

ICC@ICC: a taste of 2nd-order polytime complexity

Romain Péchoux,
Inria team Mocqua - CNRS, Inria, Université de Lorraine - LORIA

LoReL's seminar

November 28th, 2022



UNIVERSITÉ
DE LORRAINE



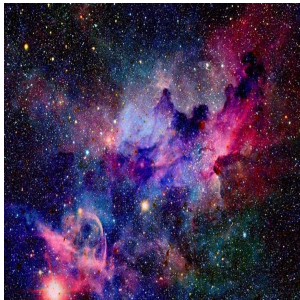
Today's talk

Today, we will focus on:

1. a brief overview of ICC (Implicit Computational Complexity)
2. a characterization of BFF (Basic Feasible Functionals)
 - ▶ \approx 2nd order polynomial time
 - ▶ a work with Emmanuel Hainry, Bruce Kapron, and Jean-Yves Marion

Computational Complexity (CC)

Computational Complexity (CC) studies problems/functions wrt resource usage.

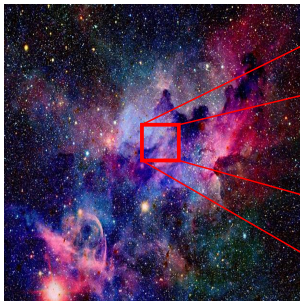


The Universe of
mathematical functions

(Images: NASA)

Computational Complexity (CC)

Computational Complexity (CC) studies problems/functions wrt resource usage.



The Universe of
mathematical functions

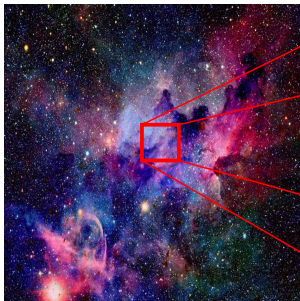


The Galaxy of
computable functions

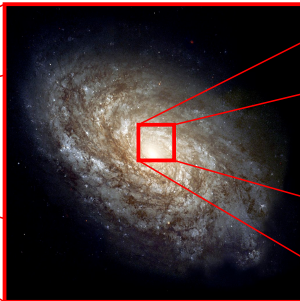
(Images: NASA)

Computational Complexity (CC)

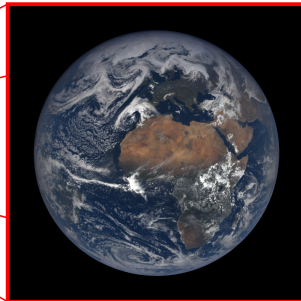
Computational Complexity (CC) studies problems/functions wrt resource usage.



The Universe of
mathematical functions



The Galaxy of
computable functions



The Planet of
tractable functions

Assume Cobham-Edmonds thesis: **tractable/feasible = polynomial time.**

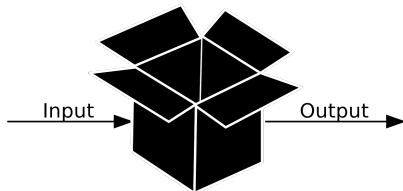
(Images: NASA)

Implicit computational complexity (ICC)

ICC: Subfield of CC aiming at providing characterizations of complexity classes:

- ▶ **machine-independent**
- ▶ with **no prior knowledge** on the complexity analyzed codes

If the characterization is **tractable** then ICC provides **automatic** static complexity analysis methods for **high level** PL.



State of the art:

- ▶ 30 years of intensive research,
- ▶ hundreds of publications,
- ▶ some academic tools
 - ▶ (Costa, SPEED, TcT, ...).

The ICC approach

ICC criterion

Take your favourite PL \mathcal{L} and your favourite complexity class \mathcal{C} :

$\mathcal{R} \subseteq \mathcal{L}$ is an **ICC criterion** if $\{\llbracket p \rrbracket \mid p \in \mathcal{R}\} = \mathcal{C}$.

Examples of complexity class \mathcal{C}

- ▶ P, FP,
- ▶ PSPACE, FSPACE,
- ▶ EXP, 2-EXP, ..., ELEMENTARY,
- ▶ NP,
- ▶ NC^0 , NC^1 , ..., NC
- ▶ PP, BPP, EQP, BQP, ...

Examples of programming language \mathcal{L}

- ▶ lambda-calculi,
- ▶ term rewrite systems,
- ▶ process calculi,
- ▶ reactive programs,
- ▶ imperative and OO programs,
- ▶ probabilistic and quantum programs.

A bunch of techniques (1/2)

Some ICC criteria

- ▶ **function algebra**: [Cobham65], [Bellantoni-Cook92], [Clote99] for a survey
- ▶ **linear logic** based approaches
 - ▶ light logics: LLL [Girard87], ILAL [Asperti-Roversi02], DLAL [Baillot-Terui04],
 - ▶ soft logics: SLL [Lafont04], STA [Gaborardi-Ronchi Della Rocca07],
 - ▶ non size-increasing [Hofmann99].
- ▶ **“potential”** based methods
 - ▶ interpretations: “quasi” [Bonfante-Marion-Moyen11], “sup” [Marion-Péchoux09], higher-order [Baillot-Dal Lago16],
 - ▶ amortized resource analysis: [Jost et al.10], [Hoffmann-Hofmann10],
 - ▶ sized-types: [Vasconcelos08], [Avanzini-Dal Lago17],
 - ▶ cost semantics: [Danner et al.15].

A bunch of techniques (2/2)

Some ICC criteria

- ▶ **control flow (tiering-based)** techniques:
 - ▶ safe recursion [Bellantoni-Cook92],
 - ▶ ramified recurrence [Leivant-Marion94],
 - ▶ tiering [Marion11],
 - ▶ read-only/write-only: [Jones01], [De Carvalho-Simonsen14].
- ▶ **matrix-based** type systems:
 - ▶ μ -measure [Niggli-Wunderlich06],
 - ▶ mwp bounds [Kristiansen-Jones09], resource control graphs [Moyen09].
- ▶ **empirical approaches** (some of them using abstract interpretations): COSTA [Albert et al.07], SPEED [Gulwani09], TcT [Avanzini-Moser-Schaper16].

Main techniques (1/2): typing

Tractable functions

Characterized by all techniques by preventing exponentiation,
i.e. by **preventing the iteration** of methods duplicating the size of their inputs.

► Prevent iteration with a **type discipline**:

► $!A \multimap \S A$ in LAL,

► $1 \rightarrow 0$ in tier-based approaches,

► Read-Only \rightarrow Write-Only in Jones/Simonsen

► $\begin{bmatrix} \ddots & & \\ & P & \\ & & \ddots \end{bmatrix}$ in mwp (whereas $\begin{bmatrix} \ddots & & \\ & M & \\ & & \ddots \end{bmatrix}$ is required for iterability).

Main techniques (2/2): potentials

Tractable functions

Characterized by all techniques by preventing exponentiation,
i.e. by **preventing the iteration** of methods duplicating the size of their inputs.

- ▶ By using a **potential-based constraints** implying a decrease along reduction:

$$P \geq \begin{array}{ccccccc} t_1 & \rightarrow & t_2 & \rightarrow & \dots & \rightarrow & t_n \\ [t_1] & \geq & [t_2] & \geq & \dots & \geq & [t_n] \end{array}$$

- ▶ (polynomial) interpretations-based methods,
- ▶ amortized resource analysis,
- ▶ ert-transformers method [Kaminski et al.06],
- ▶ sized-types.

Intensional limits

Definition [Intensional completeness]

A characterization is intensionally complete if any tractable algorithm computing this function is accepted.

Theorem [Hajek79]

Providing an intensionally-complete characterization of tractable functions is a Σ_0^2 -complete problem.

However, for automation purpose, the studied characterizations are decidable (even better tractable).

Observation

Hence there are false negative.

Beyond ICC: extensions

Intensional improvements

- ▶ Soft Type Assignment
[Gaboardi-Ronchi Della Rocca07]
- ▶ Dual Light Affine Logic [Baillot-Terui04]
- ▶ Sup-interpretations [Marion-Péchoux09]

Adaptations of existing tools

- ▶ Tiering on imperative programs
[Marion11], [Marion-Leivant13]
- ▶ Tiering on OO programs
[Hainry-Péchoux18]
- ▶ Interpretations of HO-TRS (STTRS)
[Baillot-Dal Lago12]

Extensions to new paradigms

- ▶ Concurrent systems
 - ▶ Light logics and multi-threads
[Amadio-Madet11]
 - ▶ Soft logics and processes
[Martini-Dal Lago-Sangiorgi16]
- ▶ Probabilistic programs:
[Avanzini-Dal Lago-Ghyselen19]
- ▶ Quantum programs
[Dal Lago-Masini-Zorzi10]
- ▶ Real functions
[Bournez-Gomaa-Hainry11]
- ▶ Coinductive data
[Gaboardi-Péchoux15]

Summary on ICC

Strong links with other research domains:

- ▶ Termination techniques (often coming from and/or combined with)
- ▶ Computability theory (Primrec, undecidable classes, ...)
- ▶ Finite model theory (common goals)
- ▶ Static analysis (type systems, abstract interpretations, empirical approaches)

A **survey on ICC** in my HDR, available at <https://members.loria.fr/RPechoux/>

What about 2nd order complexity classes?

2nd-order objects are functions in $\overbrace{(\mathbb{N} \rightarrow \mathbb{N})}^{\phi} \rightarrow \mathbb{N}$

2nd-order polynomial time is taken to be the class of Basic Feasible Functionals (BFF)

Goal (Open problem for more than 20 years)

Find a **tractable** static analysis technique for certifying 2nd order polynomial time complexity.

Rephrasing: Find a tractable restriction \mathcal{R} such that $\llbracket \mathcal{R} \rrbracket = \text{BFF}$.

N.B.: The problem was solved for **type-1** polytime FP by Bellantoni and Cook in 1992.

A reminder on 2nd order polynomial time

BFF was introduced by Melhorn in 1976.

Theorem [Cook and Urquhart [1989]]

$$\text{BFF} = \lambda(\text{FP} \cup \{\mathcal{R}\})_2$$

\mathcal{R} is a type-2 bounded iterator:

$$\mathcal{R}(\epsilon, a) = a$$

$$\mathcal{R}(ix, a) = \min(\phi(ix, \mathcal{R}(x, a)), \psi(ix))$$

Theorem [Cook and Kapron [1990]]

The set of functionals computable by an OTM in time $P(|\phi|, |\mathbf{a}|)$ is exactly BFF.

2nd order polynomials and size function are defined by:

- ▶ $P(X_1, X_0) ::= c \in \mathbb{N} \mid X_0 \mid X_1(P) \mid P + P \mid P \times P$
- ▶ $|\phi|(n) = \max_{|x| \leq n} |\phi(x)|$

How to get rid of 2nd order polynomials?

Definition [Oracle Polynomial Time (OPT) [Cook92]]

Let $n^{\phi, \mathbf{a}}$ be the biggest size of \mathbf{a} and of an oracle's answer in the run of $M(\phi, \mathbf{a})$.
An OTM is in OPT if its runtime is bounded by $P(n^{\phi, \mathbf{a}})$, for some type-1 polynomial P .

$\text{BFF} \subsetneq \text{OPT}$ as it contains exponential functions.

Theorem [Kapron and Steinberg [2018]]

$$\text{BFF} = \lambda(\text{OPT} \cap \text{FLR})_2 = \lambda(\text{OPT} \cap \text{FLAR})_2$$

- ▶ FLR = Finite Length Revision
- ▶ FLAR = Finite LookAhead Revision

Finite Length Revision

Definition [Finite Length Revision - Kawamura and Steinberg [2017]]

An OTM is in FLR, if, for any input, the number of times the oracle answer is bigger than all of the previous oracle answers is bounded by a constant.

Example

```
while (x > 0) {
    y =  $\phi(x)$ ;
    x = x - 1;
}
```

not (FLR) if $\phi \searrow$

Example

```
while (x < n && y < 8) {
    y =  $\phi(x)$ ;
    x = x + 1;
}
```

(FLR) with constant 8

Finite LookAhead Revision

Definition [Finite LookAhead Revision - Kapron and Steinberg [2018]]

An OTM is in FLAR, if, for any input, the number of times a query is posed whose size exceeds the size of all previous queries is bounded by a constant.

Example

```
while (x > 0) {  
    y =  $\phi(x)$ ;  
    x = x - 1;  
}
```

(FLAR) with constant 0

Example

```
while (x < n && y < 8) {  
    y =  $\phi(x)$ ;  
    x = x + 1;  
}
```

not (FLAR) for $\phi = \lambda z.4$

How to get rid of (Oracle Turing) machines?

→ Design a typed PL ensuring that computed functions are in $\text{OPT} \cap \text{FLAR}$.

Imperative PL on words with oracles

Expressions $\ni e ::= x \mid \text{true} \mid \text{false} \mid \text{op}(e, \dots, e) \mid \phi(e \upharpoonright e)$

Commands $\ni st ::= x := e; \mid st \ st \mid \text{if}(e)\{st\}\text{else}\{st\} \mid \text{while}(e)\{st\}$

In an oracle call $\phi(w \upharpoonright v)$:

- ▶ ϕ computes a type-1 function on words, i.e. $\phi \in \mathbb{W} \rightarrow \mathbb{W}$.
- ▶ w is the **oracle input**.
- ▶ v is the **input bound**: $w \upharpoonright v = w_1 \dots w_{|v|}$.

Tier-based type discipline

Tiers k, k', \dots are security levels (in \mathbb{N}) assigned to Expressions and Commands.

The type system ensures some non-interference properties.

In a tier k command:

- ▶ the program flow cannot be controlled by expressions of a lower tier $k^- < k$,
- ▶ data of upper tier $k^+ \geq k$ cannot increase (in size).

Judgments: $\Gamma, \Delta \vdash st : (k, k_{in}, k_{out})$ with $(k, k_{in}, k_{out}) \in \mathbb{N}^3$

1. The tier k implements the non-interference policy.
2. The *innermost* tier k_{in} is used for declassification.
3. The *outermost* tier k_{out} is used to ensure FLAR on oracle calls.

Tier-based type system: an overview

Typing rules

$$\frac{\vdash x : (k_1, k_{in}, k_{out}) \quad \vdash e : (k_2, k_{in}, k_{out}) \quad k_1 \leq k_2}{\vdash x := e : (k_1, k_{in}, k_{out})} \text{ (Asg)}$$

$$\frac{\vdash e : (k, k_{in}, k_{out}) \quad \vdash st : (k, k, k_{out}) \quad 1 \leq k \leq k_{out}}{\vdash \text{while}(e)\{st\} : (k, k_{in}, k_{out})} \text{ (Wh)}$$

$$\frac{\vdash e : (k, k_{in}, k_{out}) \quad \vdash e' : (k_{out}, k_{in}, k_{out}) \quad k < k_{in} \leq k_{out}}{\vdash \phi(e \upharpoonright e') : (k, k_{in}, k_{out})} \text{ (Orc)}$$

⋮

Illustrating example

Program computing the decision problem $\exists n \leq x, \phi(n) = 0$.

```
y = x;  
z = false;  
while(x1 >= 0){  
  if( $\phi(y^0 \upharpoonright x^1) == 0$ ){  
    z0 = true;  
  } else {;}  
  x1 = x1 - 1;  
}  
return  z
```

- ▶ The program is typable and the while body has tier $(1, 1, 1)$.
- ▶ The computed function is in $\text{OPT} \cap \text{FLAR}$.

A tier-based characterization of BFF

- ▶ Let SAFE be the set of typable programs.
- ▶ Let SN be the set of strongly normalizing programs.
- ▶ Let $\llbracket X \rrbracket$ be the set of functions computed by programs in X .

Theorem [Hainry-Kapron-Marion-Péchoux [LICS2020]]

$$\text{BFF} = \lambda(\llbracket \text{SAFE} \cap \text{SN} \rrbracket)_2$$

Main drawbacks:

- ▶ Lambda closure (for completeness)
- ▶ Termination assumption (for soundness)

How to get rid of the lambda-closure?

Naïve idea: internalize lambda-abstraction and application into the language.
 → cannot be done straightforwardly as it breaks soundness.

Extended language (e_i : e is a type- i object)

(Expressions)	$e ::= x_0 \mid \text{op}(e, \dots, e) \mid x_1(e \upharpoonright e)$
(Statements)	$\text{st} ::= [x_0 := e]; \mid \text{st st} \mid \text{if}(e)\{\text{st}\}\{\text{st}\} \mid \text{while}(e)\{\text{st}\}$
(Procedures)	$P ::= P(\overline{x_1}, \overline{x_0})\{\text{st return } x_0\}$
(Terms)	$t ::= x \mid \lambda x.t \mid t@t \mid \text{call } P(\overline{\{x_0 \rightarrow t_0\}}, \overline{t_0})$
(Programs)	$\text{prog} ::= t_0 \mid \text{declare } P \text{ in prog}$

Solution: type-1 arguments in a procedure call are restricted to closures $\{x_0 \rightarrow t_0\}$.

Type system

The extended type system just consists of two layers:

- ▶ SAFE procedures (using our [LICS2020] paper),
- ▶ Simply-typed terms on words \mathbb{W} .

Definitions

A program is a **type- i** program if all its λ -abstractions are of order $\leq i$.

- ▶ SAFE_i is the set of type- i typable programs.
 - ▶ Remark: SAFE_0 is the set of typable programs without lambda-abstraction.
- ▶ SN is still the set of strongly normalizing programs.

Example

```

prog( $\phi, w$ )  $\triangleq$  declare KS(Y, v) {
    u := 10;
    z :=  $\epsilon$ ;
    while ( $v^1 \neq 0$ ) { //  $k_{in} = k_{out} = 1$ 
         $v^1 := v - 1$ ;
         $z^0 := Y(z^0 \upharpoonright u^1)$ 
    }
    return z
}
in call KS( $\{x \rightarrow \phi @ (\phi @ x)\}$ , w)

```

- ▶ $\llbracket \text{prog} \rrbracket \in (W \rightarrow W) \rightarrow W \rightarrow W$
- ▶ $\llbracket \text{prog} \rrbracket(\phi^{W \rightarrow W}, w^W) = F_{|w|}(\phi)$ with $\begin{cases} F_0(\phi) = \epsilon \\ F_{n+1}(\phi) = (\phi \circ \phi)(F_n(\phi)^{\leq |10|}) \end{cases}$
- ▶ $\text{prog} \in \text{SAFE}_0 \cap \text{SN}$ whereas $\llbracket \text{prog} \rrbracket \notin \text{OPT} \cap \text{FLAR}$.

First implicit and complete characterizations of BFF

Characterizations without lambda-closure:

Theorem [Hainry-Kapron-Marion-Péchoux [FoSSaCS2022]]

$$\forall i \geq 0, \llbracket \text{SAFE}_i \cap \text{SN} \rrbracket = \text{BFF}$$

Lambda-abstraction is not required for completeness:

Theorem [Hainry-Kapron-Marion-Péchoux [FoSSaCS2022]]

$$\llbracket \text{SAFE}_0 \cap \text{SN} \rrbracket = \text{BFF}$$

In particular $\llbracket \text{prog} \rrbracket \in \llbracket \text{SAFE}_0 \cap \text{SN} \rrbracket$.

→ Can we weaken the SN requirement?

How to get rid of Strong Normalization?

We consider Size Change Termination (SCT).

General idea

Program:

```
while (x > 0) {
    y =  $\phi(x)$ ;
    x = x - 1;
}
```

\Rightarrow

Size change graph abstraction:

$$\left(\begin{array}{cc} x & \xrightarrow{-1} x \\ y & y \end{array} \right)^\omega$$

Theorem [Lee, Jones, and Ben Amram [POPL2001]]

“If every infinite computation would give rise to an infinitely decreasing value sequence in the size-change graph, then no infinite computation is possible.”

→ SCT is not “tractable”: PSPACE-complete.

Tractable characterizations of BFF

Completeness is preserved for SCT and for an instance SCP (Ben Amram-Lee [2007]).

Theorem [Hainry-Kapron-Marion-Péchoux [FoSSaCS2022]]

$$\forall i \geq 0, \llbracket \text{SAFE}_i \cap \text{SCP}_S \rrbracket = \text{BFF}$$

SCP_S can be decided in time quadratic in the program size.

Theorem [Type inference]

- ▶ $\text{prog} \in \cup_i \text{SAFE}_i \cap \text{SCP}_S$ is Ptime-complete (using Mairson[2004]).
- ▶ $\text{prog} \in \text{SAFE}_0 \cap \text{SCP}_S$ is in time cubic in $|\text{prog}|$ (using HKMP[2022]).

Conclusion

Conclusion

We have obtained **sound** and **complete** characterizations of type-2 polynomial time:

- ▶ **machine-independent**,
 - ▶ a typed programming language with procedure calls
- ▶ **implicit**,
 - ▶ no prior knowledge on the bound is required
- ▶ **tractable** and can thus be automated.
 - ▶ decidable type inference (in polynomial time)

Open issues

- ▶ What about Finite Length Revision (FLR)?
- ▶ Delineate a larger family of completeness preserving termination techniques.
- ▶ Adapt this method to a purely functional Programming Language.