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Overview

- 1. Eigenvectors and Eigenvalues
- 2. Principal Component Analysis
- 3. Practical Example

Eigenvectors and Eigenvalues

A vector $v \in \mathbb{R}^n$ is an *eigenvector* of a matrix $A \in \mathbb{R}^{n \times n}$ if

$$Av = \lambda v \tag{1}$$

where λ is a scalar called the *eigenvalue* associated with ν . Eigenvectors (values) are found by solving (1)

$$(A - \lambda I)v = 0 (2)$$

Eq. (2) has a non-zero solution v only if

$$\det(A - \lambda I) = 0 \tag{3}$$

Eigenvectors and Eigenvalues

Example: find the eigenvectors and eigenvalues of matrix

$$A = \begin{bmatrix} 1 & 0 \\ 1 & 3 \end{bmatrix}$$

Solving (3), we get

$$A - \lambda I = \begin{bmatrix} 1 - \lambda & 0 \\ 1 & 3 - \lambda \end{bmatrix}$$

$$\Rightarrow \det(A - \lambda I) = (1 - \lambda)(3 - \lambda)$$

$$\Rightarrow \lambda_1 = 1, \lambda_2 = 3$$

Two eigenvalues $\lambda_1, \lambda_2 \Rightarrow$ two eigenvectors v_1, v_2 .

Eigenvectors and Eigenvalues

Plugging λ_1 and λ_2 into (1) we have

$$\begin{bmatrix} 1 & 0 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} = 1 \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix}$$
$$\begin{bmatrix} 1 & 0 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} v_{21} \\ v_{22} \end{bmatrix} = 3 \begin{bmatrix} v_{21} \\ v_{22} \end{bmatrix}$$

From which we get $v_{11} = -2v_{12}$, $v_{21} = 0$ and $v_{22} \in \mathbb{R}$. That is:

- ▶ any vector $v_1 = [v_{11} \ v_{12}]^T$ where $v_{11} = -2v_{22}$ is an eigenvector of A with eigenvalue $\lambda_1 = 1$.
- ▶ any vector $v_2 = [v_{21} \ v_{22}]^T$ where $v_{21} = 0$ and $v_{22} \in \mathbb{R}$ is an eigenvector of A with eigenvalue $\lambda_2 = 3$.

Eigendecomposition

Decomposing a square matrix into its eigenvectors and eigenvalues is called *eigendecomposition*.

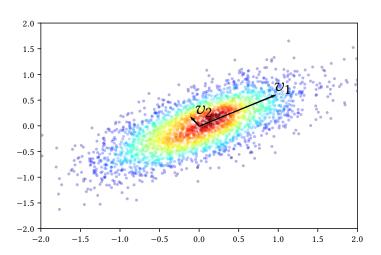
- eigenvectors are vectors which are fixed in direction under a given linear transformation
- the scaling factor of these eigenvectors is then called the eigenvalue

Suppose we have a set of data with a certain distribution.

- \triangleright eigenvectors v_i tell us the orientation of the distribution
- eigenvalues λ_i tell the variance in each dimension

Eigendecomposition

$$\Sigma = \begin{bmatrix} 0.3 & 0.2 \\ 0.2 & 0.3 \end{bmatrix}, \ \nu = \begin{bmatrix} 0.707 & -0.707 \\ 0.707 & 0.707 \end{bmatrix}, \ \lambda = \begin{bmatrix} 0.5 \\ 0.1 \end{bmatrix}$$



- Reduce the dimensionality of the original feature set by projecting onto a smaller subspace, where the *eigenvectors* will form the axes.
- ► We use the corresponding *eigenvalues* to choose which dimensions (*principal components*) to include.

Example: Iris Dataset

- R. A. Fisher, *The Use of Multiple Measurements in Taxonomic Problems*, 1936
- ► Data describing the morphologic variation of Iris flowers of three related species (three class labels)
- ► Four features: the length and width of the sepals and petals, in centimeters



(https://en.wikipedia.org/wiki/Iris_flower_data_set)

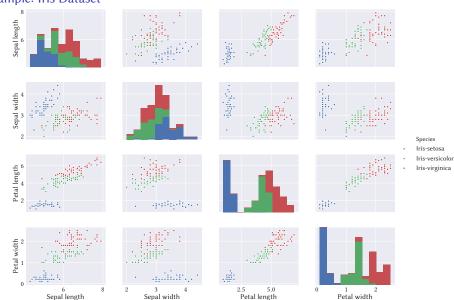
Example: Iris Dataset

Input data X

$$\mathbf{x}^{T} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} \text{Sepal length} \\ \text{Sepal width} \\ \text{Petal length} \\ \text{Petal width} \end{bmatrix}$$

- ▶ 150 instances (50 for each class), no missing values
- Predicted attribute: species

Example: Iris Dataset



Example: Iris Dataset

Step-by-step guide

- 1. Standardize the data (mean = 0, variance = 1)
- 2. Calculate eigenvectors and eigenvalues
- 3. Choose *k* principal components based on the *k* largest *eigenvalues*
- Construct projection matrix W from the selected k eigenvectors
- 5. Transform original feature space **X** using **W** to obtain *k*-dimensional feature subspace **Y**

$$\underbrace{ \begin{array}{c} \text{Projected data} \\ \text{Y} \end{array} }_{\text{Original data}} \underbrace{ \begin{array}{c} \text{Projection matrix} \\ \text{W} \end{array} }_{\text{}}$$

Example: Iris Dataset

- 1. Standardization (Z-score normalization)
 - Transform the data to have zero mean and unit variance

$$x' = \frac{x - \mu}{\sigma}$$

- Important step for many machine learning algorithms (eg., k-means, k-NN, SVM, LDA, PCA, logistic regression)
- When in doubt, standardize

Example: Iris Dataset

- 2. Eigenvectors and eigenvalues
 - ▶ Eigendecomposition of covariance matrix Σ , where

$$\sigma_{jk} = \frac{1}{n-1} \sum_{i=1}^{n} (x_{ij} - \overline{x}_j)(x_{ik} - \overline{x}_k)$$

We can also use the correlation matrix corr(X) where

$$r_{jk} = \frac{\sum_{i=1}^{n} (x_{ij} - \overline{x}_j)(x_{ik} - \overline{x}_k)}{(n-1)s_j s_k}$$

 In practice, we prefer singular value decomposition (computationally more efficient) over eigendecomposition

Example: Iris Dataset

2. Eigenvectors and eigenvalues

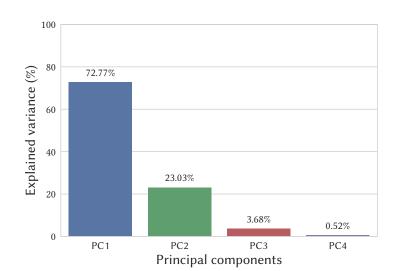
$$\Sigma = \begin{bmatrix} 1.0067 & -0.1101 & 0.8776 & 0.8234 \\ -0.1101 & 1.0067 & -0.4233 & -0.3589 \\ 0.8776 & -0.4233 & 1.0067 & 0.9692 \\ 0.8234 & -0.3589 & 0.9692 & 1.0067 \end{bmatrix}$$

$$V = \begin{bmatrix} 0.5224 & -0.3723 & -0.7210 & 0.2620 \\ -0.2634 & -0.9256 & 0.2420 & -0.1241 \\ 0.5813 & -0.0211 & 0.1409 & -0.8012 \\ 0.5656 & -0.0654 & 0.6338 & 0.5235 \end{bmatrix}, \lambda = \begin{bmatrix} 2.9304 \\ 0.9274 \\ 0.1483 \\ 0.0207 \end{bmatrix}^T$$

- ► Four dimensions → four eigen vector/value pairs
- Lamba values represent the amount of variance explained by each principal component

Example: Iris Dataset

3. Choosing principal components (PC1 and PC2)



Example: Iris Dataset

- 4. Construct the projection matrix
 - We keep the first two eigenvectors corresponding to the two principal components, and we obtain

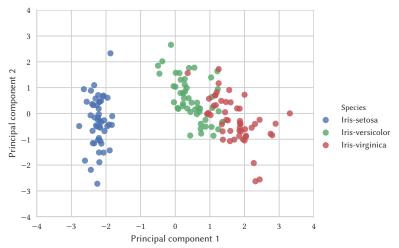
$$\mathbf{W} = \begin{bmatrix} 0.5224 & -0.3723 \\ -0.2634 & -0.9256 \\ 0.5813 & -0.0211 \\ 0.5656 & -0.0654 \end{bmatrix}$$

5. Project the feature space

$$Y = XW$$

Example: Iris Dataset

Samples scatterplot in the lower-dimensional feature space



Example: Iris Dataset

Contribution of original features to each principal component

	Principal component 1	Principal component 2
Sepal length	79.43%	12.77%
Sepal width	20.19%	78.92%
Petal length	98.34%	0.04%
Petal width	93.12%	0.39%

Question: How to reconstruct the original features?

Reconstruction of the original features

• Use \mathbf{W}^T to map the data back to the original dimensions

$$\hat{\mathbf{X}} = \mathbf{Y}\mathbf{W}^T$$

Example: image compression



(a) Original image



(b) Reconstruction from 50 PC

Other application areas

- Image processing
- Speech recognition
- Recommendation engines
- Text processing