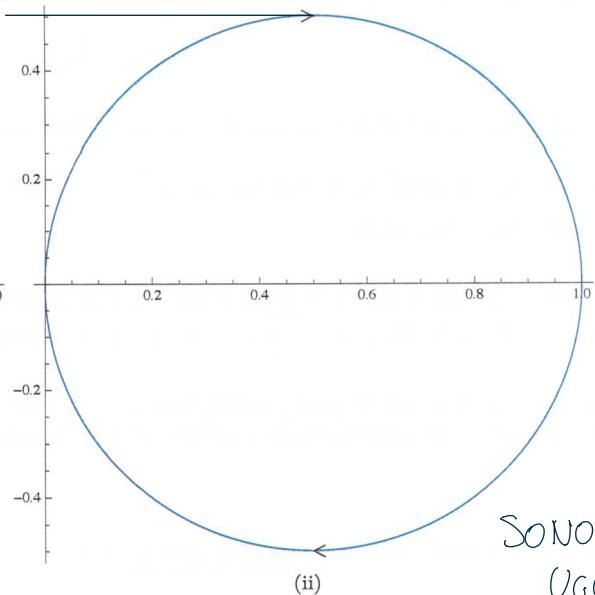
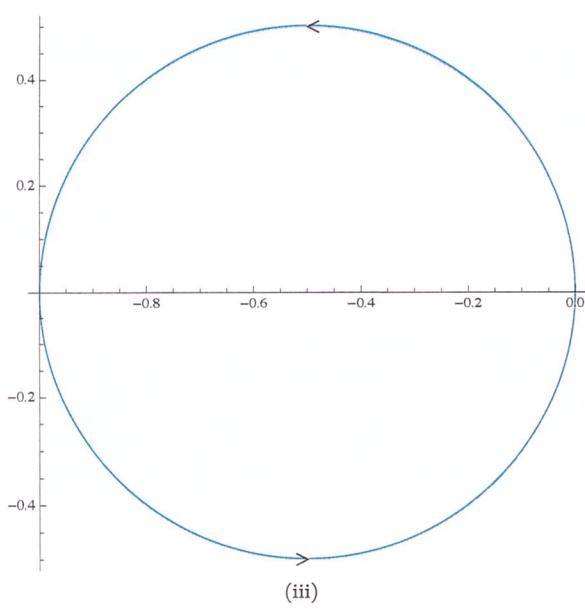


(i)

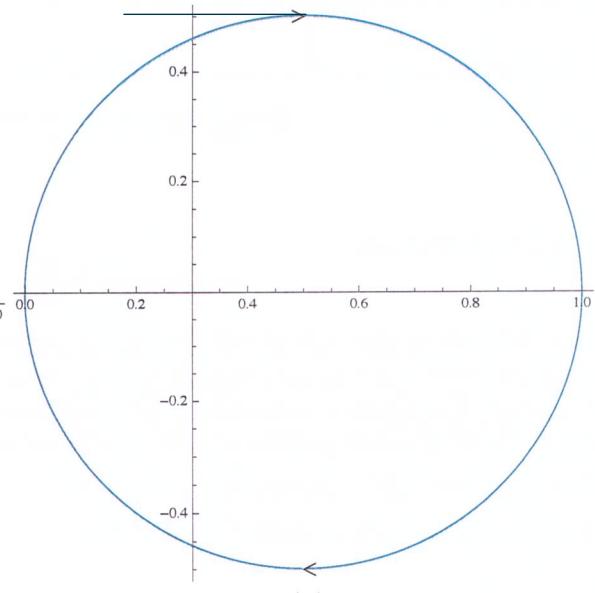


(ii)

SONO LETTERALMENTE  
UGUALI



(iii)



(iv)

### ESERCIZIO 2.

Si abbinino le funzioni di trasferimento con i corrispondenti diagrammi di Nyquist riportati nelle figure:

	5 punti
--	---------

- |     |                        |   |
|-----|------------------------|---|
| I   | $L(s) = \frac{s}{s-1}$ | ✓ |
| II  | $L(s) = \frac{s}{s+1}$ | ✗ |
| III | $L(s) = \frac{1}{s-1}$ | ✓ |
| IV  | $L(s) = \frac{1}{s+1}$ | ✗ |

(A) Fig. (ii)

(B) Fig. (iv)

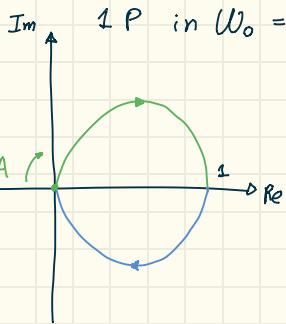
(C) Fig. (iii)

(D) Fig. (i)

$$X \quad L(s) = \frac{s}{s+1}$$

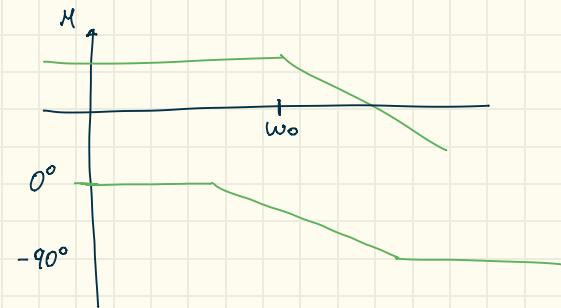
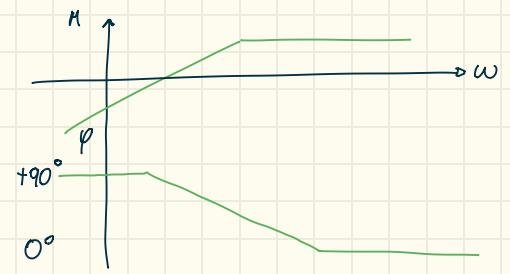
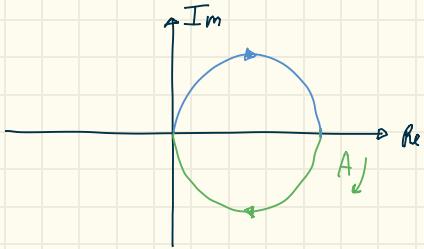
$$\omega \rightarrow 0 \quad M=0$$

$$1 \text{ Z in } O \Rightarrow M_0 = +20 \text{ dB/dec} \quad \phi_0 = +90^\circ \quad \mu_0 = 1 > 0 \Rightarrow \phi_0 = +90^\circ$$



$$X \quad L(s) = \frac{1}{s+1}$$

$$1 \text{ P in } W_0 \Rightarrow M_{W_0} = -20 \text{ dB/dec} \quad \phi_{W_0} = -90^\circ$$



$$L(s) = \frac{s^2 + 4s + 9}{(s-1)(s-10)^2}$$

1) C.Trasf  $\lim_{S \rightarrow \infty} S^2 L(S) = \frac{9}{-1 \cdot 100} = -0.09 < 0 \rightarrow$  Inizio da sx

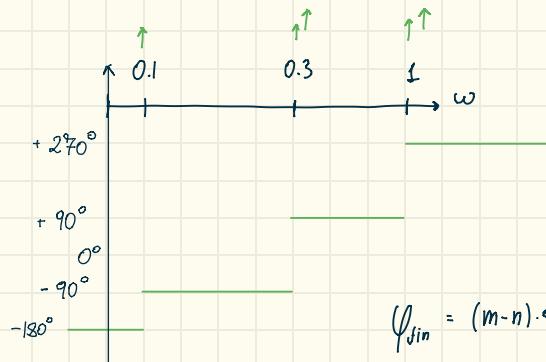
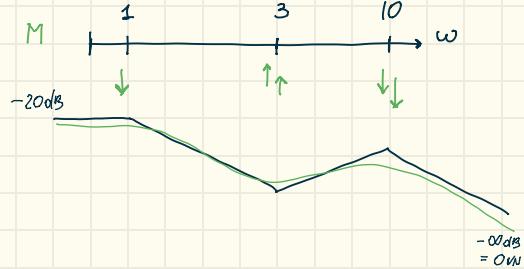
Zeri:  $\begin{cases} \bar{Z}_1 = -2 - \sqrt{5}j \\ \bar{Z}_2 = -2 + \sqrt{5}j \end{cases} \Rightarrow \text{Re}P < 0$   
 $\approx \omega_n = \sqrt{9} = 3 \text{ Rad/S}$

$\Rightarrow M_{\omega_n} = +40 \text{ dB/dec}$   
 $\varphi_{\omega_n} = +180^\circ \quad (90^\circ/\text{dec})$

$M_0 = |-0.09|_{\text{dB}} \approx -20 \text{ dB}$

Poli:  $\begin{cases} P_1 = 1 & \text{Re}P > 0 \quad \omega_1 = 1 \text{ Rad/S} \\ P_{2,3} = -10 & \text{Re}P > 0 \quad \omega_{2,3} = 30 \text{ Rad/S} \end{cases}$

$M_{\omega_1} = -20 \text{ dB/dec}$   
 $\varphi_{\omega_1} = +90^\circ$   
 $M_{\omega_2} = -40 \text{ dB/dec}$   
 $\varphi_{\omega_{2,3}} = +180^\circ$

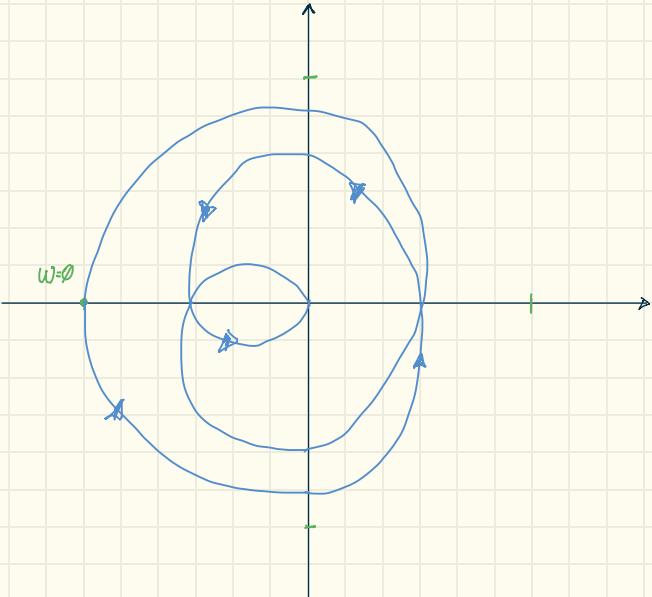


! Rispetto a  $180^\circ$

$$\varphi_{\text{fin}} = (m-n) \cdot 90^\circ = 5 \cdot 90^\circ = 450^\circ$$

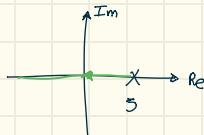
ma portalo da  $-180^\circ \rightarrow -180 + 450^\circ = 270^\circ$

! Rispetto  $0^\circ$ !



## • Luogo delle Radici

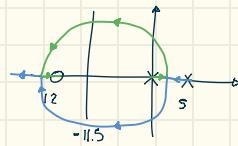
$$G(s) = \frac{1}{s-5}$$



Q:  $T_{01} < 0.4s$

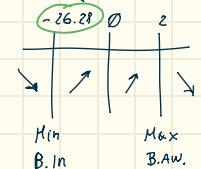
$e_T < 10\%$

$$\frac{4.6}{\sigma} < 0.4 \Rightarrow \sigma > \frac{4.6}{0.4} = 11.5$$



$$f(x) = -\frac{D(x)}{N(x)} = \frac{-(x^2 - 5x)}{x + 12} \Rightarrow f'(x) = -(2x - 5)(x + 12) + (x^2 - 5x) > 0$$

$$-2x^2 - 24x + 60 > 0 \text{ per } x > -26.28 \quad x < 2.28$$



$$C(s) = \frac{K(s+12)}{s} \Rightarrow C'(s) = \frac{K(s+12)}{s(s-5)}$$

$$|K| = \frac{|D(s^*)|}{|N(s^*)|} = \frac{[(s^*)^2 - 5s^*]}{s^* + 12} = 57.57$$

$$\mu = \lim_{s \rightarrow 0} \frac{|K(s+12)|}{|s(s-5)|} = K \cdot \frac{12}{-5} = -2.4K \Rightarrow e_T = \left| \frac{1}{\mu} \right| = \left| \frac{1}{-2.4K} \right| < 0.1 \Rightarrow K > \frac{1}{0.1 \cdot 2.4} \Rightarrow K > 4.16$$

$$\Rightarrow \text{Prendo } K = 58 \Rightarrow C(s) = \frac{58(s+12)}{s} \quad \text{Ans}$$

## • Perche' si sceglie il margine critico Negativo?

### Progetto in frequenza

#### ESERCIZIO 1.

Si consideri la funzione di trasferimento

$$G(s) = k \cdot \frac{s-9}{s(s+9)}$$

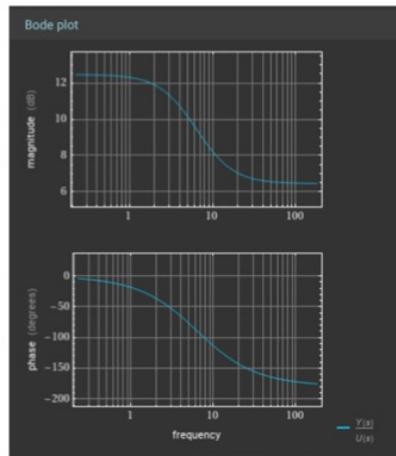
5 punti
---------

e si scelga il guadagno  $k \in \mathbb{R}$  in maniera tale che  $G(s)$  abbia un margine di fase pari a  $40^\circ$ .

Per avere  $\varphi_m = 40^\circ \Rightarrow 180 - \varphi_c = 40^\circ \Rightarrow \varphi_c = 140^\circ \Rightarrow \varphi_c = \pm 140^\circ \Rightarrow \varphi_c = -140^\circ$

$$\begin{aligned} & \omega_c \\ & |G(j\omega_c)| = 1 \text{ per } \frac{k\sqrt{\omega_c^2 + 81}}{\omega_c\sqrt{\omega_c^2 + 81}} = 1 \Rightarrow \omega_c = K \end{aligned}$$

$$\begin{aligned} & \angle G(j\omega_c) = -140^\circ \Rightarrow \angle K + \angle j\omega_c - 90^\circ - \angle j\omega_c + 90^\circ = -\alpha \tan\left(\frac{\omega_c}{9}\right) - 90^\circ - \alpha \tan\left(\frac{\omega_c}{9}\right) = -140^\circ \\ & \Rightarrow -2\alpha \tan\left(\frac{\omega_c}{9}\right) = -50 \Rightarrow \alpha \tan\left(\frac{\omega_c}{9}\right) = 25^\circ \Rightarrow \omega_c = 9 \tan(25^\circ) = 4.197 \\ & \Rightarrow |K| = \pm 4.2 \text{ ma } \mu = \lim_{s \rightarrow 0} s \frac{|K(s+9)|}{|s(s+9)|} = -K \text{ ma voglio } \mu > 0 \Rightarrow K < 0 \Rightarrow K = -4.2 \end{aligned}$$



## 2. MARGINE DI AMPIEZZA Con scelto di guadagno e zero

OPPOSTO AL POLO

$$G(s) = K \frac{(s+2)}{(s+5)^2}$$

scelgo  $Z = -5$   $\Rightarrow G(s) = \frac{K(s-5)}{(s+5)^2}$

vogliamo  $M_a = 6 \text{ dB} = 10^{\frac{6}{20}} = (2) \text{ dB}$   
vogliamo  $K < 0$

Siccome cerco il margine di ampiezza, devo trovare la  $w_c$  per la quale  $\angle G(jw_c) = -180^\circ$

Dopo calcolo  $|G(jw_c)|$  e vedo quanto differisce  $(1) \text{ dB} = 0 \text{ dB}$

### 1) Guadagno

$$\mu = \lim_{s \rightarrow 0} s^2 \cdot G(s) = \lim_{s \rightarrow 0} \frac{K(s-5)}{(s+5)^2} = -\frac{5}{25} K$$

Vogliamo un guadagno  $\mu > 0 \Rightarrow K < 0$

### 2) Trovo $w_c$

$$\angle G(jw_c) = -180^\circ = -\pi \Rightarrow \angle K(jw-5) - \angle (jw+5)^2 = -\pi \Rightarrow -\text{atan}\left(\frac{-w}{5}\right) - 2\text{atan}\left(\frac{w}{5}\right) = -\pi$$

$$\Rightarrow -3\text{atan}\left(\frac{w}{5}\right) = -\pi \Rightarrow 3\text{atan}\left(\frac{w_c}{5}\right) = \pi \Rightarrow \frac{w_c}{5} = \tan\left(\frac{\pi}{3}\right) \Rightarrow w_c = 5\tan\left(\frac{\pi}{3}\right) = 8.66 \text{ rad/s} = 5\sqrt{3} \text{ rad/s}$$

$w_c$

### 3) Modulo in $w_c = 5\sqrt{3} \text{ rad/s}$

$$|G(jw_c)| = \frac{|K(jw_c-5)|}{|(jw_c+5)^2|} = \frac{|K|\sqrt{w_c^2 + 5^2}}{w_c^2 + 25} \quad \text{per} \quad K = \frac{2(w_c^2 + 25)}{\sqrt{w_c^2 + 5^2}} = 20$$

Per trovare  $K$ :  $\frac{1}{|G(jw_c)|} = (M_a) \text{ dB}$  oppure  $\frac{1}{|G(jw_c)|} \text{ dB} = M_a \text{ dB}$

$$\Rightarrow \frac{1}{|G(jw_c)|} = \frac{w_c^2 + 25}{|K|\sqrt{w_c^2 + 5^2}} = 2 \quad \text{per} \quad |K| = \frac{w_c^2 + 25}{2\sqrt{w_c^2 + 25}} = \frac{75 + 25}{2\sqrt{100}} = 5$$

Quindi  $|K| = \begin{cases} K > 0 \Rightarrow K = 5 \\ K < 0 \Rightarrow K = -5 \end{cases}$  Scelgo  $K < 0$  perché mi serve  $\mu > 0$

$\Rightarrow G(s) = -\frac{s(s-5)}{(s+5)^2}$  Ans

NEW ↓

• Posso usare due controllori in cascata in modo da lavorare sul luogo diretto

### Luogo delle radici

#### ESERCIZIO 1.

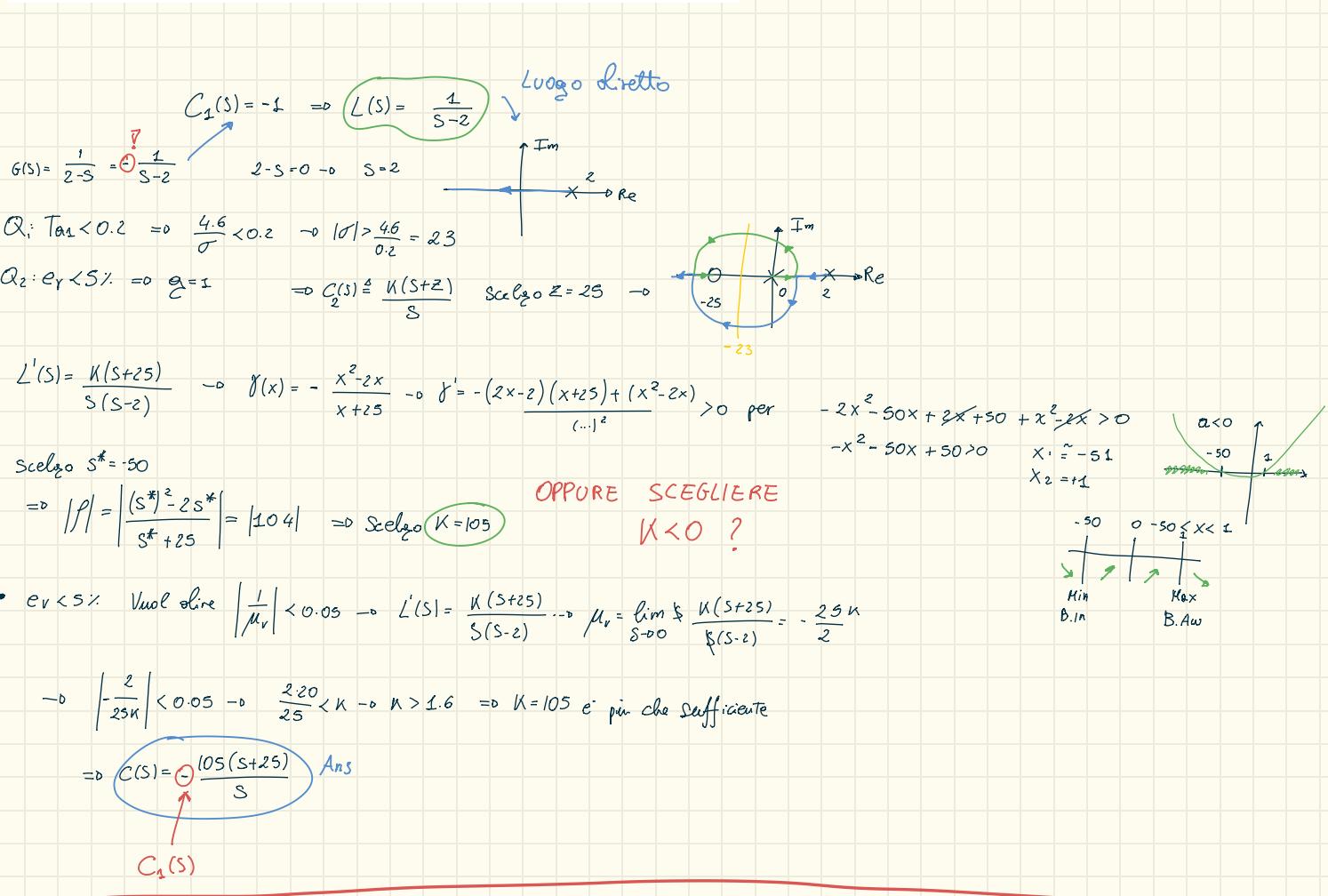
Si consideri l'impianto descritto dalla funzione di trasferimento

$$G(s) = \frac{1}{2-s}$$

e si progetti un controllore  $C(s)$  tale che, in uno schema con retroazione negativa unitaria, si garantisca:

- risposta indiciale con tempo di assettamento  $T_a$  all'1% inferiore a 0.2s;
- errore di velocità inferiore al 5%.

5 punti



errata, viene sottratto un quarto del suddetto punteggio. Se non è indicata alcuna risposta, vengono assegnati zero punti.

$$s^2 + 2\xi w_n s + w_n^2 \text{ se } \xi < -1 \quad \Delta = \sqrt{4\xi^2 w_n^2 - 4w_n^2} = 2w_n \sqrt{\xi^2 - 1} \quad \Rightarrow x_{1,2} = \frac{(-2\xi w_n) \pm (2w_n \sqrt{\xi^2 - 1})}{2} \quad \text{sicuramente ma } 2\xi w_n > 2w_n \sqrt{\xi^2 - 1} \Rightarrow \text{poli a ReP} > 0$$

1. (1 punto) Un polinomio caratteristico del secondo ordine con coefficiente di smorzamento  $\xi < -1$  presenta:

- (a) Due poli reali e distinti entrambi negativi
- (b) Due poli reali e distinti entrambi positivi
- (c) Due poli reali coincidenti
- (d) Due poli complessi e coniugati a parte reale negativa
- (e) Due poli complessi e coniugati a parte reale positiva

3. (2 punti) Si consideri un sistema di controllo con retroazione negativa unitaria dove la funzione di anello è  $L(s) = \frac{380}{(s+19)(s+4)(s+5)}$ . Si determini il margine di fase.

- (a)  $-38^\circ$
- (b)  $38^\circ$
- (c)  $180^\circ$
- (d)  $\infty$
- (e)  $0$

5 punti

ESERCIZIO 2. Si tracci il diagramma di Nyquist della f.d.t.

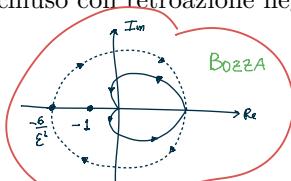
$$L(s) = 2 \frac{s+3}{s^2(s-1)}.$$

Si dica se il corrispondente sistema a ciclo chiuso con retroazione negativa unitaria è asintoticamente stabile o meno.

$$2 \frac{(s+3)}{s^2(s-1)}$$

$\mu = -6 \rightarrow \varphi_{in} = -180^\circ$

INIZIO



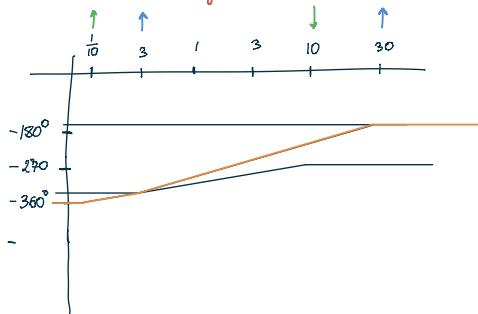
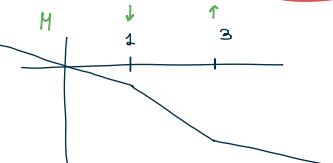
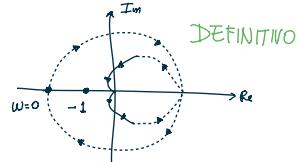
$$P_C = s^3 - s^2 + 2s + 6$$

$$\begin{array}{c|cc} s^3 & 1 & 2 \\ s^2 & -1 & 6 \\ s^1 & & \\ s^0 & & \end{array}$$

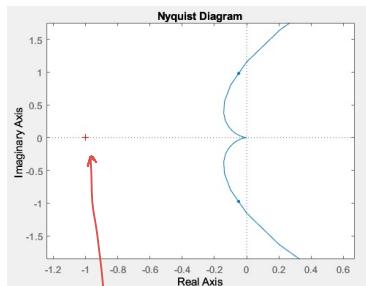
A.I.

Basta così oppure  
devo fare i Trotteggi?

Provo a farlo più accurato



1 polo a  $\text{Re} \rho > 0 \Rightarrow \text{regolo} \& \text{circondamento Ma ne ho zero!} \Rightarrow \text{A.I.}$



Nessun Circondamento

