1. Main use cases with examples. What should be prioritized?

* As many as possible, priority is our choice
* Collapsed area, eventually finding humans. (search and rescue)

1. Are CAD files and software files available for the prototype and completed robot?

* Company question.

1. Hardware datasheet with specifications for the sensors, robot manual and other documentation?

* Should be.

1. Does it need to go outdoors?

* No

1. Does it need to climb ramps or do other non-2D movements?

* No 3D needed.

1. Can we adjust existing parts of the robot or only add new ones?

* If needed you can add, if justified. (modifying not sure yet)

1. What’s the budget? Define Low-cost.

* Below €10k, currently the robot is €3k.
* Everything is discussed with Sjriek. (€1k generic)

1. Upside down movement, is it possible/defined as a use case?

* Not a question, NO.

1. What should be inspected/detected (things)?

* As many as possible, at least 3 (must), up to 10 (should), more (could)

1. When do we get the physical robot?
2. What comm protocol does the robot use to communicate with the server?

* Wifi for now, other as a should

1. What should be the server specifications?

* For now your laptop.

1. Should manual override still be available?

* Yes

1. What kind of alerts should the robot send to operators?

* Company question

1. Are we allowed to modify the given physical robot?

* Look above

1. Should the robot try to “save itself”? I.e., return to exit in case of low battery.

* YES

Multiple robots working together: Must? (should) (cool, really nice)

Other ideas:

* Add LiDAR (think 360 vs fixed FoV, Flash vs line scan)