

MARKOV CHAIN MONTE CARLO



CALCULATING POSTERIORIS

$$Pr(\theta|y) = \frac{Pr(y|\theta)Pr(\theta)}{\int_{\theta} Pr(y|\theta)Pr(\theta)d\theta}$$

BAYESIAN APPROXIMATION

- » Maximum a posteriori (MAP) estimate
- » Laplace (normal) approximation
- » Rejection sampling
- » Importance sampling
- » Sampling importance resampling (SIR)
- » Approximate Bayesian Computing (ABC)
- » Laplace Approximation

MCMC

μ

Markov chain Monte Carlo simulates a Markov chain for which some function of interest is the unique, invariant, stationary distribution.

1000

2000

3000

4000

MARKOV CHAINS

Stochastic process

$$\{X_t : t \in T\}$$

Markovian condition:

$$Pr(X_{t+1} = x_{t+1} | X_t = x_t, X_{t-1} = x_{t-1}, \dots, X_0 = x_0) = Pr(X_{t+1} = x_{t+1} | X_t = x_t)$$

REVERSIBLE MARKOV CHAINS

When the Markov chain is constructed to satisfy the detailed balance equation:

$$\pi(x)Pr(y|x) = \pi(y)Pr(x|y)$$

The π is the limiting distribution of the chain.

1000

2000

3000

4000

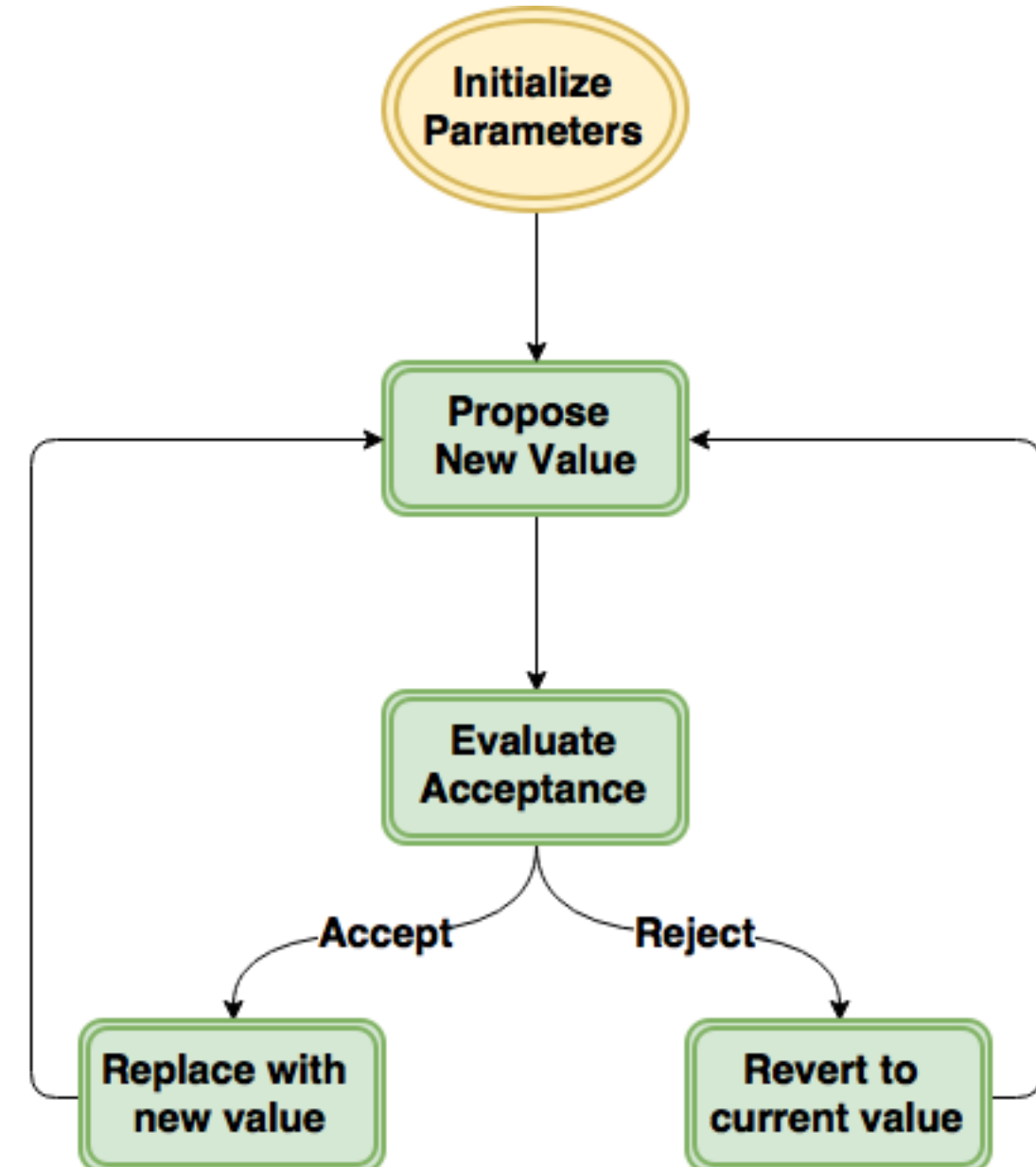
METROPOLIS SAMPLING

Repeat until convergence:

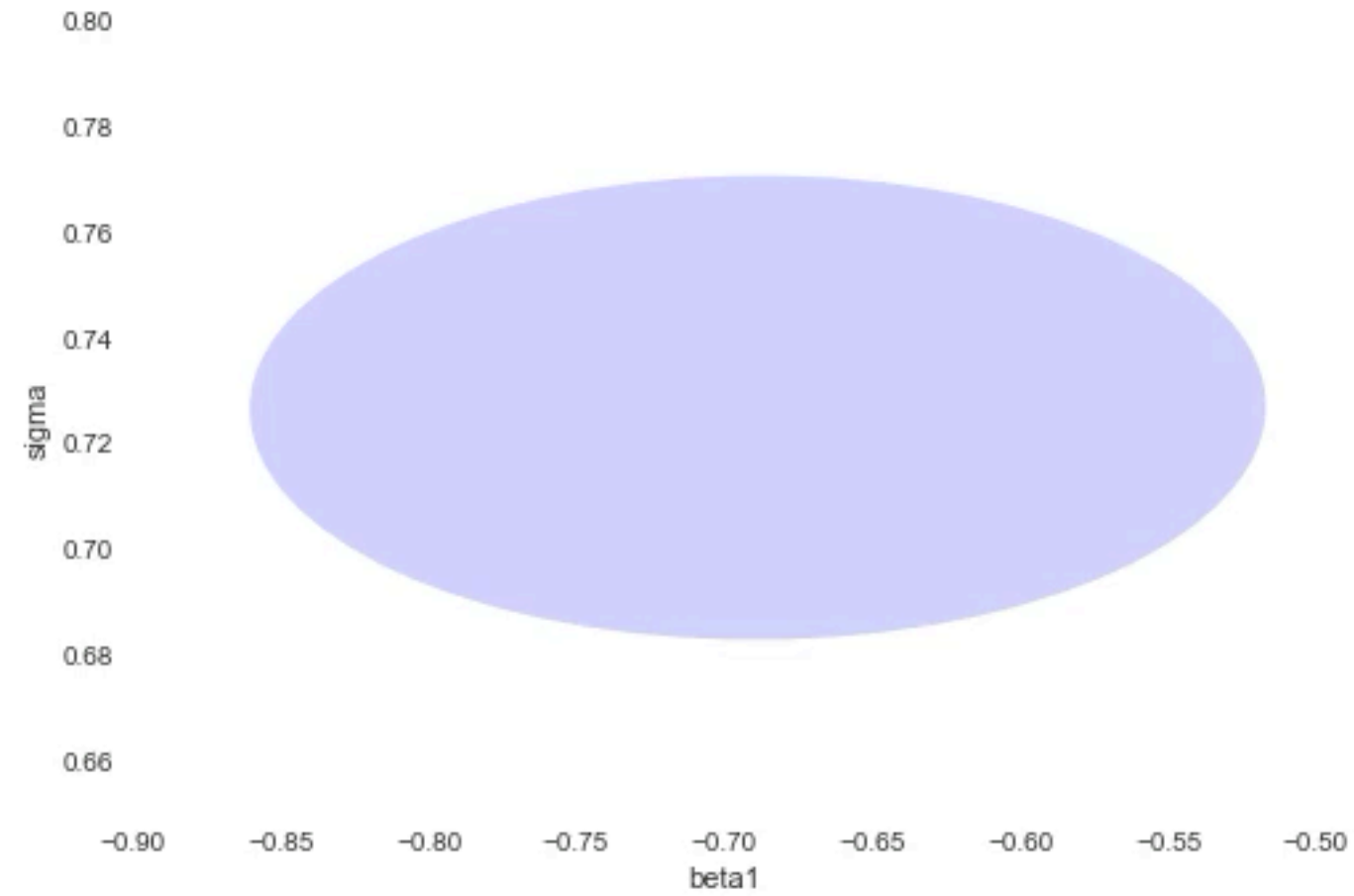
1. Sample θ' from $q(\theta'|\theta^{(t)})$.
2. Generate a Uniform[0,1] random variate u .
3. Calculate acceptance probability:

$$a(\theta', \theta) = \frac{\pi(\theta')}{\pi(\theta)}$$

1. If $a(\theta', \theta) > u$ then $\theta^{(t+1)} = \theta'$, otherwise $\theta^{(t+1)} = \theta^{(t)}$.



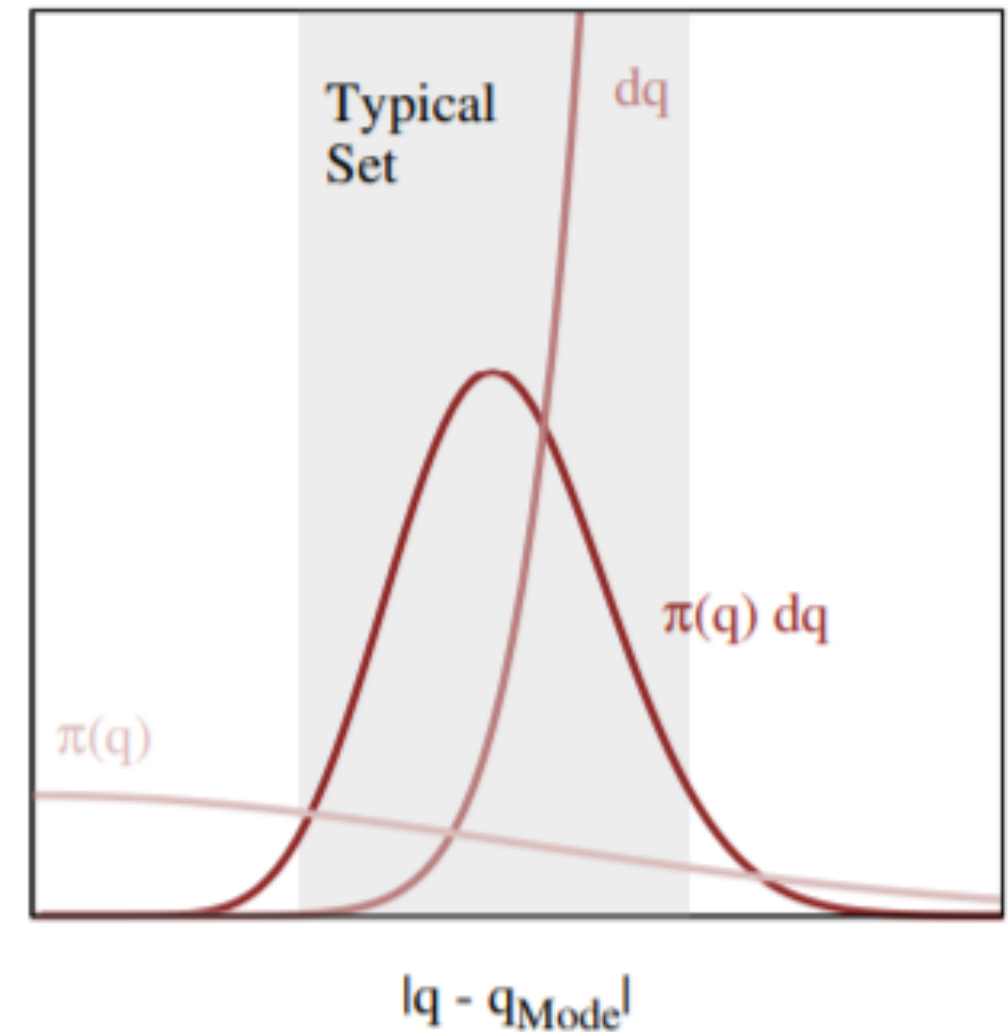
METROPOLIS SAMPLING



Most of the probability of a multivariate distribution lies in the

TYPICAL SET

rather than near the mode.



HAMILTONIAN MONTE CARLO

Uses a physical analogy of a frictionless particle moving on a hyper-surface

Requires an auxiliary variable to be specified

» position (unknown variable value)

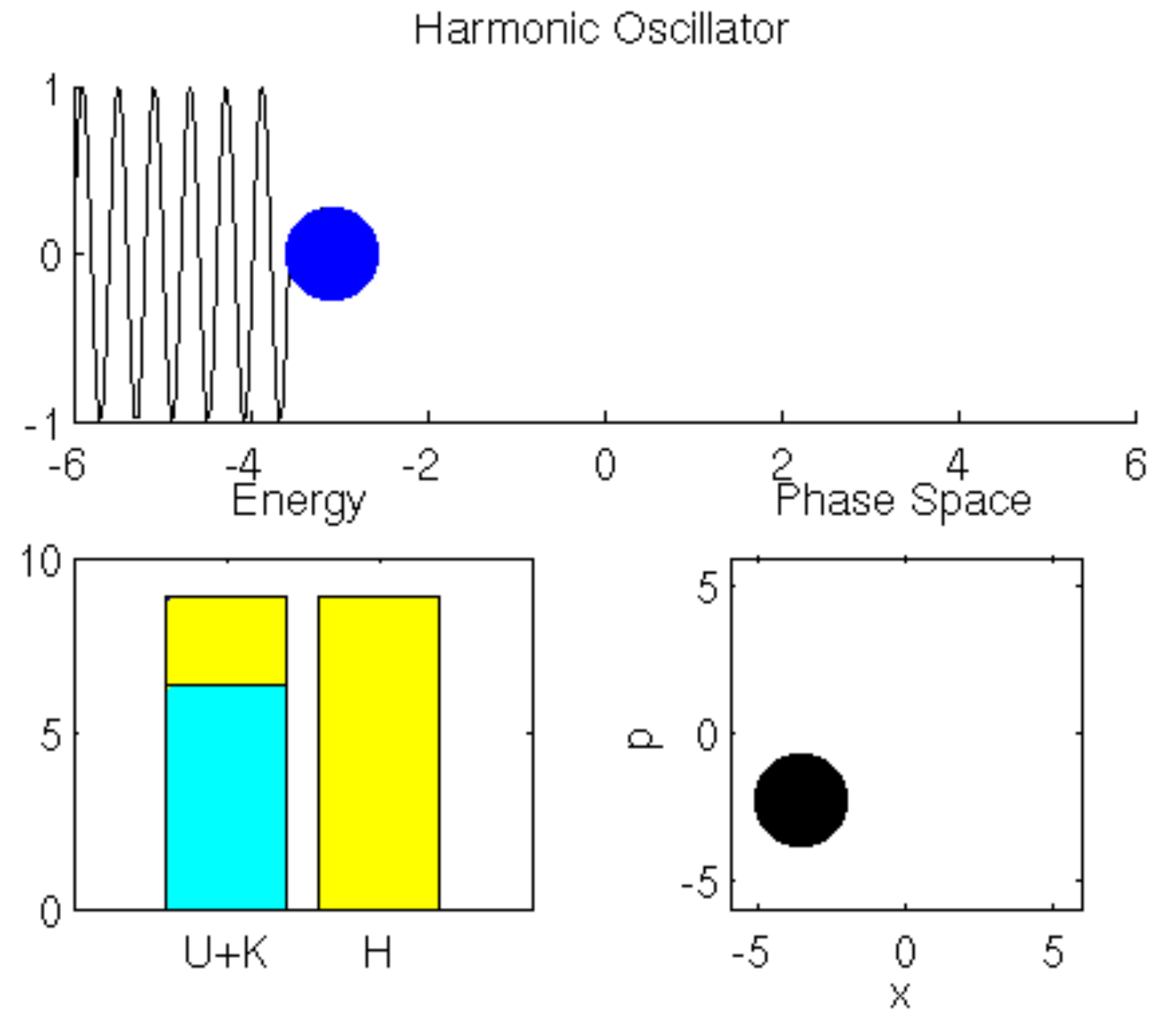
» momentum (auxiliary)

$$\mathcal{H}(s, \phi) = E(s) + K(\phi) = E(s) + \frac{1}{2} \left(\sum_i \right) \phi_i^2$$

HAMILTONIAN DYNAMICS

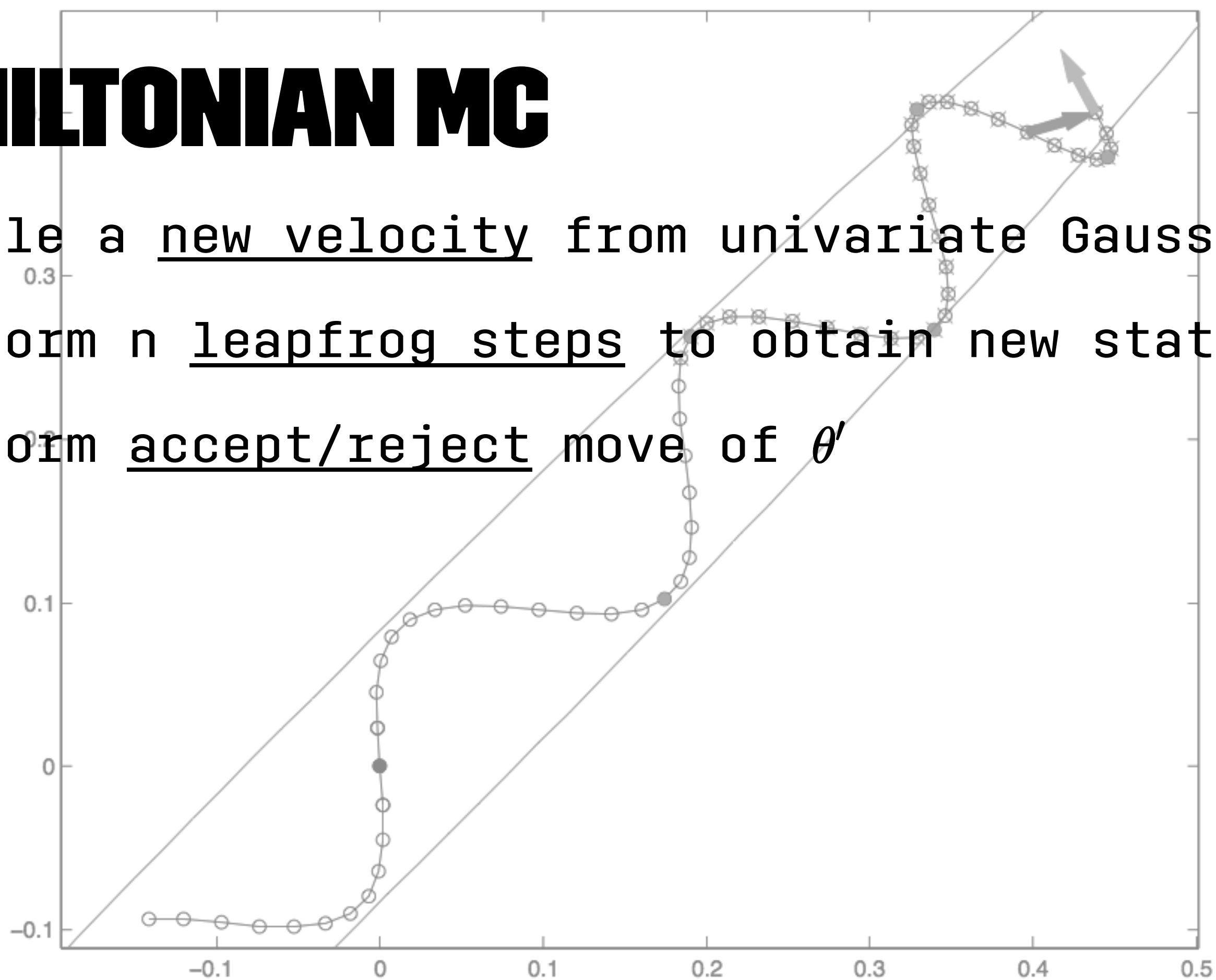
$$\frac{ds_i}{dt} = \frac{\partial \mathcal{H}}{\partial \phi_i} = \phi_i$$

$$\frac{d\phi_i}{dt} = -\frac{\partial \mathcal{H}}{\partial s_i} = -\frac{\partial E}{\partial s_i}$$

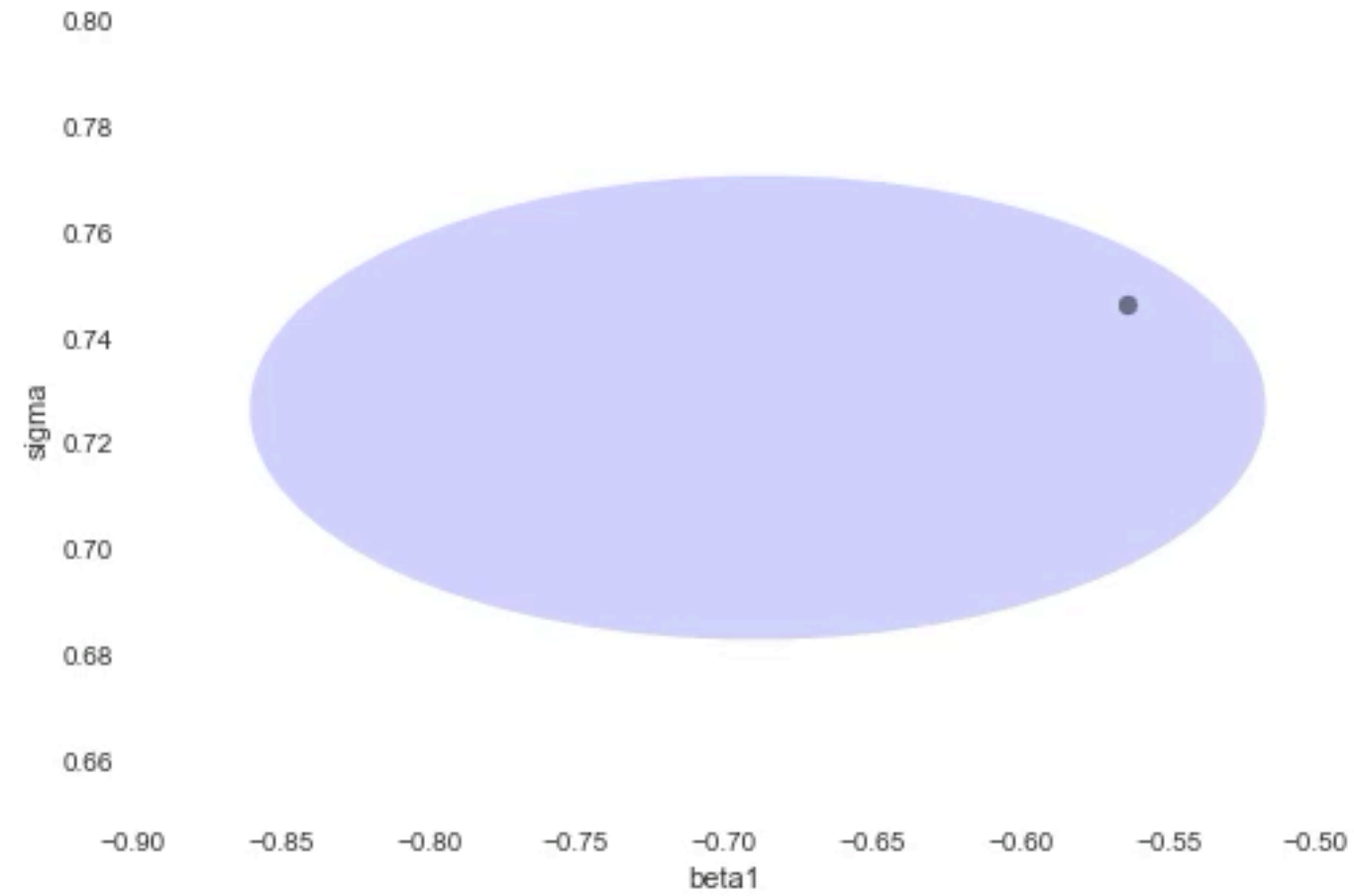


HAMILTONIAN MC

1. Sample a new velocity from univariate Gaussian
2. Perform n leapfrog steps to obtain new state θ'
3. Perform accept/reject move of θ'



HAMILTONIAN MC



NO U-TURN SAMPLER (NUTS)

Hoffmann and Gelman (2014)

