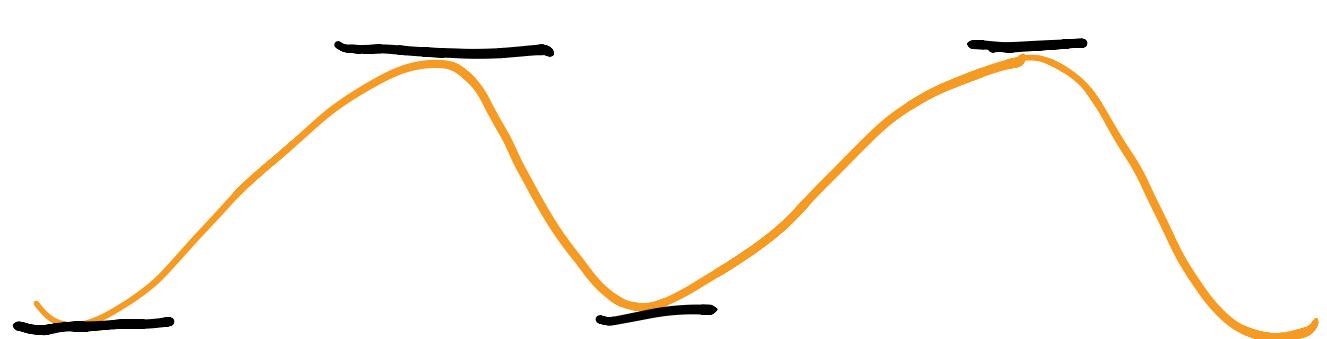


# Calculus

- the derivative rate of change between two variables at a particular point

slope =  $\frac{\text{rise} \uparrow}{\text{run} \rightarrow}$



- the max / min happen where the derivative = 0

$$y = f(x)$$

$$f'(x)$$

(Lagrange's notation)

$$\frac{dy}{dx} = \frac{d}{dx} f(x) \quad (\text{Leibniz's notation})$$

## Common derivatives

### Power functions

$$f(x) = ax + b$$

$$f'(x) = a$$

$$f(x) = ax^2 + bx$$

$$f'(x) = 2ax + b$$

$$f(x) = x^{-1}$$

$$f'(x) = -x^{-2}$$

$$f(x) = k$$

$$f'(x) = 0$$

↳ where  $k = \text{constant}$

### Inverse functions

$$g'(g) = 1/f'(x)$$

### Trigonometric

$$f(x) = \sin(x)$$

$$f'(x) = \cos(x)$$

$$f(x) = \cos(x)$$

$$f'(x) = -\sin(x)$$

$$f(x) = \tan(x)$$

$$f'(x) = \sec^2(x) = 1/\cos^2(x)$$

Inverse function if a function  $f(x)$  does something,  $g(x)$  is its inverse if it un-do that thing.

$$g(f(x)) = x$$

$$e^x$$

$$f(x) = e^x \quad f'(x) = e^x$$

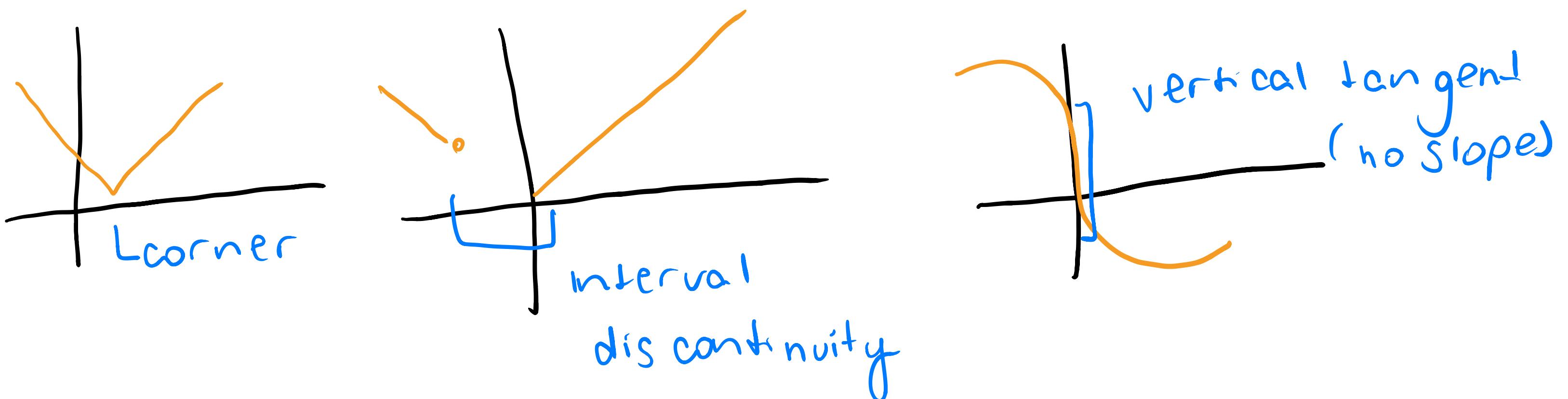
$$\log(x)$$

$$f(x) = \log(x) \quad f'(x) =$$

- Non-differentiable functions

Usually if a function has a "corner", it's non-differentiable  
(the derivative doesn't exist at that corner)

→ if you are drawing a function and you have to lift the pen up,  
it's non-differentiable



- Rule: Multiplication by scalar

$$k \cdot f(x) = k \cdot (f'(x))$$

- Rule: Sum

$$f = g + h \quad \therefore \quad f' = g' + h'$$

- Rule: Product

$$f = g \cdot h \quad \therefore \quad f' = g'h + h'g$$

$$e = (1 + 1/n)^n$$

$$e^x = k \quad x = \log$$

- Rule: Chain rule

$$\frac{d}{dt} f(g(h(t))) =$$

$$\frac{df}{dg} \cdot \frac{dg}{dh} \cdot \frac{dh}{dt} =$$

$$f'(g(h(t))) \cdot g'(h(t)) \cdot h'(t)$$

## Partial derivatives

$$f(x,y)$$

$$f_x = \frac{\partial f}{\partial x}$$

$$f_y = \frac{\partial f}{\partial y} \quad (\text{partial derivative of } f \text{ with respect to } y)$$

(partial derivative of  $f$  with respect to  $x$ )

① treat all other variables as constant

② use regular derivative rules

i.e. Given  $f(x) = 3x^2y^3$ ,  $\frac{\partial f}{\partial x} = 6xy^3$

## Gradients

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix}$$

• the gradient is a vector with all the partial derivatives of a function

example  $f(x,y) = x^2 + y^2 \therefore \nabla f = \begin{bmatrix} 2x \\ 2y \end{bmatrix}$

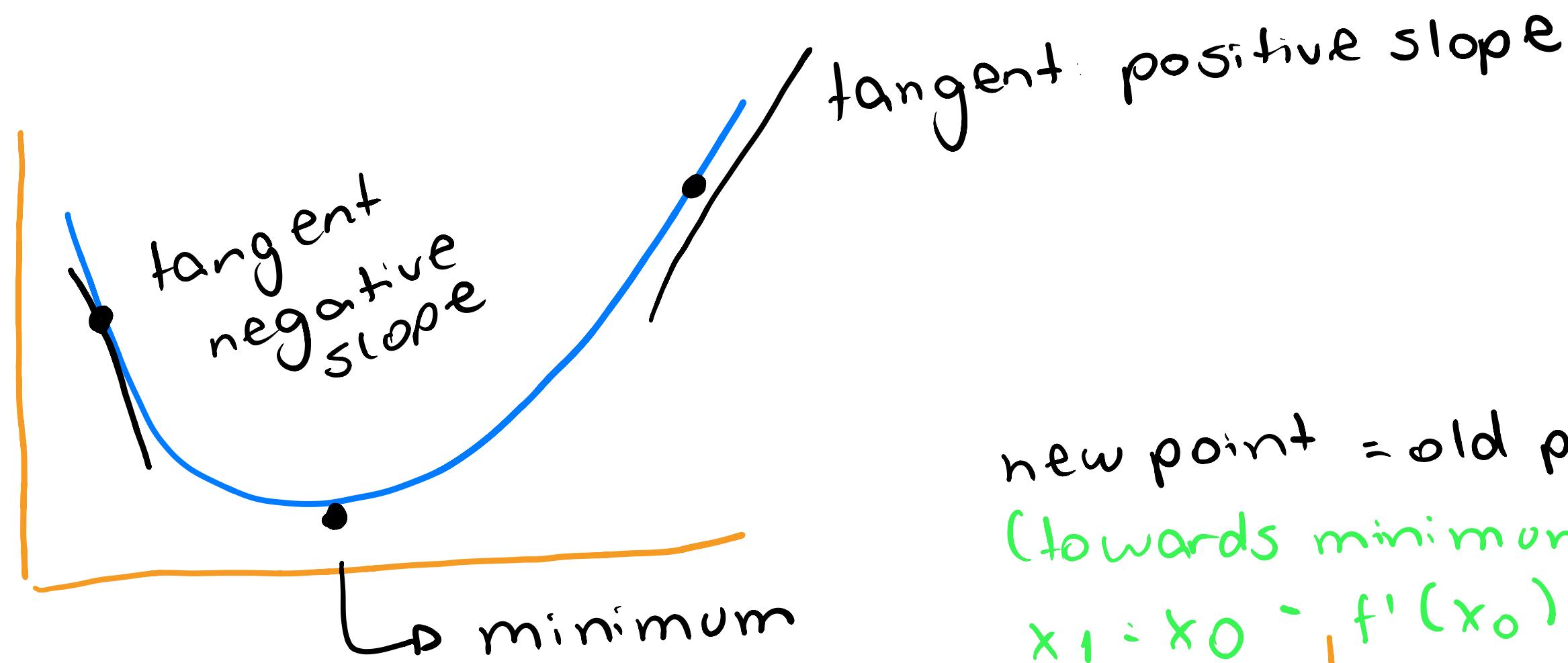
example 2:

$$f(x,y) = xy^2 + 2x + 3y$$

ps: you treat  
the other  
variables as  
constants.

$$\nabla f(x,y) = \begin{bmatrix} y^2 + 2 \\ 2xy + 3 \end{bmatrix}$$

## Gradient descent



new point = old point - slope  
(towards minimum)

$$x_1 = x_0 - \frac{f'(x_0)}{\alpha}$$

$\alpha$  (learning rate  
ensures small steps)

# Optimisation in neural networks

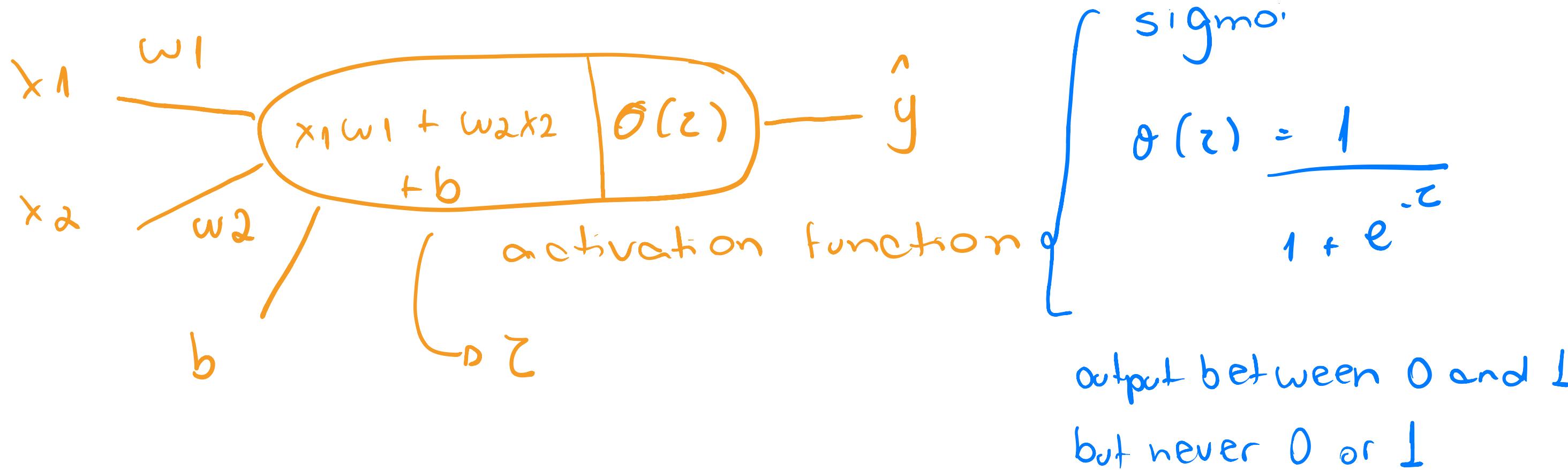
Regression with a perceptron

$$x_1 w_1 + x_2 w_2 + b = \hat{y}$$

Goal: find best  $w_1$ ,  $w_2$  and  $b$  that minimise loss function

- Loss function: mean squared error

Classification with a perceptron



- Loss function: log loss

$$L(y, \hat{y}) = -y \ln(\hat{y}) - (1-y) \ln(1-\hat{y})$$

- Newton's method

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$

(Used to find zeros of a function)

## Second derivative

- Leibniz notation =  $\frac{d^2 f(x)}{dx^2} = \frac{d}{dx} \left( \frac{df(x)}{dx} \right)$

- Lagrange notation:  $f''(x)$

Understanding the second derivative

$x$  = distance (you are travelling)

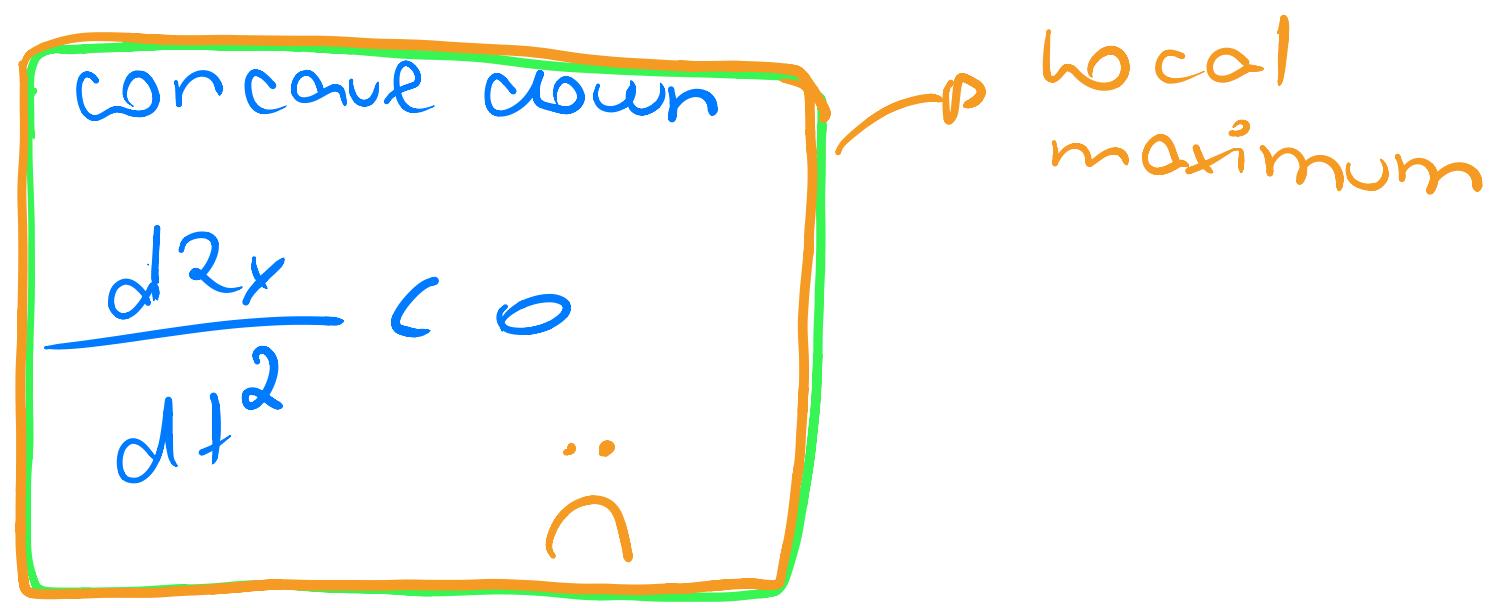
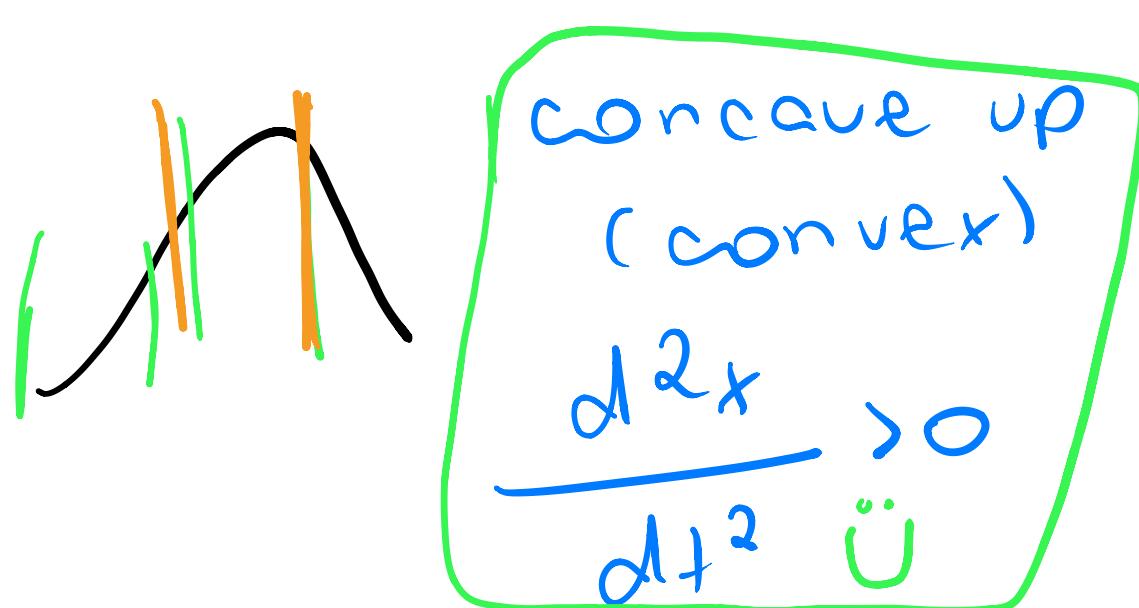
$v$  = velocity you are travelling as a function of time

↳ first derivative  $\frac{dx}{dt}$

$a$  = acceleration  $\frac{dv}{dt}$  ↗ second derivative

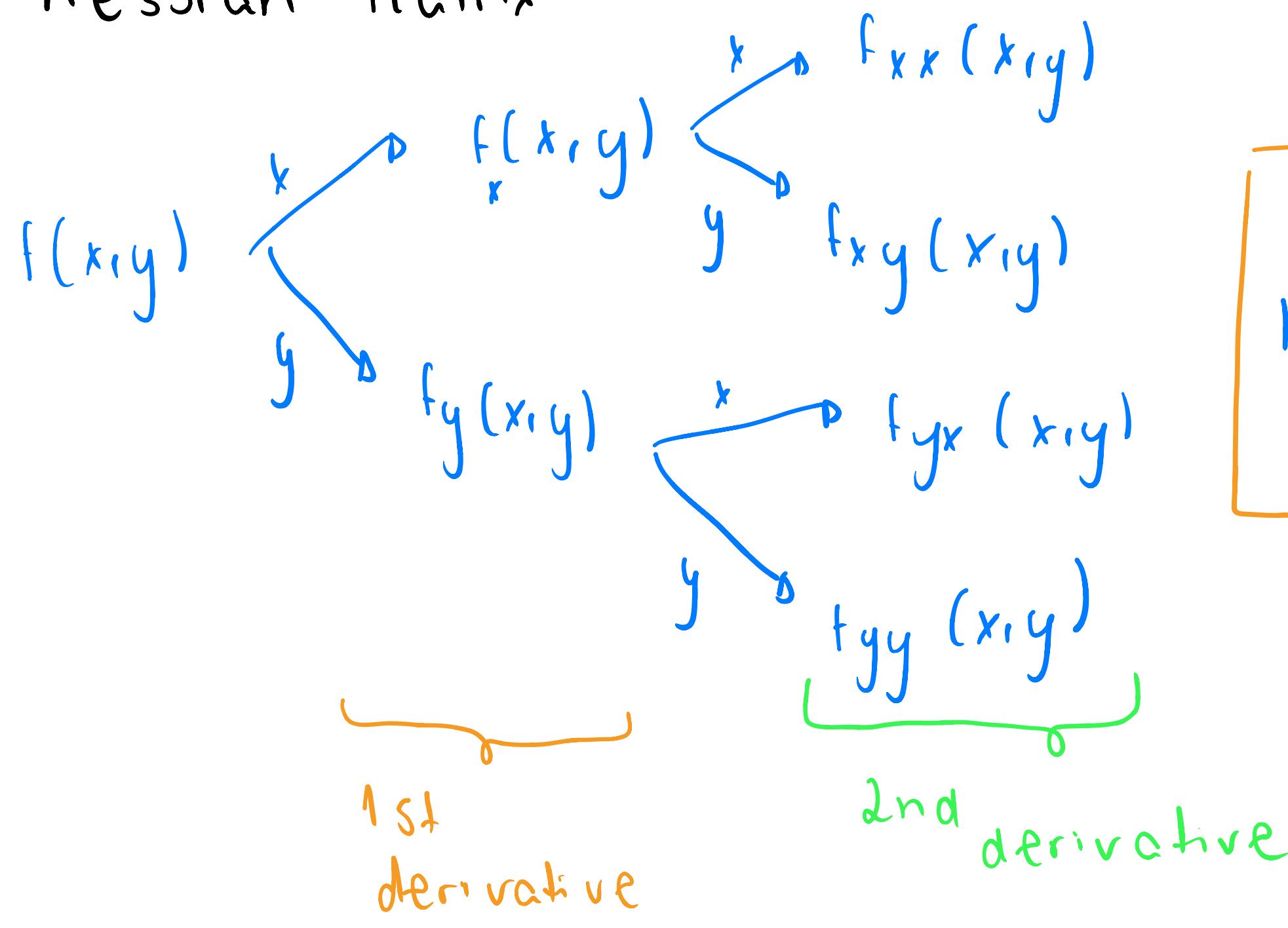
the second derivative gives a measure of the amount by which a curve deviates from being a straight line.

↳ curvature



↳ local minimum

## Hessian Matrix



$$H = \begin{bmatrix} f_{xx}(x,y) & f_{xy}(x,y) \\ f_{yx}(x,y) & f_{yy}(x,y) \end{bmatrix}$$

these values are almost always the same