the Constraints:

Add Change Delete Reset All Load/Save

☒ Make Unconstrained Variables Non-Negative

Select a Solving Method:  Options

Solving Method

Select the GRG Nonlinear engine for Solver Problems that are smooth nonlinear. Select the LP Simplex engine for linear Solver Problems, and select the Evolutionary engine for Solver problems that are non-smooth.

Help Solve Close

# MS Excel – Optimization result

	A	B	C	D	E	F	G	H	I	J	K	L	M	N
1														
2		The Farmer's Choice												
3														
4														
5														
6				LHS		sum-								
7				$x_C$	$x_G$	product	SIGN							
8	Decision Variables	field size of C and G [ha]		4.5	4.5									
9														
10	Objective Function	profit per ha of C and G [1000 CHF/ha]		5000	8000	58500								
11														
12	Inequality Constraints (incl. bounds)	limited total field size of C and G [ha]		1	1	9	≤	9						
13		upper bound G [ha]		0	1	4.5	≤	4.5						
14		upper bound C [ha]		1	0	4.5	≤	7						
15														
16														
17														
18														
19														
20														
21														
22														
23														
24														
25														

Solver Results

Solver found a solution. All Constraints and optimality conditions are satisfied.

☒ Keep Solver Solution
 ☐ Restore Original Values

☐ Return to Solver Parameters Dialog
 ☒ Outline Reports

OK

Cancel

Save Scenario...

Solver found a solution. All Constraints and optimality conditions are satisfied.

When the GRG engine is used, Solver has found at least a local optimal solution. When Simplex LP is used, this means Solver has found a global optimal solution.

Reports

Answer

Sensitivity

Limits

# MATLAB - Set up of matrix notation model I

Provide the information that Matlab needs to understand the optimization model!

Matrix notation model

$$f = \begin{pmatrix} 5000 \\ 8000 \end{pmatrix} \quad x = \begin{pmatrix} x_C \\ x_G \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{pmatrix} \leq b = \begin{pmatrix} 9 \\ 4.5 \\ 7 \end{pmatrix}$$



MATLAB syntax

$$f = \begin{pmatrix} 5000 \\ 8000 \end{pmatrix} \quad xType = \begin{pmatrix} 'C' \\ 'C' \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{pmatrix} \quad sign = \begin{pmatrix} -1 \\ -1 \\ -1 \end{pmatrix} \quad b = \begin{pmatrix} 9 \\ 4.5 \\ 7 \end{pmatrix}$$

Number type *xType*

Real number 'C'

Integer 'I'

Binary (0;1) 'B'

Signum *sign*

$\leq$  -1

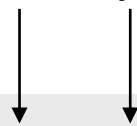
$=$  0

$\geq$  +1

# MATLAB – Set up and solve the model with two lines of code

solves MINIMIZATION problems only ➡ set **-f** for MAXIMIZATION

type    input



```
% Set up model
OptiModel = opti('f', -f, 'mix', A, b, sign, 'xType', xType);

% Solve model
[x, F] = solve(OptiModel);
```

**x** =  
4.5000  
4.5000

decision variables

**F** =  
-58500

obj. function value

detailed description >> see assignment document!



# Literature

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Lecture notes *System Modeling and Optimization* by Prof. H.-J. Lüthi, IFOR, ETH Zürich (2011)

- *3 Modeling Linear Problems* [definitions, representation]
- *4 Solving Linear Programs* [Excel-Solver]

OPTI TOOLBOX website: <http://www.i2c2.aut.ac.nz/Wiki/OPTI/>

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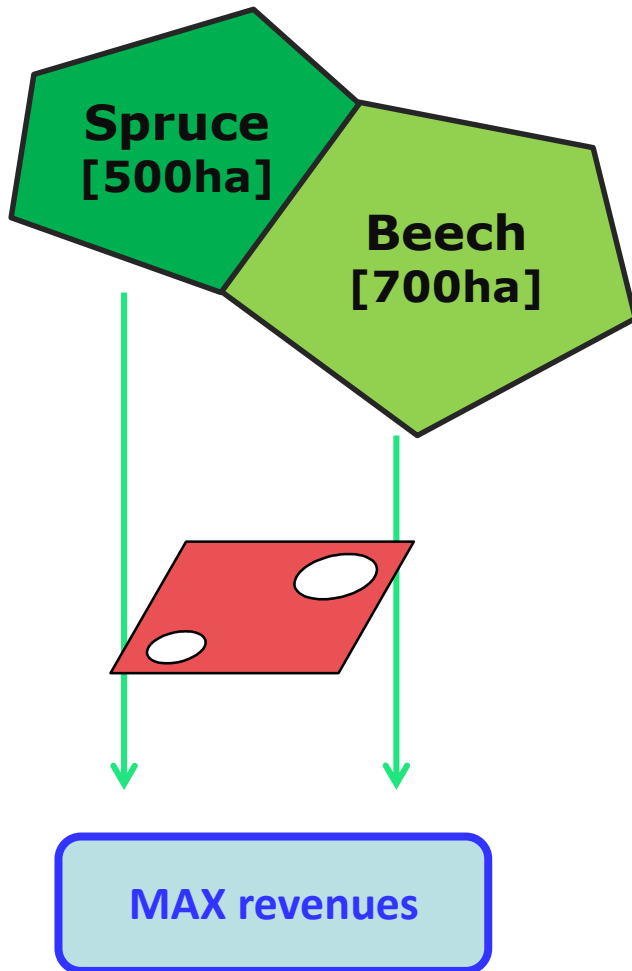
**- C -**

## **Exercise 5**

# **Product Portfolio Problem**

# Problem

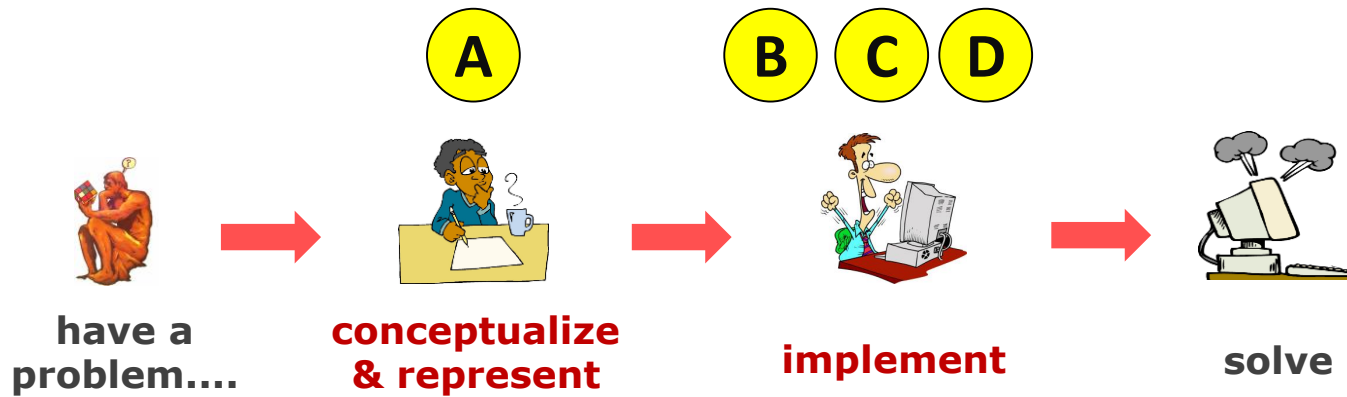
A forest company would like to plan the harvest for their forest stands of two qualities, spruce and beech trees, for the upcoming year in order to **maximize the revenues** from timber sale.



## Constraints:

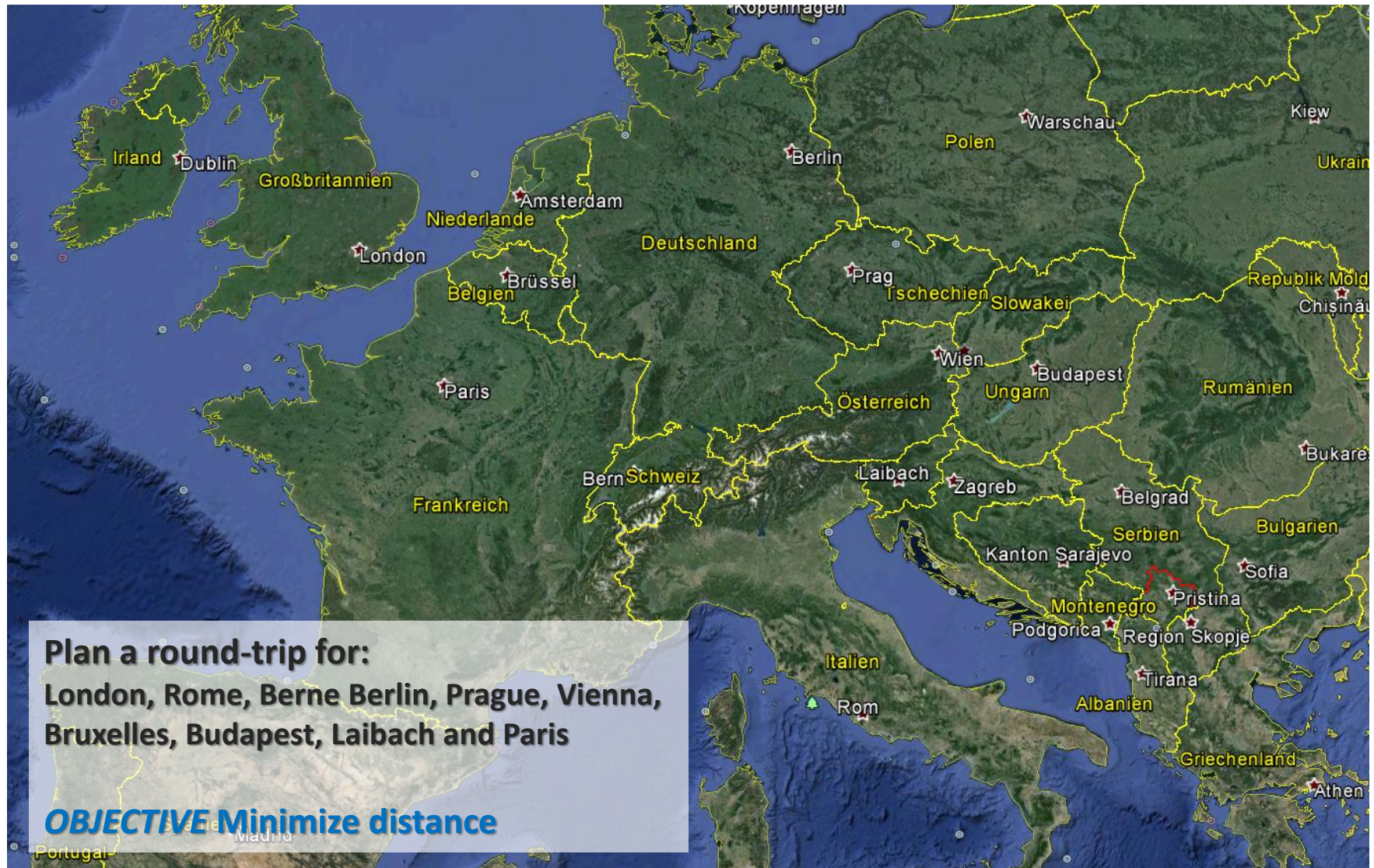
- 1) Maximum harvested volume is limited to sustainable yield
- 2) labor force of the company for a year is limited to 1'800h.

# Tasks



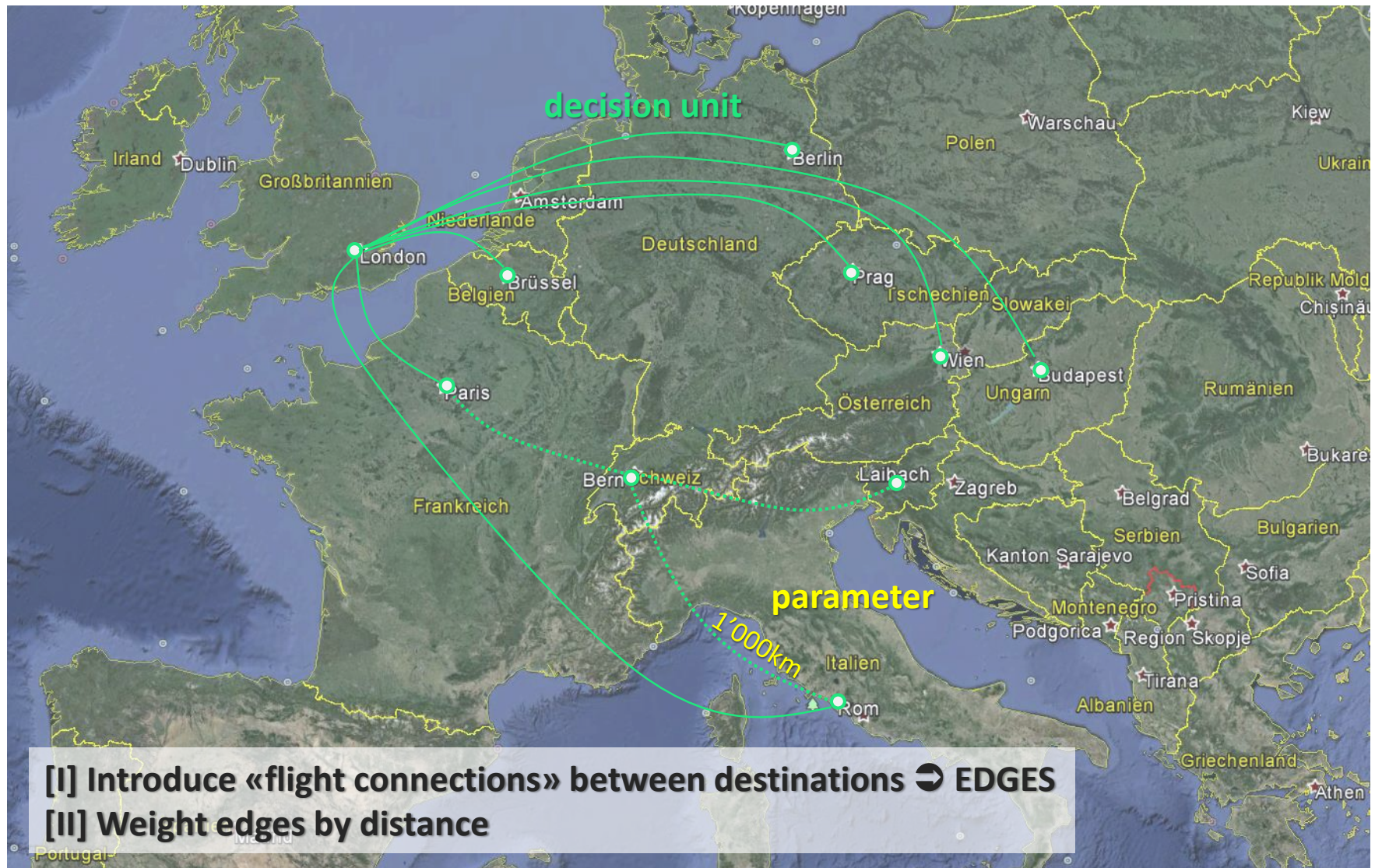
- A** Formulate a Linear Program (LP)
- B** Solve the LP graphically
- C** Implement the LP in Excel and solve it using the Solver Add-in
- D** Implement the LP in MATLAB using the OPTI toolbox

# A warm-up for REPRESENTATION



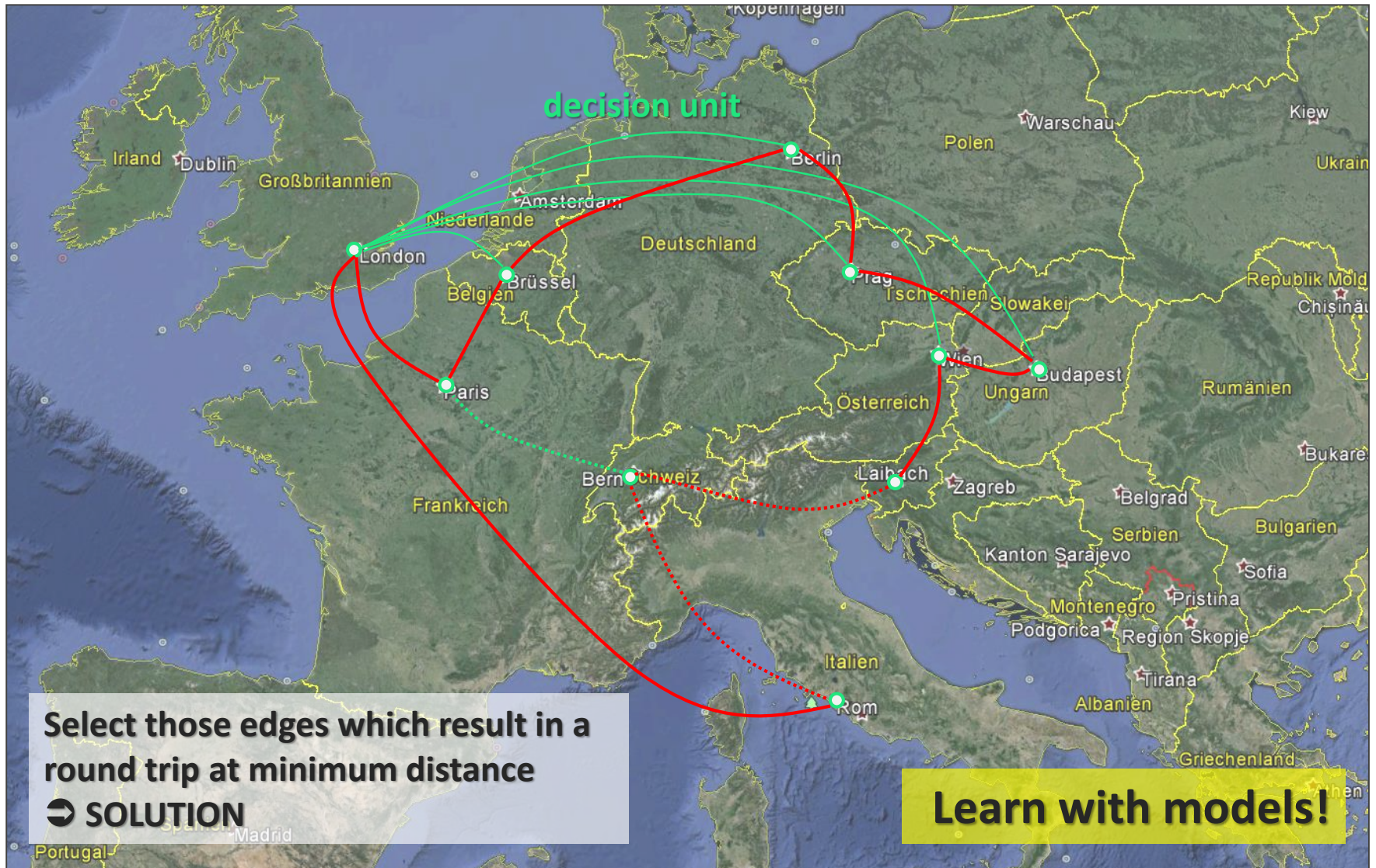


# Problem Representation





# Solution





# FS - Application to the «round trip problem»

