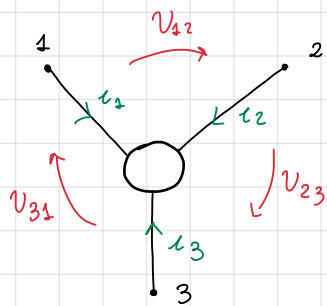


## N-POLI

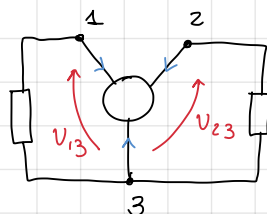


$$\begin{aligned} \text{LKC: } & i_1 + i_2 + i_3 = 0 \\ \text{LKT: } & v_{12} + v_{23} + v_{31} = 0 \end{aligned} \quad \begin{aligned} & \text{ES.} \\ & \Rightarrow \end{aligned} \quad \begin{aligned} & i_1 = -(i_2 + i_3) \\ & v_{12} = -(v_{23} + v_{31}) \end{aligned}$$

INDEPENDENTI

(1) Solo  $N-1$  tensioni e correnti sono indipendenti.

(2) Fissato un nodo, (es: ③) le grandezze indip saranno



$$i_1, i_2, v_{13}, v_{23}$$

## RELAZIONI CARAT

Possiamo esprimere le correnti con funz. di due variabili:

$$\begin{cases} i_1 = g_1(v_{13}, v_{23}) \\ i_2 = g_2(v_{13}, v_{23}) \end{cases}$$

CORRENTE

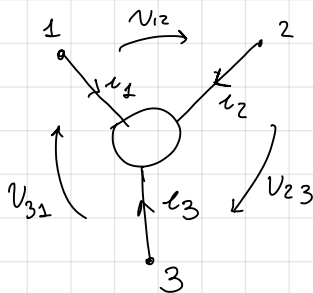
Ma abbiamo anche

$$\begin{cases} v_1 = z_1(i_1, i_2) \\ v_2 = z_2(i_1, i_2) \end{cases}$$

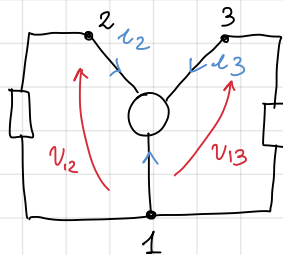
$$\begin{cases} i_1 = h_1(v_1, v_2) \\ i_2 = h_2(v_1, v_2) \end{cases}$$

$$\begin{cases} v_1 = h_1(i_1, i_2) \\ i_2 = h_2(v_1, i_2) \end{cases}$$

## POTENZA ASSORBITA



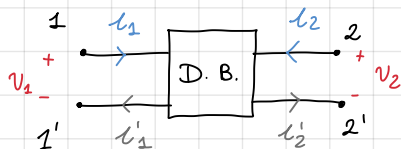
Scelgo ①



$$\Rightarrow P(t) = i_2(t) \cdot v_{12}(t) + i_3 v_{13}(t)$$

CONDIZIONI DI PORTA

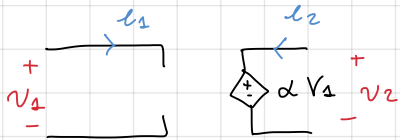
$$\begin{cases} i_1 = -i_1' \\ i_2 = -i_2' \end{cases}$$



$$P(t) = v_{11'} \cdot i_1 + v_{22'} \cdot i_2 = v_1 i_1 + v_2 i_2$$

# GENERATORI CONTROLLATI

## G.T. Controllato in Tensione



$$\text{R.C.} \quad \begin{cases} i_1 = 0 & \forall v_2 \\ v_2 = \alpha v_1 \end{cases}$$

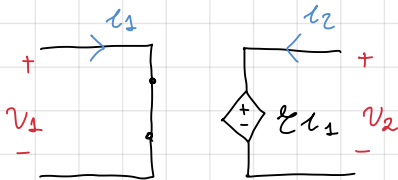
$$[\alpha] = \frac{V}{V}$$

$$\leadsto \begin{cases} i_1 = 0 v_1 + 0 i_2 \\ v_2 = \alpha v_1 + 0 i_2 \end{cases}$$

$$\leadsto \begin{pmatrix} i_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ \alpha & 0 \end{pmatrix} \begin{pmatrix} v_1 \\ i_2 \end{pmatrix}$$

↑  
# ibrido

## G.T. Controllato in CORRENTE



$$\text{R.C.} \quad \begin{cases} v_1 = 0 \\ v_2 = \beta i_1 \end{cases}$$

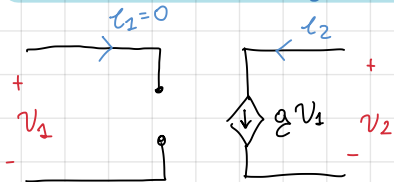
$$[\beta] = R$$

$$\leadsto \begin{cases} v_1 = 0 i_1 + 0 i_2 \\ v_2 = \beta i_1 + 0 i_2 \end{cases}$$

$$\leadsto \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ \beta & 0 \end{pmatrix} \begin{pmatrix} i_1 \\ i_2 \end{pmatrix} \leadsto \underline{V} = \underline{R} \cdot \underline{I}$$

↑  
Res

## G.C. Controllato in Tensione



$$\text{R.C.} \quad \begin{cases} i_1 = 0 \\ i_2 = g v_1 \end{cases}$$

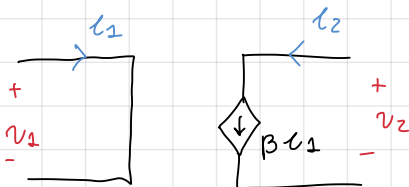
$$\left[ \frac{g}{\beta} \right] = \frac{1}{R}$$

$$\leadsto \begin{cases} i_1 = 0 v_1 + 0 v_2 \\ i_2 = g v_1 + 0 v_2 \end{cases}$$

$$\leadsto \begin{pmatrix} i_1 \\ i_2 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ g & 0 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \leadsto \underline{I} = \underline{G} \cdot \underline{V}$$

↑  
G cond

## G.C. Controllato in CORRENTE



$$\text{R.C.} \quad \begin{cases} v_1 = 0 \\ i_2 = \beta i_1 \end{cases}$$

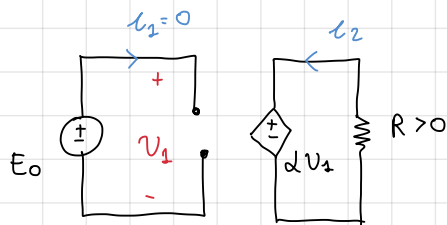
$$[\beta] = \frac{A}{A}$$

$$\leadsto \begin{cases} v_1 = 0 i_1 + 0 v_2 \\ i_2 = \beta i_1 + 0 v_2 \end{cases}$$

$$\leadsto \begin{pmatrix} v_1 \\ i_2 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ \beta & 0 \end{pmatrix} \begin{pmatrix} i_1 \\ v_2 \end{pmatrix}$$

↑  
# ibrido

# I G.C. SONO BIPOLI ATTIVI



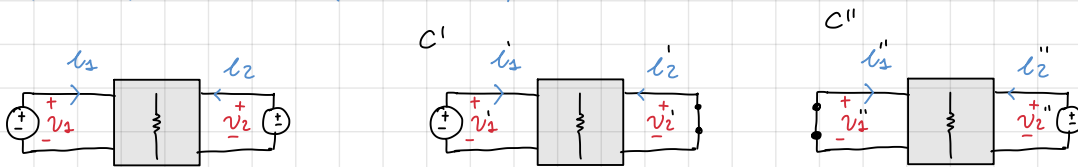
$$\begin{cases} i_1 = 0 \\ V_2 = d V_1 \end{cases} \leadsto \begin{pmatrix} i_1 \\ V_2 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ d & 0 \end{pmatrix} \begin{pmatrix} V_1 \\ i_2 \end{pmatrix}$$

$$\text{ma } \begin{cases} V_2 = -i_2 R_2 \\ V_1 = E_0 \end{cases} \leadsto i_2 = \frac{V_2}{-R} = \frac{E_0}{-R}$$

$$\Rightarrow P_a(t) = V_1 i_1 + V_2 i_2 = E_0 \cdot 0 + d E_0 \cdot \frac{E_0}{-R} = \frac{d E_0^2}{-R} \leq 0 \leadsto \text{D.B. ATTIVO}$$

## PROPRIETA' DI RECIPROCITA'

### PRIMA FORMA (TENSIONE)



Sfrutto la cons. delle potenze virtuali  $\sum^e i'(t) \cdot v''(t) = \sum^e i''(t) \cdot v'(t) = 0$

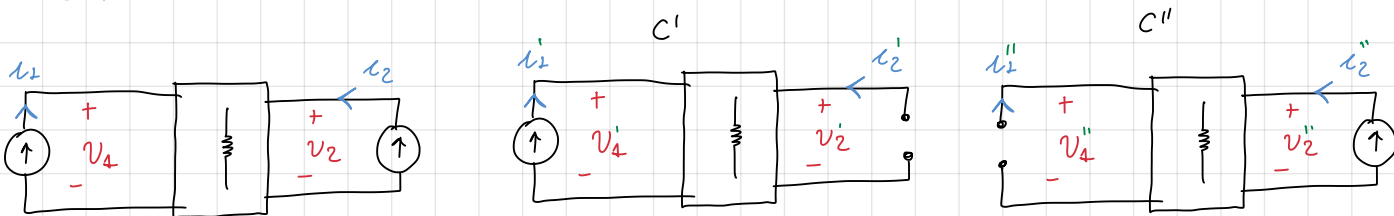
$$\begin{aligned} C' & \begin{cases} \sum^e i_k' v_k'' - i_1' v_1'' - i_2' v_2'' = 0 & (1) \\ \sum^e i_k'' v_k' - i_1'' v_1' - i_2'' v_2' = 0 & (2) \end{cases} \\ C'' & \begin{cases} \sum^e i_k' v_k'' - i_1' v_1'' - i_2' v_2'' = 0 & (1) \\ \sum^e i_k'' v_k' - i_1'' v_1' - i_2'' v_2' = 0 & (2) \end{cases} \end{aligned}$$

\*  $\sum i_k' v_k'' = \sum i_k' R_k i_k'' = \sum v_k' i_k'' = \sum v_k' i_k''$   
(a)  $\downarrow$  (b) Q.E.D.

$$(1) - (2) \leadsto -i_2' v_2'' + i_1'' v_1' = 0 \quad \text{con } v_1' = v_2'' = V \text{ generatori}$$

$$\Rightarrow \frac{i_2'}{V} = \frac{i_1''}{V}$$

### SECONDA FORMA (Corrente)



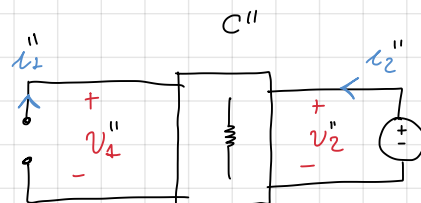
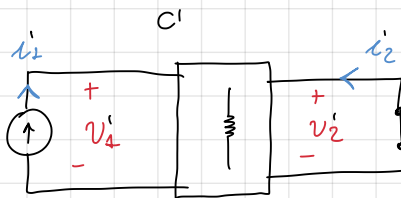
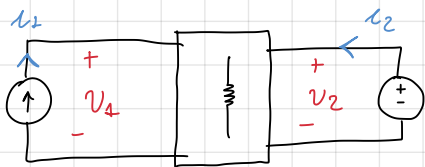
$$\begin{aligned} (1) & \begin{cases} \sum^e i_k' v_k'' - i_1' v_1'' - i_2' v_2'' = 0 \\ \sum^e i_k'' v_k' - i_1'' v_1' - i_2'' v_2' = 0 \end{cases} \\ (2) & \begin{cases} \sum^e i_k' v_k'' - i_1' v_1'' - i_2' v_2'' = 0 \\ \sum^e i_k'' v_k' - i_1'' v_1' - i_2'' v_2' = 0 \end{cases} \end{aligned}$$

$$\leadsto (1) - (2) \leadsto -i_1' v_1'' + i_2'' v_2' = 0$$

$$i_1' = i_2'' = I \leadsto$$

$$\frac{v_1''}{I} = \frac{v_2'}{I}$$

## TERZA FORMA IBRIDA

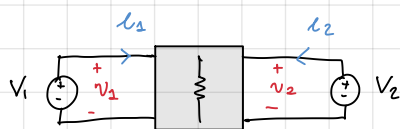


$$\begin{aligned}
 (1) \quad & \sum \cancel{\mathcal{L}_k} v_k'' - \mathcal{L}_1' v_1'' - \mathcal{L}_2' v_2'' = 0 \\
 (2) \quad & \sum \cancel{\mathcal{L}_k} v_k' - \mathcal{L}_1'' v_1' - \mathcal{L}_2'' v_2' = 0
 \end{aligned}
 \quad \leadsto \quad -\mathcal{L}_1' v_1'' - \mathcal{L}_2' v_2'' = 0 \quad \text{con } \mathcal{L}_1' = I, v_2'' = V$$

$$\Rightarrow \frac{v_1''}{I} = -\frac{\mathcal{L}_2'}{V}$$

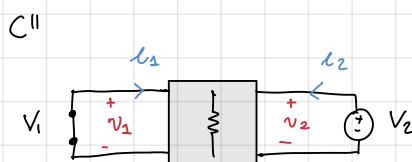
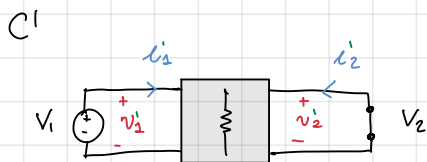
## MATRICE DELLE CONDUTTANZE

Controlliamo un D.B. in Tensione



Se controlliamo in Tensione  $\rightarrow$  le incognite sono le  $i$ :

$$\begin{cases}
 \mathcal{L}_1 = \mathcal{L}_1' + \mathcal{L}_1'' \\
 \mathcal{L}_2 = \mathcal{L}_2' + \mathcal{L}_2''
 \end{cases}$$



$$\begin{bmatrix}
 \mathcal{L}_1' = \frac{V_1}{R_{11}} = G_{11} V_1 & \mathcal{L}_1'' = G_{12} V_2 \\
 \mathcal{L}_2' = G_{21} V_1 & \mathcal{L}_2'' = G_{22} V_2
 \end{bmatrix}
 \quad \leadsto \quad \underline{\underline{G}} = \begin{pmatrix} G_{11} & G_{12} \\ G_{21} & G_{22} \end{pmatrix}$$

$$\leadsto \begin{pmatrix} \mathcal{L}_1 \\ \mathcal{L}_2 \end{pmatrix} = \begin{pmatrix} G_{11} & G_{12} \\ G_{21} & G_{22} \end{pmatrix} \begin{pmatrix} V_1 \\ V_2 \end{pmatrix}$$

$$\mathcal{L}_k = \frac{V_k}{R_{ij}} \rightarrow$$

$$\underline{\underline{G}}_{ij} = \frac{\mathcal{L}_k}{V_k}$$

$$\underline{\underline{G}} = \begin{pmatrix} G_{11} = \frac{\mathcal{L}_1}{V_1} \Big|_{V_2=0} & G_{12} = \frac{\mathcal{L}_1}{V_2} \Big|_{V_1=0} \\ G_{21} = \frac{\mathcal{L}_2}{V_1} \Big|_{V_2=0} & G_{22} = \frac{\mathcal{L}_2}{V_2} \Big|_{V_1=0} \end{pmatrix}$$

## POTENZA

$$\underline{i} = (\mathcal{L}_1 \quad \mathcal{L}_2)^T$$

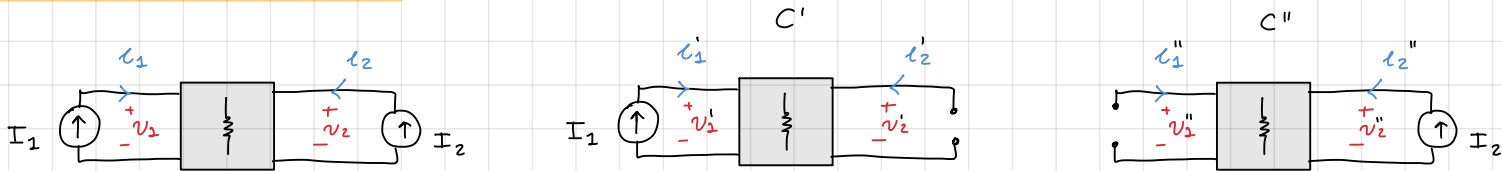
$$\underline{v} = (V_1 \quad V_2)^T$$

$$\rightarrow \underline{i} = \underline{\underline{G}} \cdot \underline{v}$$

$$P(t) = \underline{v}^T \cdot \underline{i} =$$

$$P(t) = \underline{v}^T \cdot \underline{\underline{G}} \cdot \underline{v}$$

## MATRICE RESISTENZE



$$\begin{cases} v_1 = v_1' + v_1'' \\ v_2 = v_2' + v_2'' \end{cases} \rightarrow \begin{cases} v_1 = R_{11} i_1' + R_{12} i_2'' \\ v_2 = R_{21} i_1' + R_{22} i_2'' \end{cases} \Rightarrow$$

$$R_{11} = \frac{v_1'}{i_1'} \Big|_{i_2''=0} \quad R_{12} = \frac{v_1''}{i_2''} \Big|_{i_1'=0}$$

$$R_{21} = \frac{v_2'}{i_1'} \Big|_{i_2''=0} \quad R_{22} = \frac{v_2''}{i_2''} \Big|_{i_1'=0}$$

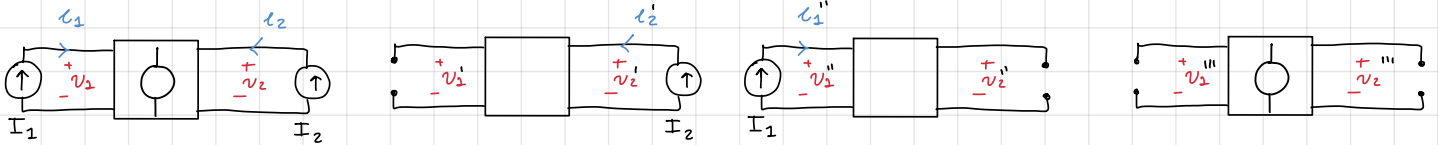
## BIPOLI INERTI

Sono **inerti** quei bipoli la cui R.C. passa per 0; ovvero che non erogano potenza quando non sono alimentati.

Sono **non inerti** quando almeno una delle tensioni  $\neq 0$  quando le correnti sono 0.

## THEVENIN PER I DB

Base current  $\rightarrow v_{1,2}$  incognite



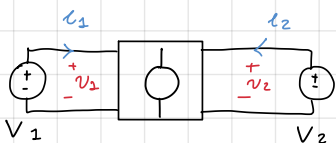
$$\begin{cases} v_1 = v_1' + v_1'' + v_1''' \\ v_2 = v_2' + v_2'' + v_2''' \end{cases} = \begin{cases} v_1 = R_{11} i_1' + R_{12} i_2'' + \begin{bmatrix} V_{10} \\ V_{20} \end{bmatrix} \\ v_2 = R_{21} i_1' + R_{22} i_2'' + \begin{bmatrix} V_{10} \\ V_{20} \end{bmatrix} \end{cases} \quad \text{Tensioni a vuoto}$$

definisco  $\underline{V}_0 = (V_{10} \ V_{20})^T$

$\hookrightarrow \underline{V} = \underline{R} \underline{I} + \underline{V}_0$  Thevenin

## NORTON PER I D.B.

$\rightarrow$  Base Tensione  $\rightarrow i_1, i_2$  incognite



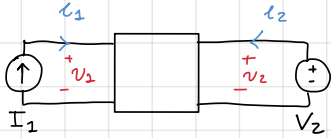
$$\begin{cases} i_1 = G_{11} v_1 + G_{12} v_2 + I_{01} \\ i_2 = G_{21} v_1 + G_{22} v_2 + I_{02} \end{cases}$$

con  $\underline{I} = (I_{01} \ I_{02})^T$

$\Rightarrow \underline{I} = \underline{G} \underline{V} + \underline{I}_0$  NORTON

## MATRICE IBRIDA

incognite:  $v_1, i_2$



$$\begin{cases} v_1 = H_1(i_1, v_2) = H_{11}i_1 + H_{12}v_2 \\ i_2 = H_2(i_1, v_2) = H_{21}i_1 + H_{22}v_2 \end{cases}$$

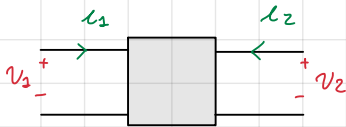
$$H_{11} = \frac{v_1}{i_1} \Big|_{v_2=0}$$

$$H_{12} = \frac{v_1}{v_2} \Big|_{i_1=0}$$

$$H_{21} = \frac{i_2}{i_1} \Big|_{v_2=0}$$

$$H_{22} = \frac{i_2}{v_2} \Big|_{i_1=0}$$

## MATRICE DI TRASMISSIONE

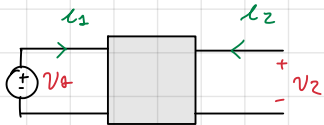


Ricaviamo le grandezze della prima porta in funzione della seconda

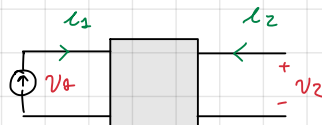
$$\begin{cases} v_1 = T_{11}v_2 + T_{12}(-i_2) \\ i_1 = T_{21}v_2 + T_{22}(-i_2) \end{cases}$$

definiti  $v_0 = (v_1 \ i_1)^T$  e  $v_1 = (v_2 \ -i_2)^T \rightsquigarrow v_0 = \begin{pmatrix} T_{11} & T_{12} \\ T_{21} & T_{22} \end{pmatrix} \cdot v_1$

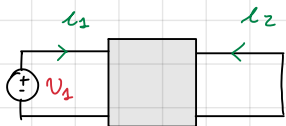
mat. di Tras.



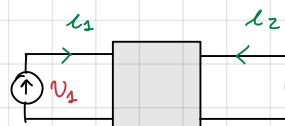
$$T_{11} = \frac{v_1}{v_2} \Big|_{i_2=0}$$



$$T_{21} = \frac{i_1}{v_2} \Big|_{i_2=0}$$



$$T_{12} = \frac{v_1}{-i_2} \Big|_{v_2=0}$$



$$T_{22} = \frac{i_1}{i_2} \Big|_{v_2=0}$$

## ACCOPIAMENTO MUTUO

$$\begin{cases} \phi_1 = L_1 i_1 + M_{12} i_2 \\ \phi_2 = L_2 i_2 + M_{12} i_1 \end{cases}$$

$$\text{ma } v = \frac{d\phi}{dt} \Rightarrow$$

$$\begin{cases} v_1 = L_1 \dot{i}_1 + M \dot{i}_2 \\ v_2 = L_2 \dot{i}_2 + M \dot{i}_1 \end{cases}$$

## POTENZA DEL TRASFORM.

$$p^a(t) = v_1(t) \cdot i_1(t) + v_2(t) i_2(t) = L_1 i_1 \frac{di_1}{dt} + M i_1 \frac{di_2}{dt} + L_2 i_2 \frac{di_2}{dt} + M i_2 \frac{di_1}{dt}$$

$$\text{Siccome } \frac{d}{dt} \left[ \frac{di^2}{dt} \right] = 2i \frac{di}{dt} \Rightarrow p^a = \frac{d}{dt} \left[ \frac{1}{2} L_1 i_1^2 \right] + M \underbrace{\left( i_1 \dot{i}_2 + i_2 \dot{i}_1 \right)}_{\frac{d}{dt} \text{ prod}} + \frac{d}{dt} \left[ \frac{1}{2} L_2 i_2^2 \right]$$

$$\Rightarrow p^a = \frac{d}{dt} \left( \frac{1}{2} L_1 i_1^2 \right) + M \frac{d}{dt} (i_1 i_2) + \frac{d}{dt} \left[ \frac{1}{2} L_2 i_2^2 \right]$$

$$\text{Siccome } p = \frac{dW}{dt} \leftarrow \text{LAVORO} \quad W = \int p dt$$

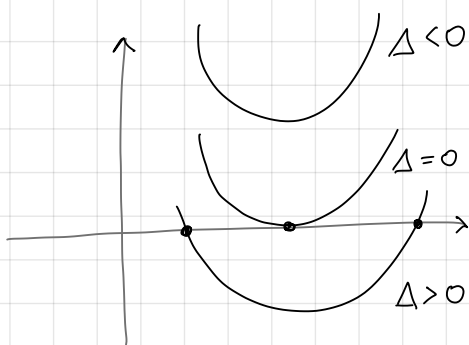
$$\Rightarrow W = \frac{1}{2} L_1 i_1^2 + \underbrace{M i_1 i_2}_{\text{Energia immagazz.}} + \frac{1}{2} L_2 i_2^2$$

## IL TRAS. E' UN BIPOLO PASSIVO $\Rightarrow W_a \geq 0$

$$\frac{1}{2} L_1 i_1^2 + M i_1 i_2 + \frac{1}{2} L_2 i_2^2 \geq 0 \quad \Rightarrow \frac{1}{2} L_1 \left( \frac{i_1}{i_2} \right)^2 + \frac{1}{2} L_2 + M \frac{i_1}{i_2} \geq 0$$

$$\Rightarrow \text{pongo } \frac{i_1}{i_2} = x \Rightarrow \frac{1}{2} L_1 x^2 + M x + \frac{1}{2} L_2 \geq 0$$

ANALISI



$$\Delta = b^2 - 4 \cdot a \cdot c = M^2 - 4 \cdot \frac{1}{2} \cdot \frac{1}{2} L_1 \cdot L_2$$

$$= M^2 - L_1 L_2$$

$$\begin{aligned} \Delta < 0 &\Rightarrow M^2 < L_1 L_2 \\ \Delta = 0 &\Rightarrow M = \sqrt{L_1 L_2} \\ \Delta > 0 &\Rightarrow M > \sqrt{L_1 L_2} \end{aligned}$$

$$\Rightarrow k = \frac{M}{\sqrt{L_1 L_2}} \quad \text{Coeff di Accoppiamento}$$

## TRASFORM. IN ACCOPIAMENTO PERFETTO

$$\begin{cases} v_1 = L_1 \dot{i}_1 + M \dot{i}_2 = L_1 \left( \dot{i}_1 + \frac{M}{L_1} \dot{i}_2 \right) \\ v_2 = L_2 \dot{i}_2 + M \dot{i}_1 = M \left( \dot{i}_1 + \frac{L_2}{M} \dot{i}_2 \right) \end{cases}$$

$$K = \frac{M^2}{L_1 L_2} = 1 \Rightarrow M^2 = L_1 L_2 \Rightarrow \frac{M}{L_1} = \frac{L_2}{M} = m$$

$$\begin{cases} v_1 = L_1 (\dot{i}_1 + n \dot{i}_2) & (1) \\ v_2 = M (\dot{i}_1 + n \dot{i}_2) & (2) \end{cases} \Rightarrow \frac{v_1}{v_2} = \frac{L_1}{M} \cdot \frac{\dot{i}_1 + m \dot{i}_2}{\dot{i}_1 + m \dot{i}_2} \Rightarrow v_1 = n v_2$$

con  $n = \frac{L_1}{M}$

$i_1 = -\frac{1}{n} i_2$

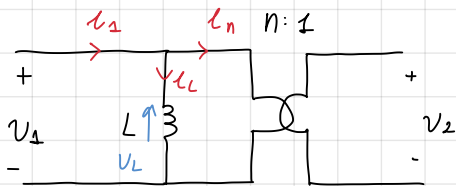
$$\left[ \frac{v_1}{v_2} = \frac{n_1}{n_2} \right] \Rightarrow n_1 v_1 = n_2 v_2 \quad \text{se } n_1 = 1 \Rightarrow v_1 = n v_2$$

$$\left[ \frac{i_1}{i_2} = -\frac{n_2}{n_1} \right] \Rightarrow i_1 = -\frac{1}{n} i_2$$

## RELAZIONI CARATTERISTICHE T.I.

$$\begin{cases} v_1 = n v_2 \\ i_2 = -n i_1 \end{cases} \Rightarrow \begin{cases} v_2 = \frac{1}{n} v_1 \\ i_1 = -\frac{1}{n} i_2 \end{cases}$$

## CIRCUITO EQUIVALENTE



Se le eq del circ sono quelle del T.I allora QED

$$\text{R.C. } v_L = L \dot{i}_L = L \frac{d}{dt} (i_1 - i_n) \\ i_L = i_1 - i_n$$

ma  $i_n = -\frac{1}{n} i_2 \Rightarrow v_L = L \frac{d}{dt} \left( i_1 + \frac{1}{n} i_2 \right) = \left( \frac{L}{n} \right) \dot{i}_2 + L \dot{i}_1$

$$\frac{L_1}{M} = n \Rightarrow \frac{L_1}{n} = M \Rightarrow v_L = M \dot{i}_2 + L \dot{i}_1 \quad \text{Eq Trasf (1)}$$

(2) devo ottenere  $v_2 = L_2 \dot{i}_2 + M \dot{i}_1$

$$v_1 = n v_2 \Rightarrow n v_2 = v_L \Rightarrow n v_2 = L \dot{i}_1 + \frac{L}{n} \dot{i}_2 \Rightarrow v_2 = \frac{L}{n} \dot{i}_1 + L \dot{i}_2 \quad \text{Eq (2)}$$